

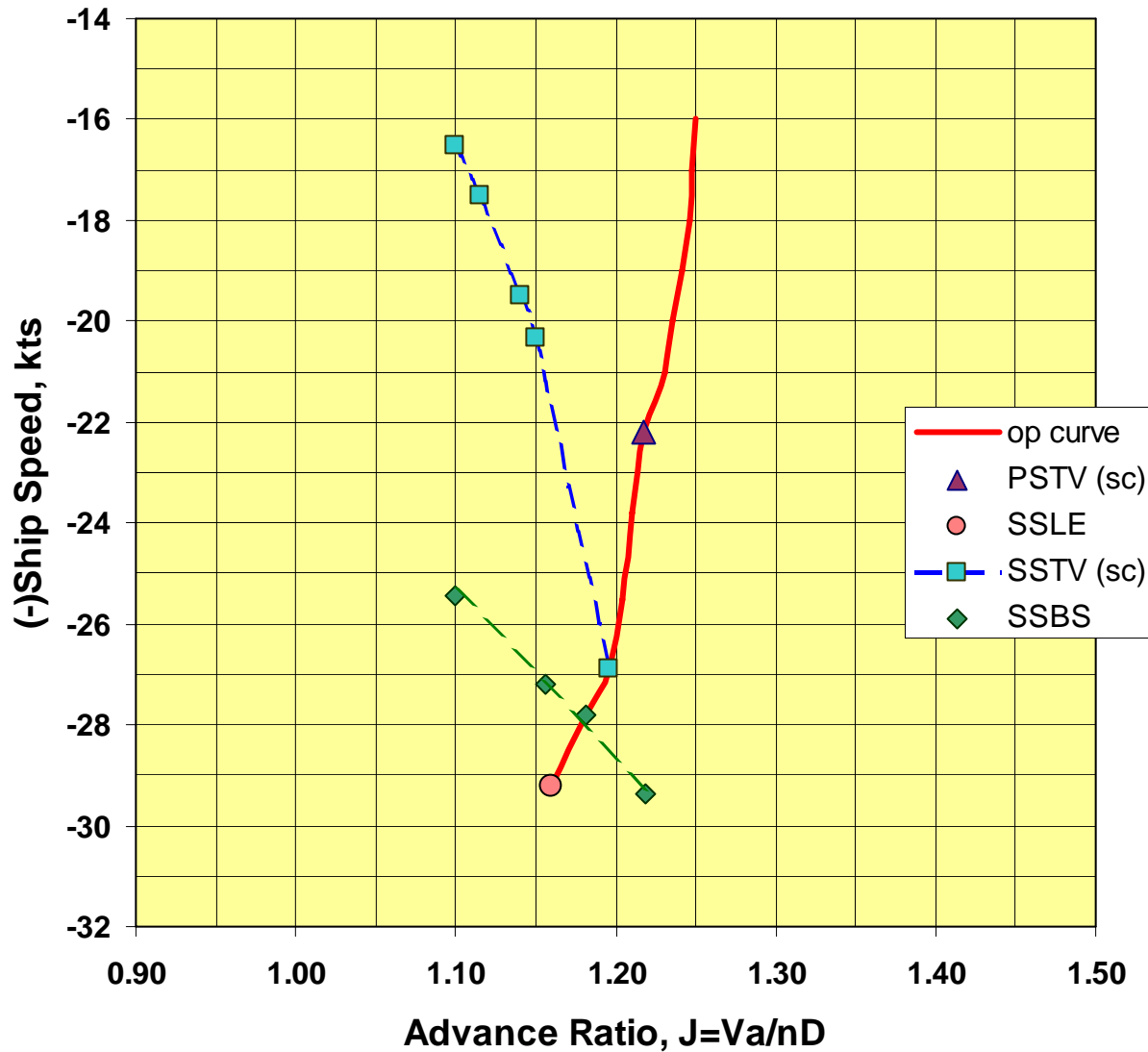
**Existing/Future Technology to Address  
Radiated Noise by Modifying Vessel  
Propulsion and Operating Parameters**

**(& a few other un-scheduled topics)**

**N. A. Brown**

*2007 NOAA Vessel-Quieting Symposium*

**Inception Ship Speed vs Advance Ratio**



**As ship speed increases, various forms of propeller cavitation are found to begin and then grow in size and intensity. For large, slowly turning propellers the inceptions can be delayed to higher ship speeds.**

Pressure Side  
Suction Side  
Blade Surface  
Tip Vortex  
Leading Edge

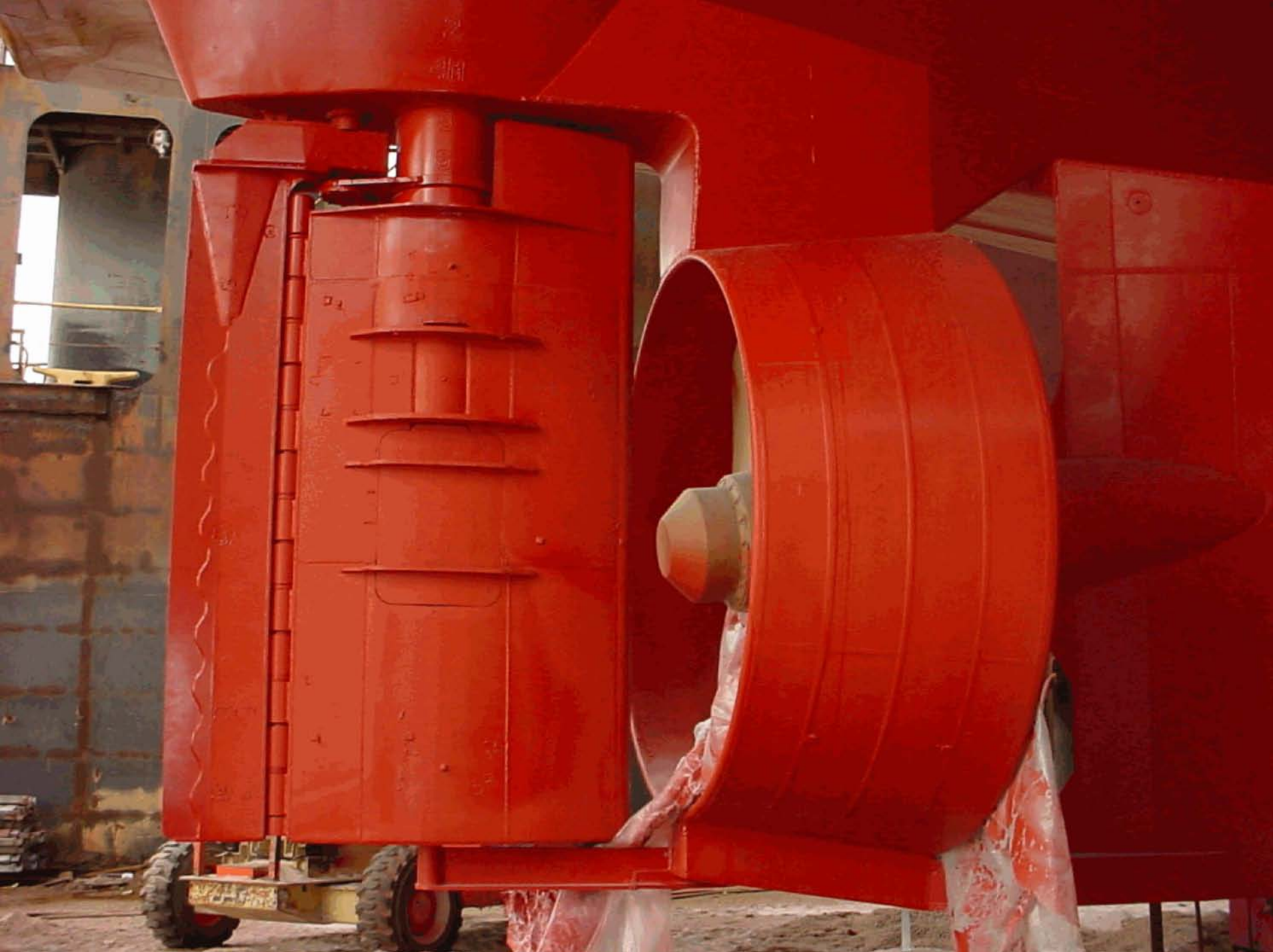
**Propeller cavitation is generally governed by a parameter, aptly named the “cavitation number”:**

$$\sigma = \frac{p - p_v}{\frac{\rho}{2} U^2}$$

**This is the ratio of pressure-above-vapor-pressure - to - dynamic pressure.**

**Cavitation of one sort or another will occur (incept) when  $\sigma$  falls below a particular value.**

**Given a submergence pressure, propeller cavitation is mitigated by reduction of propeller tip speed.**



**Single-screw ships enjoy a propulsive efficiency benefit by recovering the frictional drag energy in the wake.**

**Unfortunately, where lift is generated, as in propeller blades, by angle-of-attack ( $\alpha$ ) the cavitation number can be expanded to:**

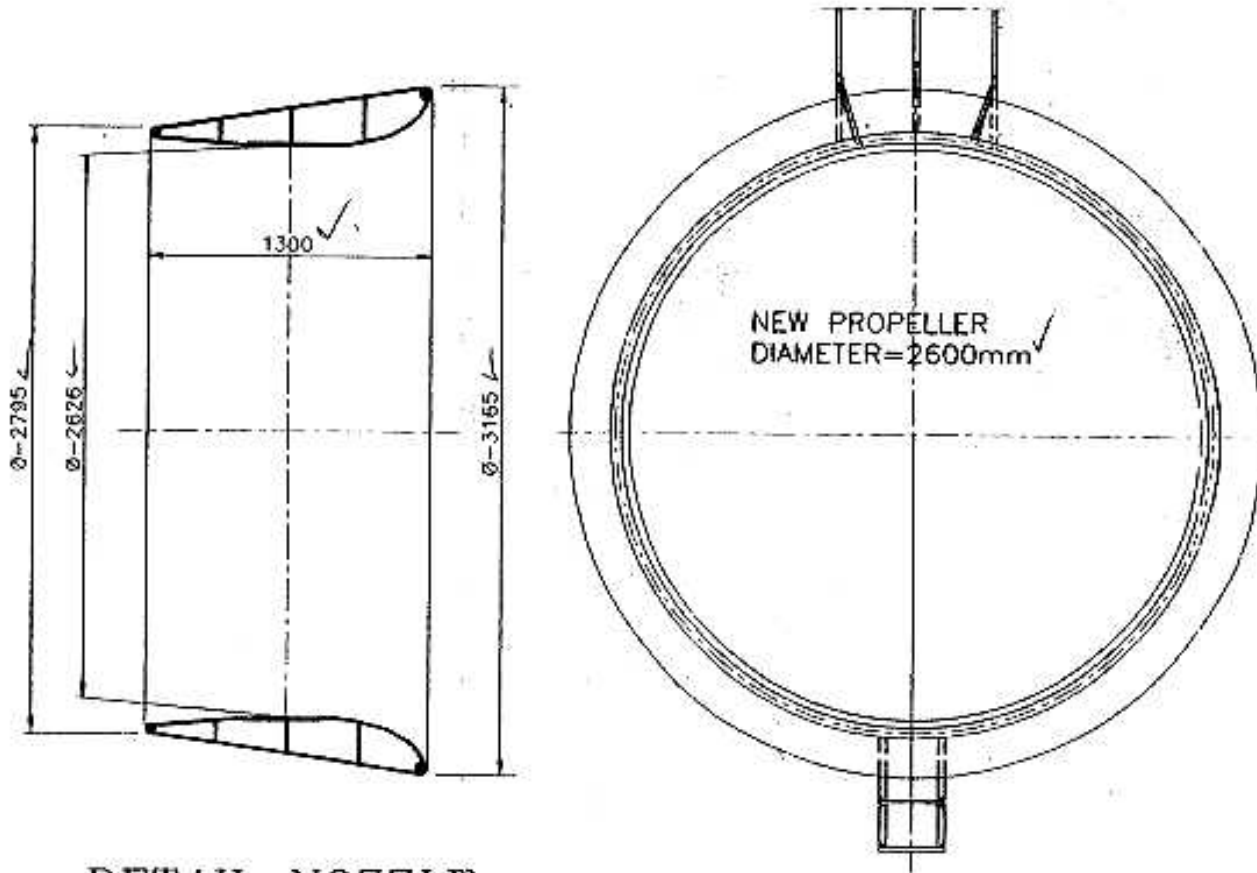
$$\sigma_e = \frac{\sigma}{\alpha^2}$$

**For Kort-nozzle propellers, the inflow is accelerated - which smooths the wake non-uniformities of velocity.**

**This beneficially reduces the  $\alpha$ 's - but, unfortunately, decreases the pressure, hence  $\downarrow$ !**



# A Typical Propeller Nozzle - for Heavily Loaded Props



DETAIL NOZZLE

(Note “airfoil” sections on the ring)

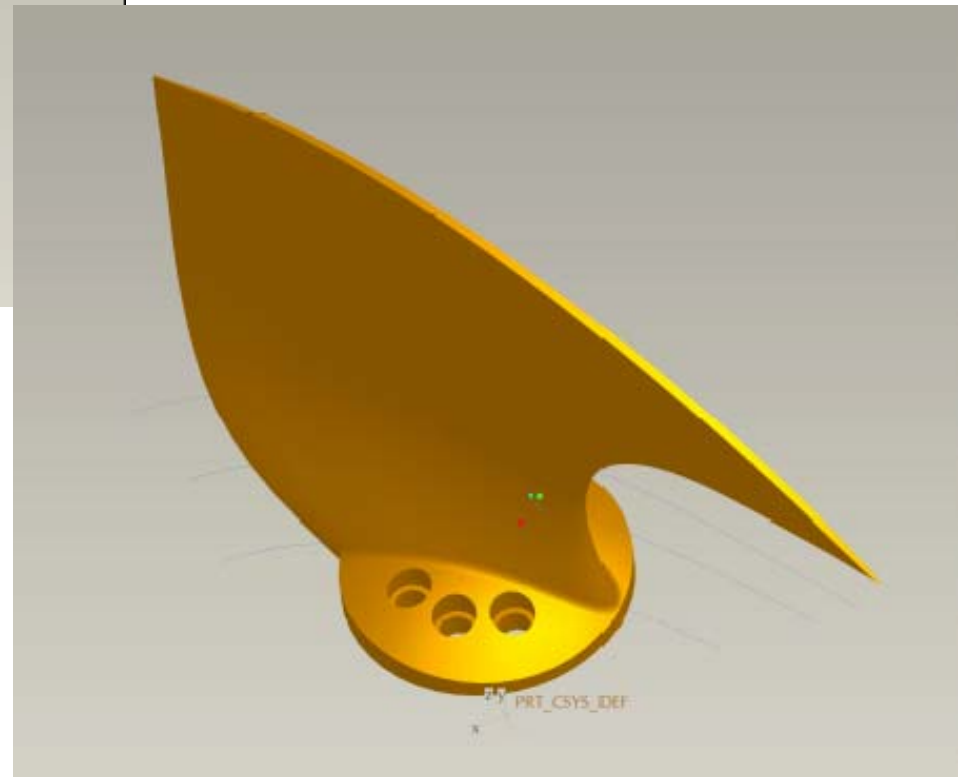
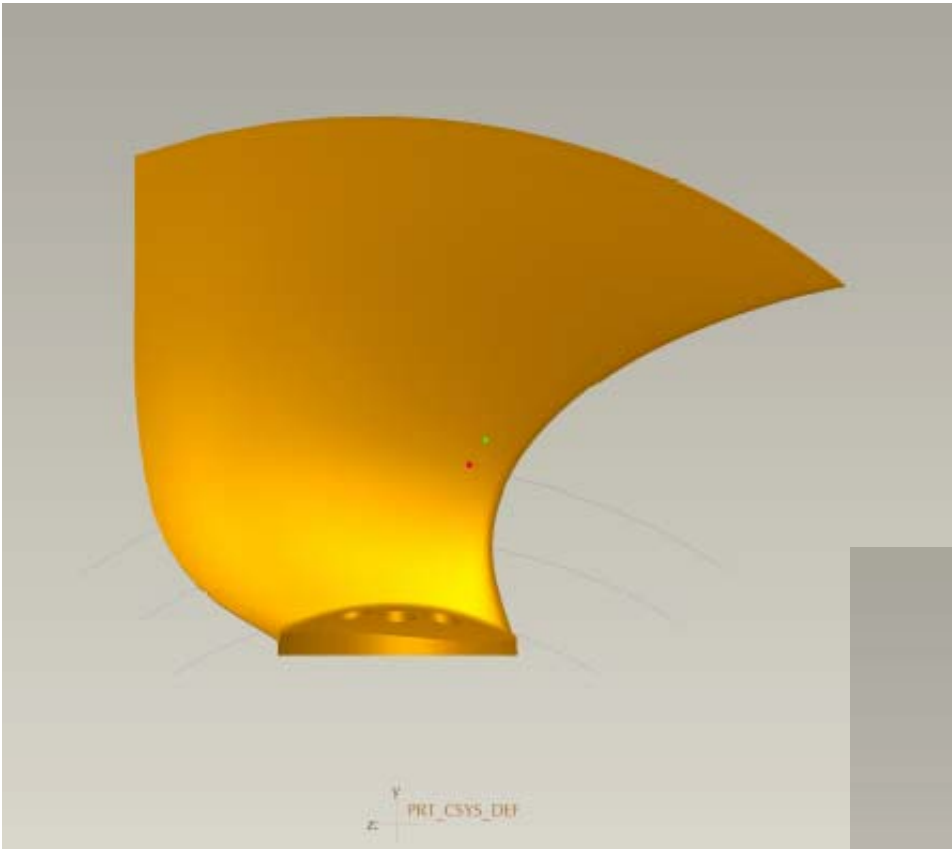
AFT VIEW





**An improved blade design for nozzle propellers is at hand - which promises to delay inception of cavitation and accommodate pitch changes on CRP's**

## The New Forward-Skewed Nozzle-Propeller Blade



**Expected to increase cavitation inception speeds, hence lower cavitation noise levels.**

**(three precedents did it!)**

# Why Twin Screws?

Observation of published data for families of propellers will show that optimum efficiency over a range of pitch-diameter ratios implies relative constancy of  $K_t$ , throughout.

For a given required thrust,  $T$ , then, there is some constancy of the product:  $nD^2$ , or  $(nD)D$ . The first part is proportional to tip speed:  $U_t = \omega nD$ . *So the tip speed is found to be inversely proportional to diameter, roughly.*

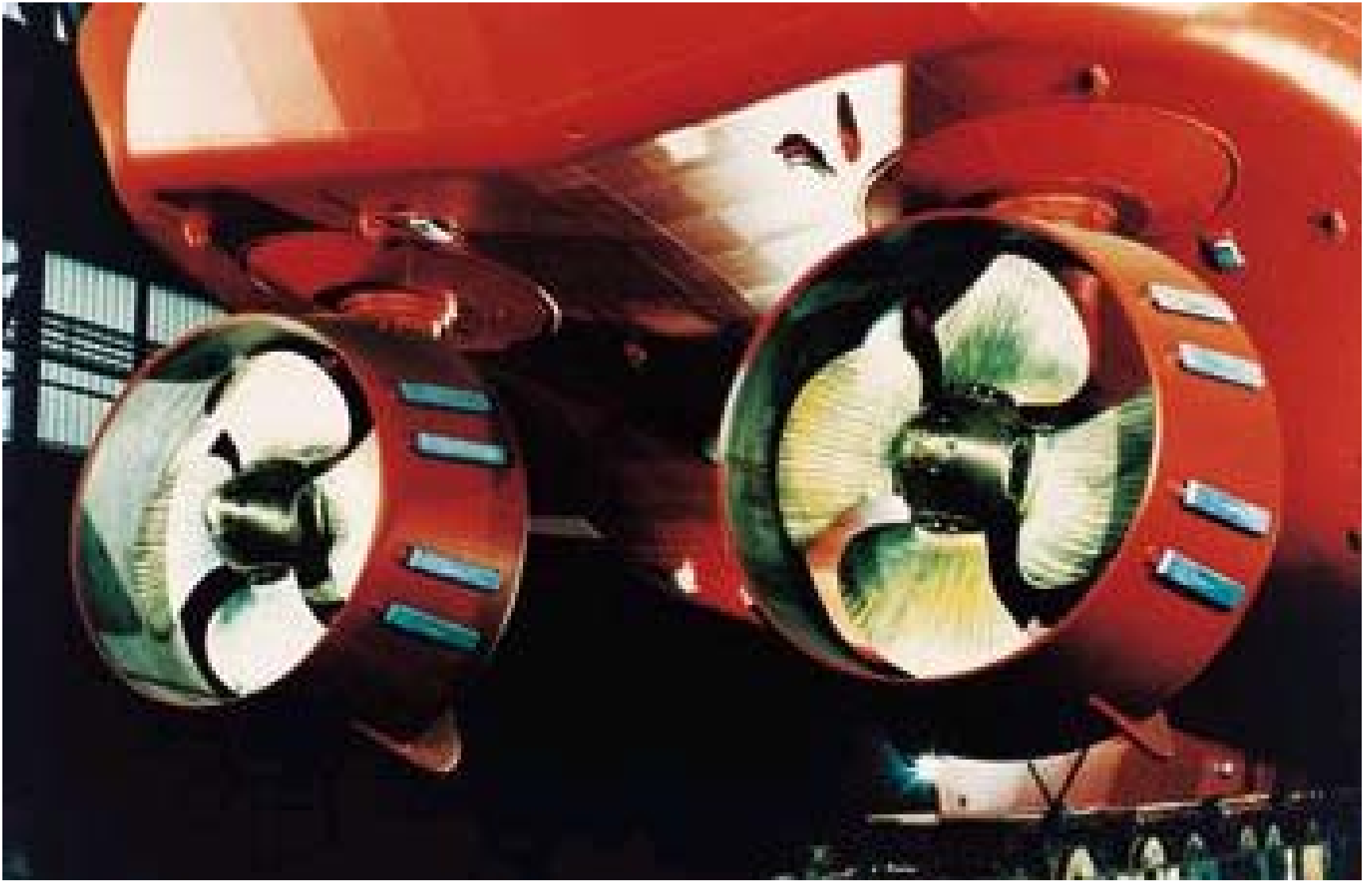
To maintain higher values of the cavitation number - in order to avoid or minimize cavitation - *use large diameter propellers and turn them slowly.*

*Twin screws can do this much more readily than single screws.*

# Twin Screws



**Azipod Trainable “Puller” Props on a Cruise Ship**  
(bow to the left)



**Twin Trainable, Controllable-Pitch, Nozzle Propellers**

# Azipod Concept

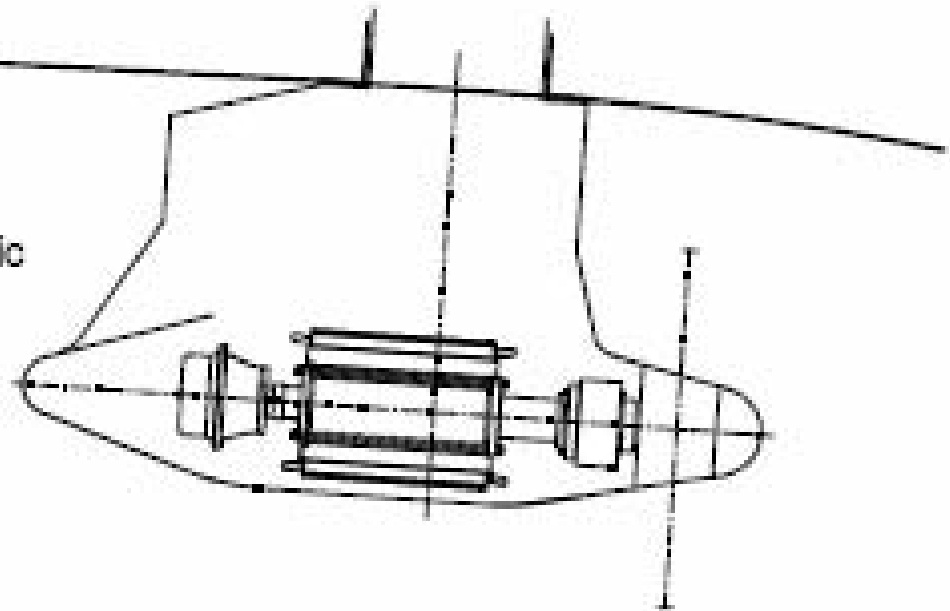
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## Operational Benefits

### Hydrodynamics

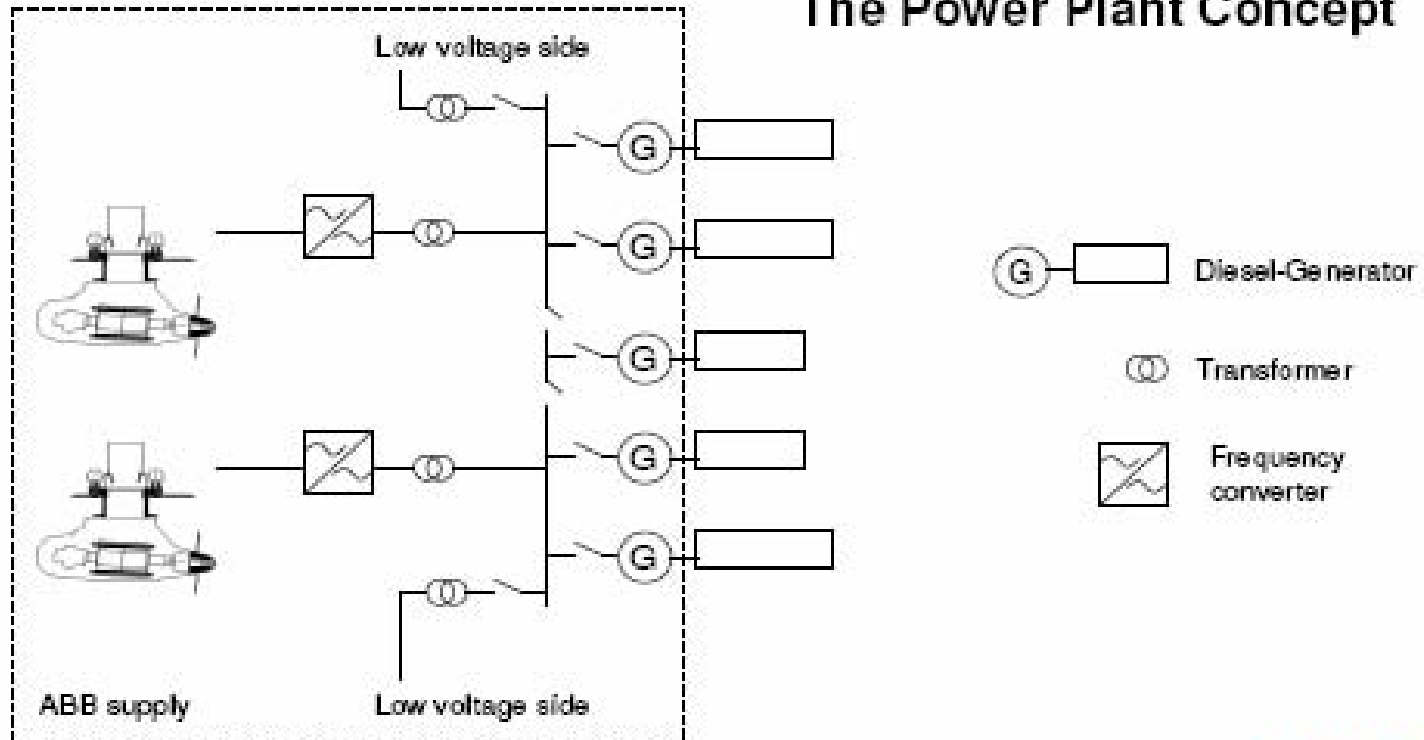
Excellent wake field leads to:

- Improved hydrodynamic efficiency (an 8% improvement was recorded on Elation)
- Less cavitation
- Reduced propeller induced vibrations
- Reduced noise levels

**ABB**

# Diesel-Electric Propulsion

## The Power Plant Concept



# **“Short Seas Shipping”**

**Developing coastal trade to employ fast, highly-powered ships - to replace/augment over-the-road trucking**

**Speeds 24 to 32 kts; powers to 120,000 SHP considered**

**Operate through potentially sensitive areas**

**Expect a future noise threat to MMs**

**BUT**

**Highest-speed ships will employ WaterJet propulsion**

**We have learned how to quiet them**

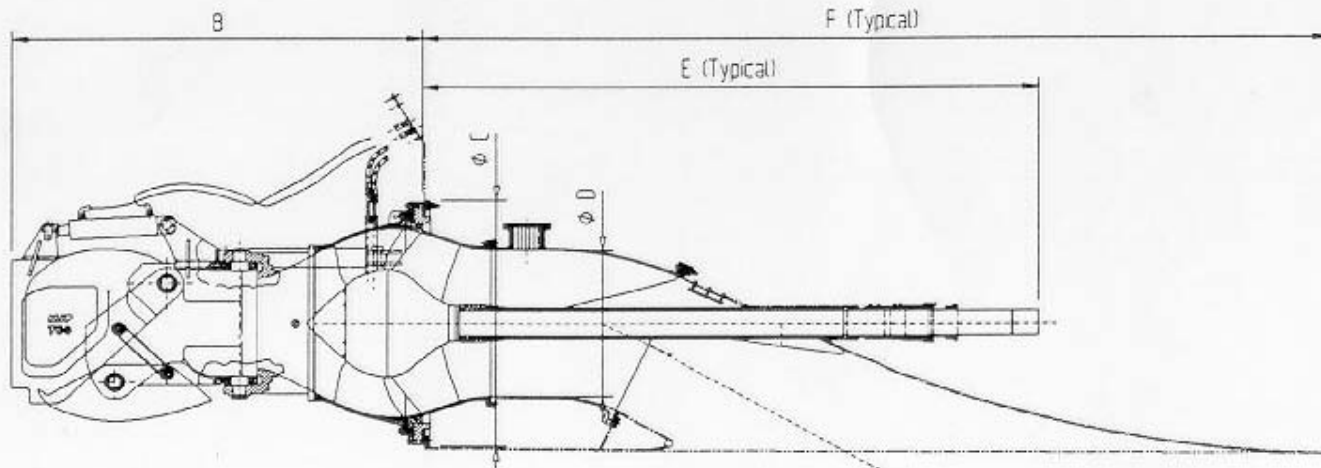


# A Family of WaterJet Propulsors (they're a lot bigger now!)

Size	*Nom kW	Max kW	A	B	Ø C	Ø D	E	F	G	H	Weight per unit kg**	
											Steerable	Booster
500	1200	1800	510	1290	855	500	2050	3400	575	460	815	575
550	1500	2250	560	1412	940	550	2250	3790	630	505	1090	710
650	2100	3150	665	1680	1120	650	2675	4510	750	600	1560	1035
750	2800	4200	765	1900	1255	750	3075	5180	860	690	2105	1460
850	3700	5550	880	2100	1440	850	3540	5890	990	795	3145	2125
950	4900	7350	1010	2460	1610	950	4070	6590	1100	915	4330	3000
1100	6950	9750	1200	2845	1890	1100	4820	7630	1350	1090	6040	4080
1350	9200	13800	1355	3490	2110	1350	5560	9370	1555	1250	8450	5830
1550												
1750												
2050												

\* Above figures are nominal, final data in accordance to technical specification.

\*\* Weight figures incl hydraulics, excl shafting & intake.

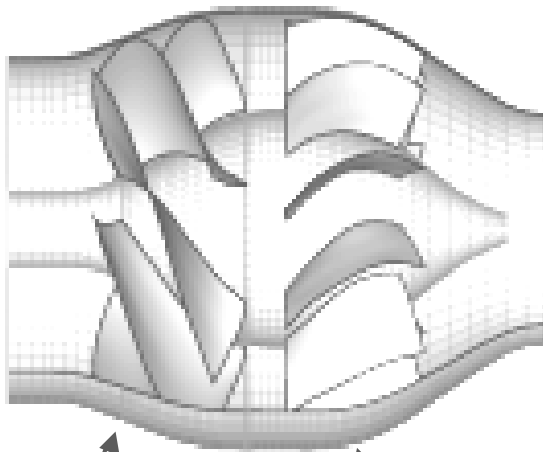


# Conventional Waterjets

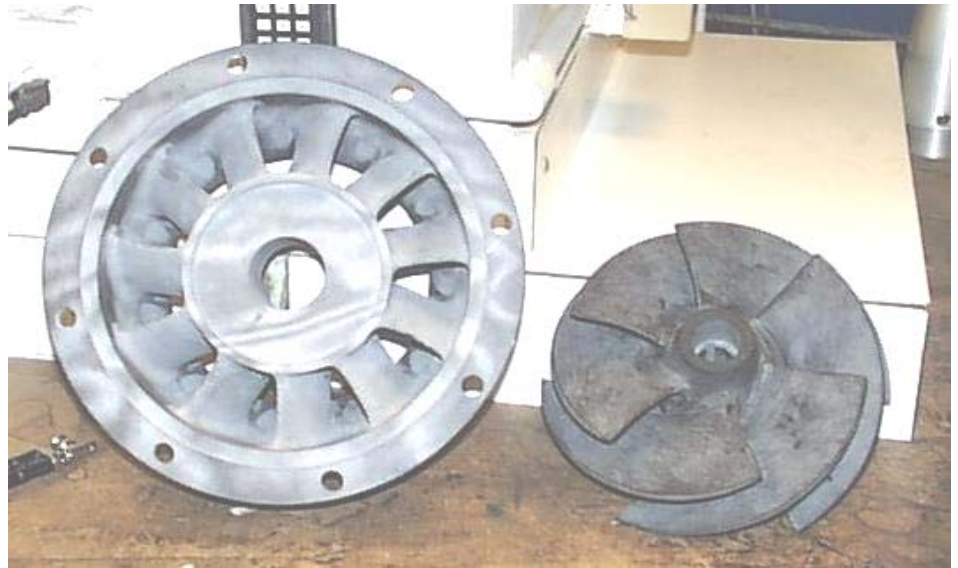
- Dominate market share of Intercoastal transport
- Propulsion of Choice in the 30-45kt range
- Beyond 45 kts, cavitation breakdown leads to excessive unit size
- Water jet efficiency poor at 15kt cruise speeds
- Robust, modular, off the shelf, designs
- Can be difficult to fit inside the hull
- Blading:
  - Typically very large blade area, low aspect ratio
  - Forward rotor with postswirl stator blades



# The Guts of most Waterjets: Mixed Flow Pump

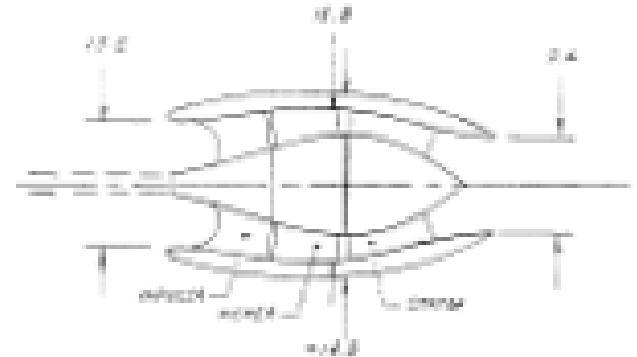


Impeller      Stators



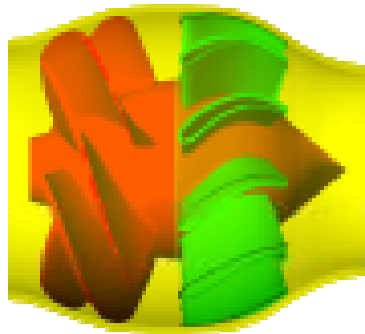
# Conventional Waterjets

- Waterjet efficiency good in low sea states at operational speeds, 40kts
- Water jet efficiency poor at 15kt cruise speeds
- Navy's SES100A w/ waterjets attained 74-78 knot speeds
- Breaking the 45-50 kt Speed Limit
  - Rotor cavitation
  - Inlet, passage, stator cavitation
- ***Breaking the 50 kt Speed Limit requires advanced design features***
  - Large blade area, tandem rotor, Inducer/kicker
  - Careful inlet design
  - Advanced blade shaping, Forward skew



# AWJ-21™ Pump

- Advanced Mixed Flow pump
  - Forward skewed blades
  - Thick blade sections to increase cavitation free speeds
- Propulsor designed with recent MIT lifting surface design tools
  - Not empirically designed (traditional approach)
- Pump flow validated with RANS



Blade surface flow visualization

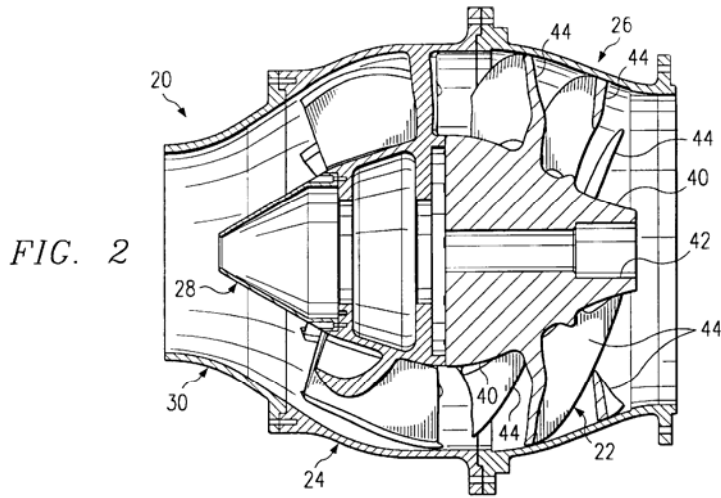


FIG. 2

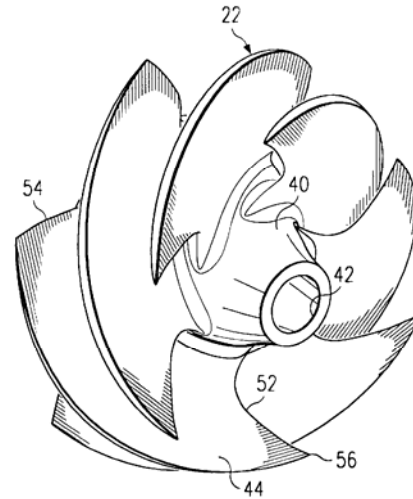


FIG. 4

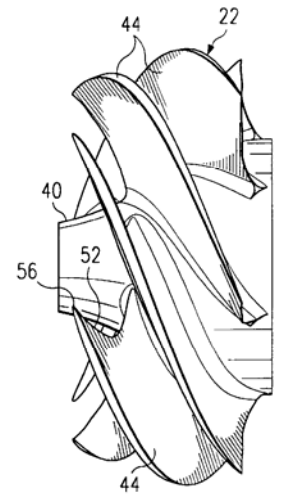


FIG. 6

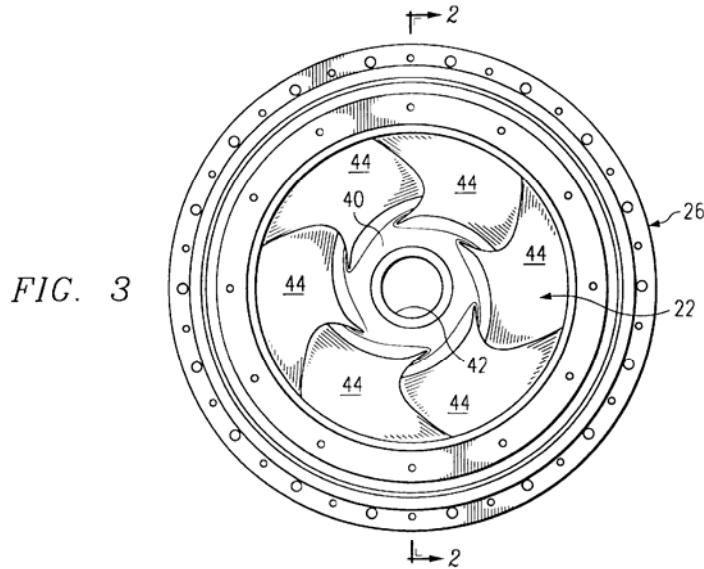


FIG. 3

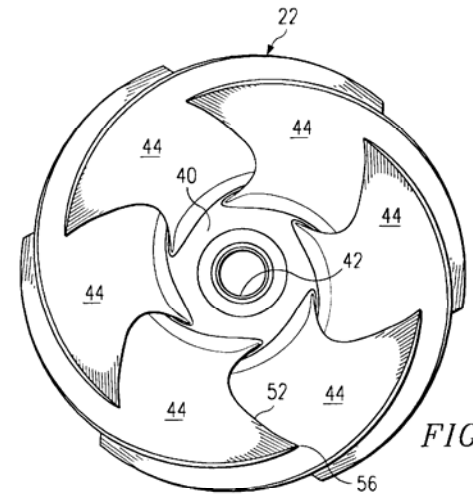


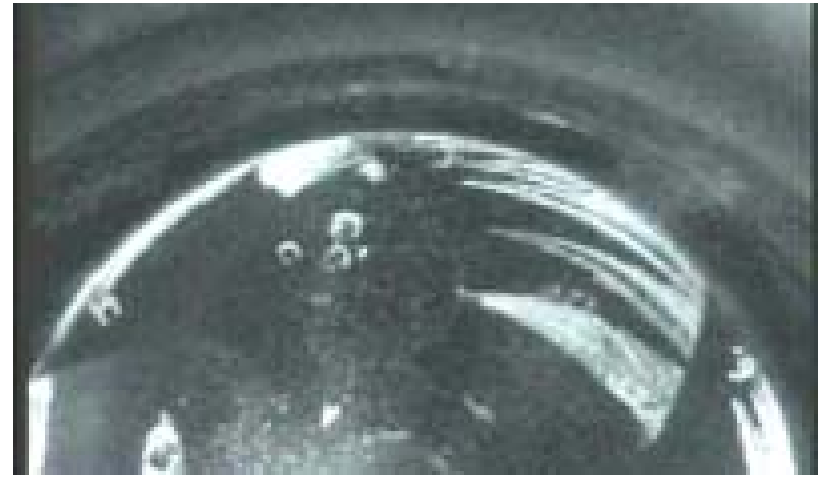
FIG. 5

# Drawings of the Fwd-Skewed Pump Rotor - from the Patent

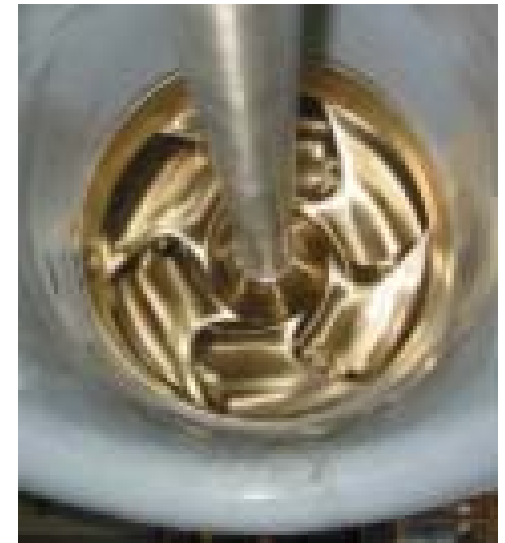
# Advanced Impeller Design - Cavitation Views

Stills from videos

Shaft camera looking at upstream side of blade



- **Observe streak cavitation emanating from blade surface imperfections and traveling bubble cavitation**
- **NO leading edge cavitation observed!**



# Estimation of Propeller Cavitation Radiated Noise

$$L_s = 163 + 10 \text{Log} \left( B D^4 N^3 f^{-2} \right) + 10 \text{Log} \left( A_c / A_d \right)$$

**dB/(1  $\mu$ Pa x m)<sup>2</sup>/Hz.**

in an upper frequency range above a peak frequency,  $f_p$ , defined by:

$$f_p = \frac{28}{D(A_c/A_d)} \sqrt{\frac{10.08}{H_s + 10.08}}$$

where:  $B$  is the total number of propeller blades (10),

$D$  is the propeller diameter in meters (1.4),

$N$  is the revolution rate in RPS,

$f$  is the frequency in Hz.,

$A_c$  is the swept area of cavitation on each blade, in the projected view,

$A_d$  is the projected disc area of a propeller,

$H_s$  is the submergence depth of the shaft in meters (1.97), and

10.08 is the atmospheric pressure head in meters of sea water.

Below the peak frequency, the spectrum level is presumed flat in frequency at the peak-frequency level.

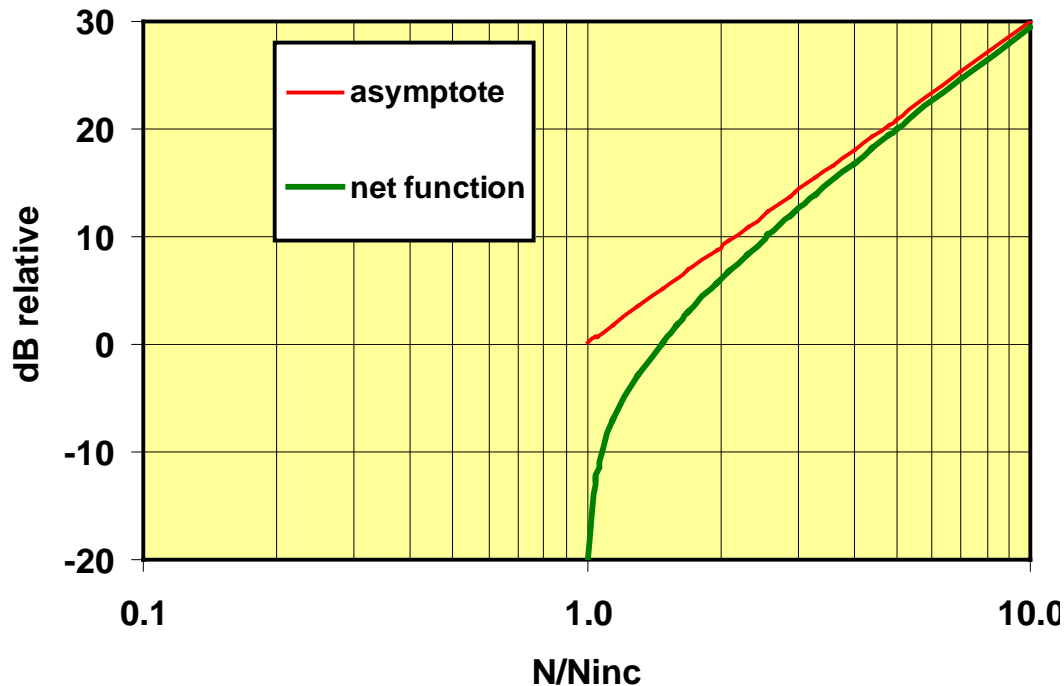


# Radiated Noise Estimation, Continued

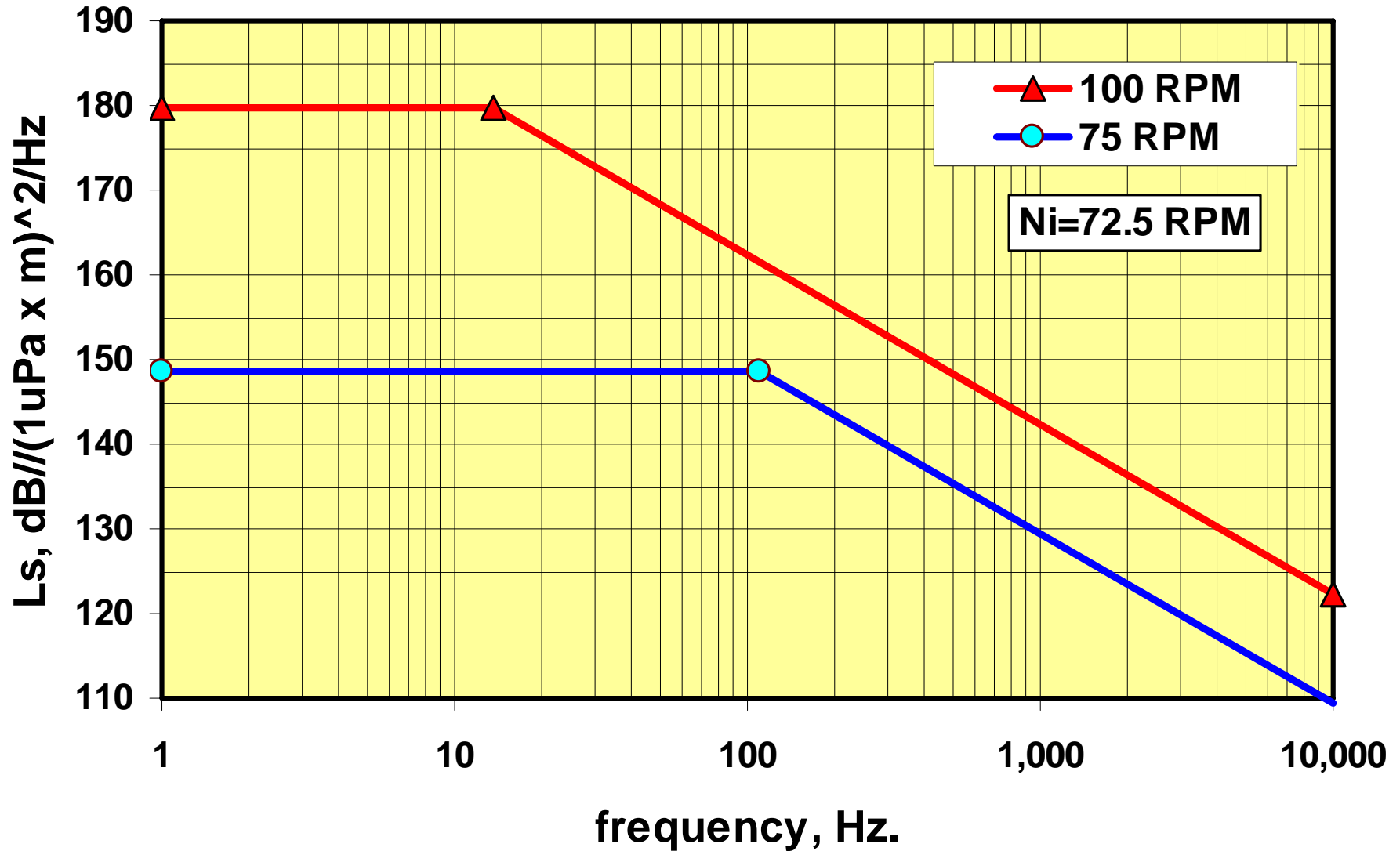
In the absence of any quantitative observed or computed information, the swept area of cavitation,  $A_c$ , is presumed to vary in a simple manner:

$$A_c/A_d = \frac{N/N_i - 1}{N/N_i}$$

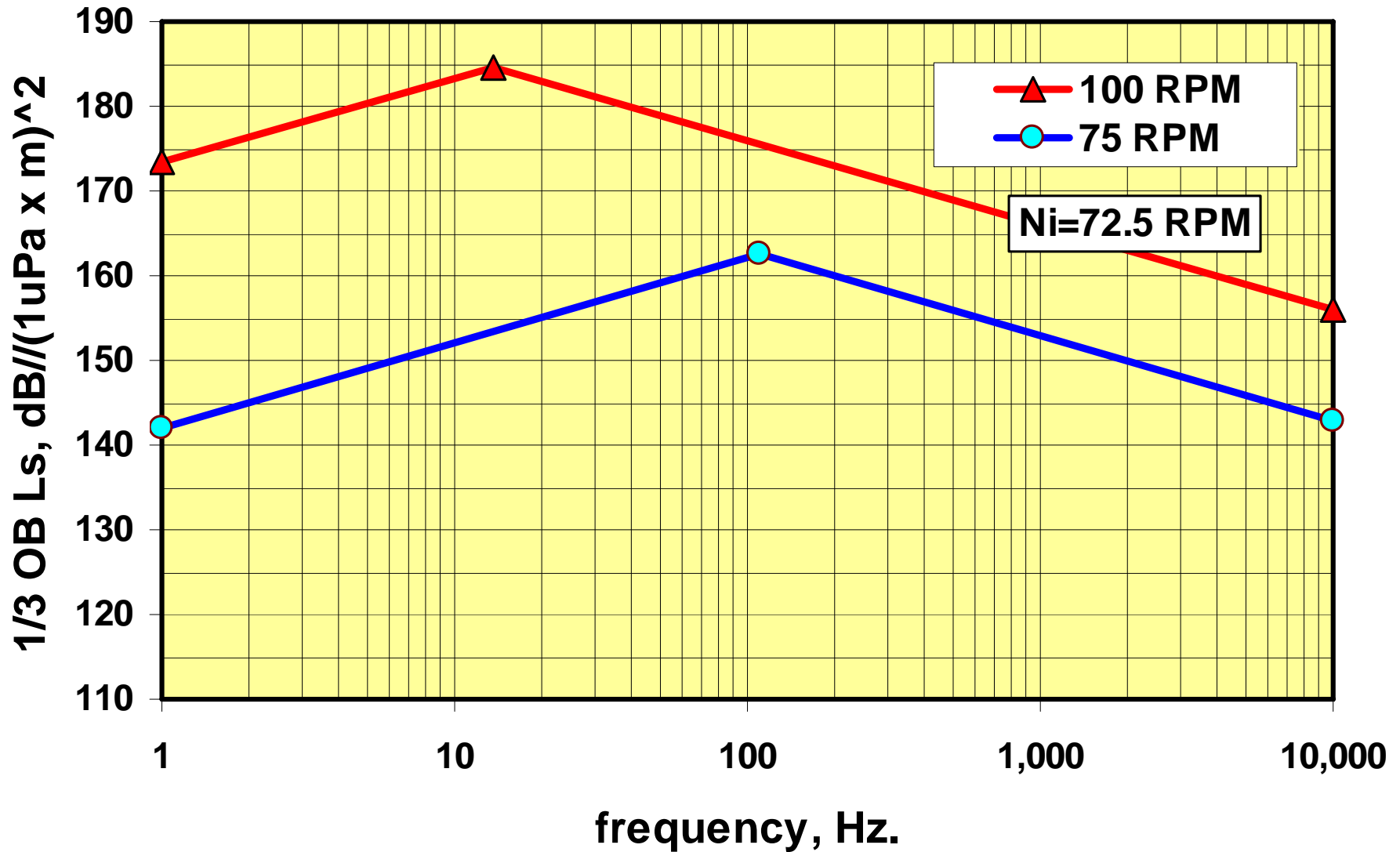
where  $N_i$  is the revolution rate at inception, and which yields a growth of radiated noise level at a fixed (higher) frequency according to the following plot.



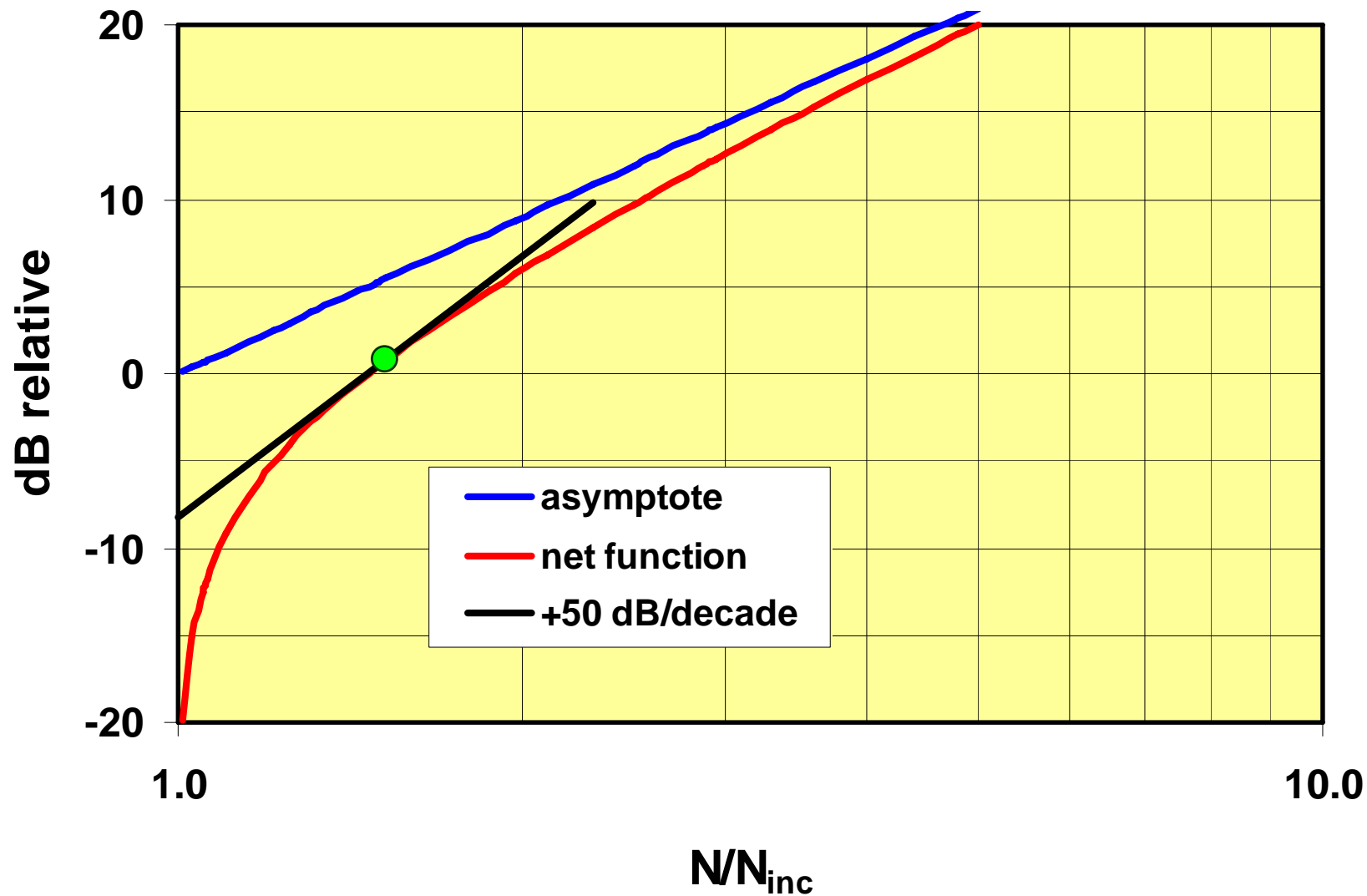
# Propeller Cavitation Radiated Noise Continuous Spectrum Source Levels



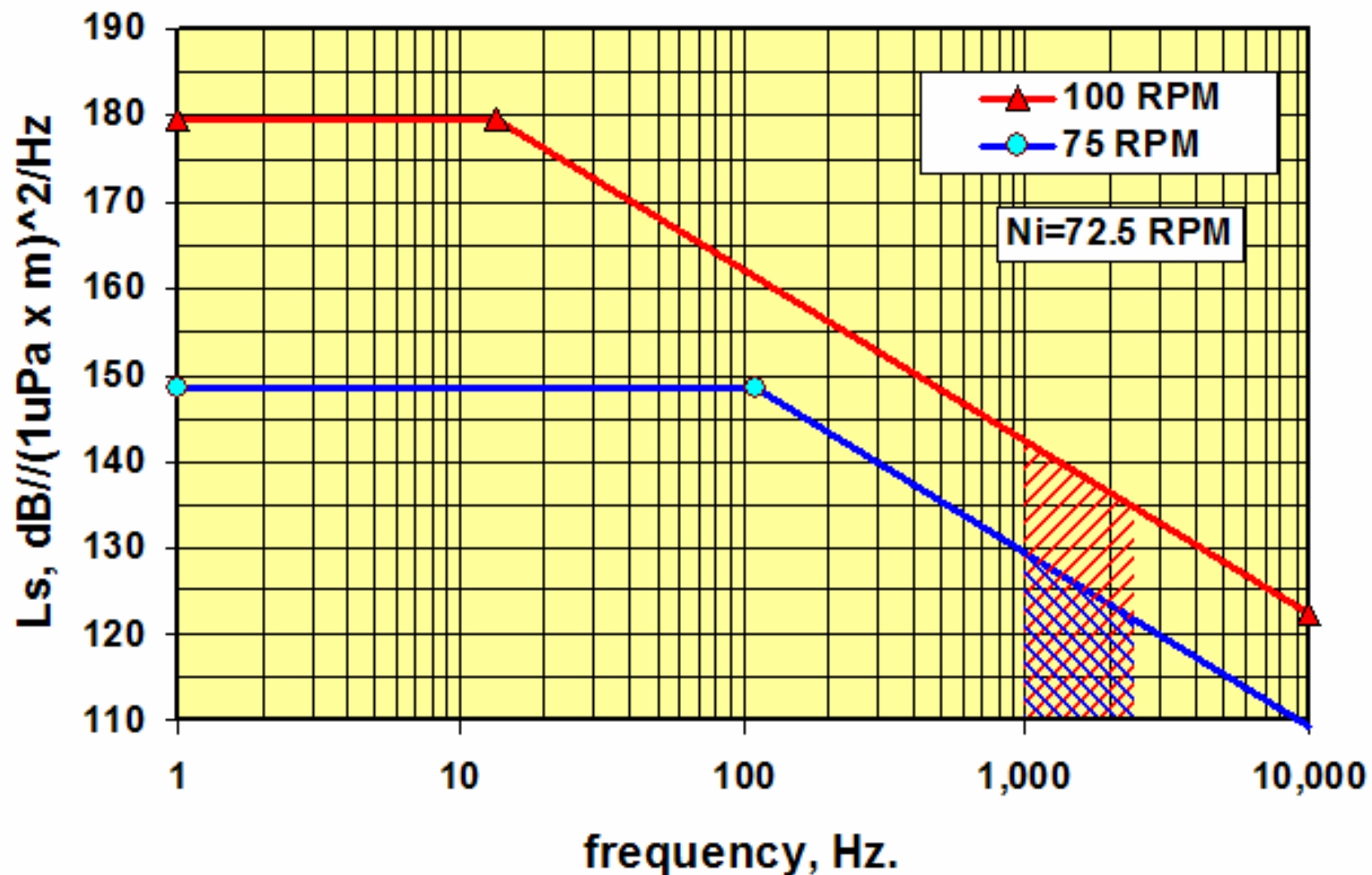
# 1/3 Octave Band Prop Cavitation Radiated Noise Continuous Spectrum Source Levels



# Cavitation Noise Generic Growth (higher frequencies)

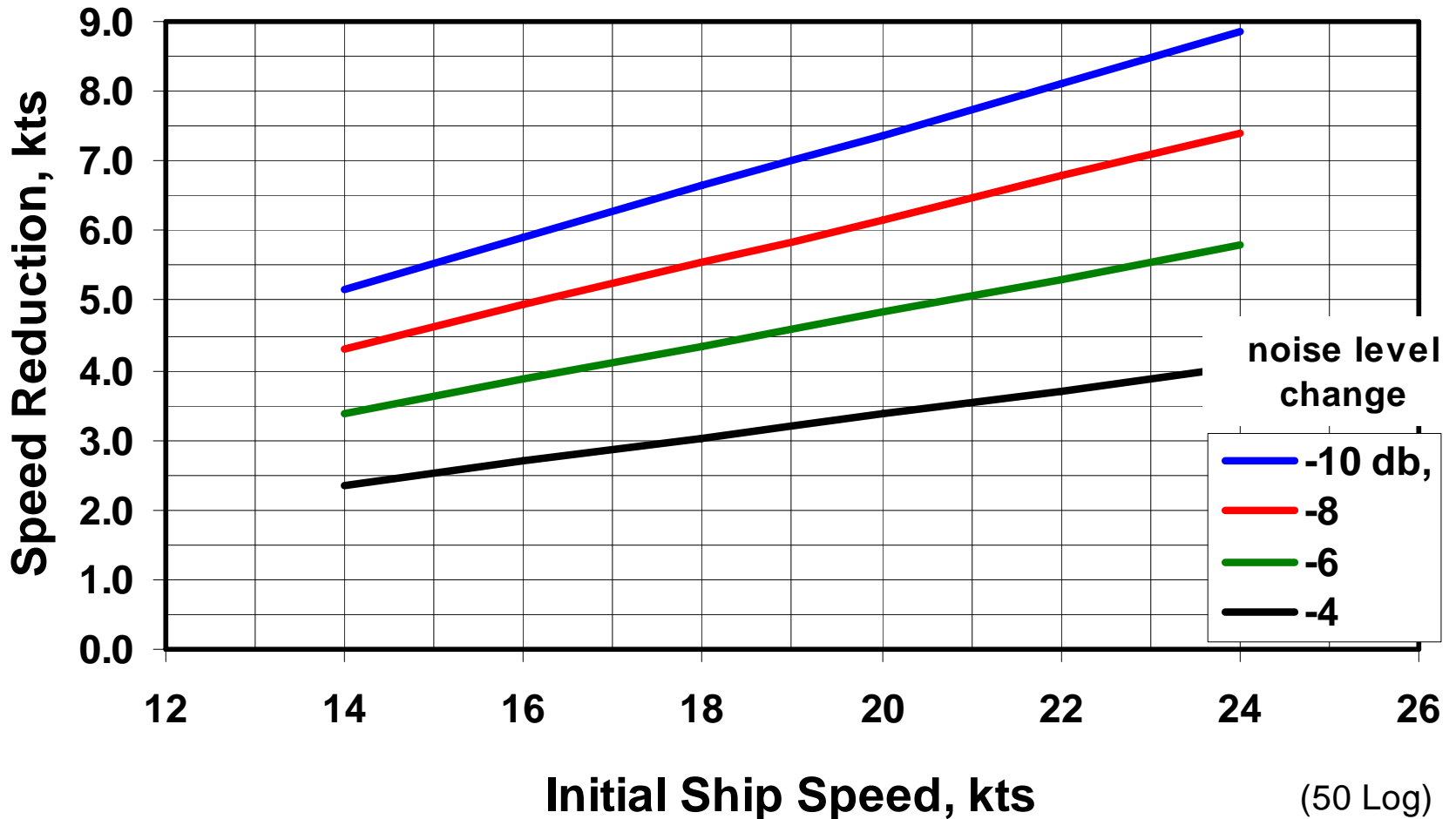


# Propeller Cavitation Radiated Noise Continuous Spectrum Source Levels

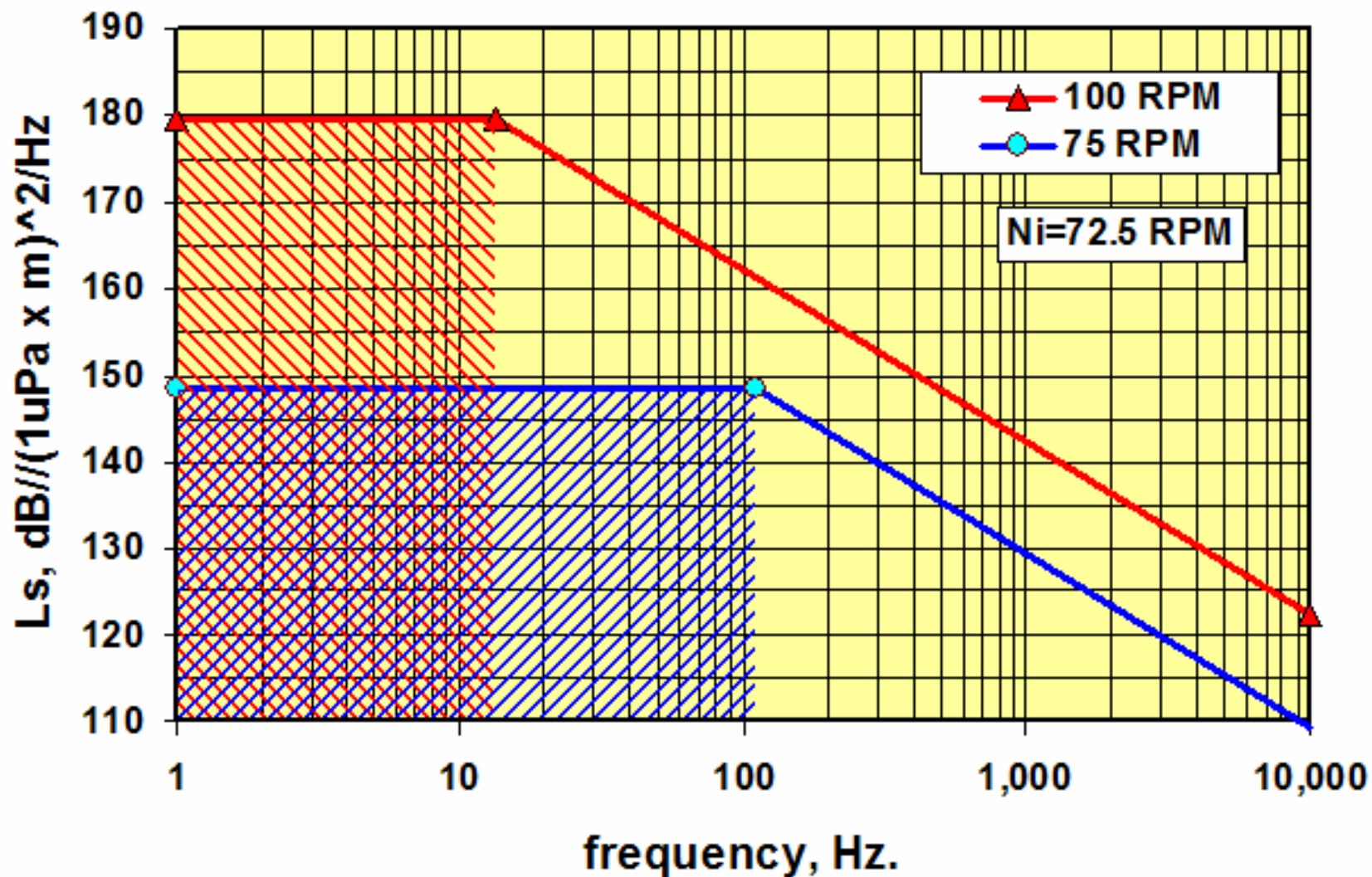


# Speed Reductions Required for High Freq Radiated Noise Reductions

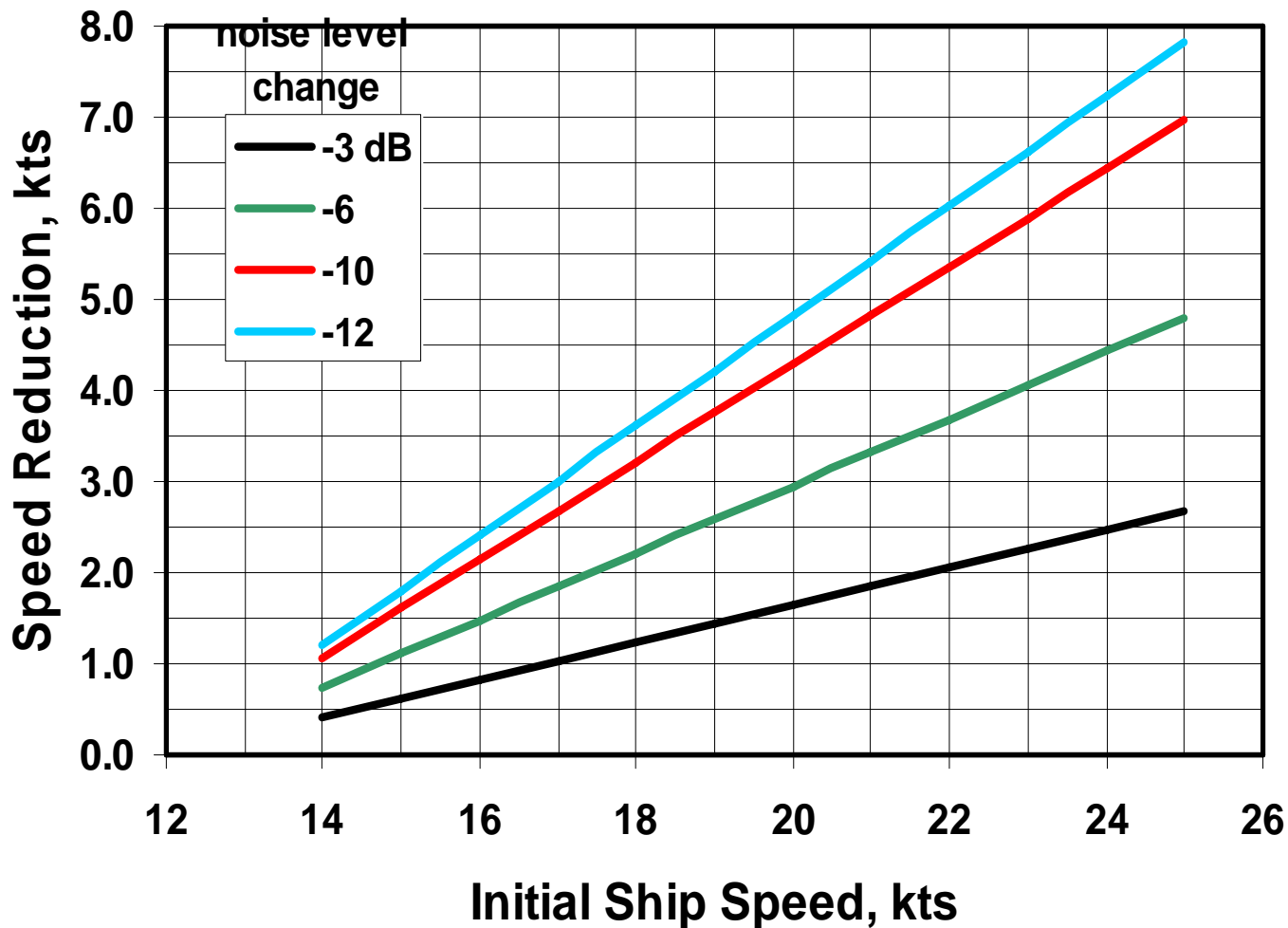
(Cavitation partially developed)



# Propeller Cavitation Radiated Noise Continuous Spectrum Source Levels



# Speed Reductions Required for Low Freq BroadBand Rad Noise Reductions, 12 kts Cav'n Inception





# Cost

**The cost of noise reduction by temporary vessel slowing is easily estimated.**

**The increased voyage time represents lost revenue.**

**The shipping company must be compensated for that loss.**

**Non-compliance must be similarly penalized.**

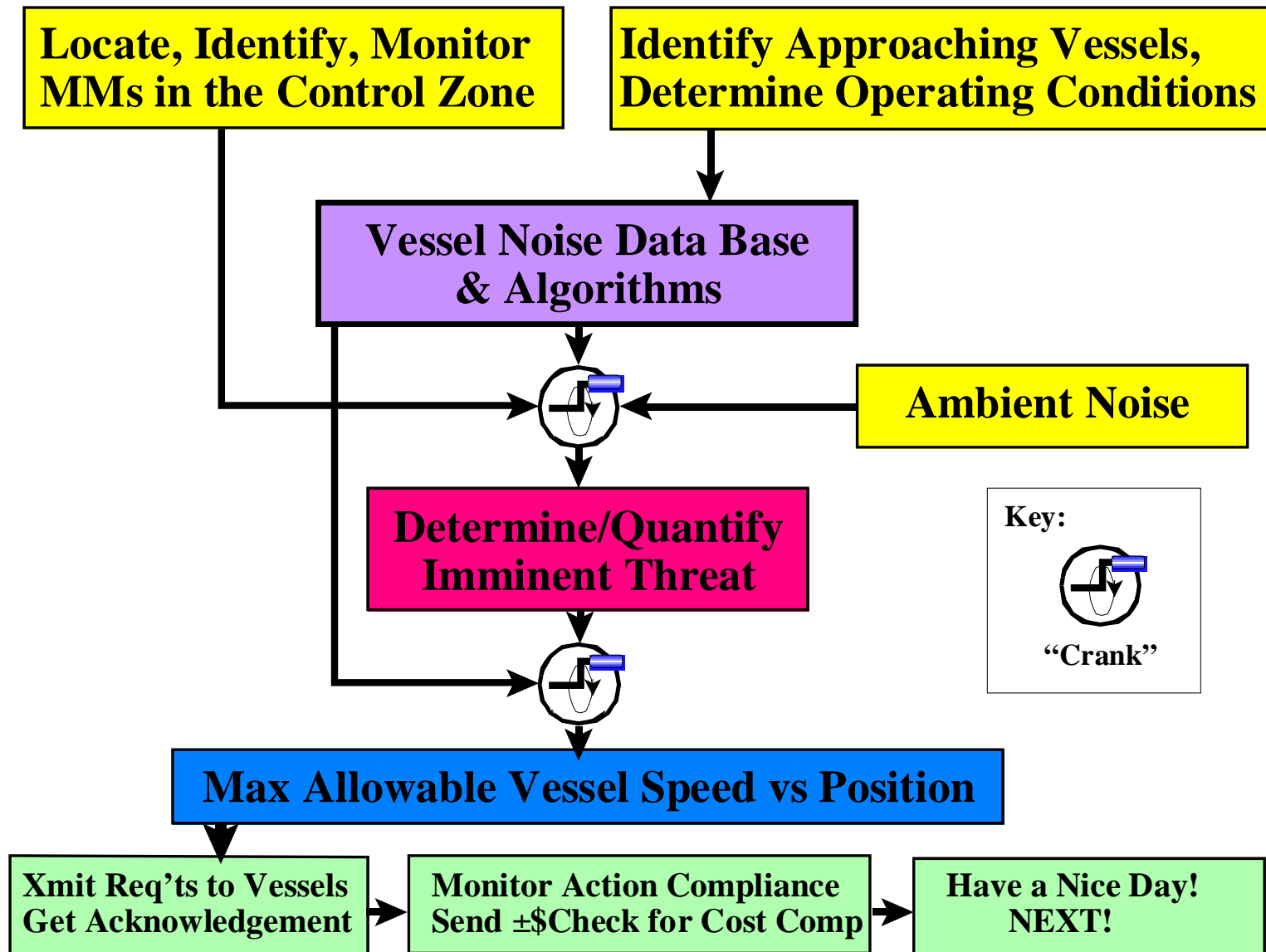
## **Suggestion:**

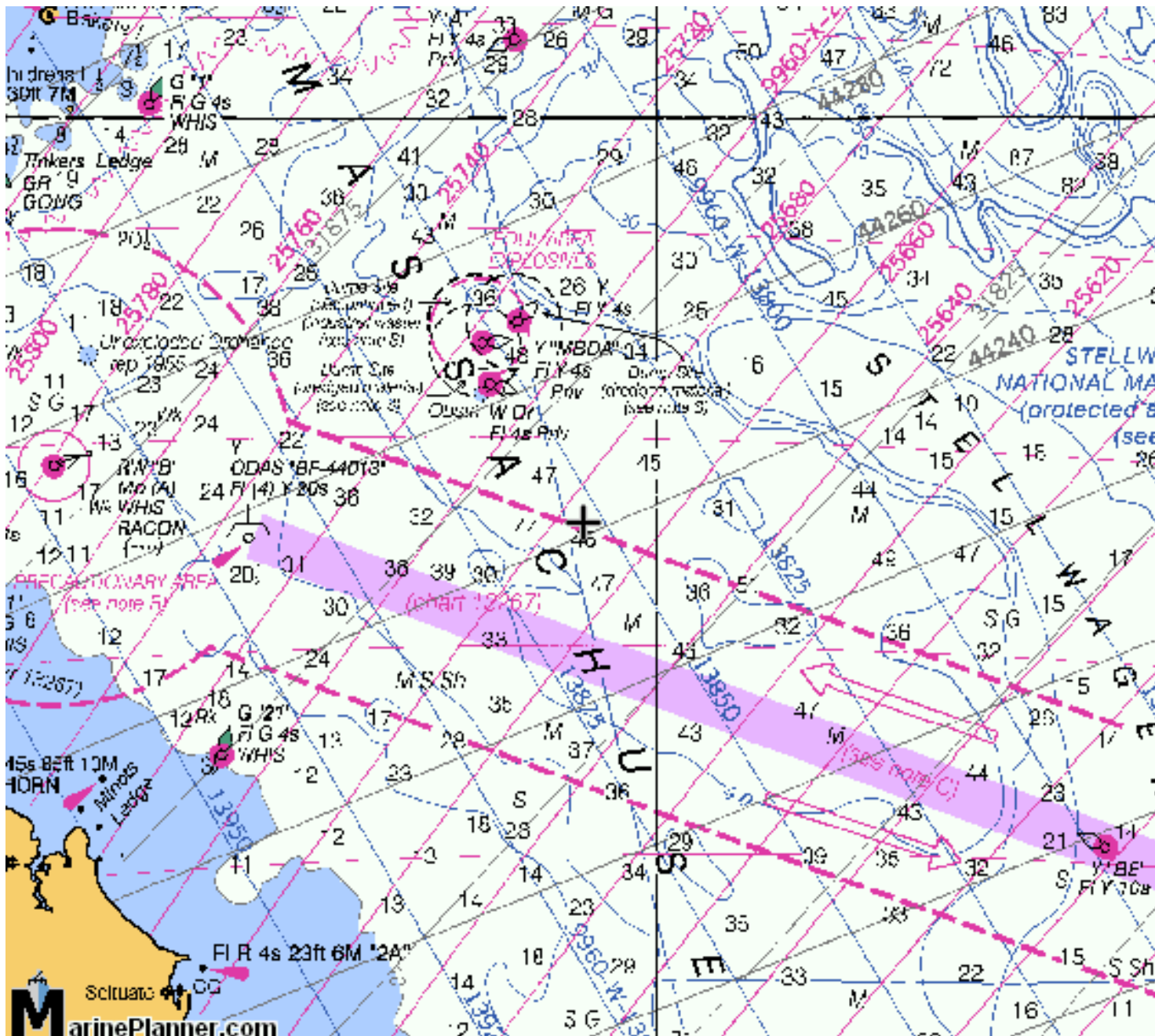
**Let us begin the protection of noise-threatened MMs by doing what we know how to do in places that are important and accessible - in a manner that encourages compliance, rather than penalizing it.**

**Namely:**

- Choose control zones around established, near-shore shipping lanes in sensitive areas**
- Demand local, temporary speed reductions tailored to the immediate situation**
- Compensate the cost of compliance & equally penalize for non-compliance**

# Noise Control in Marine Corridors Abutting/Traversing MM-Noise-Sensitive Regions

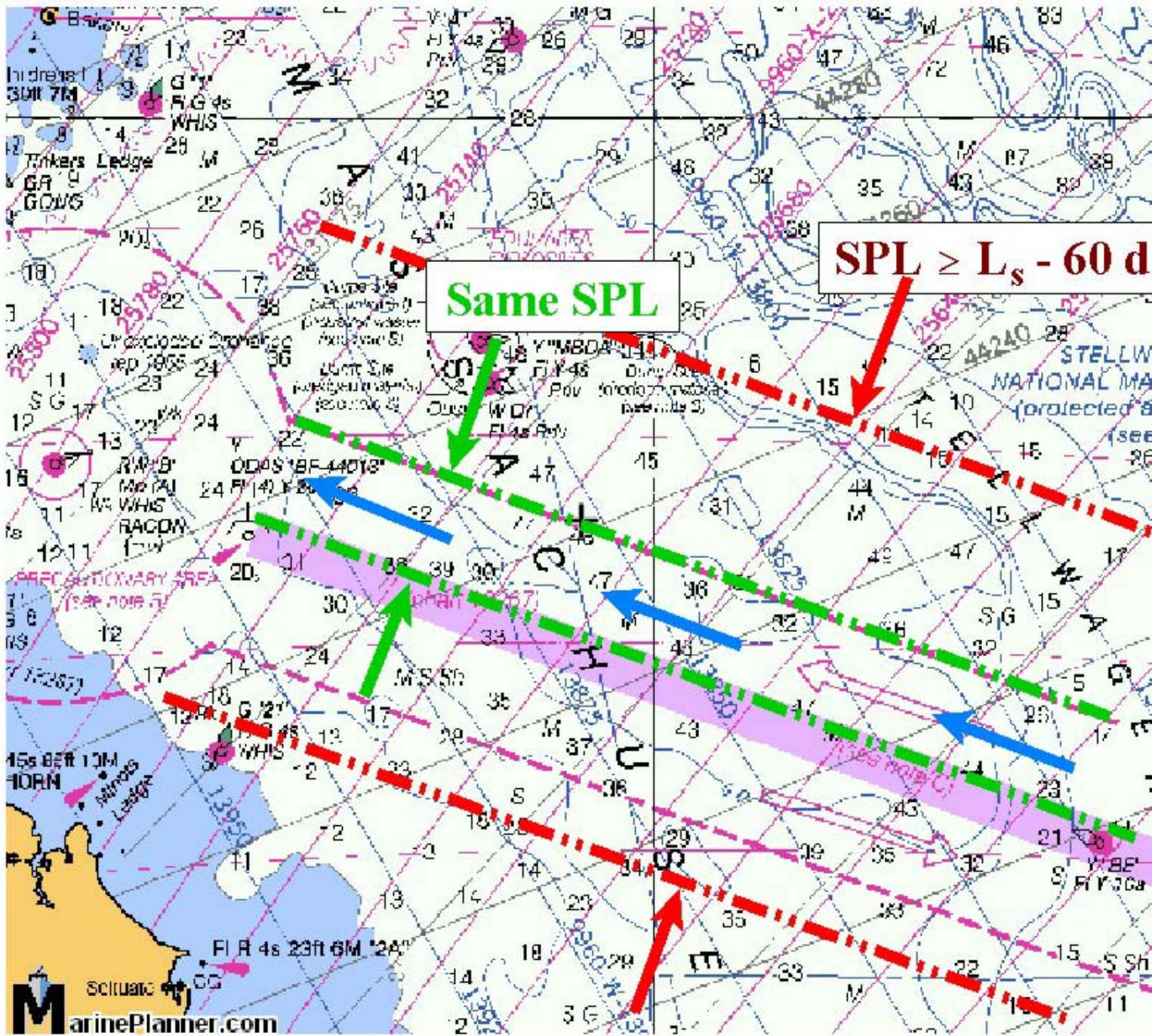




The marine traffic corridors in-bound and out-bound Boston, in Mass. Bay.

They are each 2 NM wide, separated by a 1 NM clearance.

Note location of Stellwagen Bank - a protected area.



What a 10dB noise reduction will buy in affected area.

A 5 NM radius is reduced to 1 NM for noiselevels above the source -60.

(R-1.5 propagation assumed)

-70dB, 20NM  
-75dB, 50NM



## **Re: Machinery Noise**

**An external treatment to de-couple the hull from the water is available in the form of an air-bubble blanket.**

**The effectiveness increases with frequency above a low-frequency “resonance” set by the thickness of an equivalent “solid” air layer.**

**An air emission system is provided by the Danish firm Odegaard to block propeller noise from entering the hull on cruise ships.**

**Estimate 5-600 HP compressors on 20 kt ship.**