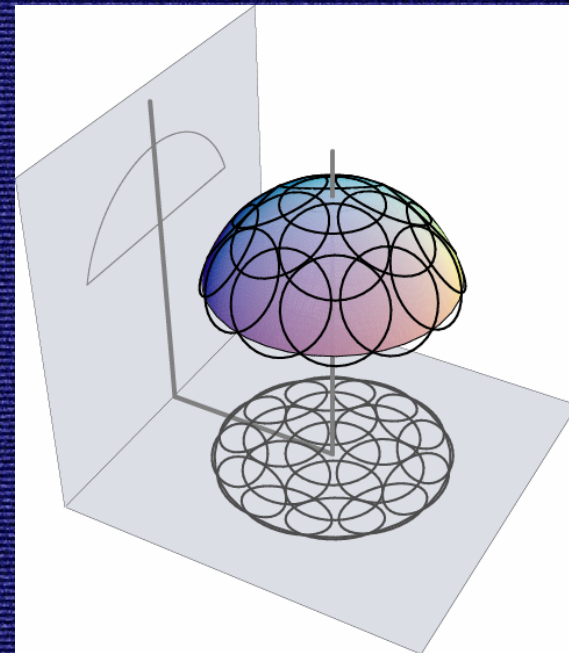


Sub-aperture Approaches to Finishing and Metrology

presented to:
Brookhaven National Laboratory

Marc Tricard
QED Technologies, Inc.

1040 University Avenue • Rochester, NY • USA
Tel: +1 (585) 256-6540 • Fax: +1 (585) 256-3211
tricard@qedmrf.com • www.qedmrf.com

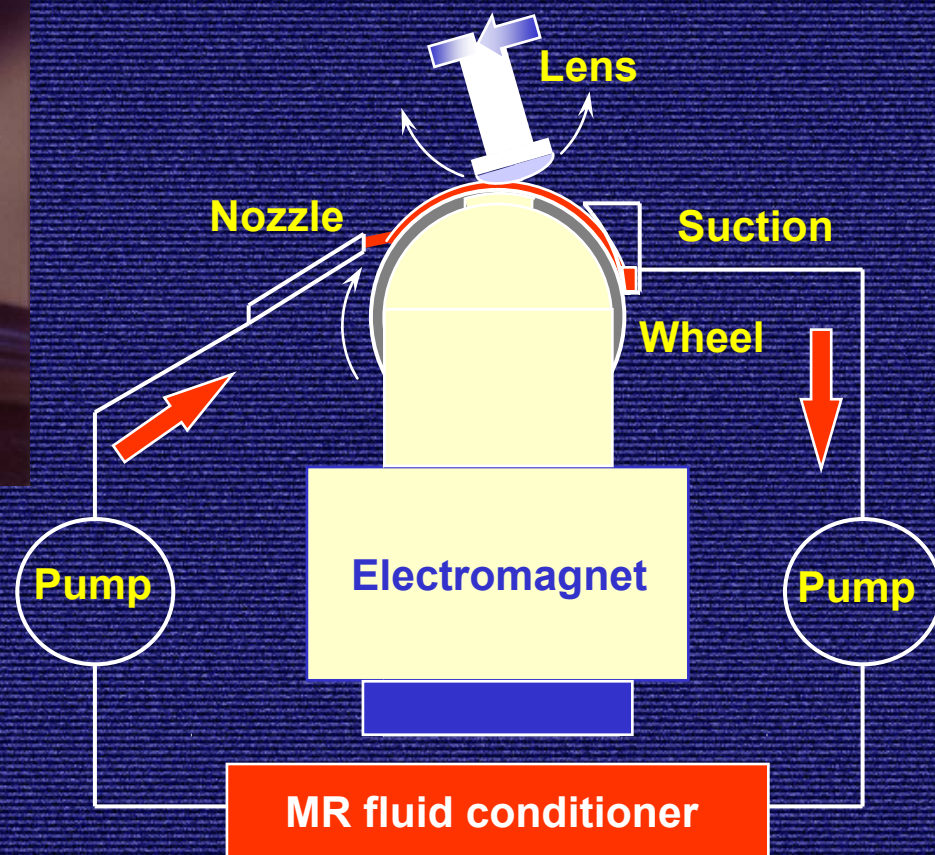


Outline

- ❖ **Overview of Magnetorheological Finishing (MRF)**
- ❖ MRF Applications
 - ❖ Jet Finishing
 - ❖ Subaperture Stitching Interferometer (SSI)
 - ❖ SSI Applications
- ❖ Conclusions

Magnetorheological Finishing (MRF)

How it works

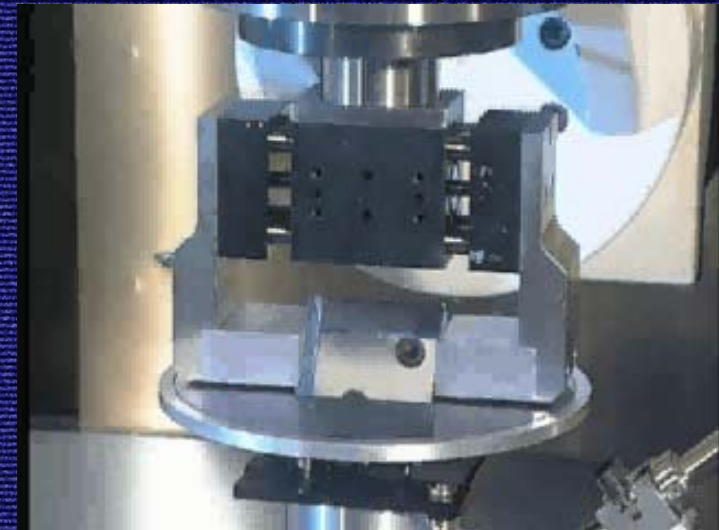
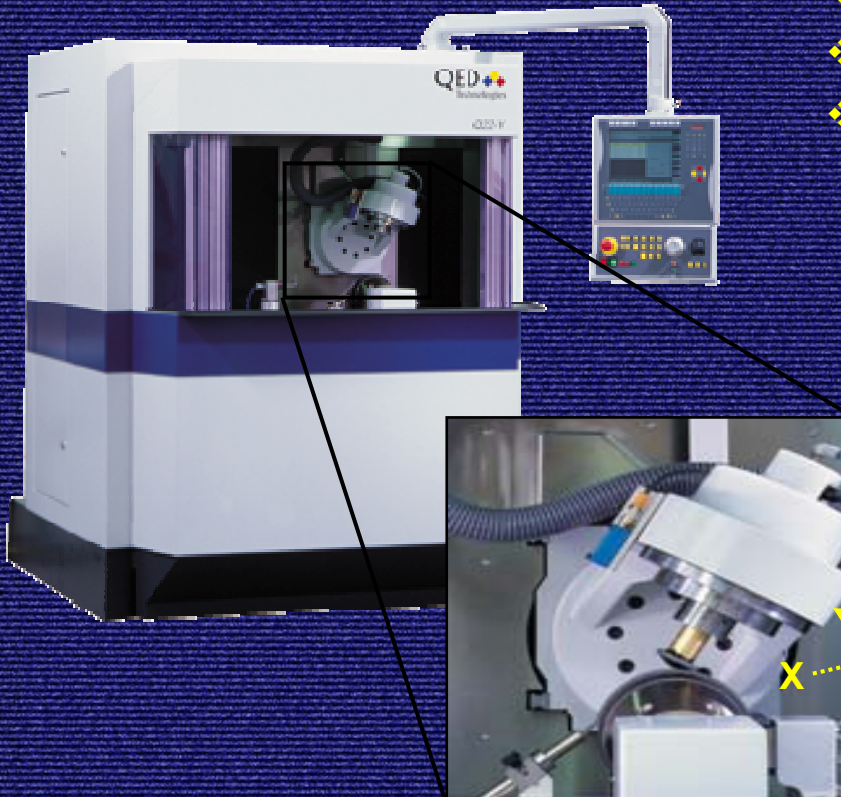




Q22-Y Raster MRF System

- ❖ Various applications for non-round optics are enabled by rastering (e.g. cylinders, prisms, free-forms...)
- ❖ The Q22-Y has all of the capabilities of the Q22-X plus the ability to polish:

- ❖ Rectangular aperture optics
- ❖ Figure and angle correction on prisms
- ❖ Figure correction on cylindrical optics



Q22-Y has additional axis of motion to allow raster polishing

MRF – Breakthrough Technology



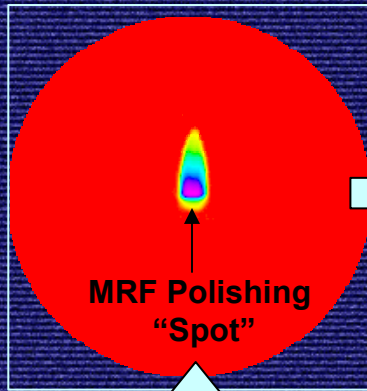
The MRF polishing tool:

- never dulls or changes
- is interferometrically characterized
- is easily adjusted
- conforms to part shape - works on complex shapes (flat, sphere, asphere, cylinder...)
- has high removal rates
- Has a removal based on shear stress so applies very low normal load on abrasive, improving surface integrity
- **Is very deterministic, leading to high convergence rate**
- **These attributes lead to a production oriented, deterministic, computer controlled polishing and figuring technique.**
- **Production proven: more than 100 machines worldwide**

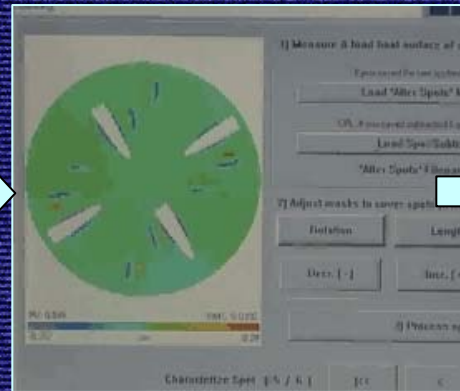
MRF Process Flow Diagram

$$removal(x, y) = dwell(x, y) \otimes spot(x, y)$$

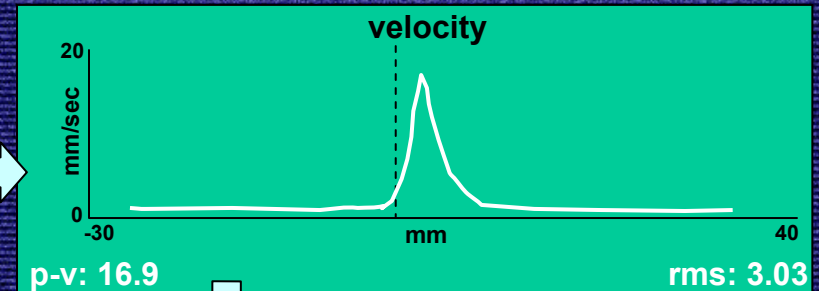
Removal Function



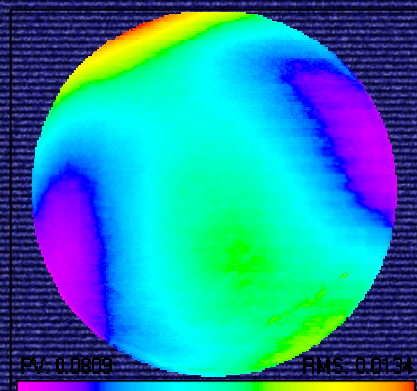
QED Software



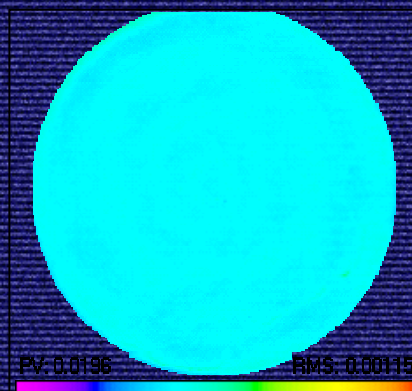
MRF Machine Instructions



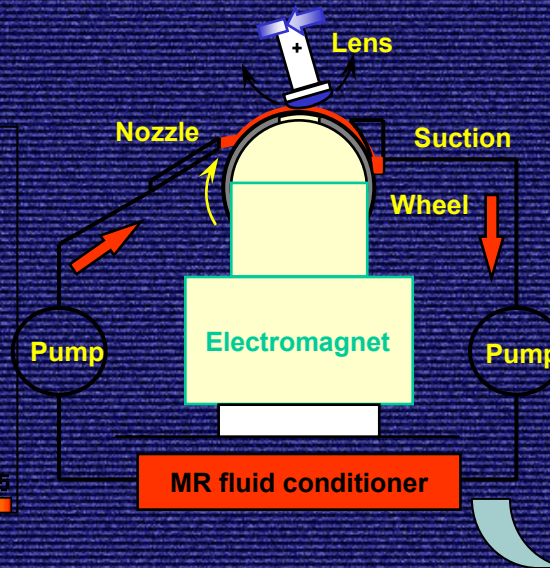
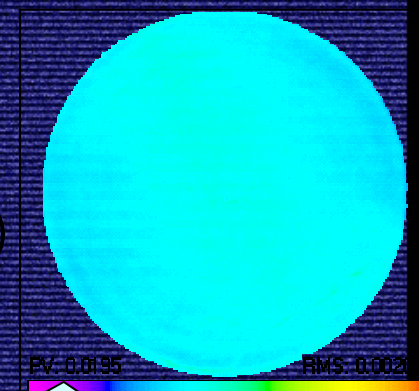
Surface to be Polished



Predicted Surface



Surface after MRF



QED MRF Product Line

100+ machines in use, many flavors...

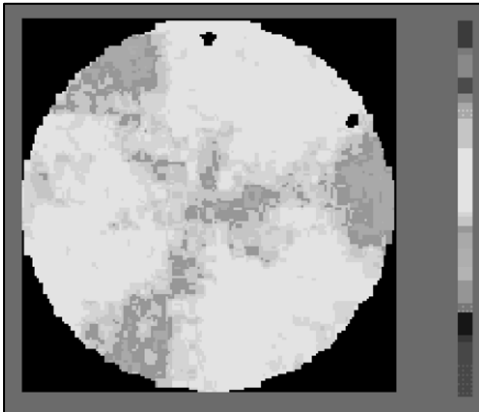


- **Q22-XE** – Up to 80 mm in diameter
- **Q22-X** – Up to 200 mm in diameter
- **Q22-Y** – Q22-X + Raster tool path
- **Q22-400X** – Up to 400 mm in diameter
- **Q22-750P2** – Plano optics up to 750 mm x1000 mm in size
- **Q22-950F** – Free-form optics up to ~ 950 x 1,250mm
- The next-generation, meter-class machine is being built to finish free-form optics
 - **Q22-xxxxF** – Multi-meters freeform
- **SSI** – Sub-aperture Stitching Interferometer (SSI) for high precision metrology

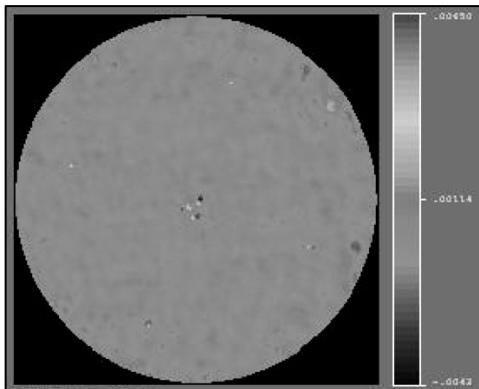
Outline

- ❖ Overview of Magnetorheological Finishing (MRF)
- ❖ **MRF Applications**
 - ❖ Jet Finishing
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 - ❖ SSI Applications
 - ❖ Conclusions

High Precision *CaF₂ Lenses for 157nm Lithography*



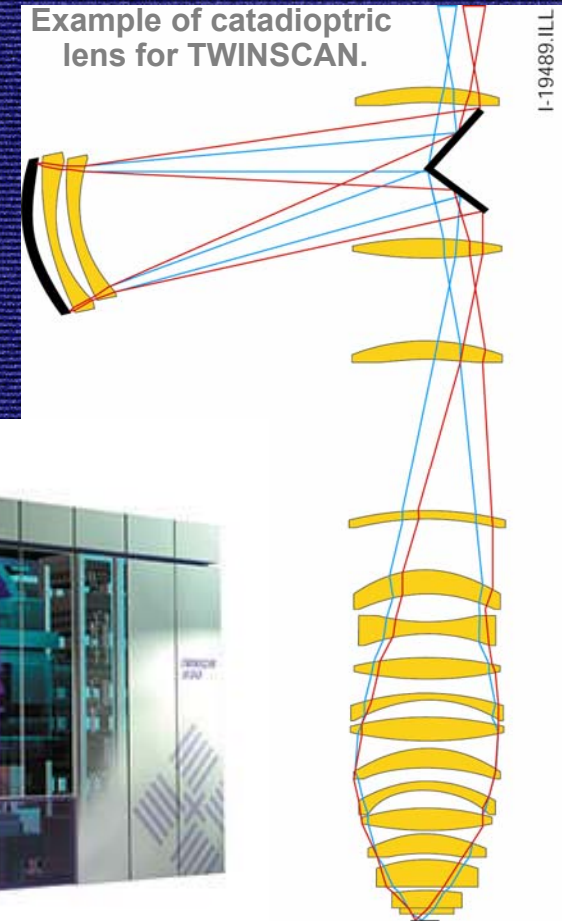
<111> Element
Surface figure: **0.57nm rms**



<100> Element
Surface figure: **0.63nm rms**



Example of catadioptric lens for TWINSKAN.

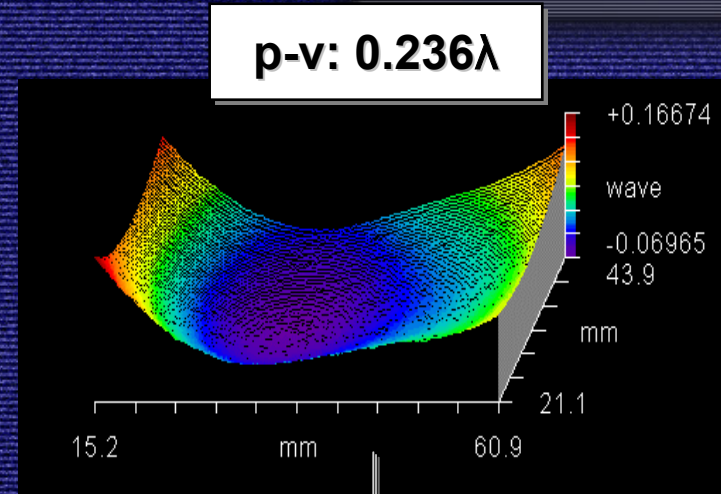
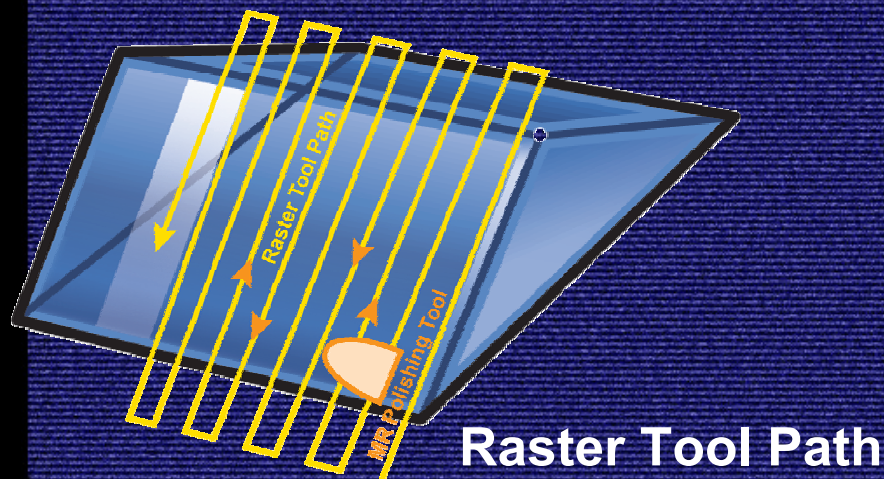
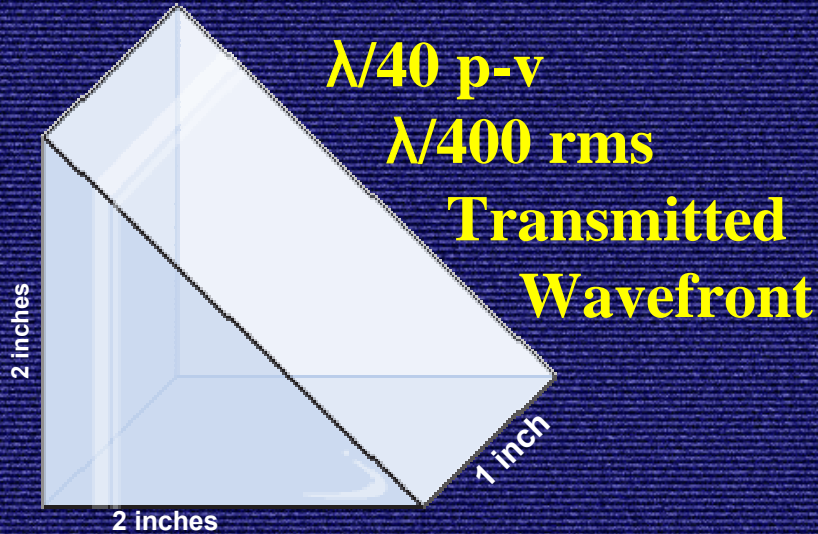


Jan Mulkens (ASML), et al., "Optical lithography solutions for sub-65 nm semiconductor devices", Proc. of SPIE, 5040; pp: 753-762, 2003.

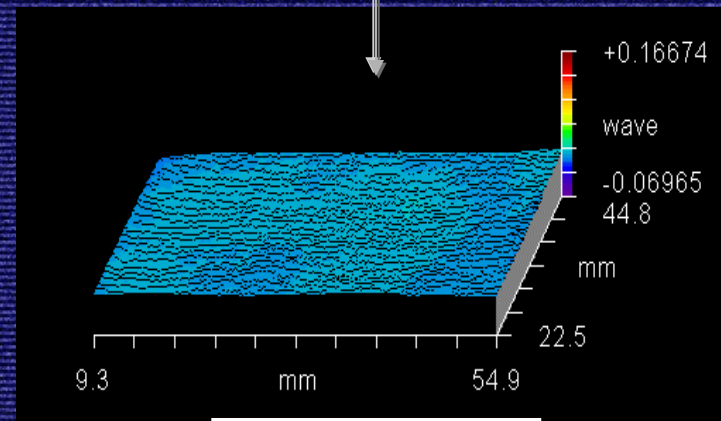
Transmitted Wavefront Correction

Fused Silica Right angle prism

Fused Silica Prism



60 minutes polish time

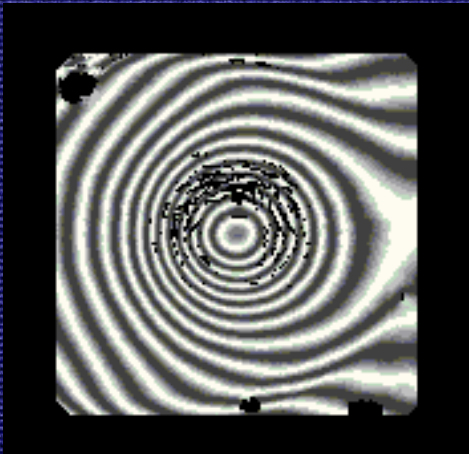


p-v: 0.024λ

Transmitted Wavefront

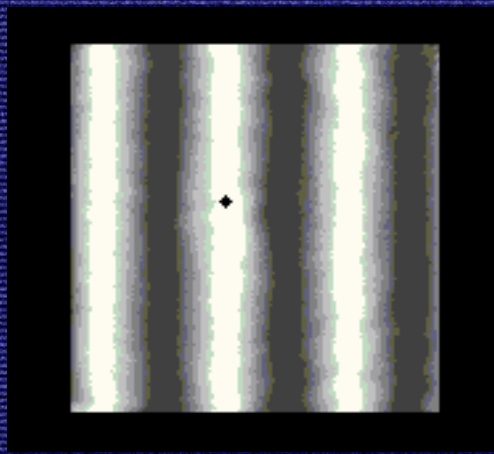
Nd:YLF Rods

Original



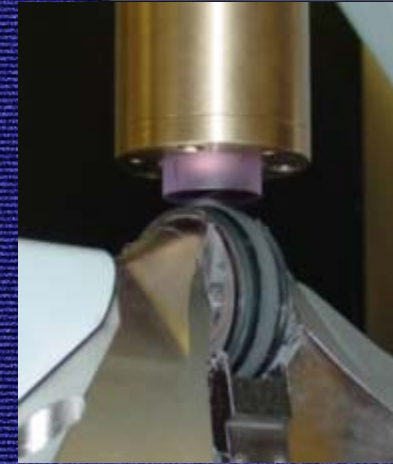
7.85 λ (p-v)
1.59 λ (rms)

After MRF

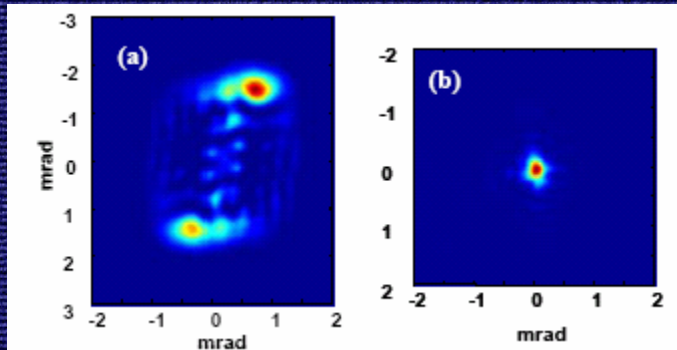


0.143 λ (p-v)
0.013 λ (rms)

Surface roughness < 7.0 Å (rms)



Central 15x15 mm² region of
25x100 mm Nd:YLF rod
($\lambda = 1053$ nm)



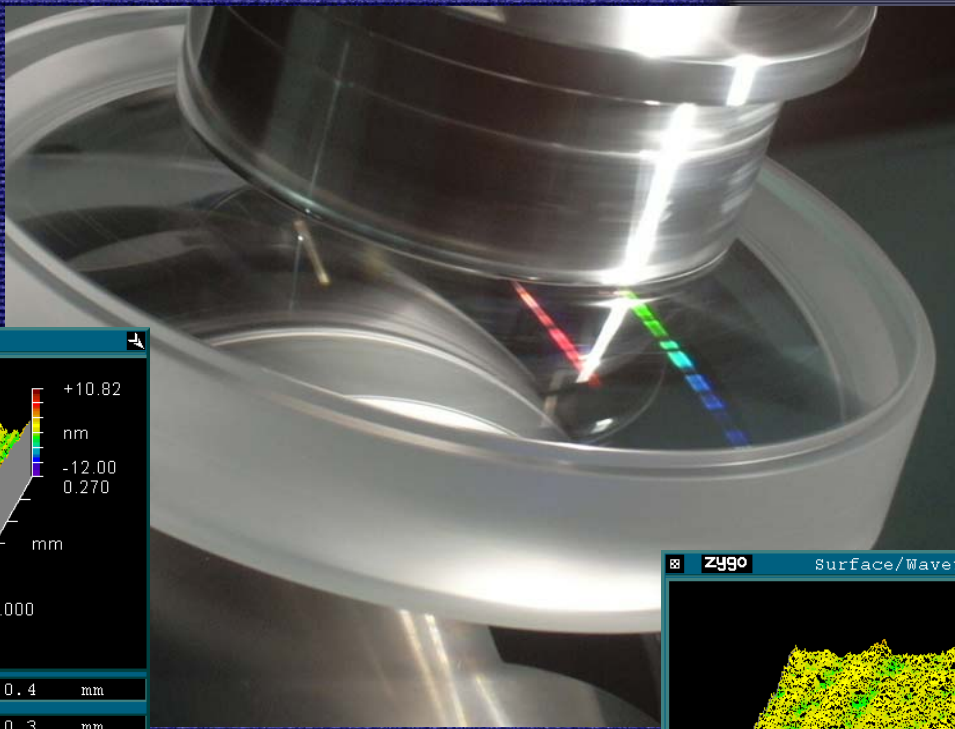
Far Field Measurements



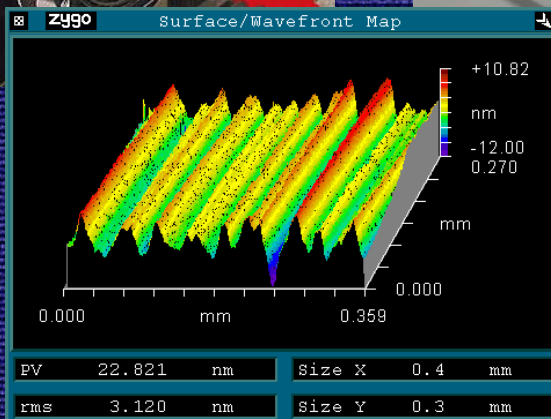
MRF deterministically
improves surface figure on
a lateral scale down to
~1mm.

High-energy, 5-Hz repetition rate laser amplifier using wavefront corrected Nd:YLF laser rods, by Vincent Bagnoud, Jason Puth, Jonathan D. Zuegel et al.

Improve SPDT surfaces

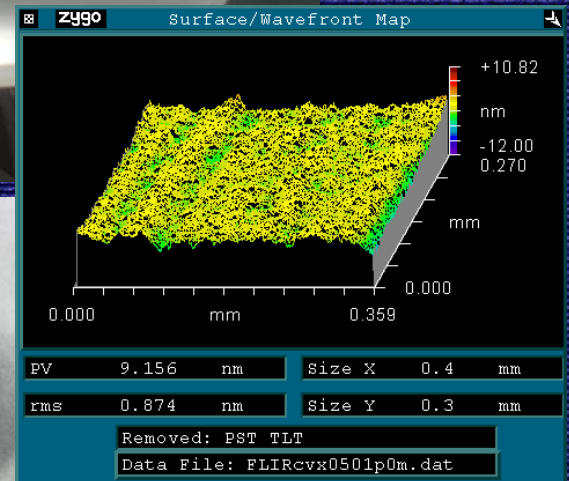


**Before
MRF**



Color

No Color



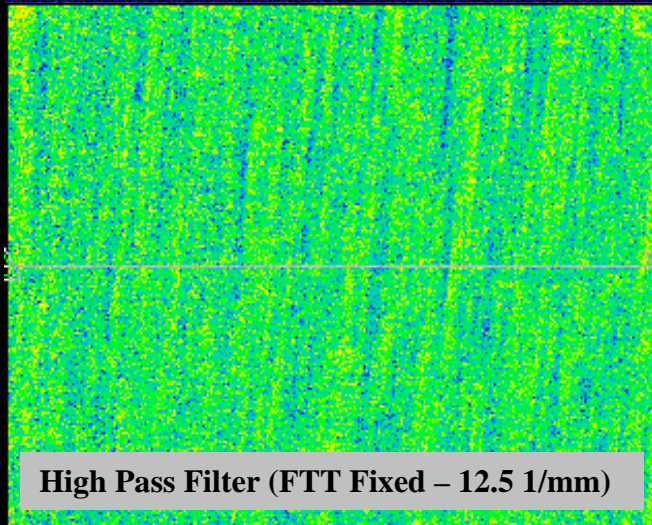
After MRF

Roughness

Cerium oxide or diamond based fluids

New-View 5000

359 x 270 μm

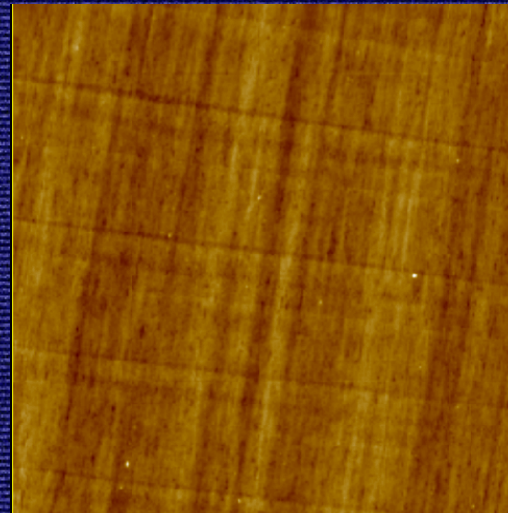


High Pass Filter (FTT Fixed - 12.5 1/mm)

Rmax	44.692	Å
Ra	2.829	Å
Rq	3.575	Å

AFM

10 x 10 μm



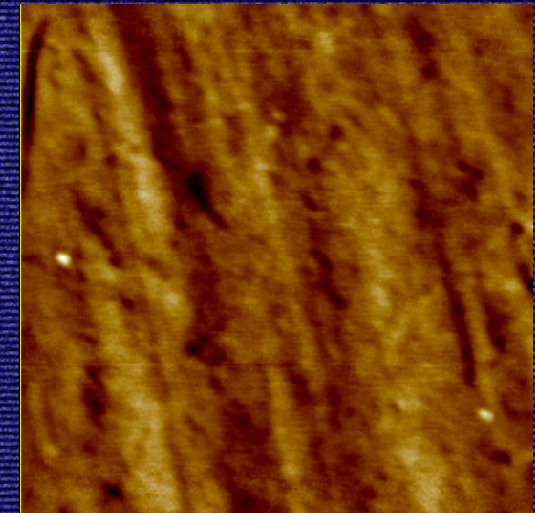
Rms (Rq) 0.347 nm

Ra 0.277 nm

Rmax 5.718 nm

AFM

1 x 1 μm



Img. Rms (Rq) 0.176 nm

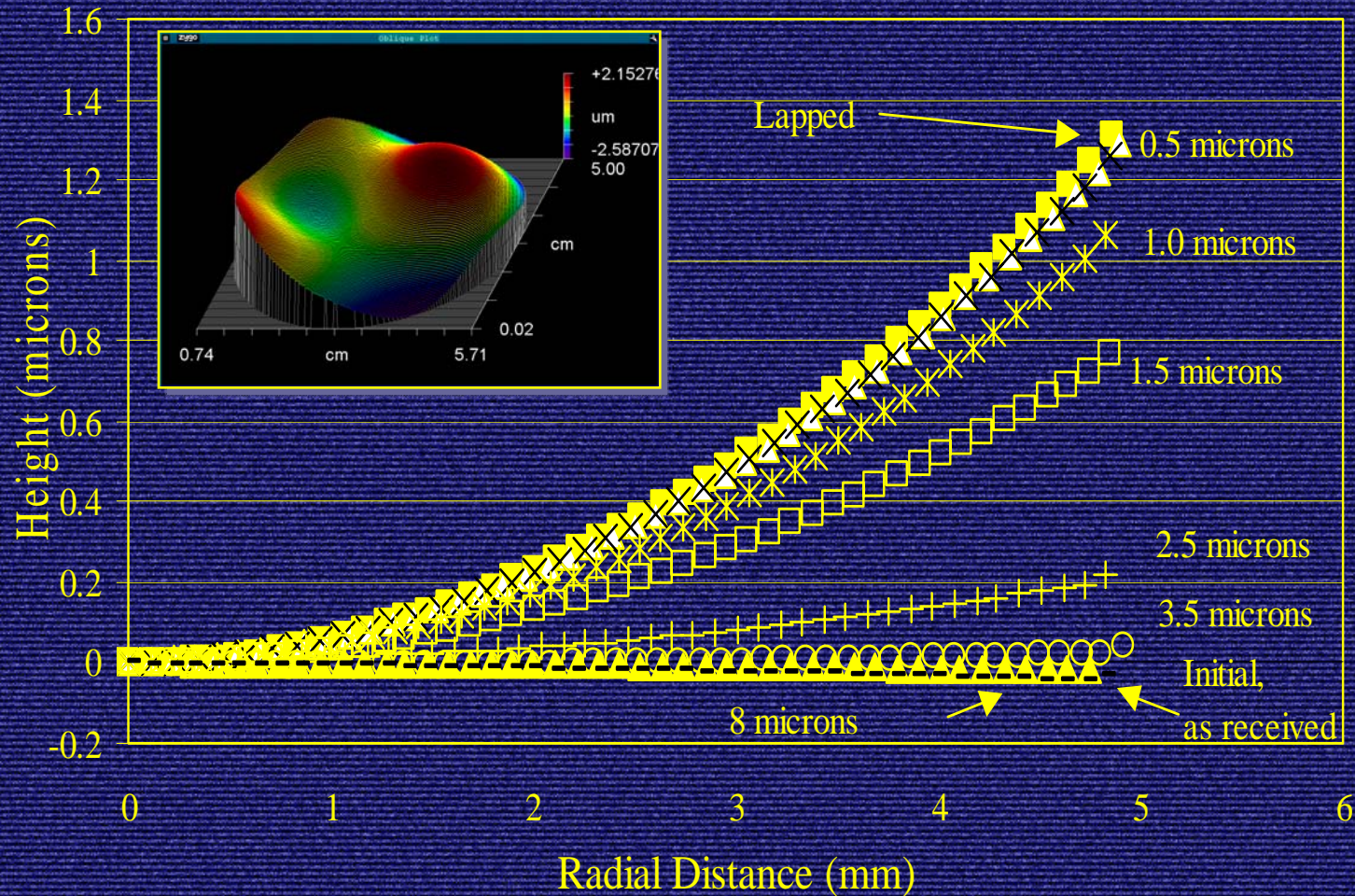
Img. Ra 0.136 nm

Img. Rmax 1.884 nm

Fused silica - round flat, 0.5 μm DC-run polishing

Improvements in Surface Integrity

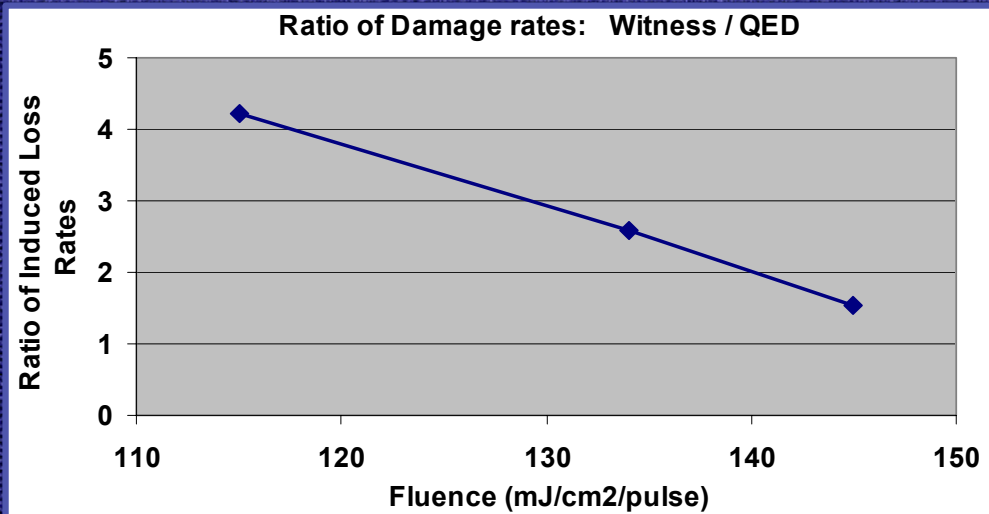
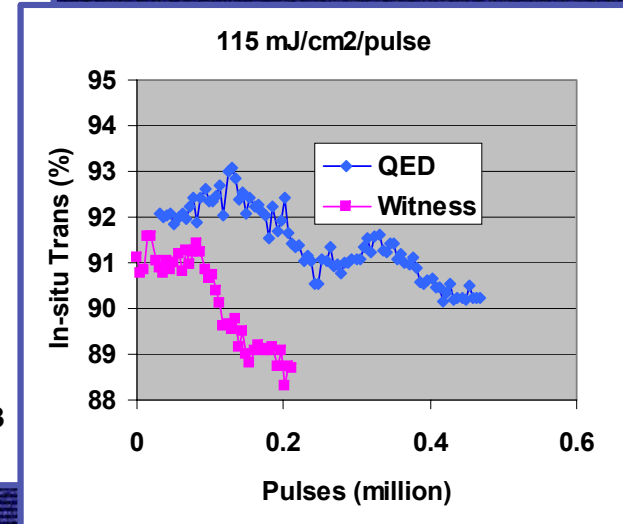
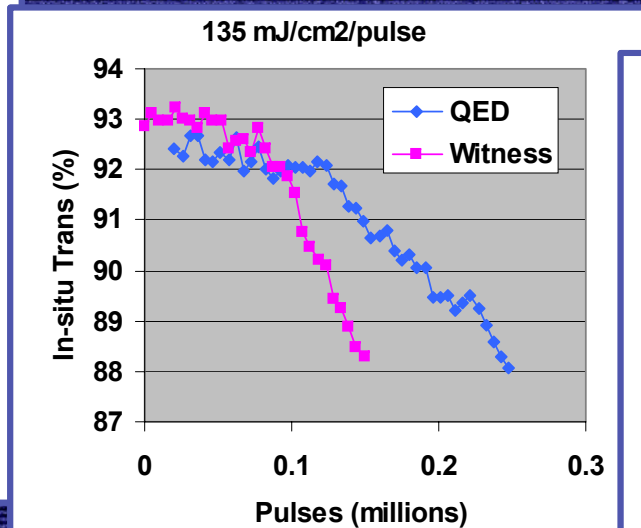
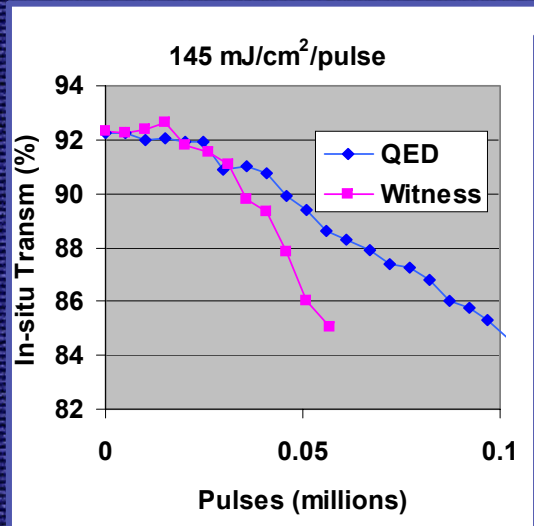
Residual stress removal



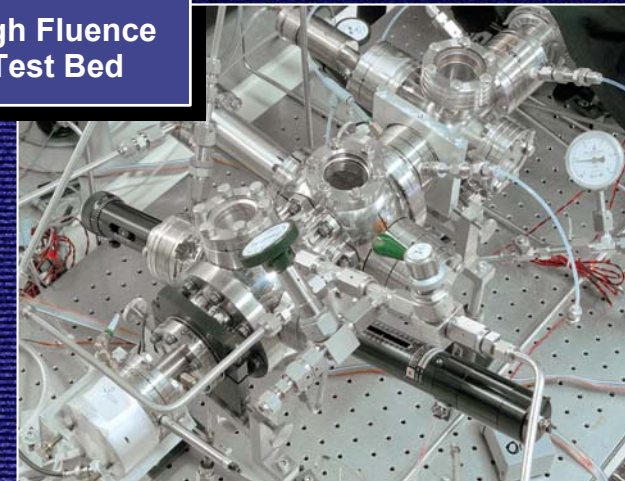
From: "Magneto-rheological Finishing (MRF) to Relieve Residual Stress and Subsurface Damage on Silicon Wafers", by Steven R. Arrasmith, Stephen D. Jacobs, John C. Lambropoulos, Alexander Maltsev, Donald Golini and William I. Kordonski.

MIT Lincoln Lab

157 nm Laser Damage Study on CaF₂

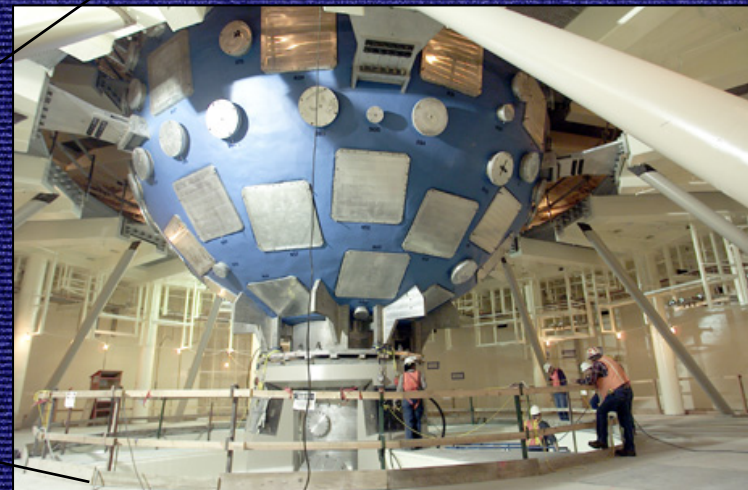
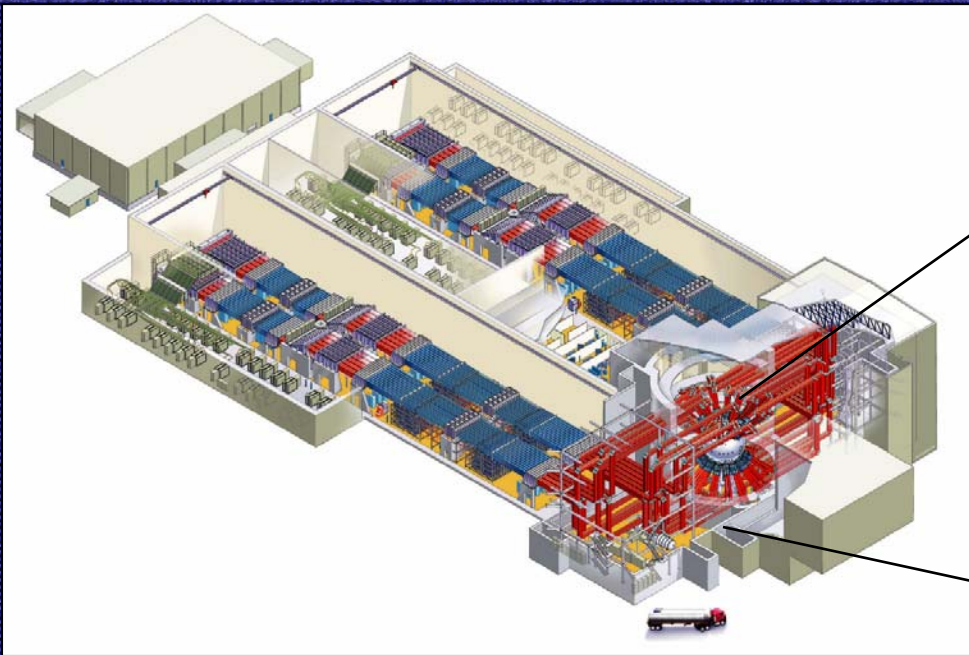
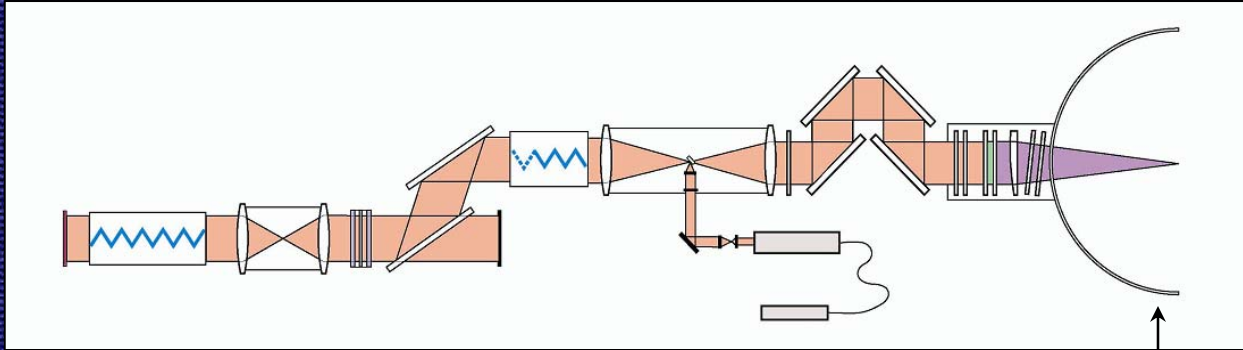


High Fluence Test Bed



Improvements in Surface Integrity

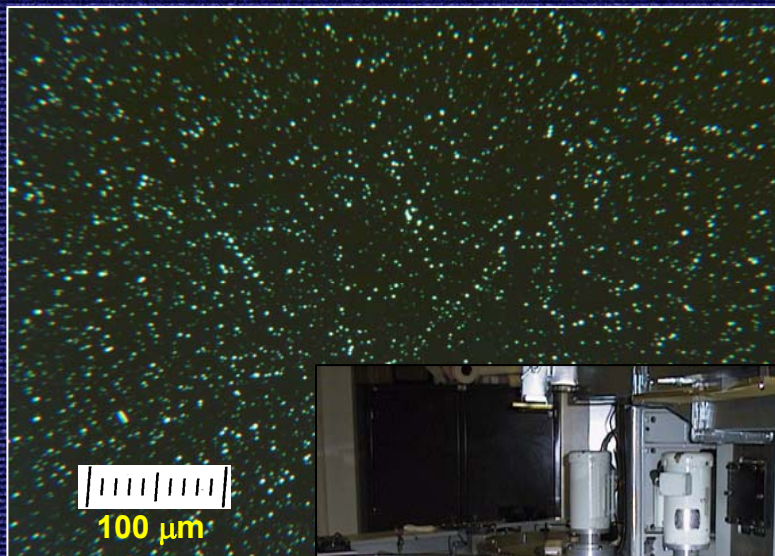
National Ignition Facility (NIF) at LLNL



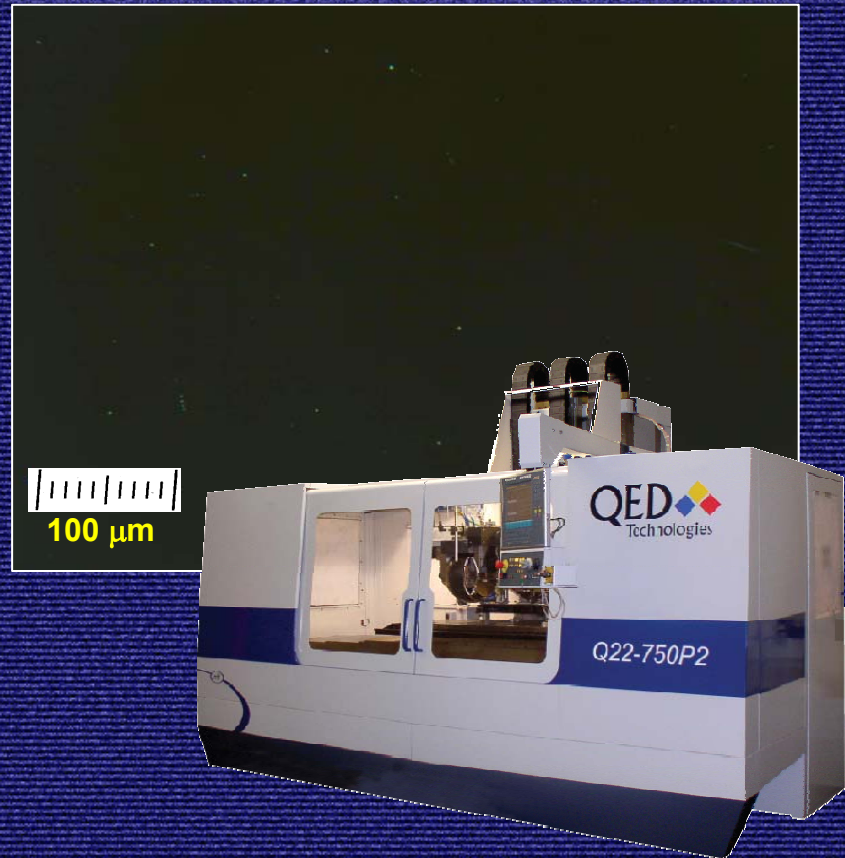
MRF polished and etched parts



Highest quality conventional polish



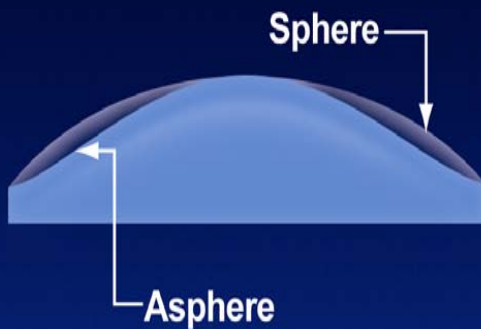
MRF polished part



Dark-field microscopy of etched MRF surfaces shows a near-absence of the sub-surface damage normally associated with conventional finishing

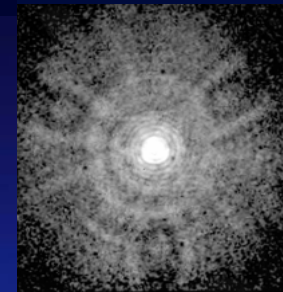
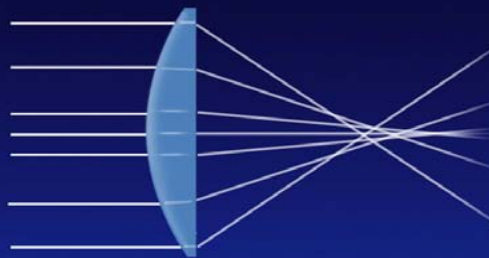
Aspheres

Spherical vs. Aspheric Optics

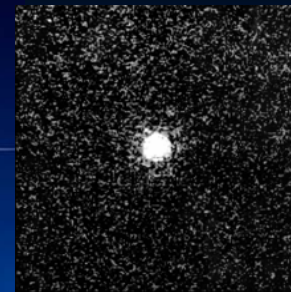
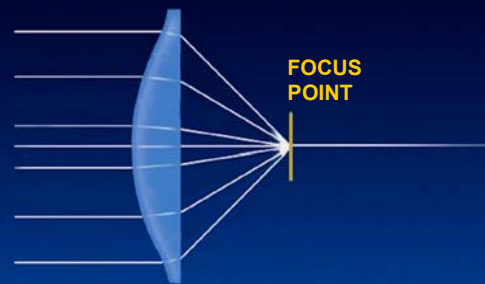


Aspheric optics provide performance advantages.

Spherical Aberration



Aspheric Correction



Pictures from the Hubble Space Telescope

MRF's Unique Attributes

MRF's unique attributes...

MR Fluid properties are
Precisely Controlled.

MRF tool is Subaperture.

therefore

MRF is Deterministic.

Lead to a unique asphere
manufacturing capability



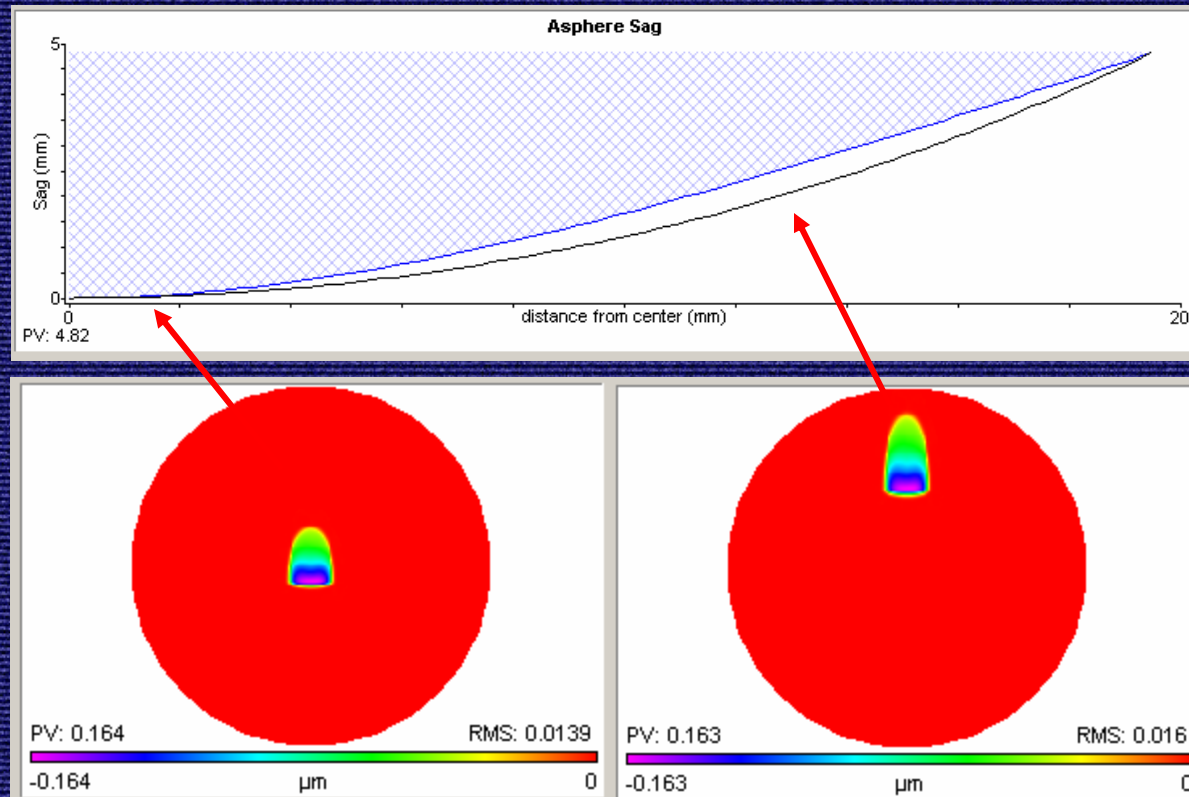
MRF Asphere Manufacturing:

1. "Mild" aspheres – Aspherize from a best fit sphere and figure correct
or
2. "Wild" aspheres – MRF figure correction following:
 - Diamond turning to aspheric
 - Ground aspheric shape
 - Intermediate pre-polish step
 - Direct from grind (in some cases)

Aspherizing from Best Fit Sphere

Asphere polishing with MRF

- Spot shape = F (local curvature)
- Impossible for conventional pads
- Algorithms to “morph” spot



MRF Aspherizing - "mild" aspheres

Complete Asphere Manufacturing

- MRF "aspherizes" or polishes in the aspheric shape from a best fit sphere
- MRF then figure corrects the optic

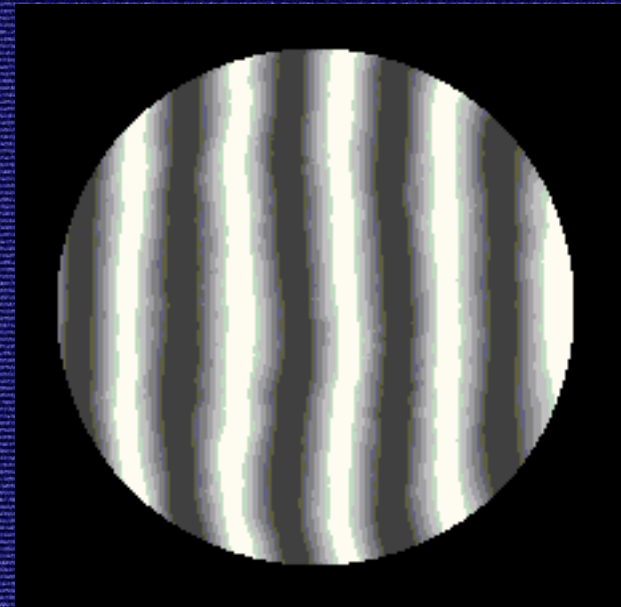
Before

- ❖ Hyperbola (conic constant = -1.355)
- ❖ OD 70 mm, CA 64 mm
- ❖ Convex base radius, $R = 272.539$ mm
- ❖ Best-fit radius = 274.059 mm (at an aperture of 70 mm)
- ❖ Aspheric departure = $3.1 \mu\text{m}$ (from best-fit sphere)

Results after 3 iterations

- ❖ (1) Shaping: 70 min
- ❖ (2) Figure corrections: 20 min and 5 min

Deviation from asphere



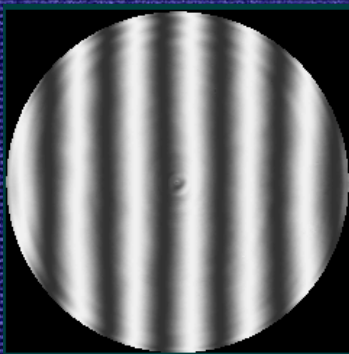
P-V $\lambda/10$, rms $\lambda/60$

**(over the 64 mm CA
in reflection)**

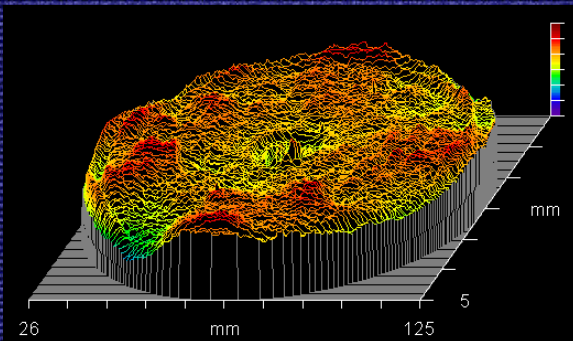
MRF Aspherizing - "mild" aspheres

BK7 Aspheres produced with MRF

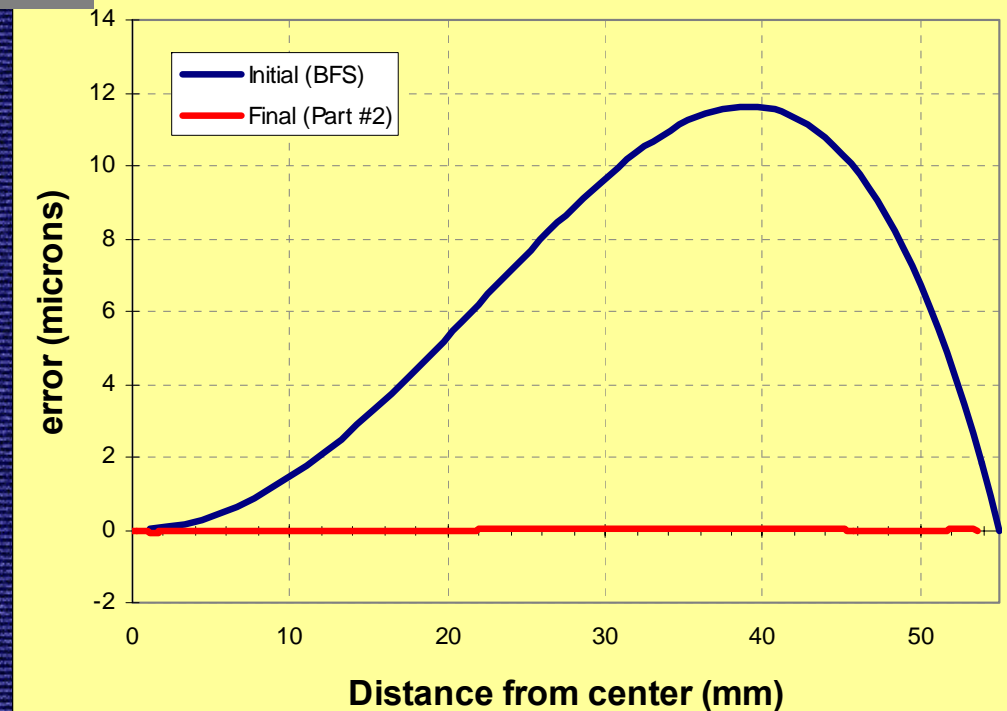
MRF aspherizes and
then figure corrects



Trial #1
0.185λ p-v
0.015λ rms



Initial & Final Error from Desired Aphere



- Aspheres are 110 mm diameter with 11 microns of departure.
- Total run time was ~5 hours per lens.

Large Optics

❖ Optics getting larger and larger

- Size and/or number of segments increasing

❖ Manufacturing time decreasing

- From month(s)/m² to day(s)/m²

❖ Increasing light-weighted structures

- From 100's kg/m² to <10 kg/m²
- Decreasing face sheet thickness
- New materials (e.g. SiC, Be, porous Si etc.)

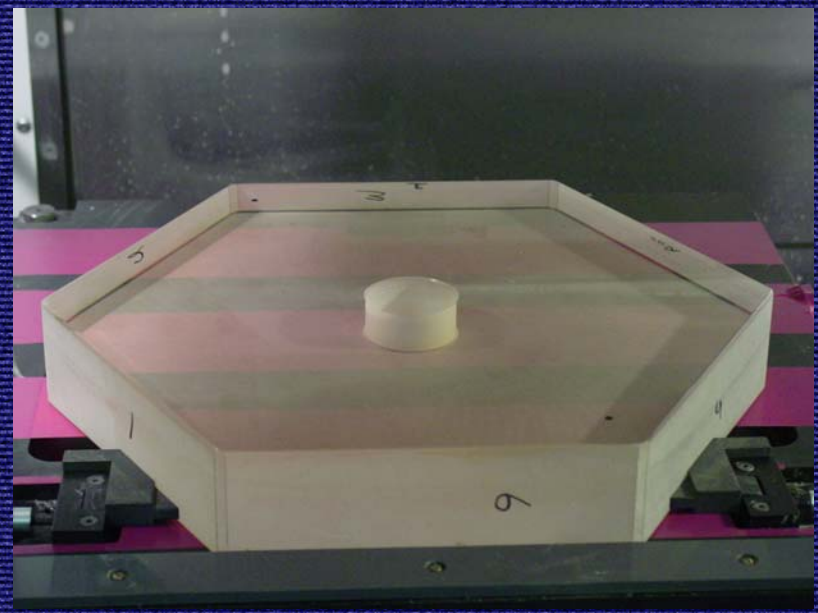
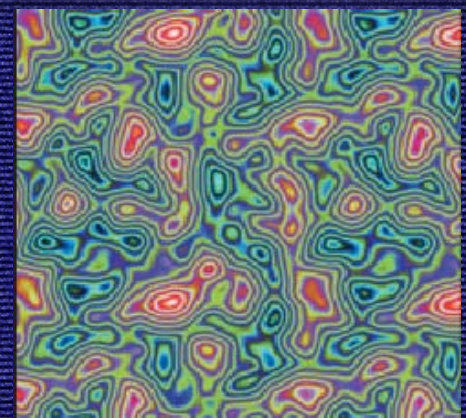
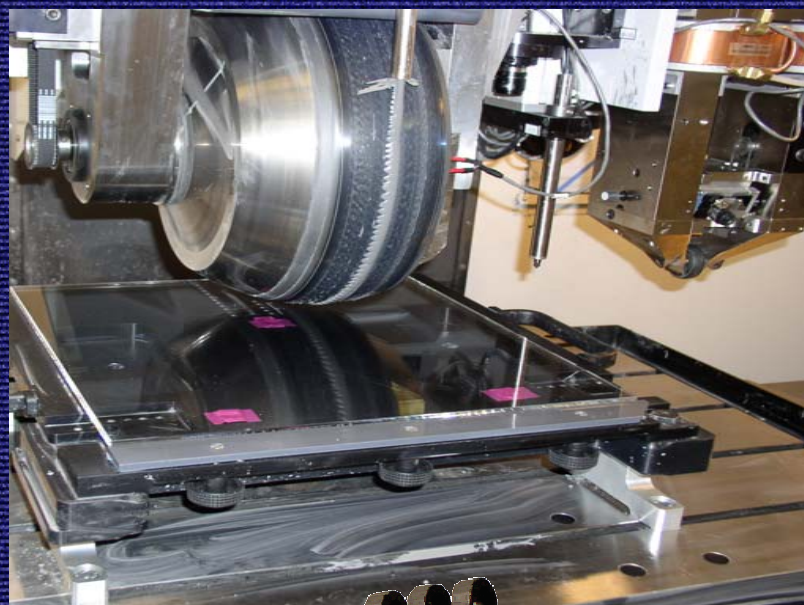
❖ Specifications tightening

- Figure, mid-spatial frequency and roughness
- Edge exclusion going to zero (for segment design)
- More challenging shapes: aspheres, off-axis etc.

❖ Costs decreasing

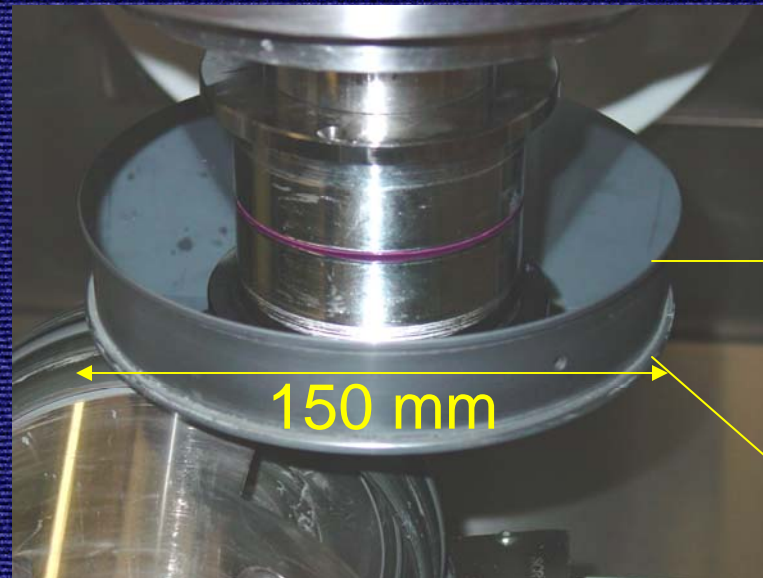


Q22-750P2 Polishing

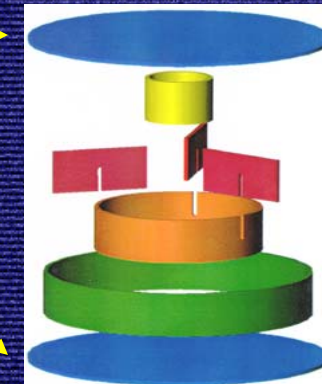


Light-weighted optics

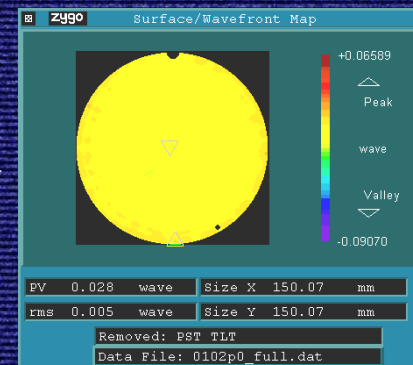
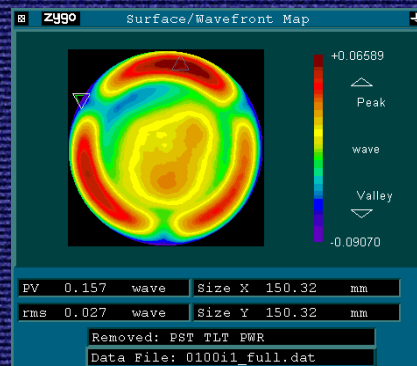
MRF Fixing quilting errors



McCarter Light-Weight
Si Mirror
Areal Density = 25 kg/m²

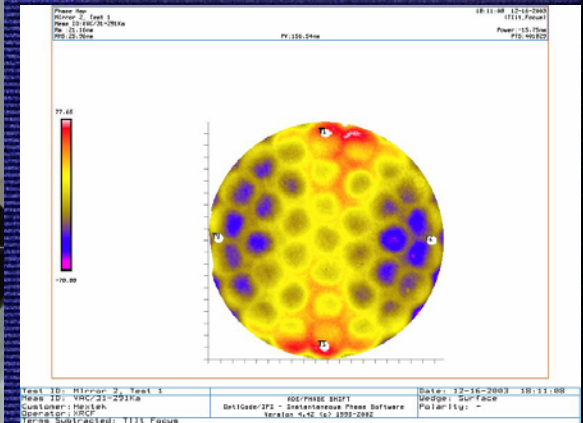
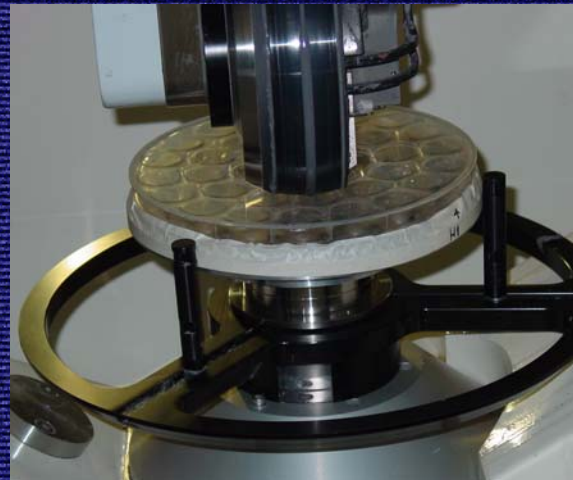
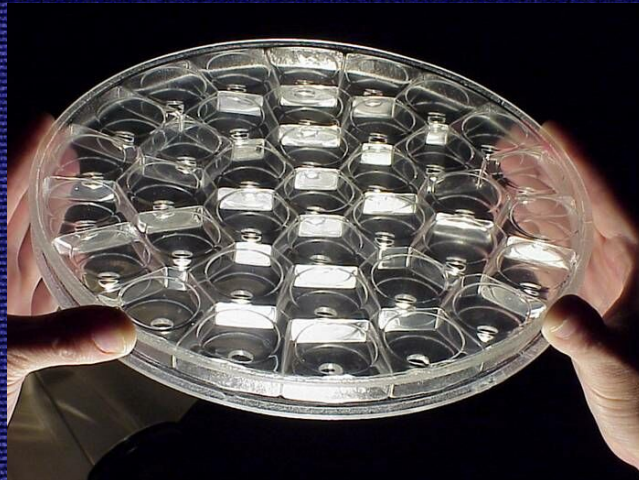


Quilt Error



Light-weighted optics

MRF Fixing quilting errors – Add'l examples



Hextek Gas Fusion™ Borosilicate 15 kg/m² mirror blank

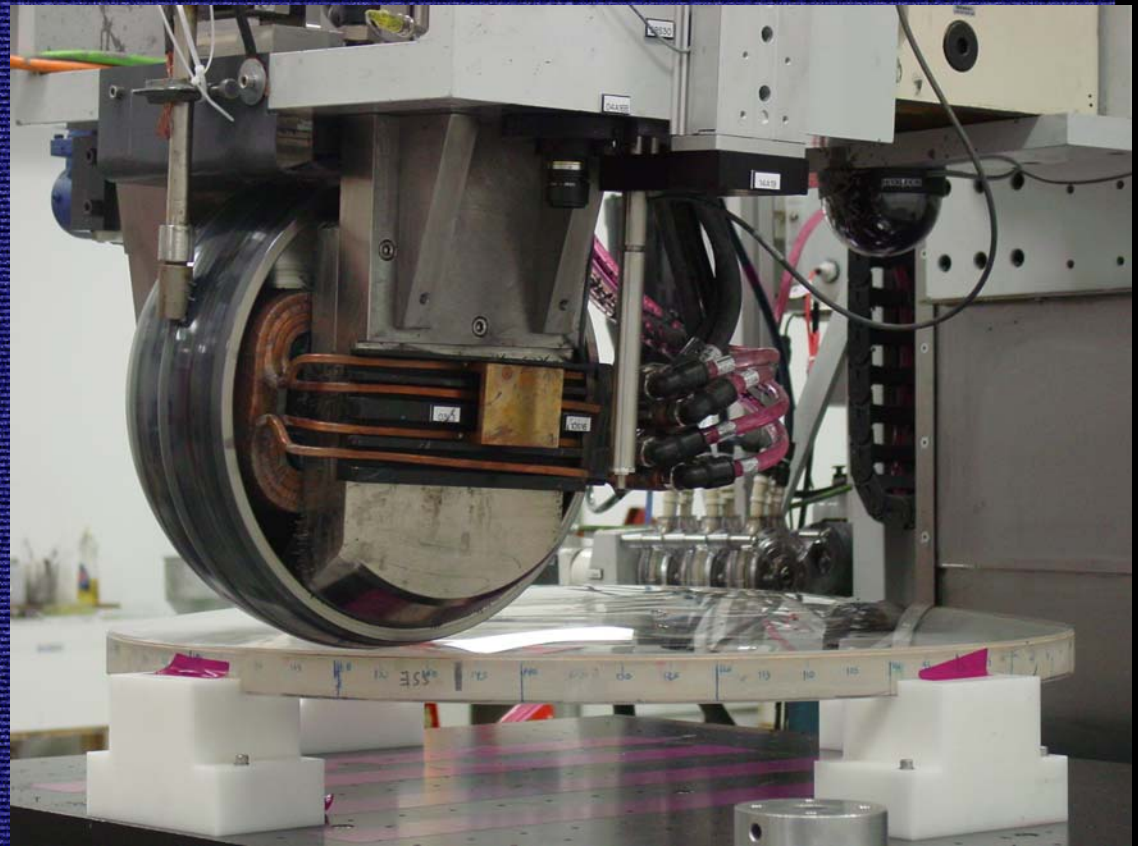
Correct cryo-quilting



CoorsTek lightweight SiC mirror 20 kg/m²

Q22-950F Large Asphere Polishing

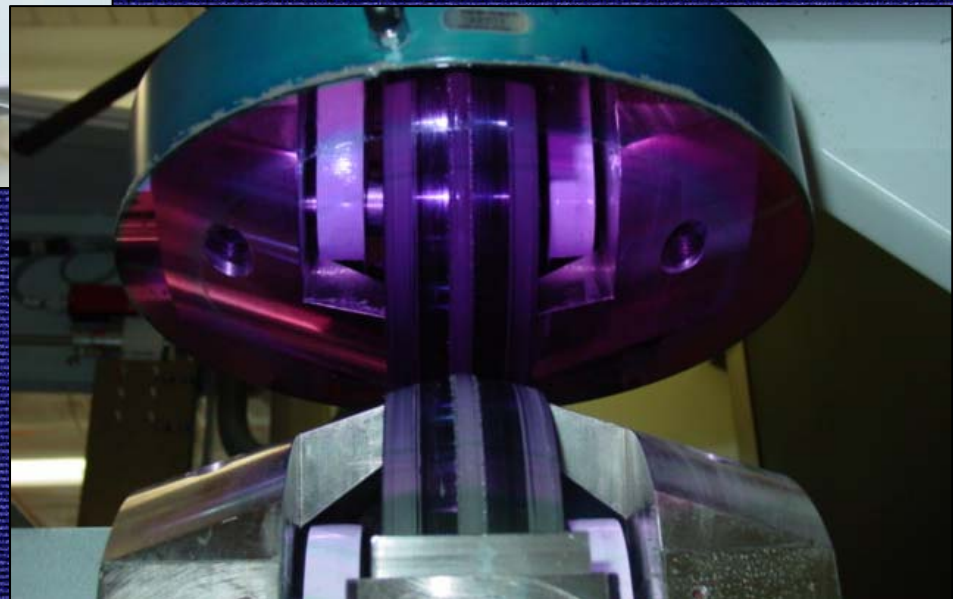
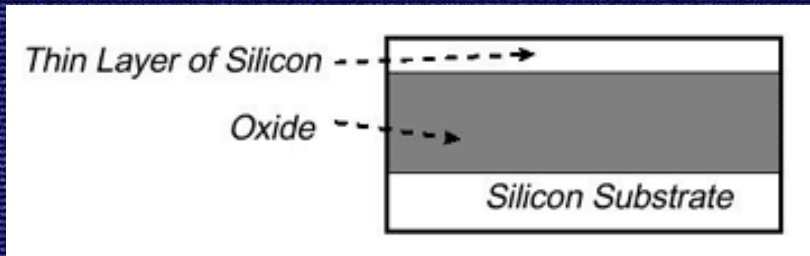
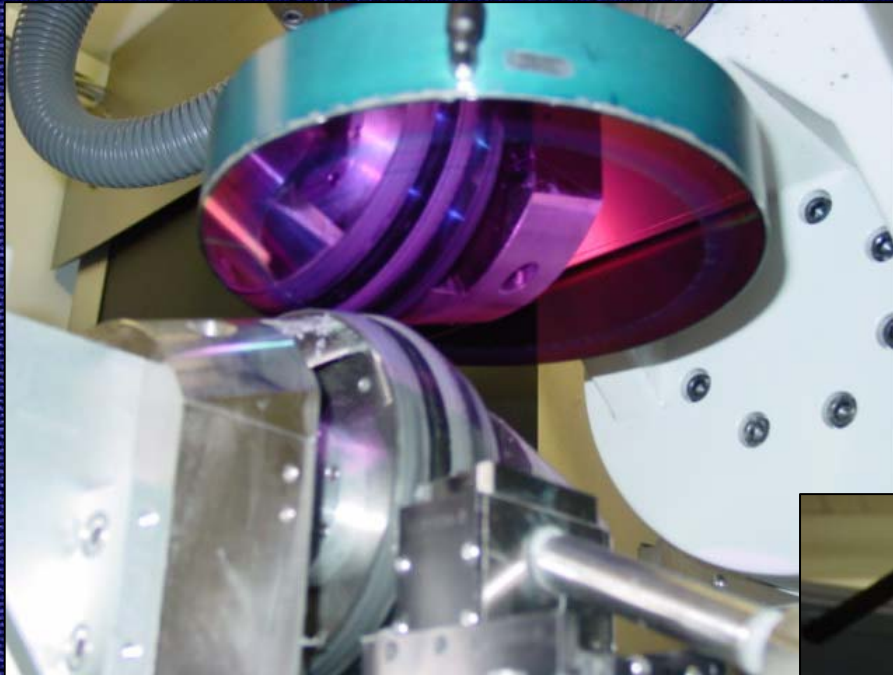
- ❖ **Asphere ~ 1,300 μm (1.3mm!) of departure from BFS**
- ❖ **Fused Silica**
- ❖ **840mm in diameter**



Asphere Polishing Video

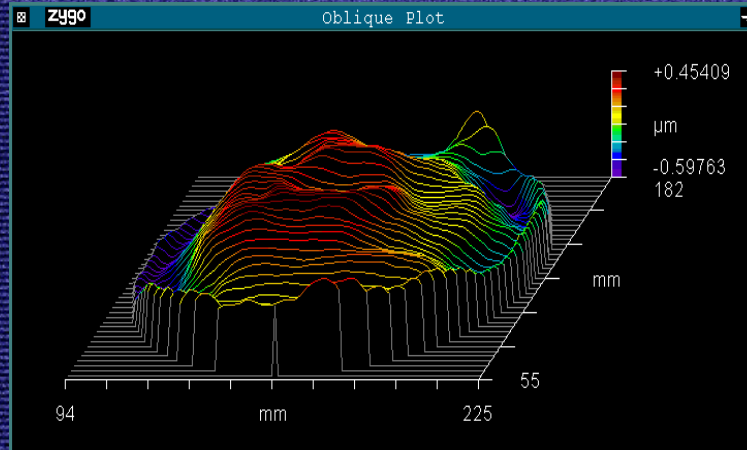


SOI Wafer

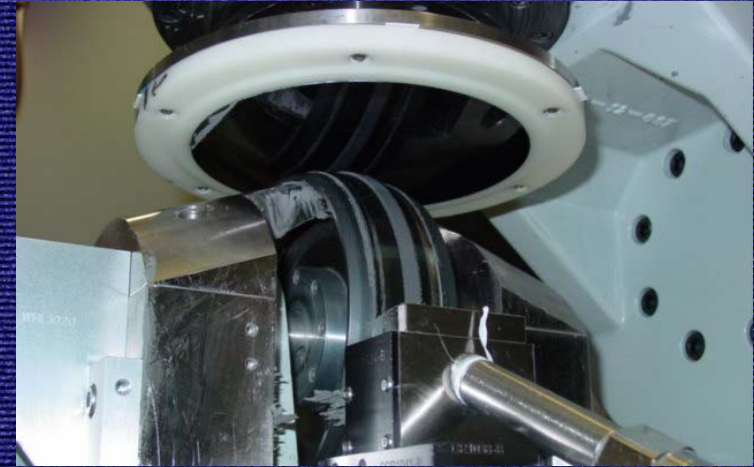


Thick film 150mm SOI wafer

Initial Condition



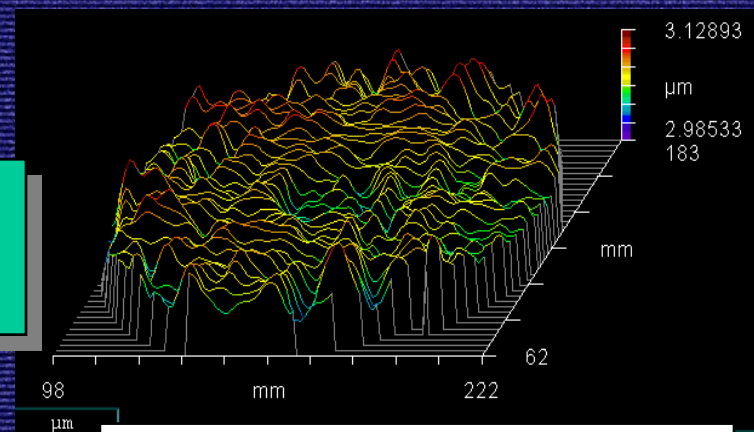
**Thickness: 5.36 μm
with TTV of 1.131 μm**



**2 MRF
Corrections**



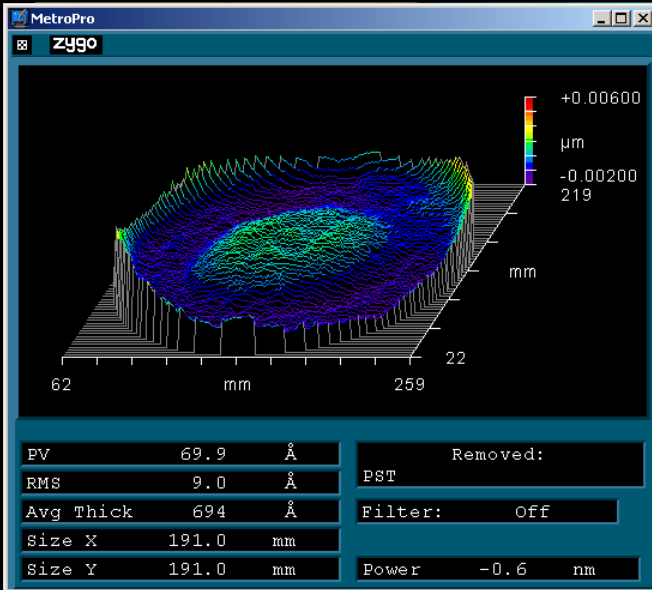
Measured over 130 mm



**Thickness: 3.07 μm with
TTV of 0.144 μm**

Thin film 200mm SOI Wafer

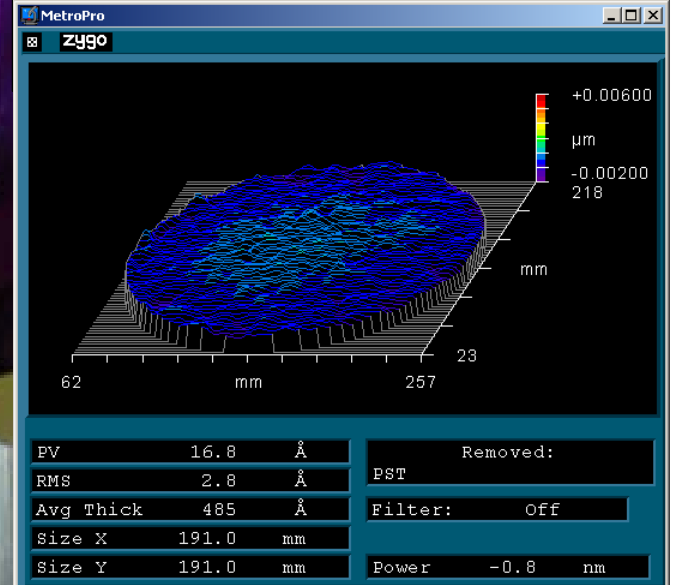
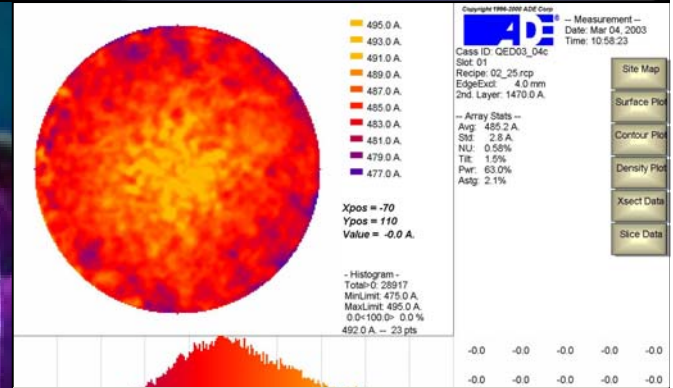
Thickness variation



Before MRF:
 Range (PV) = 70 Å
 Std (rms) = 9.0 Å
 Avg Thick = 694 Å



1 mm spacing, 191 mm aperture



After 2 Runs:
 Range (PV) = 17 Å
 Std (rms) = 2.8 Å
 Avg Thick = 485 Å

Outline

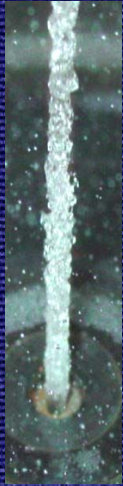
- ❖ Overview of Magnetorheological Finishing (MRF)
- ❖ MRF Applications
- ❖ **Jet Finishing**
- ❖ Subaperture Stitching Interferometer (SSI)
- ❖ SSI Applications
- ❖ Conclusions

MR Jet Polishing

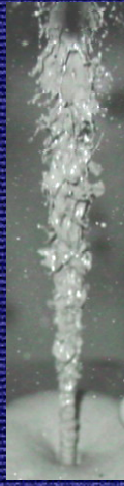


- ❖ For special geometries
- ❖ Jet of MR fluid
- ❖ Polish steep/deep concave surfaces
- ❖ Polish magnetic materials
- ❖ Stable spot over large range of standoff distances
- ❖ Same shear-based removal process

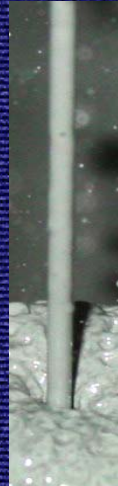
MR Jet™ Prototype



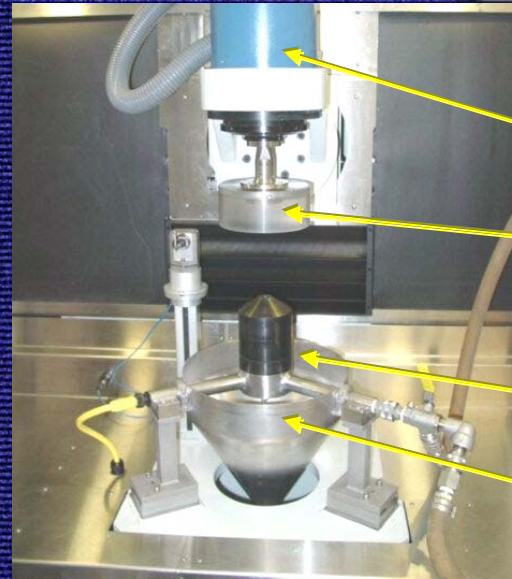
Water



MR Fluid,
Magnet off



MR Fluid,
Magnet on



Spindle

Part

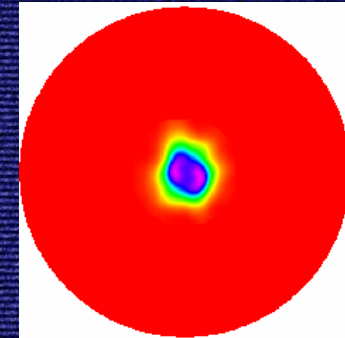
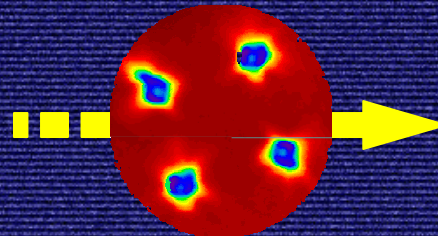
MR Shaper

Fluid Collection

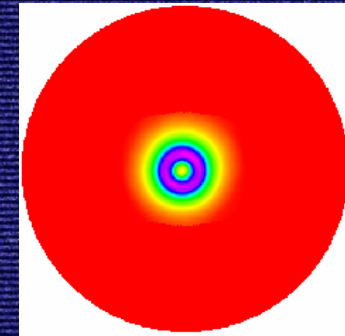
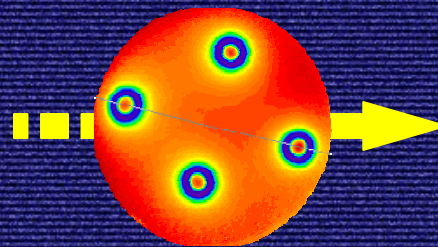
- ❖ A fluid jet can be stabilized by using a magnetorheological fluid and a magnetic field
- ❖ This stabilized jet gives significant advantages in finishing complex shapes
- ❖ Contained in the CNC machine with stable delivery system, MR Jet is used for polishing challenging shapes to high precision

MR Jet Removal Function Stability

Magnet Off
Non-deterministic

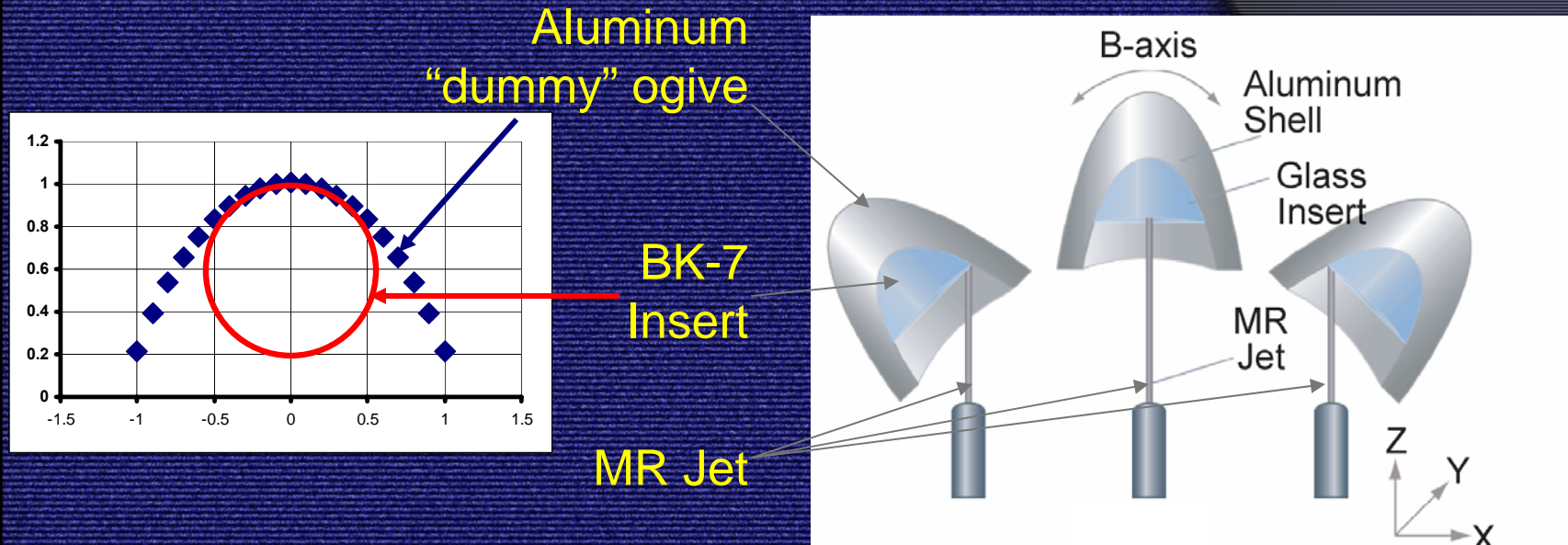


Magnet On
Deterministic



- Stability provided by MR Jet enables *deterministic finishing* at large stand-off distances

Polishing *Inside* an Ogive Dome



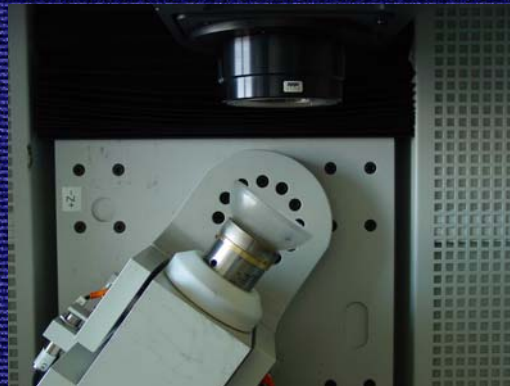
- ❖ Concave sphere in tip of aluminum "dummy" ogive
- ❖ $R = -20$ mm, Dia. = 25 mm
- ❖ ~49 mm sag, ~60 mm diameter
- ❖ Normal incidence between part and jet is maintained



Dome Polish – MR Jet



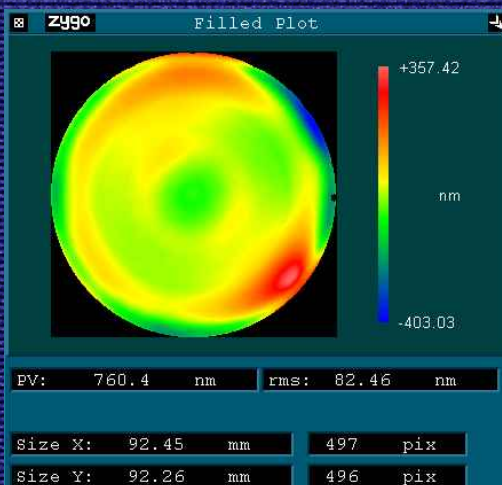
Glass Dome



Concave surface in
SSI



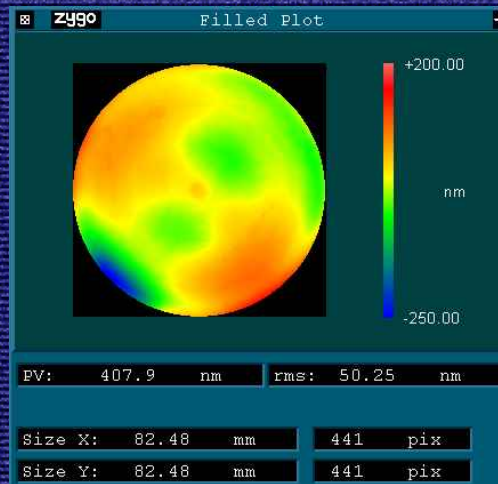
Glass dome prior to
MR Jet



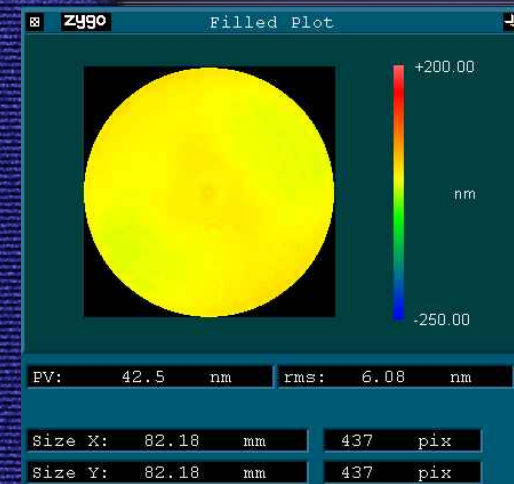
Example of conventionally
polished concave surface
measured in reflection

- 97 mm diameter, 2.5 mm thick Fused Silica dome
- Measured in reflection in SSI
- Concave surface polished with MR Jet
- Initial surface error > 1 wave error over full aperture

FS Dome Polish – MR Jet Results



Initial
408 nm P-V
50.3 nm RMS



Final
42.5 nm P-V
6.1 nm RMS

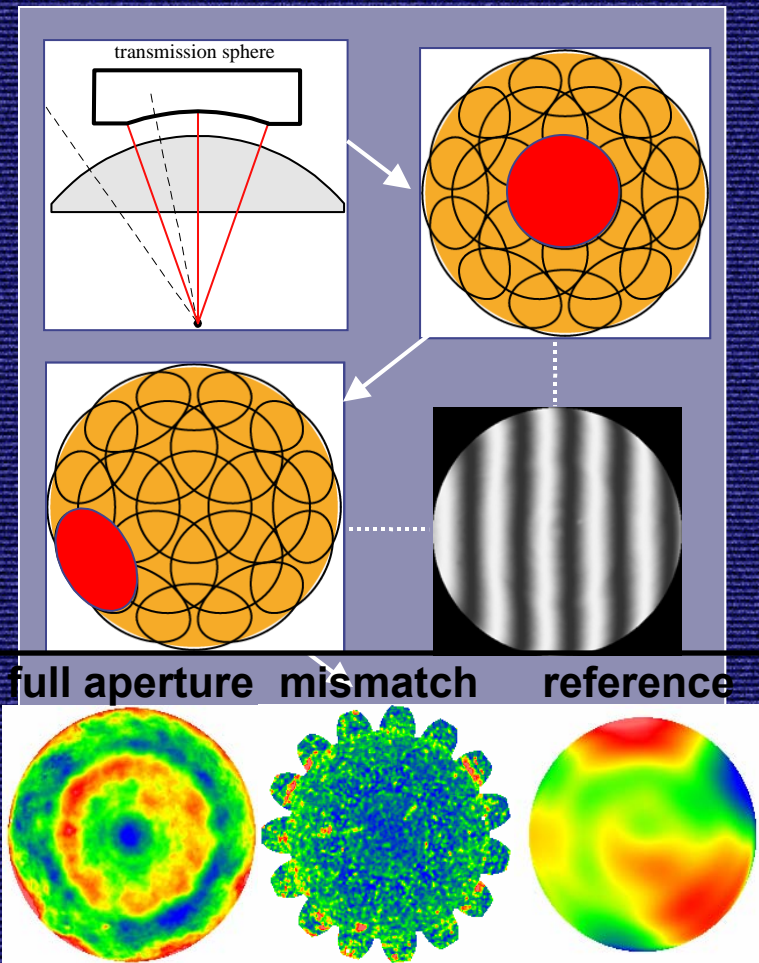
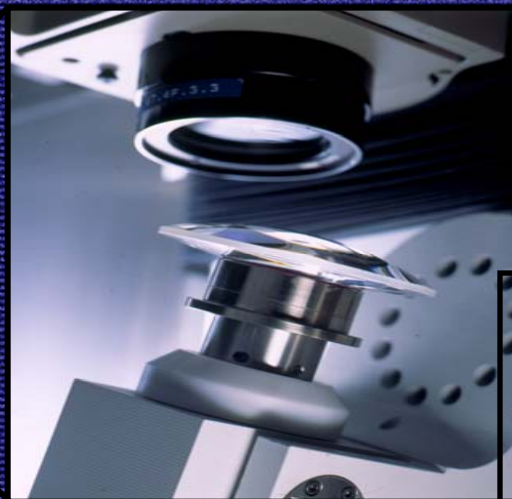
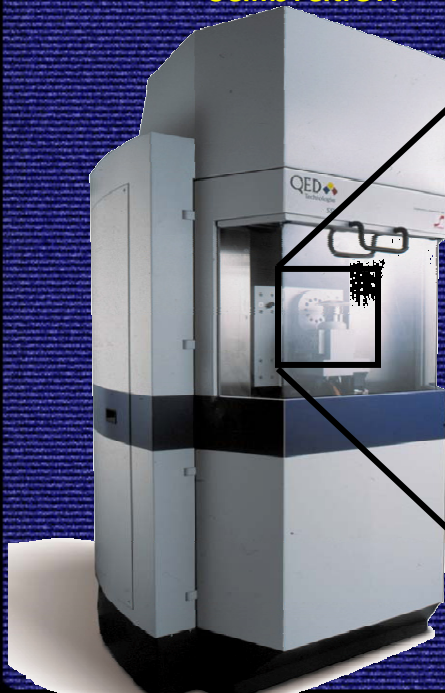
- Improved figure error from 408 nm P-V (50.2 nm RMS) to 42.5 nm P-V (6.1 nm RMS)
- MR Jet was able to polish this high aspect ratio dome to high precision
- This technique provides an opportunity to correct the concave surface of a dome, and other challenging shapes, to high precision
- Future applications will include more aerodynamic conformal shapes

Outline

- ❖ Overview of Magnetorheological Finishing (MRF)
- ❖ MRF Applications
 - ❖ Jet Finishing
 - ❖ **Subaperture Stitching Interferometer (SSI)**
 - ❖ SSI Applications
- ❖ Conclusions

Innovative Metrology: SSI

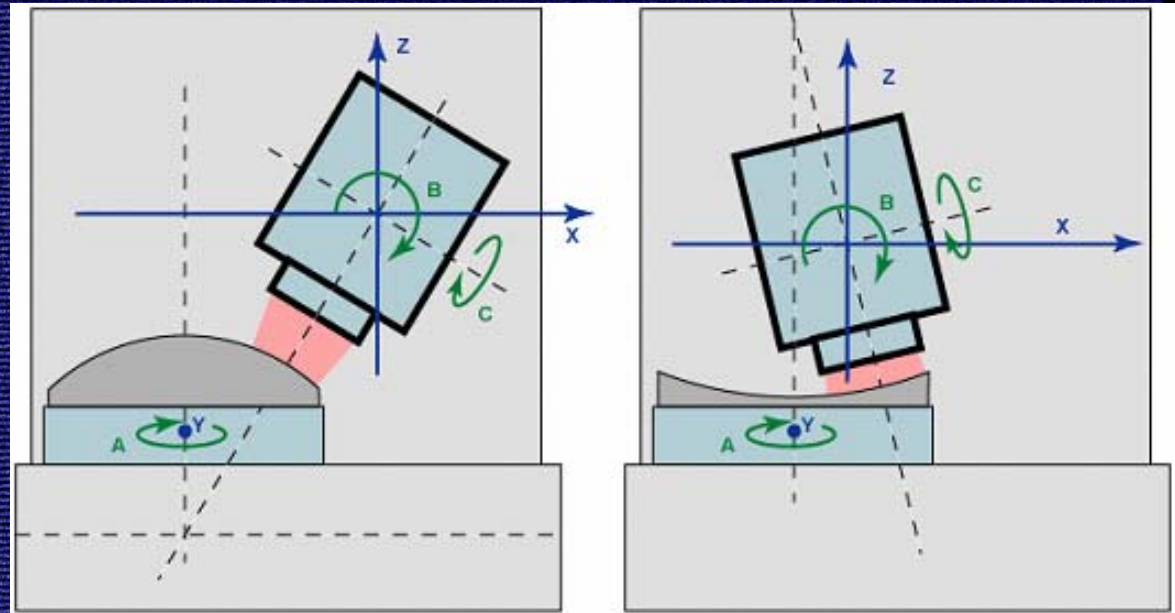
- ❖ Full aperture measurement of large NA & CA parts
- ❖ Completely Automatic
 - Auto-Positioning, nulling, & radius testing
- ❖ Intuitive & Easy to Operate
 - ❖ Reference wave, distortion, pixel scale calibration



Large Aperture Metrology



Large aperture lens mounted in QED's SSI.



Schematic representations of a six-axis platform for performing stitching interferometry on large aperture convex and concave parts.

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 - ❖ **SSI Applications**
- ❖ Conclusions

Stitching a Large AION Dome Lattice & Motions

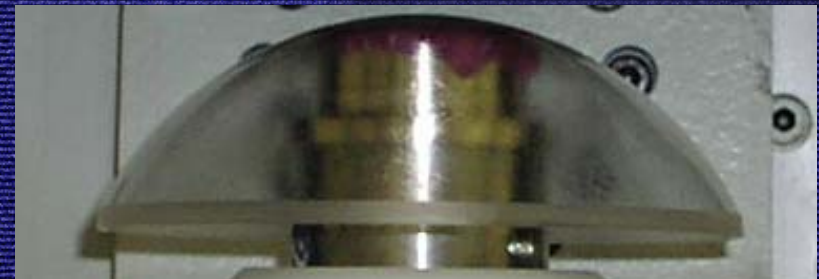
Aperture – 148.34 mm (5.84")

Radius – 82.55 mm (3.25")

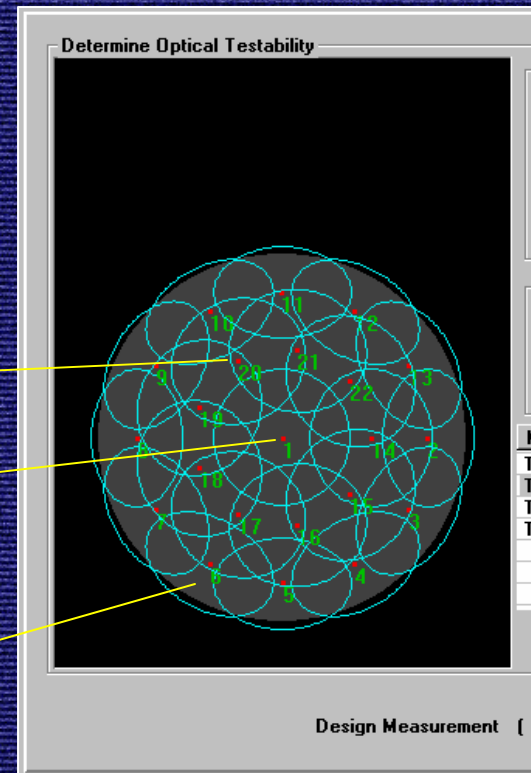
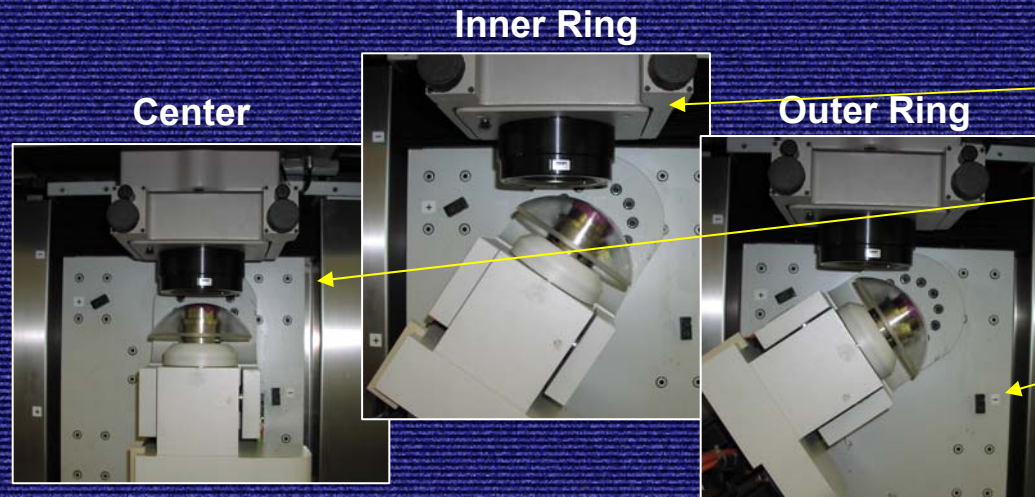
CT – 3.04 mm (0.12")

Sag – 50.39 mm (1.984")

F/0.55



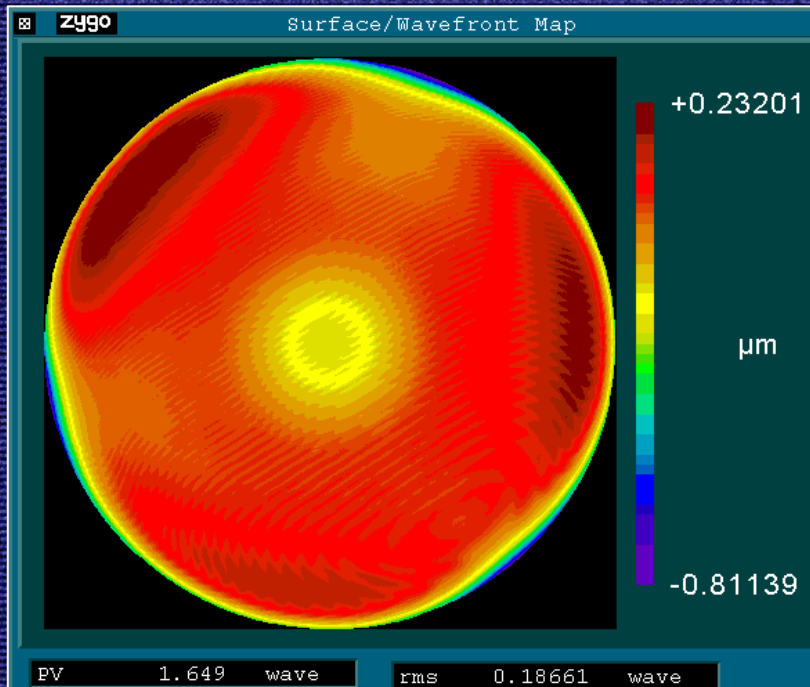
Objective - Zygo 4" f/1.5
 Subaperture = 55.1 mm
 Required 25 subapertures –
 (4 center, 9 inner, 12 outer)



Stitching a Large ALON Dome Results

Full Aperture Stitched Result

Reference Wave Error



Radius: 82.6 mm

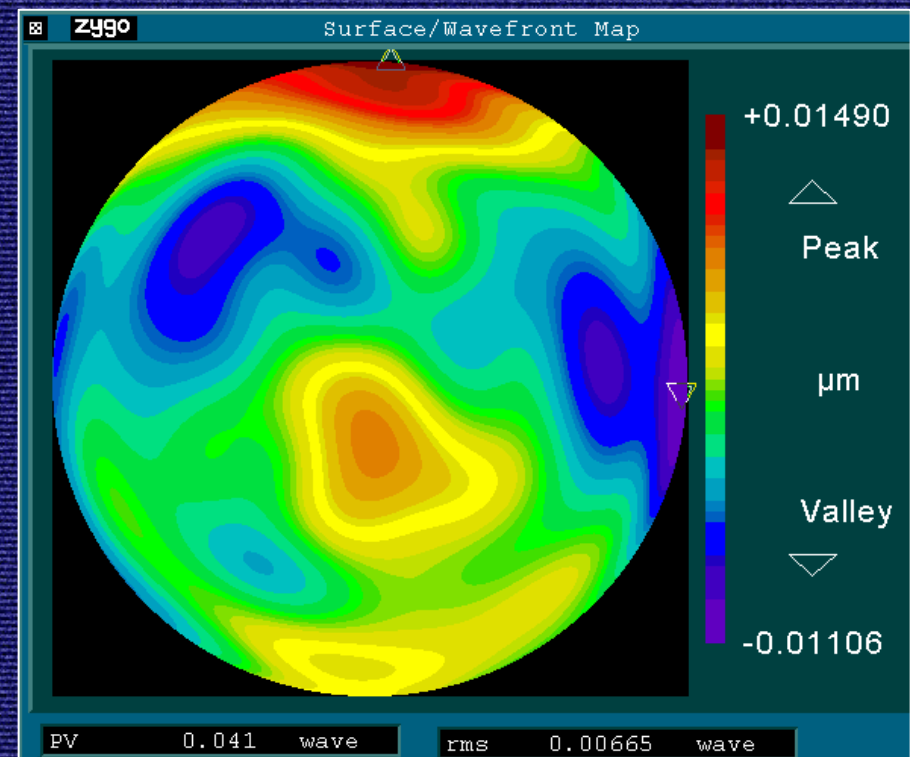
Surface:

PV – 1.649 λ (@ 633nm)

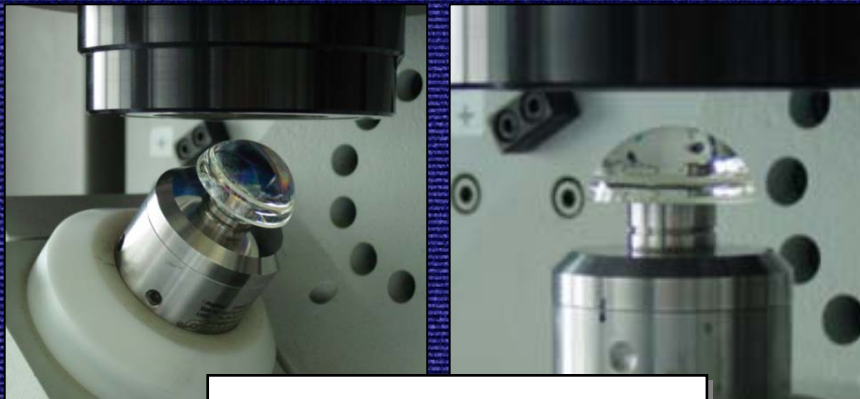
Rms – 0.187 λ (@ 633nm)

Total measurement time:

12 minutes!!



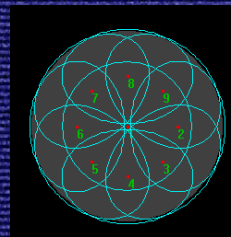
MRF/SSI Hemisphere Demonstration



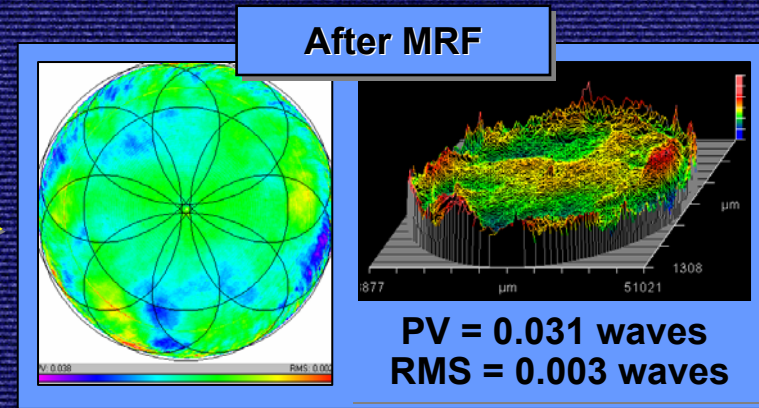
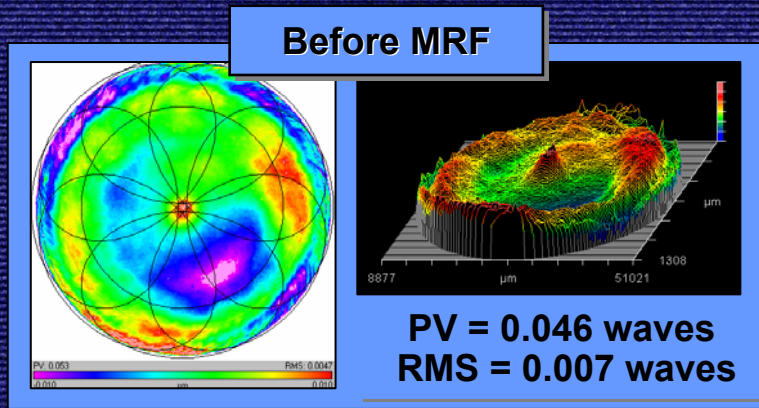
Full aperture: 42.6 mm
RC: 21.6 mm R/#: 0.51

- **Polished on the Q22-Y**
 - 7 minute polishing run
 - from $\lambda/20$ to $\lambda/30$
- **Measured on the SSI**
 - live on the exhibit hall floor

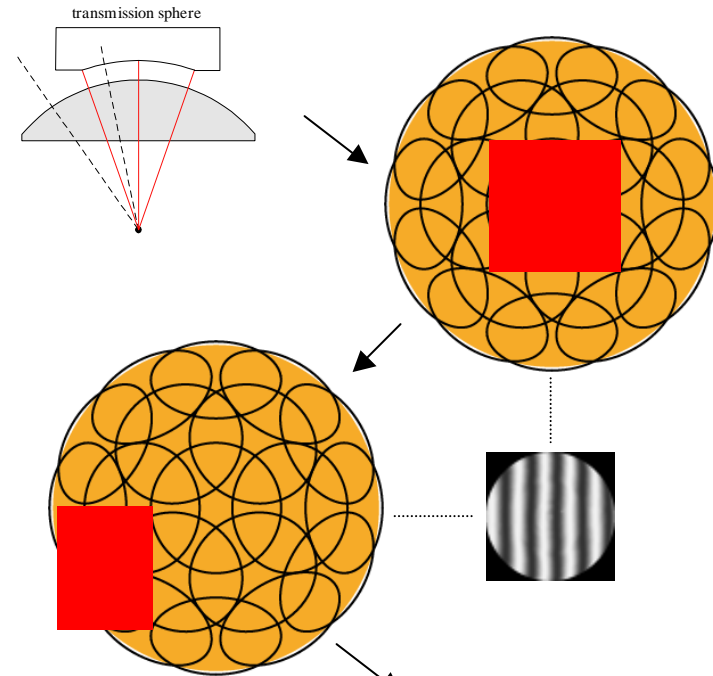
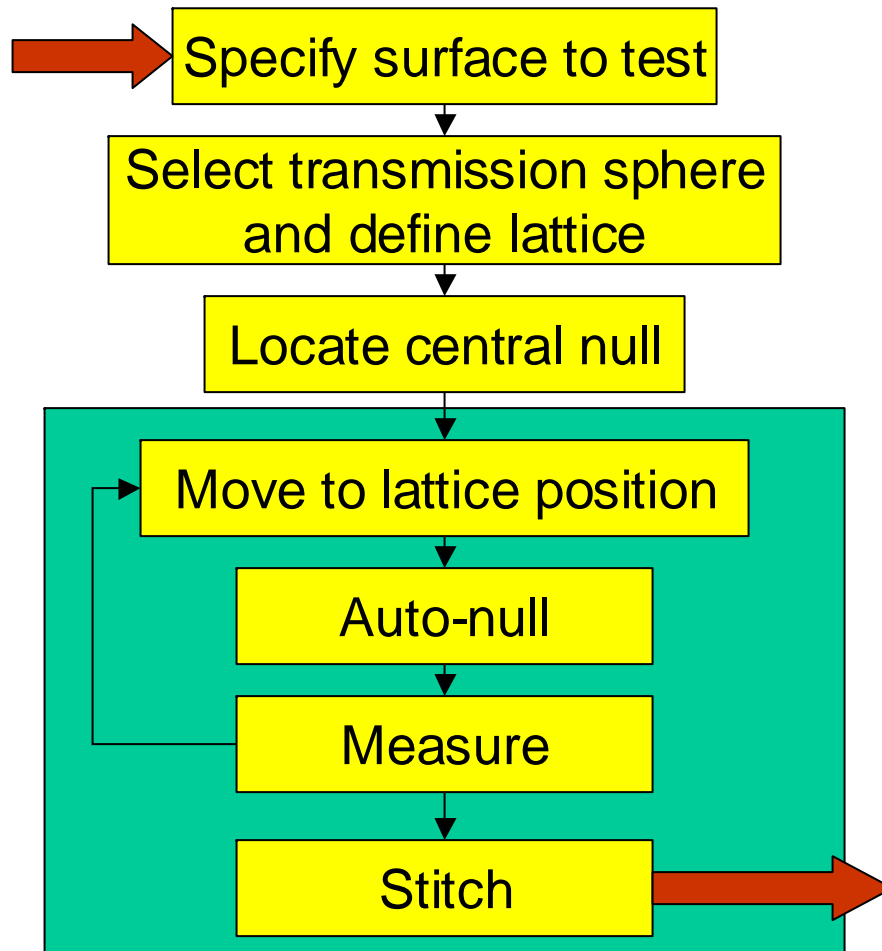
*Zygo 6" Verifire AT
4"/0.75 transmission sphere*



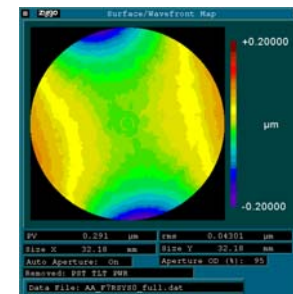
Lattice design



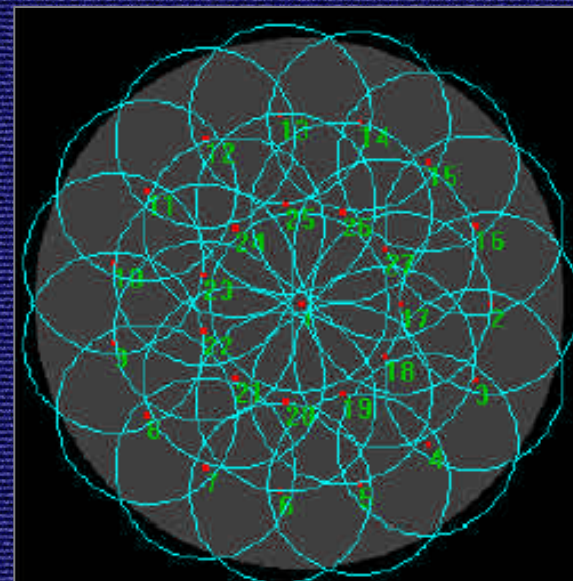
SSI measurement process



Full-aperture map



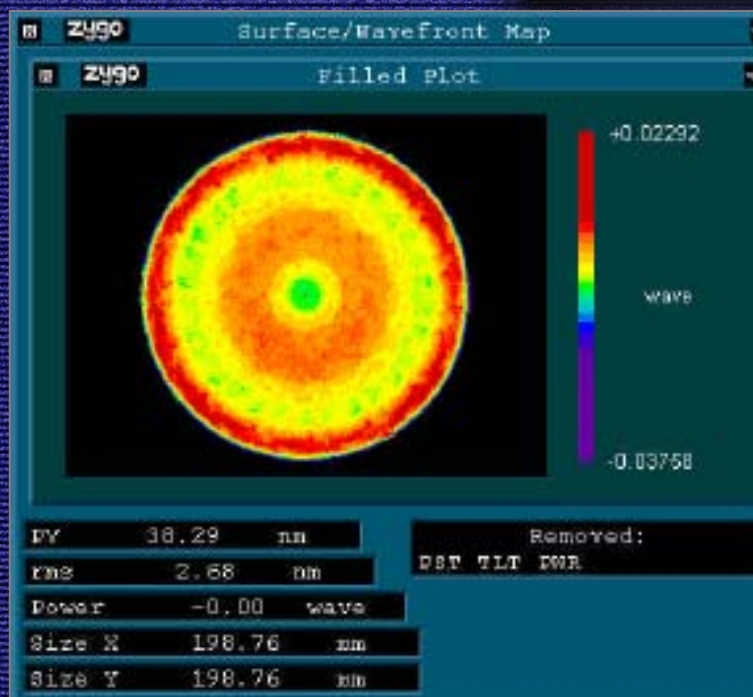
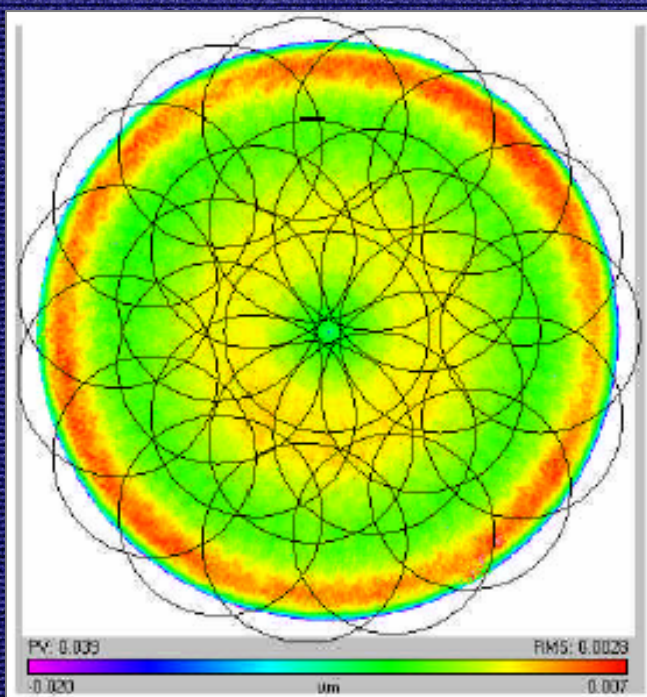
Measuring High Precision Spheres



Aperture: 200 mm (8.0")
Radius: 500 mm (19.7")
CT: 34 mm (1.3")

Objective: Zygo 4" f/7.2
Subaperture: 69.4 mm
Extension Factor: 2.95
Required subapertures: 30
(4 center, 11 inner, 15 outer)

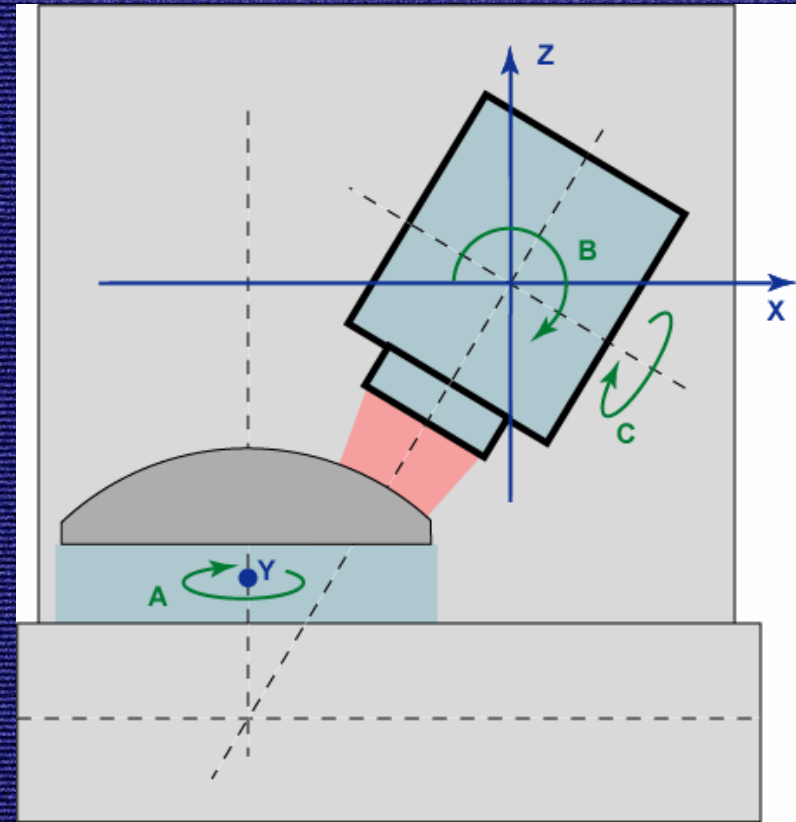
The Stitched Result



Radius: 499.9765 mm
Surface: PV = 0.060 λ (@ 633nm)
RMS = 0.004 λ (@ 633nm)
Total measurement time: 25 minutes!!

Summary

- ❖ Boosted testable aperture sizes (i.e. cost-effective reference optics)
- ❖ Boosted testable aspheric departure (can obviate need for nulls)
- ❖ Boosted accuracy (from thorough, automated calibration of reference wave, distortion, retrace, etc.)
- ❖ Boosted resolution
- ❖ Reduced non-common air path for long-radius concaves

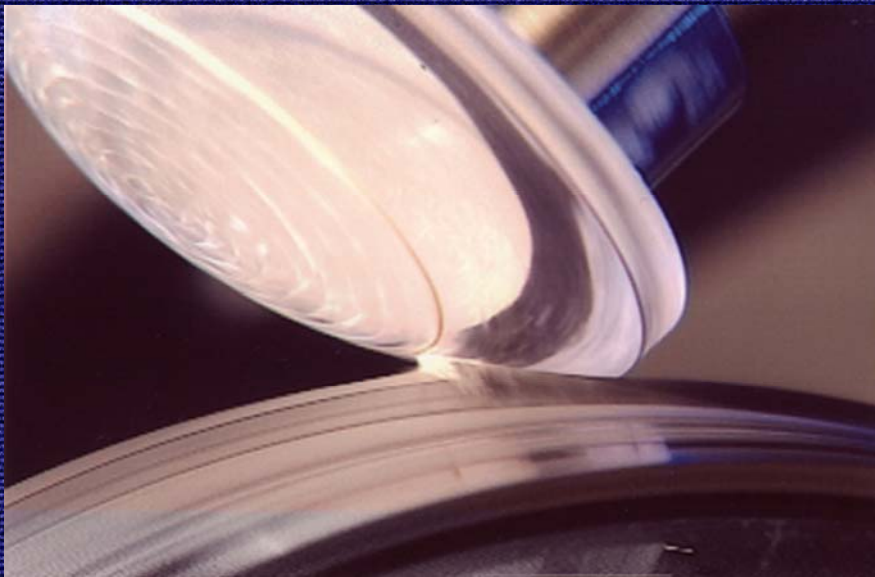


Outline

- ❖ Overview of Magnetorheological Finishing (MRF)
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 - ❖ SSI Applications
- ❖ **Conclusions**

Conclusions

- **MRF:**
 - Shaping - high precision figure correction
 - From real small to real large optics
 - Improve surface integrity
 - Thickness control – substrates, or thin/thick films
- **Jet Finishing:**
 - For difficult geometries
 - Or new materials
- **SSI:**
 - Metrology solution for small to large optics
 - Including hemispheres and other high NA parts



Sub-aperture Approaches to Finishing and Metrology

presented to:
Brookhaven National Laboratory

Marc Tricard
QED Technologies, Inc.

1040 University Avenue • Rochester, NY • USA
Tel: +1 (585) 256-6540 • Fax: +1 (585) 256-3211
tricard@qedmrf.com • www.qedmrf.com

