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Market Proxies, Correlation, and Relative Mean-Variance Efficiency: Still Living with the Roll Critique¹

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Abstract

A pricing restriction is developed to test the validity of the CAPM conditional on a prior belief about the correlation between the true market return and the proxy return used in the test. Distinguishing this pricing restriction from competing tests also based upon the relative efficiency of the proxy return is a consideration for the proxy's mismeasurement of the market return. Failure to account for this mismeasurement biases tests of the CAPM towards rejection by overstating the inefficiency of the proxy. A time-varying version of this pricing restriction links mismeasurement of the market return to time-variation in beta.

Keywords: Asset pricing, CAPM, portfolio efficiency, multivariate testing, bootstrap hypothesis testing, triangular systems, endogeneity, identification, GMM, conditional heteroskedasticity, GARCH. JEL codes: C12, C13, C32, G12.

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1. Introduction

A common feature among many asset pricing models in financial economics is the relation of expected returns on risky securities to the covariance between those securities' returns and an economic aggregate like (the marginal utility of) aggregate wealth or consumption. In empirical work, this economic aggregate (central to the pricing model under consideration) is generally unobservable and requires a proxy. Tests of the given model which, by necessity, are based on the proxy are confronted by a joint hypothesis that complicates the interpretation of a rejection of the model's prediction. In particular, does this rejection signal a violation of the model's result or the poor quality of the proxy chosen to render the model "testable"? In specific regard to the capital asset pricing model (CAPM), the existence of this dual hypothesis led Roll (1977) to conclude that the "theory is not testable unless the exact composition of the true market portfolio is known and used in the tests" (p. 130).

Roll's critique was met by two possible ways forward. First, since validity of the CAPM and mean-variance efficiency of the market return are equivalent, if the proxy is not mean-variance efficient, then any "test" based on this proxy seems besides the point. This stance led to the development of tests for mean-variance efficiency of a proxy, with Gibbons, Ross, and Shanken (1989) serving as the prominent example and MacKinlay and Richardson (1991) providing a useful generalization. Second, if the proxy is invalid (i.e., not mean-variance efficient), then the CAPM prediction based on this proxy should not be expected to hold exactly, only approximately. From this stance, bounds on the deviations from exact CAPM pricing were developed based upon the relative efficiency of the proxy (i.e., its distance inside the minimum-variance boundary). Examples of this approach include Shanken (1987) as well as Kandel and Stambaugh (1987, 1995).

This paper extends the literature on relative efficiency testing by developing a pricing restriction that reflects the way in which (1) a proxy return relates to the market return and (2) individual security returns relate to the proxy. The first relation is addressed in the works of Shanken (1987) and Kandel and Stambaugh (1987). The second is the principal contribution of this paper. A general outline of the approach is as follows. The measure of relative efficiency is the correlation between the proxy return and the market return denoted by ρ . A prior belief on the true value of ρ is denoted by ρ_o . A value for ρ is computed as the upper bound to a multivariate statistic of CAPM pricing errors measured against the proxy. If this value is less than ρ_o , such is interpreted as evidence against the CAPM. This approach is a conditional test of the CAPM based upon a prior belief about the relative efficiency of the proxy. If the proxy is determined to be too far inside the minimum-variance boundary, the market return is concluded to also be inefficient.

Conditional on the market return being mean-variance efficient, a test of relative efficiency assumes that, to some extent, the proxy return mismeasures the market return. A common starting point for most relative efficiency tests is the assumption that the relationship between security returns (or portfolios of these returns) and the proxy return can be explained by a projection of the former onto the latter. Suppose that mismeasurement of the market return by the proxy return is taken to mean that certain components relevant to the market return are excluded from the proxy. Then, the extent to which these excluded components are correlated with the proxy return will determine the extent to which innovations to a linear equation describing security returns conditional on the proxy return will tend to covary with that proxy return, since those innovations will contain the aforementioned omitted components. In other words, mismeasurement renders the proxy return endogenous in a linear equation relating security returns to the proxy. The resulting structural

equation will differ from a projection equation. This paper shows that relative efficiency tests based upon projections are biased towards rejecting the CAPM because these tests overstate a proxy's distance away from the minimum-variance boundary. Mismeasurement of the market return is the source of this bias.

A relative efficiency test based upon the aforementioned structural equation as opposed to the commonly used OLS projection requires a consistent estimator for the former in order to render the test feasible empirically. Towards that end, a novel estimator for linear equations with an endogenous regressor proposed by Prono (2008) is utilized. This estimator relies upon the conditional heteroskedasticity of security returns by basing identification on exclusionary restrictions within the functional form describing that heteroskedasticity. As such, this estimator is a higher-moment analog to common instrumental variables techniques. MacKinlay and Richardson (1991) demonstrate that heteroskedasticity in market model residuals can meaningfully impact the results of mean variance efficiency tests for a given proxy return. This paper extends their findings to tests of relative efficiency noting, however, that a particular form of heteroskedasticity can be used to describe not only the second moment patterns of market model residuals, but also the co-movement of these residuals with the proxy return caused by the latter's mismeasurement of the market return (MacKinlay and Richardson (1991), among others, assume this co-movement to be zero).

The remainder of this paper is organized as follows. Starting from a rather general pricing model, Section 2 develops a pricing restriction that can be used to test the CAPM conditional on a prior belief about the correlation between the market return and the proxy used in the test. This restriction fully encompasses the difference between the market return and an imperfect proxy. Section 3 reviews conventional tests of relative mean-variance efficiency. Section 4 presents an overview of the econometrics used to identify and estimate the structural equation describing security returns in terms of the proxy return. Section 5 details a method for conducting a test of relative mean-variance efficiency that is based upon the econometric techniques developed in section 4. Section 6 summarizes the results from employing this test, comparing them to the results obtained from the conventional methods reviewed in section 3. Section 7 presents the results of a Monte Carlo study of the test proposed in section 5 against conventional alternatives. Section 8 proposes a generalization of the pricing restriction in section 2 that provides a direct link between mismeasurement of the market return and time-variation in beta. Section 9 concludes.

2. Pricing Restriction

Assume there exists an observable risk-free rate. Let r_t be an N -vector of excess security returns, r_{pt} a scalar proxy to the unobservable excess market return r_{mt} , and let the resulting $N + 1$ components be linearly independent. Finally, define m_t as a scalar unobservable economic aggregate. Potential examples of m_t include (the marginal utility of) aggregate wealth or consumption. Consider the following pricing model

$$E[r_t] = Cov[m_t, r_t] \tag{1}$$

that relates expected excess returns to the covariance between excess returns and the economic aggregate. Many pricing models in financial economics can be characterized in terms of (1). For

instance, suppose

$$m_t = \left(\frac{E[r_{mt}]}{\sigma^2[r_{mt}]} \right) r_{mt}. \quad (2)$$

Then (1) and (2) imply

$$E[r_t] = \beta E[r_{mt}]$$

where

$$\beta = \frac{Cov[r_{mt}, r_t]}{\sigma^2[r_{mt}]}$$

which is the familiar CAPM of Sharpe (1964) and Lintner (1965). Alternatively, replacing r_{mt} in (2) with r_{ct} , the excess return on a security (or portfolio of securities) that is perfectly correlated with changes in aggregate consumption, renders (1) and (2) the CCAPM of Breeden (1979). More generally, if m_t can be decomposed into a set of K orthogonal factors where the i th factor f_{it} is weighted by $\frac{E[f_{it}]}{\sigma^2[f_{it}]}$, then (1) expresses a multi-beta factor model in the spirit of Ross (1976) and Sharpe (1977). For the purpose of this paper, however, interest is focused on proportionality of the economic aggregate to the market return as given by (2).

The model of (1) and (2) can be expressed as a linear multivariate regression

$$r_t = \alpha + \beta r_{mt} + e_t \quad (3)$$

where $E[e_t r_{mt}] = 0$ and $\alpha = 0$. Suppose that

$$r_{mt} = r_{pt} + \phi_t, \quad (4)$$

which is related to (17) in Jagannathan and Wang (1996) and casts the relationship between the market return and proxy return as a form of measurement error.³ In addition, (4) is a close counterpart to the decomposition of a proxy return used to develop the CAPM for inefficient portfolios (CAPMI) in Diacogiannis and Feldman (2006). Differences between (4) and the CAPMI are (1) ϕ_t is not assumed to be uncorrelated with r_{mt} and (2) the expected values of r_{pt} and r_{mt} are not, necessarily, equal. The variable ϕ_t reflects components to the market return that are excluded from the proxy return. Examples of these components include returns to nontraded assets and/or the returns to human capital.⁴ Substitution of (4) into (3) produces

$$r_t = \gamma + \delta r_{pt} + \tilde{e}_t \quad (5)$$

where

$$\begin{aligned} \gamma &= \alpha + \beta E[\phi_t], & \delta &= \beta \\ \tilde{e}_t &= \beta \tilde{\phi}_t + e_t, & \tilde{\phi}_t &= \phi_t - E[\phi_t] \end{aligned} \quad (6)$$

³(4) is a generalization of (17) in Jagannathan and Wang (1996) if $\phi_{vw} = 1$. ϕ_t is measurement error in a general sense not in a classical sense, since the assumption that $\phi_t \perp r_{m,t}$, r_t is not made. In fact, there is good reason for this omission, since given what the measurement error is intended to reflect, ϕ_t is related to both $r_{m,t}$ and r_t .

⁴Studies by Campbell (1996), Jagannathan and Wang (1996), and Dittmar (2002) note the importance of the return to human capital in pricing expected returns.

In Diacogiannis and Feldman (2006), r_{pt} and ϕ_t must be correlated. From (5),

$$Cov [\tilde{e}_t, r_{pt}] = \beta Cov [\phi_t, r_{pt}] = \beta (Cov [\phi_t, r_{mt}] - \sigma^2 [\phi_t]).$$

In general, this expression is not zero, which is to say that r_{pt} is an endogenous regressor in (5). As a result, (5) is a structural equation that unlike (3) cannot, necessarily, be treated as a linear projection without loss of generality. The fact that the market return is unobservable and any proxy return, by definition, is incomplete affords this distinction. The effects of this distinction on the efficiency of a proxy return relative to the market return is made explicit in the proposition below.

According to Cochrane (2001), "all factor models are derived as specializations of the consumption-based model" (p. 151). (1) reflects this fact. Empirically-based factor models attempt to tie the discount factor m_t to observable variables. Towards that end, consider a linear projection of m_t onto r_{pt} :

$$m_t = a + br_{pt} + e_{mt} \quad (7)$$

According to Lemma 1 of Shanken (1987), the combination of (5) and (7) implies that

$$Cov [\tilde{e}_t, e_{mt}]' \Sigma_{\tilde{e}}^{-1} Cov [\tilde{e}_t, e_{mt}] \leq \sigma^2 (m_t) (1 - \rho^2) \quad (8)$$

where $\Sigma_{\tilde{e}}$ is the covariance matrix of \tilde{e}_t , and ρ is the correlation between m_t and r_{pt} . All proofs in this section are given in Appendix A. From Shanken (1987), $Cov [\tilde{e}_t, e_{mt}]$ "may be interpreted as a vector of deviations from an exact [single] beta expected return relation" (p. 93). (8) places an upper bound on these deviations and is useful in determining a similar bound for deviations from CAPM pricing measured conditional on a proxy return. Proposition 1 formalizes this result in light of the structural equation in (5) and the potential nonzero covariance between \tilde{e}_t and r_{pt} .

Proposition 1 *Let the pricing model of (1) and (2) hold for all security returns including the proxy return, and consider the structural relationship between security returns and the proxy return as given by (5). Define*

$$\theta_p = \frac{E [r_{pt}]}{\sigma [r_{pt}]} \quad (9)$$

as the Sharpe performance measure for the proxy return, and

$$\eta = \frac{Cov [\tilde{e}_t, r_{pt}]}{\sigma^2 [r_{pt}]} \quad (10)$$

as a measure of the degree to which unobservable components to the market return covary with the proxy return. Then,

$$d' \Sigma_{\tilde{e}}^{-1} d \leq \theta_p^2 (\rho^{-2} - 1) \quad (11)$$

where

$$d = E [r_t] - (\delta + \eta) E [r_{pt}].$$

The pricing restriction of (1) and (2) is not testable because the market return is unobserved. With the exception of ρ , (11) is constructed entirely in terms of quantities that can be estimated di-

rectly from observable data, provided, of course, that (5) can be identified. Proposition 1, therefore, is a testable analog to (1) and (2) conditional on a prior belief about the value of ρ .

The proof of Proposition 1 in Appendix A demonstrates that

$$\rho = \frac{\theta_p}{\sigma[m_t]},$$

implying that ρ is strictly positive. Let $\theta_m = \frac{E[r_{mt}]}{\sigma[r_{mt}]}$, the Sharpe performance measure for the market return. Given (2), $\sigma[m_t] = \theta_m$, and ρ is a ratio of Sharpe performance measures. As a result, ρ is afforded a geometric interpretation in mean-standard deviation space as the ratio of the slope of the security market line passing through the excess proxy return to the slope of the security market line tangent to the minimum variance boundary at the excess market return. This ratio gauges the relative efficiency of the excess proxy return.

Corollary 1 *In (4), suppose that ϕ_t is constant such that $\phi_t = \phi_c$. Then*

$$d' \Sigma_{\tilde{e}}^{-1} d = 0 \quad (12)$$

where $d = \alpha$ from (3) if and only if $\phi_c = 0$.

If $\phi_c = 0$, then according to (52) $\rho = 1$ and (11) holds as an equality to zero. Corollary 1 then provides a basis for tests of mean-variance efficiency like those proposed by Gibbons, Ross, and Shanken (1989) as well as MacKinlay and Richardson (1991), since these tests rely on the assumption that $\phi_t = \phi_c$ so that $Cov[\tilde{e}_t, r_{pt}] = 0$. In such a case, (12) is a statement of the null hypothesis

$$H_0 : \alpha = 0; \quad \phi_c = 0, \quad (13)$$

since

$$d = E[r_t] - \delta E[r_{pt}] = \alpha + \beta \phi_c \quad (14)$$

given (5), (6) and the fact that $\eta = 0$.⁵ Failure to reject this null is a failure to reject equivalence between the market and proxy return as well as mean-variance efficiency of the market return. Rejection of this null, on the other hand, is only a rejection of mean-variance efficiency of the proxy return, since either $\phi_c \neq 0$, in which case the proxy return is inefficient because $\rho < 1$, or $\alpha \neq 0$, in which case the proxy and the market return are inefficient, or both. The inability to distinguish between these alternatives illustrates the Roll (1977) critique that the CAPM theory is not directly testable.

If $\phi_t = \phi_c$, then (5) can be treated as a projection equation without loss of generality. In this case, the manner in which Proposition 1 allows for an indirect assessment of the CAPM is parallel to that of Proposition 2 in Shanken (1987). Specifically, if $\alpha = 0$, then $d \neq 0$ because $\phi_c \neq 0$. For a given Sharpe performance measure of the proxy return, the magnitude of this distance d away from zero is bounded from above by the correlation between the market return and the proxy return.⁶

⁵From (14), $d = 0$ if $\alpha = -\beta \phi_c$. This latter equality is only satisfied under (13). To see why, note that β cannot be a zero vector. Therefore, if α is nonzero, then ϕ_c needs to be nonzero for the equality to hold. But, given (52) a nonzero ϕ_c means $\rho < 1$, which, in turn, means that $d \neq 0$ given (11).

⁶Direct proportionality between the economic aggregate and the market return in (2) leads to $\rho = \frac{Cov[r_{mt}, r_t]}{\sigma[r_{mt}]\sigma[r_t]}$.

Let ρ_o be a prior belief on the true value of ρ . For a given d , $\Sigma_{\tilde{e}_t}$, and θ_p , let $\bar{\rho}$ be the value of $\rho \in (0, 1]$ that, if it exists, satisfies (11). If $\bar{\rho} < \rho_o$, such a result is interpreted as evidence that not only is $\phi_c \neq 0$ but $\alpha \neq 0$ as well. The strength of this evidence increases as $\bar{\rho} - \rho_o$ becomes more negative and is, of course, conditional on the correctness of ρ_o .

Suppose $\phi_t \neq \phi_c$ so that the structural equation in (5) no longer coincides with a projection of r_t onto r_{pt} . Diacogiannis and Feldman (2006) postulate that correlation between r_{pt} and ϕ_t "might be material when considering the misspecification caused by ignoring, in implementations and tests, the addendum related to $[\phi_t]$ " (p. 20). The following corollary confirms this hypothesis.

Corollary 2 *Let e_{pt} be the errors from a linear multivariate projection of r_t on r_{pt} , and define Σ_{e_p} as the variance-covariance matrix of these errors. Given (4), $\Sigma_{\tilde{e}} - \Sigma_{e_p}$ is positive semi-definite.*

According to Corollary 2, $\Sigma_{\tilde{e}} \geq \Sigma_{e_p}$ and, by extension, $\Sigma_{e_p}^{-1} \geq \Sigma_{\tilde{e}}^{-1}$. From (54) and (55) in the proof of Corollary 2,

$$d = E[r_t] - (\delta + \eta) E[r_{pt}] = \alpha_p,$$

the vector of constant terms from a linear multivariate projection of r_t on r_{pt} . If (5) is replaced by (53), then the left-hand-side of (11) becomes $\alpha'_p \Sigma_{e_p}^{-1} \alpha_p$. Otherwise, the left-hand-side of (11) is $\alpha'_p \Sigma_{\tilde{e}}^{-1} \alpha_p$ and

$$\alpha'_p \Sigma_{e_p}^{-1} \alpha_p \geq \alpha'_p \Sigma_{\tilde{e}}^{-1} \alpha_p.$$

From (57), a case where these two quadratic forms equate is when $\phi_t = \phi_c$. In general, however, the degree to which expected returns deviate from the CAPM prediction measured conditional on a proxy return will tend to be overstated if $\Sigma_{e_p}^{-1}$ is used as the weighting matrix as opposed to $\Sigma_{\tilde{e}}^{-1}$. As a consequence, $\bar{\rho}$ will tend to be understated. The end result is that treating the relationship between security returns and the proxy return as a projection equation instead of a structural equation will bias test results of the inequality restriction in Proposition 1 towards rejecting the CAPM theory.

Hansen and Jagannathan (1997) criticize model misspecification tests that depend on the variance-covariance matrix of the pricing errors because these tests grant a "reward for sampling error associated with the sampling mean." In reference to the CAPM, this paper argues that higher sampling error should be accounted for to the extent that it relates to misspecification of the market return. Ignoring this misspecification will bias the test results towards rejecting the theory because of the proxy being used in the test not because of any failing in the theory itself.

If $\phi_t = \phi_c$, then according to (14),

$$\alpha_p = \alpha + \beta \phi_c. \quad (15)$$

In this case, the difference between the alpha proxy and the true alpha is directly proportional to the location-shift in the market return relative to the proxy return. This difference is expected to be positive (negative) if β is positive (negative), since a negative ϕ_c implies that $\rho > 1$ given (52). If $\phi_t \neq \phi_c$, then

$$\alpha_p = \alpha + \beta E[\phi_t] - \eta E[r_{pt}] \quad (16)$$

given (55). In this case, the difference between the alpha proxy and the true alpha is ambiguous. Affecting this difference are both the mean of the omitted components as well as the covariance

between those components and the proxy return. Provided that the CAPM holds, (15) explains the empirical discovery of "significant" alpha to be the result of mismeasuring the market return. (16) adds to this explanation the sensitivity of individual security returns to changes in the source of this mismeasurement.

3. Conventional Tests

Suppose $\phi_t = \phi_c$ in (4), and assume that $e_t \sim N(0, \Sigma_e)$. Let \hat{d} and $\hat{\Sigma}_e = \frac{1}{T} \sum_{t=1}^T \hat{e}_t \hat{e}_t'$ denote estimates of α_p in (15) and Σ_e , respectively, from N separate OLS regressions of r_{it} on r_{pt} , where r_{it} is the i th element of r_t and $t = 1, \dots, T$. $\hat{\theta}_p$ is an estimate of the proxy performance measure computed from the sample mean and variance of r_{pt} . Consider the following definitions:

$$Q \equiv \frac{T \hat{d}' \hat{\Sigma}_e^{-1} \hat{d}}{1 + \hat{\theta}_p^2}; \quad \lambda \equiv \frac{T d' \Sigma_e^{-1} d}{1 + \hat{\theta}_p^2}.$$

Gibbons, Ross, and Shanken (1989) show that $[N^{-1}(T - N - 1)/T - 2] Q$, conditional on r_{pt} , is distributed as a noncentral F with degrees of freedom N and $T - N - 1$ and non-centrality parameter λ . Multiply both sides of (11) by $T / (1 + \hat{\theta}_p^2)$. Then Proposition 1 is equivalent to

$$H_0 : \lambda \leq \frac{T \theta_p^2 (\rho^{-2} - 1)}{1 + \hat{\theta}_p^2}, \quad (17)$$

which establishes an upper-bound on the non-centrality parameter.

If $\rho = 1$, then $\lambda = 0$, meaning that under Corollary 1, Q follows a central F distribution. In this case, a test of (13) follows immediately because Q is stated entirely in terms of observable quantities. Suppose, instead, that $\rho < 1$. Then, consider conducting a test of $\rho > \bar{\rho}$ conditional on a value for θ_p by evaluating (17) given $\bar{\rho}$ and θ_p to obtain a value for λ which, in turn, can be used in the aforementioned noncentral F test. Shanken (1987) follows this approach. In addition, for a given significance level α , consider finding $\bar{\rho}$ such that the p-value from the non-central F test equals α . Then, $\bar{\rho}$ is the maximum correlation that satisfies Proposition 1 at a significance level of α (for the empirical tests in section 6, $\alpha = 0.05$). Following the discussion in section 2, whether ρ_o is greater than (less than) $\bar{\rho}$ then determines whether the CAPM is rejected (not rejected).

Violations of the normality assumption for e_t are well documented in the literature.⁷ Numerous studies support Engle's (1982) Autoregressive Conditional Heteroskedasticity (ARCH) and Bollerslev's (1986) Generalized ARCH (GARCH) in security returns.⁸ Common specifications of these models assume e_t to be conditionally normal, which (as demonstrated by Milhoj (1985) or Bollerslev (1986)) results in the unconditional distribution of e_t being leptokurtic, although the standardized residuals of e_t are still shown to be non-normal empirically. In light of these findings, the potential for mean-variance efficiency tests like those just described to be sensitive to the normality assumption motivated the search for more robust testing methods. From the results of

⁷See Mandelbrot (1963) and Fama (1965) as early examples.

⁸Bodurtha and Mark (1991) find evidence of ARCH in a conditional test of the CAPM.

section 2, it is apparent that normality is not necessary for deriving data-dependent restrictions implied by mean-variance efficiency (or relative efficiency). Rather, such a condition is statistically convenient for determining the distributional properties of the resulting test statistics. With this observation in mind, MacKinlay and Richardson (1991) proposed a GMM-based test that, by construction, is distribution free and able to accommodate general forms of heteroskedasticity. These authors uncovered material differences between their approach and that of Gibbons et al. (1989) at conventional levels of significance.

A unifying restriction of both Gibbons et al. (1989) and MacKinlay and Richardson (1991) is that $\phi_t = \phi_c$. Corollary 2 illustrates how a violation of this assumption could impact a test of relative mean-variance efficiency. The testing methodology developed in the next section is robust to ϕ_t and is built upon the premise that \tilde{e}_t follows a GARCH process but one that is not, necessarily, conditionally normal.⁹

4. Econometric Methodology

An empirical investigation into Proposition 1 requires estimation of all quantities, with the exception of ρ , in (11). From the proof of Corollary 2, d is the vector of constant terms from a multivariate projection of r_t onto r_{pt} . As such, the individual elements of d can be estimated following the same approach outlined in section 3. If $\phi_t = \phi_c$, then $\Sigma_{\tilde{e}} = \Sigma_e$ and can also be estimated in the manner described under section 3. If, on the other hand, ϕ_t is stochastic, then r_{pt} is an endogenous regressor in (5). Any method for estimating (5) and, hence, $\Sigma_{\tilde{e}}$ needs to be robust to this endogeneity.

If $Cov[\tilde{e}_t, r_{pt}] \neq 0$, then (5) represents a triangular system. In general, such a system is expressed as

$$Y_{1,t} = X_t' \gamma_{1o} + Y_{2,t} \delta_o + \epsilon_{1,t} \quad (18)$$

$$Y_{2,t} = X_t' \gamma_{2o} + \epsilon_{2,t} \quad (19)$$

where $Y_{1,t}$ and $Y_{2,t}$ are observed endogenous variables; X_t is a vector of predetermined variables that can include lags of the endogenous variables, and $\epsilon_{1,t}$ and $\epsilon_{2,t}$ are unobserved errors or shocks. Let $\epsilon_t = [\epsilon_{1,t} \ \epsilon_{2,t}]'$. The term γ_{1o} refers to the true value of γ_1 , with the same interpretation holding for all other parameter values. In the context of section 2, $Y_{1,t}$ is a given excess security return, $Y_{2,t}$ a proxy to the excess market return, and X_t is inclusive of only a constant term. In general, X_t can also contain forecasting instruments, in which case (18) is analogous to (42) in section 8. In this case, it is assumed that these forecasting instruments apply to both individual security returns and the proxy return.¹⁰ Regardless of the specification for X_t , (18) and (19) are stated such that mean restrictions (e.g., zero restrictions on some of the parameters in γ_{1o}) are not available for identifying the structural form of (18). Under these conditions, the sketch of an identification method for (18) follows together with a proposed estimator. A complete treatment of identification is relegated to Appendix B. Note that (18) makes no explicit use of the error decomposition in (6), meaning that the effect of ϕ_t is considered at the level of $\epsilon_{1,t}$ and does

⁹Diebold, Im, and Lee (1989) provide evidence that market model residuals are heteroskedastic.

¹⁰In support of this assumption, it seems difficult to envision an instrument that is strongly related to a given proxy return yet wholly unrelated to an individual security return or portfolio of security returns.

not attempt to isolate or identify properties unique to ϕ_t . The functional form describing the relationship between $\epsilon_{1,t}$ and $\epsilon_{2,t}$ is sufficiently general to place only minimal constraints on the process governing ϕ_t .

Let Ω_{t-1} be the information available to investors in period $t-1$, and consider $S_{t-1} \subset \Omega_{t-1}$ that is observable to the econometrician. Assume that ϵ_t follows the definition of semi-strong GARCH given in Drost and Nijman (1993) so that

$$E[\epsilon_t | S_{t-1}] = 0, \quad E[\epsilon_t \epsilon_t' | S_{t-1}] = H_t.$$

Let

$$\text{vech}(H_t) = h_t, \quad \text{vech}(\epsilon_t \epsilon_t') = e_t.$$

Throughout this section and Appendix B, $\text{vech}(\cdot)$ denotes the matrix operator that stacks the lower triangle, including the diagonal, of a symmetric matrix into a column vector, while $\text{vec}(\cdot)$ is the matrix operator that stacks the columns of a matrix into a column vector. Consider the parameterization

$$h_t = \tilde{C}_o + A_o e_{t-1} + B_o h_{t-1}, \quad (20)$$

where \tilde{C}_o is a 3×1 column vector and A_o and B_o are both 3×3 diagonal matrices.

Assumption A1: H_t is positive definite almost surely.

A1 restricts the parameters in \tilde{C}_o , A_o , and B_o . One way to satisfy A1 is to specify h_t according to a diagonal BEKK model. The BEKK model for general multivariate GARCH processes is developed in Engle and Kroner (1995). Details on the specification appropriate for (20) are provided in Appendix B.

(20) is the bivariate analog to the GARCH(1, 1) model of Bollerslev (1986). Let $h_t = [h_{11,t} \ h_{12,t} \ h_{22,t}]'$, where $h_{ij,t} = E[\epsilon_{i,t} \epsilon_{j,t} | S_{t-1}]$ for $i, j = 1, 2$. In addition, define a_{iio} as the i th diagonal element of A_o , with an analogous definition for b_{iio} . Then, (20) specifies

$$\begin{aligned} h_{11,t} &= \tilde{c}_{1o} + a_{11o} \epsilon_{1,t-1}^2 + b_{11o} h_{11,t-1} \\ h_{12,t} &= \tilde{c}_{2o} + a_{22o} \epsilon_{1,t-1} \epsilon_{2,t-1} + b_{22o} h_{12,t-1} \\ h_{22,t} &= \tilde{c}_{3o} + a_{33o} \epsilon_{2,t-1}^2 + b_{33o} h_{22,t-1} \end{aligned}$$

This specification imposes a set of exclusionary restrictions. For instance, $\epsilon_{1,t-1} \epsilon_{2,t-1}$ is excluded from both $h_{11,t}$ and $h_{22,t}$ as are squared cross-terms (i.e., $\epsilon_{2,t-1}^2$ from $h_{11,t}$ and $\epsilon_{1,t-1}^2$ from $h_{22,t}$). In addition, all squared cross-terms are excluded from $h_{12,t}$. These exclusionary restrictions on the functional form of $h_{ij,t}$ are what identify (18). An examination of the reduced form to (20) illustrates this result.

Let $R_t = [R_{1,t} \ R_{2,t}]'$ be the reduced form errors from (18) and (19). Relating these reduced form errors to their structural form counterparts is the equation

$$\epsilon_t = \Delta_o^{-1} R_t, \quad (21)$$

where $\Delta_o = \begin{bmatrix} 1 & \delta_o \\ 0 & 1 \end{bmatrix}$. (21) can be used to solve for the reduced form of H_t . Let $H_{r,t}$ denote this

reduced form, and consider

$$vech(H_{r,t}) = h_{r,t}, \quad vech(R_t R_t') = r_t.$$

Then

$$h_{r,t} = \tilde{C}_{r,o} + A_{r,o} r_{t-1} + B_{r,o} h_{r,t-1} \quad (22)$$

is the reduced form of (20), where $A_{r,o}$ and $B_{r,o}$ are both upper triangular. Off diagonal terms in $A_{r,o}$ ($B_{r,o}$) are functions of the structural parameters in A_o (B_o) as well as the parameter δ_o from (18). For example

$$A_{r,o} = \begin{bmatrix} a_{11,ro} & a_{12,ro} & a_{13,ro} \\ 0 & a_{22,ro} & a_{23,ro} \\ 0 & 0 & a_{33,ro} \end{bmatrix}. \quad (23)$$

From (23), consider

$$\bar{A}_{r,o} = \begin{bmatrix} a_{22,ro} & a_{23,ro} \\ 0 & a_{33,ro} \end{bmatrix} = \begin{bmatrix} a_{22,o} & \delta_o (a_{33,o} - a_{22,o}) \\ 0 & a_{33,o} \end{bmatrix}. \quad (24)$$

Since an analogous partition $\bar{B}_{r,o}$ can be defined from $B_{r,o}$, δ_o is identified from the reduced-form GARCH model in (22) as

$$\delta_o = \frac{a_{23,ro} + b_{23,ro}}{(a_{33,ro} - a_{22,ro}) + (b_{33,ro} - b_{22,ro})}. \quad (25)$$

The formal identification result is stated as Proposition 2 in Appendix B.

Proposition 2.1 of Iglesias and Phillips (2004) demonstrates that if the structural errors from a triangular system follow a diagonal GARCH process like (20), the reduced form errors, while still GARCH, are no longer diagonal GARCH. (23) illustrates this result. (24) illustrates that it is precisely this departure from diagonality in the reduced form that identifies (18).

(24) also makes plain that identification of the triangular system is a direct consequence of heteroskedastic errors. Suppose $\epsilon_{2,t}$ is homoskedastic such that all autocovariances of $\epsilon_{2,t}^2$ are zero. Then δ_o is not identified. Given A1, homoskedasticity of $\epsilon_{2,t}$ implies that $a_{22,o} = a_{33,o} = 0$ (see (20) and the definition of A_o in (59)), which prevents identification to follow from functional form restrictions on the dynamics of $h_{12,t}$ for the simple reason that $h_{12,t}$ is constant.¹¹ Moreover, the proof to Proposition 2 in Appendix B demonstrates that a constant conditional covariance is not sufficient for identification. Coupled with this restriction needs to be the condition that $\epsilon_{2,t}^2$ has nonzero autocovariances.

The above identification result is a second-moment analog to exclusion restrictions for γ_{1o} . In (20), A_o and B_o impose zero restrictions on all off-diagonal elements. Suppose instead, that A_o and B_o are fully general in the sense that they contain no zero entries. Then, the number of reduced form parameters in $A_{r,o}$ ($B_{r,o}$) is less than the corresponding number of structural parameters (i.e., those in A_o (B_o) plus δ_o). As a consequence, δ_o is not identified.

The identification result sketched above can be used to define a consistent estimator for (18)

¹¹Proposition 2.6 of Engle and Kroner (1995) states that (58) is general in the sense that it includes all possible positive definite diagonal models.

and (19). In defining this estimator, two observations are important.

Observation 1: From (24), identification of δ_o depends on the conditional covariance between $\epsilon_{1,t}$ and $\epsilon_{2,t}$ as well as the conditional variance of $\epsilon_{2,t}$.

Given this observation, the proposed estimator is defined in terms of $\bar{e}_t = [\epsilon_{1,t} \epsilon_{2,t} \quad \epsilon_{2,t}^2]'$.

Observation 2: (25) can be rewritten as

$$\delta_o = \frac{a_{23,ro} + b_{23,ro}}{(a_{33,ro} + b_{33,ro}) - (a_{22,ro} + b_{22,ro})}. \quad (26)$$

The implication of this observation is that identification of δ_o depends on $\bar{A}_{r,o} + \bar{B}_{r,o}$. Separate identification of $\bar{A}_{r,o}$ and $\bar{B}_{r,o}$, while sufficient, is not necessary to identify δ_o .

Since $X_t \in S_{t-1}$, it follows from the definition of semi-strong GARCH that

$$E[X_t \otimes \epsilon_t] = 0, \quad (27)$$

where \otimes is the Kronecker product. Let \bar{A}_o be the 2×2 diagonal matrix formed from the elements a_{22o} and a_{33o} in A_o (see (20)), with \bar{B}_o being similarly defined in terms of the elements of B_o . Define $\bar{\Phi}_o = \bar{A}_o + \bar{B}_o$. In addition,

$$E[\bar{e}_t] = \bar{\sigma}_o \quad (28)$$

where $\bar{\sigma}_o = [\sigma_{12o} \quad \sigma_{22o}]'$, $\sigma_{12o} = \frac{c_{21o}c_{22o}}{1-\phi_{11o}}$ and $\sigma_{22o} = \frac{c_{22o}^2}{1-\phi_{22o}}$.¹² From (64),

$$Cov[\bar{e}_t, \bar{e}_{t-\tau}] = \bar{\Phi}_o^{\tau-1} Cov[\bar{e}_t, \bar{e}_{t-1}], \quad \tau \geq 1. \quad (29)$$

(29) relates the autocovariances from a diagonal GARCH model. Hafner (2003) demonstrates this same result for strong GARCH processes. Necessary for (29) is that \bar{e}_t be covariance stationary, which requires fourth moment stationarity for $\epsilon_{2,t}$.

Let $\psi = \{\gamma_1, \gamma_2, \delta, c_{21}, c_{22}, \phi_{11}, \phi_{22}\}$, and define Ψ as the set of all possible values for ψ . Given Corollary 3 in Appendix B, the moment conditions in (27)–(29) are uniquely satisfied at $\psi = \psi_o$. Define

$$\epsilon_{1,t} = Y_{1,t} - X_t' \gamma_1 - Y_{2,t} \delta, \quad \epsilon_{2,t} = Y_{1,t} - X_t' \gamma_2,$$

and let

$$g_1 = \widehat{E}[X_t \otimes \epsilon_t], \quad g_2 = \widehat{E}[\bar{e}_t] - \bar{\sigma}_o, \\ g_3 = \widehat{Cov}(\bar{e}_t, \bar{e}_{t-\tau}) - \bar{\Phi}_o^{\tau-1} \widehat{Cov}(\bar{e}_t, \bar{e}_{t-1}), \quad \tau \geq 2.$$

where \widehat{E} and \widehat{Cov} are estimates of the expectation and covariance operators, respectively. Let $g = [g_1 \quad g_2 \quad vec(g_3)]'$. Then Theorem 2.6 of Newey and McFadden (1994) can be used to establish

$$\widehat{\psi} = \arg \min_{\psi \in \Psi} g' W g \quad (30)$$

¹²See (59) for the definition of the constant terms in \tilde{C}_o .

as a consistent estimator, where W is a positive definite weighting matrix. (30) is the estimator for triangular systems given semi-strong GARCH developed in Prono (2008). Monte Carlo studies of $\hat{\psi}$ support this result.¹³ If $W = I$, then (30) is the single-step GMM estimator—see Hansen (1982).

Let $\zeta_{ii}^2 = E \left[(\epsilon_{i,t} \epsilon_{2,t} - \sigma_{i2})^2 \right]$ for $i = 1, 2$, and define $\tilde{\zeta}_{ii}$ as a preliminary estimate of ζ_{ii} . Construct $\tilde{Z} = \begin{bmatrix} \tilde{\zeta}_{11} & 0 \\ 0 & \tilde{\zeta}_{22} \end{bmatrix}$. Suppose X_t is a $k \times 1$ vector, and consider the following alternative weighting matrix:

$$W(\tilde{Z}) = \begin{bmatrix} I_{2k \times 2k} & \cdots & 0 \\ \vdots & I_{2 \times 2} & \vdots \\ 0 & \cdots & (\tilde{Z} \otimes \tilde{Z})^{-1} \end{bmatrix}. \quad (31)$$

The weights $(\tilde{Z} \otimes \tilde{Z})^{-1}$ impact the moments that define the autocovariances of \bar{e}_t (i.e., g_3), transforming these autocovariances into autocorrelations. Prono (2008) documents improved finite sample properties of (30) if $W = W(\tilde{Z})$ as opposed to $W = I$. For this reason, estimation of (18) and (19) is based on (30) with $W = W(\tilde{Z})$.

Application of (30) to the N separate structural equations implied by (5) produces consistent estimates of the N elements in \bar{e}_t , which can then be used to estimate $\Sigma_{\bar{e}}$. To close this section, $\hat{\theta}_p = \frac{\hat{E}[r_{pt}]}{\hat{\sigma}_{22}}$.

5. Test Methodology

The inequality restriction in (11) is equivalent to

$$H_o : \rho \leq \sqrt{\frac{1}{1 + \theta_p^2 d' \Sigma_{\bar{e}}^{-1} d}} \quad (32)$$

which identifies an upper bound for ρ , since ρ is strictly positive. Define $\xi \equiv \sqrt{\frac{1}{1 + \theta_p^2 d' \Sigma_{\bar{e}}^{-1} d}}$. Section 4 outlines a methodology for obtaining $\hat{\xi}$. An analogous approach to Shanken (1987) would be to determine the distribution (either asymptotic or exact) of ξ so that a test of $\xi > \bar{\xi}$ could be conducted. For a given significance level α , the value of $\bar{\xi}$ that produces a p-value from that distribution equal to α is then the maximum correlation supporting Proposition 1. A comparison of $\bar{\xi}$ to ρ_o determines whether the CAPM is rejected (not rejected) depending on whether the inequality is $<$ ($>$). Determining a distribution for ξ , however, would be difficult, owing, in no small part, to the heteroskedastic properties assumed for \bar{e}_t that permit its identification. An alternative approach would be to bootstrap a standard error for $\hat{\xi}$ and use this standard error to determine $\bar{\xi}$. This paper adopts the alternative methodology.

Bootstrapping a standard error for $\hat{\xi}$ requires resampling from the N excess security returns and the excess proxy return used to form the quantities $\hat{\theta}_p$, \hat{d} , and $\hat{\Sigma}_{\bar{e}}$. Such is a nontrivial exercise

¹³These studies were presented in an earlier version of this paper and are available upon request.

since these returns are not iid and, in fact, their departure from independence (both within and across return series) is a key assumption underlying the estimator that generates $\widehat{\Sigma}_{\tilde{\epsilon}}$. Define

$$\epsilon_t^{(i)} = \begin{bmatrix} \epsilon_{i,t} & \epsilon_{\tilde{2},t} \end{bmatrix}', \quad i = 1, \dots, N,$$

where $\epsilon_{i,t} = Y_{i,t} - \gamma_{io} - Y_{\tilde{2},t} \delta_{io}$, the errors from the structural equation for the i th security return ($Y_{\tilde{2},t}$ is the proxy return), and $\epsilon_{\tilde{2},t}$ is the demeaned proxy return. Suppose that

$$\epsilon_t^{(i)} = \left(H_t^{(i)} \right)^{1/2} V_t^{(i)}, \quad (33)$$

where $H_t^{(i)}$ is the conditional variance-covariance matrix for the i th security return and the proxy return parameterized according to (20), and $V_t^{(i)} = \begin{bmatrix} V_{i,t} & V_{\tilde{2},t} \end{bmatrix}'$. The vector $V_t^{(i)}$ is assumed to be iid with mean zero and identity variance-covariance matrix. (33) defines a strong GARCH process. Unlike most applications of strong GARCH, however, no particular distribution is assumed for $V_t^{(i)}$. The estimator in (30) supplies $\widehat{\epsilon}_t^{(i)}$. Conditional on this estimate, one can obtain $\widehat{H}_t^{(i)}$. As a result, $\widehat{V}_t^{(i)} = \left(\widehat{H}_t^{(i)} \right)^{-1/2} \widehat{\epsilon}_t^{(i)}$. Bootstrap samples are drawn from $\widehat{V}_t^{(i)}$. Let $\widehat{V}_t^{(i)*}$ be a bootstrap sample. Then $\widehat{\epsilon}_t^{(i)*} = \left(\widehat{H}_t^{(i)*} \right)^{1/2} \widehat{V}_t^{(i)*}$, where $\widehat{H}_t^{(i)*}$ is based upon parameter estimates from the original sample, and

$$\widehat{Y}_{\tilde{2},t}^* = \widehat{\gamma}_{\tilde{2}} + \widehat{\epsilon}_{\tilde{2},t}^*, \quad (34)$$

$$\widehat{Y}_{i,t}^* = \widehat{\gamma}_i + \widehat{Y}_{\tilde{2},t}^* \widehat{\delta}_i + \widehat{\epsilon}_{i,t}^*, \quad i = 1, \dots, N, \quad (35)$$

where $\widehat{\gamma}_{\tilde{2}}$, $\widehat{\gamma}_i$, and $\widehat{\delta}_i$ are also obtained from the original sample. The resulting bootstrap series is then used to estimate $\widehat{\xi}^*$ given the estimation method described in section 4.

Define E^* as the expectation operator relative to the distribution of the bootstrap sample conditional on the original sample, and let

$$g = \frac{1}{T} \sum_{t=1}^T g_t.$$

Following Hall and Horowitz (1996), the bootstrap version of the moment conditions in (30) is

$$g_t^* = g_t - E^* \widehat{g}_t, \quad (36)$$

where \widehat{g}_t is g_t evaluated at $\widehat{\psi}$, the parameter estimates from the original data sample. (36) recenters the bootstrap moment conditions such that $E^* g_t^* = 0$. In general, $E^* g_t \neq 0$ when the number of moment conditions exceeds the number of parameters in ψ . If g_t is used as the moment conditions instead of g_t^* , then $\widehat{\psi}^*$ will have different asymptotic properties than $\widehat{\psi}$. In order to avoid this discrepancy,

$$\widehat{\psi}^* = \arg \min_{\psi \in \Psi} g^{*'} W^* g^*, \quad (37)$$

where $W^* = W(\tilde{Z}^*)$, the bootstrap analog to (31). The bootstrap standard error of $\hat{\xi}$ is based on $\hat{\psi}^*$.

Given a standard error for $\hat{\xi}$, the asymptotic t statistic

$$\hat{\tau} = \frac{\hat{\xi} - \bar{\xi}}{\widehat{se}(\hat{\xi})} \quad (38)$$

can be constructed to test $\hat{\xi} > \bar{\xi}$. This statistic is asymptotically pivotal with an asymptotic distribution assumed to be well approximated by a standard normal.¹⁴ As a result, for $\alpha = 0.05$, the value of $\bar{\xi}$ can be determined such that $\Phi(\hat{\tau}) = \alpha$.

According to MacKinnon (2007), bootstrapping (38) will generally lead to an asymptotic refinement. Such a practice is referred to as the double or iterated bootstrap. Implementing the double bootstrap, however, is very computationally expensive. For example, define B_1 as the number of bootstrap iterations used to generate $\widehat{se}(\hat{\xi})$ and B_2 as the number of iterations used to generate the bootstrap distribution of (38). If $B_1 = B_2 = 1000$, then the total number of iterations required for the double bootstrap is approximately 1 million. Given the size of the data samples used to construct $\hat{\xi}$ (see section 6), the standard normal will likely provide a descent approximation to the asymptotic distribution of (38). A Monte Carlo study (see section 7) verifies this claim. As a result, this approximation is used as opposed to the double bootstrap alternative.

6. Test Results

All tests are conducted using size, B/M, and momentum portfolios. The returns are measured weekly (in percentage terms) from 10/6/67 through 9/28/07. Test results consider 20- and 10-year subperiods of this overall date range. The daily 25 size-B/M and 25 size-momentum return files (each 5×5 sorts with breakpoints determined by NYSE quintiles) formed from all securities traded on the NYSE, AMEX, and NASDAQ exchanges are used to construct the weekly return series.¹⁵ Monte Carlo studies of (30) reveal sizable benefits in terms of reduced finite sample bias and increased efficiency from using large sample sizes due to the fact that higher moments are being estimated. In light of this finding, weekly returns are utilized. Further supporting this frequency choice is the fact that weekly returns reduce day-of-the-week and weekend effects as well as the effects of nonsynchronous trading and bid-ask bounce. The size portfolios considered are "Small," "Mid," and "Large." "Small" is the average of the five low-market-cap portfolios, "Mid" the average of the five medium-market-cap portfolios, and "Big" the average of the five large-market-cap portfolios. The B/M portfolios considered are "Value," "Neutral," and "Growth." "Value" is the average of the five high-B/M portfolios, "Neutral" the average of the five middle-B/M portfolios, and "Growth" the average of the five low-B/M portfolios.¹⁶ Finally, the momentum portfolios considered are "Losers," "Draws," and "Winners." "Losers" is the average of the five

¹⁴From MacKinnon (2007), "a test statistic is asymptotically pivotal if its asymptotic distribution does not depend on anything that is unknown" (p.5).

¹⁵These return files are available on Kenneth French's website.

¹⁶Definitions for the "Small," "Large," "Value," and "Growth" portfolios are taken from Lewellen and Nagel (2006).

low-return-sorted portfolios, "Neutral" the average of the five middle-return sorted portfolios, and "Winners" the average of the five high-return-sorted portfolios. The proxy return is the CRSP value-weighted index return formed from all securities traded on the NYSE, AMEX, and NASDAQ exchanges. The risk-free rate is the one-month Treasury bill rate from Ibbotson Associates.

The tests focus on (17) and (32). The former is conducted following the approach developed in Gibbons, Ross, and Shanken (1989), referred to hereafter as GRS, that is implemented in Shanken (1987) described in section 3. The latter is conducted following the approach of section 5 under two cases: (1) $\phi_t = \phi_c$, (2) ϕ_t is stochastic. Case 1 will be referred to as Bootstrap Proposition 1 constant (BPC), while case 2 will be referred to as Bootstrap Proposition 1 stochastic (BPS). The only difference in implementation between BPC and BPS is that under the former, OLS regressions estimate the relationship between security returns and the proxy while, under the latter, this relationship is estimated using (30) and its bootstrap analog in (37). A comparison of BPC to GRS evidences the effects of conditional heteroskedasticity on a test of relative mean-variance efficiency. A comparison of BPC to BPS evidences the effects of relating security returns to the proxy return via a projection as opposed to a structural equation. When implementing BPS, the number of lags used in (30) is set to $\tau = 4$. The choice of this lag length is motivated by the frequency of returns as well as the finding in Prono (2008) that higher lag lengths, while successful at reducing the variability of $\hat{\psi}$ also increases the finite sample bias. Finally, all bootstrap routines are conducted over 1000 trials.

Table 1 (A and B) and 2 (A and B) summarizes results from two 20-year subperiods: (1) 10/6/67 - 9/25/87, (2) 11/6/87 - 9/28/07. Tables 1A and 2A provide summary statistics of the returns used in the tests as well as the alpha proxies (accompanied with heteroskedasticity-corrected standard errors) from individual OLS regressions of those returns on the proxy. Tables 1B and 2B describe the maximum correlation between the proxy return and the market return that still supports the CAPM result at a 5% significance level according to the GRS, BPC, and BPS tests. Recall that all three tests are based on the inequality restriction in (11). If $\rho < 1$, then a test of this restriction requires a prior belief on the true value of the correlation ρ_o . From Roll (1977), $\rho_o = 0.90$ or above. This value will be used throughout the discussions of the test results.

For the GRS test, if $\rho < 1$, then a test of (17) also requires the true value of θ_p . Possible values for θ_p are taken from Shanken (1987). $\theta_p = 0.52$ is the most likely (or expected) value. $\theta_p = 0.22$ and $\theta_p = 0.86$ are - 1 standard deviations and + 2 standard deviations away from this expected value, respectively. All values of θ_p are annualized for presentation but expressed in weekly terms when used in the tests. Assuming an annual standard deviation of 20% for the proxy return, $\theta_p = 0.22$ corresponds to a "market" premium of 4.4%, $\theta_p = 0.52$ a "market" premium of 10.4%, and $\theta_p = 0.86$ a "market" premium of 17.2%.¹⁷ This range for θ_p is sufficiently wide to encompass the point estimates for θ_p implied by the different subperiods considered. Finally, $\theta_p = 1.00$ is also reported as a value for the proxy Sharpe ratio that is greater than any conceivable true value.

Since (17) requires θ_p to be known, for comparative purposes θ_p is treated as known in (32) for the BPC and BPS tests. In addition, however, θ_p is also treated as unknown in the latter two tests, meaning that its value is bootstrapped along with every other random quantity in $\hat{\xi}$. In the tables, the heading "unknown" under Panel F: BPC and Panel G: BPS details the results of this

¹⁷By "market" premium, what is meant is the market premium implied by the proxy.

more general treatment.

Under Tables 1B and 2B, note that (1) the projection errors appear to be non-normal, characterized by (at times) significant skewness and (often times) excess kurtosis, and (2) there exist apparent differences between the projection and structural errors. These two findings foreshadow differences between the GRS, BPC, and BPS tests. Also under Tables 1B and 2B, a comparison of the maximum correlations for known values of θ_p between the GRS and BPC tests reveals the general tendency of higher correlations implied by the former. Such a tendency implies that the former test will tend to under-reject the CAPM relative to the latter. MacKinlay and Richardson (1991) document a similar finding in their empirical work. As an example, for the period 10/6/67 - 9/25/87 at $\theta_p = 0.52$, $\bar{\rho} = 0.86$ according to GRS but $\bar{\rho} = 0.74$ according to BPC. For the period 11/6/87 - 9/28/07, the same comparison yields $\bar{\rho} = 1.00$ according to GRS as opposed to $\bar{\rho} = 0.93$ according to BPC. This latter comparison possesses economic significance since the former cannot reject mean-variance efficiency of the proxy (see Corollary 1), while the latter can. When comparing GRS and BPC across the two 20-year time periods, the largest differences in relative efficiency occur for the size portfolios. The B/M portfolios show a similar directional difference, though on a more muted scale. For both 20-year time periods, the maximum correlations measured relative to the momentum portfolios are higher for BPC than for GRS. The difference between these correlations, however, is small.

A comparison of the maximum correlations for constant values of θ_p between the BPC and BPS tests supports the results of Corollary 2. These correlations are generally higher under the latter. The largest correlation difference between BPC and BPS occurs for the size portfolios in the second 20-year time period for $\theta_p = 0.22$. In this case, $\bar{\rho} = 0.64$ under BPC, while $\bar{\rho} = 0.86$ under BPS. Also in the second 20-year period, positive correlation differences between the BPS and BPC tests are apparent across all values of θ_p for the B/M and momentum portfolios.

Treating θ_p as unknown under BPS offers the most general test considered and is the principal contribution of this paper to relative efficiency testing. In contrast, the GRS method requires θ_p to be known. The most natural means of comparison between GRS and BPS with an unknown θ_p is to assume that $\theta_p = \hat{\theta}_p$ (the sample-specific estimate of θ_p) for the former, since $\hat{\theta}_p$ is the point estimate around which bootstrap samples are generated. For the first 20-year time period, $\hat{\theta}_p = 0.22$ while for the second, $\hat{\theta}_p \approx 0.52$. In the second 20-year time period, therefore, $\bar{\rho} = 0.54$ under GRS as compared to $\bar{\rho} = 0.75$ under BPS for the momentum portfolios. The former result implies that the proxy return explains less than 30% of the variation in the market return ($0.54^2 = 0.29$), while the latter implies that the proxy return accounts for over 55% of the variation in the market return. In this case, GRS rather significantly understates the relative efficiency of the proxy return when compared to BPS. An inference from this result is that the GRS test will tend to over-reject the CAPM prediction. Understatement of the relative efficiency of the proxy return by GRS when compared to BPS (with an unknown θ_p) is consistent across both time periods and for all portfolios considered. The difference in the implied mean-variance location of the proxy portfolio can be striking. For instance, $\bar{\rho}$ is 59% and 64% higher according to BPS when compared to GRS for the B/M and momentum portfolios, respectively, in the first 20-year time period.

The BPS test with an unknown θ_p cannot reject the null hypothesis that the proxy return is mean-variance efficient for size portfolios in the most-recent 20-year period. Otherwise, the test results do not speak favorably for the CAPM. If $\rho_o = 0.90$, then the result of Proposition 1 is rejected for all remaining time periods and portfolios. The CAPM fares decidedly worse on B/M and

momentum portfolios relative to size portfolios and performs the poorest on momentum portfolios. A potential bright-spot emerges when comparing results between the two time periods. The size of the CAPM errors for all the portfolios considered is greatly reduced in the most-recent period, since the implied correlations very nearly double. This paper, therefore, documents a significant increase in the ability of the CAPM to price expected returns post the 1987 market crash.

As a robustness check, the GRS, BPC, and BPS tests are also applied to three 10-year subperiods: (1) 10/7/77 - 9/25/87, (2) 11/6/87 - 9/26/97, (3) 10/3/97 - 9/28/07.¹⁸ Tables 3 (A and B) through 5 (A and B) summarize the results. These results are largely consistent with those for the two 20-year subperiods discussed above. Namely, for constant values of θ_p , GRS tends to imply higher correlations than BPC, and BPC tends to imply lower correlations than BPS. In addition, GRS when evaluated at $\theta_p = \hat{\theta}_p$ tends to imply lower correlations than BPS evaluated with an unknown θ_p . Moreover, significant differences between the tests continue to be evidenced. For example, during the period 11/6/87 - 9/26/97, the GRS test rejects the CAPM prediction at all levels of θ_p for the B/M portfolios. The BPS test with an unknown θ_p , on the other hand, does not. During the period 10/3/97 - 9/28/07, also for the B/M portfolios, the GRS test fails to reject the CAPM at all levels of θ_p , while the BPS test with an unknown θ_p offers a sound rejection.

7. Monte Carlo

The previous section establishes that inferences on the relative efficiency of a given proxy return can be sensitive to the test considered. This section investigates the source of these differences. For instance, do these differences signal the inappropriateness of a normality assumption for the proxy return and the innovations to individual security returns? Do they signal the inappropriateness of projecting security returns onto the proxy return? Alternatively, do they reflect poor finite sample performance of the GMM estimator in (30) or the fact that the asymptotic distribution of the test statistic in (38) is not well approximated by a standard normal?

In order to assess these possibilities, consider a Monte Carlo study of the following design. From (33), with $N = 3$ let the individual components of $V_t^{(i)}$ be distributed as standardized Gamma(2,1) random variables, and parameterize $H_t^{(i)}$ using the estimates obtained for the B/M portfolios over the period 11/6/87 - 9/28/07 that do not assume $h_{i2,t} = 0$.¹⁹ Further, let $\hat{\gamma}_{\tilde{2}}$ and $\hat{\delta}_i$ from (34) and (35), respectively, be obtained from (30) applied to the same data set mentioned above, and consider $\hat{Y}_{\tilde{2},t}^*$ and $\hat{Y}_{i,t}^*$ to be a simulated proxy return and i th individual security return, respectively. Consider the pricing restriction of (11) stated in terms of estimated quantities. Conditional on $\hat{H}_t^{(i)}$, $\hat{\gamma}_{\tilde{2}}$, and $\hat{\delta}_i$, $\hat{\gamma}_i$ in (35) is set so that the individual components of \hat{d} are equal and support $\rho = 0.90$.²⁰ Therefore, the data generating process (DGP) considered in this study supports

¹⁸The period 10/6/67 - 9/30/77 is not considered because the mean of the proxy return is negative.

¹⁹The Gamma(2,1) distribution is chosen because, when combined with $\hat{H}_t^{(i)}$, this distribution produces errors with unconditional skewness and kurtosis measures comparable to those described under Panel D for the B/M portfolios of Table 2B.

²⁰From (64),

$$\hat{\gamma}_i = \hat{d}_i + \hat{\eta}_i \hat{E} [r_{p,t}].$$

Let $\hat{d}_i = \hat{d}_j \forall i, j = 1, 2, 3$. From the B/M portfolios and proxy return measured over the period 11/6/87 - 9/28/07, \hat{d}_i is calibrated such that $\rho = 0.90$ if (11) is treated as an equality. $\hat{\eta}_i$ is the slope parameter from an OLS regression of $\hat{\epsilon}_{i,t}$ on $Y_{\tilde{2},t}$. $\hat{E} [r_{p,t}]$ is the sample mean of $Y_{\tilde{2},t}$.

the CAPM.

Given the DGP described above, this study examines the rejection rates of the GRS, BPC, and BPS tests at 10%, 5%, and 1% significance levels when either $\bar{\rho}$ or $\bar{\xi}$ is set equal to 0.90. For the GRS test, θ_p is assumed to be known and is set equal to the estimate from the original sample. For the BPC and BPS tests, θ_p is treated as unknown. For all three test statistics, simulations are conducted across 500 trials generating excess return series of 1000 observations each. When constructing the individual excess return series for each trial, the first 200 observations are dropped to avoid initialization effects. For the BPC and BPS statistics, within each simulation trial a bootstrap of $\hat{\xi}$ is conducted over 250 repetitions.²¹ Parameter estimates for implementing these routines do not vary by simulation trial. These parameter estimates are generated from the original data sample in the manner described above, although in the case of the BPC statistic, the additional constraint of $h_{i2,t} = 0$ is imposed.

Table 6 reports the simulation results. Both the GRS and BPC statistics over-reject the null hypothesis that ρ is at least 0.90 or, equivalently, that the CAPM holds. Across the size levels considered, the GRS statistic over-rejects more than does the BPC statistic. Simulation studies of Zhou (1993) and Chou (1996) show that the GRS statistic tends to over-reject the null hypothesis of an efficient proxy return (i.e., that $\rho = 1$) when the distribution of the errors to the market model (see (5)) is non-elliptical.²² The results presented here compliment those of Zhou (1993) and Chou (1996) by showing that the tendency for GRS to over-reject extends to tests of relative efficiency where temporal dependence is the factor governing the non-elliptical nature of the error distributions.

In general, the BPS statistic is appropriately sized. A tendency for under-rejecting the null hypothesis is evident at the 10% significance level, but this tendency is modest and is no larger in absolute value than the size distortions evidenced by the other two tests.²³ No such tendency (in either direction) is meaningfully evidenced at either the 5% or 1% significance levels. As a result, it does not appear that poor finite sample performance of the GMM estimator and/or poor approximation of the asymptotic distribution of the test statistic by a standard normal meaningfully distorts the size of the BPS test. In addition, results from the BPC and BPS tests support the finding of Corollary 2 that describing the relationship between security returns and the proxy in terms of a linear projection leads to an over-rejection of the CAPM in cases where $\phi_t \neq \phi_c$. Finally, from Table 2B, note that the maximum correlations determined by the GRS, BPC, and BPS statistics are 0.73, 0.824, and 0.841, respectively.²⁴ The rank order of these maximum correlations is supported by the simulation results.

8. Extension

This section generalizes Proposition 1 in terms of conditional moment restrictions and, in doing so, links mismeasurement of the market return to time-variation in "beta." In order to develop this

²¹The test results bootstrap $\hat{\xi}$ for 1000 repetitions. Only 250 repetitions are considered here in order to keep the simulation time feasible. This truncated number of repetitions should still produce a decent estimate of the standard error.

²²The method proposed by Zhou (1993) requires the error distributions to be specified, while Chou (1996) utilizes a bootstrap approach, but one where temporal independence is assumed.

²³Chou (1996) reports similar size distortions at a 10% level for bootstrap tests of mean-variance efficiency.

²⁴For the GRS test, $\theta_p = \hat{\theta}_p = 0.52$. For both the BPC and BPS tests, θ_p is unknown.

generalization, moments for period t conditional on S_{t-1} are labeled with a t subscript as are parameters conditional on S_{t-1} . Consider the following conditional pricing model

$$E_t[r_t] = Cov_t[m_t, r_t], \quad (39)$$

and assume

$$m_t = \left(\frac{E_t[r_{mt}]}{\sigma_t^2[r_{mt}]} \right) r_{mt} \quad (40)$$

so that (39) represents a conditional statement of the CAPM.²⁵ In addition, assume that

$$\beta = \frac{Cov_t[r_{mt}, r_t]}{\sigma_t^2[r_{mt}]} \quad (41)$$

so that market betas are constant parameters and time variation in expected security returns are driven by changes in the market risk premium. Ferson (1990) asserts that the specification of constant betas "is an important assumption in the context of models with conditional expectations" (p.399).²⁶

Consider the following generalization of (5):

$$r_t = \gamma_t + \delta r_{pt} + \tilde{e}_t \quad (42)$$

where

$$\gamma_t = \alpha + \beta E_t[\phi_t], \quad \tilde{\phi}_t = \phi_t - E_t[\phi_t].$$

A case for $Cov[\tilde{e}_t, r_{pt}] \neq 0$ follows the same logic outlined in section 2. (42) affords a general specification for the time-varying mean of security returns.²⁷ This time variation is linked to time variation in both the expected proxy return and the expected value of the components omitted from that proxy return. In the special case where $\phi_t = \phi_c$, the source of this time variation is limited to the expected proxy return.

Next, consider a linear projection of m_t onto r_{pt} conditional on S_{t-1} :

$$m_t = a + b_t r_{pt} + e_{mt}, \quad (43)$$

where

$$b_t = \frac{Cov_t[r_{pt}, m_t]}{\sigma_t^2[r_{pt}]}.$$

Assume that the correlation between m_t and r_{pt} is constant or, equivalently, that the relative ef-

²⁵Harvey (1989), Bodurtha and Mark (1991), Jagannathan and Wang (1996), Lettau and Ludvigson (2001), Adrian and Franzoni (2004), and Ang and Chen (2007) all consider versions of the CAPM in this form.

²⁶In nearly all cases, a conditionally mean-variance efficient portfolio will exist, implying that so too will a single beta model for expected returns. In general, the beta from this model will be time-varying.

²⁷There is a consensus in the literature that expected returns are time-varying conditional on a set of forecasting instruments. Potential instruments include (i) lagged values of the proxy return to capture reversion as evidenced in Keim and Stambaugh (1986) and Fama and French (1989) among others, (ii) the term spread as measured by the difference between the 10-year and 3-month yields and advocated by Fama and French (1989), (iii) Moody's BAA - AAA credit spread (see, e.g. Campbell (1996), and (iv) the value spread as measured by the return difference between value and growth stocks (see Campbell and Vuolteenaho (2004)).

efficiency of the proxy return is constant.²⁸ Then, a straightforward generalization of Lemma 1 in Appendix A grants that

$$Cov_t [\tilde{e}_t, e'_{mt}] \Sigma_{\tilde{e}_t}^{-1} Cov_t [\tilde{e}_t, e_{mt}] \leq \sigma_t^2 [m_t] (1 - \rho^2) \quad (44)$$

where $\Sigma_{\tilde{e}_t}^{-1}$ is the variance-covariance matrix of \tilde{e}_t conditional on S_{t-1} . Given (44), an equally straightforward generalization of Proposition 1 can be stated as

Proposition 3 *Let the pricing model of (39) and (40) hold for all security returns including the proxy return, and consider the structural relationship between security returns and the proxy return as given by (42). Define*

$$\theta_{pt} = \frac{E_t [r_{pt}]}{\sigma_t [r_{pt}]}$$

and

$$\eta_t = \frac{Cov_t [\tilde{e}_t, r_{pt}]}{\sigma_t^2 [r_{pt}]}.$$

Then,

$$d' \Sigma_{\tilde{e}_t}^{-1} d \leq \theta_{pt}^2 (\rho^{-2} - 1) \quad (45)$$

where

$$d = E_t [r_t] - (\delta + \eta_t) E_t [r_{pt}].$$

Proof. See the proof of Proposition 1 in Appendix A, and condition the moments contained therein on S_{t-1} . ■

The deviation vector d from Proposition 3 is a N -vector of constant terms from the following model of r_t :

$$r_t = d + (\delta + \eta_t) E_t [r_{pt}] + u_t \quad (46)$$

where $E_t [u_t] = 0$.²⁹ From (54) and (55), it follows that the vector of time-varying beta proxies $\beta_{pt} = \delta + \eta_t$. (46) relates time-varying expected security returns to time-varying beta proxies and a time-varying expected proxy return. Proposition 3 establishes an upper bound on deviations from conditional CAPM pricing measured with respect to a proxy return. Given a time path for the Sharpe performance measure of the proxy return, this upper bound is set in terms of the efficiency of that proxy return relative to the market return. Suppose $\phi_t = \phi_c$. Then (42) is a projection of r_t onto r_{pt} . In this case, beta proxies are not time varying since $\eta_t = 0$, and time variation in expected security returns is the result of a time-varying expected proxy return.

Works by Harvey (1989), Bodurtha and Mark (1991), and more recently Adrian and Franzoni (2004) and Ang and Chen (2007) consider time-varying betas for the CAPM. Adrian and Franzoni (2004) and Ang and Chen (2007) stress time-varying betas as meaningful contributors to the improved performance of conditional specifications of the CAPM relative to their unconditional counterparts. By definition, all of these works measure time-variation in betas with respect to a

²⁸Conditioning the right-hand-side of (51) on S_{t-1} and substituting the expression for $\sigma_t [m_t]$ from (40) produces this latter result.

²⁹Noting that $\frac{Cov_t [r_t, r_{pt}]}{\sigma_t^2 [r_{pt}]} = \delta + \eta_t$ given (42), (46) is a vector statement of (4) in Bodurtha and Mark (1991).

proxy return. In the context of Proposition 3, the finding of Adrian and Franzoni (2004) and Ang and Chen (2007) can be interpreted as supporting evidence of a nonzero covariance between \tilde{e}_t and r_{pt} .

Like its unconditional counterpart, Proposition 3 provides an explanation for the empirical discovery of "significant" alphas that does not invalidate the CAPM theory. In addition, Proposition 3 provides an explanation for the significance of time-varying betas in pricing expected security returns. Like Proposition 1, a principal strength behind Proposition 3 is that with the exception of ρ , all of the quantities in (45) can be directly estimated from observable data. This fact sets up an indirect test of the conditional CAPM in analogous terms to those described in sections 2 and 5. Of course, the set S_{t-1} needs to be specified, as does the relationship of this set to expected proxy returns and the expected value of components omitted from that proxy return.

9. Conclusion

This paper develops a new test of the CAPM that accounts for a proxy's mismeasurement of the market return both in terms of the former's relation to the latter as well as the former's relation to the assets it is assumed to price. For a given collection of test assets, conventional investigations of the CAPM prediction based upon the relative mean-variance efficiency of a given proxy estimate the linear relationship between the returns on those test assets and the return on the proxy by a projection of the former onto the latter. This paper demonstrates that estimating such a projection equation is not without loss of generality. The returns to nontraded assets and the returns to human capital are omitted from common "market"-based proxies. The extent to which these returns correlate with a given proxy will determine the extent to which innovations to the linear equation describing returns to the test assets conditional on the proxy return will tend to covary with the proxy return. The resulting structural equation will necessarily differ from the projection equation. A novel estimator is proposed for this structural equation that does not require outside instruments. This estimator is then used to show that the proposed test of relative mean-variance efficiency built upon the aforementioned structural equation differs in economically significant ways from competing tests based upon the projection equation. In particular, the competing tests over-reject the CAPM prediction because these tests ignore the effects of omitted components from the market return on the linear relationship between test asset returns and the proxy return.

An extension of the pricing restriction implied by a mismeasured market return to conditional moments separates the beta measured against a proxy return into a constant and a time-varying component. Time-variation in the second component is sourced to securities omitted from the proxy. Measuring this time-variation is central to evaluating the performance of a conditional CAPM where movements in beta significant to the pricing of expected returns are caused by mismeasurement of the market return. The estimator described in section 4 treats the parameters governing the conditional covariance matrix as nuisance parameters and only estimates composite functions of these parameters. Given the specification of η_t (the term effecting time-variation in beta measured against the proxy return) in Proposition 3, a complete treatment of the conditional covariance between the market model residuals and the proxy return as well as the conditional variance of the proxy return is necessary to render the result of Proposition 3 testable. Future research will develop such an estimator while maintaining the assumption of semi-strong GARCH. As a result, the estimator will continue to be based upon the autocorrelation process of the squares

and cross-products of the structural errors to the triangular system. With the aid of this estimator, the performance of the conditional pricing restriction in Proposition 3 as measured by $\bar{\rho}$ will be compared against (1) the unconditional pricing restriction of Proposition 1 and (2) alternative pricing models like the three-factor model of Fama and French (1993), which can be readily stated in the terms of Proposition 2 in Shanken (1987).

Appendix A

Lemma 1 Consider the structural model in (5) and the linear projection in (7). Then

$$Cov [\tilde{e}_t, e_{mt}]' \Sigma_{\tilde{e}}^{-1} Cov [\tilde{e}_t, e_{mt}] \leq \sigma^2 [m_t] (1 - \rho^2)$$

where $\Sigma_{\tilde{e}}$ is the $N \times N$ covariance matrix of \tilde{e}_t , and ρ is the correlation between m_t and r_{pt} .

Proof. Since (7) describes a linear projection of m_t onto r_{pt} , $b = \frac{Cov[r_{pt}, m_t]}{\sigma^2[r_{pt}]}$ and $\sigma^2 [e_{mt}] = \sigma^2 [m_t] (1 - \rho^2)$. Consider regressing e_{mt} on \tilde{e}_t . The explained variance from that regression is $Cov [\tilde{e}_t, e_{mt}]' \Sigma_{\tilde{e}}^{-1} Cov [\tilde{e}_t, e_{mt}]$, which cannot be greater than $\sigma^2 [m_t] (1 - \rho^2)$, the total variance of e_{mt} . ■

Proof of Proposition 1 Substitution of (5) into the right-hand-side of (1) produces

$$Cov [r_t, m_t] = \delta Cov [r_{pt}, m_t] + Cov [\tilde{e}_t, m_t]. \quad (47)$$

Given (7),

$$Cov [\tilde{e}_t, m_t] = \left(\frac{Cov [\tilde{e}_t, r_{pt}]}{\sigma^2 [r_{pt}]} \right) Cov [r_{pt}, m_t] + Cov [\tilde{e}_t, e_{mt}]. \quad (48)$$

Combining (47) and (48) produces

$$Cov [r_t, m_t] = (\delta + \eta) Cov [r_{pt}, m_t] + Cov [\tilde{e}_t, e_{mt}],$$

where η is defined in (10). Substituting the result into (1) grants the following inequality,

$$d' \Sigma_{\tilde{e}}^{-1} d \leq \sigma^2 [m_t] (1 - \rho^2) \quad (49)$$

where

$$d = E [r_t] - (\delta + \eta) Cov [r_{pt}, m_t]. \quad (50)$$

Next, note that given (7) and (9),

$$\sigma^2 [m_t] = \theta_p^2 + \sigma^2 [e_{mt}].$$

The coefficient of determination from (7) is, therefore, $\frac{\theta_p^2}{\sigma^2 [m_t]}$. Recall that $\rho = \frac{Cov [m_t, r_{pt}]}{\sigma [m_t] \sigma [r_{pt}]}$. Given that (1) also holds for the proxy return,

$$\rho = \frac{E [r_{pt}]}{\sigma [m_t] \sigma [r_{pt}]} = \frac{\theta_p}{\sigma [m_t]}. \quad (51)$$

As a result, the right-hand-side of (49) equals $\theta_p^2 (\rho^{-2} - 1)$. Finally, (50) can be redefined as $E [r_t] - (\delta + \eta) E [r_{pt}]$. ■

Proof of Corollary 1 Given (2) and (51), $\rho = \frac{\theta_p}{\theta_m}$. Substituting (4) into this result produces

$$\rho = \frac{E[r_{pt}]}{\phi_c + E[r_{pt}]}, \quad (52)$$

from which follows the statement that $\rho = 1$ if and only if $\phi_c = 0$. If $\rho = 1$, then $d' \Sigma_{\tilde{e}_t}^{-1} d = 0$ in (11). Since $\phi_c = 0$, $\eta = 0$ in (10), and $d = E_t[r_t] - \delta E_t[r_{pt}]$. From (5) then follows that $d = \alpha$. ■

Proof of Corollary 2 Let

$$r_t = \alpha_p + \beta_p r_{pt} + e_{pt} \quad (53)$$

be a multivariate linear projection of r_t onto r_{pt} , where α_p is an alpha proxy, β_p is a beta proxy, and e_{pt} is a projection error. Then

$$\begin{aligned} \alpha_p &= E[r_t] - \beta_p E[r_{pt}] \\ \beta_p &= \frac{Cov[r_t, r_{pt}]}{\sigma^2[r_{pt}]} \end{aligned} \quad (54)$$

Substitution of (5) into the expression for β_p yields the following relationships between the parameters in (53) and the structural parameters in (5):

$$\begin{aligned} \alpha_p &= \gamma - \eta E[r_{pt}] \\ \beta_p &= \delta + \eta \end{aligned} \quad (55)$$

where η is defined by (10). Given these relationships,

$$e_{pt} = r_t - \alpha_p - \beta_p r_{pt} = \tilde{e}_t - \eta \tilde{r}_{pt}$$

where $\tilde{r}_{pt} = r_{pt} - E[r_{pt}]$. It then follows that

$$\Sigma_{e_p} = \Sigma_{\tilde{e}} - \frac{Cov[\tilde{e}_t, \tilde{r}_{pt}] Cov[\tilde{e}_t, \tilde{r}_{pt}]'}{\sigma^2[\tilde{r}_{pt}]} \quad (56)$$

since given the definition of \tilde{r}_{pt} , $Cov[\tilde{e}_t, r_{pt}] = Cov[\tilde{e}_t, \tilde{r}_{pt}]$ and $\sigma^2[r_{pt}] = \sigma^2[\tilde{r}_{pt}]$. Substitution of the expression for \tilde{e}_t in (6) into (56) produces

$$\Sigma_{\tilde{e}} - \Sigma_{e_p} = \left(\frac{Cov[\tilde{\phi}_t, \tilde{r}_{pt}]}{\sigma[\tilde{r}_{pt}]} \right)^2 \beta \beta'. \quad (57)$$

In general, there exists an x such that $\beta'x = 0$. Let $y = \beta'x$. Then $y'y \geq 0$. ■

Appendix B

Identification of the Triangular System

Assumption A1: H_t is positive definite almost surely.

Parameterize H_t as

$$\begin{aligned}
 H_t &= C_o' C_o + \sum_{k=1}^2 A'_{ko} \epsilon_{t-1} \epsilon'_{t-1} A_{ko} + \sum_{k=1}^2 B'_{ko} H_{t-1} B_{ko} \\
 C_o &= \begin{bmatrix} c_{11o} & 0 \\ c_{21o} & c_{22o} \end{bmatrix} \\
 A_{1o} &= \begin{bmatrix} a_{11,1o} & 0 \\ 0 & a_{22,1o} \end{bmatrix}, & A_{2o} &= \begin{bmatrix} a_{11,2o} & 0 \\ 0 & 0 \end{bmatrix} \\
 B_{1o} &= \begin{bmatrix} b_{11,1o} & 0 \\ 0 & b_{22,1o} \end{bmatrix}, & B_{2o} &= \begin{bmatrix} b_{11,2o} & 0 \\ 0 & 0 \end{bmatrix}.
 \end{aligned} \tag{58}$$

The parameters c_{11o} , c_{22o} , $a_{22,1o}$, $a_{11,2o}$, $b_{22,1o}$, and $b_{11,2o}$ are strictly positive. (58) is a bivariate diagonal BEKK model. This model satisfies A1 under very weak conditions. Applying the $vech(\cdot)$ operator to both sides of (58) and then simplifying produces (22), where

$$\begin{aligned}
 \tilde{C}_o &= [c_{11o}^2 + c_{21o}^2 \quad c_{21o}c_{22o} \quad c_{22o}^2]', \\
 A_o &= \begin{bmatrix} a_{11,1o}^2 + a_{11,2o}^2 & 0 & 0 \\ 0 & a_{11,1o}a_{22,1o} & 0 \\ 0 & 0 & a_{22,1o}^2 \end{bmatrix},
 \end{aligned} \tag{59}$$

and B_o is defined analogously to A_o in terms of the elements in B_{1o} and B_{2o} .

Assumption A2: $E[X_t X_t']$ and $E[X_t Y_t']$ are finite and identified from the data. $E[X_t X_t']$ is non-singular.

Assumption A3: (i) In (20), the eigenvalues of $A_o + B_o$ are less than one in modulus. (ii) Let $a_{ij,o}$ be the element in the i th row and j th column of the matrix A_o , and similarly define $b_{ij,o}$. $a_{33,o} + b_{33,o} \neq a_{22,o} + b_{22,o}$.

A2 identifies the reduced form residuals from (18) and (19) as

$$R_{i,t} = Y_{i,t} - X_t' E[X_t X_t']^{-1} E[X_t Y_{i,t}], \quad i = 1, 2.$$

A3(i) defines h_t in (20) (or, equivalently, H_t in (58)) as mean stationary according to Proposition 2.7 of Engle and Kroner (1995). A3(ii) preserves the off-diagonal structure of the reduced form GARCH model necessary for identification as illustrated by (24).

(20) implies that

$$e_t = h_t + \omega_t$$

where $E[\omega_t | S_{t-1}] = 0$ and $E[\omega_t \omega_s' | S_{t-1}] = 0 \forall s \neq t$. Let $\bar{e}_t = [\epsilon_{1,t} \epsilon_{2,t} \epsilon_{2,t}^2]'$, and similarly define \bar{h}_t and $\bar{\omega}_t$ such that

$$\bar{e}_t = \bar{h}_t + \bar{\omega}_t.$$

Assumption A4: (i) $E[\bar{\omega}_t \bar{\omega}_t'] = \Sigma_{\bar{\omega}} < \infty$. (ii) Define $Cov[\bar{e}_t, \bar{e}_{t-1}] \equiv E[(\bar{e}_t - \sigma_e)(\bar{e}_{t-1} - \sigma_e)']$. $Cov[\bar{e}_t, \bar{e}_{t-1}]$ is nonsingular if either $a_{11,1o}$ or $b_{11,1o}$ is nonzero.

Given A4(i), $\bar{\omega}_t$ is covariance stationary. Lemma 2 demonstrates that A3(i) and A4(i) together determine \bar{e}_t to be covariance stationary. Note that if $a_{11,1o} = b_{11,1o} = 0$, then $Cov(\bar{e}_t, \bar{e}_{t-1})$ is singular.

Lemma 2 Given A3(i) and A4(i), \bar{e}_t is covariance stationary.

Proof. Given the definitions of \bar{e}_t and \bar{h}_t , it follows from (20) that

$$\bar{h}_t = \bar{C}_o + \bar{A}_o \bar{e}_{t-1} + \bar{B}_o \bar{h}_{t-1}. \quad (60)$$

Recall that \bar{A}_o is a 2×2 diagonal matrix formed from the elements $a_{22,o}$ and $a_{33,o}$ in A_o (see (20)) and similarly for \bar{B}_o . Recursive substitution into (60) produces

$$\bar{h}_t = \sum_{i=1}^{\infty} \bar{B}_o^{i-1} (\bar{C}_o + \bar{A}_o \bar{e}_{t-i}). \quad (61)$$

Following the steps outlined in the proof to Proposition 2.7 of Engle and Kroner (1995), (61) can be used to show that

$$E_{t-\tau} \bar{e}_t = \left[I + (\bar{A}_o + \bar{B}_o) + \dots + (\bar{A}_o + \bar{B}_o)^{\tau-2} \right] \bar{C}_o + (\bar{A}_o + \bar{B}_o)^{\tau-1} \sum_{i=1}^{\infty} \bar{B}_o^{i-1} (\bar{C}_o + \bar{A}_o \bar{e}_{t-i-\tau+1})$$

where $E_{t-\tau}$ is the expectations operator conditional on the information set $S_{t-\tau}$. For a square matrix Z , it is well known that $Z^\tau \rightarrow 0$ as $\tau \rightarrow \infty$ if and only if the eigenvalues of Z are less than one in modulus. This same condition grants $(I + Z + \dots + Z^{\tau-1}) \rightarrow (I - Z)^{-1}$ as $\tau \rightarrow \infty$ for the appropriately sized identity matrix I . Given A3(i), therefore, $E_{t-\tau} \bar{e}_t \xrightarrow{p} [I - (\bar{A}_o + \bar{B}_o)]^{-1} \bar{C}_o$ (as $\tau \rightarrow \infty$).

Since $\bar{e}_t = \bar{h}_t + \bar{\omega}_t$, where $E[\bar{\omega}_t | S_{t-1}] = 0$, given A4(i),

$$E[\bar{e}_t \bar{e}_t'] = E[\bar{h}_t \bar{h}_t'] + \Sigma_{\bar{\omega}}.$$

Let $\bar{\sigma}_o = [I - (\bar{A}_o + \bar{B}_o)]^{-1} \bar{C}_o$.

$$\begin{aligned} E[\bar{h}_t \bar{h}_t'] &= \eta_o + \bar{A}_o E[\bar{h}_{t-1} \bar{h}_{t-1}'] \bar{A}_o' + \bar{A}_o \Sigma_{\bar{\omega}} \bar{A}_o' + \bar{A}_o E[\bar{h}_{t-1} \bar{h}_{t-1}'] \bar{B}_o' \\ &\quad + \bar{B}_o E[\bar{h}_{t-1} \bar{h}_{t-1}'] \bar{A}_o' + \bar{B}_o E[\bar{h}_{t-1} \bar{h}_{t-1}'] \bar{B}_o' \end{aligned} \quad (62)$$

where $\eta_o = \bar{C}_o \bar{C}'_o + (\bar{A}_o + \bar{B}_o) \bar{\sigma}_o \bar{C}'_o + \bar{C}_o \bar{\sigma}'_o (\bar{A}_o + \bar{B}_o)'$. Applying the $vec(\cdot)$ operator to (62) and simplifying yields

$$\begin{aligned}
vec\left(E\left[\bar{h}_t \bar{h}'_t\right]\right) &= \eta_o + (D_o) vec\left(E\left[\bar{h}_{t-1} \bar{h}'_{t-1}\right]\right) + (\bar{A}_o \otimes \bar{A}_o) vec(\Sigma_{\bar{w}}) \\
&= [I + D_o] (\eta_o + (\bar{A}_o \otimes \bar{A}_o) vec(\Sigma_{\bar{w}})) + (D_o^2) vec\left(E\left[\bar{h}_{t-2} \bar{h}'_{t-2}\right]\right) \\
&= [I + D_o + D_o^2] (\eta_o + (\bar{A}_o \otimes \bar{A}_o) vec(\Sigma_{\bar{w}})) + (D_o^3) vec\left(E\left[\bar{h}_{t-3} \bar{h}'_{t-3}\right]\right) \\
&= \dots \\
&= [I + D_o + \dots + D_o^{\tau-1}] (\eta_o + (\bar{A}_o \otimes \bar{A}_o) vec(\Sigma_{\bar{w}})) + (D_o^\tau) vec\left(E\left[\bar{h}_{t-\tau} \bar{h}'_{t-\tau}\right]\right)
\end{aligned}$$

where $D_o = (\bar{A}_o + \bar{B}_o) \otimes (\bar{A}_o + \bar{B}_o)$. Given A3(i), the eigenvalues of D_o are less than one in modulus, granting that $vec\left(E\left[\bar{h}_t \bar{h}'_t\right]\right)$ converges to $[I - D_o]^{-1} (\eta_o + (\bar{A}_o \otimes \bar{A}_o) vec(\Sigma_{\bar{w}}))$ as $\tau \rightarrow \infty$.

Note that

$$Cov[\bar{e}_t, \bar{e}_{t-\tau}] = E\left[\bar{e}_t \bar{e}'_{t-\tau}\right] - \bar{\sigma}_o \bar{\sigma}'_o$$

Consider the case where $\tau = 1$.

$$E\left[\bar{e}_t \bar{e}'_{t-1} \mid S_{t-1}\right] = \bar{C}_o \bar{e}'_{t-1} + \bar{A}_o \bar{e}_{t-1} \bar{e}'_{t-1} + \bar{B}_o \bar{h}_{t-1} \bar{e}'_{t-1}.$$

By iterated expectations,

$$E\left[\bar{e}_t \bar{e}'_{t-1}\right] = \bar{C}_o \bar{\sigma}'_o + (\bar{A}_o + \bar{B}_o) \Sigma_{\bar{h}} + \bar{A}_o \Sigma_{\bar{w}}$$

and, as a result,

$$Cov[\bar{e}_t, \bar{e}_{t-1}] = (\bar{C}_o - \bar{\sigma}_o) \bar{\sigma}'_o + (\bar{A}_o + \bar{B}_o) \Sigma_{\bar{h}} + \bar{A}_o \Sigma_{\bar{w}}$$

where $\Sigma_{\bar{h}} = E\left[\bar{h}_t \bar{h}'_t\right]$. Next, consider the case where $\tau \geq 2$.

$$\begin{aligned}
E\left[\bar{h}_t \mid S_{t-\tau}\right] &= E\left[\bar{C}_o + \bar{A}_o \bar{e}_{t-1} + \bar{B}_o \bar{h}_{t-1} \mid S_{t-\tau}\right] \\
&= \bar{C}_o + (\bar{A}_o + \bar{B}_o) E\left[\bar{h}_{t-1} \mid S_{t-\tau}\right] \\
&= [I + (\bar{A}_o + \bar{B}_o)] \bar{C}_o + (\bar{A}_o + \bar{B}_o)^2 E\left[\bar{h}_{t-2} \mid S_{t-\tau}\right] \\
&= \dots \\
&= \left[I + (\bar{A}_o + \bar{B}_o) + \dots + (\bar{A}_o + \bar{B}_o)^{\tau-1}\right] \bar{C}_o + (\bar{A}_o + \bar{B}_o)^{\tau-1} [\bar{A}_o \bar{e}_{t-\tau} + \bar{B}_o \bar{h}_{t-\tau}] \\
&= [I - (\bar{A}_o + \bar{B}_o)^\tau] \bar{\sigma}_o + (\bar{A}_o + \bar{B}_o)^{\tau-1} [\bar{A}_o \bar{e}_{t-\tau} + \bar{B}_o \bar{h}_{t-\tau}].
\end{aligned}$$

By iterated expectations,

$$\begin{aligned}
E \left[\bar{e}_t \bar{e}'_{t-\tau} \right] &= E \left[E \left[\bar{e}_t \bar{e}'_{t-\tau} \mid S_{t-\tau} \right] \right] \\
&= E \left[E \left[\bar{h}_t \mid S_{t-\tau} \right] \bar{e}'_{t-\tau} \right] \\
&= \left[I - (\bar{A}_o + \bar{B}_o)^\tau \right] \bar{\sigma}_o \bar{\sigma}'_o + (\bar{A}_o + \bar{B}_o)^{\tau-1} \left[(\bar{A}_o + \bar{B}_o) E \left[\bar{h}_{t-\tau} \bar{h}'_{t-\tau} \right] + \bar{A}_o E \left[\bar{\omega}_{t-\tau} \bar{\omega}'_{t-\tau} \right] \right].
\end{aligned}$$

As a result,

$$Cov \left[\bar{e}_t, \bar{e}_{t-\tau} \right] = (\bar{A}_o + \bar{B}_o)^{\tau-1} \left[(\bar{A}_o + \bar{B}_o) \left(\Sigma_{\bar{h}} - \bar{\sigma}_o \bar{\sigma}'_o \right) + \bar{A}_o \Sigma_{\bar{\omega}} \right] \quad (63)$$

which converges to zero as $\tau \rightarrow \infty$, since $(\bar{A}_o + \bar{B}_o)^{\tau-1} \rightarrow 0$ (as $\tau \rightarrow \infty$). ■

Proposition 2 *Given A1–A4 for the model of (18) and (19), the structural parameters β_{1o} , β_{2o} , and γ_o are identified.*

Proof. Given A2, $\beta_{2o} = E \left[X_t X_t' \right]^{-1} E \left[X_t Y_{2,t} \right]$. If either $a_{11,1o}$ or $b_{11,1o}$ is nonzero as in A3(ii), then $E \left[\epsilon_{1,t} \epsilon_{2,t} \mid S_{t-1} \right]$ is time-varying. In this case, consider $Cov \left[\bar{e}_t, \bar{e}_{t-\tau} \right] = Cov \left[\bar{h}_t, \bar{e}_{t-\tau} \right]$. From (63), it follows that

$$Cov \left[\bar{e}_t, \bar{e}_{t-\tau} \right] = (\bar{A}_o + \bar{B}_o)^{\tau-1} Cov \left[\bar{e}_t, \bar{e}_{t-1} \right]. \quad (64)$$

Given (21), let \bar{r}_t be the reduced form \bar{e}_t . Then the reduced form of (64) when $\tau = 2$ is

$$Cov \left[\bar{r}_t, \bar{r}_{t-2} \right] = (\bar{A}_{ro} + \bar{B}_{ro}) Cov \left[\bar{r}_t, \bar{r}_{t-1} \right], \quad (65)$$

where the relationship between \bar{A}_{ro} and A_{ro} in (22) is equivalent to the relationship between \bar{A}_o in (60) and A_o in (20). An analogous relationship exists between \bar{B}_{ro} and B_{ro} . Identification of $\bar{A}_{ro} + \bar{B}_{ro}$ follows from the nonsingularity of $Cov \left[\bar{e}_t, \bar{e}_{t-1} \right]$. γ_o is then identified as (26).

Next, consider the case where $a_{11,1o} = b_{11,1o} = 0$. Define $Z_{t-1} = \left[\epsilon_{2,t-1}^2 \cdots \epsilon_{2,t-l}^2 \right]'$ for finite $l \geq 1$. Since $E \left[\epsilon_{1,t} \epsilon_{2,t} \mid S_{t-1} \right] = c_{21,0o} c_{22,0o}$, it follows that

$$Cov \left[\epsilon_{1,t} \epsilon_{2,t}, Z_{t-1} \right] = 0. \quad (66)$$

From (21), $\epsilon_{1,t} = R_{1,t} - R_{2,t} \gamma_o$ and $R_{2,t} = \epsilon_{2,t}$. Substitution of these results into (66) produces

$$Cov \left[R_{1,t} \epsilon_{2,t}, Z_{t-1} \right] = Cov \left[\epsilon_{2,t}^2, Z_{t-1} \right] \gamma_o.$$

Let $\Omega = Cov \left[\epsilon_{2,t}^2, Z_{t-1} \right]$, and note that $\Omega \neq 0$ given (20). Then γ_o is identified as $\gamma_o = (\Omega' \Omega)^{-1} \Omega' Cov \left[R_{1,t} \epsilon_{2,t}, Z_{t-1} \right]$.

Finally, given identification of γ_o , β_{1o} is identified as $\beta_{1o} = E \left[X_t X_t' \right]^{-1} E \left[X_t \left(Y_{1,t} - Y_{2,t} \gamma_o \right) \right]$.

■

Proposition 2 identifies (18) and (19) given the nuisance parameters in \bar{C}_o and $\bar{\Phi}_o$. A complete treatment of (20) is not necessary to identify the triangular model. Note that the moment conditions in (30) cover both the case where A3(ii) holds as well as the case where $a_{11,1o} = b_{11,1o} = 0$.

Corollary 3 From (28),

$$E [\bar{e}_t - \bar{\sigma}_o] = 0. \quad (67)$$

From (29),

$$E \left[(\bar{e}_t - \bar{\sigma}_o) (\bar{e}_{t-2} - \bar{\sigma}_o)' - \bar{\Phi}_o (\bar{e}_t - \bar{\sigma}_o) (\bar{e}_{t-1} - \bar{\sigma}_o)' \right] = 0. \quad (68)$$

Stack the moments of (27), (67), and $vec((68))$ into a single vector U . Let

$$\psi = \{\gamma_1, \gamma_2, \delta, c_{21}, c_{22}, \phi_{11}, \phi_{22}\} \in \Psi,$$

and define ψ_o as the true value of ψ . Then $E[U] = 0$ is uniquely satisfied at $\psi = \psi_o$.

Proof. (27) identifies the reduced form residuals $R_{i,t}$, $i = 1, 2$. Given (21), substituting these residuals into (67) and (68) produces (65). The result that $E[U] = 0$ is uniquely satisfied at $\psi = \psi_o$ then follows from Proposition 2. ■

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Table 1A

Summary statistics for size, B/M, and momentum portfolios, 10/6/67 - 9/25/87. The portfolio return series are measured weekly (in percentage terms) so that relatively high frequency data is utilized (to estimate higher moments) that reduces day-of-the-week and weekend effects as well as the effects of nonsynchronous trading and bid-ask bounce. The proxy return is the CRSP market-value-weighted index of all securities on the NYSE, AMEX, and NASDAQ exchanges. Security returns are constructed from the 25 size-B/M portfolios and the 25 size-momentum portfolios (each 5×5 sorts with breakpoints determined by NYSE quintiles). "Small" is the average of the five low-market-cap portfolios, "Mid" the average of the five medium-market-cap portfolios, and "Big" the average of the five large-market-cap portfolios. "Value" is the average of the five high-B/M portfolios, "Neutral" the average of the five middle-B/M portfolios, and "Growth" the average of the five low-B/M portfolios. Finally, "Losers" is the average of the five low-return-sorted portfolios, "Neutral" the average of the five middle-return-sorted portfolios, and "Winners" the average of the five high-return-sorted portfolios.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Growth
Panel A: Excess returns									
mean	0.103	0.120	0.075	0.169	0.108	0.023	-0.034	0.101	0.198
stdev	2.31	2.14	2.03	2.08	1.96	2.64	2.72	1.99	2.44
skew	-0.33	-0.20	0.11	-0.21	-0.18	-0.19	0.32	-0.10	-0.58
kurt	5.12	4.80	4.83	5.18	4.70	4.71	5.84	5.22	4.95
Panel B: Alpha Proxy									
est	0.045	0.060	0.016	0.113	0.053	-0.053	-0.106	0.045	0.132
std error ^a	0.039	0.024	0.012	0.028	0.021	0.025	0.038	0.020	0.031

Notes:

^aHeteroskedasticity consistent

Table 1B

Test results for size, B/M, and momentum portfolios, 10/6/67 - 9/25/87. Projection errors are the residuals from OLS regressions of security returns on the proxy return. Structural errors are the residuals from linear equations relating security returns to the proxy return, where the residual from each equation and the proxy return is allowed to covary. Gibbons, Ross, and Shanken (1989), or GRS, Bootstrap Proposition 1 constant covariance (BPC), and Bootstrap Proposition 1 stochastic (BPS), are alternative ways of determining the maximum correlation between the CRSP value-weighted proxy return and the market return that supports the CAPM at a 5% significance level. GRS is based on the assumption that the projection errors are normally distributed. BPC is also based on the projection errors, but assumes those errors to follow strong, univariate GARCH(1,1) processes with unknown distributions. BPS is based on the assumption that the structural errors follow strong, univariate GARCH (1,1) processes with unknown distributions.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Winners
Panel C: Projection errors									
skew	0.23	0.22	0.09	0.39	0.48	0.11	0.98	0.39	-0.70
kurt	5.08	5.85	4.15	5.76	8.19	4.45	7.95	5.32	6.83
Panel D: Structural errors									
skew	0.17	0.23	0.00	0.40	0.47	0.10	0.59	0.30	-0.85
kurt	5.67	5.81	5.68	5.99	8.15	4.41	5.97	4.99	6.89
Panel E: GRS ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.565			0.277			0.236	
0.52		0.855			0.570			0.504	
0.86		0.939			0.753			0.694	
1.00		0.953			0.800			0.746	
Panel F: BPC ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.410			0.272			0.260	
0.52		0.737			0.551			0.530	
0.86		0.892			0.737			0.715	
1.00		0.924			0.787			0.766	
unknown		0.581			0.429			0.398	
Panel G: BPS ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.409			0.271			0.242	
0.52		0.741			0.552			0.511	
0.86		0.896			0.738			0.706	
1.00		0.927			0.787			0.761	
unknown		0.590			0.440			0.388	

Notes:

^bMaximum correlations are reported that support the CAPM prediction.

^cValues for the proxy Sharpe ratio are taken from Shanken (1987). These values are annualized. 0.52 is the expected value; 0.22 and 0.86 are -1 and +2 standard deviations away from this expected value, respectively. 1.00 is a value for the proxy Sharpe ratio that is greater than any conceivable true value. Unknown means that the proxy Sharpe ratio is bootstrapped along with every other estimated quantity in the expression determining an upper bound for the correlation between the proxy and the market return.

Table 2A

Summary statistics for size, B/M, and momentum portfolios, 11/6/87 - 9/28/07. The portfolio return series are measured weekly (in percentage terms) so that relatively high frequency data is utilized (to estimate higher moments) that reduces day-of-the-week and weekend effects as well as the effects of nonsynchronous trading and bid-ask bounce. The proxy return is the CRSP market-value-weighted index of all securities on the NYSE, AMEX, and NASDAQ exchanges. Security returns are constructed from the 25 size-B/M portfolios and the 25 size-momentum portfolios (each 5×5 sorts with breakpoints determined by NYSE quintiles). "Small" is the average of the five low-market-cap portfolios, "Mid" the average of the five medium-market-cap portfolios, and "Big" the average of the five large-market-cap portfolios. "Value" is the average of the five high-B/M portfolios, "Neutral" the average of the five middle-B/M portfolios, and "Growth" the average of the five low-B/M portfolios. Finally, "Losers" is the average of the five low-return-sorted portfolios, "Neutral" the average of the five middle-return-sorted portfolios, and "Winners" the average of the five high-return-sorted portfolios.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Growth
Panel A: Excess returns									
mean	0.169	0.176	0.157	0.209	0.183	0.103	0.041	0.172	0.315
stdev	2.16	2.09	1.92	1.88	1.83	2.61	2.94	1.74	2.60
skew	-1.04	-0.64	-0.29	-0.91	-0.75	-0.75	0.03	-0.60	-0.89
kurt	11.76	6.64	4.97	9.24	6.66	9.05	7.00	6.72	10.96
Panel B: Alpha Proxy									
est	0.049	0.040	0.027	0.094	0.063	-0.070	-0.129	0.059	0.148
std error ^a	0.044	0.029	0.023	0.032	0.025	0.034	0.056	0.025	0.039

Notes:

^aHeteroskedasticity consistent

Table 2B

Test results for size, B/M, and momentum portfolios, 11/6/87 - 9/28/07. Projection errors are the residuals from OLS regressions of security returns on the proxy return. Structural errors are the residuals from linear equations relating security returns to the proxy return, where the residual from each equation and the proxy return is allowed to covary. Gibbons, Ross, and Shanken (1989), or GRS, Bootstrap Proposition 1 constant covariance (BPC), and Bootstrap Proposition 1 stochastic (BPS), are alternative ways of determining the maximum correlation between the CRSP value-weighted proxy return and the market return that supports the CAPM at a 5% significance level. GRS is based on the assumption that the projection errors are normally distributed. BPC is also based on the projection errors, but assumes those errors to follow strong, univariate GARCH(1,1) processes with unknown distributions. BPS is based on the assumption that the structural errors follow strong, univariate GARCH (1,1) processes with unknown distributions.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Winners
Panel C: Projection errors									
skew	-0.04	0.14	1.41	-0.08	0.17	-0.07	1.13	0.89	-0.25
kurt	7.56	6.06	19.54	6.68	6.70	7.71	9.22	11.49	6.83
Panel D: Structural errors									
skew	-0.43	-0.33	-0.07	-0.75	-0.63	-0.28	1.07	-0.36	-0.72
kurt	9.72	6.68	5.05	10.20	6.59	8.36	9.24	7.39	10.96
Panel E: GRS ^{b, c}									
Proxy Sharpe ratio:									
0.22		1.000			0.406			0.258	
0.52		1.000			0.730			0.540	
0.86		1.000			0.870			0.727	
1.00		1.000			0.899			0.776	
Panel F: BPC ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.639			0.397			0.277	
0.52		0.926			0.698			0.554	
0.86		0.997			0.852			0.745	
1.00		1.000			0.888			0.796	
unknown		1.000			0.824			0.679	
Panel G: BPS ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.857			0.442			0.319	
0.52		1.000			0.739			0.622	
0.86		1.000			0.878			0.805	
1.00		1.000			0.908			0.851	
unknown		1.000			0.841			0.745	

Notes:

^bMaximum correlations are reported that support the CAPM prediction.

^cValues for the proxy Sharpe ratio are taken from Shanken (1987). These values are annualized. 0.52 is the expected value; 0.22 and 0.86 are -1 and +2 standard deviations away from this expected value, respectively. 1.00 is a value for the proxy Sharpe ratio that is greater than any conceivable true value. Unknown means that the proxy Sharpe ratio is bootstrapped along with every other estimated quantity in the expression determining an upper bound for the correlation between the proxy and the market return.

Table 3A

Summary statistics for size, B/M, and momentum portfolios, 10/7/77 - 9/25/87. The portfolio return series are measured weekly (in percentage terms) so that relatively high frequency data is utilized (to estimate higher moments) that reduces day-of-the-week and weekend effects as well as the effects of nonsynchronous trading and bid-ask bounce. The proxy return is the CRSP market-value-weighted index of all securities on the NYSE, AMEX, and NASDAQ exchanges. Security returns are constructed from the 25 size-B/M portfolios and the 25 size-momentum portfolios (each 5×5 sorts with breakpoints determined by NYSE quintiles). "Small" is the average of the five low-market-cap portfolios, "Mid" the average of the five medium-market-cap portfolios, and "Big" the average of the five large-market-cap portfolios. "Value" is the average of the five high-B/M portfolios, "Neutral" the average of the five middle-B/M portfolios, and "Growth" the average of the five low-B/M portfolios. Finally, "Losers" is the average of the five low-return-sorted portfolios, "Neutral" the average of the five middle-return-sorted portfolios, and "Winners" the average of the five high-return-sorted portfolios.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Growth
Panel A: Excess returns									
mean	0.221	0.226	0.151	0.257	0.205	0.140	0.077	0.184	0.316
stdev	1.96	1.98	1.99	1.79	1.83	2.49	2.31	1.82	2.43
skew	-1.08	-0.52	0.04	-0.91	-0.54	-0.30	0.36	-0.39	-0.87
kurt	7.96	5.99	4.51	7.81	5.59	4.91	5.72	5.61	6.59
Panel B: Alpha Proxy									
est	0.091	0.081	-0.002	0.130	0.068	-0.045	-0.081	0.048	0.141
std error ^a	0.048	0.031	0.016	0.035	0.024	0.034	0.048	0.025	0.044

Notes:

^aHeteroskedasticity consistent

Table 3B

Test results for size, B/M, and momentum portfolios, 10/7/77 - 9/25/87. Projection errors are the residuals from OLS regressions of security returns on the proxy return. Structural errors are the residuals from linear equations relating security returns to the proxy return, where the residual from each equation and the proxy return is allowed to covary. Gibbons, Ross, and Shanken (1989), or GRS, Bootstrap Proposition 1 constant covariance (BPC), and Bootstrap Proposition 1 stochastic (BPS), are alternative ways of determining the maximum correlation between the CRSP value-weighted proxy return and the market return that supports the CAPM at a 5% significance level. GRS is based on the assumption that the projection errors are normally distributed. BPC is also based on the projection errors, but assumes those errors to follow strong, univariate GARCH(1,1) processes with unknown distributions. BPS is based on the assumption that the structural errors follow strong, univariate GARCH (1,1) processes with unknown distributions.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Winners
Panel C: Projection errors									
skew	-0.71	-0.35	0.20	-0.77	-0.63	-0.13	0.95	-0.15	-0.97
kurt	7.00	4.90	3.72	7.64	5.57	3.88	8.35	5.06	7.10
Panel D: Structural errors									
skew	-0.77	-0.29	0.20	-1.06	-0.76	-0.15	1.08	-0.11	-0.55
kurt	7.39	4.58	3.69	9.29	6.23	4.03	9.26	4.91	5.50
Panel E: GRS ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.437			0.244			0.352	
0.52		0.759			0.518			0.671	
0.86		0.888			0.707			0.831	
1.00		0.913			0.758			0.867	
Panel F: BPC ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.291			0.220			0.286	
0.52		0.590			0.465			0.577	
0.86		0.785			0.660			0.770	
1.00		0.835			0.719			0.821	
unknown		0.772			0.614			0.733	
Panel G: BPS ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.353			0.231			0.316	
0.52		0.645			0.483			0.644	
0.86		0.815			0.672			0.849	
1.00		0.872			0.728			0.899	
unknown		0.810			0.644			0.795	

Notes:

^bMaximum correlations are reported that support the CAPM prediction.

^cValues for the proxy Sharpe ratio are taken from Shanken (1987). These values are annualized. 0.52 is the expected value; 0.22 and 0.86 are -1 and +2 standard deviations away from this expected value, respectively. 1.00 is a value for the proxy Sharpe ratio that is greater than any conceivable true value. Unknown means that the proxy Sharpe ratio is bootstrapped along with every other estimated quantity in the expression determining an upper bound for the correlation between the proxy and the market return.

Table 4A

Summary statistics for size, B/M, and momentum portfolios, 11/6/87 - 9/26/97. The portfolio return series are measured weekly (in percentage terms) so that relatively high frequency data is utilized (to estimate higher moments) that reduces day-of-the-week and weekend effects as well as the effects of nonsynchronous trading and bid-ask bounce. The proxy return is the CRSP market-value-weighted index of all securities on the NYSE, AMEX, and NASDAQ exchanges. Security returns are constructed from the 25 size-B/M portfolios and the 25 size-momentum portfolios (each 5×5 sorts with breakpoints determined by NYSE quintiles). "Small" is the average of the five low-market-cap portfolios, "Mid" the average of the five medium-market-cap portfolios, and "Big" the average of the five large-market-cap portfolios. "Value" is the average of the five high-B/M portfolios, "Neutral" the average of the five middle-B/M portfolios, and "Growth" the average of the five low-B/M portfolios. Finally, "Losers" is the average of the five low-return-sorted portfolios, "Neutral" the average of the five middle-return-sorted portfolios, and "Winners" the average of the five high-return-sorted portfolios.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Growth
Panel A: Excess returns									
mean	0.172	0.220	0.221	0.242	0.217	0.149	0.075	0.207	0.336
stdev	1.54	1.58	1.71	1.47	1.43	1.95	2.05	1.37	1.95
skew	-0.51	-0.44	-0.10	-0.30	-0.50	-0.35	0.15	-0.48	-0.51
kurt	6.51	5.36	4.14	5.26	5.58	4.91	5.95	5.91	4.39
Panel B: Alpha Proxy									
est	0.029	0.039	0.008	0.079	0.047	-0.074	-0.134	0.044	0.112
std error ^a	0.048	0.032	0.017	0.033	0.023	0.040	0.054	0.023	0.038

Notes:

^aHeteroskedasticity consistent

Table 4B

Test results for size, B/M, and momentum portfolios, 11/6/87 - 9/26/97. Projection errors are the residuals from OLS regressions of security returns on the proxy return. Structural errors are the residuals from linear equations relating security returns to the proxy return, where the residual from each equation and the proxy return is allowed to covary. Gibbons, Ross, and Shanken (1989), or GRS, Bootstrap Proposition 1 constant covariance (BPC), and Bootstrap Proposition 1 stochastic (BPS), are alternative ways of determining the maximum correlation between the CRSP value-weighted proxy return and the market return that supports the CAPM at a 5% significance level. GRS is based on the assumption that the projection errors are normally distributed. BPC is also based on the projection errors, but assumes those errors to follow strong, univariate GARCH(1,1) processes with unknown distributions. BPS is based on the assumption that the structural errors follow strong, univariate GARCH (1,1) processes with unknown distributions.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Winners
Panel C: Projection errors									
skew	0.24	0.09	0.14	0.88	-0.02	-0.16	0.74	0.29	-0.15
kurt	5.07	3.95	3.17	5.99	5.32	3.83	5.64	5.29	3.81
Panel D: Structural errors									
skew	-0.20	-0.08	0.11	0.86	-0.48	-0.16	0.60	-0.27	-0.18
kurt	6.50	4.74	3.25	6.36	6.13	3.69	6.55	7.02	3.95
Panel E: GRS ^{b, c}									
Proxy Sharpe ratio:									
0.22		1.000			0.388			0.165	
0.52		1.000			0.712			0.372	
0.86		1.000			0.858			0.553	
1.00		1.000			0.889			0.611	
Panel F: BPC ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.554			0.310			0.174	
0.52		0.892			0.597			0.385	
0.86		1.000			0.780			0.562	
1.00		1.000			0.828			0.619	
unknown		1.000			0.941			0.714	
Panel G: BPS ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.636			0.366			0.172	
0.52		0.971			0.661			0.383	
0.86		1.000			0.826			0.562	
1.00		1.000			0.866			0.619	
unknown		1.000			0.931			0.690	

Notes:

^bMaximum correlations are reported that support the CAPM prediction.

^cValues for the proxy Sharpe ratio are taken from Shanken (1987). These values are annualized. 0.52 is the expected value; 0.22 and 0.86 are -1 and +2 standard deviations away from this expected value, respectively. 1.00 is a value for the proxy Sharpe ratio that is greater than any conceivable true value. Unknown means that the proxy Sharpe ratio is bootstrapped along with every other estimated quantity in the expression determining an upper bound for the correlation between the proxy and the market return.

Table 5A

Summary statistics for size, B/M, and momentum portfolios, 10/3/97 - 9/28/07. The portfolio return series are measured weekly (in percentage terms) so that relatively high frequency data is utilized (to estimate higher moments) that reduces day-of-the-week and weekend effects as well as the effects of nonsynchronous trading and bid-ask bounce. The proxy return is the CRSP market-value-weighted index of all securities on the NYSE, AMEX, and NASDAQ exchanges. Security returns are constructed from the 25 size-B/M portfolios and the 25 size-momentum portfolios (each 5×5 sorts with breakpoints determined by NYSE quintiles). "Small" is the average of the five low-market-cap portfolios, "Mid" the average of the five medium-market-cap portfolios, and "Big" the average of the five large-market-cap portfolios. "Value" is the average of the five high-B/M portfolios, "Neutral" the average of the five middle-B/M portfolios, and "Growth" the average of the five low-B/M portfolios. Finally, "Losers" is the average of the five low-return-sorted portfolios, "Neutral" the average of the five middle-return-sorted portfolios, and "Winners" the average of the five high-return-sorted portfolios.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Growth
Panel A: Excess returns									
mean	0.166	0.133	0.094	0.177	0.150	0.057	0.007	0.138	0.293
stdev	2.63	2.49	2.11	2.22	2.16	3.12	3.61	2.04	3.12
skew	-1.04	-0.60	-0.36	-1.00	-0.74	-0.76	0.03	-0.57	-0.90
kurt	9.85	5.62	5.00	8.53	5.78	7.96	5.51	5.85	9.91
Panel B: Alpha Proxy									
est	0.087	0.048	0.021	0.107	0.077	-0.052	-0.102	0.070	0.190
std error ^a	0.072	0.048	0.038	0.054	0.043	0.054	0.096	0.043	0.067

Notes:

^aHeteroskedasticity consistent

Table 5B

Test results for size, B/M, and momentum portfolios, 10/3/97 - 9/28/07. Projection errors are the residuals from OLS regressions of security returns on the proxy return. Structural errors are the residuals from linear equations relating security returns to the proxy return, where the residual from each equation and the proxy return is allowed to covary. Gibbons, Ross, and Shanken (1989), or GRS, Bootstrap Proposition 1 constant covariance (BPC), and Bootstrap Proposition 1 stochastic (BPS), are alternative ways of determining the maximum correlation between the CRSP value-weighted proxy return and the market return that supports the CAPM at a 5% significance level. GRS is based on the assumption that the projection errors are normally distributed. BPC is also based on the projection errors, but assumes those errors to follow strong, univariate GARCH(1,1) processes with unknown distributions. BPS is based on the assumption that the structural errors follow strong, univariate GARCH (1,1) processes with unknown distributions.

	Size			B/M			Momentum		
	Small	Mid	Large	Value	Neutral	Growth	Losers	Draws	Winners
Panel C: Projection errors									
skew	-0.11	0.16	1.15	-0.32	0.15	-0.02	1.09	0.81	-0.29
kurt	6.75	5.51	12.23	5.51	5.16	8.02	7.69	8.72	5.49
Panel D: Structural errors									
skew	-0.82	-0.44	-0.18	-1.01	-0.70	-0.46	0.89	-0.46	-0.84
kurt	9.33	5.62	5.29	9.22	5.59	8.06	7.13	6.11	10.07
Panel E: GRS ^{b, c}									
Proxy Sharpe ratio:									
0.22		1.000			1.000			0.469	
0.52		1.000			1.000			0.788	
0.86		1.000			1.000			0.904	
1.00		1.000			1.000			0.926	
Panel F: BPC ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.648			0.427			0.337	
0.52		0.955			0.766			0.645	
0.86		1.000			0.928			0.836	
1.00		1.000			0.960			0.883	
unknown		0.910			0.714			0.579	
Panel G: BPS ^{b, c}									
Proxy Sharpe ratio:									
0.22		0.771			0.434			0.391	
0.52		1.000			0.798			0.741	
0.86		1.000			0.975			0.933	
1.00		1.000			1.000			0.974	
unknown		0.966			0.655			0.597	

Notes:

^bMaximum correlations are reported that support the CAPM prediction.

^cValues for the proxy Sharpe ratio are taken from Shanken (1987). These values are annualized. 0.52 is the expected value; 0.22 and 0.86 are -1 and +2 standard deviations away from this expected value, respectively. 1.00 is a value for the proxy Sharpe ratio that is greater than any conceivable true value. Unknown means that the proxy Sharpe ratio is bootstrapped along with every other estimated quantity in the expression determining an upper bound for the correlation between the proxy and the market return.

TABLE 6

Simulation evidence for the size of the three relative efficiency tests considered under the null hypothesis that the correlation of the proxy return with the true market return is at least 90%. Errors to the excess security returns and excess proxy return follow semi-strong GARCH(1,1) processes with standardized Gamma(2,1) innovations. Parameters for the GARCH processes are the sample estimates obtained from the B/M portfolios measured over the weekly period 11/6/87 - 9/28/07 that are robust to endogeneity of the proxy return. These parameter estimates are termed the "true" values. The Gamma(2,1) distribution is chosen because, when combined with these GARCH parameters, this distribution produces errors with unconditional skewness and kurtosis measures comparable to those described under Panel D for the B/M portfolios of Table 2B. Betas for the excess security returns are the sample estimates from the same time period. Alpha proxies for each of the excess security returns are calibrated from the sample returns so that (1) they are all equal and (2) they imply a 90% correlation between the proxy and the market return. For the GRS test, the Sharpe Performance Measure for the proxy return is assumed to be known and is set equal to the estimate from the original sample. For the BPC and BPS tests, the Sharpe Performance Measure is treated as unknown. For all three test statistics, the simulations are conducted across 500 trials with excess return series of 1000 observations each. When constructing the individual excess return series for each trial, the first 200 observations are dropped to avoid initialization effects. For the BPC and BPS statistics, within each simulation trial is a bootstrap of the maximum correlation between the proxy and market return conducted over 250 repetitions. In each case, the bootstrap routines use parameter estimates from the original sample along with constant terms implied by the calibrated alpha proxies. Parameter estimates used in the BPC test assume that innovations to the excess security returns are uncorrelated with the proxy return. Parameter estimates used in the BPS test are the "true" values described above. The table reports rejection rates for the test statistics at 10%, 5%, and 1% significance levels.

Statistic	Size =		
	0.10	0.05	0.01
GRS	0.180	0.112	0.038
BPC	0.114	0.082	0.026
BPS	0.084	0.050	0.016