

DEFECT DETECTION AND CHARACTERIZATION IN PIPELINES

Current Programs at SwRI

**Gary Burkhardt
Southwest Research Institute**

Government/Industry Pipeline R&D Forum

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New Orleans, LA



TARGET AREAS

- ❖ Inspection of unpiggable pipelines
- ❖ Monitoring of cased pipelines
- ❖ Characterization of mechanical damage defects



APPLICATION OF RFEC TESTING TO INSPECTION OF UNPIGGABLE PIPELINES

U.S. DOT-PHMSA Contract No. DTRS56-02-T-0001



Participation by
Northeast Gas Assn.
Carnegie Mellon
U.S. DOE-NETL



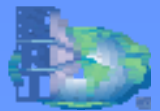
PROBLEM

Some pipelines are “unpiggable” and cannot be inspected



Low Flow Rates
Low Pressures

Branch Connections
Non-Circular Valves
90-degree Elbows
Multiple Diameters
No Launch Traps



Project Objectives

- ❖ Develop remote field eddy current (RFEC) inspection system for natural gas pipelines that are currently unpiggable
- ❖ Accommodate obstacles such as elbows and Tees
- ❖ Integrate RFEC system with Carnegie Mellon robot
- ❖ Demonstrate in operating pipeline

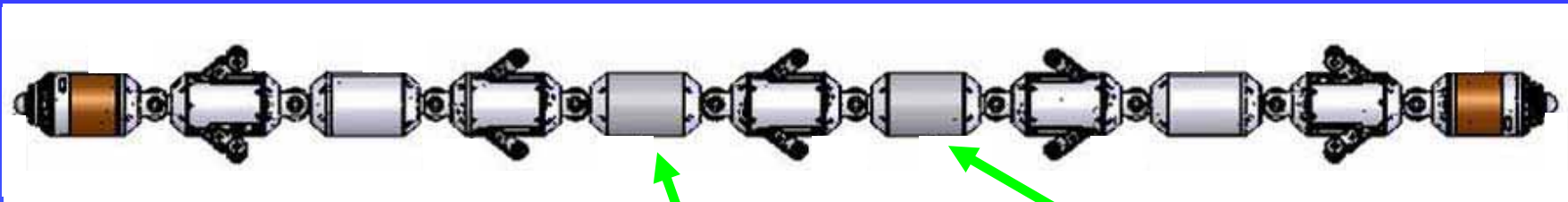


APPROACH

- ❖ Use remote-field eddy current (RFEC) method
 - RFEC system can adjust to variable pipe size and retract to pass through obstacles
 - Detects ID and OD corrosion defects
 - Can characterize defect depth, length, width
- ❖ Integrate RFEC with Carnegie Mellon Explorer II robotic transport system
 - Adjusts to variable pipe size and retracts to pass through obstacles
 - Self-powered
 - Nontethered—wireless remote control
 - Launched while pipe in service

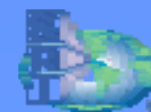
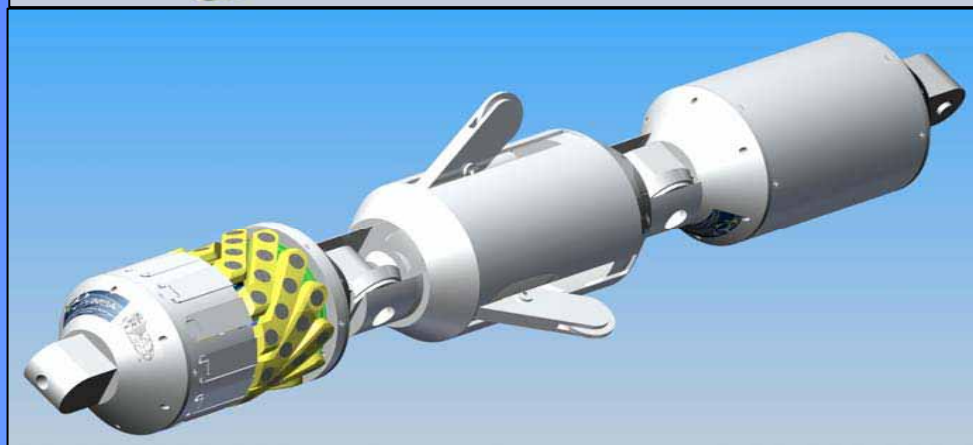
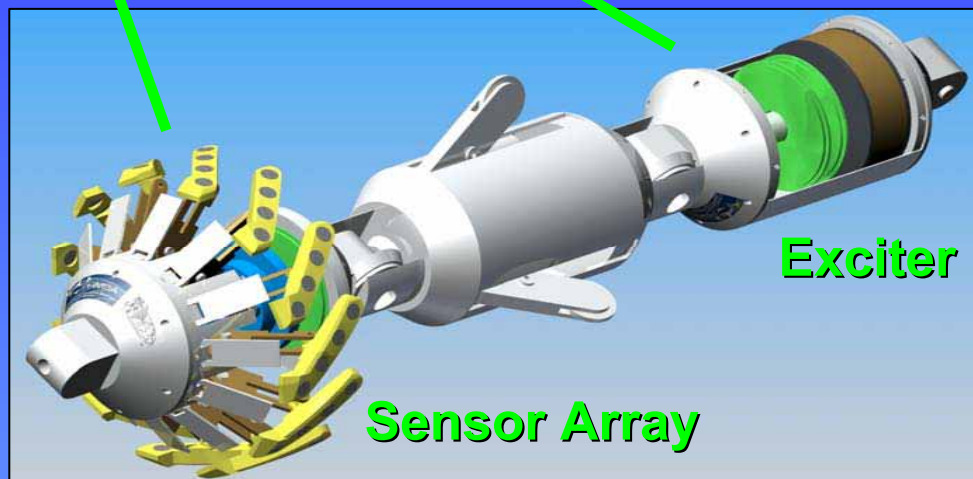


RFEC DESIGN FOR EXPLORER II

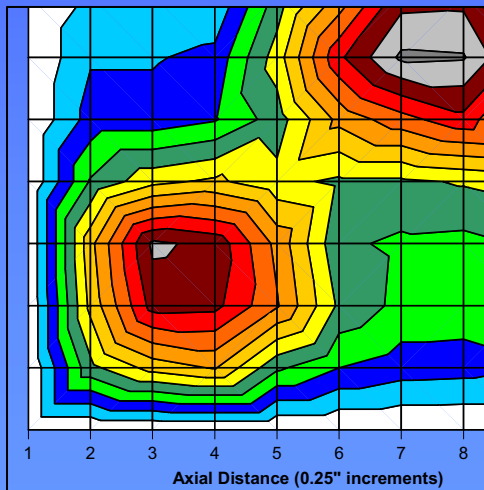
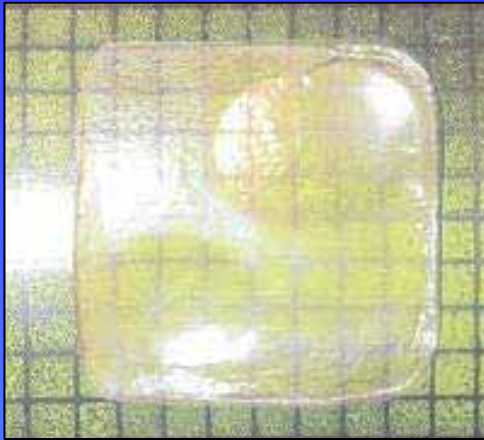


CMU Explorer II
Robot

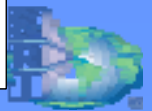
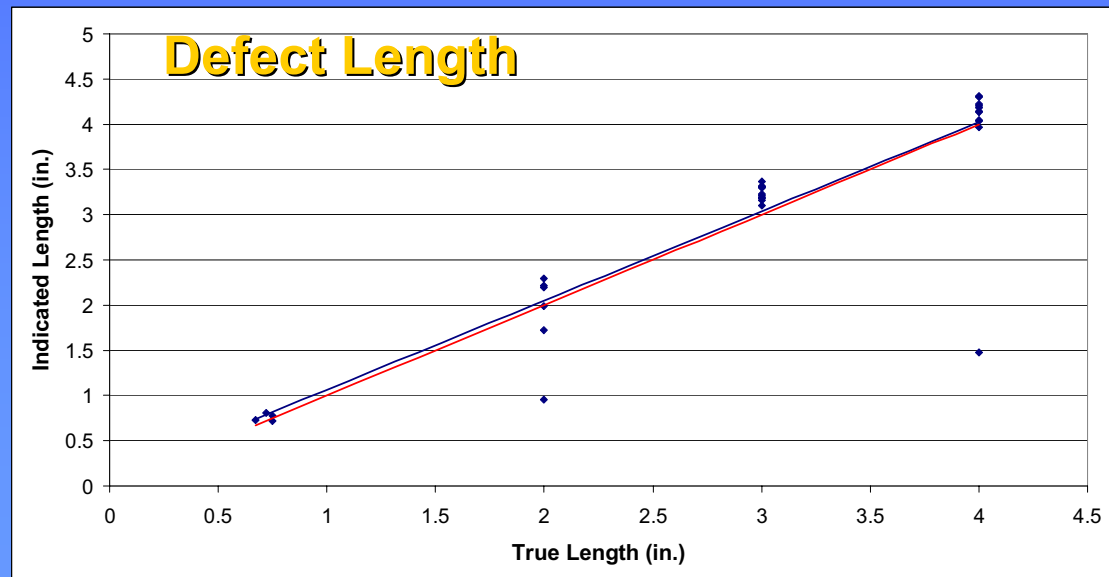
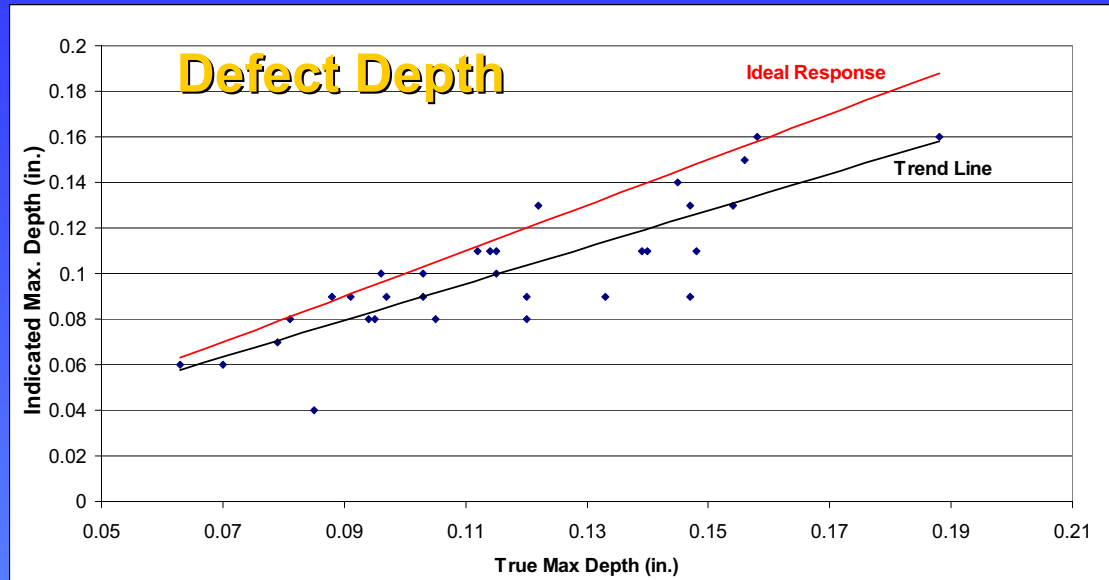
SwRI RFEC
Inspection
Modules



BLIND TEST DEFECT CHARACTERIZATION (Breadboard System)



Typical Defects



CURRENT STATUS/PLANS

- ❖ RFEC modules undergoing fabrication and testing
- ❖ Integration with Explorer II robot in Spring 2007
- ❖ Demonstration on live pipeline in Summer 2007



Expected Outcome

- ❖ Inspection system for 6-8 inch pipelines that can negotiate 90 deg. elbows and Tee joints
- ❖ Analysis capability to characterize depth, length, & width of wall-loss defects
- ❖ Demonstration in live pipeline
- ❖ Transfer of technology



LONG-TERM MONITORING OF CASED PIPELINES USING LONG-RANGE GUIDED-WAVE TECHNIQUE

**SwRI Project 14.12266
for
NYSEARCH/NGA and DOT/PHMSA**



PROBLEM

INSPECTION of CASED LINES AT ROAD CROSSINGS

- ❖ High-consequence area
- ❖ Require direct assessment (DA)
- ❖ Access is difficult, need remote inspection technique



PROJECT OBJECTIVE

- ❖ Apply Magnetostrictive Sensor (MsS) long-range guided-wave testing to “cased crossings”
- ❖ Develop defect characterization capability
- ❖ Develop long-term monitoring capability using permanently installed sensors
- ❖ Perform field validation



MsS (MAGNETOSTRICTIVE SENSOR)

- ❖ MsS is a guided-wave probe that uses magnetostrictive effects for wave generation and detection
- ❖ Thin, ferromagnetic strips are bonded around pipe with encircling coils over the strips
- ❖ Sensors are inexpensive and suitable for long-term monitoring



MsS TEST SETUP ON A CASED-LINE MOCKUP



PROJECT STATUS/PLANS

- ❖ Defect signal modeling refined and validated
- ❖ Defect characterization algorithm development & software improvement underway—complete in March 2007
- ❖ Field evaluation to begin in April 2007
 - In NGA's test bed in Binghamton, New York



EXPECTED OUTCOME

- ❖ Defect signal simulation software
- ❖ Data analysis software for inspection and monitoring
 - Including some capability of defect sizing
- ❖ Procedures for sensor installation for long-term monitoring
- ❖ Determine capabilities and limitations of long-range guided wave technique for cased pipeline



NONLINEAR HARMONIC (NLH) MONITORING OF GOUGED DENTS IN PIPELINE SPECIMENS UNDER CYCLIC LOADING

U.S. DOT-PHMSA Contract No. DTRS 56-04-T-001
and PRCI Contract GRI 8715



PROBLEM

- ❖ Delayed failures from mechanical damage are related to time-dependent accumulation of damage (e.g. fatigue cracking)
- ❖ Current ILI systems cannot determine mechanical damage severity



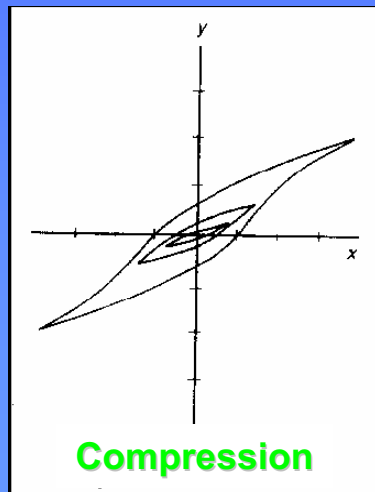
PROJECT OBJECTIVES

- ❖ Measure Nonlinear Harmonic (NLH) signals as a function of pressure cycles on full-scale pipe segments containing realistic gouged dents
- ❖ Derive NLH-based defect severity criteria related to fatigue life (delayed failure)
- ❖ Transfer NLH technology to ILLI company (Tuboscope)

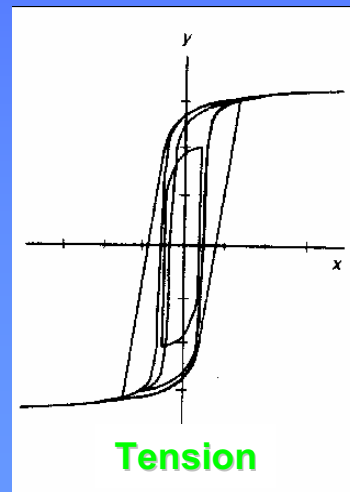


NONLINEAR HARMONICS (NLH)

- ❖ Uses AC magnetic field to locally infer magnetic properties of steel
- ❖ Strain anomalies produced by gouging change magnetic properties of steel and sensed by NLH

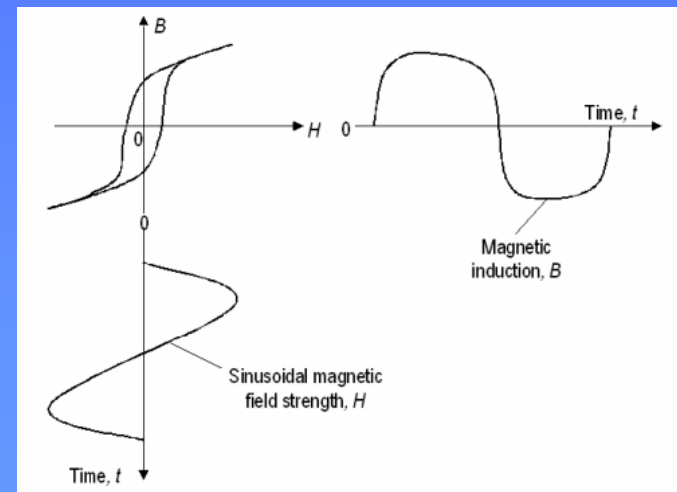


Compression

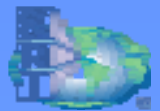


Tension

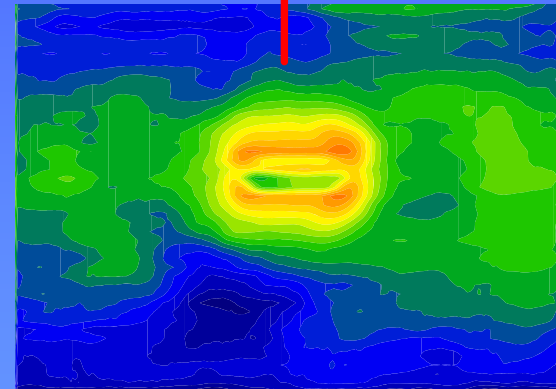
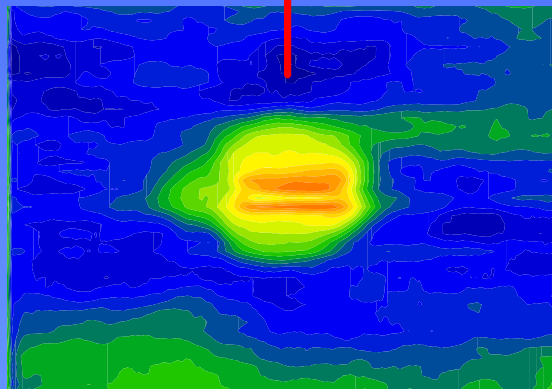
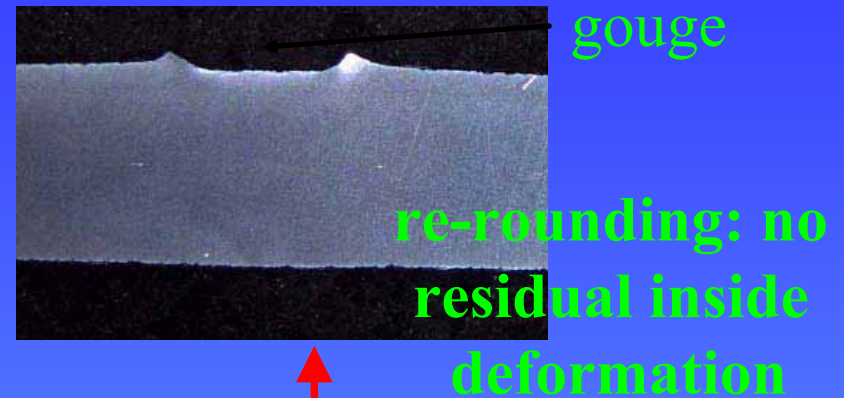
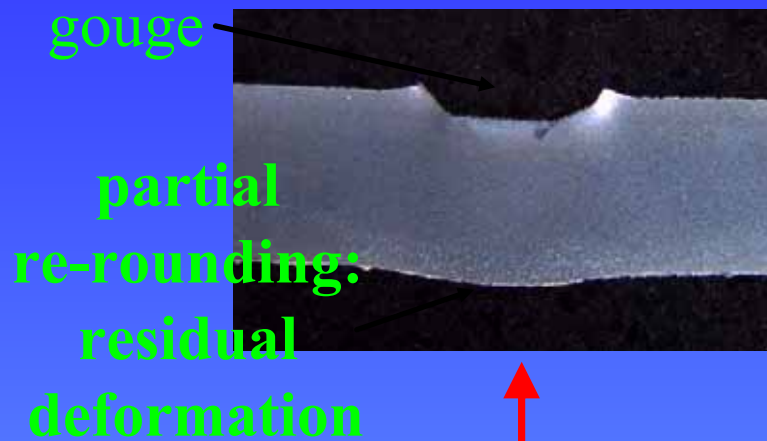
Magnetization Curves



NLH Signal Generation

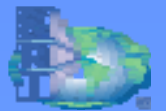


NLH RESPONSE TO GOUGING-INDUCED STRAINS

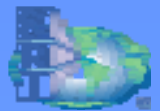
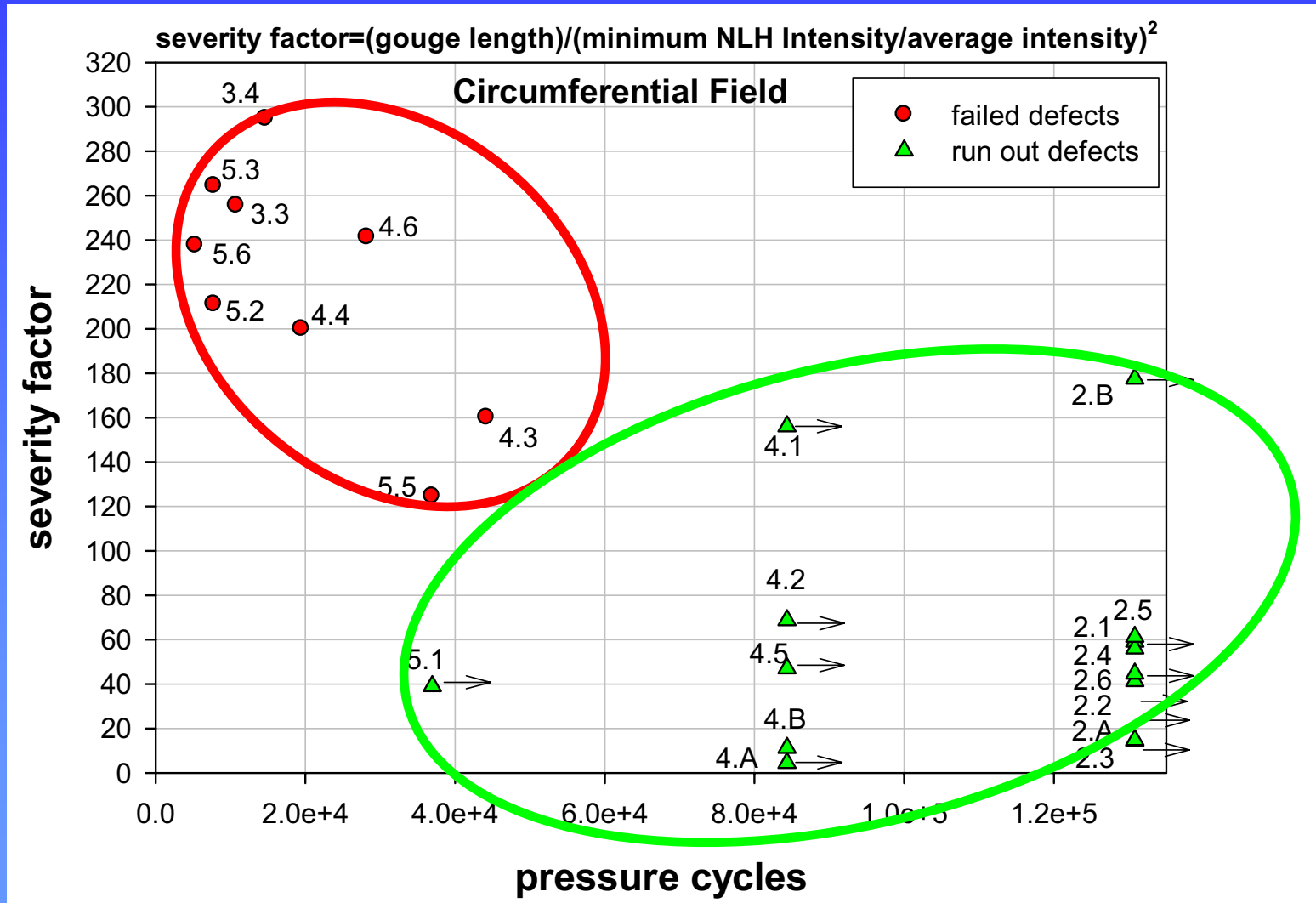


NLH signal measurements

Calipers and other ILI methods may miss re-rounded defects.



NLH DEFECT SEVERITY FACTOR RELATED TO FATIGUE LIFE



PROJECT OUTCOME

- ❖ NLH detects strain due to gouge-like defects even after re-rounding
- ❖ NLH severity index ranks the severity of gouge-like defects against fatigue (delayed) failure
- ❖ NLH severity index specification provided to ILI vendor and demonstrated in analysis software

