

## Introduction to High Performance Computers

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Why Do You Care About Architecture?

- To use HPC systems well, you need to understand the basics and conceptual design
  - Otherwise, too many things are mysterious
- Programming for HPC systems is hard
  - To get your code to work properly
  - To make it run efficiently (performance)
- You want to efficiently configure the way your job runs
- The technology is just cool!







#### **Topics**

- Terminology
- 5 main parts of an HPC system
- CPUs
- Memory
- Nodes
- Interconnect
- Data Storage







## **5 Major Parts of an HPC System**

We'll take the perspective of an application programmer or a scientist.

What features of an HPC system are important for you to know about?

- 1. CPUs
- 2. Memory (volatile)
- 3. Nodes
- 4. Inter-node network
- 5. Non-volatile storage (disks, tape)







#### Let's Build an HPC System

#### We'll talk about the components in just a bit.







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#### Interconnect









# **CPUs**









#### **Stored Program Computers**

- Modern computers are "stored program computers"
  - Conceived by Turing in 1936
  - Implemented in 1949 (EDVAC)
- Instructions are stored as data in memory
  - Read and executed by control units
- Arithmetic and logic
  - Performed by functional units separate from instruction control units



































- There's a lot more on the CPU than shown previously, e.g.
  - L3 cache (~10 MB)
  - SQRT/Divide/Trig FP unit
  - "TLB" to cache memory addresses
  - Instruction decode







#### On-Chip Performance Enhancements

- Chip designers have added lots of complexity to increase performance
- Instruction Parallelism
  - Pipelined functional units (e.g. FPU)
  - Superscalar processors
- Data Parallelism
  - SIMD
- Cache lines
  - Data brought into cache in contiguous chunks
- Out of order & speculative execution







#### SIMD

- Special registers hold multiple words of data
- A single instruction (e.g. floating point multiply) is applied to all the data at once
- "SSE[2-4]" : Streaming **SIMD Extension** instruction set for x86
- aka "Vectorization"









#### Latency

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# Time to send a zero-length message.

## "Data Access Time"













- All CPUs (processors) now have multiple compute "cores" on a single "chip" or "die" with possibly multiple chips per "socket" (the unit that plugs into the motherboard)
- Increased complexity
- The trend is for ever-more cores per die, mainly to hold down power needs







#### Hypothetical Socket (8 core)





## **HPC Nodes**





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#### **HPC Node**

- A "node" is a (physical) collection of CPUs, memory, and interfaces to other nodes and devices.
  - Single memory address space
  - Memory access "on-node" is significantly faster than "off-node" memory access







#### **Example NUMA Node**

NUMA Node – Non-Uniform Memory Access Single address space





#### GPUs

- Many of top-ranked HPC systems are GPU-accelerated
- "Graphics Processing Units" are composed of 100s of simple "cores" that provide data-level on-chip parallelism
- Private, limited memory
- Yet more low-level complexity to consider
  - Another memory hierarchy
  - Have to move data to GPU memory "by hand"
  - 400-800 cycle latency to GPU memory
- Computations are extremely fast once data is in GPU memory
- Programmability is currently poor
- Legacy codes may have to be rewritten to minimize data movement
- Not all algorithms map well to GPUs
- What is their future in HPC?????

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## **Internode Networks**





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- Most HPC systems are "distributed memory"
  - Many nodes, each with its own local memory and distinct memory space
  - Nodes communicate over a specialized high-speed, low-latency network







#### **Interconnect Characteristics**

• Latency

Latencies between different nodes may be different

- Typically ~ a few µsec
- Bandwidth
  - Typically ~ a few GB/sec in/out of a node







#### • Switched

Network switches connect and route network traffic over the interconnect

• Mesh

Each node sends and receives its own data, and also relays data from other nodes
Messages hop from one node to another until they reach their destination (must deal with routing around down nodes)









#### **Mesh Networks**

Mesh network topologies can be complex

Grids Cubes Hypercubes Tori









## **Disk and Tape Storage**





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# • File storage is the slowest level in the data memory hierarchy

 Not uncommon for checkpoints / memory dumps to be taking a large fraction of total run time (>50%?)

NERSC users say they want no more than 10% of time to be IO









#### **Archival Storage**

- Large, Permanent Storage
  - Many PBs
  - Often tape storage fronted by a disk cache
  - Often accessed via ftp, grid tools, and/or custom clients (e.g. hsi for HPSS)







## **HPC Operating Systems**

- Most HPC OSs are Linux-Based
  - IBM AIX on POWER (also offers Linux)
- "Generic" Cluster Systems
  - Full Linux OS on each node
- Specialized HPC Systems (e.g., Cray XT series, IBM Blue Gene)
  - Full Linux OS on login, "services" nodes
  - Lightweight kernel on compute nodes
    - Helps performance
    - May hinder functionality (DLLs, dynamic process creation, some system calls may not be supported.)







#### Summary: Why Do You Care About Architecture?

- Details of machine are important for performance
  - Processor and memory system (not just parallelism)
  - What to expect? Use understanding of hardware limits
- There is parallelism hidden within processors
  - Pipelining, SIMD, etc
- Locality is at least as important as computation
  - Temporal: re-use of data recently used
  - Spatial: using data nearby that recently used
- Machines have memory hierarchies
  - 100s of cycles to read from DRAM (main memory)
  - Caches are fast (small) memory that optimize average case
- Can rearrange code/data to improve locality







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