



3D Laser Scanning (LiDAR Surveying) and Oblique Photogrammetry Assessment During the 2004 High Flow Test

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Evaluation of Mapping Techniques at 30 Mile Sandbar in Grand Canyon

- **LiDAR Surveying**
 - Nov. 19, 2004 data collection
- **Oblique Photogrammetry**
 - Nov. 19, 2004 data collection

And compared to

- **Conventional Surveying**
 - Nov. 16, 2004 data collection



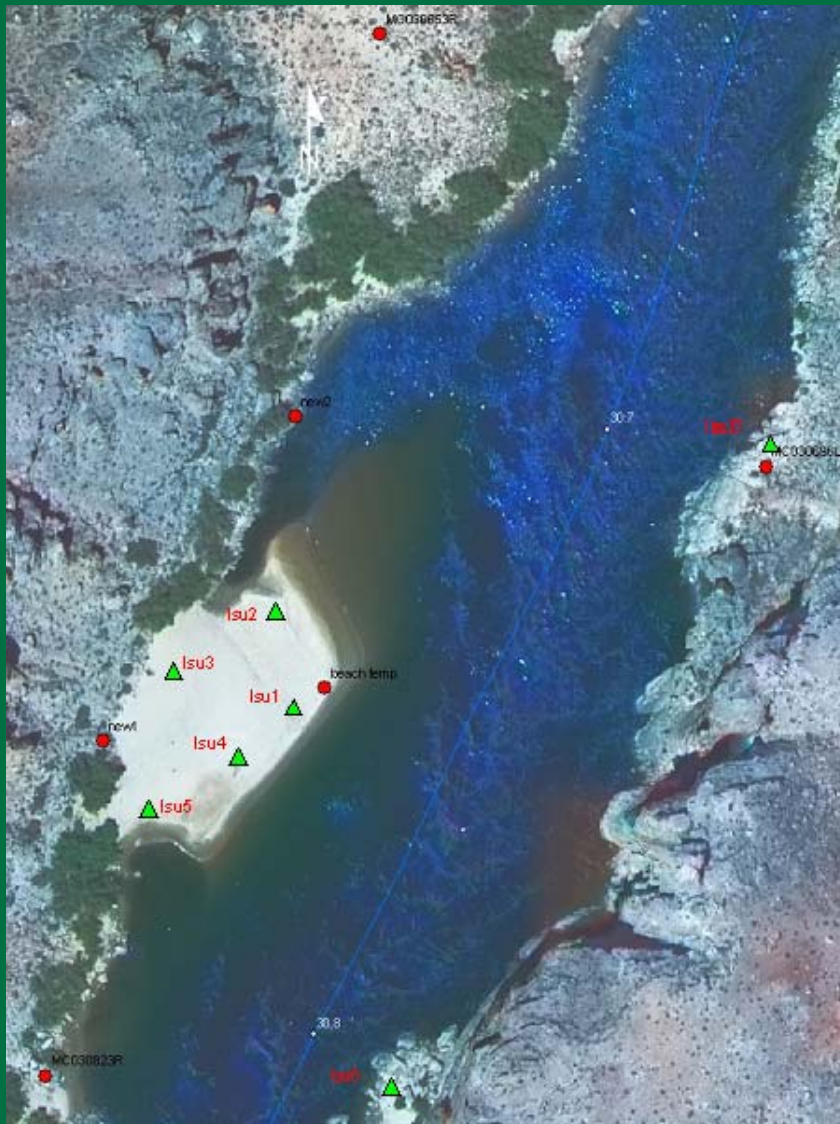
LiDAR Surveying

- Tripod mounted LiDAR system
- Requires control visible in the scan
- 15-20 minutes per scan
 - Multiple scans may be needed to fill in “shadow zones”
- Scan of 336 degrees
- A maximum of two people needed to run system
- Cost for LiDAR Scanner and Software
 - \$50,000 and up

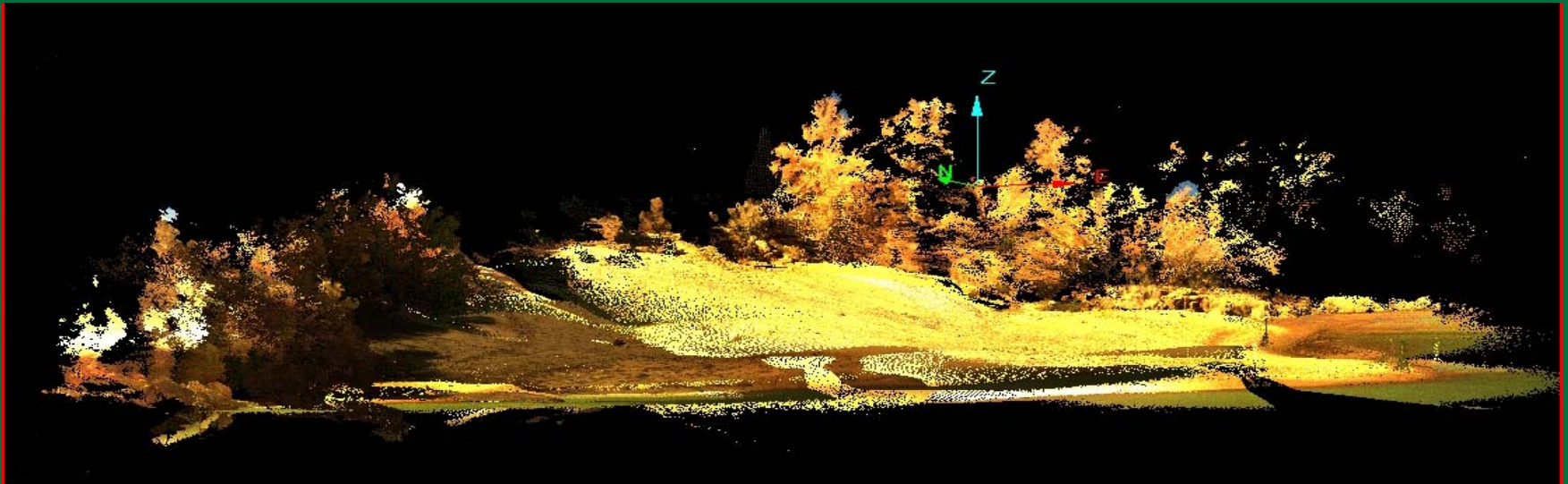


Mile 30 Sand Bar

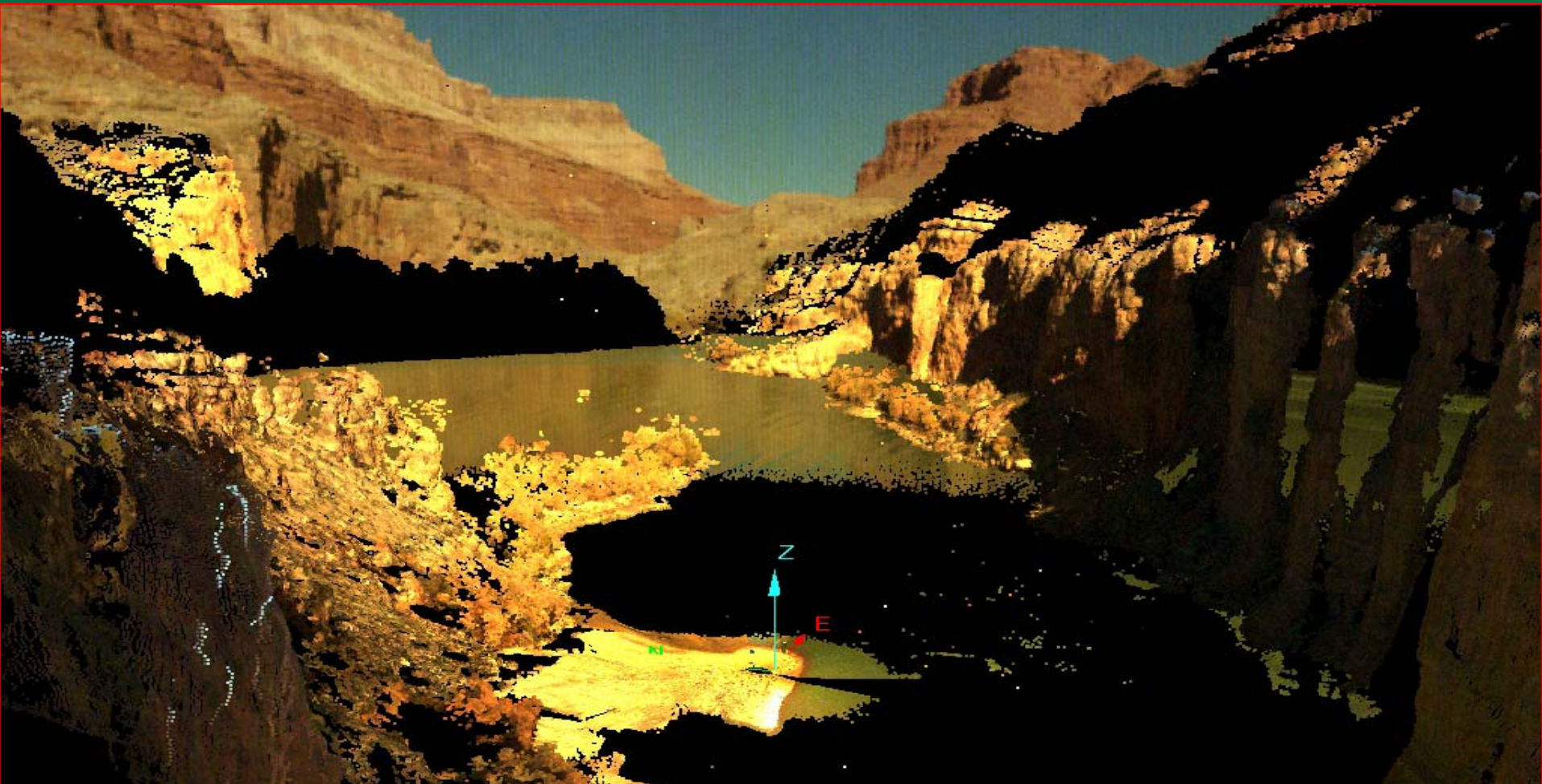
Locations of
laser scans and
survey control.



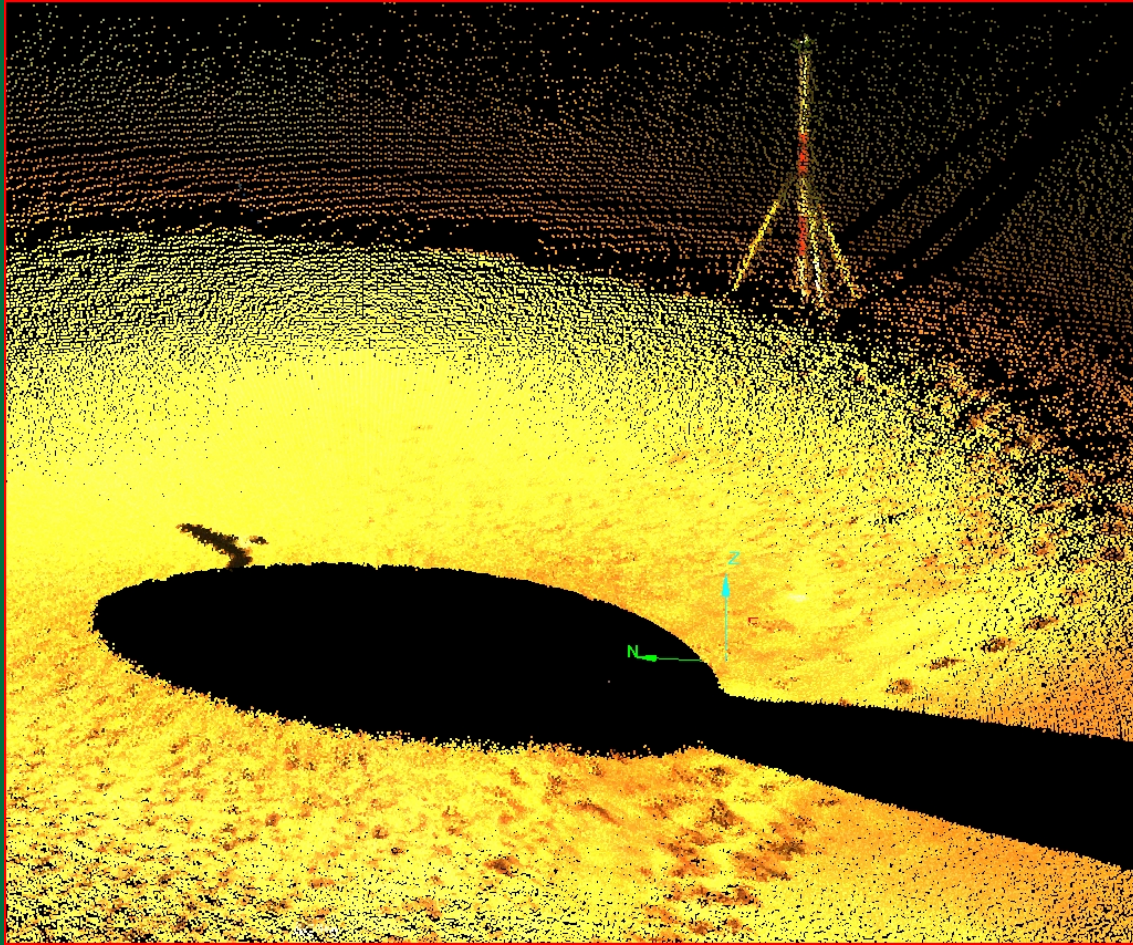
Raw Point Cloud LiDAR Data for 30 Mile Sand Bar



Fly through perspective looking upstream and includes background color data

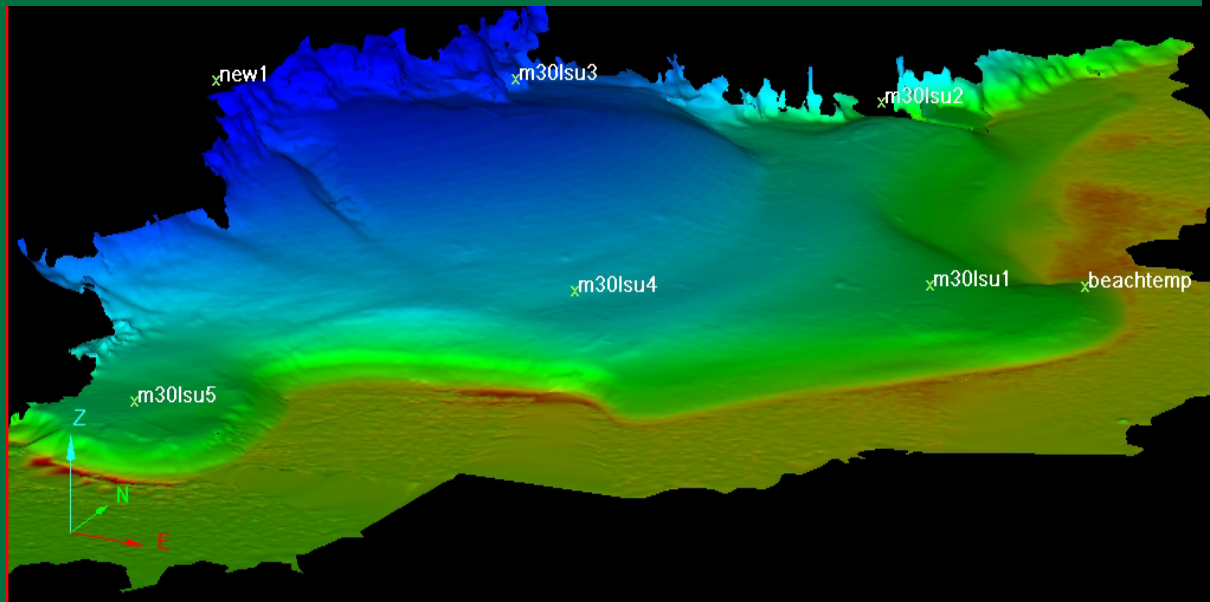
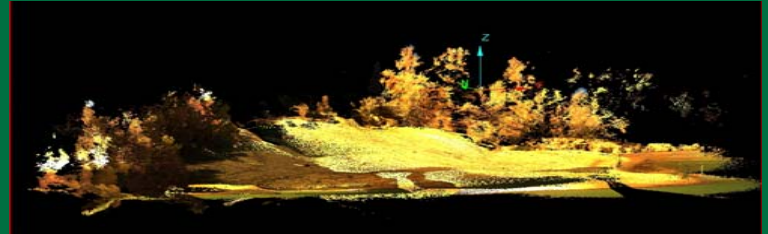


LiDAR Scan captures detail of sand bar surface



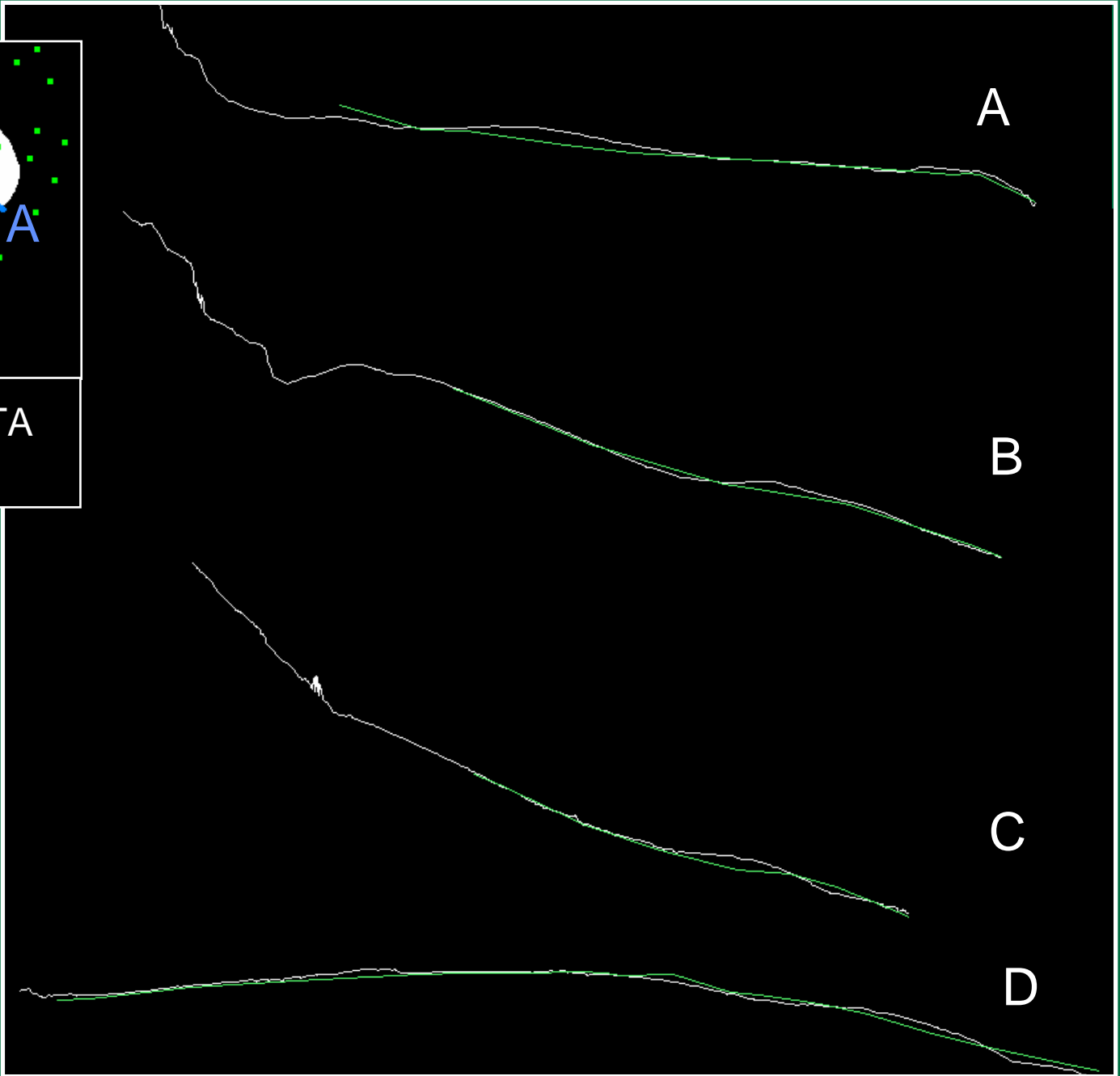
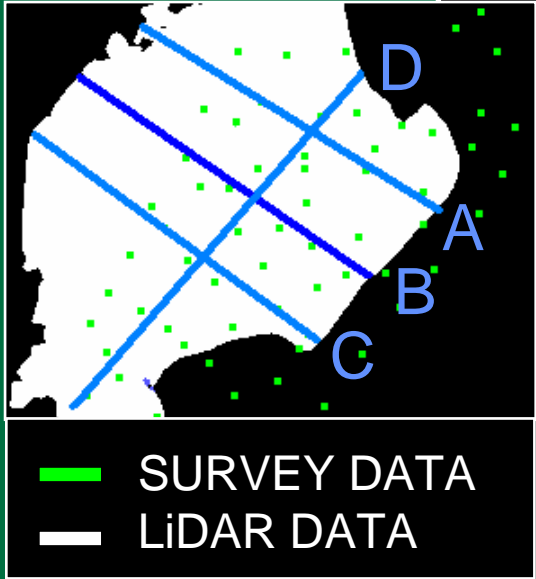
Processing LiDAR Data

- Edit Raw Scan Data
 - Delete vegetation
- Filter Scan Data to desired resolution
- Generate surface for each scan
- Combine surfaces with best fit fusion to generate new surface points



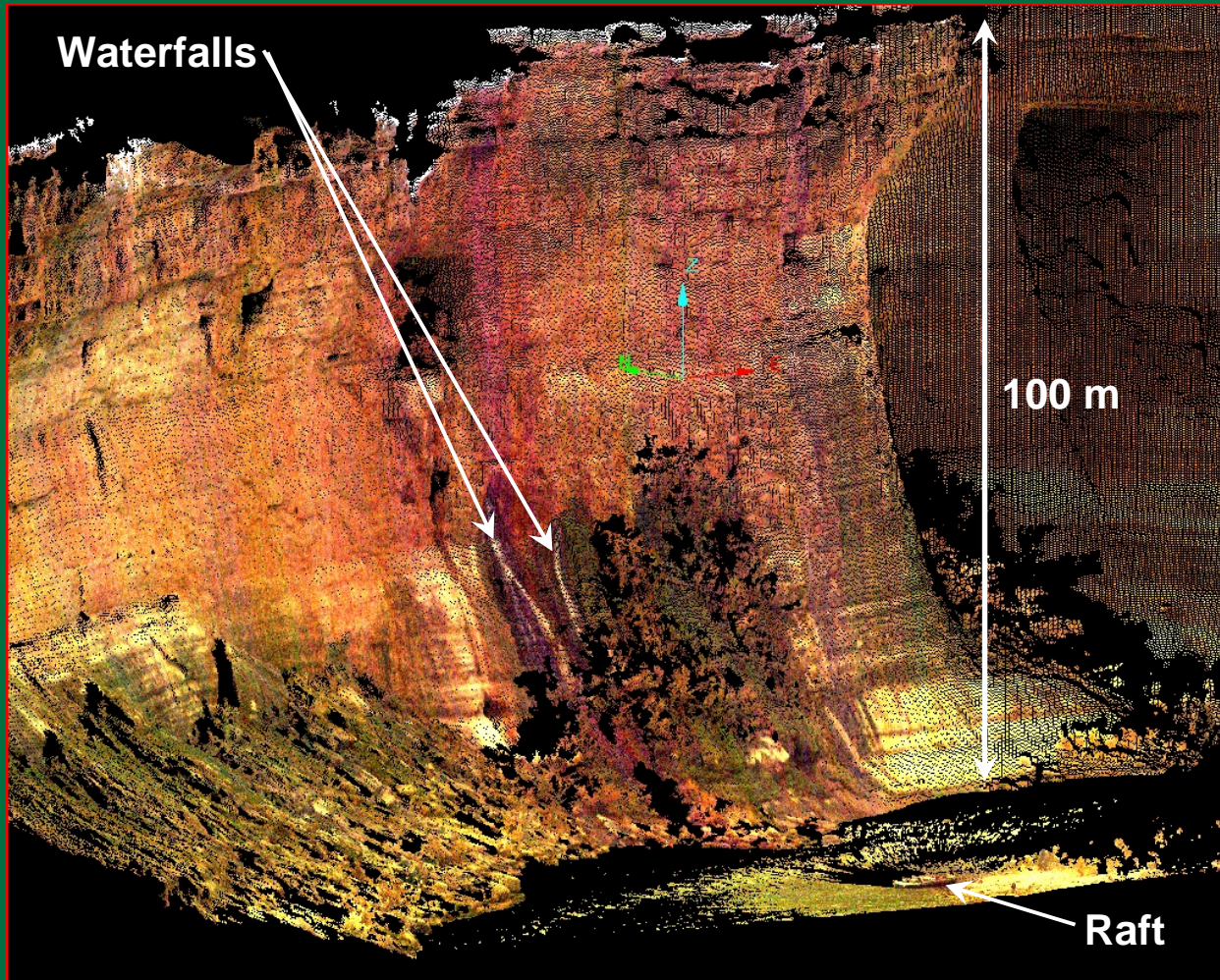
Point to Point Comparison

Difference (cm) n=37	Northing	Easting	Elevation
Average	2.9	1.9	4.6
Maximum	44.5	43.2	49.0
Minimum	-13.5	-12.3	-31.0
Range	58.0	55.5	80.0
Standard Deviation	10.5	9.6	17.6
Median	1.9	-0.1	1.0



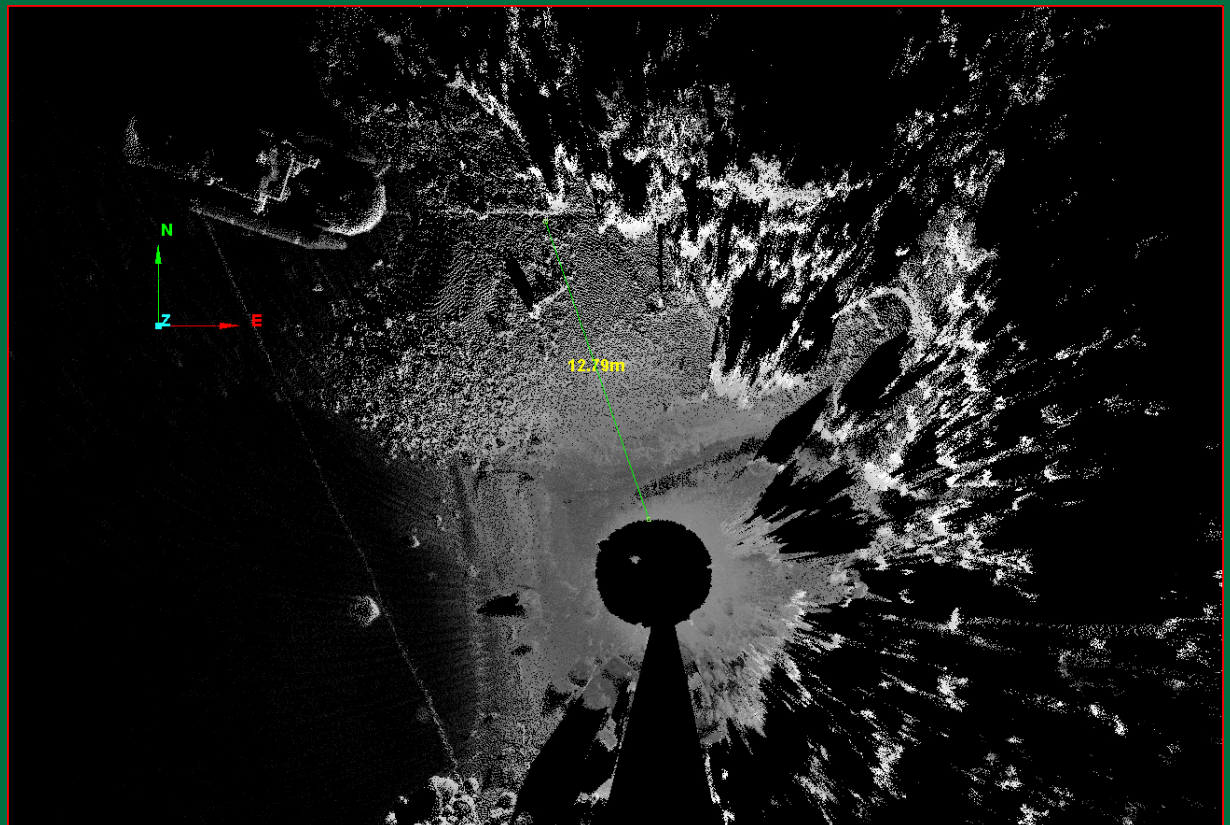
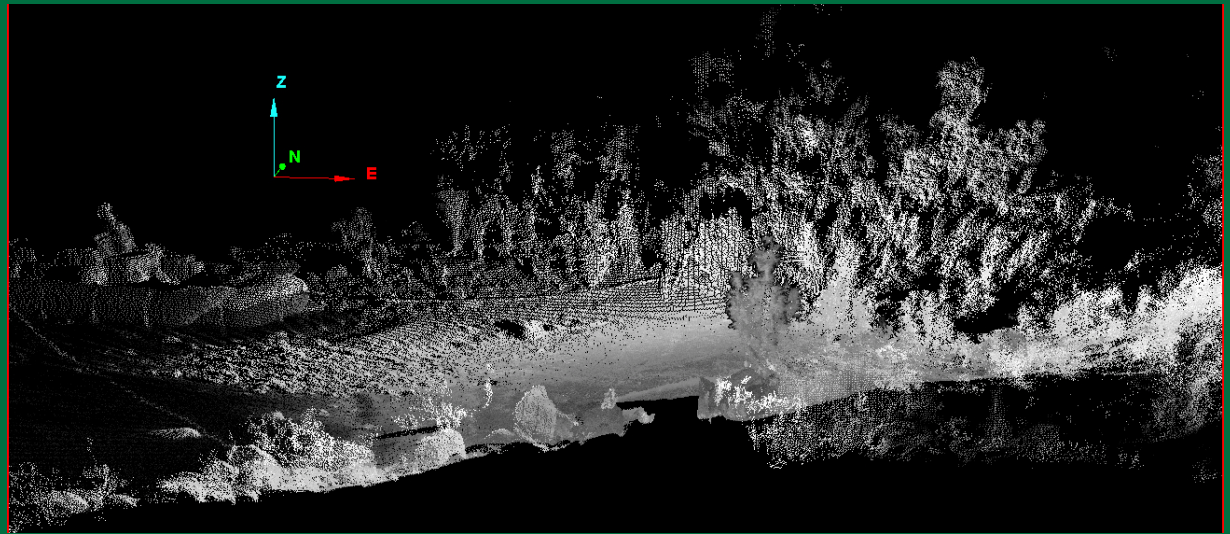
Relative Cross Section Comparison

LiDAR Surveying at Vasey's Paradise



Palisades Raw LiDAR Data

- Vegetation and flat terrain impaired LiDAR data acquisition



Oblique Photogrammetry

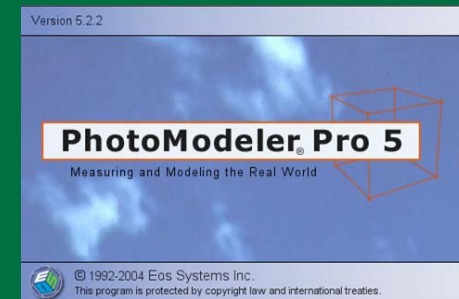
Equipment

- Digital Camera - 6 Megapixel or better
- Control Points, targets and objects of known length
- Software – PhotoModeler, Z/I Imaging ImagineStation

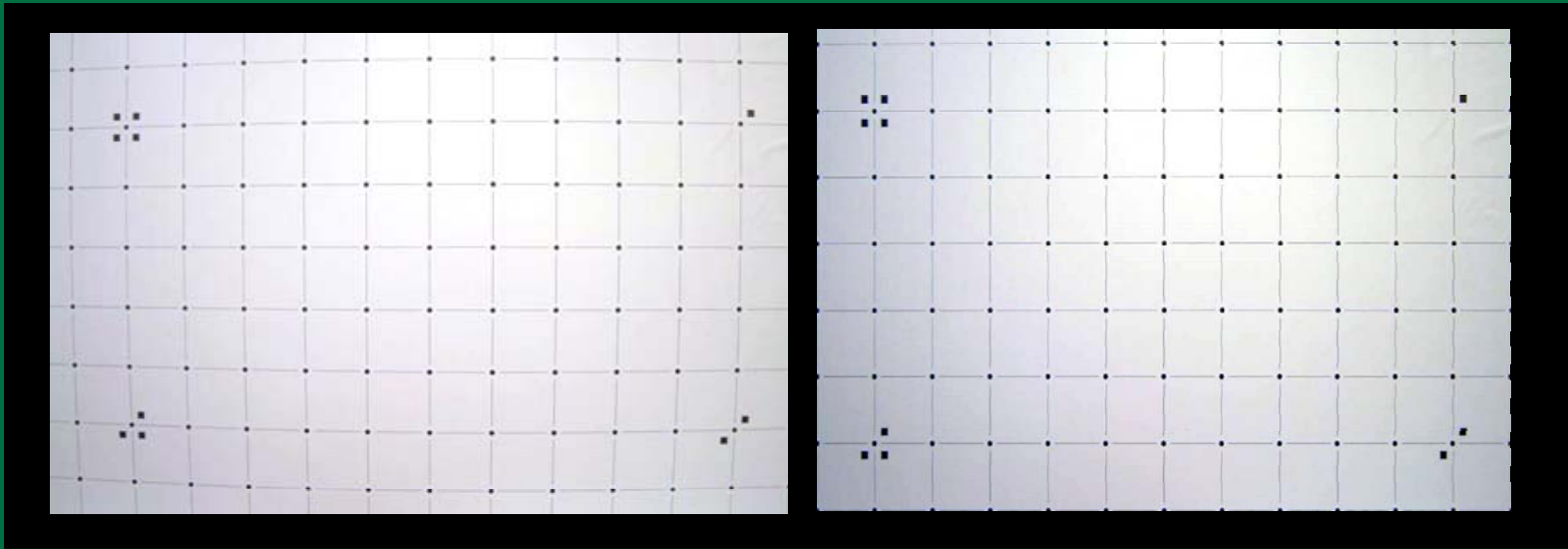
The Process

- Camera Calibration
- Visible control for georeferencing
- Targets or natural reference points visible on multiple photographs
- Series of “orientation” or “survey” photographs
- Series of “stereo photographs

Cost for camera set-up, hardware, and software – up to \$5,000 to \$50,000



Camera Calibration



The following parameters are provided from completing the camera calibration process:

- format size
- focal length
- principal point
- distortion coefficients



Field Set-up for Oblique Photogrammetry Work



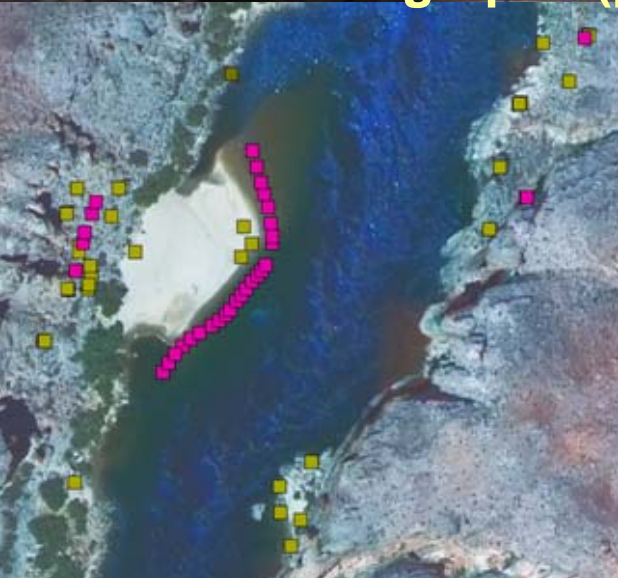
TARGETS



Photographs are taken from several locations

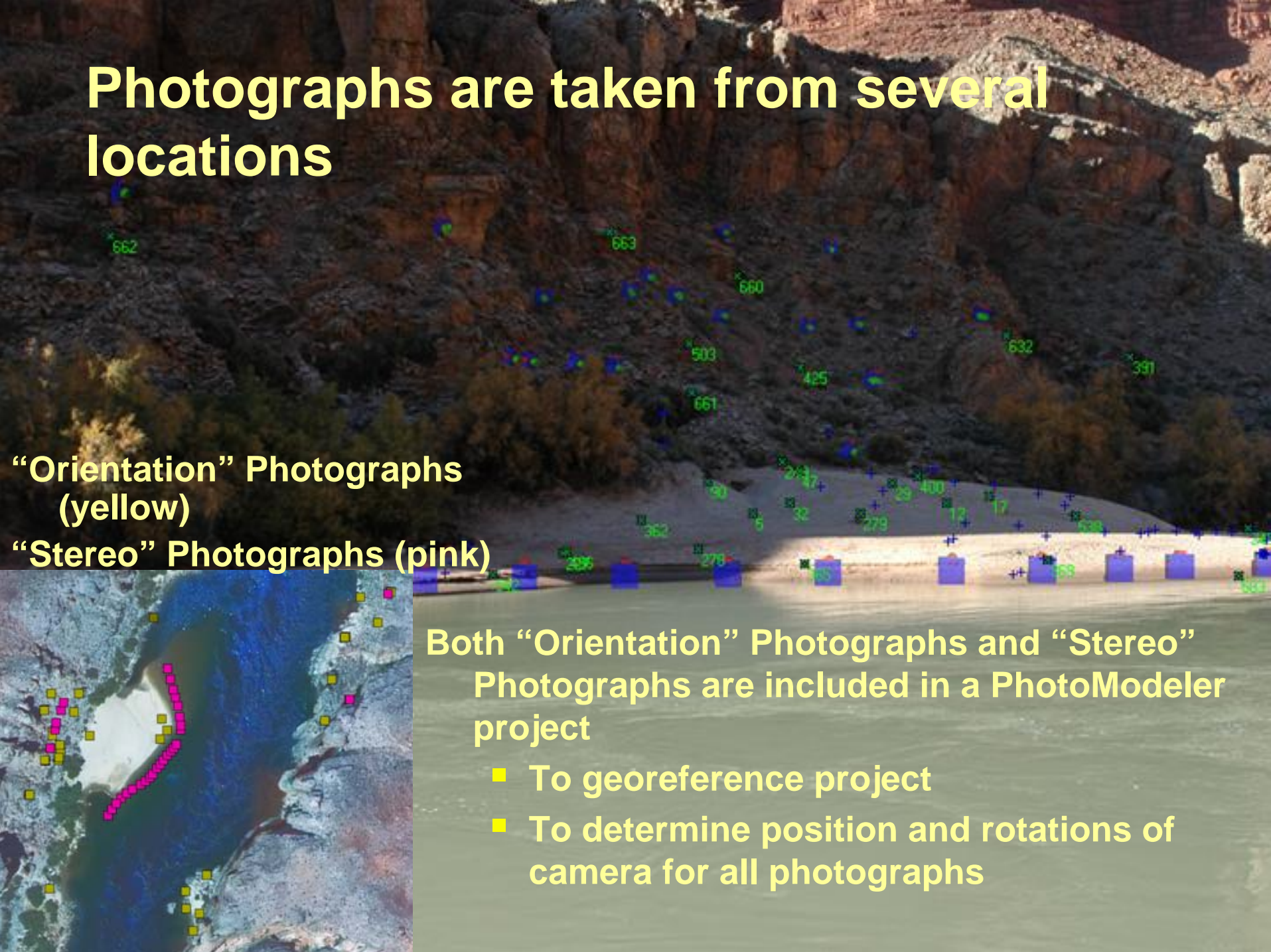
“Orientation” Photographs
(yellow)

“Stereo” Photographs (pink)



Both “Orientation” Photographs and “Stereo” Photographs are included in a PhotoModeler project

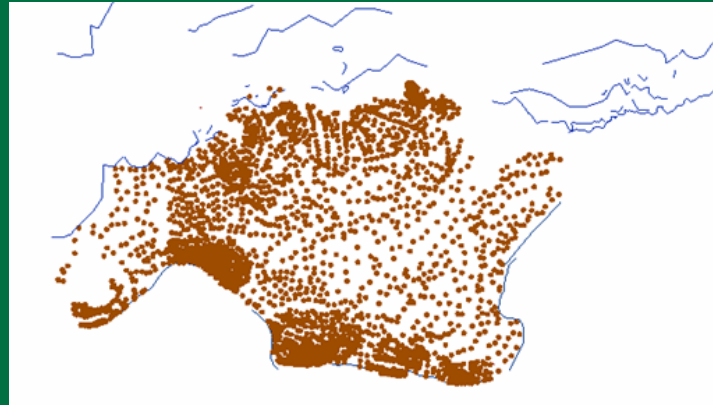
- To georeference project
- To determine position and rotations of camera for all photographs



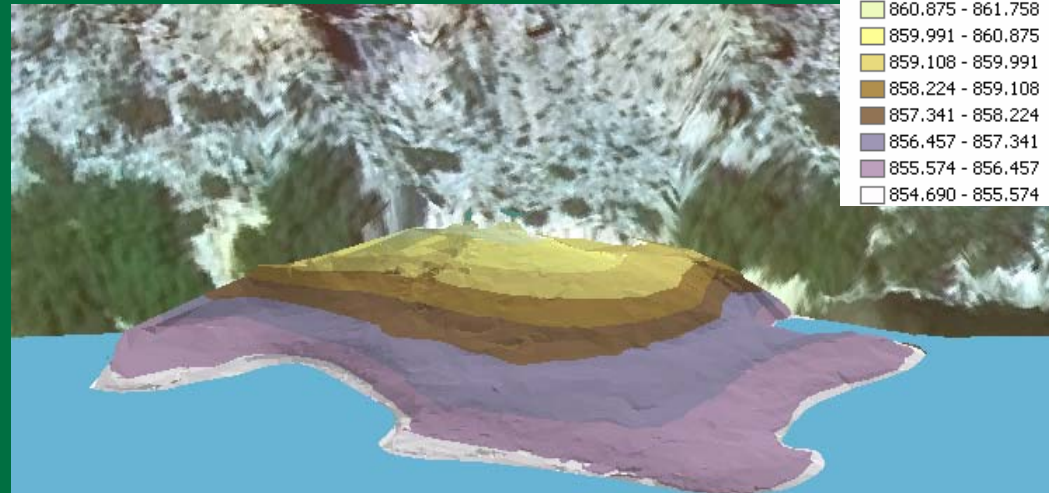
Softcopy Photogrammetry Workstation



- Define breaklines and select common points between photographs
- Perform Image matching

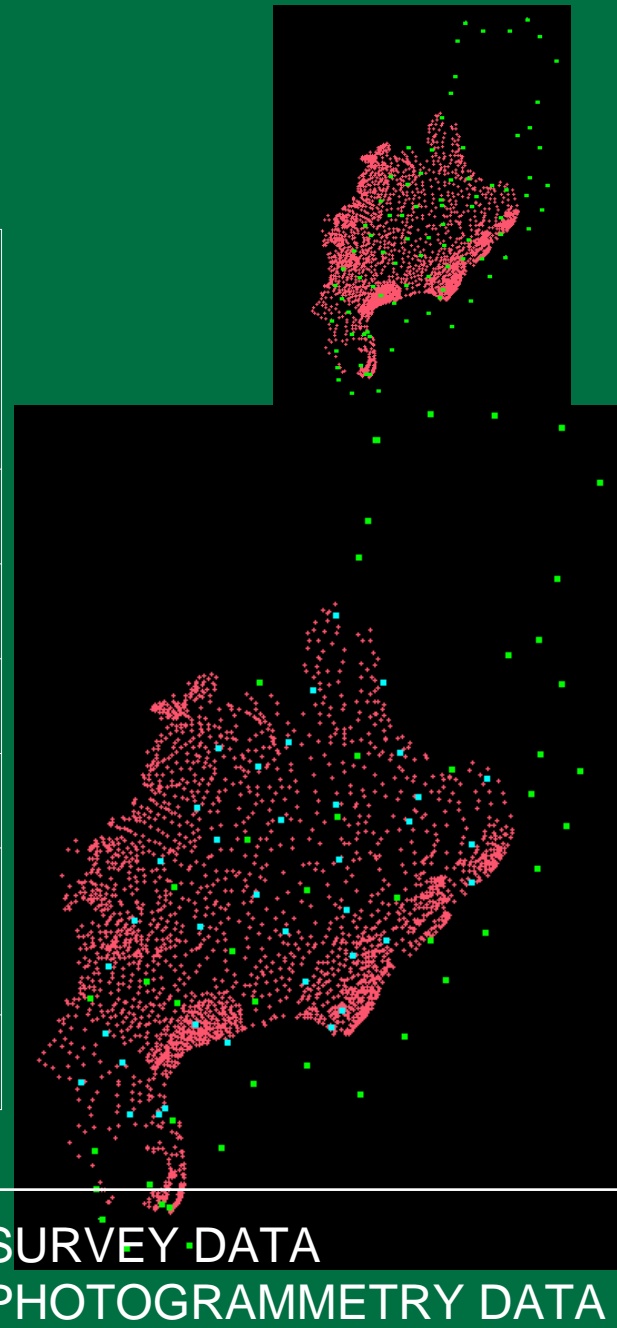


Points are generated from image matching or manually selected in the photogrammetry software (2411 pts)

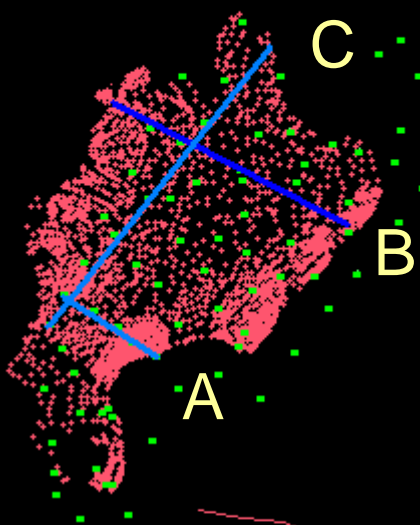


Point to Point Comparison

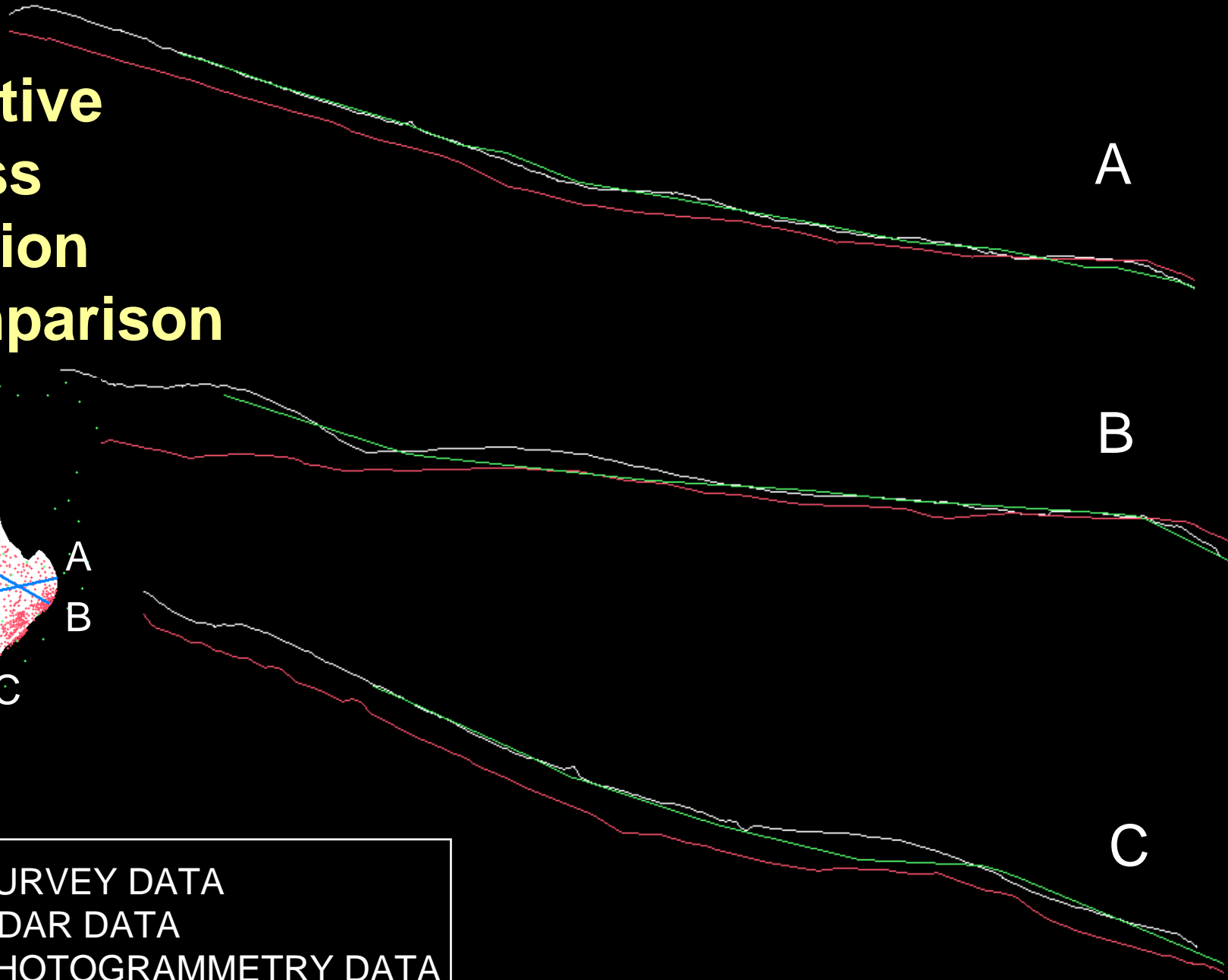
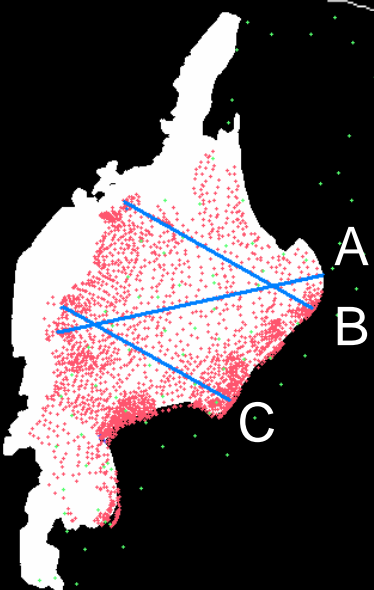
Difference (cm) n=38	Northing	Easting	Elevation
Average	0.5	5.8	-38.8
Minimum	-66.6	-86.6	-92.0
Maximum	49.8	72.0	15.0
Range	116.4	158.6	107.0
Standard Deviation	29.2	41.2	26.9
Median	4.1	12.9	-38.0



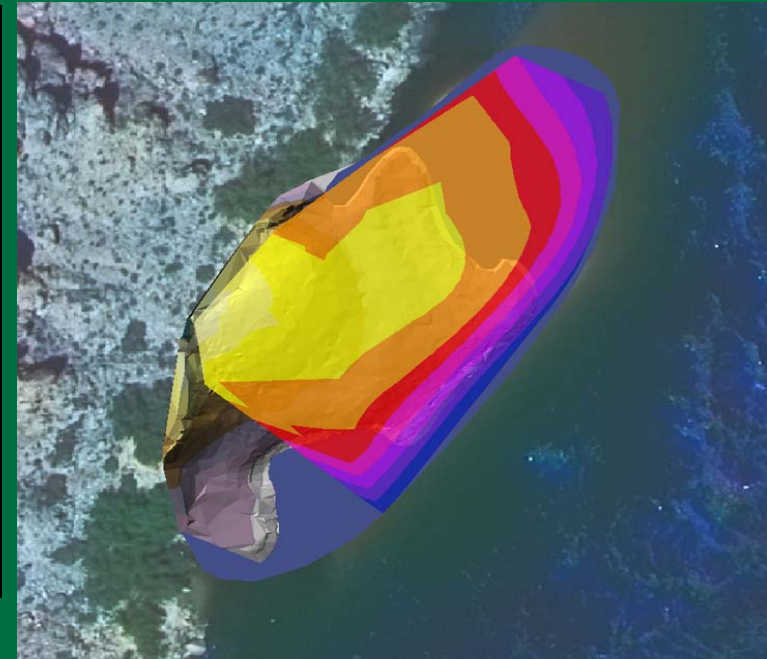
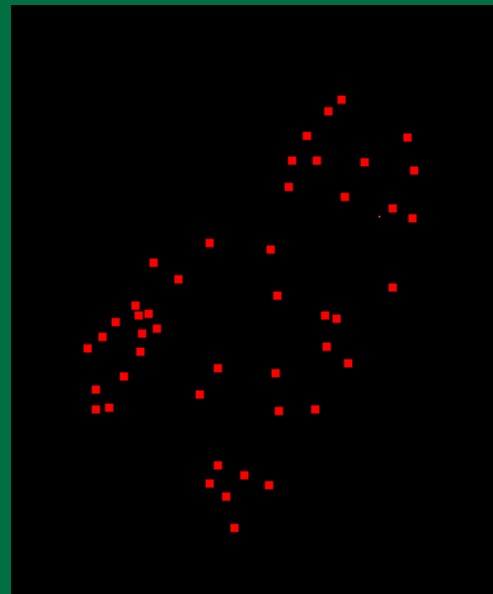
Relative Cross Section Comparison



Relative Cross Section Comparison



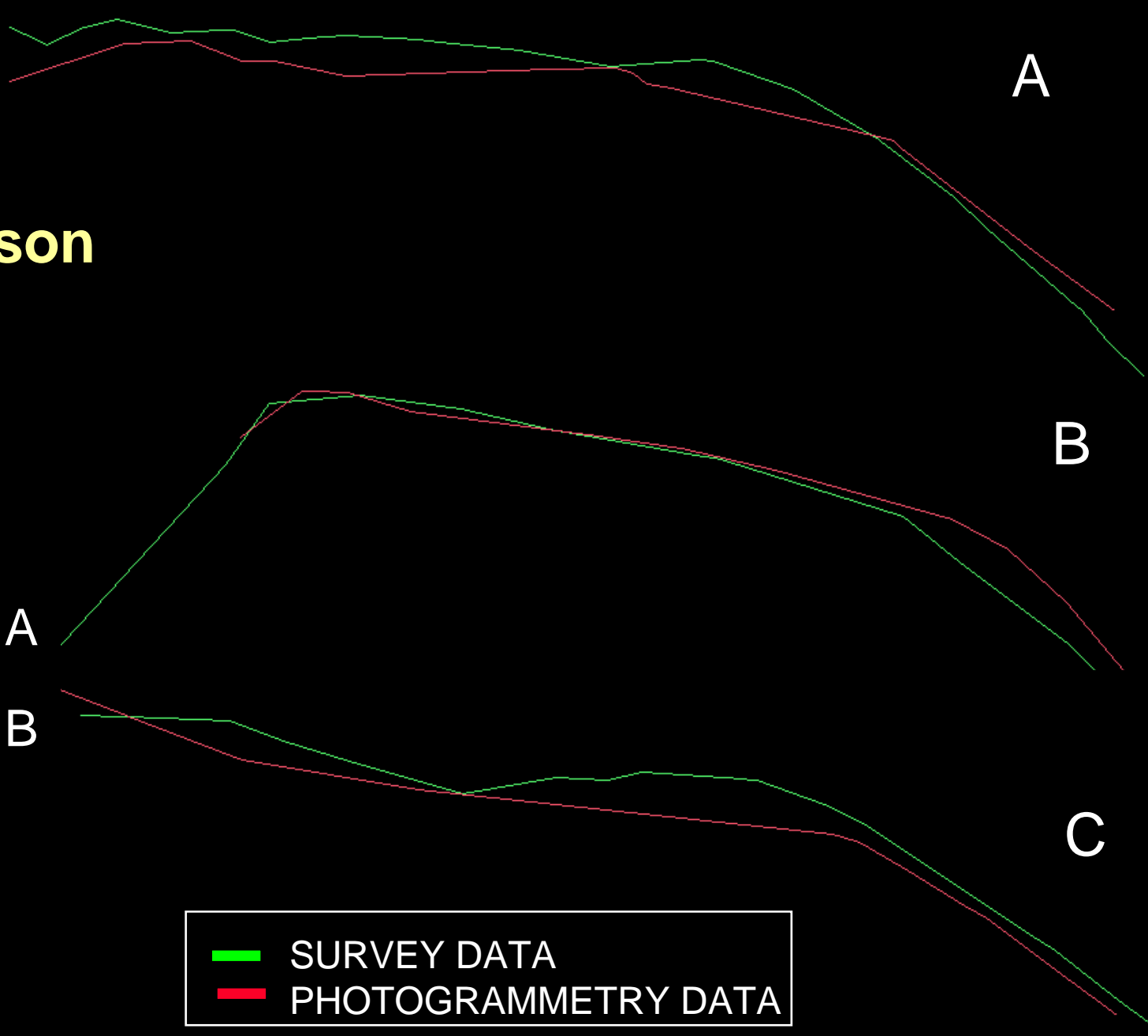
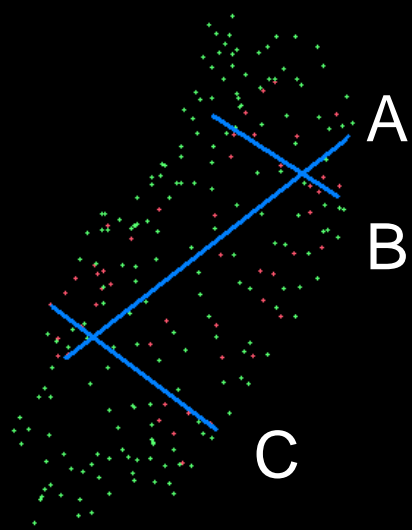
Post Flood Photographs to Generate Terrain Models



Point to Point Comparison

DIFFERENCE (cm) n=9	NORTHING	EASTING	ELEVATION
AVERAGE	-13.0	6.2	-31.9
MAXIMUM	84.0	66.0	26.0
MINIMUM	-83.0	-72.0	-70.0
RANGE	167.0	138.0	96.0
STANDARD DEVIATION	60.0	47.0	36.8
MEDIAN	-22.0	16.0	-37.0

Relative Cross Section Comparison



Conclusions

- **Vertical Error Assessment (Std value)**
 - LiDAR – 18 cm and an average of 5 cm
 - Photogrammetry – 27 cm and an average of 38 cm

Benefits of LiDAR Surveying and Oblique Photogrammetry

- Applicable to research that will tolerate the error
- Increased point density
- Applicable to monitor small features
- Efficient mapping methods
- Collect data for inaccessible sites
- Remote data acquisition (Photogrammetry)

Shortcomings

- Require exposed ground, topographic relief, and minimal vegetation
- Trouble in complicated terrain - arroyos



Thanks!