Exploiting Effective Field Time Derivative Information to Improve Accuracy of a Norm-preserving Landau-Lifshitz Solver

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Background

• For fixed H, the Landau-Lifshitz equation

(1)
$$\dot{m} = \frac{|\gamma|}{1+\alpha^2}H \times m + \frac{\alpha|\gamma|}{1+\alpha^2}m \times H \times m$$

has analytical solution.

• In spherical coordinates based on H and initial m,

(2)
$$\phi(t) = |\gamma H| t$$

(3)
$$\theta(t) = 2 \tan^{-1}\left(\tan\left(\frac{\theta(0)}{2}\right) \exp\left(-|\alpha \gamma \boldsymbol{H}|t\right)\right)$$

• While H remains fixed, exact trajectory m(t) can be computed for any time step.

Semi-analytical Solution Technique

- Apply analytical solution only over time steps small enough that fixed *H* assumption remains an acceptable approximation.
- Computed trajectories satisfy |m| = 1.
- No renormalization scheme required.
- Naturally avoids errors in energy computations, dissipation rates, etc. that renormalization schemes can introduce.
- Semi-analytical step extends to predictor-corrector scheme.

Ben Van de Wiele, Femke Olyslager, and Luc Dupré, "Fast semianalytical time integration schemes for the Landau-Lifshitz equation", *IEEE Trans. Magn.*, vol. 43, no. 6, pp. 2917–2919, June 2007.

Semi-analytical predictor/corrector

- **Step 1a:** Compute H_0 at m_0 .
- Step 1b: Assuming $H = H_0$ is fixed, compute m_1 using (2) and (3).
- **Step 1c:** Compute H_1 at m_1 .

Step 2: Compute m_{final} using (2) and (3) and $H = (H_0 + H_1)/2$.

The resulting method is 2nd order in Δt .





Limitations

- *H* is a function of *m*; varies over simulation time scales.
- When exchange or demagnetization dominates, *H* is expected to vary at same rate as *m*.
- Semi-analytical technique only valid for small time steps

Predictor/corrector using dH/dt

Idea: Use \dot{H}_0 to produce time-varying estimate H(t).

Step 1a: Compute H_0 and \dot{H}_0 at m_0 .

Step 1b: Compute m_1 along sphere using linear estimate $H(t) = H_0 + t\dot{H}_0$.

Step 1c: Compute H_1 at m_1 .



Predictor/corrector using dH/dt

Step 2a: Fit quadratic estimate $H(t) = H_0 + t\dot{H}_0 + ct^2$ where $c = \left[H_1 - \left(H_0 + t_1\dot{H}_0\right)\right]/t_1^2$.

Step 2b: Compute m_{final} using quadratic H(t) estimate.

The resulting method is 3rd order in Δt .



Computation of
$$dH/dt$$

 $H_i^{\text{demag}} = -\sum_j N_{ij} m_j$ $\dot{H}_i^{\text{demag}} = -\sum_j N_{ij} \dot{m}_j$
 $H_i^{\text{exch}} = \frac{2A}{\mu_0 M_s \Delta^2} \sum_{j \in \mathcal{N}_i} m_j$ $\dot{H}_i^{\text{exch}} = \frac{2A}{\mu_0 M_s \Delta^2} \sum_{j \in \mathcal{N}_i} \dot{m}_j$
 $H_i^{\text{anis}} = \frac{2K_1}{\mu_0 M_s} (m_i \cdot u_i) u_i$ $\dot{H}_i^{\text{anis}} = \frac{2K_1}{\mu_0 M_s} (\dot{m}_i \cdot u_i) u_i$
 $H^{\text{Zeeman}} = ?$ $\dot{H}^{\text{Zeeman}} = \dot{?}$ (often 0)
Notes: \dot{m} is given by (1). Computational cost for dH/dt similar to cost for H .







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Summary: Two spin system

- LLG has been integrated on the sphere using H_0 , \dot{H}_0 , and H_1 .
- Computing \dot{H}_0 costs similar to computing H_0 .
- Proposed predictor/corrector method is 3rd order in Δt .
- On 2-spin test, proposed method yields smaller errors than 4th order Runge-Kutta for reasonable Δt .

Summary: Multi-spin test

- Smaller cells require smaller Δt to reach stable regime.
- In stable regime, integration error depends on Δt but not cellsize.
- Stability critical Δt for 4th order RK is 4 times larger than for 2nd order RK.
- The semi-analytic methods have good stability characteristics.