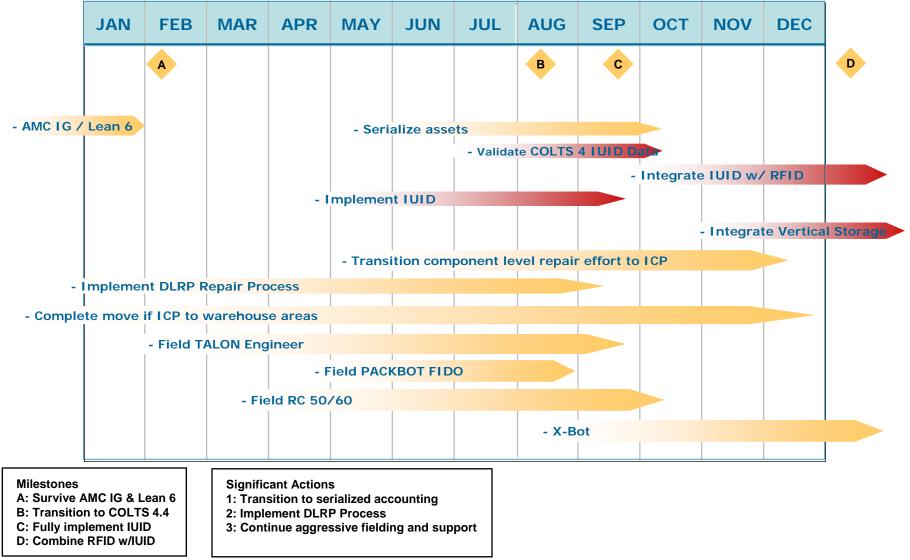
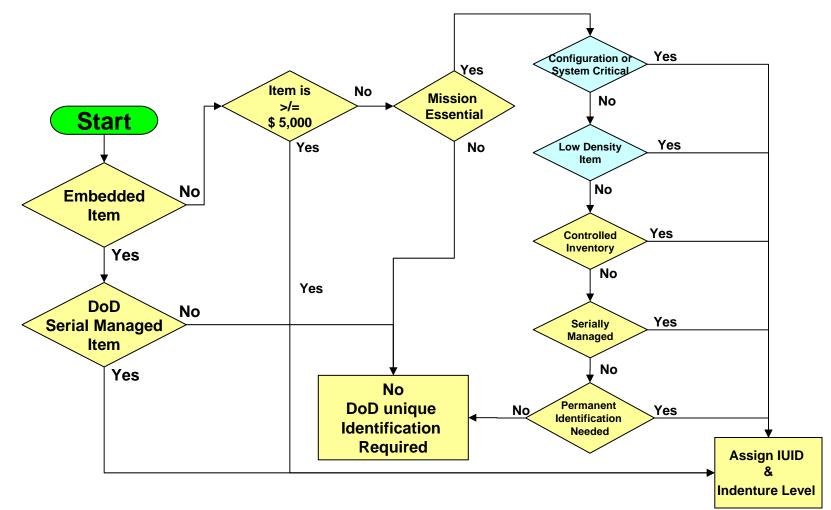
ICP 2007 Initiatives



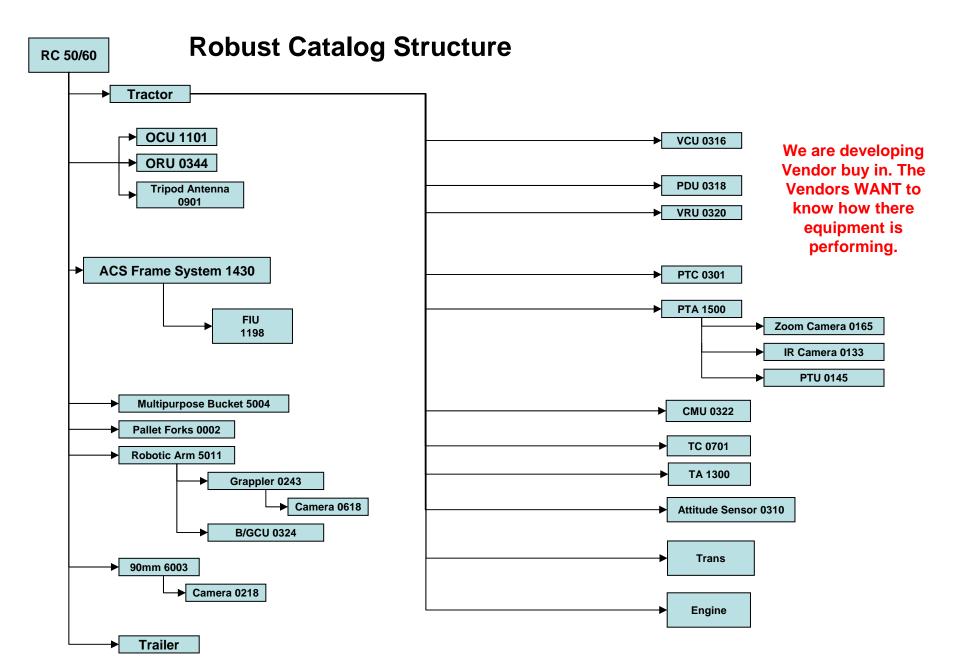
COLTS Catalog build process



RSJPO COLTS Catalog Build Decision Matrix



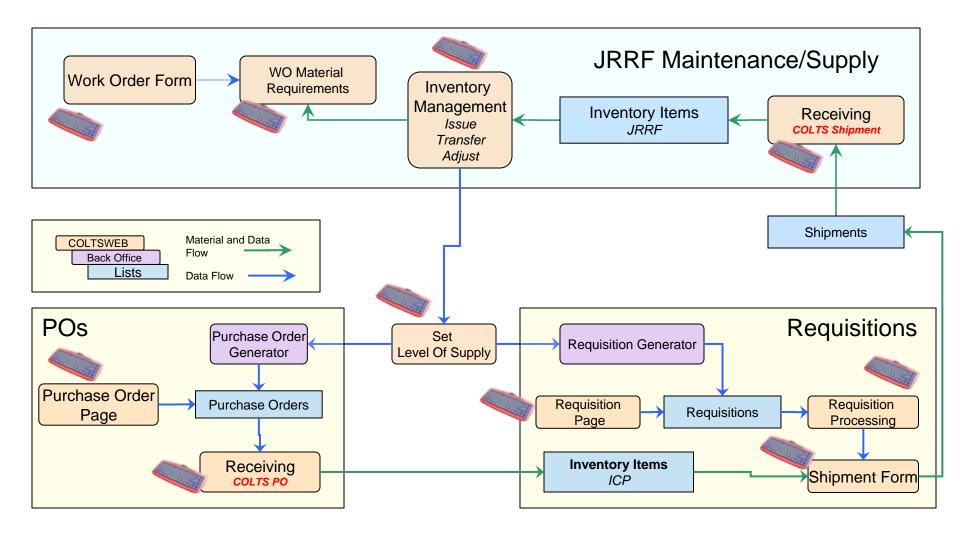
Inadequate Vendor Structure



JRRF Prior to IUID integration

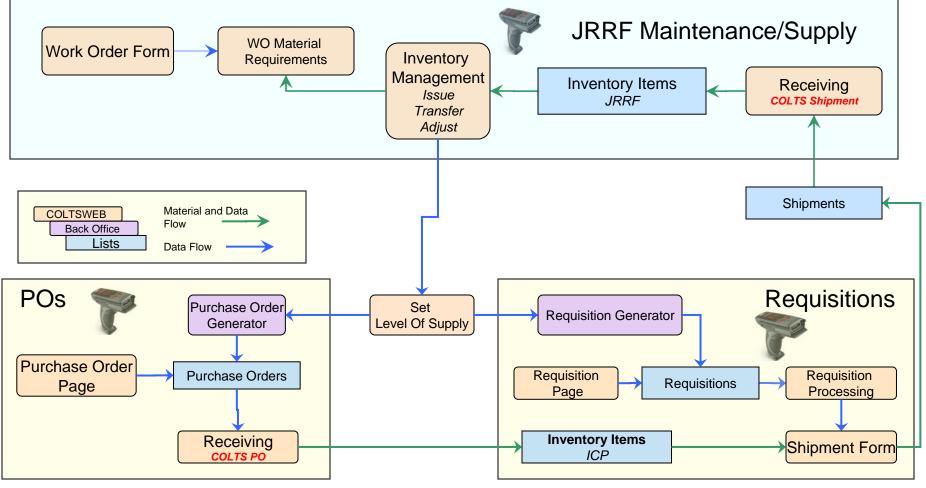
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Each Keyboard represents opportunity for error



JRRF Prior to IUID integration

Each Scanner represent a process streamlined and error elimination.



Step One: Select View, Columns and Restrict

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Step Two: Enter Contact Information, Defaults and Output

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UID Manager	UID Manager	
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Name: Gerald Perlmutter	Display List Search New List Current Row: 8	Rows Visible: 8 of 10168 rows
EMail: gerryp@avantix.com	Site Site Name Part Number Descrip Name: Gerald Perlmutter	UID IAC UID Grade UID UID UID UID A
Organization: RS JPO	5tock	Sent Verifie Marked Preassi
Phone: 619.697.1166	DEPOT 2ND EOD COMPANY DSI-500-0369 FIRE SET DEPOT 2ND EOD COMPANY DSI-500-0398 FIRE OPTIC SP EMail: gerryp@avantix.com	
Defaults		
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	DEPOT 2ND EOD COMPANY RDSI-04209 MK 2 BATTERY Phone: 619.697.1166	
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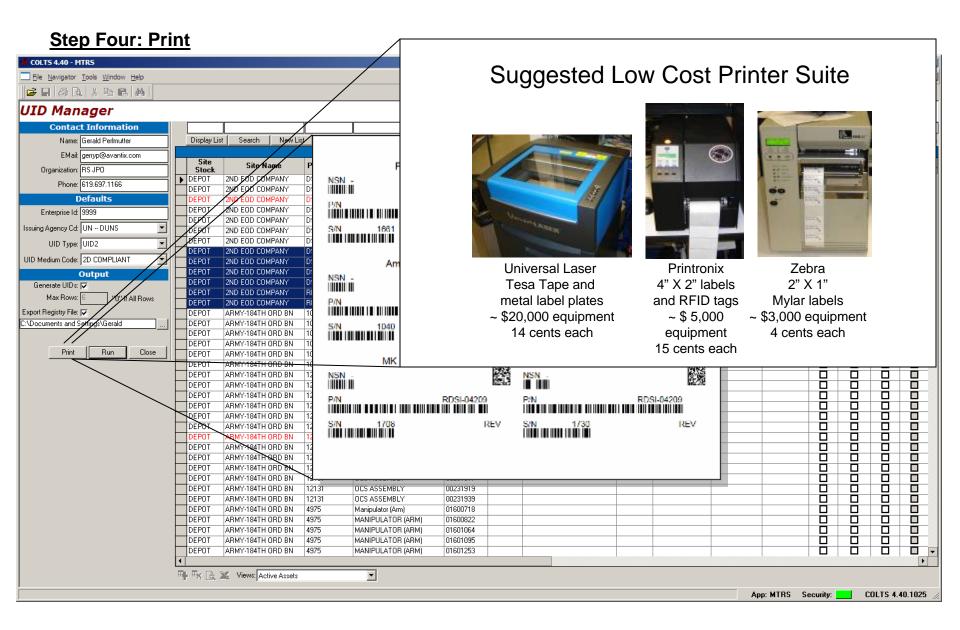
Step Three: Export Registry File

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	Gerald Perlmutter			Display Lis	t Search New 🖌	st Current R	lowr 1	<originalpartnumber>DSI-</originalpartnumber>
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Organization:	RS JPO			Stock	Site Name	Part Number	Description	<uidtype>UID2</uidtype>
Phone:	619.697.1166			DEPOT	2ND EOD COMPANY		PAN AND TILT CAMERA	 <mark></mark>
	efaults			DEPOT	2ND EOD COMPANY	DSI-500-0182	VEHICLE BATTERY	<baggedortaggedcode></baggedortaggedcode>
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				DEPOT	ARMY-184TH ORD BN	12130	CHASSIS (VEHICLE)	- <mark></mark>
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				DEPOT	ARMY-184TH ORD BN	12131	OCS Assembly	<contents>UID</contents>
				DEPOT	ARMY-184TH ORD BN	12131	OCS ASSEMBLY	<effectivedate>2007-08</effectivedate>
				DEPOT	ARMY-184TH ORD BN	12131	OCS ASSEMBLY	<addedorremovedcode></addedorremovedcode>
				DEPOT	ARMY-184TH ORD BN	12131	OCS ASSEMBLY	<markercode>UN</markercode>
				DEPOT	ARMY-184TH ORD BN	1213	OCS ASSEMBLY	<markeridentifier>9999<</markeridentifier>
				DEPOT	ARMY-184TH ORD BN	12131	OCS ASSEMBLY	<mediumcode>2D COMP</mediumcode>
				DEPOT	ARMY-184TH ORD BN ARMY-184TH ORD BN	12131 4975	OCS ASSEMBLY	
				DEPOT		4975	Manipulator (Arm)	
				DEPOT	ARMY-184TH ORD BN ARMY-184TH ORD BN	4975	MANINULATOR (ARM) MANIPUDATOR (ARM)	
				DEPOT	ARMY-184TH ORD BN	4975	MANIPULATOR (ARM)	
				DEPOT	ARMY-184TH ORD BN	4975	MANIPULATOR (ARM)	- <endproduct></endproduct>
			4		ALIMIT TOUT OND BN	-3/3		 <contractinfo></contractinfo>
							\rightarrow	<description>Arm Assembly</description>
			-	• ≞x Lo,)	🔌 Views: Active Assets		-	- dlidlist

xml version="1.0" encoding="utf-8" ?> UidDocument> <LegacyOrNewCode>LEGACY </LegacyOrNewCode> <Version>3.3</Version> <Contact> <Email>gerryp@avantix.com</Email> <Name>Gerald Perimutter</Name> <Organization>RS JPO </Organization> <Phone>619.697.1166</Phone> </Contact> - 🗆 🗵 _ 8 × ription> </EnterpriseIdentifier> IssuingAgencyCode> ~ 500-0369 </ OriginalPartNumber> Rows Visible: 1 of 10168 rows alNumber> 691661</Uid> UID UID UID 🔺 UID UID Grade Sent Verified Marked Preassi N</BaggedOrTaggedCode> ts> 27</EffectiveDate> $\overline{\overline{\mathbf{B}}}$ A</AddedOrRemovedCode> rCode> /MarkerIdentifier> \mathbf{v} LIANT</MediumCode> \checkmark $\overline{}$ ~ \checkmark $\overline{}$ POOLER</Description> </EnterpriseIdentifier> IssuingAgencyCode> 500-0398</OriginalPartNumber> alNumber> 981661</Uid> П N</BaggedOrTaggedCode> Ē 155 -27</EffectiveDate> A</AddedOrRemovedCode> Ē rCode> /MarkerIdentifier> LIANT</MediumCode> Ē Ē Ē Ē Ē □ ▼ /Description>

 \checkmark

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Step Five: Verify

	Asset UID Grade	×
📌 COLTS 4.40 - MTRS		
Elle Navigator Tools Window Help	Part Number: DSI-500-0227 S/N: 1661	_8×
	IUID: UN99999999990 SI-500-02271661	i 💷 💷
UID Manager		
Contact Information 0227	Description: MK2 ROBOT VEHICLE	
Name: Gerald Perlmutter V Display List Search New List Current Row: 1	Scan successful	Rows Visible: 1 of 598 rows
EMail: geryp@avantix.com		UID UID UID 🔺
Organization: RS JPO Site Site Name Part Number Description	Details Label Placement Instructions Additional Fields and Flags	erified Marked Preassigne
Phone: 613.637.1166 DEPOT 2ND EOD COMPANY DSI-500-0227 MK2 ROBOT VEHICLE DEPOT ARMY-184TH OB/ BN DSI-500-0227 MK2 ROBOT VEHICLE	Date Graded: 8/28/2007 11:51:04 AM	
Defaults DEPOT ARMY-184TH ORD BN DSI-500-0227 MK2 ROBOT VEHICLE		
Enterprise Id: 9999 DEPOT ARMY-13/ H ORD BN DSI-500-0227 MK2 ROBOT VEHICLE DEPOT ARMY-92D ORD BN DSI-500-0227 MK2 ROBOT VEHICLE	Device Type: COGNEX DM7500	
Issuing Agency Cd: UN DUNS DEPOT APMY-1ST MARINE DSI-500-0227 MK2 ROBOT VEHICLE	Grade Parameter Value	
UID Type: UID2 DEPOT ARMY-217TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE DEPOT ARMY-319TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE		
UID Medium Code: 2D COMPLIANT	UID Grade: DPM4/13/639/30T	
Output DEPOT ARMY-387TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE	Angle Distortion:	
Generate UIDs: DEPOT ARMY-38TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE DEPOT ARMY-430TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE		
Max Rows: 0" If All Rows DEPOT ARMY-47TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE	Axial Non-Uniform: A +0.009	
Export Registry File: DEPOT ARMY-47TH ORD C0 DSI-500-0227 MK2 ROBOT VEHICLE Coutput XML file> DEPOT ARMY-47TH ORD C0 DSI-500-0227 MK2 ROBOT VEHICLE	Cell Contrast: A +0.812	
Couplet XME INES		
DEPOT ARMY-47TH ORD CO DSI-500-0227 MK2 R0B0T VEHICLE Print Run Verify Close DEPOT ARMY-501ST ORD RN DSI-500-0227 MK2 R0B0T VEHICLE	Cell Growth Horiz: +19.547	
Print Run Verify Close DEPOT ARMY-501ST ORD BN DSI-500-0227 MK2 ROBOT VEHICLE DEPOT ARMY-53RD ORD CO DSI-500-0227 MK2 ROBOT VEHICLE	Cell Growth Vertical +19.505	
DEPOT ARMY-53RD ORD CO DSI-500-0227 MK2 ROBOT VEHICLE	Cell Growth Vertical: +19.505	
DEPOT ARMY-53RD ORD CO DSI-500-0227 MK2 ROBOT VEHICLE DEPOT ARMY-59TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE	Cell Modulation: A	
DEPOT ARMY-53TH OHO CO DSI-500-0227 MK2 ROBOT VEHICLE		
DEROT ARMY-59TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE	Fixed Pattern Dmg: A	
DEPOT ARMY-59TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE DEPOT ARMY-59TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE	Grid Non-Uniform: A +0.084	
DEPOT ARMY SED ORD CO EOD DSI-500-0227 MK2 ROBOT VEHICLE		
DEPOT ARMY-62D DRD C0 E0D DSI-500-0227 MK2 ROBOT VEHICLE DEPOT ARMY-666TH ORD C0 DSI-500-0227 MK2 ROBOT VEHICLE	Min Reflect: A 81	
DEPOT ARMY-702D ORD CO DSI-500-0227 MK2 ROBOT VEHICLE		
DEPOT ARMY-702D ORD CO D3N500-0227 MK2 ROBOT VEHICLE	Reference Decode: A	
DEPOT ARMY-703D ORD CO DSI-50D9227 MK2 ROBOT VEHICLE DEPOT ARMY-703D ORD CO DSI-500-022 MK2 ROBOT VEHICLE	Unused ECC: A +1.000	
DEPOT ARMY-703D ORD CO DSI-500-0227 MR2 ROBOT VEHICLE		
DEPOT ARMY-703D ORD CO DSI-500-0227 MK2 R0B0T VEHICLE DEPOT ARMY-705TH ORD CO DSI-500-0227 MK2 R0B0T VEHICLE		
DEPOT ARMY-7051H ORD CO DSI-500-0227 MK2 ROBOT VEHICLE	Ready Clear All Update Close	
DEPOT ARMY-706TH ORD CO DSI-500-0227 MK2 ROBOT VEHICLE		
🖷 🖅 🗟 💥 Views: Active Assets 💌		
	App: MTRS Se	curity: COLTS 4.40.1026 //

Step Six: Secure Label

	http://localhost/colts4I/Pics/Scanner PicLJPG - Microsoft Internet Explorer
COLTS Part Form - Microsoft Internet Explorer	
Ele Edit » Google 🕞 Coogle 🕞 Coogle 🕞 Coogle 🕞 Coogle	
You have new notifications fraintenance inventory rienu togoff relp My Pr	
MTRS Part	
Part Number: DSI-500-0227	
Supplier Name: FOSTER-MILLER CAGE: 08KG1	
Description: MK2 ROBOT VEHICLE	
System: MK2 MOD0 🔽	
Cognizance Code: FSC: NIIN:	
UID Type: VID IAC: VID EID: Catalog Price: 131900 UM: Pach VID EID:	
Shelf Life Shelf Life Action	
Sch B Exp Cd:	
Serialized: 🔽 Can Req: 🗌 Inactive: 🗌	
Exclude From Tracked II Controlled: II Mission Critical: II	
Alternates IVID Label Placement Additional Fields	2
IUID Figure:	
Labeling Instructions: Place the label on left side of Rc below top track	
Save Close	
	v
Done	ocal intranet

Portable On-Site Suite

Air Card for off site Citrix connection to SCM Server \$60/month

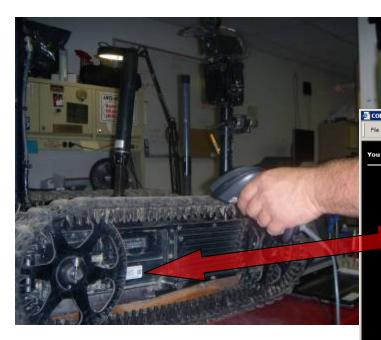


Zebra PT403 Portable Rugged Printer 2" x 1" Mylar ~ \$1000 each

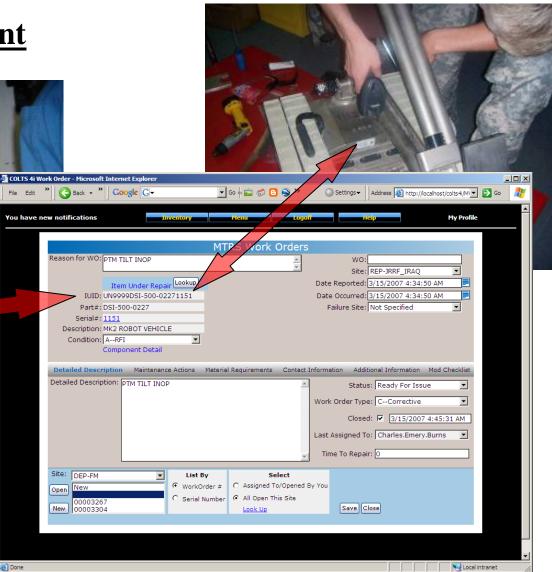
> Note: this Verifier is NMCI compatible and does not need special software.



Maintenance Management

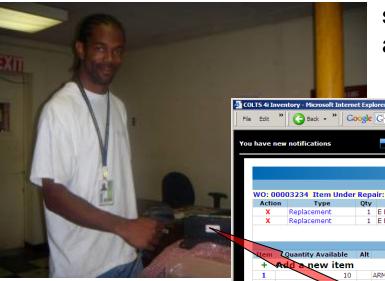


One Scan opens a Work Order and transfers equipment for Asset and Property Book Management.



Shipping, Receiving & **Inventory Management**

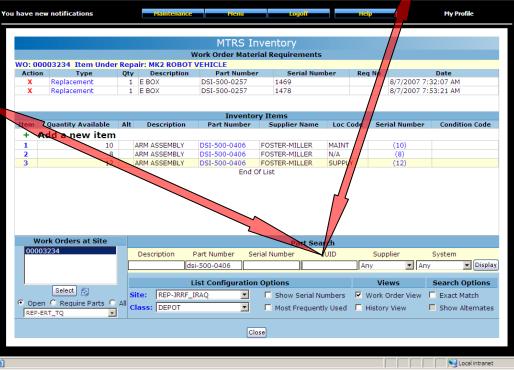
Google G-



Scan to identify issued inventory

Scan to identify issued inventory, items shipped (DD1149). and Items received.

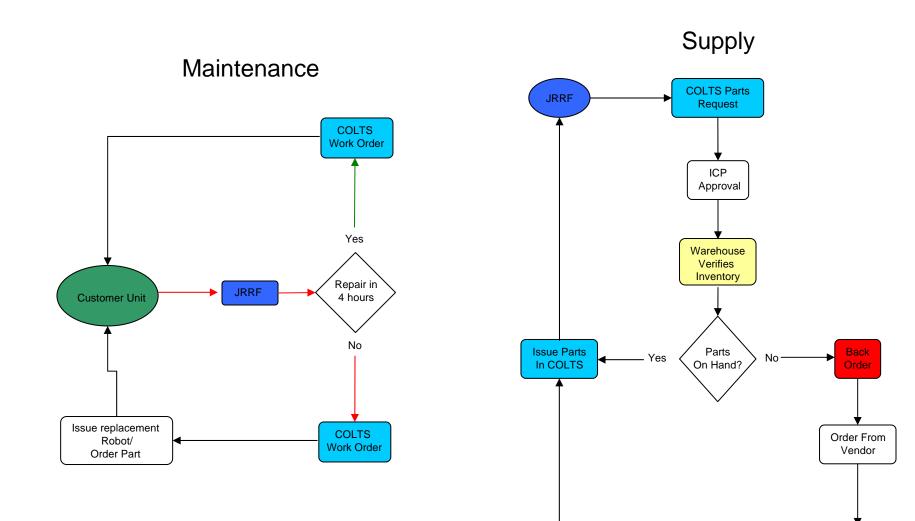
💌 Go 🗄 💼 🧔 🕒 🍛 🌺



Scan to ID items shipped & Received (DD1149)

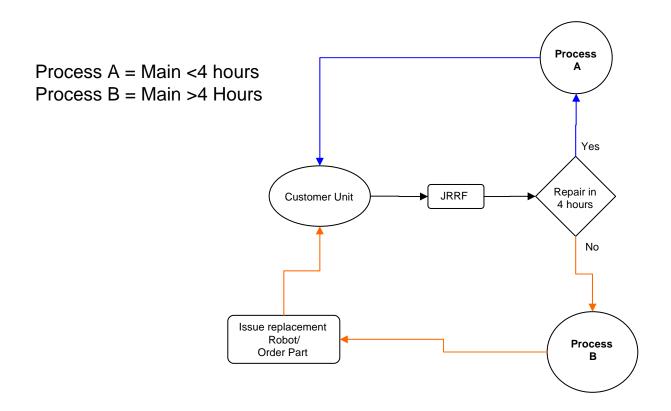
- 🗆 ×

/localhost/colts4i/M 💌 🔁 Go



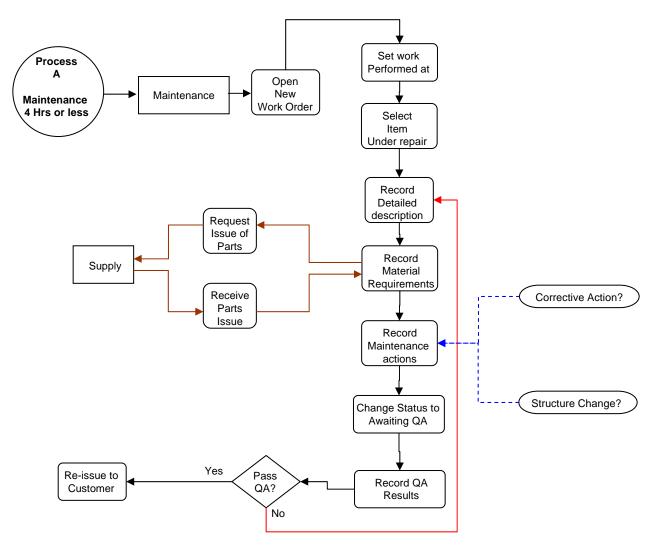
Receive Parts

Maintenance Roadmap



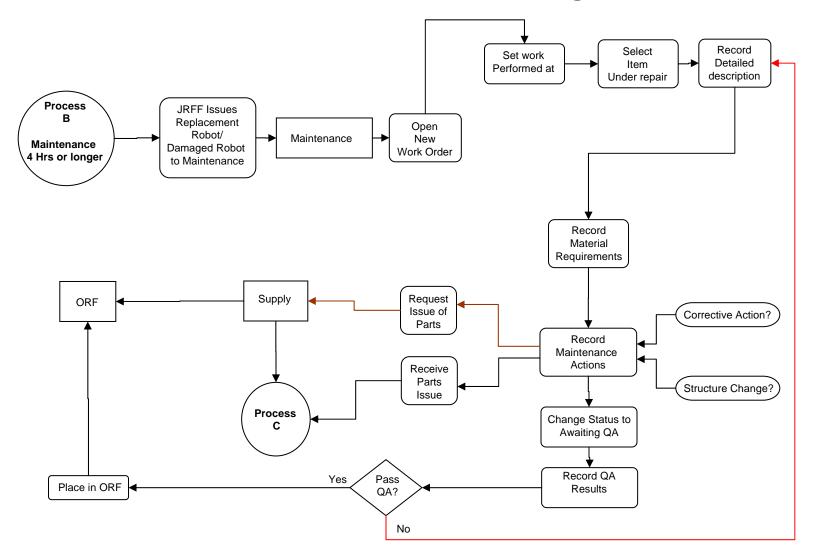
Process A

Maintenance 4 hours or less



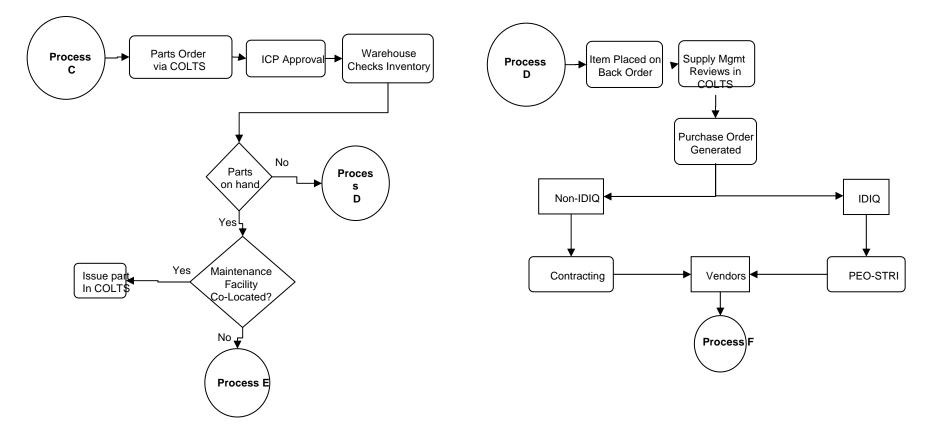
Process B

Maintenance 4 hours or longer

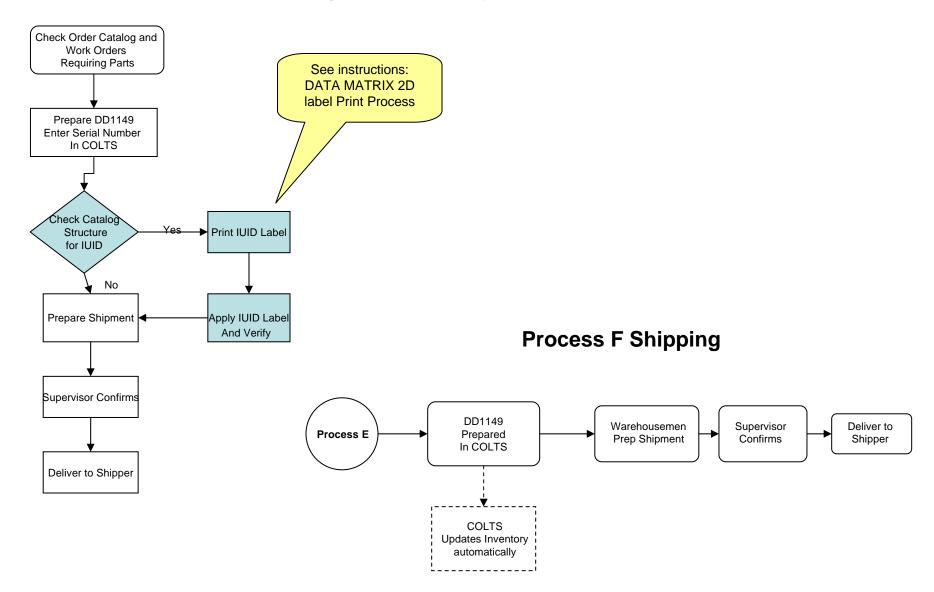




Process D Back Order Parts



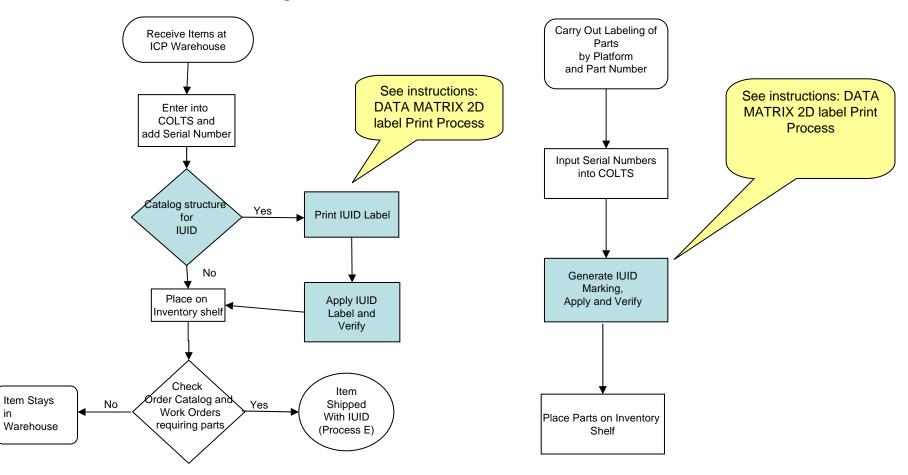
Process E: ICP Shipping from inventory



Process F : ICP Receiving

in

Process G: IUID Applied to Inventory



But what about my reports ?

- COLTS exports to excel. Generate tailored reports
- COLTS can produce "canned reports"
- Our process does not support "mandatory data crunchers"

OIF/OEF Report

Joint Robotic Rep	bair Faci	ility OIF and OEF		C	urrent S	Status as o	f 24-Oct-20	007		JRRF Support
				Qty in Theater	JRRF	Operational	Not	Destroyed	Turned In	Awaiting Repairs/
COTS Items	Unit Cost	Strategy	Theater	(Note 1)	Floats (Note 2)	(Note 3)	(Note 4)	(Note 5)	Last 30 Days	Carcass
Remotec F6A heavy EOD Robot: Air Force	05.040		Iraq	59	2	49	9	0	6	8
an annual MOA between RSJPO and Air Force	85,848	Annual MOA for support	Afghan	1	0	1	0	0	0	0
LVUSS: PoPortable low profile surveillance			Iraq	19	2	17	2	0	3	1
COTS Items Remotec F6A heavy EOD Robot: Air Force platform used to EOD missions. Supported an annual MOA between RSJPO and Air For LVUSS: PoPortable low profile surveillance ground robot. Designed for under vehicle inspection providing stand off capability. Jf supported PACKBOT FIDO PreProduction version: This is a pre-production deployment. Consist of a modified PACKBOT EOD chassis and a FIDO sensor head with no midifications from PACKBOT FIDO: PACKBOT FODO: Modified PACKBOT with FIDO sensor head FIDO: XT Handheld sensor system: FIDO XT Handheld sensor. Can be used as a stand alone or with the PACKBOT FIDO robotic platform. JRRF Supported PACKBOT (Scout): PACKBOT - Scout COTS Matransportable Scout Robot with optics controlled by a Radio Controller Unit (Standard Camera & Multiple Payload PACKBOT - Explorer: PACKBOT chassis with single link arm and camera head assembly PACKBOT (Counter IED): COTS Man- transportable EOD Robot with Robotic Arm, Gripper, and Optics controlled by a Radio Controller Unit (Multiple Payload Capabilitie TALON ENGINEER Platform (3B Chassis): TALOP 3B Chassis modified for engineer missions MINI ANDROS: COTS Man-transportable EOD Robot with Robotic Arm, Gripper, and Optic controller Unit MINI ANDROS: COTS Man-transportable EOD Robot with Robotic Arm, Gripper, and Optic controlled by a Radio Controller Unit DOKING: COTS 6 Ton, Diesel Powered, Removal Fiz Robot controlled by a Radio Controller Unit DOKING: COTS robot for remote vehicle undercarriage inspection with rotating camera.	14,995	JRRF Supported	Afghan	1	0	1	0	0	0	0
PACKBOT FIDO PreProduction version: This is a			Iraq	12	0	12	0	0	0	0
modified PACKBOT EOD chassis and a FIDO XT	175,000	Repair and Return through the JRRF	Afghan	0	0	0	0	0	0	0
			Iraq	90	0	88	1	0	4	0
	184,000	JRRF support repair and return	Afghan	0	0	0	0	0	0	0
2			Iraq	1	0	1	0	0	0	0
alone or with the PACKBOT FIDO robotic	20,770	JRRF Supported	Afghan	0	0	0	0	0	0	0
PACKBOT (Scout): PACKBOT - Scout COTS Man-			Iraq	21	1	19	2	0	1	0
controlled by a Radio Controller Unit	56,500	repair and spare	Afghan	3	0	3	0	0	0	0
			Iraq	0	0	0	0	0	0	0
ngle link arm and camera head assembly.	89,000	Repair at JRRF	Afghan	3	0	3	0	0	0	0
			Iraq	95	8	86	7	0	30	2
Gripper, and Optics controlled by a Radio	115,021	repair and spare	Afghan	48	1	46	2	2	7	1
	404.000	Danaia and Onesa	Iraq	189	11	181	8	0	36	6
TALON EOD: TALON 3B EOD	104,200	Repair and Spare	Afghan	7	1	7	0	2	2	0
TALON ENGINEER Platform (3B Chassis): TALON	105,257	Repair and Spare	Iraq	115	21	106	7	0	30	6
3B Chassis modified for engineer missions.	105,257	Repair and Spare	Afghan	0	0	0	0	0	0	0
	42,401	repair and spare	Iraq	7	0	7	0	0	Turned In Last 30 Days Awaiting F Carca 0 0 0 0 3 1 0 0 3 1 0 0 1 0 36 6	0
	42,401		Afghan	0	0	0	0	0	0	0
DOKING: COTS 6 Ton, Diesel Powered, Remote	0	repair and spare	Iraq	10	0	7	2	0	4	4
	Ū		Afghan	6	1	6	0	0	1	0
	19,000	repair and spare	Iraq	17	7	17	0	0	0	0
	19,000		Afghan	5	0	5	0	0	0	0
MARCBOT: COTS RC Car Robot with with small Robotic Arm and Ontics controlled by a Radio	8,000	repair and spare	Iraq	471	29	457	14	1	21	2
	0,000		Afghan	72	7	72	0	1	2	0
PANTHER Robotic M1: Robotic M-1 Tank Chassis	250,000	JRRF Supported	Iraq	5	0	5	0	0	0	0
	200,000	JANE Supported	Afghan	0	0	0	0	0	0	0

JRRF Daily In-C	Out Re	port																				As o	f 24-Oc
	FI PROD N PA	KBOT DO, DUCTIO CKAGE	PAC MK1 F	rrs Kbot Robot	E	KBOT DD	MK2 RO (WITH GEN	TALON MOD 0 BOT H OCU, I. IV)	VEH ASSE	OS F6A IICLE MBLY	SCO	CBOT OUT	ROB VEH	ICLE	4 SY	NG MV- STEM	EOD F	ROBOT	ENGI ROI VEH	LON NEER BOT ICLE	(see	HER note)	тот
Date	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN	OUT	IN
JRRF - IRAQ (C	AMP \	VICTOR	Y - IRA	NQ)																			
(Mon) 01-Oct-2007	0	1	3	0	0	0	1	0	1	0	0	0	0	0	0	0	0	0	2	0	0	10	
(Tue) 02-Oct-2007	0	0	0	0	4	0	0	0	1	0	2	0	0	0	0	0	0	0	0	1	1	0	
(Wed) 03-Oct-2007	0	0	3	0	5	0	0	0	1	0	1	0	0	0	0	0	0	0	3	0	0	0	
(Thu) 04-Oct-2007	0	1	0	0	0	0	0	3	1	0	0	1	0	1	0	0	0	3	0	1	0	2	
(Fri) 05-Oct-2007	0	0	0	1	1	1	2	2	0	2	0	0	0	0	0	0	0	2	0	3	0	0	
(Sat) 06-Oct-2007	0	0	0	0	0	0	0	0	0	0	0	0	2	0	0	0	0	0	1	0	1	0	
(Sun) 07-Oct-2007	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	1	0	1	0	0	0	
(Mon) 08-Oct-2007	2	0	0	5	0	9	0	3	0	1	0	4	0	2	0	0	1	4	0	4	0	4	
(Tue) 09-Oct-2007	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	1	0	
(Wed) 10-Oct-2007	0	0	0	0	1	0	0	0	0	0	0	0	0	0	1	0	0	1	3	0	0	0	
(Thu) 11-Oct-2007	0	0	0	0	0	0	2	0	0	0	0	0	0	0	0	0	1	0	1	0	1	0	
(Fri) 12-Oct-2007	0	2	0	0	0	1	0	0	0	1	1	0	0	0	0	0	1	1	1	4	1	1	
(Sat) 13-Oct-2007	0	0	4	2	3	0	6	5	0	0	0	2	0	0	0	0	0	1	0	3	1	0	
(Sun) 14-Oct-2007	0	0	2	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	2	2	
(Mon) 15-Oct-2007	0	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0	0	0	1	0	0	0	
(Tue) 16-Oct-2007	0	0	0	2	0	2	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	
(Wed) 17-Oct-2007	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	
(Thu) 18-Oct-2007	0	0	1	0	0	0	1	1	0	0	0	0	0	0	0	0	1	0	5	0	1	0	
(Fri) 19-Oct-2007	0	0	0	1	0	1	0	1	0	0	0	0	0	0	0	0	1	2	0	5	1	1	
(Sat) 20-Oct-2007	0	0	1	0	2	1	9	9	0	0	1	0	0	0	0	0	4	1	0	1	3	0	
(Sun) 21-Oct-2007	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	2	0	0	0	0	0	
(Mon) 22-Oct-2007	0	0	0	1	2	1	1	0	0	0	0	0	0	0	0	0	2	6	1	0	0	3	
(Tue) 23-Oct-2007	0	0	0	0	0	0	1	0	0	0	0	0	0	0	1	0	1	0	1	0	3	0	
(Wed) 24-Oct-2007	0	0	0	0	1	2	0	1	0	0	0	0	0	0	1	0	2	1	0	0	0	0	
MONTH	2	4	14	13	20	18	24	28	4	4	6	7	2	3	3	0	18	22	20	22	16	23	129
Week 1	0	2	6	1	10	1	3	5	4	2	3	1	2	1	0	0	0	5	6	5	2	12	36
Week 2	2	2	4	7	4	10	8	9	0	2	2	6	0	2	1	0	4	7	6	11	4	5	35
Week 3	0	0	4	4	3	4	11	13	0	0	1	0	0	0	0	0	7	3	6	6	7	3	39
Week 4	0	0	0	1	3	3	2	1	0	0	0	0	0	0	2	0	7	7	2	0	3	3	19
ORF (24-Oct-2007)	0		0		7		0		2		15		0		0		7		9		8		

JRRF JRRF - IRAQ (CAMP VICTORY - IRAQ) Date 10/24/2007

	Asset Information					Work Order Information
					Status	Date
Loc Code	Description	Serial Number	Cond	Status		Work Order # Reported Last Tech
MAINT	ANDROS F6A VEHICLE ASSEMBLY	F8011-19	F	AWAITING PARTS	3/8/2007	RM7067F8011-19 3/8/2007 Azzinaro Hayes - JRRF-I came from the Air Force missing these items JRRD-1 ORD Awaiting Parts In Stock E2455-2000 7 C2455-3650 8
MAINT	ANDROS F6A VEHICLE ASSEMBLY	F8084-41	F	AWAITING PARTS	5/25/2007	RM7144F084-41 5/24/2007 Azzinaro Hayes - JRRF-I no power / arm assy/wheels/tracks/battery Awaiting Parts In Stock B-2021-1062 0
MAINT	ANDROS F6A VEHICLE ASSEMBLY	F8011-24	F	AWAITING PARTS	10/12/2007	E-2455-2000 0 RM7277F8011-24 10/4/2007 Azzinaro Hayes - JRRF-I
						Awaiting Parts In Stock E-2455-2000 0 C7040-4638 1 C2455-3650 8 E2455-3080 0 E2455-8150 0
MAINT	ASSY,SYSTEM,PCC,PACKBOT EOD	00200392	F	IN PROCESS	10/9/2007	RM7282392 10/9/2007 Donald Osborne JRRF-I Arm preset will not work
MAINT	DOK-ING MV-4 SYSTEM	MV-4-047	F	AWAITING SHOP	10/10/2007	RM7283MV4047 10/10/2007 Jim Yaronczyk INITIAL INSPECTION COLTS SAYS IRAQ ARMY (UNK) SEVERAL DISCEPANCIES NOTED ON VEHICLE AND TRAILER (SEE WRITE UPS); AWAITING DECISION ON DISPOSITION OF TRAILER
MAINT	MTRS TALON MK2 MOD 0 ROBOT (WITH OCU, GEN. IV)	I TAL-MTRS-1073	A	IN PROCESS	10/11/2007	MTRS72841073 10/11/2007 Phil Edwards Had broken vehicle power switch. In process of upgrading to V2.0, LAN connector on computer failed and Vehicle stopped communication with OCU and Comp via Menu. Swapped out E box SN 1404 with SN 1073. OCU will not boot. Swapped out OCU 1073 for 1183. Evidently some of the OCU's don't get along with the upgrade. I reverted the Veh and OCU back and they worked.
MAINT	MARCBOT SCOUT	MK4-0191-0432	F	IN PROCESS	10/20/2007	Programmed radio to red. RM7293432 10/20/2007 Donald Osborne JRRF-I Lower arm motor inop, will not drive fwr,movement in left and right control, camera assy has a short. Replaced data antenna. Replace IR camera. Calibrated arm, wrist, PT
MAINT	TALON ENGINEER ROBOT VEHICLE	TAL3B-FMI-ENG-608	A	READY FOR ISSUE	10/24/2007	and gripper settings. RM7295608 10/22/2007 Charles.Emery.Burns JRRF-I Replaced Gripper due to bent fingers. Replaced PT due to tilt inop. Replaced arm lower harness due to breakage. Repaired vehicle power switch. During Ops check, power started to cycle. Lost power. Upon investigation, had problem with rear camera. Replaced C box manifold, had problem with PDB. Replaced PDB, had problem with Power switch in wire ahead of repalced switch. Replaced E-box manifold. The problem was the LI battery in the vehicle. It would run for about 5 min then cut out. It would come on after a minute and ther
MAINT	TALON ENGINEER ROBOT VEHICLE	TAL3B-FMI-ENG-440	F	IN PROCESS	10/23/2007	out again. The meter read 40.5 volts. RM7296440 10/23/2007 Jim Yaronczyk NO COMMS; NO PWR FROM VEHICLE 1138 ENG CO. (WX2JAA) FOUND F6 FUSE BLOWN; REPLACED; NO POWER TO FREEWAVE; REPLACED VMUX; INTERMITTENT POWER AFTER RUNNING TESTS; Awaiting Parts In Stock RDSI-01147 58

Inventory Status Report

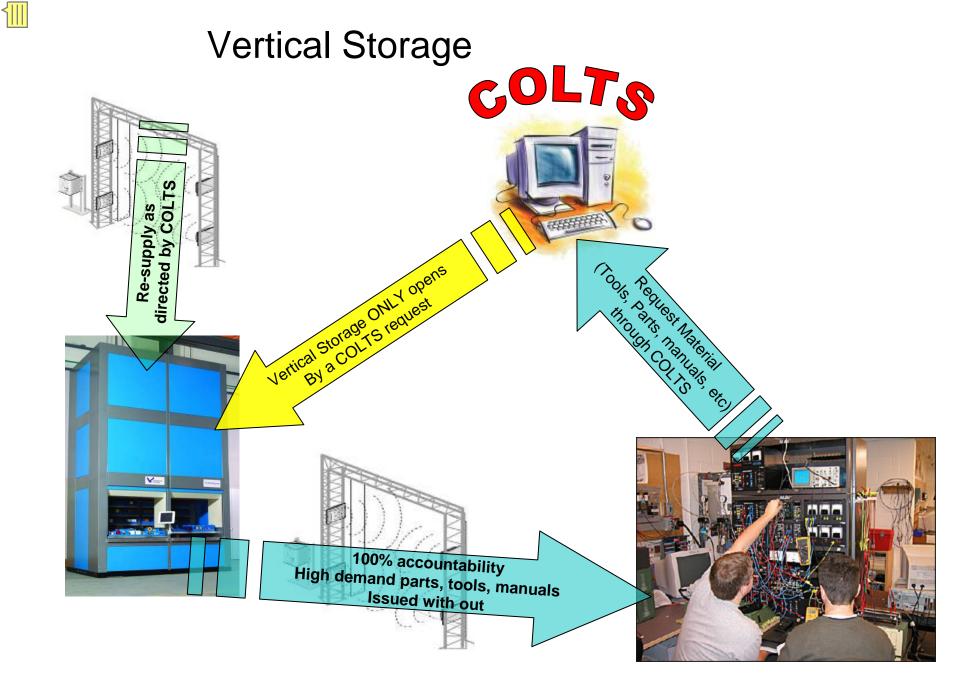
			JRRF								
	Inver	tory Status f		FGHA	NISTAN					i	
Part Number	Description	Supplier Name	Project	Loc Code	Qty Available	Reorder Point	Stock Obj	Demand	Qty On Order	Reorder Qty	
3TC-70801	SOLDIER PORTABLE CHARGER (SPC), MULTI-	BREN-TRONICS		N/A	11	4		10	D	0	
STC-UN110	CHARGER, FOR TALON 3B ROBOT	FOSTER-MILLEI		N/A	10	4		10	D	0	
28767WN		HEWLETT PACK		N/A	29	0)	0	D	0	
CH-16492	FILTER	DOK-ING	DOK-ING	N/A	8	0)	0	D	0	
OSI-100-0020	BULB, HALOGEN, P/N 376686 (FOR ILLUMINTIC	FOSTER-MILLEI	TALON	INV CO5	12	4	1	6	D	0	
SI-130-0052	HARNESS ASSEMBLY, EXTENSION, CAMERA,			AAE2B	3	2	2	3	D	0	
SI-130-0058		FOSTER-MILLEI		N/A	12	2	2	8	D	0	
SI-130-0092	HARNESS, ARM EXTENSION	FOSTER-MILLEI	TALON	N/A	14	2		8	D	0	
SI-130-0101		FOSTER-MILLEI		N/A	4	2		4	D	0	
SI-130-0109		FOSTER-MILLEI		N/A	4	2		-	D	0	
OSI-130-0111		FOSTER-MILLE		AAE2C	6	1		3	D	0	
SI-130-0129	CABLE ASSEMBLY, GRIPPER ADAPTER, THRE			N/A	15	4		-	D	0	
SI-130-0144	CABLE ASSEMBLY, OCU CONTROL SIDE ANTE			N/A	10	2		10	D	0	
)SI-130-0159	HARNESS ASSEMBLY, FOR NIGHT VISION ZOO			N/A	2	1		2	D	0	
SI-140-0001		FOSTER-MILLEI		N/A	7	3			D	0	
SI-140-0034		FOSTER-MILLEI		N/A	4	2		4	0	0	
SI-140-0080	CABLE ASSEMBLY, FOUR-PIN MALE, STRAIGH			N/A	4	2		4	0	0	
SI-140-0109	BEARING, FLANGED	FOSTER-MILLEI		N/A	10	5		•	0	0	
SI-140-0110	BEARING, FLANGED, EXTERNAL RETAINING R			N/A	10	5			0	0	-
OSI-140-0147	BATTERY PLUG, SIX-PIN CONNECTOR COVER			N/A	5	4			0	0	-
SI-140-0153	CABLE ASSEMBLY, SUBCONN 16 PIN (X2 MAL			N/A	4	2	·	-	0	0	
)SI-140-0179		FOSTER-MILLEI		N/A	4	2		-	n l	0	
SI-140-0204		FOSTER-MILLEI		N/A	6	4	-	-	0	0	-
OSI-140-0204	BATTERY CHARGER, ILLUMINATION PACKAGE			N/A	6	3		-	0	0	
OSI-140-0070	IDLER HUB BUSHING, FLANGED BEARING (8/P			N/A	59	8		-	0	0	-
)SI-140-0735	FREEWAVE RADIO TRANSCEIVER, DATA, S-BA			N/A	7	6		-	0	0	-
SI-140-0702	RADIO TRANSMITTER, DATA, L-BAND - 918 MH			N/A	4	2		-	0	0	-
)SI-160-0132		FOSTER-MILLEI		N/A	- 4	2		-	0	4	-
SI-160-0132		FOSTER-MILLEI		N/A	9	2		•	0	0	-
SI-160-0408	CAMERA MOUNT, IR ILLUMINTAED CAMERA			N/A	3	2		-	0	0	-
SI-160-0490		FOSTER-MILLEI			8	2		-	0	0	-
SI-160-0705	ANTENNA, VIDEO, OCU, 2.0-2.5 GHZ (S-BAND)				4	2		-	0	0	-
	ANTENNA, VIDEO, OCO, 2.0-2.5 GHZ (S-BAND) ANTENNA, VEHICLE, DATA, OCU, 3B & MTRS,				8	2		-	0	0	<u> </u>
SI-160-0693-2		FOSTER-MILLEI		N/A	0 1	1			D D	1	-
SI-200-0004		FOSTER-MILLEI		INV CO5	18	0		-	0	0	-
SI-200-0004 SI-200-0015	· · ·	FOSTER-MILLEI		N/A	27	0		-	0	0	<u> </u>
SI-200-0015		FOSTER-MILLEI		N/A	8	0		-	0	0	
SI-500-0024	CAMERA ASSEMBLY, REMOTE CONTROLLED			N/A	7	0		-	0	0	
SI-500-0042	ANTENNA, VIDEO, BASE VEHICLE, 3B & MTRS				12	2			0	0	
SI-500-0096		FOSTER-MILLEI		N/A N/A	4	2	-	-	0	0	
SI-500-0113	· · · · · · · · · · · · · · · · · · ·			N/A N/A	4			-	0	0	-
	ILLUMINATION PACKAGE, FOWARD LOOKING					2		-	-	-	
SI-500-0125	TRACK AND SPROCKET ASSY, TALON HEAVY	FUSTER-MILLE	TALON	N/A	2	3		6	D	4	



Where we are going

Where we are going

- Vertical storage (Feb 2008)
 - 100% automated accountability. COLTS opens the drawer not the user
 - High use items will be co-located with technicians
 - Tool room and library functions
- Integrated RFID (Apr 2008)
 - End items will receive passive RFID
 - ICP inventory will receive passive RFID
 - IUID/RFID and our SCM will be one package



Just the facts (1 Jan 07 - 1 Oct 07)

- COLTS Supply & Maintenance Data
 - 6073 Work orders completed
 - 26,375 maintenance actions
 - 64,419 Inventory events (Parts movement)
 - 78,467 Asset events (Robot actions/movement/repair, etc)
 - 4,816 Items shipped
- 64 EOD robots rebuilt from destroyed condition. Cost savings approximately 3.2 million dollars.
- Operational rate on all supported platforms has never been below 100% since Apr 05.
- IUID integration saves the RSJPO time, money and ultimately lives on the battlefield.
 - No more "lost" data due to human error
 - Shorter repair cycle time as a result of IUID "scan in & scan out"
 - More fidelity of data tracked in COLTS due to IUID decision process.
 - Routine logistics processes streamlined with IUID and hand scanner.
 - Configuration management integrated with all SCM actions

