

Computer-Assisted Hip Osteotomy with Real-Time Biomechanical Guidance System



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Introduction

- Objective:
 - Demonstrate the feasibility of imageguided joint surgery when near real-time feedback of the biomechanical state of the joint is presented intraoperatively
- Hip dysplasia:
 - A significant cause of osteoarthritis in young adults
- Surgery goals:
 - To reduce patient pain
 - To reduce joint subluxation by reorienting the acetabulum to contain the femoral head
- Bernese Osteotomy:
 - Technically challenging procedure
 - Can benefit from computer-aided surgery





Introduction

Preoperative Planning:

- Aims at quantifying the abnormal anatomy based on anatomical angles
- Limited biomechanical analysis

Image-guided Osteotomy:



- Langlotz et al. reported the first 12 cases (1997)
- Limited clinical application due to high cost, interface problems, space constraints, additional intervention time
- Intraoperative Biomechanical Guidance:
 - A tool to help the surgeon change the plans when fixation, congruency, impingement, and joint stability problems arise during the surgery



Approach: Analysis Tool

Discrete Element Analysis

Analysis technique requirements:

- Relative accuracy
- Fault-tolerant on the joint geometry
- Suitable for simulation of individual-based functional data
- Experimental validation











Approach: System architecture

- System requirements:
 - Run independent of imaging system
 - Minimal additional effort for registration
 - Provide information at request of surgeon in < 1 min</p>





Study Plan

- BGS Development
 - Preoperative Planning Module
 - Model reconstruction from CT images
 - Surgical planning based on joint kinematics and biomechanics
 - Intraoperative Module
 - Model registration
 - Joint kinematics and biomechanical simulation
- Test of reliability and functionality
 - Cadaver testing
 - Satisfaction of minimal criteria for joint alignments
- Analysis of outcomes
 - Surgeries on 10 patients
 - Clinical follow-up at 6 months
 - Comparison with traditional technique

