

Characterization of Aerosols and Surface Optical Properties from Airborne Spectral Measurements of Directional Reflectance

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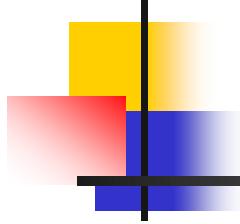
Acknowledgements:

G.T. Arnold (SSAI & GSFC)

Gala Wind (SSAI & GSFC)

Rajesh Poudyal (SSAI & GSFC)

Hal Maring & Andy Roberts (NASA HQ)



Background:

CAR Airborne Platforms 1998-2008

Convair CV-580



Aerocommander 690A



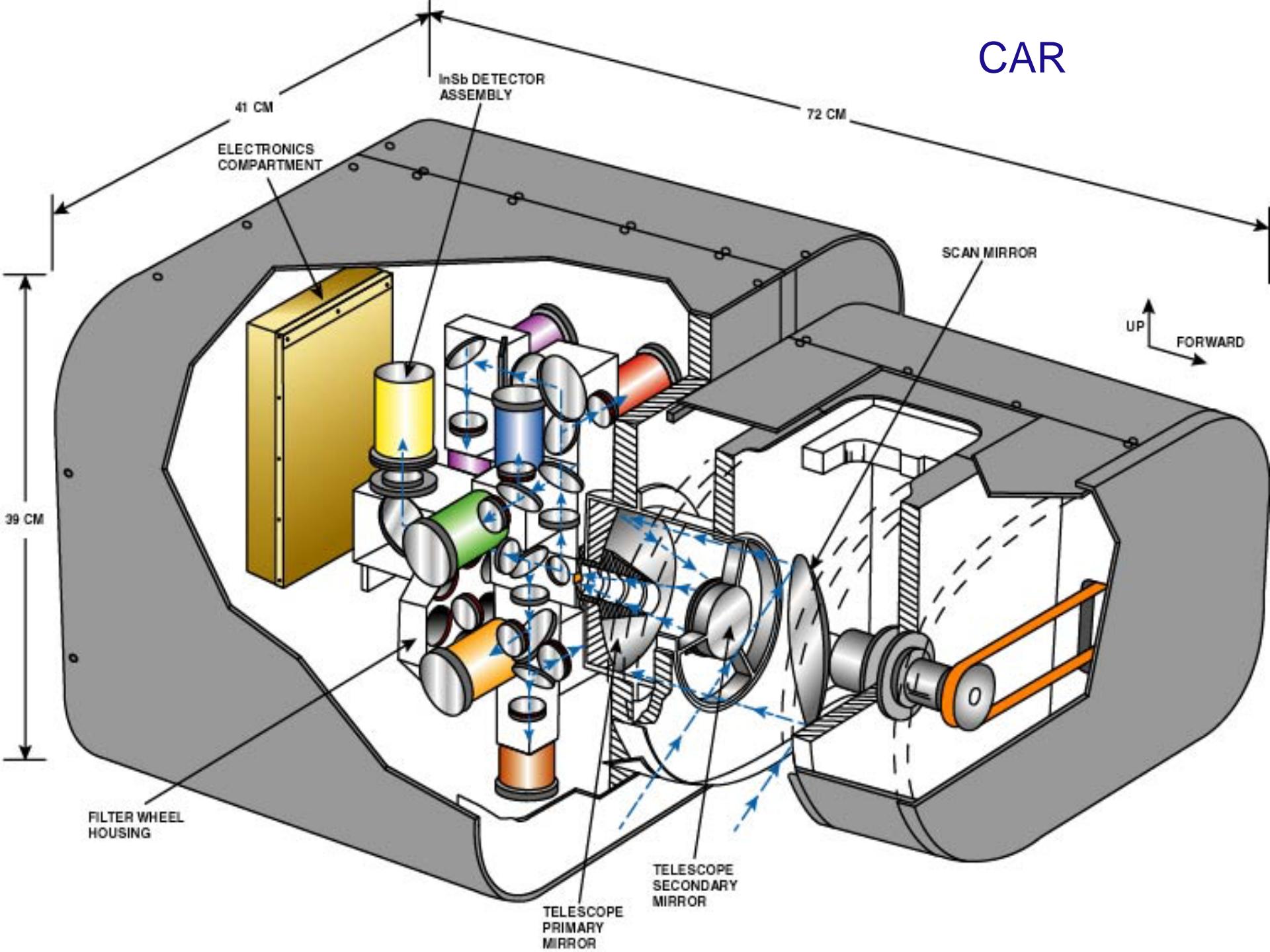
Jetstream-31



NASA P-3B



CAR



CAR Quicklook Image 2008

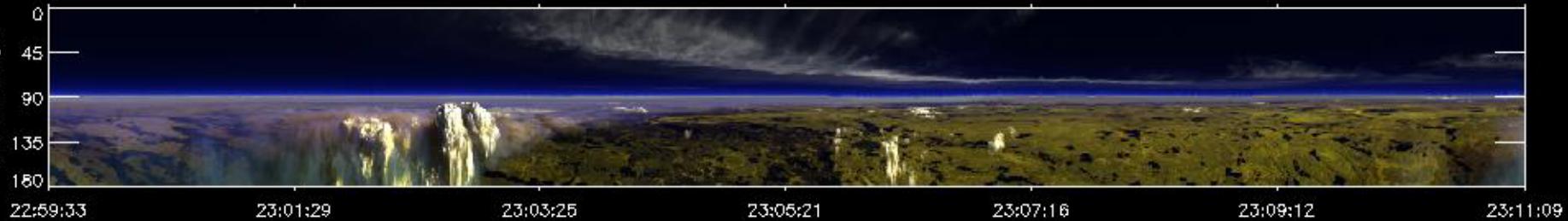
Zenith



CAR View Angle



CAR View Angle

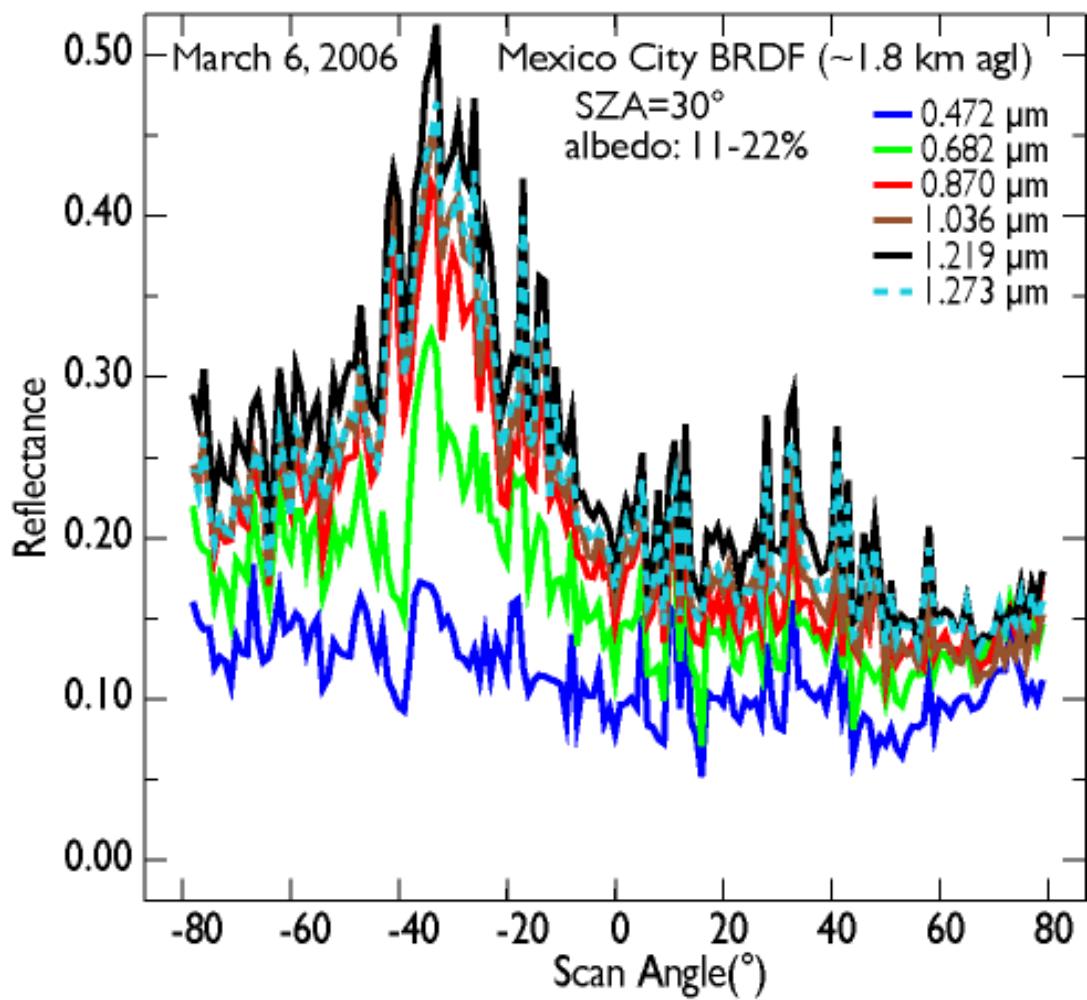
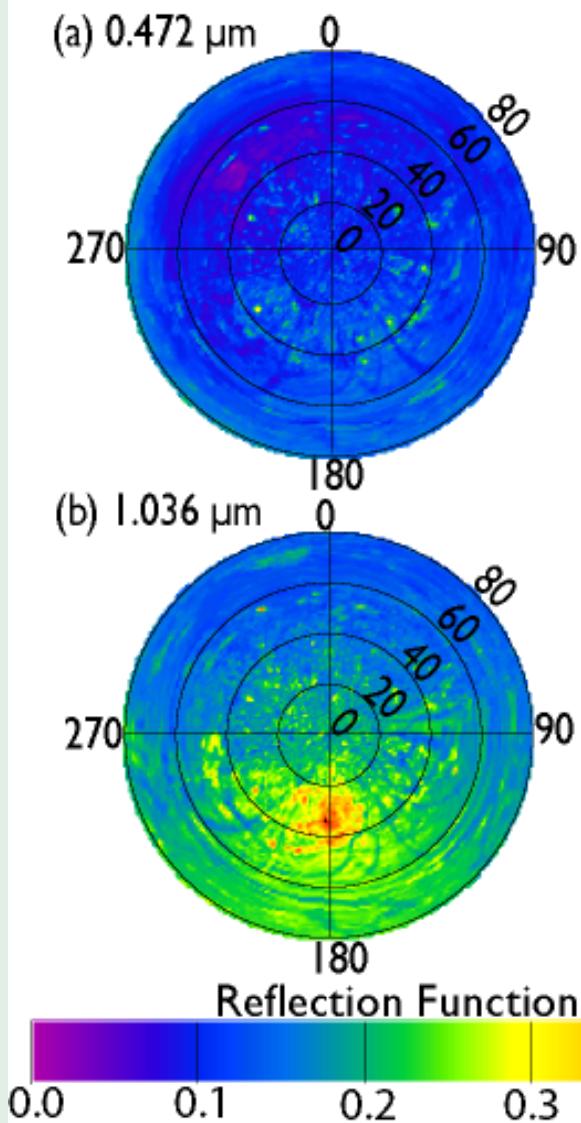


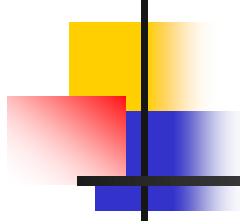
CAR View Angle



BRDF Measurements

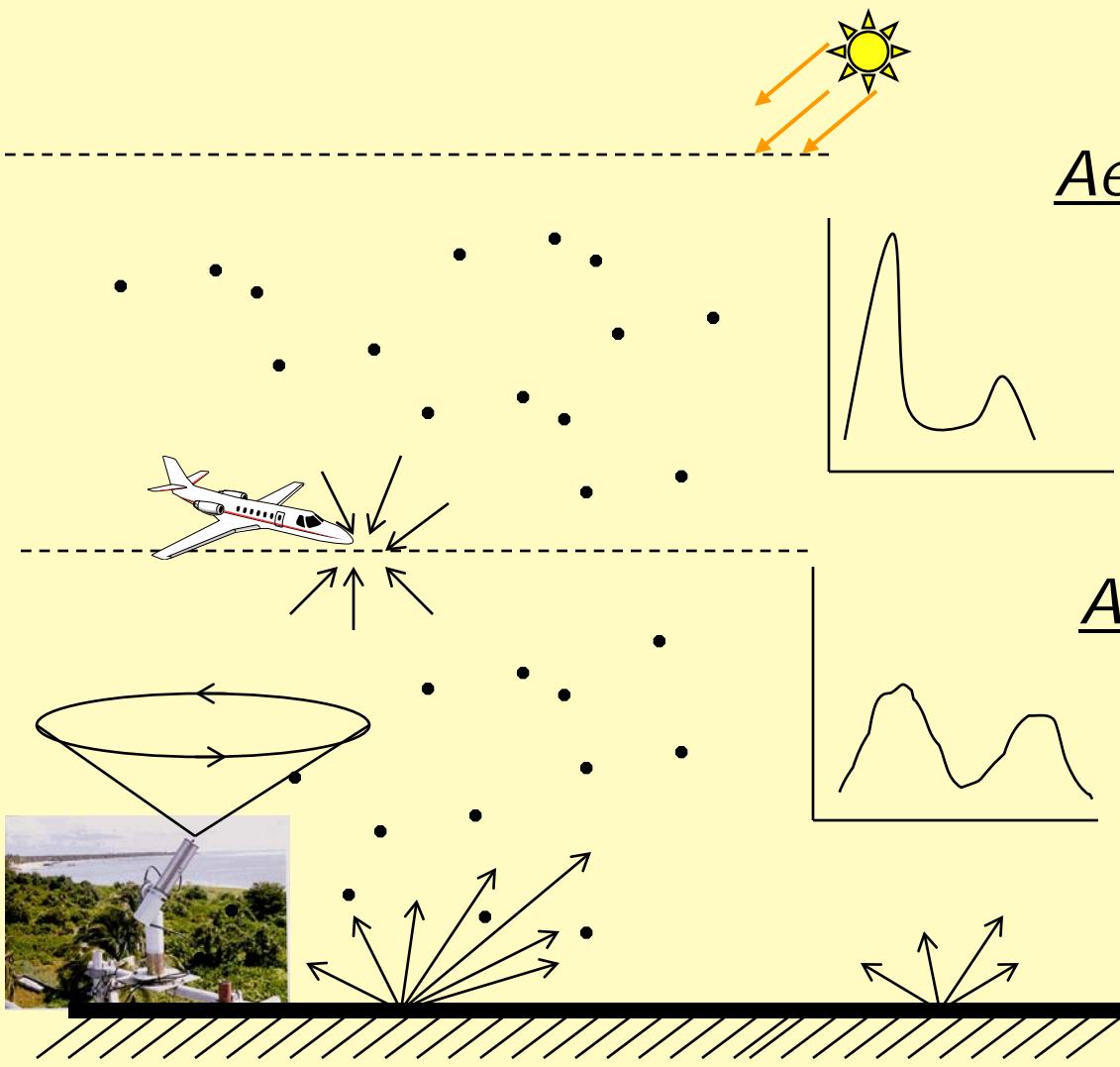
Mexico City BRDF: Higher Alt.





Aerosol Inversion:

Retrieval using combinations of up- and down-looking observations



Retrieved:

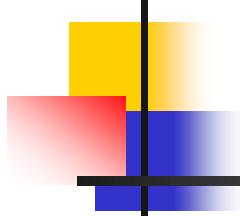
Aerosol above plane:

- size distr.
- real ref. ind.
- imag. ref. ind

Aerosol below plane:

- size distribution
- real ref. ind.
- imag. ref. ind

Surface Parameters:
- albedo, etc.



Inversion Method

Inversion (Dubovik & King 2000)
[JGR, Vol. 105, 20,673]

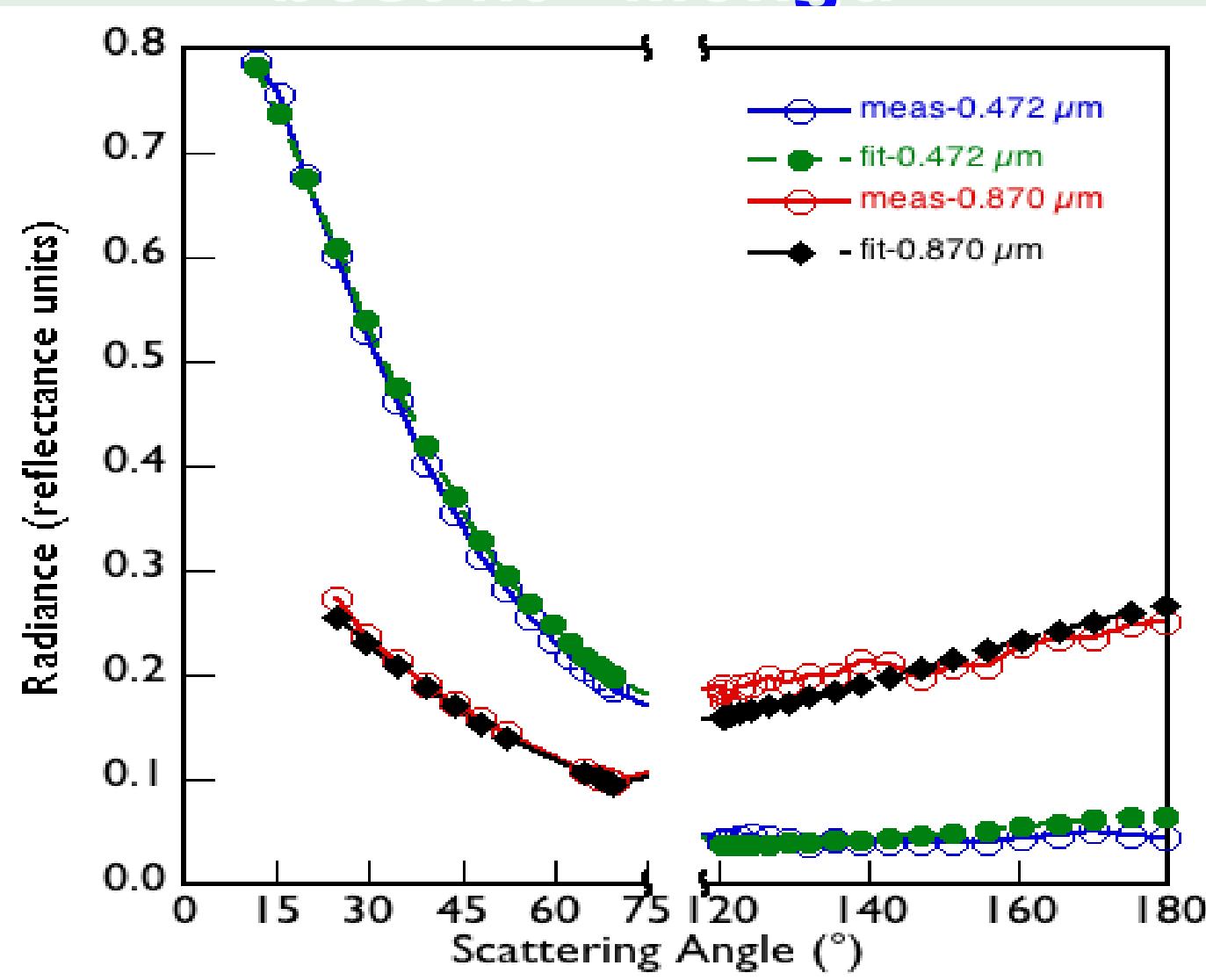
Best soln corresponds to a minimum of

$$\psi(a) = \frac{1}{2} \sum_{k=1}^9 \gamma_k \{ [f_k^* - f_k(a)]^T (W_k)^{-1} [f_k^* - f_k(a)] \},$$

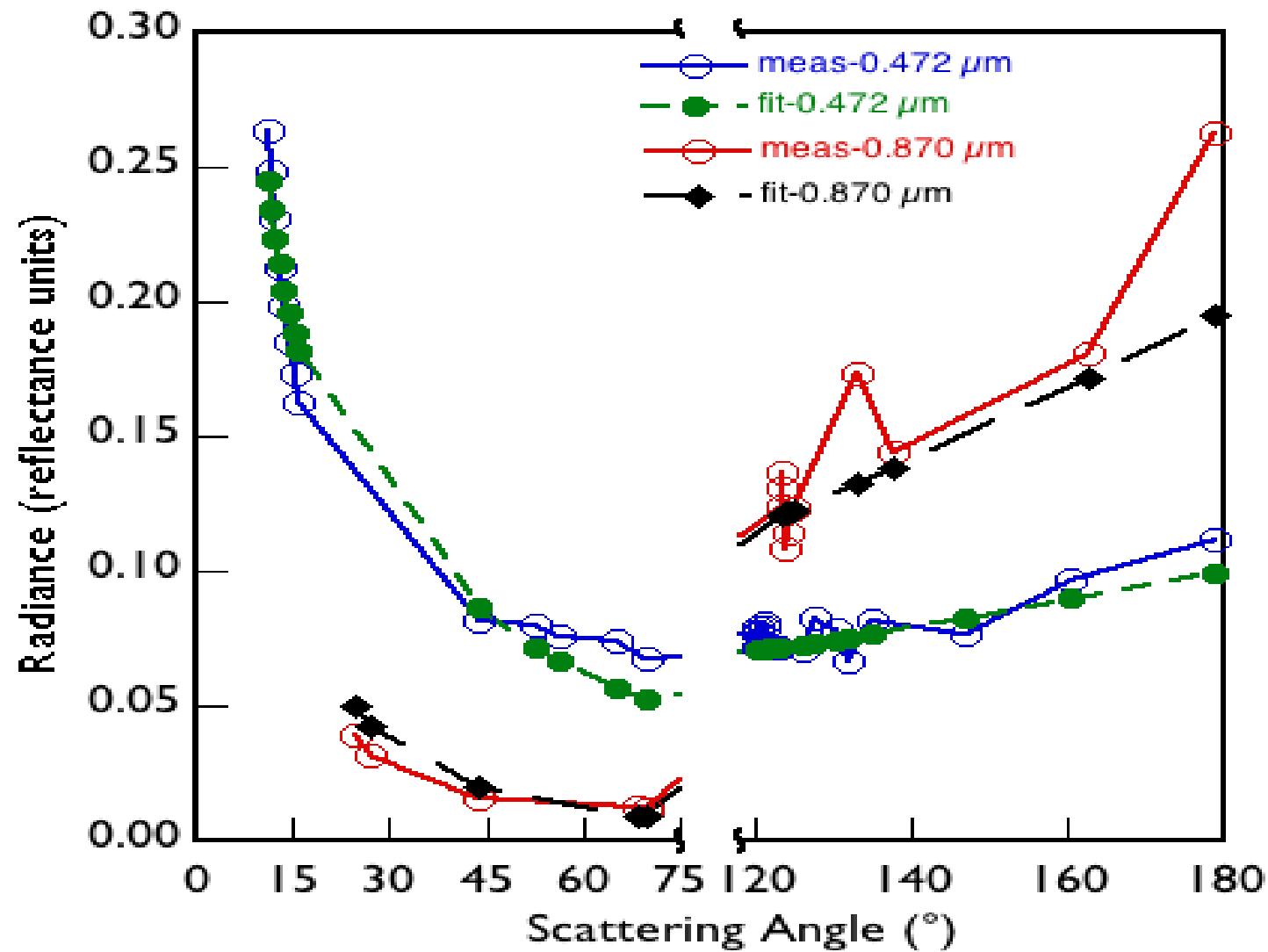
Residual:

$$RES = (\sqrt{\frac{1}{N} \sum_{i=1}^N [\ln(f_i^*) - \ln(f_i)]^2}) * 100$$

CAR Measurements best fit - Mongu

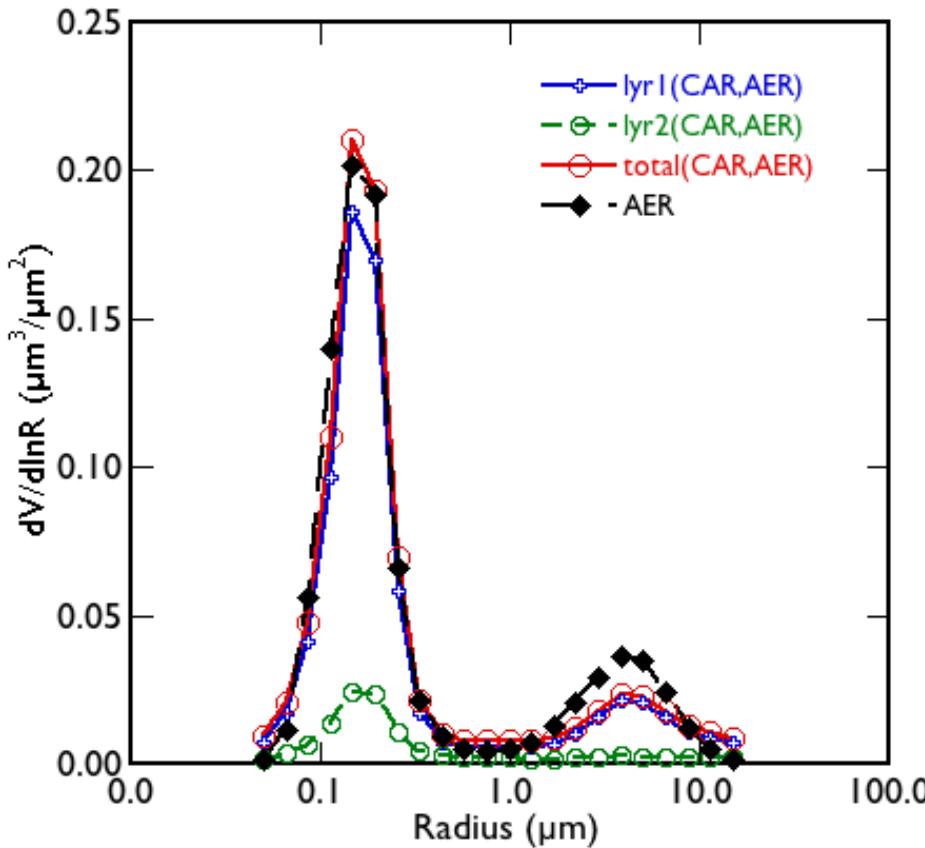


CAR Measurements best fit- Mexico City

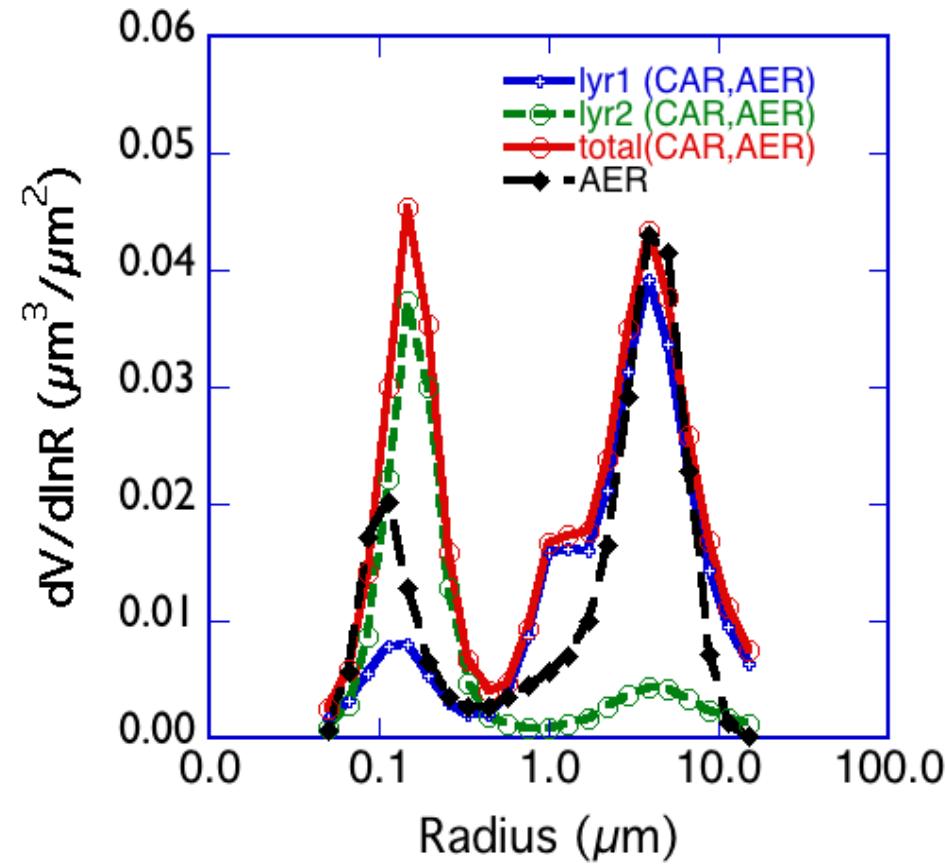


Aerosol Size Distribution

Mongu, Zambia

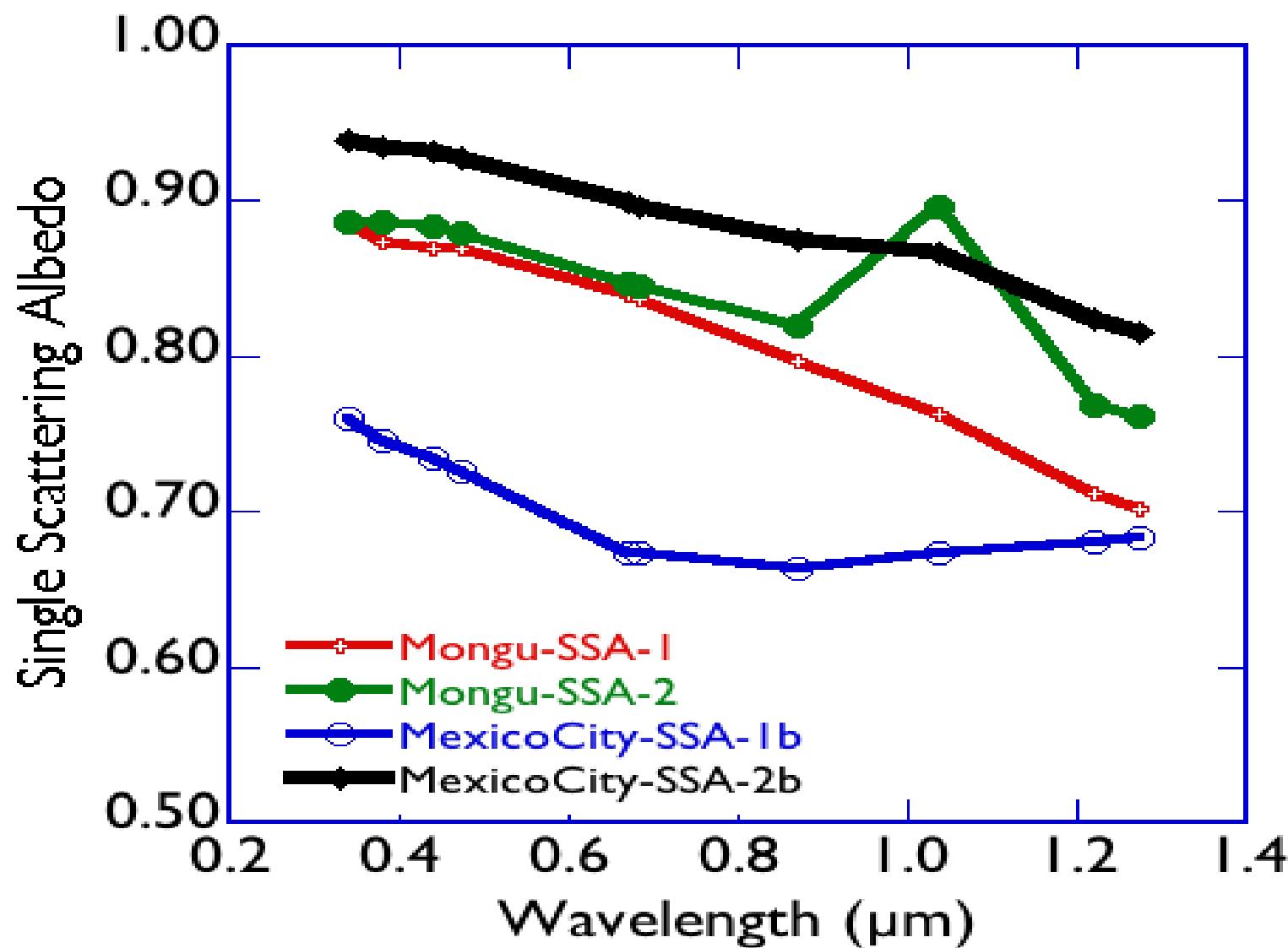


Mexico City, Mexico

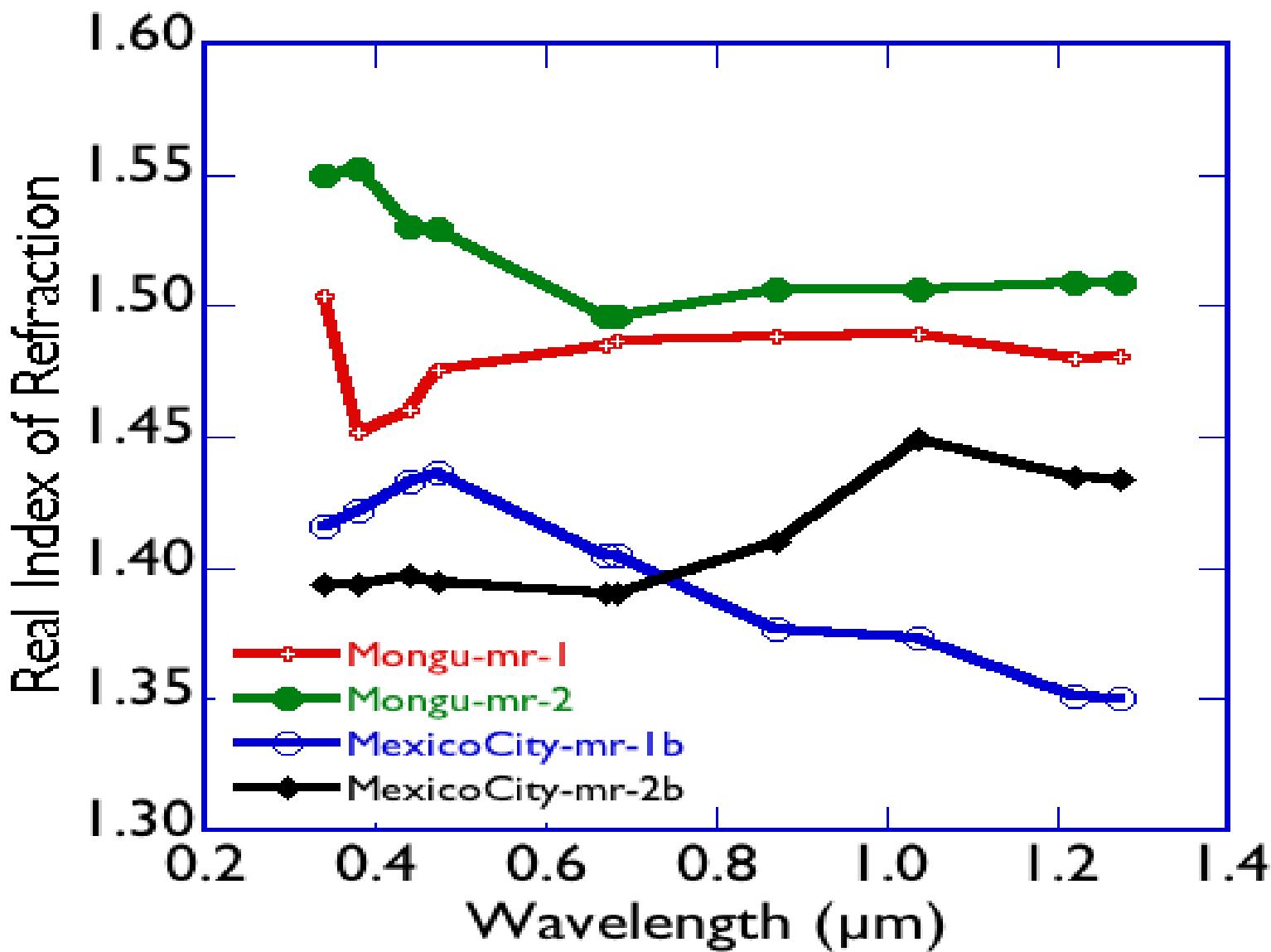


- Retrieved aerosol volume size distribution from combined data sets: CAR and AERONET.

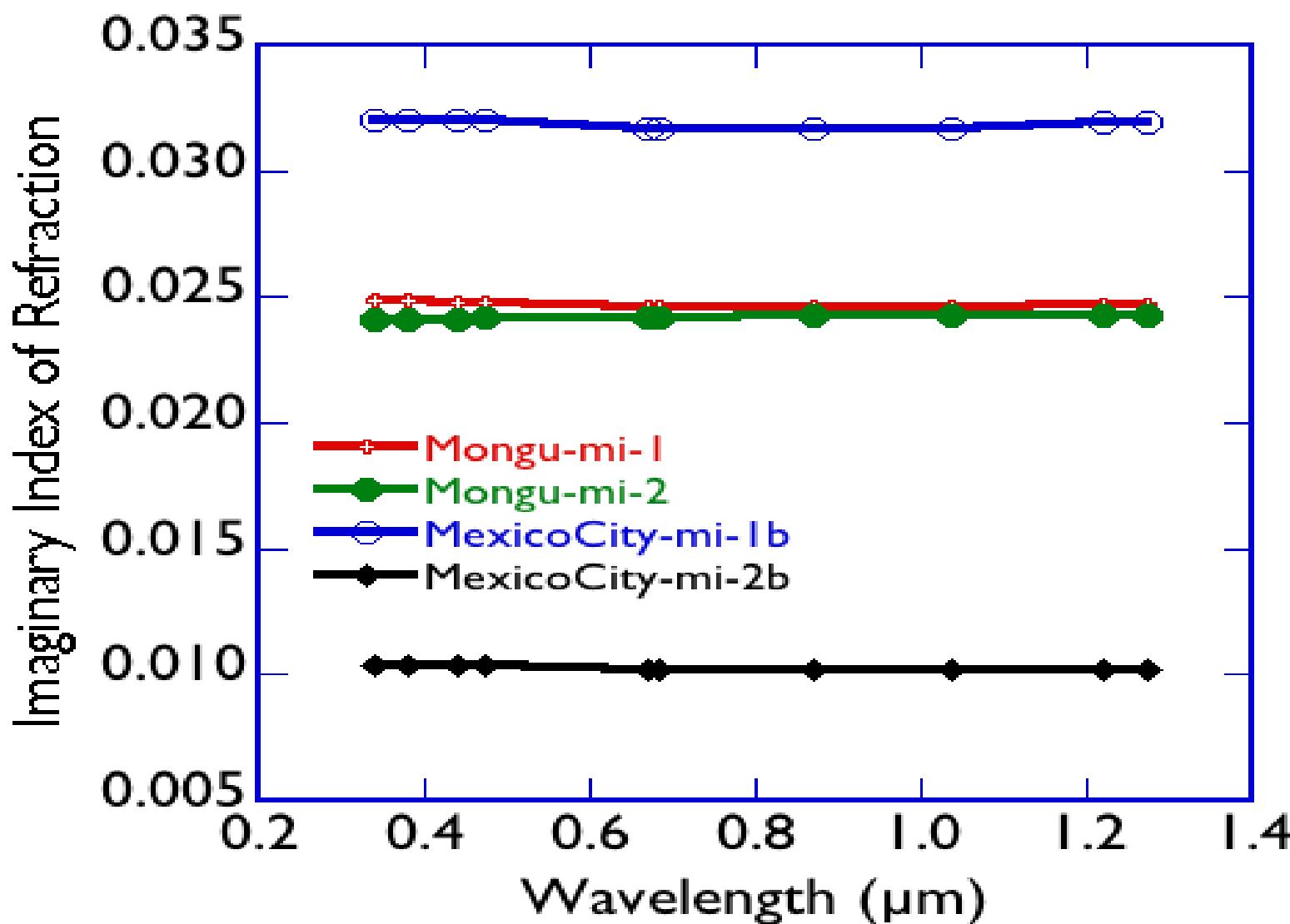
Single Scattering Albedo Retrieved from CAR & AERONET



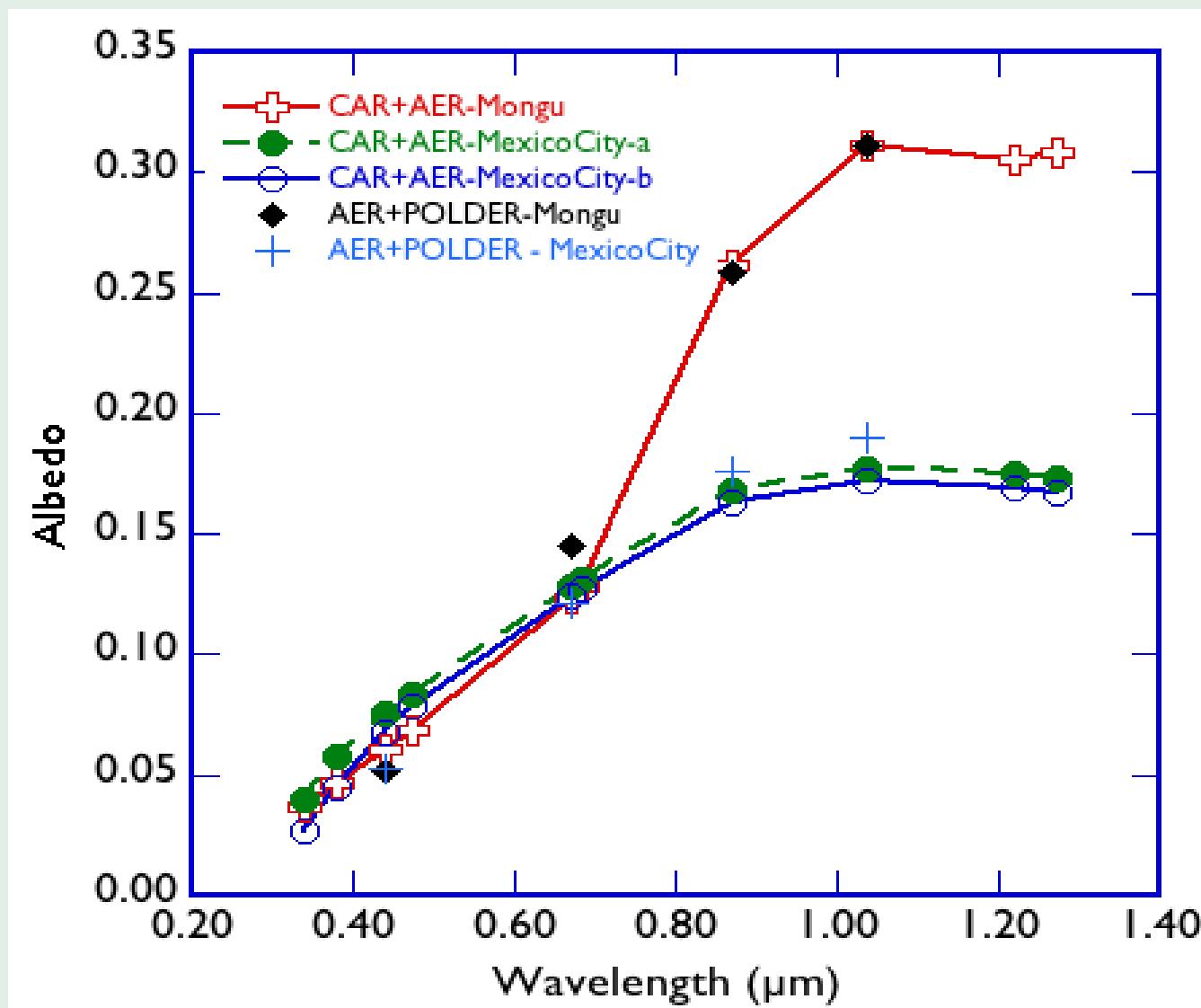
Real Index of Refraction Retrieved from CAR & AERONET

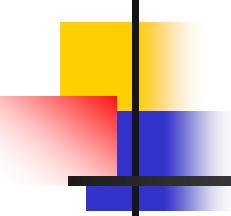


Imaginary Index of Refraction Retrieved from CAR & AERONET



Retrieved Albedo





Conclusion:

- *Retrieval of both aerosol and surface optical parameters from combined up-and down-looking observations has been demonstrated for both bright and dark surface targets.*
- *Future efforts will revolve around studies on:*
 - clarifying the use of different BRDF models, optimum parameterization, sensitivity, etc);*
 - “closure” experiments for validating the algorithm.*