

1 Understanding Shock Dynamics in the Inner
2 Heliosphere with Modeling and Type II Radio Data:
3 the 2010-04-03 event

H. Xie,¹ D. Odstrcil,² L. Mays,³ O. C. St. Cyr,⁴ N. Gopalswamy,⁴ and H.
Cremades⁵

¹Department of Physics, The Catholic
University of America, Washington DC,
USA.

²Department of Computational and Data
Sciences, George Mason University, Fairfax,
Virginia, USA.

³NASA Postdoctoral Fellow, Goddard
Space Flight Center, Greenbelt, Maryland,
USA

⁴Code 670, NASA/Goddard Space Flight
Center, Greenbelt, Maryland, USA.

⁵UTN-FRM/CONICET, Mendoza,
Argentina.

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4 **Abstract.** The 2010 April 03 solar event was studied using observations
5 from STEREO SECCHI, SOHO LASCO, and Wind kilometric Type II data
6 (kmTII) combined with WSA-Cone-ENLIL model simulations performed at
7 the Community Coordinated Modeling Center (CCMC). In particular, we
8 identified the origin of the coronal mass ejection (CME) using STEREO EUVI
9 and SOHO EIT images. A flux-rope model was fit to the SECCHI A and B,
10 and LASCO images to determine the CME's direction, size, and actual speed.
11 J-maps from STEREO COR2/HI-1/HI-2 and simulations from CCMC were
12 used to study the formation and evolution of the shock in the inner helio-
13 sphere. In addition, we also studied the time-distance profile of the shock prop-
14 agation from kmTII radio burst observations. The J-maps together with in-
15 situ data from the Wind spacecraft provided an opportunity to validate the
16 simulation results and the kmTII prediction. Here we report on a compar-
17 ison of two methods of predicting interplanetary shock arrival time: the ENLIL
18 model and the kmTII method; and investigate whether or not using the ENLIL
19 model density improves the kmTII prediction. We found that the ENLIL model
20 predicted the kinematics of shock evolution well. The shock arrival times (SAT)
21 and linear-fit shock velocities in the ENLIL model agreed well with those mea-
22 surements in the J-maps along both the CME leading edge and the Sun-Earth
23 line. The ENLIL model also reproduced most of the large scale structures
24 of the shock propagation and gave the SAT prediction at Earth with an er-
25 ror of $\sim 1 \pm 7$ hours. The kmTII method predicted the SAT at Earth with
26 an error of ~ 15 hours when using $n_0 = 4.16 \text{ cm}^{-3}$, the ENLIL model plasma

²⁷ density near Earth; but it improved to ~ 2 hours when using $n_0 = 6.64 \text{ cm}^{-3}$,
²⁸ the model density near the CME leading edge at 1 AU.

1. Introduction

29 For decades groundbased telescopes have detected the slowly-drifting (downward in
 30 frequency) solar radio emissions at metric wavelengths called “Type II” radio bursts.
 31 When a shock travels outward from the solar corona, it accelerates electrons that in turn
 32 produce radio emission at the local plasma frequency (f_p [kHz] = $9 \sqrt{n_e}$ [cm⁻³]) and its first
 33 harmonic ($2f_p$). As the shock encounters less-dense regions the local plasma frequency
 34 decreases giving rise to the slow-drift. These radio emissions can start at frequencies
 35 below 150 MHz in the low corona and extend down to the kilometric domain, slowly
 36 drifting to lower frequencies all the way to 1 AU, where the local plasma frequency of
 37 the solar wind is ~ 25 kHz [Gopalswamy *et al.*, 2005a]. Since Earth’s ionosphere blocks
 38 radio signals at frequencies below ~ 10 MHz, the only way to detect the longer-wavelength
 39 emissions is by means of instruments in interplanetary space. These emissions have been
 40 regularly detected by the Wind Radio and Plasma Wave (WAVES) experiment [Bougeret
 41 *et al.*, 1995] and more recently by the Solar Terrestrial Relations Observatory (STEREO)
 42 WAVES [Bougeret *et al.*, 2008], whose space weather beacon makes them available in
 43 near-real-time.

44 Recently Cremades *et al.* [2007] described a novel technique to predict interplanetary
 45 (IP) shock arrival at L1 by measuring the drift rate of the kilometric (≤ 300 kHz) Type II
 46 (kmTII) emissions. Shocks between 1997-2004 were identified from catalogues maintained
 47 by Wind and Advanced Composition Explorer (ACE) investigators, and altogether 160
 48 kmTII radio bursts were identified in the Wind WAVES dataset. A subset of 84 kmTII
 49 events could be reliably measured and used to make a prediction as to when the shock

50 should be seen at L1. 66% of the predictions were within ± 6 hours of the actual shock
51 arrival time, and space weather forecasters have shown keen interest in incorporating this
52 technique into their forecasts.

53 STEREO is comprised of two identical spacecraft orbiting the Sun ahead STEREO-A
54 (STA) and behind STEREO-B (STB) Earth near the ecliptic plane [*Kaiser et al.*, 2008].
55 The two spacecraft separate away from Earth at a rate of about 22° per year. The ex-
56 tended solar minimum of 2007 - 2009 did not provide many earthward halo CMEs for
57 the two STEREO spacecraft to study, but on April 3, 2010 a fast CME was observed
58 to propagate towards Earth. The April 3 CME produced an interplanetary (IP) shock
59 followed by an IP coronal mass ejection (ICME), which caused an extended geomagnetic
60 storm with minimum Dst = -72 nT on April 5-7, 2010. During the storm, communication
61 with the Galaxy 15 satellite was lost (W. Ferster, Intelsat Loses Contact with Galaxy 15
62 Satellite, Space News, 8 April 2010). Both STA [STB] observed the CME expanding off
63 the West [East] limb around 09:00 UT; the Large Angle and Spectrometric Coronagraph
64 Experiment (LASCO; *Brueckner et al.* [1995]) on board the Solar and Heliospheric Ob-
65 servatory (SOHO) observed the CME appearing as a halo event around 10:33 UT. The
66 separation angles of STA [STB] with Earth were 67° [71°]. When we include SOHO, the
67 three spacecraft (STA/B and SOHO) provided almost $\sim 140^\circ$ view of the event. The Sun
68 Earth Connection Coronal and Heliospheric Investigation (SECCHI) instrument package
69 includes: the inner and outer coronagraph (COR1 and COR2), and the Heliospheric Im-
70 agers (HI1 and HI2)[*Eyles et al.*, 2009]. STEREO successfully tracked the April 3, 2010
71 event from the Sun into the heliosphere all the way to 1 AU. HI1 and HI2 image movies
72 on STA showed clearly the evolution of the CME-driven shock in the heliosphere (see

73 online supplementary materials in the HTML). Furthermore, a kmTII radio burst was
74 detected by Wind WAVES [*Bougeret et al.*, 1995] on April 4 from 00:58 until 16:33 UT.
75 The associated shock arrived at the Wind spacecraft on April 5 07:48 UT. The wealth
76 of data for this event provides us with a good opportunity to study the formation and
77 the evolution of the CME-driven shock and to validate different methods of modeling and
78 predicting IP shock dynamics and arrival time.

79 The April 3, 2010 event has been studied by several authors. *Möstl et al.* [2010] carried
80 out an analysis of the in situ data of the associated IP shock and ICME that drove the
81 shock. They showed that the ICME was a magnetic-cloud-like structure but it could not
82 be fitted by any magnetic cloud models. By linking STEREO/SECCHI images to in situ
83 observations, they demonstrated that the apex of the ICME was southward directed and
84 only its northern flank passed over Earth. *Wood et al.* [2011] performed a thorough white-
85 light analysis of the CME using an empirical flux-rope reconstruction and demonstrated
86 that the CME could be fitted reasonably well with a 3D flux rope shape, where its orien-
87 tation angle out of the ecliptic plane has been rotated from -80° (i.e., nearly N- S) close
88 to the Sun to 10° (i.e., nearly E-W) far from the Sun. Using combined STEREO SECCHI
89 imaging and the modeling of the CME driven shock, *Rouillard et al.* [2011] investigated
90 the corresponding solar energetic particle (SEP) events measured at L1 and STB, and
91 associated the origin and magnitude of the SEP event with the shock properties along
92 different interplanetary magnetic field (IMF) lines.

93 In this paper, we perform a comprehensive study on the evolution and propagation of
94 the April 3, 2010 CME/shock, combining STEREO and SOHO white light observations,
95 kmTII radio data with the WSA-Cone-ENLIL model simulation. We use a flux rope model

96 [e.g. *Krall and St.Cyr*, 2006; *Xie et al.*, 2009] fit to SECCHI and LASCO observations to
97 determine the CME speed, size and direction, as well as its time-distance profile when the
98 CME is close to the Sun. To fully investigate the IP shock dynamics we use a heliospheric
99 WSA-Cone-ENLIL simulation model. The fitted CME radial speed and half angular
100 width are used to specify a hydrodynamic spherical cloud launched into the heliospheric
101 computational domain. We derive the time-distance profile of the CME-driven shock in
102 the heliosphere from J-maps (plots of elongation from the Sun versus time along fixed
103 position angles [e.g., *Sheeley et al.*, 1999, 2008]) constructed from SECCHI images. The
104 simulation results are directly compared with the SECCHI observations. We focus on two
105 aspects in the paper: 1) using SECCHI and radio data to constrain the ENLIL model
106 output; 2) determining whether or not a combination of techniques yields an improved
107 prediction.

108 The paper is organized as follows: Section 2 presents the observations, including the
109 CME solar source, flux rope model fit to coronagraphic images, and kinematic analysis
110 with J-maps. Section 3 describes the WSA-Cone-ENLIL model simulation, and Section
111 4 gives the simulation results and comparison between the simulation results and obser-
112 vations. Section 5 introduces the kmTII technique and applies the ENLIL model results
113 to the method to improve the prediction. Finally, the discussion and conclusions are
114 presented in Section 6.

2. Observations

2.1. CME Solar Source

115 The April 3, 2010 CME was an Earth-directed CME, which was associated with a X-ray
116 flare with a peak flux level of B7.4 recorded by GOES X-ray monitor from NOAA Active

117 Region (AR) 11059 (S25W03) between 09:04 UT and 10:58 UT, with a peak at 09:54 UT.
118 The flare was first seen in the Extreme Ultraviolet Imaging Telescope (EIT) on board
119 SOHO between 09:14 UT and 10:00 UT with a faint EIT wave associated with the flare
120 (http://cdaw.gsfc.nasa.gov/movie/make_javamovie.php?date=20100403&img1=soh_e195).
121 The evolution of the flare showed a clear sigmoid to post-arcade structure, and the neu-
122 tral line in the sigmoid active region was tilted $\sim 80^\circ$ relative to the horizontal (east-west)
123 direction (Figure 1b). On April 3, the separation angles of STA and STB with Earth are
124 67° and 71° , respectively. The flare was observed at S25E64 from STA and S25W74 from
125 STB. An eruptive prominence (EP) was observed to the south of AR 11059 by SECCHI's
126 Extreme Ultraviolet Imager (EUVI) at 304 \AA on STA at 09:46 UT, as shown in Figure
127 1a. The prominence began to be active around 08:56 UT and erupted around 09:16 UT.
128 EUVI 304 \AA movie and EIT 195 \AA movies show that both the prominence eruption and
129 the X-ray flare eruption are related to the CME and the EP appeared as the CME core in
130 COR1 around 10:15 UT. The flare location and post-eruption arcade are shown in Figure
131 1c as observed by EUVI 195 \AA on STB at 11:00 UT.

2.2. CME Speed, Width and Propagation Direction: Flux Rope Model Fit

132 The CME was seen edge-on by COR1-A off the southeast limb starting at 09:05 UT,
133 and by COR1-B off the southwest limb (<http://cor1.gsfc.nasa.gov/catalog/>). LASCO
134 observed a halo CME on April 3 and its first appearance time in LASCO C2 was 10:33 UT.
135 (http://cdaw.gsfc.nasa.gov/CME_list/). In Figure 2, we show the CME running difference
136 images from STA/B COR1 and SOHO C2, respectively, along with the COR1(STA/B)
137 and COR2-B original images at bottom panel. In COR2-B original image, a streamer
138 ahead of the CME leading edge was clearly seen.

139 To determine the radial speed, angular width, and propagation direction of the CME,
 140 we applied a flux-rope model fit to SECCHI COR1 and COR2 and LASCO C2 and C3
 141 images. The flux rope model used here is *Krall and St.Cyr* [2006]’s flux rope model
 142 (hereafter KS06). The KS06 model is also called the elliptical flux rope model, which
 143 assumes that the flux rope has an elliptical axis with varying radial circular cross-section.
 144 The coordinate system used in the KS06 model has its origin at the CME eruption region
 145 on Sun’s surface, the z -axis directed towards North, the x -axis directed towards West,
 146 and the y -axis directed along the Earth-Sun line, away from Earth. *For simplicity*, the
 147 separation distance between two flux-rope footpoints has been neglected in the model.
 148 The geometry of the flux rope can be described by two parameters: the ratio of the semi-
 149 minor to semi-major axis of the ellipse $\lambda_e = R_2/R_1$ and the axial aspect ratio $\Lambda_\alpha = 2R_1/d$,
 150 where R_1 , R_2 , and d are semi-major axis, semi-minor axis and width of the flux rope at
 151 its apex [c.f. Figure 1 in *Xie et al.*, 2009]. The orientation of the flux rope is defined by
 152 three angles: latitude λ , longitude ϕ , and tilt angle α , where the tilt angle is the rotation
 153 around its central axis. We used an iterative method to parameterize the flux rope model.
 154 First, we chose initial test parameters of the flux rope model based on the coronagraphic
 155 observations; we then iteratively adjusted the test parameters until the best fit of the flux
 156 rope model to both SECCHI and LASCO images were obtained by visual examination.

157 Figure 3 shows the flux rope (FR) model fit for the CME; from left to right are COR1-A
 158 , C2 , and COR1-B images superimposed with the flux rope model projected wireframe
 159 (yellow curves) at $t = 09:50$ UT, $10:55$ UT and $09:50$ UT, respectively. The model best-fit
 160 radial distances to SECCHI COR1/2 and LASCO C2/3 image frames at different times
 161 yield the height-time profile of the CME (Figure 4), $R_{tip}(t)$, where R_{tip} is the radial

162 distance from the origin to the apex of the FR. The widths of the CME are given by:
 163 $\omega_{edge} = 2 \times tg^{-1}(0.5/\Lambda_\alpha)$, $\omega_{broad} = 2 \times tg^{-1}(\lambda_\epsilon)$, where ω_{edge} and ω_{broad} are the widths of
 164 the CME from edge-on and face-on views respectively. For the April 3 CME, the fitting
 165 results gave that $R_1 = 0.8 R_s$, $R_2 = 0.6 R_s$, and $d = 2.0 R_s$ at $R_{tip} = 2.6 R_s$, where R_s
 166 is the solar radius, which yielded $\omega_{broad} = 74^\circ$, and $\omega_{edge} = 64^\circ$; the best-fit propagation
 167 direction of the CME are $(\lambda, \phi, \alpha) = (-23^\circ, 3^\circ, -70^\circ)$. Comparison of our fit direction
 168 with previous studies shows that there is a very good agreement in longitude and decent
 169 agreement in latitude and tilt angle. The CME direction determined in *Möstl et al.* [2010]
 170 was S27° and W0°, and in *Wood et al.* [2011] was S16°, W2° with tilt angle of -80°.
 171 Difference between *Wood et al.* (*Möstl et al.*)’s results and ours are 4° (7°), 3° (1°), 10°,
 172 respectively, in λ , ϕ , and α .

173 Figure 4 shows the FR model fit height-time profile (solid line) and derived velocity
 174 (dashed line) over-plotted with the GOES X-ray flux (blue dotted line). The velocities
 175 are computed from adjacent data points of R_{tip} and the uncertainties in the computed
 176 velocity are estimated assuming the measurement uncertainty in distance $\pm 0.2 R_s$ at 15
 177 R_s , i.e., the estimated fractional error in the distance is 1.3%. From the figure, we can see
 178 that the April 3 CME is accelerated from 268 km/s to 873 km/s rapidly within the COR1
 179 FOV and its velocity reached a small peak around 10:05 UT, which is roughly the peak
 180 time of the X-ray flux, then accelerated gradually to 1011 km/s at $\sim 12:08$ UT. Note,
 181 however, that the resulting CME acceleration within the COR2 FOV should be taken
 182 cautiously since the maximum velocity uncertainty is ~ 150 km/s in the COR2 FOV,
 183 which is almost half as large as the velocity variation. Comparison of our CME velocity
 184 (1011 km/s) with those in *Möstl et al.* [2010] (990 km/s) and in *Wood et al.* [2011] (960

185 km/s) gives errors of 21 km/s and 51 km/s, respectively. These errors fall within the
 186 maximum velocity uncertainty range.

2.3. Kinematic Analysis with J-maps

187 With the help of J-maps constructed from COR2, HI1 and HI2 images, we can derive
 188 the CME trajectory in the heliosphere from near the Sun all the way to 1 AU [*Wood*
 189 *et al.*, 2010]. Three methods have been generally used to infer radial distances, r , from
 190 the measured elongation angles, ϵ , from white light images: 1) Point-P [*Howard et al.*,
 191 2006]; 2) Fixed- ϕ [*Kahler and Webb*, 2007; *Wood et al.*, 2010]; and 3) Harmonic Mean
 192 [*Lugaz et al.*, 2009]. The Point-P method assumes a broad spherical front centered at the
 193 Sun, and r and ϵ are related by: $r = d \sin \epsilon$, where d is the distance from the spacecraft to
 194 the Sun. The Fixed- ϕ method assumes a very narrow CME traveling with fixed direction
 195 with: $r = d \sin \epsilon / \sin(\epsilon + \phi)$, where ϕ is the angle between the CME trajectory and the line
 196 of sight (LOS) from the observer to the Sun. The Harmonic Mean method approximates
 197 the CME as a sphere centered halfway between the Sun and the CME's leading edge, and
 198 yields a CME radial distance given by: $r = 2d \sin \epsilon / (1 + \sin(\epsilon + \phi))$, which is the harmonic
 199 average of the Point-P and the Fixed- ϕ approximations.

200 We show in Figure 5, from left to right, running difference images of HI1-A ,HI2-A, and
 201 a time-elongation J-map along the Sun-Earth line with PA = 95°, where PA is the position
 202 angle measured counterclockwise from the north. Figure 5a shows three features of the
 203 propagating CME: the southward ejecta (flux rope); the shock front with faint and sharp
 204 brightness enhancements, extending much wider in latitude than ejecta; and the core at
 205 rear of the flux rope. Note that there was a deformation at the shock front along the
 206 CME central leading edge (LE; hereafter LE denotes the leading edge of the CME at its

207 central axis) due to the interaction between the CME and the streamer ahead of it. The
 208 Wilcox Solar Observatory (WSO) source surface synoptic charts ($R = 2.5$ radial model)
 209 (<http://wso.stanford.edu/synsourcel.html>) indicated that the location of the *current* sheet
 210 (streamer belt neutral line) was $\sim S23^\circ$ on Apr 2 - 3, 2010, *just ahead of the CME LE*.
 211 *The streamer was marked by arrows in the COR1 and COR2 images (Figure 2)*. The
 212 CME/shock front was interacting with and indented by the streamer; an arc-like front
 213 formed, as marked by thick arrows in Figure 5a and 5b. The heliocentric distances of the
 214 shock along the Sun-Earth line and the LE on April 3, 20:09 UT are $\sim 56 R_s$ and $\sim 49 R_s$,
 215 respectively. In Figure 5b, when the CME propagated farther out into the HI2-A FOV,
 216 the shock sheath and the flux rope ejecta along the LE had been compressed together
 217 and we can only see one complex compressed front. The ejecta along the Sun-Earth line
 218 is too faint to see due to the further expansion.

219 Figure 6 (top panel) shows a time-distance $r(t)$ plot of the shock along the Sun-Earth
 220 line with $PA = 95^\circ$, where distances are derived from elongation angles in the J-map using
 221 the three methods discussed above. We used the CME direction $\phi = 75^\circ$ with respect to
 222 STA (i.e., $E8^\circ$ with respect to Earth) for the Fixed- ϕ and Harmonic Mean approximations.
 223 The direction was chosen so that $r(t)$ matched best with both the FR model fit results
 224 and the observed SAT at Wind. The bottom panel of Figure 6 is the inferred velocity
 225 of the shock. Here we omitted some distance points (6 points in this case) instead of
 226 using adjacent data points to compute velocities to avoid large errors caused by distance
 227 measurement errors. The velocity uncertainties are estimated assuming 1%, 2% and 3%
 228 fractional errors in the distance measurements for COR2, HI1 and HI2, respectively, the
 229 same as in *Wood et al.* [2010].

230 We found that the three approximations yield similar profiles within the COR2 and
 231 HI1 FOV, but not in the HI2 FOV. The Point-P approximation produced a dramatic
 232 deceleration, while the Fixed- ϕ approximation produced a large acceleration. These are
 233 apparent accelerations and caused by *the apparent leading edges seen by HI. Due to a*
 234 *projection effect and the CME angular width as it expands, the actual LE of the CME*
 235 *is not seen by HI but the far-side or near-side flank of the CME*, resulting in artificial
 236 distance increases and decreases (c.f. Figure 4 in *Wood et al. [2010]*). Among three
 237 approximations, the Harmonic Mean method yields a more plausible kinematic profile.
 238 Compared to the Wind SAT and in situ plasma bulk velocity in the sheath, marked by
 239 red "X" symbols in Figure 6, the Harmonic Mean method gives the smallest errors of \sim
 240 2 hours and ~ 50 km/s respectively. Note that there is an overlap of distances from the
 241 J-map and the flux rope model fit in COR2, denoted by orange plus symbols in the figure.
 242 These two distances are shown to be consistent with each other.

3. Simulation with Numerical Heliospheric Model

243 To fully investigate the three-dimensional (3D) evolution and formation of the CME-
 244 driven shock in the inner heliosphere, we used the WSA-Cone-ENLIL model. The WSA-
 245 Cone-ENLIL model [e.g., *Odstrčil et al., 1996; Odstrcil and Pizzo, 1999; Odstrcil et al.,*
 246 *2005*] is well-known in the solar-helio community, and ENLIL version 2.3a is currently
 247 available to users at the Community Coordinated Modeling Center (CCMC). ENLIL is a
 248 time-dependent 3D MHD model of the heliosphere, and it solves for plasma mass, momen-
 249 tum and energy density, as well as magnetic field, using a Total-Variation-Diminishing
 250 Lax-Friedrich (TVDLF) algorithm [*Toth and Odstrcil, 1996*]. Its inner radial boundary
 251 is located beyond the sonic point, typically at $21.5 R_s$ (or 0.1 AU) for WSA ($30 R_s$ for

252 MAS), and the outer boundary is set at 2.0 AU. In the simulation spherical coordinates
253 are used, and the three independent spatial variables are the radial position r , the merid-
254 ional (latitude) angle θ , and the azimuthal (longitude) angle ϕ . The meridional and
255 azimuthal extents span 30° - 150° and 0° - 360° , respectively. The computational region has
256 $512 \times 60 \times 180$ grid points, and the uniform spacing of computational grid points are $\Delta r =$
257 $0.794 R_s$, $\Delta\theta = 2^\circ$, and $\Delta\phi = 2^\circ$.

258 The CME is input into the ENLIL simulation domain as a hydrodynamic spherical
259 cloud. This ejecta has a uniform velocity and diameter corresponding to the fitted radial
260 CME speed and width. Parameters describing the CME's geometry and kinematics,
261 such as size, speed and direction, can be obtained by fitting the cone model (or other
262 forward-modeling techniques, e.g. flux rope model) to coronagraph observations [e.g., *Xie*
263 *et al.*, 2004, 2009; *Krall and St.Cyr*, 2006; *Thernisien et al.*, 2006]. Further, the model
264 assumes that the ejecta density has the density four times larger than the mean value in
265 the fast stream and the same temperature as in the fast stream. It is assumed that the
266 momentum flow and thermal pressure are constant at the inner boundary (0.1 AU) and
267 that the density and temperature in the fast stream is 250 cm^{-3} and 0.8 MK, respectively.
268 The input values were chosen by matching the simulated properties of the shock upstream
269 reasonable well with in situ *measurements* at 1AU.

270 The numerical simulation is done in two stages: 1) setup the background solar wind
271 based on the Wang-Sheeley-Argge (WSA) [e.g., *Arge and Pizzo*, 2000; *Arge et al.*, 2004] or
272 MAS [e.g., *Linker et al.*, 1999; *Riley et al.*, 2001] models; 2) insert a CME propagating in
273 that background at the time when the observed CME passes the inner boundary (which
274 is usually at $21.5 R_s$ for WSA). In the simulation, we used the flux rope model fit results

275 of actual speed (1011 km/s), face-on half angular width (37°), and direction (described in
276 Section 2.2) as input parameters of the CME. The background solar wind was set up using
277 the WSA model with photospheric magnetograms from the National Solar Observatory's
278 (NSO) Global Oscillation Network Group (GONG) system, and the CME was launched
279 into the computational heliospheric domain at the inner boundary $21.5 R_s$ at $t = 13:29$
280 UT.

4. Simulation Results

4.1. Comparison of the simulation results with in-situ observations

281 Figure 7 shows the simulated density in the ecliptic plane (left panel) and meridian plane
282 (middle panel) as two-dimensional (2D) density contours on April 4 at 18:00 UT (movies
283 are available online: http://ccmc.gsfc.nasa.gov/database_SH/h_xie_100311_SH_1.php and
284 *in the online supplementary materials*). In the figure W (West) is up and E (East) is
285 down in the ecliptic plane (left panel); and N (North) is up and S (South) is down in
286 the meridian plane (middle panel). The Sun-Earth line is roughly horizontal with the
287 Earth to the right. The heliographic location of the Earth is S6.3W00, i.e., in the center
288 of the ecliptic plane and slightly southward in the meridian plane, as marked by yellow
289 filled circles. The 2D density contours show that the CME has encountered two slow,
290 dense streamers: one is located at the west flank of the CME and another is located at
291 the center of the CME along the LE. The interaction between the CME and the dense
292 streamers and the ambient solar wind has led to the formation of an arc-like structure at
293 the CME LE (middle panel) and caused the IMF (black-white dashed line) to be deflected
294 (left panel). The right panel of Figure 7 shows the simulated (blue solid lines) and the
295 observed Wind solar wind plasma and magnetic field data (red dotted lines) at 1 AU

296 between April 2 and 9. The IP shock arrived at Wind on April 5 at 07:58 UT, followed by
297 an ICME from April 5 at 12:00 UT to April 6 at 17:00 UT. Figure 8 is the in situ Wind
298 observation data plus the Dst index. From Figure 8, we can see that the long-duration
299 geomagnetic storm was first *caused* by a negative B_y with a peak of ~ -16 nT on Apr 5,
300 18:00 UT, and then enhanced farther by long-duration negative B_z and B_y of ~ -7 nT.
301 The observed ICME has a smooth magnetic rotation and enhanced magnetic strength $|B|$,
302 low proton temperature T and plasma β , and a declining velocity V profile (due to the
303 ICME expansion in the solar wind). However, it cannot be fitted to any magnetic cloud
304 models [c.f., *Möstl et al.*, 2010] because the ICME was southward directed (S25W03) and
305 only its northern flank passed over Earth.

306 The ENLIL model predicted the shock arrival at Earth at 08:57 UT on April 5, with
307 an error of ~ 1.0 hour compared to the Wind SAT of 07:58 UT. Thus the ENLIL model
308 provided a good prediction of the SAT for this event. Note that, however, the model
309 requires the CME density and temperature as input at 0.1 AU which are not direct
310 measurements, *thus adding a degree of uncertainty*. We have performed runs *by assuming*
311 *that the CME has the density* either four times or twice larger than the fast stream value,
312 and it yields a variation in SAT (shock arrival time) of ~ 7 hrs. Furthermore, since the
313 ENLIL ejecta is a pure hydrodynamic structure, the absence of the CME internal magnetic
314 structure has caused the model to overestimate plasma density N and temperature T , and
315 to underestimate total B field of the ICME.

4.2. Comparison of the simulation results with J-maps

316 In order to study the evolution of the IP shock driven by the CME, we need to find
317 the locations of the shock front where the sudden increase of density (or velocity) occurs.

318 Figure 9 (left panels) shows an example of how to locate the simulated shock, where we
 319 plot density times the square of radial distance nr^2 as function of distance r : a) along the
 320 LE propagation direction; b) along the Sun-Earth line on April 5 at 06:01 UT. In Figures
 321 9a and b, locations of the shock front, upstream and downstream are marked by three
 322 vertical lines r_{sk} , r_{up} , and r_{dw} . We define a shock front r_{sk} by locating the largest slope of
 323 nr^2 , i.e. largest $d(nr^2)/dr$. The shock downstream is defined as $r_{dw} = r_{sk} - 2$ spacing grids
 324 *because* the average thickness of the shock is ~ 4 spacing grids due to the limitation of
 325 the 3D code resolution. We choose the shock upstream r_{up} to be $r_{sk} + 5$ spacing grids to
 326 ensure that the selected upstream has fallen into the smooth ambient solar wind region,
 327 where nr_{up}^2 remains nearly constant.

328 Right panels of Figure 9 plot the upstream density nr_{up}^2 , the downstream density nr_{dw}^2 ,
 329 and the shock compression ratio nr_{dw}^2/nr_{up}^2 as function of time : c) along the LE propaga-
 330 tion direction and d) along the Sun-Earth line. Comparing Figures 9c and d, we can see
 331 that the shock compression ratios along two propagation directions have similar trends.
 332 Both curves experience an initial increase and then gradually decrease. The compression
 333 ratio along the LE (Sun-Earth) propagation direction reaches a maximum value of 5.81
 334 (6.10) on April 4, 06:03 UT. The background solar wind density, nr_{up}^2 , remains nearly con-
 335 stant along the Sun-Earth line and slightly increases along the LE propagation direction
 336 , due to the slow dense streamer ahead of the CME. The mean values of the solar wind
 337 density along the LE and Sun-Earth are 6.64 cm^{-3} and 4.16 cm^{-3} , respectively. We apply
 338 these values to the kmTII method in Section 5. Note that the maximum compression
 339 ratios along the both LE and Sun-Earth propagation directions are greater than the the-
 340 oretical threshold of 4 [Priest, 1982]. This is due to a limitation of the 3D code resolution

341 producing the shock front thickness to be too large (the spacing of grids) [*Steinolfson*
342 *et al.*, 1975].

343 Figure 10a compares the simulated time-distance profiles of the shock along the LE and
344 Sun-Earth line with the time-distance profiles from J-maps along the LE and Sun-Earth
345 line. All the distances in the figure are measured for the shock front. We found that the
346 shock propagation along the LE propagation direction lagged behind the one along the
347 Sun-Earth line in both the ENLIL model and J-map, due to the interaction between the
348 CME and the streamer at the LE. HI2-A movies (see online supplementary materials in
349 the HTML) clearly show that the shock front has been flattened and compressed and the
350 Earthward shock front (a faint brightness enhancement) arrived earlier at 1 AU than the
351 shock front along the LE.

352 The shock arrival times along the LE and Sun-Earth line are 12:10 UT and 08:57 UT
353 in the ENLIL model; and 17:27 UT and 05:42 UT in the J-map (all these times refer to
354 April 5). The linear-fit shock velocities along the LE and Sun-Earth line are 778 km/s
355 and 849 km/s in the ENLIL model; and 712 km/s and 925 km/s in the J-map. The
356 differences in SAT between the ENLIL model and J-map are ~ 5 hours along the LE, and
357 ~ -3 hours along the Sun-Earth line. The differences in linear shock speed between the
358 ENLIL model and J-map are 66 km/s along the LE, and ~ -76 km/s along the Sun-Earth
359 line. Thus the simulation results agree with the observations within the error range of the
360 measurements. The simulation reproduced the overall dynamics of the shock propagation
361 with realistic large scale structures.

362 Note that the difference between the two propagation directions for the shock, in the
363 ENLIL model, is much smaller than that in the J-map. The differences in SAT and shock

364 speed in the ENLIL model are ~ 3 hours and 71 km/s between the two directions; and
 365 11.5 hours and 213 km/s in the J-map. We will discuss this in Section 6.

366 Figure 10b shows the time-velocity profiles of the CME inferred from the distances in
 367 Figure 10a. All four velocity profiles show small decelerations. The linear-fit decelerations
 368 along the Sun-Earth line are similar, with values of -0.49 and -0.50 m/s² in the ENLIL
 369 model and J-map, respectively. But the linear-fit deceleration in the ENLIL model is
 370 smaller (-0.82 m/s²) than that (-1.43 m/s²) in the J-map along the LE. The deceleration
 371 from the J-map along the LE is consistent with the IP acceleration $a = 2.193 - 0.0054u$
 372 from *Gopalswamy et al.* [2005b]’s empirical shock arrival (ESA) model, where u is the
 373 CME speed. For $u = 712$ km/s; $a = -1.65$ m/s². The ESA model gives an SAT of 15:30
 374 UT for an earthward speed of 925 km/s, which gives an error of ~ 7.5 hours.

5. The “kmTII” Technique

375 For the April 3, 2010 CME, no decameter-hectometric (DH) type II radio burst was
 376 detected. But a kilometric type II (kmTII) radio burst starting from April 4 00:58 to 16:33
 377 UT was detected by Wind/WAVES. Such events are generally rare and have a relatively
 378 slower average speed compared to other CMEs with radio-loud shocks as discussed in
 379 *Gopalswamy et al.* [2010]. Figure 11 shows the dynamic spectrum of the kmTII radio
 380 burst recorded by the TNR receiver on April 4, 2010. Note the scale of the vertical axis
 381 is in units of 1/f. The solid line represents the linear fit of the drifting 1/f as a function of
 382 time. Using a simple density model in which $n = n_0/r^2$ (n_0 is the plasma density at 1 AU
 383 in units of cm⁻³) [e.g., *Leblanc et al.*, 1998], the time-distance profile of the CME-driven
 384 shock can then be obtained from the frequency drift given by $r(t) = a\sqrt{n_0}/f(t)$, where
 385 $r(t)$ is the heliocentric distance where the kmTII occurs in units of AU, $f(t)$ is the drifting

386 frequency in units of kHz, and $a = 9$ or 18 is a constant for fundamental or harmonic
 387 emission respectively. The derived shock speed is $V_{sh} = a\sqrt{n_0} \times \frac{d}{dt}(1/f) \times 1.5 \times 10^8$ (km/
 388 s) [Reiner et al., 1998]. Figure 12 plots the time-distance profile of the shock propagation
 389 inferred from the kmTII method, superimposed with trajectories extracted from the J-
 390 maps. Open circles represent data points extracted from the J-maps along the LE (blue)
 391 and the Sun-Earth line (red), and green diamonds represent the results derived from the
 392 kmTII method using the ENLIL model density a) at Earth $n_0 = 4.16 \text{ cm}^{-3}$ and b) at the
 393 LE $n_0 = 6.64 \text{ cm}^{-3}$ in Figure 9. In Figure 12a, assuming that the kmTII occurs near the
 394 Sun-Earth line, the kmTII estimated linear shock speed is 656 km/s and the estimated
 395 SAT is 22:57 UT, yielding errors of ~ 15 hours and 269 km/s , compared to the Wind
 396 SAT of 07:58 UT and the J-map Earthward shock speed of 925 km/s . In Figure 12b,
 397 the kmTII is assumed to occur near the shock at the LE. The kmTII prediction gives a
 398 linear-fit shock speed of 829 km/s and the predicted SAT is 09:44 UT, yielding errors of \sim
 399 2 hours and 96 km/s , compared to the Wind SAT and the J-map Earthward shock speed.
 400 Thus applying the plasma density value near the LE has improved the kmTII prediction
 401 error from 15 hours to 2 hours, and the kmTII prediction accuracy largely relies on the
 402 value of the plasma density it used. Table 1 summarizes the derived shock propagation
 403 characteristics from the ENLIL simulation, J-maps, and kmTII method.

6. Discussion and Conclusion

404 We have comprehensively investigated the evolution and propagation of the April 3, 2010
 405 CME-driven shock, combining STEREO and SOHO white light observations, kilometric
 406 type II radio data with the simulation using the WSA-Cone-ENLIL model. We used the
 407 KS06 flux rope model fit to SECCHI and LASCO observations to determine the CME

408 speed, size and direction, as well as its time-distance profile when the CME is within
409 the C3 FOV. We derived the time-distance profile of the CME/shock in the heliosphere
410 from the J-maps constructed from SECCHI images, from near the Sun all the way to 1
411 AU. The shock front was seen clearly in the HI1-A images starting from April 3 \sim 15:29
412 UT. Three methods, i.e., P-Point, Fixed- ϕ , and Harmonic Mean, were used to derive
413 the radial distances from elongation angles in the J-maps. The obtained results show
414 that the harmonic mean approximation gives the best results for the time-distance and
415 time-velocity profiles of the shock, yielding the smallest errors compared to the Wind
416 observations of the shock arrival time and in situ plasma bulk velocity in the sheath. To
417 fully investigate the formation and evolution of the shock and predict the shock arrival
418 time, we used the WSA-Cone-ENLIL model simulation and the kmTII technique. The
419 kinematic analysis from J-maps together with in-situ data provided us with a valuable
420 opportunity to validate the simulated results and the kmTII prediction.

421 We found that the ENLIL model provided good predictions on the shock arrival time
422 along both the Sun-Earth line and the CME-LE propagation directions. The ENLIL
423 model predicted the SAT at Earth on April 5 at 08:57 UT and the SAT at 1AU along the
424 LE of \sim 12:10 UT with $\sim 1 \pm 7$ hours and $\sim 5 \pm 7$ hours errors, respectively, compared
425 to the Wind SAT and J-map SAT along the LE. It also reproduced the overall dynamics
426 of the shock propagation with realistic large scale structures in the simulation, including
427 the background solar wind density along the Sun-Earth line, the locations of streamer
428 outflows, the CME-streamer interaction, and the flattened arc-like shock front along the
429 LE.

430 The kmTII prediction largely relies on the coronal density model and the electron
431 density n_0 at 1 AU, which is assumed to be the average solar wind value 7.2 cm^{-3} in
432 *Cremades et al.* [2007]. To investigate the possibility of using the ENLIL model density
433 to improve the kmTII prediction, we applied the solar wind density obtained from the
434 simulation to the kmTII method. With $n_0 = 4.16 \text{ cm}^{-3}$ at Earth and $n_0 = 6.64 \text{ cm}^{-3}$ at
435 the LE, the estimated shock speeds are 656 km/s and 829 km/s, yielding SATs of 22:57
436 UT and 09:44 UT and errors of ~ 15 hours and ~ 2 hours, compared to the Wind SAT
437 of 07:58 UT.

438 Note that, however, the good prediction of ~ 2 hours was due to the cancellation of
439 two errors, i.e., the error in the location where the kmTII occurred and the density error
440 from the simulation. First, the kmTII radio emission was assumed to occur at the CME
441 LE, where the shock had been intensified due to the CME-streamer interaction and low
442 Alfvén speed (high density) in the streamer, as shown in Figure 9a. Second, the actual
443 error is ~ 7.7 hours when compared to the J-map SAT of 17:27 UT at the LE, indicating
444 the ENLIL model had overestimated the density along the LE, resulting in a smaller SAT,
445 which yielded a small error of ~ 2 hours (compared with 07:58 UT).

446 One possible reason for the ENLIL model's overestimating the plasma density along
447 the LE may be because the simulation didn't reproduce the small flux-rope like V-shaped
448 structure which is observed by HI-A. On closer examination of HI-A image movie, we
449 see that a small flux-rope like V-shaped structure was formed out of the streamer outflow
450 ahead of the CME LE. The first appearance time of this small FR-like V-shaped structure
451 in HI1-A was around April 3 20:09 UT. Its formation was likely due to reconnection of
452 magnetic field lines at the tip of helmet streamers [e.g., *Rouillard et al.*, 2010]. This V-

453 shaped structure was observed to be entrained by the streamer outflows and traveling with
454 the similar speed as the solar wind. The CME caught up with the V-shaped structure
455 at $\sim 02:09$ UT on April 4, as shown in HI2-A image movie, and then merged together
456 around $\sim 20:09$ UT. An arc-like shaped front was formed due to the large compression
457 caused by the interaction of the CMEs in the HI2-A movie. This interacting duration was
458 consistent with the time period when the kilometer type II burst occurred, suggesting
459 that the CME-streamer (or CME-CME) interaction enhanced the shock intensity and
460 produced the type II radio burst [e.g., *Gopalswamy et al.*, 2001]. Since the ENLIL model
461 didn't include the CME's internal magnetic field, it didn't reproduce the V-shaped FR-
462 like structure formed out of the streamer. This may explain why the simulation results
463 didn't reproduce as big of a difference of the shock along two propagation directions, i.e.,
464 the LE and the Sun-Earth line, as that shown in the J-map. It may also explain why the
465 ENLIL model produced too large of a plasma density upstream of the shock in order to
466 compensate the magnetic field pressure from the small FR-like CME along the LE. If a
467 CME-driven shock occurs in a background solar wind which is more homogeneous, using
468 the ENLIL model has the potential to improve the kmTII prediction. In turn, the kmTII
469 observations can constrain and help improve the future modeling of shocks.

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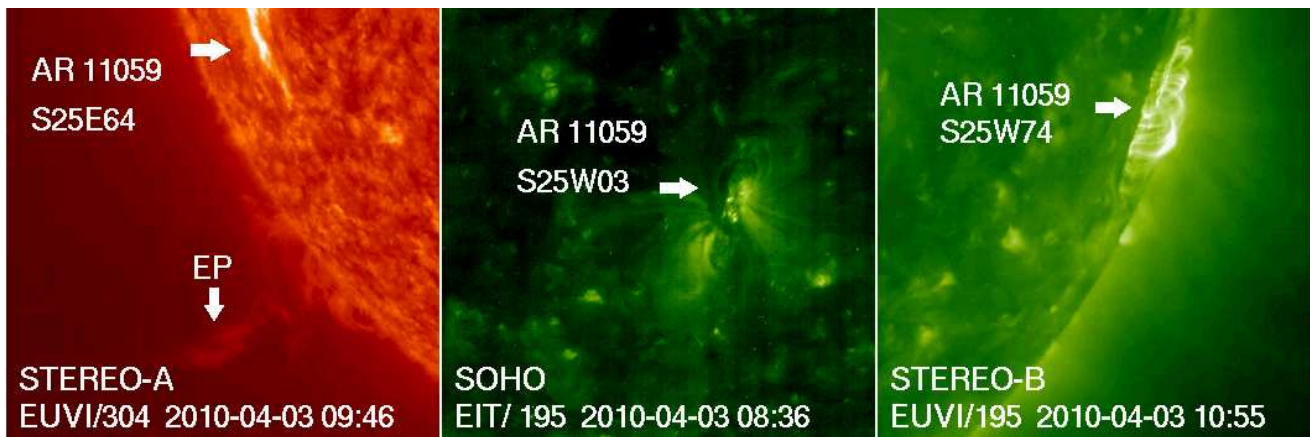


Figure 1. (Left) EUVI 304 Å image on STEREO A showing an eruptive prominence to the south of AR 11059 at 09:46 UT; (middle) EIT 195 Å image at 08:36 UT and (right) EUVI 195 Å image at 10:55 UT showing a sigmoid to post eruption arcade flare in AR 11059 observed from SOHO and STEREO B, respectively.

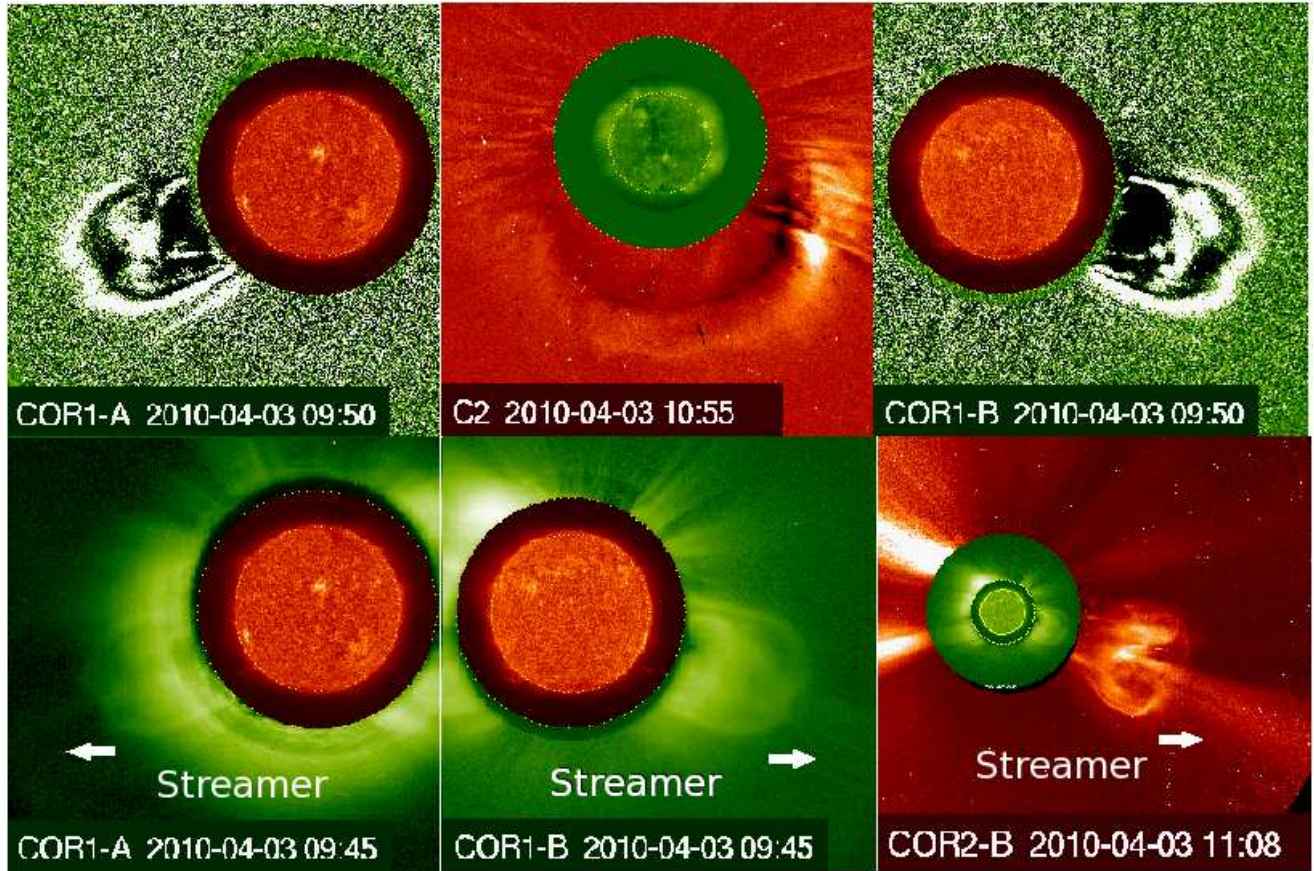


Figure 2. (Top) STEREO A (left) and B (right) COR1 running-difference images superimposed with EUVI 304 Å image at 09:50 UT and SOHO C2 running-difference image (middle) superimposed with EIT 195 Å image at 10:55 UT showing edge-on and face-on views of the *April 03* CME. (Bottom) STEREO A (left) and B (middle) COR1 original images superimposed with EUVI 304 Å image at 09:45 UT and STEREO B COR2 image (right) at 11:08 UT showing a streamer located ahead of the CME leading edge.

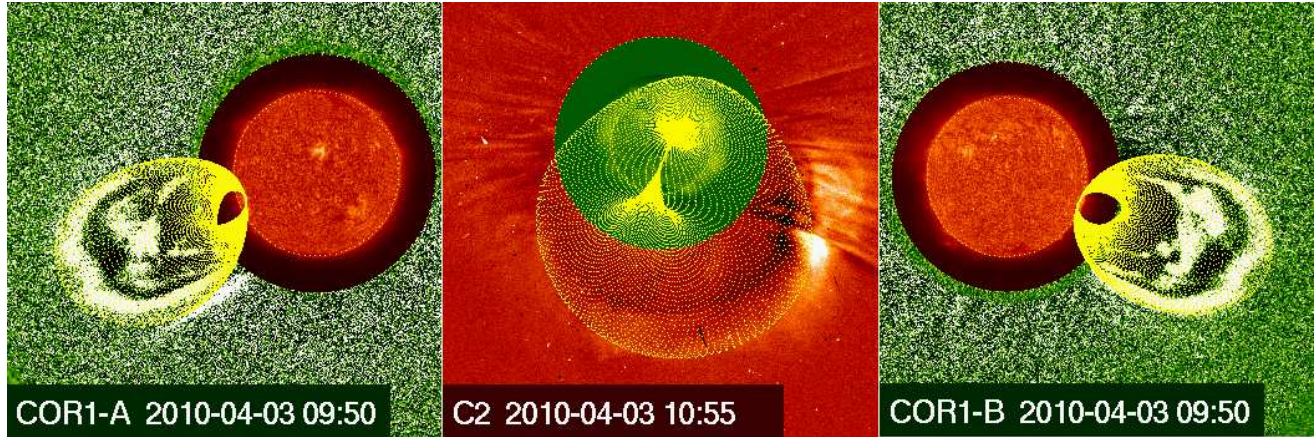


Figure 3. Flux-rope Modeling of the Apr 3, 2010 CME. STEREO A and B COR1 and SOHO C2 images with the flux-rope projected wireframe (yellow curves) overlaid on top.

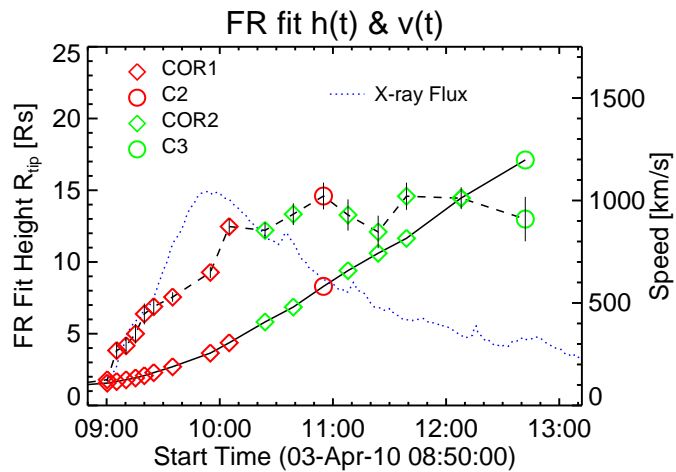


Figure 4. The flux-rope model fit results to the CME in COR1 (red diamonds), COR2 (green diamonds), C2 (red open circle), and C3 (green open circle) images. The model fit height-time profile and derived velocity profile are denoted by the solid and dashed lines respectively, overplotted with the GOES X-ray flux (blue dotted line). The short vertical lines in the figure indicate the velocity uncertainties.

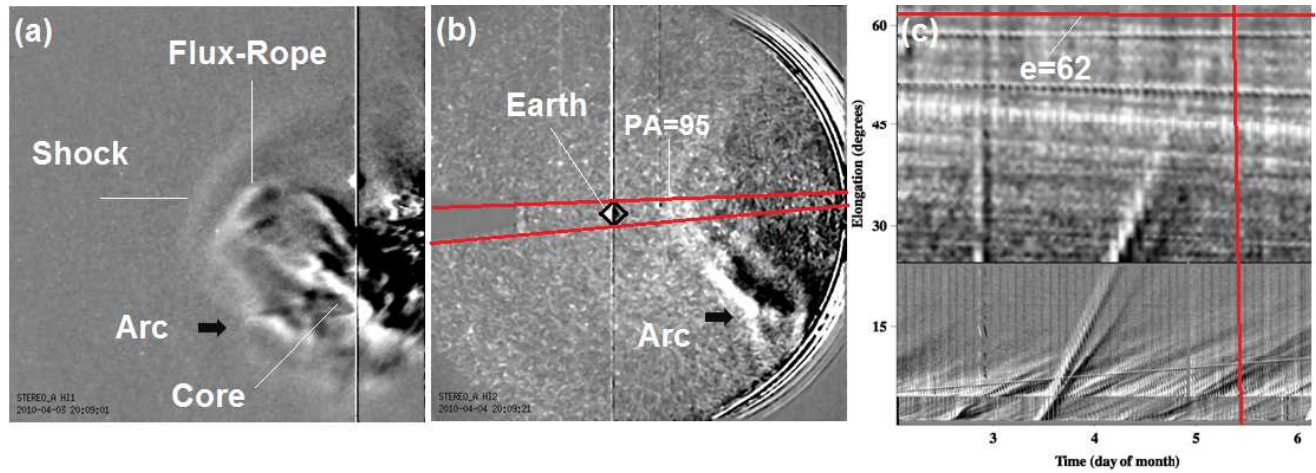


Figure 5. From left to right: running difference image of HI1-A on April 3, 20:09 UT, HI2-A image on April 4, 20:09 UT and a time-elongation J-map along PA = 95°. Shock front, CME features and the Earth location are marked in the HI images. Thick arrows in (a) and (b) denote the CME arc-like leading edge which has been indented. Two red lines in (b) label the slit we use to make the Jmap at PA = 95°. The horizontal and vertical lines in the J-map mark the Earth position (at 62°) and the time (05:42 UT) when the shock arrived at Earth.

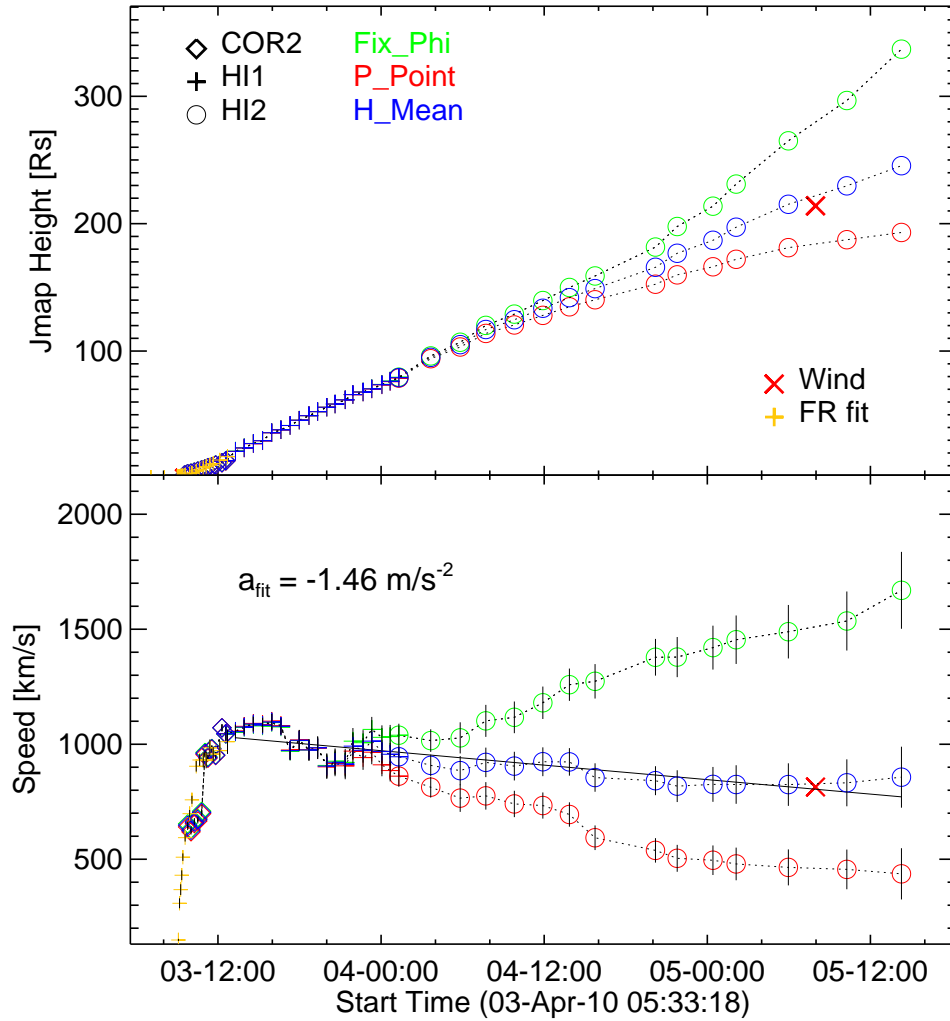


Figure 6. (Top) time-distance and (bottom) time-velocity profiles along the Sun-Earth line, for the three approximations denoted by red, green, and blue respectively. The Fixed- ϕ method produces an apparent acceleration in HI2 FOV, while the Point-P method produces an apparent deceleration. The Harmonic Mean method yields the most plausible kinematic profile, with the smallest errors compared to the Wind observations.

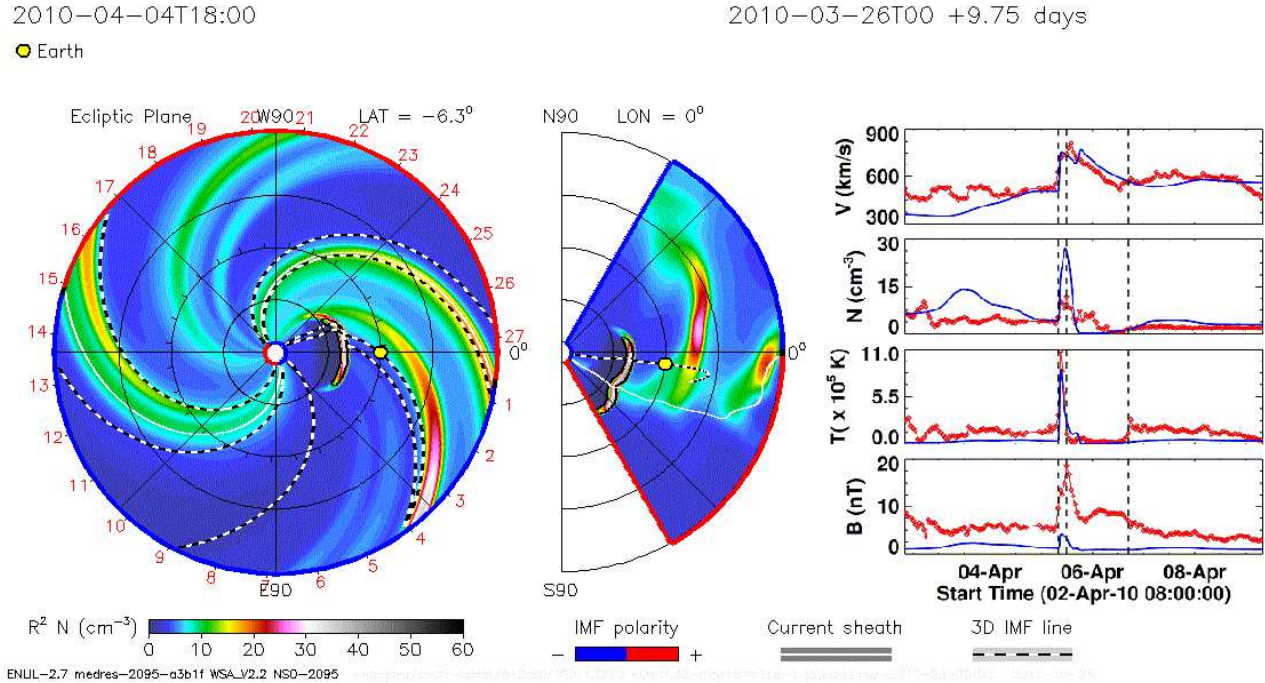


Figure 7. Simulation results of 2D density contours in the ecliptic plane (left panel) and meridian plane (middle panel) on April 4, 18:00 UT. The density in the simulation is normalized for an r^{-2} falloff with distance. Right panel is the comparison of the simulated (blue solid lines) and observed Wind solar wind plasma and magnetic field data (red dotted lines) at 1 AU between April 2 and 9.

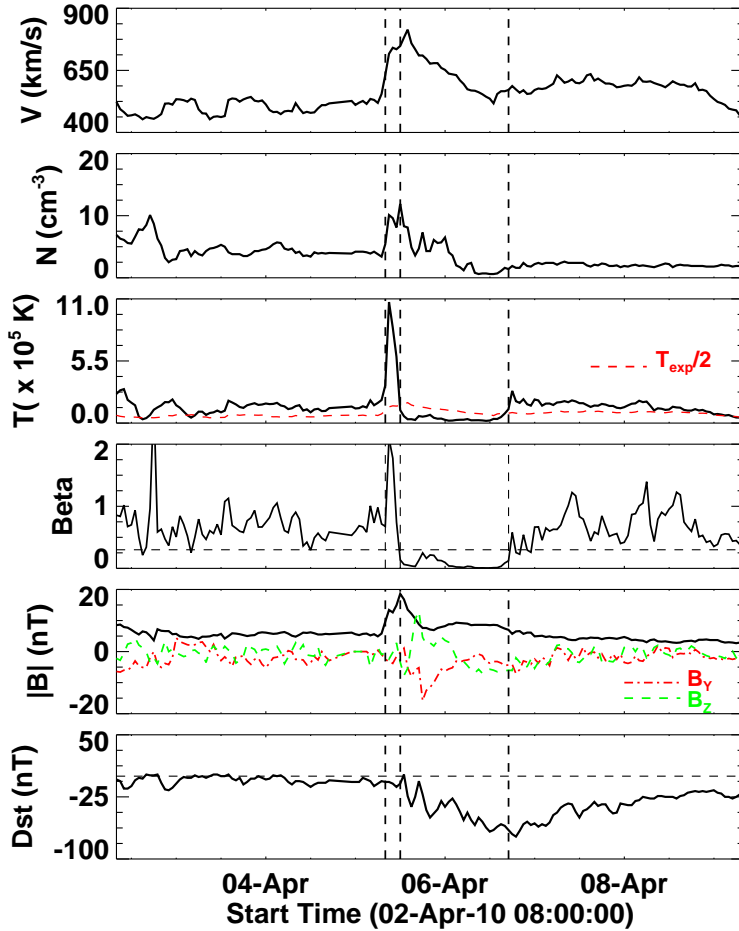


Figure 8. Solar wind plasma and magnetic field data (Wind). From top to bottom: proton bulk velocity V , proton number density N , proton temperature T , plasma β , magnetic field magnitude $|B|$ and components B_y and B_z , and Dst index. The three vertical dashed lines indicate the shock arrival and the ICME interval, where the ICME is identified by the interval that shows proton temperature depression below half the expected solar wind temperature T_{exp} . The horizontal lines in β and D_{st} are lines for $\beta = 0.3$ and $D_{st} = 0$, respectively.

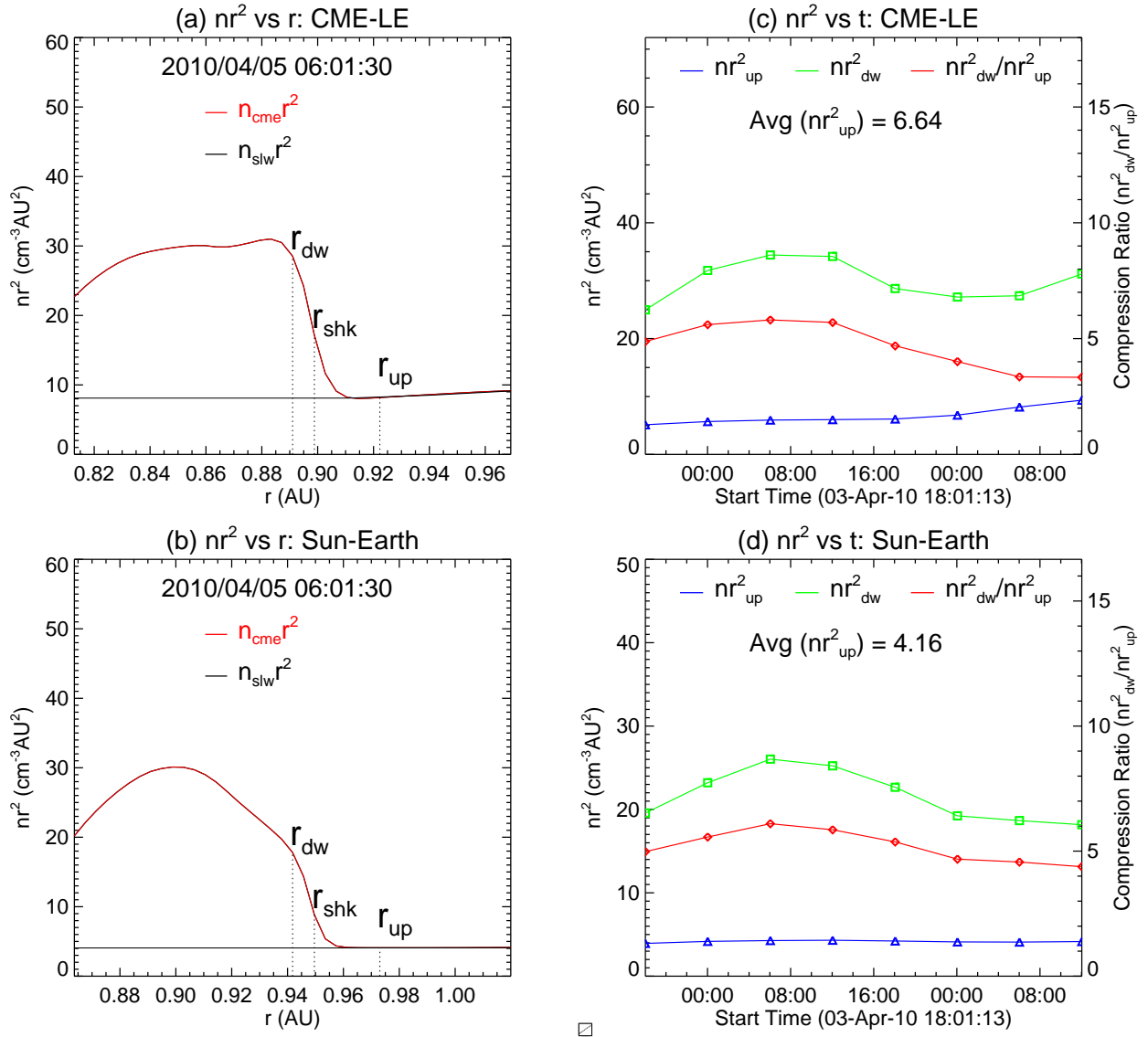


Figure 9. (Left) Simulation results of nr^2 (density times square of radial distance) as function of distance r : a) along the LE propagation direction; b) along the Sun- Earth line on April 5, 06:01:30 UT, where red and black lines denote the CME and ambient solar wind plasma density respectively, and three dashed vertical lines mark locations of the shock front, upstream and downstream. (Right) nr_{up}^2 , nr_{dw}^2 , shock compression ratio $nr_{\text{dw}}^2/nr_{\text{up}}^2$ as function of time : c) along the LE and d) along the Sun-Earth line.

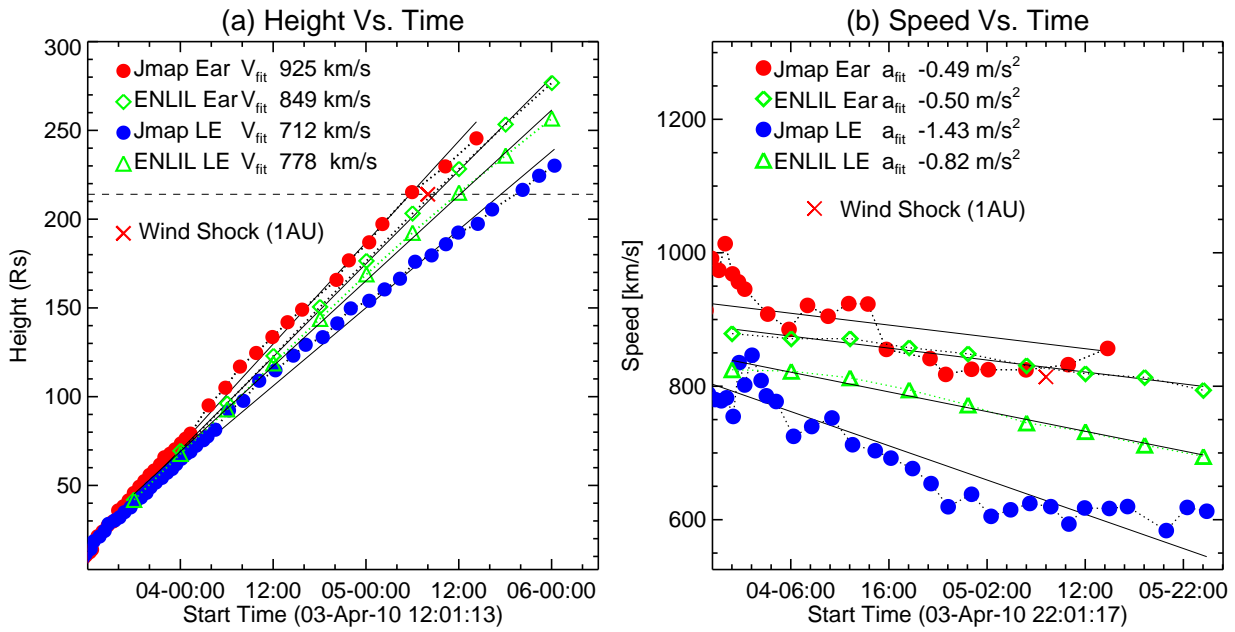


Figure 10. Comparison of (a) time-distance and (b) time-velocity profiles of the shock from the ENLIL model and J-maps, where V_{fit} and a_{fit} are the linear-fit velocity and acceleration.

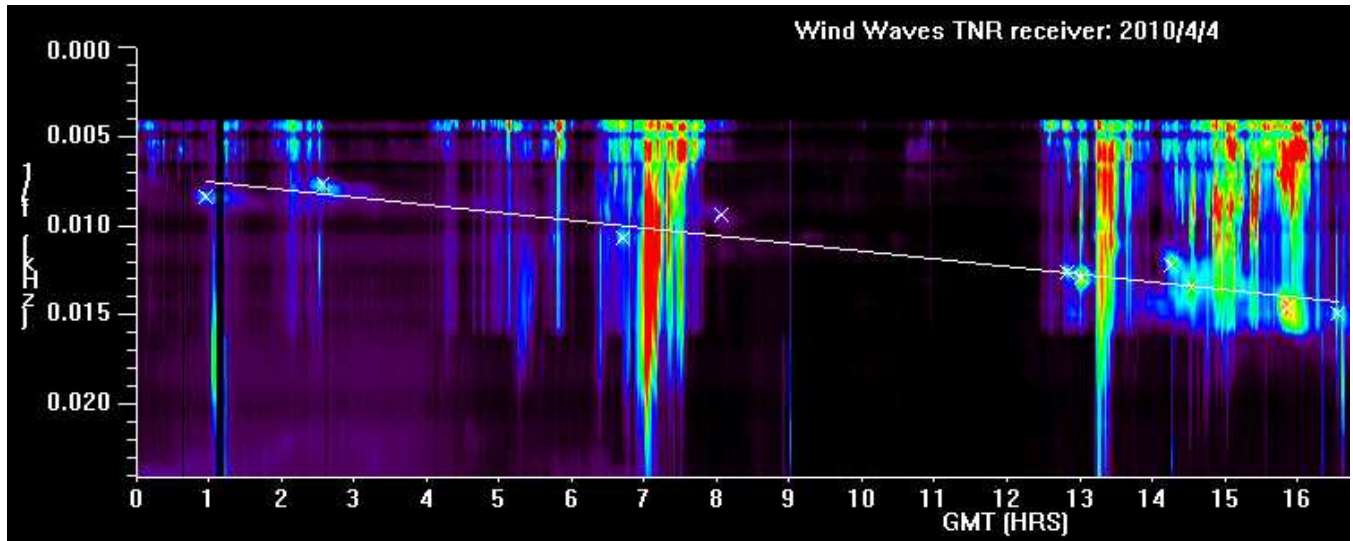


Figure 11. kmTII dynamic spectrum detected by the TNR receiver on April 4 2010. Note the scale of the vertical axis is in units of $1/f$. "X" symbols in the figure mark the selected data points in the spectrum.

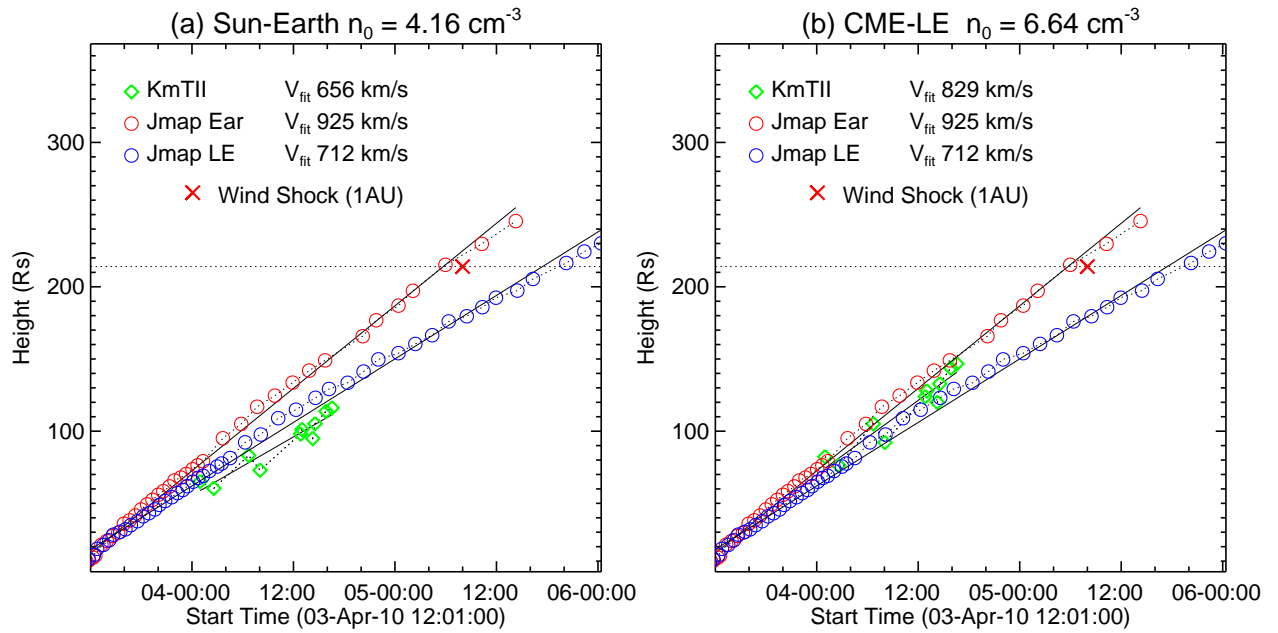


Figure 12. Comparison of the time-distance profiles of the shock from J-maps and kmTII with a) $n_0 = 4.16 \text{ cm}^{-3}$ along the Sun-Earth line and b) $n_0 = 6.64 \text{ cm}^{-3}$ along the CME LE.

Table 1. Summary of the predicted shock properties from the simulation, J-maps and kmTII method.

	ENLIL		J-map		kmTII	
	Sun-Earth	CME-LE	Sun-Earth	CME-LE	Sun-Earth	CME-LE
					$n_0(4.16)$ (cm^{-3})	$n_0(6.64)$ (cm^{-3})
SAT (UT) ^a	08:57	12:10	05:42	17:27	22:57	09:44
V_{fit} (km s^{-1}) ^b	849	778	925	712	656	829
a_{fit} (m s^{-2}) ^c	-0.50	-0.82	-0.49	-1.43	—	—

^a Shock arrival time; all times are on Apr 5

^b Shock linear-fit velocity

^c Shock linear-fit acceleration