

APPENDIX A – Model and data assumptions for the candidate set of multinomial logit models.

For a large population, let π_0 , π_1 , and π_2 correspond to the proportion of population units that have responses of 0, 1, and 2, respectively. If a sample of size n is obtained by independently sampling units from this large population, then the sampled frequencies f_0 , f_1 , and f_2 of response categories 0, 1, and 2, respectively, follow a multinomial distribution with expected frequencies $F_0 = n\pi_0$, $F_1 = n\pi_1$, and $F_2 = n\pi_2$.

For each species monitored during our study, the population consisted of all winter OSV human/wildlife encounters with that species along established roads used by snowmobiles and coaches. The sampling unit was an encounter with a wildlife group, not an encounter with individual animals. Across the four winter seasons (2003-2006), the size of these encounter populations were large for bison, elk, and trumpeter swans. Though the number of bald eagle and coyote observations did not appear large, it was the number of actual encounters that formed the populations (both observed and unobserved). Thus, we can reasonably assume the populations for these species are also large.

Ideally, the collected sample should be random, but this was not the case during our study for two reasons. First, we did not know when or where human/wildlife encounters would occur. Hence, we had no control to randomly select which encounters would be observed. Second, the established roads used by snowmobiles and coaches were stratified into road segments that were repeatedly sampled across the winter. The effects of this deviation from strict random sampling (which often is infeasible in wildlife studies) should be negligible given similar effort in sampling each road segment within a winter season. That is, given equal sampling effort in each road segment across time, we expect the observed numbers and types of human/wildlife encounters in each segment to be close to the numbers and types of encounters that would be expected under with true random sampling during the winter.

Hypothetically, a predetermined sample of size n should be collected. However, our sample sizes were random rather than predetermined. Like other statistical procedures where a fixed sample size is assumed but not obtained, the fact that it is random should not seriously affect our conclusions.

APPENDIX B – The *a priori* candidate set of multinomial logit models. Abbreviations are: *year* (year of study); *dist* (distance of group from road); *sppnum* (group size); *onroad* (on or off road); *hact* (human activity); *intxn* (interaction time); *sb* (number of snowmobiles); *coach* (number of coaches); *hab* (habitat), and *cumvis* (cumulative daily number of over-snow vehicles).

Bison and Elk (86 models): Each *a priori* model contains the base model, *year + sppnum + dist + hact + intxn + onroad + sb + coach + sppnum*dist*, plus the effects indicated by X in the table.

ID	hab	cumvis	dist*hact	sppnum*hact	intxn*dist	intxn*sppnum	sppnum*hab	year*cumvis
A	X	X	X	X	X	X	X	X
B	X	X	X	X	X	X		X
C	X	X	X	X	X	X	X	
D	X	X	X	X	X	X		
E		X	X	X	X	X		X
F		X	X	X	X	X		
G	X		X	X	X	X	X	
H	X		X	X	X	X		
I			X	X	X	X		
1A1	X	X		X	X	X	X	X
1A2	X	X	X		X	X	X	X
1A3	X	X	X	X		X	X	X
1A4	X	X	X	X	X		X	X
1B1	X	X		X	X	X		X
1B2	X	X	X		X	X		X
1B3	X	X	X	X		X		X
1B4	X	X	X	X	X			X
1C1	X	X		X	X	X	X	
1C2	X	X	X		X	X	X	
1C3	X	X	X	X		X	X	
1C4	X	X	X	X	X		X	
1D1	X	X		X	X	X		
1D2	X	X	X		X	X		
1D3	X	X	X	X		X		
1D4	X	X	X	X	X			
1E1		X		X	X	X		X
1E2		X	X		X	X		X
1E3		X	X	X		X		X

ID	hab	cumvis	dist*hact	sppnum*hact	intxn*dist	intxn*sppnum	sppnum*hab	year*cumvis
1E4		X	X	X	X			X
1F1		X		X	X	X		
1F2		X	X		X	X		
1F3		X	X	X		X		
1F4		X	X	X	X			
1G1	X			X	X	X	X	
1G2	X		X		X	X	X	
1G3	X		X	X		X	X	
1G4	X		X	X	X		X	
2A1	X	X			X	X	X	X
2A2	X	X		X		X	X	X
2A3	X	X		X	X		X	X
2A4	X	X	X			X	X	X
2A5	X	X	X		X		X	X
2B1	X	X			X	X		X
2B2	X	X		X		X		X
2B3	X	X		X	X			X
2B4	X	X	X			X		X
2B5	X	X	X		X			X
2C1	X	X			X	X	X	
2C2	X	X		X		X	X	
2C3	X	X		X	X		X	
2C4	X	X	X			X	X	
2C5	X	X	X		X		X	
2D1	X	X			X	X		
2D2	X	X		X		X		
2D3	X	X		X	X			
2D4	X	X	X			X		
2D5	X	X	X		X			
2E1		X			X	X		X
2E2		X		X		X		X
2E3		X		X	X			X
2E4		X	X			X		X
2E5		X	X		X			X
2F1		X			X	X		

ID	<i>hab</i>	<i>cumvis</i>	<i>dist*hact</i>	<i>sppnum*hact</i>	<i>intxn*dist</i>	<i>intxn*sppnum</i>	<i>sppnum*hab</i>	<i>year*cumvis</i>
2F2		X		X		X		
2F3		X		X	X			
2F4		X	X			X		
2F5		X	X		X			
2G1	X	X			X	X	X	
2G2	X	X		X		X	X	
2G3	X	X		X	X		X	
2G4	X	X	X			X	X	
2G5	X	X	X		X		X	
3A1	X	X				X	X	X
3A2	X	X			X		X	X
3B1	X	X				X		X
3B2	X	X			X			X
3C1	X	X				X	X	
3C2	X	X			X		X	
3D1	X	X				X		
3D2	X	X			X			
3E1		X				X		X
3E2		X			X			X
3F1		X				X		
3F2		X			X			
3G1	X					X	X	
3G2	X				X		X	

Trumpeter Swans (36 models): Each *a priori* model contains the base model, *year + sppnum + dist + hact + intxn + sb + coach + sppnum*dist*, plus the effects indicated by X in the table.

ID	<i>cumvis</i>	<i>dist*hact</i>	<i>sppnum*hact</i>	<i>intxn*dist</i>	<i>intxn*sppnum</i>	<i>year*cumvis</i>
A	X	X	X	X	X	X
B	X	X	X	X	X	
C		X	X	X	X	
1A1	X		X	X	X	X
1A2	X	X		X	X	X
1A3	X	X	X		X	X
1A4	X	X	X	X		X

ID	<i>cumvis</i>	<i>dist*hact</i>	<i>sppnum*hact</i>	<i>intxn*dist</i>	<i>intxn*sppnum</i>	<i>year*cumvis</i>
1B1	X		X	X	X	
1B2	X	X		X	X	
1B3	X	X	X		X	
1B4	X	X	X	X		
1C1			X	X	X	
1C2		X		X	X	
1C3		X	X		X	
1C4		X	X	X		
2A1	X			X	X	X
2A2	X		X		X	X
2A3	X		X	X		X
2A4	X	X			X	X
2A5	X	X		X		X
2B1	X			X	X	
2B2	X		X		X	
2B3	X		X	X		
2B4	X	X			X	
2B5	X	X		X		
2C1				X	X	
2C2			X		X	
2C3			X	X		
2C4		X			X	
2C5		X		X		
3A1	X				X	X
3A2	X			X		X
3B1	X				X	
3B2	X			X		
3C1					X	
3C2				X		

Bald Eagles (12 models): Each *a priori* model contains the base model, *year + sppnum + dist + hact + intxn + sb + coach*, plus the effects indicated by X in the table.

ID	<i>cumvis</i>	<i>intxn*dist</i>	<i>year*cumvis</i>	<i>hab</i>
A	X	X	X	X
B	X	X	X	
C	X	X		X
D	X	X		
E		X		X
F		X		
1A	X		X	X
1B	X		X	
1C	X			X
1D	X			
1E				X
1F				

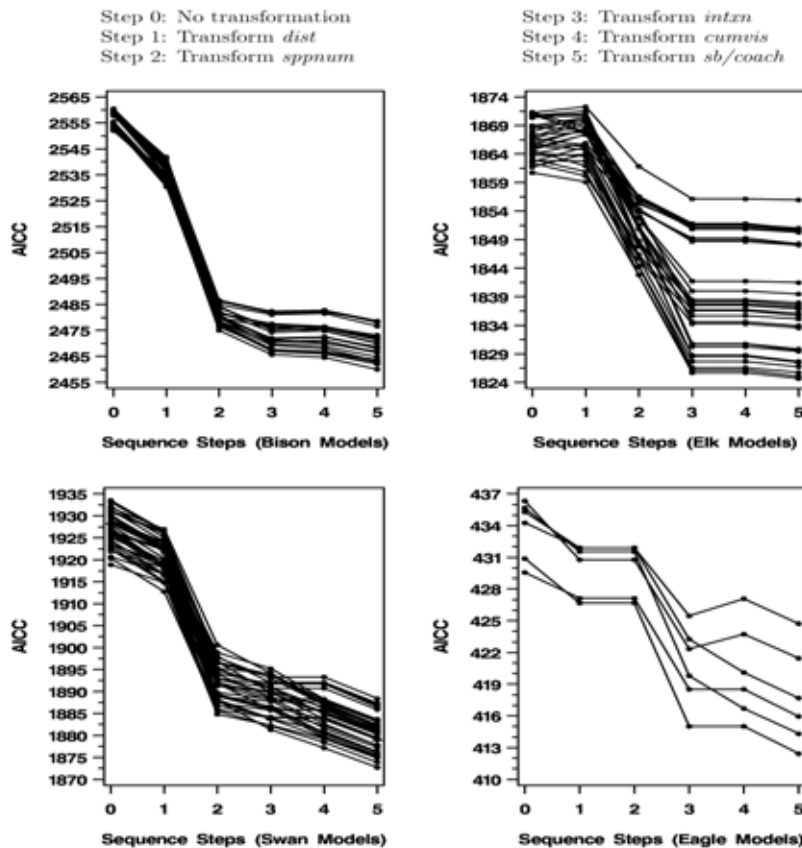
Coyotes (6 models): Each *a priori* model contains the base model, *year + sppnum + dist + hact + intxn + sb + coach*, plus the effects indicated by X in the table.

ID	<i>cumvis</i>	<i>intxn*dist</i>	<i>year*cumvis</i>
A	X	X	X
B	X	X	
C		X	
1A	X		X
1B			X
1C			

APPENDIX C – Results of the sequential approach for evaluating various forms of the quantitative covariates.

We graphically summarized the AIC_C values for the best models at each step in the sequential process determining the best covariate forms for bison, elk, swans, and eagles (Figure 1). A change in covariate form can cause dramatic changes in AIC_C . For bison, elk, and swans, the greatest improvements in AIC_C occurred with setting a threshold for group size (*sppnum*), while for bald eagles and coyote the greatest improvements occurred with setting a threshold for interaction time (*intxn*). There were also large improvements in AIC_C by using either a distance (*dist*) threshold form for bison, bald eagles, and coyotes, or a moderated form for swans. A large improvement in elk model AIC_C values also occurred with an interaction time (*intxn*) threshold. Limiting the number of best models prior to examining alternative covariate forms can seriously affect the final results. For example, the initial elk models at Step 0 had the 31st and 32nd smallest AIC_C values, but had the 7th and 2nd smallest AIC_C values after Step 5 in the sequential process.

Figure 1: AIC_C Values from Sequential Modeling Process



APPENDIX D – Estimates, standard errors, and *P*-values for the movement (M) logit and vigilance (V) logit from exploratory analyses of the bison model best supported by the data. Abbreviations are: *year* (year of study); *dist* (distance of group from road); *sppnum* (group size); *onroad* (on or off road); *hact* (human activity); *intxn* (interaction time); *sb* (number of snowmobiles); *coach* (number of coaches); *hab* (habitat); *cumvis* (cumulative daily number of over-snow vehicles); IH (impeded/hastened animal movement); AP (approached animals on foot); D (dismounted or exited OSVs); S (stopped to observe animals); N (no visible reaction); ON (animals on the road); OFF (animals off the road); A (aquatic); BF (burned forest); F (unburned forest); TH (thermal); and M (meadow). For each categorical variable, results are presented relative to the baseline level (i.e., 2006 for *year*, N for *hact*, ON for *onroad*, and M for *hab*) and each estimate represents a departure from zero (i.e., no effect).

Effect	Movement logit			Vigilance logit		
	Estimate	SE	<i>P</i>	Estimate	SE	<i>P</i>
<i>intercept</i>	-0.23	0.63	0.776	0.82	0.42	0.055
<i>year</i> = 2003	2.20	0.42	<0.0001	0.74	0.25	0.003
= 2004	-0.08	0.40	0.839	-0.03	0.27	0.912
= 2005	-0.08	0.48	0.545	0.21	0.30	0.478
= 2006	-1.83	0.63	0.004	-0.92	0.31	0.003
<i>sppnum</i>	-2.9	0.72	<0.0001	1.53	0.54	0.004
<i>dist</i>	-6.82	2.61	0.009	-2.32	0.81	0.004
<i>hact</i> = IH	1.41	0.33	<0.0001	1.12	0.31	<0.001
= AP	0.33	0.65	0.608	-0.53	0.49	0.282
= D	-1.47	0.50	0.003	0.08	0.30	0.782
= S	0.20	0.27	0.456	-0.07	0.22	0.738
= N	-0.47	0.30	0.112	-0.60	0.23	0.009
<i>intxn</i>	0.27	0.21	0.206	0.49	0.14	<0.001
<i>onroad</i> = OFF	-1.43	0.20	<0.0001	-0.50	0.12	<0.0001
= ON	1.43	0.20	<0.0001	0.50	0.12	<0.0001
<i>sb</i>	0.11	0.04	0.002	0.08	0.03	0.002
<i>coach</i>	0.41	0.15	0.009	0.32	0.12	0.009
<i>hab</i> = A	1.90	0.53	<0.001	1.28	0.34	<0.001
= BF	-0.37	0.27	0.161	-0.27	0.19	0.156
= F	-0.11	0.21	0.588	0.08	0.14	0.581
= TH	-0.47	0.24	0.047	-0.66	0.17	<0.0001
= M	-0.95	0.22	<0.0001	-0.43	0.14	0.002
<i>cumvis</i>	0.00	0.02	0.825	-0.04	0.01	0.001
<i>sppnum</i> * <i>dist</i>	4.85	1.25	<0.001	-0.74	0.72	0.305
<i>dist</i> * <i>hact</i> = IH	1.06	3.77	0.779	-2.10	2.47	0.395
= AP	-11.62	8.87	0.190	-0.11	1.29	0.935
= D	5.38	2.47	0.029	0.70	0.84	0.406
= S	2.59	2.39	0.279	0.85	0.75	0.256
= N	2.59	2.38	0.277	0.66	0.72	0.364
<i>intxn</i> * <i>sppnum</i>	0.01	0.32	0.966	-0.66	0.22	0.003
<i>cumvis</i> * <i>year</i> = 2003	-0.07	0.02	0.005	0.03	0.02	0.095
= 2004	0.07	0.03	0.786	-0.03	0.02	0.110
= 2005	0.03	0.04	0.496	-0.01	0.03	0.656
= 2006	0.03	0.04	0.399	0.02	0.02	0.392

APPENDIX E – Estimates, standard errors, and *P*-values for the movement logit and vigilance logit from exploratory analyses of the elk model best supported by the data. Abbreviations are: *year* (year of study); *dist* (distance of group from road); *sppnum* (group size); *onroad* (on or off road); *hact* (human activity); *intxn* (interaction time); *coach* (number of coaches); *hab* (habitat); *cumvis* (cumulative daily number of over-snow vehicles); AP (approached animals on foot); D (dismounted or exited OSVs); S (stopped to observe animals); N (no visible reaction); ON (animals on the road); OFF (animals off the road); A (aquatic); BF (burned forest); F (unburned forest); TH (thermal); and M (meadow). For each categorical variable, results are presented relative to the baseline level (i.e., 2006 for *year*, ON for *onroad*, N for *hact*, and M for *hab*) and each estimate represents a departure from zero (i.e., no effect).

Effect	Movement logit			Vigilance logit		
	Estimate	SE	<i>P</i>	Estimate	SE	<i>P</i>
<i>intercept</i>	-1.87	0.50	<0.001	-0.50	0.35	0.151
<i>year</i> = 2003	0.40	0.30	0.182	0.40	0.15	0.008
= 2004	0.24	0.22	0.203	-0.02	0.10	0.841
= 2005	1.17	0.29	<0.0001	0.61	0.15	<0.0001
= 2006	-1.81	0.35	<0.0001	-0.99	0.14	<0.0001
<i>intxn</i>	1.34	0.17	<0.0001	0.98	0.13	<0.0001
<i>onroad</i> = OFF	-1.71	0.32	<0.0001	-0.18	0.30	0.536
= ON	1.71	0.32	<0.0001	0.18	0.30	0.536
<i>coach</i>	0.58	0.29	0.045	-0.04	0.15	0.786
<i>cumvis</i>	0.02	0.02	0.332	0.03	0.01	0.007
<i>sppnum</i> * <i>hact</i> = AP	1.69	0.57	0.003	0.19	0.40	0.635
= D	0.31	0.71	0.666	-0.14	0.41	0.729
= S	0.46	0.56	0.414	0.60	0.30	0.043
= N	-2.45	0.62	<0.0001	-0.65	0.26	0.011
<i>intxn</i> * <i>dist</i>	-0.42	0.13	0.001	-0.43	0.09	<0.0001
<i>intxn</i> * <i>sppnum</i>	-1.13	0.18	<0.0001	-0.69	0.13	<0.0001
<i>sppnum</i> * <i>hab</i> = A	3.18	0.70	<0.0001	1.37	0.39	<0.001
= BF	-0.66	0.60	0.275	-0.33	0.24	0.173
= F	1.30	0.63	0.039	0.57	0.34	0.089
= TH	-3.67	1.07	<0.001	-0.98	0.38	0.010
= M	-0.15	0.64	0.809	-0.62	0.27	0.020

APPENDIX F – Estimates, standard errors, and *P*-values for the movement logit and vigilance logit from exploratory analyses of the trumpeter swan model best supported by the data. Abbreviations are: *year* (year of study); *dist* (distance of group from road); *sppnum* (group size); *hact* (human activity); *intxn* (interaction time); *sb* (number of snowmobiles); *coach* (number of coaches); and *cumvis* (cumulative daily number of over-snow vehicles); AP (approached animals on foot); D (dismounted or exited OSVs); S (stopped to observe animals); and N (no visible reaction). For each categorical variable, results are presented relative to the baseline level (i.e., 2006 for *year* and N for *hact*) and each estimate represents a departure from zero (i.e., no effect).

Effect	Movement logit			Vigilance logit		
	Estimate	SE	<i>P</i>	Estimate	SE	<i>P</i>
<i>intercept</i>	0.56	0.68	0.409	2.07	0.45	<0.0001
<i>year</i> = 2003	1.40	0.56	0.013	0.32	0.39	0.414
= 2004	0.75	0.77	0.331	1.44	0.48	0.003
= 2005	-1.99	0.97	0.041	0.04	0.45	0.932
= 2006	-0.15	0.64	0.811	-1.80	0.50	<0.001
<i>sppnum</i>	-1.83	0.55	<0.001	-2.16	0.34	<0.0001
<i>dist</i>	-2.12	0.48	<0.0001	-2.07	0.30	<0.0001
<i>hact</i> = AP	0.33	0.34	0.340	0.30	0.31	0.334
= D	0.34	0.28	0.228	-0.30	0.27	0.266
= S	0.11	0.22	0.616	0.23	0.18	0.208
= N	-0.77	0.23	<0.001	-0.23	0.18	0.215
<i>intxn</i>	0.21	0.05	<0.0001	0.03	0.04	0.569
<i>sb</i>	0.09	0.03	0.009	0.06	0.02	0.004
<i>coach</i>	0.55	0.18	0.002	0.45	0.14	0.001
<i>cumvis</i>	-0.10	0.07	0.156	-0.08	0.04	0.060
<i>cumvis</i> * <i>year</i> = 2003	-0.10	0.09	0.272	0.00	0.06	0.981
= 2004	-0.09	0.12	0.473	-0.18	0.07	0.018
= 2005	0.38	0.15	0.011	0.08	0.07	0.263
= 2006	-0.20	0.11	0.070	0.09	0.08	0.232

APPENDIX G – Estimates, standard errors, and *P*-values for the movement logit and vigilance logit from exploratory analyses of the bald eagle model best supported by the data. Abbreviations are: *year* (year of study); *dist* (distance of group from road); *hact* (human activity); *intxn* (interaction time); *sb* (number of snowmobiles); *coach* (number of coaches); *hab* (habitat); AP (approached animals on foot); S (stopped to observe animals); N (no visible reaction); BF (burned forest); F (unburned forest); and M (meadow). For each categorical variable, results are presented relative to the baseline level (i.e., 2006 for *year*, N for *hact*, and M for *hab*) and each estimate represents a departure from zero (i.e., no effect).

Effect	Movement logit			Vigilance logit		
	Estimate	SE	<i>P</i>	Estimate	SE	<i>P</i>
<i>intercept</i>	0.13	1.36	0.925	-3.38	1.23	0.006
<i>year</i> = 2003	1.13	0.45	0.011	0.09	0.37	0.814
= 2004	-0.23	0.50	0.648	0.78	0.34	0.020
= 2005	0.53	0.43	0.220	0.35	0.36	0.334
= 2006	-1.43	0.55	0.010	-1.21	0.35	<0.001
<i>dist</i>	-1.25	0.71	0.080	0.59	0.55	0.284
<i>hact</i> = AP	0.83	0.77	0.280	-0.43	0.67	0.518
= S	-0.08	0.48	0.860	-0.70	0.42	0.093
= N	-0.75	0.64	0.239	1.14	0.52	0.028
<i>intxn</i>	-0.06	1.25	0.960	4.09	1.14	<0.001
<i>sb</i>	0.24	0.08	0.002	0.19	0.07	0.004
<i>coach</i>	1.44	0.65	0.027	0.66	0.50	0.185
<i>hab</i> = BF	.45	0.36	0.211	2.14	0.33	<0.0001
= F	-0.72	0.39	0.066	-0.29	0.32	0.365
= M	0.26	0.45	0.556	-1.85	0.48	<0.0001
<i>intxn*dist</i>	0.28	0.65	0.667	-1.21	0.57	0.032

APPENDIX H – Estimates, standard errors, and *P*-values for the movement logit and vigilance logit from exploratory analyses of the coyote model best supported by the data. Abbreviations are: *year* (year of study); *dist* (distance of group from road); *hact* (human activity); *intxn* (interaction time); AP (approached animals on foot); N (no visible reaction). For each categorical variable, results are presented relative to the baseline level (i.e., 2006 for *year* and N for *hact*) and each estimate represents a departure from zero (i.e., no effect).

Effect	Movement logit			Vigilance logit		
	Estimate	SE	<i>P</i>	Estimate	SE	<i>P</i>
<i>intercept</i>	-0.50	1.33	0.706	-1.54	1.05	0.141
<i>year</i> = 2003	0.79	0.56	0.157	1.06	0.40	0.008
= 2004	-0.44	0.58	0.449	-0.32	0.40	0.428
= 2005	0.49	0.53	0.356	0.73	0.37	0.048
= 2006	-0.84	0.54	0.120	-1.47	0.43	<0.001
<i>dist</i>	-5.10	1.21	<0.0001	-1.49	1.06	0.160
<i>hact</i> = AP	1.13	0.58	0.053	-0.42	0.74	0.571
= N	-1.13	0.58	0.053	0.42	0.74	0.571
<i>intxn</i>	3.21	1.22	0.008	2.18	0.68	0.001

APPENDIX I – Output from a maximum likelihood analysis of variance for *a priori* and post hoc exploratory bison model main effects and interactions. Degrees of freedom (*df*) and *P*-values indicate if a variable’s effect was statistically significant.

Model Effect	<i>a priori</i> model		exploratory model	
	<i>df</i>	<i>P</i> -value	<i>df</i>	<i>P</i> -value
<i>year</i>	6	<.0001	6	<.0001
<i>sppnum</i>	2	.0001	2	.0001
<i>dist</i>	2	.0009	2	.0009
<i>hact</i>	8	<.0001	8	<.0001
<i>intxn</i>	2	.0027	2	.0027
<i>oroad</i>	2	<.0001	2	<.0001
<i>sb</i>	2	.0009	2	.0009
<i>coach</i>	2	.0083	2	.0083
<i>hab</i>	8	<.0001	8	<.0001
<i>cumvis</i>	2	.0020	2	.0020
<i>sppnum*dist</i>	2	<.0001	2	<.0001
<i>dist*hact</i>	6	.1490	6	.1490
<i>sppnum*intxnt</i>	2	.0055	2	.0055
<i>cumvis*year</i>	8	.0048	8	.0048

APPENDIX J – Output from a maximum likelihood analysis of variance for *a priori* and post hoc exploratory elk model main effects and interactions. Degrees of freedom (*df*) and *P*-values indicate if a variable’s effect was statistically significant.

Model Effect	<i>a priori</i> model		exploratory model	
	<i>df</i>	<i>P</i> -value	<i>df</i>	<i>P</i> -value
<i>year</i>	6	<.0001	6	<.0001
<i>sppnum</i>	2	.3628		
<i>dist</i>	2	.1443		
<i>hact</i>	6	.1512		
<i>intxn</i>	2	<.0001	2	<.0001
<i>oroad</i>	2	<.0001	2	<.0001
<i>sb</i>	2	.7010		
<i>coach</i>	2	.0843	2	.0758
<i>hab</i>	8	.0004		
<i>cumvis</i>	2	.0258	2	.0272
<i>sppnum*dist</i>	2	.0556		
<i>sppnum*hact</i>	6	.0023	6	.0002
<i>dist*intxn</i>	2	.0325	2	<.0001
<i>sppnum*intxn</i>	2	<.0001	2	<.0001
<i>sppnum*hab</i>			8	<.0001

APPENDIX K – Output from a maximum likelihood analysis of variance for *a priori* and post hoc exploratory trumpeter swan model main effects and interactions. Degrees of freedom (*df*) and *P*-values indicate if a variable’s effect was statistically significant.

	<i>a priori</i> model		exploratory model	
Model Effect	<i>df</i>	<i>P</i> -value	<i>df</i>	<i>P</i> -value
<i>year</i>	6	.0005	6	.0006
<i>sppnum</i>	2	.0275	2	<.0001
<i>dist</i>	2	.0004	2	<.0001
<i>hact</i>	6	.0073	6	.0094
<i>intxn</i>	2	.0163	2	.0003
<i>sb</i>	2	.0037	2	.0035
<i>coach</i>	2	.0017	2	.0014
<i>cumvis</i>	2	.1045	2	.1072
<i>sppnum*dist</i>	2	.7007		
<i>dist*intxn</i>	2	.2631		
<i>cumvis*year</i>	6	.0349	6	.0420

APPENDIX L – Output from a maximum likelihood analysis of variance for *a priori* and post hoc exploratory bald eagle model main effects and interactions. Degrees of freedom (*df*) and *P*-values indicate if a variable’s effect was statistically significant.

	<i>a priori</i> model		exploratory model	
Model Effect	<i>df</i>	<i>P</i> -value	<i>df</i>	<i>P</i> -value
<i>year</i>	6	.0004	6	.0003
<i>sppnum</i>	2	.3114		
<i>dist</i>	2	.0356	2	.0363
<i>hact</i>	6	.0230	4	.0056
<i>intxn</i>	2	<.0001	2	.0001
<i>Sb</i>	2	.0094	2	.0064
<i>coach</i>	2	.1098	2	.0855
<i>hab</i>	4	<.0001	4	<.0001
<i>dist*intxn</i>	2	.0195	2	.0254

APPENDIX M – Output from a maximum likelihood analysis of variance for *a priori* and post hoc exploratory coyote model main effects and interactions. Degrees of freedom (*df*) and *P*-values indicate if a variable’s effect was statistically significant.

	<i>a priori</i> model		exploratory model	
Model Effect	<i>df</i>	<i>P</i> -value	<i>df</i>	<i>P</i> -value
<i>year</i>	6	.0160	6	.0111
<i>sppnum</i>	2	.1999		
<i>dist</i>	2	.0061	2	<.0001
<i>hact</i>	6	.1407	2	.0087
<i>intxn</i>	2	.0230	2	.0015
<i>oroad</i>	2	.9078		
<i>sb</i>	2	.2457		
<i>coach</i>	2	.9410		