

# PICTURE THIS: HOT MEASUREMENT AND MODELING METHODS IN MOVEMENT DISORDERS RESEARCH

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## Warren Grant Magnuson Clinical Center & the Clinical Research Center



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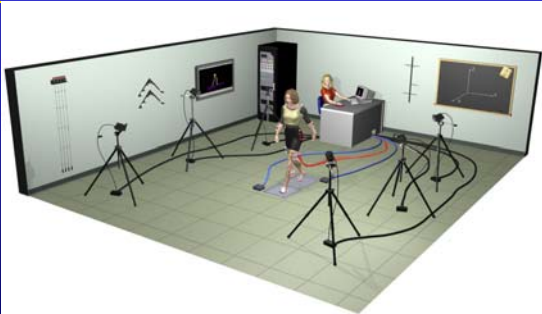
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## Movement Analysis Laboratory



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## Overview of the basic process

Attach markers and obtain physical parameters

Build a scaled geometric model

Apply a generic musculoskeletal model

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## Enhanced Movement Analysis (6 DOF Joint Models)

Visual inspection of data/errors

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## Enhanced Movement Analysis (Muscle kinematics)

Landmark targets

Tracking targets

Landmark targets

Muscle origin & insertion estimates

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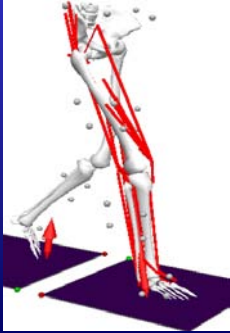
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### Enhanced Movement Analysis (Muscle lines of action)



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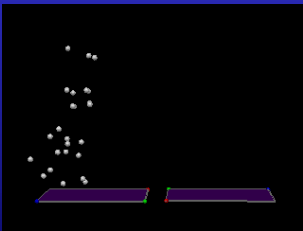
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### Picture this: (Modeling Methods)



Repeat animation of walking  
depicting various models

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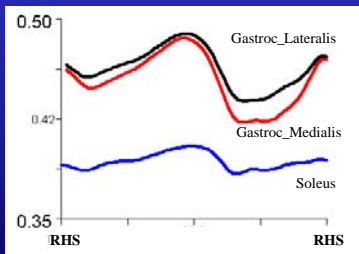
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### Muscle Kinematics



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## Muscle Kinematics

Muscle lines of action  
Muscle length changes  
Muscle contraction velocities

### Are precursors to:

Individual muscle motion control "sensitivities"  
Individual muscle forces and their effects?

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## Picture this: (Motion control sensitivities)



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## Patient case



- 54 y/o Male
- Amyotrophic lateral sclerosis
- Impairments: lower extremity weakness  
Left (2/5), right (4/5)

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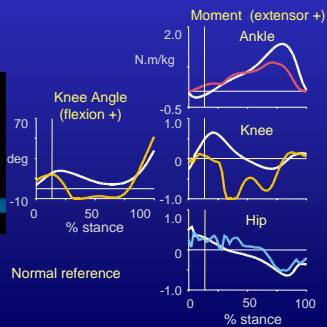
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## Patient case - Motion and Moments



What causes the left knee to extend so rapidly?

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## Picture this:

The ability to inspect all possible causes



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## Induced Acceleration Analysis (IAA)

1. Perform a movement analysis that includes inverse dynamics analysis.
2. Insert one sample (instant) of the subject's measured position and force data into a **coupled dynamics** model.
3. Numerically explore the set of **coupled dynamics** equations to determine the muscle moment/joint movement (acceleration) relationships.
4. Return to step 2 until last instant.

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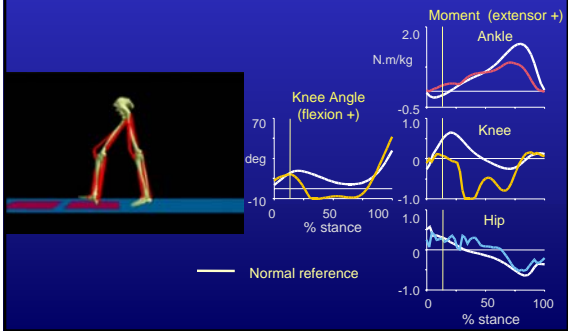
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## Patient case - Motion and Moments




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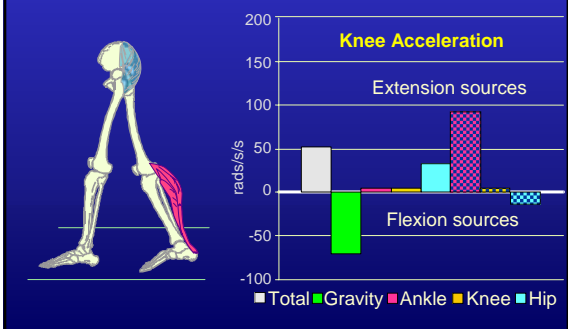
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## IAA - Left Knee Control




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## Motion simulation using right ankle moment




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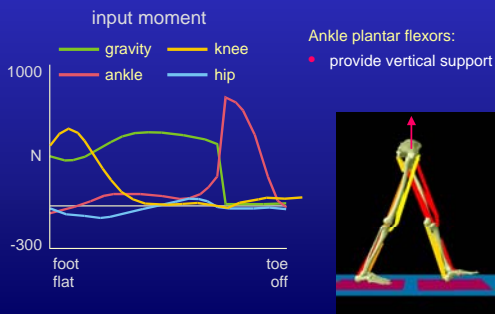
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## COM Control – Vertical Force / Acceleration



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## Picture this: Contribution of assistive technologies



Advanced Prosthetics and Orthotics Inc., Encinitas, CA

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## Determining the AFO's contribution

Understanding the contribution of a Dynamic Ankle Foot Orthosis (DAFO) and the patient's adaptation to the DAFO during the stance phase of gait are important steps towards predicting and obtaining desired outcomes.

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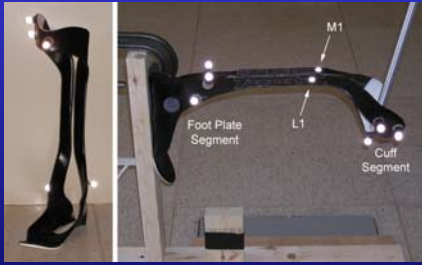
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## Dynamic AFO Model



STIFFNESS MODELS

	Subject 1	Subject 2
KDF (Nm/deg)	-4.0	-3.0
KPF (Nm/deg)	-6.5	-4.5

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## Dynamic AFO - Subjects

	Subject 1	Subject 2
Diagnosis	Post Polio Syndrome	Post Polio Syndrome
Age/Gender	66/M	58/F
Ht/Wt (m/kg)	1.85/81.8	1.6/52.3
Prescription	Bilateral Dynamic AFO	Dynamic AFO - Left 5/8" Lift - Right

	Subject 1	Subject 2
Speed Unbraced (Stat/s)	0.65	0.55
Speed AFO (Stat/s)	Same	Faster
Stride Length Unbraced (Stat)	0.84	0.68
Stride Length AFO (Stat)	Same	Longer

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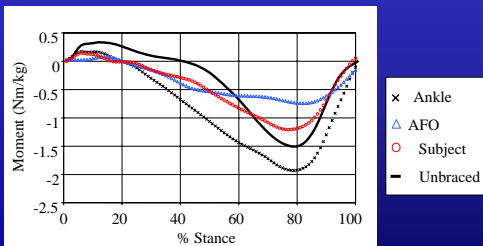
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## Subject 1




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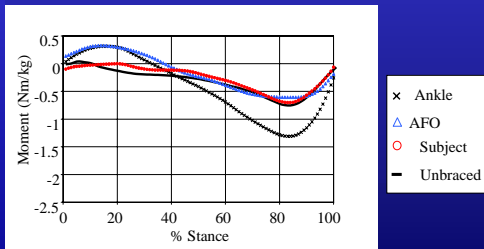
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## Subject 2



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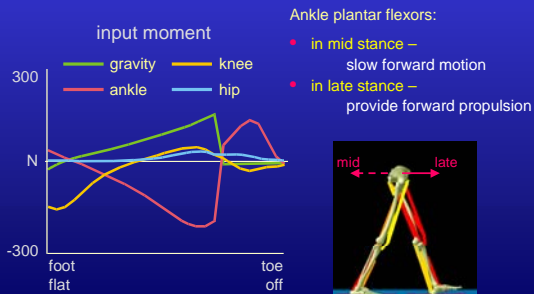
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## COM Control – A/P Force / Acceleration



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## Summary

- 6 Degree of Freedom Models (visualization)
- Muscle Kinematics (LOA)
- Induced Acceleration Analysis (IAA)
- Limb (joint) control
- Body support & propulsion
- Contribution of assistive technology

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## Contributors

Karen Lohmann Siegel (NIH)  
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