# Citrus Grove Change Detection Using Heterogeneously Sensed Imagery

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#### OUTLINE

- Background
- Challenge
- Solution
- Histogram Matching for Normalization
- Experimental Results
- Conclusions

## Background

- Citrus grove change detection is critical to production inventory monitoring, map updating, and policy making
- Current manual process is labor intensive and inefficient
- Automation required
- How to automate the citrus grove change detection
  - Open problem
  - Solution needed

### Challenge

- Florida citrus data conditions
  - Different sensors (digital/film)
    - Radiometric differences
    - Dynamic range differences (8-bit and 16-bit)
    - Resolution differences (1m and 2m) =>mixed-pixel
    - Spectral coverage differences (R/G/IR and R/G/B)
  - Unknown data acquiring conditions
    - Sun-angle
    - Atmospheric effects/Weather condition
    - Season/date/time

## Original Images

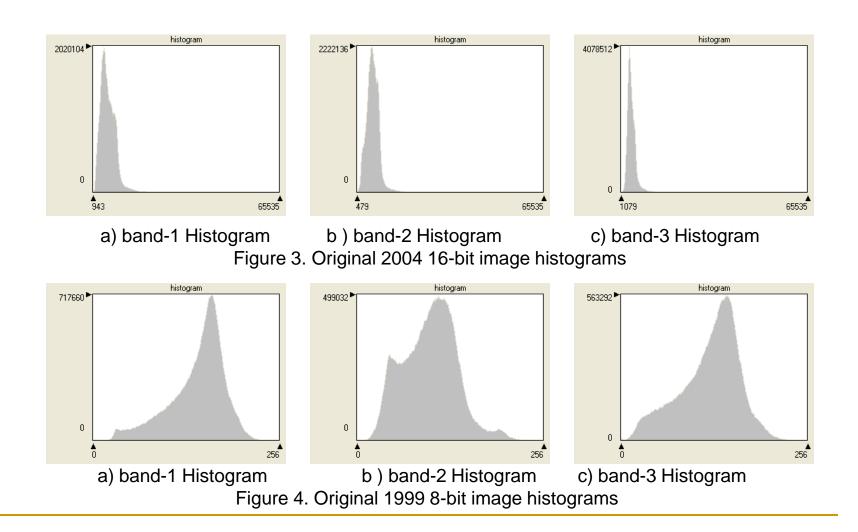


Figure 1. Original 2004 16-bit image



Figure 2. Original 1999 8-bit image

## Histogram of Original Images



#### Solution

- Use image differencing method the most straightforward method
  - Sensitive to radiometric difference
  - Sensitive to dynamic range
- Quantize the 16-bit image to 8-bit to fix the dynamic range
- Use Histogram matching to normalize the radiometric response relatively

#### Histogram Matching for Normalization

- What is histogram matching
  - Transformation from one histogram to a specified histogram
- Why histogram matching normalization
  - Changes occurred only on small portion of the images
    - Image histograms should be roughly same
  - Nonlinear transformation
    - Approximate nonlinear radiometric response relation well
  - Virtually no other methods are effective to heterogeneous sensor normalization

### Experimental Results

- Histogram matching results
- Result comparison between direct image differencing and normalized image differencing
- Change detection result comparison between different reference images
- Zoomed change detection result comparison between different reference images

## Images Before Histogram Matching

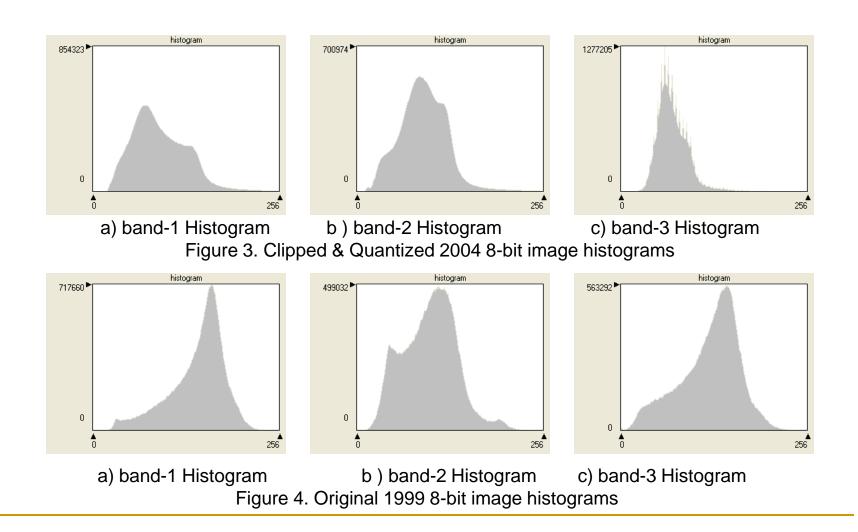


Figure 1. Clipped 2004 8-bit image



Figure 2. Original 1999 8-bit image

### Histograms before Histogram Matching



## Histogram Matched Images

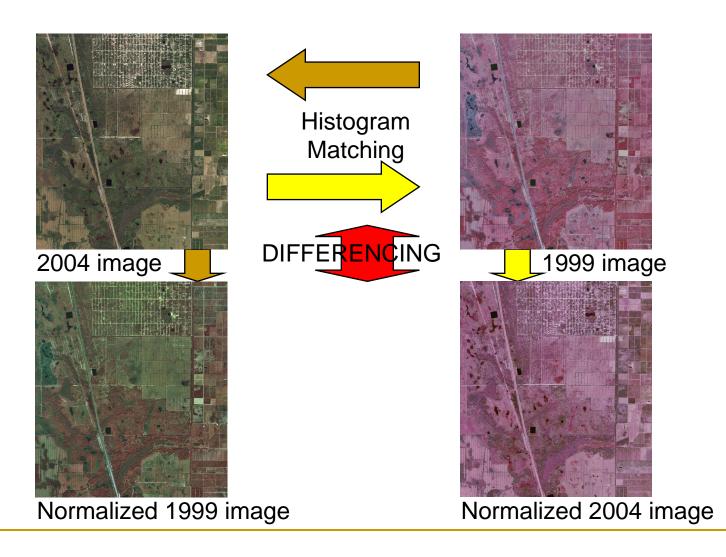


Fig 5. Histogram matched 1999 image Using 2004 image as reference

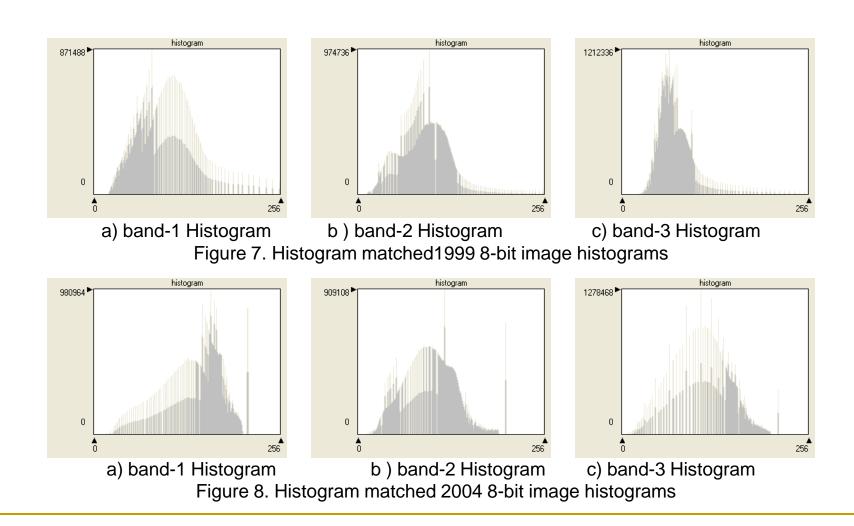


Fig 6. Histogram matched 2004 image Using 1999 image as reference

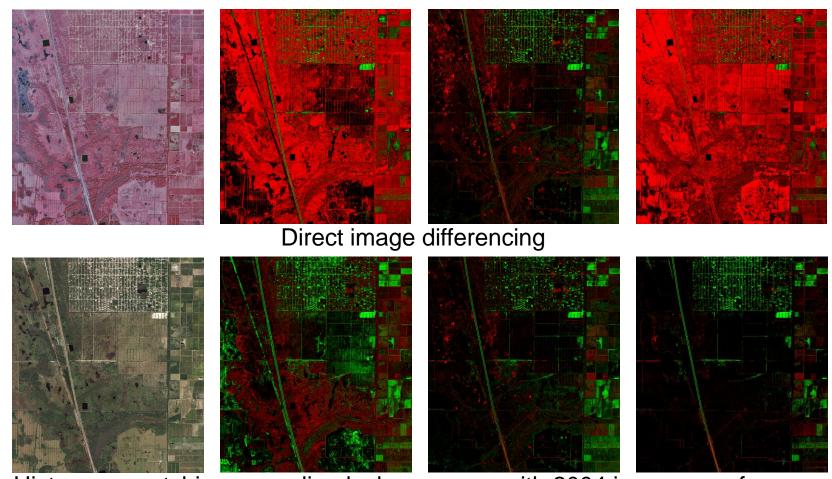
#### Reference and Normalized Image Relationships



#### Histograms of Histogram Matched Images

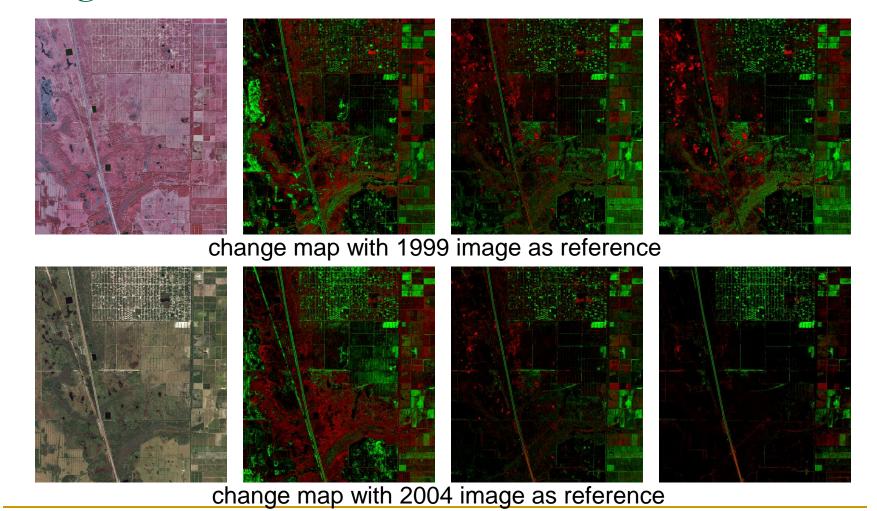


#### Compare with Direct Image Differencing

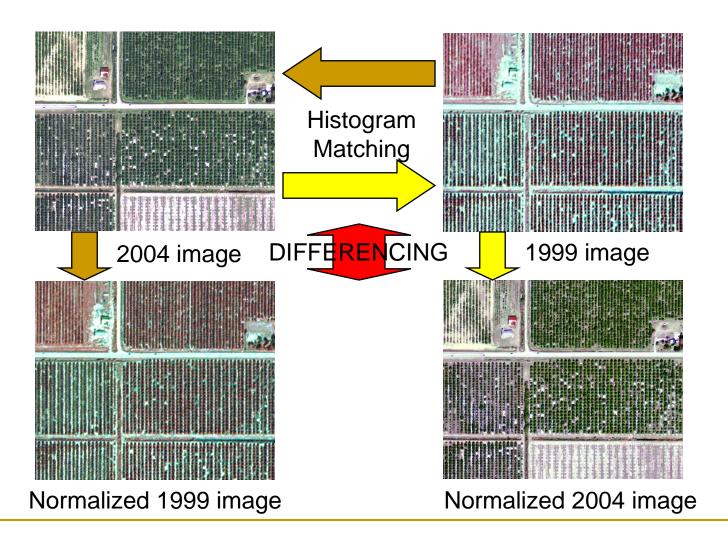


Histogram matching normalized, change map with 2004 image as reference

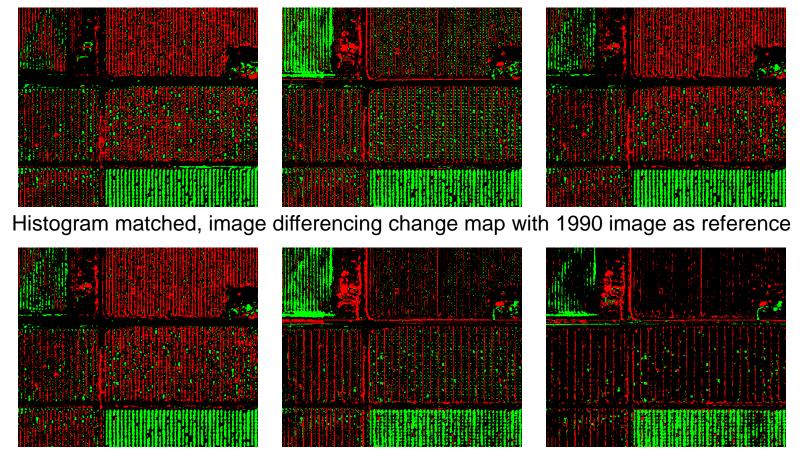
# Overall Change Maps with Different reference image



#### Zoomed Reference and Normalized Image Relationships

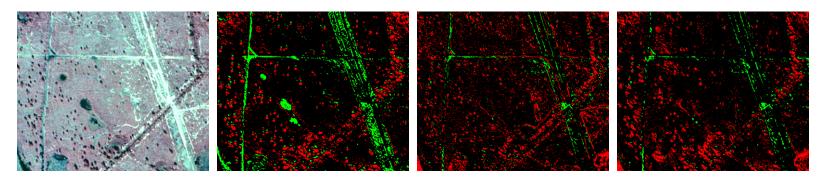


## Zoomed Change Maps of Different Bands/References - Citrus Field (20%)

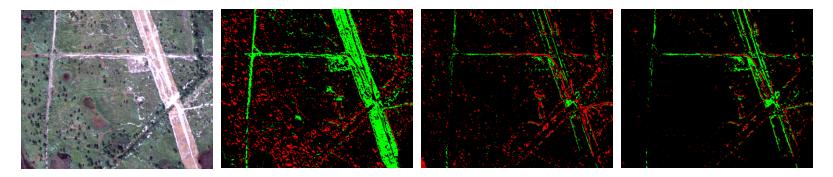


Histogram matched, image differencing change map with 2004 image as reference

## Zoomed Change Maps of Different Bands/References – Non-Citrus field (20%)



Histogram matched, image differencing change map with 1990 image as reference



Histogram matched, image differencing change map with 2004 image as reference

#### Conclusions

- Direct Image differencing change detection method completely fails for some bands of heterogeneously sensed images
- Histogram matching normalization is effective to the images acquired from different sensors
- Histogram matching normalization greatly improves the change detection results to the heterogeneously sensed images
- Normalization result is band-dependent. The worst result comes from the normalization among different spectral bands (histograms differ dramatically)
- Histogram matching results is reference image-dependent.
- The best change detection results come from optimizing the reference image, band and threshold!

## THANK YOU!

QUESTION?