Reliability, Availability, and Serviceability (RAS) for High-Performance Computing

Presented by

Stephen L. Scott Christian Engelmann

Computer Science Research Group Computer Science and Mathematics Division



Research and development activities

- Reactive fault tolerance for HPC compute nodes utilizing the job-pause approach and checkpoint placement adaptation
- Proactive fault tolerance using migration of computation away from compute nodes that are about to fail
- Reliability analysis for identifying pre-fault indicators, predicting failures, and modeling and monitoring reliability
- Holistic fault tolerance through combination of adaptive proactive and reactive fault tolerance mechanisms











Reactive fault tolerance for HPC with LAM/MPI+BLCR job-pause mechanism



- Operational nodes: Pause
 - BLCR reuses existing processes
 - LAM/MPI reuses existing connections
 - Restore partial process state from checkpoint
- Failed nodes: Migrate
 - Restart process on new node from checkpoint
 - Reconnect with paused processes
- Scalable MPI membership
 management for low overhead
- Efficient, transparent, and automatic failure recovery



Incremental checkpointing with BLCR

- Recent enhancement for Berkeley Lab Checkpoint/ Restart (BLCR)
- Track differences with dirty bit at PTE
- Hybrid: 1 full and k
 incremental checkpoints
- Available through BLCR distribution



Fig. 1: Hybrid Full/Incremental C/R Mechanism vs. Full C/R



Number of incremental checkpoints between two full checkpoints



4 Managed by UT-Battelle for the U.S. Department of Energy

LAM/MPI+BLCR job-pause performance



- 3.4% overhead over job restart, but
 - No LAM reboot overhead
 - Transparent continuation of execution

- No requeue penalty
- Less staging overhead



Proactive fault tolerance with migration

- Relies on a feedback-loop control mechanism
 - Application health is constantly monitored and analyzed
 - Application is reallocated to improve its health and avoid failures
- Real-time control problem
 - Need to act in time to avoid imminent failures
- No 100% coverage
 - Not all failures can be anticipated





VM-level migration using Xen

- System setup
 - Xen VMM on entire system
 - Host OS for management
 - Guest OS for computation
 - Spare nodes without Guest OS
 - System monitoring in Host OS
 - Decentralized scheduler/load balancer using Ganglia
- Deteriorating node health
 - Ganglia threshold trigger
 - Migrate guest OS to spare
- Utilize Xen's migration facility





VM-level migration performance

- Single node migration
 - 0.5-5% longer run time
- Double node migration
 - 2-8% longer run time
- Migration duration
 - Stop & copy: 13-14 s
 - Live : 14-24 s
- Application downtime
 - Stop & copy > live



16-node Linux cluster at NCSU with dual core, dual-processor AMD Opteron and Gigabit Ethernet



Process-level migration with BLCR

- LAM/MPI with Berkeley Lab Checkpoint/Restart (BLCR)
- Per-node health monitoring
- New decentralized scheduler/ load balancer in LAM
- New process migration facility in BLCR (stop & copy and live)
- Deteriorating node health
 - Simple threshold trigger
 - Migrate process to spare

Available through BLCR distribution





Process-level migration performance

- Single node migration overhead
 - Stop & copy : 0.09–6%
 - Live : 0.08–2.98%
- Single node migration duration
 - Stop & copy : 1.0-1.9 s
 - Live : 2.6–6.5 s
- Application downtime
 - Stop & copy > live
- Node eviction time
 - Stop & copy < live</p>



16-node Linux cluster at NCSU with dual core, dual-processor AMD Opteron and Gigabit Ethernet



Proactive fault tolerance framework

- Central MySQL database
- Environmental monitoring
 - OpenIPMI and Ganglia
- Event logging and analysis
 - Syslog forwarding
- Job and resource monitoring
 - Torque
 (epilogue/prologue)
- Migration mechanism
 - Process-level with BLCR





MRNet-based system monitoring

- Aggregation of metrics
- Tree-based overlay network
- Fan-in for metric data
- Fan-out for management
- Classification of data on back-end nodes
- In-flight processing on intermediate nodes
- Collection and storing on front-end node



- 1 MB of data in 4 hours
- ≈250 kB/hour
- ≈2 kb/interval
- ≈56x less than Ganglia



Simulation of fault tolerance policies

- Evaluation of fault tolerance policies
 - Reactive only
 - Proactive only
 - Reactive/proactive combination
- Evaluation of fault tolerance parameters
 - Checkpoint interval
 - Prediction accuracy
- Event-based simulation framework using actual HPC system logs
- Customizable simulated environment
 - Number of active and spare nodes
 - Checkpoint and migration overheads





Combining proactive and reactive FT

- Best: Prediction accuracy >60% and checkpoint interval 16–32 h
- Better than only proactive or only reactive
- Results for higher accuracies and very low intervals are worse than only proactive or only reactive

| Number of processes | 125 |
|---------------------|--------|
| Active/Spare nodes | 125/12 |
| Checkpoint overhead | 50 min |
| Migration overhead | 1 min |

Simulation based on ASCI White system logs (nodes 1–125 and 500–512)

Execution overhead for various checkpoint intervals and different prediction accuracy





Research in reliability modeling

- Type 3 system setup
 - Monitoring of application and system health
 - Recording of application and system health monitoring data
 - Reliability analysis on recorded data
 - Application mean time to interrupt (AMTTI) estimation
- Type 4 system setup
 - Additional recording of application interrupts
 - Reliability analysis on recent and historical data



System Scale (Number of Nodes)



Acknowledgments

Investigators at Oak Ridge National Laboratory

-Stephen L. Scott (Lead PI), Christian Engelmann, Geoffroy Vallée, Thomas Naughton, Anand Tikotekar, George Ostrouchov

- Investigators at Louisiana Tech University
 - *–Chokchai (Box) Leangsuksun (Lead PI),* Nichamon Naksinehaboon, Raja Nassar, Mihaela Paun
- Investigators at North Carolina State University
 - *–Frank Mueller (Lead PI)*, Chao Wang, Arun Nagarajan, Jyothish Varma
- Funding sources
 - -U.S. Department of Energy, Office of Science, FASTOS 2









Contacts regarding HPC RAS research

Stephen L. Scott

Computer Science Research Group Computer Science and Mathematics Division (865) 574-3144 scottsl@ornl.ornl

Christian Engelmann

Computer Science Research Group Computer Science and Mathematics Division (865) 574-3132 engelmannc@ornl.ornl

www.fastos.org/ras

