# ESTABLISHING ACTIVE FIRE DATA CONTINUITY BETWEEN AQUA MODIS AND SUOMI NPP VIIRS

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# Why do we need MODIS-VIIRS continuity?

- MODIS is the first sensor designed to <u>detect and</u> <u>characterize hot targets</u> (predominantly actively burning fires) on a <u>global and systematic basis</u>
- MODIS fire data have been <u>extensively used</u> for disaster and resource management, air quality applications, ecosystem monitoring, climate studies etc.
- The community expects and <u>society needs</u> the continuation of these high quality observations from VIIRS on NPP (launched on October 28, 2011) and future JPSS satellites

#### **Examples of MODIS fires/thermal anomalies**



JANUARY FEBRUARY MARCH APRIL MAY JUNE JULY AUGUST SEPTEMBER OCTOBER NOVEMBER DECEMBER

Announcements

## MODIS – VIIRS fire continuity: fundamental possible scenarios

- 1. <u>Orbital/daily</u> MODIS and VIIRS fire maps are <u>compatible</u>.
- 2. Spatially and temporally <u>aggregated fire statistics</u> from MODIS and VIIRS <u>are compatible</u>.

 Not even spatially and temporally aggregated fire statistics from MODIS and VIIRS are compatible, but MODIS and VIIRS provide <u>compatible general</u> <u>patterns and trends of fire dynamics</u>.

## Aqua MODIS vs. NPP VIIRS: fundamental features

- Aqua and NPP have similar overpass times (1:30pm)
  - sampling of the diurnal fire cycle is similar
- Saturation levels of the primary bands allow <u>unsaturated</u> radiance measurements for most fires
  - Band 21/22 for MODIS and M13 for VIIRS
- Some differences in <u>spectral placement</u>
- Processing <u>algorithms are compatible</u>
  - Current VIIRS algorithm is based on MODIS, albeit an earlier version
  - Differences can be resolved and the impact can be minimized
- Primary driver of differences is spatial sampling
  - Pixel size
  - Variations along scanline (aggregation schemes)
  - Variations within pixels (line-spread function, aggregation)
  - Differences in swath width (VIIRS has no gaps at low latitudes)

# Will orbital/daily MODIS and VIRS fire maps be compatible?

VIIRS spatial resolution is higher that of MODIS; in general, VIIRS is expected to detect smaller fires at nadir



90% probability of detection; boreal forest; nadir view



(based on modeling using ASTER fire masks)

7 Aug 2004 1405 UTC ~11.7° S 56.6° W (Brazil)

First light NPP VIIRS fire data

M5-M4-M3 RGB + IDPS Active Fire ARP

January 19, 2012 ~11:05 UTC



...followed by Aqua MODIS five minutes later

Band 1-4-3 RGB + MYD14

January 19, 2012 ~11:05 UTC



MODIS vs. VIIRS detections

both near-nadir

32 38 34 36 30 40 0 72/9730/26/50 0/0/0 607  $\bigcirc$  $\infty$ 52/42/5<mark>6</mark>\* 87\*/76/137 50/40/63 4/3/5 တ Ø 146/84/105 6/10/30 0/0/0 4/3/5 124/63/63 159/83/114 0/0/0 0/0/0 30/22/17  $\sim$ 41/41/52 1/1/20/0/2 3/0/0 3\*/0/1 38 32 30 34 36 40 **VIIRS/overlap/MODIS** VIIRS Scan Angle (deg) 32 36 20 24 28 8 12 16  $\bigcirc$ 4

January 19, 2012 ~11:05 UTC

#### **Angular sampling**



#### MODIS vs. VIIRS fire counts

Jan 19-24



Preliminary, for illustration purposes only!

![](_page_11_Figure_0.jpeg)

Jan 19 2012

Aqua

NPP

#### Western Australia

![](_page_12_Figure_1.jpeg)

Jan 19 2012 06:00 UTC

#### Western Australia

![](_page_13_Figure_1.jpeg)

#### Jan 19 2012 05:45 UTC

#### South-East Asia

![](_page_14_Figure_1.jpeg)

#### Jan 19 2012 06:15 UTC

#### South-East Asia

![](_page_15_Figure_1.jpeg)

#### Jan 19 2012 05:57 UTC

![](_page_16_Figure_0.jpeg)

Aqua

Jan 20 2012

NPP

### Florida

![](_page_17_Figure_1.jpeg)

VIIRS Scan Angle (deg)

35

Jan 20 2012 18:33 UTC

<sup>39</sup> 41 43 46 48 50 52 54 VIIRS/overlap/MODIS 37

29

27

25

### Florida

![](_page_18_Figure_1.jpeg)

35

Jan 20 2012 19:15 UTC

<sup>37</sup> <sup>39</sup> <sup>41</sup> <sup>43</sup> <sup>46</sup> <sup>48</sup> <sup>50</sup> <sup>52</sup> <sup>54</sup> **VIIRS/overlap/MODIS** 

## Truly compatible spatial sampling for MODIS-VIIRS comparison

- Simultaneous, compatible spatial sampling
  - SNO/SNOx type method for intercalibration
  - primarily driven by sample size
  - angular effects secondary, but potentially nonnegligible, especially for off-nadir looks
- Matching swath segments with similar spatial sampling
- Advantage: allows for direct comparison of fire data
- Disadvantage: angular effects are not accounted for

#### **Compatible swath segments**

![](_page_20_Figure_1.jpeg)

In principle, it is possible to select swath segments with compatible sampling for direct intercomparison

*Compatible cloud masks are crucial* 

(Need for spatially explicit land/water/cloud/fire mask in the VIIRS product!)

## **Possible scenarios - practicalities**

- Orbital/daily MODIS and VIIRS fire maps are compatible.
  - Not crucial for operational users as long as VIIRS is comparable or superior to MODIS
- 2. Spatially and temporally <u>aggregated fire statistics</u> from MODIS and VIIRS <u>are compatible</u>.
  - Useful for evaluating algorithm consistency, data continuity
- MODIS and VIIRS provide <u>compatible general</u> <u>patterns and trends of fire dynamics</u>.
  - Contingent upon the statistical population of fires
  - Statistics can be derived from Landsat-class data
  - Fire of interest what is the desired lower limit?

# **Explicit validation**

<u>Near-nadir</u> pixels (using ~2,500 coincident ASTER scenes)

17K MOD14 pixels sampled

120K MODIS pixels with 1+ ASTER fire pixel

![](_page_22_Picture_4.jpeg)

<u>Off-nadir</u> pixels (using ~3,700 near-coincident TM scenes)

12K MOD14 pixels sampled

#### 270K MODIS pixels with 1+ TM fire pixel

![](_page_22_Figure_8.jpeg)

# **Explicit validation**

Near-nadir pixels

(using ~2,500 coincident ASTER scenes) ASTER 2001-2006 SWIR detector problem > May 2007

Kilometers

MODIS/ASTER 19 Jan 2006 0852UTC (near nadir)

<u>Off-nadir</u> pixels (using ~3,700 near-coincident TM scenes)

Landsat5 TM 2001-2010

Fire-related artifacts – saturation/bleeding

![](_page_23_Figure_8.jpeg)

MODIS/TM 04 Aug 2007 1533UTC (52° scan angle)

# **Explicit validation**

Near-nadir pixels

(using ~2,500 coincident ASTER scenes) ASTER 2001-2006

SWIR detector problem > May 2007

![](_page_24_Figure_4.jpeg)

MODIS/ASTER 19 Jan 2006 0852UTC (near nadir)

<u>Off-nadir</u> pixels (using ~3,700 near-coincident TM scenes)

Landsat5 TM 2001-2010

Fire-related artifacts – saturation/bleeding

![](_page_24_Figure_9.jpeg)

MODIS/TM 04 Aug 2007 1533UTC (52° scan angle)

## Algorithm continuity: MODIS Collection 6 updates

- Adaptive assignment of potential fire thresholds to <u>better capture small, cool fires</u> and <u>reduce false</u> <u>alarms</u> occurring in hot, arid environments;
- A new rejection test to <u>eliminate persistent false</u> <u>alarms</u> caused by <u>small clearings</u> within Amazonian rainforest
- Extended processing to <u>water pixels</u> to facilitate monitoring of offshore gas flaring
- Improvements to the <u>internal cloud mask</u> to eliminate occasional misclassification of snow and desert as cloud.

## Algorithm continuity: MODIS Collection 6 updates

#### **MODIS Collection 5 (and 4)**

#### **MODIS Collection 6**

![](_page_26_Figure_3.jpeg)

True fire detections and false alarms from Terra MODIS over a small-scale cleared area in the Amazon on August 27, 2001, as detected by the MODIS Collection 5 and 6 algorithms. The MODIS Collection 6 algorithm removed the false alarms.

# Summary and conclusions

- Initial assessment of the NPP VIIRS fire product is encouraging
- True statistical <u>comparison is possible</u> using proper matching of similar sampling conditions
- Implementation of <u>new MODIS algorithm</u> <u>components</u> and sensor-specific tuning are necessary
- Need for spatially explicit <u>fire mask</u> and <u>Fire</u>
  <u>Radiative Power</u> in the VIIRS product
- Explicit validation is crucial
- Continuity of the MODIS <u>Climate Modeling Grid</u> (CMG) product is necessary for <u>long-term and large-</u> <u>scale monitoring</u>