

Hopper, the New NERSC-6 System

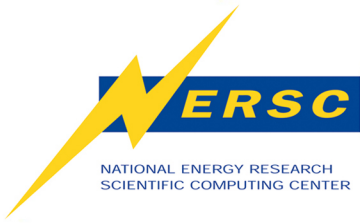
Jonathan Carter

October 7th, 2009



Timeline

- **Initial Project approval Mar 08**
- **Lehman Review Jul 08**
- **RFP released Sep 08**
- **Responses received Oct 08**
- **Evaluation conducted Nov 08**
 - Jonathan Carter replaced Bill Kramer as Project Lead
- **Negotiations conducted Dec 08 - Mar 09**
- **Final Project approval Apr 09**
- **Contract was signed Jul 09**
- **Factory Test of Phase 1 System Sep 09**



Cray Proposal is the Best Value

- **Best application performance per dollar**
- **Highest sustained application performance commitment**
- **Best sustained application performance per MW**
- **Excellent in-house testing facility and benchmarking/performance/support expertise at Cray**
- **Easy to integrate into our facility**
- **Acceptable risk**

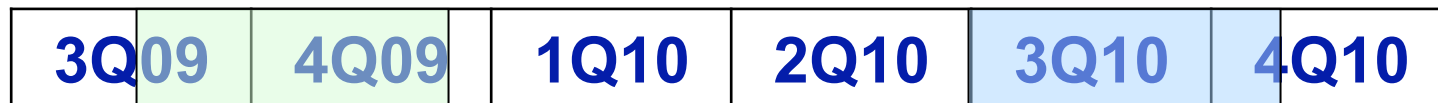
Hopper System

Phase 1 - XT5

- 668 nodes, 5,344 cores
- 2.4 GHz AMD Opteron (Shanghai, 4-core)
- 50 Tflop/s peak
- 5 Tflop/s SSP
- 11 TB DDR2 memory total
- Seastar2+ Interconnect
- 2 PB disk, 25 GB/s
- Air cooled

Phase 2

- >6000 nodes, >150,000 cores
- AMD Opteron (Magny-Cours, 12-core)
- >1.0 Pflop/s peak
- >100 Tflop/s SSP
- >200 TB DDR3 memory total
- Gemini Interconnect
- 2 PB disk, 80 GB/s
- Liquid cooled



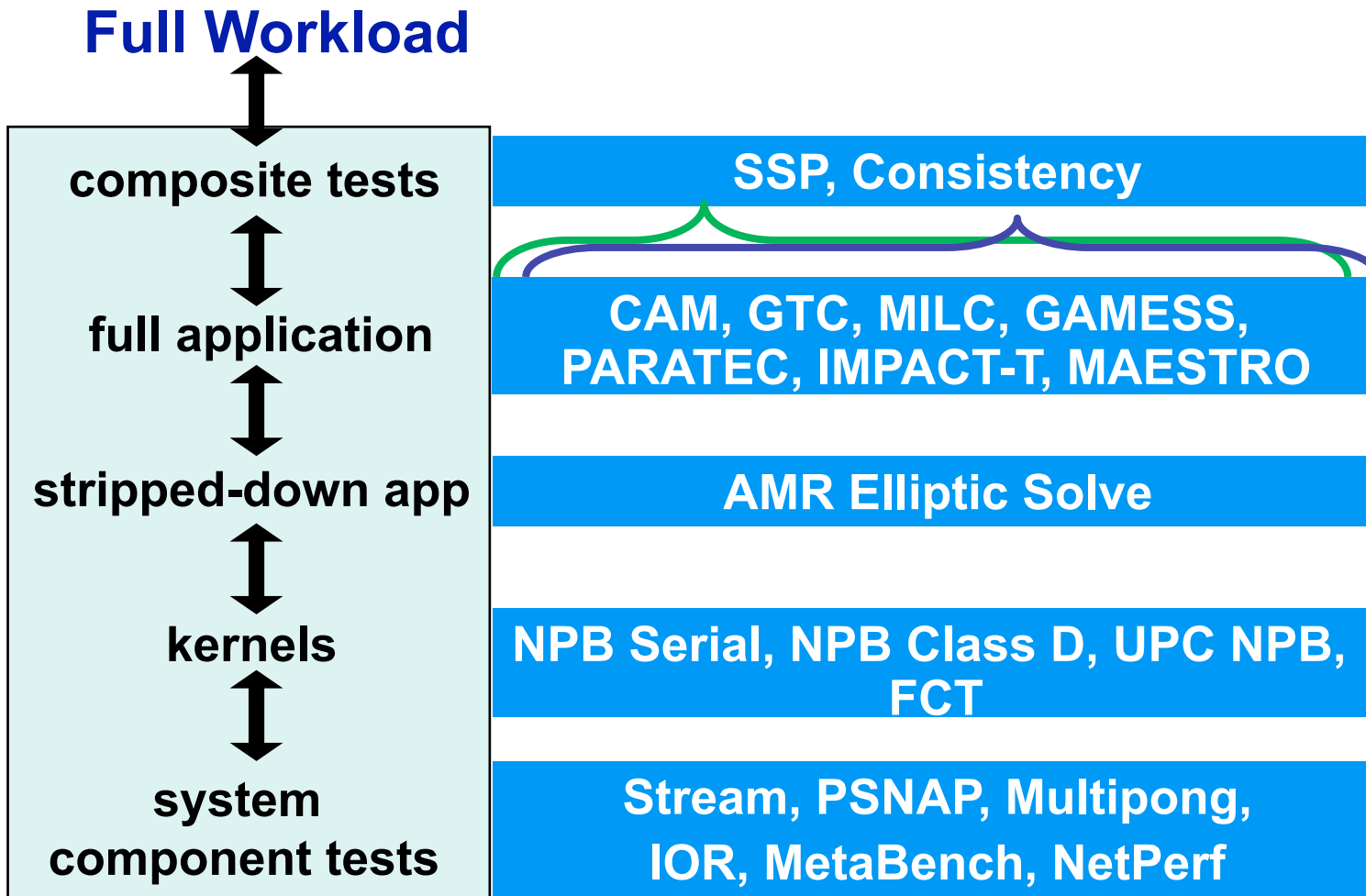


Project Goals

- **Deploy a complete, integrated computing environment for a multi-user, multi-application, parallel scientific workload**
- **Support entire DOE Office of Science Workload**
- **Greatly increase computational resources available to users using measured performance criteria**
- **Integrate into the NERSC environment**

- **13 ‘Minimum Requirements’** (e.g., 24x7 support) that absolutely must be met
 - Proposals that don’t meet are not responsive and are not evaluated further
- **38 ‘Performance Features’** (e.g., fully featured development environment) wish list of features
 - Evaluated qualitatively via in-depth study of Offeror narrative.
- **Benchmarks**
 - Kernel tests and full applications
 - Sustained application performance (measured by SSP benchmarks)
- **Supplier attributes** (ability to produce/test, corporate risk, commitment to HPC, etc.)
- **Cost of ownership** (incl. life-cycle, facilities, base, and ongoing costs) and affordability

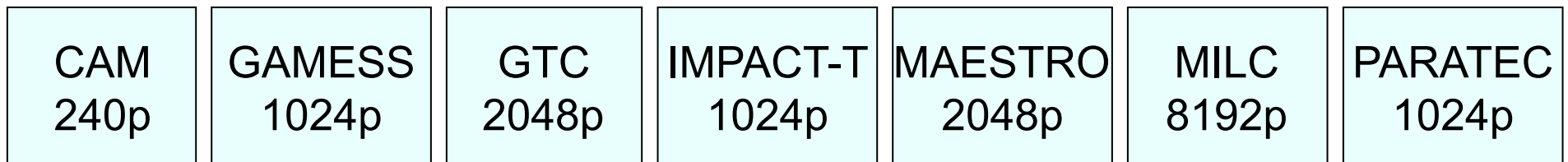
NERSC-6 Benchmarks



NERSC-6 SSP Metric

The largest concurrency time of each full application benchmark is used to calculate the SSP

NERSC-6 SSP



CAM 240p	GAMESS 1024p	GTC 2048p	IMPACT-T 1024p	MAESTRO 2048p	MILC 8192p	PARATEC 1024p
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For each benchmark measure

- FLOP counts on a reference system*
- Wall clock run time on various systems*



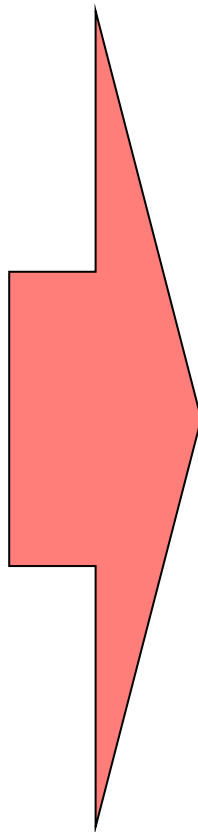
Technology Observations

- **Multi-core continued its progression:**
 - Most proposals had more than 2X number of cores as current largest NERSC system
 - All Offers had two sockets per node – interconnect becoming more sparse and NUMA becoming more important
 - Clock speeds remained the same or showed modest increase
- **Several commodity-based systems (Nehalem / IB + Linux) packaged for HPC**
- **Systems with open-source software stacks were offered**
- **No accelerator- or GPU-based systems proposed**
- **Several different Infiniband topologies were offered**
- **Vendors responded to request to comply with stricter thermal (ASHRAE recommended) standards with innovative solutions**

Feedback from NERSC Users was crucial to NERSC6 negotiations

User Feedback from Franklin

Login nodes need more memory
Shared libraries are not supported
Need more disk space
Increase I/O bandwidth
Connect NERSC Global FileSystem to compute nodes
Workflow models are limited by memory on MOM (host) nodes



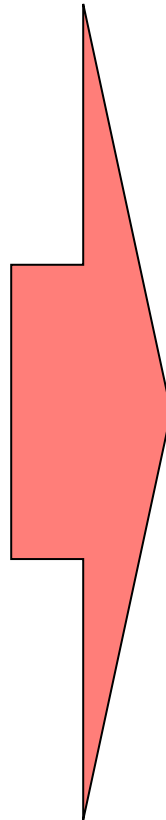
NERSC6 Enhancement

8 external login nodes with 128 GB of memory (with swap space)
Shared libraries are supported.
Includes a 7x increase in disk space over Franklin (2PB)
Includes a 3x increase in I/O bandwidth over Franklin (70 GB/sec)
/project file system will be available to compute nodes
<ul style="list-style-type: none"> •Increased # and amount of memory on MOM nodes •Phase II compute nodes can be repartitioned as MOM nodes

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User Feedback from Franklin

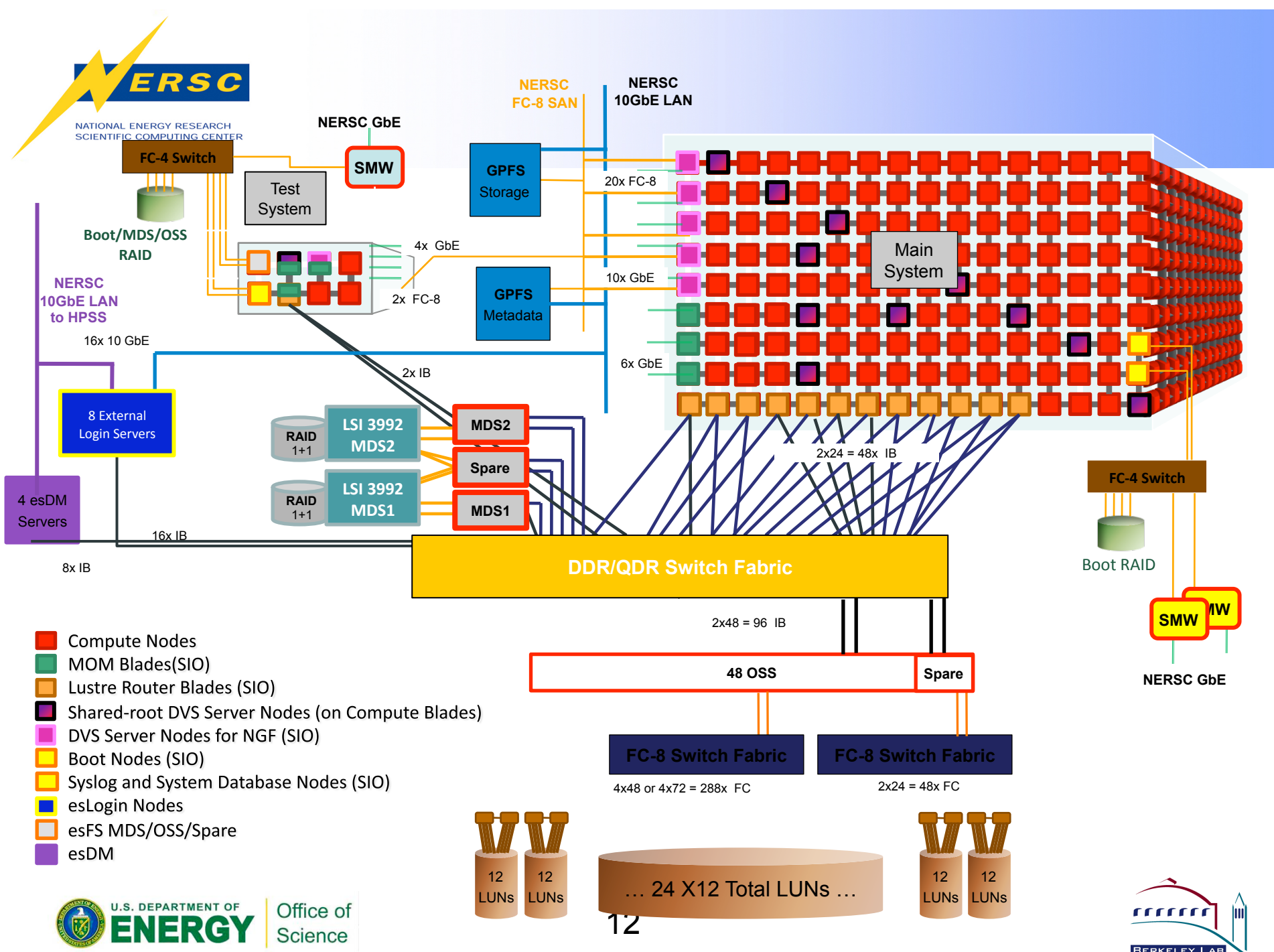
Improve Stability and Reliability



NERSC6 Enhancement

- External login nodes will allow users to login, compile and submit jobs even when computational portion of the machine is down
- External file system will allow users to access files if the compute system is unavailable and will also give administrators more flexibility during system maintenances
- Gemini interconnect has redundancy and adaptive routing. (System will survive a down link.)

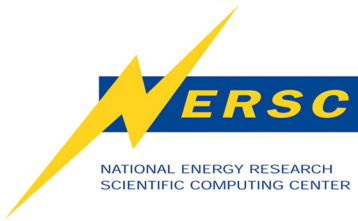
(All will still require some shakeout!)





Software and Compilers

- **Software will be very similar to Franklin but with shared library support**
- **Four different compilers**
 - Portland Group
 - PathScale
 - Cray Compilers
 - GNU
- **Some codes see significant performance improvements with a specific compiler**
- **NERSC will provide guidance and support to help users choose**



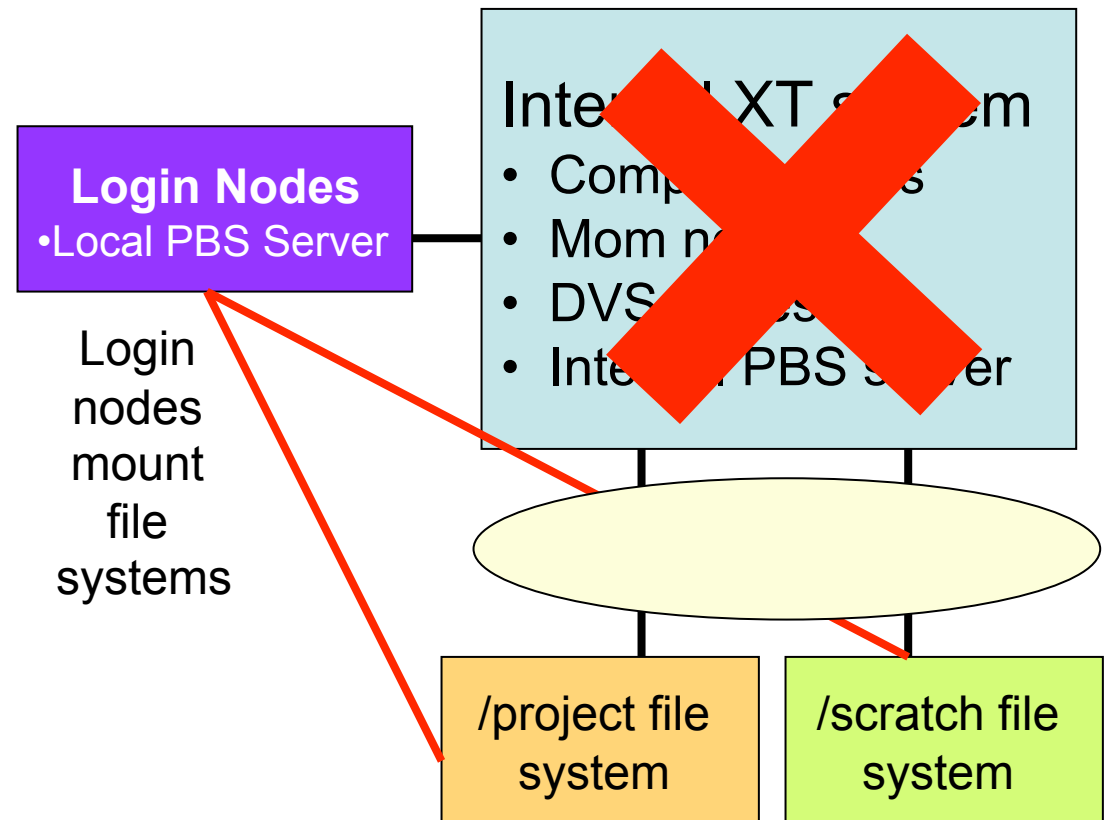
Hopper Login Nodes

- **8 login nodes external to main XT system**
- **Quad socket, quad-core AMD Opteron 2.4GHz**
- **128 GB of memory with swap space**
- **Load balanced for more optimal usage**
- **Ability to run more intensive tools on login nodes, IDL, debuggers, etc.**
- **Available when XT is down**

Access to data and login nodes even when XT is unavailable

- Submit jobs when XT down
- Local PBS server on login nodes
- Holds jobs while XT is down
- Jobs forwarded to internal XT PBS server when XT available again

Sketch of Hopper



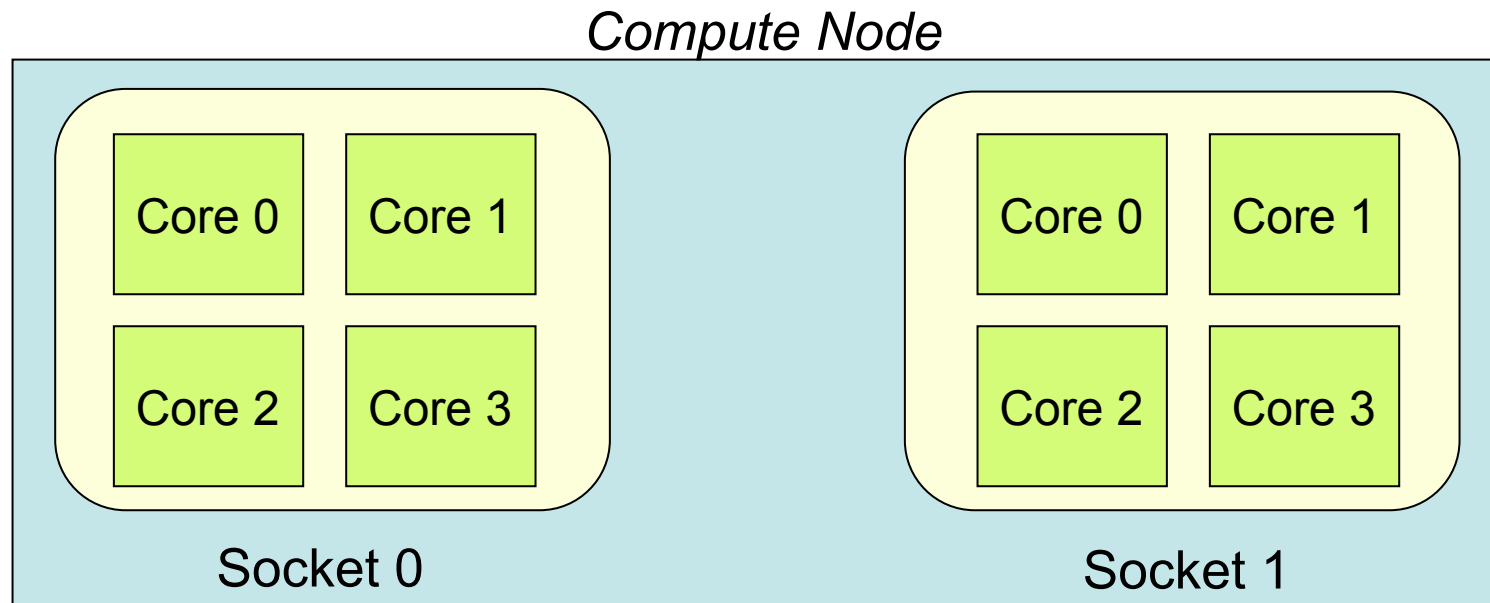


Dynamic and Shared Libraries

- **All user software has a shared library version (mpich, acml, libsci, etc.)**
- **Static binaries is default environment**
- **Use the -dynamic compiler and linker flag**
- **In batch script set environment variable `CRAY_ROOTFS=DSL` which enables shared root file system**

aprun Options

- Hopper has 2 sockets per core, increasing the aprun options, particularly for openMP codes



- New options to specify, how many sockets, which socket, cores per socket, strict memory containment between sockets
- **NERSC will provide guidance on the options**



Hopper Phase I Target Users

- **Application performance will be similar to Franklin**
- **All users welcome to run on Hopper, but target users who need additional functionality**
 - I/O intensive applications
 - Shared and dynamic libraries support
 - Heavy use of login nodes
 - Heavy use of MOM (host) nodes

Proposed Hopper Queues

Submit Queue	Execution Queue	Nodes	Cores	Time Limit	Relative Priority	Charge Factor	User Run Limit
interactive	interactive	1-16	1-128	30 mins	1	1	1
debug	debug	1-64	1-512	30 mins	2	1	1
regular	reg_short	1-16	1-128	4 hrs	3	1	5
	reg_small	1-16	1-128	48 hrs	3	1	3
	reg_med	17-64	129-512	36 hrs	3	1	3
	reg_big	65-256	513-2,048	24 hrs	3	1	3
	reg_long	1-4	1-32	72 hrs	3	1	1
low	low	1-64	1-512	12 hrs	4	0.5	5

Limits

- 5 running jobs/user (system-wide limit)
- 4 queued (eligible for scheduling) jobs/user
- reg_long: 1 running job/user, 1 queued job/user, 4 running jobs max