

E911 PHASE 2 ACCURACY DEFINITION MODIFICATION PROPOSAL

MEAN RADIAL ERROR (MRE)

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Accuracy Proposals

- **RMS**
 - Root Mean Square of all location attempt errors
 - **Current FCC sanctioned accuracy definition**
 - **Assessment:**
 - › Gives undue weight to outliers
 - › Includes all location attempts in accuracy calculation
- **67%**
 - Abscissa value at which the location error CDF crosses the 67% level
 - **Assessment:**
 - › Very insensitive to outliers
 - › Magnitude of largest 33% errors not counted in accuracy calculation
- **90% RMS**
 - Root Mean Square of location attempt errors with largest 10% excluded
 - **Assessment:**
 - › Insensitive to outliers
 - › Magnitude of largest 10% errors not counted in accuracy calculation
- **New proposal: MRE (Mean Radial Error)**

Mean Radial Error (MRE) Proposal

- **Proposal development criteria**

- all location attempts should be counted as part of the accuracy definition
- a small fraction of location failures or “outliers” should not unduly skew the results of an otherwise excellent ALI technology
- the original accuracy goals of the Commission should not be relaxed

- **MRE proposal**

- Calculate accuracy as the Mean of the Radial Error
- Comparison: RMS and MRE

- › **RMS** error equation (assumes actual location at origin)

$$A_{RMS} = \sqrt{\frac{1}{N} \sum_{i=1}^N (x_i^2 + y_i^2)}$$

Errors accumulated as magnitude squared

- › **MRE** error equation (same assumption)

$$A_{MRE} = \frac{1}{N} \sum_{i=1}^N \sqrt{x_i^2 + y_i^2}$$

Errors accumulated as magnitude

- › Errors accumulated by magnitude for MRE and magnitude squared for RMS
- › MRE includes all errors, but does not unduly magnify “outliers”

- **MRE provides for more equitable error weighting**

ACCURACY EQUIVALENCE

- **Probability theory**

- **Gaussian probability density function (PDF)**

$$f(x, y) = \frac{1}{2\pi\sigma^2} e^{-(x^2+y^2)/2\sigma^2} \longrightarrow A_{RMS} = \sqrt{2\sigma^2}$$

- **Transform this density by the function: $r = \sqrt{x^2 + y^2}$**
 - › **Resulting random variable has a Rayleigh PDF**

$$f_r(r) = \frac{r}{\sigma^2} e^{-r^2/2\sigma^2} U(r)$$

- › **The mean of this transformed Gaussian process is well known to be:**

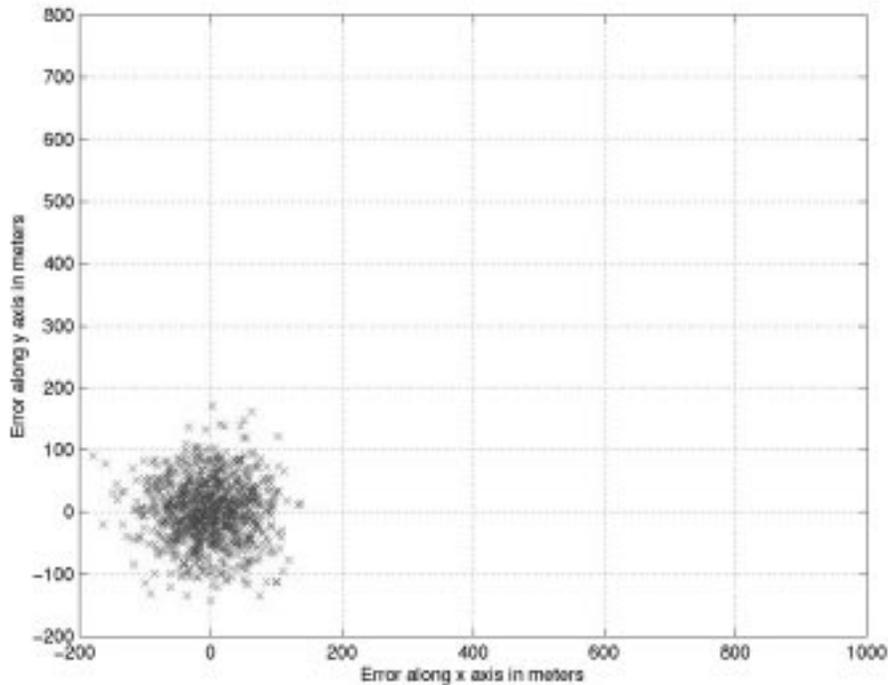
$$A_{MRE} = \sigma \sqrt{\pi/2}$$

- **Accuracy equivalence**

- **$A_{RMS} = 125$ m for $\sigma = 88.39$ m**
- **For $\sigma = 88.39$ m, $A_{MRE} = 110$ m**
- **Thus, setting a 110 meter MRE accuracy goal is equivalent to an RMS goal of 125 meters**

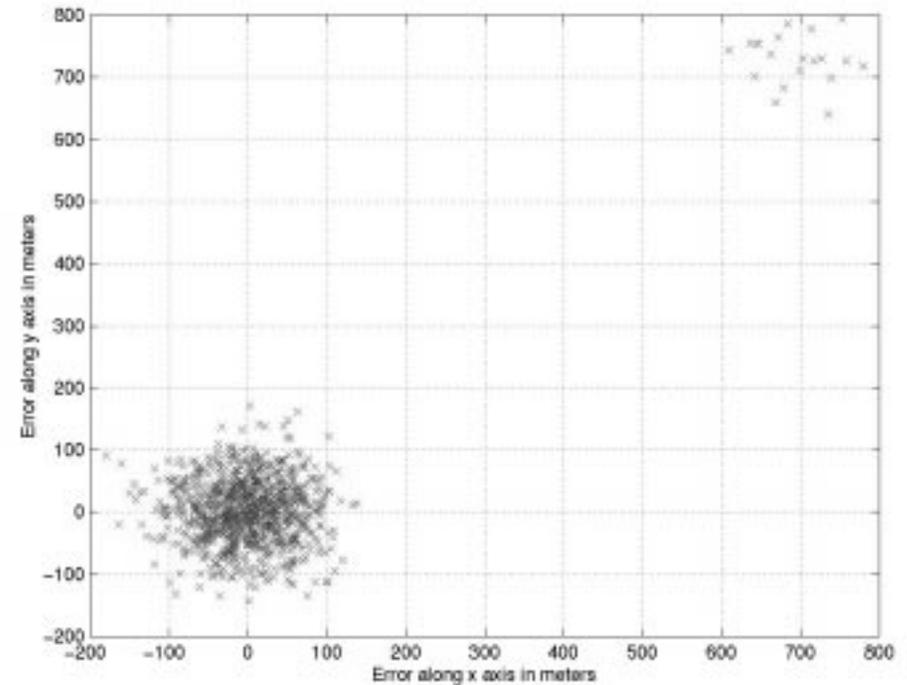
- **MRE accuracy goal of 110 meters is equivalent to 125 meter RMS goal**

ACCURACY DEFINITION CASE STUDIES



- **Case 1**

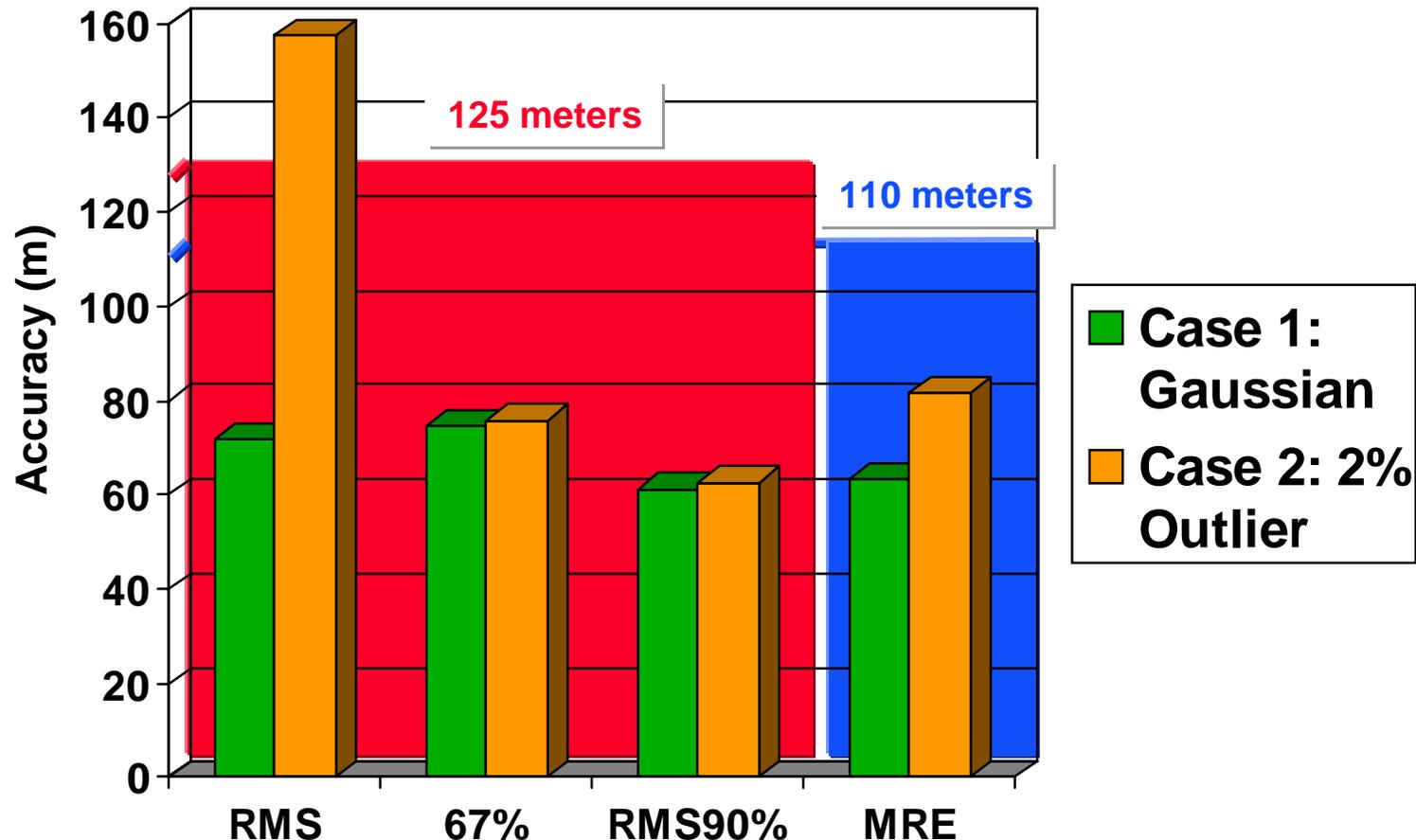
- 1000 2-D Gaussian draws
- $\sigma = 50$ m (both dimensions)
- Radial error $\sigma = 71$ m



- **Case 2**

- 980 points identical to Case 1
- 20 “outliers” created
 - › offset points by 1000 m
 - › 2% outlier probability

ACCURACY RESULTS



- **Accuracy impact of 2% outlier as compared to Gaussian case**
 - RMS accuracy degraded by 120%, non-compliant
 - RME accuracy degraded by 30%, compliant
 - 67% and RMS90% accuracies degraded by less than 2%, compliant

CONCLUSIONS

- **The MRE definition:**
 - Assures that all errors are counted in the accuracy calculation
 - Reduces sensitivity to outliers
 - Assures equivalent accuracy to the 125m/RMS goal (Gaussian assumption)
 - › By setting MRE accuracy goal to 110 meters
- **Win/Win for the interested parties**
 - Public safety assured that all location errors counted in accuracy calculation
 - Carriers and vendors assured relief from excessive outlier impact on accuracy calculation
- **We now have at least four accuracy definition proposals**
 - RMS
 - 67%
 - 90% RMS
 - MRE
- **Which one represents the best compromise between public safety requirements and wireless industry compliance difficulty?**
- **Let's work together to expeditiously decide**