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# *Navy Unmanned Maritime Systems*

*Presented to: ONR MCM Systems for LCS  
Advanced Flight Mission Package Industry Day*

*Presented by: Mr. Mike Alperi*

*Deputy Program Manager*

*PMS403*

*(202) 781-4444*

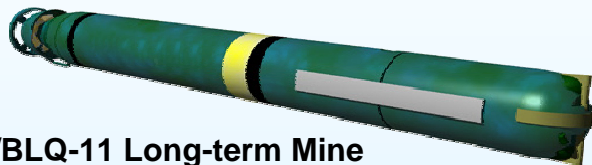
*michael.alperi@navy.mil*



# Unmanned Maritime Vehicle Systems



**Mission: Develop, acquire and maintain operationally superior and affordable surface and submarine launched Unmanned Maritime Vehicle Systems for the Warfighter**



## AN/BLQ-11 Long-term Mine Reconnaissance System (LMRS)

- MRUUVS risk reduction; SSN688/I torpedo tube launch and recovery
- Clandestine Mine Counter-Measures (MCM)
- ACAT II



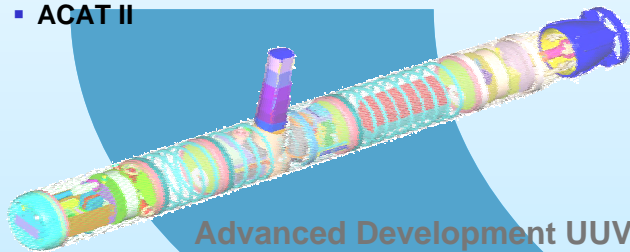
## Battlespace Prep Autonomous Undersea Vehicle (BPAUV)

- MCM search and localization capability
- LCS Flight 0
- Direct leverage of ONR investment



## Large Displacement MRUUVS

- Future development (ACAT Undesignated)
- Significantly improved range and payload capability
- SSGN, VIRGINIA, Littoral Combat Ship compatible
- Modular payloads open systems architecture
- Extended Anti-Submarine Warfare, Mine Countermeasure, Intelligence Surveillance and Reconnaissance (ISR), and Special Operations Forces missions



## Advanced Development UUV

- MRUUVS risk reduction
  - Modular payloads
  - Reconfigurable vehicle design
  - Test-bed for future payloads
- Program Terminated FY06

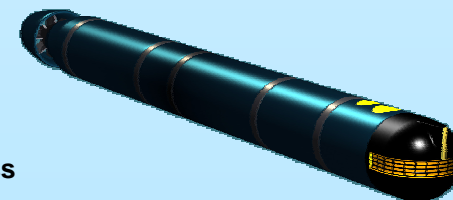


## Surface Mine Countermeasure UUV (SMCM UUV)

- MCM search and localization capability
- UOES – User Operational Evaluation System
- MCM-1, LCS, Craft of Opportunity
- ACAT Program will detect buried mines

## 21" Mission Reconfigurable UUV System

- Modular payloads
- Open systems architecture
- Clandestine SSN launch and recovery
- Pre-MDAP
- Current Program – MCM 688/688I Class
- Future Capability – ISR and 774 Class

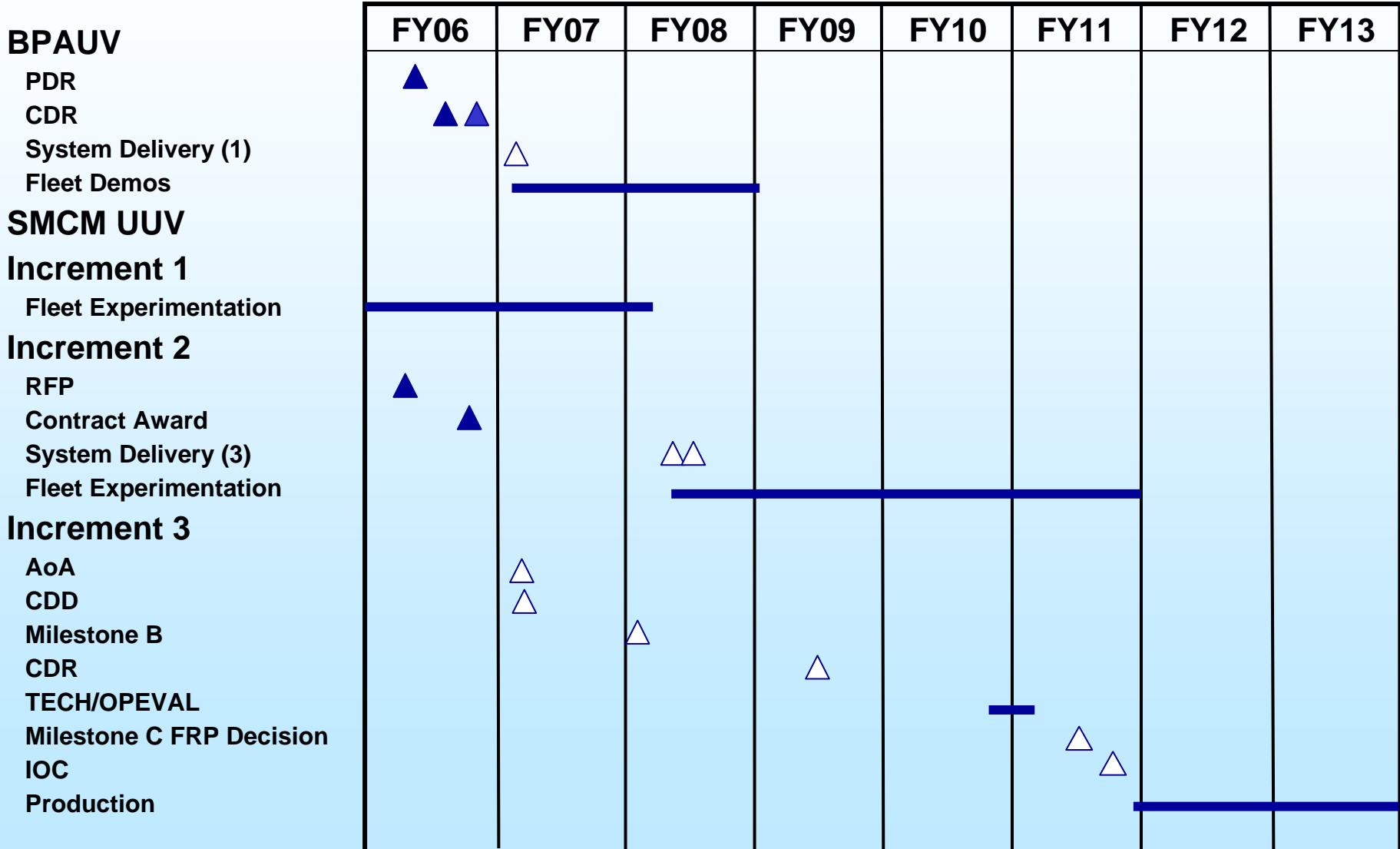


## USV

- MCM Sweep, Delivery, and Neutralization
- ISR / Gun Payloads
- SOF Support



# Surface Launched UUV Program Schedule





# Battlespace Prep Autonomous Undersea Vehicle (BPAUV)



- **Littoral Combat Ship Flight 0 MCM mission module payload (Demo program)**
  - Mitigates ship integration risk for future UUV acquisition programs (especially launch and recovery)
- **Side scan sonar/ environmental sensors support Mine Reconnaissance and Intelligence Preparation of the Environment**
- **Tactical and environmental data is downloaded and analyzed post-mission then transmitted to MEDAL**
- **BPAUV undergoing acceptance testing at NSWC PC**
- **BPAUV system available for training in Apr 2007**
- **LCS Crew Training scheduled in Jul 2007**

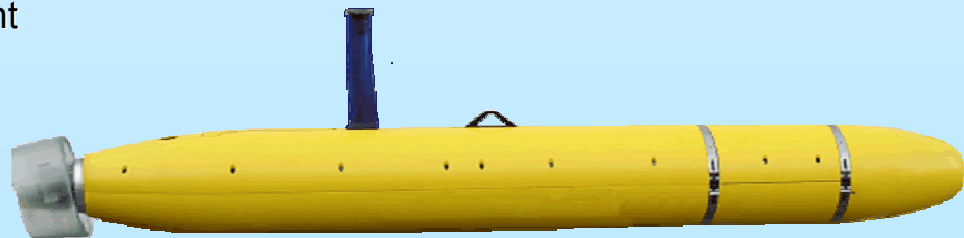
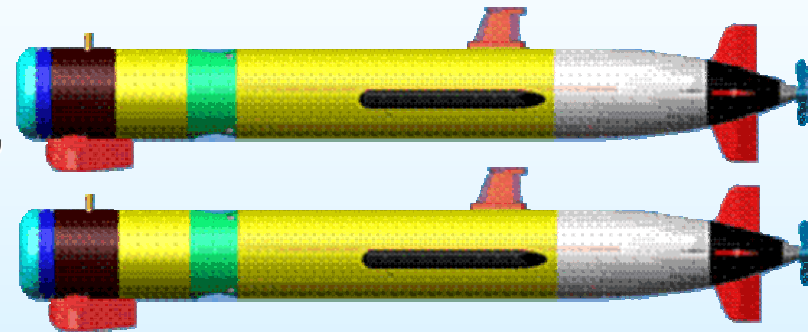




# Surface Mine Countermeasure Unmanned Undersea Vehicle (SMCM UUV) Increment 1

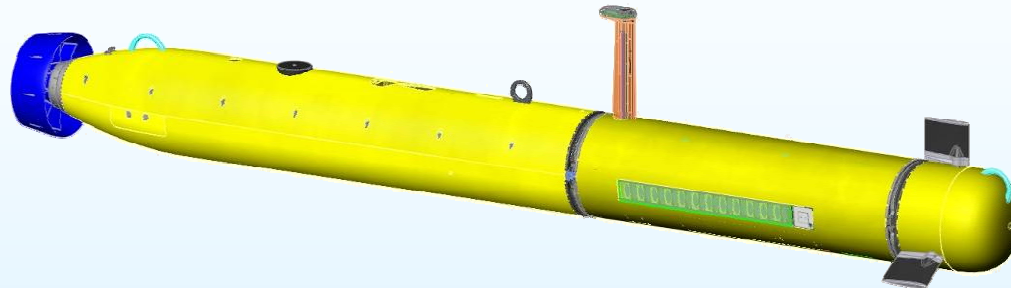


- User Operational Evaluation Systems employed from MCMs and crafts of opportunity
- 2 man portable REMUS Systems
- 1 12" UUV
- Systems successfully employed during NURC, RIMPAC, and GOMEX Exercises
- Recent exercises:
  - NURC – Dec 05
  - Gulf of Mexico Exercise (GOMEX 06-02) – USS PIONEER (MCM 9)
  - RIMPAC 2006 – USNS PATHFINDER and SEAFIGHTER
    - ◆ PATHFINDER
      - 12 UUV missions
      - 25 Contact Reference Numbers (CRN) generated
      - 4 of 5 CRNs re-acquired
      - 11 CRNs correlated to mine plant
      - 72 hours in-water
      - 32 hours Post Mission Analysis
    - ◆ SEAFIGHTER
      - 5 UUV missions
      - 8 CRNs generated
      - 15 hours in-water





# SMCM UUV Increment 2



- 3 User Operational Evaluation systems of 2 vehicles and support equipment employed from MCMs and crafts of opportunity
- Synthetic Aperture Sonar
- Contract awarded to Bluefin Aug 06
- 1st System Delivery to NMAWC 2nd Qtr 08
- Will be employed until Increment 3 IOC in FY11



# SMCM UUV-2 Schedule



	FY06	FY07				FY08			
	4Q	1Q	2Q	3Q	4Q	1Q	2Q	3Q	4Q
Contract Award	▲								
Preliminary Design Review		△							
Critical Design Review				△					
SW Delivery						△			
System Fabrication				△	—————			△	
System FAT							△		
Sea Acceptance Tests							△		
System Delivery								△	△
Training								△	
MCM Integration Test								△	
OOC									△

# SMCM UUV Program Increment 3

## SMCM UUV Increment 3



**Buried Mine Detection UUV**

### Status:

- Analysis of Alternatives to be completed by Jan 07
- WB&B contracted to finalize draft AoA/CDD
- N852 LFBB platform study/warfighting analysis in process
- N852 requested that the CDD not be submitted until the study results are briefed
- ONR Low Frequency Broadband vehicle rerun against buried mines (after settling) at NSWC PC in Aug 06
- Blind testing vs naturally buried mines planned for Corpus op area Dec 06

### Program Schedule

2004				2005				2006				2007				2008				2009				2010				2011				2012				2013																							
1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4	1	2	3	4																				
												CDD Submit				MS B																MS C IOC																											
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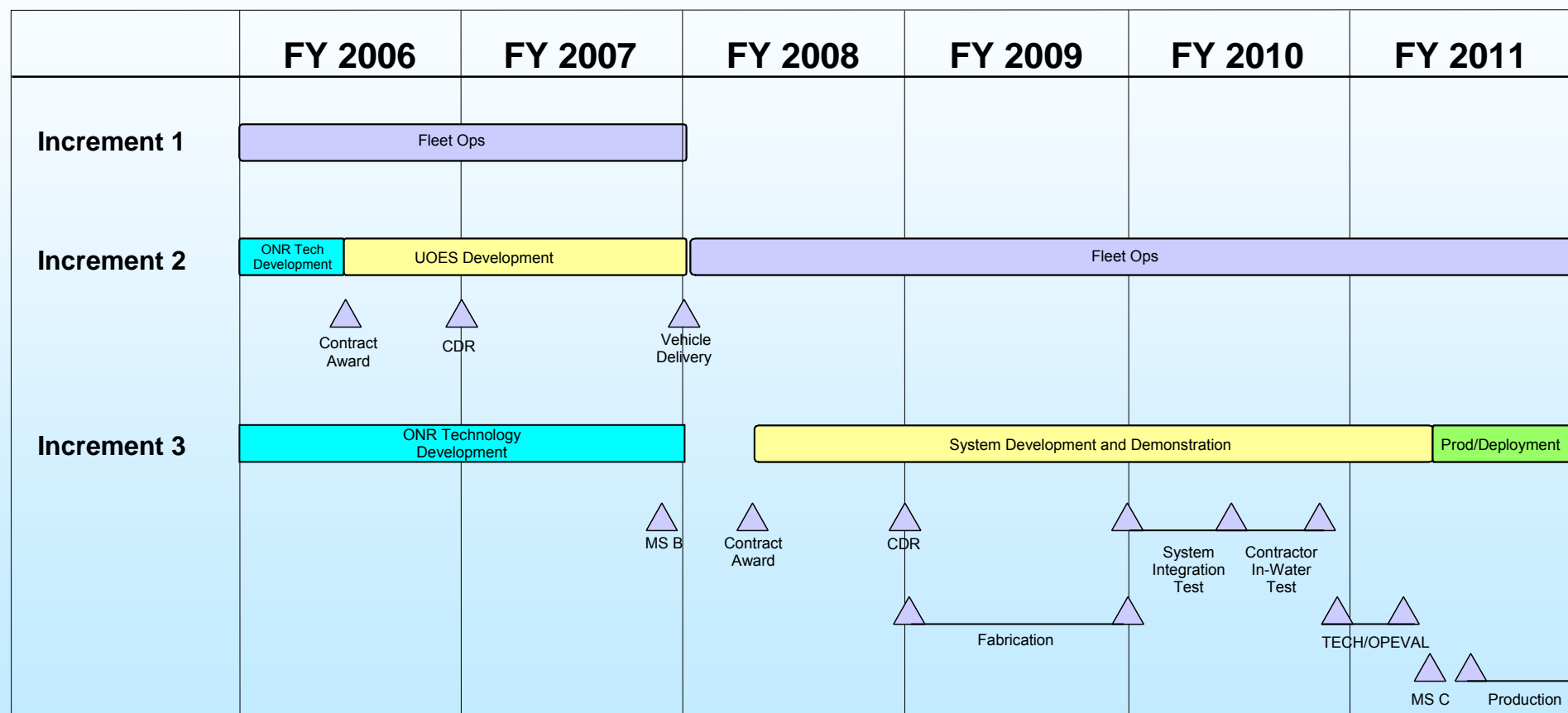
# Surface Mine Countermeasure (SMCM) UUV Payload Development – Comparison of Performance



	Increment 1: UOES	Increment 2: UOES	Increment 3: Draft Capability
<b>Payload</b>	Sidescan Sonar	Dual Frequency SAS	Low Frequency Broadband Sonar
<b>Endurance</b>	8 hrs/12 hrs	10-12 hrs	12-16 hrs
<b>Speed</b>	3 knots	3-5 knots	2.5-3 knots
<b>Swath Description</b>	60 m (3" x 3" resolution) 10 m (1" x 1" resolution) Nadir Gap 5/10 m	80 m (3" x 3" or 1" x 1" resolution)  Nadir Gap 10 m	500-600 m – LFBB Mine Detection  No Gap
<b>Sea Bottom Penetration</b>	None	Limited (Lower Frequency Band)	Up to 75 cm
<b>Comms</b>	Iridium/Radio/Acoustic Communications	Iridium/Wireless/Acomms	TBD
<b>Operational Capability</b>	Improved Classification of MLCO vs. SQQ-32 Clandestine Small Area Search	Improved Classification of MLCO vs. SQQ-32 and Incr 1: UOES Clandestine Small Area Search	Buried Mine Detection  Clandestine Wide Area Search
<b>Equipment</b>	7.5 " Remus 100 – 2 UUVs 12.75" Bluefin – 1 UUV	System of two 12.75" UUVs Contractor TBD	System of at least two 21" UUVs Contractor TBD
<b>Delivery</b>	Sept 2005 – 3 UUVs	Sept 2007 – 3 Systems	1 refurbished Engineering Development Model System 6 Production Systems

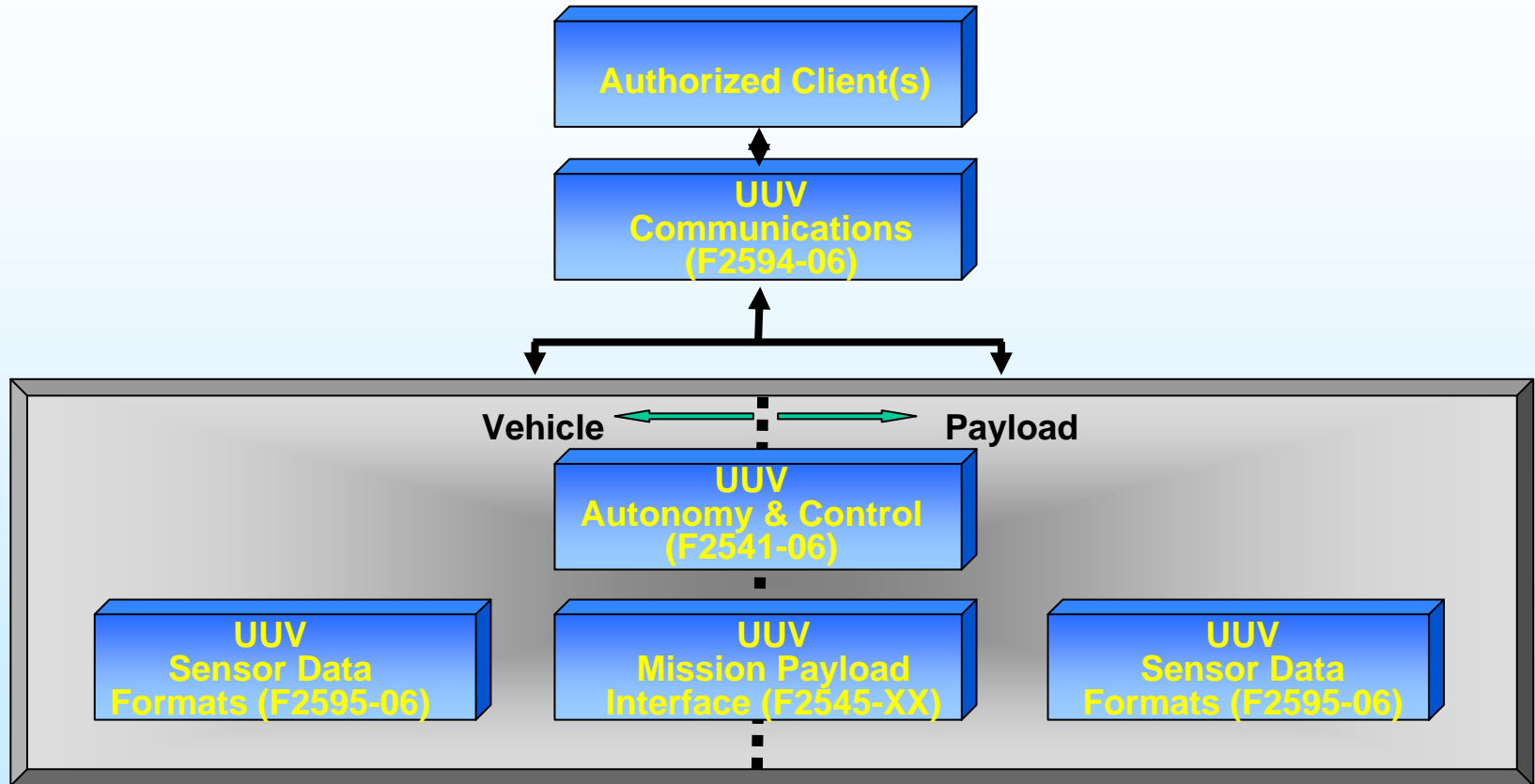


# Surface MCM UUV Acquisition Schedule





# ASTM UUV Standards



Refinement and improvement of standards will continue

Approved Standards available in public domain via ASTM website

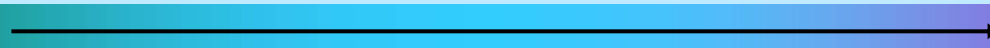


# Unmanned Maritime Vehicle Technology Focus Areas



- **Reliable launch and recovery**
- **Reliable communications**
- **Open system architecture**
- **Vehicle**
- **Platform integration**
- **Information assurance**
- **FORCEnet & C<sup>4</sup>I Compliance**
- **Energy**
- **Reliable/robust autonomy**
- **Advanced sensors**
- **Signature**
- **Real time sensor processing**
- **Payload deployment**
- **Net mitigation**
- **MCM neutralization**
- **ASW sensors**
- **EM signature for mine ID**
- **RCS/IR/optical signature for far forward ISR**
- **Non-lethal ASW weapons**

Near-Term



Far-Term