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# DAKOTA, A Multilevel Parallel Object-Oriented Framework for Design Optimization, Parameter Estimation, Uncertainty Quantification, and Sensitivity Analysis

## Version 4.1 Developers Manual

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## Abstract

The DAKOTA (Design Analysis Kit for Optimization and Terascale Applications) toolkit provides a flexible and extensible interface between simulation codes and iterative analysis methods. DAKOTA contains algorithms for optimization with gradient and nongradient-based methods; uncertainty quantification with sampling, reliability, and stochastic finite element methods; parameter estimation with nonlinear least squares methods; and sensitivity/variance analysis with design of experiments and parameter study methods. These capabilities may be used on their own or as components within advanced strategies such as surrogate-based optimization, mixed integer nonlinear programming, or optimization under uncertainty. By employing object-oriented design to implement abstractions of the key components required for iterative systems analyses, the DAKOTA toolkit provides a flexible and extensible problem-solving environment for design and performance analysis of computational models on high performance computers.

This report serves as a developers manual for the DAKOTA software and describes the DAKOTA class hierarchies and their interrelationships. It derives directly from annotation of the actual source code and provides detailed class documentation, including all member functions and attributes.

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# Chapter 1

## DAKOTA Developers Manual

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### 1.1 Introduction

The DAKOTA (Design Analysis Kit for Optimization and Terascale Applications) toolkit provides a flexible, extensible interface between analysis codes and iteration methods. DAKOTA contains algorithms for optimization with gradient and nongradient-based methods, uncertainty quantification with sampling, reliability, and stochastic finite element methods, parameter estimation with nonlinear least squares methods, and sensitivity/variance analysis with design of experiments and parameter study capabilities. These capabilities may be used on their own or as components within advanced strategies such as surrogate-based optimization, mixed integer nonlinear programming, or optimization under uncertainty. By employing object-oriented design to implement abstractions of the key components required for iterative systems analyses, the DAKOTA toolkit provides a flexible problem-solving environment as well as a platform for rapid prototyping of new solution approaches.

The Developers Manual focuses on documentation of the class structures used by the DAKOTA system. It derives directly from annotation of the actual source code. For information on input command syntax, refer to the [Reference Manual](#), and for a tour of DAKOTA features and capabilities, refer to the Users Manual.

### 1.2 Overview of DAKOTA

In the DAKOTA system, the *strategy* creates and manages *iterators* and *models*. In the simplest case, the strategy creates a single iterator and a single model and executes the iterator on the model to perform a single study. In a more advanced case, a hybrid optimization strategy might manage a global optimizer operating on a low-fidelity

model in coordination with a local optimizer operating on a high-fidelity model. And on the high end, a surrogate-based optimization under uncertainty strategy would employ an uncertainty quantification iterator nested within an optimization iterator and would employ truth models layered within surrogate models. Thus, iterators and models provide both stand-alone capabilities as well as building blocks for more sophisticated studies.

A model contains a set of *variables*, an *interface*, and a set of *responses*, and the iterator operates on the model to map the variables into responses using the interface. Each of these components is a flexible abstraction with a variety of specializations for supporting different types of iterative studies. In a DAKOTA input file, the user specifies these components through strategy, method, model, variables, interface, and responses keyword specifications.

The use of class hierarchies provides a mechanism for extensibility in DAKOTA components. In each of the various class hierarchies, adding a new capability typically involves deriving a new class and providing a small number of virtual function redefinitions. These redefinitions define the coding portions specific to the new derived class, with the common portions already defined at the base class. Thus, with a small amount of new code, the existing facilities can be extended, reused, and leveraged for new purposes.

The software components are presented in the following sections using a top-down order.

### 1.2.1 Strategies

Class hierarchy: [Strategy](#).

Strategies provide a control layer for creation and management of iterators and models. Specific strategies include:

- [SingleMethodStrategy](#): the simplest strategy. A single iterator is run on a single model to perform a single study.
- [MultilevelOptStrategy](#): hybrid optimization using a succession of iterators employing a succession of models of varying fidelity. The best results obtained are passed from one iterator to the next.
- [SurrBasedOptStrategy](#): surrogate-based optimization. Employs a single iterator with a [SurrogateModel](#) (either data fit or hierarchical). A sequence of approximate optimizations is performed, each of which involves build, optimize, and verify steps.
- [ConcurrentStrategy](#): two similar algorithms are available: (1) multi-start iteration from several different starting points, and (2) pareto set optimization for several different multiobjective weightings. Employs a single iterator with a single model, but runs multiple instances of the iterator concurrently for different settings within the model.

### 1.2.2 Iterators

Class hierarchy: [Iterator](#).

The iterator hierarchy contains a variety of iterative algorithms for optimization, uncertainty quantification, non-linear least squares, design of experiments, and parameter studies. The hierarchy is divided into [Minimizer](#) and [Analyzer](#) branches. The [Minimizer](#) classes include:

- Optimization: [Optimizer](#) provides a base class for the [DOTOptimizer](#), [CONMINOptimizer](#), [NPSOLOptimizer](#), [NLPQLPOptimizer](#), and [SNLLOptimizer](#) gradient-based optimization libraries and the

[COLINOptimizer](#), [JEGAOptimizer](#), [NCSUOptimizer](#), and [EffGlobalOptimizer](#) nongradient-based optimization methods and libraries.

- Parameter estimation: [LeastSq](#) provides a base class for [NL2SOLLeastSq](#), a least-squares solver based on NL2SOL, [SNLLLeastSq](#), a Gauss-Newton least-squares solver, and [NLSSOLLeastSq](#), an SQP-based least-squares solver.

and the [Analyzer](#) classes include:

- Uncertainty quantification: [NonD](#) provides a base class for [NonDReliability](#) (reliability analysis), [NonDEvidence](#) (Dempster-Shafer Theory of Evidence), [NonDPolynomialChaos](#) (generalized polynomial chaos expansions), [NonDSampling](#), and [NonDIntegration](#). [NonDReliability](#) is further specialized with local and global methods ([NonDLocalReliability](#) and [NonDGlobalReliability](#)), [NonDIntegration](#) is further specialized with quadrature and cubature methods ([NonDQuadrature](#) and [NonDCubature](#)), and [NonDSampling](#) is further specialized with the [NonDLHSSampling](#) class for Latin hypercube and Monte Carlo sampling, the [NonDIncrLHSSampling](#) class for incremental Latin hypercube sampling, and [NonDAdaptImpSampling](#) for multimodal adaptive importance sampling.
- Parameter studies and design of experiments: [PStudyDACE](#) provides a base class for [ParamStudy](#), which provides capabilities for directed parameter space interrogation, [PSUADEDesignCompExp](#), which provides access to the Morris One-At-a-Time (MOAT) method for parameter screening, and [DDACEDesignCompExp](#) and [FSUDesignCompExp](#), which provide for parameter space exploration through design and analysis of computer experiments. [NonDLHSSampling](#) from the uncertainty quantification branch also supports a design of experiments mode.

### 1.2.3 Models

Class hierarchy: [Model](#).

The model classes are responsible for mapping variables into responses when an iterator makes a function evaluation request. There are several types of models, some supporting sub-iterators and sub-models for enabling layered and nested relationships. When sub-models are used, they may be of arbitrary type so that a variety of recursions are supported.

- [SingleModel](#): variables are mapped into responses using a single [Interface](#) object. No sub-iterators or sub-models are used.
- [SurrogateModel](#): variables are mapped into responses using an approximation. The approximation is built and/or corrected using data from a sub-model (the truth model) and the data may be obtained using a sub-iterator (a design of experiments iterator). [SurrogateModel](#) has two derived classes: [DataFitSurrModel](#) for data fit surrogates and [HierarchSurrModel](#) for hierarchical models of varying fidelity. The relationship of the sub-iterators and sub-models is considered to be "layered" since they are not used as part of every response evaluation on the top level model, but rather used periodically in surrogate update and verification steps.
- [NestedModel](#): variables are mapped into responses using a combination of an optional [Interface](#) and a sub-iterator/sub-model pair. The relationship of the sub-iterators and sub-models is considered to be "nested" since they are used to perform a complete iterative study as part of every response evaluation on the top level model.

- [RecastModel](#): recasts the inputs and outputs of a sub-model for the purposes of variable transformations (e.g., variable scaling, transformations to standardized random variables) and problem reformulation (e.g., multiobjective optimization, response scaling, augmented Lagrangian merit functions, expected improvement).

## 1.2.4 Variables

Class hierarchy: [Variables](#).

The [Variables](#) class hierarchy manages design, uncertain, and state variable types for continuous and discrete domain types. This hierarchy is specialized according to various views of the data.

- [DistinctVariables](#): both variable and domain type distinctions are retained, i.e. separate arrays for design, uncertain, and state variables types and for continuous and discrete domains.
- [AllVariables](#): variable types are combined and domain type distinction is retained, i.e. design, uncertain, and state variable types combined into a single continuous variables array and a single discrete variables array.
- [MergedVariables](#): variable type distinction is retained and domain types are combined, i.e. continuous and discrete variables merged into continuous arrays (integrality is relaxed) for design, uncertain, and state variable types.

The variables view that is chosen depends on the type of iterative study. For design optimization and uncertainty quantification, for example, variable and domain type distinctions are important and a [DistinctVariables](#) view is used. For parameter studies and design of experiments, however, the variable type distinctions can be ignored and an [AllVariables](#) view is used.

The [Constraints](#) hierarchy manages bound, linear, and nonlinear constraints and utilizes the same specializations for managing bounds on the variables (see [DistinctConstraints](#), [AllConstraints](#), and [MergedConstraints](#)).

## 1.2.5 Interfaces

Class hierarchy: [Interface](#).

Interfaces provide access to simulation codes or, conversely, approximations based on simulation code data. In the simulation case, an [ApplicationInterface](#) is used. [ApplicationInterface](#) is specialized according to the simulation invocation mechanism, for which the following nonintrusive approaches

- [SysCallApplicInterface](#): the simulation is invoked using a system call (the C function `system()`). Asynchronous invocation utilizes a background system call. Utilizes the [SysCallAnalysisCode](#) class to define syntax for input filter, analysis code, output filter, or combined spawning, which in turn utilize the [CommandShell](#) utility.
- [ForkApplicInterface](#): the simulation is invoked using a fork (the `fork/exec/wait` family of functions). Asynchronous invocation utilizes a nonblocking fork. Utilizes the [ForkAnalysisCode](#) class for lower level fork operations.

- [GridApplicInterface](#): the simulation is invoked using distributed resource facilities. This capability is experimental and still under development. The design is evolving into the use of Condor and/or Globus tools.

and the following semi-intrusive approach

- [DirectFnApplicInterface](#): the simulation is linked into the DAKOTA executable and is invoked using a procedure call. Asynchronous invocations will utilize nonblocking threads (capability not yet available).

are supported. Scheduling of jobs for asynchronous local, message passing, and hybrid parallelism approaches is performed in the [ApplicationInterface](#) class, with job initiation and job capture specifics implemented in the derived classes.

In the data fit approximation case, global, multipoint, or local approximations to simulation code response data can be built and used as surrogates for the actual, expensive simulation. The interface class providing this capability is

- [ApproximationInterface](#): builds an approximation using data from a truth model and then employs the approximation for mapping variables to responses. This class contains an array of [Approximation](#) objects, one per response function, which permits the mixing of approximation types (using the [Approximation](#) derived classes: [SurfpackApproximation](#) (provides kriging, neural network, MARS, polynomial regression, and radial basis functions), [GaussProcApproximation](#), [OrthogPolyApproximation](#) (utilizes an array of [OrthogonalPolynomial](#) instances to manage multivariate orthogonal polynomials from the Wiener-Askey scheme), [TANA3Approximation](#), and [TaylorApproximation](#)).

Note: in the data fit approximation case, [DataFitSurrModel](#) provides the bulk of the surrogate management logic. It contains an [ApproximationInterface](#) object which provides the approximate parameter to response mappings. In the hierarchical approximation case, an [ApproximationInterface](#) object is not used since [HierarchSurrModel](#) uses low and high fidelity models to manage surrogate construction/usage.

## 1.2.6 Responses

Class: [Response](#).

The [Response](#) class provides an abstract data representation of response functions and their first and second derivatives (gradient vectors and Hessian matrices). These response functions can be interpreted as an objective function and constraints (optimization data set), residual functions and constraints (least squares data set), or generic response functions (uncertainty quantification data set). This class is not currently part of a class hierarchy, since the abstraction has been sufficiently general and has not required specialization.

## 1.3 Services

A variety of services are provided in DAKOTA for parallel computing, failure capturing, restart, graphics, etc. An overview of the classes and member functions involved in performing these services is included below.

- Multilevel parallel computing: DAKOTA supports multiple levels of nested parallelism. A strategy can manage concurrent iterators, each of which manages concurrent function evaluations, each of which manages concurrent analyses executing on multiple processors. Partitioning of these levels with MPI communicators is managed in [ParallelLibrary](#) and scheduling routines for the levels are part of [ConcurrentStrategy](#), [ApplicationInterface](#), and [ForkApplicInterface](#).

- Parsing: DAKOTA employs the Input Deck Reader (IDR) parser to retrieve information from user input files. Parsing options are processed in [CommandLineHandler](#) and parsing occurs in [ProblemDescDB::manage\\_inputs\(\)](#) called from [main.C](#). IDR uses the keyword handlers in the [IDRProblemDescDB](#) derived class to populate data within the [ProblemDescDB](#) base class, which maintains a [DataStrategy](#) specification and lists of [DataMethod](#), [DataModel](#), [DataVariables](#), [DataInterface](#), and [DataResponses](#) specifications. Procedures for modifying the parsing subsystem are described in [Instructions for Modifying DAKOTA's Input Specification](#).
- Failure capturing: Simulation failures can be trapped and managed using exception handling in [ApplicationInterface](#) and its derived classes.
- Restart: DAKOTA maintains a record of all function evaluations both in memory (for capturing any duplication) and on the file system (for restarting runs). Restart options are processed in [CommandLineHandler](#) and retrieved in [ParallelLibrary::specify\\_outputs\\_restart\(\)](#), restart file management occurs in [ParallelLibrary::manage\\_outputs\\_restart\(\)](#), and restart file insertions occur in [ApplicationInterface](#). The `dakota_restart_util` executable, built from [restart\\_util.C](#), provides a variety of services for interrogating, converting, repairing, concatenating, and post-processing restart files.
- Memory management: DAKOTA employs the techniques of reference counting and representation sharing through the use of letter-envelope and handle-body idioms (Coplien, "Advanced C++"). The former idiom provides for memory efficiency and enhanced polymorphism in the following class hierarchies: [Strategy](#), [Iterator](#), [Model](#), [Variables](#), [Constraints](#), [Interface](#), [ProblemDescDB](#), [Approximation](#), and [OrthogonalPolynomial](#). The latter idiom provides for memory efficiency in data-intensive classes which do not involve a class hierarchy. Currently, only the [Response](#) class uses this idiom. When managing reference-counted data containers (e.g., [Variables](#) or [Response](#) objects), it is important to properly manage shallow and deep copies, to allow for both efficiency and data independence as needed in a particular context.
- [Graphics](#): DAKOTA provides 2D iteration history graphics using Motif widgets and 3D surface plotting graphics from the PLPLOT package. [Graphics](#) data can also be catalogued in a tabular data file for post-processing with 3rd party tools such as Matlab, Tecplot, etc. All of these capabilities are encapsulated within the [Graphics](#) class.

## 1.4 Additional Resources

Additional development resources include:

- [Recommended Practices for DAKOTA Development](#)
- [Software Tools for DAKOTA Development](#)
- [Instructions for Modifying DAKOTA's Input Specification](#)
- In addition to its normal usage as a stand-alone application, DAKOTA may be interfaced as an algorithm library as described in [Interfacing with DAKOTA as a Library](#).
- The execution of function evaluations is a core component of DAKOTA involving several class hierarchies. An overview of the classes and member functions involved in performing these evaluations is provided in [Performing Function Evaluations](#).

- Project web pages are maintained at <http://www.cs.sandia.gov/DAKOTA> with software specifics and documentation pointers provided at <http://www.cs.sandia.gov/DAKOTA/software.html>, and a list of publications provided at <http://www.cs.sandia.gov/DAKOTA/references.html>





## Chapter 2

# DAKOTA Namespace Index

### 2.1 DAKOTA Namespace List

Here is a list of all documented namespaces with brief descriptions:

<a href="#">Dakota</a> (The primary namespace for DAKOTA ) . . . . .	29
<a href="#">SIM</a> (Plug facilities into DAKOTA ) . . . . .	61



# Chapter 3

## DAKOTA Hierarchical Index

### 3.1 DAKOTA Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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ForkAnalysisCode . . . . .	227
SysCallAnalysisCode . . . . .	575
Approximation . . . . .	93
GaussProcApproximation . . . . .	237
OrthogPolyApproximation . . . . .	459
SurfpackApproximation . . . . .	550
TANA3Approximation . . . . .	580
TaylorApproximation . . . . .	583
Array . . . . .	104
BaseConstructor . . . . .	108
BaseVector . . . . .	109
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# Chapter 4

## DAKOTA Class Index

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# Chapter 5

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# Chapter 6

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# Chapter 7

## DAKOTA Namespace Documentation

### 7.1 Dakota Namespace Reference

The primary namespace for DAKOTA.

#### Classes

- class [AllConstraints](#)  
*employs the all data view.*
- class [AllVariables](#)  
*the all data view.*
- class [AnalysisCode](#)  
*processes for managing simulations.*
- class [ApplicationInterface](#)  
*interfaces to simulation codes.*
- class [ApproximationInterface](#)  
*approximations to simulation-based results.*
- class [COLINApplication](#)
- class [COLINOptimizer](#)  
*Wrapper class for optimizers defined using COLIN.*
- class [GetLongOpt](#)  
*(Advanced Computer Research Institute, Lyon, France).*

- class [CommandLineHandler](#)  
*Utility class for managing command line inputs to DAKOTA.*
- class [CommandShell](#)  
*processes with system calls.*
- class [ConcurrentStrategy](#)  
*Strategy for multi-start iteration or pareto set optimization.*
- class [CONMINOptimizer](#)  
*Wrapper class for the CONMIN optimization library.*
- class [ActiveSet](#)  
*active set request vector and the derivative variables vector.*
- class [Analyzer](#)  
*hierarchy.*
- class [SurrogateDataPoint](#)  
*for defining a "truth" data point.*
- class [SurrogateDataPointRep](#)  
*or body, may be shared by multiple [SurrogateDataPoint](#) handle instances.*
- class [Approximation](#)  
*Base class for the approximation class hierarchy.*
- class [Array](#)  
*Template class for the [Dakota](#) bookkeeping array.*
- class [BaseVector](#)  
*Base class for the [Dakota::Matrix](#) and [Dakota::Vector](#) classes.*
- class [BiStream](#)  
*data types*
- class [BoStream](#)  
*data types*
- class [Constraints](#)  
*Base class for the variable constraints class hierarchy.*
- class [Graphics](#)  
*for post-processing with Matlab, Tecplot, etc.*



- class [Interface](#)  
*Base class for the interface class hierarchy.*
- class [Iterator](#)  
*Base class for the iterator class hierarchy.*
- class [LeastSq](#)  
*Base class for the nonlinear least squares branch of the iterator hierarchy.*
- class [List](#)  
*Template class for the [Dakota](#) bookkeeping list.*
- class [FunctionCompare](#)
- class [Matrix](#)  
*Template class for the [Dakota](#) numerical matrix.*
- class [Minimizer](#)  
*iterator hierarchy.*
- class [Model](#)  
*Base class for the model class hierarchy.*
- class [NonD](#)  
*Base class for all nondeterministic iterators (the [DAKOTA/UQ](#) branch).*
- class [Optimizer](#)  
*Base class for the optimizer branch of the iterator hierarchy.*
- class [PStudyDACE](#)  
*design of experiments methods.*
- class [Response](#)  
*[Response](#) provides the handle class.*
- class [ResponseRep](#)  
*[ResponseRep](#) provides the body class.*
- class [Strategy](#)  
*Base class for the strategy class hierarchy.*
- class [String](#)  
*[Dakota::String](#) class, used as main string class for [Dakota](#).*
- class [Variables](#)  
*Base class for the variables class hierarchy.*

- class [Vector](#)  
*Template class for the [Dakota](#) numerical vector.*
- class [DataFitSurrModel](#)  
*data fit surrogates (global and local)*
- class [DataInterface](#)  
*Container class for interface specification data.*
- class [DataMethod](#)  
*Container class for method specification data.*
- class [DataModel](#)  
*Container class for model specification data.*
- class [DataResponses](#)  
*Container class for responses specification data.*
- class [DataStrategy](#)  
*Container class for strategy specification data.*
- class [DataVariables](#)  
*Container class for variables specification data.*
- class [DDACEDesignCompExp](#)  
*Wrapper class for the [DDACE](#) design of experiments library.*
- class [DirectFnApplicInterface](#)  
*and testers using direct procedure calls.*
- class [DistinctConstraints](#)  
*the default data view (no variable or domain type array merging).*
- class [DistinctVariables](#)  
*the default data view (no variable or domain type array merging).*
- class [DOTOptimizer](#)  
*Wrapper class for the [DOT](#) optimization library.*
- class [EffGlobalOptimizer](#)  
*Implementation of [Efficient Global Optimization](#) algorithm.*
- class [ForkAnalysisCode](#)  
*simulations using forks.*
- class [ForkApplicInterface](#)

*using forks.*

- class [FSUDesignCompExp](#)  
*Wrapper class for the FSUDace QMC/CVT library.*
- class [GaussProcApproximation](#)  
*Derived approximation class for Gaussian Process implementation.*
- class [GenLaguerreOrthogPolynomial](#)  
*Derived orthogonal polynomial class for generalized Laguerre polynomials.*
- struct [BaseConstructor](#)  
*Dummy struct for overloading letter-envelope constructors.*
- struct [NoDBBaseConstructor](#)  
*Dummy struct for overloading constructors used in on-the-fly instantiations.*
- struct [RecastBaseConstructor](#)  
*instantiations.*
- class [GridApplicInterface](#)  
*using grid services such as Condor or Globus.*
- class [HermiteOrthogPolynomial](#)  
*Derived orthogonal polynomial class for Hermite polynomials.*
- class [HierarchSurrModel](#)  
*hierarchical surrogates (models of varying fidelity).*
- class [IDRProblemDescDB](#)  
*The derived input file database utilizing the IDR parser.*
- class [JacobiOrthogPolynomial](#)  
*Derived orthogonal polynomial class for Jacobi polynomials.*
- class [JEGAOptimizer](#)  
*A version of [Dakota::Optimizer](#) for instantiation of John Eddy's Genetic Algorithms (JEGA).*
- class [LaguerreOrthogPolynomial](#)  
*Derived orthogonal polynomial class for Laguerre polynomials.*
- class [LegendreOrthogPolynomial](#)  
*Derived orthogonal polynomial class for Legendre polynomials.*
- class [MergedConstraints](#)  
*the merged data view.*

- class [MergedVariables](#)  
*merged data view.*
- class [MPIPackBuffer](#)  
*Class for packing MPI message buffers.*
- class [MPIUnpackBuffer](#)  
*Class for unpacking MPI message buffers.*
- class [MultilevelOptStrategy](#)  
*multiple models of varying fidelity.*
- class [NCSUOptimizer](#)  
*Wrapper class for the NCSU DIRECT optimization library.*
- class [NestedModel](#)  
*execution within every evaluation of the model.*
- struct [NI2Misc](#)  
*Auxiliary information passed to calcr and calcj via ur.*
- class [NL2SOLLeastSq](#)  
*Wrapper class for the NL2SOL nonlinear least squares library.*
- class [NLPQLPOptimizer](#)  
*Wrapper class for the NLPQLP optimization library, Version 2.0.*
- class [NLSSOLLeastSq](#)  
*Wrapper class for the NLSSOL nonlinear least squares library.*
- class [NonDAdaptImpSampling](#)  
*Class for the Adaptive Importance Sampling methods within DAKOTA.*
- class [NonDCubature](#)  
*integrals over uncorrelated uniforms.*
- class [NonDEvidence](#)  
*Class for the Dempster-Shafer Evidence Theory methods within DAKOTA/UQ.*
- class [NonDGlobalReliability](#)  
*Class for global reliability methods within DAKOTA/UQ.*
- class [NonDIncrLHSSampling](#)  
*Performs incremental LHS sampling for uncertainty quantification.*

- class [NonDIntegration](#)  
*numerical integration points for evaluation of expectation integrals*
- class [NonDLHSSampling](#)  
*Performs LHS and Monte Carlo sampling for uncertainty quantification.*
- class [NonDLocalReliability](#)  
*Class for the reliability methods within DAKOTA/UQ.*
- class [NonDPolynomialChaos](#)  
*quantification*
- class [NonDQuadrature](#)  
*normals/uniforms/exponentials/betas/gammas.*
- class [NonDReliability](#)  
*Base class for the reliability methods within DAKOTA/UQ.*
- class [NonDSampling](#)  
*NonDIncrLHSSampling, and NonDAdaptImpSampling.*
- class [NPSOLOptimizer](#)  
*Wrapper class for the NPSOL optimization library.*
- class [OrthogonalPolynomial](#)  
*Base class for the orthogonal polynomial class hierarchy.*
- class [OrthogPolyApproximation](#)  
*approximation).*
- class [ParallelLevel](#)  
*communicator partitioning.*
- class [ParallelConfiguration](#)  
*collectively identify a particular multilevel parallel configuration.*
- class [ParallelLibrary](#)  
*message passing within these levels.*
- class [ParamResponsePair](#)  
*evaluation id.*
- class [ParamStudy](#)  
*Class for vector, list, centered, and multidimensional parameter studies.*
- class [ProblemDescDB](#)

*The database containing information parsed from the DAKOTA input file.*

- class [PSUADEDesignCompExp](#)  
*Wrapper class for the PSUADE library.*
- class [RecastModel](#)  
*in order to recast the form of its inputs and/or outputs.*
- class [SingleMethodStrategy](#)  
*single model.*
- class [SingleModel](#)  
*variables into responses.*
- class [SNLLBase](#)  
*Base class for OPT++ optimization and least squares methods.*
- class [SNLLLeastSq](#)  
*Wrapper class for the OPT++ optimization library.*
- class [SNLLOptimizer](#)  
*Wrapper class for the OPT++ optimization library.*
- class [SOLBase](#)  
*Base class for Stanford SOL software.*
- class [SurfpackApproximation](#)  
*Interface between Surfpack and Dakota.*
- class [SurrBasedOptStrategy](#)  
*Strategy for provably-convergent surrogate-based optimization.*
- class [SurrogateModel](#)  
*Base class for surrogate models ([DataFitSurrModel](#) and [HierarchSurrModel](#)).*
- class [SysCallAnalysisCode](#)  
*simulations using system calls.*
- class [SysCallApplicInterface](#)  
*using system calls.*
- class [TANA3Approximation](#)  
*approximation (a multipoint approximation).*
- class [TaylorApproximation](#)  
*series (a local approximation).*

- class [VariablesUtil](#)  
*continuous and discrete variable domains.*

## Typedefs

- typedef double **Real**
- typedef [Vector](#)< Real > **RealVector**
- typedef [Vector](#)< int > **IntVector**
- typedef [BaseVector](#)< Real > **RealBaseVector**
- typedef [Matrix](#)< Real > **RealMatrix**
- typedef [Matrix](#)< int > **IntMatrix**
- typedef std::deque< bool > **BoolDeque**
- typedef [Array](#)< BoolDeque > **BoolDequeArray**
- typedef [Array](#)< Real > **RealArray**
- typedef [Array](#)< int > **IntArray**
- typedef [Array](#)< short > **ShortArray**
- typedef [Array](#)< size\_t > **SizetArray**
- typedef [Array](#)< [SizetArray](#) > **Sizet2DArray**
- typedef [Array](#)< [String](#) > **StringArray**
- typedef [Array](#)< [StringArray](#) > **String2DArray**
- typedef [Array](#)< [RealVector](#) > **RealVectorArray**
- typedef [Array](#)< [RealVectorArray](#) > **RealVector2DArray**
- typedef [Array](#)< [RealBaseVector](#) > **RealBaseVectorArray**
- typedef [Array](#)< [RealMatrix](#) > **RealMatrixArray**
- typedef [Array](#)< [Variables](#) > **VariablesArray**
- typedef [Array](#)< [Response](#) > **ResponseArray**
- typedef [Array](#)< [Model](#) > **ModelArray**
- typedef [Array](#)< [Iterator](#) > **IteratorArray**
- typedef [Array](#)< [ParamResponsePair](#) > **PRPArray**
- typedef [List](#)< bool > **BoolList**
- typedef [List](#)< int > **IntList**
- typedef [List](#)< size\_t > **SizetList**
- typedef [List](#)< Real > **RealList**
- typedef [List](#)< [String](#) > **StringList**
- typedef [List](#)< [RealVector](#) > **RealVectorList**
- typedef [List](#)< [Variables](#) > **VariablesList**
- typedef [List](#)< [Interface](#) > **InterfaceList**
- typedef [List](#)< [Response](#) > **ResponseList**
- typedef [List](#)< [Model](#) > **ModelList**
- typedef [List](#)< [Iterator](#) > **IteratorList**
- typedef [List](#)< [ParamResponsePair](#) > **PRPList**
- typedef std::set< int > **IntSet**
- typedef std::set< Real > **RealSet**
- typedef std::map< int, short > **IntShortMap**

- typedef std::map< int, int > **IntIntMap**
- typedef std::map< int, [RealVector](#) > **IntRealVectorMap**
- typedef std::map< int, [ActiveSet](#) > **IntActiveSetMap**
- typedef std::map< int, [Variables](#) > **IntVariablesMap**
- typedef std::map< int, [Response](#) > **IntResponseMap**
- typedef IntList::iterator **ILIter**
- typedef IntList::const\_iterator **ILCIter**
- typedef SisetList::iterator **StLIter**
- typedef SisetList::const\_iterator **StLCIter**
- typedef RealList::iterator **RLIter**
- typedef RealList::const\_iterator **RLCIter**
- typedef StringList::iterator **StringLIter**
- typedef StringList::const\_iterator **StringLCIter**
- typedef RealVectorList::iterator **RVLIter**
- typedef RealVectorList::const\_iterator **RVLCIter**
- typedef VariablesList::iterator **VarsLIter**
- typedef InterfaceList::iterator **InterfLIter**
- typedef ResponseList::iterator **RespLIter**
- typedef ModelList::iterator **ModelLIter**
- typedef IteratorList::iterator **IterLIter**
- typedef PRPList::iterator **PRPLIter**
- typedef [List](#)< [ParallelLevel](#) >::iterator **ParLevLIter**
- typedef [List](#)< [ParallelConfiguration](#) >::iterator **ParConfigLIter**
- typedef IntSet::iterator **ISIter**
- typedef IntSet::const\_iterator **ISCIter**
- typedef IntShortMap::iterator **IntShMIter**
- typedef IntIntMap::iterator **IntIntMIter**
- typedef IntIntMap::const\_iterator **IntIntMCIter**
- typedef IntRealVectorMap::iterator **IntRVMIter**
- typedef IntActiveSetMap::iterator **IntASMIter**
- typedef IntVariablesMap::iterator **IntVarsMIter**
- typedef IntVariablesMap::const\_iterator **IntVarsMCIter**
- typedef IntResponseMap::iterator **IntRespMIter**
- typedef IntResponseMap::const\_iterator **IntRespMCIter**
- typedef void(\*) **dl\_find\_optimum\_t** (void \*, Optimizer1 \*, char \*)
- typedef void(\*) **dl\_destructor\_t** (void \*\*)
- typedef double **Real**
- typedef int(\*) **start\_grid\_computing\_t** (char \*analysis\_driver\_script, char \*params\_file, char \*results\_file)
- typedef int(\*) **perform\_analysis\_t** (char \*iteration\_num)
- typedef int (\*) **get\_jobs\_completed\_t** ()
- typedef int(\*) **stop\_grid\_computing\_t** ()
- typedef unsigned char **u\_char**
- typedef unsigned short **u\_short**
- typedef unsigned int **u\_int**
- typedef unsigned long **u\_long**
- typedef long long **long\_long**
- typedef void(\*) **Calcrj** (int \*n, int \*p, Real \*x, int \*nf, Real \*r, int \*ui, void \*ur, Vf vf)
- typedef void(\*) **Vf** ()



## Enumerations

- enum { **OBJECTIVE, INEQUALITY\_CONSTRAINT, EQUALITY\_CONSTRAINT** }  
*define algebraic function types*
- enum { **SCALE\_NONE = 0, SCALE\_VALUE = 1, SCALE\_LOG = 2** }
- enum { **CDV, LINEAR, NONLIN, FN\_LSQ** }
- enum { **DISALLOW, TARGET, BOUNDS** }
- enum {  
**DESIGN, NORMAL, LOGNORMAL, UNIFORM,**  
**LOGUNIFORM, TRIANGULAR, EXPONENTIAL, BETA,**  
**GAMMA, GUMBEL, FRECHET, WEIBULL,**  
**STATE** }
- enum { **NO\_REFINE, IS, AIS, MMAIS** }
- enum { **PROBABILITIES, RELIABILITIES, GEN\_RELIABILITIES** }
- enum { **ORIGINAL\_OBJECTIVE, LAGRANGIAN\_OBJECTIVE, AUGMENTED\_LAGRANGIAN\_OBJECTIVE** }
- enum { **NO\_CONSTRAINTS, LINEARIZED\_CONSTRAINTS, ORIGINAL\_CONSTRAINTS** }
- enum { **NO\_RELAX, HOMOTOPY, COMPOSITE\_STEP** }
- enum { **PENALTY\_MERIT, ADAPTIVE\_PENALTY\_MERIT, LAGRANGIAN\_MERIT, AUGMENTED\_LAGRANGIAN\_MERIT** }
- enum { **FILTER, TR\_RATIO** }
- enum **LHSNames** {  
**LHS\_NORMAL, LHS\_LOGNORMAL, LHS\_UNIFORM, LHS\_LOGUNIFORM,**  
**LHS\_WEIBULL, LHS\_CONSTANT, LHS\_USERDEFINED** }
- enum {  
**N\_MEAN, N\_STD\_DEV, N\_LWR\_BND, N\_UPR\_BND,**  
**LN\_MEAN, LN\_STD\_DEV, LN\_ERR\_FACT, LN\_LWR\_BND,**  
**LN\_UPR\_BND, U\_LWR\_BND, U\_UPR\_BND, LU\_LWR\_BND,**  
**LU\_UPR\_BND, T\_MODE, T\_LWR\_BND, T\_UPR\_BND,**  
**E\_BETA, B\_ALPHA, B\_BETA, B\_LWR\_BND,**  
**B\_UPR\_BND, GA\_ALPHA, GA\_BETA, GU\_ALPHA,**  
**GU\_BETA, F\_ALPHA, F\_BETA, W\_ALPHA,**  
**W\_BETA** }
- enum { **PENALTY, AUG\_LAG, LAG** }
- enum { **EGRA\_X, EGRA\_U** }
- enum {  
**MV, AMV\_X, AMV\_U, AMV\_PLUS\_X,**  
**AMV\_PLUS\_U, TANA\_X, TANA\_U, NO\_APPROX** }
- enum { **BREITUNG, HOHENRACK, HONG** }
- enum {  
**UNCERTAIN, UNCERTAIN\_UNIFORM, ACTIVE, ACTIVE\_UNIFORM,**  
**ALL, ALL\_UNIFORM** }

- enum { **IGNORE\_RANKS, SET\_RANKS, GET\_RANKS, SET\_GET\_RANKS** }
- enum {  
**HERMITE, LEGENDRE, LAGUERRE, JACOBI,**  
**GENERALIZED\_LAGUERRE** }  
*variable spec order of normal, uniform, exponential, beta, gamma)*
- enum { **QUADRATURE, CUBATURE, POINT\_COLLOCATION, SAMPLING** }  
*solution approaches for calculating the polynomial chaos coefficients*
- enum **EvalType** { **NLFEvaluator, CONEvaluator** }  
*enumeration for the type of evaluator function*
- enum {  
**EMPTY, MERGED\_ALL, MIXED\_ALL, MERGED\_DISTINCT\_DESIGN,**  
**MERGED\_DISTINCT\_UNCERTAIN, MERGED\_DISTINCT\_STATE, MIXED\_DISTINCT\_-**  
**DESIGN, MIXED\_DISTINCT\_UNCERTAIN,**  
**MIXED\_DISTINCT\_STATE** }

## Functions

- bool **operator==** (const [AllVariables](#) &vars1, const [AllVariables](#) &vars2)  
*equality operator*
- [CommandShell](#) & **flush** ([CommandShell](#) &shell)  
*convenient shell manipulator function to "flush" the shell*
- bool **operator==** (const [ActiveSet](#) &set1, const [ActiveSet](#) &set2)  
*equality operator*
- [istream](#) & **operator>>** ([istream](#) &s, [ActiveSet](#) &set)  
*istream extraction operator for [ActiveSet](#). Calls read(istream&).*
- [ostream](#) & **operator<<** ([ostream](#) &s, const [ActiveSet](#) &set)  
*ostream insertion operator for [ActiveSet](#). Calls write(istream&).*
- [BiStream](#) & **operator>>** ([BiStream](#) &s, [ActiveSet](#) &set)  
*[BiStream](#) extraction operator for [ActiveSet](#). Calls read(BiStream&).*
- [BoStream](#) & **operator<<** ([BoStream](#) &s, const [ActiveSet](#) &set)  
*[BoStream](#) insertion operator for [ActiveSet](#). Calls write(BoStream&).*
- [MPIUnpackBuffer](#) & **operator>>** ([MPIUnpackBuffer](#) &s, [ActiveSet](#) &set)  
*Calls read(MPIUnpackBuffer&).*
- [MPIPackBuffer](#) & **operator<<** ([MPIPackBuffer](#) &s, const [ActiveSet](#) &set)

*MPIPackBuffer* insertion operator for *ActiveSet*. Calls `write(MPIPackBuffer&)`.

- `bool operator!= (const ActiveSet &set1, const ActiveSet &set2)`  
*inequality operator*
- `template<class T> istream & operator>> (istream &s, Array< T > &data)`  
*global istream extraction operator for Vector*
- `template<class T> ostream & operator<< (ostream &s, const Array< T > &data)`  
*global ostream insertion operator for Array*
- `template<class T> BiStream & operator>> (BiStream &s, Array< T > &data)`  
*global BiStream extraction operator for Array*
- `template<class T> BoStream & operator<< (BoStream &s, const Array< T > &data)`  
*global BoStream insertion operator for Array*
- `template<class T> MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, Array< T > &data)`  
*global MPIUnpackBuffer extraction operator for Array*
- `template<class T> MPIPackBuffer & operator<< (MPIPackBuffer &s, const Array< T > &data)`  
*global MPIPackBuffer insertion operator for Array*
- `istream & operator>> (istream &s, Constraints &con)`  
*istream extraction operator for Constraints*
- `ostream & operator<< (ostream &s, const Constraints &con)`  
*ostream insertion operator for Constraints*
- `bool interface_id_compare (const Interface &interface, const void *id)`  
*global comparison function for Interface*
- `bool method_id_compare (const Iterator &iterator, const void *id)`  
*global comparison function for Iterator*
- `template<class T> ostream & operator<< (ostream &s, const List< T > &data)`  
*global ostream insertion operator for List*
- `template<class T> MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, List< T > &data)`  
*global MPIUnpackBuffer extraction operator for List*
- `template<class T> MPIPackBuffer & operator<< (MPIPackBuffer &s, const List< T > &data)`  
*global MPIPackBuffer insertion operator for List*
- `template<class T> istream & operator>> (istream &s, Matrix< T > &data)`  
*global istream extraction operator for Matrix*

- `template<class T> ostream & operator<<` (`ostream &s`, `const Matrix< T > &data`)  
*global ostream insertion operator for [Matrix](#)*
- `template<class T> MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `Matrix< T > &data`)  
*global [MPIUnpackBuffer](#) extraction operator for [Matrix](#)*
- `template<class T> MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const Matrix< T > &data`)  
*global [MPIPackBuffer](#) insertion operator for [Matrix](#)*
- `bool model_id_compare` (`const Model &model`, `const void *id`)  
*global comparison function for [Model](#)*
- `bool operator==` (`const ResponseRep &rep1`, `const ResponseRep &rep2`)  
*equality operator*
- `bool responses_id_compare` (`const Response &resp`, `const void *id`)  
*global comparison function for [Response](#)*
- `istream & operator>>` (`istream &s`, `Response &response`)  
*istream extraction operator for [Response](#). Calls `read(istream&)`.*
- `ostream & operator<<` (`ostream &s`, `const Response &response`)  
*ostream insertion operator for [Response](#). Calls `write(ostream&)`.*
- `BiStream & operator>>` (`BiStream &s`, `Response &response`)  
*[BiStream](#) extraction operator for [Response](#). Calls `read(BiStream&)`.*
- `BoStream & operator<<` (`BoStream &s`, `const Response &response`)  
*[BoStream](#) insertion operator for [Response](#). Calls `write(BoStream&)`.*
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `Response &response`)  
*`read(MPIUnpackBuffer&)`.*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const Response &response`)  
*[MPIPackBuffer](#) insertion operator for [Response](#). Calls `write(MPIPackBuffer&)`.*
- `bool operator==` (`const Response &resp1`, `const Response &resp2`)  
*equality operator*
- `bool operator!=` (`const Response &resp1`, `const Response &resp2`)  
*inequality operator*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const String &data`)  
*Reads [String](#) from buffer.*

- **MPIUnpackBuffer & operator>>** (MPIUnpackBuffer &s, String &data)  
*Writes String to buffer.*
- **String operator+** (const String &s1, const String &s2)  
*Concatenate two Strings and return the resulting String.*
- **String operator+** (const char \*s1, const String &s2)  
*Append a String to a char\* and return the resulting String.*
- **String operator+** (const String &s1, const char \*s2)  
*Append a char\* to a String and return the resulting String.*
- **String operator+** (const DAKOTA\_BASE\_STRING &s1, const String &s2)  
*Append a String to a DAKOTA\_BASE\_STRING and return the resulting String.*
- **String operator+** (const String &s1, const DAKOTA\_BASE\_STRING &s2)  
*Append a DAKOTA\_BASE\_STRING to a String and return the resulting String.*
- **String toUpper** (const String &str)  
*Returns a String converted to upper case. Calls String::upper().*
- **String toLower** (const String &str)  
*Returns a String converted to lower case. Calls String::lower().*
- **bool operator==** (const Variables &vars1, const Variables &vars2)  
*equality operator*
- **bool variables\_id\_compare** (const Variables &vars, const void \*id)  
*global comparison function for Variables*
- **istream & operator>>** (istream &s, Variables &vars)  
*istream extraction operator for Variables.*
- **ostream & operator<<** (ostream &s, const Variables &vars)  
*ostream insertion operator for Variables.*
- **BiStream & operator>>** (BiStream &s, Variables &vars)  
*BiStream extraction operator for Variables.*
- **BoStream & operator<<** (BoStream &s, const Variables &vars)  
*BoStream insertion operator for Variables.*
- **MPIUnpackBuffer & operator>>** (MPIUnpackBuffer &s, Variables &vars)  
*MPIUnpackBuffer extraction operator for Variables.*
- **MPIPackBuffer & operator<<** (MPIPackBuffer &s, const Variables &vars)

*MPIPackBuffer* insertion operator for *Variables*.

- `bool operator!= (const Variables &vars1, const Variables &vars2)`  
*inequality operator*
- `template<class T> istream & operator>> (istream &s, Vector< T > &data)`  
*global istream extraction operator for Vector*
- `template<class T> ostream & operator<< (ostream &s, const Vector< T > &data)`  
*global ostream insertion operator for Vector*
- `template<class T> MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, Vector< T > &data)`  
*global MPIUnpackBuffer extraction operator for Vector*
- `template<class T> MPIPackBuffer & operator<< (MPIPackBuffer &s, const Vector< T > &data)`  
*global MPIPackBuffer insertion operator for Vector*
- `bool operator== (const RealVector &drv1, const RealVector &drv2)`  
*equality operator for RealVector*
- `bool operator== (const IntVector &div1, const IntVector &div2)`  
*equality operator for IntVector*
- `bool operator== (const IntArray &dia1, const IntArray &dia2)`  
*equality operator for IntArray*
- `bool operator== (const ShortArray &dsa1, const ShortArray &dsa2)`  
*equality operator for ShortArray*
- `bool operator== (const RealMatrix &drm1, const RealMatrix &drm2)`  
*equality operator for RealMatrix*
- `bool operator== (const RealMatrixArray &drma1, const RealMatrixArray &drma2)`  
*equality operator for RealMatrixArray*
- `bool operator== (const StringArray &dsa1, const StringArray &dsa2)`  
*equality operator for StringArray*
- `void copy_data (const NEWMAT::ColumnVector &cv, RealBaseVector &drbv)`  
*copy NEWMAT::ColumnVector to RealBaseVector*
- `void copy_data (const RealBaseVector &drbv, NEWMAT::ColumnVector &cv)`  
*copy RealBaseVector to NEWMAT::ColumnVector*
- `void copy_data (const RealArray &dra, NEWMAT::ColumnVector &cv)`  
*copy RealArray to NEWMAT::ColumnVector*

- void `copy_data` (const [RealMatrix](#) &drm, [NEWMAT::SymmetricMatrix](#) &sm)  
*copy RealMatrix to NEWMAT::SymmetricMatrix*
- void `copy_data` (const [RealMatrix](#) &drm, [NEWMAT::Matrix](#) &m)  
*copy RealMatrix to NEWMAT::Matrix*
- void `copy_data` (const [Epetra\\_SerialDenseVector](#) &psdv, [RealVector](#) &drv)  
*copy Epetra\_SerialDenseVector to RealVector*
- void `copy_data` (const [Epetra\\_SerialDenseVector](#) &psdv, [RealBaseVector](#) &drbv)  
*copy Epetra\_SerialDenseVector to RealBaseVector*
- void `copy_data` (const [Epetra\\_SerialDenseMatrix](#) &psdm, [RealMatrix](#) &drm)  
*copy Epetra\_SerialDenseMatrix to RealMatrix*
- void `copy_data` (const [Epetra\\_SerialSymDenseMatrix](#) &ps sdm, [RealMatrix](#) &drm)  
*copy Epetra\_SerialSymDenseMatrix to RealMatrix*
- void `copy_data` (const [RealVector](#) &drv, [Epetra\\_SerialDenseVector](#) &psdv)  
*copy RealVector to Epetra\_SerialDenseVector*
- void `copy_data` (const [RealArray](#) &dra, [Epetra\\_SerialDenseVector](#) &psdv)  
*copy RealArray to Epetra\_SerialDenseVector*
- void `copy_data` (const [RealBaseVector](#) &drbv, [Epetra\\_SerialDenseVector](#) &psdv)  
*copy RealBaseVector to Epetra\_SerialDenseVector*
- void `copy_data` (const [Real](#) \*ptr, const int ptr\_len, [Epetra\\_SerialDenseVector](#) &psdv)  
*copy Real\* to Epetra\_SerialDenseVector*
- void `copy_data` (const [RealMatrix](#) &drm, [Epetra\\_SerialDenseMatrix](#) &psdm)  
*copy RealMatrix to Epetra\_SerialDenseMatrix*
- void `copy_data` (const [RealMatrix](#) &drm, [Epetra\\_SerialSymDenseMatrix](#) &ps sdm)  
*copy RealMatrix to Epetra\_SerialSymDenseMatrix*
- void `copy_data` (const [RealMatrixArray](#) &drma, [Array](#)< [Epetra\\_SerialSymDenseMatrix](#) > &ps sdm)  
*copy RealMatrixArray to Array<Epetra\_SerialSymDenseMatrix>*
- void `copy_data` (const [NEWMAT::ColumnVector](#) &cv, [Epetra\\_SerialDenseVector](#) &psdv)  
*copy NEWMAT::ColumnVector to Epetra\_SerialDenseVector*
- void `copy_data` (const [DDaceSamplePoint](#) &dsp, [RealVector](#) &drva)  
*copy DDACE point to RealVector*

- void `copy_data` (const std::vector< DDaceSamplePoint > &dspa, [RealVectorArray](#) &drva)  
*copy DDACE point array to RealVectorArray*
- void `copy_data` (const std::vector< DDaceSamplePoint > &dspa, Real \*ptr, const int ptr\_len)  
*copy DDACE point array to Real\**
- bool `operator!=` (const [RealVector](#) &drv1, const [RealVector](#) &drv2)  
*inequality operator for RealVector*
- bool `operator!=` (const [IntVector](#) &div1, const [IntVector](#) &div2)  
*inequality operator for IntVector*
- bool `operator!=` (const [IntArray](#) &dia1, const [IntArray](#) &dia2)  
*inequality operator for IntArray*
- bool `operator!=` (const [ShortArray](#) &dsa1, const [ShortArray](#) &dsa2)  
*inequality operator for ShortArray*
- bool `operator!=` (const [RealMatrix](#) &drm1, const [RealMatrix](#) &drm2)  
*inequality operator for RealMatrix*
- bool `operator!=` (const [RealMatrixArray](#) &drma1, const [RealMatrixArray](#) &drma2)  
*inequality operator for RealMatrixArray*
- bool `operator!=` (const [StringArray](#) &dsa1, const [StringArray](#) &dsa2)  
*inequality operator for StringArray*
- void `build_label` ([String](#) &label, const [String](#) &root\_label, size\_t tag)  
*create a label by appending a numerical tag to the root\_label*
- void `build_labels` ([StringArray](#) &label\_array, const [String](#) &root\_label)  
*label\_array. Uses `build_label()`.*
- void `build_labels_partial` ([StringArray](#) &label\_array, const [String](#) &root\_label, size\_t start\_index, size\_t num\_items)  
*of entries in label\_array. Uses `build_label()`.*
- template<class T> ostream & `operator<<` (ostream &s, const std::set< T > &data)  
*global ostream insertion operator for std::set*
- template<class T> [MPIUnpackBuffer](#) & `operator>>` ([MPIUnpackBuffer](#) &s, std::set< T > &data)  
*global `MPIUnpackBuffer` extraction operator for std::set*
- template<class T> [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &s, const std::set< T > &data)  
*global `MPIPackBuffer` insertion operator for std::set*



- template<class T> void [copy\\_data](#) (const T \*ptr, const int ptr\_len, [Vector](#)< T > &dv)  
*copy T\* to Vector<T>*
- template<class T> void [copy\\_data](#) (const T \*ptr, const int ptr\_len, [BaseVector](#)< T > &dbv)  
*copy T\* to BaseVector<T>*
- template<class T> void [copy\\_data](#) (const T \*ptr, const int ptr\_len, const [String](#) &ptr\_type, [Matrix](#)< T > &dm, size\_t nr, size\_t nc)  
*copy T\* to Matrix<T>*
- template<class T> void [copy\\_data](#) (const T \*ptr, const int ptr\_len, const [String](#) &ptr\_type, [Array](#)< [Vector](#)< T > > &dva, size\_t num\_vec, size\_t vec\_len)  
*copy T\* to Array<Vector<T> >*
- template<class T> void [copy\\_data](#) (const [Vector](#)< T > &dv, T \*ptr, const int ptr\_len)  
*copy Vector<T> to T\**
- template<class T> void [copy\\_data](#) (const [BaseVector](#)< T > &dbv, T \*ptr, const int ptr\_len)  
*copy BaseVector<T> to T\**
- template<class T> void [copy\\_data](#) (const [Matrix](#)< T > &dm, T \*ptr, const int ptr\_len, const [String](#) &ptr\_type)  
*copy Matrix<T> to T\**
- template<class T> void [copy\\_data](#) (const [Array](#)< [Vector](#)< T > > &dva, T \*ptr, const int ptr\_len, const [String](#) &ptr\_type)  
*copy Array<Vector<T> > to T\**
- template<class T> void [copy\\_data](#) (const [Vector](#)< T > &dv, [Matrix](#)< T > &dm, size\_t nr, size\_t nc)  
*copy Vector<T> to Matrix<T>*
- template<class T> void [copy\\_data](#) (const [Vector](#)< T > &dv, [Array](#)< [Vector](#)< T > > &dva, size\_t num\_vec, size\_t vec\_len)  
*copy Vector<T> to Array<Vector<T> >*
- template<class T> void [copy\\_data](#) (const [Array](#)< T > &da, [Vector](#)< T > &dv)  
*copy Array<T> to Vector<T>*
- template<class T> void [copy\\_data](#) (const [BaseVector](#)< T > &dbv, [Vector](#)< T > &dv)  
*copy BaseVector<T> to Vector<T>*
- template<class T> void [copy\\_data](#) (const [List](#)< T > &dl, [Array](#)< T > &da)  
*copy List<T> to Array<T>*
- template<class T> void [copy\\_data](#) (const [List](#)< T > &dl, [Array](#)< [Array](#)< T > > &d2a, size\_t num\_a, size\_t a\_len)

*copy List<T> to Array<Array<T> >*

- template<class T> void `copy_data` (const `Array< Array< T > >` &d2a, `Array< T >` &da)  
*copy Array<Array<T> > to Array<T> (unroll 2D array into 1D array)*
- template<class T> void `copy_data_partial` (const `Vector< T >` &dv1, size\_t start\_index, size\_t num\_items, `Vector< T >` &dv2)  
*copy portion of first Vector<T> to all of second Vector<T>*
- template<class T> void `copy_data_partial` (const `Vector< T >` &dv1, `Vector< T >` &dv2, size\_t start\_index)  
*copy all of first Vector<T> to portion of second Vector<T>*
- template<class T> void `copy_data_partial` (const `Vector< T >` &dv1, size\_t start\_index1, size\_t num\_items, `Vector< T >` &dv2, size\_t start\_index2)  
*copy portion of first Vector<T> to portion of second Vector<T>*
- template<class T> void `copy_data_partial` (const `Array< T >` &da1, size\_t start\_index, size\_t num\_items, `Array< T >` &da2)  
*copy portion of first Array<T> to all of second Array<T>*
- template<class T> void `copy_data_partial` (const `Array< T >` &da1, `Array< T >` &da2, size\_t start\_index)  
*copy all of first Array<T> to portion of second Array<T>*
- template<class T> void `copy_data_partial` (const `Array< T >` &da1, size\_t start\_index1, size\_t num\_items, `Array< T >` &da2, size\_t start\_index2)  
*copy portion of first Array<T> to portion of second Array<T>*
- template<class T> void `copy_data` (const `utilib::NumArray< T >` &na, `Vector< T >` &dv)  
*copy utilib::NumArray<T> to Vector<T>*
- template<class T> void `copy_data` (const `Vector< T >` &dv, `utilib::NumArray< T >` &na)  
*copy Vector<T> to utilib::NumArray<T>*
- template<class T> void `copy_data` (const `utilib::NumArray< T >` &na, `Array< T >` &da)  
*copy utilib::NumArray<T> to Array<T>*
- template<class T> void `copy_data` (const `List< T >` &dl, `utilib::NumArray< T >` &na)  
*copy List<T> to utilib::NumArray<T>*
- template<class T> void `copy_data` (const `TNT::Vector< T >` &tntv, `Vector< T >` &dv)  
*copy TNT::Vector<T> to Vector<T>*
- template<class T> void `copy_data` (const `Vector< T >` &dv, `TNT::Vector< T >` &tntv)  
*copy Vector<T> to TNT::Vector<T>*

- `template<class T> void copy_data (const T *ptr, const int ptr_len, TNT::Vector< T > &tntv)`  
*copy T\* to TNT::Vector<T>*
- `template<class T> void copy_data (const Matrix< T > &dm, TNT::Matrix< T > &tntm)`  
*copy Matrix<T> to TNT::Matrix<T>*
- `bool data_interface_id_compare (const DataInterface &di, const void *id)`  
*global comparison function for DataInterface*
- `MPIPackBuffer & operator<< (MPIPackBuffer &s, const DataInterface &data)`  
*MPIPackBuffer insertion operator for DataInterface.*
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, DataInterface &data)`  
*MPIUnpackBuffer extraction operator for DataInterface.*
- `ostream & operator<< (ostream &s, const DataInterface &data)`  
*ostream insertion operator for DataInterface*
- `bool data_method_id_compare (const DataMethod &dm, const void *id)`  
*global comparison function for DataMethod*
- `MPIPackBuffer & operator<< (MPIPackBuffer &s, const DataMethod &data)`  
*MPIPackBuffer insertion operator for DataMethod.*
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, DataMethod &data)`  
*MPIUnpackBuffer extraction operator for DataMethod.*
- `ostream & operator<< (ostream &s, const DataMethod &data)`  
*ostream insertion operator for DataMethod*
- `bool data_model_id_compare (const DataModel &dm, const void *id)`  
*global comparison function for DataModel*
- `MPIPackBuffer & operator<< (MPIPackBuffer &s, const DataModel &data)`  
*MPIPackBuffer insertion operator for DataModel.*
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, DataModel &data)`  
*MPIUnpackBuffer extraction operator for DataModel.*
- `ostream & operator<< (ostream &s, const DataModel &data)`  
*ostream insertion operator for DataModel*
- `bool data_responses_id_compare (const DataResponses &dr, const void *id)`  
*global comparison function for DataResponses*
- `MPIPackBuffer & operator<< (MPIPackBuffer &s, const DataResponses &data)`

- MPIPackBuffer* insertion operator for *DataResponses*.
- [MPIUnpackBuffer](#) & [operator>>](#) ([MPIUnpackBuffer](#) &s, [DataResponses](#) &data)  
*MPIUnpackBuffer* extraction operator for *DataResponses*.
  - [ostream](#) & [operator<<](#) ([ostream](#) &s, const [DataResponses](#) &data)  
*ostream* insertion operator for *DataResponses*
  - [MPIPackBuffer](#) & [operator<<](#) ([MPIPackBuffer](#) &s, const [DataStrategy](#) &data)  
*MPIPackBuffer* insertion operator for *DataStrategy*.
  - [MPIUnpackBuffer](#) & [operator>>](#) ([MPIUnpackBuffer](#) &s, [DataStrategy](#) &data)  
*MPIUnpackBuffer* extraction operator for *DataStrategy*.
  - [ostream](#) & [operator<<](#) ([ostream](#) &s, const [DataStrategy](#) &data)  
*ostream* insertion operator for *DataStrategy*
  - [bool](#) [data\\_variables\\_id\\_compare](#) (const [DataVariables](#) &dv, const void \*id)  
*global comparison function for DataVariables*
  - [MPIPackBuffer](#) & [operator<<](#) ([MPIPackBuffer](#) &s, const [DataVariables](#) &data)  
*MPIPackBuffer* insertion operator for *DataVariables*.
  - [MPIUnpackBuffer](#) & [operator>>](#) ([MPIUnpackBuffer](#) &s, [DataVariables](#) &data)  
*MPIUnpackBuffer* extraction operator for *DataVariables*.
  - [ostream](#) & [operator<<](#) ([ostream](#) &s, const [DataVariables](#) &data)  
*ostream* insertion operator for *DataVariables*
  - [int](#) [salinas\\_main](#) ([int](#) argc, [char](#) \*argv[], [MPI\\_Comm](#) \*comm)  
*subroutine interface to SALINAS simulation code*
  - [bool](#) [operator==](#) (const [DistinctVariables](#) &vars1, const [DistinctVariables](#) &vars2)  
*equality operator*
  - [int](#) [dlsolver\\_option](#) ([Opt\\_Info](#) \*)
  - [void](#) [abort\\_handler](#) ([int](#) code)  
*global function which handles serial or parallel aborts*
  - [RealVector](#) const \* [continuous\\_lower\\_bounds](#) ([Optimizer1](#) \*o)
  - [RealVector](#) const \* [continuous\\_upper\\_bounds](#) ([Optimizer1](#) \*o)
  - [RealVector](#) const \* [nonlinear\\_ineq\\_constraint\\_lower\\_bounds](#) ([Optimizer1](#) \*o)
  - [RealVector](#) const \* [nonlinear\\_ineq\\_constraint\\_upper\\_bounds](#) ([Optimizer1](#) \*o)
  - [RealVector](#) const \* [nonlinear\\_eq\\_constraint\\_targets](#) ([Optimizer1](#) \*o)
  - [RealVector](#) const \* [linear\\_ineq\\_constraint\\_lower\\_bounds](#) ([Optimizer1](#) \*o)
  - [RealVector](#) const \* [linear\\_ineq\\_constraint\\_upper\\_bounds](#) ([Optimizer1](#) \*o)

- [RealVector](#) const \* **linear\_eq\_constraint\_targets** (Optimizer1 \*o)
- [RealMatrix](#) const \* **linear\_ineq\_constraint\_coeffs** (Optimizer1 \*o)
- [RealMatrix](#) const \* **linear\_eq\_constraint\_coeffs** (Optimizer1 \*o)
- [RealVector](#) \* **bestFunctions** (Optimizer1 \*o)
- void **ComputeResponses** (Optimizer1 \*o, int mode, int n, double \*x)
- void **GetFuncs** (Optimizer1 \*o, int m0, int m1, double \*f)
- void **GetGrads** (Optimizer1 \*o, int m0, int m1, int n, int is, int js, double \*g)
- void **GetContVars** (Optimizer1 \*o, int n, double \*x)
- void **SetBestContVars** (Optimizer1 \*o, int n, double \*x)
- void \* **dl\_constructor** (Optimizer1 \*, Dakota\_funcs \*, dl\_find\_optimum\_t \*, dl\_destructor\_t \*)
- static [RealVector](#) const \* **continuous\_lower\_bounds1** (Optimizer1 \*o)
- static [RealVector](#) const \* **continuous\_upper\_bounds1** (Optimizer1 \*o)
- static [RealVector](#) const \* **nonlinear\_ineq\_constraint\_lower\_bounds1** (Optimizer1 \*o)
- static [RealVector](#) const \* **nonlinear\_ineq\_constraint\_upper\_bounds1** (Optimizer1 \*o)
- static [RealVector](#) const \* **nonlinear\_eq\_constraint\_targets1** (Optimizer1 \*o)
- static [RealVector](#) const \* **linear\_ineq\_constraint\_lower\_bounds1** (Optimizer1 \*o)
- static [RealVector](#) const \* **linear\_ineq\_constraint\_upper\_bounds1** (Optimizer1 \*o)
- static [RealVector](#) const \* **linear\_eq\_constraint\_targets1** (Optimizer1 \*o)
- static [RealMatrix](#) const \* **linear\_eq\_constraint\_coeffs1** (Optimizer1 \*o)
- static [RealMatrix](#) const \* **linear\_ineq\_constraint\_coeffs1** (Optimizer1 \*o)
- static [RealVector](#) \* **bestFunctions1** (Optimizer1 \*o)
- static void **ComputeResponses1** (Optimizer1 \*o, int mode, int n, double \*x)
- static void **GetFuncs1** (Optimizer1 \*o, int m0, int m1, double \*f)
- static void **GetGrads1** (Optimizer1 \*o, int m0, int m1, int n, int is, int js, double \*g)
- static void **GetContVars1** (Optimizer1 \*o, int n, double \*x)
- static void **SetBestContVars1** (Optimizer1 \*o, int n, double \*x)
- Real **getdist** ([RealVector](#) &x1, [RealVector](#) &x2)
- Real **mindist** ([RealVector](#) &x, [RealMatrix](#) &xset, int except)
- Real **mindistindx** ([RealVector](#) &x, [RealMatrix](#) &xset, [IntVector](#) &indx)
- Real **getRmax** ([RealMatrix](#) &xset)
- int **Ifinite** (const Real &x)
- template<typename T> T **abort\_handler\_t** (int code)
- int **start\_grid\_computing** (char \*analysis\_driver\_script, char \*params\_file, char \*results\_file)
- int **stop\_grid\_computing** ()
- int **perform\_analysis** (char \*iteration\_num)
- template<typename T> string **asstring** (const T &val)  
*Creates a string from the argument val using an ostream.*
- bool **operator==** (const [MergedVariables](#) &vars1, const [MergedVariables](#) &vars2)  
*equality operator*
- **PACKBUF** (int, MPI\_INT)
- **UNPACKBUF** (int, MPI\_INT)
- **PACKSIZE** (int, MPI\_INT)
- [MPIPackBuffer](#) & **operator<<** ([MPIPackBuffer](#) &buff, const int &data)  
*insert an int*

- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const u_int &data`)  
*insert a u\_int*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const long &data`)  
*insert a long*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const u_long &data`)  
*insert a u\_long*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const short &data`)  
*insert a short*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const u_short &data`)  
*insert a u\_short*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const char &data`)  
*insert a char*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const u_char &data`)  
*insert a u\_char*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const double &data`)  
*insert a double*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const float &data`)  
*insert a float*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &buff`, `const bool &data`)  
*insert a bool*
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `int &data`)  
*extract an int*
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `u_int &data`)  
*extract a u\_int*
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `long &data`)  
*extract a long*
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `u_long &data`)  
*extract a u\_long*
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &buff`, `short &data`)  
*extract a short*

- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, u_short &data)`  
*extract a u\_short*
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, char &data)`  
*extract a char*
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, u_char &data)`  
*extract a u\_char*
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, double &data)`  
*extract a double*
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, float &data)`  
*extract a float*
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, bool &data)`  
*extract a bool*
- `int MPIPackSize (const int &data, const int num=1)`  
*return packed size of an int*
- `int MPIPackSize (const u_int &data, const int num=1)`  
*return packed size of a u\_int*
- `int MPIPackSize (const long &data, const int num=1)`  
*return packed size of a long*
- `int MPIPackSize (const u_long &data, const int num=1)`  
*return packed size of a u\_long*
- `int MPIPackSize (const short &data, const int num=1)`  
*return packed size of a short*
- `int MPIPackSize (const u_short &data, const int num=1)`  
*return packed size of a u\_short*
- `int MPIPackSize (const char &data, const int num=1)`  
*return packed size of a char*
- `int MPIPackSize (const u_char &data, const int num=1)`  
*return packed size of a u\_char*
- `int MPIPackSize (const double &data, const int num=1)`  
*return packed size of a double*
- `int MPIPackSize (const float &data, const int num=1)`

*return packed size of a float*

- int [MPIPackSize](#) (const bool &data, const int num=1)  
*return packed size of a bool*
- void [dn2f\\_](#) (int \*n, int \*p, Real \*x, Calcrlj, int \*iv, int \*liv, int \*lv, Real \*v, int \*ui, void \*ur, Vf)
- void [dn2fb\\_](#) (int \*n, int \*p, Real \*x, Real \*b, Calcrlj, int \*iv, int \*liv, int \*lv, Real \*v, int \*ui, void \*ur, Vf)
- void [dn2g\\_](#) (int \*n, int \*p, Real \*x, Calcrlj, Calcrlj, int \*iv, int \*liv, int \*lv, Real \*v, int \*ui, void \*ur, Vf)
- void [dn2gb\\_](#) (int \*n, int \*p, Real \*x, Real \*b, Calcrlj, Calcrlj, int \*iv, int \*liv, int \*lv, Real \*v, int \*ui, void \*ur, Vf)
- void [divset\\_](#) (int \*, int \*, int \*, int \*, Real \*)
- double [dr7mdc\\_](#) (int \*)
- double [rnum1](#) (void)
- double [rnum2](#) (void)
- bool [operator==](#) (const [ParamResponsePair](#) &pair1, const [ParamResponsePair](#) &pair2)  
*equality operator*
- bool [vars\\_set\\_compare](#) (const [ParamResponsePair](#) &database\_pr, const void \*search\_pr)  
*search function for a particular [ParamResponsePair](#) within a [List](#)*
- bool [eval\\_id\\_compare](#) (const [ParamResponsePair](#) &pair, const void \*id)  
*search function for a particular [ParamResponsePair](#) within a [List](#)*
- bool [eval\\_id\\_sort\\_fn](#) (const [ParamResponsePair](#) &pr1, const [ParamResponsePair](#) &pr2)  
*sort function for [ParamResponsePair](#)*
- istream & [operator>>](#) (istream &s, [ParamResponsePair](#) &pair)  
*istream extraction operator for [ParamResponsePair](#)*
- ostream & [operator<<](#) (ostream &s, const [ParamResponsePair](#) &pair)  
*ostream insertion operator for [ParamResponsePair](#)*
- [BiStream](#) & [operator>>](#) ([BiStream](#) &s, [ParamResponsePair](#) &pair)  
*[BiStream](#) extraction operator for [ParamResponsePair](#).*
- [BoStream](#) & [operator<<](#) ([BoStream](#) &s, const [ParamResponsePair](#) &pair)  
*[BoStream](#) insertion operator for [ParamResponsePair](#).*
- [MPIUnpackBuffer](#) & [operator>>](#) ([MPIUnpackBuffer](#) &s, [ParamResponsePair](#) &pair)  
*[MPIUnpackBuffer](#) extraction operator for [ParamResponsePair](#).*
- [MPIPackBuffer](#) & [operator<<](#) ([MPIPackBuffer](#) &s, const [ParamResponsePair](#) &pair)  
*[MPIPackBuffer](#) insertion operator for [ParamResponsePair](#).*
- bool [operator!=](#) (const [ParamResponsePair](#) &pair1, const [ParamResponsePair](#) &pair2)  
*inequality operator*



- void [print\\_restart](#) (int argc, char \*\*argv, [String](#) print\_dest)  
*print a restart file*
- void [print\\_restart\\_tabular](#) (int argc, char \*\*argv, [String](#) print\_dest)  
*print a restart file (tabular format)*
- void [read\\_neutral](#) (int argc, char \*\*argv)  
*read a restart file (neutral file format)*
- void [repair\\_restart](#) (int argc, char \*\*argv, [String](#) identifier\_type)  
*repair a restart file by removing corrupted evaluations*
- void [concatenate\\_restart](#) (int argc, char \*\*argv)  
*concatenate multiple restart files*

## Variables

- [ProblemDescDB dummy\\_db](#)  
*dummy [ProblemDescDB](#) object used for mandatory reference initialization when a real [ProblemDescDB](#) instance is unavailable*
- [ParallelLibrary dummy\\_lib](#)  
*dummy [ParallelLibrary](#) object used for mandatory reference initialization when a real [ParallelLibrary](#) instance is unavailable*
- [ProblemDescDB dummy\\_db](#)  
*dummy [ProblemDescDB](#) object used for mandatory reference initialization when a real [ProblemDescDB](#) instance is unavailable*
- [Graphics dakota\\_graphics](#)  
*the global [Dakota::Graphics](#) object used by strategies, models, and approximations*
- [Interface dummy\\_interface](#)  
*dummy [Interface](#) object used for mandatory reference initialization or default virtual function return by reference when a real [Interface](#) instance is unavailable*
- [Model dummy\\_model](#)  
*dummy [Model](#) object used for mandatory reference initialization or default virtual function return by reference when a real [Model](#) instance is unavailable*
- [Iterator dummy\\_iterator](#)  
*dummy [Iterator](#) object used for mandatory reference initialization or default virtual function return by reference when a real [Iterator](#) instance is unavailable*

- [ProblemDescDB dummy\\_db](#)  
*dummy [ProblemDescDB](#) object used for mandatory reference initialization when a real [ProblemDescDB](#) instance is unavailable*
- [ParallelLibrary dummy\\_lib](#)  
*dummy [ParallelLibrary](#) object used for mandatory reference initialization when a real [ParallelLibrary](#) instance is unavailable*
- `Dakota_funcs * DF`
- `Dakota_funcs DakFuncs0`
- `ostream * dakota_cout = &cout`  
*DAKOTA stdout initially points to cout, but may be redirected to a tagged ofstream if there are concurrent iterators.*
- `ostream * dakota_cerr = &cerr`  
*DAKOTA stderr initially points to cerr, but may be redirected to a tagged ofstream if there are concurrent iterators.*
- [PRPList data\\_pairs](#)  
*list of all parameter/response pairs.*
- [BoStream write\\_restart](#)  
*the restart binary output stream (doesn't really need to be global anymore except for [abort\\_handler\(\)](#)).*
- [Graphics dakota\\_graphics](#)  
*the global [Dakota::Graphics](#) object used by strategies, models, and approximations*
- `int write_precision = 10`  
*used in ostream data output functions ([restart\\_util.C](#) overrides this default value)*
- [ParallelLibrary dummy\\_lib \(0\)](#)  
*dummy [ParallelLibrary](#) object used for mandatory reference initialization when a real [ParallelLibrary](#) instance is unavailable*
- [ProblemDescDB dummy\\_db](#)  
*dummy [ProblemDescDB](#) object used for mandatory reference initialization when a real [ProblemDescDB](#) instance is unavailable*
- `int mc_ptr_int = 0`  
*global pointer for ModelCenter API*
- `ostream * dakota_cout`  
*DAKOTA stdout initially points to cout, but may be redirected to a tagged ofstream if there are concurrent iterators.*
- `ostream * dakota_cerr`  
*DAKOTA stderr initially points to cerr, but may be redirected to a tagged ofstream if there are concurrent iterators.*
- `int write_precision`

*used in ostream data output functions (`restart_util.C` overrides this default value)*

- `int mc_ptr_int`  
*global pointer for ModelCenter API*
- `FILE * yyin`
- `const int LHS_NONRANDOM = 0`
- `const int LHS_RANDOM = 1`
- `Dakota::GSL_Singleton GSL_RNG`
- `ParallelLibrary dummy_lib`  
*dummy `ParallelLibrary` object used for mandatory reference initialization when a real `ParallelLibrary` instance is unavailable*
- `const int LARGE_SCALE = 100`
- `const size_t _NPOS = ~(size_t)0`  
*special value returned by `index()` when entry not found*

### 7.1.1 Detailed Description

The primary namespace for DAKOTA.

The `Dakota` namespace encapsulates the core classes of the DAKOTA framework and prevents name clashes with third-party libraries from methods and packages. The C++ source files defining these core classes reside in `Dakota/src` as `*.[CH]`.

### 7.1.2 Function Documentation

#### 7.1.2.1 `CommandShell & flush (CommandShell & shell)`

convenient shell manipulator function to "flush" the shell

global convenience function for manipulating the shell; invokes the class member flush function.

#### 7.1.2.2 `bool Dakota::operator==(const DistinctVariables & vars1, const DistinctVariables & vars2)`

equality operator

Checks each array using `operator==` from `data_types.C`. Labels are ignored.

#### 7.1.2.3 `Real Dakota::getdist (RealVector & x1, RealVector & x2)`

Gets the Euclidean distance between `x1` and `x2`

**7.1.2.4 Real Dakota::mindist (RealVector & x, RealMatrix & xset, int except)**

Returns the minimum distance between the point *x* and the points in the set *xset* (compares against all points in *xset* except point "except"): if *except* is not needed, pass 0.

**7.1.2.5 Real Dakota::mindistindx (RealVector & x, RealMatrix & xset, IntVector & indx)**

Gets the min distance between *x* and points in the set *xset* defined by the *indx* values in *indx*.

**7.1.2.6 Real Dakota::getRmax (RealMatrix & xset)**

Gets the maximum of the min distance between each point and the rest of the set.

**7.1.2.7 string Dakota::asstring (const T & val)**

Creates a string from the argument *val* using an ostream.

This only gets used in this file and is only ever called with ints so no error checking is in place.

**Parameters:**

*val* The value of type *T* to convert to a string.

**Returns:**

The string representation of *val* created using an ostream.

**7.1.2.8 bool Dakota::vars\_set\_compare (const ParamResponsePair & database\_pr, const void \* search\_pr) [inline]**

search function for a particular [ParamResponsePair](#) within a [List](#)

a global function to compare the parameter values, ASV, & interface id of a particular *database\_pr* (presumed to be in the global history list) with a passed in set of parameters, ASV, & interface id provided by *search\_pr*.

**7.1.2.9 bool Dakota::eval\_id\_compare (const ParamResponsePair & pair, const void \* id) [inline]**

search function for a particular [ParamResponsePair](#) within a [List](#)

a global function to compare the *evalId* of a particular [ParamResponsePair](#) (from a [List](#)) with a passed in evaluation id. \*((int\*)id) construct casts void\* to int\* and then dereferences.

**7.1.2.10 bool Dakota::eval\_id\_sort\_fn (const ParamResponsePair & pr1, const ParamResponsePair & pr2) [inline]**

sort function for [ParamResponsePair](#)

a global function used to sort a PRPList by evalId's.

#### 7.1.2.11 void print\_restart (int argc, char \*\* argv, String print\_dest)

print a restart file

**Usage:** "dakota\_restart\_util print dakota.rst"

"dakota\_restart\_util to\_neutral dakota.rst dakota.neu"

Prints all evals. in full precision to either stdout or a neutral file. The former is useful for ensuring that duplicate detection is successful in a restarted run (e.g., starting a new method from the previous best), and the latter is used for translating binary files between platforms.

#### 7.1.2.12 void print\_restart\_tabular (int argc, char \*\* argv, String print\_dest)

print a restart file (tabular format)

**Usage:** "dakota\_restart\_util to\_pdb dakota.rst dakota.pdb"

"dakota\_restart\_util to\_tabular dakota.rst dakota.txt"

Unrolls all data associated with a particular tag for all evaluations and then writes this data in a tabular format (e.g., to a PDB database or MATLAB/TECPLOT data file).

#### 7.1.2.13 void read\_neutral (int argc, char \*\* argv)

read a restart file (neutral file format)

**Usage:** "dakota\_restart\_util from\_neutral dakota.neu dakota.rst"

Reads evaluations from a neutral file. This is used for translating binary files between platforms.

#### 7.1.2.14 void repair\_restart (int argc, char \*\* argv, String identifier\_type)

repair a restart file by removing corrupted evaluations

**Usage:** "dakota\_restart\_util remove 0.0 dakota\_old.rst dakota\_new.rst"

"dakota\_restart\_util remove\_ids 2 7 13 dakota\_old.rst dakota\_new.rst"

Repairs a restart file by removing corrupted evaluations. The identifier for evaluation removal can be either a double precision number (all evaluations having a matching response function value are removed) or a list of integers (all evaluations with matching evaluation ids are removed).

#### 7.1.2.15 void concatenate\_restart (int argc, char \*\* argv)

concatenate multiple restart files

**Usage:** "dakota\_restart\_util cat dakota\_1.rst ... dakota\_n.rst dakota\_new.rst"

Combines multiple restart files into a single restart database.

### 7.1.3 Variable Documentation

#### 7.1.3.1 Dakota\_funcs DakFuncs0

**Initial value:**

```
{
    fprintf,
    abort_handler,
    dlsolver_option,
    continuous_lower_bounds1,
    continuous_upper_bounds1,
    nonlinear_ineq_constraint_lower_bounds1,
    nonlinear_ineq_constraint_upper_bounds1,
    nonlinear_eq_constraint_targets1,
    linear_ineq_constraint_lower_bounds1,
    linear_ineq_constraint_upper_bounds1,
    linear_eq_constraint_targets1,
    linear_ineq_constraint_coeffs1,
    linear_eq_constraint_coeffs1,
    bestFunctions1,
    ComputeResponses1,
    GetFuncs1,
    GetGrads1,
    GetContVars1,
    SetBestContVars1
}
```

## 7.2 SIM Namespace Reference

plug facilities into DAKOTA.

### Classes

- class [DirectFnApplicInterface](#)

*Sample derived interface class for testing plug-ins using [assign\\_rep\(\)](#).*

### 7.2.1 Detailed Description

plug facilities into DAKOTA.

A typical use of plug-ins with `assign_rep()` is to publish a simulation interface for use in library mode See [Interfacing with DAKOTA as a Library](#) for more information.





# Chapter 8

## DAKOTA Class Documentation

### 8.1 ActiveSet Class Reference

active set request vector and the derivative variables vector.

#### Public Member Functions

- [ActiveSet](#) ()  
*default constructor*
- [ActiveSet](#) (size\_t num\_fns, size\_t num\_deriv\_vars)  
*standard constructor*
- [ActiveSet](#) (const [ActiveSet](#) &set)  
*copy constructor*
- [~ActiveSet](#) ()  
*destructor*
- [ActiveSet](#) & [operator=](#) (const [ActiveSet](#) &set)  
*assignment operator*
- void [reshape](#) (size\_t num\_fns, size\_t num\_deriv\_vars)  
*reshape requestVector and derivVarsVector*
- const [ShortArray](#) & [request\\_vector](#) () const  
*return the request vector*

- void [request\\_vector](#) (const [ShortArray](#) &rv)  
*set the request vector*
- void [request\\_values](#) (const int rv\_val)  
*set all request vector values*
- void [request\\_value](#) (const size\_t index, const int rv\_val)  
*set the value of an entry in the request vector*
- const [IntArray](#) & [derivative\\_vector](#) () const  
*return the derivative variables vector*
- void [derivative\\_vector](#) (const [IntArray](#) &dvv)  
*set the derivative variables vector*
- void [derivative\\_start\\_value](#) (const int dvv\_start\_val)  
*set the derivative variables vector values*
- void [read](#) (istream &s)  
*read an active set object from an istream*
- void [write](#) (ostream &s) const  
*write an active set object to an ostream*
- void [write\\_annotated](#) (ostream &s) const  
*write an active set object to an ostream in annotated format*
- void [read](#) ([BiStream](#) &s)  
*read an active set object from the binary restart stream*
- void [write](#) ([BoStream](#) &s) const  
*write an active set object to the binary restart stream*
- void [read](#) ([MPIUnpackBuffer](#) &s)  
*read an active set object from a packed MPI buffer*
- void [write](#) ([MPIPackBuffer](#) &s) const  
*write an active set object to a packed MPI buffer*

## Private Attributes

- [ShortArray](#) [requestVector](#)  
*the vector of response requests*
- [IntArray](#) [derivVarsVector](#)  
*the vector of variable ids used for computing derivatives*

## Friends

- `bool operator==(const ActiveSet &set1, const ActiveSet &set2)`  
*equality operator*
- `bool operator!=(const ActiveSet &set1, const ActiveSet &set2)`  
*inequality operator*

### 8.1.1 Detailed Description

active set request vector and the derivative variables vector.

The `ActiveSet` class is a small class whose initial design function is to avoid having to pass the ASV and DVV separately. It is not part of a class hierarchy and does not employ reference-counting/ representation-sharing idioms (e.g., handle-body).

### 8.1.2 Member Data Documentation

#### 8.1.2.1 `ShortArray requestVector` [private]

the vector of response requests

It uses a 0 value for inactive functions and sums 1 (value), 2 (gradient), and 4 (Hessian) for active functions.

#### 8.1.2.2 `IntArray derivVarsVector` [private]

the vector of variable ids used for computing derivatives

These ids will generally identify either the active continuous variables or the inactive continuous variables.

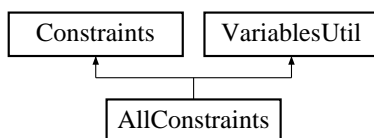
The documentation for this class was generated from the following files:

- `DakotaActiveSet.H`
- `DakotaActiveSet.C`

## 8.2 AllConstraints Class Reference

employs the all data view.

Inheritance diagram for AllConstraints::



### Public Member Functions

- [AllConstraints](#) ()  
*default constructor*
- [AllConstraints](#) (const [ProblemDescDB](#) &problem\_db, const pair< short, short > &view)  
*standard constructor*
- [~AllConstraints](#) ()  
*destructor*
- const [RealVector](#) & [continuous\\_lower\\_bounds](#) () const  
*return the active continuous variable lower bounds*
- void [continuous\\_lower\\_bounds](#) (const [RealVector](#) &c\_l\_bnds)  
*set the active continuous variable lower bounds*
- const [RealVector](#) & [continuous\\_upper\\_bounds](#) () const  
*return the active continuous variable upper bounds*
- void [continuous\\_upper\\_bounds](#) (const [RealVector](#) &c\_u\_bnds)  
*set the active continuous variable upper bounds*
- const [IntVector](#) & [discrete\\_lower\\_bounds](#) () const  
*return the active discrete variable lower bounds*
- void [discrete\\_lower\\_bounds](#) (const [IntVector](#) &d\_l\_bnds)  
*set the active discrete variable lower bounds*
- const [IntVector](#) & [discrete\\_upper\\_bounds](#) () const  
*return the active discrete variable upper bounds*

- void `discrete_upper_bounds` (const `IntVector` &d\_u\_bnds)  
*set the active discrete variable upper bounds*
- `RealVector` `all_continuous_lower_bounds` () const  
*returns a single array with all continuous lower bounds*
- void `all_continuous_lower_bounds` (const `RealVector` &a\_c\_l\_bnds)  
*sets all continuous lower bounds using a single array*
- `RealVector` `all_continuous_upper_bounds` () const  
*returns a single array with all continuous upper bounds*
- void `all_continuous_upper_bounds` (const `RealVector` &a\_c\_u\_bnds)  
*sets all continuous upper bounds using a single array*
- `IntVector` `all_discrete_lower_bounds` () const  
*returns a single array with all discrete lower bounds*
- void `all_discrete_lower_bounds` (const `IntVector` &a\_d\_l\_bnds)  
*sets all discrete lower bounds using a single array*
- `IntVector` `all_discrete_upper_bounds` () const  
*returns a single array with all discrete upper bounds*
- void `all_discrete_upper_bounds` (const `IntVector` &a\_d\_u\_bnds)  
*sets all discrete upper bounds using a single array*
- void `write` (ostream &s) const  
*write a variable constraints object to an ostream*
- void `read` (istream &s)  
*read a variable constraints object from an istream*

### Protected Member Functions

- void `copy_rep` (const `Constraints` \*con\_rep)  
*Used by `copy()` to copy the contents of a letter class.*
- void `reshape_rep` (const `Sizet2DArray` &vars\_comps)  
*Used by `reshape(Sizet2DArray&)` to reshape the contents of a letter class.*

## Private Attributes

- [RealVector allContinuousLowerBnds](#)  
*uncertain, and continuous state variable types (all view).*
- [RealVector allContinuousUpperBnds](#)  
*uncertain, and continuous state variable types (all view).*
- [IntVector allDiscreteLowerBnds](#)  
*discrete state variable types (all view).*
- [IntVector allDiscreteUpperBnds](#)  
*discrete state variable types (all view).*
- `size_t numCDV`  
*number of continuous design variables*
- `size_t numDDV`  
*number of discrete design variables*

### 8.2.1 Detailed Description

employs the all data view.

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [AllConstraints](#) derived class combines design, uncertain, and state variable types but separates continuous and discrete domain types. The result is combined continuous bounds arrays (`allContinuousLowerBnds`, `allContinuousUpperBnds`) and combined discrete bounds arrays (`allDiscreteLowerBnds`, `allDiscreteUpperBnds`). Parameter and DACE studies currently use this approach (see `Variables::get_variables(problem_db)` for variables view selection; variables view is passed to the [Constraints](#) constructor in [Model](#)).

### 8.2.2 Constructor & Destructor Documentation

#### 8.2.2.1 [AllConstraints](#) (`const ProblemDescDB & problem_db, const pair< short, short > & view`)

standard constructor

In this class, the all data approach (design, uncertain, and state types are combined) is used. Iterators/strategies which use this class include: parameter studies, dace, and nond\_sampling in all\_variables mode. Extract fundamental lower and upper bounds and combine them into `allContinuousLowerBnds`, `allContinuousUpperBnds`, `allDiscreteLowerBnds`, and `allDiscreteUpperBnds` using utilities from [VariablesUtil](#).

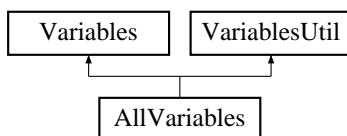
The documentation for this class was generated from the following files:

- AllConstraints.H
- AllConstraints.C

### 8.3 AllVariables Class Reference

the all data view.

Inheritance diagram for AllVariables::



#### Public Member Functions

- [AllVariables](#) ()  
*default constructor*
- [AllVariables](#) (const [ProblemDescDB](#) &problem\_db, const pair< short, short > &view)  
*standard constructor*
- [~AllVariables](#) ()  
*destructor*
- size\_t [tv](#) () const  
*Returns total number of vars.*
- const [RealVector](#) & [continuous\\_variables](#) () const  
*return the active continuous variables*
- void [continuous\\_variables](#) (const [RealVector](#) &c\_vars)  
*set the active continuous variables*
- const [IntVector](#) & [discrete\\_variables](#) () const  
*return the active discrete variables*
- void [discrete\\_variables](#) (const [IntVector](#) &d\_vars)  
*set the active discrete variables*
- const [StringArray](#) & [continuous\\_variable\\_labels](#) () const  
*return the active continuous variable labels*
- void [continuous\\_variable\\_labels](#) (const [StringArray](#) &cv\_labels)  
*set the active continuous variable labels*



- `const StringArray & discrete_variable_labels () const`  
*return the active discrete variable labels*
- `void discrete_variable_labels (const StringArray &dv_labels)`  
*set the active discrete variable labels*
- `size_t acv () const`  
*returns total number of continuous vars*
- `size_t adv () const`  
*returns total number of discrete vars*
- `RealVector all_continuous_variables () const`  
*returns a single array with all continuous variables*
- `void all_continuous_variables (const RealVector &a_c_vars)`  
*sets all continuous variables using a single array*
- `IntVector all_discrete_variables () const`  
*returns a single array with all discrete variables*
- `void all_discrete_variables (const IntVector &a_d_vars)`  
*sets all discrete variables using a single array*
- `StringArray all_continuous_variable_labels () const`  
*returns a single array with all continuous variable labels*
- `void all_continuous_variable_labels (const StringArray &a_c_v_labels)`  
*sets all continuous variable labels using a single array*
- `StringArray all_discrete_variable_labels () const`  
*returns a single array with all discrete variable labels*
- `void all_discrete_variable_labels (const StringArray &a_d_v_labels)`  
*sets all discrete variable labels using a single array*
- `StringArray all_variable_labels () const`  
*returns a single array with all variable labels*
- `void read (istream &s)`  
*read a variables object from an istream*
- `void write (ostream &s) const`  
*write a variables object to an ostream*

- void [write\\_aprepro](#) (ostream &s) const  
*write a variables object to an ostream in aprepro format*
- void [read\\_annotated](#) (istream &s)  
*read a variables object in annotated format from an istream*
- void [write\\_annotated](#) (ostream &s) const  
*write a variables object in annotated format to an ostream*
- void [write\\_tabular](#) (ostream &s) const  
*write a variables object in tabular format to an ostream*
- void [read](#) (BiStream &s)  
*read a variables object from the binary restart stream*
- void [write](#) (BoStream &s) const  
*write a variables object to the binary restart stream*
- void [read](#) (MPIUnpackBuffer &s)  
*read a variables object from a packed MPI buffer*
- void [write](#) (MPIPackBuffer &s) const  
*write a variables object to a packed MPI buffer*

### Protected Member Functions

- void [copy\\_rep](#) (const Variables \*vars\_rep)  
*Used by [copy\(\)](#) to copy the contents of a letter class.*
- void [reshape\\_rep](#) (const Sizer2DArray &vars\_comps)  
*Used by [reshape\(\)](#) to reshape the contents of a letter class.*

### Private Member Functions

- void [build\\_types\\_ids](#) ()  
*construct VarTypes and VarIds arrays using variablesComponents*

### Private Attributes

- RealVector [allContinuousVars](#)  
*(design, uncertain, and state).*

- [IntVector allDiscreteVars](#)  
(*design and state*).
- [StringArray allContinuousLabels](#)  
(*design, uncertain, and state*).
- [StringArray allDiscreteLabels](#)  
(*design and state*).

## Friends

- `bool operator==(const AllVariables &vars1, const AllVariables &vars2)`  
*equality operator*

### 8.3.1 Detailed Description

the all data view.

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [AllVariables](#) derived class combines design, uncertain, and state variable types but separates continuous and discrete domain types. The result is a single array of continuous variables ([allContinuousVars](#)) and a single array of discrete variables ([allDiscreteVars](#)). Parameter and DACE studies currently use this approach (see `Variables::get_variables(problem_db)`).

### 8.3.2 Constructor & Destructor Documentation

#### 8.3.2.1 [AllVariables](#) (const [ProblemDescDB](#) & *problem\_db*, const pair< short, short > & *view*)

standard constructor

In this class, the all data approach (design, uncertain, and state types are combined) is used. Iterators/strategies which use this class include: parameter studies, DACE, and the `all_variables` mode of `nond_sampling`. Extract fundamental variable types and labels and combine them into [allContinuousVars](#), [allDiscreteVars](#), [allContinuousLabels](#), and [allDiscreteLabels](#) using utilities from [VariablesUtil](#).

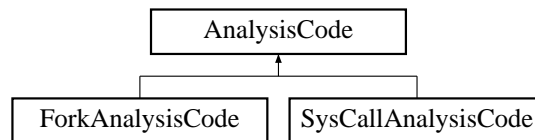
The documentation for this class was generated from the following files:

- [AllVariables.H](#)
- [AllVariables.C](#)

## 8.4 AnalysisCode Class Reference

processes for managing simulations.

Inheritance diagram for AnalysisCode::



### Public Member Functions

- void `define_filenames` (const int id)  
*file and tagging options*
- void `write_parameters_files` (const `Variables` &vars, const `ActiveSet` &set, const int id)  
*write\_parameters\_file()* in either standard or aprepro format
- void `read_results_files` (`Response` &response, const int id)  
*read the response object from one or more results files*
- const `StringArray` & `program_names` () const  
*return programNames*
- const `String` & `input_filter_name` () const  
*return iFilterName*
- const `String` & `output_filter_name` () const  
*return oFilterName*
- const `String` & `parameters_filename` () const  
*return paramsFileName*
- const `String` & `results_filename` () const  
*return resultsFileName*
- const `String` & `results_filename` (const int id)  
*return the results filename entry in fileNameMap corresponding to id*
- void `suppress_output_flag` (const bool flag)  
*set suppressOutputFlag*

- bool `suppress_output_flag` () const  
*return suppressOutputFlag*
- bool `multiple_parameters_filenames` () const  
*return multipleParamsFiles*

### Protected Member Functions

- `AnalysisCode` (const `ProblemDescDB` &problem\_db)  
*constructor*
- virtual `~AnalysisCode` ()  
*destructor*

### Protected Attributes

- bool `suppressOutputFlag`  
*flag set by master processor to suppress output from slave processors*
- bool `verboseFlag`  
*flag for additional analysis code output if method verbosity is set*
- bool `fileTagFlag`  
*flags tagging of parameter/results files*
- bool `fileSaveFlag`  
*flags retention of parameter/results files*
- bool `apreproFlag`  
*format for parameter files*
- bool `multipleParamsFiles`  
*analysis drivers*
- `String` `iFilterName`  
*the name of the input filter (input\_filter user specification)*
- `String` `oFilterName`  
*the name of the output filter (output\_filter user specification)*
- `StringArray` `programNames`  
*specification)*

- `size_t numPrograms`  
*the number of analysis code programs (length of programNames)*
- `String specifiedParamsFileName`  
*the name of the parameters file from user specification*
- `String paramsFileName`  
*temp files)*
- `String specifiedResultsFileName`  
*the name of the results file from user specification*
- `String resultsFileName`  
*the results file name actually used (modified with tagging or temp files)*
- `map< int, pair< String, String > > fileNameMap`  
*evaluations. Map key is the function evaluation identifier.*

### Private Member Functions

- void `write_parameters_file` (const `Variables` &vars, const `ActiveSet` &set, const `StringArray` &an\_comps, const `String` &params\_fname)  
*standard or aprepro format*

### Private Attributes

- `ParallelLibrary` & `parallelLib`  
*reference to the `ParallelLibrary` object. Used in `define_filenames()`.*
- `String2DArray` `analysisComponents`  
*(from the `analysis_components` interface specification)*

## 8.4.1 Detailed Description

processes for managing simulations.

The `AnalysisCode` class hierarchy provides simulation spawning services for `ApplicationInterface` derived classes and alleviates these classes of some of the specifics of simulation code management. The hierarchy does not employ the letter-envelope technique since the `ApplicationInterface` derived classes instantiate the appropriate derived `AnalysisCode` class directly.

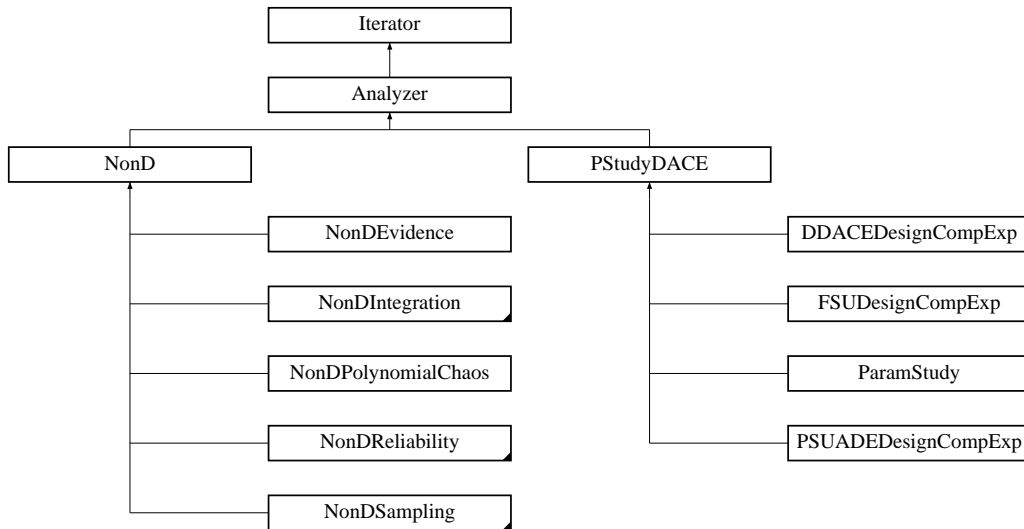
The documentation for this class was generated from the following files:

- AnalysisCode.H
- AnalysisCode.C

## 8.5 Analyzer Class Reference

hierarchy.

Inheritance diagram for Analyzer::



### Public Member Functions

- `const VariablesArray & all_variables () const`  
*return the complete set of evaluated variables*
- `const ResponseArray & all_responses () const`  
*return the complete set of computed responses*
- `const VariablesArray & variables_array_results () const`  
*return multiple final iterator solutions (variables)*
- `const ResponseArray & response_array_results () const`  
*return multiple final iterator solutions (response)*

### Protected Member Functions

- `Analyzer ()`  
*default constructor*



- [Analyzer \(Model &model\)](#)  
*standard constructor*
- [Analyzer \(NoDBBaseConstructor, Model &model\)](#)  
*alternate constructor for instantiations "on the fly" with a [Model](#)*
- [Analyzer \(NoDBBaseConstructor\)](#)  
*alternate constructor for instantiations "on the fly" without a [Model](#)*
- [~Analyzer \(\)](#)  
*destructor*
- virtual void [update\\_best](#) (const [RealVector](#) &vars, const [Response](#) &response, const int eval\_num)  
*compares current evaluation to best evaluation and updates best*
- virtual void [vary\\_pattern](#) (bool pattern\_flag)  
*sets varyPattern in derived classes that support it*
- virtual void [get\\_parameter\\_sets](#) (const [Model](#) &model)  
*Returns one block of samples (ndim \* num\_samples).*
- void [evaluate\\_parameter\\_sets](#) ([Model](#) &model, bool log\_resp\_flag, bool log\_best\_flag)  
*into response sets (allResponses)*
- void [var\\_based\\_decomp](#) (const int ndim, const int num\_samples)
- void [volumetric\\_quality](#) (int ndim, int num\_samples, double \*sample\_points)  
*Calculation of volumetric quality measures.*
- void [print\\_vbd](#) (ostream &s, const [RealVectorArray](#) &S, const [RealVectorArray](#) &T) const  
*Printing of VBD results.*

### Protected Attributes

- [VariablesArray allVariables](#)  
*array of all variables evaluated*
- [ResponseArray allResponses](#)  
*array of all responses computed*
- [StringArray allHeaders](#)  
*array of headers to insert into output while evaluating allVariables*
- bool [qualityFlag](#)

*flag to indicated if quality metrics were calculated*

- double [chiMeas](#)  
*quality measure*
- double [dMeas](#)  
*quality measure*
- double [hMeas](#)  
*quality measure*
- double [tauMeas](#)  
*quality measure*

### 8.5.1 Detailed Description

hierarchy.

The [Analyzer](#) class provides common data and functionality for various types of systems analysis, including nondeterministic analysis, design of experiments, and parameter studies.

### 8.5.2 Member Function Documentation

#### 8.5.2.1 void [evaluate\\_parameter\\_sets](#) ([Model](#) & *model*, bool *log\_resp\_flag*, bool *log\_best\_flag*) [protected]

into response sets (allResponses)

Convenience function for derived classes with sets of function evaluations to perform (e.g., [NonDSampling](#), [DDACEDesignCompExp](#), [FSUDesignCompExp](#), [ParamStudy](#)).

#### 8.5.2.2 void [var\\_based\\_decomp](#) (const int *ndim*, const int *num\_samples*) [protected]

Calculation of sensitivity indices obtained by variance based decomposition. These indices are obtained by the Saltelli version of the Sobol VBD which uses  $(K+2)*N$  function evaluations, where K is the number of dimensions (uncertain vars) and N is the number of samples.

#### 8.5.2.3 void [volumetric\\_quality](#) (int *ndim*, int *num\_samples*, double \* *sample\_points*) [protected]

Calculation of volumetric quality measures.

Calculation of volumetric quality measures developed by FSU.

---

**8.5.2.4** void print\_vbd (ostream & *s*, const RealVectorArray & *S*, const RealVectorArray & *T*) const  
[protected]

Printing of VBD results.

printing of variance based decomposition indices.

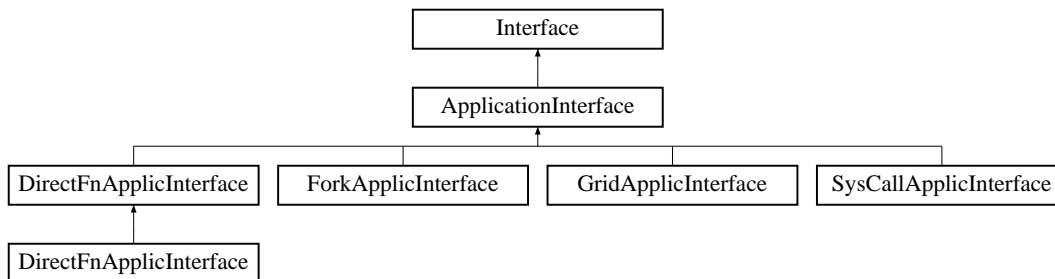
The documentation for this class was generated from the following files:

- DakotaAnalyzer.H
- DakotaAnalyzer.C

## 8.6 ApplicationInterface Class Reference

interfaces to simulation codes.

Inheritance diagram for ApplicationInterface::



### Public Member Functions

- [ApplicationInterface](#) (const [ProblemDescDB](#) &problem\_db)  
*constructor*
- [~ApplicationInterface](#) ()  
*destructor*

### Protected Member Functions

- void [init\\_communicators](#) (const [IntArray](#) &message\_lengths, const int &max\_iterator\_concurrency)  
*iterator and concurrent multiprocessor analyses within an evaluation.*
- void [set\\_communicators](#) (const [IntArray](#) &message\_lengths)  
*(the partitions are already allocated in [ParallelLibrary](#)).*
- void [free\\_communicators](#) ()  
*iterator and concurrent multiprocessor analyses within an evaluation.*
- void [init\\_serial](#) ()
- int [asynch\\_local\\_evaluation\\_concurrency](#) () const  
*return asynchLocalEvalConcurrency*
- [String](#) [interface\\_synchronization](#) () const  
*return interfaceSynchronization*

- void `map` (const `Variables` &vars, const `ActiveSet` &set, `Response` &response, const bool asynch\_flag=false)  
*Protected due to `Interface` letter-envelope idiom.*
- void `manage_failure` (const `Variables` &vars, const `ActiveSet` &set, `Response` &response, int failed\_eval\_id)  
*manages a simulation failure using abort/retry/recover/continuation*
- const `ResponseArray` & `synch` ()  
*the beforeSynchCorePRPList queue and returns all jobs*
- const `IntResponseMap` & `synch_nowait` ()  
*beforeSynchCorePRPList queue and returns a partial list of completed jobs*
- void `serve_evaluations` ()  
*run on evaluation servers to serve the iterator master*
- void `stop_evaluation_servers` ()  
*used by the iterator master to terminate evaluation servers*
- virtual void `derived_map` (const `Variables` &vars, const `ActiveSet` &set, `Response` &response, int fn\_eval\_id)  
*that is specific to a derived class.*
- virtual void `derived_map_asynch` (const `ParamResponsePair` &pair)  
*asynchronous evaluation that is specific to a derived class.*
- virtual void `derived_synch` (`PRPList` &prp\_list)  
*classes. This version waits for at least one completion.*
- virtual void `derived_synch_nowait` (`PRPList` &prp\_list)  
*any completions if none are immediately available.*
- void `self_schedule_analyses` ()  
*evaluation using message passing*
- void `serve_analyses_synch` ()  
*analysis job at a time*
- virtual int `derived_synchronous_local_analysis` (const int &analysis\_id)  
*`ApplicationInterface::serve_analyses_synch()`.*

## Protected Attributes

- `ParallelLibrary` & `parallelLib`  
*the concurrent evaluations and concurrent analyses parallelism levels*
- `bool suppressOutput`  
*flag for suppressing output on slave processors*
- `int evalCommSize`  
*size of evalComm*
- `int evalCommRank`  
*processor rank within evalComm*
- `int evalServerId`  
*evaluation server identifier*
- `bool eaDedMasterFlag`  
*flag for dedicated master partitioning at ea level*
- `int analysisCommSize`  
*size of analysisComm*
- `int analysisCommRank`  
*processor rank within analysisComm*
- `int analysisServerId`  
*analysis server identifier*
- `int numAnalysisServers`  
*number of analysis servers*
- `bool multiProcAnalysisFlag`  
*flag for multiprocessor analysis partitions*
- `bool asynchLocalAnalysisFlag`  
*flag for asynchronous local parallelism of analyses*
- `int asynchLocalAnalysisConcurrency`  
*scheduling and specifies hybrid concurrency when message passing*
- `int numAnalysisDrivers`  
*(from the analysis\_drivers interface specification)*
- `IntSet completionSet`  
*and derived\_synch\_nowait()*

## Private Member Functions

- bool `duplication_detect` (const `Variables` &vars, `Response` &response, const bool `asynch_flag`)  
*evaluation request has already been performed or queued*
- void `self_schedule_evaluations` ()  
*using message passing; executes on iteratorComm master*
- void `static_schedule_evaluations` ()  
*using message passing; executes on iteratorComm master*
- void `asynchronous_local_evaluations` (`PRPList` &prp\_list)  
*the local processor*
- void `synchronous_local_evaluations` (`PRPList` &prp\_list)  
*the local processor*
- void `asynchronous_local_evaluations_nowait` (`PRPList` &prp\_list)  
*process any completed jobs*
- void `serve_evaluations_synch` ()  
*one synchronous evaluation at a time*
- void `serve_evaluations_asynch` ()  
*multiple asynchronous evaluations*
- void `serve_evaluations_peer` ()  
*one synchronous evaluation at a time as part of the 1st peer*
- void `set_evaluation_communicators` (const `IntArray` &message\_lengths)  
*following `ParallelLibrary::init_evaluation_communicators()`.*
- void `set_analysis_communicators` ()  
*following `ParallelLibrary::init_analysis_communicators()`.*
- void `check_configuration` (const int &max\_iterator\_concurrency)  
*perform some error checks on the parallel configuration*
- const `ParamResponsePair` & `get_source_pair` (const `Variables` &target\_vars)  
*evaluation to the failed "target"*
- void `continuation` (const `Variables` &target\_vars, const `ActiveSet` &set, `Response` &response, const `ParamResponsePair` &source\_pair, int failed\_eval\_id)  
*Invoked by `manage_failure()` for failAction == "continuation".*
- void `common_input_filtering` (const `Variables` &vars)

*common input filtering operations, e.g. mesh movement*

- void `common_output_filtering` (`Response &response`)  
*common output filtering operations, e.g. data filtering*

## Private Attributes

- int `worldSize`  
*size of `MPI_COMM_WORLD`*
- int `worldRank`  
*processor rank within `MPI_COMM_WORLD`*
- int `iteratorCommSize`  
*size of `iteratorComm`*
- int `iteratorCommRank`  
*processor rank within `iteratorComm`*
- bool `ieMessagePass`  
*flag for message passing at ie scheduling level*
- int `numEvalServers`  
*number of evaluation servers*
- bool `eaMessagePass`  
*flag for message passing at ea scheduling level*
- int `procsPerAnalysis`  
*processors per analysis servers*
- int `lenVarsMessage`  
*computed in `Model::init_communicators()`*
- int `lenVarsActSetMessage`  
*`ActiveSet` object; computed in `Model::init_communicators()`.*
- int `lenResponseMessage`  
*computed in `Model::init_communicators()`*
- int `lenPRPairMessage`  
*computed in `Model::init_communicators()`*
- String `evalScheduling`  
*auto-configure logic in `ParallelLibrary::resolve_inputs()`.*



- **String analysisScheduling**  
*auto-configure logic in `ParallelLibrary::resolve_inputs()`.*
- **int asynchLocalEvalConcurrency**  
*scheduling and specifies hybrid concurrency when message passing*
- **String interfaceSynchronization**  
*or asynchronous*
- **bool headerFlag**  
*function may be called many times prior to any completions)*
- **bool asvControlFlag**  
*on each evaluation.*
- **bool evalCacheFlag**  
*cache (i.e., queries and insertions using the `data_pairs` list).*
- **bool restartFileFlag**  
*insertions into `write_restart`).*
- **ShortArray defaultASV**  
*the static ASV values used when the user has selected `asvControl = off`*
- **String failAction**  
*retry, recover, or continuation*
- **int failRetryLimit**  
*limit on the number of retries for the retry failAction*
- **RealVector failRecoveryFn Vals**  
*the dummy function values used for the recover failAction*
- **IntList beforeSynchIdList**  
*bookkeeps `fnEvalId`'s of `_all_` asynchronous evaluations (new & duplicate)*
- **IntResponseMap historyDuplicateMap**  
*evaluations. Map key is `fnEvalId`, `mad` data is corresponding response.*
- **std::map< int, pair< PRPLiter, Response > > beforeSynchDuplicateMap**  
*beforeSynchCorePRPList evaluations*
- **PRPList beforeSynchCorePRPList**  
*that is later scheduled in `synch()` or `synch_nowait()`.*

- [PRPList beforeSynchAlgPRPList](#)  
*that is later evaluated in `synch()` or `synch_nowait()`.*
- [ResponseList beforeSynchTotalRespList](#)  
*asynchronous `map()` and later used in `synch()` or `synch_nowait()`.*
- [IntSet runningSet](#)  
*used by `asynchronous_local_nowait` to bookkeep which jobs are running*

### 8.6.1 Detailed Description

interfaces to simulation codes.

[ApplicationInterface](#) provides an interface class for performing parameter to response mappings using simulation code(s). It provides common functionality for a number of derived classes and contains the majority of all of the scheduling algorithms in DAKOTA. The derived classes provide the specifics for managing code invocations using system calls, forks, direct procedure calls, or distributed resource facilities.

### 8.6.2 Member Function Documentation

#### 8.6.2.1 `void init_serial()` [inline, protected, virtual]

DataInterface.C defaults of 0 servers are needed to distinguish an explicit user request for 1 server (serialization of a parallelism level) from no user request (use parallel auto-config). This default causes problems when `init_communicators()` is not called for an interface object (e.g., static scheduling fails in [DirectFnApplicInterface::derived\\_map\(\)](#) for [NestedModel::optionalInterface](#)). This is the reason for this function: to reset certain defaults for interface objects that are used serially.

Reimplemented from [Interface](#).

#### 8.6.2.2 `void map (const Variables & vars, const ActiveSet & set, Response & response, const bool asynch_flag = false)` [protected, virtual]

Protected due to [Interface](#) letter-envelope idiom.

The function evaluator for application interfaces. Called from `derived_compute_response()` and `derived_asynch_compute_response()` in derived [Model](#) classes. If `asynch_flag` is not set, perform a blocking evaluation (using `derived_map()`). If `asynch_flag` is set, add the job to the `beforeSynchCorePRPList` queue for execution by one of the scheduler routines in `synch()` or `synch_nowait()`. Duplicate function evaluations are detected with `duplication_detect()`.

Reimplemented from [Interface](#).

### 8.6.2.3 `const ResponseArray & synch ()` [protected, virtual]

the beforeSynchCorePRPList queue and returns all jobs

This function provides blocking synchronization for all cases of asynchronous evaluations, including the local asynchronous case (background system call, nonblocking fork, & multithreads), the message passing case, and the hybrid case. Called from derived\_synch() in derived [Model](#) classes.

Reimplemented from [Interface](#).

### 8.6.2.4 `const IntResponseMap & synch_nowait ()` [protected, virtual]

beforeSynchCorePRPList queue and returns a partial list of completed jobs

This function will eventually provide nonblocking synchronization for all cases of asynchronous evaluations, however it currently supports only the local asynchronous case since nonblocking message passing schedulers have not yet been implemented. Called from derived\_synch\_nowait() in derived [Model](#) classes.

Reimplemented from [Interface](#).

### 8.6.2.5 `void serve_evaluations ()` [protected, virtual]

run on evaluation servers to serve the iterator master

Invoked by the serve() function in derived [Model](#) classes. Passes control to [serve\\_evaluations\\_asynch\(\)](#), [serve\\_evaluations\\_peer\(\)](#), or [serve\\_evaluations\\_synch\(\)](#) according to specified concurrency and self/static scheduler configuration.

Reimplemented from [Interface](#).

### 8.6.2.6 `void stop_evaluation_servers ()` [protected, virtual]

used by the iterator master to terminate evaluation servers

This code is executed on the iteratorComm rank 0 processor when iteration on a particular model is complete. It sends a termination signal (tag = 0 instead of a valid fn\_eval\_id) to each of the slave analysis servers. NOTE: This function is called from the [Strategy](#) layer even when in serial mode. Therefore, use iteratorCommSize to provide appropriate fall through behavior.

Reimplemented from [Interface](#).

### 8.6.2.7 `void self_schedule_analyses ()` [protected]

evaluation using message passing

This code is called from derived classes to provide the master portion of a master-slave algorithm for the dynamic self-scheduling of analyses among slave servers. It is patterned after [self\\_schedule\\_evaluations\(\)](#). It performs no analyses locally and matches either [serve\\_analyses\\_synch\(\)](#) or [serve\\_analyses\\_asynch\(\)](#) on the slave servers, depending on the value of asynchLocalAnalysisConcurrency. Self-scheduling approach assigns jobs in 2 passes. The 1st pass gives each server the same number of jobs (equal to asynchLocalAnalysisConcurrency). The 2nd

pass assigns the remaining jobs to slave servers as previous jobs are completed. Single- and multilevel parallel use intra- and inter-communicators, respectively, for send/receive. Specific syntax is encapsulated within [ParallelLibrary](#).

#### 8.6.2.8 void `serve_analyses_synch()` [protected]

analysis job at a time

This code is called from derived classes to run synchronous analyses on slave processors. The slaves receive requests (blocking receive), do local derived\_map\_ac's, and return codes. This is done continuously until a termination signal is received from the master. It is patterned after [serve\\_evaluations\\_synch\(\)](#).

#### 8.6.2.9 bool `duplication_detect(const Variables & vars, Response & response, const bool asynch_flag)` [private]

evaluation request has already been performed or queued

Called from [map\(\)](#) to check incoming evaluation request for duplication with content of `data_pairs` and `beforeSynchCorePRPList`. If duplication is detected, return true, else return false. Manage bookkeeping with `history-DuplicateMap` and `beforeSynchDuplicateMap`. Note that the list searches can get very expensive if a long list is searched on every new function evaluation (either from a large number of previous jobs, a large number of pending jobs, or both). For this reason, a user request for deactivation of the evaluation cache results in a complete bypass of [duplication\\_detect\(\)](#), even though a `beforeSynchCorePRPList` search would still be meaningful. Since the intent of this request is to streamline operations, both list searches are bypassed.

#### 8.6.2.10 void `self_schedule_evaluations()` [private]

using message passing; executes on iteratorComm master

This code is called from [synch\(\)](#) to provide the master portion of a master-slave algorithm for the dynamic self-scheduling of evaluations among slave servers. It performs no evaluations locally and matches either [serve\\_evaluations\\_synch\(\)](#) or [serve\\_evaluations\\_asynch\(\)](#) on the slave servers, depending on the value of `asynchLocalEvalConcurrency`. Self-scheduling approach assigns jobs in 2 passes. The 1st pass gives each server the same number of jobs (equal to `asynchLocalEvalConcurrency`). The 2nd pass assigns the remaining jobs to slave servers as previous jobs are completed. Single- and multilevel parallel use intra- and inter-communicators, respectively, for send/receive. Specific syntax is encapsulated within [ParallelLibrary](#).

#### 8.6.2.11 void `static_schedule_evaluations()` [private]

using message passing; executes on iteratorComm master

This code runs on the `iteratorCommRank 0` processor (the iterator) and is called from [synch\(\)](#) in order to assign a static schedule. It matches [serve\\_evaluations\\_peer\(\)](#) for any other processors within the 1st evaluation partition and [serve\\_evaluations\\_synch\(\)/serve\\_evaluations\\_asynch\(\)](#) for all other evaluation partitions (depending on `asynchLocalEvalConcurrency`). It performs function evaluations locally for its portion of the static schedule using either [asynchronous\\_local\\_evaluations\(\)](#) or [synchronous\\_local\\_evaluations\(\)](#). Single-level and multilevel parallel use intra- and inter-communicators, respectively, for send/receive. Specific syntax is encapsulated within [ParallelLibrary](#). The `iteratorCommRank 0` processor assigns the static schedule since it is the only processor with access to `beforeSynchCorePRPList` (it runs the iterator and calls `synchronize`). The alternate design of each peer

selecting its own jobs using the modulus operator would be applicable if execution of this function (and therefore the job list) were distributed.

#### 8.6.2.12 void asynchronous\_local\_evaluations (PRPList & prp\_list) [private]

the local processor

This function provides blocking synchronization for the local asynch case (background system call, non-blocking fork, or threads). It can be called from [synch\(\)](#) for a complete local scheduling of all asynchronous jobs or from [static\\_schedule\\_evaluations\(\)](#) to perform a local portion of the total job set. It uses the [derived\\_map\\_asynch\(\)](#) to initiate asynchronous evaluations and [derived\\_synch\(\)](#) to capture completed jobs, and mirrors the [self\\_schedule\\_evaluations\(\)](#) message passing scheduler as much as possible ([derived\\_synch\(\)](#) is modeled after [MPI\\_Waitsome\(\)](#)).

#### 8.6.2.13 void synchronous\_local\_evaluations (PRPList & prp\_list) [private]

the local processor

This function provides blocking synchronization for the local synchronous case (foreground system call, blocking fork, or procedure call from [derived\\_map\(\)](#)). It is called from [static\\_schedule\\_evaluations\(\)](#) to perform a local portion of the total job set.

#### 8.6.2.14 void asynchronous\_local\_evaluations\_nowait (PRPList & prp\_list) [private]

process any completed jobs

This function provides nonblocking synchronization for the local asynch case (background system call, non-blocking fork, or threads). It is called from [synch\\_nowait\(\)](#) and passed the complete set of all asynchronous jobs (beforeSynchCorePRPList). It uses [derived\\_map\\_asynch\(\)](#) to initiate asynchronous evaluations and [derived\\_synch\\_nowait\(\)](#) to capture completed jobs in nonblocking mode. It mirrors a nonblocking message passing scheduler as much as possible ([derived\\_synch\\_nowait\(\)](#) modeled after [MPI\\_Testsome\(\)](#)). The result of this function is rawResponseMap, which uses [fn\\_eval\\_id](#) as a key. It is assumed that the incoming [prp\\_list](#) contains only active and new jobs - i.e., all completed jobs are cleared by [synch\\_nowait\(\)](#).

#### 8.6.2.15 void serve\_evaluations\_synch () [private]

one synchronous evaluation at a time

This code is invoked by [serve\\_evaluations\(\)](#) to perform one synchronous job at a time on each slave/peer server. The servers receive requests (blocking receive), do local synchronous maps, and return results. This is done continuously until a termination signal is received from the master (sent via [stop\\_evaluation\\_servers\(\)](#)).

#### 8.6.2.16 void serve\_evaluations\_asynch () [private]

multiple asynchronous evaluations

This code is invoked by [serve\\_evaluations\(\)](#) to perform multiple asynchronous jobs on each slave/peer server. The servers test for any incoming jobs, launch any new jobs, process any completed jobs, and return any results. Each

of these components is nonblocking, although the server loop continues until a termination signal is received from the master (sent via [stop\\_evaluation\\_servers\(\)](#)). In the master-slave case, the master maintains the correct number of jobs on each slave. In the static scheduling case, each server is responsible for limiting concurrency (since the entire static schedule is sent to the peers at start up).

#### 8.6.2.17 void `serve_evaluations_peer()` [private]

one synchronous evaluation at a time as part of the 1st peer

This code is invoked by [serve\\_evaluations\(\)](#) to perform a synchronous evaluation in coordination with the `iteratorCommRank 0` processor (the iterator) for static schedules. The `bcast()` matches either the `bcast()` in [synchronous\\_local\\_evaluations\(\)](#), which is invoked by [static\\_schedule\\_evaluations\(\)](#), or the `bcast()` in [map\(\)](#).

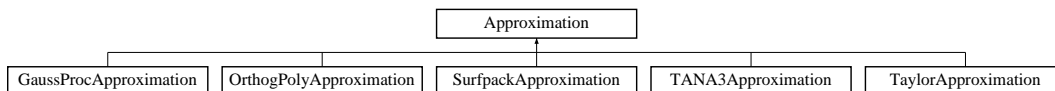
The documentation for this class was generated from the following files:

- `ApplicationInterface.H`
- `ApplicationInterface.C`

## 8.7 Approximation Class Reference

Base class for the approximation class hierarchy.

Inheritance diagram for Approximation::



### Public Member Functions

- [Approximation](#) ()  
*default constructor*
- [Approximation](#) ([ProblemDescDB](#) &problem\_db, const size\_t &num\_vars)  
*standard constructor for envelope*
- [Approximation](#) (const [String](#) &approx\_type, short approx\_order, const size\_t &num\_vars)  
*alternate constructor*
- [Approximation](#) (const [Approximation](#) &approx)  
*copy constructor*
- virtual [~Approximation](#) ()  
*destructor*
- [Approximation](#) operator= (const [Approximation](#) &approx)  
*assignment operator*
- virtual const Real & [get\\_value](#) (const [RealVector](#) &x)  
*retrieve the approximate function value for a given parameter vector*
- virtual const [RealBaseVector](#) & [get\\_gradient](#) (const [RealVector](#) &x)  
*retrieve the approximate function gradient for a given parameter vector*
- virtual const [RealMatrix](#) & [get\\_hessian](#) (const [RealVector](#) &x)  
*retrieve the approximate function Hessian for a given parameter vector*
- virtual const Real & [get\\_variance](#) (const [RealVector](#) &x)  
*retrieve the variance of the predicted value for a given parameter vector*

- virtual const [RealVector](#) & [approximation\\_coefficients](#) () const  
*return the coefficient array computed by [find\\_coefficients\(\)](#)*
- virtual void [approximation\\_coefficients](#) (const [RealVector](#) &approx\_coeffs)  
*computing with [find\\_coefficients\(\)](#)*
- virtual void [print\\_coefficients](#) (ostream &s) const  
*print the coefficient array computed in [find\\_coefficients\(\)](#)*
- virtual int [num\\_coefficients](#) () const  
*derived class approximation type in numVars dimensions*
- virtual int [num\\_constraints](#) () const  
*return the number of constraints to be enforced via anchorPoint*
- virtual void [clear\\_current](#) ()  
*clear current build data in preparation for next build*
- int [required\\_samples](#) (bool constraint\_flag) const  
*type in numVars dimensions. Uses [num\\_coefficients\(\)](#) and [num\\_constraints\(\)](#).*
- int [num\\_variables](#) () const  
*return the number of variables used in the approximation*
- const [List](#)< [SurrogateDataPoint](#) > & [current\\_points](#) () const  
*return currentPoints*
- const [SurrogateDataPoint](#) & [anchor\\_point](#) () const  
*return anchorPoint*
- void [update](#) (const [Variables](#) &vars, const [Response](#) &response, const int &fn\_index)  
*populates/replaces anchorPoint*
- void [update](#) (const [RealVector](#) &c\_vars, const Real &fn\_val, const [RealBaseVector](#) &fn\_grad, const [RealMatrix](#) &fn\_hess)  
*populates/replaces anchorPoint*
- void [update](#) (const [VariablesArray](#) &vars\_array, const [ResponseArray](#) &resp\_array, const int &fn\_index)  
*populates/replaces currentPoints*
- void [append](#) (const [Variables](#) &vars, const [Response](#) &response, const int &fn\_index)  
*appends one additional entry to currentPoints*
- void [append](#) (const [RealVector](#) &c\_vars, const Real &fn\_val, const [RealBaseVector](#) &fn\_grad, const [RealMatrix](#) &fn\_hess)  
*appends one additional entry to currentPoints*



- void `append` (const `VariablesArray` &vars\_array, const `ResponseArray` &resp\_array, const int &fn\_index)  
*appends multiple additional entries to currentPoints*
- void `build` ()  
*builds the approximation by invoking `find_coefficients()`*
- bool `anchor` () const  
*queries the status of anchorPoint*
- void `clear_all` ()  
*clear all build data (current and history) to restore original state*
- void `set_bounds` (const `RealVector` &lower, const `RealVector` &upper)  
*set approximation lower and upper bounds (currently only used by graphics)*
- void `draw_surface` ()  
*problems only)*
- `Approximation * approx_rep` () const  
*that are not mapped to the top `Approximation` level*

### Protected Member Functions

- `Approximation` (`BaseConstructor`, `ProblemDescDB` &problem\_db, const size\_t &num\_vars)  
*derived class constructors - Coplien, p. 139)*
- virtual void `find_coefficients` ()  
*calculate the data fit coefficients using currentPoints and anchorPoint*

### Protected Attributes

- bool `useGradsFlag`  
*trust region), but not require gradient evaluations at every point.*
- bool `verboseFlag`  
*flag for verbose approximation output*
- int `numVars`  
*number of variables in the approximation*
- String `approxType`  
*approximation type identifier*

- short [approxOrder](#)  
*orthogonal polynomials, and Taylor series)*
- Real [approxValue](#)  
*value of the approximation returned by [get\\_value\(\)](#)*
- [RealBaseVector](#) [approxGradient](#)  
*gradient of the approximation returned by [get\\_gradient\(\)](#)*
- [RealMatrix](#) [approxHessian](#)  
*Hessian of the approximation returned by [get\\_hessian\(\)](#).*
- Real [approxVariance](#)  
*value of the approximation returned by [get\\_variance\(\)](#)*
- [List](#)< [SurrogateDataPoint](#) > [currentPoints](#)  
*are fit approximately (e.g., using least squares regression).*
- [SurrogateDataPoint](#) [anchorPoint](#)  
*least squares regression).*

## Private Member Functions

- [Approximation](#) \* [get\\_approx](#) ([ProblemDescDB](#) &problem\_db, const size\_t &num\_vars)  
*approxRep to the appropriate derived type.*
- [Approximation](#) \* [get\\_approx](#) (const [String](#) &approx\_type, short approx\_order, const size\_t &num\_vars)  
*approxRep to the appropriate derived type.*
- void [add](#) (const [Variables](#) &vars, const [Response](#) &response, const int &fn\_index, bool anchor\_flag)  
*add\_anchor()*.
- void [add\\_point](#) (const [RealVector](#) &x, const Real &fn\_val, const [RealBaseVector](#) &fn\_grad, const [RealMatrix](#) &fn\_hess)  
*add a new data point by appending to currentPoints*
- void [add\\_anchor](#) (const [RealVector](#) &x, const Real &fn\_val, const [RealBaseVector](#) &fn\_grad, const [RealMatrix](#) &fn\_hess)  
*add a new data point by assigning to anchorPoint*

## Private Attributes

- [RealVector approxLowerBounds](#)  
*approximation lower bounds (used only by 3D graphics)*
- [RealVector approxUpperBounds](#)  
*approximation upper bounds (used only by 3D graphics)*
- [Approximation \\* approxRep](#)  
*pointer to the letter (initialized only for the envelope)*
- [int referenceCount](#)  
*number of objects sharing approxRep*

### 8.7.1 Detailed Description

Base class for the approximation class hierarchy.

The [Approximation](#) class is the base class for the response data fit approximation class hierarchy in DAKOTA. One instance of an [Approximation](#) must be created for each function to be approximated (a vector of Approximations is contained in [ApproximationInterface](#)). For memory efficiency and enhanced polymorphism, the approximation hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Approximation](#)) serves as the envelope and one of the derived classes (selected in `Approximation::get_approximation()`) serves as the letter.

### 8.7.2 Constructor & Destructor Documentation

#### 8.7.2.1 [Approximation](#) ()

default constructor

The default constructor is used in `Array<Approximation>` instantiations and by the alternate envelope constructor. `approxRep` is NULL in this case (`problem_db` is needed to build a meaningful [Approximation](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

#### 8.7.2.2 [Approximation](#) ([ProblemDescDB](#) & *problem\_db*, `const size_t` & *num\_vars*)

standard constructor for envelope

Envelope constructor only needs to extract enough data to properly execute `get_approx`, since `Approximation(BaseConstructor, problem_db)` builds the actual base class data for the derived approximations.

### 8.7.2.3 **Approximation** (const **String** & *approx\_type*, short *approx\_order*, const *size\_t* & *num\_vars*)

alternate constructor

This is the alternate envelope constructor for instantiations on the fly. Since it does not have access to `problem_db`, the letter class is not fully populated. This constructor executes `get_approx(type)`, which invokes the default constructor of the derived letter class, which in turn invokes the default constructor of the base class.

### 8.7.2.4 **Approximation** (const **Approximation** & *approx*)

copy constructor

Copy constructor manages sharing of `approxRep` and incrementing of `referenceCount`.

### 8.7.2.5 **~Approximation** () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `approxRep` when `referenceCount` reaches zero.

### 8.7.2.6 **Approximation** (**BaseConstructor**, **ProblemDescDB** & *problem\_db*, const *size\_t* & *num\_vars*) [protected]

derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. `get_approx()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid recursion in the base class constructor calling `get_approx()` again). Since the letter IS the representation, its rep pointer is set to NULL (an uninitialized pointer causes problems in `~Approximation`).

## 8.7.3 Member Function Documentation

### 8.7.3.1 **Approximation** operator= (const **Approximation** & *approx*)

assignment operator

Assignment operator decrements `referenceCount` for old `approxRep`, assigns new `approxRep`, and increments `referenceCount` for new `approxRep`.

### 8.7.3.2 **void clear\_current** () [inline, virtual]

clear current build data in preparation for next build

Redefined by [TANA3Approximation](#) to clear current data but preserve history.

Reimplemented in [TANA3Approximation](#).

**8.7.3.3 void clear\_all () [inline]**

clear all build data (current and history) to restore original state

Clears out any history (e.g., [TANA3Approximation](#) use for a different response function in [NonDReliability](#)).

**8.7.3.4 Approximation \* get\_approx (ProblemDescDB & problem\_db, const size\_t & num\_vars) [private]**

approxRep to the appropriate derived type.

Used only by the envelope constructor to initialize approxRep to the appropriate derived type.

**8.7.3.5 Approximation \* get\_approx (const String & approx\_type, short approx\_order, const size\_t & num\_vars) [private]**

approxRep to the appropriate derived type.

Used only by the envelope constructor to initialize approxRep to the appropriate derived type.

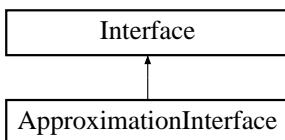
The documentation for this class was generated from the following files:

- DakotaApproximation.H
- DakotaApproximation.C

## 8.8 ApproximationInterface Class Reference

approximations to simulation-based results.

Inheritance diagram for ApproximationInterface::



### Public Member Functions

- [ApproximationInterface](#) ([ProblemDescDB](#) &problem\_db, const [Variables](#) &actual\_model\_vars, const size\_t &num\_fns)  
*primary constructor*
- [ApproximationInterface](#) (const [String](#) &approx\_type, const short &approx\_order, const [Variables](#) &actual\_model\_vars, const size\_t &num\_fns)  
*alternate constructor for instantiations on the fly*
- [~ApproximationInterface](#) ()  
*destructor*

### Protected Member Functions

- void [map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, const bool asynch\_flag=false)  
*the variables to the responses using functionSurfaces*
- int [minimum\\_samples](#) (bool constraint\_flag) const  
*functionSurfaces*
- void [approximation\\_function\\_indices](#) (const IntSet &approx\_fn\_indices)  
*set the (currently active) approximation function index set*
- void [update\\_approximation](#) (const [Variables](#) &vars, const [Response](#) &response)
- void [update\\_approximation](#) (const [VariablesArray](#) &vars\_array, const [ResponseArray](#) &resp\_array)
- void [append\\_approximation](#) (const [Variables](#) &vars, const [Response](#) &response)
- void [append\\_approximation](#) (const [VariablesArray](#) &vars\_array, const [ResponseArray](#) &resp\_array)
- void [build\\_approximation](#) (const [RealVector](#) &lower\_bnds, const [RealVector](#) &upper\_bnds)

- void `clear_current ()`  
*clears current data from an approximation interface*
- void `clear_all ()`  
*clears all data from an approximation interface*
- bool `anchor () const`  
*queries the presence of an anchorPoint within an approximation interface*
- `Array< Approximation > & approximations ()`  
*retrieve the Approximations within an ApproximationInterface*
- const `RealVectorArray & approximation_coefficients ()`  
*within an ApproximationInterface*
- void `approximation_coefficients (const RealVectorArray &approx_coeffs)`  
*within an ApproximationInterface*
- void `print_coefficients (ostream &s, size_t index) const`  
*Approximation instance within an ApproximationInterface.*
- const `RealVector & approximation_variances (const RealVector &c_vars)`  
*within an ApproximationInterface*
- const `List< SurrogateDataPoint > & approximation_data (size_t index)`  
*within an ApproximationInterface*
- const `ResponseArray & synch ()`  
*recovers data from a series of asynchronous evaluations (blocking)*
- const `IntResponseMap & synch_nowait ()`  
*recovers data from a series of asynchronous evaluations (nonblocking)*

### Private Attributes

- `IntSet approxFnIndices`  
*response function subset that is approximated*
- `Array< Approximation > functionSurfaces`  
*list of approximations, one per response function*
- `RealVectorArray functionSurfaceCoeffs`  
*response function*
- `RealVector functionSurfaceVariances`

*vector of approximation variances, one value per response function*

- [List< SurrogateDataPoint > functionSurfaceDataPoints](#)  
*for a particular response function*
- [bool graphicsFlag](#)  
*controls 3D graphics of approximation surfaces*
- [Variables actualModelVars](#)  
*among differing variable views*
- [IntResponseMap beforeSynchResponseMap](#)  
*but asynchronous virtual functions are supported through bookkeeping).*

### 8.8.1 Detailed Description

approximations to simulation-based results.

[ApproximationInterface](#) provides an interface class for building a set of global/local/multipoint approximations and performing approximate function evaluations using them. It contains a list of [Approximation](#) objects, one for each response function.

### 8.8.2 Member Function Documentation

**8.8.2.1 void update\_approximation (const [Variables](#) & vars, const [Response](#) & response)** [protected, virtual]

This function populates/replaces each [Approximation::anchorPoint](#) with the incoming variables/response data point.

Reimplemented from [Interface](#).

**8.8.2.2 void update\_approximation (const [VariablesArray](#) & vars\_array, const [ResponseArray](#) & resp\_array)** [protected, virtual]

This function populates/replaces each [Approximation::currentPoints](#) with the incoming variables/response arrays.

Reimplemented from [Interface](#).

**8.8.2.3 void append\_approximation (const [Variables](#) & vars, const [Response](#) & response)**  
[protected, virtual]

This function appends to each [Approximation::currentPoints](#) with one incoming variables/response data point.

Reimplemented from [Interface](#).



**8.8.2.4** `void append_approximation (const VariablesArray & vars_array, const ResponseArray & resp_array)` [protected, virtual]

This function appends to each `Approximation::currentPoints` with multiple incoming variables/response data points.

Reimplemented from [Interface](#).

**8.8.2.5** `void build_approximation (const RealVector & lower_bnds, const RealVector & upper_bnds)` [protected, virtual]

This function finds the coefficients for each `Approximation` based on the data passed through `update_approximation()` calls. The bounds are used only for graphics visualization.

Reimplemented from [Interface](#).

### 8.8.3 Member Data Documentation

**8.8.3.1** `Array<Approximation> functionSurfaces` [private]

list of approximations, one per response function

This formulation allows the use of mixed approximations (i.e., different approximations used for different response functions), although the input specification is not currently general enough to support it.

The documentation for this class was generated from the following files:

- `ApproximationInterface.H`
- `ApproximationInterface.C`

## 8.9 Array Class Template Reference

Template class for the [Dakota](#) bookkeeping array.

### Public Member Functions

- [Array](#) ()  
*Default constructor.*
- [Array](#) (size\_t size)  
*Constructor which takes an initial size.*
- [Array](#) (size\_t size, const T &initial\_val)  
*Constructor which takes an initial size and an initial value.*
- [Array](#) (const [Array](#)< T > &a)  
*Copy constructor.*
- [Array](#) (const T \*p, size\_t size)  
*Constructor which copies size entries from T\*.*
- [~Array](#) ()  
*Destructor.*
- [Array](#)< T > & [operator=](#) (const [Array](#)< T > &a)  
*Normal const assignment operator.*
- [Array](#)< T > & [operator=](#) ([Array](#)< T > &a)  
*Normal assignment operator.*
- [Array](#)< T > & [operator=](#) (const T &ival)  
*Sets all elements in self to the value ival.*
- [operator T \\*](#) () const  
*Converts the [Array](#) to a standard C-style array. Use with care!*
- T & [operator\[\]](#) (int i)  
*alternate bounds-checked indexing operator for int indices*
- const T & [operator\[\]](#) (int i) const  
*alternate bounds-checked const indexing operator for int indices*

- `T & operator[] (size_t i)`  
*Index operator, returns the *i*th value of the array.*
- `const T & operator[] (size_t i) const`  
*Index operator const, returns the *i*th value of the array.*
- `T & operator() (size_t i)`  
*Index operator, not bounds checked.*
- `const T & operator() (size_t i) const`  
*Index operator const, not bounds checked.*
- `void read (istream &s)`  
*Reads an *Array* from an *istream*.*
- `void write (ostream &s) const`  
*Writes an *Array* to an output stream.*
- `void write (ostream &s, const Array< String > &label_array) const`  
*Writes an *Array* and associated label array to an output stream.*
- `void write_aprepro (ostream &s, const Array< String > &label_array) const`  
*aprepro format*
- `void write_annotated (ostream &s, bool write_len) const`  
*Writes an *Array* to an output stream in annotated format.*
- `void read (BiStream &s)`  
*Reads an *Array* from a binary input stream.*
- `void write (BoStream &s) const`  
*Writes an *Array* to a binary output stream.*
- `void read (MPIUnpackBuffer &s)`  
*Reads an *Array* from a buffer after an MPI receive.*
- `void write (MPIPackBuffer &s) const`  
*Writes an *Array* to a buffer prior to an MPI send.*
- `size_t length () const`  
*Returns size of array.*
- `void reshape (size_t sz)`  
*Resizes array to size *sz*.*
- `size_t index (const T &a) const`

Returns the index of the first array item which matches the object *a*.

- bool [contains](#) (const T &a) const

Checks if the array contains an object which matches the object *a*.

- size\_t [count](#) (const T &a) const

Returns the number of items in the array matching the object *a*.

- const T \* [data](#) () const

Returns pointer T\* to continuous data.

### 8.9.1 Detailed Description

```
template<class T> class Dakota::Array< T >
```

Template class for the [Dakota](#) bookkeeping array.

An array class template that provides additional functionality that is specific to Dakota's needs. The [Array](#) class adds additional functionality needed by [Dakota](#) to the inherited base array class. The [Array](#) class can inherit from either the STL or RW vector classes.

### 8.9.2 Constructor & Destructor Documentation

#### 8.9.2.1 [Array](#) (const T \*p, size\_t size) [inline]

Constructor which copies size entries from T\*.

Assigns size values from p into array.

### 8.9.3 Member Function Documentation

#### 8.9.3.1 [Array](#)< T > & operator= (const T &ival) [inline]

Sets all elements in self to the value ival.

Assigns all values of array to the value passed in as ival. For the Rogue Wave case, utilizes base class operator=(ival), while for the ANSI case, uses the STL assign() method.

**8.9.3.2 operator T \* () const** [inline]

Converts the [Array](#) to a standard C-style array. Use with care!

The operator() returns a c style pointer to the data within the array. Calls the [data\(\)](#) method. USE WITH CARE.

**8.9.3.3 ]**

T & operator[] (size\_t i) [inline]

Index operator, returns the ith value of the array.

Index operator; calls the STL method at() which is bounds checked. Mimics the RW vector class. Note: the at() method is not supported by the \_\_GNUC\_\_ STL implementation or by builds omitting exceptions (e.g., SIERRA).

**8.9.3.4 ]**

const T & operator[] (size\_t i) const [inline]

Index operator const, returns the ith value of the array.

A const version of the index operator; calls the STL method at() which is bounds checked. Mimics the RW vector class. Note: the at() method is not supported by the \_\_GNUC\_\_ STL implementation or by builds omitting exceptions (e.g., SIERRA).

**8.9.3.5 T & operator() (size\_t i)** [inline]

Index operator, not bounds checked.

Non bounds check index operator, calls the STL operator[] which is not bounds checked. Needed to mimic the RW vector class

**8.9.3.6 const T & operator() (size\_t i) const** [inline]

Index operator const, not bounds checked.

A const version of the non-bounds check index operator, calls the STL operator[] which is not bounds checked. Needed to mimic the RW vector class

**8.9.3.7 const T \* data () const** [inline]

Returns pointer T\* to continuous data.

Returns a C style pointer to the data within the array. USE WITH CARE. Needed to mimic RW vector class, is used in the operator(). Uses the STL front method.

The documentation for this class was generated from the following file:

- DakotaArray.H

## 8.10 BaseConstructor Struct Reference

Dummy struct for overloading letter-envelope constructors.

### Public Member Functions

- [BaseConstructor](#) (int=0)  
*C++ structs can have constructors.*

#### 8.10.1 Detailed Description

Dummy struct for overloading letter-envelope constructors.

[BaseConstructor](#) is used to overload the constructor for the base class portion of letter objects. It avoids infinite recursion (Coplien p.139) in the letter-envelope idiom by preventing the letter from instantiating another envelope. Putting this struct here avoids circular dependencies.

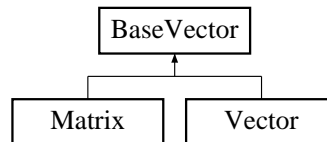
The documentation for this struct was generated from the following file:

- `global_defs.h`

## 8.11 BaseVector Class Template Reference

Base class for the [Dakota::Matrix](#) and [Dakota::Vector](#) classes.

Inheritance diagram for BaseVector::



### Public Member Functions

- [BaseVector](#) ()  
*Default constructor.*
- [BaseVector](#) (size\_t size)  
*Constructor, creates vector of size.*
- [BaseVector](#) (size\_t size, const T &initial\_val)  
*Constructor, creates vector of size with initial value of initial\_val.*
- [~BaseVector](#) ()  
*Destructor.*
- [BaseVector](#) (const [BaseVector](#)< T > &a)  
*Copy constructor.*
- [BaseVector](#)< T > & [operator=](#) (const [BaseVector](#)< T > &a)  
*Normal assignment operator.*
- [BaseVector](#)< T > & [operator=](#) (const T &ival)  
*Assigns all values of vector to ival.*
- T & [operator](#)[ ] (int i)  
*alternate bounds-checked indexing operator for int indices*
- const T & [operator](#)[ ] (int i) const  
*alternate bounds-checked const indexing operator for int indices*
- T & [operator](#)[ ] (size\_t i)  
*Returns the object at index i, (can use as lvalue).*

- `const T & operator[] (size_t i) const`  
*Returns the object at index i, const (can't use as lvalue).*
- `T & operator() (size_t i)`  
*Index operator, not bounds checked.*
- `const T & operator() (size_t i) const`  
*Index operator const , not bounds checked.*
- `size_t length () const`  
*Returns size of vector.*
- `void reshape (size_t sz)`  
*Resizes vector to size sz.*
- `const T * data () const`  
*Returns const pointer to standard C array. Use with care.*

## Protected Member Functions

- `T * array () const`  
*Returns pointer to standard C array. Use with care.*

### 8.11.1 Detailed Description

`template<class T> class Dakota::BaseVector< T >`

Base class for the `Dakota::Matrix` and `Dakota::Vector` classes.

The `Dakota::BaseVector` class is the base class for the `Dakota::Matrix` class. It is used to define a common vector interface for both the STL and RW vector classes. If the STL version is based on the `valarray` class then some basic vector operations such as `+`, `*` are available.

### 8.11.2 Constructor & Destructor Documentation

#### 8.11.2.1 `BaseVector (size_t size, const T & initial_val) [inline]`

Constructor, creates vector of size with initial value of `initial_val`.

Constructor which takes an initial size and an initial value, allocates an area of initial size and initializes it with input value. Calls base class constructor



### 8.11.3 Member Function Documentation

#### 8.11.3.1 ]

`T & operator[] (size_t i) [inline]`

Returns the object at index `i`, (can use as lvalue).

Index operator, calls the STL method `at()` which is bounds checked. Mimics the RW vector class. Note: the `at()` method is not supported by the `__GNUC__` STL implementation or by builds omitting exceptions (e.g., SIERRA).

#### 8.11.3.2 ]

`const T & operator[] (size_t i) const [inline]`

Returns the object at index `i`, `const` (can't use as lvalue).

Const versions of the index operator calls the STL method `at()` which is bounds checked. Mimics the RW vector class. Note: the `at()` method is not supported by the `__GNUC__` STL implementation or by builds omitting exceptions (e.g., SIERRA).

#### 8.11.3.3 `T & operator() (size_t i) [inline]`

Index operator, not bounds checked.

Non bounds check index operator, calls the STL `operator[]` which is not bounds checked. Needed to mimic the RW vector class

#### 8.11.3.4 `const T & operator() (size_t i) const [inline]`

Index operator `const`, not bounds checked.

Const version of the non-bounds check index operator, calls the STL `operator[]` which is not bounds checked. Needed to mimic the RW vector class

#### 8.11.3.5 `size_t length () const [inline]`

Returns size of vector.

Returns the length of the array by calling the STL `size` method. Needed to mimic the RW vector class

#### 8.11.3.6 `void reshape (size_t sz) [inline]`

Resizes vector to size `sz`.

Resizes the array to size `sz` by calling the STL `resize` method. Needed to mimic the RW vector class

**8.11.3.7** `const T * data () const` [inline]

Returns const pointer to standard C array. Use with care.

Returns a const pointer to the data within the array. USE WITH CARE. Needed to mimic RW vector class.

**8.11.3.8** `T * array () const` [inline, protected]

Returns pointer to standard C array. Use with care.

Returns a non-const pointer to the data within the array. Non-const version of [data\(\)](#) used by derived classes.

The documentation for this class was generated from the following file:

- DakotaBaseVector.H

## 8.12 BiStream Class Reference

data types

### Public Member Functions

- [BiStream \(\)](#)  
*Default constructor, need to open.*
- [BiStream \(const char \\*s\)](#)  
*Constructor takes name of input file.*
- [BiStream \(const char \\*s, std::ios\\_base::openmode mode\)](#)  
*Constructor takes name of input file, mode.*
- [BiStream \(const char \\*s, int mode\)](#)  
*Constructor takes name of input file, mode.*
- [~BiStream \(\)](#)  
*Destructor, calls `xdr_destroy` to delete xdr stream.*
- [BiStream & operator>> \(String &ds\)](#)  
*Binary Input stream operator>>.*
- [BiStream & operator>> \(char \\*s\)](#)  
*Input operator, reads char\* from binary stream [BiStream](#).*
- [BiStream & operator>> \(char &c\)](#)  
*Input operator, reads char from binary stream [BiStream](#).*
- [BiStream & operator>> \(int &i\)](#)  
*Input operator, reads int\* from binary stream [BiStream](#).*
- [BiStream & operator>> \(long &l\)](#)  
*Input operator, reads long from binary stream [BiStream](#).*
- [BiStream & operator>> \(short &s\)](#)  
*Input operator, reads short from binary stream [BiStream](#).*
- [BiStream & operator>> \(bool &b\)](#)  
*Input operator, reads bool from binary stream [BiStream](#).*

- [BiStream](#) & `operator>>` (double &d)  
*Input operator, reads double from binary stream [BiStream](#).*
- [BiStream](#) & `operator>>` (float &f)  
*Input operator, reads float from binary stream [BiStream](#).*
- [BiStream](#) & `operator>>` (unsigned char &c)  
*Input operator, reads unsigned char\* from binary stream [BiStream](#).*
- [BiStream](#) & `operator>>` (unsigned int &i)  
*Input operator, reads unsigned int from binary stream [BiStream](#).*
- [BiStream](#) & `operator>>` (unsigned long &l)  
*Input operator, reads unsigned long from binary stream [BiStream](#).*
- [BiStream](#) & `operator>>` (unsigned short &s)  
*Input operator, reads unsigned short from binary stream [BiStream](#).*

## Private Attributes

- XDR [xdrInBuf](#)  
*XDR input stream buffer.*
- char [inBuf](#) [MAX\_NETOBJ\_SZ]  
*Buffer to hold data as it is read in.*

### 8.12.1 Detailed Description

data types

The [Dakota::BiStream](#) class is a binary input class which overloads the `>>` operator for all standard data types (int, char, float, etc). The class relies on the methods within the `ifstream` base class. The [Dakota::BiStream](#) class inherits from the `ifstream` class. If available, the class utilize `rpc/xdr` to construct machine independent binary files. These [Dakota](#) restart files can be moved from host to host. The motivation to develop these classes was to replace the `Rogue wave` classes which [Dakota](#) historically used for binary I/O.

### 8.12.2 Constructor & Destructor Documentation

### 8.12.2.1 **BiStream** ()

Default constructor, need to open.

Default constructor, allocates xdr stream , but does not call the open method. The open method must be called before stream can be read.

### 8.12.2.2 **BiStream** (const char \* s)

Constructor takes name of input file.

Constructor which takes a char\* filename. Calls the base class open method with the filename and no other arguments. Also allocates the xdr stream.

### 8.12.2.3 **BiStream** (const char \* s, std::ios\_base::openmode mode)

Constructor takes name of input file, mode.

Constructor which takes a char\* filename and int flags. Calls the base class open method with the filename and flags as arguments. Also allocates xdr stream.

### 8.12.2.4 **~BiStream** ()

Destructor, calls xdr\_destroy to delete xdr stream.

Destructor, destroys the xdr stream allocated in constructor

## 8.12.3 Member Function Documentation

### 8.12.3.1 **BiStream** & operator>> (String & ds)

Binary Input stream operator>>.

The **String** input operator must first read both the xdr buffer size and the size of the string written. Once these our read it can then read and convert the **String** correctly.

### 8.12.3.2 **BiStream** & operator>> (char \* s)

Input operator, reads char\* from binary stream **BiStream**.

Reading char array is a special case. The method has no way of knowing if the length to the input array is large enough, it assumes it is one char longer than actual string, (Null terminator added). As with the **String** the size of the xdr buffer as well as the char array size written must be read from the stream prior to reading and converting the char array.

The documentation for this class was generated from the following files:

- [DakotaBinStream.H](#)
- [DakotaBinStream.C](#)

## 8.13 BoStream Class Reference

data types

### Public Member Functions

- [BoStream \(\)](#)  
*Default constructor, need to open.*
- [BoStream \(const char \\*s\)](#)  
*Constructor takes name of input file.*
- [BoStream \(const char \\*s, std::ios\\_base::openmode mode\)](#)  
*Constructor takes name of input file, mode.*
- [BoStream \(const char \\*s, int mode\)](#)  
*Constructor takes name of input file, mode.*
- [~BoStream \(\)](#)  
*Destructor, calls `xdr_destroy` to delete xdr stream.*
- [BoStream & operator<< \(const String &ds\)](#)  
*Binary Output stream operator<<.*
- [BoStream & operator<< \(const char \\*s\)](#)  
*Output operator, writes char\* TO binary stream [BoStream](#).*
- [BoStream & operator<< \(const char &c\)](#)  
*Output operator, writes char to binary stream [BoStream](#).*
- [BoStream & operator<< \(const int &i\)](#)  
*Output operator, writes int to binary stream [BoStream](#).*
- [BoStream & operator<< \(const long &l\)](#)  
*Output operator, writes long to binary stream [BoStream](#).*
- [BoStream & operator<< \(const short &s\)](#)  
*Output operator, writes short to binary stream [BoStream](#).*
- [BoStream & operator<< \(const bool &b\)](#)  
*Output operator, writes bool to binary stream [BoStream](#).*

- [BoStream](#) & `operator<<` (const double &d)  
*Output operator, writes double to binary stream [BoStream](#).*
- [BoStream](#) & `operator<<` (const float &f)  
*Output operator, writes float to binary stream [BoStream](#).*
- [BoStream](#) & `operator<<` (const unsigned char &c)  
*Output operator, writes unsigned char to binary stream [BoStream](#).*
- [BoStream](#) & `operator<<` (const unsigned int &i)  
*Output operator, writes unsigned int to binary stream [BoStream](#).*
- [BoStream](#) & `operator<<` (const unsigned long &l)  
*Output operator, writes unsigned long to binary stream [BoStream](#).*
- [BoStream](#) & `operator<<` (const unsigned short &s)  
*Output operator, writes unsigned short to binary stream [BoStream](#).*

## Private Attributes

- XDR [xdrOutBuf](#)  
*XDR output stream buffer.*
- char [outBuf](#) [MAX\_NETOBJ\_SZ]  
*Buffer to hold converted data before it is written.*

### 8.13.1 Detailed Description

data types

The [Dakota::BoStream](#) class is a binary output classes which overloads the `<<` operator for all standard data types (int, char, float, etc). The class relies on the built in write methods within the ostream base classes. [Dakota::BoStream](#) inherits from the ostream class. The motivation to develop this class was to replace the Rogue wave class which [Dakota](#) historically used for binary I/O. If available, the class utilize rpc/xdr to construct machine independent binary files. These [Dakota](#) restart files can be moved between hosts.

### 8.13.2 Constructor & Destructor Documentation



### 8.13.2.1 BoStream ()

Default constructor, need to open.

Default constructor allocates the xdr stream but does not call the open() method. The open() method must be called before stream can be written to.

### 8.13.2.2 BoStream (const char \* s)

Constructor takes name of input file.

Constructor, takes char \* filename as argument. Calls base class open method with filename and no other arguments. Also allocates xdr stream

### 8.13.2.3 BoStream (const char \* s, std::ios\_base::openmode mode)

Constructor takes name of input file, mode.

Constructor, takes char \* filename and int flags as arguments. Calls base class open method with filename and flags as arguments. Also allocates xdr stream. Note : If no rpc/xdr support xdr calls are #ifdef'd out.

## 8.13.3 Member Function Documentation

### 8.13.3.1 BoStream & operator<< (const String & ds)

Binary Output stream operator<<.

The [String](#) operator<< must first write the xdr buffer size and the original string size to the stream. The input operator needs this information to be able to correctly read and convert the [String](#).

### 8.13.3.2 BoStream & operator<< (const char \* s)

Output operator, writes char\* TO binary stream [BoStream](#).

The output of char\* is the same as the output of the [String](#). The size of the xdr buffer and the size of the string must be written first, then the string itself.

The documentation for this class was generated from the following files:

- DakotaBinStream.H
- DakotaBinStream.C

## 8.14 COLINApplication Class Reference

### Public Member Functions

- [COLINApplication \(Model &model\)](#)  
*constructor*
- [~COLINApplication \(\)](#)  
*destructor*
- void [DoEval \(ColinPoint &point, int &priority, ColinResponse \\*response, bool synch\\_flag\)](#)  
*launch a function evaluation either synchronously or asynchronously*
- unsigned int [num\\_evaluation\\_servers \(\)](#)  
*The value '0' indicates that this is a sequential application.*
- void [synchronize \(\)](#)  
*blocking retrieval of all pending jobs*
- int [next\\_eval \(\)](#)  
*nonblocking query and retrieval of a job if completed*
- void [blocking\\_synch \(const bool &blocking\\_synch\)](#)  
*construct time.*
- void [dakota\\_asynch\\_flag \(const bool &asynch\\_flag\)](#)  
*(asynchFlag not initialized properly at construction).*

### Private Member Functions

- void [map\\_response \(ColinResponse &colin\\_response, const \[Response\]\(#\) &dakota\\_response\)](#)  
*utility function for mapping a DAKOTA response to a COLIN response*

### Private Attributes

- [Model](#) & [iteratedModel](#)  
*reference to the COLINOptimizer's model passed in the constructor*
- [ActiveSet](#) [activeSet](#)  
*copy/conversion of the COLIN request vector*

- bool [dakotaModelAsynchFlag](#)  
*a flag for asynchronous DAKOTA evaluations*
- bool [blockingSynch](#)  
*needed for APPS, to enforce blocking synch despite call of [next\\_eval\(\)](#).*
- IntResponseMap [dakotaResponseMap](#)  
*map of DAKOTA responses returned by [synchronize\\_nowait\(\)](#)*
- size\_t [numObjFns](#)  
*number of objective functions*
- size\_t [numNonlinCons](#)  
*number of nonlinear constraints*
- int [num\\_real\\_params](#)  
*number of continuous design variables*
- int [num\\_integer\\_params](#)  
*number of discrete design variables*
- int [synchronization\\_state](#)  
*tracks the state of asynchronous evaluations*

### 8.14.1 Detailed Description

[COLINApplication](#) is a DAKOTA class that is derived from COLIN's OptApplication hierarchy. It redefines a variety of virtual COLIN functions to use the corresponding DAKOTA functions. This is a more flexible algorithm library interfacing approach than can be obtained with the function pointer approaches used by [NPSOLOptimizer](#) and [SNLLOptimizer](#).

### 8.14.2 Member Function Documentation

#### 8.14.2.1 void DoEval ([ColinPoint](#) & *pt*, int & *priority*, ColinResponse \* *prob\_response*, bool *synch\_flag*)

launch a function evaluation either synchronously or asynchronously

Converts the [ColinPoint](#) variables and request vector to DAKOTA variables and active set vector, performs a DAKOTA function evaluation with synchronization governed by *synch\_flag*, and then copies the [Response](#) data to the ColinResponse response (synchronous) or bookkeeps the response object (asynchronous).

**8.14.2.2 void synchronize ()**

blocking retrieval of all pending jobs

Blocking synchronize of asynchronous DAKOTA jobs followed by conversion of the [Response](#) objects to Colin-Response response objects.

**8.14.2.3 int next\_eval ()**

nonblocking query and retrieval of a job if completed

Nonblocking job retrieval. Finds a completion (if available), populates the COLIN response, and sets id to the completed job's id. Else set id = -1.

**8.14.2.4 void map\_response (ColinResponse & colin\_response, const [Response](#) & dakota\_response)**  
[private]

utility function for mapping a DAKOTA response to a COLIN response

map\_response Maps a [Response](#) object into a ColinResponse class that is compatible with COLIN.

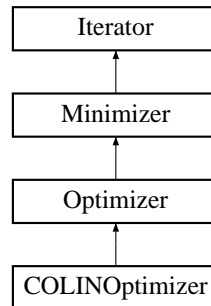
The documentation for this class was generated from the following files:

- COLINApplication.H
- COLINApplication.C

## 8.15 COLINOptimizer Class Template Reference

Wrapper class for optimizers defined using COLIN.

Inheritance diagram for COLINOptimizer::



### Public Member Functions

- [COLINOptimizer](#) ([Model](#) &model)

---

- [COLINOptimizer](#) ([Model](#) &model, int seed)  
*alternate constructor for on-the-fly instantiations*
- [~COLINOptimizer](#) ()  
*destructor*
- void [find\\_optimum](#) ()  
*Performs the iterations to determine the optimal solution.*
- bool [returns\\_multiple\\_points](#) () const  
*COLINY methods can return multiple points.*
- template<> void [set\\_method\\_parameters](#) ()
- template<> void [set\\_method\\_parameters](#) ()
- template<> void [set\\_method\\_parameters](#) ()
- template<> void [set\\_runtime\\_parameters](#) ()
- template<> void [set\\_method\\_parameters](#) ()
- template<> void [set\\_method\\_parameters](#) ()
- template<> void [set\\_method\\_parameters](#) ()
- template<> void [get\\_final\\_points](#) ()
- template<> void [get\\_final\\_points](#) ()
- template<> void [get\\_final\\_points](#) ()

## Protected Member Functions

- virtual void [set\\_rng](#) (int seed)  
*sets up the random number generator for stochastic methods*
- virtual void [set\\_initial\\_point](#) (ColinPoint &pt)  
*sets the iteration starting point prior to minimization*
- virtual void [get\\_min\\_point](#) (ColinPoint &pt)  
*retrieves the final solution after minimization*
- virtual void [set\\_method\\_parameters](#) ()  
*(called at construction time)*
- void [set\\_standard\\_method\\_parameters](#) ()  
*sets the standard method parameters shared by all methods*
- virtual void [set\\_runtime\\_parameters](#) ()  
*not available until run time*
- virtual void [get\\_final\\_points](#) ()  
*Get the set of best points from the solver.*
- void [resize\\_final\\_points](#) (size\_t newsize)  
*resize bestVariablesArray*

## Protected Attributes

- OptimizerT \* [optimizer](#)  
*Pointer to COLIN base optimizer object.*
- COLINApplication \* [application](#)  
*Pointer to the COLINApplication object.*
- colin::OptProblem< ColinPoint > [problem](#)  
*the COLIN problem object*
- utilib::RNG \* [rng](#)  
*RNG ptr.*
- bool [blockingSynch](#)  
*nonblocking*
- Real [solverStartTime](#)  
*Start time for keeping track of time for solver to run.*

- Real [solverTime](#)

*Time taken by solver to run.*

### 8.15.1 Detailed Description

**template<class OptimizerT> class Dakota::COLINOptimizer< OptimizerT >**

Wrapper class for optimizers defined using COLIN.

The [COLINOptimizer](#) class provides a templated wrapper for COLIN, a Sandia-developed C++ optimization interface library. A variety of COLIN optimizers are defined in the COLINY optimization library, which contains the optimization components from the old SGOPT library. COLINY contains optimizers such as genetic algorithms, pattern search methods, and other nongradient-based techniques. [COLINOptimizer](#) uses a [COLINApplication](#) object to perform the function evaluations.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `solution_accuracy` and `max_cpu_time` are mapped into COLIN's `max_iters`, `max_neval`, `ftol`, `accuracy`, and `max_time` data attributes. An output setting of `verbose` is passed to COLIN's `set_output()` function and a setting of `debug` activates output of method initialization and sets the COLIN debug attribute to 10000. Refer to [Hart, W.E., 2006] for additional information on COLIN objects and controls.

### 8.15.2 Member Function Documentation

#### 8.15.2.1 void find\_optimum () [inline, virtual]

Performs the iterations to determine the optimal solution.

`find_optimum` redefines the [Optimizer](#) virtual function to perform the optimization using COLIN. It first sets up the problem data, then executes `minimize()` on the COLIN optimizer, and finally catalogues the results.

Implements [Optimizer](#).

#### 8.15.2.2 void set\_standard\_method\_parameters () [inline, protected]

sets the standard method parameters shared by all methods

`set_standard_method_parameters` propagates standard DAKOTA user input to the optimizer.

#### 8.15.2.3 void set\_method\_parameters () [inline]

specialization of [set\\_method\\_parameters\(\)](#) for DIRECT

**8.15.2.4 void set\_method\_parameters () [inline]**

specialization of [set\\_method\\_parameters\(\)](#) for CobyLa

**8.15.2.5 void set\_method\_parameters () [inline]**

specialization of [set\\_method\\_parameters\(\)](#) for APPS

**8.15.2.6 void set\_runtime\_parameters () [inline]**

specialization of [set\\_runtime\\_parameters\(\)](#) for PatternSearch

**8.15.2.7 void set\_method\_parameters () [inline]**

specialization of [set\\_method\\_parameters\(\)](#) for PatternSearch

**8.15.2.8 void set\_method\_parameters () [inline]**

specialization of [set\\_method\\_parameters\(\)](#) for SolisWets

**8.15.2.9 void set\_method\_parameters () [inline]**

specialization of [set\\_method\\_parameters\(\)](#) for EAminlp

The documentation for this class was generated from the following file:

- COLINOptimizer.H



## 8.16 ColinPoint Class Reference

### Public Attributes

- `vector< double > rvec`  
*continuous parameter values*
- `vector< int > ivec`  
*discrete parameter values*

### 8.16.1 Detailed Description

A class containing a vector of doubles and integers.

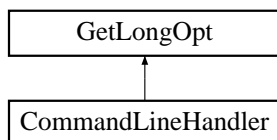
The documentation for this class was generated from the following file:

- COLINApplication.H

## 8.17 CommandLineHandler Class Reference

Utility class for managing command line inputs to DAKOTA.

Inheritance diagram for CommandLineHandler::



### Public Member Functions

- [CommandLineHandler](#) ()  
*default constructor, requires [check\\_usage\(\)](#) call for parsing*
- [CommandLineHandler](#) (int argc, char \*\*argv)  
*constructor with parsing*
- [~CommandLineHandler](#) ()  
*destructor*
- void [check\\_usage](#) (int argc, char \*\*argv)  
*Prints a descriptive message and exits the program if incorrect.*
- int [read\\_restart\\_evals](#) () const  
*instead of a const char\*.*

### Private Member Functions

- void [initialize\\_options](#) ()  
*enrolls the supported command line inputs.*
- void [output\\_version](#) (ostream &s) const  
*outputs the DAKOTA version*

### 8.17.1 Detailed Description

Utility class for managing command line inputs to DAKOTA.

[CommandLineHandler](#) provides additional functionality that is specific to DAKOTA's needs for the definition and parsing of command line options. Inheritance is used to allow the class to have all the functionality of the base class, [GetLongOpt](#).

The documentation for this class was generated from the following files:

- [CommandLineHandler.H](#)
- [CommandLineHandler.C](#)

## 8.18 CommandShell Class Reference

processes with system calls.

### Public Member Functions

- [CommandShell \(\)](#)  
*constructor*
- [~CommandShell \(\)](#)  
*destructor*
- [CommandShell & operator<< \(const char \\*string\)](#)  
*adds string to unixCommand*
- [CommandShell & operator<< \(CommandShell &\(\\*f\)\(CommandShell &\)\)](#)  
*allows passing of the flush function to the shell using <<*
- [CommandShell & flush \(\)](#)  
*"flushes" the shell; i.e. executes the unixCommand*
- void [asynch\\_flag](#) (const bool flag)  
*set the asynchFlag*
- bool [asynch\\_flag \(\)](#) const  
*get the asynchFlag*
- void [suppress\\_output\\_flag](#) (const bool flag)  
*set the suppressOutputFlag*
- bool [suppress\\_output\\_flag \(\)](#) const  
*get the suppressOutputFlag*

### Private Attributes

- [String unixCommand](#)  
*insertions and then executed by flush*
- bool [asynchFlag](#)  
*flags nonblocking operation (background system calls)*

- bool [suppressOutputFlag](#)  
*flags suppression of shell output (no command echo)*

### 8.18.1 Detailed Description

processes with system calls.

The [CommandShell](#) class wraps the C `system()` utility and defines convenience operators for building a command string and then passing it to the shell.

### 8.18.2 Member Function Documentation

#### 8.18.2.1 [CommandShell](#) & `flush ()`

"flushes" the shell; i.e. executes the `unixCommand`

Executes the `unixCommand` by passing it to `system()`. Appends an "&" if `asynchFlag` is set (background system call) and echos the `unixCommand` to `Cout` if `suppressOutputFlag` is not set.

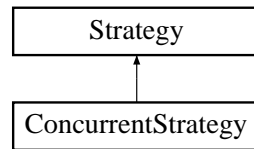
The documentation for this class was generated from the following files:

- `CommandShell.H`
- `CommandShell.C`

## 8.19 ConcurrentStrategy Class Reference

[Strategy](#) for multi-start iteration or pareto set optimization.

Inheritance diagram for ConcurrentStrategy::



### Public Member Functions

- [ConcurrentStrategy \(ProblemDescDB &problem\\_db\)](#)  
*constructor*
- [~ConcurrentStrategy \(\)](#)  
*destructor*
- void [run\\_strategy \(\)](#)  
*settings within the iterator or model.*

### Private Member Functions

- void [self\\_schedule\\_iterators \(\)](#)  
*among slave iterator servers (called by [run\\_strategy\(\)](#))*
- void [serve\\_iterators \(\)](#)  
*assigned by the strategy master (called by [run\\_strategy\(\)](#))*
- void [static\\_schedule\\_iterators \(\)](#)  
*(called by [run\\_strategy\(\)](#))*
- void [print\\_results \(\)](#)  
*prints the concurrent iteration results summary (called by [run\\_strategy\(\)](#))*

## Private Attributes

- [Model](#) `userDefinedModel`  
*the model used by the iterator*
- [Iterator](#) `selectedIterator`  
*the iterator used by the concurrent strategy*
- `int` [numIteratorServers](#)  
*number of concurrent iterator partitions*
- `int` [numIteratorJobs](#)  
*total number of iterator executions to schedule over the servers*
- [RealVectorArray](#) `parameterSets`  
*sets or pareto multiobjective weighting sets) to be performed.*
- [PRPArray](#) `prpResults`  
*an array of results corresponding to the parameter set vectors.*
- `bool` [multiStartFlag](#)  
*distinguishes multi-start from Pareto-set*
- `bool` [strategyDedicatedMasterFlag](#)  
*signals ded. master partitioning*
- `int` [iteratorServerId](#)  
*identifier for an iterator server*
- `int` [drvMsgLen](#)  
*length of an MPI buffer containing a RealVector from parameterSets*

### 8.19.1 Detailed Description

[Strategy](#) for multi-start iteration or pareto set optimization.

This strategy maintains two concurrent iterator capabilities. First, a general capability for running an iterator multiple times from different starting points is provided (often used for multi-start optimization, but not restricted to optimization). Second, a simple capability for mapping the "pareto frontier" (the set of optimal solutions in mutiobjective formulations) is provided. This pareto set is mapped through running an optimizer multiple times for different sets of multiobjective weightings.

### 8.19.2 Member Function Documentation

**8.19.2.1 void self\_schedule\_iterators () [private]**

among slave iterator servers (called by [run\\_strategy\(\)](#))

This function is adapted from [ApplicationInterface::self\\_schedule\\_evaluations\(\)](#).

**8.19.2.2 void serve\_iterators () [private]**

assigned by the strategy master (called by [run\\_strategy\(\)](#))

This function is similar in structure to [ApplicationInterface::serve\\_evaluations\\_synch\(\)](#).

The documentation for this class was generated from the following files:

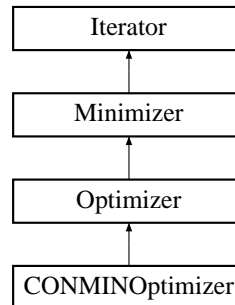
- [ConcurrentStrategy.H](#)
- [ConcurrentStrategy.C](#)



## 8.20 CONMINOptimizer Class Reference

Wrapper class for the CONMIN optimization library.

Inheritance diagram for CONMINOptimizer::



### Public Member Functions

- [CONMINOptimizer \(Model &model\)](#)  
*constructor*
- [~CONMINOptimizer \(\)](#)  
*destructor*
- void [find\\_optimum \(\)](#)  
*Redefines the run virtual function for the optimizer branch.*

### Protected Member Functions

- virtual void [derived\\_pre\\_run \(\)](#)  
*performs run-time set up*

### Private Member Functions

- void [allocate\\_workspace \(\)](#)  
*Allocates workspace for the optimizer.*
- void [deallocate\\_workspace \(\)](#)  
*Releases workspace memory.*

- void [allocate\\_constraints](#) ()  
*Allocates constraint mappings.*

## Private Attributes

- int [conminInfo](#)  
*INFO from CONMIN manual.*
- int [printControl](#)  
*IPRINT from CONMIN manual (controls output verbosity).*
- int [optimizationType](#)  
*MINMAX from DOT manual (minimize or maximize).*
- Real [objFnValue](#)  
*value of the objective function passed to CONMIN*
- [RealVector](#) [constraintValues](#)  
*array of nonlinear constraint values passed to CONMIN*
- int [numConminNlnConstr](#)  
*total number of nonlinear constraints seen by CONMIN*
- int [numConminLinConstr](#)  
*total number of linear constraints seen by CONMIN*
- int [numConminConstr](#)  
*total number of linear and nonlinear constraints seen by CONMIN*
- [SizetList](#) [constraintMappingIndices](#)  
*Response constraints used in computing the CONMIN constraints.*
- [RealList](#) [constraintMappingMultipliers](#)  
*the CONMIN constraints.*
- [RealList](#) [constraintMappingOffsets](#)  
*CONMIN constraints.*
- int [N1](#)  
*Size variable for CONMIN arrays. See CONMIN manual.*
- int [N2](#)  
*Size variable for CONMIN arrays. See CONMIN manual.*

- int [N3](#)  
*Size variable for CONMIN arrays. See CONMIN manual.*
- int [N4](#)  
*Size variable for CONMIN arrays. See CONMIN manual.*
- int [N5](#)  
*Size variable for CONMIN arrays. See CONMIN manual.*
- int [NFDG](#)  
*Finite difference flag.*
- int [IPRINT](#)  
*Flag to control amount of output data.*
- int [ITMAX](#)  
*Flag to specify the maximum number of iterations.*
- double [FDCH](#)  
*Relative finite difference step size.*
- double [FDCHM](#)  
*Absolute finite difference step size.*
- double [CT](#)  
*Constraint thickness parameter.*
- double [CTMIN](#)  
*Minimum absolute value of CT used during optimization.*
- double [CTL](#)  
*Constraint thickness parameter for linear and side constraints.*
- double [CTLMIN](#)  
*Minimum value of CTL used during optimization.*
- double [DELFUN](#)  
*Relative convergence criterion threshold.*
- double [DABFUN](#)  
*Absolute convergence criterion threshold.*
- double \* [conminDesVars](#)  
*Array of design variables used by CONMIN (length N1 = numdv+2).*
- double \* [conminLowerBnds](#)

*Array of lower bounds used by CONMIN (length  $NI = numdv+2$ ).*

- double \* **conminUpperBnds**

*Array of upper bounds used by CONMIN (length  $NI = numdv+2$ ).*

- double \* **S**

*Internal CONMIN array.*

- double \* **G1**

*Internal CONMIN array.*

- double \* **G2**

*Internal CONMIN array.*

- double \* **B**

*Internal CONMIN array.*

- double \* **C**

*Internal CONMIN array.*

- int \* **MS1**

*Internal CONMIN array.*

- double \* **SCAL**

*Internal CONMIN array.*

- double \* **DF**

*Internal CONMIN array.*

- double \* **A**

*Internal CONMIN array.*

- int \* **ISC**

*Internal CONMIN array.*

- int \* **IC**

*Internal CONMIN array.*

### 8.20.1 Detailed Description

Wrapper class for the CONMIN optimization library.

The **CONMINOptimizer** class provides a wrapper for CONMIN, a Public-domain Fortran 77 optimization library written by Gary Vanderplaats under contract to NASA Ames Research Center. The CONMIN User's Manual is contained in NASA Technical Memorandum X-62282, 1978. CONMIN uses a reverse communication mode,

which avoids the static member function issues that arise with function pointer designs (see [NPSOLOptimizer](#) and [SNLLOptimizer](#)).

The user input mappings are as follows: `max_iterations` is mapped into CONMIN's `ITMAX` parameter, `max_function_evaluations` is implemented directly in the `find_optimum()` loop since there is no CONMIN parameter equivalent, `convergence_tolerance` is mapped into CONMIN's `DELFUN` and `DABFUN` parameters, output verbosity is mapped into CONMIN's `IPRINT` parameter (verbose: `IPRINT = 4`; quiet: `IPRINT = 2`), gradient mode is mapped into CONMIN's `NFDG` parameter, and finite difference step size is mapped into CONMIN's `FDCH` and `FDCHM` parameters. Refer to [Vanderplaats, 1978] for additional information on CONMIN parameters.

## 8.20.2 Member Data Documentation

### 8.20.2.1 `int conminInfo` [private]

INFO from CONMIN manual.

Information requested by CONMIN: 1 = evaluate objective and constraints, 2 = evaluate gradients of objective and constraints.

### 8.20.2.2 `int printControl` [private]

IPRINT from CONMIN manual (controls output verbosity).

Values range from 0 (nothing) to 4 (most output). 0 = nothing, 1 = initial and final function information, 2 = all of #1 plus function value and design vars at each iteration, 3 = all of #2 plus constraint values and direction vectors, 4 = all of #3 plus gradients of the objective function and constraints, 5 = all of #4 plus proposed design vector, plus objective and constraint functions from the 1-D search

### 8.20.2.3 `int optimizationType` [private]

MINMAX from DOT manual (minimize or maximize).

Values of 0 or -1 (minimize) or 1 (maximize).

### 8.20.2.4 `RealVector constraintValues` [private]

array of nonlinear constraint values passed to CONMIN

This array must be of nonzero length and must contain only one-sided inequality constraints which are  $\leq 0$  (which requires a transformation from 2-sided inequalities and equalities).

### 8.20.2.5 `SizeList constraintMappingIndices` [private]

[Response](#) constraints used in computing the CONMIN constraints.

The length of the list corresponds to the number of CONMIN constraints, and each entry in the list points to the corresponding DAKOTA constraint.

#### 8.20.2.6 **RealList constraintMappingMultipliers** [private]

the CONMIN constraints.

The length of the list corresponds to the number of CONMIN constraints, and each entry in the list contains a multiplier for the DAKOTA constraint identified with constraintMappingIndices. These multipliers are currently +1 or -1.

#### 8.20.2.7 **RealList constraintMappingOffsets** [private]

CONMIN constraints.

The length of the list corresponds to the number of CONMIN constraints, and each entry in the list contains an offset for the DAKOTA constraint identified with constraintMappingIndices. These offsets involve inequality bounds or equality targets, since CONMIN assumes constraint allowables = 0.

#### 8.20.2.8 **int N1** [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N1 = \text{number of variables} + 2$

#### 8.20.2.9 **int N2** [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N2 = \text{number of constraints} + 2 * (\text{number of variables})$

#### 8.20.2.10 **int N3** [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N3 = \text{Maximum possible number of active constraints.}$

#### 8.20.2.11 **int N4** [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N4 = \text{Maximum}(N3, \text{number of variables})$

#### 8.20.2.12 **int N5** [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N5 = 2 * (N4)$

**8.20.2.13 double CT** [private]

Constraint thickness parameter.

The value of CT decreases in magnitude during optimization.

**8.20.2.14 double\* S** [private]

Internal CONMIN array.

Move direction in N-dimensional space.

**8.20.2.15 double\* G1** [private]

Internal CONMIN array.

Temporary storage of constraint values.

**8.20.2.16 double\* G2** [private]

Internal CONMIN array.

Temporary storage of constraint values.

**8.20.2.17 double\* B** [private]

Internal CONMIN array.

Temporary storage for computations involving array S.

**8.20.2.18 double\* C** [private]

Internal CONMIN array.

Temporary storage for use with arrays B and S.

**8.20.2.19 int\* MS1** [private]

Internal CONMIN array.

Temporary storage for use with arrays B and S.

**8.20.2.20 double\* SCAL** [private]

Internal CONMIN array.

[Vector](#) of scaling parameters for design parameter values.

**8.20.2.21** `double* DF` [private]

Internal CONMIN array.

Temporary storage for analytic gradient data.

**8.20.2.22** `double* A` [private]

Internal CONMIN array.

Temporary 2-D array for storage of constraint gradients.

**8.20.2.23** `int* ISC` [private]

Internal CONMIN array.

[Array](#) of flags to identify linear constraints. (not used in this implementation of CONMIN)

**8.20.2.24** `int* IC` [private]

Internal CONMIN array.

[Array](#) of flags to identify active and violated constraints

The documentation for this class was generated from the following files:

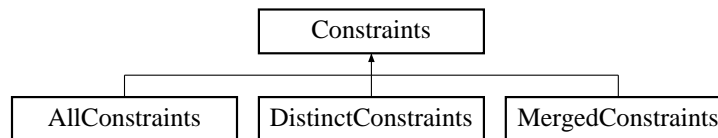
- CONMINOptimizer.H
- CONMINOptimizer.C



## 8.21 Constraints Class Reference

Base class for the variable constraints class hierarchy.

Inheritance diagram for Constraints::



### Public Member Functions

- [Constraints](#) ()  
*default constructor*
- [Constraints](#) (const [ProblemDescDB](#) &problem\_db, const pair< short, short > &view)  
*standard constructor*
- [Constraints](#) (const pair< short, short > &view)  
*alternate constructor for instantiations on the fly*
- [Constraints](#) (const [Constraints](#) &con)  
*copy constructor*
- virtual [~Constraints](#) ()  
*destructor*
- [Constraints operator=](#) (const [Constraints](#) &con)  
*assignment operator*
- virtual const [RealVector](#) & [continuous\\_lower\\_bounds](#) () const  
*return the active continuous variable lower bounds*
- virtual void [continuous\\_lower\\_bounds](#) (const [RealVector](#) &c\_l\_bnds)  
*set the active continuous variable lower bounds*
- virtual const [RealVector](#) & [continuous\\_upper\\_bounds](#) () const  
*return the active continuous variable upper bounds*
- virtual void [continuous\\_upper\\_bounds](#) (const [RealVector](#) &c\_u\_bnds)  
*set the active continuous variable upper bounds*

- virtual const [IntVector](#) & [discrete\\_lower\\_bounds](#) () const  
*return the active discrete variable lower bounds*
- virtual void [discrete\\_lower\\_bounds](#) (const [IntVector](#) &d\_l\_bnds)  
*set the active discrete variable lower bounds*
- virtual const [IntVector](#) & [discrete\\_upper\\_bounds](#) () const  
*return the active discrete variable upper bounds*
- virtual void [discrete\\_upper\\_bounds](#) (const [IntVector](#) &d\_u\_bnds)  
*set the active discrete variable upper bounds*
- virtual const [RealVector](#) & [inactive\\_continuous\\_lower\\_bounds](#) () const  
*return the inactive continuous lower bounds*
- virtual void [inactive\\_continuous\\_lower\\_bounds](#) (const [RealVector](#) &i\_c\_l\_bnds)  
*set the inactive continuous lower bounds*
- virtual const [RealVector](#) & [inactive\\_continuous\\_upper\\_bounds](#) () const  
*return the inactive continuous upper bounds*
- virtual void [inactive\\_continuous\\_upper\\_bounds](#) (const [RealVector](#) &i\_c\_u\_bnds)  
*set the inactive continuous upper bounds*
- virtual const [IntVector](#) & [inactive\\_discrete\\_lower\\_bounds](#) () const  
*return the inactive discrete lower bounds*
- virtual void [inactive\\_discrete\\_lower\\_bounds](#) (const [IntVector](#) &i\_d\_l\_bnds)  
*set the inactive discrete lower bounds*
- virtual const [IntVector](#) & [inactive\\_discrete\\_upper\\_bounds](#) () const  
*return the inactive discrete upper bounds*
- virtual void [inactive\\_discrete\\_upper\\_bounds](#) (const [IntVector](#) &i\_d\_u\_bnds)  
*set the inactive discrete upper bounds*
- virtual [RealVector](#) [all\\_continuous\\_lower\\_bounds](#) () const  
*returns a single array with all continuous lower bounds*
- virtual void [all\\_continuous\\_lower\\_bounds](#) (const [RealVector](#) &a\_c\_l\_bnds)  
*sets all continuous lower bounds using a single array*
- virtual [RealVector](#) [all\\_continuous\\_upper\\_bounds](#) () const  
*returns a single array with all continuous upper bounds*

- virtual void `all_continuous_upper_bounds` (const `RealVector` &a\_c\_u\_bnds)  
*sets all continuous upper bounds using a single array*
- virtual `IntVector` `all_discrete_lower_bounds` () const  
*returns a single array with all discrete lower bounds*
- virtual void `all_discrete_lower_bounds` (const `IntVector` &a\_d\_l\_bnds)  
*sets all discrete lower bounds using a single array*
- virtual `IntVector` `all_discrete_upper_bounds` () const  
*returns a single array with all discrete upper bounds*
- virtual void `all_discrete_upper_bounds` (const `IntVector` &a\_d\_u\_bnds)  
*sets all discrete upper bounds using a single array*
- virtual void `write` (ostream &s) const  
*write a variable constraints object to an ostream*
- virtual void `read` (istream &s)  
*read a variable constraints object from an istream*
- size\_t `num_linear_ineq_constraints` () const  
*return the number of linear inequality constraints*
- size\_t `num_linear_eq_constraints` () const  
*return the number of linear equality constraints*
- const `RealMatrix` & `linear_ineq_constraint_coeffs` () const  
*return the linear inequality constraint coefficients*
- void `linear_ineq_constraint_coeffs` (const `RealMatrix` &lin\_ineq\_coeffs)  
*set the linear inequality constraint coefficients*
- const `RealVector` & `linear_ineq_constraint_lower_bounds` () const  
*return the linear inequality constraint lower bounds*
- void `linear_ineq_constraint_lower_bounds` (const `RealVector` &lin\_ineq\_l\_bnds)  
*set the linear inequality constraint lower bounds*
- const `RealVector` & `linear_ineq_constraint_upper_bounds` () const  
*return the linear inequality constraint upper bounds*
- void `linear_ineq_constraint_upper_bounds` (const `RealVector` &lin\_ineq\_u\_bnds)  
*set the linear inequality constraint upper bounds*
- const `RealMatrix` & `linear_eq_constraint_coeffs` () const

*return the linear equality constraint coefficients*

- void `linear_eq_constraint_coeffs` (const `RealMatrix` &lin\_eq\_coeffs)  
*set the linear equality constraint coefficients*
- const `RealVector` & `linear_eq_constraint_targets` () const  
*return the linear equality constraint targets*
- void `linear_eq_constraint_targets` (const `RealVector` &lin\_eq\_targets)  
*set the linear equality constraint targets*
- size\_t `num_nonlinear_ineq_constraints` () const  
*return the number of nonlinear inequality constraints*
- size\_t `num_nonlinear_eq_constraints` () const  
*return the number of nonlinear equality constraints*
- const `RealVector` & `nonlinear_ineq_constraint_lower_bounds` () const  
*return the nonlinear inequality constraint lower bounds*
- void `nonlinear_ineq_constraint_lower_bounds` (const `RealVector` &nln\_ineq\_l\_bnds)  
*set the nonlinear inequality constraint lower bounds*
- const `RealVector` & `nonlinear_ineq_constraint_upper_bounds` () const  
*return the nonlinear inequality constraint upper bounds*
- void `nonlinear_ineq_constraint_upper_bounds` (const `RealVector` &nln\_ineq\_u\_bnds)  
*set the nonlinear inequality constraint upper bounds*
- const `RealVector` & `nonlinear_eq_constraint_targets` () const  
*return the nonlinear equality constraint targets*
- void `nonlinear_eq_constraint_targets` (const `RealVector` &nln\_eq\_targets)  
*set the nonlinear equality constraint targets*
- `Constraints copy` () const  
*for use when a deep copy is needed (the representation is `_not_shared`)*
- void `reshape` (const size\_t &num\_nln\_ineq\_cons, const size\_t &num\_nln\_eq\_cons, const size\_t &num\_lin\_ineq\_cons, const size\_t &num\_lin\_eq\_cons)  
*Constraints hierarchy.*
- void `reshape` (const `Sizet2DArray` &vars\_comps)  
*reshape the bounds arrays within the `Constraints` hierarchy*
- bool `is_null` () const  
*function to check constraintsRep (does this envelope contain a letter)*

## Protected Member Functions

- [Constraints](#) ([BaseConstructor](#), const [ProblemDescDB](#) &problem\_db, const pair< short, short > &view)  
*derived class constructors - Coplien, p. 139*
- virtual void [copy\\_rep](#) (const [Constraints](#) \*con\_rep)  
*Used by [copy\(\)](#) to copy the contents of a letter class.*
- virtual void [reshape\\_rep](#) (const [Sizet2DArray](#) &vars\_comps)  
*Used by [reshape\(Sizet2DArray&\)](#) to reshape the contents of a letter class.*
- void [manage\\_linear\\_constraints](#) (const [ProblemDescDB](#) &problem\_db)  
*coefficient input to matrices, and assign defaults*

## Protected Attributes

- pair< short, short > [variablesView](#)  
*view enumerations*
- size\_t [numNonlinearIneqCons](#)  
*number of nonlinear inequality constraints*
- size\_t [numNonlinearEqCons](#)  
*number of nonlinear equality constraints*
- [RealVector](#) [nonlinearIneqConLowerBnds](#)  
*nonlinear inequality constraint lower bounds*
- [RealVector](#) [nonlinearIneqConUpperBnds](#)  
*nonlinear inequality constraint upper bounds*
- [RealVector](#) [nonlinearEqConTargets](#)  
*nonlinear equality constraint targets*
- size\_t [numLinearIneqCons](#)  
*number of linear inequality constraints*
- size\_t [numLinearEqCons](#)  
*number of linear equality constraints*
- [RealMatrix](#) [linearIneqConCoeffs](#)  
*linear inequality constraint coefficients*
- [RealMatrix](#) [linearEqConCoeffs](#)  
*linear equality constraint coefficients*

- [RealVector linearIneqConLowerBnds](#)  
*linear inequality constraint lower bounds*
- [RealVector linearIneqConUpperBnds](#)  
*linear inequality constraint upper bounds*
- [RealVector linearEqConTargets](#)  
*linear equality constraint targets*
- [RealVector emptyRealVector](#)  
*no variable constraints corresponding to the request*
- [IntVector emptyIntVector](#)  
*no variable constraints corresponding to the request*

### Private Member Functions

- [Constraints \\* get\\_constraints](#) (const [ProblemDescDB](#) &problem\_db, const pair< short, short > &view)  
*appropriate derived type.*
- [Constraints \\* get\\_constraints](#) (const pair< short, short > &view) const  
*derived type.*

### Private Attributes

- [Constraints \\* constraintsRep](#)  
*pointer to the letter (initialized only for the envelope)*
- int [referenceCount](#)  
*number of objects sharing constraintsRep*

### 8.21.1 Detailed Description

Base class for the variable constraints class hierarchy.

The [Constraints](#) class is the base class for the class hierarchy managing bound, linear, and nonlinear constraints. Using the variable lower and upper bounds arrays from the input specification, different derived classes define different views of this data. The linear and nonlinear constraint data is consistent in all views and is managed at the base class level. For memory efficiency and enhanced polymorphism, the variable constraints hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Constraints](#)) serves as the envelope and one of the derived classes (selected in [Constraints::get\\_constraints\(\)](#)) serves as the letter.

## 8.21.2 Constructor & Destructor Documentation

### 8.21.2.1 `Constraints ()`

default constructor

The default constructor: `constraintsRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful `Constraints` object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

### 8.21.2.2 `Constraints (const ProblemDescDB & problem_db, const pair< short, short > & view)`

standard constructor

The envelope constructor only needs to extract enough data to properly execute `get_constraints`, since the constructor overloaded with `BaseConstructor` builds the actual base class data inherited by the derived classes.

### 8.21.2.3 `Constraints (const pair< short, short > & view)`

alternate constructor for instantiations on the fly

Envelope constructor for instantiations on the fly.

### 8.21.2.4 `Constraints (const Constraints & con)`

copy constructor

Copy constructor manages sharing of `constraintsRep` and incrementing of `referenceCount`.

### 8.21.2.5 `~Constraints ()` [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `constraintsRep` when `referenceCount` reaches zero.

### 8.21.2.6 `Constraints (BaseConstructor, const ProblemDescDB & problem_db, const pair< short, short > & view)` [protected]

derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. `get_constraints()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid recursion in the base class constructor calling `get_constraints()` again). Since the letter IS the representation, its `rep` pointer is set to NULL (an uninitialized pointer causes problems in `~Constraints`).

### 8.21.3 Member Function Documentation

#### 8.21.3.1 `Constraints` operator= (const `Constraints` & *con*)

assignment operator

Assignment operator decrements referenceCount for old constraintsRep, assigns new constraintsRep, and increments referenceCount for new constraintsRep.

#### 8.21.3.2 `Constraints` copy () const

for use when a deep copy is needed (the representation is `_not_shared`)

Deep copies are used for history mechanisms such as `bestVariables` and `data_pairs` since these must catalogue copies (and should not change as the representation within `currentVariables` changes).

#### 8.21.3.3 void reshape (const size\_t & num\_nln\_ineq\_cons, const size\_t & num\_nln\_eq\_cons, const size\_t & num\_lin\_ineq\_cons, const size\_t & num\_lin\_eq\_cons)

`Constraints` hierarchy.

Resizes the linear and nonlinear constraint arrays at the base class. Does NOT currently resize the derived bounds arrays.

#### 8.21.3.4 void reshape (const `Sizet2DArray` & vars\_comps)

reshape the bounds arrays within the `Constraints` hierarchy

Resizes the derived bounds arrays.

#### 8.21.3.5 void manage\_linear\_constraints (const `ProblemDescDB` & problem\_db) [protected]

coefficient input to matrices, and assign defaults

Convenience function called from derived class constructors. The number of variables active for applying linear constraints is currently defined to be the number of active continuous variables plus the number of active discrete variables (the most general case), even though very few optimizers can currently support mixed variable linear constraints.

#### 8.21.3.6 `Constraints` \* get\_constraints (const `ProblemDescDB` & problem\_db, const pair< short, short > & view) [private]

appropriate derived type.

Initializes constraintsRep to the appropriate derived type, as given by the variables view.



**8.21.3.7 Constraints** \* `get_constraints (const pair< short, short > & view) const` [private]

derived type.

Initializes constraintsRep to the appropriate derived type, as given by the variables view. The default derived class constructors are invoked.

The documentation for this class was generated from the following files:

- DakotaConstraints.H
- DakotaConstraints.C

## 8.22 CtelRegexp Class Reference

### Public Types

- enum [RStatus](#) {  
GOOD = 0, EXP\_TOO\_BIG, OUT\_OF\_MEM, TOO\_MANY\_PAR,  
UNMATCH\_PAR, STARPLUS\_EMPTY, STARPLUS\_NESTED, INDEX\_RANGE,  
INDEX\_MATCH, STARPLUS\_NOTHING, TRAILING, INT\_ERROR,  
BAD\_PARAM, BAD\_OPCODE }  
*occurs with this implementation.*

### Public Member Functions

- [CtelRegexp](#) (const std::string &pattern)  
*Constructor - compile a regular expression.*
- [~CtelRegexp](#) ()  
*Destructor.*
- bool [compile](#) (const std::string &pattern)  
*Compile a new regular expression.*
- std::string [match](#) (const std::string &str)  
*that is a sub-string matching with the regular expression*
- bool [match](#) (const std::string &str, size\_t \*start, size\_t \*size)  
*another form of matching: returns the indexes of the matching*
- [RStatus](#) [getStatus](#) ()  
*Get status.*
- const std::string & [getStatusMsg](#) ()  
*Get status message.*
- void [clearErrors](#) ()  
*Clear all errors.*
- const std::string & [getRe](#) ()  
*Return regular expression pattern.*
- bool [split](#) (const std::string &str, std::vector< std::string > &all\_matches)

*Split.*

### Private Member Functions

- [CtelRegexp](#) (const [CtelRegexp](#) &)  
*Private copy constructor.*
- [CtelRegexp](#) & `operator=` (const [CtelRegexp](#) &)  
*Private assignment operator.*

### Private Attributes

- `std::string` [strPattern](#)  
*STL string to hold pattern.*
- `regexp * r`  
*Pointer to regexp.*
- [RStatus](#) [status](#)  
*Return status, enumerated type.*
- `std::string` [statusMsg](#)  
*STL string to hold status message.*

#### 8.22.1 Detailed Description

DESCRIPTION: Wrapper for the Regular Expression engine( `regexp` ) released by Henry Spencer of the University of Toronto.

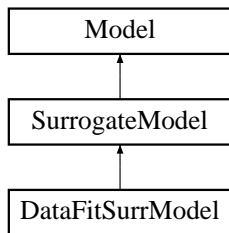
The documentation for this class was generated from the following files:

- `CtelRegExp.H`
- `CtelRegExp.C`

## 8.23 DataFitSurrModel Class Reference

data fit surrogates (global and local)

Inheritance diagram for DataFitSurrModel::



### Public Member Functions

- [DataFitSurrModel](#) ([ProblemDescDB](#) &problem\_db)  
*constructor*
- [DataFitSurrModel](#) ([Iterator](#) &dace\_iterator, [Model](#) &actual\_model, const pair< short, short > &view, const [ActiveSet](#) &set, const [String](#) &approx\_type, const short &approx\_order, const [String](#) &corr\_type, const short &corr\_order, const [String](#) &sample\_reuse)  
*alternate constructor for instantiations on the fly*
- [~DataFitSurrModel](#) ()  
*destructor*

### Protected Member Functions

- void [derived\\_compute\\_response](#) (const [ActiveSet](#) &set)  
*portion of [compute\\_response\(\)](#) specific to [DataFitSurrModel](#)*
- void [derived\\_asynch\\_compute\\_response](#) (const [ActiveSet](#) &set)  
*portion of [asynch\\_compute\\_response\(\)](#) specific to [DataFitSurrModel](#)*
- const [ResponseArray](#) & [derived\\_synchronize](#) ()  
*portion of [synchronize\(\)](#) specific to [DataFitSurrModel](#)*
- const [IntResponseMap](#) & [derived\\_synchronize\\_nowait](#) ()  
*portion of [synchronize\\_nowait\(\)](#) specific to [DataFitSurrModel](#)*

- [Iterator](#) & [subordinate\\_iterator](#) ()  
*return daceIterator*
- [Model](#) & [surrogate\\_model](#) ()  
*return this model instance*
- [Model](#) & [truth\\_model](#) ()  
*return actualModel*
- void [derived\\_subordinate\\_models](#) ([ModelList](#) &ml, bool recurse\_flag)  
*return actualModel (and optionally its sub-models)*
- void [update\\_from\\_subordinate\\_model](#) (bool recurse\_flag=true)  
*pass request to actualModel if recursing and then update from it*
- [Interface](#) & [interface](#) ()  
*return approxInterface*
- void [surrogate\\_bypass](#) (bool bypass\_flag)  
*any lower-level surrogates.*
- void [surrogate\\_function\\_indices](#) (const [IntSet](#) &surr\_fn\_indices)  
*and [ApproximationInterface::approxFnIndices](#)*
- void [build\\_approximation](#) ()  
*daceIterator/actualModel to generate new data points*
- bool [build\\_approximation](#) (const [Variables](#) &vars, const [Response](#) &response)  
*augment the vars/response anchor point*
- void [update\\_approximation](#) (const [Variables](#) &vars, const [Response](#) &response, bool rebuild\_flag)  
*approximation if requested*
- void [update\\_approximation](#) (const [VariablesArray](#) &vars\_array, const [ResponseArray](#) &resp\_array, bool rebuild\_flag)  
*approximation if requested*
- void [append\\_approximation](#) (const [Variables](#) &vars, const [Response](#) &response, bool rebuild\_flag)  
*requested (requests forwarded to approxInterface)*
- void [append\\_approximation](#) (const [VariablesArray](#) &vars\_array, const [ResponseArray](#) &resp\_array, bool rebuild\_flag)  
*rebuilds it if requested (requests forwarded to approxInterface)*
- [Array](#)< [Approximation](#) > & [approximations](#) ()  
*retrieve the set of Approximations from approxInterface*

- const [RealVectorArray](#) & [approximation\\_coefficients](#) ()  
*(request forwarded to approxInterface)*
- void [approximation\\_coefficients](#) (const [RealVectorArray](#) &approx\_coeffs)  
*(request forwarded to approxInterface)*
- void [print\\_coefficients](#) (ostream &s, size\_t index) const  
*(request forwarded to approxInterface)*
- const [RealVector](#) & [approximation\\_variances](#) (const [RealVector](#) &c\_vars)  
*(request forwarded to approxInterface)*
- const [List](#)< [SurrogateDataPoint](#) > & [approximation\\_data](#) (size\_t index)  
*(request forwarded to approxInterface)*
- void [component\\_parallel\\_mode](#) (short mode)  
*update component parallel mode for supporting parallelism in actualModel*
- void [derived\\_init\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*set up actualModel for parallel operations*
- void [derived\\_init\\_serial](#) ()  
*set up actualModel for serial operations.*
- void [derived\\_set\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*set active parallel configuration within actualModel*
- void [derived\\_free\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*(request forwarded to actualModel)*
- void [serve](#) ()  
*Completes when a termination message is received from [stop\\_servers\(\)](#).*
- void [stop\\_servers](#) ()  
*when [DataFitSurrModel](#) iteration is complete.*
- const [String](#) & [interface\\_id](#) () const  
*return the approxInterface identifier*
- int [evaluation\\_id](#) () const  
*return the current evaluation id for the [DataFitSurrModel](#)*
- void [set\\_evaluation\\_reference](#) ()  
*(request forwarded to approxInterface and actualModel)*

- void [print\\_evaluation\\_summary](#) (ostream &s, bool minimal\_header=false, bool relative\_count=true) const  
*(request forwarded to approxInterface and actualModel)*

### Private Member Functions

- void [update\\_global](#) ()  
*Updates fit arrays for global approximations.*
- void [update\\_local\\_multipoint](#) ()  
*Updates fit arrays for local or multipoint approximations.*
- void [build\\_global](#) ()  
*Builds a global approximation using daceIterator.*
- void [build\\_local\\_multipoint](#) ()  
*Builds a local or multipoint approximation using actualModel.*
- void [update\\_actual\\_model](#) ()  
*update actualModel with data from current variables/labels/bounds/targets*
- void [update\\_from\\_actual\\_model](#) ()  
*update current variables/labels/bounds/targets with data from actualModel*

### Private Attributes

- int [surrModelEvals](#)  
*derived\_asynch\_compute\_response()*
- String [sampleReuse](#)  
*all, region, file, or none (default)*
- String [sampleReuseFile](#)  
*file name for sampleReuse == "file"*
- Interface [approxInterface](#)  
*(required for both global and local)*
- Model [actualModel](#)  
*(optional for global, required for local)*
- Iterator [daceIterator](#)  
*(optional for global since restart data may also be used)*

### 8.23.1 Detailed Description

data fit surrogates (global and local)

The [DataFitSurrModel](#) class manages global or local approximations (surrogates that involve data fits) that are used in place of an expensive model. The class contains an [approxInterface](#) (required for both global and local) which manages the approximate function evaluations, an [actualModel](#) (optional for global, required for local) which provides truth evaluations for building the surrogate, and a [daceIterator](#) (optional for global, not used for local) which selects parameter sets on which to evaluate [actualModel](#) in order to generate the necessary data for building global approximations.

### 8.23.2 Member Function Documentation

#### 8.23.2.1 void [derived\\_compute\\_response](#) (const [ActiveSet](#) & *set*) [[protected](#), [virtual](#)]

portion of [compute\\_response\(\)](#) specific to [DataFitSurrModel](#)

Compute the response synchronously using [actualModel](#), [approxInterface](#), or both (mixed case). For the [approxInterface](#) portion, build the approximation if needed, evaluate the approximate response, and apply correction (if active) to the results.

Reimplemented from [Model](#).

#### 8.23.2.2 void [derived\\_asynch\\_compute\\_response](#) (const [ActiveSet](#) & *set*) [[protected](#), [virtual](#)]

portion of [asynch\\_compute\\_response\(\)](#) specific to [DataFitSurrModel](#)

Compute the response asynchronously using [actualModel](#), [approxInterface](#), or both (mixed case). For the [approxInterface](#) portion, build the approximation if needed and evaluate the approximate response in a quasi-asynchronous approach ([ApproximationInterface::map\(\)](#) performs the map synchronously and bookkeeps the results for return in [derived\\_synchronize\(\)](#) below).

Reimplemented from [Model](#).

#### 8.23.2.3 const [ResponseArray](#) & [derived\\_synchronize](#) () [[protected](#), [virtual](#)]

portion of [synchronize\(\)](#) specific to [DataFitSurrModel](#)

Blocking retrieval of asynchronous evaluations from [actualModel](#), [approxInterface](#), or both (mixed case). For the [approxInterface](#) portion, apply correction (if active) to each response in the array. [derived\\_synchronize\(\)](#) is designed for the general case where [derived\\_asynch\\_compute\\_response\(\)](#) may be inconsistent in its use of actual evaluations, approximate evaluations, or both.

Reimplemented from [Model](#).

#### 8.23.2.4 const [IntResponseMap](#) & [derived\\_synchronize\\_nowait](#) () [[protected](#), [virtual](#)]

portion of [synchronize\\_nowait\(\)](#) specific to [DataFitSurrModel](#)



Nonblocking retrieval of asynchronous evaluations from `actualModel`, `approxInterface`, or both (mixed case). For the `approxInterface` portion, apply correction (if active) to each response in the map. `derived_synchronize_nowait()` is designed for the general case where `derived_asynch_compute_response()` may be inconsistent in its use of actual evals, approx evals, or both.

Reimplemented from [Model](#).

#### 8.23.2.5 void build\_approximation () [protected, virtual]

`daceIterator/actualModel` to generate new data points

This function constructs a new approximation, discarding any previous data. It constructs any required currentPoints and does not define an anchorPoint.

Reimplemented from [Model](#).

#### 8.23.2.6 bool build\_approximation (const Variables & vars, const Response & response) [protected, virtual]

augment the vars/response anchor point

This function constructs a new approximation, discarding any previous data. It uses the passed data to populate the anchorPoint and constructs any required currentPoints.

Reimplemented from [Model](#).

#### 8.23.2.7 void update\_approximation (const Variables & vars, const Response & response, bool rebuild\_flag) [protected, virtual]

approximation if requested

This function populates/replaces [Approximation::anchorPoint](#) and rebuilds the approximation, if requested. It does not clear other data (i.e., [Approximation::currentPoints](#)) and does not update the `actualModel` with revised bounds, labels, etc. Thus, it updates data from a previous call to `build_approximation()`, and is not intended to be used in isolation.

Reimplemented from [Model](#).

#### 8.23.2.8 void update\_approximation (const VariablesArray & vars\_array, const ResponseArray & resp\_array, bool rebuild\_flag) [protected, virtual]

approximation if requested

This function populates/replaces [Approximation::currentPoints](#) and rebuilds the approximation, if requested. It does not clear other data (i.e., [Approximation::anchorPoint](#)) and does not update the `actualModel` with revised bounds, labels, etc. Thus, it updates data from a previous call to `build_approximation()`, and is not intended to be used in isolation.

Reimplemented from [Model](#).

**8.23.2.9** `void append_approximation (const Variables & vars, const Response & response, bool rebuild_flag)` [protected, virtual]

requested (requests forwarded to approxInterface)

This function appends one point to [Approximation::currentPoints](#) and rebuilds the approximation, if requested. It does not modify other data (i.e., [Approximation::anchorPoint](#)) and does not update the actualModel with revised bounds, labels, etc. Thus, it appends to data from a previous call to [build\\_approximation\(\)](#), and is not intended to be used in isolation.

Reimplemented from [Model](#).

**8.23.2.10** `void append_approximation (const VariablesArray & vars_array, const ResponseArray & resp_array, bool rebuild_flag)` [protected, virtual]

rebuilds it if requested (requests forwarded to approxInterface)

This function appends multiple points to [Approximation::currentPoints](#) and rebuilds the approximation, if requested. It does not modify other data (i.e., [Approximation::anchorPoint](#)) and does not update the actualModel with revised bounds, labels, etc. Thus, it appends to data from a previous call to [build\\_approximation\(\)](#), and is not intended to be used in isolation.

Reimplemented from [Model](#).

**8.23.2.11** `void derived_init_communicators (const int & max_iterator_concurrency, bool recurse_flag = true)` [inline, protected, virtual]

set up actualModel for parallel operations

asynchronous flags need to be initialized for the sub-models. In addition, `max_iterator_concurrency` is the outer level iterator concurrency, not the DACE concurrency that actualModel will see, and recomputing the message\_lengths on the sub-model is probably not a bad idea either. Therefore, recompute everything on actualModel using `init_communicators`.

Reimplemented from [Model](#).

**8.23.2.12** `int evaluation_id () const` [inline, protected, virtual]

return the current evaluation id for the [DataFitSurrModel](#)

return the [DataFitSurrModel](#) evaluation count. Due to possibly intermittent use of surrogate bypass, this is not the same as either the approxInterface or actualModel model evaluation counts. It also does not distinguish duplicate evals.

Reimplemented from [Model](#).

**8.23.2.13** `void build_global ()` [private]

Builds a global approximation using `daceIterator`.

Determine sample points to use in building the approximation and then evaluate them on actualModel using daceIterator. Any changes to the bounds should be performed by setting them at a higher level (e.g., [SurrBasedOptStrategy](#)).

#### 8.23.2.14 void build\_local\_multipoint () [private]

Builds a local or multipoint approximation using actualModel.

Evaluate the value, gradient, and possibly Hessian needed for a local or multipoint approximation using actualModel.

#### 8.23.2.15 void update\_actual\_model () [private]

update actualModel with data from current variables/labels/bounds/targets

Update variables and constraints data within actualModel using values and labels from currentVariables and bound/linear/nonlinear constraints from userDefinedConstraints.

#### 8.23.2.16 void update\_from\_actual\_model () [private]

update current variables/labels/bounds/targets with data from actualModel

Update values and labels in currentVariables and bound/linear/nonlinear constraints in userDefinedConstraints from variables and constraints data within actualModel.

### 8.23.3 Member Data Documentation

#### 8.23.3.1 Model actualModel [private]

(optional for global, required for local)

actualModel is unrestricted in type; arbitrary nestings are possible.

The documentation for this class was generated from the following files:

- DataFitSurrModel.H
- DataFitSurrModel.C

## 8.24 DataInterface Class Reference

Container class for interface specification data.

### Public Member Functions

- [DataInterface](#) ()  
*constructor*
- [DataInterface](#) (const [DataInterface](#) &)  
*copy constructor*
- [~DataInterface](#) ()  
*destructor*
- [DataInterface](#) & [operator=](#) (const [DataInterface](#) &)  
*assignment operator*
- bool [operator==](#) (const [DataInterface](#) &)  
*equality operator*
- void [write](#) (ostream &s) const  
*write a [DataInterface](#) object to an ostream*
- void [read](#) (MPIUnpackBuffer &s)  
*read a [DataInterface](#) object from a packed MPI buffer*
- void [write](#) (MPIPackBuffer &s) const  
*write a [DataInterface](#) object to a packed MPI buffer*

### Public Attributes

- [String](#) [idInterface](#)  
*(from the `id_interface` specification in [InterfIndControl](#))*
- [String](#) [interfaceType](#)  
*the interface selection: `system`, `fork`, `direct`, or `grid`*
- [String](#) [algebraicMappings](#)  
*(AMPL format) from JAGUAR.*

- [StringArray analysisDrivers](#)  
(from the `analysis_drivers` specification in **InterfIndControl**)
- [String2DArray analysisComponents](#)  
(from the `analysis_components` specification in **InterfIndControl**)
- [String inputFilter](#)  
`input_filter` specification in **InterfIndControl**)
- [String outputFilter](#)  
`output_filter` specification in **InterfIndControl**)
- [String parametersFile](#)  
**InterfApplicF**)
- [String resultsFile](#)  
**InterfApplicF**)
- [String analysisUsage](#)  
(from the `analysis_usage` specification in **InterfApplicSC**)
- [bool apreproFormatFlag](#)  
specification in **InterfApplicSC** and **InterfApplicF**)
- [bool fileTagFlag](#)  
specification in **InterfApplicSC** and **InterfApplicF**)
- [bool fileSaveFlag](#)  
specification in **InterfApplicSC** and **InterfApplicF**)
- [int procsPerAnalysis](#)  
`processors_per_analysis` specification in **InterfApplicDF**)
- [StringArray gridHostNames](#)  
`hostnames` specification in **InterfApplicG**)
- [IntArray gridProcsPerHost](#)  
`processors_per_host` specification in **InterfApplicG**)
- [String interfaceSynchronization](#)  
`InterfaceSynchronization` specification in **InterfIndControl**).
- [int asynchLocalEvalConcurrency](#)  
`the_evaluation_concurrency` specification in **InterfIndControl**)
- [int asynchLocalAnalysisConcurrency](#)

(from the `analysis_concurrency` specification in **InterfIndControl**)

- int `evalServers`  
(from the `evaluation_servers` specification in **InterfIndControl**)
- String `evalScheduling`  
*evaluation\_static\_scheduling* specifications in **InterfIndControl**)
- int `analysisServers`  
(from the `analysis_servers` specification in **InterfIndControl**)
- String `analysisScheduling`  
`analysis_static_scheduling` specifications in **InterfIndControl**)
- String `failAction`  
*specification* in **InterfIndControl**)
- int `retryLimit`  
*retry* specification in **InterfIndControl**)
- RealVector `recoveryFnVals`  
*in* **InterfIndControl**)
- bool `activeSetVectorFlag`  
**InterfIndControl**)
- bool `evalCacheFlag`  
*specification* in **InterfIndControl**)
- bool `restartFileFlag`  
`deactivate_restart_file` specification in **InterfIndControl**)

## Private Member Functions

- void `assign` (const `DataInterface` &`data_interface`)  
*by copy constructor and assignment operator*)

### 8.24.1 Detailed Description

Container class for interface specification data.

The `DataInterface` class is used to contain the data from an interface keyword specification. It is populated by `ProblemDescDB::interface_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. A list of `DataInterface` objects is maintained in `ProblemDescDB::interfaceList`, one for each interface specification

in an input file. Default values are managed in the `DataInterface` constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within `ProblemDescDB` since `ProblemDescDB::interfaceList` is private (a similar model is used with `SurrogateDataPoint` objects contained in `Dakota::Approximation`).

The documentation for this class was generated from the following files:

- `DataInterface.H`
- `DataInterface.C`

## 8.25 DataMethod Class Reference

Container class for method specification data.

### Public Member Functions

- [DataMethod \(\)](#)  
*constructor*
- [DataMethod \(const DataMethod &\)](#)  
*copy constructor*
- [~DataMethod \(\)](#)  
*destructor*
- [DataMethod & operator= \(const DataMethod &\)](#)  
*assignment operator*
- [bool operator== \(const DataMethod &\)](#)  
*equality operator*
- [void write \(ostream &s\) const](#)  
*write a DataMethod object to an ostream*
- [void read \(MPIUnpackBuffer &s\)](#)  
*read a DataMethod object from a packed MPI buffer*
- [void write \(MPIPackBuffer &s\) const](#)  
*write a DataMethod object to a packed MPI buffer*

### Public Attributes

- [String idMethod](#)  
*the id\_method specification in MethodIndControl)*
- [String modelPointer](#)  
*(from the model\_pointer specification in MethodIndControl)*
- [String methodOutput](#)  
*(default) (from the output specification in MethodIndControl)*



- int `maxIterations`  
*max\_iterations specification in **MethodIndControl***
- int `maxFunctionEvaluations`  
*the max\_function\_evaluations specification in **MethodIndControl***
- bool `speculativeFlag`  
*(from the speculative specification in **MethodIndControl**)*
- Real `convergenceTolerance`  
*convergence\_tolerance specification in **MethodIndControl***
- Real `constraintTolerance`  
*constraint\_tolerance specification in **MethodIndControl***
- bool `methodScaling`  
**MethodIndControl**)
- RealVector `linearIneqConstraintCoeffs`  
*MethodIndControl).*
- RealVector `linearIneqLowerBnds`  
*linear\_inequality\_lower\_bounds specification in **MethodIndControl***
- RealVector `linearIneqUpperBnds`  
*linear\_inequality\_upper\_bounds specification in **MethodIndControl***
- StringArray `linearIneqScaleTypes`  
*linear\_inequality\_scale\_types specification in **MethodIndControl***
- RealVector `linearIneqScales`  
*linear\_inequality\_scales specification in **MethodIndControl***
- RealVector `linearEqConstraintCoeffs`  
*MethodIndControl).*
- RealVector `linearEqTargets`  
*linear\_equality\_targets specification in **MethodIndControl***
- StringArray `linearEqScaleTypes`  
*linear\_equality\_scale\_types specification in **MethodIndControl***
- RealVector `linearEqScales`  
*linear\_equality\_scales specification in **MethodIndControl***
- String `methodName`

*or parameter study methods*

- [String minMaxType](#)  
*the optimization\_type specification in **MethodDOTDC***
- [String dlDetails](#)  
*string of options for a dynamically linked solver*
- [int verifyLevel](#)  
*the verify\_level specification in **MethodNPSOLDC***
- [Real functionPrecision](#)  
*the function\_precision specification in **MethodNPSOLDC***
- [Real lineSearchTolerance](#)  
*the linesearch\_tolerance specification in **MethodNPSOLDC***
- [Real absConvTol](#)  
*absolute function convergence tolerance*
- [Real xConvTol](#)  
*x-convergence tolerance*
- [Real singConvTol](#)  
*singular convergence tolerance*
- [Real singRadius](#)  
*radius for singular convergence test*
- [Real falseConvTol](#)  
*false-convergence tolerance*
- [Real initTRRadius](#)  
*initial trust radius*
- [int covarianceType](#)  
*kind of covariance required*
- [bool regressDiag](#)  
*whether to print the regression diagnostic vector*
- [String searchMethod](#)  
*interior-point methods in **MethodOPTPPDC***
- [Real gradientTolerance](#)  
*the gradient\_tolerance specification in **MethodOPTPPDC***

- Real [maxStep](#)  
*the max\_step specification in **MethodOPTPPDC***
- String [meritFn](#)  
*interior-point methods in **MethodOPTPPDC***
- String [centralPath](#)  
*methods in **MethodOPTPPDC***
- Real [stepLenToBoundary](#)  
*interior-point methods in **MethodOPTPPDC***
- Real [centeringParam](#)  
*interior-point methods in **MethodOPTPPDC***
- int [searchSchemeSize](#)  
**MethodOPTPPDC**
- String [evalSynchronization](#)  
*methods in **MethodCOLINYPS** and **MethodCOLINYAPPS***
- Real [constraintPenalty](#)  
**MethodCOLINYSW** and **MethodCOLINYEA**
- bool [constantPenalty](#)  
**MethodCOLINYPS** and **MethodCOLINYSW**
- Real [globalBalanceParam](#)  
**MethodCOLINYDIR**
- Real [localBalanceParam](#)  
**MethodCOLINYDIR**
- Real [maxBoxSize](#)  
*the max\_boxsize\_limit for the **DIRECT** method in **MethodCOLINYDIR***
- Real [minBoxSize](#)  
*the min\_boxsize\_limit for the **DIRECT** method in **MethodCOLINYDIR***
- Real [volBoxSize](#)  
*the volume\_boxsize\_limit for the **DIRECT** method in **MethodNCSUDC***
- String [boxDivision](#)  
*the **DIRECT** method in **MethodCOLINYDIR***

- bool [mutationAdaptive](#)  
**MethodCOLINYEA**
- bool [showMiscOptions](#)  
*the show\_misc\_options specification in **MethodCOLINYDC***
- [StringArray miscOptions](#)  
*the misc\_options specification in **MethodCOLINYDC***
- Real [solnAccuracy](#)  
*the solution\_accuracy specification in **MethodCOLINYDC***
- Real [crossoverRate](#)  
*the crossover\_rate specification for EA methods in **MethodCOLINYEA***
- Real [mutationRate](#)  
*the mutation\_rate specification for EA methods in **MethodCOLINYEA***
- Real [mutationScale](#)  
*the mutation\_scale specification for EA methods in **MethodCOLINYEA***
- Real [mutationMinScale](#)  
**MethodCOLINYEA**
- Real [initDelta](#)  
*and **MethodCOLINYSW***
- Real [threshDelta](#)  
*and **MethodCOLINYSW***
- Real [contractFactor](#)  
**MethodCOLINYAPPS, MethodCOLINYPS, and MethodCOLINYSW**
- int [newSolnsGenerated](#)  
*in **MethodCOLINYEA***
- int [numberRetained](#)  
***MethodCOLINYEA**.*
- bool [expansionFlag](#)  
**MethodCOLINYAPPS, MethodCOLINYPS, and MethodCOLINYSW**
- int [expandAfterSuccess](#)  
**MethodCOLINYPS and MethodCOLINYSW**
- int [contractAfterFail](#)

**MethodCOLINYSW**

- int [mutationRange](#)

**MethodCOLINYEAE**

- int [totalPatternSize](#)

*MethodCOLINYPSE.*

- bool [randomizeOrderFlag](#)

*MethodCOLINYPSE.*

- String [selectionPressure](#)

*the fitness\_type specification for EA methods in MethodCOLINYEAE*

- String [replacementType](#)

*MethodCOLINYEAE.*

- String [crossoverType](#)

*the crossover\_type specification for EA methods in MethodCOLINYEAE*

- String [mutationType](#)

*the mutation\_type specification for EA methods in MethodCOLINYEAE*

- String [exploratoryMoves](#)

*MethodCOLINYPSE.*

- String [patternBasis](#)

*MethodCOLINYAPPS and MethodCOLINYPSE.*

- size\_t [numCrossPoints](#)

*The number of crossover points or multi-point schemes.*

- size\_t [numParents](#)

*The number of parents to use in a crossover operation.*

- size\_t [numOffspring](#)

*The number of children to produce in a crossover operation.*

- String [fitnessType](#)

*the fitness assessment operator to use.*

- String [convergenceType](#)

*The means by which this JEGA should converge.*

- Real [percentChange](#)

*for a fitness tracker converger.*

- `size_t numGenerations`  
*tracker converger should track.*
- Real `fitnessLimit`  
*below\_limit selector).*
- Real `shrinkagePercent`  
*must take place on each call to the selector (0, 1).*
- String `nichingType`  
*The niching type.*
- RealVector `nicheVector`  
*The discretization percentage along each objective.*
- String `postProcessorType`  
*The post processor type.*
- RealVector `distanceVector`  
*The discretization percentage along each objective.*
- String `initializationType`  
*The means by which the JEGA should initialize the population.*
- String `flatFile`  
*The filename to use for initialization.*
- String `logFile`  
*The filename to use for logging.*
- int `populationSize`  
*MethodCOLINYEA.*
- bool `printPopFlag`  
*at each generation*
- String `daceMethod`  
*dace specification in **MethodDDACE**)*
- int `numSymbols`  
*the symbols specification for DACE methods*
- bool `mainEffectsFlag`  
*in **MethodDDACE**)*

- bool [latinizeFlag](#)  
**MethodFSUDACE**
- bool [volQualityFlag](#)  
*and CVT methods in **MethodFSUDACE**)*
- bool [varBasedDecompFlag](#)  
*and CVT methods in **MethodFSUDACE**)*
- [IntVector](#) [sequenceStart](#)  
*the sequenceStart specification in **MethodFSUDACE***
- [IntVector](#) [sequenceLeap](#)  
*the sequenceLeap specification in **MethodFSUDACE***
- [IntVector](#) [primeBase](#)  
*the primeBase specification in **MethodFSUDACE***
- int [numTrials](#)  
*the numTrials specification in **MethodFSUDACE***
- [String](#) [trialType](#)  
*the trial\_type specification in **MethodFSUDACE***
- int [randomSeed](#)  
*the seed specification for COLINY, *NonD*, & DACE methods*
- int [numSamples](#)  
*the samples specification for *NonD* & DACE methods*
- bool [fixedSeedFlag](#)  
*stencil/pattern throughout a strategy with repeated sampling.*
- bool [fixedSequenceFlag](#)  
*stencil/pattern throughout a strategy with repeated sampling.*
- int [previousSamples](#)  
*the number of previous samples when augmenting a LHS sample*
- int [expansionTerms](#)  
*the expansion\_terms specification in **MethodNonDPCE***
- short [expansionOrder](#)  
*the expansion\_order specification in **MethodNonDPCE***
- int [expansionSamples](#)

*the expansion\_samples specification in **MethodNonDPCE***

- [ShortArray quadratureOrder](#)  
*the quadrature\_order specification in **MethodNonDPCE***
- short [cubatureLevel](#)  
*the cubature\_level specification in **MethodNonDPCE***
- int [collocationPoints](#)  
*the collocation\_points specification in **MethodNonDPCE***
- [String expansionImportFile](#)  
*the expansion\_import\_file specification in **MethodNonDPCE***
- [String sampleType](#)  
*MethodNonDPCE.*
- [String reliabilitySearchType](#)  
**MethodNonDGGlobalRel** (*x\_gaussian\_process or u\_gaussian\_process*)
- [String reliabilitySearchAlgorithm](#)  
*by sqp or nip in **MethodNonDLocalRel***
- [String reliabilityIntegration](#)  
**MethodNonDLocalRel**
- [String reliabilityIntegrationRefine](#)  
*integration refinement selection in **MethodNonDLocalRel***
- [String distributionType](#)  
*and **MethodNonDGGlobalRel***
- [String responseLevelMappingType](#)  
**MethodNonDLocalRel**, *and **MethodNonDGGlobalRel***
- [RealVectorArray responseLevels](#)  
**MethodNonDPCE**, **MethodNonDLocalRel**, *and **MethodNonDGGlobalRel***
- [RealVectorArray probabilityLevels](#)  
**MethodNonDPCE**, **MethodNonDLocalRel**, *and **MethodNonDGGlobalRel***
- [RealVectorArray reliabilityLevels](#)  
**MethodNonDPCE**, *and **MethodNonDLocalRel***
- [RealVectorArray genReliabilityLevels](#)  
**MethodNonDPCE**, **MethodNonDLocalRel**, *and **MethodNonDGGlobalRel***



- bool [allVarsFlag](#)  
*the all\_variables specification in **MethodNonDMC***
- short [paramStudyType](#)  
*centered(4), or multidim(5)*
- **RealVector** [finalPoint](#)  
*the final\_point specification in **MethodPSVPS***
- **RealVector** [stepVector](#)  
*the step\_vector specification in **MethodPSVPS***
- Real [stepLength](#)  
*the step\_length specification in **MethodPSVPS***
- int [numSteps](#)  
*the num\_steps specification in **MethodPSVPS***
- **RealVector** [listOfPoints](#)  
*the list\_of\_points specification in **MethodPSLPS***
- Real [percentDelta](#)  
*the percent\_delta specification in **MethodPSCPS***
- int [deltasPerVariable](#)  
*the deltas\_per\_variable specification in **MethodPSCPS***
- **IntArray** [varPartitions](#)  
*MethodPSMPS.*

## Private Member Functions

- void [assign](#) (const [DataMethod](#) &data\_method)  
*by copy constructor and assignment operator*

### 8.25.1 Detailed Description

Container class for method specification data.

The [DataMethod](#) class is used to contain the data from a method keyword specification. It is populated by `ProblemDescDB::method_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. A list of [DataMethod](#) objects is maintained in `ProblemDescDB::methodList`, one for each method specification in an input file. Default values are managed in the [DataMethod](#) constructor. Data is public to avoid maintaining

set/get functions, but is still encapsulated within [ProblemDescDB](#) since `ProblemDescDB::methodList` is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- `DataMethod.H`
- `DataMethod.C`

## 8.26 DataModel Class Reference

Container class for model specification data.

### Public Member Functions

- [DataModel \(\)](#)  
*constructor*
- [DataModel \(const DataModel &\)](#)  
*copy constructor*
- [~DataModel \(\)](#)  
*destructor*
- [DataModel & operator= \(const DataModel &\)](#)  
*assignment operator*
- [bool operator== \(const DataModel &\)](#)  
*equality operator*
- [void write \(ostream &s\) const](#)  
*write a [DataModel](#) object to an ostream*
- [void read \(MPIUnpackBuffer &s\)](#)  
*read a [DataModel](#) object from a packed MPI buffer*
- [void write \(MPIPackBuffer &s\) const](#)  
*write a [DataModel](#) object to a packed MPI buffer*

### Public Attributes

- [String idModel](#)  
*the id\_model specification in **ModelIndControl**)*
- [String modelType](#)  
*specification in **ModelIndControl**)*
- [String variablesPointer](#)  
*(from the variables\_pointer specification in **ModelIndControl**)*

- [String interfacePointer](#)  
*the optional\_interface\_pointer specification in **ModelNested**)*
- [String responsesPointer](#)  
*(from the responses\_pointer specification in **ModelIndControl**)*
- [IntSet surrogateFnIndices](#)  
*array specifying the response function set that is approximated*
- [String surrogateType](#)  
*polynomial,kriging), or hierarchical*
- [String actualModelPtr](#)  
*and **ModelSurrMP**)*
- [String lowFidelityModelPtr](#)  
*specification in **ModelSurrH**)*
- [String highFidelityModelPtr](#)  
*specification in **ModelSurrH**)*
- [String approxDaceMethodPtr](#)  
*specification in **ModelSurrG**)*
- [String approxSampleReuse](#)  
**ModelSurrG)**
- [String approxSampleReuseFile](#)  
*specification in **ModelSurrG***
- [String approxCorrectionType](#)  
*in **ModelSurrG** and **ModelSurrH**)*
- short [approxCorrectionOrder](#)  
*and **ModelSurrH**)*
- bool [approxGradUsageFlag](#)  
*(from the use\_gradients specification in **ModelSurrG**)*
- [RealVector krigingCorrelations](#)  
*(from the correlations specification in **ModelSurrG**)*
- short [polynomialOrder](#)  
*in **ModelSurrG**)*
- short [trendOrder](#)

`gaussian_process` specification in **ModelSurrG**)

- [bool pointSelection](#)  
*flag indicating the use of point selection in the Gaussian process*
- [String optionalInterfRespPointer](#)  
*optional\_interface\_responses\_pointer specification in **ModelNested**)*
- [String subMethodPointer](#)  
*the sub\_method\_pointer specification in **ModelNested**)*
- [StringArray primaryVarMaps](#)  
**ModelNested)**
- [StringArray secondaryVarMaps](#)  
*secondary\_variable\_mapping specification in **ModelNested**)*
- [RealVector primaryRespCoeffs](#)  
*specification in **ModelNested**)*
- [RealVector secondaryRespCoeffs](#)  
*specification in **ModelNested**)*

## Private Member Functions

- `void assign` (const [DataModel](#) &data\_model)  
*by copy constructor and assignment operator)*

### 8.26.1 Detailed Description

Container class for model specification data.

The [DataModel](#) class is used to contain the data from a model keyword specification. It is populated by `ProblemDescDB::model_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. A list of [DataModel](#) objects is maintained in `ProblemDescDB::modelList`, one for each model specification in an input file. Default values are managed in the [DataModel](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within `ProblemDescDB` since `ProblemDescDB::modelList` is private (a similar model is used with [SurrogateDataPoint](#) objects contained in `Dakota::Approximation`).

The documentation for this class was generated from the following files:

- `DataModel.H`
- `DataModel.C`

## 8.27 DataResponses Class Reference

Container class for responses specification data.

### Public Member Functions

- [DataResponses](#) ()  
*constructor*
- [DataResponses](#) (const [DataResponses](#) &)  
*copy constructor*
- [~DataResponses](#) ()  
*destructor*
- [DataResponses](#) & [operator=](#) (const [DataResponses](#) &)  
*assignment operator*
- bool [operator==](#) (const [DataResponses](#) &)  
*equality operator*
- void [write](#) (ostream &s) const  
*write a [DataResponses](#) object to an ostream*
- void [read](#) (MPIUnpackBuffer &s)  
*read a [DataResponses](#) object from a packed MPI buffer*
- void [write](#) (MPIPackBuffer &s) const  
*write a [DataResponses](#) object to a packed MPI buffer*

### Public Attributes

- size\_t [numObjectiveFunctions](#)  
*num\_objective\_functions specification in **RespFnOpt***
- size\_t [numNonlinearIneqConstraints](#)  
*num\_nonlinear\_inequality\_constraints specification in **RespFnOpt***
- size\_t [numNonlinearEqConstraints](#)  
*num\_nonlinear\_equality\_constraints specification in **RespFnOpt***

- [size\\_t numLeastSqTerms](#)  
*num\_least\_squares\_terms* specification in **RespFnLS**)
- [size\\_t numResponseFunctions](#)  
*num\_response\_functions* specification in **RespFnGen**)
- [StringArray objectiveFunctionScaleTypes](#)  
*objective\_function\_scale\_types* specification in **RespFnOpt**)
- [RealVector objectiveFunctionScales](#)  
*objective\_function\_scales* specification in **RespFnOpt**)
- [RealVector multiObjectiveWeights](#)  
*multi\_objective\_weights* specification in **RespFnOpt**)
- [String leastSqDataFile](#)  
**RespFnOpt**)
- [StringArray leastSqTermScaleTypes](#)  
*least\_squares\_term\_scale\_types* specification in **RespFnOpt**)
- [RealVector leastSqTermScales](#)  
*least\_squares\_term\_scales* specification in **RespFnOpt**)
- [RealVector nonlinearIneqLowerBnds](#)  
*nonlinear\_inequality\_lower\_bounds* specification in **RespFnOpt**)
- [RealVector nonlinearIneqUpperBnds](#)  
*nonlinear\_inequality\_upper\_bounds* specification in **RespFnOpt**)
- [StringArray nonlinearIneqScaleTypes](#)  
*nonlinear\_inequality\_scale\_types* specification in **RespFnOpt**)
- [RealVector nonlinearIneqScales](#)  
*nonlinear\_inequality\_scales* specification in **RespFnOpt**)
- [RealVector nonlinearEqTargets](#)  
*nonlinear\_equality\_targets* specification in **RespFnOpt**)
- [StringArray nonlinearEqScaleTypes](#)  
*nonlinear\_equality\_scale\_types* specification in **RespFnOpt**)
- [RealVector nonlinearEqScales](#)  
*nonlinear\_equality\_scales* specification in **RespFnOpt**)
- [String gradientType](#)

`mixed_gradients` specifications in **RespGrad**)

- [String hessianType](#)  
**RespHess**)
- [String quasiHessianType](#)  
*and `sr1` specifications in **RespHess**)*
- [String methodSource](#)  
*method\_source specification in **RespGradNum** and **RespGradMixed**)*
- [String intervalType](#)  
*interval\_type specification in **RespGradNum** and **RespGradMixed**)*
- [RealVector fdGradStepSize](#)  
*specification in **RespGradNum** and **RespGradMixed**)*
- [RealVector fdHessStepSize](#)  
**RespHessMixed**)
- [IntList idNumericalGrads](#)  
*specification in **RespGradMixed**)*
- [IntList idAnalyticGrads](#)  
*specification in **RespGradMixed**)*
- [IntList idNumericalHessians](#)  
*specification in **RespHessMixed**)*
- [IntList idQuasiHessians](#)  
*specification in **RespHessMixed**)*
- [IntList idAnalyticHessians](#)  
*specification in **RespHessMixed**)*
- [String idResponses](#)  
*(from the `id_responses` specification in **RespSetId**)*
- [StringArray responseLabels](#)  
*specification in **RespLabels**)*

## Private Member Functions

- void [assign](#) (const [DataResponses](#) &data\_responses)  
*by copy constructor and assignment operator)*



### 8.27.1 Detailed Description

Container class for responses specification data.

The [DataResponses](#) class is used to contain the data from a responses keyword specification. It is populated by `ProblemDescDB::responses_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. A list of [DataResponses](#) objects is maintained in `ProblemDescDB::responsesList`, one for each responses specification in an input file. Default values are managed in the [DataResponses](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since `ProblemDescDB::responsesList` is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataResponses.H](#)
- [DataResponses.C](#)

## 8.28 DataStrategy Class Reference

Container class for strategy specification data.

### Public Member Functions

- [DataStrategy \(\)](#)  
*constructor*
- [DataStrategy \(const DataStrategy &\)](#)  
*copy constructor*
- [~DataStrategy \(\)](#)  
*destructor*
- [DataStrategy & operator= \(const DataStrategy &\)](#)  
*assignment operator*
- void [write](#) (ostream &s) const  
*write a DataStrategy object to an ostream*
- void [read](#) (MPIUnpackBuffer &s)  
*read a DataStrategy object from a packed MPI buffer*
- void [write](#) (MPIPackBuffer &s) const  
*write a DataStrategy object to a packed MPI buffer*

### Public Attributes

- [String strategyType](#)  
*branch\_and\_bound, multi\_start, pareto\_set, or single\_method*
- bool [graphicsFlag](#)  
*specification in StratIndControl)*
- bool [tabularDataFlag](#)  
*the tabular\_graphics\_data specification in StratIndControl)*
- [String tabularDataFile](#)  
*the tabular\_graphics\_file specification in StratIndControl)*

- int `iteratorServers`  
*the `iterator_servers` specification in **StratIndControl**)*
- String `iteratorScheduling`  
*`iterator_static_scheduling` specifications in **StratIndControl**)*
- String `methodPointer`  
*`StratMultiStart`.*
- StringArray `multilevelMethodList`  
*strategy (from the `method_list` specification in **StratML**)*
- String `multilevelType`  
*`adaptive_hybrid`, and coupled specifications in **StratML**)*
- Real `multilevelProgThresh`  
*(from the `progress_threshold` specification in **StratML**)*
- String `multilevelGlobalMethodPointer`  
*(from the `global_method_pointer` specification in **StratML**)*
- String `multilevelLocalMethodPointer`  
*(from the `local_method_pointer` specification in **StratML**)*
- Real `multilevelLSProb`  
*(from the `local_search_probability` specification in **StratML**)*
- size\_t `numSolutionsTransferred`  
*to a subsequent method the multilevel strategy*
- int `surrBasedOptMaxIterations`  
*in **StratSBO**)*
- Real `surrBasedOptConvTol`  
*(from the `convergence_tolerance` specification in **StratSBO**)*
- int `surrBasedOptSoftConvLimit`  
*specification in **StratSBO**)*
- bool `surrBasedOptLayerBypass`  
*in evaluating truth response values in **SBO**.*
- Real `surrBasedOptTRInitSize`  
*distance (upper bound - lower bound) for each variable*
- Real `surrBasedOptTRMinSize`

*regions)*

- Real [surrBasedOptTRContractTrigger](#)  
*("eta\_1" in the Conn-Gould-Toint trust region book)*
- Real [surrBasedOptTRExpandTrigger](#)  
*Conn-Gould-Toint trust region book).*
- Real [surrBasedOptTRContract](#)  
*specification in **StratSBO**)*
- Real [surrBasedOptTRExpand](#)  
*in **StratSBO**)*
- short [surrBasedOptSubProbObj](#)  
*LAGRANGIAN\_OBJECTIVE, or AUGMENTED\_LAGRANGIAN\_OBJECTIVE.*
- short [surrBasedOptSubProbCon](#)  
*LINEARIZED\_CONSTRAINTS, or ORIGINAL\_CONSTRAINTS.*
- short [surrBasedOptMeritFn](#)  
*BASIC\_LAGRANGIAN, or AUGMENTED\_LAGRANGIAN.*
- short [surrBasedOptAcceptLogic](#)  
*SBO iterate acceptance logic: TR\_RATIO or FILTER.*
- short [surrBasedOptConstrRelax](#)  
*SBO constraint relaxation method: NO\_RELAX or HOMOTOPY.*
- int [concurrentRandomJobs](#)  
*in **StratMultiStart** and **StratParetoSet**)*
- int [concurrentSeed](#)  
*and **StratParetoSet**)*
- [RealVector](#) [concurrentParameterSets](#)  
*StratMultiStart and **StratParetoSet**).*

## Private Member Functions

- void [assign](#) (const [DataStrategy](#) &data\_strategy)  
*by copy constructor and assignment operator)*

### 8.28.1 Detailed Description

Container class for strategy specification data.

The [DataStrategy](#) class is used to contain the data from a strategy keyword specification. It is populated by `ProblemDescDB::strategy_kwhandler()` and is queried by the `ProblemDescDB::get_<datatype>()` functions. Default values are managed in the [DataStrategy](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since `ProblemDescDB::strategySpec` is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataStrategy.H](#)
- [DataStrategy.C](#)

## 8.29 DataVariables Class Reference

Container class for variables specification data.

### Public Member Functions

- [DataVariables](#) ()  
*constructor*
- [DataVariables](#) (const [DataVariables](#) &)  
*copy constructor*
- [~DataVariables](#) ()  
*destructor*
- [DataVariables](#) & [operator=](#) (const [DataVariables](#) &)  
*assignment operator*
- bool [operator==](#) (const [DataVariables](#) &)  
*equality operator*
- void [write](#) (ostream &s) const  
*write a [DataVariables](#) object to an ostream*
- void [read](#) (MPIUnpackBuffer &s)  
*read a [DataVariables](#) object from a packed MPI buffer*
- void [write](#) (MPIPackBuffer &s) const  
*write a [DataVariables](#) object to a packed MPI buffer*
- size\_t [design](#) ()  
*return total number of design variables*
- size\_t [uncertain](#) ()  
*return total number of uncertain variables*
- size\_t [state](#) ()  
*return total number of state variables*
- size\_t [num\\_continuous\\_variables](#) ()  
*return total number of continuous variables*

- size\_t [num\\_discrete\\_variables](#) ()  
*return total number of discrete variables*
- size\_t [num\\_variables](#) ()  
*return total number of variables*

## Public Attributes

- [String idVariables](#)  
*(from the `id_variables` specification in **VarSetId**)*
- size\_t [numContinuousDesVars](#)  
*specification in **VarDV**)*
- size\_t [numDiscreteDesVars](#)  
*specification in **VarDV**)*
- size\_t [numNormalUncVars](#)  
*specification in **VarUV**)*
- size\_t [numLognormalUncVars](#)  
*specification in **VarUV**)*
- size\_t [numUniformUncVars](#)  
*specification in **VarUV**)*
- size\_t [numLoguniformUncVars](#)  
*loguniform\_uncertain specification in **VarUV**)*
- size\_t [numTriangularUncVars](#)  
*triangular\_uncertain specification in **VarUV**)*
- size\_t [numExponentialUncVars](#)  
*exponential\_uncertain specification in **VarUV**)*
- size\_t [numBetaUncVars](#)  
*specification in **VarUV**)*
- size\_t [numGammaUncVars](#)  
*specification in **VarUV**)*
- size\_t [numGumbelUncVars](#)  
*specification in **VarUV**)*
- size\_t [numFrechetUncVars](#)

- specification in **VarUV**)*
- [size\\_t numWeibullUncVars](#)  
*specification in **VarUV**)*
- [size\\_t numHistogramUncVars](#)  
*specification in **VarUV**)*
- [size\\_t numIntervalUncVars](#)  
*specification in **VarUV**)*
- [size\\_t numContinuousStateVars](#)  
*specification in **VarSV**)*
- [size\\_t numDiscreteStateVars](#)  
*specification in **VarSV**)*
- [RealVector continuousDesignVars](#)  
*the `cdv_initial_point` specification in **VarDV**)*
- [RealVector continuousDesignLowerBnds](#)  
*`cdv_lower_bounds` specification in **VarDV**)*
- [RealVector continuousDesignUpperBnds](#)  
*`cdv_upper_bounds` specification in **VarDV**)*
- [StringArray continuousDesignScaleTypes](#)  
*`cdv_scale_types` specification in **VarDV**)*
- [RealVector continuousDesignScales](#)  
*`cdv_scales` specification in **VarDV**)*
- [IntVector discreteDesignVars](#)  
*the `ddv_initial_point` specification in **VarDV**)*
- [IntVector discreteDesignLowerBnds](#)  
*`ddv_lower_bounds` specification in **VarDV**)*
- [IntVector discreteDesignUpperBnds](#)  
*`ddv_upper_bounds` specification in **VarDV**)*
- [StringArray continuousDesignLabels](#)  
*specification in **VarDV**)*
- [StringArray discreteDesignLabels](#)  
*specification in **VarDV**)*



- [RealVector normalUncMeans](#)  
*specification in **VarUV**)*
- [RealVector normalUncStdDevs](#)  
*the nuv\_std\_deviations specification in **VarUV**)*
- [RealVector normalUncLowerBnds](#)  
*(from the nuv\_lower\_bounds specification in **VarUV**)*
- [RealVector normalUncUpperBnds](#)  
*(from the nuv\_upper\_bounds specification in **VarUV**)*
- [RealVector lognormalUncMeans](#)  
*lnuv\_means specification in **VarUV**)*
- [RealVector lognormalUncStdDevs](#)  
*the lnuv\_std\_deviations specification in **VarUV**)*
- [RealVector lognormalUncErrFacts](#)  
*the lnuv\_error\_factors specification in **VarUV**)*
- [RealVector lognormalUncLowerBnds](#)  
*(from the lnuv\_lower\_bounds specification in **VarUV**)*
- [RealVector lognormalUncUpperBnds](#)  
*(from the lnuv\_upper\_bounds specification in **VarUV**)*
- [RealVector uniformUncLowerBnds](#)  
*(from the uuv\_lower\_bounds specification in **VarUV**)*
- [RealVector uniformUncUpperBnds](#)  
*(from the uuv\_upper\_bounds specification in **VarUV**)*
- [RealVector loguniformUncLowerBnds](#)  
*(from the luuv\_lower\_bounds specification in **VarUV**)*
- [RealVector loguniformUncUpperBnds](#)  
*(from the luuv\_upper\_bounds specification in **VarUV**)*
- [RealVector triangularUncModes](#)  
*specification in **VarUV**)*
- [RealVector triangularUncLowerBnds](#)  
*(from the tuv\_lower\_bounds specification in **VarUV**)*

- [RealVector triangularUncUpperBnds](#)  
(from the `tuv_upper_bounds` specification in **VarUV**)
- [RealVector exponentialUncBetas](#)  
(the `euv_betas` specification in **VarUV**)
- [RealVector betaUncAlphas](#)  
(the `buv_means` specification in **VarUV**)
- [RealVector betaUncBetas](#)  
(the `buv_std_deviations` specification in **VarUV**)
- [RealVector betaUncLowerBnds](#)  
(from the `buv_lower_bounds` specification in **VarUV**)
- [RealVector betaUncUpperBnds](#)  
(from the `buv_upper_bounds` specification in **VarUV**)
- [RealVector gammaUncAlphas](#)  
(the `gauv_alphas` specification in **VarUV**)
- [RealVector gammaUncBetas](#)  
(the `gauv_betas` specification in **VarUV**)
- [RealVector gumbelUncAlphas](#)  
(`guuv_alphas` specification in **VarUV**)
- [RealVector gumbelUncBetas](#)  
(the `guuv_betas` specification in **VarUV**)
- [RealVector frechetUncAlphas](#)  
(the `fuv_alphas` specification in **VarUV**)
- [RealVector frechetUncBetas](#)  
(the `fuv_betas` specification in **VarUV**)
- [RealVector weibullUncAlphas](#)  
(the `wuv_alphas` specification in **VarUV**)
- [RealVector weibullUncBetas](#)  
(the `wuv_betas` specification in **VarUV**)
- [RealVectorArray histogramUncBinPairs](#)  
(specifications in **VarUV**)
- [RealVectorArray histogramUncPointPairs](#)

*specifications in VarUV)*

- [RealVectorArray intervalUncBasicProbs](#)  
*iuv\_interval\_probs specification in VarUV)*
- [RealVectorArray intervalUncBounds](#)  
*iuv\_interval\_bounds specification in VarUV)*
- [RealMatrix uncertainCorrelations](#)  
*matrix) for analytic reliability methods.*
- [RealVector uncertainVars](#)  
*initialized in IDRProblemDescDB::variables\_kwhandler())*
- [RealVector uncertainLowerBnds](#)  
*for gamma, gumbel, frechet, weibull and histogram specifications)*
- [RealVector uncertainUpperBnds](#)  
*for gamma, gumbel, frechet, weibull and histogram specifications)*
- [StringArray uncertainLabels](#)  
*huv\_descriptors specifications in VarUV)*
- [RealVector continuousStateVars](#)  
*the csv\_initial\_state specification in VarSV)*
- [RealVector continuousStateLowerBnds](#)  
*csv\_lower\_bounds specification in VarSV)*
- [RealVector continuousStateUpperBnds](#)  
*csv\_upper\_bounds specification in VarSV)*
- [IntVector discreteStateVars](#)  
*the dsv\_initial\_state specification in VarSV)*
- [IntVector discreteStateLowerBnds](#)  
*dsv\_lower\_bounds specification in VarSV)*
- [IntVector discreteStateUpperBnds](#)  
*dsv\_upper\_bounds specification in VarSV)*
- [StringArray continuousStateLabels](#)  
*specification in VarSV)*
- [StringArray discreteStateLabels](#)  
*specification in VarSV)*

## Private Member Functions

- void `assign` (const [DataVariables](#) &data\_variables)  
*by copy constructor and assignment operator*

### 8.29.1 Detailed Description

Container class for variables specification data.

The [DataVariables](#) class is used to contain the data from a variables keyword specification. It is populated by [IDRProblemDescDB::variables\\_kwhandler\(\)](#) and is queried by the `ProblemDescDB::get_<datatype>()` functions. A list of [DataVariables](#) objects is maintained in [ProblemDescDB::variablesList](#), one for each variables specification in an input file. Default values are managed in the [DataVariables](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since [ProblemDescDB::variablesList](#) is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

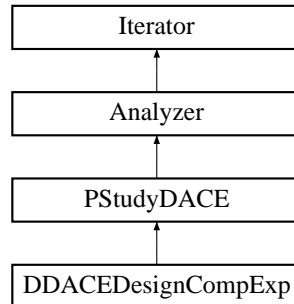
The documentation for this class was generated from the following files:

- [DataVariables.H](#)
- [DataVariables.C](#)

## 8.30 DDACEDesignCompExp Class Reference

Wrapper class for the DDACE design of experiments library.

Inheritance diagram for DDACEDesignCompExp::



### Public Member Functions

- [DDACEDesignCompExp \(Model &model\)](#)  
*primary constructor for building a standard DACE iterator*
- [DDACEDesignCompExp \(Model &model, int samples, int symbols, int seed, const String &sampling\\_method\)](#)  
*alternate constructor used for building approximations*
- [~DDACEDesignCompExp \(\)](#)  
*destructor*
- void [extract\\_trends \(\)](#)  
*Redefines the run\_iterator virtual function for the PStudy/DACE branch.*
- void [sampling\\_reset](#) (int min\_samples, bool all\_data\_flag, bool stats\_flag)  
*reset sampling iterator*
- const [String & sampling\\_scheme \(\)](#) const  
*return sampling name*
- void [vary\\_pattern](#) (bool pattern\_flag)  
*sets varyPattern in derived classes that support it*
- void [get\\_parameter\\_sets](#) (const [Model](#) &model)  
*Returns one block of samples (ndim \* num\_samples).*

## Private Member Functions

- void `compute_main_effects()`  
*builds a `DDaceMainEffects::OneWayANOVA` if `mainEffectsFlag` is set*
- void `resolve_samples_symbols()`  
*number of symbols from input.*

## Private Attributes

- String `daceMethod`  
*oas, lhs, oa\_lhs, random, box\_behnken, central\_composite, or grid*
- int `samplesSpec`  
*initial specification of number of samples*
- int `symbolsSpec`  
*initial specification of number of symbols*
- int `numSamples`  
*current number of samples to be evaluated*
- int `numSymbols`  
*(inversely related to number of replications)*
- const int `originalSeed`  
*(allows repeatable results)*
- int `randomSeed`  
*current seed for the random number generator*
- bool `allDataFlag`  
*`Iterator::all_variables()` and `Iterator::all_responses()`.*
- size\_t `numDACERuns`  
*counter for number of `run()` executions for this object*
- bool `varyPattern`  
*multiple executions are repeatable but not correlated.*
- bool `volQualityFlag`  
*flag which specifies evaluating the volumetric quality measures*
- bool `varBasedDecompFlag`  
*flag which specifies variance based decomposition*

- bool [mainEffectsFlag](#)  
*flag which specifies main effects*
- std::vector< std::vector< int > > [symbolMapping](#)  
*mapping of symbols for main effects calculations*

### 8.30.1 Detailed Description

Wrapper class for the DDACE design of experiments library.

The [DDACEDesignCompExp](#) class provides a wrapper for DDACE, a C++ design of experiments library from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site. This class uses design and analysis of computer experiments (DACE) methods to sample the design space spanned by the bounds of a [Model](#). It returns all generated samples and their corresponding responses as well as the best sample found.

### 8.30.2 Constructor & Destructor Documentation

#### 8.30.2.1 [DDACEDesignCompExp \(Model & model\)](#)

primary constructor for building a standard DACE iterator

This constructor is called for a standard iterator built with data from probDescDB.

#### 8.30.2.2 [DDACEDesignCompExp \(Model & model, int samples, int symbols, int seed, const String & sampling\\_method\)](#)

alternate constructor used for building approximations

This alternate constructor is used for instantiations on-the-fly, using only the incoming data. No problem description database queries are used.

### 8.30.3 Member Function Documentation

#### 8.30.3.1 `void resolve_samples_symbols () [private]`

number of symbols from input.

This function must define a combination of samples and symbols that is acceptable for a particular sampling algorithm. Users provide requests for these quantities, but this function must enforce any restrictions imposed by the sampling algorithms.

The documentation for this class was generated from the following files:

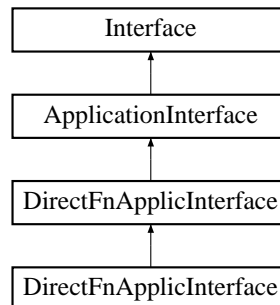
- DDACEDesignCompExp.H
- DDACEDesignCompExp.C



## 8.31 DirectFnApplicInterface Class Reference

Sample derived interface class for testing plug-ins using [assign\\_rep\(\)](#).

Inheritance diagram for DirectFnApplicInterface::



### Public Member Functions

- [DirectFnApplicInterface](#) (const [Dakota::ProblemDescDB](#) &problem\_db)  
*constructor*
- [~DirectFnApplicInterface](#) ()  
*destructor*

### Protected Member Functions

- int [derived\\_map\\_ac](#) (const [Dakota::String](#) &ac\_name)  
*execute an analysis code portion of a direct evaluation invocation*

#### 8.31.1 Detailed Description

Sample derived interface class for testing plug-ins using [assign\\_rep\(\)](#).

The plug-in [DirectFnApplicInterface](#) resides in namespace [SIM](#) and uses a copy of [rosenbrock\(\)](#) to perform parameter to response mappings. It may be activated by specifying the `--with-plugin` configure option, which activates the `DAKOTA_PLUGIN` macro in `dakota_config.h` used by [main.C](#) (which activates the plug-in code block within that file) and activates the `PLUGIN_S` declaration defined in `Makefile.include` and used in `Makefile.source` (which add this class to the build). Test input files should then use an `analysis_driver` of "plugin\_rosenbrock".

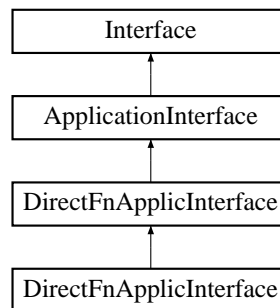
The documentation for this class was generated from the following files:

- [PluginDirectFnApplicInterface.H](#)
- [PluginDirectFnApplicInterface.C](#)

## 8.32 DirectFnApplicInterface Class Reference

and testers using direct procedure calls.

Inheritance diagram for DirectFnApplicInterface::



### Public Member Functions

- [DirectFnApplicInterface](#) (const [ProblemDescDB](#) &problem\_db)  
*constructor*
- [~DirectFnApplicInterface](#) ()  
*destructor*
- void [derived\\_map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, int fn\_eval\_id)  
*that is specific to a derived class.*
- void [derived\\_map\\_async](#) (const [ParamResponsePair](#) &pair)  
*asynchronous evaluation that is specific to a derived class.*
- void [derived\\_synch](#) ([PRPList](#) &prp\_list)  
*classes. This version waits for at least one completion.*
- void [derived\\_synch\\_nowait](#) ([PRPList](#) &prp\_list)  
*any completions if none are immediately available.*
- int [derived\\_synchronous\\_local\\_analysis](#) (const int &analysis\_id)
- const [StringArray](#) & [analysis\\_drivers](#) () const  
*retrieve the analysis drivers specification for application interfaces*

## Protected Member Functions

- virtual int `derived_map_if` (const `String` &if\_name)  
*execute the input filter portion of a direct evaluation invocation*
- virtual int `derived_map_ac` (const `String` &ac\_name)  
*execute an analysis code portion of a direct evaluation invocation*
- virtual int `derived_map_of` (const `String` &of\_name)  
*execute the output filter portion of a direct evaluation invocation*
- void `set_local_data` (const `Variables` &vars, const `ActiveSet` &set, const `Response` &response)  
*variable attributes and zeros response data*
- void `overlay_response` (`Response` &response)  
*response contributions from multiple analyses using `MPI_Reduce`*

## Protected Attributes

- `String` `iFilterName`  
*name of the direct function input filter*
- `String` `oFilterName`  
*name of the direct function output filter*
- bool `gradFlag`  
*signals use of `fnGrads` in direct simulator functions*
- bool `hessFlag`  
*signals use of `fnHessians` in direct simulator functions*
- size\_t `numFns`  
*number of functions in `fnVals`*
- size\_t `numVars`  
*total number of continuous and discrete variables*
- size\_t `numACV`  
*total number of continuous variables*
- size\_t `numADV`  
*total number of discrete variables*
- size\_t `numDerivVars`  
*number of active derivative variables*

- [RealVector xC](#)  
*continuous variables used within direct simulator fns*
- [IntVector xD](#)  
*discrete variables used within direct simulator fns*
- [StringArray xCLabels](#)  
*continuous variable labels*
- [StringArray xDLabels](#)  
*discrete variable labels*
- [ShortArray directFnASV](#)  
*class scope active set vector*
- [IntArray directFnDVV](#)  
*class scope derivative variables vector*
- [RealVector fnVals](#)  
*response fn values within direct simulator fns*
- [RealMatrix fnGrads](#)  
*response fn gradients w/i direct simulator fns*
- [RealMatrixArray fnHessians](#)  
*response fn Hessians w/i direct simulator fns*
- [StringArray fnLabels](#)  
*response function labels*
- [StringArray analysisDrivers](#)  
*analysis\_drivers interface specification)*
- `size_t` [analysisDriverIndex](#)  
*the index of the active analysis driver within analysisDrivers*
- [String2DArray analysisComponents](#)  
*(from the analysis\_components interface specification)*
- `engine *` [matlabEngine](#)  
*pointer to the MATLAB engine used for direct evaluations*

## Private Member Functions

- int [cantilever](#) ()  
*the cantilever UQ/OUU test function*
- int [cyl\\_head](#) ()  
*the cylinder head constrained optimization test fn*
- int [rosenbrock](#) ()  
*the Rosenbrock optimization and least squares test fn*
- int [generalized\\_rosenbrock](#) ()  
*n-dimensional Rosenbrock (Schittkowski)*
- int [extended\\_rosenbrock](#) ()  
*n-dimensional Rosenbrock (Nocedal/Wright)*
- int [log\\_ratio](#) ()  
*the log\_ratio UQ test function*
- int [short\\_column](#) ()  
*the short\_column UQ/OUU test function*
- int [steel\\_column\\_cost](#) ()  
*the steel\_column\_cost UQ/OUU test function*
- int [steel\\_column\\_perf](#) ()  
*the short\_column\_perf UQ/OUU test function*
- int [text\\_book](#) ()  
*the text\_book constrained optimization test function*
- int [text\\_book1](#) ()  
*portion of [text\\_book\(\)](#) evaluating the objective fn*
- int [text\\_book2](#) ()  
*portion of [text\\_book\(\)](#) evaluating constraint 1*
- int [text\\_book3](#) ()  
*portion of [text\\_book\(\)](#) evaluating constraint 2*
- int [text\\_book\\_ouu](#) ()  
*the text\_book\_ouu OUU test function*
- int [multimodal](#) ()  
*multimodal UQ test function*

- int [salinas](#) ()  
*direct interface to the SALINAS structural dynamics code*
- int [mc\\_api\\_run](#) ()  
*direct interface to ModelCenter via API, HKIM 4/3/03*
- int [matlab\\_engine\\_run](#) ()  
*direct interface to Matlab via API, BMA 11/28/05*
- int [python\\_run](#) ()  
*direct interface to Python via API, BMA 07/02/07*
- template<class ArrayT> bool [python\\_convert\\_int](#) (const ArrayT &src, PyObject \*\*dst)  
*convert arrays of integer types to Python*
- bool [python\\_convert](#) (const [RealVector](#) &src, PyObject \*\*dst)  
*convert RealVector to Python list or numpy array*
- bool [python\\_convert](#) (const [RealVector](#) &c\_src, const [IntVector](#) &d\_src, PyObject \*\*dst)  
*convert RealVector + IntVector to Python mixed list or numpy double array*
- bool [python\\_convert](#) (const [StringArray](#) &src, PyObject \*\*dst)  
*convert labels*
- bool [python\\_convert](#) (const [StringArray](#) &c\_src, const [StringArray](#) &d\_src, PyObject \*\*dst)  
*convert all labels to single list*
- bool [python\\_convert](#) (PyObject \*pyv, [RealBaseVector](#) &rv, const int &dim)  
*convert python list of int or float to RealVector*
- bool [python\\_convert](#) (PyObject \*pym, [RealMatrix](#) &rm)  
*convert python list of lists of int or float to RealMatrix*
- bool [python\\_convert](#) (PyObject \*pyma, [RealMatrixArray](#) &rma)  
*convert python list of lists of lists of int or float to RealMatrixArray*

### Private Attributes

- bool [userNumpyFlag](#)  
*whether the user requested numpy data structures*

### 8.32.1 Detailed Description

and testers using direct procedure calls.

[DirectFnApplicInterface](#) uses a few linkable simulation codes and several internal member functions to perform parameter to response mappings.

### 8.32.2 Member Function Documentation

#### 8.32.2.1 `int derived_synchronous_local_analysis (const int & analysis_id) [inline, virtual]`

This code provides the derived function used by [ApplicationInterface::serve\\_analyses\\_synch\(\)](#).

Reimplemented from [ApplicationInterface](#).

#### 8.32.2.2 `int derived_map_ac (const String & ac_name) [protected, virtual]`

execute an analysis code portion of a direct evaluation invocation

When a direct analysis/filter is a member function, the (vars,set,response) data does not need to be passed through the API. If, however, non-member analysis/filter functions are added, then pass (vars,set,response) through to the non-member fns:

```
// API declaration
int sim(const Variables& vars, const ActiveSet& set, Response& response);
// use of API within derived_map_ac()
if (ac_name == "sim")
    fail_code = sim(directFnVars, directFnActSet, directFnResponse);
```

Reimplemented in [DirectFnApplicInterface](#).

The documentation for this class was generated from the following files:

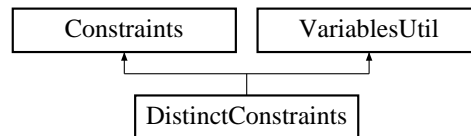
- [DirectFnApplicInterface.H](#)
- [DirectFnApplicInterface.C](#)



## 8.33 DistinctConstraints Class Reference

the default data view (no variable or domain type array merging).

Inheritance diagram for DistinctConstraints::



### Public Member Functions

- [DistinctConstraints](#) ()  
*default constructor*
- [DistinctConstraints](#) (const [ProblemDescDB](#) &problem\_db, const pair< short, short > &view)  
*standard constructor*
- [~DistinctConstraints](#) ()  
*destructor*
- const [RealVector](#) & [continuous\\_lower\\_bounds](#) () const  
*return the active continuous variable lower bounds*
- void [continuous\\_lower\\_bounds](#) (const [RealVector](#) &c\_l\_bnds)  
*set the active continuous variable lower bounds*
- const [RealVector](#) & [continuous\\_upper\\_bounds](#) () const  
*return the active continuous variable upper bounds*
- void [continuous\\_upper\\_bounds](#) (const [RealVector](#) &c\_u\_bnds)  
*set the active continuous variable upper bounds*
- const [IntVector](#) & [discrete\\_lower\\_bounds](#) () const  
*return the active discrete variable lower bounds*
- void [discrete\\_lower\\_bounds](#) (const [IntVector](#) &d\_l\_bnds)  
*set the active discrete variable lower bounds*
- const [IntVector](#) & [discrete\\_upper\\_bounds](#) () const  
*return the active discrete variable upper bounds*

- void `discrete_upper_bounds` (const `IntVector` &d\_u\_bnds)  
*set the active discrete variable upper bounds*
- const `RealVector` & `inactive_continuous_lower_bounds` () const  
*return the inactive continuous lower bounds*
- void `inactive_continuous_lower_bounds` (const `RealVector` &i\_c\_l\_bnds)  
*set the inactive continuous lower bounds*
- const `RealVector` & `inactive_continuous_upper_bounds` () const  
*return the inactive continuous upper bounds*
- void `inactive_continuous_upper_bounds` (const `RealVector` &i\_c\_u\_bnds)  
*set the inactive continuous upper bounds*
- const `IntVector` & `inactive_discrete_lower_bounds` () const  
*return the inactive discrete lower bounds*
- void `inactive_discrete_lower_bounds` (const `IntVector` &i\_d\_l\_bnds)  
*set the inactive discrete lower bounds*
- const `IntVector` & `inactive_discrete_upper_bounds` () const  
*return the inactive discrete upper bounds*
- void `inactive_discrete_upper_bounds` (const `IntVector` &i\_d\_u\_bnds)  
*set the inactive discrete upper bounds*
- `RealVector` `all_continuous_lower_bounds` () const  
*returns a single array with all continuous lower bounds*
- void `all_continuous_lower_bounds` (const `RealVector` &a\_c\_l\_bnds)  
*sets all continuous lower bounds using a single array*
- `RealVector` `all_continuous_upper_bounds` () const  
*returns a single array with all continuous upper bounds*
- void `all_continuous_upper_bounds` (const `RealVector` &a\_c\_u\_bnds)  
*sets all continuous upper bounds using a single array*
- `IntVector` `all_discrete_lower_bounds` () const  
*returns a single array with all discrete lower bounds*
- void `all_discrete_lower_bounds` (const `IntVector` &a\_d\_l\_bnds)  
*sets all discrete lower bounds using a single array*

- [IntVector all\\_discrete\\_upper\\_bounds](#) () const  
*returns a single array with all discrete upper bounds*
- void [all\\_discrete\\_upper\\_bounds](#) (const [IntVector](#) &a\_d\_u\_bnds)  
*sets all discrete upper bounds using a single array*
- void [write](#) (ostream &s) const  
*write a variable constraints object to an ostream*
- void [read](#) (istream &s)  
*read a variable constraints object from an istream*

### Protected Member Functions

- void [copy\\_rep](#) (const [Constraints](#) \*con\_rep)  
*Used by [copy\(\)](#) to copy the contents of a letter class.*
- void [reshape\\_rep](#) (const [Sizet2DArray](#) &vars\_comps)  
*Used by [reshape\(Sizet2DArray&\)](#) to reshape the contents of a letter class.*

### Private Attributes

- [RealVector continuousDesignLowerBnds](#)  
*the continuous design lower bounds array*
- [RealVector continuousDesignUpperBnds](#)  
*the continuous design upper bounds array*
- [IntVector discreteDesignLowerBnds](#)  
*the discrete design lower bounds array*
- [IntVector discreteDesignUpperBnds](#)  
*the discrete design upper bounds array*
- [RealVector uncertainLowerBnds](#)  
*the uncertain distribution lower bounds array*
- [RealVector uncertainUpperBnds](#)  
*the uncertain distribution upper bounds array*
- [RealVector continuousStateLowerBnds](#)  
*the continuous state lower bounds array*

- [RealVector continuousStateUpperBnds](#)  
*the continuous state upper bounds array*
- [IntVector discreteStateLowerBnds](#)  
*the discrete state lower bounds array*
- [IntVector discreteStateUpperBnds](#)  
*the discrete state upper bounds array*

### 8.33.1 Detailed Description

the default data view (no variable or domain type array merging).

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [DistinctConstraints](#) derived class separates the design, uncertain, and state variable types as well as the continuous and discrete domain types. The result is separate lower and upper bounds arrays for continuous design, discrete design, uncertain, continuous state, and discrete state variables. This is the default approach, so all iterators and strategies not specifically utilizing the All or Merged views use this approach (see [Variables::get\\_variables\(problem\\_db\)](#) for variables type selection; variables type is passed to the [Constraints](#) constructor in [Model](#)).

### 8.33.2 Constructor & Destructor Documentation

#### 8.33.2.1 [DistinctConstraints](#) (const [ProblemDescDB](#) & *problem\_db*, const pair< short, short > & *view*)

standard constructor

In this class, the distinct approach (design, uncertain, and state types are distinct) is used. Most iterators/strategies use this approach, which is the default in [Constraints::get\\_constraints\(\)](#). Extract distinct lower and upper bounds ([VariablesUtil](#) is not used).

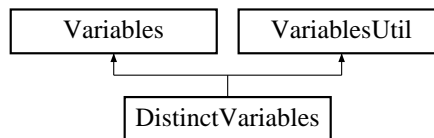
The documentation for this class was generated from the following files:

- [DistinctConstraints.H](#)
- [DistinctConstraints.C](#)

## 8.34 DistinctVariables Class Reference

the default data view (no variable or domain type array merging).

Inheritance diagram for DistinctVariables::



### Public Member Functions

- [DistinctVariables](#) ()  
*default constructor*
- [DistinctVariables](#) (const [ProblemDescDB](#) &problem\_db, const pair< short, short > &view)  
*standard constructor*
- [~DistinctVariables](#) ()  
*destructor*
- size\_t tv () const  
*Returns total number of vars.*
- const [RealVector](#) & [continuous\\_variables](#) () const  
*return the active continuous variables*
- void [continuous\\_variables](#) (const [RealVector](#) &c\_vars)  
*set the active continuous variables*
- const [IntVector](#) & [discrete\\_variables](#) () const  
*return the active discrete variables*
- void [discrete\\_variables](#) (const [IntVector](#) &d\_vars)  
*set the active discrete variables*
- const [StringArray](#) & [continuous\\_variable\\_labels](#) () const  
*return the active continuous variable labels*
- void [continuous\\_variable\\_labels](#) (const [StringArray](#) &c\_v\_labels)  
*set the active continuous variable labels*

- `const StringArray & discrete_variable_labels () const`  
*return the active discrete variable labels*
- `void discrete_variable_labels (const StringArray &d_v_labels)`  
*set the active discrete variable labels*
- `const RealVector & inactive_continuous_variables () const`  
*return the inactive continuous variables*
- `void inactive_continuous_variables (const RealVector &i_c_vars)`  
*set the inactive continuous variables*
- `const IntVector & inactive_discrete_variables () const`  
*return the inactive discrete variables*
- `void inactive_discrete_variables (const IntVector &i_d_vars)`  
*set the inactive discrete variables*
- `const StringArray & inactive_continuous_variable_labels () const`  
*return the inactive continuous variable labels*
- `void inactive_continuous_variable_labels (const StringArray &i_c_v_labels)`  
*set the inactive continuous variable labels*
- `const StringArray & inactive_discrete_variable_labels () const`  
*return the inactive discrete variable labels*
- `void inactive_discrete_variable_labels (const StringArray &i_d_v_labels)`  
*set the inactive discrete variable labels*
- `size_t acv () const`  
*returns total number of continuous vars*
- `size_t adv () const`  
*returns total number of discrete vars*
- `RealVector all_continuous_variables () const`  
*returns a single array with all continuous variables*
- `void all_continuous_variables (const RealVector &a_c_vars)`  
*sets all continuous variables using a single array*
- `IntVector all_discrete_variables () const`  
*returns a single array with all discrete variables*

- void `all_discrete_variables` (const `IntVector` &a\_d\_vars)  
*sets all discrete variables using a single array*
- `StringArray all_continuous_variable_labels` () const  
*returns a single array with all continuous variable labels*
- void `all_continuous_variable_labels` (const `StringArray` &a\_c\_v\_labels)  
*sets all continuous variable labels using a single array*
- `StringArray all_discrete_variable_labels` () const  
*returns a single array with all discrete variable labels*
- void `all_discrete_variable_labels` (const `StringArray` &a\_d\_v\_labels)  
*sets all discrete variable labels using a single array*
- `StringArray all_variable_labels` () const  
*returns a single array with all variable labels*
- void `read` (istream &s)  
*read a variables object from an istream*
- void `write` (ostream &s) const  
*write a variables object to an ostream*
- void `write_aprepro` (ostream &s) const  
*write a variables object to an ostream in aprepro format*
- void `read_annotated` (istream &s)  
*read a variables object in annotated format from an istream*
- void `write_annotated` (ostream &s) const  
*write a variables object in annotated format to an ostream*
- void `write_tabular` (ostream &s) const  
*write a variables object in tabular format to an ostream*
- void `read` (`BiStream` &s)  
*read a variables object from the binary restart stream*
- void `write` (`BoStream` &s) const  
*write a variables object to the binary restart stream*
- void `read` (`MPIUnpackBuffer` &s)  
*read a variables object from a packed MPI buffer*
- void `write` (`MPIPackBuffer` &s) const  
*write a variables object to a packed MPI buffer*

## Protected Member Functions

- void `copy_rep` (const `Variables` \*vars\_rep)  
*Used by `copy()` to copy the contents of a letter class.*
- void `reshape_rep` (const `Size2DArray` &vars\_comps)  
*Used by `reshape()` to reshape the contents of a letter class.*

## Private Member Functions

- void `build_types_ids` ()  
*construct `VarTypes` and `VarIds` arrays using `variablesComponents`*

## Private Attributes

- `RealVector` `continuousDesignVars`  
*the continuous design variables array*
- `IntVector` `discreteDesignVars`  
*the discrete design variables array*
- `RealVector` `uncertainVars`  
*the uncertain variables array*
- `RealVector` `continuousStateVars`  
*the continuous state variables array*
- `IntVector` `discreteStateVars`  
*the discrete state variables array*
- `StringArray` `continuousDesignLabels`  
*the continuous design variables label array*
- `StringArray` `discreteDesignLabels`  
*the discrete design variables label array*
- `StringArray` `uncertainLabels`  
*the uncertain variables label array*
- `StringArray` `continuousStateLabels`  
*the continuous state variables label array*
- `StringArray` `discreteStateLabels`  
*the discrete state variables label array*



## Friends

- `bool operator==(const DistinctVariables &vars1, const DistinctVariables &vars2)`  
*equality operator*

### 8.34.1 Detailed Description

the default data view (no variable or domain type array merging).

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The `DistinctVariables` derived class separates the design, uncertain, and state variable types as well as the continuous and discrete domain types. The result is separate arrays for continuous design, discrete design, uncertain, continuous state, and discrete state variables. This is the default approach, so all iterators and strategies not specifically utilizing the All or Merged views use this approach (see `Variables::get_variables(problem_db)`).

### 8.34.2 Constructor & Destructor Documentation

#### 8.34.2.1 `DistinctVariables` (const `ProblemDescDB` & `problem_db`, const pair< short, short > & `view`)

standard constructor

In this class, the distinct approach is used (design, uncertain, and state variable types and continuous and discrete domain types are distinct). Most iterators/strategies use this approach. Extract distinct variable types and labels (`VariablesUtil` is not used).

### 8.34.3 Friends And Related Function Documentation

#### 8.34.3.1 `bool operator==(const DistinctVariables & vars1, const DistinctVariables & vars2)` [friend]

equality operator

Checks each array using `operator==` from `data_types.C`. Labels are ignored.

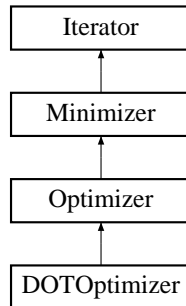
The documentation for this class was generated from the following files:

- `DistinctVariables.H`
- `DistinctVariables.C`

## 8.35 DOTOptimizer Class Reference

Wrapper class for the DOT optimization library.

Inheritance diagram for DOTOptimizer::



### Public Member Functions

- [DOTOptimizer](#) ([Model](#) &model)  
*constructor*
- [~DOTOptimizer](#) ()  
*destructor*
- void [find\\_optimum](#) ()  
*Redefines the run virtual function for the optimizer branch.*

### Protected Member Functions

- virtual void [derived\\_pre\\_run](#) ()  
*performs run-time set up*

### Private Member Functions

- void [allocate\\_workspace](#) ()  
*Allocates workspace for the optimizer.*
- void [allocate\\_constraints](#) ()  
*Allocates constraint mappings.*

## Private Attributes

- int [dotInfo](#)  
*INFO from DOT manual.*
- int [dotFDSinfo](#)  
*internal DOT parameter NGOTOZ*
- int [dotMethod](#)  
*METHOD from DOT manual.*
- int [printControl](#)  
*IPRINT from DOT manual (controls output verbosity).*
- int [optimizationType](#)  
*MINMAX from DOT manual (minimize or maximize).*
- [RealArray](#) [realCntlParmArray](#)  
*RPRM from DOT manual.*
- [IntArray](#) [intCntlParmArray](#)  
*IPRM from DOT manual.*
- [RealVector](#) [designVars](#)  
*array of design variable values passed to DOT*
- [Real](#) [objFnValue](#)  
*value of the objective function passed to DOT*
- [RealVector](#) [constraintValues](#)  
*array of nonlinear constraint values passed to DOT*
- int [realWorkSpaceSize](#)  
*size of realWorkSpace*
- int [intWorkSpaceSize](#)  
*size of intWorkSpace*
- [RealArray](#) [realWorkSpace](#)  
*real work space for DOT*
- [IntArray](#) [intWorkSpace](#)  
*int work space for DOT*
- int [numDotNlnConstr](#)  
*total number of nonlinear constraints seen by DOT*

- `int numDotLinConstr`  
*total number of linear constraints seen by DOT*
- `int numDotConstr`  
*total number of linear and nonlinear constraints seen by DOT*
- `SizeList constraintMappingIndices`  
*Response constraints used in computing the DOT constraints.*
- `RealList constraintMappingMultipliers`  
*the DOT constraints.*
- `RealList constraintMappingOffsets`  
*DOT constraints.*

### 8.35.1 Detailed Description

Wrapper class for the DOT optimization library.

The `DOTOptimizer` class provides a wrapper for DOT, a commercial Fortran 77 optimization library from Vanderplaats Research and Development. It uses a reverse communication mode, which avoids the static member function issues that arise with function pointer designs (see `NPSOLOptimizer` and `SNLLOptimizer`).

The user input mappings are as follows: `max_iterations` is mapped into DOT's `ITMAX` parameter within its `IPRM` array, `max_function_evaluations` is implemented directly in the `find_optimum()` loop since there is no DOT parameter equivalent, `convergence_tolerance` is mapped into DOT's `DELOBJ` parameter (the relative convergence tolerance) within its `RPRM` array, `output_verbosity` is mapped into DOT's `IPRINT` parameter within its function call parameter list (verbose: `IPRINT = 7`; quiet: `IPRINT = 3`), and `optimization_type` is mapped into DOT's `MINMAX` parameter within its function call parameter list. Refer to [Vanderplaats Research and Development, 1995] for information on `IPRM`, `RPRM`, and the DOT function call parameter list.

### 8.35.2 Member Data Documentation

#### 8.35.2.1 `int dotInfo` [private]

INFO from DOT manual.

Information requested by DOT: 0=optimization complete, 1=get values, 2=get gradients

#### 8.35.2.2 `int dotFDSinfo` [private]

internal DOT parameter `NGOTOZ`

the DOT parameter list has been modified to pass NGOTOZ, which signals whether DOT is finite-differencing (nonzero value) or performing the line search (zero value).

#### 8.35.2.3 **int dotMethod** [private]

METHOD from DOT manual.

For nonlinear constraints: 0/1 = dot\_mmfd, 2 = dot\_slp, 3 = dot\_sqp. For unconstrained: 0/1 = dot\_bfgs, 2 = dot\_frcg.

#### 8.35.2.4 **int printControl** [private]

IPRINT from DOT manual (controls output verbosity).

Values range from 0 (least output) to 7 (most output).

#### 8.35.2.5 **int optimizationType** [private]

MINMAX from DOT manual (minimize or maximize).

Values of 0 or -1 (minimize) or 1 (maximize).

#### 8.35.2.6 **RealArray realCntlParmArray** [private]

RPRM from DOT manual.

[Array](#) of real control parameters.

#### 8.35.2.7 **IntArray intCntlParmArray** [private]

IPRM from DOT manual.

[Array](#) of integer control parameters.

#### 8.35.2.8 **RealVector constraintValues** [private]

array of nonlinear constraint values passed to DOT

This array must be of nonzero length and must contain only one-sided inequality constraints which are  $\leq 0$  (which requires a transformation from 2-sided inequalities and equalities).

#### 8.35.2.9 **SizeList constraintMappingIndices** [private]

[Response](#) constraints used in computing the DOT constraints.

The length of the list corresponds to the number of DOT constraints, and each entry in the list points to the corresponding DAKOTA constraint.

**8.35.2.10 RealList constraintMappingMultipliers** [private]

the DOT constraints.

The length of the list corresponds to the number of DOT constraints, and each entry in the list contains a multiplier for the DAKOTA constraint identified with constraintMappingIndices. These multipliers are currently +1 or -1.

**8.35.2.11 RealList constraintMappingOffsets** [private]

DOT constraints.

The length of the list corresponds to the number of DOT constraints, and each entry in the list contains an offset for the DAKOTA constraint identified with constraintMappingIndices. These offsets involve inequality bounds or equality targets, since DOT assumes constraint allowables = 0.

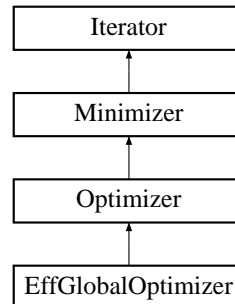
The documentation for this class was generated from the following files:

- DOTOptimizer.H
- DOTOptimizer.C

## 8.36 EffGlobalOptimizer Class Reference

Implementation of Efficient Global Optimization algorithm.

Inheritance diagram for EffGlobalOptimizer::



### Public Member Functions

- [EffGlobalOptimizer](#) ([Model](#) &model)  
*standard constructor*
- [~EffGlobalOptimizer](#) ()  
*alternate constructor for instantiations "on the fly" destructor*
- void [find\\_optimum](#) ()  
*Redefines the run virtual function for the optimizer branch.*

### Private Member Functions

- void [find\\_optimum\\_on\\_model](#) ()  
*called by find\_optimum for setUpType == "model"*
- void [get\\_best\\_sample](#) ()  
*imporovement function*
- [Real](#) [expected\\_improvement](#) (const [RealVector](#) &expected\_values, const [RealVector](#) &c\_variables)  
*expected improvement function for the GP*
- [RealVector](#) [expected\\_violation](#) (const [RealVector](#) &variances, const [RealVector](#) &c\_variables)  
*expected violation function for the constraint functions*

- void `update_penalty ()`  
*initialize and update the penaltyParameter*
- void `update_augmented_lagrange_multipliers (const RealVector &fn_vals)`  
*initialize and update the Lagrange multipliers for augmented Lagrangian*
- Real `augmented_lagrangian_merit (const RealVector &fn_vals, const RealVector &nln_ineq_l_bnds, const RealVector &nln_ineq_u_bnds, const RealVector &nln_eq_tgts)`  
*compute an augmented Lagrangian function from a set of function values*
- Real `objective (const RealVector &fn_vals)`  
*compute a composite objective value from one or more objective functions*
- Real `constraint_violation (const RealVector &fn_vals, const Real &constraint_tol)`  
*compute the constraint violation from a set of function values*

### Static Private Member Functions

- static void `EIF_objective_eval (const Variables &sub_model_vars, const Variables &recast_vars, const Response &sub_model_response, Response &recast_response)`  
*Expected Improvement (EIF) problem formulation for PMA.*
- static void `merit_objective_eval (const Variables &sub_model_vars, const Variables &recast_vars, const Response &sub_model_response, Response &recast_response)`  
*defines an augmented Lagrangian merit function from the sub\_model\_response*

### Private Attributes

- String `setUpType`  
*(user-supplied functions mode for "on the fly" instantiations).*
- Real `Pi`  
 $pi = 3.1415926535897932385$
- Model `meritModel`  
*recast model to create an augmented Lagrangian merit function*
- Model `fHatModel`  
*if constraints present*
- Model `EIFModel`  
*recast model used in solving the max(EIF) sub-problem*



- [Iterator eifOptimizer](#)  
*iterator used to solve the max(EIF) sub-problem*
- [Real meritFnStar](#)  
*minimum penalized response from among true function evaluations*
- [RealVector truthFnStar](#)  
*true function values corresponding to the minimum penalized response*
- [RealVector varStar](#)  
*point that corresponds to the optimal value meritFnStar*
- [RealVector augLagrangeMult](#)  
*Lagrange multipliers for augmented Lagrangian calculations.*
- [Real penaltyParameter](#)  
*penalty calculations; increased in [update\\_penalty\(\)](#)*
- [Real eta](#)  
*constant used in [etaSequence](#) updates*
- [Real alphaEta](#)  
*power for [etaSequence](#) updates when updating penalty*
- [Real betaEta](#)  
*power for [etaSequence](#) updates when updating multipliers*
- [Real etaSequence](#)  
*Lagrangian updates (refer to Conn, Gould, and Toint, section 14.4).*
- [size\\_t numFns](#)  
*number of response functions*
- [size\\_t numVars](#)  
*number of active continuous variables*
- [size\\_t numObjFns](#)  
*number of objective functions*
- [size\\_t numNonlinIneqConstr](#)  
*number of nonlinear inequality constraints*
- [size\\_t numNonlinEqConstr](#)  
*number of nonlinear equality constraints*
- [RealVector nonlinIneqLowerBnds](#)

*nonlinear inequality constraint lower bounds*

- [RealVector nonlinIneqUpperBnds](#)  
*nonlinear inequality constraint upper bounds*
- [RealVector nonlinEqTargets](#)  
*nonlinear equality constraint targets*
- Real [bigRealBoundSize](#)  
*cutoff value for continuous bounds*
- `size_t` [approxIters](#)  
*iteration counter*

### Static Private Attributes

- static [EffGlobalOptimizer](#) \* [effGlobalInstance](#)  
*functions in order to avoid the need for static data*

## 8.36.1 Detailed Description

Implementation of Efficient Global Optimization algorithm.

The [EffGlobalOptimizer](#) class provides an implementation of the Efficient Global Optimization algorithm developed by Jones, Schonlau, & Welch.

The user input mappings are as follows:

## 8.36.2 Constructor & Destructor Documentation

### 8.36.2.1 [~EffGlobalOptimizer](#) ()

alternate constructor for instantiations "on the fly" destructor

This is an alternate constructor for instantiations on the fly using a [Model](#) but no [ProblemDescDB](#).

## 8.36.3 Member Function Documentation

**8.36.3.1 Real objective (const RealVector & fn\_vals) [private]**

compute a composite objective value from one or more objective functions

The composite objective computation sums up the contributions from one of more objective functions using the multiobjective weights.

**8.36.3.2 Real constraint\_violation (const RealVector & fn\_vals, const Real & constraint\_tol) [private]**

compute the constraint violation from a set of function values

Compute the quadratic constraint violation defined as  $cv = g^T g + h^T h$ . This implementation supports equality constraints and 2-sided inequalities. The `constraint_tol` allows for a small constraint infeasibility (used for penalty methods, but not Lagrangian methods).

The documentation for this class was generated from the following files:

- EffGlobalOptimizer.H
- EffGlobalOptimizer.C

## 8.37 ErrorTable Struct Reference

Data structure to hold errors.

### Public Attributes

- [CtelRegexp::RStatus rc](#)  
*Enumerated type to hold status codes.*
- `const char * msg`  
*Holds character string error message.*

### 8.37.1 Detailed Description

Data structure to hold errors.

This module implements a C++ wrapper for Regular Expressions based on the public domain engine for regular expressions released by: Copyright (c) 1986 by University of Toronto. Written by Henry Spencer. Not derived from licensed software.

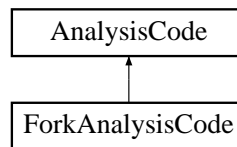
The documentation for this struct was generated from the following file:

- CtelRegExp.C

## 8.38 ForkAnalysisCode Class Reference

simulations using forks.

Inheritance diagram for ForkAnalysisCode::



### Public Member Functions

- [ForkAnalysisCode](#) (const [ProblemDescDB](#) &problem\_db)  
*constructor*
- [~ForkAnalysisCode](#) ()  
*destructor*
- pid\_t [fork\\_program](#) (const bool block\_flag)  
*for completion using waitpid() if block\_flag is true*
- void [check\\_status](#) (const int status)  
*error code was returned*
- void [ifilter\\_argument\\_list](#) ()  
*set argList for execution of the input filter*
- void [ofilter\\_argument\\_list](#) ()  
*set argList for execution of the output filter*
- void [driver\\_argument\\_list](#) (const int analysis\_id)  
*set argList for execution of the specified analysis driver*

### Private Attributes

- [StringArray](#) argList  
*These are converted to an array of const char\*'s in [fork\\_program\(\)](#).*

### 8.38.1 Detailed Description

simulations using forks.

[ForkAnalysisCode](#) creates a copy of the parent DAKOTA process using `fork()/vfork()` and then replaces the copy with a simulation process using `execvp()`. The parent process can then use `waitpid()` to wait on completion of the simulation process.

### 8.38.2 Member Function Documentation

#### 8.38.2.1 `void check_status (const int status)`

error code was returned

Check to see if the process terminated abnormally (`WIFEXITED(status)==0`) or if either `execvp` or the application returned a status code of -1 (`WIFEXITED(status)!=0 && (signed char)WEXITSTATUS(status)==-1`). If one of these conditions is detected, output a failure message and abort. Note: the application code should not return a status code of -1 unless an immediate abort of dakota is wanted. If for instance, failure capturing is to be used, the application code should write the word "FAIL" to the appropriate results file and return a status code of 0 through `exit()`.

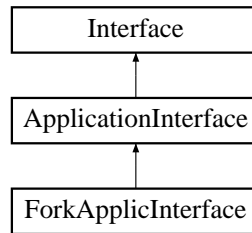
The documentation for this class was generated from the following files:

- `ForkAnalysisCode.H`
- `ForkAnalysisCode.C`

## 8.39 ForkApplicInterface Class Reference

using forks.

Inheritance diagram for ForkApplicInterface::



### Public Member Functions

- [ForkApplicInterface](#) (const [ProblemDescDB](#) &problem\_db)  
*constructor*
- [~ForkApplicInterface](#) ()  
*destructor*
- void [derived\\_map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, int fn\_eval\_id)  
*that is specific to a derived class.*
- void [derived\\_map\\_async](#) (const [ParamResponsePair](#) &pair)  
*asynchronous evaluation that is specific to a derived class.*
- void [derived\\_synch](#) ([PRPLList](#) &prp\_list)  
*classes. This version waits for at least one completion.*
- void [derived\\_synch\\_nowait](#) ([PRPLList](#) &prp\_list)  
*any completions if none are immediately available.*
- int [derived\\_synchronous\\_local\\_analysis](#) (const int &analysis\_id)
- const [StringArray](#) & [analysis\\_drivers](#) () const  
*retrieve the analysis drivers specification for application interfaces*

### Private Member Functions

- void [derived\\_synch\\_kernel](#) ([PRPLList](#) &prp\_list, const pid\_t pid)

*derived\_synch\_nowait()*

- pid\_t `fork_application` (const bool `block_flag`)  
*filter, analysis programs, and output filter*
- void `asynchronous_local_analyses` (const int &start, const int &end, const int &step)  
*execute analyses asynchronously on the local processor*
- void `synchronous_local_analyses` (const int &start, const int &end, const int &step)  
*execute analyses synchronously on the local processor*
- void `serve_analyses_asynch` ()  
*serve the analysis scheduler and execute analysis jobs asynchronously*

## Private Attributes

- ForkAnalysisCode `forkSimulator`  
*individual programs and checking fork exit status*
- std::map< pid\_t, int > `processIdMap`  
*asynchronous evaluations*

### 8.39.1 Detailed Description

using forks.

`ForkApplicInterface` uses a `ForkAnalysisCode` object for performing simulation invocations.

### 8.39.2 Member Function Documentation

#### 8.39.2.1 int `derived_synchronous_local_analysis` (const int & *analysis\_id*) [inline, virtual]

This code provides the derived function used by `ApplicationInterface::serve_analyses_synch()` as well as a convenience function for `ForkApplicInterface::synchronous_local_analyses()` below.

Reimplemented from `ApplicationInterface`.

#### 8.39.2.2 pid\_t `fork_application` (const bool *block\_flag*) [private]

filter, analysis programs, and output filter



Manage the input filter, 1 or more analysis programs, and the output filter in blocking or nonblocking mode as governed by `block_flag`. In the case of a single analysis and no filters, a single fork is performed, while in other cases, an initial fork is reforked multiple times. Called from `derived_map()` with `block_flag == BLOCK` and from `derived_map_asynch()` with `block_flag == FALL_THROUGH`. Uses `ForkAnalysisCode::fork_program()` to spawn individual program components within the function evaluation.

### 8.39.2.3 `void asynchronous_local_analyses (const int & start, const int & end, const int & step)` [private]

execute analyses asynchronously on the local processor

Schedule analyses asynchronously on the local processor using a self-scheduling approach (start to end in step increments). Concurrency is limited by `asynchLocalAnalysisConcurrency`. Modeled after `ApplicationInterface::asynchronous_local_evaluations()`. NOTE: This function should be elevated to `ApplicationInterface` if and when another derived interface class supports asynchronous local analyses.

### 8.39.2.4 `void synchronous_local_analyses (const int & start, const int & end, const int & step)` [inline, private]

execute analyses synchronously on the local processor

Execute analyses synchronously in succession on the local processor (start to end in step increments). Modeled after `ApplicationInterface::synchronous_local_evaluations()`.

### 8.39.2.5 `void serve_analyses_asynch ()` [private]

serve the analysis scheduler and execute analysis jobs asynchronously

This code runs multiple asynch analyses on each server. It is modeled after `ApplicationInterface::serve_evaluations_asynch()`. NOTE: This fn should be elevated to `ApplicationInterface` if and when another derived interface class supports hybrid analysis parallelism.

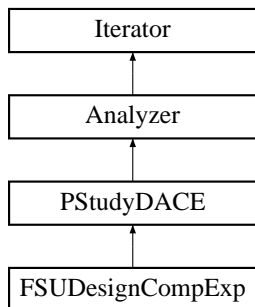
The documentation for this class was generated from the following files:

- ForkApplicInterface.H
- ForkApplicInterface.C

## 8.40 FSUDesignCompExp Class Reference

Wrapper class for the FSUDace QMC/CVT library.

Inheritance diagram for FSUDesignCompExp::



### Public Member Functions

- [FSUDesignCompExp \(Model &model\)](#)  
*primary constructor for building a standard DACE iterator*
- [FSUDesignCompExp \(Model &model, int samples, int seed, const String &sampling\\_method\)](#)  
*alternate constructor for building a DACE iterator on-the-fly*
- [~FSUDesignCompExp \(\)](#)  
*destructor*
- `void extract_trends ()`  
*Redefines the run\_iterator virtual function for the PStudy/DACE branch.*
- `void sampling_reset (int min_samples, bool all_data_flag, bool stats_flag)`  
*reset sampling iterator*
- `const String & sampling_scheme () const`  
*return sampling name*
- `void vary_pattern (bool pattern_flag)`  
*sets varyPattern in derived classes that support it*
- `void get_parameter_sets (const Model &model)`  
*Returns one block of samples (ndim \* num\_samples).*

## Private Member Functions

- void `enforce_input_rules()`  
*enforce sanity checks/modifications for the user input specification*

## Private Attributes

- int `samplesSpec`  
*initial specification of number of samples*
- int `numSamples`  
*current number of samples to be evaluated*
- bool `allDataFlag`  
*Iterator::all\_variables() and Iterator::all\_responses().*
- size\_t `numDACERuns`  
*counter for number of run() executions for this object*
- bool `latinizeFlag`  
*flag which specifies latinization of QMC or CVT sample sets*
- bool `volQualityFlag`  
*flag which specifies evaluating the volumetric quality measures*
- bool `varBasedDecompFlag`  
*sensitivity analysis metrics*
- `IntVector` `sequenceStart`  
*variable sampled. Default is 0 0 0 (e.g. for three random variables).*
- `IntVector` `sequenceLeap`  
*generated. Default is 1 1 1 (e.g. for three random vars.)*
- `IntVector` `primeBase`  
*generated. Default is 2 3 5 (e.g., for three random vars.)*
- int `originalSeed`  
*(allows repeatable results)*
- int `randomSeed`  
*current seed for the random number generator*
- bool `varyPattern`  
*multiple executions are repeatable but not identical.*

- int `numCVTTrials`  
*specifies the number of sample points taken at internal CVT iteration*
- int `trialType`  
*halton (1), uniform (0), or random (-1). Default is random.*

### 8.40.1 Detailed Description

Wrapper class for the FSUDace QMC/CVT library.

The `FSUDesignCompExp` class provides a wrapper for FSUDace, a C++ design of experiments library from Florida State University. This class uses quasi Monte Carlo (QMC) and Centroidal Voronoi Tessellation (CVT) methods to uniformly sample the parameter space spanned by the active bounds of the current `Model`. It returns all generated samples and their corresponding responses as well as the best sample found.

### 8.40.2 Constructor & Destructor Documentation

#### 8.40.2.1 `FSUDesignCompExp (Model & model)`

primary constructor for building a standard DACE iterator

This constructor is called for a standard iterator built with data from `probDescDB`.

#### 8.40.2.2 `FSUDesignCompExp (Model & model, int samples, int seed, const String & sampling_method)`

alternate constructor for building a DACE iterator on-the-fly

This alternate constructor is used for instantiations on-the-fly, using only the incoming data. No problem description database queries are used.

### 8.40.3 Member Function Documentation

#### 8.40.3.1 `void enforce_input_rules () [private]`

enforce sanity checks/modifications for the user input specification

Users may input a variety of quantities, but this function must enforce any restrictions imposed by the sampling algorithms.

The documentation for this class was generated from the following files:

- FSUDesignCompExp.H
- FSUDesignCompExp.C

## 8.41 FunctionCompare Class Template Reference

### Public Member Functions

- [FunctionCompare](#) (bool(\*func)(const T &, void \*), void \*v)  
*Constructor that defines the pointer to function and search value.*
- bool [operator\(\)](#) (T t) const  
*The operator() must be defined. Calls the function test\_fn.*

### Private Attributes

- bool(\* [test\\_fn](#))(const T &, void \*)  
*Pointer to test function.*
- void \* [search\\_val](#)  
*Holds the value to search for.*

#### 8.41.1 Detailed Description

```
template<class T> class Dakota::FunctionCompare< T >
```

Internal functor to mimic the RW find and index functions using the STL find\_if() method. The class holds a pointer to the test function and the search value.

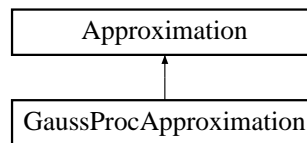
The documentation for this class was generated from the following file:

- DakotaList.H

## 8.42 GaussProcApproximation Class Reference

Derived approximation class for Gaussian Process implementation.

Inheritance diagram for GaussProcApproximation::



### Public Member Functions

- [GaussProcApproximation \(\)](#)  
*default constructor*
- [GaussProcApproximation \(ProblemDescDB &problem\\_db, const size\\_t &num\\_acv\)](#)  
*standard constructor*
- [~GaussProcApproximation \(\)](#)  
*destructor*

### Protected Member Functions

- [int num\\_coefficients \(\) const](#)  
*derived class approximation type in numVars dimensions*
- [int num\\_constraints \(\) const](#)  
*return the number of constraints to be enforced via anchorPoint*
- [void find\\_coefficients \(\)](#)  
*find the covariance parameters governing the Gaussian process response*
- [const Real & get\\_value \(const RealVector &x\)](#)  
*retrieve the function value for a given parameter set x*
- [const Real & get\\_variance \(const RealVector &x\)](#)  
*retrieve the variance of the predicted value for a given parameter set x*

## Private Member Functions

- void `GPmodel_build ()`  
*Function to compute hyperparameters governing the GP.*
- void `GPmodel_apply (const RealVector &new_x, bool variance_flag)`  
*Function returns a response value using the GP surface.*
- void `normalize_training_data ()`  
*Normalizes the initial inputs upon which the GP surface is based.*
- void `get_trend ()`  
*linear; if order = 2, trend is quadratic.*
- void `get_beta_coefficients ()`  
*Gets the beta coefficients for the calculation of the mean of the GP.*
- int `get_cholesky_factor ()`  
*error checking*
- void `get_process_variance ()`  
*the correlation lengthscales*
- void `get_cov_matrix ()`  
*calculates the covariance matrix for a given set of input points*
- void `get_cov_vector ()`  
*set of inputs upon which the GP is based*
- void `optimize_theta_global ()`  
*parameters using NCSUDirect*
- void `optimize_theta_multipoint ()`  
*parameters using a gradient-based solver and multiple starting points*
- void `predict (bool variance_flag)`  
*Calculates the predicted new response value for x in normalized space.*
- Real `calc_nll ()`  
*matrix)*
- void `calc_grad_nll ()`  
*to the correlation lengthscales, theta*
- void `run_point_selection ()`  
*estimate the necessary parameters*



- void `initialize_point_selection` ()  
*initial subset of the training points*
- void `pointsel_get_errors` (RealVector &)  
*training points and find the errors*
- int `addpoint` (int, IntVector &)  
*Adds a point to the effective training set. Returns 1 on success.*
- int `pointsel_add_sel` (RealVector &)  
*them*
- Real `maxval` (RealVector &)  
*Return the maximum value of the elements in a vector.*
- void `pointsel_write_points` ()  
*Writes out the training set before and after point selection.*
- void `lhood_2d_grid_eval` ()  
*likelihood on a grid*
- void `writex` (char[ ])  
*specified file*
- void `writeCovMat` (char[ ])  
*Writes out the covariance matrix to a specified file.*

### Static Private Member Functions

- static void `negloglik` (int mode, int n, const NEWMAT::ColumnVector &X, NEWMAT::Real &fx, NEWMAT::ColumnVector &grad\_x, int &result\_mode)  
*by minimizing the negative log likelihood*
- static void `constraint_eval` (int mode, int n, const NEWMAT::ColumnVector &X, NEWMAT::ColumnVector &g, NEWMAT::Matrix &gradC, int &result\_mode)  
*this function is empty: it is an unconstrained optimization.*
- static void `negloglikNCSU` (int &n, double \*x, double &f, int &flag, int \*idata, int &isize, double \*ddata, int &dsize, char \*cdata, int &csize)  
*static function used by DIRECT to optimize negloglik objective*

## Private Attributes

- Epetra\_SerialDenseMatrix [trainPoints](#)  
*used to create the Gaussian process*
- Epetra\_SerialDenseMatrix [trainValues](#)  
*An array of response values; one response value per sample site.*
- Epetra\_SerialDenseVector [trainMeans](#)  
*The mean of the input columns of trainPoints.*
- Epetra\_SerialDenseVector [trainStdvs](#)  
*The standard deviation of the input columns of trainPoints.*
- Epetra\_SerialDenseMatrix [normTrainPoints](#)  
*Current working set of normalized points upon which the GP is based.*
- Epetra\_SerialDenseMatrix [trendFunction](#)  
*matrix to hold the trend function*
- Epetra\_SerialDenseMatrix [betaCoeffs](#)  
*matrix to hold the beta coefficients for the trend function*
- Epetra\_SerialSymDenseMatrix [covMatrix](#)  
*between points  $X_i$  and  $X_j$  in the initial set of samples*
- Epetra\_SerialDenseMatrix [covVector](#)  
*between a new point  $X$  and point  $X_j$  from the initial set of samples*
- Epetra\_SerialDenseMatrix [approxPoint](#)  
*single point, but it could be generalized to be a vector of points.*
- Epetra\_SerialDenseMatrix [gradNegLogLikTheta](#)  
*with respect to the theta correlation terms*
- Epetra\_SerialSpdDenseSolver [covSlvr](#)  
*the covariance matrix*
- Epetra\_SerialDenseMatrix [normTrainPointsAll](#)  
*Set of all original samples available.*
- Epetra\_SerialDenseMatrix [trainValuesAll](#)  
*All original samples available.*
- Epetra\_SerialDenseMatrix [trendFunctionAll](#)  
*Trend function values corresponding to all original samples.*

- `size_t numObs`  
*The number of observations on which the GP surface is built.*
- `size_t numObsAll`  
*The original number of observations.*
- `short trendOrder`  
*linear, if order = 2, trend is quadratic.*
- `RealVector thetaParams`  
*same point. sig is the underlying process error.*
- `Real procVar`  
*The process variance, the multiplier of the correlation matrix.*
- `RealVector pointsAddedIndex`  
*all points which have been added*
- `int cholFlag`  
*A global indicator for success of the Cholesky factorization.*
- `bool usePointSelection`  
*a flag to indicate the use of point selection*

### Static Private Attributes

- `static GaussProcApproximation * GPInstance`  
*pointer to the active object instance used within the static evaluator*

#### 8.42.1 Detailed Description

Derived approximation class for Gaussian Process implementation.

The `GaussProcApproximation` class provides a global approximation (surrogate) based on a Gaussian process. The Gaussian process is built after normalizing the function values, with zero mean. Opt++ is used to determine the optimal values of the covariance parameters, those which minimize the negative log likelihood function.

#### 8.42.2 Member Function Documentation

**8.42.2.1 void GPmodel\_apply (const [RealVector](#) & *new\_x*, bool *variance\_flag*) [private]**

Function returns a response value using the GP surface.

The response value is computed at the design point specified by the [RealVector](#) function argument.

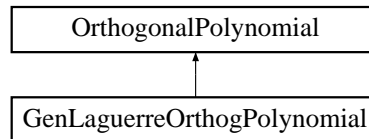
The documentation for this class was generated from the following files:

- [GaussProcApproximation.H](#)
- [GaussProcApproximation.C](#)

## 8.43 GenLaguerreOrthogPolynomial Class Reference

Derived orthogonal polynomial class for generalized Laguerre polynomials.

Inheritance diagram for GenLaguerreOrthogPolynomial::



### Public Member Functions

- [GenLaguerreOrthogPolynomial \(\)](#)  
*default constructor*
- [GenLaguerreOrthogPolynomial \(const Real &alpha\\_stat\)](#)  
*standard constructor*
- [~GenLaguerreOrthogPolynomial \(\)](#)  
*destructor*

### Protected Member Functions

- const Real & [get\\_value](#) (const Real &x, size\_t n)  
*parameter x*
- const Real & [get\\_gradient](#) (const Real &x, size\_t n)  
*given parameter x*
- const Real & [norm\\_squared](#) (size\_t n)  
*return the inner product  $\langle L^{\alpha}_n, L^{\alpha}_n \rangle = \|L^{\alpha}_n\|^2$*
- const [RealVector](#) & [gauss\\_points](#) (size\_t n)  
*corresponding to polynomial order n*
- const [RealVector](#) & [gauss\\_weights](#) (size\_t n)  
*corresponding to polynomial order n*
- void [alpha\\_stat](#) (const Real &alpha)  
*set alphaPoly using the conversion  $\alpha_{\text{Poly}} = \alpha_{\text{stat}} - 1$ .*

## Private Attributes

- Real [alphaPoly](#)  
*by Abramowitz and Stegun (differs from statistical PDF notation)*

### 8.43.1 Detailed Description

Derived orthogonal polynomial class for generalized Laguerre polynomials.

The [GenLaguerreOrthogPolynomial](#) class evaluates a univariate generalized/associated Laguerre polynomial  $L^{\alpha}_n$  of a particular order. These polynomials are orthogonal with respect to the weight function  $x^{\alpha} \exp(-x)$  when integrated over the support range of  $[0, +\infty]$ . This corresponds to the probability density function  $f(x) = x^{\alpha} \exp(-x) / \Gamma(\alpha+1)$  for the standard gamma distribution, although common statistical PDF parameter conventions (see, e.g., the uncertain variables section in the DAKOTA Reference Manual) and the Abramowitz and Stegun orthogonal polynomial parameter conventions require an offset conversion in this case ( $\alpha_{\text{poly}} = \alpha_{\text{stat}} - 1$  with the poly definition used in both cases above). It enables (mixed) multidimensional orthogonal polynomial basis functions within [OrthogPolyApproximation](#). A special case is the [LaguerreOrthogPolynomial](#) (implemented separately), for which  $\alpha_{\text{poly}} = 0$  and weight function =  $\exp(-x)$  (the standard exponential distribution).

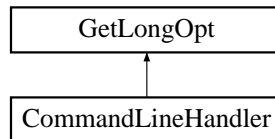
The documentation for this class was generated from the following files:

- GenLaguerreOrthogPolynomial.H
- GenLaguerreOrthogPolynomial.C

## 8.44 GetLongOpt Class Reference

(Advanced Computer Research Institute, Lyon, France).

Inheritance diagram for GetLongOpt::



### Public Types

- enum `OptType` { `Valueless`, `OptionalValue`, `MandatoryValue` }  
*enum for different types of values associated with command line options.*

### Public Member Functions

- `GetLongOpt` (const char optmark= '-')  
*Constructor.*
- `~GetLongOpt` ()  
*Destructor.*
- int `parse` (int argc, char \*const \*argv)  
*parse the command line args (argc, argv).*
- int `parse` (char \*const str, char \*const p)  
*parse a string of options (typically given from the environment).*
- int `enroll` (const char \*const opt, const `OptType` t, const char \*const desc, const char \*const val)  
*Add an option to the list of valid command options.*
- const char \* `retrieve` (const char \*const opt) const  
*Retrieve value of option.*
- void `usage` (ostream &outfile=cout) const  
*Print usage information to outfile.*
- void `usage` (const char \*str)  
*Change header of usage output to str.*

## Private Member Functions

- char \* [basename](#) (char \*const p) const  
*extract the base name from a string as delimited by '/'*
- int [setcell](#) (Cell \*c, char \*valtoken, char \*nexttoken, const char \*p)  
*internal convenience function for setting Cell::value*

## Private Attributes

- Cell \* [table](#)  
*option table*
- const char \* [ustring](#)  
*usage message*
- char \* [pname](#)  
*program basename*
- char [optmarker](#)  
*option marker*
- int [enroll\\_done](#)  
*finished enrolling*
- Cell \* [last](#)  
*last entry in option table*

### 8.44.1 Detailed Description

(Advanced Computer Research Institute, Lyon, France).

[GetLongOpt](#) manages the definition and parsing of "long options." Command line options can be abbreviated as long as there is no ambiguity. If an option requires a value, the value should be separated from the option either by whitespace or an "=".

### 8.44.2 Constructor & Destructor Documentation



### 8.44.2.1 `GetLongOpt` (`const char optmark = ' - '`)

Constructor.

Constructor for `GetLongOpt` takes an optional argument: the option marker. If unspecified, this defaults to ' - ', the standard (?) Unix option marker.

## 8.44.3 Member Function Documentation

### 8.44.3.1 `int parse (int argc, char *const * argv)`

parse the command line args (argc, argv).

A return value < 1 represents a parse error. Appropriate error messages are printed when errors are seen. parse returns the the optind (see `getopt(3)`) if parsing is successful.

### 8.44.3.2 `int parse (char *const str, char *const p)`

parse a string of options (typically given from the environment).

A return value < 1 represents a parse error. Appropriate error messages are printed when errors are seen. parse takes two strings: the first one is the string to be parsed and the second one is a string to be prefixed to the parse errors.

### 8.44.3.3 `int enroll (const char *const opt, const OptType t, const char *const desc, const char *const val)`

Add an option to the list of valid command options.

enroll adds option specifications to its internal database. The first argument is the option sting. The second is an enum saying if the option is a flag (Valueless), if it requires a mandatory value (MandatoryValue) or if it takes an optional value (OptionalValue). The third argument is a string giving a brief description of the option. This description will be used by `GetLongOpt::usage`. `GetLongOpt`, for usage-printing, uses `{ $val }` to represent values needed by the options. `{ <$val> }` is a mandatory value and `{ [ $val ] }` is an optional value. The final argument to enroll is the default string to be returned if the option is not specified. For flags (options with Valueless), use "" (empty string, or in fact any arbitrary string) for specifying TRUE and 0 (null pointer) to specify FALSE.

### 8.44.3.4 `const char * retrieve (const char *const opt) const`

Retrieve value of option.

The values of the options that are enrolled in the database can be retrieved using `retrieve`. This returns a string and this string should be converted to whatever type you want. See `atoi`, `atof`, `atol`, etc. If a "parse" is not done before retrieving all you will get are the default values you gave while enrolling! Ambiguities while retrieving (may happen when options are abbreviated) are resolved by taking the matching option that was enrolled last. For example, `-{v}` will expand to `{-verify}`. If you try to retrieve something you didn't enroll, you will get a warning message.

**8.44.3.5 void usage (const char \* *str*) [inline]**

Change header of usage output to *str*.

[GetLongOpt::usage](#) is overloaded. If passed a string "*str*", it sets the internal usage string to "*str*". Otherwise it simply prints the command usage.

The documentation for this class was generated from the following files:

- CommandLineHandler.H
- CommandLineHandler.C

## 8.45 Graphics Class Reference

for post-processing with Matlab, Tecplot, etc.

### Public Member Functions

- [Graphics](#) ()  
*constructor*
- [~Graphics](#) ()  
*destructor*
- void [create\\_plots\\_2d](#) (const [Variables](#) &vars, const [Response](#) &response)  
*creates the 2d graphics window and initializes the plots*
- void [create\\_tabular\\_datastream](#) (const [Variables](#) &vars, const [Response](#) &response, const [String](#) &tabular\_data\_file)  
*opens the tabular data file stream and prints the headings*
- void [add\\_datapoint](#) (const [Variables](#) &vars, const [Response](#) &response)  
*the tabular data file based on the results of a model evaluation*
- void [add\\_datapoint](#) (int i, double x, double y)  
*adds data to a single window in the 2d graphics*
- void [new\\_dataset](#) (int i)  
*for a single window in the 2d graphics*
- void [show\\_data\\_3d](#) (const [RealVector](#) &X, const [RealVector](#) &Y, const [RealMatrix](#) &F)  
*generate a new 3d plot for  $F(X,Y)$*
- void [close](#) ()  
*close graphics windows and tabular datastream*
- void [set\\_x\\_labels2d](#) (const char \*x\_label)  
*set x label for each plot equal to x\_label*
- void [set\\_y\\_labels2d](#) (const char \*y\_label)  
*set y label for each plot equal to y\_label*
- void [set\\_x\\_label2d](#) (int i, const char \*x\_label)  
*set x label for ith plot equal to x\_label*

- void `set_y_label2d` (int i, const char \*y\_label)  
*set y label for ith plot equal to y\_label*
- void `graphics_counter` (int cntr)  
*set graphicsCntr equal to cntr*
- int `graphics_counter` () const  
*return graphicsCntr*
- void `tabular_counter_label` (const `String` &label)  
*set tabularCntrLabel equal to label*

### Private Attributes

- `Graphics2D` \* `graphics2D`  
*pointer to the 2D graphics object*
- bool `win2dOn`  
*flag to indicate if 2D graphics window is active*
- bool `win3dOn`  
*flag to indicate if 3D graphics window is active*
- bool `tabularDataFlag`  
*flag to indicate if tabular data stream is active*
- int `graphicsCntr`  
*used for x axis values in 2D graphics and for 1st column in tabular data*
- `String` `tabularCntrLabel`  
*label for counter used in first line comment w/i the tabular data file*
- ofstream `tabularDataFStream`  
*file stream for tabulation of graphics data within compute\_response*

### 8.45.1 Detailed Description

for post-processing with Matlab, Tecplot, etc.

There is only one `Graphics` object (`dakotaGraphics`) and it is global (for convenient access from strategies, models, and approximations).

## 8.45.2 Member Function Documentation

### 8.45.2.1 void create\_plots\_2d (const Variables & vars, const Response & response)

creates the 2d graphics window and initializes the plots

Sets up a single event loop for duration of the dakotaGraphics object, continuously adding data to a single window. There is no reset. To start over with a new data set, you need a new object (delete old and instantiate new).

### 8.45.2.2 void create\_tabular\_datastream (const Variables & vars, const Response & response, const String & tabular\_data\_file)

opens the tabular data file stream and prints the headings

Opens the tabular data file stream and prints headings, one for each continuous and discrete variable and one for each response function, using the variable and response function labels. This tabular data is used for post-processing of DAKOTA results in Matlab, Tecplot, etc.

### 8.45.2.3 void add\_datapoint (const Variables & vars, const Response & response)

the tabular data file based on the results of a model evaluation

Adds data to each 2d plot and each tabular data column (one for each active variable and for each response function). graphicsCntr is used for the x axis in the graphics and the first column in the tabular data.

### 8.45.2.4 void add\_datapoint (int i, double x, double y)

adds data to a single window in the 2d graphics

Adds data to a single 2d plot. Allows complete flexibility in defining other kinds of x-y plotting in the 2D graphics.

### 8.45.2.5 void new\_dataset (int i)

for a single window in the 2d graphics

Used for displaying multiple data sets within the same plot.

### 8.45.2.6 void show\_data\_3d (const RealVector & X, const RealVector & Y, const RealMatrix & F)

generate a new 3d plot for F(X,Y)

3D plotting clears data set and builds from scratch each time show\_data3d is called. This still involves an event loop waiting for a mouse click (right button) to continue. X = 1-D x grid values only and Y = 1-D Y grid values only [X and Y are \_not\_ (X,Y) pairs]. F = 2-d grid of values for a single function for all (X,Y) combinations.

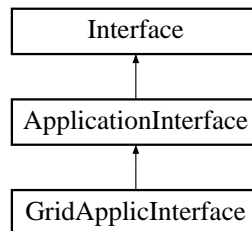
The documentation for this class was generated from the following files:

- DakotaGraphics.H
- DakotaGraphics.C

## 8.46 GridApplicInterface Class Reference

using grid services such as Condor or Globus.

Inheritance diagram for GridApplicInterface::



### Public Member Functions

- [GridApplicInterface](#) (const [ProblemDescDB](#) &problem\_db)  
*constructor*
- [~GridApplicInterface](#) ()  
*destructor*
- void [derived\\_map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, int fn\_eval\_id)  
*that is specific to a derived class.*
- void [derived\\_map\\_async](#) (const [ParamResponsePair](#) &pair)  
*asynchronous evaluation that is specific to a derived class.*
- void [derived\\_sync](#) ([PRPLList](#) &prp\_list)  
*classes. This version waits for at least one completion.*
- void [derived\\_sync\\_nowait](#) ([PRPLList](#) &prp\_list)  
*any completions if none are immediately available.*
- int [derived\\_synchronous\\_local\\_analysis](#) (const int &analysis\_id)

### Public Attributes

- [SysCallAnalysisCode](#) code  
*Used to read/write parameter files and responses.*

## Protected Member Functions

- void [derived\\_synch\\_kernel](#) (PRPList &prp\_list)  
*Convenience function for common code between wait and nowait case.*
- bool [grid\\_file\\_test](#) (const String &root\_file)  
*test file(s) for existence based on root\_file name*

## Protected Attributes

- IntSet [idSet](#)  
*system call evaluations*
- IntShortMap [failCountMap](#)  
*map linking function evaluation id's to number of response read failures*
- start\_grid\_computing\_t [start\\_grid\\_computing](#)  
*handle to dynamically linked start\_grid\_computing function*
- perform\_analysis\_t [perform\\_analysis](#)  
*handle to dynamically linked perform\_analysis grid function*
- get\_jobs\_completed\_t [get\\_jobs\\_completed](#)  
*handle to dynamically linked get\_jobs\_completed grid function*
- stop\_grid\_computing\_t [stop\\_grid\\_computing](#)  
*handle to dynamically linked stop\_grid\_computing function*

### 8.46.1 Detailed Description

using grid services such as Condor or Globus.

This class is currently a modified copy of [SysCallApplicInterface](#) adapted for use with an external grid services library which was dynamically linked using dlopen() services.

### 8.46.2 Member Function Documentation

#### 8.46.2.1 int [derived\\_synchronous\\_local\\_analysis](#) (const int & *analysis\_id*) [inline, virtual]

This code provides the derived function used by [ApplicationInterface::serve\\_analyses\\_synch\(\)](#).

TODO - allow local analyses?????



Reimplemented from [ApplicationInterface](#).

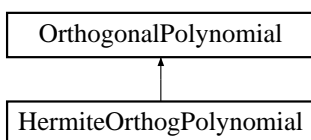
The documentation for this class was generated from the following files:

- GridApplicInterface.H
- GridApplicInterface.C

## 8.47 HermiteOrthogPolynomial Class Reference

Derived orthogonal polynomial class for Hermite polynomials.

Inheritance diagram for HermiteOrthogPolynomial::



### Public Member Functions

- [HermiteOrthogPolynomial \(\)](#)  
*default constructor*
- [~HermiteOrthogPolynomial \(\)](#)  
*destructor*

### Protected Member Functions

- `const Real & get\_value (const Real &x, size_t n)`  
*retrieve the Hermite polynomial value for a given parameter  $x$*
- `const Real & get\_gradient (const Real &x, size_t n)`  
*retrieve the Hermite polynomial gradient for a given parameter  $x$*
- `const Real & norm\_squared (size_t n)`  
*return the inner product  $\langle He_n, He_n \rangle = \|He_n\|^2$*
- `const RealVector & gauss\_points (size_t n)`  
*polynomial order  $n$*
- `const RealVector & gauss\_weights (size_t n)`  
*polynomial order  $n$*

### 8.47.1 Detailed Description

Derived orthogonal polynomial class for Hermite polynomials.

The [HermiteOrthogPolynomial](#) class evaluates a univariate Hermite polynomial of a particular order. It uses the "probabilist's" formulation for which the polynomials are orthogonal with respect to the weight function  $1/\sqrt{2\pi} \exp(-x^2/2)$  when integrated over the support range of  $[-\infty, +\infty]$ . It enables (mixed) multi-dimensional orthogonal polynomial basis functions within [OrthogPolyApproximation](#).

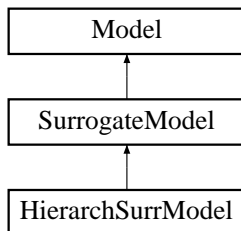
The documentation for this class was generated from the following files:

- HermiteOrthogPolynomial.H
- HermiteOrthogPolynomial.C

## 8.48 HierarchSurrModel Class Reference

hierarchical surrogates (models of varying fidelity).

Inheritance diagram for HierarchSurrModel::



### Public Member Functions

- [HierarchSurrModel \(ProblemDescDB &problem\\_db\)](#)  
*constructor*
- [~HierarchSurrModel \(\)](#)  
*destructor*

### Protected Member Functions

- void [derived\\_compute\\_response](#) (const [ActiveSet](#) &set)  
*portion of [compute\\_response\(\)](#) specific to [HierarchSurrModel](#)*
- void [derived\\_async\\_compute\\_response](#) (const [ActiveSet](#) &set)  
*portion of [async\\_compute\\_response\(\)](#) specific to [HierarchSurrModel](#)*
- const [ResponseArray](#) & [derived\\_synchronize](#) ()  
*portion of [synchronize\(\)](#) specific to [HierarchSurrModel](#)*
- const [IntResponseMap](#) & [derived\\_synchronize\\_nowait](#) ()  
*portion of [synchronize\\_nowait\(\)](#) specific to [HierarchSurrModel](#)*
- [Model](#) & [surrogate\\_model](#) ()  
*return [lowFidelityModel](#)*
- [Model](#) & [truth\\_model](#) ()  
*return [highFidelityModel](#)*

- void `derived_subordinate_models` (`ModelList &ml`, `bool recurse_flag`)  
*return lowFidelityModel and highFidelityModel*
- void `surrogate_bypass` (`bool bypass_flag`)  
*for any lower-level surrogates.*
- void `surrogate_function_indices` (`const IntSet &surr_fn_indices`)  
*(re)set the surrogate index set in `SurrogateModel::surrogateFnIndices`*
- void `build_approximation` ()  
*correction of lowFidelityModel results*
- void `component_parallel_mode` (`short mode`)  
*lowFidelityModel and highFidelityModel*
- void `derived_init_communicators` (`const int &max_iterator_concurrency`, `bool recurse_flag=true`)  
*set up lowFidelityModel and highFidelityModel for parallel operations*
- void `derived_init_serial` ()  
*set up lowFidelityModel and highFidelityModel for serial operations.*
- void `derived_set_communicators` (`const int &max_iterator_concurrency`, `bool recurse_flag=true`)  
*highFidelityModel*
- void `derived_free_communicators` (`const int &max_iterator_concurrency`, `bool recurse_flag=true`)  
*(request forwarded to lowFidelityModel and highFidelityModel)*
- void `serve` ()  
*stop\_servers().*
- void `stop_servers` ()  
*HierarchSurrModel is complete.*
- int `evaluation_id` () const  
*Return the current evaluation id for the `HierarchSurrModel`.*
- void `set_evaluation_reference` ()  
*(request forwarded to lowFidelityModel and highFidelityModel)*
- void `print_evaluation_summary` (`ostream &s`, `bool minimal_header=false`, `bool relative_count=true`) const  
*(request forwarded to lowFidelityModel and highFidelityModel)*

## Private Member Functions

- void [update\\_model](#) ([Model](#) &model)  
*with current variable values/bounds/labels*

## Private Attributes

- int [hierModelEvals](#)  
*derived\_asynch\_compute\_response()*
- [IntResponseMap](#) [cachedTruthRespMap](#)  
*portions were still pending.*
- [Model](#) [lowFidelityModel](#)  
*a data fit surrogate on a low fidelity model).*
- [Model](#) [highFidelityModel](#)  
*fidelity results. [Model](#) is of arbitrary type and supports recursions.*
- [Response](#) [highFidRefResponse](#)  
*and used for calculating corrections.*

### 8.48.1 Detailed Description

hierarchical surrogates (models of varying fidelity).

The [HierarchSurrModel](#) class manages hierarchical models of varying fidelity. In particular, it uses a low fidelity model as a surrogate for a high fidelity model. The class contains a [lowFidelityModel](#) which performs the approximate low fidelity function evaluations and a [highFidelityModel](#) which provides truth evaluations for computing corrections to the low fidelity results.

### 8.48.2 Member Function Documentation

#### 8.48.2.1 void [derived\\_compute\\_response](#) (const [ActiveSet](#) & set) [protected, virtual]

portion of [compute\\_response\(\)](#) specific to [HierarchSurrModel](#)

Compute the response synchronously using [lowFidelityModel](#), [highFidelityModel](#), or both (mixed case). For the [lowFidelityModel](#) portion, compute the high fidelity response if needed with [build\\_approximation\(\)](#), and, if correction is active, correct the low fidelity results.

Reimplemented from [Model](#).

**8.48.2.2 void derived\_async\_compute\_response (const [ActiveSet](#) & set) [protected, virtual]**

portion of [async\\_compute\\_response\(\)](#) specific to [HierarchSurrModel](#)

Compute the response asynchronously using [lowFidelityModel](#), [highFidelityModel](#), or both (mixed case). For the [lowFidelityModel](#) portion, compute the high fidelity response with [build\\_approximation\(\)](#) (for correcting the low fidelity results in [derived\\_synchronize\(\)](#) and [derived\\_synchronize\\_nowait\(\)](#)) if not performed previously.

Reimplemented from [Model](#).

**8.48.2.3 const [ResponseArray](#) & derived\_synchronize () [protected, virtual]**

portion of [synchronize\(\)](#) specific to [HierarchSurrModel](#)

Blocking retrieval of asynchronous evaluations from [lowFidelityModel](#), [highFidelityModel](#), or both (mixed case). For the [lowFidelityModel](#) portion, apply correction (if active) to each response in the array. [derived\\_synchronize\(\)](#) is designed for the general case where [derived\\_async\\_compute\\_response\(\)](#) may be inconsistent in its use of low fidelity evaluations, high fidelity evaluations, or both.

Reimplemented from [Model](#).

**8.48.2.4 const [IntResponseMap](#) & derived\_synchronize\_nowait () [protected, virtual]**

portion of [synchronize\\_nowait\(\)](#) specific to [HierarchSurrModel](#)

Nonblocking retrieval of asynchronous evaluations from [lowFidelityModel](#), [highFidelityModel](#), or both (mixed case). For the [lowFidelityModel](#) portion, apply correction (if active) to each response in the map. [derived\\_synchronize\\_nowait\(\)](#) is designed for the general case where [derived\\_async\\_compute\\_response\(\)](#) may be inconsistent in its use of actual evals, approx evals, or both.

Reimplemented from [Model](#).

**8.48.2.5 int evaluation\_id () const [inline, protected, virtual]**

Return the current evaluation id for the [HierarchSurrModel](#).

return the hierarchical model evaluation count. Due to possibly intermittent use of surrogate bypass, this is not the same as either the loFi or hiFi model evaluation counts. It also does not distinguish duplicate evals.

Reimplemented from [Model](#).

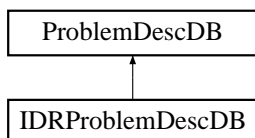
The documentation for this class was generated from the following files:

- [HierarchSurrModel.H](#)
- [HierarchSurrModel.C](#)

## 8.49 IDRProblemDescDB Class Reference

The derived input file database utilizing the IDR parser.

Inheritance diagram for IDRProblemDescDB::



### Public Member Functions

- [IDRProblemDescDB](#) ([ParallelLibrary](#) &parallel\_lib)  
*constructor*
- [~IDRProblemDescDB](#) ()  
*destructor*
- void [derived\\_manage\\_inputs](#) (const char \*dakota\_input\_file)  
*database using IDR.*

### Static Public Member Functions

- static void [strategy\\_kwhandler](#) (const struct FunctionData \*parsed\_data)  
*specification is parsed*
- static void [method\\_kwhandler](#) (const struct FunctionData \*parsed\_data)  
*specification is parsed*
- static void [model\\_kwhandler](#) (const struct FunctionData \*parsed\_data)  
*specification is parsed*
- static void [variables\\_kwhandler](#) (const struct FunctionData \*parsed\_data)  
*variables specification is parsed*
- static void [interface\\_kwhandler](#) (const struct FunctionData \*parsed\_data)  
*interface specification is parsed*
- static void [responses\\_kwhandler](#) (const struct FunctionData \*parsed\_data)  
*responses specification is parsed*



## Static Private Member Functions

- static void `idr_kw_id_error` (const char \*kw)  
*Error handler for missing required IDR keyword.*
- static Int `idr_find_id` (Int \*id\_pos, const Int cntr, const char \*id, const char \*\*id\_list, const char \*kw)  
*instances of a particular keyword*
- static Int \*\* `idr_get_int_table` (const struct FunctionData \*parsed\_data, Int identifier, Int &table\_len, Int num\_lists, Int list\_entry\_len)  
*Function for creating an IDR table of Ints.*
- static Real \*\* `idr_get_real_table` (const struct FunctionData \*parsed\_data, Int identifier, Int &table\_len, Int num\_lists, Int list\_entry\_len)  
*Function for creating an IDR table of Reals.*
- static char \*\*\* `idr_get_string_table` (const struct FunctionData \*parsed\_data, Int identifier, Int &table\_len, Int num\_lists, Int list\_entry\_len)  
*Function for creating an IDR table of strings.*

## Static Private Attributes

- static `IDRProblemDescDB * pDDBInstance`  
*functions in order to avoid the need for static data*
- static Int \*\* `intTable`  
*integer table populated in `idr_get_int_table()`*
- static Real \*\* `realTable`  
*real table populated in `idr_get_real_table()`*
- static char \*\*\* `stringTable`  
*string table populated in `idr_get_string_table()`*

### 8.49.1 Detailed Description

The derived input file database utilizing the IDR parser.

The `IDRProblemDescDB` class is a database for DAKOTA input file data that is populated by the Input Deck Reader (IDR) parser. When the parser reads a complete keyword (delimited by a newline), it calls the corresponding kwhandler function from this class which populates the corresponding Data object from the base class. For information on modifying the IDR input parsing procedures, refer to `Dakota/docs/Dev_Spec_Change.dox`

## 8.49.2 Member Function Documentation

### 8.49.2.1 void derived\_manage\_inputs (const char \* *dakota\_input\_file*) [virtual]

database using IDR.

Parse the input file using the Input Deck Reader (IDR) parsing system. IDR populates the [IDRProblemDescDB](#) object with the input file data.

Reimplemented from [ProblemDescDB](#).

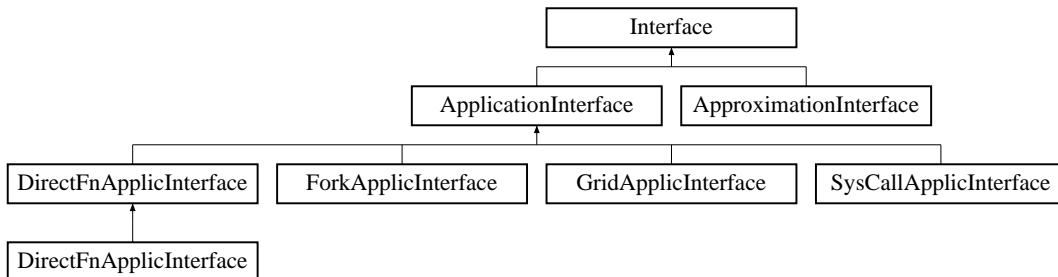
The documentation for this class was generated from the following files:

- IDRProblemDescDB.H
- IDRProblemDescDB.C

## 8.50 Interface Class Reference

Base class for the interface class hierarchy.

Inheritance diagram for Interface::



### Public Member Functions

- [Interface](#) ()  
*default constructor*
- [Interface](#) ([ProblemDescDB](#) &problem\_db)  
*standard constructor for envelope*
- [Interface](#) (const [Interface](#) &interface)  
*copy constructor*
- virtual [~Interface](#) ()  
*destructor*
- [Interface](#) operator= (const [Interface](#) &interface)  
*assignment operator*
- virtual void [map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, const bool asynch\_flag=false)  
*variables to the responses.*
- virtual const [ResponseArray](#) & [synch](#) ()  
*recovers data from a series of asynchronous evaluations (blocking)*
- virtual const [IntResponseMap](#) & [synch\\_nowait](#) ()  
*recovers data from a series of asynchronous evaluations (nonblocking)*

- virtual void [serve\\_evaluations](#) ()  
*evaluation server function for multiprocessor executions*
- virtual void [stop\\_evaluation\\_servers](#) ()  
*send messages from iterator rank 0 to terminate evaluation servers*
- virtual void [init\\_communicators](#) (const [IntArray](#) &message\_lengths, const int &max\_iterator\_concurrency)  
*iterator and concurrent multiprocessor analyses within an evaluation.*
- virtual void [set\\_communicators](#) (const [IntArray](#) &message\_lengths)  
*(the partitions are already allocated in [ParallelLibrary](#)).*
- virtual void [free\\_communicators](#) ()  
*iterator and concurrent multiprocessor analyses within an evaluation.*
- virtual void [init\\_serial](#) ()  
*reset certain defaults for serial interface objects.*
- virtual int [asynch\\_local\\_evaluation\\_concurrency](#) () const  
*return the user-specified concurrency for asynch local evaluations*
- virtual [String](#) [interface\\_synchronization](#) () const  
*return the user-specified interface synchronization*
- virtual int [minimum\\_samples](#) (bool constraint\_flag) const  
*[ApproximationInterface](#) (used by [DataFitSurrModels](#)).*
- virtual void [approximation\\_function\\_indices](#) (const [IntSet](#) &approx\_fn\_indices)  
*set the (currently active) approximation function index set*
- virtual void [update\\_approximation](#) (const [Variables](#) &vars, const [Response](#) &response)  
*updates the anchor point for an approximation*
- virtual void [update\\_approximation](#) (const [VariablesArray](#) &vars\_array, const [ResponseArray](#) &resp\_array)  
*updates the current data points for an approximation*
- virtual void [append\\_approximation](#) (const [Variables](#) &vars, const [Response](#) &response)  
*appends a single point to an existing approximation*
- virtual void [append\\_approximation](#) (const [VariablesArray](#) &vars\_array, const [ResponseArray](#) &resp\_array)  
*appends multiple points to an existing approximation*
- virtual void [build\\_approximation](#) (const [RealVector](#) &lower\_bnds, const [RealVector](#) &upper\_bnds)

*builds the approximation*

- virtual void `clear_current ()`  
*clears current data from an approximation interface*
- virtual void `clear_all ()`  
*clears all data from an approximation interface*
- virtual bool `anchor () const`  
*queries the presence of an anchorPoint within an approximation interface*
- virtual `Array< Approximation > & approximations ()`  
*retrieve the Approximations within an ApproximationInterface*
- virtual const `RealVectorArray & approximation_coefficients ()`  
*within an ApproximationInterface*
- virtual void `approximation_coefficients (const RealVectorArray &approx_coeffs)`  
*within an ApproximationInterface*
- virtual void `print_coefficients (ostream &s, size_t index) const`  
*Approximation instance within an ApproximationInterface.*
- virtual const `RealVector & approximation_variances (const RealVector &c_variables)`  
*within an ApproximationInterface*
- virtual const `List< SurrogateDataPoint > & approximation_data (size_t index)`  
*within an ApproximationInterface*
- virtual const `StringArray & analysis_drivers () const`  
*retrieve the analysis drivers specification for application interfaces*
- void `assign_rep (Interface *interface_rep, bool ref_count_incr=true)`  
*replaces existing letter with a new one*
- const `String & interface_type () const`  
*returns the interface type*
- const `String & interface_id () const`  
*returns the interface identifier*
- int `evaluation_id () const`  
*returns the current function evaluation id for the interface*
- void `set_eval_reference ()`  
*set evaluation count reference points for the interface*

- void [print\\_eval\\_summary](#) (ostream &s, bool minimal\_header, bool relative\_count) const  
*print an evaluation summary for the interface*
- bool [multi\\_proc\\_eval\\_flag](#) () const  
*returns a flag signaling the use of multiprocessor evaluation partitions*
- bool [iterator\\_eval\\_dedicated\\_master\\_flag](#) () const  
*iterator-evaluation scheduling level*
- bool [is\\_null](#) () const  
*function to check interfaceRep (does this envelope contain a letter?)*

## Protected Member Functions

- [Interface](#) (BaseConstructor, const [ProblemDescDB](#) &problem\_db)  
*derived class constructors - Coplien, p. 139)*
- [Interface](#) (NoDBBaseConstructor)  
*(NoDBBaseConstructor used for on the fly instantiations without a DB)*
- void [asv\\_mapping](#) (const [ActiveSet](#) &total\_set, [ActiveSet](#) &algebraic\_set, [ActiveSet](#) &core\_set, const [Variables](#) &vars, const [Response](#) &response)  
*from the total [Interface](#) evaluation requirements (total\_set). Also*
- void [algebraic\\_mappings](#) (const [Variables](#) &vars, const [ActiveSet](#) &algebraic\_set, [Response](#) &algebraic\_response)  
*and the data extracted from the algebraic\_mappings file*
- void [response\\_mapping](#) (const [Response](#) &algebraic\_response, const [Response](#) &core\_response, [Response](#) &total\_response)  
*from derived\_map() to create the total response*

## Protected Attributes

- [String](#) interfaceType  
*the interface type: system, fork, direct, grid, or approximation*
- [String](#) idInterface  
*(used in [print\\_eval\\_summary](#)())*
- bool [algebraicMappings](#)  
*Interface's parameter to response mapping that is explicit and algebraic.*

- `bool coreMappings`  
*ApplicationInterface* or *functionSurfaces* for *ApproximationInterface*).
- `int fnEvalId`  
*total interface evaluation counter*
- `int newFnEvalId`  
*new (non-duplicate) interface evaluation counter*
- `int fnEvalIdRefPt`  
*iteration reference point for fnEvalId*
- `int newFnEvalIdRefPt`  
*iteration reference point for newFnEvalId*
- `IntArray fnValCounter`  
*number of value evaluations by resp fn*
- `IntArray fnGradCounter`  
*number of gradient evaluations by resp fn*
- `IntArray fnHessCounter`  
*number of Hessian evaluations by resp fn*
- `IntArray newFnValCounter`  
*number of new value evaluations by resp fn*
- `IntArray newFnGradCounter`  
*number of new gradient evaluations by resp fn*
- `IntArray newFnHessCounter`  
*number of new Hessian evaluations by resp fn*
- `IntArray fnValRefPt`  
*iteration reference point for fnValCounter*
- `IntArray fnGradRefPt`  
*iteration reference point for fnGradCounter*
- `IntArray fnHessRefPt`  
*iteration reference point for fnHessCounter*
- `IntArray newFnValRefPt`  
*iteration reference point for newFnValCounter*

- [IntArray newFnGradRefPt](#)  
*iteration reference point for newFnGradCounter*
- [IntArray newFnHessRefPt](#)  
*iteration reference point for newFnHessCounter*
- [ResponseArray rawResponseArray](#)  
*asynchronous evaluations.*
- [IntResponseMap rawResponseMap](#)  
*asynchronous evaluations.*
- [StringArray responseTags](#)  
*(used in [print\\_eval\\_summary\(\)](#) and derived direct interface classes)*
- [bool multiProcEvalFlag](#)  
*flag for multiprocessor evaluation partitions ([evalComm](#))*
- [bool ieDedMasterFlag](#)  
*flag for dedicated master partitioning at the iterator level*
- [bool silentFlag](#)  
*flag for really quiet (*silent*) interface output*
- [bool quietFlag](#)  
*flag for quiet interface output*
- [bool verboseFlag](#)  
*flag for verbose interface output*
- [bool debugFlag](#)  
*flag for really verbose (*debug*) interface output*

## Private Member Functions

- [Interface \\* get\\_interface](#) ([ProblemDescDB](#) &[problem\\_db](#))  
*Used by the envelope to instantiate the correct letter class.*
- [int algebraic\\_function\\_type](#) ([String](#))  
*evaluation call to make*



## Private Attributes

- [StringArray algebraicVarTags](#)  
*set of variable tags from AMPL stub.col*
- [SizetArray algebraicACVIndices](#)  
*continuous variables*
- [SizetArray algebraicDerivIndices](#)  
*derivative variables*
- [StringArray algebraicFnTags](#)  
*set of function tags from AMPL stub.row*
- [IntArray algebraicFnTypes](#)  
*AMPL objval (conival) calls.*
- [RealArray algebraicConstraintWeights](#)  
*set of weights for computing Hessian matrices for algebraic constraints;*
- [SizetArray algebraicFnIndices](#)  
*DAKOTA response functions.*
- `int numAlgebraicResponses`  
*number of algebraic responses (objectives+constraints)*
- `Interface * interfaceRep`  
*pointer to the letter (initialized only for the envelope)*
- `int referenceCount`  
*number of objects sharing interfaceRep*
- `ASL * asl`  
*pointer to an AMPL solver library (ASL) object*

### 8.50.1 Detailed Description

Base class for the interface class hierarchy.

The [Interface](#) class hierarchy provides the part of a [Model](#) that is responsible for mapping a set of [Variables](#) into a set of Responses. The mapping is performed using either a simulation-based application interface or a surrogate-based approximation interface. For memory efficiency and enhanced polymorphism, the interface hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Interface](#)) serves as the envelope and one of the derived classes (selected in [Interface::get\\_interface\(\)](#)) serves as the letter.

## 8.50.2 Constructor & Destructor Documentation

### 8.50.2.1 `Interface ()`

default constructor

used in `Model` envelope class instantiations

### 8.50.2.2 `Interface (ProblemDescDB & problem_db)`

standard constructor for envelope

Used in `Model` instantiation to build the envelope. This constructor only needs to extract enough data to properly execute `get_interface`, since `Interface::Interface(BaseConstructor, problem_db)` builds the actual base class data inherited by the derived interfaces.

### 8.50.2.3 `Interface (const Interface & interface)`

copy constructor

Copy constructor manages sharing of `interfaceRep` and incrementing of `referenceCount`.

### 8.50.2.4 `~Interface () [virtual]`

destructor

Destructor decrements `referenceCount` and only deletes `interfaceRep` if `referenceCount` is zero.

### 8.50.2.5 `Interface (BaseConstructor, const ProblemDescDB & problem_db) [protected]`

derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all inherited interfaces. `get_interface()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_interface()` again). Since this is the letter and the letter IS the representation, `interfaceRep` is set to NULL (an uninitialized pointer causes problems in `~Interface`).

## 8.50.3 Member Function Documentation

### 8.50.3.1 `Interface operator= (const Interface & interface)`

assignment operator

Assignment operator decrements referenceCount for old interfaceRep, assigns new interfaceRep, and increments referenceCount for new interfaceRep.

#### 8.50.3.2 void assign\_rep (Interface \* interface\_rep, bool ref\_count\_incr = true)

replaces existing letter with a new one

Similar to the assignment operator, the `assign_rep()` function decrements referenceCount for the old interfaceRep and assigns the new interfaceRep. It is different in that it is used for publishing derived class letters to existing envelopes, as opposed to sharing representations among multiple envelopes (in particular, `assign_rep` is passed a letter object and `operator=` is passed an envelope object). Letter assignment supports two models as governed by `ref_count_incr`:

- `ref_count_incr = true` (default): the incoming letter belongs to another envelope. In this case, increment the reference count in the normal manner so that deallocation of the letter is handled properly.
- `ref_count_incr = false`: the incoming letter is instantiated on the fly and has no envelope. This case is modeled after `get_interface()`: a letter is dynamically allocated using `new` and passed into `assign_rep`, the letter's reference count is not incremented, and the letter is not remotely deleted (its memory management is passed over to the envelope).

#### 8.50.3.3 Interface \* get\_interface (ProblemDescDB & problem\_db) [private]

Used by the envelope to instantiate the correct letter class.

used only by the envelope constructor to initialize interfaceRep to the appropriate derived type.

### 8.50.4 Member Data Documentation

#### 8.50.4.1 ResponseArray rawResponseArray [protected]

asynchronous evaluations.

The array is the raw set of responses corresponding to all asynchronous map calls. This raw array is postprocessed (i.e., finite difference gradients merged) in `Model::synchronize()` where it becomes `responseArray`.

#### 8.50.4.2 IntResponseMap rawResponseMap [protected]

asynchronous evaluations.

The map is a partial set of completions which are identified through their `fn_eval_id` key. Postprocessing from raw to combined form (i.e., finite difference gradient merging) is not currently supported in `Model::synchronize_nowait()`.

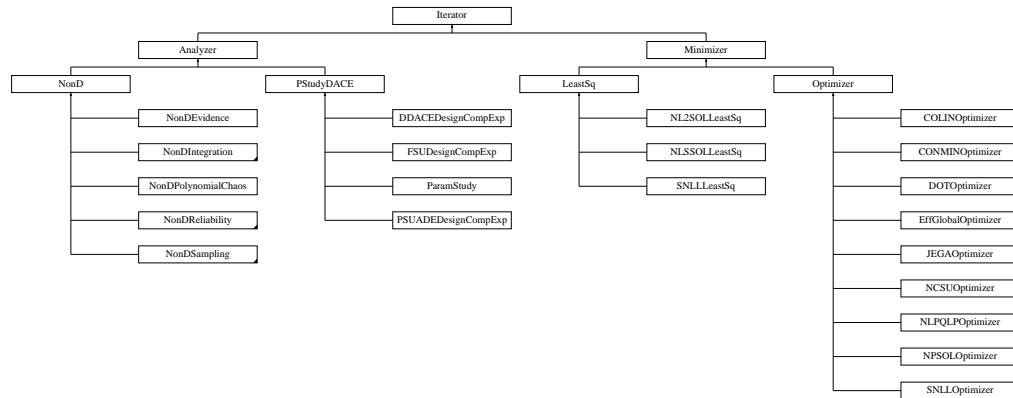
The documentation for this class was generated from the following files:

- [DakotaInterface.H](#)
- [DakotaInterface.C](#)

## 8.51 Iterator Class Reference

Base class for the iterator class hierarchy.

Inheritance diagram for Iterator::



### Public Member Functions

- [Iterator](#) ()  
*default constructor*
- [Iterator](#) (Model &model)  
*standard constructor for envelope*
- [Iterator](#) (const [Iterator](#) &iterator)  
*copy constructor*
- virtual [~Iterator](#) ()  
*destructor*
- [Iterator operator=](#) (const [Iterator](#) &iterator)  
*assignment operator*
- virtual void [run](#) ()  
*run the iterator; portion of [run\\_iterator\(\)](#)*
- virtual const [Variables](#) & [variables\\_results](#) () const  
*return a single final iterator solution (variables)*
- virtual const [Response](#) & [response\\_results](#) () const

*return a single final iterator solution (response)*

- virtual bool `accepts_multiple_points ()` const  
*return is false. Override to return true if appropriate.*
- virtual bool `returns_multiple_points ()` const  
*return is false. Override to return true if appropriate.*
- virtual const `VariablesArray & variables_array_results ()` const  
*only be used if `returns_multiple_points()` returns true.*
- virtual const `ResponseArray & response_array_results ()` const  
*only be used if `returns_multiple_points()` returns true.*
- virtual void `initial_points (const VariablesArray &pts)`  
*only be used if `accepts_multiple_points()` returns true.*
- virtual void `response_results_active_set (const ActiveSet &set)`  
*set the requested data for the final iterator response results*
- virtual void `print_results (ostream &s)` const  
*print the final iterator results*
- virtual void `multi_objective_weights (const RealVector &multi_obj_wts)`  
*Used by `ConcurrentStrategy` for Pareto set optimization.*
- virtual void `sampling_reset (int min_samples, bool all_data_flag, bool stats_flag)`  
*reset sampling iterator*
- virtual const `String & sampling_scheme ()` const  
*return sampling name*
- virtual `String uses_method ()` const  
*return name of any enabling iterator used by this iterator*
- virtual void `method_recourse ()`  
*perform a method switch, if possible, due to a detected conflict*
- virtual const `VariablesArray & all_variables ()` const  
*return the complete set of evaluated variables*
- virtual const `ResponseArray & all_responses ()` const  
*return the complete set of computed responses*
- void `pre_run (ostream &s)`  
*utility function to verbosely perform common operations prior to `run()`*

- void `pre_run()`  
*utility function to quietly perform common operations prior to `run()`*
- void `run_iterator` (ostream &s)  
*utility function to automate `pre_run()/run()/post_run()` verbosely*
- void `run_iterator` ()  
*utility function to automate `pre_run()/run()/post_run()` quietly*
- void `post_run` (ostream &s)  
*utility function to verbosely perform common operations following `run()`*
- void `post_run` ()  
*utility function to quietly perform common operations following `run()`*
- void `assign_rep` (Iterator \*iterator\_rep, bool ref\_count\_incr=true)  
*replaces existing letter with a new one*
- const `ProblemDescDB` & `problem_description_db` () const  
*return the problem description database (`probDescDB`)*
- const `String` & `method_name` () const  
*return the method name*
- const `String` & `method_id` () const  
*return the method identifier (`idMethod`)*
- const int & `maximum_concurrency` () const  
*return the maximum concurrency supported by the iterator*
- void `maximum_concurrency` (const int &max\_conc)  
*set the maximum concurrency supported by the iterator*
- void `active_set` (const `ActiveSet` &set)  
*employ `evaluate_parameter_sets()`*
- const `ActiveSet` & `active_set` () const  
*employ `evaluate_parameter_sets()`*
- void `sub_iterator_flag` (bool si\_flag)  
*set `subIteratorFlag`*
- void `variable_mappings` (const `SizetArray` &c\_index1, const `SizetArray` &d\_index1, const `SizetArray` &index2)  
*set `primaryCVarMapIndices`, `primaryDVarMapIndices`, `secondaryVarMapIndices`*

- `bool is_null () const`  
*function to check iteratorRep (does this envelope contain a letter?)*
- `Iterator * iterator_rep () const`  
*that are not mapped to the top *Iterator* level*

## Protected Member Functions

- `Iterator (BaseConstructor, Model &model)`  
*derived class constructors - Coplien, p. 139)*
- `Iterator (NoDBBaseConstructor, Model &model)`  
*alternate constructor for base iterator classes constructed on the fly*
- `Iterator (NoDBBaseConstructor)`  
*alternate constructor for base iterator classes constructed on the fly*
- `virtual void derived_pre_run ()`  
*portions of pre\_run specific to derived iterators*
- `virtual void derived_post_run ()`  
*portions of post\_run specific to derived iterators*
- `virtual const VariablesArray & initial_points () const`  
*be meaningful after a call to initial\_points mutator.*

## Protected Attributes

- `Model iteratedModel`  
*or a thin *RecastModel* wrapped around it*
- `const ProblemDescDB & probDescDB`  
*class member reference to the problem description database*
- `String methodName`  
*name of the iterator (the user's method spec)*
- `Real convergenceTol`  
*iteration convergence tolerance*
- `int maxIterations`  
*maximum number of iterations for the iterator*



- int `maxFunctionEvals`  
*maximum number of fn evaluations for the iterator*
- int `maxConcurrency`  
*maximum coarse-grained concurrency*
- size\_t `numFunctions`  
*number of response functions*
- size\_t `numContinuousVars`  
*number of active continuous vars.*
- size\_t `numDiscreteVars`  
*number of active discrete vars.*
- `ActiveSet` `activeSet`  
*tracks the response data requirements on each function evaluation*
- bool `subIteratorFlag`  
*(`NestedModel::subIterator` or `DataFitSurrModel::daceIterator`)*
- `SizeTArray` `primaryCVarMapIndices`  
*level iteration*
- `SizeTArray` `primaryDVarMapIndices`  
*level iteration*
- `SizeTArray` `secondaryVarMapIndices`  
*"secondary" variable mappings flowed down from higher level iteration*
- `String` `gradientType`  
*type of gradient data: analytic, numerical, mixed, or none*
- `String` `methodSource`  
*source of numerical gradient routine: dakota or vendor*
- `String` `intervalType`  
*type of numerical gradient interval: central or forward*
- `String` `hessianType`  
*type of Hessian data: analytic, numerical, quasi, mixed, or none*
- Real `fdGradStepSize`  
*relative finite difference step size for numerical gradients*

- Real [fdHessByGradStepSize](#)  
*using first-order differences of gradients*
- Real [fdHessByFnStepSize](#)  
*using second-order differences of function values*
- bool [silentOutput](#)  
*flag for really quiet (silent) algorithm output*
- bool [quietOutput](#)  
*flag for quiet algorithm output*
- bool [verboseOutput](#)  
*flag for verbose algorithm output*
- bool [debugOutput](#)  
*flag for really verbose (debug) algorithm output*
- bool [asynchFlag](#)  
*copy of the model's asynchronous evaluation flag*

### Private Member Functions

- [Iterator](#) \* [get\\_iterator](#) ([Model](#) &model)  
*Used by the envelope to instantiate the correct letter class.*

### Private Attributes

- [String](#) [idMethod](#)  
*method identifier string from the input file*
- [Iterator](#) \* [iteratorRep](#)  
*pointer to the letter (initialized only for the envelope)*
- int [referenceCount](#)  
*number of objects sharing iteratorRep*

#### 8.51.1 Detailed Description

Base class for the iterator class hierarchy.

The [Iterator](#) class is the base class for one of the primary class hierarchies in DAKOTA. The iterator hierarchy contains all of the iterative algorithms which use repeated execution of simulations as function evaluations. For

memory efficiency and enhanced polymorphism, the iterator hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Iterator](#)) serves as the envelope and one of the derived classes (selected in [Iterator::get\\_iterator\(\)](#)) serves as the letter.

## 8.51.2 Constructor & Destructor Documentation

### 8.51.2.1 [Iterator](#) ()

default constructor

The default constructor is used in `Vector<Iterator>` instantiations and for initialization of [Iterator](#) objects contained in [Strategy](#) derived classes (see derived class header files). `iteratorRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful [Iterator](#) object). This makes it necessary to check for NULL pointers in the copy constructor, assignment operator, and destructor.

### 8.51.2.2 [Iterator](#) ([Model](#) & *model*)

standard constructor for envelope

Used in iterator instantiations within strategy constructors. Envelope constructor only needs to extract enough data to properly execute `get_iterator`, since [Iterator](#)([BaseConstructor](#), *model*) builds the actual base class data inherited by the derived iterators.

### 8.51.2.3 [Iterator](#) (const [Iterator](#) & *iterator*)

copy constructor

Copy constructor manages sharing of `iteratorRep` and incrementing of `referenceCount`.

### 8.51.2.4 [~Iterator](#) () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `iteratorRep` when `referenceCount` reaches zero.

### 8.51.2.5 [Iterator](#) ([BaseConstructor](#), [Model](#) & *model*) [protected]

derived class constructors - Coplien, p. 139)

This constructor builds the base class data for all inherited iterators. `get_iterator()` instantiates a derived class and the derived class selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_iterator()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Iterator`).

### 8.51.2.6 **Iterator** (**NoDBBaseConstructor**, **Model & model**) [protected]

alternate constructor for base iterator classes constructed on the fly

This alternate constructor builds base class data for inherited iterators. It is used for on-the-fly instantiations for which DB queries cannot be used. Therefore it only sets attributes taken from the incoming model.

### 8.51.2.7 **Iterator** (**NoDBBaseConstructor**) [protected]

alternate constructor for base iterator classes constructed on the fly

This alternate constructor builds base class data for inherited iterators. It is used for on-the-fly instantiations for which DB queries cannot be used. It has no incoming model, so only sets up a minimal set of defaults. However, its use is preferable to the default constructor, which should remain as minimal as possible.

## 8.51.3 Member Function Documentation

### 8.51.3.1 **Iterator** operator= (**const Iterator & iterator**)

assignment operator

Assignment operator decrements referenceCount for old iteratorRep, assigns new iteratorRep, and increments referenceCount for new iteratorRep.

### 8.51.3.2 **void run ()** [virtual]

run the iterator; portion of [run\\_iterator\(\)](#)

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented in [LeastSq](#), [NonD](#), [Optimizer](#), and [PStudyDACE](#).

### 8.51.3.3 **void print\_results (ostream & s) const** [virtual]

print the final iterator results

This virtual function provides additional iterator-specific final results outputs beyond the function evaluation summary printed in [post\\_run\(\)](#).

Reimplemented in [LeastSq](#), [Optimizer](#), [PStudyDACE](#), [NonDEvidence](#), [NonDGlobalReliability](#), [NonDIncrLHSSampling](#), [NonDLHSSampling](#), [NonDLocalReliability](#), and [NonDPolynomialChaos](#).

### 8.51.3.4 **void pre\_run (ostream & s)**

utility function to verbosely perform common operations prior to [run\(\)](#)

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is one form of the overloaded pre-run function. This form accepts an ostream and executes verbosely. It is used for standard stand-alone iterator executions. This function is not virtual: derived portions are defined in [derived\\_pre\\_run\(\)](#).

#### 8.51.3.5 void pre\_run ()

utility function to quietly perform common operations prior to [run\(\)](#)

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is one form of the overloaded pre-run function. This form does not accept an ostream and executes quietly. It is commonly used in sub-iterator executions. This function is not virtual: derived portions are defined in [derived\\_pre\\_run\(\)](#).

#### 8.51.3.6 void run\_iterator (ostream & s)

utility function to automate [pre\\_run\(\)/run\(\)/post\\_run\(\)](#) verbosely

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This non-virtual function is one form of the overloaded run\_iterator function which automates the pre-run/run/post-run portions of the progression. This form accepts an ostream and executes verbosely.

#### 8.51.3.7 void run\_iterator ()

utility function to automate [pre\\_run\(\)/run\(\)/post\\_run\(\)](#) quietly

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This non-virtual function is one form of the overloaded run\_iterator function which automates the pre-run/run/post-run portions of the progression. This form does not accept an ostream and executes quietly.

#### 8.51.3.8 void post\_run (ostream & s)

utility function to verbosely perform common operations following [run\(\)](#)

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is one form of the overloaded post-run function. This form accepts an ostream and executes verbosely. This function is not virtual: derived portions are defined in [derived\\_post\\_run\(\)](#).

#### 8.51.3.9 void post\_run ()

utility function to quietly perform common operations following [run\(\)](#)

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is one form of the overloaded post-run function. This form does not accept an ostream and executes quietly. This function is not virtual: derived portions are defined in [derived\\_post\\_run\(\)](#).

#### 8.51.3.10 void assign\_rep (Iterator \* iterator\_rep, bool ref\_count\_incr = true)

replaces existing letter with a new one

Similar to the assignment operator, the [assign\\_rep\(\)](#) function decrements referenceCount for the old iteratorRep and assigns the new iteratorRep. It is different in that it is used for publishing derived class letters to existing envelopes, as opposed to sharing representations among multiple envelopes (in particular, assign\_rep is passed a letter object and operator= is passed an envelope object). Letter assignment supports two models as governed by ref\_count\_incr:

- ref\_count\_incr = true (default): the incoming letter belongs to another envelope. In this case, increment the reference count in the normal manner so that deallocation of the letter is handled properly.
- ref\_count\_incr = false: the incoming letter is instantiated on the fly and has no envelope. This case is modeled after [get\\_iterator\(\)](#): a letter is dynamically allocated using new and passed into assign\_rep, the letter's reference count is not incremented, and the letter is not remotely deleted (its memory management is passed over to the envelope).

#### 8.51.3.11 void derived\_pre\_run () [protected, virtual]

portions of pre\_run specific to derived iterators

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual derived class portion of [pre\\_run\(\)](#). Redefinition by derived classes is optional.

Reimplemented in [CONMINOptimizer](#), [DOTOptimizer](#), [NLPQLPOptimizer](#), [SNLLLeastSq](#), and [SNLLOptimizer](#).

#### 8.51.3.12 void derived\_post\_run () [protected, virtual]

portions of post\_run specific to derived iterators

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual derived class portion of [post\\_run\(\)](#). Redefinition by derived classes is optional.

Reimplemented in [LeastSq](#), [Optimizer](#), and [SNLLLeastSq](#).

#### 8.51.3.13 [Iterator](#) \* get\_iterator (Model & model) [private]

Used by the envelope to instantiate the correct letter class.

Used only by the envelope constructor to initialize iteratorRep to the appropriate derived type, as given by the methodName attribute.

### 8.51.4 Member Data Documentation

**8.51.4.1 Real `fdGradStepSize`** [protected]

relative finite difference step size for numerical gradients

A scalar value (instead of the vector `fd_gradient_step_size` spec) is used within the iterator hierarchy since this attribute is only used to publish a step size to vendor numerical gradient algorithms.

**8.51.4.2 Real `fdHessByGradStepSize`** [protected]

using first-order differences of gradients

A scalar value (instead of the vector `fd_hessian_step_size` spec) is used within the iterator hierarchy since this attribute is only used to publish a step size to vendor numerical Hessian algorithms.

**8.51.4.3 Real `fdHessByFnStepSize`** [protected]

using second-order differences of function values

A scalar value (instead of the vector `fd_hessian_step_size` spec) is used within the iterator hierarchy since this attribute is only used to publish a step size to vendor numerical Hessian algorithms.

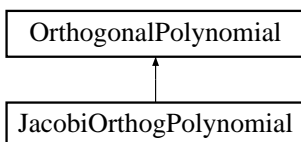
The documentation for this class was generated from the following files:

- `DakotaIterator.H`
- `DakotaIterator.C`

## 8.52 JacobiOrthogPolynomial Class Reference

Derived orthogonal polynomial class for Jacobi polynomials.

Inheritance diagram for JacobiOrthogPolynomial::



### Public Member Functions

- [JacobiOrthogPolynomial \(\)](#)  
*default constructor*
- [JacobiOrthogPolynomial \(const Real &alpha\\_stat, const Real &beta\\_stat\)](#)  
*standard constructor*
- [~JacobiOrthogPolynomial \(\)](#)  
*destructor*

### Protected Member Functions

- const Real & [get\\_value](#) (const Real &x, size\_t n)  
*retrieve the Jacobi polynomial value for a given parameter x*
- const Real & [get\\_gradient](#) (const Real &x, size\_t n)  
*retrieve the Jacobi polynomial gradient for a given parameter x*
- const Real & [norm\\_squared](#) (size\_t n)  
 $||P^{(\alpha, \beta)}_n||^2$
- const [RealVector](#) & [gauss\\_points](#) (size\_t n)  
*polynomial order n*
- const [RealVector](#) & [gauss\\_weights](#) (size\_t n)  
*polynomial order n*
- void [alpha\\_stat](#) (const Real &alpha)



set `betaPoly` using the conversion `betaPoly = alpha_stat - 1`.

- void `beta_stat` (const Real &beta)  
set `alphaPoly` using the conversion `alphaPoly = beta_stat - 1`.

### Private Attributes

- Real `alphaPoly`  
*Abramowitz and Stegun (differs from statistical PDF notation).*
- Real `betaPoly`  
*Abramowitz and Stegun (differs from statistical PDF notation).*

### 8.52.1 Detailed Description

Derived orthogonal polynomial class for Jacobi polynomials.

The [JacobiOrthogPolynomial](#) class evaluates a univariate Jacobi polynomial  $P^{(\alpha,\beta)}_n$  of a particular order. These polynomials are orthogonal with respect to the weight function  $(1-x)^\alpha (1+x)^\beta$  when integrated over the support range of  $[-1,+1]$ . This corresponds to the probability density function  $f(x) = (1-x)^\alpha (1+x)^\beta / (2^{(\alpha+\beta+1)} B(\alpha+1,\beta+1))$  for the beta distribution for  $[L,U]=[-1,1]$ , where common statistical PDF notation conventions (see, e.g., the uncertain variables section in the DAKOTA Reference Manual) and the Abramowitz and Stegun orthogonal polynomial conventions are inverted and require conversion in this case (`alpha_poly = beta_stat - 1`; `beta_poly = alpha_stat - 1` with the poly definitions used in both cases above). It enables (mixed) multidimensional orthogonal polynomial basis functions within [OrthogPolyApproximation](#). A special case is the [LegendreOrthogPolynomial](#) (implemented separately), for which `alpha_poly = beta_poly = 0`.

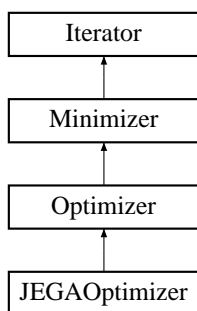
The documentation for this class was generated from the following files:

- [JacobiOrthogPolynomial.H](#)
- [JacobiOrthogPolynomial.C](#)

## 8.53 JEGAOptimizer Class Reference

A version of [Dakota::Optimizer](#) for instantiation of John Eddy's Genetic Algorithms (JEGA).

Inheritance diagram for JEGAOptimizer::



### Public Member Functions

- virtual void [find\\_optimum](#) ()  
*Performs the iterations to determine the optimal set of solutions.*
- virtual bool [accepts\\_multiple\\_points](#) () const  
*Overridden to return true since JEGA algorithms can accept multiple initial points.*
- virtual bool [returns\\_multiple\\_points](#) () const  
*Overridden to return true since JEGA algorithms can return multiple final points.*
- virtual void [initial\\_points](#) (const [VariablesArray](#) &pts)  
*Overridden to assign the `_initPts` member variable to the passed in collection of [Dakota::Variables](#).*
- virtual const [VariablesArray](#) & [initial\\_points](#) () const  
*Overridden to return the collection of initial points for the JEGA algorithm created and run by this [JEGAOptimizer](#).*
- [JEGAOptimizer](#) ([Model](#) &model)  
*Constructs a [JEGAOptimizer](#) class object.*
- [~JEGAOptimizer](#) ()  
*Destructs a [JEGAOptimizer](#).*

## Protected Member Functions

- void [LoadDakotaResponses](#) (const JEGA::Utilities::Design &from, [Variables](#) &vars, [Response](#) &resp) const  
*Loads the JEGA-style Design class into equivalent Dakota-style [Variables](#) and [Response](#) objects.*
- void [ReCreateTheParameterDatabase](#) ()  
*Destroys the current parameter database and creates a new empty one.*
- void [LoadTheParameterDatabase](#) ()  
*Reads information out of the known [Dakota::ProblemDescDB](#) and puts it into the current parameter database.*
- void [LoadAlgorithmConfig](#) (JEGA::FrontEnd::AlgorithmConfig &aConfig)  
*Completely initializes the supplied algorithm configuration.*
- void [LoadProblemConfig](#) (JEGA::FrontEnd::ProblemConfig &pConfig)  
*Completely initializes the supplied problem configuration.*
- void [LoadTheDesignVariables](#) (JEGA::FrontEnd::ProblemConfig &pConfig)  
*Adds [DesignVariableInfo](#) objects into the problem configuration object.*
- void [LoadTheObjectiveFunctions](#) (JEGA::FrontEnd::ProblemConfig &pConfig)  
*Adds [ObjectiveFunctionInfo](#) objects into the problem configuration object.*
- void [LoadTheConstraints](#) (JEGA::FrontEnd::ProblemConfig &pConfig)  
*Adds [ConstraintInfo](#) objects into the problem configuration object.*
- const JEGA::Utilities::Design \* [GetBestSolution](#) (const JEGA::Utilities::DesignOFSortSet &from)  
*Chooses the best Design from a set of solutions taking into account the algorithm type.*
- const JEGA::Utilities::Design \* [GetBestMOSolution](#) (const JEGA::Utilities::DesignOFSortSet &from)  
*Chooses the best Design from a set of solutions assuming that they are generated by a multi objective algorithm.*
- const JEGA::Utilities::Design \* [GetBestSOSolution](#) (const JEGA::Utilities::DesignOFSortSet &from)  
*Chooses the best Design from a set of solutions assuming that they are generated by a single objective algorithm.*
- JEGA::DoubleMatrix [ToDoubleMatrix](#) (const [VariablesArray](#) &variables) const  
*Converts the items in a [VariablesArray](#) into a [DoubleMatrix](#) whereby the items in the matrix are the design variables.*
- void [resize\\_variables\\_results\\_array](#) (std::size\_t newsize)  
*Safely resizes the best variables array taking into account the requirements put forth by the envelope-letter design pattern.*
- void [resize\\_response\\_results\\_array](#) (std::size\_t newsize)  
*Safely resizes the best response array taking into account the requirements put forth by the envelope-letter design pattern.*

## Private Attributes

- [EvaluatorCreator](#) \* [\\_theEvalCreator](#)  
*A pointer to an [EvaluatorCreator](#) used to create the evaluator used by JEGA in [Dakota](#) (a [JEGAEvaluator](#)).*
- [JEGA::Utilities::ParameterDatabase](#) \* [\\_theParamDB](#)  
*A pointer to the [ParameterDatabase](#) from which all parameters are retrieved by the created algorithms.*
- [VariablesArray](#) [\\_initPts](#)  
*An array of initial points to use as an initial population.*

## Static Private Attributes

- static const std::string [\\_sogaMethodText](#)  
*The text that indicates the SOGA method.*
- static const std::string [\\_mogaMethodText](#)  
*The text that indicates the MOGA method.*

## Classes

- class [Driver](#)  
*A subclass of the JEGA front end driver that exposes the individual protected methods to execute the algorithm.*
- class [EvaluatorCreator](#)  
*A specialization of the [JEGA::FrontEnd::EvaluatorCreator](#) that creates a new instance of a [Evaluator](#).*

### 8.53.1 Detailed Description

A version of [Dakota::Optimizer](#) for instantiation of John Eddy's Genetic Algorithms (JEGA).

This class encapsulates the necessary functionality for creating and properly initializing the JEGA algorithms (MOGA and SOGA).

### 8.53.2 Constructor & Destructor Documentation

### 8.53.2.1 JEGAOptimizer (Model & model)

Constructs a `JEGAOptimizer` class object.

This method does some of the initialization work for the algorithm. In particular, it initialized the JEGA core.

**Parameters:**

*model* The `Dakota::Model` that will be used by this optimizer for problem information, etc.

## 8.53.3 Member Function Documentation

### 8.53.3.1 void LoadDakotaResponses (const JEGA::Utilities::Design & from, Variables & vars, Response & resp) const [protected]

Loads the JEGA-style Design class into equivalent Dakota-style `Variables` and `Response` objects.

This version is meant for the case where a `Variables` and a `Response` object exist and just need to be loaded.

**Parameters:**

*from* The JEGA Design class object from which to extract the variable and response information for `Dakota`.

*vars* The `Dakota::Variables` object into which to load the design variable values of *from*.

*resp* The `Dakota::Response` object into which to load the objective function and constraint values of *from*.

### 8.53.3.2 void LoadTheParameterDatabase () [protected]

Reads information out of the known `Dakota::ProblemDescDB` and puts it into the current parameter database.

This should be called from the `JEGAOptimizer` constructor since it is the only time when the problem description database is certain to be configured to supply data for this optimizer.

### 8.53.3.3 void LoadAlgorithmConfig (JEGA::FrontEnd::AlgorithmConfig & aConfig) [protected]

Completely initializes the supplied algorithm configuration.

This loads the supplied configuration object with appropriate data retrieved from the parameter database.

**Parameters:**

*aConfig* The algorithm configuration object to load.

**8.53.3.4 void LoadProblemConfig (JEGA::FrontEnd::ProblemConfig & *pConfig*) [protected]**

Completely initializes the supplied problem configuration.

This loads the fresh configuration object using the LoadTheDesignVariables, LoadTheObjectiveFunctions, and LoadTheConstraints methods.

**Parameters:**

*pConfig* The problem configuration object to load.

**8.53.3.5 void LoadTheDesignVariables (JEGA::FrontEnd::ProblemConfig & *pConfig*) [protected]**

Adds DesignVariableInfo objects into the problem configuration object.

This retrieves design variable information from the ParameterDatabase and creates DesignVariableInfo's from it.

**Parameters:**

*pConfig* The problem configuration object to load.

**8.53.3.6 void LoadTheObjectiveFunctions (JEGA::FrontEnd::ProblemConfig & *pConfig*) [protected]**

Adds ObjectiveFunctionInfo objects into the problem configuration object.

This retrieves objective function information from the ParameterDatabase and creates ObjectiveFunctionInfo's from it.

**Parameters:**

*pConfig* The problem configuration object to load.

**8.53.3.7 void LoadTheConstraints (JEGA::FrontEnd::ProblemConfig & *pConfig*) [protected]**

Adds ConstraintInfo objects into the problem configuration object.

This retrieves constraint function information from the ParameterDatabase and creates ConstraintInfo's from it.

**Parameters:**

*pConfig* The problem configuration object to load.

**8.53.3.8** `const JEGA::Utilities::Design* GetBestSolution (const JEGA::Utilities::DesignOFSortSet & from)` [protected]

Chooses the best Design from a set of solutions taking into account the algorithm type.  
eventually this functionality must be moved into a separate post-processing application for MO datasets.

**8.53.3.9** `const JEGA::Utilities::Design* GetBestMOSolution (const JEGA::Utilities::DesignOFSortSet & from)` [protected]

Chooses the best Design from a set of solutions assuming that they are generated by a multi objective algorithm.  
eventually this functionality must be moved into a separate post-processing application for MO datasets.

**8.53.3.10** `const JEGA::Utilities::Design* GetBestSOSolution (const JEGA::Utilities::DesignOFSortSet & from)` [protected]

Chooses the best Design from a set of solutions assuming that they are generated by a single objective algorithm.  
eventually this functionality must be moved into a separate post-processing application for MO datasets.

**8.53.3.11** `JEGA::DoubleMatrix ToDoubleMatrix (const VariablesArray & variables)` const [protected]

Converts the items in a VariablesArray into a DoubleMatrix whereby the items in the matrix are the design variables.

The matrix will not contain responses but when being used by [Dakota](#), this doesn't matter. JEGA will attempt to re-evaluate these points but [Dakota](#) will recognize that they do not require re-evaluation and thus it will be a cheap operation.

**Parameters:**

*variables* The array of DakotaVariables objects to use as the contents of the returned matrix.

**Returns:**

The matrix created using the supplied VariablesArray.

**8.53.3.12** `void resize_variables_results_array (std::size_t newsize)` [protected]

Safely resizes the best variables array taking into account the requirements put forth by the envelope-letter design pattern.

Do not directly call `resize` on the `bestVariablesArray` object unless you intend to share the internal content (letter) with other objects after assignment.

**Parameters:**

*newsize* The new size for the variables array.

**8.53.3.13 void resize\_response\_results\_array (std::size\_t newsize) [protected]**

Safely resizes the best response array taking into account the requirements put forth by the envelope-letter design pattern.

Do not directly call `resize` on the `bestResponseArray` object unless you intend to share the internal content (letter) with other objects after assignment.

**Parameters:**

*newsize* The new size for the responses array.

**8.53.3.14 void find\_optimum () [virtual]**

Performs the iterations to determine the optimal set of solutions.

Override of pure virtual method in [Optimizer](#) base class.

The extraction of parameter values actually occurs in this method when the `JEGA::FrontEnd::Driver::ExecuteAlgorithm` is called. Also the loading of the problem and algorithm configurations occurs in this method. That way, if it is called more than once and the algorithm or problem has changed, it will be accounted for.

Implements [Optimizer](#).

**8.53.3.15 bool accepts\_multiple\_points () const [virtual]**

Overridden to return true since JEGA algorithms can accept multiple initial points.

**Returns:**

true, always.

Reimplemented from [Iterator](#).

**8.53.3.16 bool returns\_multiple\_points () const [virtual]**

Overridden to return true since JEGA algorithms can return multiple final points.

**Returns:**

true, always.

Reimplemented from [Iterator](#).



**8.53.3.17** void `initial_points` (const [VariablesArray](#) & *pts*) [virtual]

Overridden to assign the `_initPts` member variable to the passed in collection of [Dakota::Variables](#).

**Parameters:**

*The* array of initial points for the JEGA algorithm created and run by this [JEGAOptimizer](#).

Reimplemented from [Iterator](#).

**8.53.3.18** const [VariablesArray](#) & `initial_points` () const [virtual]

Overridden to return the collection of initial points for the JEGA algorithm created and run by this [JEGAOptimizer](#).

**Returns:**

The collection of initial points for the JEGA algorithm created and run by this [JEGAOptimizer](#).

Reimplemented from [Iterator](#).

**8.53.4 Member Data Documentation****8.53.4.1** [VariablesArray\\_initPts](#) [private]

An array of initial points to use as an initial population.

This member is here to help support the use of JEGA algorithms in [Dakota](#) strategies. If this array is populated, then whatever initializer is specified will be ignored and the `DoubleMatrix` initializer will be used instead on a matrix created from the data in this array.

The documentation for this class was generated from the following files:

- [JEGAOptimizer.H](#)
- [JEGAOptimizer.C](#)

## 8.54 JEGAOptimizer::Driver Class Reference

A subclass of the JEGA front end driver that exposes the individual protected methods to execute the algorithm.

### Public Member Functions

- GeneticAlgorithm \* [ExtractAllData](#) (const AlgorithmConfig &algConfig)  
*Reads all required data from the problem description database stored in the supplied algorithm config.*
- DesignOFSortSet [PerformIterations](#) (GeneticAlgorithm \*theGA)  
*Performs the required iterations on the supplied GA.*
- void [DestroyAlgorithm](#) (GeneticAlgorithm \*theGA)  
*Deletes the supplied GA.*
- [Driver](#) (const ProblemConfig &probConfig)  
*Default constructs a [Driver](#).*

### 8.54.1 Detailed Description

A subclass of the JEGA front end driver that exposes the individual protected methods to execute the algorithm.

This is necessary because DAKOTA requires that all problem information be extracted from the problem description DB at the time of [Optimizer](#) construction and the front end does it all in the execute algorithm method which must be called in find\_optimum.

### 8.54.2 Constructor & Destructor Documentation

#### 8.54.2.1 [Driver](#) (const ProblemConfig & *probConfig*) [inline]

Default constructs a [Driver](#).

#### Parameters:

*probConfig* The definition of the problem to be solved by this [Driver](#) whenever ExecuteAlgorithm is called.

The problem can be solved in multiple ways by multiple algorithms even using multiple different evaluators by issuing multiple calls to ExecuteAlgorithm with different AlgorithmConfigs.

### 8.54.3 Member Function Documentation

#### 8.54.3.1 GeneticAlgorithm\* ExtractAllData (const AlgorithmConfig & algConfig) [inline]

Reads all required data from the problem description database stored in the supplied algorithm config.

The returned GA is fully configured and ready to be run. It must also be destroyed at some later time. You MUST call DestroyAlgorithm for this purpose. Failure to do so could result in a memory leak and an eventual segmentation fault! Be sure to call DestroyAlgorithm prior to destroying the algorithm config that was used to create it!

This is just here to expose the base class method to users.

#### Parameters:

*algConfig* The fully loaded configuration object containing the database of parameters for the algorithm to be run on the known problem.

#### Returns:

The fully configured and loaded GA ready to be run using the PerformIterations method.

#### 8.54.3.2 DesignOFSortSet PerformIterations (GeneticAlgorithm \* theGA) [inline]

Performs the required iterations on the supplied GA.

This includes the calls to AlgorithmInitialize and AlgorithmFinalize and logs some information if appropriate.

This is just here to expose the base class method to users.

#### Parameters:

*theGA* The GA on which to perform iterations. This parameter must be non-null.

#### Returns:

The final solutions reported by the supplied GA after all iterations and call to AlgorithmFinalize.

#### 8.54.3.3 void DestroyAlgorithm (GeneticAlgorithm \* theGA) [inline]

Deletes the supplied GA.

Use this method to destroy a GA after all iterations have been run. This method knows if the log associated with the GA was created here and needs to be destroyed as well or not.

This is just here to expose the base class method to users.

Be sure to use this prior to destroying the algorithm config object which contains the target. The GA destructor needs the target to be in tact.

**Parameters:**

*data* The algorithm and associated logger that are no longer needed and thus must be destroyed.

The documentation for this class was generated from the following file:

- [JEGAOptimizer.C](#)

## 8.55 JEGAOptimizer::EvaluatorCreator Class Reference

A specialization of the JEGA::FrontEnd::EvaluatorCreator that creates a new instance of a Evaluator.

### Public Member Functions

- virtual GeneticAlgorithmEvaluator \* [CreateEvaluator](#) (GeneticAlgorithm &alg)  
*Overriden to return a newly created Evaluator.*
- [EvaluatorCreator](#) (Model &theModel)  
*Constructs an [EvaluatorCreator](#) using the supplied model and optimizer.*

### Private Attributes

- [Model](#) & [\\_theModel](#)  
*The user defined model to be passed to the constructor of the Evaluator.*

### 8.55.1 Detailed Description

A specialization of the JEGA::FrontEnd::EvaluatorCreator that creates a new instance of a Evaluator.

### 8.55.2 Constructor & Destructor Documentation

#### 8.55.2.1 [EvaluatorCreator](#) (Model & *theModel*) [inline]

Constructs an [EvaluatorCreator](#) using the supplied model and optimizer.

#### Parameters:

*theModel* The [Dakota::Model](#) this creator will pass to the created evaluator.

*theOptimizer* The [JEGAOptimizer](#) this creator will pass to the created evaluator.

### 8.55.3 Member Function Documentation

**8.55.3.1 virtual GeneticAlgorithmEvaluator\* CreateEvaluator (GeneticAlgorithm & *alg*)** [`inline`, `virtual`]

Overriden to return a newly created Evaluator.

The GA will assume ownership of the evaluator so we needn't worry about keeping track of it for destruction. The additional parameters needed by the Evaluator are stored as members of this class at construction time.

**Parameters:**

*alg* The GA for which the evaluator is to be created.

**Returns:**

A pointer to a newly created Evaluator.

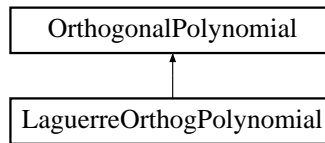
The documentation for this class was generated from the following file:

- [JEGAOptimizer.C](#)

## 8.56 LaguerreOrthogPolynomial Class Reference

Derived orthogonal polynomial class for Laguerre polynomials.

Inheritance diagram for LaguerreOrthogPolynomial::



### Public Member Functions

- [LaguerreOrthogPolynomial \(\)](#)  
*default constructor*
- [~LaguerreOrthogPolynomial \(\)](#)  
*destructor*

### Protected Member Functions

- const Real & [get\\_value](#) (const Real &x, size\_t n)  
*retrieve the Laguerre polynomial value for a given parameter x*
- const Real & [get\\_gradient](#) (const Real &x, size\_t n)  
*retrieve the Laguerre polynomial gradient for a given parameter x*
- const Real & [norm\\_squared](#) (size\_t n)  
*return the inner product  $\langle L_n, L_n \rangle = \|L_n\|^2$*
- const [RealVector](#) & [gauss\\_points](#) (size\_t n)  
*polynomial order n*
- const [RealVector](#) & [gauss\\_weights](#) (size\_t n)  
*polynomial order n*

### 8.56.1 Detailed Description

Derived orthogonal polynomial class for Laguerre polynomials.

The [LaguerreOrthogPolynomial](#) class evaluates a univariate Laguerre polynomial of a particular order. These polynomials are orthogonal with respect to the weight function  $\exp(-x)$  when integrated over the support range of  $[0,+\infty]$ . This corresponds to the probability density function for the standard exponential distribution. It enables (mixed) multidimensional orthogonal polynomial basis functions within [OrthogPolyApproximation](#). Laguerre polynomials are a special case ( $\alpha = 0$ ) of the generalized Laguerre polynomials (implemented separately) which correspond to the standard gamma distribution.

The documentation for this class was generated from the following files:

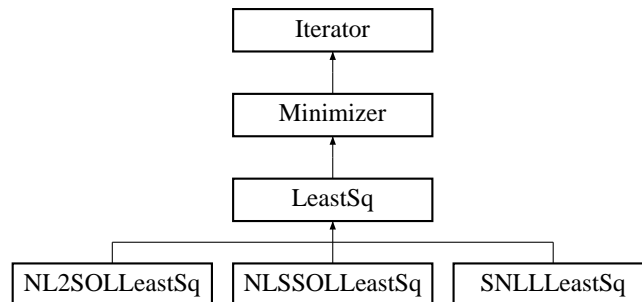
- [LaguerreOrthogPolynomial.H](#)
- [LaguerreOrthogPolynomial.C](#)



## 8.57 LeastSq Class Reference

Base class for the nonlinear least squares branch of the iterator hierarchy.

Inheritance diagram for LeastSq::



### Protected Member Functions

- [LeastSq \(\)](#)  
*default constructor*
- [LeastSq \(Model &model\)](#)  
*standard constructor*
- [~LeastSq \(\)](#)  
*destructor*
- void [run \(\)](#)  
*run the iterator; portion of [run\\_iterator\(\)](#)*
- void [print\\_results](#) (ostream &s) const
- void [derived\\_initialize\\_scaling](#) (StringArray &fn\_scale\_types, RealVector &fn\_scales)  
*respectively*
- void [derived\\_post\\_run \(\)](#)
- virtual void [minimize\\_residuals \(\)=0](#)  
*for the least squares branch.*
- void [read\\_observed\\_data \(\)](#)  
*read user data file to load observed data points*

## Static Protected Member Functions

- static void [primary\\_resp\\_recast](#) (const [Variables](#) &native\_vars, const [Variables](#) &scaled\_vars, const [Response](#) &native\_response, [Response](#) &scaled\_response)  
*from native (user) to iterator space*

## Protected Attributes

- int [numLeastSqTerms](#)  
*number of least squares terms*
- String [obsDataFilename](#)  
*filename from which to read observed data*
- bool [obsDataFlag](#)  
*flag indicating whether user-supplied data is active*
- [RealVector](#) [obsData](#)  
*storage for user-supplied data for computing residuals*

## Static Protected Attributes

- static [LeastSq](#) \* [leastSqInstance](#)  
*pointer to [LeastSq](#) instance used in static member functions*

### 8.57.1 Detailed Description

Base class for the nonlinear least squares branch of the iterator hierarchy.

The [LeastSq](#) class provides common data and functionality for [NLSSOLLeastSq](#) and [SNLLLeastSq](#).

### 8.57.2 Constructor & Destructor Documentation

#### 8.57.2.1 [LeastSq](#) ([Model](#) & *model*) [protected]

standard constructor

This constructor extracts the inherited data for the least squares branch and performs sanity checking on gradient and constraint settings.

### 8.57.3 Member Function Documentation

#### 8.57.3.1 void run () [inline, protected, virtual]

run the iterator; portion of [run\\_iterator\(\)](#)

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented from [Iterator](#).

#### 8.57.3.2 void print\_results (ostream & s) const [protected, virtual]

Redefines default iterator results printing to include nonlinear least squares results (residual terms and constraints).

Reimplemented from [Iterator](#).

#### 8.57.3.3 void derived\_post\_run () [protected, virtual]

Implements portions of `post_run` specific to [LeastSq](#) for scaling back to native variables and functions

Reimplemented from [Iterator](#).

Reimplemented in [SNLLLeastSq](#).

#### 8.57.3.4 void primary\_resp\_recast (const Variables & native\_vars, const Variables & scaled\_vars, const Response & native\_response, Response & iterator\_response) [static, protected]

from native (user) to iterator space

Least squares function map from user/native space to iterator/scaled space using a [RecastModel](#). If no scaling also copies constraints.

#### 8.57.3.5 void read\_observed\_data () [protected]

read user data file to load observed data points

read user's observation data for computation of least squares residuals (currently reading on all processors – need to read once and broadcast)

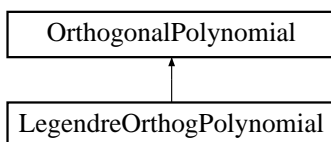
The documentation for this class was generated from the following files:

- [DakotaLeastSq.H](#)
- [DakotaLeastSq.C](#)

## 8.58 LegendreOrthogPolynomial Class Reference

Derived orthogonal polynomial class for Legendre polynomials.

Inheritance diagram for LegendreOrthogPolynomial::



### Public Member Functions

- [LegendreOrthogPolynomial\(\)](#)  
*default constructor*
- [~LegendreOrthogPolynomial\(\)](#)  
*destructor*

### Protected Member Functions

- `const Real & get\_value (const Real &x, size_t n)`  
*retrieve the Legendre polynomial value for a given parameter  $x$*
- `const Real & get\_gradient (const Real &x, size_t n)`  
*retrieve the Legendre polynomial gradient for a given parameter  $x$*
- `const Real & norm\_squared (size_t n)`  
*return the inner product  $\langle P_n, P_n \rangle = \|P_n\|^2$*
- `const RealVector & gauss\_points (size_t n)`  
*polynomial order  $n$*
- `const RealVector & gauss\_weights (size_t n)`  
*polynomial order  $n$*

### 8.58.1 Detailed Description

Derived orthogonal polynomial class for Legendre polynomials.

The [LegendreOrthogPolynomial](#) class evaluates a univariate Legendre polynomial of a particular order. These polynomials are orthogonal with respect to the weight function 1 when integrated over the support range of  $[-1,+1]$ . This corresponds to the probability density function  $f(x) = 1/(U-L) = 1/2$  for the uniform distribution for  $[L,U]=[-1,1]$ . It enables (mixed) multidimensional orthogonal polynomial basis functions within [OrthogPolyApproximation](#). Legendre polynomials are a special case ( $\alpha = \beta = 0$ ) of the more general Jacobi polynomials (implemented separately) which correspond to the beta distribution.

The documentation for this class was generated from the following files:

- LegendreOrthogPolynomial.H
- LegendreOrthogPolynomial.C

## 8.59 List Class Template Reference

Template class for the [Dakota](#) bookkeeping list.

### Public Member Functions

- [List](#) ()  
*Default constructor.*
- [List](#) (const [List](#)< T > &a)  
*Copy constructor.*
- [~List](#) ()  
*Destructor.*
- template<class InputIter> [List](#) (InputIter first, InputIter last)  
*Range constructor (member template).*
- [List](#)< T > & [operator=](#) (const [List](#)< T > &a)  
*assignment operator*
- void [write](#) (ostream &s) const  
*Writes a [List](#) to an output stream.*
- void [read](#) ([MPIUnpackBuffer](#) &s)  
*Reads a [List](#) from an [MPIUnpackBuffer](#) after an MPI receive.*
- void [write](#) ([MPIPackBuffer](#) &s) const  
*Writes a [List](#) to a [MPIPackBuffer](#) prior to an MPI send.*
- size\_t [entries](#) () const  
*Returns the number of items that are currently in the list.*
- T [get](#) ()  
*Removes and returns the first item in the list.*
- T [removeAt](#) (size\_t index)  
*Removes and returns the item at the specified index.*
- bool [remove](#) (const T &a)  
*Removes the specified item from the list.*

- void `insert` (const T &a)  
*Adds the item a to the end of the list.*
- bool `contains` (const T &a) const  
*Returns TRUE if list contains object a, returns FALSE otherwise.*
- bool `find` (bool(\*test\_fn)(const T &, const void \*), const void \*test\_fn\_data, T &found\_item) const  
*function finds and sets k to this object*
- `List< T >::iterator find` (bool(\*test\_fn)(const T &, const void \*), const void \*test\_fn\_data)  
*function finds*
- `size_t index` (bool(\*test\_fn)(const T &, const void \*), const void \*test\_fn\_data) const  
*Returns the index of object that the user defined test function finds.*
- `size_t index` (const T &a) const  
*Returns the index of the object.*
- `size_t count` (const T &a) const  
*Returns the number of items in the list equal to object.*
- T & `operator[]` (size\_t i)  
*Returns the object at index i (can use as lvalue).*
- const T & `operator[]` (size\_t i) const  
*Returns the object at index i, const (can't use as lvalue).*

### 8.59.1 Detailed Description

`template<class T> class Dakota::List< T >`

Template class for the `Dakota` bookkeeping list.

The `List` is the common list class for `Dakota`. It inherits from either the RW list class or the STL list class. Extends the base list class to add `Dakota` specific methods Builds upon the previously existing `DakotaValList` class

### 8.59.2 Member Function Documentation

#### 8.59.2.1 T get ()

Removes and returns the first item in the list.

Remove and return item from front of list. Returns the object pointed to by the `list::begin()` iterator. It also deletes the first node by calling the `list::pop_front()` method. Note: `get()` is not the same as `list::front()` since the latter would return the 1st item but would not delete it.

#### 8.59.2.2 `T removeAt (size_t index)`

Removes and returns the item at the specified index.

Removes the item at the index specified. Uses the STL `advance()` function to step to the appropriate position in the list and then calls the `list::erase()` method.

#### 8.59.2.3 `bool remove (const T & a)`

Removes the specified item from the list.

Removes the first instance matching object `a` from the list (and therefore differs from the STL `list::remove()` which removes all instances). Uses the STL `find()` algorithm to find the object and the `list::erase()` method to perform the remove.

#### 8.59.2.4 `void insert (const T & a) [inline]`

Adds the item `a` to the end of the list.

Insert item at end of list, calls `list::push_back()` method.

#### 8.59.2.5 `bool contains (const T & a) const [inline]`

Returns TRUE if list contains object `a`, returns FALSE otherwise.

Uses the STL `find()` algorithm to locate the first instance of object `a`. Returns true if an instance is found.

#### 8.59.2.6 `bool find (bool(*)(const T &, const void *) test_fn, const void * test_fn_data, T & found_item) const`

function finds and sets `k` to this object

Find the first item in the list which satisfies the test function. Sets `k` if the object is found.

#### 8.59.2.7 `List< T >::iterator find (bool(*)(const T &, const void *) test_fn, const void * test_fn_data)`

function finds

Find the first item in the list which satisfies the test function and return an iterator pointing to it.

#### 8.59.2.8 `size_t index (bool(*)(const T &, const void *) test_fn, const void * test_fn_data) const`

Returns the index of object that the user defined test function finds.



Returns the index of the first item in the list which satisfies the test function. Uses a single list traversal to both locate the object and return its index (generic algorithms would require two loop traversals).

#### 8.59.2.9 `size_t index (const T & a) const`

Returns the index of the object.

Returns the index of the first item in the list which matches the object `a`. Uses a single list traversal to both locate the object and return its index (generic algorithms would require two loop traversals).

#### 8.59.2.10 `size_t count (const T & a) const [inline]`

Returns the number of items in the list equal to object.

Uses the STL `count()` algorithm to return the number of occurrences of the specified object.

#### 8.59.2.11 `]`

`T & operator[] (size_t i)`

Returns the object at index `i` (can use as lvalue).

Returns item at position `i` of the list by stepping through the list using forward or reverse STL iterators (depending on which end of the list is closer to the desired item). Once the object is found, it returns the value pointed to by the iterator.

This functionality is inefficient in `0->len` loop-based list traversals and is being replaced by iterator-based list traversals in the main DAKOTA code. For isolated look-ups of a particular index, however, this approach is acceptable.

#### 8.59.2.12 `]`

`const T & operator[] (size_t i) const`

Returns the object at index `i`, `const` (can't use as lvalue).

Returns `const` item at position `i` of the list by stepping through the list using forward or reverse STL iterators (depending on which end of the list is closer to the desired item). Once the object is found it returns the value pointed to by the iterator.

This functionality is inefficient in `0->len` loop-based list traversals and is being replaced by iterator-based list traversals in the main DAKOTA code. For isolated look-ups of a particular index, however, this approach is acceptable.

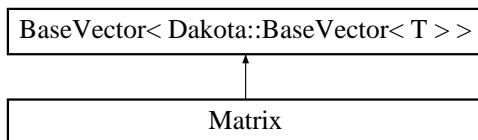
The documentation for this class was generated from the following file:

- `DakotaList.H`

## 8.60 Matrix Class Template Reference

Template class for the [Dakota](#) numerical matrix.

Inheritance diagram for Matrix::



### Public Member Functions

- [Matrix](#) (size\_t num\_rows=0, size\_t num\_cols=0)  
*Constructor, takes number of rows, and number of columns as arguments.*
- [~Matrix](#) ()  
*Destructor.*
- [Matrix< T > & operator=](#) (const T &ival)  
*Sets all elements in the matrix to ival.*
- [size\\_t num\\_rows](#) () const  
*Returns the number of rows for the matrix.*
- [size\\_t num\\_columns](#) () const  
*Returns the number of columns for the matrix.*
- void [reshape\\_2d](#) (size\_t num\_rows, size\_t num\_cols)  
*Resizes the matrix to num\_rows by num\_cols.*
- void [read](#) (istream &s, size\_t nr, size\_t nc)  
*Reads a portion of the [Matrix](#) from an input stream.*
- void [read](#) (istream &s)  
*Reads the complete [Matrix](#) from an input stream.*
- void [read\\_row\\_vector](#) (istream &s, size\_t i, size\_t nc)  
*Reads a portion of the *ith* [Matrix](#) row vector from an input stream.*
- void [read\\_row\\_vector](#) (istream &s, size\_t i)  
*Reads the *ith* [Matrix](#) row vector from an input stream.*

- void `write` (ostream &s, size\_t nr, size\_t nc, bool brackets, bool row\_rtn, bool final\_rtn) const  
*Writes a portion of the `Matrix` to an output stream.*
- void `write` (ostream &s, bool brackets, bool row\_rtn, bool final\_rtn) const  
*Writes the complete `Matrix` to an output stream.*
- void `write_row_vector` (ostream &s, size\_t i, size\_t nc, bool brackets, bool break\_line, bool final\_rtn) const  
*Writes a portion of the `i`th `Matrix` row vector to an output stream.*
- void `write_row_vector` (ostream &s, size\_t i, bool brackets, bool break\_line, bool final\_rtn) const  
*Writes the `i`th `Matrix` row vector to an output stream.*
- void `read` (BiStream &s, size\_t nr, size\_t nc)  
*Reads a portion of the `Matrix` from a binary input stream.*
- void `read` (BiStream &s)  
*Reads the complete `Matrix` from a binary input stream.*
- void `read_row_vector` (BiStream &s, size\_t i, size\_t nc)  
*Reads a portion of the `i`th `Matrix` row vector from a binary input stream.*
- void `read_row_vector` (BiStream &s, size\_t i)  
*Reads the `i`th `Matrix` row vector from a binary input stream.*
- void `write` (BoStream &s, size\_t nr, size\_t nc) const  
*Writes a portion of the `Matrix` to a binary output stream.*
- void `write` (BoStream &s) const  
*Writes the complete `Matrix` to a binary output stream.*
- void `write_row_vector` (BoStream &s, size\_t i, size\_t nc) const  
*Writes a portion of the `i`th `Matrix` row vector to a binary output stream.*
- void `write_row_vector` (BoStream &s, size\_t i) const  
*Writes the `i`th `Matrix` row vector to a binary output stream.*
- void `read` (MPIUnpackBuffer &s)  
*Reads a `Matrix` from an `MPIUnpackBuffer` after an MPI receive.*
- void `read_annotated` (MPIUnpackBuffer &s)  
*Reads an annotated `Matrix` from an `MPIUnpackBuffer` after an MPI receive.*
- void `read_row_vector` (MPIUnpackBuffer &s, size\_t i)  
*Reads the `i`th `Matrix` row vector from an `MPIUnpackBuffer` after an MPI recv.*

- void [write](#) ([MPIPackBuffer](#) &s) const  
*Writes a [Matrix](#) to a [MPIPackBuffer](#) prior to an MPI send.*
- void [write\\_annotated](#) ([MPIPackBuffer](#) &s) const  
*Writes an annotated [Matrix](#) to a [MPIPackBuffer](#) prior to an MPI send.*
- void [write\\_row\\_vector](#) ([MPIPackBuffer](#) &s, size\_t i) const  
*Writes the *i*th [Matrix](#) row vector to a [MPIPackBuffer](#) prior to an MPI send.*

### 8.60.1 Detailed Description

`template<class T> class Dakota::Matrix< T >`

Template class for the [Dakota](#) numerical matrix.

A matrix class template to provide 2D arrays of objects. The matrix is zero-based, rows: 0 to (numRows-1) and cols: 0 to (numColumns-1). The class supports overloading of the subscript operator allowing it to emulate a normal built-in 2D array type. [Matrix](#) relies on the [BaseVector](#) template class to manage any differences between underlying DAKOTA\_BASE\_VECTOR implementations (RW, STL, etc.).

### 8.60.2 Member Function Documentation

#### 8.60.2.1 [Matrix](#)< T > & operator=(const T & val) [inline]

Sets all elements in the matrix to ival.

calls base class operator=(ival)

Reimplemented from [BaseVector](#).

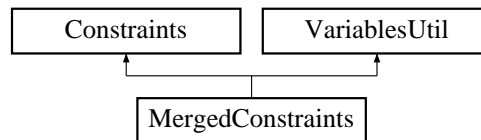
The documentation for this class was generated from the following file:

- DakotaMatrix.H

## 8.61 MergedConstraints Class Reference

the merged data view.

Inheritance diagram for MergedConstraints::



### Public Member Functions

- [MergedConstraints \(\)](#)  
*default constructor*
- [MergedConstraints \(const ProblemDescDB &problem\\_db, const pair< short, short > &view\)](#)  
*standard constructor*
- [~MergedConstraints \(\)](#)  
*destructor*
- [const RealVector & continuous\\_lower\\_bounds \(\) const](#)  
*return the active continuous variable lower bounds*
- [void continuous\\_lower\\_bounds \(const RealVector &c\\_l\\_bnds\)](#)  
*set the active continuous variable lower bounds*
- [const RealVector & continuous\\_upper\\_bounds \(\) const](#)  
*return the active continuous variable upper bounds*
- [void continuous\\_upper\\_bounds \(const RealVector &c\\_u\\_bnds\)](#)  
*set the active continuous variable upper bounds*
- [const RealVector & inactive\\_continuous\\_lower\\_bounds \(\) const](#)  
*return the inactive continuous lower bounds*
- [void inactive\\_continuous\\_lower\\_bounds \(const RealVector &i\\_c\\_l\\_bnds\)](#)  
*set the inactive continuous lower bounds*
- [const RealVector & inactive\\_continuous\\_upper\\_bounds \(\) const](#)  
*return the inactive continuous upper bounds*

- void `inactive_continuous_upper_bounds` (const `RealVector` &i\_c\_u\_bnds)  
*set the inactive continuous upper bounds*
- `RealVector` `all_continuous_lower_bounds` () const  
*returns a single array with all continuous lower bounds*
- void `all_continuous_lower_bounds` (const `RealVector` &a\_c\_l\_bnds)  
*sets all continuous lower bounds using a single array*
- `RealVector` `all_continuous_upper_bounds` () const  
*returns a single array with all continuous upper bounds*
- void `all_continuous_upper_bounds` (const `RealVector` &a\_c\_u\_bnds)  
*sets all continuous upper bounds using a single array*
- void `write` (ostream &s) const  
*write a variable constraints object to an ostream*
- void `read` (istream &s)  
*read a variable constraints object from an istream*

### Protected Member Functions

- void `copy_rep` (const `Constraints` \*con\_rep)  
*Used by `copy()` to copy the contents of a letter class.*
- void `reshape_rep` (const `Sizet2DArray` &vars\_comps)  
*Used by `reshape(Sizet2DArray&)` to reshape the contents of a letter class.*

### Private Attributes

- `RealVector` `mergedDesignLowerBnds`  
*domains (integer values promoted to reals)*
- `RealVector` `mergedDesignUpperBnds`  
*domains (integer values promoted to reals)*
- `RealVector` `uncertainLowerBnds`  
*uncertain to merge)*
- `RealVector` `uncertainUpperBnds`  
*uncertain to merge)*

- [RealVector mergedStateLowerBnds](#)  
*domains (integer values promoted to reals)*
- [RealVector mergedStateUpperBnds](#)  
*domains (integer values promoted to reals)*

### 8.61.1 Detailed Description

the merged data view.

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [MergedConstraints](#) derived class combines continuous and discrete domain types but separates design, uncertain, and state variable types. The result is merged design bounds arrays ([mergedDesignLowerBnds](#), [mergedDesignUpperBnds](#)), uncertain distribution bounds arrays ([uncertainLowerBnds](#), [uncertainUpperBnds](#)), and merged state bounds arrays ([mergedStateLowerBnds](#), [mergedStateUpperBnds](#)). The branch and bound strategy uses this approach (see [Variables::get\\_variables\(problem\\_db\)](#) for variables type selection; variables type is passed to the [Constraints](#) constructor in [Model](#)).

### 8.61.2 Constructor & Destructor Documentation

#### 8.61.2.1 [MergedConstraints](#) (const [ProblemDescDB](#) & *problem\_db*, const pair< short, short > & *view*)

standard constructor

In this class, a merged data approach is used in which continuous and discrete arrays are combined into a single continuous array (integrality is relaxed; the converse of truncating reals is not currently supported but could be in the future if needed). Iterators/strategies which use this class include: [BranchBndStrategy](#). Extract fundamental lower and upper bounds and merge continuous and discrete domains to create [mergedDesignLowerBnds](#), [mergedDesignUpperBnds](#), [mergedStateLowerBnds](#), and [mergedStateUpperBnds](#) using utilities from [VariablesUtil](#) (uncertain distribution bounds do not require any merging).

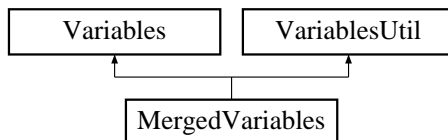
The documentation for this class was generated from the following files:

- [MergedConstraints.H](#)
- [MergedConstraints.C](#)

## 8.62 MergedVariables Class Reference

merged data view.

Inheritance diagram for MergedVariables::



### Public Member Functions

- [MergedVariables \(\)](#)  
*default constructor*
- [MergedVariables \(const ProblemDescDB &problem\\_db, const pair< short, short > &view\)](#)  
*standard constructor*
- [~MergedVariables \(\)](#)  
*destructor*
- `size_t tv () const`  
*Returns total number of vars.*
- `const IntArray & merged_discrete_ids () const`  
*returns the list of discrete variables merged into a continuous array*
- `const RealVector & continuous_variables () const`  
*return the active continuous variables*
- `void continuous_variables (const RealVector &c_vars)`  
*set the active continuous variables*
- `const StringArray & continuous_variable_labels () const`  
*return the active continuous variable labels*
- `void continuous_variable_labels (const StringArray &c_v_labels)`  
*set the active continuous variable labels*
- `const RealVector & inactive_continuous_variables () const`  
*return the inactive continuous variables*



- void `inactive_continuous_variables` (const `RealVector` &i\_c\_vars)  
*set the inactive continuous variables*
- const `StringArray` & `inactive_continuous_variable_labels` () const  
*return the inactive continuous variable labels*
- void `inactive_continuous_variable_labels` (const `StringArray` &i\_c\_v\_labels)  
*set the inactive continuous variable labels*
- size\_t `acv` () const  
*returns total number of continuous vars*
- `RealVector` `all_continuous_variables` () const  
*returns a single array with all continuous variables*
- void `all_continuous_variables` (const `RealVector` &a\_c\_vars)  
*sets all continuous variables using a single array*
- `StringArray` `all_continuous_variable_labels` () const  
*returns a single array with all continuous variable labels*
- void `all_continuous_variable_labels` (const `StringArray` &a\_c\_v\_labels)  
*sets all continuous variable labels using a single array*
- `StringArray` `all_variable_labels` () const  
*returns a single array with all variable labels*
- void `read` (istream &s)  
*read a variables object from an istream*
- void `write` (ostream &s) const  
*write a variables object to an ostream*
- void `write_aprepro` (ostream &s) const  
*write a variables object to an ostream in aprepro format*
- void `read_annotated` (istream &s)  
*read a variables object in annotated format from an istream*
- void `write_annotated` (ostream &s) const  
*write a variables object in annotated format to an ostream*
- void `write_tabular` (ostream &s) const  
*write a variables object in tabular format to an ostream*

- void [read](#) ([BiStream](#) &s)  
*read a variables object from the binary restart stream*
- void [write](#) ([BoStream](#) &s) const  
*write a variables object to the binary restart stream*
- void [read](#) ([MPIUnpackBuffer](#) &s)  
*read a variables object from a packed MPI buffer*
- void [write](#) ([MPIPackBuffer](#) &s) const  
*write a variables object to a packed MPI buffer*

### Protected Member Functions

- void [copy\\_rep](#) (const [Variables](#) \*vars\_rep)  
*Used by [copy\(\)](#) to copy the contents of a letter class.*
- void [reshape\\_rep](#) (const [Sizet2DArray](#) &vars\_comps)  
*Used by [reshape\(\)](#) to reshape the contents of a letter class.*

### Private Member Functions

- void [build\\_types\\_ids](#) ()  
*construct [VarTypes](#) and [VarIds](#) arrays using [variablesComponents](#)*

### Private Attributes

- [RealVector](#) [mergedDesignVars](#)  
*domains (discrete values promoted to continuous)*
- [RealVector](#) [uncertainVars](#)  
*the uncertain variables array (no discrete uncertain to merge)*
- [RealVector](#) [mergedStateVars](#)  
*domains (discrete values promoted to continuous)*
- [StringArray](#) [mergedDesignLabels](#)  
*a label array combining continuous and discrete design labels*
- [StringArray](#) [uncertainLabels](#)  
*the uncertain variables label array (no discrete uncertain to combine)*

- [StringArray mergedStateLabels](#)  
*a label array combining continuous and discrete state labels*
- [IntArray mergedDiscreteIds](#)  
*requirement is relaxed by merging them into a continuous array*

## Friends

- `bool operator==(const MergedVariables &vars1, const MergedVariables &vars2)`  
*equality operator*

### 8.62.1 Detailed Description

merged data view.

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [MergedVariables](#) derived class combines continuous and discrete domain types but separates design, uncertain, and state variable types. The result is a single continuous array of design variables (`mergedDesignVars`), a single continuous array of uncertain variables (`uncertainVars`), and a single continuous array of state variables (`mergedStateVars`). The branch and bound strategy uses this approach (see `Variables::get_variables(problem_db)`).

### 8.62.2 Constructor & Destructor Documentation

#### 8.62.2.1 [MergedVariables](#) (const [ProblemDescDB](#) & *problem\_db*, const pair< short, short > & *view*)

standard constructor

In this class, a merged data approach is used in which continuous and discrete arrays are combined into a single continuous array (integrality is relaxed; the converse of truncating reals is not currently supported but could be in the future if needed). Iterators/strategies which use this class include: `BranchBndStrategy`. Extract fundamental variable types and labels and merge continuous and discrete domains to create `mergedDesignVars`, `mergedStateVars`, `mergedDesignLabels`, and `mergedStateLabels` using utilities from [VariablesUtil](#) (uncertain variables and labels do not require any merging).

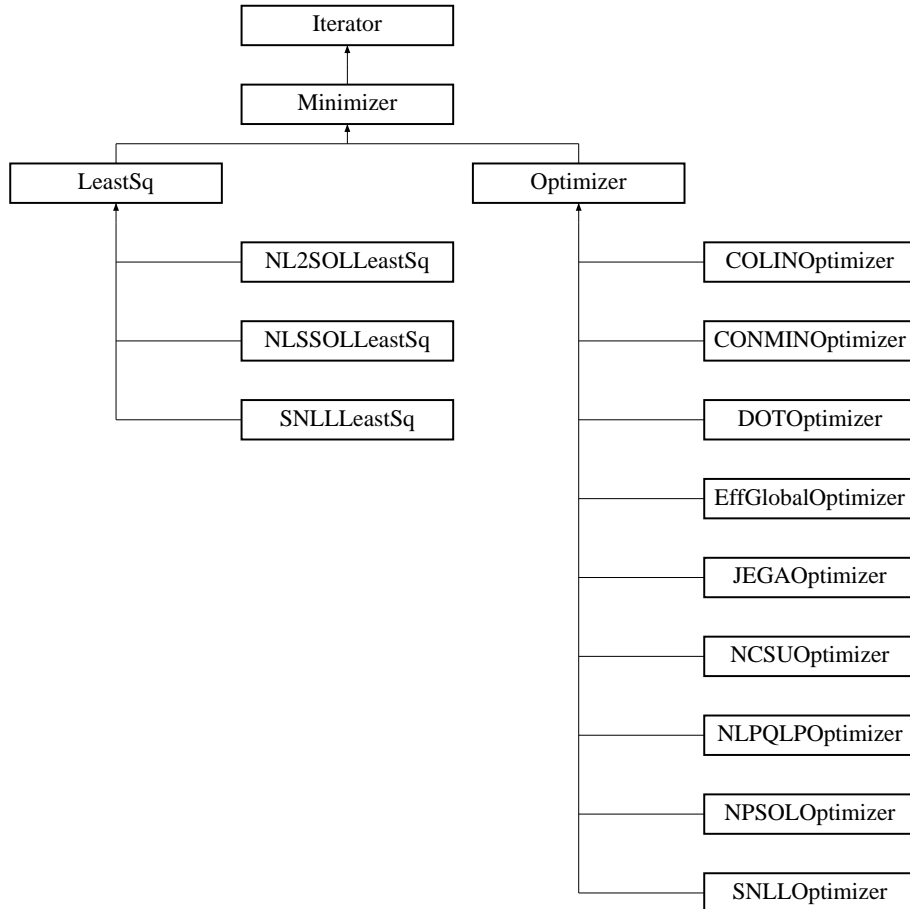
The documentation for this class was generated from the following files:

- `MergedVariables.H`
- `MergedVariables.C`

## 8.63 Minimizer Class Reference

iterator hierarchy.

Inheritance diagram for Minimizer::



### Public Member Functions

- `const Variables & variables_results () const`  
*return a single final iterator solution (variables)*
- `const Response & response_results () const`  
*return a single final iterator solution (response)*
- `const VariablesArray & variables_array_results () const`

*return multiple final iterator solutions (variables)*

- const [ResponseArray](#) & [response\\_array\\_results](#) () const  
*return multiple final iterator solutions (response)*

## Protected Member Functions

- [Minimizer](#) ()  
*default constructor*
- [Minimizer](#) ([Model](#) &model)  
*standard constructor*
- [Minimizer](#) ([NoDBBaseConstructor](#), [Model](#) &model)  
*alternate constructor for "on the fly" instantiations*
- [Minimizer](#) ([NoDBBaseConstructor](#), size\_t num\_lin\_ineq, size\_t num\_lin\_eq, size\_t num\_nln\_ineq, size\_t num\_nln\_eq)  
*alternate constructor for "on the fly" instantiations*
- [~Minimizer](#) ()  
*destructor*
- void [response\\_results\\_active\\_set](#) (const [ActiveSet](#) &set)  
*set the requested data for the final iterator response results*
- virtual void [derived\\_initialize\\_scaling](#) ([StringArray](#) &fn\_scale\_types, [RealVector](#) &fn\_scales)=0  
*respectively*
- void [initialize\\_scaling](#) ()  
*checking*
- void [compute\\_scaling](#) (int object\_type, int auto\_type, int num\_vars, [RealVector](#) &lbs, [RealVector](#) &ubs, [RealVector](#) &targets, const [StringArray](#) &scale\_strings, const [RealVector](#) &scales, [IntVector](#) &scale\_types, [RealVector](#) &scale\_mults, [RealVector](#) &scale\_offsets)  
*vector of variables, functions, constraints, etc.*
- bool [compute\\_scale\\_factor](#) (const Real lower\_bound, const Real upper\_bound, Real \*multiplier, Real \*offset)  
*automatically compute a single scaling factor – bounds case*
- bool [compute\\_scale\\_factor](#) (const Real target, Real \*multiplier)  
*automatically compute a single scaling factor – target case*

- [RealVector modify\\_n2s](#) (const [RealVector](#) &native\_vars, const [IntVector](#) &scale\_types, const [RealVector](#) &multipliers, const [RealVector](#) &offsets) const  
*general RealVector mapping from native to scaled variables vectors:*
- [RealVector modify\\_s2n](#) (const [RealVector](#) &scaled\_vars, const [IntVector](#) &scale\_types, const [RealVector](#) &multipliers, const [RealVector](#) &offsets) const  
*general RealVector mapping from scaled to native variables:*
- void [response\\_modify\\_n2s](#) (const [Variables](#) &scaled\_vars, const [Response](#) &native\_response, [Response](#) &scaled\_response, int native\_offset, int recast\_offset, int num\_responses) const  
*map responses from native to scaled variable space*
- [RealMatrix lin\\_coeffs\\_modify\\_n2s](#) (const [RealMatrix](#) &native\_coeffs, const [RealVector](#) &cv\_multipliers, const [RealVector](#) &lin\_multipliers) const  
*general linear coefficients mapping from native to scaled space*

## Static Protected Member Functions

- static void [variables\\_recast](#) (const [Variables](#) &scaled\_vars, [Variables](#) &native\_vars)  
*variables from scaled to native (user) space*
- static void [secondary\\_resp\\_recast](#) (const [Variables](#) &native\_vars, const [Variables](#) &scaled\_vars, const [Response](#) &native\_response, [Response](#) &scaled\_response)  
*transform constraints (fns, grads, Hessians) from native (user) to*

## Protected Attributes

- Real [constraintTol](#)  
*optimizer/least squares constraint tolerance*
- Real [bigRealBoundSize](#)  
*cutoff value for inequality constraint and continuous variable bounds*
- int [bigIntBoundSize](#)  
*cutoff value for discrete variable bounds*
- size\_t [numNonlinearIneqConstraints](#)  
*number of nonlinear inequality constraints*
- size\_t [numNonlinearEqConstraints](#)  
*number of nonlinear equality constraints*
- size\_t [numLinearIneqConstraints](#)

- number of linear inequality constraints*
- `size_t numLinearEqConstraints`  
*number of linear equality constraints*
- `int numNonlinearConstraints`  
*total number of nonlinear constraints*
- `int numLinearConstraints`  
*total number of linear constraints*
- `int numConstraints`  
*total number of linear and nonlinear constraints*
- `bool boundConstraintFlag`  
*constraints. Used for method selection and error checking.*
- `bool speculativeFlag`  
*flag for speculative gradient evaluations*
- `size_t numUserFnsLsq`  
*number of objective functions of least squares terms in the user's model*
- `size_t numIterFnsLsq`  
*number of objective functions of least squares terms in iterator's view*
- `bool scaleFlag`  
*flag indicating scaling status*
- `IntVector cvScaleTypes`  
*scale flags for continuous vars.*
- `RealVector cvScaleMultipliers`  
*scales for continuous variables*
- `RealVector cvScaleOffsets`  
*offsets for continuous variables*
- `IntVector responseScaleTypes`  
*scale flags for all responses*
- `RealVector responseScaleMultipliers`  
*scales for all responses*
- `RealVector responseScaleOffsets`  
*offsets for all responses (zero for functions, not for nonlin con)*

- [IntVector linearIneqScaleTypes](#)  
*scale flags for linear ineq*
- [RealVector linearIneqScaleMultipliers](#)  
*scales for linear ineq constrs.*
- [RealVector linearIneqScaleOffsets](#)  
*offsets for linear ineq constrs.*
- [IntVector linearEqScaleTypes](#)  
*scale flags for linear eq.*
- [RealVector linearEqScaleMultipliers](#)  
*scales for linear constraints*
- [RealVector linearEqScaleOffsets](#)  
*offsets for linear constraints*
- `bool vendorNumericalGradFlag`  
*convenience flag for gradType == numerical && methodSource == vendor*
- [Variables bestVariables](#)  
*best variables found in minimization*
- [RealVector bestFunctions](#)  
*best function values found in minimization; used in multiobjective/scaling cases*
- [Response bestResponses](#)  
*best responses found in minimization*
- [VariablesArray bestVariablesArray](#)  
*collection of all best solution variables.*
- [ResponseArray bestResponseArray](#)  
*collection of all best solution responses.*

## Static Protected Attributes

- `static Minimizer * minimizerInstance`  
*pointer to [Minimizer](#) used in static member functions*



## Friends

- class [SOLBase](#)  
*access to iterator hierarchy data (to avoid attribute replication)*
- class [SNLLBase](#)  
*access to iterator hierarchy data (to avoid attribute replication)*

### 8.63.1 Detailed Description

iterator hierarchy.

The [Minimizer](#) class provides common data and functionality for [Optimizer](#) and [LeastSq](#).

### 8.63.2 Constructor & Destructor Documentation

#### 8.63.2.1 [Minimizer \(Model & model\)](#) [protected]

standard constructor

This constructor extracts inherited data for the optimizer and least squares branches and performs sanity checking on constraint settings.

### 8.63.3 Member Function Documentation

#### 8.63.3.1 `void initialize_scaling()` [protected]

checking

helper function used in constructors of derived classes to set up scaling types, multipliers and offsets when input scaling flag is enabled; includes call to the derived class' [derived\\_initialize\\_scaling\(\)](#)

#### 8.63.3.2 `void variables_recast(const Variables & scaled_vars, Variables & native_vars)` [static, protected]

variables from scaled to native (user) space

[Variables](#) map from iterator/scaled space to user/native space using a [RecastModel](#).

**8.63.3.3** `void secondary_resp_recast (const Variables & native_vars, const Variables & scaled_vars, const Response & native_response, Response & iterator_response) [static, protected]`

transform constraints (fns, grads, Hessians) from native (user) to

Constraint function map from user/native space to iterator/scaled/combined space using a [RecastModel](#).

**8.63.3.4** `RealVector modify_n2s (const RealVector & native_vars, const IntVector & scale_types, const RealVector & multipliers, const RealVector & offsets) const [protected]`

general [RealVector](#) mapping from native to scaled variables vectors:

general [RealVector](#) mapping from native to scaled variables; loosely, in greatest generality:  $\text{scaled\_var} = \log(\text{native\_var} - \text{offset}) / \text{multiplier}$

**8.63.3.5** `RealVector modify_s2n (const RealVector & scaled_vars, const IntVector & scale_types, const RealVector & multipliers, const RealVector & offsets) const [protected]`

general [RealVector](#) mapping from scaled to native variables:

general [RealVector](#) mapping from scaled to native variables; loosely, in greatest generality:  $\text{scaled\_var} = (\text{LOG\_BASE}^{\text{scaled\_var}}) * \text{multiplier} + \text{offset}$

**8.63.3.6** `void response_modify_n2s (const Variables & native_vars, const Response & native_response, Response & recast_response, int native_offset, int recast_offset, int num_responses) const [protected]`

map responses from native to scaled variable space

scaling response mapping: modifies response from a model (user/native) for use in iterators (scaled) – not including `multi_objective_modify`

**8.63.3.7** `RealMatrix lin_coeffs_modify_n2s (const RealMatrix & src_coeffs, const RealVector & cv_multipliers, const RealVector & lin_multipliers) const [protected]`

general linear coefficients mapping from native to scaled space

compute scaled linear constraint matrix given design variable multipliers and linear scaling multipliers. Only scales components corresponding to continuous variables so for `src_coeffs` of size  $M \times N$ , `lin_multipliers.size() <= M`, `cv_multipliers.size() <= N`

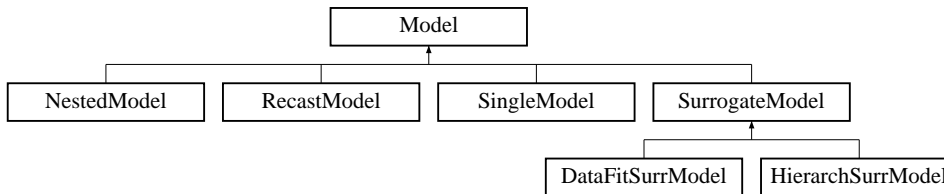
The documentation for this class was generated from the following files:

- `DakotaMinimizer.H`
- `DakotaMinimizer.C`

## 8.64 Model Class Reference

Base class for the model class hierarchy.

Inheritance diagram for Model::



### Public Member Functions

- [Model](#) ()  
*default constructor*
- [Model](#) ([ProblemDescDB](#) &problem\_db)  
*standard constructor for envelope*
- [Model](#) (const [Model](#) &model)  
*copy constructor*
- virtual [~Model](#) ()  
*destructor*
- [Model operator=](#) (const [Model](#) &model)  
*assignment operator*
- virtual [Iterator](#) & [subordinate\\_iterator](#) ()  
*return the sub-iterator in nested and surrogate models*
- virtual [Model](#) & [surrogate\\_model](#) ()  
*return the approximation sub-model in surrogate models*
- virtual [Model](#) & [truth\\_model](#) ()  
*return the truth sub-model in surrogate models*
- virtual void [derived\\_subordinate\\_models](#) ([ModelList](#) &ml, bool recurse\_flag)  
*portion of [subordinate\\_models](#)() specific to derived model classes*

- virtual void `update_from_subordinate_model` (bool recurse\_flag=true)  
*propagate vars/labels/bounds/targets from the bottom up*
- virtual `Interface` & `interface` ()  
*or `NestedModel::optionalInterface`*
- virtual void `surrogate_bypass` (bool bypass\_flag)  
*models contained within this model*
- virtual void `surrogate_function_indices` (const `IntSet` &surr\_fn\_indices)  
*set the (currently active) surrogate function index set*
- virtual void `build_approximation` ()  
*build a new `SurrogateModel` approximation*
- virtual bool `build_approximation` (const `Variables` &vars, const `Response` &response)  
*response at vars*
- virtual void `update_approximation` (const `Variables` &vars, const `Response` &response, bool rebuild\_flag)  
*update an existing surrogate model with a new anchor*
- virtual void `update_approximation` (const `VariablesArray` &vars\_array, const `ResponseArray` &resp\_array, bool rebuild\_flag)  
*update an existing surrogate model with new data points*
- virtual void `append_approximation` (const `Variables` &vars, const `Response` &response, bool rebuild\_flag)  
*append a single point to an existing surrogate model's data*
- virtual void `append_approximation` (const `VariablesArray` &vars\_array, const `ResponseArray` &resp\_array, bool rebuild\_flag)  
*append multiple points to an existing surrogate model's data*
- virtual `Array`< `Approximation` > & `approximations` ()  
*retrieve the set of `Approximations` within a `DataFitSurrModel`*
- virtual const `RealVectorArray` & `approximation_coefficients` ()  
*within a `DataFitSurrModel`*
- virtual void `approximation_coefficients` (const `RealVectorArray` &approx\_coeffs)  
*a `DataFitSurrModel`*
- virtual void `print_coefficients` (ostream &s, size\_t index) const  
*within a `DataFitSurrModel`*
- virtual const `RealVector` & `approximation_variances` (const `RealVector` &c\_vars)  
*Approximation within a `DataFitSurrModel`.*

- virtual const `List< SurrogateDataPoint > & approximation_data` (size\_t index)  
*instance within a `DataFitSurrModel`*
- virtual void `compute_correction` (const `Response` &truth\_response, const `Response` &approx\_response, const `RealVector` &c\_vars)  
*compute correction factors for use in `SurrogateModels`*
- virtual void `auto_correction` (bool correction\_flag)  
*manages automatic application of correction factors in `SurrogateModels`*
- virtual bool `auto_correction` ()  
*model's responses*
- virtual void `apply_correction` (`Response` &approx\_response, const `RealVector` &c\_vars, bool quiet\_flag=false)  
*apply correction factors to approx\_response (for use in `SurrogateModels`)*
- virtual void `component_parallel_mode` (short mode)  
*(`SUB_MODEL/HF_MODEL/TRUTH_MODEL`)*.
- virtual `String local_eval_synchronization` ()  
*return derived model synchronization setting*
- virtual int `local_eval_concurrency` ()  
*return derived model asynchronous evaluation concurrency*
- virtual void `serve` ()  
*a termination message is received from `stop_servers()`.*
- virtual void `stop_servers` ()  
*particular model when iteration on the model is complete.*
- virtual bool `derived_master_overload` () const  
*of trying to run a multiprocessor job on the master.*
- virtual const `String & interface_id` () const  
*return the interface identifier*
- virtual int `evaluation_id` () const  
*Return the current function evaluation id for the `Model`.*
- virtual void `set_evaluation_reference` ()  
*Set the reference points for the evaluation counters within the `Model`.*

- virtual void [print\\_evaluation\\_summary](#) (ostream &s, bool minimal\_header=false, bool relative\_count=true) const  
*Print an evaluation summary for the [Model](#).*
- [ModelList](#) & [subordinate\\_models](#) (bool recurse\_flag=true)  
*return the sub-models in nested and surrogate models*
- void [compute\\_response](#) ()  
*Compute the [Response](#) at currentVariables (default [ActiveSet](#)).*
- void [compute\\_response](#) (const [ActiveSet](#) &set)  
*Compute the [Response](#) at currentVariables (specified [ActiveSet](#)).*
- void [asynch\\_compute\\_response](#) ()  
*[Response](#) at currentVariables (default [ActiveSet](#)).*
- void [asynch\\_compute\\_response](#) (const [ActiveSet](#) &set)  
*[Response](#) at currentVariables (specified [ActiveSet](#)).*
- const [ResponseArray](#) & [synchronize](#) ()  
*complete set of results from a group of asynchronous evaluations.*
- const [IntResponseMap](#) & [synchronize\\_nowait](#) ()  
*available results from a group of asynchronous evaluations.*
- void [init\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*configuration in modelPCIterMap*
- void [init\\_serial](#) ()  
*modify some default settings to behave properly in serial.*
- void [set\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*from modelPCIterMap)*
- void [free\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*deallocate communicator partitions for a model*
- void [estimate\\_message\\_lengths](#) ()  
*estimate messageLengths for a model*
- void [assign\\_rep](#) ([Model](#) \*model\_rep, bool ref\_count\_incr=true)  
*replaces existing letter with a new one*
- size\_t [tv](#) () const  
*return total number of vars*

- `size_t cv () const`  
*return number of active continuous variables*
- `size_t dv () const`  
*return number of active discrete variables*
- `size_t icv () const`  
*return number of inactive continuous variables*
- `size_t idv () const`  
*return number of inactive discrete variables*
- `size_t acv () const`  
*return total number of continuous variables*
- `size_t adv () const`  
*return total number of discrete variables*
- `void active_variables (const Variables &vars)`  
*set the active variables in currentVariables*
- `const RealVector & continuous_variables () const`  
*return the active continuous variables from currentVariables*
- `void continuous_variables (const RealVector &c_vars)`  
*set the active continuous variables in currentVariables*
- `const IntVector & discrete_variables () const`  
*return the active discrete variables from currentVariables*
- `void discrete_variables (const IntVector &d_vars)`  
*set the active discrete variables in currentVariables*
- `const RealVector & inactive_continuous_variables () const`  
*return the inactive continuous variables in currentVariables*
- `void inactive_continuous_variables (const RealVector &i_c_vars)`  
*set the inactive continuous variables in currentVariables*
- `const IntVector & inactive_discrete_variables () const`  
*return the inactive discrete variables in currentVariables*
- `void inactive_discrete_variables (const IntVector &i_d_vars)`  
*set the inactive discrete variables in currentVariables*
- `RealVector all_continuous_variables () const`

*return all continuous variables in currentVariables*

- void `all_continuous_variables` (const `RealVector` &a\_c\_vars)  
*set all continuous variables in currentVariables*
- `IntVector` `all_discrete_variables` () const  
*return all discrete variables in currentVariables*
- void `all_discrete_variables` (const `IntVector` &a\_d\_vars)  
*set all discrete variables in currentVariables*
- const `RealVector` & `normal_means` () const  
*return the normal uncertain variable means*
- void `normal_means` (const `RealVector` &n\_means)  
*set the normal uncertain variable means*
- const `RealVector` & `normal_std_deviations` () const  
*return the normal uncertain variable standard deviations*
- void `normal_std_deviations` (const `RealVector` &n\_std\_devs)  
*set the normal uncertain variable standard deviations*
- const `RealVector` & `normal_lower_bounds` () const  
*return the normal uncertain variable lower bounds*
- void `normal_lower_bounds` (const `RealVector` &n\_lower\_bnds)  
*set the normal uncertain variable lower bounds*
- const `RealVector` & `normal_upper_bounds` () const  
*return the normal uncertain variable upper bounds*
- void `normal_upper_bounds` (const `RealVector` &n\_upper\_bnds)  
*set the normal uncertain variable upper bounds*
- const `RealVector` & `lognormal_means` () const  
*return the lognormal uncertain variable means*
- void `lognormal_means` (const `RealVector` &ln\_means)  
*set the lognormal uncertain variable means*
- const `RealVector` & `lognormal_std_deviations` () const  
*return the lognormal uncertain variable standard deviations*
- void `lognormal_std_deviations` (const `RealVector` &ln\_std\_devs)  
*set the lognormal uncertain variable standard deviations*



- const [RealVector](#) & [lognormal\\_error\\_factors](#) () const  
*return the lognormal uncertain variable error factors*
- void [lognormal\\_error\\_factors](#) (const [RealVector](#) &ln\_err\_facts)  
*set the lognormal uncertain variable error factors*
- const [RealVector](#) & [lognormal\\_lower\\_bounds](#) () const  
*return the lognormal uncertain variable lower bounds*
- void [lognormal\\_lower\\_bounds](#) (const [RealVector](#) &ln\_lower\_bnds)  
*set the lognormal uncertain variable lower bounds*
- const [RealVector](#) & [lognormal\\_upper\\_bounds](#) () const  
*return the lognormal uncertain variable upper bounds*
- void [lognormal\\_upper\\_bounds](#) (const [RealVector](#) &ln\_upper\_bnds)  
*set the lognormal uncertain variable upper bounds*
- const [RealVector](#) & [uniform\\_lower\\_bounds](#) () const  
*return the uniform uncertain variable lower bounds*
- void [uniform\\_lower\\_bounds](#) (const [RealVector](#) &u\_lower\_bnds)  
*set the uniform uncertain variable lower bounds*
- const [RealVector](#) & [uniform\\_upper\\_bounds](#) () const  
*return the uniform uncertain variable upper bounds*
- void [uniform\\_upper\\_bounds](#) (const [RealVector](#) &u\_upper\_bnds)  
*set the uniform uncertain variable upper bounds*
- const [RealVector](#) & [loguniform\\_lower\\_bounds](#) () const  
*return the loguniform uncertain variable lower bounds*
- void [loguniform\\_lower\\_bounds](#) (const [RealVector](#) &lu\_lower\_bnds)  
*set the loguniform uncertain variable lower bounds*
- const [RealVector](#) & [loguniform\\_upper\\_bounds](#) () const  
*return the loguniform uncertain variable upper bounds*
- void [loguniform\\_upper\\_bounds](#) (const [RealVector](#) &lu\_upper\_bnds)  
*set the loguniform uncertain variable upper bounds*
- const [RealVector](#) & [triangular\\_modes](#) () const  
*return the triangular uncertain variable modes*

- void `triangular_modes` (const `RealVector` &t\_modes)  
*set the triangular uncertain variable modes*
- const `RealVector` & `triangular_lower_bounds` () const  
*return the triangular uncertain variable lower bounds*
- void `triangular_lower_bounds` (const `RealVector` &t\_lower\_bnds)  
*set the triangular uncertain variable lower bounds*
- const `RealVector` & `triangular_upper_bounds` () const  
*return the triangular uncertain variable upper bounds*
- void `triangular_upper_bounds` (const `RealVector` &t\_upper\_bnds)  
*set the triangular uncertain variable upper bounds*
- const `RealVector` & `exponential_betas` () const  
*return the exponential uncertain variable beta parameters*
- void `exponential_betas` (const `RealVector` &e\_betas)  
*set the exponential uncertain variable beta parameters*
- const `RealVector` & `beta_alphas` () const  
*return the beta uncertain variable alphas*
- void `beta_alphas` (const `RealVector` &b\_alphas)  
*set the beta uncertain variable alphas*
- const `RealVector` & `beta_betas` () const  
*return the beta uncertain variable betas*
- void `beta_betas` (const `RealVector` &b\_betas)  
*set the beta uncertain variable betas*
- const `RealVector` & `beta_lower_bounds` () const  
*return the beta uncertain variable lower bounds*
- void `beta_lower_bounds` (const `RealVector` &b\_lower\_bnds)  
*set the beta uncertain variable lower bounds*
- const `RealVector` & `beta_upper_bounds` () const  
*return the beta uncertain variable upper bounds*
- void `beta_upper_bounds` (const `RealVector` &b\_upper\_bnds)  
*set the beta uncertain variable upper bounds*
- const `RealVector` & `gamma_alphas` () const

*return the gamma uncertain variable alpha parameters*

- void `gamma_alphas` (const `RealVector` &ga\_alphas)  
*set the gamma uncertain variable alpha parameters*
- const `RealVector` & `gamma_betas` () const  
*return the gamma uncertain variable beta parameters*
- void `gamma_betas` (const `RealVector` &ga\_betas)  
*set the gamma uncertain variable beta parameters*
- const `RealVector` & `gumbel_alphas` () const  
*return the gumbel uncertain variable alphas*
- void `gumbel_alphas` (const `RealVector` &gu\_alphas)  
*set the gumbel uncertain variable alphas*
- const `RealVector` & `gumbel_betas` () const  
*return the gumbel uncertain variable betas*
- void `gumbel_betas` (const `RealVector` &gu\_betas)  
*set the gumbel uncertain variable betas*
- const `RealVector` & `frechet_alphas` () const  
*return the frechet uncertain variable alpha parameters*
- void `frechet_alphas` (const `RealVector` &f\_alphas)  
*set the frechet uncertain variable alpha parameters*
- const `RealVector` & `frechet_betas` () const  
*return the frechet uncertain variable beta parameters*
- void `frechet_betas` (const `RealVector` &f\_betas)  
*set the frechet uncertain variable beta parameters*
- const `RealVector` & `weibull_alphas` () const  
*return the weibull uncertain variable alpha parameters*
- void `weibull_alphas` (const `RealVector` &w\_alphas)  
*set the weibull uncertain variable alpha parameters*
- const `RealVector` & `weibull_betas` () const  
*return the weibull uncertain variable beta parameters*
- void `weibull_betas` (const `RealVector` &w\_betas)  
*set the weibull uncertain variable beta parameters*

- const [RealVectorArray](#) & [histogram\\_bin\\_pairs](#) () const  
*return the histogram uncertain bin pairs*
- void [histogram\\_bin\\_pairs](#) (const [RealVectorArray](#) &h\_bin\_pairs)  
*set the histogram uncertain bin pairs*
- const [RealVectorArray](#) & [histogram\\_point\\_pairs](#) () const  
*return the histogram uncertain point pairs*
- void [histogram\\_point\\_pairs](#) (const [RealVectorArray](#) &h\_pt\_pairs)  
*set the histogram uncertain point pairs*
- const [RealVectorArray](#) & [interval\\_probabilities](#) () const  
*return the interval basic probability values*
- void [interval\\_probabilities](#) (const [RealVectorArray](#) &int\_probs)  
*set the interval basic probability values*
- const [RealVectorArray](#) & [interval\\_bounds](#) () const  
*return the interval bounds*
- void [interval\\_bounds](#) (const [RealVectorArray](#) &int\_bounds)  
*set the interval bounds*
- const [RealMatrix](#) & [uncertain\\_correlations](#) () const  
*return the uncertain variable correlations*
- void [uncertain\\_correlations](#) (const [RealMatrix](#) &uncertain\_corr)  
*set the uncertain variable correlations*
- const [StringArray](#) & [continuous\\_variable\\_types](#) () const  
*return the active continuous variable types from currentVariables*
- const [StringArray](#) & [discrete\\_variable\\_types](#) () const  
*return the active discrete variable types from currentVariables*
- const [StringArray](#) & [continuous\\_variable\\_labels](#) () const  
*return the active continuous variable labels from currentVariables*
- void [continuous\\_variable\\_labels](#) (const [StringArray](#) &c\_v\_labels)  
*set the active continuous variable labels in currentVariables*
- const [StringArray](#) & [discrete\\_variable\\_labels](#) () const  
*return the active discrete variable labels from currentVariables*

- void `discrete_variable_labels` (const `StringArray` &d\_v\_labels)  
*set the active discrete variable labels in currentVariables*
- const `StringArray` & `inactive_continuous_variable_labels` () const  
*return the inactive continuous variable labels in currentVariables*
- void `inactive_continuous_variable_labels` (const `StringArray` &i\_c\_v\_labels)  
*set the inactive continuous variable labels in currentVariables*
- const `StringArray` & `inactive_discrete_variable_labels` () const  
*return the inactive discrete variable labels in currentVariables*
- void `inactive_discrete_variable_labels` (const `StringArray` &i\_d\_v\_labels)  
*set the inactive discrete variable labels in currentVariables*
- `StringArray` `all_continuous_variable_labels` () const  
*return all continuous variable labels in currentVariables*
- void `all_continuous_variable_labels` (const `StringArray` &a\_c\_v\_labels)  
*set all continuous variable labels in currentVariables*
- `StringArray` `all_discrete_variable_labels` () const  
*return all discrete variable labels in currentVariables*
- void `all_discrete_variable_labels` (const `StringArray` &a\_d\_v\_labels)  
*set all discrete variable labels in currentVariables*
- const `StringArray` & `response_labels` () const  
*return the response labels from currentResponse*
- void `response_labels` (const `StringArray` &resp\_labels)  
*set the response labels in currentResponse*
- const `RealVector` & `continuous_lower_bounds` () const  
*return the active continuous lower bounds from userDefinedConstraints*
- void `continuous_lower_bounds` (const `RealVector` &c\_l\_bnds)  
*set the active continuous lower bounds in userDefinedConstraints*
- const `RealVector` & `continuous_upper_bounds` () const  
*return the active continuous upper bounds from userDefinedConstraints*
- void `continuous_upper_bounds` (const `RealVector` &c\_u\_bnds)  
*set the active continuous upper bounds in userDefinedConstraints*
- const `IntVector` & `discrete_lower_bounds` () const

*return the active discrete lower bounds from userDefinedConstraints*

- void `discrete_lower_bounds` (const `IntVector` &d\_l\_bnds)  
*set the active discrete lower bounds in userDefinedConstraints*
- const `IntVector` & `discrete_upper_bounds` () const  
*return the active discrete upper bounds from userDefinedConstraints*
- void `discrete_upper_bounds` (const `IntVector` &d\_u\_bnds)  
*set the active discrete upper bounds in userDefinedConstraints*
- const `RealVector` & `inactive_continuous_lower_bounds` () const  
*return the inactive continuous lower bounds in userDefinedConstraints*
- void `inactive_continuous_lower_bounds` (const `RealVector` &i\_c\_l\_bnds)  
*set the inactive continuous lower bounds in userDefinedConstraints*
- const `RealVector` & `inactive_continuous_upper_bounds` () const  
*return the inactive continuous upper bounds in userDefinedConstraints*
- void `inactive_continuous_upper_bounds` (const `RealVector` &i\_c\_u\_bnds)  
*set the inactive continuous upper bounds in userDefinedConstraints*
- const `IntVector` & `inactive_discrete_lower_bounds` () const  
*return the inactive discrete lower bounds in userDefinedConstraints*
- void `inactive_discrete_lower_bounds` (const `IntVector` &i\_d\_l\_bnds)  
*set the inactive discrete lower bounds in userDefinedConstraints*
- const `IntVector` & `inactive_discrete_upper_bounds` () const  
*return the inactive discrete upper bounds in userDefinedConstraints*
- void `inactive_discrete_upper_bounds` (const `IntVector` &i\_d\_u\_bnds)  
*set the inactive discrete upper bounds in userDefinedConstraints*
- `RealVector` `all_continuous_lower_bounds` () const  
*return all continuous lower bounds in userDefinedConstraints*
- void `all_continuous_lower_bounds` (const `RealVector` &a\_c\_l\_bnds)  
*set all continuous lower bounds in userDefinedConstraints*
- `RealVector` `all_continuous_upper_bounds` () const  
*return all continuous upper bounds in userDefinedConstraints*
- void `all_continuous_upper_bounds` (const `RealVector` &a\_c\_u\_bnds)  
*set all continuous upper bounds in userDefinedConstraints*

- `IntVector all_discrete_lower_bounds () const`  
*return all discrete lower bounds in userDefinedConstraints*
- `void all_discrete_lower_bounds (const IntVector &a_d_l_bnds)`  
*set all discrete lower bounds in userDefinedConstraints*
- `IntVector all_discrete_upper_bounds () const`  
*return all discrete upper bounds in userDefinedConstraints*
- `void all_discrete_upper_bounds (const IntVector &a_d_u_bnds)`  
*set all discrete upper bounds in userDefinedConstraints*
- `size_t num_linear_ineq_constraints () const`  
*return the number of linear inequality constraints*
- `size_t num_linear_eq_constraints () const`  
*return the number of linear equality constraints*
- `const RealMatrix & linear_ineq_constraint_coeffs () const`  
*return the linear inequality constraint coefficients*
- `void linear_ineq_constraint_coeffs (const RealMatrix &lin_ineq_coeffs)`  
*set the linear inequality constraint coefficients*
- `const RealVector & linear_ineq_constraint_lower_bounds () const`  
*return the linear inequality constraint lower bounds*
- `void linear_ineq_constraint_lower_bounds (const RealVector &lin_ineq_l_bnds)`  
*set the linear inequality constraint lower bounds*
- `const RealVector & linear_ineq_constraint_upper_bounds () const`  
*return the linear inequality constraint upper bounds*
- `void linear_ineq_constraint_upper_bounds (const RealVector &lin_ineq_u_bnds)`  
*set the linear inequality constraint upper bounds*
- `const RealMatrix & linear_eq_constraint_coeffs () const`  
*return the linear equality constraint coefficients*
- `void linear_eq_constraint_coeffs (const RealMatrix &lin_eq_coeffs)`  
*set the linear equality constraint coefficients*
- `const RealVector & linear_eq_constraint_targets () const`  
*return the linear equality constraint targets*

- void `linear_eq_constraint_targets` (const `RealVector` &lin\_eq\_targets)  
*set the linear equality constraint targets*
- size\_t `num_nonlinear_ineq_constraints` () const  
*return the number of nonlinear inequality constraints*
- size\_t `num_nonlinear_eq_constraints` () const  
*return the number of nonlinear equality constraints*
- const `RealVector` & `nonlinear_ineq_constraint_lower_bounds` () const  
*return the nonlinear inequality constraint lower bounds*
- void `nonlinear_ineq_constraint_lower_bounds` (const `RealVector` &nln\_ineq\_l\_bnds)  
*set the nonlinear inequality constraint lower bounds*
- const `RealVector` & `nonlinear_ineq_constraint_upper_bounds` () const  
*return the nonlinear inequality constraint upper bounds*
- void `nonlinear_ineq_constraint_upper_bounds` (const `RealVector` &nln\_ineq\_u\_bnds)  
*set the nonlinear inequality constraint upper bounds*
- const `RealVector` & `nonlinear_eq_constraint_targets` () const  
*return the nonlinear equality constraint targets*
- void `nonlinear_eq_constraint_targets` (const `RealVector` &nln\_eq\_targets)  
*set the nonlinear equality constraint targets*
- const `IntArray` & `merged_discrete_ids` () const  
*merged into a continuous array in currentVariables*
- const `Variables` & `current_variables` () const  
*return the current variables (currentVariables)*
- const `Constraints` & `user_defined_constraints` () const  
*return the user-defined constraints (userDefinedConstraints)*
- const `Response` & `current_response` () const  
*return the current response (currentResponse)*
- const `ProblemDescDB` & `problem_description_db` () const  
*return the problem description database (probDescDB)*
- const `String` & `model_type` () const  
*return the model type (modelType)*
- const `String` & `model_id` () const



*return the model identifier (idModel)*

- `size_t num_functions () const`  
*return number of functions in currentResponse*
- `const String & gradient_type () const`  
*return the gradient evaluation type (gradType)*
- `const String & method_source () const`  
*return the numerical gradient evaluation method source (methodSrc)*
- `const String & interval_type () const`  
*return the numerical gradient evaluation interval type (intervalType)*
- `const RealVector & fd_gradient_step_size () const`  
*return the finite difference gradient step size (fdGradSS)*
- `const IntList & gradient_id_analytic () const`  
*return the mixed gradient analytic IDs (gradIdAnalytic)*
- `const IntList & gradient_id_numerical () const`  
*return the mixed gradient numerical IDs (gradIdNumerical)*
- `const String & hessian_type () const`  
*return the Hessian evaluation type (hessType)*
- `const String & quasi_hessian_type () const`  
*return the Hessian evaluation type (quasiHessType)*
- `const RealVector & fd_hessian_by_grad_step_size () const`  
*return gradient-based finite difference Hessian step size (fdHessByGradSS)*
- `const RealVector & fd_hessian_by_fn_step_size () const`  
*return function-based finite difference Hessian step size (fdHessByFnSS)*
- `const IntList & hessian_id_analytic () const`  
*return the mixed Hessian analytic IDs (hessIdAnalytic)*
- `const IntList & hessian_id_numerical () const`  
*return the mixed Hessian analytic IDs (hessIdNumerical)*
- `const IntList & hessian_id_quasi () const`  
*return the mixed Hessian analytic IDs (hessIdQuasi)*
- `void supports_estimated_derivatives (bool sed_flag)`  
*set whether this model should perform or pass on derivative estimation*

- `const int & evaluation_capacity () const`  
*return the evaluation capacity for use in iterator logic*
- `int derivative_concurrency () const`  
*return the gradient concurrency for use in parallel configuration logic*
- `bool asynch_flag () const`  
*return the asynchronous evaluation flag (*asynchEvalFlag*)*
- `void asynch_flag (const bool flag)`  
*set the asynchronous evaluation flag (*asynchEvalFlag*)*
- `const IntArray & message_lengths () const`  
*return the array of MPI packed message buffer lengths (*messageLengths*)*
- `void parallel_configuration_iterator (const ParConfigLIter &pc_iter)`  
*set *modelPCIter**
- `const ParConfigLIter & parallel_configuration_iterator () const`  
*return *modelPCIter**
- `void auto_graphics (const bool flag)`  
*the model as opposed to graphics posting at the strategy level).*
- `bool is_null () const`  
*function to check *modelRep* (does this envelope contain a letter)*
- `Model * model_rep () const`  
*that are not mapped to the top *Model* level*

## Protected Member Functions

- `Model (BaseConstructor, ProblemDescDB &problem_db)`  
*derived class constructors - Coplien, p. 139)*
- `Model (NoDBBaseConstructor, const pair< short, short > &view, const ActiveSet &set)`  
*constructed on the fly*
- `Model (RecastBaseConstructor, ParallelLibrary &parallel_lib)`  
*constructed on the fly*
- `virtual void derived_compute_response (const ActiveSet &set)`  
*portion of *compute\_response()* specific to derived model classes*

- virtual void `derived_asynch_compute_response` (const `ActiveSet` &set)  
*portion of `asynch_compute_response()` specific to derived model classes*
- virtual const `ResponseArray` & `derived_synchronize` ()  
*portion of `synchronize()` specific to derived model classes*
- virtual const `IntResponseMap` & `derived_synchronize_nowait` ()  
*portion of `synchronize_nowait()` specific to derived model classes*
- virtual void `derived_init_communicators` (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*portion of `init_communicators()` specific to derived model classes*
- virtual void `derived_init_serial` ()  
*portion of `init_serial()` specific to derived model classes*
- virtual void `derived_set_communicators` (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*portion of `set_communicators()` specific to derived model classes*
- virtual void `derived_free_communicators` (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*portion of `free_communicators()` specific to derived model classes*

### Protected Attributes

- `Variables currentVariables`  
*function evaluations*
- `size_t numDerivVars`  
*corrections where only the active continuous variables are supported)*
- `Response currentResponse`  
*function evaluations*
- `size_t numFns`  
*the number of functions in `currentResponse`*
- `Constraints userDefinedConstraints`  
*an iterator at startup.*
- `String modelType`  
*type of model: single, nested, or surrogate*
- `String surrogateType`  
*type of surrogate model: local\_\*, multipoint\_\*, global\_\*, or hierarchical*
- `String gradType`

*grad type: none,numerical,analytic,mixed*

- [String methodSrc](#)

*method source: dakota,vendor*

- [String intervalType](#)

*interval type: forward,central*

- [RealVector fdGradSS](#)

*relative step sizes for numerical gradients*

- [IntList gradIdAnalytic](#)

*analytic id's for mixed gradients*

- [IntList gradIdNumerical](#)

*numerical id's for mixed gradients*

- [String hessType](#)

*Hess type: none,numerical,quasi,analytic,mixed.*

- [String quasiHessType](#)

*quasi-Hessian type: bfgs, damped\_bfgs, sr1*

- [RealVector fdHessByGradSS](#)

*relative step sizes for numerical Hessians estimated with 1st-order grad differences*

- [RealVector fdHessByFnSS](#)

*relative step sizes for numerical Hessians estimated with 2nd-order fn differences*

- [IntList hessIdAnalytic](#)

*analytic id's for mixed Hessians*

- [IntList hessIdNumerical](#)

*numerical id's for mixed Hessians*

- [IntList hessIdQuasi](#)

*quasi id's for mixed Hessians*

- [bool supportsEstimDerivs](#)

*whether model should perform or forward derivative estimation*

- [IntArray messageLengths](#)

*and PRPair*

- [const ProblemDescDB & probDescDB](#)

*class member reference to the problem description database*

- [ParallelLibrary](#) & [parallelLib](#)  
*class member reference to the parallel library*
- [ParConfigLIter](#) [modelPCIter](#)  
*the [ParallelConfiguration](#) node used by this model instance*
- short [componentParallelMode](#)  
*(SUB\_MODEL/HF\_MODEL/TRUTH\_MODEL)*
- bool [asynchEvalFlag](#)  
*flags asynch evaluations (local or distributed)*
- [RealVector](#) [normalMeans](#)  
*normal uncertain variable means*
- [RealVector](#) [normalStdDevs](#)  
*normal uncertain variable standard deviations*
- [RealVector](#) [normalLowerBnds](#)  
*normal uncertain variable lower bounds*
- [RealVector](#) [normalUpperBnds](#)  
*normal uncertain variable upper bounds*
- [RealVector](#) [lognormalMeans](#)  
*lognormal uncertain variable means*
- [RealVector](#) [lognormalStdDevs](#)  
*lognormal uncertain variable standard deviations*
- [RealVector](#) [lognormalErrFacts](#)  
*lognormal uncertain variable error factors*
- [RealVector](#) [lognormalLowerBnds](#)  
*lognormal uncertain variable lower bounds*
- [RealVector](#) [lognormalUpperBnds](#)  
*lognormal uncertain variable upper bounds*
- [RealVector](#) [uniformLowerBnds](#)  
*uniform uncertain variable lower bounds*
- [RealVector](#) [uniformUpperBnds](#)  
*uniform uncertain variable upper bounds*

- [RealVector loguniformLowerBnds](#)  
*loguniform uncertain variable lower bounds*
- [RealVector loguniformUpperBnds](#)  
*loguniform uncertain variable upper bounds*
- [RealVector triangularModes](#)  
*triangular uncertain variable modes*
- [RealVector triangularLowerBnds](#)  
*triangular uncertain variable lower bounds*
- [RealVector triangularUpperBnds](#)  
*triangular uncertain variable upper bounds*
- [RealVector exponentialBetas](#)  
*exponential uncertain variable betas*
- [RealVector betaAlphas](#)  
*beta uncertain variable alphas*
- [RealVector betaBetas](#)  
*beta uncertain variable betas*
- [RealVector betaLowerBnds](#)  
*beta uncertain variable lower bounds*
- [RealVector betaUpperBnds](#)  
*beta uncertain variable upper bounds*
- [RealVector gammaAlphas](#)  
*gamma uncertain variable alphas*
- [RealVector gammaBetas](#)  
*gamma uncertain variable betas*
- [RealVector gumbelAlphas](#)  
*gumbel uncertain variable alphas*
- [RealVector gumbelBetas](#)  
*gumbel uncertain variable betas*
- [RealVector frechetAlphas](#)  
*frechet uncertain variable alphas*
- [RealVector frechetBetas](#)

*frechet uncertain variable betas*

- [RealVector weibullAlphas](#)  
*weibull uncertain variable alphas*
- [RealVector weibullBetas](#)  
*weibull uncertain variable betas*
- [RealVectorArray histogramBinPairs](#)  
*histogram uncertain (x,y) bin pairs (continuous linear histogram)*
- [RealVectorArray histogramPointPairs](#)  
*histogram uncertain (x,y) point pairs (discrete histogram)*
- [RealVectorArray intervalBasicProbs](#)  
*basic probability values for interval uncertain variables*
- [RealVectorArray intervalBounds](#)  
*interval lower/upper bounds for interval uncertain variables*
- [RealMatrix uncertainCorrelations](#)  
*and correlation coefficients for reliability)*

## Private Member Functions

- [Model \\* get\\_model](#) ([ProblemDescDB](#) &problem\_db)  
*Used by the envelope to instantiate the correct letter class.*
- [int estimate\\_derivatives](#) (const [ShortArray](#) &map\_asv, const [ShortArray](#) &fd\_grad\_asv, const [ShortArray](#) &fd\_hess\_asv, const [ShortArray](#) &quasi\_hess\_asv, const [ActiveSet](#) &original\_set, const bool asynch\_flag)  
*method\_source) in the numerical gradient specification.*
- [void synchronize\\_derivatives](#) (const [Variables](#) &vars, const [ResponseArray](#) &fd\_responses, [Response](#) &new\_response, const [ShortArray](#) &fd\_grad\_asv, const [ShortArray](#) &fd\_hess\_asv, const [ShortArray](#) &quasi\_hess\_asv, const [ActiveSet](#) &original\_set)  
*objects (fd\_grad\_responses) into a single response (new\_response)*
- [void update\\_response](#) (const [Variables](#) &vars, [Response](#) &new\_response, const [ShortArray](#) &fd\_grad\_asv, const [ShortArray](#) &fd\_hess\_asv, const [ShortArray](#) &quasi\_hess\_asv, const [ActiveSet](#) &original\_set, [Response](#) &initial\_map\_response, const [RealMatrix](#) &new\_fn\_grads, const [RealMatrixArray](#) &new\_fn\_hessians)  
*overlay results to update a response object*
- [void update\\_quasi\\_hessians](#) (const [Variables](#) &vars, [Response](#) &new\_response, const [ActiveSet](#) &original\_set)

*perform quasi-Newton Hessian updates*

- bool `manage_asv` (const [ShortArray](#) &asv\_in, [ShortArray](#) &map\_asv\_out, [ShortArray](#) &fd\_grad\_asv\_out, [ShortArray](#) &fd\_hess\_asv\_out, [ShortArray](#) &quasi\_hess\_asv\_out)

*Coordinates usage of `estimate_derivatives()` calls based on `asv_in`.*

## Private Attributes

- [String](#) `idModel`  
*model identifier string from the input file*
- bool `estDerivsFlag`  
*`asynch_compute_response()`*
- int `evaluationCapacity`  
*capacity for concurrent evaluations supported by the [Model](#)*
- `std::map< int, ParConfigLIter >` `modelPCIterMap`  
*level as the lookup key*
- bool `modelAutoGraphicsFlag`  
*graphics posting at the strategy level)*
- bool `silentFlag`  
*flag for really quiet (silent) model output*
- bool `quietFlag`  
*flag for quiet model output*
- [ModelList](#) `modelList`  
*used to collect sub-models for `subordinate_models()`*
- [VariablesList](#) `varsList`  
*`synchronize()`.*
- `List< ShortArray >` `asvList`  
*`asynch_compute_response()` to `synchronize()`*
- `List< ActiveSet >` `setList`  
*`asynch_compute_response()` to `synchronize()`*
- [BoolList](#) `initialMapList`  
*`synchronize_derivatives()`*
- [BoolList](#) `dbCaptureList`



- synchronize\_derivatives()*
- [ResponseList dbResponseList](#)
  - synchronize\_derivatives()*
- [RealList deltaList](#)
  - transfers deltas from estimate\_derivatives() to synchronize\_derivatives()*
- [IntList numMapsList](#)
  - into numerical gradients.*
- [RealMatrix xPrev](#)
  - previous parameter vectors used in computing s for quasi-Newton updates*
- [RealMatrix fnGradsPrev](#)
  - previous gradient vectors used in computing y for quasi-Newton updates*
- [RealMatrixArray quasiHessians](#)
  - quasi-Newton Hessian approximations*
- [SizetArray numQuasiUpdates](#)
  - number of quasi-Newton Hessian updates applied*
- [ResponseArray responseArray](#)
  - similar array in [Interface](#) contains the raw responses.*
- [IntResponseMap graphicsRespMap](#)
  - prior to sequential input into the graphics*
- [Model \\* modelRep](#)
  - pointer to the letter (initialized only for the envelope)*
- [int referenceCount](#)
  - number of objects sharing modelRep*

### 8.64.1 Detailed Description

Base class for the model class hierarchy.

The [Model](#) class is the base class for one of the primary class hierarchies in DAKOTA. The model hierarchy contains a set of variables, an interface, and a set of responses, and an iterator operates on the model to map the variables into responses using the interface. For memory efficiency and enhanced polymorphism, the model hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Model](#)) serves as the envelope and one of the derived classes (selected in [Model::get\\_model\(\)](#)) serves as the letter.

## 8.64.2 Constructor & Destructor Documentation

### 8.64.2.1 `Model()`

default constructor

The default constructor is used in `vector<Model>` instantiations and for initialization of `Model` objects contained in `Iterator` and derived `Strategy` classes. `modelRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful `Model` object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

### 8.64.2.2 `Model(ProblemDescDB & problem_db)`

standard constructor for envelope

Used in model instantiations within strategy constructors. Envelope constructor only needs to extract enough data to properly execute `get_model`, since `Model(BaseConstructor, problem_db)` builds the actual base class data for the derived models.

### 8.64.2.3 `Model(const Model & model)`

copy constructor

Copy constructor manages sharing of `modelRep` and incrementing of `referenceCount`.

### 8.64.2.4 `~Model()` [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `modelRep` when `referenceCount` reaches zero.

### 8.64.2.5 `Model(BaseConstructor, ProblemDescDB & problem_db)` [protected]

derived class constructors - Coplien, p. 139)

This constructor builds the base class data for all inherited models. `get_model()` instantiates a derived class and the derived class selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_model()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Model`).

### 8.64.2.6 `Model(RecastBaseConstructor, ParallelLibrary & parallel_lib)` [protected]

constructed on the fly

This constructor also builds the base class data for inherited models. However, it is used for recast models which are instantiated on the fly. Therefore it only initializes a small subset of attributes.

### 8.64.3 Member Function Documentation

#### 8.64.3.1 **Model** operator= (const **Model** & *model*)

assignment operator

Assignment operator decrements referenceCount for old modelRep, assigns new modelRep, and increments referenceCount for new modelRep.

#### 8.64.3.2 **Iterator** & subordinate\_iterator () [virtual]

return the sub-iterator in nested and surrogate models

return by reference requires use of dummy objects, but is important to allow use of [assign\\_rep\(\)](#) since this operation must be performed on the original envelope object.

Reimplemented in [DataFitSurrModel](#), and [NestedModel](#).

#### 8.64.3.3 **Model** & surrogate\_model () [virtual]

return the approximation sub-model in surrogate models

return by reference requires use of dummy objects, but is important to allow use of [assign\\_rep\(\)](#) since this operation must be performed on the original envelope object.

Reimplemented in [DataFitSurrModel](#), and [HierarchSurrModel](#).

#### 8.64.3.4 **Model** & truth\_model () [virtual]

return the truth sub-model in surrogate models

return by reference requires use of dummy objects, but is important to allow use of [assign\\_rep\(\)](#) since this operation must be performed on the original envelope object.

Reimplemented in [DataFitSurrModel](#), and [HierarchSurrModel](#).

#### 8.64.3.5 void update\_from\_subordinate\_model (bool *recurse\_flag* = true) [virtual]

propagate vars/labels/bounds/targets from the bottom up

used only for instantiate-on-the-fly model recursions (all [RecastModel](#) instantiations and alternate [DataFitSurrModel](#) instantiations). Single, Hierarchical, and Nested Models do not redefine the function since they do not support instantiate-on-the-fly. This means that the recursion will stop as soon as it encounters a [Model](#) that was instantiated normally, which is appropriate since ProblemDescDB-constructed Models use top-down information flow and do not require bottom-up updating.

Reimplemented in [DataFitSurrModel](#), and [RecastModel](#).

**8.64.3.6 Interface & interface () [virtual]**

or [NestedModel::optionalInterface](#)

return by reference requires use of dummy objects, but is important to allow use of [assign\\_rep\(\)](#) since this operation must be performed on the original envelope object.

Reimplemented in [DataFitSurrModel](#), [NestedModel](#), [RecastModel](#), and [SingleModel](#).

**8.64.3.7 String local\_eval\_synchronization () [virtual]**

return derived model synchronization setting

[SingleModels](#) and [HierarchSurrModels](#) redefine this virtual function. A default value of "synchronous" prevents asynch local operations for:

- [NestedModels](#): a subIterator can support message passing parallelism, but not asynch local.
- [DataFitSurrModels](#): while asynch evals on approximations will work due to some added bookkeeping, avoiding them is preferable.

Reimplemented in [RecastModel](#), and [SingleModel](#).

**8.64.3.8 int local\_eval\_concurrency () [virtual]**

return derived model asynchronous evaluation concurrency

[SingleModels](#) and [HierarchSurrModels](#) redefine this virtual function.

Reimplemented in [RecastModel](#), and [SingleModel](#).

**8.64.3.9 const String & interface\_id () const [virtual]**

return the interface identifier

return by reference requires use of dummy objects, but is important to allow use of [assign\\_rep\(\)](#) since this operation must be performed on the original envelope object.

Reimplemented in [DataFitSurrModel](#), [NestedModel](#), [RecastModel](#), and [SingleModel](#).

**8.64.3.10 ModelList & subordinate\_models (bool recurse\_flag = true)**

return the sub-models in nested and surrogate models

since `modelList` is built with list insertions (using envelope copies), these models may not be used for `model.assign_rep()` since this operation must be performed on the original envelope object. They may, however, be used for letter-based operations (including [assign\\_rep\(\)](#) on letter contents such as an interface).

**8.64.3.11 void init\_communicators (const int & max\_iterator\_concurrency, bool recurse\_flag = true)**

configuration in `modelPCIterMap`

The `init_communicators()` and `derived_init_communicators()` functions are structured to avoid performing the `messageLengths` estimation more than once. `init_communicators()` (not virtual) performs the estimation and then forwards the results to `derived_init_communicators` (virtual) which uses the data in different contexts.

#### 8.64.3.12 `void init_serial ()`

modify some default settings to behave properly in serial.

The `init_serial()` and `derived_init_serial()` functions are structured to separate base class (common) operations from derived class (specialized) operations.

#### 8.64.3.13 `void estimate_message_lengths ()`

estimate `messageLengths` for a model

This functionality has been pulled out of `init_communicators()` and defined separately so that it may be used in those cases when `messageLengths` is needed but `model.init_communicators()` is not called, e.g., for the master processor in the self-scheduling of a concurrent iterator strategy.

#### 8.64.3.14 `void assign_rep (Model * model_rep, bool ref_count_incr = true)`

replaces existing letter with a new one

Similar to the assignment operator, the `assign_rep()` function decrements `referenceCount` for the old `modelRep` and assigns the new `modelRep`. It is different in that it is used for publishing derived class letters to existing envelopes, as opposed to sharing representations among multiple envelopes (in particular, `assign_rep` is passed a letter object and `operator=` is passed an envelope object). Letter assignment supports two models as governed by `ref_count_incr`:

- `ref_count_incr = true` (default): the incoming letter belongs to another envelope. In this case, increment the reference count in the normal manner so that deallocation of the letter is handled properly.
- `ref_count_incr = false`: the incoming letter is instantiated on the fly and has no envelope. This case is modeled after `get_model()`: a letter is dynamically allocated using `new` and passed into `assign_rep`, the letter's reference count is not incremented, and the letter is not remotely deleted (its memory management is passed over to the envelope).

#### 8.64.3.15 `int derivative_concurrency () const`

return the gradient concurrency for use in parallel configuration logic

This function assumes derivatives with respect to the active continuous variables. Therefore, concurrency with respect to the inactive continuous variables is not captured.

### 8.64.3.16 `Model * get_model (ProblemDescDB & problem_db) [private]`

Used by the envelope to instantiate the correct letter class.

Used only by the envelope constructor to initialize modelRep to the appropriate derived type, as given by the modelType attribute.

### 8.64.3.17 `int estimate_derivatives (const ShortArray & map_asv, const ShortArray & fd_grad_asv, const ShortArray & fd_hess_asv, const ShortArray & quasi_hess_asv, const ActiveSet & original_set, const bool asynch_flag) [private]`

method\_source) in the numerical gradient specification.

Estimate derivatives by computing finite difference gradients, finite difference Hessians, and/or quasi-Newton Hessians. The total number of finite difference evaluations is returned for use by `synchronize()` to track response arrays, and it could be used to improve management of max\_function\_evaluations within the iterators.

### 8.64.3.18 `void synchronize_derivatives (const Variables & vars, const ResponseArray & fd_responses, Response & new_response, const ShortArray & fd_grad_asv, const ShortArray & fd_hess_asv, const ShortArray & quasi_hess_asv, const ActiveSet & original_set) [private]`

objects (fd\_grad\_responses) into a single response (new\_response)

Merge an array of fd\_responses into a single new\_response. This function is used both by synchronous `compute_response()` for the case of asynchronous `estimate_derivatives()` and by `synchronize()` for the case where one or more `asynch_compute_response()` calls has employed asynchronous `estimate_derivatives()`.

### 8.64.3.19 `void update_response (const Variables & vars, Response & new_response, const ShortArray & fd_grad_asv, const ShortArray & fd_hess_asv, const ShortArray & quasi_hess_asv, const ActiveSet & original_set, Response & initial_map_response, const RealMatrix & new_fn_grads, const RealMatrixArray & new_fn_hessians) [private]`

overlay results to update a response object

Overlay the initial\_map\_response with numerically estimated new\_fn\_grads and new\_fn\_hessians to populate new\_response as governed by asv vectors. Quasi-Newton secant Hessian updates are also performed here, since this is where the gradient data needed for the updates is first consolidated. Convenience function used by `estimate_derivatives()` for the synchronous case and by `synchronize_derivatives()` for the asynchronous case.

### 8.64.3.20 `void update_quasi_hessians (const Variables & vars, Response & new_response, const ActiveSet & original_set) [private]`

perform quasi-Newton Hessian updates

quasi-Newton updates are performed for approximating response function Hessians using BFGS or SR1 formulations. These Hessians are supported only for the active continuous variables, and a check is performed on the DVV prior to invoking the function.

**8.64.3.21** `bool manage_asv (const ShortArray & asv_in, ShortArray & map_asv_out, ShortArray & fd_grad_asv_out, ShortArray & fd_hess_asv_out, ShortArray & quasi_hess_asv_out)`  
[private]

Coordinates usage of [estimate\\_derivatives\(\)](#) calls based on asv\_in.

Splits asv\_in total request into map\_asv\_out, fd\_grad\_asv\_out, fd\_hess\_asv\_out, and quasi\_hess\_asv\_out as governed by the responses specification. If the returned use\_est\_deriv is true, then these asv outputs are used by [estimate\\_derivatives\(\)](#) for the initial map, finite difference gradient evals, finite difference Hessian evals, and quasi-Hessian updates, respectively. If the returned use\_est\_deriv is false, then only map\_asv\_out is used.

The documentation for this class was generated from the following files:

- DakotaModel.H
- DakotaModel.C

## 8.65 MPIPackBuffer Class Reference

Class for packing MPI message buffers.

### Public Member Functions

- [MPIPackBuffer](#) (int size\_=1024)  
*Constructor, which allows the default buffer size to be set.*
- [~MPIPackBuffer](#) ()  
*Desctructor.*
- const char \* [buf](#) ()  
*Returns a pointer to the internal buffer that has been packed.*
- int [size](#) ()  
*The number of bytes of packed data.*
- int [capacity](#) ()  
*the allocated size of Buffer.*
- void [reset](#) ()  
*Resets the buffer index in order to reuse the internal buffer.*
- void [pack](#) (const int \*data, const int num=1)  
*Pack one or more **int**'s.*
- void [pack](#) (const u\_int \*data, const int num=1)  
*Pack one or more **unsigned int**'s.*
- void [pack](#) (const long \*data, const int num=1)  
*Pack one or more **long**'s.*
- void [pack](#) (const u\_long \*data, const int num=1)  
*Pack one or more **unsigned long**'s.*
- void [pack](#) (const short \*data, const int num=1)  
*Pack one or more **short**'s.*
- void [pack](#) (const u\_short \*data, const int num=1)  
*Pack one or more **unsigned short**'s.*



- void `pack` (const char \*data, const int num=1)  
*Pack one or more **char**'s.*
- void `pack` (const u\_char \*data, const int num=1)  
*Pack one or more **unsigned char**'s.*
- void `pack` (const double \*data, const int num=1)  
*Pack one or more **double**'s.*
- void `pack` (const float \*data, const int num=1)  
*Pack one or more **fbat**'s.*
- void `pack` (const bool \*data, const int num=1)  
*Pack one or more **bool**'s.*
- void `pack` (const int &data)  
*Pack a **int**.*
- void `pack` (const u\_int &data)  
*Pack a **unsigned int**.*
- void `pack` (const long &data)  
*Pack a **long**.*
- void `pack` (const u\_long &data)  
*Pack a **unsigned long**.*
- void `pack` (const short &data)  
*Pack a **short**.*
- void `pack` (const u\_short &data)  
*Pack a **unsigned short**.*
- void `pack` (const char &data)  
*Pack a **char**.*
- void `pack` (const u\_char &data)  
*Pack a **unsigned char**.*
- void `pack` (const double &data)  
*Pack a **double**.*
- void `pack` (const float &data)  
*Pack a **fbat**.*
- void `pack` (const bool &data)  
*Pack a **bool**.*

## Protected Member Functions

- void [resize](#) (const int newsize)  
*Resizes the internal buffer.*

## Protected Attributes

- char \* [Buffer](#)  
*The internal buffer for packing.*
- int [Index](#)  
*The index into the current buffer.*
- int [Size](#)  
*The total size that has been allocated for the buffer.*

### 8.65.1 Detailed Description

Class for packing MPI message buffers.

A class that provides a facility for packing message buffers using the MPI\_Pack facility. The [MPIPackBuffer](#) class dynamically resizes the internal buffer to contain enough memory to pack the entire object. When deleted, the [MPIPackBuffer](#) object deletes this internal buffer. This class is based on the Dakota\_Version\_3\_0 version of utilib::PackBuffer from utilib/src/io/PackBuf.[cpp,h]

The documentation for this class was generated from the following files:

- MPIPackBuffer.H
- MPIPackBuffer.C

## 8.66 MPIUnpackBuffer Class Reference

Class for unpacking MPI message buffers.

### Public Member Functions

- void **setup** (char \*buf\_, int size\_, bool flag\_=false)  
*Method that does the setup for the constructors.*
- **MPIUnpackBuffer** ()  
*Default constructor.*
- **MPIUnpackBuffer** (int size\_)  
*Constructor that specifies the size of the buffer.*
- **MPIUnpackBuffer** (char \*buf\_, int size\_, bool flag\_=false)  
*Constructor that sets the internal buffer to the given array.*
- **~MPIUnpackBuffer** ()  
*Destructor.*
- void **resize** (const int newsize)  
*Resizes the internal buffer.*
- const char \* **buf** ()  
*Returns a pointer to the internal buffer.*
- int **size** ()  
*Returns the length of the buffer.*
- int **curr** ()  
*Returns the number of bytes that have been unpacked from the buffer.*
- void **reset** ()  
*Resets the index of the internal buffer.*
- void **unpack** (int \*data, const int num=1)  
*Unpack one or more **int**'s.*
- void **unpack** (u\_int \*data, const int num=1)  
*Unpack one or more **unsigned int**'s.*

- void **unpack** (long \*data, const int num=1)  
*Unpack one or more **long**'s.*
- void **unpack** (u\_long \*data, const int num=1)  
*Unpack one or more **unsigned long**'s.*
- void **unpack** (short \*data, const int num=1)  
*Unpack one or more **short**'s.*
- void **unpack** (u\_short \*data, const int num=1)  
*Unpack one or more **unsigned short**'s.*
- void **unpack** (char \*data, const int num=1)  
*Unpack one or more **char**'s.*
- void **unpack** (u\_char \*data, const int num=1)  
*Unpack one or more **unsigned char**'s.*
- void **unpack** (double \*data, const int num=1)  
*Unpack one or more **double**'s.*
- void **unpack** (float \*data, const int num=1)  
*Unpack one or more **float**'s.*
- void **unpack** (bool \*data, const int num=1)  
*Unpack one or more **bool**'s.*
- void **unpack** (int &data)  
*Unpack a **int**.*
- void **unpack** (u\_int &data)  
*Unpack a **unsigned int**.*
- void **unpack** (long &data)  
*Unpack a **long**.*
- void **unpack** (u\_long &data)  
*Unpack a **unsigned long**.*
- void **unpack** (short &data)  
*Unpack a **short**.*
- void **unpack** (u\_short &data)  
*Unpack a **unsigned short**.*
- void **unpack** (char &data)

*Unpack a char.*

- void `unpack` (u\_char &data)  
*Unpack a unsigned char.*
- void `unpack` (double &data)  
*Unpack a double.*
- void `unpack` (float &data)  
*Unpack a float.*
- void `unpack` (bool &data)  
*Unpack a bool.*

## Protected Attributes

- char \* `Buffer`  
*The internal buffer for unpacking.*
- int `Index`  
*The index into the current buffer.*
- int `Size`  
*The total size that has been allocated for the buffer.*
- bool `ownFlag`  
*If TRUE, then this class owns the internal buffer.*

### 8.66.1 Detailed Description

Class for unpacking MPI message buffers.

A class that provides a facility for unpacking message buffers using the MPI\_Unpack facility. This class is based on the Dakota\_Version\_3\_0 version of utilib::UnPackBuffer from utilib/src/io/PackBuf.[cpp,h]

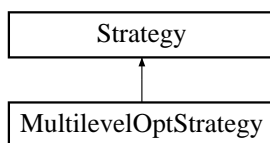
The documentation for this class was generated from the following files:

- MPIPackBuffer.H
- MPIPackBuffer.C

## 8.67 MultilevelOptStrategy Class Reference

multiple models of varying fidelity.

Inheritance diagram for MultilevelOptStrategy::



### Public Member Functions

- [MultilevelOptStrategy \(ProblemDescDB &problem\\_db\)](#)  
*constructor*
- [~MultilevelOptStrategy \(\)](#)  
*destructor*
- void [run\\_strategy \(\)](#)  
*iterators on different models of varying fidelity*
- const [Variables & variables\\_results \(\)](#) const  
*return the final solution from selectedIterators (variables)*
- const [Response & response\\_results \(\)](#) const  
*return the final solution from selectedIterators (response)*

### Private Member Functions

- void [run\\_coupled \(\)](#)  
*run a tightly coupled hybrid*
- void [run\\_uncoupled \(\)](#)  
*run an uncoupled hybrid*
- void [run\\_uncoupled\\_adaptive \(\)](#)  
*run an uncoupled adaptive hybrid*

## Private Attributes

- [String multiLevelType](#)  
*coupled, uncoupled, or uncoupled\_adaptive*
- [StringArray methodList](#)  
*the list of method identifiers*
- [int numIterators](#)  
*number of methods in methodList*
- [size\\_t numSolutionsTransferred](#)  
*to the next iterator*
- [Real localSearchProb](#)  
*phases of the global optimization for coupled hybrids*
- [Real progressMetric](#)  
*an uncoupled adaptive hybrid*
- [Real progressThreshold](#)  
*uncoupled adaptive hybrid switches to the next method*
- [IteratorArray selectedIterators](#)  
*the set of iterators, one for each entry in methodList*
- [ModelArray userDefinedModels](#)  
*the set of models, one for each iterator*

### 8.67.1 Detailed Description

multiple models of varying fidelity.

This strategy has three approaches to hybrid optimization: (1) the uncoupled hybrid runs one method to completion, passes its best results as the starting point for a subsequent method, and continues this succession until all methods have been executed; (2) the uncoupled adaptive hybrid is similar to the uncoupled hybrid, except that the stopping rules for the optimizers are controlled adaptively by the strategy instead of internally by each optimizer; and (3) the coupled hybrid uses multiple methods in close coordination, generally using a local search optimizer repeatedly within a global optimizer (the local search optimizer refines candidate optima which are fed back to the global optimizer). The uncoupled strategies only pass information forward, whereas the coupled strategy allows both feed forward and feedback. Note that while the strategy is targeted at optimizers, any iterator may be used so long as it defines the notion of a final solution which can be passed as the starting point for subsequent iterators.

### 8.67.2 Member Function Documentation

**8.67.2.1 void run\_coupled () [private]**

run a tightly coupled hybrid

In the coupled case, use is made of external hybridization capabilities, such as those available in the global/local hybrids from SGOPT. This function is responsible only for publishing the local optimizer selection to the global optimizer and then invoking the global optimizer; the logic of method switching is handled entirely within the global optimizer. Status: incomplete.

**8.67.2.2 void run\_uncoupled () [private]**

run an uncoupled hybrid

In the uncoupled nonadaptive case, there is no interference with the iterators. Each runs until its own convergence criteria is satisfied. Status: fully operational.

**8.67.2.3 void run\_uncoupled\_adaptive () [private]**

run an uncoupled adaptive hybrid

In the uncoupled adaptive case, there is interference with the iterators through the use of the ++ overloaded operator. iterator++ runs the iterator for one cycle, after which a progress\_metric is computed. This progress metric is used to dictate method switching instead of each iterator's internal convergence criteria. Status: incomplete.

The documentation for this class was generated from the following files:

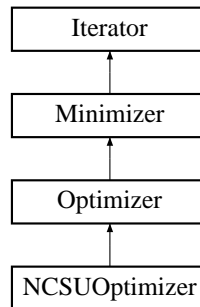
- MultilevelOptStrategy.H
- MultilevelOptStrategy.C



## 8.68 NCSUOptimizer Class Reference

Wrapper class for the NCSU DIRECT optimization library.

Inheritance diagram for NCSUOptimizer::



### Public Member Functions

- [NCSUOptimizer](#) ([Model](#) &model)  
*standard constructor*
- [NCSUOptimizer](#) ([Model](#) &model, const int &max\_iterations, const int &max\_fn\_evals)  
*alternate constructor for instantiations "on the fly"*
- [NCSUOptimizer](#) (const [RealVector](#) &var\_lower\_bnds, const [RealVector](#) &var\_upper\_bnds, const int &max\_iterations, const int &max\_fn\_eval, void(\*user\_obj\_eval)(int &, double \*, double &, int &, int \*, int &, double \*, int &, char \*, int &))  
*alternate constructor for instantiations "on the fly"*
- [~NCSUOptimizer](#) ()  
*destructor*
- void [find\\_optimum](#) ()  
*Redefines the run virtual function for the optimizer branch.*

### Private Member Functions

- void [find\\_optimum\\_on\\_model](#) ()  
*called by find\_optimum for setUpType == "model"*
- void [find\\_optimum\\_on\\_user\\_functions](#) ()

called by *find\_optimum* for *setUpType* == "user\_functions"

## Static Private Member Functions

- static void [objective\\_eval](#) (int &n, double \*x, double &f, int &flag, int \*idata, int &isize, double \*ddata, int &dsize, char \*cdata, int &csize)  
*objective function (passed by function pointer to NCSUDirect).*

## Private Attributes

- String [setUpType](#)  
*GaussProcApproximation currently uses the user\_functions mode.*
- int [maxIterations](#)  
*holds maximum number of iterations allowed*
- int [maxFunctionEvals](#)  
*holds maximum number of function evaluations allowed*
- Real [minBoxSize](#)  
*holds the minimum boxsize*
- Real [volBoxSize](#)  
*hold the minimum volume boxsize*
- Real [solutionAccuracy](#)  
*holds the solution tolerance accuracy*
- RealVector [lowerBounds](#)  
*holds variable lower bounds passed in for "user\_functions" mode.*
- RealVector [upperBounds](#)  
*holds variable upper bounds passed in for "user\_functions" mode.*
- void(\* [userObjectiveEval](#) )(int &, double \*, double &, int &, int \*, int &, double \*, int &, char \*, int &)  
*"user\_functions" mode.*

## Static Private Attributes

- static [NCSUOptimizer](#) \* [ncsudirectInstance](#)  
*functions in order to avoid the need for static data*

### 8.68.1 Detailed Description

Wrapper class for the NCSU DIRECT optimization library.

The [NCSUOptimizer](#) class provides a wrapper for a Fortran 77 implementation of the DIRECT algorithm developed at North Carolina State University. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function or accessed through a static pointer.

The user input mappings are as follows:

### 8.68.2 Constructor & Destructor Documentation

#### 8.68.2.1 [NCSUOptimizer](#) ([Model](#) & *model*, const int & *max\_iterations*, const int & *max\_fn\_evals*)

alternate constructor for instantiations "on the fly"

This is an alternate constructor for instantiations on the fly using a [Model](#) but no [ProblemDescDB](#).

#### 8.68.2.2 [NCSUOptimizer](#) (const [RealVector](#) & *var\_lower\_bnds*, const [RealVector](#) & *var\_upper\_bnds*, const int & *max\_iterations*, const int & *max\_fn\_evals*, void(\*)*(int &, double \*, double &, int &, int \*, int &, double \*, int &, char \*, int &)* *user\_obj\_eval*)

alternate constructor for instantiations "on the fly"

This is an alternate constructor for performing an optimization using the passed in objective function pointer.

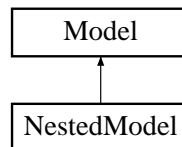
The documentation for this class was generated from the following files:

- [NCSUOptimizer.H](#)
- [NCSUOptimizer.C](#)

## 8.69 NestedModel Class Reference

execution within every evaluation of the model.

Inheritance diagram for NestedModel::



### Public Member Functions

- [NestedModel \(ProblemDescDB &problem\\_db\)](#)  
*constructor*
- [~NestedModel \(\)](#)  
*destructor*

### Protected Member Functions

- void [derived\\_compute\\_response](#) (const [ActiveSet](#) &set)  
*portion of compute\_response() specific to NestedModel*
- void [derived\\_async\\_compute\\_response](#) (const [ActiveSet](#) &set)  
*portion of async\_compute\_response() specific to NestedModel*
- [Iterator](#) & [subordinate\\_iterator](#) ()  
*return subIterator*
- void [derived\\_subordinate\\_models](#) ([ModelList](#) &ml, bool recurse\_flag)  
*return subModel*
- [Interface](#) & [interface](#) ()  
*return optionalInterface*
- void [surrogate\\_bypass](#) (bool bypass\_flag)  
*to the subModel for any lower-level surrogates.*
- void [component\\_parallel\\_mode](#) (short mode)

*optionalInterface and subModel*

- bool [derived\\_master\\_overload](#) () const  
*evaluation (forwarded to optionalInterface)*
- void [derived\\_init\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*set up optionalInterface and subModel for parallel operations*
- void [derived\\_init\\_serial](#) ()  
*set up optionalInterface and subModel for serial operations.*
- void [derived\\_set\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*set active parallel configuration within subModel*
- void [derived\\_free\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*(forwarded to optionalInterface and subModel)*
- void [serve](#) ()  
*stop\_servers().*
- void [stop\\_servers](#) ()  
*optionalInterface when iteration on the [NestedModel](#) is complete.*
- const [String](#) & [interface\\_id](#) () const  
*return the optionalInterface identifier*
- int [evaluation\\_id](#) () const  
*Return the current evaluation id for the [NestedModel](#).*
- void [set\\_evaluation\\_reference](#) ()  
*(request forwarded to optionalInterface and subModel)*
- void [print\\_evaluation\\_summary](#) (ostream &s, bool minimal\_header=false, bool relative\_count=true) const  
*(request forwarded to optionalInterface and subModel)*

### Private Member Functions

- void [asv\\_mapping](#) (const [ShortArray](#) &mapped\_asv, [ShortArray](#) &interface\_asv, [ShortArray](#) &sub\_iterator\_asv)  
*total model evaluation requirements (mapped\_asv)*
- void [response\\_mapping](#) (const [Response](#) &interface\_response, const [Response](#) &sub\_iterator\_response, [Response](#) &mapped\_response)  
*mappings to create the total response for the model*

- void `update_sub_model ()`  
*update subModel with current variable values/bounds/labels*

## Private Attributes

- int `nestedModelEvals`  
*derived\_async\_compute\_response()*
- Iterator `subIterator`  
*the sub-iterator that is executed on every evaluation of this model*
- Model `subModel`  
*the sub-model used in sub-iterator evaluations*
- size\_t `numSubIterFns`  
*number of sub-iterator response functions prior to mapping*
- size\_t `numSubIterMappedIneqCon`  
*sub-iteration results*
- size\_t `numSubIterMappedEqCon`  
*sub-iteration results*
- Interface `optionalInterface`  
*the total model response*
- String `optInterfacePointer`  
*the optional interface pointer from the nested model specification*
- Response `optInterfaceResponse`  
*the response object resulting from optional interface evaluations*
- size\_t `numOptInterfPrimary`  
*functions) resulting from optional interface evaluations*
- size\_t `numOptInterfIneqCon`  
*interface evaluations*
- size\_t `numOptInterfEqCon`  
*interface evaluations*
- SizerArray `primaryCVarMapIndices`  
*replace the subModel variable values.*

- [SizetArray primaryDVarMapIndices](#)  
*insertions replace the subModel variable values.*
- [SizetArray secondaryVarMapIndices](#)  
*for uncertain variables) of the active continuous subModel variables.*
- `size_t subModelCVOffset`  
*mappings when the subModel is in an All variables view.*
- `size_t subModelDVOffset`  
*mappings when the subModel is in an All variables view.*
- [RealMatrix primaryRespCoeffs](#)  
*generic response terms.*
- [RealMatrix secondaryRespCoeffs](#)  
*contributions to the top-level inequality and equality constraints.*

### 8.69.1 Detailed Description

execution within every evaluation of the model.

The [NestedModel](#) class nests a sub-iterator execution within every model evaluation. This capability is most commonly used for optimization under uncertainty, in which a nondeterministic iterator is executed on every optimization function evaluation. The [NestedModel](#) also contains an optional interface, for portions of the model evaluation which are independent from the sub-iterator, and a set of mappings for combining sub-iterator and optional interface data into a top level response for the model.

### 8.69.2 Member Function Documentation

#### 8.69.2.1 `void derived_compute_response (const ActiveSet & set) [protected, virtual]`

portion of `compute_response()` specific to [NestedModel](#)

Update subModel's inactive variables with active variables from currentVariables, compute the optional interface and sub-iterator responses, and map these to the total model response.

Reimplemented from [Model](#).

#### 8.69.2.2 `void derived_async_compute_response (const ActiveSet & set) [protected, virtual]`

portion of `async_compute_response()` specific to [NestedModel](#)

Not currently supported by NestedModels (need to add concurrent iterator support). As a result, [derived\\_synchronize\(\)](#) and [derived\\_synchronize\\_nowait\(\)](#) are inactive as well).

Reimplemented from [Model](#).

### 8.69.2.3 `bool derived_master_overload () const` [inline, protected, virtual]

evaluation (forwarded to optionalInterface)

Derived master overload for subModel is handled separately in `subModel.compute_response()` within `subIterator.run()`.

Reimplemented from [Model](#).

### 8.69.2.4 `void derived_init_communicators (const int & max_iterator_concurrency, bool recurse_flag = true)` [inline, protected, virtual]

set up optionalInterface and subModel for parallel operations

Asynchronous flags need to be initialized for the subModel. In addition, `max_iterator_concurrency` is the outer level iterator concurrency, not the subIterator concurrency that subModel will see, and recomputing the message\_lengths on the subModel is probably not a bad idea either. Therefore, recompute everything on subModel using [init\\_communicators\(\)](#).

Reimplemented from [Model](#).

### 8.69.2.5 `int evaluation_id () const` [inline, protected, virtual]

Return the current evaluation id for the [NestedModel](#).

return the top level nested evaluation count. To get the lower level eval count, the subModel must be explicitly queried. This is consistent with the eval counter definitions in surrogate models.

Reimplemented from [Model](#).

### 8.69.2.6 `void response_mapping (const Response & opt_interface_response, const Response & sub_iterator_response, Response & mapped_response)` [private]

mappings to create the total response for the model

In the OUU case,

```
optionalInterface fns = {f}, {g} (deterministic primary functions, constraints)
subIterator fns      = {S}      (UQ response statistics)
```

Problem formulation for mapped functions:

```
minimize    {f} + [W]{S}
subject to  {g_l} <= {g}    <= {g_u}
            {a_l} <= [A]{S} <= {a_u}
            {g}    == {g_t}
            [A]{S} == {a_t}
```



where  $[W]$  is the `primary_mapping_matrix` user input (`primaryRespCoeffs` class attribute),  $[A]$  is the `secondary_mapping_matrix` user input (`secondaryRespCoeffs` class attribute),  $\{g_l, a_l\}$  are the top level inequality constraint lower bounds,  $\{g_u, a_u\}$  are the top level inequality constraint upper bounds, and  $\{g_t, a_t\}$  are the top level equality constraint targets.

NOTE: optionalInterface/subIterator primary fns (obj/lsg/generic fns) overlap but optionalInterface/subIterator secondary fns (ineq/eq constraints) do not. The  $[W]$  matrix can be specified so as to allow

- some purely deterministic primary functions and some combined:  $[W]$  filled and  $[W].num\_rows() < \{f\}.length()$  [combined first] *or*  $[W].num\_rows() == \{f\}.length()$  and  $[W]$  contains rows of zeros [combined last]
- some combined and some purely stochastic primary functions:  $[W]$  filled and  $[W].num\_rows() > \{f\}.length()$
- separate deterministic and stochastic primary functions:  $[W].num\_rows() > \{f\}.length()$  and  $[W]$  contains  $\{f\}.length()$  rows of zeros.

If the need arises, could change constraint definition to allow overlap as well:  $\{g_l\} \leq \{g\} + [A]\{S\} \leq \{g_u\}$  with  $[A]$  usage the same as for  $[W]$  above.

In the UOO case, things are simpler, just compute statistics of each optimization response function:  $[W] = [I]$ ,  $\{f\}/\{g\}/[A]$  are empty.

### 8.69.3 Member Data Documentation

#### 8.69.3.1 `Model subModel` [private]

the sub-model used in sub-iterator evaluations

There are no restrictions on `subModel`, so arbitrary nestings are possible. This is commonly used to support surrogate-based optimization under uncertainty by having `NestedModels` contain `SurrogateModels` and vice versa.

The documentation for this class was generated from the following files:

- `NestedModel.H`
- `NestedModel.C`

## 8.70 NL2Misc Struct Reference

Auxiliary information passed to `calcr` and `calcj` via `ur`.

### Public Attributes

- Real \* `J` [2]  
*cache the two most recent Jacobian values in speculative-evaluation mode*
- int `nf` [2]  
*function-evaluation counts corresponding to cached Jacobian values (used to tell which J value to use)*
- int `specgrad`  
*whether to cache J values (0 == no, 1 == yes)*

### 8.70.1 Detailed Description

Auxiliary information passed to `calcr` and `calcj` via `ur`.

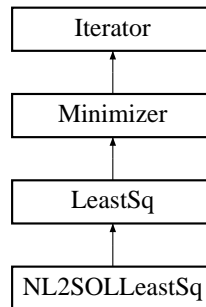
The documentation for this struct was generated from the following file:

- `NL2SOLLeastSq.C`

## 8.71 NL2SOLLeastSq Class Reference

Wrapper class for the NL2SOL nonlinear least squares library.

Inheritance diagram for NL2SOLLeastSq::



### Public Member Functions

- [NL2SOLLeastSq](#) ([Model](#) &model)  
*standard constructor*
- [~NL2SOLLeastSq](#) ()  
*destructor*
- void [minimize\\_residuals](#) ()  
*for the least squares branch.*

### Static Private Member Functions

- static void [calcr](#) (int \*np, int \*pp, Real \*x, int \*nfp, Real \*r, int \*ui, void \*ur, Vf vf)  
*evaluator function for residual vector*
- static void [calcj](#) (int \*np, int \*pp, Real \*x, int \*nfp, Real \*J, int \*ui, void \*ur, Vf vf)  
*evaluator function for residual Jacobian*

### Private Attributes

- int [auxprt](#)

auxiliary printing bits (see [Dakota Ref Manual](#)): sum of 1 = x0prt (print initial guess) 2 = solprt (print final solution) 4 = statpr (print solution statistics) 8 = parprt (print nondefault parameters) 16 = dradpr (print bound constraint drops/adds) debug/verbose/normal use default = 31 (everything), quiet uses 3, silent uses 0.

- int [outlev](#)  
frequency of output summary lines in number of iterations (debug/verbose/normal/quiet use default = 1, silent uses 0)
- Real [dltfdj](#)  
finite-diff step size for computing Jacobian approximation (fd\_gradient\_step\_size)
- Real [delta0](#)  
finite-diff step size for gradient differences for H (a component of some covariance approximations, if desired) (fd\_hessian\_step\_size)
- Real [dltfdc](#)  
finite-diff step size for function differences for H (fd\_hessian\_step\_size)
- int [mxfcsl](#)  
function-evaluation limit (max\_function\_evaluations)
- int [mxiter](#)  
iteration limit (max\_iterations)
- Real [rfctol](#)  
relative fn convergence tolerance (convergence\_tolerance)
- Real [afctol](#)  
absolute fn convergence tolerance (absolute\_conv\_tol)
- Real [xctol](#)  
x-convergence tolerance (x\_conv\_tol)
- Real [sctol](#)  
singular convergence tolerance (singular\_conv\_tol)
- Real [lmaxs](#)  
radius for singular-convergence test (singular\_radius)
- Real [xftol](#)  
false-convergence tolerance (false\_conv\_tol)
- int [covreq](#)  
kind of covariance required (covariance): 1 or -1 ==>  $\sigma^2 H^{-1} J^T J H^{-1}$  2 or -2 ==>  $\sigma^2 H^{-1}$  3 or -3 ==>  $\sigma^2 (J^T J)^{-1}$  1 or 2 ==> use gradient diffs to estimate H -1 or -2 ==> use function diffs to estimate H default = 0 (no covariance)

- int `rdreq`  
*whether to compute the regression diagnostic vector (regression\_diagnostics)*
- Real `fprec`  
*expected response function precision (function\_precision)*
- Real `lmax0`  
*initial trust-region radius (initial\_trust\_radius)*

### Static Private Attributes

- static `NL2SOLLeastSq * nl2solInstance`  
*evaluator functions*

#### 8.71.1 Detailed Description

Wrapper class for the NL2SOL nonlinear least squares library.

The `NL2SOLLeastSq` class provides a wrapper for NL2SOL (TOMS Algorithm 573), in the updated form of Port Library routines `dn[fg][b ]` from Bell Labs; see <http://www.netlib.org/port/readme>. The Fortran from Port has been turned into C by `f2c`. NL2SOL uses a function pointer approach for which passed functions must be either global functions or static member functions.

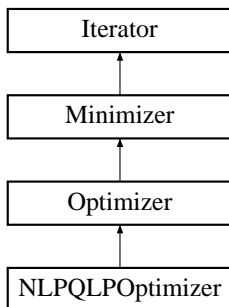
The documentation for this class was generated from the following files:

- `NL2SOLLeastSq.H`
- `NL2SOLLeastSq.C`

## 8.72 NLPQLPOptimizer Class Reference

Wrapper class for the NLPQLP optimization library, Version 2.0.

Inheritance diagram for NLPQLPOptimizer::



### Public Member Functions

- [NLPQLPOptimizer \(Model &model\)](#)  
*constructor*
- [~NLPQLPOptimizer \(\)](#)  
*destructor*
- void [find\\_optimum \(\)](#)  
*Redefines the run virtual function for the optimizer branch.*

### Protected Member Functions

- virtual void [derived\\_pre\\_run \(\)](#)  
*performs run-time set up*

### Private Member Functions

- void [allocate\\_workspace \(\)](#)  
*Allocates workspace for the optimizer.*
- void [deallocate\\_workspace \(\)](#)  
*Releases workspace memory.*

- void `allocate_constraints` ()  
*Allocates constraint mappings.*

### Private Attributes

- int `L`  
*the serial version by setting  $L=1$ .*
- int `numEqConstraints`  
*numEqConstraints : Number of equality constraints.*
- int `MMAX`  
*MMAX must be at least one and greater or equal to  $M$ .*
- int `N`  
 *$N$  : Number of optimization variables.*
- int `NMAX`  
*than  $N$ .*
- int `MNN2`  
*MNN2 : Must be equal to  $M+N+N+2$ .*
- double \* `X`  
*function values should be computed simultaneously.*
- double \* `F`  
*values to be computed from  $L$  iterates stored in  $X$ .*
- double \* `G`  
*function values to be computed from  $L$  iterates stored in  $X$ .*
- double \* `DF`  
*of  $F$  to compute  $DF$ .*
- double \* `DG`  
*has to be equal to  $MMAX$ .*
- double \* `U`  
*inequality constraints should be nonnegative.*
- double \* `C`  
*to  $NMAX$ .*

- double \* **D**  
*array D.*
- double **ACC**  
*than the accuracy by which gradients are computed.*
- double **ACCQP**  
*by NLPQLP and subsequently multiplied by 1.0D+4.*
- double **STPMIN**  
*by STPMIN\*\*((1/L-1). If STPMIN<=0, then STPMIN=ACC is used.*
- int **MAXFUN**  
*than 50.*
- int **MAXIT**  
*gradients (e.g. 100).*
- int **MAX\_NM**  
*MAX\_NM=0, monotone line search is performed.*
- double **TOL\_NM**  
*non-negative (e.g. 0.1).*
- int **IPRINT**  
*values are displayed during the line search.*
- int **MODE**  
*function in C and D in form of an LDL decomposition.*
- int **IOUT**  
*write-statements start with 'WRITE(IOUT,...) '.*
- int **IFAIL**  
*constraint.*
- double \* **WA**  
*WA(LWA) : WA is a real working array of length LWA.*
- int **LWA**  
*LWA : LWA value extracted from NLPQLP20.f.*
- int \* **KWA**  
*KWA(LKWA) : The user has to provide working space for an integer array.*
- int **LKWA**



*LKWA : LKWA should be at least  $N+10$ .*

- int \* **ACTIVE**  
*ACTIVE(J)=TRUE., J=1,...,M.*
- int **LACTIVE**  
*least  $2*M+10$ .*
- int **LQL**  
*contains only an upper triangular factor.*
- int **numNlpqConstr**  
*total number of constraints seen by NLPQL*
- **SizeList nonlinIneqConMappingIndices**  
*constraints used in computing the corresponding NLPQL constraints.*
- **RealList nonlinIneqConMappingMultipliers**  
*constraints to the corresponding NLPQL constraints.*
- **RealList nonlinIneqConMappingOffsets**  
*constraints to the corresponding NLPQL constraints.*
- **SizeList linIneqConMappingIndices**  
*constraints used in computing the corresponding NLPQL constraints.*
- **RealList linIneqConMappingMultipliers**  
*constraints to the corresponding NLPQL constraints.*
- **RealList linIneqConMappingOffsets**  
*constraints to the corresponding NLPQL constraints.*

### 8.72.1 Detailed Description

Wrapper class for the NLPQLP optimization library, Version 2.0.

\*\*\*\*\*

AN IMPLEMENTATION OF A SEQUENTIAL QUADRATIC PROGRAMMING METHOD FOR SOLVING  
NONLINEAR OPTIMIZATION PROBLEMS BY DISTRIBUTED COMPUTING AND NON-MONOTONE  
LINE SEARCH

This subroutine solves the general nonlinear programming problem

minimize  $F(X)$  subject to  $G(J,X) = 0$ ,  $J=1,\dots,ME$   $G(J,X) \geq 0$ ,  $J=ME+1,\dots,M$   $XL \leq X \leq XU$

and is an extension of the code NLPQLD. NLPQLP is specifically tuned to run under distributed systems. A new input parameter L is introduced for the number of parallel computers, that is the number of function calls to be

executed simultaneously. In case of  $L=1$ , NLPQLP is identical to NLPQLD. Otherwise the line search is modified to allow  $L$  parallel function calls in advance. Moreover the user has the opportunity to use distributed function calls for evaluating gradients.

The algorithm is a modification of the method of Wilson, Han, and Powell. In each iteration step, a linearly constrained quadratic programming problem is formulated by approximating the Lagrangian function quadratically and by linearizing the constraints. Subsequently, a one-dimensional line search is performed with respect to an augmented Lagrangian merit function to obtain a new iterate. Also the modified line search algorithm guarantees convergence under the same assumptions as before.

For the new version, a non-monotone line search is implemented which allows to increase the merit function in case of instabilities, for example caused by round-off errors, errors in gradient approximations, etc.

The subroutine contains the option to predetermine initial guesses for the multipliers or the Hessian of the Lagrangian function and is called by reverse communication.

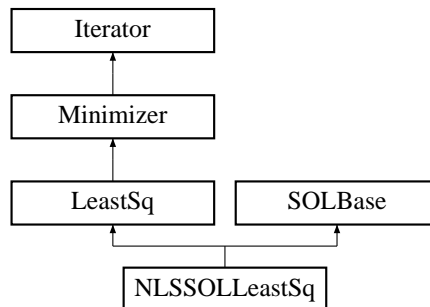
The documentation for this class was generated from the following files:

- NLPQLPOptimizer.H
- NLPQLPOptimizer.C

## 8.73 NLSSOLLeastSq Class Reference

Wrapper class for the NLSSOL nonlinear least squares library.

Inheritance diagram for NLSSOLLeastSq::



### Public Member Functions

- [NLSSOLLeastSq \(Model &model\)](#)  
*standard constructor*
- [~NLSSOLLeastSq \(\)](#)  
*destructor*
- void [minimize\\_residuals \(\)](#)  
*for the least squares branch.*

### Static Private Member Functions

- static void [least\\_sq\\_eval](#) (int &mode, int &m, int &n, int &nrowfj, double \*x, double \*f, double \*gradf, int &nstate)  
*least squares terms (passed by function pointer to NLSSOL).*

### Static Private Attributes

- static [NLSSOLLeastSq \\* nlssolInstance](#)  
*functions in order to avoid the need for static data*

### 8.73.1 Detailed Description

Wrapper class for the NLSSOL nonlinear least squares library.

The `NLSSOLLeastSq` class provides a wrapper for NLSSOL, a Fortran 77 sequential quadratic programming library from Stanford University marketed by Stanford Business Associates. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any nonstatic attribute used within static member functions must be either local to that function or accessed through a static pointer.

The user input mappings are as follows: `max_function_evaluations` is implemented directly in `NLSSOLLeastSq`'s evaluator functions since there is no NLSSOL parameter equivalent, and `max_iterations`, `convergence_tolerance`, `output_verbosity`, `verify_level`, `function_precision`, and `linesearch_tolerance` are mapped into NLSSOL's "Major Iteration Limit", "Optimality Tolerance", "Major Print Level" (`verbose`: Major Print Level = 20; `quiet`: Major Print Level = 10), "Verify Level", "Function Precision", and "Linesearch Tolerance" parameters, respectively, using NLSSOL's `npoptn()` subroutine (as wrapped by `npoptn2()` from the `npoptn_wrapper.f` file). Refer to [Gill, P.E., Murray, W., Saunders, M.A., and Wright, M.H., 1986] for information on NLSSOL's optional input parameters and the `npoptn()` subroutine.

The documentation for this class was generated from the following files:

- `NLSSOLLeastSq.H`
- `NLSSOLLeastSq.C`

## 8.74 NoDBBaseConstructor Struct Reference

Dummy struct for overloading constructors used in on-the-fly instantiations.

### Public Member Functions

- [NoDBBaseConstructor](#) (int=0)  
*C++ structs can have constructors.*

### 8.74.1 Detailed Description

Dummy struct for overloading constructors used in on-the-fly instantiations.

[NoDBBaseConstructor](#) is used to overload the constructor used for on-the-fly instantiations in which [ProblemDescDB](#) queries cannot be used. Putting this struct here avoids circular dependencies.

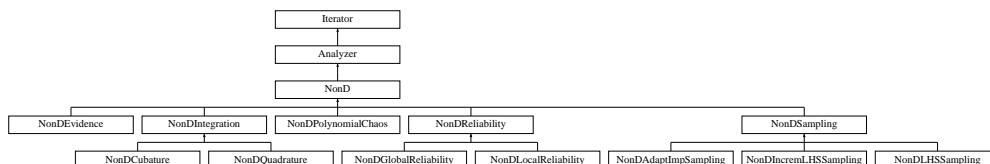
The documentation for this struct was generated from the following file:

- `global_defs.h`

## 8.75 NonD Class Reference

Base class for all nondeterministic iterators (the DAKOTA/UQ branch).

Inheritance diagram for NonD::



### Public Member Functions

- void `initialize_random_variables ()`  
*iteratedModel (corrCholeskyFactorZ and correlationFlagX set separately)*
- void `initialize_random_variables (const ShortArray &x_types, const ShortArray &u_types, const Epetra_SerialDenseVector &x_means, const Epetra_SerialDenseVector &x_std_devs, const Epetra_SerialDenseVector &x_l_bnds, const Epetra_SerialDenseVector &x_u_bnds, const Array< Epetra_SerialDenseVector > &x_addtl, const Epetra_SerialDenseMatrix &z_chol_fact, bool x_corr_flag, bool ext_u_space)`  
*correlationFlagX, and extendedUSpace based on incoming data*
- void `requested_levels (const RealVectorArray &req_resp_levels, const RealVectorArray &req_prob_levels, const RealVectorArray &req_rel_levels, const RealVectorArray &req_gen_rel_levels, short resp_lev_target, bool cdf_flag)`  
*combination with alternate ctors)*
- void `moments (const RealVector &means, const RealVector &std_devs)`  
*set meanStats and stdDevStats*

### Protected Member Functions

- `NonD (Model &model)`  
*constructor*
- `NonD (NoDBBaseConstructor, Model &model)`  
*alternate constructor for sample generation and evaluation "on the fly"*
- `NonD (NoDBBaseConstructor, const RealVector &lower_bnds, const RealVector &upper_bnds)`  
*alternate constructor for sample generation "on the fly"*

- `~NonD ()`  
*destructor*
- `void run ()`  
*invoke quantify\_uncertainty*
- `const Response & response_results () const`  
*return the final statistics from the nondeterministic iteration*
- `void response_results_active_set (const ActiveSet &set)`  
*set the active set within finalStatistics*
- `virtual void quantify_uncertainty ()=0`  
*distributions into response statistics*
- `virtual void initialize_final_statistics ()`  
*initializes finalStatistics for storing NonD final results*
- `void initialize_random_variable_types ()`  
*initializes ranVarTypesX and ranVarTypesU*
- `void initialize_random_variable_parameters ()`  
*ranVarUpperBndsX, and ranVarAddtlParamsX*
- `void reshape_correlation_matrix ()`  
*reshape corrMatrix for an all\_variables specification*
- `void trans_U_to_X (const Epetra_SerialDenseVector &u_vars, Epetra_SerialDenseVector &x_vars)`  
*variables to x-space of correlated random variables*
- `void trans_U_to_X (const RealVector &u_vars, RealVector &x_vars)`  
*Overloaded form using RealVectors.*
- `void trans_U_to_Z (const Epetra_SerialDenseVector &u_vars, Epetra_SerialDenseVector &z_vars)`  
*variables to z-space of correlated standard normal variables*
- `void trans_Z_to_X (const Epetra_SerialDenseVector &z_vars, Epetra_SerialDenseVector &x_vars)`  
*variables to x-space of correlated random variables*
- `void trans_X_to_U (const Epetra_SerialDenseVector &x_vars, Epetra_SerialDenseVector &u_vars)`  
*to u-space of uncorrelated standard normal variables*
- `void trans_X_to_U (const RealVector &x_vars, RealVector &u_vars)`  
*Overloaded form using RealVectors.*

- void [trans\\_X\\_to\\_Z](#) (const Epetra\_SerialDenseVector &x\_vars, Epetra\_SerialDenseVector &z\_vars)  
*to z-space of correlated standard normal variables*
- void [trans\\_Z\\_to\\_U](#) (Epetra\_SerialDenseVector &z\_vars, Epetra\_SerialDenseVector &u\_vars)  
*variables to u-space of uncorrelated standard normal variables*
- void [trans\\_correlations](#) ()  
*and decomposes it into its Cholesky factor (corrCholeskyFactorZ).*
- void [trans\\_grad\\_X\\_to\\_U](#) (const Epetra\_SerialDenseVector &fn\_grad\_x, Epetra\_SerialDenseVector &fn\_grad\_u, const Epetra\_SerialDenseVector &x\_vars)  
*Transformation routine for gradient vector from x-space to u-space.*
- void [trans\\_grad\\_U\\_to\\_X](#) (const Epetra\_SerialDenseVector &fn\_grad\_u, Epetra\_SerialDenseVector &fn\_grad\_x, const Epetra\_SerialDenseVector &x\_vars)  
*Transformation routine for gradient vector from u-space to x-space.*
- void [trans\\_hess\\_X\\_to\\_U](#) (const Epetra\_SerialSymDenseMatrix &fn\_hess\_x, Epetra\_SerialSymDenseMatrix &fn\_hess\_u, const Epetra\_SerialDenseVector &x\_vars, const Epetra\_SerialDenseVector &fn\_grad\_x)  
*Transformation routine for Hessian matrix from x-space to u-space.*
- void [jacobian\\_dX\\_dU](#) (const Epetra\_SerialDenseVector &x\_vars, Epetra\_SerialDenseMatrix &jacobian\_xu)  
*Jacobian of  $x(u)$  mapping obtained from  $dX/dZ dZ/dU$ .*
- void [jacobian\\_dX\\_dZ](#) (const Epetra\_SerialDenseVector &x\_vars, Epetra\_SerialDenseMatrix &jacobian\_xz)  
*Jacobian of  $x(z)$  mapping obtained from differentiation of [trans\\_Z\\_to\\_X\(\)](#).*
- void [jacobian\\_dU\\_dX](#) (const Epetra\_SerialDenseVector &x\_vars, Epetra\_SerialDenseMatrix &jacobian\_ux)  
*Jacobian of  $u(x)$  mapping obtained from  $dU/dZ dZ/dX$ .*
- void [jacobian\\_dZ\\_dX](#) (const Epetra\_SerialDenseVector &x\_vars, Epetra\_SerialDenseMatrix &jacobian\_zx)  
*Jacobian of  $z(x)$  mapping obtained from differentiation of [trans\\_X\\_to\\_Z\(\)](#).*
- void [hessian\\_d2X\\_dU2](#) (const Epetra\_SerialDenseVector &x\_vars, [Array](#)< Epetra\_SerialSymDenseMatrix > &hessian\_xu)  
*Hessian of  $x(u)$  mapping obtained from  $dZ/dU^T d^2X/dZ^2 dZ/dU$ .*
- void [hessian\\_d2X\\_dZ2](#) (const Epetra\_SerialDenseVector &x\_vars, [Array](#)< Epetra\_SerialSymDenseMatrix > &hessian\_xz)  
*Hessian of  $x(z)$  mapping obtained from differentiation of [jacobian\\_dX\\_dZ\(\)](#).*
- Real [phi](#) (const Real &beta)



*Standard normal density function.*

- Real [Phi](#) (const Real &beta)  
*Standard normal cumulative distribution function.*
- Real [Phi\\_inverse](#) (const Real &p)  
*Inverse of standard normal cumulative distribution function.*
- Real [erf\\_inverse](#) (const Real &p)  
*Inverse of error function used in [Phi\\_inverse\(\)](#).*
- Real [cdf\\_beta\\_Pinv](#) (const Real &normcdf, const Real &alpha, const Real &beta)  
*Inverse of standard beta CDF (not supported by GSL).*

### Static Protected Member Functions

- static void [vars\\_u\\_to\\_x\\_mapping](#) (const [Variables](#) &u\_vars, [Variables](#) &x\_vars)  
*for [NonD](#) Iterators to x-space variables for Models.*
- static void [resp\\_x\\_to\\_u\\_mapping](#) (const [Variables](#) &x\_vars, const [Variables](#) &u\_vars, const [Response](#) &x\_response, [Response](#) &u\_response)  
*static function used to define the approximate subproblem constraints.*

### Protected Attributes

- bool [extendedUSpace](#)  
*std uniforms, std exponentials, std betas, and std gammas.*
- [ShortArray](#) [ranVarTypesX](#)  
*vector of indices indicating the type of each x-space uncertain variable*
- [ShortArray](#) [ranVarTypesU](#)  
*which each x-space variable is transformed*
- [Epetra\\_SerialDenseVector](#) [ranVarMeansX](#)  
*vector of means for all x-space uncertain variables*
- [Epetra\\_SerialDenseVector](#) [ranVarStdDevsX](#)  
*vector of standard deviations for all x-space uncertain variables*
- [Epetra\\_SerialDenseVector](#) [ranVarLowerBndsX](#)  
*vector of distribution lower bounds for selected x-space uncertain vars*

- Epetra\_SerialDenseVector [ranVarUpperBndsX](#)  
*vector of distribution upper bounds for selected x-space uncertain vars*
- [Array< Epetra\\_SerialDenseVector > ranVarAddtlParamsX](#)  
*for selected x-space uncertain variables*
- bool [correlationFlagX](#)  
*uncertain variables*
- Epetra\_SerialDenseMatrix [corrCholeskyFactorZ](#)  
*in [trans\\_correlations\(\)](#) for use in z-space)*
- Epetra\_SerialSymDenseMatrix [corrMatrix](#)  
*Epetra copy of [Model::uncertainCorrelations](#).*
- const Real [Pi](#)  
*the value for Pi used in several numerical routines*
- size\_t [numDesignVars](#)  
*within design variable bounds for All view modes)*
- size\_t [numStateVars](#)  
*within state variable bounds for All view modes)*
- size\_t [numNormalVars](#)  
*number of normal uncertain variables*
- size\_t [numLognormalVars](#)  
*number of lognormal uncertain variables*
- size\_t [numUniformVars](#)  
*number of uniform uncertain variables*
- size\_t [numLoguniformVars](#)  
*number of loguniform uncertain variables*
- size\_t [numTriangularVars](#)  
*number of triangular uncertain variables*
- size\_t [numExponentialVars](#)  
*number of exponential uncertain variables*
- size\_t [numBetaVars](#)  
*number of beta uncertain variables*
- size\_t [numGammaVars](#)

- number of gamma uncertain variables*
- `size_t numGumbelVars`  
*number of gumbel uncertain variables*
- `size_t numFrechetVars`  
*number of frechet uncertain variables*
- `size_t numWeibullVars`  
*number of weibull uncertain variables*
- `size_t numHistogramVars`  
*number of histogram uncertain variables*
- `size_t numIntervalVars`  
*number of interval uncertain variables*
- `size_t numUncertainVars`  
*total number of uncertain variables*
- `size_t numResponseFunctions`  
*number of response functions*
- `RealVector meanStats`  
*means of response functions (calculated in compute\_statistics())*
- `RealVector stdDevStats`  
*std deviations of response functions (calculated in compute\_statistics())*
- `RealVectorArray requestedRespLevels`  
*requested response levels for all response functions*
- `RealVectorArray computedProbLevels`  
*from requestedRespLevels*
- `RealVectorArray computedRelLevels`  
*from requestedRespLevels*
- `RealVectorArray computedGenRelLevels`  
*resulting from requestedRespLevels*
- `short respLevelTarget`  
*or  $z \rightarrow \beta * (GEN\_RELIABILITIES)$*
- `RealVectorArray requestedProbLevels`  
*requested probability levels for all response functions*

- [RealVectorArray requestedRelLevels](#)  
*requested reliability levels for all response functions*
- [RealVectorArray requestedGenRelLevels](#)  
*requested generalized reliability levels for all response functions*
- [RealVectorArray computedRespLevels](#)  
*requestedProbLevels, requestedRelLevels, or requestedGenRelLevels*
- `size_t totalLevelRequests`  
*requestedProbLevels, and requestedRelLevels*
- `bool cdfFlag`  
*cumulative/CDF (true) or complementary/CCDF (false)*
- [Response finalStatistics](#)  
*response means, standard deviations, and probabilities of failure*

### Static Protected Attributes

- `static NonD * nondInstance`  
*functions in order to avoid the need for static data*

### Private Member Functions

- `void distribute_levels (RealVectorArray &levels)`  
*response functions if a short-hand specification is employed.*

#### 8.75.1 Detailed Description

Base class for all nondeterministic iterators (the DAKOTA/UQ branch).

The base class for nondeterministic iterators consolidates uncertain variable data and probabilistic utilities for inherited classes.

#### 8.75.2 Member Function Documentation

**8.75.2.1 void initialize\_random\_variables ()**

iteratedModel (corrCholeskyFactorZ and correlationFlagX set separately)

Build ranVar arrays containing the uncertain variable distribution types and their corresponding means/standard deviations.

**8.75.2.2 void initialize\_final\_statistics () [protected, virtual]**

initializes finalStatistics for storing [NonD](#) final results

Default definition of virtual function (used by sampling, reliability, and polynomial chaos) defines the set of statistical results to include means, standard deviations, and level mappings.

Reimplemented in [NonDEvidence](#).

**8.75.2.3 void initialize\_random\_variable\_types () [protected]**

initializes ranVarTypesX and ranVarTypesU

Build ranVar arrays containing the uncertain variable distribution types and their corresponding means/standard deviations.

**8.75.2.4 void initialize\_random\_variable\_parameters () [protected]**

ranVarUpperBndsX, and ranVarAddtlParamsX

Build ranVar arrays containing the uncertain variable distribution types and their corresponding means/standard deviations.

**8.75.2.5 void trans\_U\_to\_X (const Epetra\_SerialDenseVector & u\_vars, Epetra\_SerialDenseVector & x\_vars) [protected]**

variables to x-space of correlated random variables

This procedure performs the transformation from u to x space. u\_vars is the vector of random variables in uncorrelated standard normal space (u-space). x\_vars is the vector of random variables in the original user-defined x-space.

**8.75.2.6 void trans\_U\_to\_Z (const Epetra\_SerialDenseVector & u\_vars, Epetra\_SerialDenseVector & z\_vars) [protected]**

variables to z-space of correlated standard normal variables

This procedure computes the transformation from u to z space. u\_vars is the vector of random variables in uncorrelated standard normal space (u-space). z\_vars is the vector of random variables in normal space with proper correlations (z-space).

**8.75.2.7 void trans\_Z\_to\_X (const Epetra\_SerialDenseVector & z\_vars, Epetra\_SerialDenseVector & x\_vars) [protected]**

variables to x-space of correlated random variables

This procedure computes the transformation from z to x space. z\_vars is the vector of random variables in normal space with proper correlations (z-space). x\_vars is the vector of random variables in the original user-defined x-space

**8.75.2.8 void trans\_X\_to\_U (const Epetra\_SerialDenseVector & x\_vars, Epetra\_SerialDenseVector & u\_vars) [protected]**

to u-space of uncorrelated standard normal variables

This procedure performs the transformation from x to u space u\_vars is the vector of random variables in uncorrelated standard normal space (u-space). x\_vars is the vector of random variables in the original user-defined x-space.

**8.75.2.9 void trans\_X\_to\_Z (const Epetra\_SerialDenseVector & x\_vars, Epetra\_SerialDenseVector & z\_vars) [protected]**

to z-space of correlated standard normal variables

This procedure performs the transformation from x to z space: z\_vars is the vector of random variables in normal space with proper correlations (z-space). x\_vars is the vector of random variables in the original user-defined x-space.

**8.75.2.10 void trans\_Z\_to\_U (Epetra\_SerialDenseVector & z\_vars, Epetra\_SerialDenseVector & u\_vars) [protected]**

variables to u-space of uncorrelated standard normal variables

This procedure computes the transformation from z to u space. u\_vars is the vector of random variables in uncorrelated standard normal space (u-space). z\_vars is the vector of random variables in normal space with proper correlations (z-space).

**8.75.2.11 void trans\_correlations () [protected]**

and decomposes it into its Cholesky factor (corrCholeskyFactorZ).

This procedure modifies the correlation matrix input by the user for use in the Nataf distribution model (Der Kiureghian and Liu, ASCE JEM 112:1, 1986). It uses empirical expressions derived from least-squares polynomial fits to numerical integration data.

- corrMatrix: the correlation coefficient matrix of the random variables provided by the user
- mod\_corr\_matrix: modified correlation matrix

- `corrCholeskyFactorZ`: Cholesky factor of the modified correlation matrix for use in `Z_to_U` and `U_to_Z` transformations.

Note: The modification is exact for normal-normal, lognormal-lognormal, and normal-lognormal transformations. All other cases are approximations with some error as noted below.

**8.75.2.12** `void trans_grad_X_to_U (const Epetra_SerialDenseVector & fn_grad_x,  
Epetra_SerialDenseVector & fn_grad_u, const Epetra_SerialDenseVector & x_vars)`  
[protected]

Transformation routine for gradient vector from x-space to u-space.

This procedure transforms a gradient vector from the original user-defined x-space (where evaluations are performed) to uncorrelated standard normal space (u-space). `x_vars` is the vector of random variables in x-space.

**8.75.2.13** `void trans_grad_U_to_X (const Epetra_SerialDenseVector & fn_grad_u,  
Epetra_SerialDenseVector & fn_grad_x, const Epetra_SerialDenseVector & x_vars)`  
[protected]

Transformation routine for gradient vector from u-space to x-space.

This procedure transforms a gradient vector from uncorrelated standard space (u-space) to the original user-defined x-space. `x_vars` is the vector of random variables in u-space.

**8.75.2.14** `void trans_hess_X_to_U (const Epetra_SerialSymDenseMatrix & fn_hess_x,  
Epetra_SerialSymDenseMatrix & fn_hess_u, const Epetra_SerialDenseVector & x_vars, const  
Epetra_SerialDenseVector & fn_grad_x)` [protected]

Transformation routine for Hessian matrix from x-space to u-space.

This procedure transforms a Hessian matrix from the original user-defined x-space (where evaluations are performed) to uncorrelated standard normal space (u-space). `x_vars` is the vector of the random variables in x-space.

**8.75.2.15** `void jacobian_dX_dU (const Epetra_SerialDenseVector & x_vars, Epetra_SerialDenseMatrix  
& jacobian_xu)` [protected]

Jacobian of  $x(u)$  mapping obtained from  $dX/dZ$   $dZ/dU$ .

This procedure computes the Jacobian of the transformation  $x(u)$ . `x_vars` is the vector of random variables in the original user-defined x-space.

**8.75.2.16** `void jacobian_dX_dZ (const Epetra_SerialDenseVector & x_vars, Epetra_SerialDenseMatrix  
& jacobian_xz)` [protected]

Jacobian of  $x(z)$  mapping obtained from differentiation of `trans_Z_to_X()`.

This procedure computes the Jacobian of the transformation  $x(z)$ .  $x\_vars$  is the vector of random variables in the original user-defined  $x$ -space.

**8.75.2.17** `void jacobian_dU_dX (const Epetra_SerialDenseVector &  $x\_vars$ , Epetra_SerialDenseMatrix &  $jacobian\_ux$ )` [protected]

Jacobian of  $u(x)$  mapping obtained from  $dU/dZ dZ/dX$ .

This procedure computes the Jacobian of the transformation  $u(x)$ .  $x\_vars$  is the vector of random variables in the original user-defined  $x$ -space.

**8.75.2.18** `void jacobian_dZ_dX (const Epetra_SerialDenseVector &  $x\_vars$ , Epetra_SerialDenseMatrix &  $jacobian\_zx$ )` [protected]

Jacobian of  $z(x)$  mapping obtained from differentiation of [trans\\_X\\_to\\_Z\(\)](#).

This procedure computes the Jacobian of the transformation  $z(x)$ .  $x\_vars$  is the vector of random variables in the original user-defined  $x$ -space.

**8.75.2.19** `void hessian_d2X_dU2 (const Epetra_SerialDenseVector &  $x\_vars$ , Array< Epetra_SerialSymDenseMatrix > &  $hessian\_xu$ )` [protected]

Hessian of  $x(u)$  mapping obtained from  $dZ/dU^T d^2X/dZ^2 dZ/dU$ .

This procedure computes the Hessian of the transformation  $x(u)$ .  $hessian\_xu$  is a 3D tensor modeled as an array of matrices, where the  $i$ \_th matrix is  $d^2X_i/dU^2$ .  $x\_vars$  is the vector of random variables in the original user-defined  $x$ -space.

**8.75.2.20** `void hessian_d2X_dZ2 (const Epetra_SerialDenseVector &  $x\_vars$ , Array< Epetra_SerialSymDenseMatrix > &  $hessian\_xz$ )` [protected]

Hessian of  $x(z)$  mapping obtained from differentiation of [jacobian\\_dX\\_dZ\(\)](#).

This procedure computes the Hessian of the transformation  $x(z)$ .  $hessian\_xz$  is a 3D tensor modeled as an array of matrices, where the  $i$ \_th matrix is  $d^2X_i/dZ^2$ .  $x\_vars$  is the vector of random variables in the original user-defined  $x$ -space.

**8.75.2.21** `Real Phi (const Real &  $beta$ )` [inline, protected]

Standard normal cumulative distribution function.

returns a probability  $< 0.5$  for negative  $beta$  and a probability  $> 0.5$  for positive  $beta$ .

**8.75.2.22** `Real Phi_inverse (const Real &  $p$ )` [inline, protected]

Inverse of standard normal cumulative distribution function.

returns a negative  $beta$  for probability  $< 0.5$  and a positive  $beta$  for probability  $> 0.5$ .



**8.75.2.23 Real cdf\_beta\_Pinv (const Real & normcdf, const Real & alpha, const Real & beta)**  
[protected]

Inverse of standard beta CDF (not supported by GSL).

Solve is performed in scaled space (for the standard beta distribution).

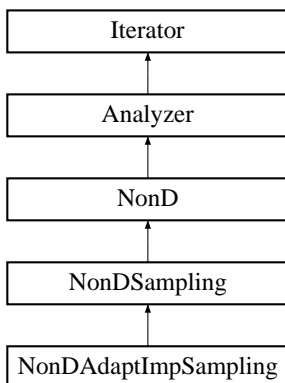
The documentation for this class was generated from the following files:

- DakotaNonD.H
- DakotaNonD.C

## 8.76 NonDAdaptImpSampling Class Reference

Class for the Adaptive Importance Sampling methods within DAKOTA.

Inheritance diagram for NonDAdaptImpSampling::



### Public Member Functions

- [NonDAdaptImpSampling](#) ([Model](#) &model, int samples, int seed, short sampling\_type, const bool cdf\_flag, const bool x\_space\_data, const bool x\_space\_model, const bool bounded\_model)  
*constructor*
- [~NonDAdaptImpSampling](#) ()  
*destructor*
- void [quantify\\_uncertainty](#) ()  
*failure.*
- void [initialize](#) (const [RealVectorArray](#) &initial\_points, int resp\_fn, const Real &initial\_prob, const Real &failure\_threshold)  
*initial probability to refine, and flags to control transformations*
- void [initialize](#) (const [RealVector](#) &initial\_point, int resp\_fn, const Real &initial\_prob, const Real &failure\_threshold)  
*initial probability to refine, and flags to control transformations*
- const Real & [get\\_probability](#) ()  
*returns the probability calculated by the importance sampling*

## Private Member Functions

- void `converge_cov ()`  
*until coefficient of variation converges*
- void `converge_probability ()`  
*until probability converges*
- void `select_init_rep_points (const RealVectorArray &samples)`  
*select representative points from initial set of samples*
- void `select_rep_points (const RealVectorArray &samples)`  
*select representative points from a set of samples*
- void `calculate_rep_weights ()`  
*calculate relative weights of representative points*
- void `generate_samples (RealVectorArray &samples)`  
*generate a set of samples based on multimodal sampling density*
- void `calculate_statistics (const RealVectorArray &samples, const size_t &total_sample_number, Real &probability_sum, Real &probability, bool cov_flag, Real &variance_sum, Real &coeff_of_variation)`  
*the coefficient of variation (if requested)*

## Private Attributes

- short `importanceSamplingType`  
*integration type (is, ais, mmais) provided by input specification*
- bool `invertProb`  
*flag for inversion of probability values using 1.-p*
- size\_t `numRepPoints`  
*the number of representative points around which to sample*
- size\_t `respFn`  
*the response function in the model to be sampled*
- `RealVectorArray` `initPoints`  
*the original set of samples passed into the MMAIS routine*
- `RealVectorArray` `repPoints`  
*the set of representative points around which to sample*
- `RealVector` `repWeights`

*the weight associated with each representative point*

- [RealVector designPoint](#)  
*design point at which uncertain space is being sampled*
- bool [transInitPoints](#)  
*initial points*
- bool [transPoints](#)  
*before evaluation*
- bool [useModelBounds](#)  
*flag to control if the sampler should respect the model bounds*
- Real [initProb](#)  
*the initial probability (from FORM or SORM)*
- Real [finalProb](#)  
*the final calculated probability ( $p$ )*
- Real [failThresh](#)  
*the failure threshold ( $z$ -bar) for the problem.*

### 8.76.1 Detailed Description

Class for the Adaptive Importance Sampling methods within DAKOTA.

The [NonDAdaptImpSampling](#) implements the multi-modal adaptive importance sampling used for reliability calculations. (eventually we will want to broaden this). Need to add more detail to this description.

### 8.76.2 Member Function Documentation

**8.76.2.1 void initialize (const [RealVectorArray](#) & *initial\_points*, int *resp\_fn*, const Real & *initial\_prob*, const Real & *failure\_threshold*)**

initial probability to refine, and flags to control transformations

Initializes data using a set of starting points.

**8.76.2.2 void initialize (const [RealVector](#) & *initial\_point*, int *resp\_fn*, const Real & *initial\_prob*, const Real & *failure\_threshold*)**

initial probability to refine, and flags to control transformations

Initializes data using only one starting point.

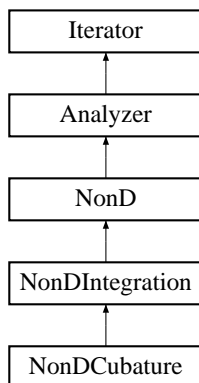
The documentation for this class was generated from the following files:

- NonDAdaptImpSampling.H
- NonDAdaptImpSampling.C

## 8.77 NonDCubature Class Reference

integrals over uncorrelated uniforms.

Inheritance diagram for NonDCubature::



### Public Member Functions

- [NonDCubature](#) ([Model](#) &model, const short &level)
- const short & [cubature\\_level](#) () const  
*return cubatureLevel*

### Protected Member Functions

- [NonDCubature](#) ([Model](#) &model)  
*constructor*
- [~NonDCubature](#) ()  
*destructor*
- void [get\\_parameter\\_sets](#) (const [Model](#) &model)  
*Returns one block of samples (ndim \* num\_samples).*
- void [check\\_input](#) ()  
*verify self-consistency of data*
- void [sampling\\_reset](#) (int min\_samples, bool all\_data\_flag, bool stats\_flag)

## Private Attributes

- short `cubatureLevelSpec`  
*the user specification for the cubature level*
- short `cubatureLevel`  
*communicated through `sampling_reset()`*

### 8.77.1 Detailed Description

integrals over uncorrelated uniforms.

This class is used by `NonDPolynomialChaos`, but could also be used for general numerical integration of moments. It employs Clenshaw-Curtis cubature for use with uniform density functions and integration bounds.

### 8.77.2 Constructor & Destructor Documentation

#### 8.77.2.1 `NonDCubature` (`Model` & `model`, `const short` & `level`)

This alternate constructor is used for on-the-fly generation and evaluation of numerical cubature points.

#### 8.77.2.2 `NonDCubature` (`Model` & `model`) [protected]

constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification. It is not currently used, as there is not yet a separate `nond_cubature` method specification.

### 8.77.3 Member Function Documentation

#### 8.77.3.1 `void sampling_reset` (`int min_samples`, `bool all_data_flag`, `bool stats_flag`) [protected, virtual]

used by `DataFitSurrModel::build_global()` to publish the minimum number of points needed from the cubature routine in order to build a particular global approximation.

Reimplemented from `Iterator`.

The documentation for this class was generated from the following files:

- `NonDCubature.H`

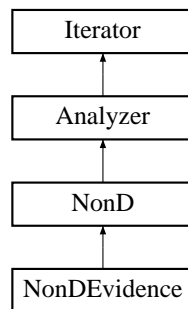
- NonDCubature.C



## 8.78 NonDEvidence Class Reference

Class for the Dempster-Shafer Evidence Theory methods within DAKOTA/UQ.

Inheritance diagram for NonDEvidence::



### Public Member Functions

- [NonDEvidence](#) ([Model](#) &model)  
*constructor*
- [~NonDEvidence](#) ()  
*destructor*
- void [quantify\\_uncertainty](#) ()  
*for cumulative distribution functions of belief and plausibility*
- void [print\\_results](#) (ostream &s) const  
*print the cumulative distribution functions for belief and plausibility*

### Protected Member Functions

- void [initialize\\_final\\_statistics](#) ()  
*initialize finalStatistics for belief/plausibility results sets*
- void [compute\\_statistics](#) ()  
*or vice-versa*

## Private Member Functions

- void `calculate_basic_prob_intervals` ()  
*basic probability assignments for input interval combinations*
- void `calculate_maxmin_per_interval` (const size\_t &func\_num)  
*maximum and minimum values within each input interval combination (cell).*
- void `calculate_cum_belief_plaus` (const size\_t &func\_num)  
*per interval cell*

## Private Attributes

- Iterator `lhsSampler`  
*the LHS sampler instance*
- const int `originalSeed`  
*the user seed specification (default is 0)*
- int `numSamples`  
*the number of samples used in the surrogate*
- int `NV`  
*Size variable for DDS arrays.*
- int `NCMB`  
*Size variable for DDS arrays.*
- int `MAXINTVLS`  
*Size variable for DDS arrays.*
- Real `Y`  
*Temporary output variable.*
- Real \* `BPA`  
*Internal DDS array.*
- Real \* `VMIN`  
*Internal DDS array.*
- Real \* `VMAX`  
*Internal DDS array.*
- Real \* `BPAC`  
*Internal DDS array.*

- Real \* [CMIN](#)  
*Internal DDS Array.*
- Real \* [CMAX](#)  
*Internal DDS Array.*
- Real \* [X](#)  
*Internal DDS Array.*
- int \* [NI](#)  
*Internal DDS array.*
- int \* [IP](#)  
*Internal DDS array.*
- int \* [IPBEL](#)  
*Internal DDS array.*
- int \* [IPPLA](#)  
*Internal DDS array.*
- [RealVectorArray cc\\_bel\\_fn](#)  
*Storage array to hold CCBF values.*
- [RealVectorArray cc\\_plaus\\_fn](#)  
*Storage array to hold CCPF values.*
- [RealVectorArray cc\\_bel\\_val](#)  
*Storage array to hold CCB response values.*
- [RealVectorArray cc\\_plaus\\_val](#)  
*Storage array to hold CCP response values.*
- [VariablesArray all\\_vars](#)  
*Storage array to hold variables.*
- [ResponseArray all\\_responses](#)  
*Storage array to hold responses.*

### 8.78.1 Detailed Description

Class for the Dempster-Shafer Evidence Theory methods within DAKOTA/UQ.

The [NonDEvidence](#) class implements the propagation of epistemic uncertainty using Dempster-Shafer theory of evidence. In this approach, one assigns a set of basic probability assignments (BPA) to intervals defined for the

uncertain variables. Input interval combinations are calculated, along with their BPA. Currently, the response function is evaluated at a set of sample points, then a response surface is constructed which is sampled extensively to find the minimum and maximum within each input interval cell, corresponding to the belief and plausibility within that cell, respectively. This data is then aggregated to calculate cumulative distribution functions for belief and plausibility.

## 8.78.2 Member Data Documentation

### 8.78.2.1 `int NV` [private]

Size variable for DDS arrays.

NV = number of interval variables

### 8.78.2.2 `int NCMB` [private]

Size variable for DDS arrays.

NCMB = number of cell combinations

### 8.78.2.3 `int MAXINTVLS` [private]

Size variable for DDS arrays.

MAXINTVLS = maximum number of intervals per individual interval var

### 8.78.2.4 `Real Y` [private]

Temporary output variable.

Y = current output to be placed in cell

### 8.78.2.5 `Real* BPA` [private]

Internal DDS array.

Basic Probability Assignments

### 8.78.2.6 `Real* VMIN` [private]

Internal DDS array.

Minimum ends of intervals.

**8.78.2.7 Real\* VMAX** [private]

Internal DDS array.

Maximum ends of intervals.

**8.78.2.8 Real\* BPAC** [private]

Internal DDS array.

Basic Probability Combinations.

**8.78.2.9 Real\* CMIN** [private]

Internal DDS Array.

Minimum per cell combination.

**8.78.2.10 Real\* CMAX** [private]

Internal DDS Array.

Maximum per cell combination.

**8.78.2.11 Real\* X** [private]

Internal DDS Array.

X per cell combination.

**8.78.2.12 int\* NI** [private]

Internal DDS array.

Number of intervals per interval variable

**8.78.2.13 int\* IP** [private]

Internal DDS array.

Sort order for combinations

**8.78.2.14 int\* IPBEL** [private]

Internal DDS array.

Sort order for belief values

**8.78.2.15** `int* IPPLA` [private]

Internal DDS array.

Sort order for belief values

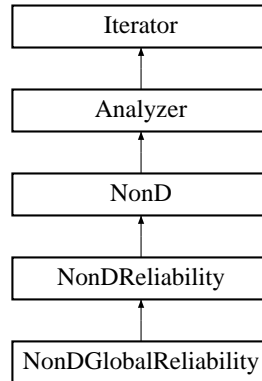
The documentation for this class was generated from the following files:

- NonDEvidence.H
- NonDEvidence.C

## 8.79 NonDGlobalReliability Class Reference

Class for global reliability methods within DAKOTA/UQ.

Inheritance diagram for NonDGlobalReliability::



### Public Member Functions

- [NonDGlobalReliability](#) ([Model](#) &model)  
*constructor*
- [~NonDGlobalReliability](#) ()  
*destructor*
- void [quantify\\_uncertainty](#) ()  
*approximations of the cumulative distribution function of response*
- void [print\\_results](#) (ostream &s) const  
*MPP-search-based reliability methods.*

### Private Member Functions

- void [optimize\\_gaussian\\_process](#) ()  
*construct the GP using EGO/SKO*
- void [importance\\_sampling](#) ()  
*perform multimodal adaptive importance sampling on the GP*
- void [get\\_best\\_sample](#) ()

*improvement function in Performance Measure Approach (PMA)*

- Real [constraint\\_penalty](#) (const Real &constraint, const [RealVector](#) &c\_variables)  
*calculate the penalty to be applied to the PMA constraint value*
- Real [expected\\_improvement](#) (const [RealVector](#) &expected\_values, const [RealVector](#) &c\_variables)  
*expected improvement function for the GP*
- Real [expected\\_feasibility](#) (const [RealVector](#) &expected\_values, const [RealVector](#) &c\_variables)  
*expected feasibility function for the GP*

### Static Private Member Functions

- static void [EIF\\_objective\\_eval](#) (const [Variables](#) &sub\_model\_vars, const [Variables](#) &recast\_vars, const [Response](#) &sub\_model\_response, [Response](#) &recast\_response)  
*Expected Improvement (EIF) problem formulation for PMA.*
- static void [EFF\\_objective\\_eval](#) (const [Variables](#) &sub\_model\_vars, const [Variables](#) &recast\_vars, const [Response](#) &sub\_model\_response, [Response](#) &recast\_response)  
*Expected Feasibility (EFF) problem formulation for RIA.*

### Private Attributes

- Real [fnStar](#)  
*minimum penalized response from among true function evaluations*
- short [meritFunctionType](#)  
*type of merit function used to penalize sample data*
- Real [lagrangeMult](#)  
*Lagrange multiplier for standard Lagrangian merit function.*
- Real [augLagrangeMult](#)  
*Lagrange multiplier for augmented Lagrangian merit function.*
- Real [penaltyParameter](#)  
*penalty parameter for augmented Lagrangian merit function*
- Real [lastConstraintViolation](#)  
*current iterate should be accepted (must reduce violation)*
- bool [lastIterateAccepted](#)  
*this controls update of parameters for augmented Lagrangian merit fn*



## Static Private Attributes

- static [NonDGlobalReliability](#) \* [nondGlobRelInstance](#)  
*functions in order to avoid the need for static data*

### 8.79.1 Detailed Description

Class for global reliability methods within DAKOTA/UQ.

The [NonDGlobalReliability](#) class implements EGO/SKO for global MPP search, which maximizes an expected improvement function derived from Gaussian process models. Once the limit state has been characterized, a multimodal importance sampling approach is used to compute probabilities.

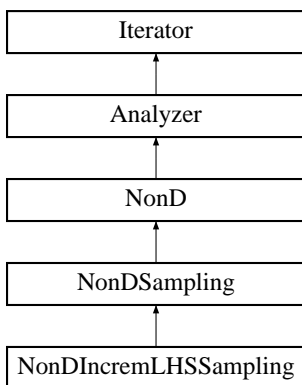
The documentation for this class was generated from the following files:

- NonDGlobalReliability.H
- NonDGlobalReliability.C

## 8.80 NonDIncrLHSSampling Class Reference

Performs incremental LHS sampling for uncertainty quantification.

Inheritance diagram for NonDIncrLHSSampling::



### Public Member Functions

- [NonDIncrLHSSampling \(Model &model\)](#)  
*constructor*
- [~NonDIncrLHSSampling \(\)](#)  
*destructor*
- void [quantify\\_uncertainty \(\)](#)  
*parameter samples, and computing statistics on the ensemble of results.*
- void [print\\_results](#) (ostream &s) const  
*print the final statistics*

### Static Protected Member Functions

- static bool [rank\\_sort](#) (const int &x, const int &y)  
*sort algorithm to compute ranks for rank correlations*

## Private Attributes

- int `previousSamples`  
*number of samples in previous LHS run*
- bool `varBasedDecompFlag`  
*flags computation of VBD*

## Static Private Attributes

- static `RealArray rawData`  
*vector to hold raw data before rank sort*

### 8.80.1 Detailed Description

Performs incremental LHS sampling for uncertainty quantification.

The Latin Hypercube Sampling (LHS) package from Sandia Albuquerque's Risk and Reliability organization provides comprehensive capabilities for Monte Carlo and Latin Hypercube sampling within a broad array of user-specified probabilistic parameter distributions. The incremental LHS sampling capability allows one to supplement an initial sample of size  $n$  to size  $2n$  while maintaining the correct stratification of the  $2n$  samples and also maintaining the specified correlation structure. The incremental version of LHS will return a sample of size  $n$ , which when combined with the original sample of size  $n$ , allows one to double the size of the sample.

### 8.80.2 Constructor & Destructor Documentation

#### 8.80.2.1 NonDIncrLHSSampling (Model & model)

constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification.

### 8.80.3 Member Function Documentation

#### 8.80.3.1 void `quantify_uncertainty()` [virtual]

parameter samples, and computing statistics on the ensemble of results.

Loop over the set of samples and compute responses. Compute statistics on the set of responses if `statsFlag` is set.

Implements [NonD](#).

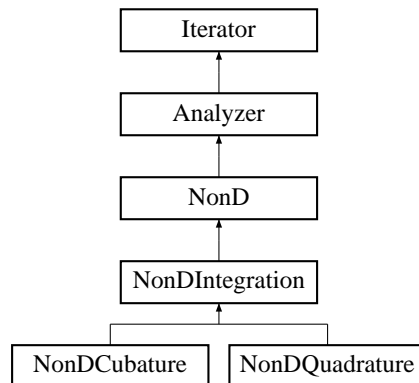
The documentation for this class was generated from the following files:

- [NonDIncrLHSSampling.H](#)
- [NonDIncrLHSSampling.C](#)

## 8.81 NonDIntegration Class Reference

numerical integration points for evaluation of expectation integrals

Inheritance diagram for NonDIntegration::



### Public Member Functions

- `const RealVector & weight_products () const`  
*return weightProducts*

### Protected Member Functions

- `NonDIntegration (Model &model)`  
*constructor*
- `NonDIntegration (NoDBBaseConstructor, Model &model)`  
*alternate constructor for instantiations "on the fly"*
- `~NonDIntegration ()`  
*destructor*
- `virtual void check_input ()=0`  
*verify self-consistency of data*
- `void quantify_uncertainty ()`  
*distributions into response statistics*

## Protected Attributes

- [RealVector weightProducts](#)  
*n-dimensional stencil*

## Private Attributes

- `size_t numIntegrations`  
*counter for number of integration executions for this object*

### 8.81.1 Detailed Description

numerical integration points for evaluation of expectation integrals

This class provides a base class for shared code among [NonDQuadrature](#) and [NonDCubature](#).

### 8.81.2 Constructor & Destructor Documentation

#### 8.81.2.1 [NonDIntegration \(Model & model\)](#) [protected]

constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification. It is not currently used, as there are not yet separate `nond_quadrature/nond_cubature` method specifications.

#### 8.81.2.2 [NonDIntegration \(NoDBBaseConstructor, Model & model\)](#) [protected]

alternate constructor for instantiations "on the fly"

This alternate constructor is used for on-the-fly generation and evaluation of numerical integration points.

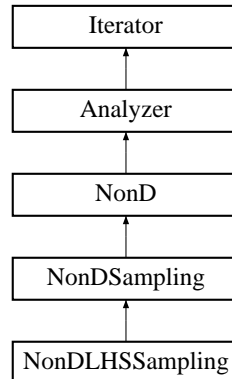
The documentation for this class was generated from the following files:

- `NonDIntegration.H`
- `NonDIntegration.C`

## 8.82 NonDLHSSampling Class Reference

Performs LHS and Monte Carlo sampling for uncertainty quantification.

Inheritance diagram for NonDLHSSampling::



### Public Member Functions

- [NonDLHSSampling](#) ([Model](#) &model)  
*standard constructor*
- [NonDLHSSampling](#) ([Model](#) &model, int samples, int seed, short sampling\_vars\_mode=ACTIVE)  
*alternate constructor for sample generation and evaluation "on the fly"*
- [NonDLHSSampling](#) (int samples, int seed, const [RealVector](#) &lower\_bnds, const [RealVector](#) &upper\_bnds)  
*alternate constructor for sample generation "on the fly"*
- [~NonDLHSSampling](#) ()  
*destructor*

### Protected Member Functions

- void [quantify\\_uncertainty](#) ()  
*parameter samples, and computing statistics on the ensemble of results.*
- void [print\\_results](#) (ostream &s) const  
*print the final statistics*

## Private Attributes

- bool `varBasedDecompFlag`  
*flags computation of VBD*

### 8.82.1 Detailed Description

Performs LHS and Monte Carlo sampling for uncertainty quantification.

The Latin Hypercube Sampling (LHS) package from Sandia Albuquerque's Risk and Reliability organization provides comprehensive capabilities for Monte Carlo and Latin Hypercube sampling within a broad array of user-specified probabilistic parameter distributions. It enforces user-specified rank correlations through use of a mixing routine. The `NonDLHSSampling` class provides a C++ wrapper for the LHS library and is used for performing forward propagations of parameter uncertainties into response statistics.

### 8.82.2 Constructor & Destructor Documentation

#### 8.82.2.1 `NonDLHSSampling (Model & model)`

standard constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification.

#### 8.82.2.2 `NonDLHSSampling (Model & model, int samples, int seed, short sampling_vars_mode = ACTIVE)`

alternate constructor for sample generation and evaluation "on the fly"

This alternate constructor is used by `NonDEvidence` for generation and evaluation of Model-based sample sets. It is `_not_` a letter-envelope instantiation and a `set_db_list_nodes` has not been performed. It is called with all needed data passed through the constructor. Its purpose is to avoid the need for a separate LHS specification within methods that use LHS sampling.

#### 8.82.2.3 `NonDLHSSampling (int samples, int seed, const RealVector & lower_bnds, const RealVector & upper_bnds)`

alternate constructor for sample generation "on the fly"

This alternate constructor is used by `ConcurrentStrategy` for generation of uniform, uncorrelated sample sets. It is `_not_` a letter-envelope instantiation and a `set_db_list_nodes` has not been performed. It is called with all needed data passed through the constructor and is designed to allow more flexibility in variables set definition (i.e., relax connection to a variables specification and allow sampling over parameter sets such as multiobjective weights). In this case, a `Model` is not used and the object must only be used for sample generation (no evaluation).



### 8.82.3 Member Function Documentation

#### 8.82.3.1 void quantify\_uncertainty () [protected, virtual]

parameter samples, and computing statistics on the ensemble of results.

Loop over the set of samples and compute responses. Compute statistics on the set of responses if statsFlag is set.

Implements [NonD](#).

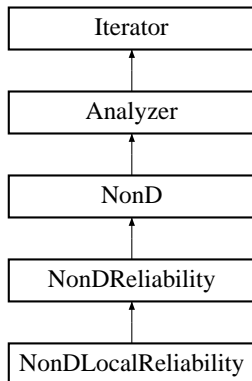
The documentation for this class was generated from the following files:

- NonDLHSSampling.H
- NonDLHSSampling.C

## 8.83 NonDLocalReliability Class Reference

Class for the reliability methods within DAKOTA/UQ.

Inheritance diagram for NonDLocalReliability::



### Public Member Functions

- [NonDLocalReliability \(Model &model\)](#)  
*constructor*
- [~NonDLocalReliability \(\)](#)  
*destructor*
- void [quantify\\_uncertainty \(\)](#)  
*approximations of the cumulative distribution function of response*
- void [print\\_results \(ostream &s\) const](#)  
*MPP-search-based reliability methods.*
- [String uses\\_method \(\) const](#)  
*return name of active MPP optimizer*
- void [method\\_recourse \(\)](#)  
*perform an MPP optimizer method switch due to a detected conflict*

### Private Member Functions

- void [initial\\_taylor\\_series \(\)](#)

*Taylor-series approximation.*

- void `mean_value` ()  
*computation of approximate statistics and importance factors*
- void `mpp_search` ()  
*employ a search for the most probable point (AMV, AMV+, FORM, SORM)*
- void `initialize_class_data` ()  
*convenience function for initializing class scope arrays*
- void `initialize_level_data` ()  
*data for each response function prior to level 0*
- void `initialize_mpp_search_data` ()  
*data for each z/p/beta level for each response function*
- void `update_mpp_search_data` (const `Variables` &vars\_star, const `Response` &resp\_star)  
*z/p/beta level for each response function*
- void `update_level_data` (`RealVector` &final\_stats, `RealMatrix` &final\_stat\_grads)  
*statistics following MPP convergence*
- void `update_pma_reliability_level` ()  
*generalized reliabilities by inverting second-order integrations*
- void `update_limit_state_surrogate` ()  
*to the data fit embedded within uSpaceModel*
- void `assign_mean_data` ()  
*from ranVarMeansX/U, fnValsMeanX, fnGradsMeanX, and fnHessiansMeanX*
- void `dg_ds_eval` (const `Epetra_SerialDenseVector` &x\_vars, const `Epetra_SerialDenseVector` &fn\_grad\_x, `RealMatrix` &final\_stat\_grads)  
*convenience function for evaluating dg/ds*
- `Real probability` (const `Real` &beta, bool cdf\_flag)  
*second-order integration*
- `Real reliability` (const `Real` &p, bool cdf\_flag)  
*second-order integration*
- bool `reliability_residual` (const `Real` &p, const `Real` &beta, const `Epetra_SerialDenseVector` &kappa, `Real` &res)  
*corrections using Newton's method (called by reliability(p))*

- Real [reliability\\_residual\\_derivative](#) (const Real &p, const Real &beta, const Epetra\_SerialDenseVector &kappa)  
*probability corrections using Newton's method (called by reliability(p))*
- void [principal\\_curvatures](#) ()  
*Compute the kappaU vector of principal curvatures from fnHessU.*

## Private Attributes

- Epetra\_SerialDenseVector [fnGradX](#)  
*evaluation*
- Epetra\_SerialDenseVector [fnGradU](#)  
*Jacobian dx/du.*
- Epetra\_SerialSymDenseMatrix [fnHessX](#)  
*evaluation*
- Epetra\_SerialSymDenseMatrix [fnHessU](#)  
*Jacobian dx/du.*
- Epetra\_SerialDenseVector [kappaU](#)  
*transformation of fnHessU*
- Epetra\_SerialDenseVector [fnValsMeanX](#)  
*response function values evaluated at mean x*
- Epetra\_SerialDenseMatrix [fnGradsMeanX](#)  
*response function gradients evaluated at mean x*
- [Array](#)< Epetra\_SerialSymDenseMatrix > [fnHessiansMeanX](#)  
*response function Hessians evaluated at mean x*
- [RealVector](#) [medianFnVals](#)  
*p=0.5 -> median function values). Used to determine the sign of beta.*
- Epetra\_SerialDenseVector [ranVarMeansU](#)  
*vector of means for all uncertain random variables in u-space*
- [RealVector](#) [initialPtU](#)  
*initial guess for MPP search in u-space*
- Epetra\_SerialDenseVector [mostProbPointX](#)  
*location of MPP in x-space*

- `Epetra_SerialDenseVector` `mostProbPointU`  
*location of MPP in u-space*
- `RealVectorArray` `prevMPPULev0`  
*initialPtU within RBDO.*
- `RealMatrix` `prevFnGradDLev0`  
*for level 0. Used for warm-starting initialPtU within RBDO.*
- `RealMatrix` `prevFnGradULev0`  
*for level 0. Used for warm-starting initialPtU within RBDO.*
- `RealVector` `prevICVars`  
*previous design vector. Used for warm-starting initialPtU within RBDO.*
- `ShortArray` `prevCumASVLev0`  
*for warm-starting initialPtU within RBDO.*
- `bool` `npsolFlag`  
*selection (SQP or NIP)*
- `bool` `warmStartFlag`  
*flag indicating the use of warm starts*
- `bool` `nipModeOverrideFlag`  
*flag indicating the use of move overrides within OPT++ NIP*
- `bool` `curvatureDataAvailable`  
*mostProbPointU) is available for computing principal curvatures*
- `short` `integrationOrder`  
*integration order (1 or 2) provided by integration specification*
- `short` `secondOrderIntType`  
*type of second-order integration: Breitung, Hohenbichler-Rackwitz, or Hong*
- `Real` `curvatureThresh`  
*cut-off value for  $1/\sqrt{t}$  term in second-order probability corrections.*
- `short` `taylorOrder`  
*derived from hessianType*
- `RealMatrix` `impFactor`  
*importance factors predicted by MV*
- `int` `npsolDerivLevel`

*fn, 2 = analytic grads of constraints, 3 = analytic grads of both).*

- unsigned short `warningBits`  
*set of warnings accumulated during execution*

### 8.83.1 Detailed Description

Class for the reliability methods within DAKOTA/UQ.

The `NonDLocalReliability` class implements the following reliability methods through the support of different limit state approximation and integration options: mean value (MVFOSM/MVSOSM), advanced mean value method (AMV, AMV<sup>2</sup>) in x- or u-space, iterated advanced mean value method (AMV+, AMV<sup>2</sup>+) in x- or u-space, two-point adaptive nonlinearity approximation (TANA) in x- or u-space, first order reliability method (FORM), and second order reliability method (SORM). All options except mean value employ an optimizer (currently NPSOL SQP or OPT++ NIP) to solve an equality-constrained optimization problem for the most probable point (MPP). The MPP search may be formulated as the reliability index approach (RIA) for mapping response levels to reliabilities/probabilities or as the performance measure approach (PMA) for performing the inverse mapping of reliability/probability levels to response levels.

### 8.83.2 Member Function Documentation

#### 8.83.2.1 `void initial_taylor_series () [private]`

Taylor-series approximation.

An initial first- or second-order Taylor-series approximation is required for MV/AMV/AMV+/TANA or for the case where meanStats or stdDevStats (from MV) are required within finalStatistics for subIterator usage of `NonDLocalReliability`.

#### 8.83.2.2 `void initialize_class_data () [private]`

convenience function for initializing class scope arrays

Initialize class-scope arrays and perform other start-up activities, such as evaluating median limit state responses.

#### 8.83.2.3 `void initialize_level_data () [private]`

data for each response function prior to level 0

For a particular response function prior to the first z/p/beta level, initialize/warm-start optimizer initial guess (initialPtU), expansion point (mostProbPointX/U), and associated response data (computedRespLevel, fnGrad-X/U, and fnHessX/U).

**8.83.2.4 void initialize\_mpp\_search\_data () [private]**

data for each z/p/beta level for each response function

For a particular response function at a particular z/p/beta level, warm-start or reset the optimizer initial guess (initialPtU), expansion point (mostProbPointX/U), and associated response data (computedRespLevel, fnGradX/U, and fnHessX/U).

**8.83.2.5 void update\_mpp\_search\_data (const Variables & vars\_star, const Response & resp\_star) [private]**

z/p/beta level for each response function

Includes case-specific logic for updating MPP search data for the AMV/AMV+/TANA/NO\_APPROX methods.

**8.83.2.6 void update\_level\_data (RealVector & final\_stats, RealMatrix & final\_stat\_grads) [private]**

statistics following MPP convergence

Updates computedRespLevels/computedProbLevels/computedRelLevels, final\_stats/final\_stat\_grads, warm start, and graphics data.

**8.83.2.7 void update\_pma\_reliability\_level () [private, virtual]**

generalized reliabilities by inverting second-order integrations

For PMA SORM with prescribed p-level or prescribed generalized beta-level, requestedCDFRelLevel must be updated. This virtual function redefinition is called from [NonDReliability::PMA\\_constraint\\_eval\(\)](#).

Reimplemented from [NonDReliability](#).

**8.83.2.8 void dg\_ds\_eval (const Epetra\_SerialDenseVector & x\_vars, const Epetra\_SerialDenseVector & fn\_grad\_x, RealMatrix & final\_stat\_grads) [private]**

convenience function for evaluating dg/ds

Computes dg/ds where s = design variables. Supports potentially overlapping cases of design variable augmentation and insertion.

**8.83.2.9 Real probability (const Real & beta, bool cdf\_flag) [private]**

second-order integration

Converts beta into a probability using either first-order (FORM) or second-order (SORM) integration. The SORM calculation first calculates the principal curvatures at the MPP (using the approach in Ch. 8 of Haldar & Mahadevan), and then applies correction formulations from the literature (Breitung, Hohenbichler-Rackwitz, or Hong).

**8.83.2.10 Real reliability** (`const Real & p, bool cdf_flag`) [`private`]

second-order integration

Converts a probability into a reliability using the inverse of the first-order or second-order integrations implemented in [NonDLocalReliability::probability\(\)](#).

The documentation for this class was generated from the following files:

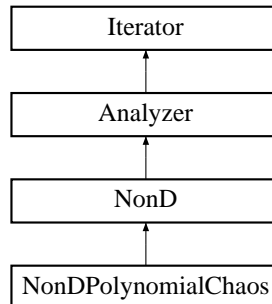
- NonDLocalReliability.H
- NonDLocalReliability.C



## 8.84 NonDPolynomialChaos Class Reference

quantification

Inheritance diagram for NonDPolynomialChaos::



### Public Member Functions

- [NonDPolynomialChaos \(Model &model\)](#)  
*constructor*
- [~NonDPolynomialChaos \(\)](#)  
*destructor*
- void [quantify\\_uncertainty \(\)](#)  
*perform a forward uncertainty propagation using SFEM/PCE methods*
- void [print\\_results \(ostream &s\) const](#)  
*print the final statistics and PCE coefficient array*

### Private Attributes

- [Model uSpaceModel](#)  
*u-space recasting and orthogonal polynomial data fit recursions*
- [Iterator pceSampler](#)  
*an LHS sampling instance, but AIS could also be used.*
- size\_t [numPCEAnalyses](#)  
*number of invocations of [quantify\\_uncertainty\(\)](#)*

- short [chaosCoeffsApproach](#)  
*method for calculation of the chaos coefficients*
- int [numSamplesOnExpansion](#)  
*to estimate probabilities*
- String [expansionImportFile](#)  
*filename for import of chaos coefficients*
- RealMatrix [pceGradsMeanX](#)  
*evaluated at the means (used as uncertainty importance metrics)*

### 8.84.1 Detailed Description

quantification

The [NonDPolynomialChaos](#) class uses a polynomial chaos expansion (PCE) approach to approximate the effect of parameter uncertainties on response functions of interest. It utilizes the [OrthogPolyApproximation](#) class to manage multiple types of orthogonal polynomials within a Wiener-Askey scheme to PCE. It supports PCE coefficient estimation via sampling, quadrature, point-collocation, and file import.

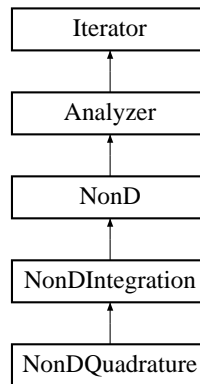
The documentation for this class was generated from the following files:

- NonDPolynomialChaos.H
- NonDPolynomialChaos.C

## 8.85 NonDQuadrature Class Reference

normals/uniforms/exponentials/betas/gammas.

Inheritance diagram for NonDQuadrature::



### Public Member Functions

- `NonDQuadrature` (`Model &model`, `const ShortArray &order`)
- `const ShortArray & quadrature_order` () `const`  
*return quadOrder*

### Protected Member Functions

- `NonDQuadrature` (`Model &model`)  
*constructor*
- `~NonDQuadrature` ()  
*destructor*
- `void get_parameter_sets` (`const Model &model`)  
*Returns one block of samples (ndim \* num\_samples).*
- `void check_input` ()  
*verify self-consistency of data*
- `void sampling_reset` (`int min_samples`, `bool all_data_flag`, `bool stats_flag`)

## Private Attributes

- [ShortArray quadOrderSpec](#)  
*the user specification for the number of Gauss points per dimension*
- [ShortArray quadOrder](#)  
*external requirements communicated through [sampling\\_reset\(\)](#)*

### 8.85.1 Detailed Description

normals/uniforms/exponentials/betas/gammas.

This class is used by [NonDPolynomialChaos](#), but could also be used for general numerical integration of moments. It employs Gauss-Hermite, Gauss-Legendre, Gauss-Laguerre, Gauss-Jacobi and generalized Gauss-Laguerre quadrature for use with normal, uniform, exponential, beta, and gamma density functions and integration bounds. The abscissas and weights for one-dimensional integration are extracted from the appropriate [OrthogonalPolynomial](#) class and are extended to n-dimensions using a tensor product approach.

### 8.85.2 Constructor & Destructor Documentation

#### 8.85.2.1 [NonDQuadrature](#) ([Model](#) & *model*, const [ShortArray](#) & *order*)

This alternate constructor is used for on-the-fly generation and evaluation of numerical quadrature points.

#### 8.85.2.2 [NonDQuadrature](#) ([Model](#) & *model*) [protected]

constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification. It is not currently used, as there is not yet a separate `nond_quadrature` method specification.

### 8.85.3 Member Function Documentation

#### 8.85.3.1 `void sampling_reset (int min_samples, bool all_data_flag, bool stats_flag)` [inline, protected, virtual]

used by [DataFitSurrModel::build\\_global\(\)](#) to publish the minimum number of points needed from the quadrature routine in order to build a particular global approximation.

Reimplemented from [Iterator](#).

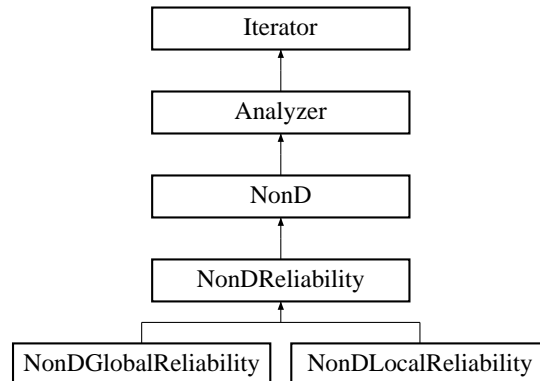
The documentation for this class was generated from the following files:

- NonDQuadrature.H
- NonDQuadrature.C

## 8.86 NonDReliability Class Reference

Base class for the reliability methods within DAKOTA/UQ.

Inheritance diagram for NonDReliability::



### Public Member Functions

- [NonDReliability](#) ([Model](#) &model)  
*constructor*
- [~NonDReliability](#) ()  
*destructor*

### Protected Member Functions

- virtual void [update\\_pma\\_reliability\\_level](#) ()  
*update requestedCDFRelLevel for use in [PMA\\_constraint\\_eval\(\)](#)*
- void [jacobian\\_dX\\_dS](#) (const [Epetra\\_SerialDenseVector](#) &x\_vars, [Epetra\\_SerialDenseMatrix](#) &jacobian\_xs)  
*[trans\\_U\\_to\\_X\(\)](#) with respect to distribution parameters S*
- void [numerical\\_design\\_jacobian](#) (const [Epetra\\_SerialDenseVector](#) &x\_vars, bool xs, [Epetra\\_SerialDenseMatrix](#) &num\_jacobian\_xs, bool zs, [Epetra\\_SerialDenseMatrix](#) &num\_jacobian\_zs)  
*and zs booleans*
- void [verify\\_trans\\_jacobian\\_hessian](#) (const [Epetra\\_SerialDenseVector](#) &v0)  
*routine for verification of transformation Jacobian/Hessian terms*

- void `verify_design_jacobian` (const `Epetra_SerialDenseVector` &u0)  
*routine for verification of design Jacobian terms*
- const `Real` & `distribution_parameter` (const `size_t` &index)  
*return a particular random variable distribution parameter*
- void `distribution_parameter` (const `size_t` &index, const `Real` &param)  
*update derived quantities*

### Static Protected Member Functions

- static void `RIA_objective_eval` (const `Variables` &sub\_model\_vars, const `Variables` &recast\_vars, const `Response` &sub\_model\_response, `Response` &recast\_response)  
*(MPP) with the objective function of  $(\text{norm } u)^2$ .*
- static void `RIA_constraint_eval` (const `Variables` &sub\_model\_vars, const `Variables` &recast\_vars, const `Response` &sub\_model\_response, `Response` &recast\_response)  
*(MPP) with the constraint of  $G(u) = \text{response level}$ .*
- static void `PMA_objective_eval` (const `Variables` &sub\_model\_vars, const `Variables` &recast\_vars, const `Response` &sub\_model\_response, `Response` &recast\_response)  
*(MPP) with the objective function of  $G(u)$ .*
- static void `PMA_constraint_eval` (const `Variables` &sub\_model\_vars, const `Variables` &recast\_vars, const `Response` &sub\_model\_response, `Response` &recast\_response)  
*(MPP) with the constraint of  $(\text{norm } u)^2 = \text{beta}^2$ .*
- static void `PMA2_asv_mapping` (const `ShortArray` &recast\_asv, `ShortArray` &sub\_model\_asv)  
*beta-bar constraint target update is required for second-order PMA*

### Protected Attributes

- `Model` `uSpaceModel`  
*recastings and data fits*
- `Model` `mppModel`  
*RecastModel which formulates the optimization subproblem: RIA, PMA, EGO.*
- `Iterator` `mppOptimizer`  
*Iterator which optimizes the mppModel.*
- short `mppSearchType`

*x/u-space TANA, x/u-space EGO, or NO\_APPROX*

- [Iterator importanceSampler](#)  
*importance sampling instance used to compute/refine probabilities*
- short [integrationRefinement](#)  
*refinement specification*
- size\_t [numRelAnalyses](#)  
*number of invocations of [quantify\\_uncertainty\(\)](#)*
- size\_t [approxIters](#)  
*number of approximation cycles for the current [respFnCount/levelCount](#)*
- bool [approxConverged](#)  
*indicates convergence of approximation-based iterations*
- int [respFnCount](#)  
*counter for which response function is being analyzed*
- size\_t [levelCount](#)  
*counter for which response/probability level is being analyzed*
- size\_t [statCount](#)  
*counter for which final statistic is being computed*
- Real [requestedRespLevel](#)  
*the response level target for the current response function*
- Real [requestedCDFProbLevel](#)  
*the CDF probability level target for the current response function*
- Real [requestedCDFRelLevel](#)  
*the CDF reliability level target for the current response function*
- Real [computedRespLevel](#)  
*output response level calculated*
- Real [computedRelLevel](#)  
*output reliability level calculated*

### Static Protected Attributes

- static [NonDReliability](#) \* [nondRelInstance](#)  
*functions in order to avoid the need for static data*



### 8.86.1 Detailed Description

Base class for the reliability methods within DAKOTA/UQ.

The [NonDReliability](#) class provides a base class for [NonDLocalReliability](#), which implements traditional MPP-based reliability methods, and [NonDGlobalReliability](#), which implements global limit state search using Gaussian process models in combination with multimodal importance sampling.

### 8.86.2 Member Function Documentation

**8.86.2.1** void RIA\_objective\_eval (const [Variables](#) & sub\_model\_vars, const [Variables](#) & recast\_vars, const [Response](#) & sub\_model\_response, [Response](#) & recast\_response) [static, protected]

(MPP) with the objective function of  $(\text{norm } u)^2$ .

This function recasts a  $G(u)$  response set (already transformed and approximated in other recursions) into an RIA objective function.

**8.86.2.2** void RIA\_constraint\_eval (const [Variables](#) & sub\_model\_vars, const [Variables](#) & recast\_vars, const [Response](#) & sub\_model\_response, [Response](#) & recast\_response) [static, protected]

(MPP) with the constraint of  $G(u) = \text{response level}$ .

This function recasts a  $G(u)$  response set (already transformed and approximated in other recursions) into an RIA equality constraint.

**8.86.2.3** void PMA\_objective\_eval (const [Variables](#) & sub\_model\_vars, const [Variables](#) & recast\_vars, const [Response](#) & sub\_model\_response, [Response](#) & recast\_response) [static, protected]

(MPP) with the objective function of  $G(u)$ .

This function recasts a  $G(u)$  response set (already transformed and approximated in other recursions) into an PMA objective function.

**8.86.2.4** void PMA\_constraint\_eval (const [Variables](#) & sub\_model\_vars, const [Variables](#) & recast\_vars, const [Response](#) & sub\_model\_response, [Response](#) & recast\_response) [static, protected]

(MPP) with the constraint of  $(\text{norm } u)^2 = \text{beta}^2$ .

This function recasts a  $G(u)$  response set (already transformed and approximated in other recursions) into a PMA equality constraint.

**8.86.2.5** `void jacobian_dX_dS (const Epetra_SerialDenseVector & x_vars, Epetra_SerialDenseMatrix & jacobian_xs)` [protected]

[trans\\_U\\_to\\_X\(\)](#) with respect to distribution parameters S

This procedure computes the derivative of the original variables  $x$  with respect to the random variable distribution parameters  $s$ . This provides the design Jacobian of the transformation for use in computing RBDO design sensitivities.

**8.86.2.6** `void numerical_design_jacobian (const Epetra_SerialDenseVector & x_vars, bool xs, Epetra_SerialDenseMatrix & num_jacobian_xs, bool zs, Epetra_SerialDenseMatrix & num_jacobian_zs)` [protected]

and  $zs$  booleans

This procedure computes numerical derivatives of  $x$  and/or  $z$  with respect to distribution parameters  $s$ , and is used by [jacobian\\_dX\\_dS\(\)](#) to provide data that is not available analytically. Numerical  $dz/ds$  involves  $dL/ds$  ( $z(s) = L(s) u$  and  $dz/ds = dL/ds u$ ) and is needed to evaluate  $dx/ds$  semi-analytically for correlated variables. Numerical  $dx/ds$  is needed for distributions lacking simple closed-form CDF expressions (beta and gamma distributions).

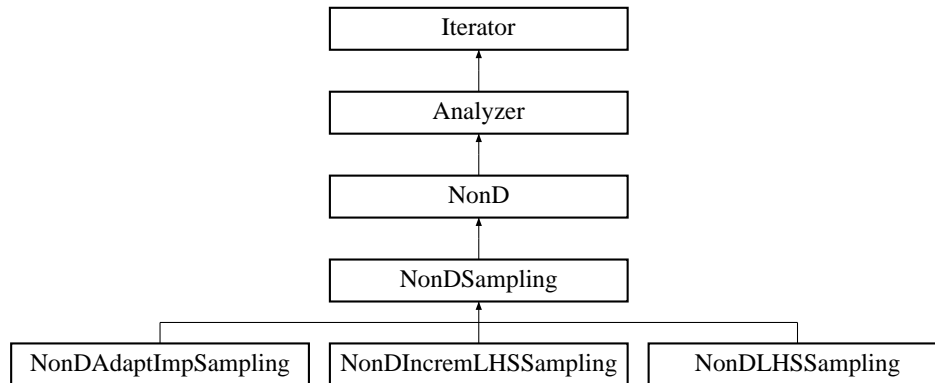
The documentation for this class was generated from the following files:

- NonDReliability.H
- NonDReliability.C

## 8.87 NonDSampling Class Reference

[NonDIncrLHSSampling](#), and [NonDAdaptImpSampling](#).

Inheritance diagram for NonDSampling::



### Public Member Functions

- void `compute_distribution_mappings` (const [ResponseArray](#) &samples)  
*z to p/beta and of p/beta to z*
- void `compute_correlations` (const [VariablesArray](#) &vars\_samples, const [ResponseArray](#) &resp\_samples)  
*simple, partial, simple rank, and partial rank*
- void `update_final_statistics` ()  
*and computedProbLevels/computedRelLevels/computedRespLevels*
- void `print_distribution_mappings` (ostream &s) const  
*prints the p/beta/z mappings computed in `compute_distribution_mappings()`*
- void `print_correlations` (ostream &s) const  
*prints the correlations computed in `compute_correlations()`*

### Protected Member Functions

- `NonDSampling` ([Model](#) &model)  
*constructor*
- `NonDSampling` ([NoDBBaseConstructor](#), [Model](#) &model, int samples, int seed)

*alternate constructor for sample generation and evaluation "on the fly"*

- [NonDSampling](#) ([NoDBBaseConstructor](#), int samples, int seed, const [RealVector](#) &lower\_bnds, const [RealVector](#) &upper\_bnds)  
*alternate constructor for sample generation "on the fly"*
- [~NonDSampling](#) ()  
*destructor*
- void [sampling\\_reset](#) (int min\_samples, bool all\_data\_flag, bool stats\_flag)  
*resets number of samples and sampling flags*
- const [String](#) & [sampling\\_scheme](#) () const  
*return sampleType: "lhs" or "random"*
- void [vary\\_pattern](#) (bool pattern\_flag)  
*set varyPattern*
- void [get\\_parameter\\_sets](#) (const [Model](#) &model)  
*called several times.*
- void [get\\_parameter\\_sets](#) (const [RealVector](#) &lower\_bnds, const [RealVector](#) &upper\_bnds)  
*lower\_bnds/upper\_bnds.*
- void [run\\_lhs](#) (const [RealVector](#) &d\_l\_bnds, const [RealVector](#) &d\_u\_bnds, const [RealVector](#) &s\_l\_bnds, const [RealVector](#) &s\_u\_bnds, const [RealVector](#) &n\_means, const [RealVector](#) &n\_std\_devs, const [RealVector](#) &n\_l\_bnds, const [RealVector](#) &n\_u\_bnds, const [RealVector](#) &ln\_means, const [RealVector](#) &ln\_std\_devs, const [RealVector](#) &ln\_err\_facts, const [RealVector](#) &ln\_l\_bnds, const [RealVector](#) &ln\_u\_bnds, const [RealVector](#) &u\_l\_bnds, const [RealVector](#) &u\_u\_bnds, const [RealVector](#) &lu\_l\_bnds, const [RealVector](#) &lu\_u\_bnds, const [RealVector](#) &t\_modes, const [RealVector](#) &t\_l\_bnds, const [RealVector](#) &t\_u\_bnds, const [RealVector](#) &e\_betas, const [RealVector](#) &b\_alphas, const [RealVector](#) &b\_betas, const [RealVector](#) &b\_l\_bnds, const [RealVector](#) &b\_u\_bnds, const [RealVector](#) &ga\_alphas, const [RealVector](#) &ga\_betas, const [RealVector](#) &w\_alphas, const [RealVector](#) &w\_betas, const [RealVectorArray](#) &h\_bin\_prs, const [RealVectorArray](#) &h\_pt\_prs, const [RealVectorArray](#) &i\_probs, const [RealVectorArray](#) &i\_bounds, const [RealMatrix](#) &correlations, [RealVectorArray](#) &rank\_array, int num\_samples, bool write\_message)  
*new LHS libraries.*
- void [compute\\_statistics](#) (const [VariablesArray](#) &vars\_samples, const [ResponseArray](#) &resp\_samples)  
*or intervals (epistemic or mixed uncertainties)*
- void [compute\\_intervals](#) (const [ResponseArray](#) &samples)  
*called by [compute\\_statistics\(\)](#) to calculate min/max intervals*
- void [compute\\_moments](#) (const [ResponseArray](#) &samples)  
*deviations, and confidence intervals*
- void [print\\_statistics](#) (ostream &s) const

*prints the statistics computed in `compute_statistics()`*

- void `print_intervals` (ostream &s) const  
*prints the intervals computed in `compute_intervals()`*
- void `print_moments` (ostream &s) const  
*prints the moments computed in `compute_moments()`*
- void `simple_corr` (Epetra\_SerialDenseMatrix &total\_data, bool rank\_on, const int &num\_in)  
*computes simple correlations*
- void `partial_corr` (Epetra\_SerialDenseMatrix &total\_data, bool rank\_on, const int &num\_in)  
*computes partial correlations*

### Static Protected Member Functions

- static bool `rank_sort` (const int &x, const int &y)  
*sort algorithm to compute ranks for rank correlations*

### Protected Attributes

- const int `originalSeed`  
*the user seed specification (default is 0)*
- int `samplesSpec`  
*initial specification of number of samples*
- int `numSamples`  
*the current number of samples to evaluate*
- String `sampleType`  
*the sample type: random, lhs, or incremental\_lhs*
- bool `statsFlag`  
*flags computation/output of statistics*
- bool `allDataFlag`  
*flags update of allVariables/allResponses*
- short `samplingVarsMode`  
*the sampling mode: ACTIVE, ACTIVE\_UNIFORM, ALL, or ALL\_UNIFORM*
- short `sampleRanksMode`

*SET\_RANKS, or SET\_GET\_RANKS.*

- bool [varyPattern](#)  
*optimization) are not repeated, but are still repeatable*
- [RealVectorArray](#) [sampleRanks](#)  
*data structure to hold the sample ranks*
- [RealVector](#) [mean95CIDeltas](#)  
*intervals (calculated in [compute\\_moments\(\)](#))*
- [RealVector](#) [stdDev95CILowerBnds](#)  
*(calculated in [compute\\_moments\(\)](#))*
- [RealVector](#) [stdDev95CIUpperBnds](#)  
*(calculated in [compute\\_moments\(\)](#))*

### Private Member Functions

- void [check\\_error](#) (const int &err\_code, const char \*err\_source) const  
*error is returned*

### Private Attributes

- int [randomSeed](#)  
*the current random number seed*
- size\_t [numLHSRuns](#)  
*counter for number of executions of [run\\_lhs\(\)](#) for this object*
- [RealVector](#) [minValues](#)  
*(calculated in [compute\\_intervals\(\)](#))*
- [RealVector](#) [maxValues](#)  
*(calculated in [compute\\_intervals\(\)](#))*
- [Epetra\\_SerialDenseMatrix](#) [simpleCorr](#)  
*matrix to hold simple raw correlations*
- [Epetra\\_SerialDenseMatrix](#) [simpleRankCorr](#)  
*matrix to hold simple rank correlations*
- [Epetra\\_SerialDenseMatrix](#) [partialCorr](#)

*matrix to hold partial raw correlations*

- Epetra\_SerialDenseMatrix [partialRankCorr](#)  
*matrix to hold partial rank correlations*

## Static Private Attributes

- static [RealArray](#) [rawData](#)  
*vector to hold raw data before rank sort*
- static int [pgf90Initialized](#)  
*flag indicating whether `pghpf_init()` has been called.*

### 8.87.1 Detailed Description

[NonDIncrLHSSampling](#), and [NonDAdaptImpSampling](#).

This base class provides common code for sampling methods which employ the Latin Hypercube Sampling (LHS) package from Sandia Albuquerque's Risk and Reliability organization. [NonDSampling](#) manages two LHS versions within a `#ifdef` construct in `run_lhs()`: (1) the 1998 Fortran 90 LHS version as documented in SAND98-0210, which was converted to a UNIX link library in 2001, (2) the 1970's vintage LHS that had been f2c'd and converted to (incomplete) classes.

### 8.87.2 Constructor & Destructor Documentation

#### 8.87.2.1 [NonDSampling](#) ([Model](#) & *model*) [protected]

constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification.

#### 8.87.2.2 [NonDSampling](#) ([NoDBBaseConstructor](#), [Model](#) & *model*, *int samples*, *int seed*) [protected]

alternate constructor for sample generation and evaluation "on the fly"

This alternate constructor is used for generation and evaluation of on-the-fly sample sets.

#### 8.87.2.3 [NonDSampling](#) ([NoDBBaseConstructor](#), *int samples*, *int seed*, *const RealVector* & *lower\_bnds*, *const RealVector* & *upper\_bnds*) [protected]

alternate constructor for sample generation "on the fly"

This alternate constructor is used by [ConcurrentStrategy](#) for generation of uniform, uncorrelated sample sets.

### 8.87.3 Member Function Documentation

**8.87.3.1 void `sampling_reset` (int `min_samples`, bool `all_data_flag`, bool `stats_flag`)** [`inline`, `protected`, `virtual`]

resets number of samples and sampling flags

used by [DataFitSurrModel::build\\_global\(\)](#) to publish the minimum number of samples needed from the sampling routine (to build a particular global approximation) and to set `allDataFlag` and `statsFlag`. In this case, `allDataFlag` is set to true (vectors of variable and response sets must be returned to build the global approximation) and `statsFlag` is set to false (statistics computations are not needed).

Reimplemented from [Iterator](#).

**8.87.3.2 void `get_parameter_sets` (const [Model](#) & `model`)** [`protected`, `virtual`]

called several times.

This version of [get\\_parameter\\_sets\(\)](#) extracts data from the user-defined model in any of the four sampling modes.

Reimplemented from [Analyzer](#).

**8.87.3.3 void `get_parameter_sets` (const [RealVector](#) & `lower_bnds`, const [RealVector](#) & `upper_bnds`)** [`protected`]

`lower_bnds/upper_bnds`.

This version of [get\\_parameter\\_sets\(\)](#) does not extract data from the user-defined model, but instead relies on the incoming bounded region definition. It only support a UNIFORM sampling mode, where the distinction of ACTIVE\_UNIFORM vs. ALL\_UNIFORM is handled elsewhere.

The documentation for this class was generated from the following files:

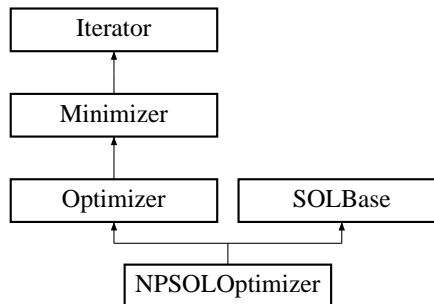
- [NonDSampling.H](#)
- [NonDSampling.C](#)



## 8.88 NPSOLOptimizer Class Reference

Wrapper class for the NPSOL optimization library.

Inheritance diagram for NPSOLOptimizer::



### Public Member Functions

- [NPSOLOptimizer \(Model &model\)](#)  
*standard constructor*
- [NPSOLOptimizer \(Model &model, const int &derivative\\_level, const Real &conv\\_tol\)](#)  
*alternate constructor for instantiations "on the fly"*
- [NPSOLOptimizer \(const RealVector &initial\\_point, const RealVector &var\\_lower\\_bnds, const RealVector &var\\_upper\\_bnds, const RealMatrix &lin\\_ineq\\_coeffs, const RealVector &lin\\_ineq\\_lower\\_bnds, const RealVector &lin\\_ineq\\_upper\\_bnds, const RealMatrix &lin\\_eq\\_coeffs, const RealVector &lin\\_eq\\_targets, const RealVector &nonlin\\_ineq\\_lower\\_bnds, const RealVector &nonlin\\_ineq\\_upper\\_bnds, const RealVector &nonlin\\_eq\\_targets, void\(\\*user\\_obj\\_eval\)\(int &, int &, double \\*, double &, double \\*, int &\), void\(\\*user\\_con\\_eval\)\(int &, int &, int &, int &, int \\*, double \\*, double \\*, double \\*, int &\), const int &derivative\\_level, const Real &conv\\_tol\)](#)  
*alternate constructor for instantiations "on the fly"*
- [~NPSOLOptimizer \(\)](#)  
*destructor*
- [void find\\_optimum \(\)](#)  
*Redefines the run virtual function for the optimizer branch.*

### Private Member Functions

- [void find\\_optimum\\_on\\_model \(\)](#)

called by `find_optimum` for `setUpType == "model"`

- void [find\\_optimum\\_on\\_user\\_functions](#) ()  
called by `find_optimum` for `setUpType == "user_functions"`

## Static Private Member Functions

- static void [objective\\_eval](#) (int &mode, int &n, double \*x, double &f, double \*gradf, int &nstate)  
*objective function (passed by function pointer to NPSOL).*

## Private Attributes

- String [setUpType](#)  
*NonDReliability currently uses the user\_functions mode.*
- RealVector [initialPoint](#)  
*holds initial point passed in for "user\_functions" mode.*
- RealVector [lowerBounds](#)  
*holds variable lower bounds passed in for "user\_functions" mode.*
- RealVector [upperBounds](#)  
*holds variable upper bounds passed in for "user\_functions" mode.*
- void(\* [userObjectiveEval](#) )(int &, int &, double \*, double &, double \*, int &)  
*"user\_functions" mode.*
- void(\* [userConstraintEval](#) )(int &, int &, int &, int &, int \*, double \*, double \*, double \*, int &)  
*"user\_functions" mode.*

## Static Private Attributes

- static [NPSOLOptimizer](#) \* [npsolInstance](#)  
*functions in order to avoid the need for static data*

### 8.88.1 Detailed Description

Wrapper class for the NPSOL optimization library.

The [NPSOLOptimizer](#) class provides a wrapper for NPSOL, a Fortran 77 sequential quadratic programming library from Stanford University marketed by Stanford Business Associates. It uses a function pointer approach

for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function or accessed through a static pointer.

The user input mappings are as follows: `max_function_evaluations` is implemented directly in `NPSOLOptimizer`'s evaluator functions since there is no NPSOL parameter equivalent, and `max_iterations`, `convergence_tolerance`, `output_verbosity`, `verify_level`, `function_precision`, and `linesearch_tolerance` are mapped into NPSOL's "Major Iteration Limit", "Optimality Tolerance", "Major Print Level" (`verbose`: Major Print Level = 20; `quiet`: Major Print Level = 10), "Verify Level", "Function Precision", and "Linesearch Tolerance" parameters, respectively, using NPSOL's `npoptn()` subroutine (as wrapped by `npoptn2()` from the `npoptn_wrapper.f` file). Refer to [Gill, P.E., Murray, W., Saunders, M.A., and Wright, M.H., 1986] for information on NPSOL's optional input parameters and the `npoptn()` subroutine.

## 8.88.2 Constructor & Destructor Documentation

### 8.88.2.1 NPSOLOptimizer (Model & model, const int & derivative\_level, const Real & conv\_tol)

alternate constructor for instantiations "on the fly"

This is an alternate constructor for instantiations on the fly using a [Model](#) but no [ProblemDescDB](#).

### 8.88.2.2 NPSOLOptimizer (const RealVector & initial\_point, const RealVector & var\_lower\_bnds, const RealVector & var\_upper\_bnds, const RealMatrix & lin\_ineq\_coeffs, const RealVector & lin\_ineq\_lower\_bnds, const RealVector & lin\_ineq\_upper\_bnds, const RealMatrix & lin\_eq\_coeffs, const RealVector & lin\_eq\_targets, const RealVector & nonlin\_ineq\_lower\_bnds, const RealVector & nonlin\_ineq\_upper\_bnds, const RealVector & nonlin\_eq\_targets, void(\*) (int &, int &, double \*, double &, double \*, int &) user\_obj\_eval, void(\*) (int &, int &, int &, int &, int \*, double \*, double \*, double \*, int &) user\_con\_eval, const int & derivative\_level, const Real & conv\_tol)

alternate constructor for instantiations "on the fly"

This is an alternate constructor for performing an optimization using the passed in objective function and constraint function pointers.

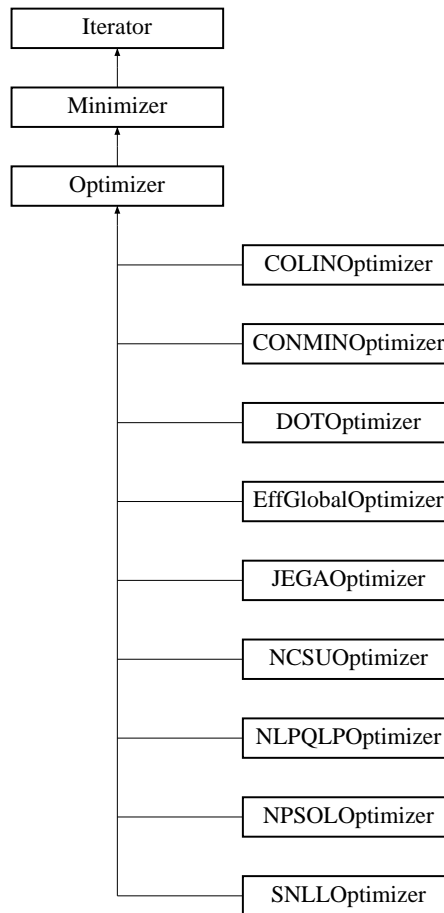
The documentation for this class was generated from the following files:

- [NPSOLOptimizer.H](#)
- [NPSOLOptimizer.C](#)

## 8.89 Optimizer Class Reference

Base class for the optimizer branch of the iterator hierarchy.

Inheritance diagram for Optimizer::



### Public Member Functions

- void `run()`  
*run the iterator; portion of `run_iterator()`*

### Protected Member Functions

- `Optimizer()`

*default constructor*

- [Optimizer](#) ([Model](#) &model)  
*standard constructor*
- [Optimizer](#) ([NoDBBaseConstructor](#), [Model](#) &model)  
*alternate constructor for "on the fly" instantiations*
- [Optimizer](#) ([NoDBBaseConstructor](#), [size\\_t](#) num\_cv, [size\\_t](#) num\_dv, [size\\_t](#) num\_lin\_ineq, [size\\_t](#) num\_lin\_eq, [size\\_t](#) num\_nln\_ineq, [size\\_t](#) num\_nln\_eq)  
*alternate constructor for "on the fly" instantiations*
- [~Optimizer](#) ()  
*destructor*
- void [print\\_results](#) ([ostream](#) &s) const
- void [multi\\_objective\\_weights](#) (const [RealVector](#) &multi\_obj\_wts)  
*Used by [ConcurrentStrategy](#) for Pareto set optimization.*
- void [derived\\_initialize\\_scaling](#) ([StringArray](#) &fn\_scale\_types, [RealVector](#) &fn\_scales)  
*respectively*
- void [derived\\_post\\_run](#) ()
- virtual void [find\\_optimum](#) ()=0  
*Redefines the run virtual function for the optimizer branch.*
- [Response](#) [multi\\_objective\\_modify](#) (const [Response](#) &raw\_response) const  
*objective for single-objective optimizers*
- const [RealVector](#) & [multi\\_objective\\_retrieve](#) (const [Variables](#) &vars, const [Response](#) &response) const  
*from the solution of a single-objective optimizer*

## Static Protected Member Functions

- static void [primary\\_resp\\_recast](#) (const [Variables](#) &native\_vars, const [Variables](#) &scaled\_vars, const [Response](#) &native\_response, [Response](#) &scaled\_response)  
*from native (user) to iterator space*

## Protected Attributes

- [size\\_t](#) [numObjectiveFunctions](#)  
*number of objective functions (iterator view)*

- `size_t numUserObjectiveFunctions`  
*number of objective functions (user's model view)*
- `RealVector multiObjWeights`  
*user-specified weights for multiple objective functions*
- `bool multiObjFlag`  
*flag indicating whether multi-objective transformations are necessary*

### Static Protected Attributes

- `static Optimizer * optimizerInstance`  
*pointer to `Optimizer` instance used in static member functions*

### 8.89.1 Detailed Description

Base class for the optimizer branch of the iterator hierarchy.

The `Optimizer` class provides common data and functionality for `DOTOptimizer`, `CONMINOptimizer`, `NPSOLOptimizer`, `SNLLOptimizer`, `NLPQLPOptimizer`, `COLINOptimizer`, and `JEGAOptimizer`.

### 8.89.2 Constructor & Destructor Documentation

#### 8.89.2.1 `Optimizer (Model & model)` [protected]

standard constructor

This constructor extracts the inherited data for the optimizer branch and performs sanity checking on gradient and constraint settings.

### 8.89.3 Member Function Documentation

#### 8.89.3.1 `void run ()` [inline, virtual]

run the iterator; portion of `run_iterator()`

`Iterator` supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented from `Iterator`.

**8.89.3.2 void print\_results (ostream & s) const** [protected, virtual]

Redefines default iterator results printing to include optimization results (objective functions and constraints).

Reimplemented from [Iterator](#).

**8.89.3.3 void derived\_post\_run ()** [protected, virtual]

Implements portions of post\_run specific to Optimizers.

Reimplemented from [Iterator](#).

**8.89.3.4 void primary\_resp\_recast (const Variables & native\_vars, const Variables & scaled\_vars, const Response & native\_response, Response & iterator\_response)** [static, protected]

from native (user) to iterator space

Objective function map from user/native space to iterator/scaled/combined space using a [RecastModel](#). If resizing the response, copies the constraint (secondary) data from native\_response too

**8.89.3.5 Response multi\_objective\_modify (const Response & raw\_response) const** [protected]

objective for single-objective optimizers

This function is responsible for the mapping of multiple objective functions into a single objective for publishing to single-objective optimizers. Used in [DOTOptimizer](#), [NPSOLOptimizer](#), [SNLLOptimizer](#), and [SGOPTApplication](#) on every function evaluation. The simple weighting approach (using [multiObjWeights](#)) is the only technique supported currently. The weightings are used to scale function values, gradients, and Hessians as needed.

**8.89.3.6 const RealVector & multi\_objective\_retrieve (const Variables & vars, const Response & response) const** [protected]

from the solution of a single-objective optimizer

Retrieve a full multiobjective response based on the data returned by a single objective optimizer by performing a `data_pairs` search.

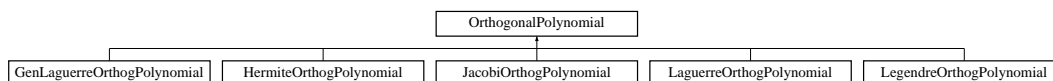
The documentation for this class was generated from the following files:

- [DakotaOptimizer.H](#)
- [DakotaOptimizer.C](#)

## 8.90 OrthogonalPolynomial Class Reference

Base class for the orthogonal polynomial class hierarchy.

Inheritance diagram for OrthogonalPolynomial::



### Public Member Functions

- [OrthogonalPolynomial](#) ()  
*default constructor*
- [OrthogonalPolynomial](#) (short poly\_type)  
*alternate constructor*
- [OrthogonalPolynomial](#) (const [OrthogonalPolynomial](#) &polynomial)  
*copy constructor*
- virtual [~OrthogonalPolynomial](#) ()  
*destructor*
- [OrthogonalPolynomial operator=](#) (const [OrthogonalPolynomial](#) &polynomial)  
*assignment operator*
- virtual const Real & [get\\_value](#) (const Real &x, size\_t n)  
*retrieve the orthogonal polynomial value for a given parameter value*
- virtual const Real & [get\\_gradient](#) (const Real &x, size\_t n)  
*retrieve the orthogonal polynomial gradient for a given parameter value*
- virtual const Real & [norm\\_squared](#) (size\_t n)  
*of the orthogonality statement for the derived polynomial type.*
- virtual const [RealVector](#) & [gauss\\_points](#) (size\_t n)  
*return the [gaussPoints](#) corresponding to polynomial order n*
- virtual const [RealVector](#) & [gauss\\_weights](#) (size\_t n)  
*return the [gaussWeights](#) corresponding to polynomial order n*
- virtual void [alpha\\_stat](#) (const Real &alpha)



*set alphaPoly from alpha\_stat*

- virtual void [beta\\_stat](#) (const Real &beta)  
*set betaPoly from beta\_stat*
- void [gauss\\_check](#) (size\_t n)  
*perform unit testing on the Gauss points/weights*

## Protected Member Functions

- [OrthogonalPolynomial](#) ([BaseConstructor](#))  
*derived class constructors - Coplien, p. 139*
- size\_t [factorial](#) (size\_t n)  
*compute n!*
- Real [factorial\\_ratio](#) (size\_t num, size\_t den)  
*compute num!/den!*
- size\_t [n\\_choose\\_k](#) (size\_t n, size\_t k)  
*compute n!/(k!(n-k)!)*
- Real [pochhammer](#) (const Real &m, size\_t n)  
*compute the Pochhammer symbol (m)\_n = m\*(m+1)...\*(m+n-1)*

## Protected Attributes

- Real [orthogPolyValue](#)  
*value of the 1-D orthogonal polynomial returned by [get\\_value\(\)](#)*
- Real [orthogPolyGradient](#)  
*gradient of the 1-D orthogonal polynomial returned by [get\\_gradient\(\)](#)*
- Real [orthogPolyNormSq](#)  
 $\langle \text{Poly}_n, \text{Poly}_n \rangle = \|\text{Poly}_n\|^2$  (returned by [norm\\_squared\(\)](#))
- [RealVector](#) [gaussPoints](#)  
*(x parameter values for which  $\text{Poly}_n(x) = 0$ )*
- [RealVector](#) [gaussWeights](#)  
*Gauss weights for one-dimensional Gaussian quadrature.*

## Private Member Functions

- [OrthogonalPolynomial](#) \* [get\\_polynomial](#) (short *poly\_type*)  
*appropriate derived type.*

## Private Attributes

- [OrthogonalPolynomial](#) \* [polyRep](#)  
*pointer to the letter (initialized only for the envelope)*
- int [referenceCount](#)  
*number of objects sharing polyRep*

### 8.90.1 Detailed Description

Base class for the orthogonal polynomial class hierarchy.

The [OrthogonalPolynomial](#) class is the base class for the univariate orthogonal polynomial class hierarchy in DAKOTA. One instance of an [OrthogonalPolynomial](#) is created for each variable within a multidimensional orthogonal polynomial basis function (a vector of [OrthogonalPolynomials](#) is contained in [OrthogPolyApproximation](#), which may be mixed and matched in, e.g., the Wiener-Askey scheme for polynomial chaos). For memory efficiency and enhanced polymorphism, the orthogonal polynomial hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([OrthogonalPolynomial](#)) serves as the envelope and one of the derived classes (selected in [OrthogonalPolynomial::get\\_polynomial\(\)](#)) serves as the letter.

### 8.90.2 Constructor & Destructor Documentation

#### 8.90.2.1 [OrthogonalPolynomial](#) ()

default constructor

The default constructor is used in `Array<OrthogonalPolynomial>` instantiations and by the alternate envelope constructor. `polyRep` is NULL in this case (`problem_db` is needed to build a meaningful instance). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

#### 8.90.2.2 [OrthogonalPolynomial](#) (short *poly\_type*)

alternate constructor

Envelope constructor which does not require access to `problem_db`. This constructor executes `get_polynomial(type)`, which invokes the default constructor of the derived letter class, which in turn invokes the [BaseConstructor](#) of the base class.

### 8.90.2.3 OrthogonalPolynomial (const OrthogonalPolynomial & polynomial)

copy constructor

Copy constructor manages sharing of polyRep and incrementing of referenceCount.

### 8.90.2.4 ~OrthogonalPolynomial () [virtual]

destructor

Destructor decrements referenceCount and only deletes polyRep when referenceCount reaches zero.

### 8.90.2.5 OrthogonalPolynomial (BaseConstructor) [protected]

derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. `get_polynomial()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid recursion in the base class constructor calling `get_polynomial()` again). Since the letter IS the representation, its rep pointer is set to NULL (an uninitialized pointer causes problems in `~OrthogonalPolynomial`).

## 8.90.3 Member Function Documentation

### 8.90.3.1 OrthogonalPolynomial operator= (const OrthogonalPolynomial & polynomial)

assignment operator

Assignment operator decrements referenceCount for old polyRep, assigns new polyRep, and increments referenceCount for new polyRep.

### 8.90.3.2 size\_t factorial (size\_t n) [inline, protected]

compute n!

This implementation is unprotected from overflow, but this should be fine for the polynomial orders that we would expect to encounter. Whenever possible, orthogonal polynomial implementations should use `factorial_ratio()` or `n_choose_k()` instead of `factorial()` to avoid size\_t overflow.

### 8.90.3.3 Real factorial\_ratio (size\_t num, size\_t den) [inline, protected]

compute num!/den!

This implementation sequences products in order to minimize the chances of overflow, and its use should be preferred to `factorial()` whenever possible.

**8.90.3.4** `size_t n_choose_k (size_t n, size_t k)` [inline, protected]

compute  $n!/(k!(n-k)!)$

This implementation sequences products in order to minimize the chances of overflow, and its use should be preferred to `factorial()` whenever possible.

**8.90.3.5** `Real pochhammer (const Real & m, size_t n)` [inline, protected]

compute the Pochhammer symbol  $(m)_n = m*(m+1)*\dots*(m+n-1)$

This is the rising/upper factorial formulation of the Pochhammer symbol  $(m)_n$ .

**8.90.3.6** `OrthogonalPolynomial * get_polynomial (short poly_type)` [private]

appropriate derived type.

Used only by the envelope constructor to initialize `polyRep` to the appropriate derived type.

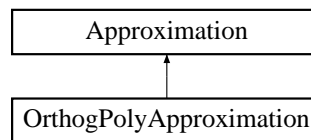
The documentation for this class was generated from the following files:

- `OrthogonalPolynomial.H`
- `OrthogonalPolynomial.C`

## 8.91 OrthogPolyApproximation Class Reference

approximation).

Inheritance diagram for OrthogPolyApproximation::



### Public Member Functions

- [OrthogPolyApproximation \(\)](#)  
*default constructor*
- [OrthogPolyApproximation \(ProblemDescDB &problem\\_db, const size\\_t &num\\_acv\)](#)  
*standard constructor*
- [~OrthogPolyApproximation \(\)](#)  
*destructor*
- void [solution\\_approach](#) (short soln\_approach)  
*set coeffSolnApproach*
- short [solution\\_approach](#) () const  
*get coeffSolnApproach*
- void [expansion\\_terms](#) (const int &exp\_terms)  
*set numExpansionTerms*
- const int & [expansion\\_terms](#) () const  
*get numExpansionTerms*
- void [integration\\_iterator](#) (const [Iterator](#) &iterator)  
*set integrationRep*
- void [basis\\_types](#) (const [ShortArray](#) &basis)  
*set basisTypes*
- const [ShortArray](#) & [basis\\_types](#) () const  
*get basisTypes*

- void `jacobi_alphas` (const `RealVector` &alphas)  
*pass alpha\_stat parameters to JACOBI polynomial bases*
- void `jacobi_betas` (const `RealVector` &betas)  
*pass beta\_stat parameters to JACOBI polynomial bases*
- void `generalized_laguerre_alphas` (const `RealVector` &alphas)  
*pass alpha\_stat parameters to GENERALIZED\_LAGUERRE polynomial bases*
- void `resolve_inputs` ()  
*(numExpansionTerms and approxOrder) based on user input*
- const `Real` & `get_mean` ()  
*return the mean of the PCE, treating all variables as random*
- const `Real` & `get_mean` (const `RealVector` &x, const `BoolDeque` &random\_vars\_key)  
*treating a subset of the variables as random*
- const `RealBaseVector` & `get_mean_gradient` (const `RealVector` &x, const `BoolDeque` &random\_vars\_key, const `IntArray` &dvv)  
*treating a subset of the variables as random*
- const `Real` & `get_variance` ()  
*return the variance of the PCE, treating all variables as random*
- const `Real` & `get_variance` (const `RealVector` &x, const `BoolDeque` &random\_vars\_key)  
*treating a subset of the variables as random*
- const `RealBaseVector` & `get_variance_gradient` (const `RealVector` &x, const `BoolDeque` &random\_vars\_key, const `IntArray` &dvv)  
*treating a subset of the variables as random*
- const `Real` & `norm_squared` (size\_t expansion\_index)  
*treating all variables as random*
- const `Real` & `norm_squared` (size\_t expansion\_index, const `BoolDeque` &random\_vars\_key)  
*treating a subset of the variables as random*

### Protected Member Functions

- int `num_coefficients` () const  
*derived class approximation type in numVars dimensions*
- int `num_constraints` () const

*return the number of constraints to be enforced via anchorPoint*

- const `RealVector` & `approximation_coefficients` () const  
*return the coefficient array computed by `find_coefficients()`*
- void `approximation_coefficients` (const `RealVector` &approx\_coeffs)  
*computing with `find_coefficients()`*
- void `find_coefficients` ()  
*orthogonal polynomials*
- void `print_coefficients` (ostream &s) const  
*print the coefficients for the expansion*
- const Real & `get_value` (const `RealVector` &x)  
*retrieve the response PCE value for a given parameter vector*
- const `RealBaseVector` & `get_gradient` (const `RealVector` &x)  
*and default DVV*
- const `RealBaseVector` & `get_gradient` (const `RealVector` &x, const `IntArray` &dvv)  
*and given DVV*

## Private Member Functions

- const `RealVector` & `get_multivariate_polynomials` (const `RealVector` &xi)  
*evaluated at a particular parameter set*
- void `integration` ()  
*(chaosCoeffsSolnApproach is QUADRATURE or CUBATURE)*
- void `regression` ()  
*(chaosCoeffsSolnApproach is POINT\_COLLOCATION)*
- void `expectation` ()  
*(chaosCoeffsSolnApproach is SAMPLING)*
- void `gradient_check` ()  
*cross-validates alternate gradient expressions*

## Private Attributes

- short `chaosCoeffsSolnApproach`  
*QUADRATURE, CUBATURE, POINT\_COLLOCATION, or SAMPLING.*
- int `numExpansionTerms`  
*number of terms in Polynomial Chaos expansion (length of chaosCoeffs)*
- `NonDIntegration * integrationRep`  
*weight products*
- `Array< OrthogonalPolynomial > polynomialBasis`  
*(wienerAskeyChaos) based on multiIndex*
- `ShortArray basisTypes`  
*HERMITE, LEGENDRE, LAGUERRE, JACOBI, or GENERALIZED\_LAGUERRE.*
- `Size2DArray multiIndex`  
*of the multivariate orthogonal polynomials*
- `RealVector wienerAskeyChaos`  
*a particular xi (returned by `get_multivariate_polynomials()`)*
- Real `pceMean`  
*expected value of the expansion*
- `RealVector pceMeanGradient`  
*gradient of the expected value of the expansion*
- Real `pceVariance`  
*variance of the expansion*
- `RealVector pceVarianceGradient`  
*gradient of the variance of the expansion*
- Real `multiPolyNormSq`  
*norm-squared of one of the multivariate polynomial basis functions*
- `RealVector chaosCoeffs`  
*numExpansionTerms entries*
- `RealVectorArray chaosSamples`  
*numExpansionTerms\*num\_pts entries*



### 8.91.1 Detailed Description

approximation).

The [OrthogPolyApproximation](#) class provides a global approximation based on orthogonal polynomials. It is used primarily for polynomial chaos expansions (for stochastic finite element approaches to uncertainty quantification).

### 8.91.2 Member Function Documentation

#### 8.91.2.1 `const Real & get_mean ()`

return the mean of the PCE, treating all variables as random

In this case, all expansion variables are random variables and the mean of the expansion is simply the first chaos coefficient.

#### 8.91.2.2 `const Real & get_mean (const RealVector & x, const BoolDeque & random_vars_key)`

treating a subset of the variables as random

In this case, a subset of the expansion variables are random variables and the mean of the expansion involves evaluating the expectation over this subset.

#### 8.91.2.3 `const RealBaseVector & get_mean_gradient (const RealVector & x, const BoolDeque & random_vars_key, const IntArray & dvv)`

treating a subset of the variables as random

In this function, a subset of the expansion variables are random variables, for which the mean of the expansion is the expectation over the random subset and the derivative of the mean is the derivative of the remaining expansion over the non-random subset.

#### 8.91.2.4 `const Real & get_variance ()`

return the variance of the PCE, treating all variables as random

In this case, all expansion variables are random variables and the variance of the expansion is the sum over all but the first term of the coefficients squared times the polynomial norms squared.

#### 8.91.2.5 `void integration () [private]`

(chaosCoeffsSolnApproach is QUADRATURE or CUBATURE)

The coefficients of the PCE for the response are calculated using a Galerkin projection of the response against each multivariate orthogonal polynomial basis  $f_n$  using the inner product ratio  $\langle f, \Psi \rangle / \langle \Psi, \Psi \rangle$ , where inner product  $\langle a, b \rangle$  is the n-dimensional integral of  $a \cdot b$  weighting over the support range of the n-dimensional (composite)

weighting function. 1-D quadrature rules are defined for specific 1-D weighting functions and support ranges and approximate the integral of  $f \cdot \text{weighting}$  as the  $\text{Sum}_i$  of  $w_i f_i$ . To extend this to n-dimensions, a tensor product quadrature rule or sparse grid cubature rule is applied using the product of 1-D weightings applied to the n-dimensional stencil of points. It is not necessary to approximate the integral for the denominator numerically, since this is available analytically.

#### 8.91.2.6 void regression () [private]

(chaosCoeffsSolnApproach is POINT\_COLLOCATION)

In this case, regression is used in place of Galerkin projection. That is, instead of calculating the PCE coefficients using inner product ratios, linear least squares is used to estimate the PCE coefficients which best match a set of response samples. This approach is also known as stochastic response surfaces. The least squares estimation is performed using DGELSS (SVD) or DGGLSE (equality-constrained) from LAPACK, based on the presence of an anchorPoint.

#### 8.91.2.7 void expectation () [private]

(chaosCoeffsSolnApproach is SAMPLING)

The coefficients of the PCE for the response are calculated using a Galerkin projection of the response against each multivariate orthogonal polynomial basis  $f_n$  using the inner product ratio  $\langle f, \Psi_i \rangle / \langle \Psi_i, \Psi_i \rangle$ , where inner product  $\langle a, b \rangle$  is the n-dimensional integral of  $a \cdot b \cdot \text{weighting}$  over the support range of the n-dimensional (composite) weighting function. When interpreting the weighting function as a probability density function,  $\langle a, b \rangle =$  expected value of  $a \cdot b$ , which can be evaluated by sampling from the probability density function and computing the mean statistic. It is not necessary to compute the mean statistic for the denominator, since this is available analytically.

#### 8.91.2.8 void gradient\_check () [private]

cross-validates alternate gradient expressions

This test works in combination with DEBUG settings in (Legendre,Laguerre,Jacobi,GenLaguerre)Orthog-Polynomial::get\_gradient().

The documentation for this class was generated from the following files:

- OrthogPolyApproximation.H
- OrthogPolyApproximation.C

## 8.92 ParallelConfiguration Class Reference

collectively identify a particular multilevel parallel configuration.

### Public Member Functions

- [ParallelConfiguration](#) ()  
*default constructor*
- [ParallelConfiguration](#) (const [ParallelConfiguration](#) &pl)  
*copy constructor*
- [~ParallelConfiguration](#) ()  
*destructor*
- [ParallelConfiguration](#) & [operator=](#) (const [ParallelConfiguration](#) &pl)  
*assignment operator*
- const [ParallelLevel](#) & [w\\_parallel\\_level](#) () const  
*return the [ParallelLevel](#) corresponding to wPLIter*
- const [ParallelLevel](#) & [si\\_parallel\\_level](#) () const  
*return the [ParallelLevel](#) corresponding to siPLIter*
- const [ParallelLevel](#) & [ie\\_parallel\\_level](#) () const  
*return the [ParallelLevel](#) corresponding to iePLIter*
- const [ParallelLevel](#) & [ea\\_parallel\\_level](#) () const  
*return the [ParallelLevel](#) corresponding to eaPLIter*

### Private Member Functions

- void [assign](#) (const [ParallelConfiguration](#) &pl)  
*assign the attributes of the incoming pl to this object*

### Private Attributes

- short [numParallelLevels](#)  
*number of parallel levels*

- [ParLevLIter wPLIter](#)  
*improves modularity by avoiding explicit usage of MPI\_COMM\_WORLD*
- [ParLevLIter siPLIter](#)  
*(there may be more than one per parallel configuration instance)*
- [ParLevLIter iePLIter](#)  
*(there can only be one)*
- [ParLevLIter eaPLIter](#)  
*(there can only be one)*

## Friends

- class [ParallelLibrary](#)  
*streamline implementation*

### 8.92.1 Detailed Description

collectively identify a particular multilevel parallel configuration.

Rather than containing the multilevel parallel configuration directly, [ParallelConfiguration](#) instead provides a set of list iterators which point into a combined list of [ParallelLevels](#). This approach allows different configurations to reuse [ParallelLevels](#) without copying them. A list of [ParallelConfigurations](#) is contained in [ParallelLibrary](#) ([ParallelLibrary::parallelConfigurations](#)).

The documentation for this class was generated from the following file:

- [ParallelLibrary.H](#)

## 8.93 ParallelLevel Class Reference

communicator partitioning.

### Public Member Functions

- [ParallelLevel \(\)](#)  
*default constructor*
- [ParallelLevel \(const ParallelLevel &pl\)](#)  
*copy constructor*
- [~ParallelLevel \(\)](#)  
*destructor*
- [ParallelLevel & operator= \(const ParallelLevel &pl\)](#)  
*assignment operator*
- [bool dedicated\\_master\\_flag \(\) const](#)  
*return dedicatedMasterFlag*
- [bool communicator\\_split\\_flag \(\) const](#)  
*return commSplitFlag*
- [bool server\\_master\\_flag \(\) const](#)  
*return serverMasterFlag*
- [bool message\\_pass \(\) const](#)  
*return messagePass*
- [const int & num\\_servers \(\) const](#)  
*return numServers*
- [const int & processors\\_per\\_server \(\) const](#)  
*return procsPerServer*
- [const MPI\\_Comm & server\\_intra\\_communicator \(\) const](#)  
*return serverIntraComm*
- [const int & server\\_communicator\\_rank \(\) const](#)  
*return serverCommRank*

- const int & [server\\_communicator\\_size](#) () const  
*return serverCommSize*
- const MPI\_Comm & [hub\\_server\\_intra\\_communicator](#) () const  
*return hubServerIntraComm*
- const int & [hub\\_server\\_communicator\\_rank](#) () const  
*return hubServerCommRank*
- const int & [hub\\_server\\_communicator\\_size](#) () const  
*return hubServerCommSize*
- const MPI\_Comm & [hub\\_server\\_inter\\_communicator](#) () const  
*return hubServerInterComm*
- MPI\_Comm \* [hub\\_server\\_inter\\_communicators](#) () const  
*return hubServerInterComms*
- const int & [server\\_id](#) () const  
*return serverId*

### Private Member Functions

- void [assign](#) (const [ParallelLevel](#) &pl)  
*assign the attributes of the incoming pl to this object*

### Private Attributes

- bool [dedicatedMasterFlag](#)  
*signals dedicated master partitioning*
- bool [commSplitFlag](#)  
*signals a communicator split was used*
- bool [serverMasterFlag](#)  
*identifies master server processors*
- bool [messagePass](#)  
*flag for message passing at this level*
- int [numServers](#)  
*number of servers*

- int [procsPerServer](#)  
*processors per server*
- MPI\_Comm [serverIntraComm](#)  
*intracomm. for each server partition*
- int [serverCommRank](#)  
*rank in serverIntraComm*
- int [serverCommSize](#)  
*size of serverIntraComm*
- MPI\_Comm [hubServerIntraComm](#)  
*intracomm for all serverCommRank==0 w/i next higher level serverIntraComm*
- int [hubServerCommRank](#)  
*rank in hubServerIntraComm*
- int [hubServerCommSize](#)  
*size of hubServerIntraComm*
- MPI\_Comm [hubServerInterComm](#)  
*intercomm. between a server & the hub (on server partitions only)*
- MPI\_Comm \* [hubServerInterComms](#)  
*intercomm. array on hub processor*
- int [serverId](#)  
*server identifier*

## Friends

- class [ParallelLibrary](#)  
*streamline implementation*

### 8.93.1 Detailed Description

communicator partitioning.

A list of these levels is contained in [ParallelLibrary](#) ([ParallelLibrary::parallelLevels](#)), which defines all of the parallelism levels across one or more multilevel parallelism configurations.

The documentation for this class was generated from the following file:

- [ParallelLibrary.H](#)

## 8.94 ParallelLibrary Class Reference

message passing within these levels.

### Public Member Functions

- [ParallelLibrary](#) (int &argc, char \*\*&argv)  
*stand-alone mode constructor*
- [ParallelLibrary](#) ()  
*library mode constructor*
- [ParallelLibrary](#) (int dummy)  
*dummy constructor (used for dummy\_lib)*
- [~ParallelLibrary](#) ()  
*destructor*
- const [ParallelLevel](#) & [init\\_iterator\\_communicators](#) (const int &iterator\_servers, const int &procs\_per\_iterator, const int &max\_iterator\_concurrency, const [String](#) &default\_config, const [String](#) &iterator\_scheduling)  
*split MPI\_COMM\_WORLD into iterator communicators*
- const [ParallelLevel](#) & [init\\_evaluation\\_communicators](#) (const int &evaluation\_servers, const int &procs\_per\_evaluation, const int &max\_evaluation\_concurrency, const int &asynch\_local\_evaluation\_concurrency, const [String](#) &default\_config, const [String](#) &evaluation\_scheduling)  
*split an iterator communicator into evaluation communicators*
- const [ParallelLevel](#) & [init\\_analysis\\_communicators](#) (const int &analysis\_servers, const int &procs\_per\_analysis, const int &max\_analysis\_concurrency, const int &asynch\_local\_analysis\_concurrency, const [String](#) &default\_config, const [String](#) &analysis\_scheduling)  
*split an evaluation communicator into analysis communicators*
- void [free\\_iterator\\_communicators](#) ()  
*deallocate iterator communicators*
- void [free\\_evaluation\\_communicators](#) ()  
*deallocate evaluation communicators*
- void [free\\_analysis\\_communicators](#) ()  
*deallocate analysis communicators*
- void [print\\_configuration](#) ()



*print the parallel level settings for a particular parallel configuration*

- void [specify\\_outputs\\_restart](#) ([CommandLineHandler](#) &cmd\_line\_handler)  
*inputs (normal mode)*
- void [specify\\_outputs\\_restart](#) (const char \*clh\_std\_output\_filename, const char \*clh\_std\_error\_filename, const char \*clh\_read\_restart\_filename, const char \*clh\_write\_restart\_filename, int restart\_evals)  
*inputs (library mode).*
- void [manage\\_outputs\\_restart](#) (const [ParallelLevel](#) &pl)  
*manage output streams and restart file(s) (both modes)*
- void [close\\_streams](#) ()  
*close streams, files, and any other services*
- void [send\\_si](#) ([MPIPackBuffer](#) &send\_buff, int dest, int tag)  
*blocking send at the strategy-iterator communication level*
- void [isend\\_si](#) ([MPIPackBuffer](#) &send\_buff, int dest, int tag, [MPI\\_Request](#) &send\_req)  
*nonblocking send at the strategy-iterator communication level*
- void [recv\\_si](#) ([MPIUnpackBuffer](#) &recv\_buff, int source, int tag, [MPI\\_Status](#) &status)  
*blocking receive at the strategy-iterator communication level*
- void [irecv\\_si](#) ([MPIUnpackBuffer](#) &recv\_buff, int source, int tag, [MPI\\_Request](#) &recv\_req)  
*nonblocking receive at the strategy-iterator communication level*
- void [send\\_ie](#) ([MPIPackBuffer](#) &send\_buff, int dest, int tag)  
*blocking send at the iterator-evaluation communication level*
- void [isend\\_ie](#) ([MPIPackBuffer](#) &send\_buff, int dest, int tag, [MPI\\_Request](#) &send\_req)  
*nonblocking send at the iterator-evaluation communication level*
- void [recv\\_ie](#) ([MPIUnpackBuffer](#) &recv\_buff, int source, int tag, [MPI\\_Status](#) &status)  
*blocking receive at the iterator-evaluation communication level*
- void [irecv\\_ie](#) ([MPIUnpackBuffer](#) &recv\_buff, int source, int tag, [MPI\\_Request](#) &recv\_req)  
*nonblocking receive at the iterator-evaluation communication level*
- void [send\\_ea](#) (int &send\_int, int dest, int tag)  
*blocking send at the evaluation-analysis communication level*
- void [isend\\_ea](#) (int &send\_int, int dest, int tag, [MPI\\_Request](#) &send\_req)  
*nonblocking send at the evaluation-analysis communication level*
- void [recv\\_ea](#) (int &recv\_int, int source, int tag, [MPI\\_Status](#) &status)

*blocking receive at the evaluation-analysis communication level*

- void `irecv_ea` (int &recv\_int, int source, int tag, MPI\_Request &recv\_req)  
*nonblocking receive at the evaluation-analysis communication level*
- void `bcast_w` (int &data)  
*broadcast an integer across MPI\_COMM\_WORLD*
- void `bcast_i` (int &data)  
*broadcast an integer across an iterator communicator*
- void `bcast_i` (short &data)  
*broadcast a short integer across an iterator communicator*
- void `bcast_e` (int &data)  
*broadcast an integer across an evaluation communicator*
- void `bcast_a` (int &data)  
*broadcast an integer across an analysis communicator*
- void `bcast_si` (int &data)  
*broadcast an integer across a strategy-iterator intra communicator*
- void `bcast_w` (MPIPackBuffer &send\_buff)  
*broadcast a packed buffer across MPI\_COMM\_WORLD*
- void `bcast_i` (MPIPackBuffer &send\_buff)  
*broadcast a packed buffer across an iterator communicator*
- void `bcast_e` (MPIPackBuffer &send\_buff)  
*broadcast a packed buffer across an evaluation communicator*
- void `bcast_a` (MPIPackBuffer &send\_buff)  
*broadcast a packed buffer across an analysis communicator*
- void `bcast_si` (MPIPackBuffer &send\_buff)  
*broadcast a packed buffer across a strategy-iterator intra communicator*
- void `bcast_w` (MPIUnpackBuffer &recv\_buff)  
*matching receive for packed buffer broadcast across MPI\_COMM\_WORLD*
- void `bcast_i` (MPIUnpackBuffer &recv\_buff)  
*matching receive for packed buffer bcast across an iterator communicator*
- void `bcast_e` (MPIUnpackBuffer &recv\_buff)  
*matching receive for packed buffer bcast across an evaluation communicator*

- void `bcast_a` (`MPIUnpackBuffer` &recv\_buff)  
*matching receive for packed buffer bcast across an analysis communicator*
- void `bcast_si` (`MPIUnpackBuffer` &recv\_buff)  
*matching recv for packed buffer bcast across a strat-iterator intra comm*
- void `barrier_w` ()  
*enforce MPI\_Barrier on MPI\_COMM\_WORLD*
- void `barrier_i` ()  
*enforce MPI\_Barrier on an iterator communicator*
- void `barrier_e` ()  
*enforce MPI\_Barrier on an evaluation communicator*
- void `barrier_a` ()  
*enforce MPI\_Barrier on an analysis communicator*
- void `reduce_sum_ea` (double \*local\_vals, double \*sum\_vals, const int &num\_vals)  
*compute a sum over an eval-analysis intra-communicator using MPI\_Reduce*
- void `reduce_sum_a` (double \*local\_vals, double \*sum\_vals, const int &num\_vals)  
*compute a sum over an analysis communicator using MPI\_Reduce*
- void `test` (`MPI_Request` &request, int &test\_flag, `MPI_Status` &status)  
*test a nonblocking send/receive request for completion*
- void `wait` (`MPI_Request` &request, `MPI_Status` &status)  
*wait for a nonblocking send/receive request to complete*
- void `waitall` (const int &num\_recvs, `MPI_Request` \*&recv\_reqs)  
*wait for all messages from a series of nonblocking receives*
- void `waitsome` (const int &num\_sends, `MPI_Request` \*&recv\_requests, int &num\_recvs, int \*&index\_array, `MPI_Status` \*&status\_array)  
*but complete all that are available*
- void `free` (`MPI_Request` &request)  
*free an MPI\_Request*
- const int & `world_size` () const  
*return worldSize*
- const int & `world_rank` () const  
*return worldRank*

- bool `mpirun_flag ()` const  
*return mpirunFlag*
- bool `is_null ()` const  
*return dummyFlag*
- Real `parallel_time ()` const  
*returns current MPI wall clock time*
- void `parallel_configuration_iterator (const ParConfigLIter &pc_iter)`  
*set the current ParallelConfiguration node*
- const ParConfigLIter & `parallel_configuration_iterator ()` const  
*return the current ParallelConfiguration node*
- const ParallelConfiguration & `parallel_configuration ()` const  
*return the current ParallelConfiguration instance*
- size\_t `num_parallel_configurations ()` const  
*returns the number of entries in parallelConfigurations*
- bool `parallel_configuration_is_complete ()`  
*identifies if the current ParallelConfiguration has been fully populated*
- void `increment_parallel_configuration ()`  
*add a new node to parallelConfigurations and increment currPCIter*
- bool `w_parallel_level_defined ()` const  
*parallel level*
- bool `si_parallel_level_defined ()` const  
*strategy-iterator parallel level*
- bool `ie_parallel_level_defined ()` const  
*iterator-evaluation parallel level*
- bool `ea_parallel_level_defined ()` const  
*evaluation-analysis parallel level*
- `Array< MPI_Comm > analysis_intra_communicators ()`  
*prior to execution time).*

## Private Member Functions

- void `init_communicators` (const [ParallelLevel](#) &parent\_pl, const int &num\_servers, const int &procs\_per\_server, const int &max\_concurrency, const int &asynch\_local\_concurrency, const [String](#) &default\_config, const [String](#) &scheduling\_override)  
*split a parent communicator into child server communicators*
- void `free_communicators` ([ParallelLevel](#) &pl)  
*deallocate intra/inter communicators for a particular [ParallelLevel](#)*
- bool `split_communicator_dedicated_master` (const [ParallelLevel](#) &parent\_pl, [ParallelLevel](#) &child\_pl, const int &proc\_remainder)  
*and num\_servers child communicators*
- bool `split_communicator_peer_partition` (const [ParallelLevel](#) &parent\_pl, [ParallelLevel](#) &child\_pl, const int &proc\_remainder)  
*communicators (no dedicated master processor)*
- bool `resolve_inputs` (int &num\_servers, int &procs\_per\_server, const int &avail\_procs, int &proc\_remainder, const int &max\_concurrency, const int &capacity\_multiplier, const [String](#) &default\_config, const [String](#) &scheduling\_override, bool print\_rank)  
*resolve user inputs into a sensible partitioning scheme*
- void `send` ([MPIPackBuffer](#) &send\_buff, const int &dest, const int &tag, [ParallelLevel](#) &parent\_pl, [ParallelLevel](#) &child\_pl)  
*blocking buffer send at the current communication level*
- void `send` (int &send\_int, const int &dest, const int &tag, [ParallelLevel](#) &parent\_pl, [ParallelLevel](#) &child\_pl)  
*blocking integer send at the current communication level*
- void `isend` ([MPIPackBuffer](#) &send\_buff, const int &dest, const int &tag, [MPI\\_Request](#) &send\_req, [ParallelLevel](#) &parent\_pl, [ParallelLevel](#) &child\_pl)  
*nonblocking buffer send at the current communication level*
- void `isend` (int &send\_int, const int &dest, const int &tag, [MPI\\_Request](#) &send\_req, [ParallelLevel](#) &parent\_pl, [ParallelLevel](#) &child\_pl)  
*nonblocking integer send at the current communication level*
- void `recv` ([MPIUnpackBuffer](#) &recv\_buff, const int &source, const int &tag, [MPI\\_Status](#) &status, [ParallelLevel](#) &parent\_pl, [ParallelLevel](#) &child\_pl)  
*blocking buffer receive at the current communication level*
- void `recv` (int &recv\_int, const int &source, const int &tag, [MPI\\_Status](#) &status, [ParallelLevel](#) &parent\_pl, [ParallelLevel](#) &child\_pl)  
*blocking integer receive at the current communication level*

- void `irecv` (`MPIUnpackBuffer` &recv\_buff, const int &source, const int &tag, `MPI_Request` &recv\_req, `ParallelLevel` &parent\_pl, `ParallelLevel` &child\_pl)  
*nonblocking buffer receive at the current communication level*
- void `irecv` (int &recv\_int, const int &source, const int &tag, `MPI_Request` &recv\_req, `ParallelLevel` &parent\_pl, `ParallelLevel` &child\_pl)  
*nonblocking integer receive at the current communication level*
- void `bcast` (int &data, const `MPI_Comm` &comm)  
*broadcast an integer across a communicator*
- void `bcast` (short &data, const `MPI_Comm` &comm)  
*broadcast a short integer across a communicator*
- void `bcast` (`MPIPackBuffer` &send\_buff, const `MPI_Comm` &comm)  
*send a packed buffer across a communicator using a broadcast*
- void `bcast` (`MPIUnpackBuffer` &recv\_buff, const `MPI_Comm` &comm)  
*matching receive for a packed buffer broadcast*
- void `barrier` (const `MPI_Comm` &comm)  
*enforce MPI\_Barrier on comm*
- void `reduce_sum` (double \*local\_vals, double \*sum\_vals, const int &num\_vals, const `MPI_Comm` &comm)  
*compute a sum over comm using MPI\_Reduce*
- void `check_error` (const `String` &err\_source, const int &err\_code)  
*check the MPI return code and abort if error*

## Private Attributes

- ofstream `output_ofstream`  
*tagged file redirection of stdout*
- ofstream `error_ofstream`  
*tagged file redirection of stderr*
- int `worldRank`  
*rank in MPI\_COMM\_WORLD*
- int `worldSize`  
*size of MPI\_COMM\_WORLD*
- bool `mpirunFlag`

*flag for a parallel mpirun/yod launch*

- bool [ownMPIFlag](#)  
*flag for ownership of MPI\_Init/MPI\_Finalize*
- bool [dummyFlag](#)  
*prevents multiple MPI\_Finalize calls due to dummy\_lib*
- bool [stdOutputFlag](#)  
*flags redirection of DAKOTA std output to a file*
- bool [stdErrorFlag](#)  
*flags redirection of DAKOTA std error to a file*
- Real [startCPUTime](#)  
*start reference for UTILIB CPU timer*
- Real [startWCTime](#)  
*start reference for UTILIB wall clock timer*
- Real [startMPITime](#)  
*start reference for MPI wall clock timer*
- long [startClock](#)  
*start reference for local clock() timer measuring parent+child CPU*
- const char \* [stdOutputFilename](#)  
*filename for redirection of stdout*
- const char \* [stdErrorFilename](#)  
*filename for redirection of stderr*
- const char \* [readRestartFilename](#)  
*input filename for restart*
- const char \* [writeRestartFilename](#)  
*output filename for restart*
- int [restartEvals](#)  
*number of restart evals to read*
- [List< ParallelLevel > parallelLevels](#)  
*parallelism among one or more configurations*
- [List< ParallelConfiguration > parallelConfigurations](#)  
*indexing into parallelLevels*

- `ParLevLIter` `currPLIter`  
*list iterator identifying the current node in parallelLevels*
- `ParConfigLIter` `currPCIter`  
*list iterator identifying the current node in parallelConfigurations*

### 8.94.1 Detailed Description

message passing within these levels.

The `ParallelLibrary` class encapsulates all of the details of performing message passing within multiple levels of parallelism. It provides functions for partitioning of levels according to user configuration input and functions for passing messages within and across MPI communicators for each of the parallelism levels. If support for other message-passing libraries beyond MPI becomes needed (PVM, ...), then `ParallelLibrary` would be promoted to a base class with virtual functions to encapsulate the library-specific syntax.

### 8.94.2 Constructor & Destructor Documentation

#### 8.94.2.1 `ParallelLibrary` (`int & argc`, `char **& argv`)

stand-alone mode constructor

This constructor is the one used by `main.C`. It calls `MPI_Init` conditionally based on whether a parallel launch is detected.

#### 8.94.2.2 `ParallelLibrary` ()

library mode constructor

This constructor provides a library mode and is used by the SIERRA Adak application. It does not call `MPI_Init`, but rather gathers data from `MPI_COMM_WORLD` if `MPI_Init` has been called elsewhere.

#### 8.94.2.3 `ParallelLibrary` (`int dummy`)

dummy constructor (used for `dummy_lib`)

This constructor is used for creation of the global `dummy_lib` object, which is used to satisfy initialization requirements when the real `ParallelLibrary` object is not available.

### 8.94.3 Member Function Documentation



**8.94.3.1 void specify\_outputs\_restart (CommandLineHandler & cmd\_line\_handler)**

inputs (normal mode)

Get the -output, -error, -read\_restart, and -write\_restart filenames and the -stop\_restart limit from the command line. Defaults for the filenames from the command line handler are NULL for the filenames and 0 for restart\_evals if no user specification. Only worldRank==0 has access to command line arguments and must Bcast this data to all iterator masters.

**8.94.3.2 void manage\_outputs\_restart (const ParallelLevel & pl)**

manage output streams and restart file(s) (both modes)

If the user has specified the use of files for DAKOTA standard output and/or standard error, then bind these filenames to the Cout/Cerr macros. In addition, if concurrent iterators are to be used, create and tag multiple output streams in order to prevent jumbled output. Manage restart file(s) by processing any incoming evaluations from an old restart file and by setting up the binary output stream for new evaluations. Only master iterator processor(s) read & write restart information. This function must follow init\_iterator\_communicators so that restart can be managed properly for concurrent iterator strategies. In the case of concurrent iterators, each iterator has its own restart file tagged with iterator number.

**8.94.3.3 void close\_streams ()**

close streams, files, and any other services

Close streams associated with manage\_outputs and manage\_restart and terminate any additional services that may be active.

**8.94.3.4 void increment\_parallel\_configuration () [inline]**

add a new node to parallelConfigurations and increment currPCIter

Called from the ParallelLibrary ctor and from Model::init\_communicators(). An increment is performed for each Model initialization except the first (which inherits the world and strategy-iterator parallel levels from the first partial configuration).

**8.94.3.5 void init\_communicators (const ParallelLevel & parent\_pl, const int & num\_servers, const int & procs\_per\_server, const int & max\_concurrency, const int & asynch\_local\_concurrency, const String & default\_config, const String & scheduling\_override) [private]**

split a parent communicator into child server communicators

Split parent communicator into concurrent child server partitions as specified by the passed parameters. This constructs new child intra-communicators and parent-child inter-communicators. This function is called from the Strategy constructor for the concurrent iterator level and from ApplicationInterface::init\_communicators() for the concurrent evaluation and concurrent analysis levels.

**8.94.3.6** `bool resolve_inputs (int & num_servers, int & procs_per_server, const int & avail_procs, int & proc_remainder, const int & max_concurrency, const int & capacity_multiplier, const String & default_config, const String & scheduling_override, bool print_rank) [private]`

resolve user inputs into a sensible partitioning scheme

This function is responsible for the "auto-configure" intelligence of DAKOTA. It resolves a variety of inputs and overrides into a sensible partitioning configuration for a particular parallelism level. It also handles the general case in which a user's specification request does not divide out evenly with the number of available processors for the level. If `num_servers` & `procs_per_server` are both nondefault, then the former takes precedence.

The documentation for this class was generated from the following files:

- `ParallelLibrary.H`
- `ParallelLibrary.C`

## 8.95 ParamResponsePair Class Reference

evaluation id.

### Public Member Functions

- [ParamResponsePair](#) ()  
*default constructor*
- [ParamResponsePair](#) (const [Variables](#) &vars, const [String](#) &interface\_id, const [Response](#) &response, bool deep\_copy=false)  
*alternate constructor for temporaries*
- [ParamResponsePair](#) (const [Variables](#) &vars, const [String](#) &interface\_id, const [Response](#) &response, const int eval\_id, bool deep\_copy=true)  
*standard constructor for history uses*
- [ParamResponsePair](#) (const [ParamResponsePair](#) &pair)  
*copy constructor*
- [~ParamResponsePair](#) ()  
*destructor*
- [ParamResponsePair](#) & operator= (const [ParamResponsePair](#) &pair)  
*assignment operator*
- void [read](#) (istream &s)  
*read a [ParamResponsePair](#) object from an istream*
- void [write](#) (ostream &s) const  
*write a [ParamResponsePair](#) object to an ostream*
- void [read\\_annotated](#) (istream &s)  
*read a [ParamResponsePair](#) object in annotated format from an istream*
- void [write\\_annotated](#) (ostream &s) const  
*write a [ParamResponsePair](#) object in annotated format to an ostream*
- void [write\\_tabular](#) (ostream &s) const  
*write a [ParamResponsePair](#) object in tabular format to an ostream*
- void [read](#) ([BiStream](#) &s)

read a *ParamResponsePair* object from the binary restart stream

- void `write (BoStream &s)` const  
write a *ParamResponsePair* object to the binary restart stream
- void `read (MPIUnpackBuffer &s)`  
read a *ParamResponsePair* object from a packed MPI buffer
- void `write (MPIPackBuffer &s)` const  
write a *ParamResponsePair* object to a packed MPI buffer
- int `eval_id ()` const  
return the evaluation identifier
- const `Variables & prp_parameters ()` const  
return the parameters object
- const `Response & prp_response ()` const  
return the response object
- void `prp_response (const Response &response)`  
set the response object
- const `ActiveSet & active_set ()` const  
return the active set object from the response object
- void `active_set (const ActiveSet &set)`  
set the active set object within the response object
- const `String & interface_id ()` const  
return the interface identifier from the response object

## Private Attributes

- `Variables prPairParameters`  
the set of parameters for the function evaluation
- `Response prPairResponse`  
the response set for the function evaluation
- `String idInterface`  
detection on results from different interfaces.
- int `evalId`  
*ApplicationInterface::fnEvalId*).

## Friends

- `bool operator==(const ParamResponsePair &pair1, const ParamResponsePair &pair2)`  
*equality operator*
- `bool operator!=(const ParamResponsePair &pair1, const ParamResponsePair &pair2)`  
*inequality operator*

### 8.95.1 Detailed Description

evaluation id.

`ParamResponsePair` provides a container class for association of the input for a particular function evaluation (a variables object) with the output from this function evaluation (a response object), along with an evaluation identifier. This container defines the basic unit used in the `data_pairs` list, in restart file operations, and in a variety of scheduling algorithm bookkeeping operations. With the advent of STL, replacement of arrays of this class with `map<>` and `pair<>` template constructs may be possible (using `map<int, pair<vars,response> >`, for example), assuming that deep copies, I/O, alternate constructors, etc., can be adequately addressed.

### 8.95.2 Constructor & Destructor Documentation

#### 8.95.2.1 `ParamResponsePair` (const Variables & vars, const String & interface\_id, const Response & response, bool deep\_copy = false) [inline]

alternate constructor for temporaries

Uses of this constructor often employ the standard `Variables` and `Response` copy constructors to share representations since this constructor is commonly used for `search_pairs` (which are local instantiations that go out of scope prior to any changes to values; i.e., they are not used for history).

#### 8.95.2.2 `ParamResponsePair` (const Variables & vars, const String & interface\_id, const Response & response, const int eval\_id, bool deep\_copy = true) [inline]

standard constructor for history uses

Uses of this constructor often do not share representations since deep copies are used when history mechanisms (e.g., `beforeSynchCorePRPList`, `data_pairs`) are involved.

### 8.95.3 Member Function Documentation

### 8.95.3.1 void read ([MPIUnpackBuffer](#) & s) [inline]

read a [ParamResponsePair](#) object from a packed MPI buffer

idInterface is omitted since master processor retains interface ids and communicates asv and response data only with slaves.

### 8.95.3.2 void write ([MPIPackBuffer](#) & s) const [inline]

write a [ParamResponsePair](#) object to a packed MPI buffer

idInterface is omitted since master processor retains interface ids and communicates asv and response data only with slaves.

## 8.95.4 Member Data Documentation

### 8.95.4.1 String idInterface [private]

detection on results from different interfaces.

idInterface belongs here rather than in [Response](#) since some [Response](#) objects involve consolidation of several fn evals (e.g., [Model::synchronize\\_derivatives\(\)](#)) that are not, in total, generated by a single interface. The prPair, on the other hand, is used for storage of all low level fn evals that get evaluated in [ApplicationInterface::map\(\)](#).

### 8.95.4.2 int evalId [private]

[ApplicationInterface::fnEvalId](#)).

evalId belongs here rather than in [Response](#) since some [Response](#) objects involve consolidation of several fn evals (e.g., [Model::synchronize\\_derivatives\(\)](#)). The prPair, on the other hand, is used for storage of all low level fn evals that get evaluated in [ApplicationInterface::map\(\)](#).

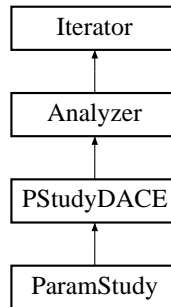
The documentation for this class was generated from the following files:

- [ParamResponsePair.H](#)
- [ParamResponsePair.C](#)

## 8.96 ParamStudy Class Reference

Class for vector, list, centered, and multidimensional parameter studies.

Inheritance diagram for ParamStudy::



### Public Member Functions

- [ParamStudy \(Model &model\)](#)  
*constructor*
- [~ParamStudy \(\)](#)  
*destructor*
- void [extract\\_trends \(\)](#)  
*Redefines the run\_iterator virtual function for the PStudy/DACE branch.*

### Private Member Functions

- void [compute\\_vector\\_steps \(\)](#)  
*and either numSteps or stepLength (pStudyType is 1 or 2)*
- void [sample \(const RealVectorArray &list\\_of\\_points\)](#)  
*performs the parameter study by sampling from a list of points*
- void [vector\\_loop \(const RealVector &start, const RealVector &step\\_vect, const int &num\\_steps\)](#)  
*increments of step\_vect. Total number of evaluations is num\_steps + 1.*
- void [centered\\_loop \(const RealVector &start, const Real &percent\\_delta, const int &deltas\\_per\\_variable\)](#)  
*centered about start*

- void `multidim_loop` (const `IntArray` &var\_partitions)  
*performs vector\_loops recursively in multiple dimensions*

## Private Attributes

- `RealVectorArray` `listOfPoints`  
*array of evaluation points for the list\_parameter\_study*
- `RealVector` `initialPoint`  
*the starting point for vector and centered parameter studies*
- `RealVector` `finalPoint`  
*the ending point for vector\_parameter\_study (a specification option)*
- `RealVector` `stepVector`  
*the n-dimensional increment in vector\_parameter\_study*
- int `numSteps`  
*the number of times stepVector is applied in vector\_parameter\_study*
- short `pStudyType`  
*(different vector specifications), 4 (centered), or 5 (multidim)*
- int `deltasPerVariable`  
*variable in a centered\_parameter\_study*
- Real `stepLength`  
*(a specification option)*
- Real `percentDelta`  
*centered\_parameter\_study*
- `IntArray` `variablePartitions`  
*number of partitions for each variable in a multidim\_parameter\_study*

### 8.96.1 Detailed Description

Class for vector, list, centered, and multidimensional parameter studies.

The `ParamStudy` class contains several algorithms for performing parameter studies of different types. It is not a wrapper for an external library, rather its algorithms are self-contained. The vector parameter study steps along an n-dimensional vector from an arbitrary initial point to an arbitrary final point in a specified number of steps. The centered parameter study performs a number of plus and minus offsets in each coordinate direction around a center point. A multidimensional parameter study fills an n-dimensional hypercube based on a specified number



of intervals for each dimension. It is a nested study in that it utilizes the vector parameter study internally as it recurses through the variables. And the list parameter study provides for a user specification of a list of points to evaluate, which allows general parameter investigations not fitting the structure of vector, centered, or multidim parameter studies.

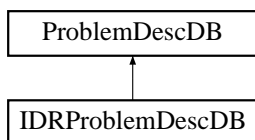
The documentation for this class was generated from the following files:

- ParamStudy.H
- ParamStudy.C

## 8.97 ProblemDescDB Class Reference

The database containing information parsed from the DAKOTA input file.

Inheritance diagram for ProblemDescDB::



### Public Member Functions

- [ProblemDescDB](#) ()  
*default constructor*
- [ProblemDescDB](#) ([ParallelLibrary](#) &parallel\_lib)  
*standard constructor*
- [ProblemDescDB](#) (const [ProblemDescDB](#) &db)  
*copy constructor*
- [~ProblemDescDB](#) ()  
*destructor*
- [ProblemDescDB](#) operator= (const [ProblemDescDB](#) &db)  
*assignment operator*
- void [manage\\_inputs](#) ([CommandLineHandler](#) &cmd\_line\_handler)  
*passed with the "-input" option on the DAKOTA command line.*
- void [manage\\_inputs](#) (const char \*dakota\_input\_file)  
*This version reads from the dakota input filename passed in.*
- void [check\\_input](#) ()  
*keywords in the dakota input file. Used by [manage\\_inputs](#)().*
- void [lock](#) ()  
*may not be set properly. Unlocked by a set nodes operation.*
- void [set\\_db\\_list\\_nodes](#) (const [String](#) &method\_tag)  
*this method specification to set all other list iterators.*

- void `set_db_list_nodes` (const `size_t` &`method_index`)  
*specification to set all other list iterators.*
- void `set_db_method_node` (const `size_t` &`method_index`)  
*particular method specification (only).*
- `size_t` `get_db_method_node` ()  
*return the index of the active node in `dataMethodList`*
- void `set_db_model_nodes` (const `String` &`model_tag`)  
*identifier string*
- void `set_db_model_nodes` (const `size_t` &`model_index`)  
*within `dataModelList`*
- `size_t` `get_db_model_node` ()  
*return the index of the active node in `dataModelList`*
- void `set_db_variables_node` (const `String` &`variables_tag`)  
*set `dataVariablesIter` based on the variables identifier string*
- void `set_db_interface_node` (const `String` &`interface_tag`)  
*set `dataInterfaceIter` based on the interface identifier string*
- void `set_db_responses_node` (const `String` &`responses_tag`)  
*set `dataResponsesIter` based on the responses identifier string*
- `ParallelLibrary` & `parallel_library` () const  
*return the `parallelLib` reference*
- `IteratorList` & `iterator_list` ()  
*return a list of all `Iterator` objects that have been instantiated*
- `ModelList` & `model_list` ()  
*return a list of all `Model` objects that have been instantiated*
- `VariablesList` & `variables_list` ()  
*return a list of all `Variables` objects that have been instantiated*
- `InterfaceList` & `interface_list` ()  
*return a list of all `Interface` objects that have been instantiated*
- `ResponseList` & `response_list` ()  
*return a list of all `Response` objects that have been instantiated*

- const [Iterator](#) & [get\\_iterator](#) ([Model](#) &model)  
*retrieve an existing [Iterator](#), if it exists, or instantiate a new one*
- const [Model](#) & [get\\_model](#) ()  
*retrieve an existing [Model](#), if it exists, or instantiate a new one*
- const [Variables](#) & [get\\_variables](#) ()  
*retrieve an existing [Variables](#), if it exists, or instantiate a new one*
- const [Interface](#) & [get\\_interface](#) ()  
*retrieve an existing [Interface](#), if it exists, or instantiate a new one*
- const [Response](#) & [get\\_response](#) (const [Variables](#) &vars)  
*retrieve an existing [Response](#), if it exists, or instantiate a new one*
- const [RealVector](#) & [get\\_drv](#) (const [String](#) &entry\_name) const  
*get a [RealVector](#) out of the database based on an identifier string*
- const [IntVector](#) & [get\\_div](#) (const [String](#) &entry\_name) const  
*get an [IntVector](#) out of the database based on an identifier string*
- const [IntArray](#) & [get\\_dia](#) (const [String](#) &entry\_name) const  
*get an [IntArray](#) out of the database based on an identifier string*
- const [ShortArray](#) & [get\\_dsha](#) (const [String](#) &entry\_name) const  
*get an [ShortArray](#) out of the database based on an identifier string*
- const [RealMatrix](#) & [get\\_drm](#) (const [String](#) &entry\_name) const  
*get a [RealMatrix](#) out of the database based on an identifier string*
- const [RealVectorArray](#) & [get\\_drva](#) (const [String](#) &entry\_name) const  
*get a [RealVectorArray](#) out of the database based on an identifier string*
- const [IntList](#) & [get\\_dil](#) (const [String](#) &entry\_name) const  
*get an [IntList](#) out of the database based on an identifier string*
- const [IntSet](#) & [get\\_dis](#) (const [String](#) &entry\_name) const  
*get an [IntSet](#) out of the database based on an identifier string*
- const [StringArray](#) & [get\\_dsa](#) (const [String](#) &entry\_name) const  
*get a [StringArray](#) out of the database based on an identifier string*
- const [String2DArray](#) & [get\\_ds2a](#) (const [String](#) &entry\_name) const  
*get a [String2DArray](#) out of the database based on an identifier string*
- const [String](#) & [get\\_string](#) (const [String](#) &entry\_name) const

get a *String* out of the database based on an identifier string

- const Real & [get\\_real](#) (const [String](#) &entry\_name) const  
get a *Real* out of the database based on an identifier string
- const int & [get\\_int](#) (const [String](#) &entry\_name) const  
get an *int* out of the database based on an identifier string
- const short & [get\\_short](#) (const [String](#) &entry\_name) const  
get a *short int* out of the database based on an identifier string
- const size\_t & [get\\_sizet](#) (const [String](#) &entry\_name) const  
get a *size\_t* out of the database based on an identifier string
- const bool & [get\\_bool](#) (const [String](#) &entry\_name) const  
get a *bool* out of the database based on an identifier string
- void [insert\\_node](#) (const [DataStrategy](#) &data\_strategy)  
set the *DataStrategy* object
- void [insert\\_node](#) (const [DataMethod](#) &data\_method)  
add a *DataMethod* object to the *dataMethodList*
- void [insert\\_node](#) (const [DataModel](#) &data\_model)  
add a *DataModel* object to the *dataModelList*
- void [insert\\_node](#) (const [DataVariables](#) &data\_variables)  
add a *DataVariables* object to the *dataVariablesList*
- void [insert\\_node](#) (const [DataInterface](#) &data\_interface)  
add a *DataInterface* object to the *dataInterfaceList*
- void [insert\\_node](#) (const [DataResponses](#) &data\_responses)  
add a *DataResponses* object to the *dataResponsesList*
- bool [is\\_null](#) () const  
function to check *dbRep* (does this envelope contain a letter)

## Protected Member Functions

- [ProblemDescDB](#) ([BaseConstructor](#), [ParallelLibrary](#) &parallel\_lib)  
derived class constructors - Coplien, p. 139)
- virtual void [derived\\_manage\\_inputs](#) (const char \*dakota\_input\_file)  
This version reads from the *dakota* input filename passed in.

## Protected Attributes

- [DataStrategy](#) `strategySpec`  
*to `strategy_kwhandler()` or `insert_node()`*
- [List](#)< [DataMethod](#) > `dataMethodList`  
*or `insert_node()`*
- [List](#)< [DataModel](#) > `dataModelList`  
*or `insert_node()`*
- [List](#)< [DataVariables](#) > `dataVariablesList`  
*`variables_kwhandler()` or `insert_node()`*
- [List](#)< [DataInterface](#) > `dataInterfaceList`  
*`interface_kwhandler()` or `insert_node()`*
- [List](#)< [DataResponses](#) > `dataResponsesList`  
*`responses_kwhandler()` or `insert_node()`*
- `size_t` `strategyCntr`  
*counter for strategy specifications used in `check_input`*

## Private Member Functions

- [ProblemDescDB](#) \* `get_db` ([ParallelLibrary](#) &parallel\_lib)  
*correct letter class*
- `void` `send_db_buffer` ()  
*and `dataResponsesList`. Used by `manage_inputs()`.*
- `void` `receive_db_buffer` ()  
*and `dataResponsesList`. Used by `manage_inputs()`.*

## Private Attributes

- [ParallelLibrary](#) & `parallelLib`  
*reference to the `parallel_lib` object passed from main*
- [List](#)< [DataMethod](#) >::iterator `dataMethodIter`  
*iterator identifying the active list node in `dataMethodList`*
- [List](#)< [DataModel](#) >::iterator `dataModelIter`

*iterator identifying the active list node in dataModelList*

- [List< DataVariables >::iterator dataVariablesIter](#)  
*iterator identifying the active list node in dataVariablesList*
- [List< DataInterface >::iterator dataInterfaceIter](#)  
*iterator identifying the active list node in dataInterfaceList*
- [List< DataResponses >::iterator dataResponsesIter](#)  
*iterator identifying the active list node in dataResponsesList*
- [IteratorList iteratorList](#)  
*list of iterator objects, one for each method specification*
- [ModelList modelList](#)  
*list of model objects, one for each model specification*
- [VariablesList variablesList](#)  
*list of variables objects, one for each variables specification*
- [InterfaceList interfaceList](#)  
*list of interface objects, one for each interface specification*
- [ResponseList responseList](#)  
*list of response objects, one for each responses specification*
- [bool dbLocked](#)  
*set\_db\_list\_nodes invocation*
- [ProblemDescDB \\* dbRep](#)  
*pointer to the letter (initialized only for the envelope)*
- [int referenceCount](#)  
*number of objects sharing dbRep*

### 8.97.1 Detailed Description

The database containing information parsed from the DAKOTA input file.

The [ProblemDescDB](#) class is a database for DAKOTA input file data that is populated by a parser defined in a derived class. When the parser reads a complete keyword (delimited by a newline), it populates a data class object ([DataStrategy](#), [DataMethod](#), [DataVariables](#), [DataInterface](#), or [DataResponses](#)) and, for all cases except strategy, appends the object to a linked list ([dataMethodList](#), [dataVariablesList](#), [dataInterfaceList](#), or [dataResponsesList](#)). No strategy linked list is used since only one strategy specification is allowed.

## 8.97.2 Constructor & Destructor Documentation

### 8.97.2.1 [ProblemDescDB](#) ()

default constructor

The default constructor: dbRep is NULL in this case. This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

### 8.97.2.2 [ProblemDescDB](#) ([ParallelLibrary](#) & *parallel\_lib*)

standard constructor

This is the primary envelope constructor which uses problem\_db to build a fully populated db object. It only needs to extract enough data to properly execute get\_db(problem\_db), since the constructor overloaded with [BaseConstructor](#) builds the actual base class data inherited by the derived classes.

### 8.97.2.3 [ProblemDescDB](#) (const [ProblemDescDB](#) & *db*)

copy constructor

Copy constructor manages sharing of dbRep and incrementing of referenceCount.

### 8.97.2.4 [~ProblemDescDB](#) ()

destructor

Destructor decrements referenceCount and only deletes dbRep when referenceCount reaches zero.

### 8.97.2.5 [ProblemDescDB](#) ([BaseConstructor](#), [ParallelLibrary](#) & *parallel\_lib*) [protected]

derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. [get\\_db\(\)](#) instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling [get\\_db\(\)](#) again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in [~ProblemDescDB](#)).

## 8.97.3 Member Function Documentation

### 8.97.3.1 [ProblemDescDB](#) operator= (const [ProblemDescDB](#) & *db*)

assignment operator



Assignment operator decrements referenceCount for old dbRep, assigns new dbRep, and increments referenceCount for new dbRep.

#### 8.97.3.2 void manage\_inputs (CommandLineHandler & cmd\_line\_handler)

passed with the "-input" option on the DAKOTA command line.

Manage command line inputs using the [CommandLineHandler](#) class and parse the input file.

#### 8.97.3.3 void manage\_inputs (const char \* dakota\_input\_file)

This version reads from the dakota input filename passed in.

Parse the input file.

#### 8.97.3.4 ProblemDescDB \* get\_db (ParallelLibrary & parallel\_lib) [private]

correct letter class

Initializes dbRep to the appropriate derived type. The standard derived class constructors are invoked.

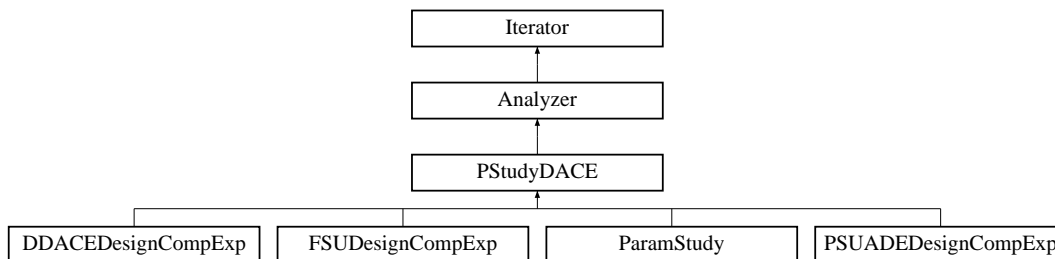
The documentation for this class was generated from the following files:

- ProblemDescDB.H
- ProblemDescDB.C

## 8.98 PStudyDACE Class Reference

design of experiments methods.

Inheritance diagram for PStudyDACE::



### Protected Member Functions

- [PStudyDACE \(Model &model\)](#)  
*constructor*
- [PStudyDACE \(NoDBBaseConstructor, Model &model\)](#)  
*alternate constructor for instantiations "on the fly"*
- [~PStudyDACE \(\)](#)  
*destructor*
- void [run \(\)](#)  
*run the iterator; portion of [run\\_iterator\(\)](#)*
- const [Variables & variables\\_results \(\)](#) const  
*return a single final iterator solution (variables)*
- const [Response & response\\_results \(\)](#) const  
*return a single final iterator solution (response)*
- void [response\\_results\\_active\\_set \(const ActiveSet &set\)](#)  
*set the requested data for the final iterator response results*
- void [print\\_results \(ostream &s\)](#) const  
*print the final iterator results*
- virtual void [extract\\_trends \(\)=0](#)

*Redefines the `run_iterator` virtual function for the PStudy/DACE branch.*

- void `update_best` (const `RealVector` &vars, const `Response` &response, const int eval\_num)  
*compares current evaluation to best evaluation and updates best*

## Protected Attributes

- `Variables bestVariables`  
*best variables found during the study*
- `Response bestResponses`  
*best responses found during the study*
- Real `bestObjFn`  
*best objective function found during the study*
- Real `bestConViol`  
*precedence over objective function reduction.*
- size\_t `numObjFns`  
*number of objective functions*
- size\_t `numLSqTerms`  
*number of least squares terms*
- `RealVector multiObjWts`  
*vector of multiobjective weights*

### 8.98.1 Detailed Description

design of experiments methods.

The `PStudyDACE` base class manages common data and functions, such as those involving the best solutions located during the parameter set evaluations or the printing of final results.

### 8.98.2 Member Function Documentation

#### 8.98.2.1 void `run` () [`inline`, `protected`, `virtual`]

run the iterator; portion of `run_iterator()`

[Iterator](#) supports a construct/pre-run/run/post-run/destroy progression. This function is the virtual run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented from [Iterator](#).

#### 8.98.2.2 void print\_results (ostream & s) const [protected, virtual]

print the final iterator results

This virtual function provides additional iterator-specific final results outputs beyond the function evaluation summary printed in [post\\_run\(\)](#).

Reimplemented from [Iterator](#).

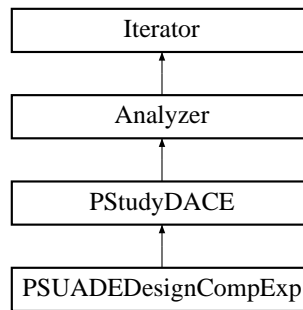
The documentation for this class was generated from the following files:

- DakotaPStudyDACE.H
- DakotaPStudyDACE.C

## 8.99 PSUADEDDesignCompExp Class Reference

Wrapper class for the PSUADE library.

Inheritance diagram for PSUADEDDesignCompExp::



### Public Member Functions

- [PSUADEDDesignCompExp \(Model &model\)](#)  
*primary constructor for building a standard DACE iterator*
- [~PSUADEDDesignCompExp \(\)](#)  
*destructor*
- void [extract\\_trends \(\)](#)  
*Redefines the run\_iterator virtual function for the PStudy/DACE branch.*
- void [sampling\\_reset](#) (int min\_samples, bool all\_data\_flag, bool stats\_flag)  
*reset sampling iterator*
- const [String & sampling\\_scheme \(\)](#) const  
*return sampling name*
- void [vary\\_pattern](#) (bool pattern\_flag)  
*sets varyPattern in derived classes that support it*
- void [get\\_parameter\\_sets](#) (const [Model](#) &model)  
*Returns one block of samples (ndim \* num\_samples).*

## Private Member Functions

- void `enforce_input_rules` ()  
*enforce sanity checks/modifications for the user input specification*

## Private Attributes

- int `samplesSpec`  
*initial specification of number of samples*
- int `numSamples`  
*current number of samples to be evaluated*
- const `IntArray` & `varPartitionsSpec`  
*number of partitions in each variable direction*
- int `numPartitions`  
*number of partitions to pass to PSUADE (levels = partitions + 1)*
- bool `allDataFlag`  
*`Iterator::all_variables()` and `Iterator::all_responses()`.*
- size\_t `numDACERuns`  
*counter for number of `run()` executions for this object*
- bool `varyPattern`  
*but are still repeatable*
- int `originalSeed`  
*(allows repeatable results)*
- int `randomSeed`  
*current seed for the random number generator*

### 8.99.1 Detailed Description

Wrapper class for the PSUADE library.

The `PSUADEDesignCompExp` class provides a wrapper for PSUADE, a C++ design of experiments library from Lawrence Livermore National Laboratory. Currently this class only includes the PSUADE Morris One-at-a-time (MOAT) method to uniformly sample the parameter space spanned by the active bounds of the current `Model`. It returns all generated samples and their corresponding responses as well as the best sample found.

## 8.99.2 Constructor & Destructor Documentation

### 8.99.2.1 PSUADEDesignCompExp (Model & model)

primary constructor for building a standard DACE iterator

This constructor is called for a standard iterator built with data from probDescDB.

## 8.99.3 Member Function Documentation

### 8.99.3.1 void enforce\_input\_rules() [private]

enforce sanity checks/modifications for the user input specification

Users may input a variety of quantities, but this function must enforce any restrictions imposed by the sampling algorithms.

The documentation for this class was generated from the following files:

- PSUADEDesignCompExp.H
- PSUADEDesignCompExp.C

## 8.100 RecastBaseConstructor Struct Reference

instantiations.

### Public Member Functions

- [RecastBaseConstructor](#) (int=0)  
*C++ structs can have constructors.*

### 8.100.1 Detailed Description

instantiations.

[RecastBaseConstructor](#) is used to overload the constructor used for on-the-fly [Model](#) instantiations. Putting this struct here avoids circular dependencies.

The documentation for this struct was generated from the following file:

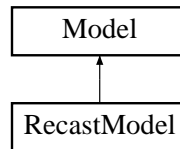
- `global_defs.h`



## 8.101 RecastModel Class Reference

in order to recast the form of its inputs and/or outputs.

Inheritance diagram for RecastModel::



### Public Member Functions

- **RecastModel** (**Model** &sub\_model, const **Sizet2DArray** &vars\_map\_indices, bool nonlinear\_vars\_mapping, void(\*variables\_map)(const **Variables** &recast\_vars, **Variables** &sub\_model\_vars), void(\*asv\_map)(const **ShortArray** &recast\_asv, **ShortArray** &sub\_model\_asv), const **Sizet2DArray** &primary\_resp\_map\_indices, const **Sizet2DArray** &secondary\_resp\_map\_indices, const size\_t &recast\_secondary\_offset, const **BoolDequeArray** &nonlinear\_resp\_mapping, void(\*primary\_resp\_map)(const **Variables** &sub\_model\_vars, const **Variables** &recast\_vars, const **Response** &sub\_model\_response, **Response** &recast\_response), void(\*secondary\_resp\_map)(const **Variables** &sub\_model\_vars, const **Variables** &recast\_vars, const **Response** &sub\_model\_response, **Response** &recast\_response))

*standard constructor*

- **RecastModel** (**Model** &sub\_model, const size\_t &num\_recast\_primary\_fns, const size\_t &num\_recast\_secondary\_fns, const size\_t &recast\_secondary\_offset)

*alternate constructor*

- **~RecastModel** ()

*destructor*

- void **initialize** (const **Sizet2DArray** &vars\_map\_indices, bool nonlinear\_vars\_mapping, void(\*variables\_map)(const **Variables** &recast\_vars, **Variables** &sub\_model\_vars), void(\*asv\_map)(const **ShortArray** &recast\_asv, **ShortArray** &sub\_model\_asv), const **Sizet2DArray** &primary\_resp\_map\_indices, const **Sizet2DArray** &secondary\_resp\_map\_indices, const **BoolDequeArray** &nonlinear\_resp\_mapping, void(\*primary\_resp\_map)(const **Variables** &sub\_model\_vars, const **Variables** &recast\_vars, const **Response** &sub\_model\_response, **Response** &recast\_response), void(\*secondary\_resp\_map)(const **Variables** &sub\_model\_vars, const **Variables** &recast\_vars, const **Response** &sub\_model\_response, **Response** &recast\_response))

*completes initialization of the RecastModel after alternate construction*

- void **submodel\_supports\_estimated\_derivatives** (bool ssed\_flag)

*override the submodel's derivative estimation behavior*

## Protected Member Functions

- void `derived_compute_response` (const `ActiveSet` &set)  
*(forward to subModel.compute\_response())*
- void `derived_asynch_compute_response` (const `ActiveSet` &set)  
*(forward to subModel.asynch\_compute\_response())*
- const `ResponseArray` & `derived_synchronize` ()  
*(forward to subModel.synchronize())*
- const `IntResponseMap` & `derived_synchronize_nowait` ()  
*(forward to subModel.synchronize\_nowait())*
- void `derived_subordinate_models` (`ModelList` &ml, bool recurse\_flag)  
*add subModel to list and recurse into subModel*
- void `update_from_subordinate_model` (bool recurse\_flag=true)  
*pass request to subModel if recursing and then update from it*
- `Interface` & `interface` ()  
*return subModel interface*
- void `surrogate_function_indices` (const `IntSet` &surr\_fn\_indices)  
*forward to subModel*
- void `surrogate_bypass` (bool bypass\_flag)  
*models contained within this model*
- void `build_approximation` ()  
*builds the subModel approximation*
- bool `build_approximation` (const `Variables` &vars, const `Response` &response)  
*builds the subModel approximation*
- void `update_approximation` (const `Variables` &vars, const `Response` &response, bool rebuild\_flag)  
*updates the subModel approximation*
- void `update_approximation` (const `VariablesArray` &vars\_array, const `ResponseArray` &resp\_array, bool rebuild\_flag)  
*updates the subModel approximation*
- void `append_approximation` (const `Variables` &vars, const `Response` &response, bool rebuild\_flag)  
*appends the subModel approximation*
- void `append_approximation` (const `VariablesArray` &vars\_array, const `ResponseArray` &resp\_array, bool rebuild\_flag)

*appends the subModel approximation*

- [Array< Approximation >](#) & [approximations](#) ()  
*retrieve the set of Approximations from the subModel*
- const [RealVectorArray](#) & [approximation\\_coefficients](#) ()  
*retrieve the approximation coefficients from the subModel*
- void [approximation\\_coefficients](#) (const [RealVectorArray](#) &approx\_coeffs)  
*set the approximation coefficients within the subModel*
- void [print\\_coefficients](#) (ostream &s, size\_t index) const  
*print a particular set of approximation coefficients within the subModel*
- const [RealVector](#) & [approximation\\_variances](#) (const [RealVector](#) &c\_vars)  
*retrieve the approximation variances from the subModel*
- const [List< SurrogateDataPoint >](#) & [approximation\\_data](#) (size\_t index)  
*retrieve the approximation data from the subModel*
- void [component\\_parallel\\_mode](#) (short mode)  
*virtual function redefinition is simply a sanity check.*
- [String](#) [local\\_eval\\_synchronization](#) ()  
*return subModel local synchronization setting*
- int [local\\_eval\\_concurrency](#) ()  
*return subModel local evaluation concurrency*
- bool [derived\\_master\\_overload](#) () const  
*evaluation (request forwarded to subModel)*
- void [derived\\_init\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*set up RecastModel for parallel operations (request forwarded to subModel)*
- void [derived\\_init\\_serial](#) ()  
*set up RecastModel for serial operations (request forwarded to subModel).*
- void [derived\\_set\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*set active parallel configuration within subModel*
- void [derived\\_free\\_communicators](#) (const int &max\_iterator\_concurrency, bool recurse\_flag=true)  
*to subModel)*
- void [serve](#) ()  
*Completes when a termination message is received from stop\_servers().*

- void `stop_servers ()`  
*when `RecastModel` iteration is complete.*
- const `String & interface_id ()` const  
*return the `subModel` interface identifier*
- int `evaluation_id ()` const  
*forwarded to `subModel`*
- void `set_evaluation_reference ()`  
*(request forwarded to `subModel`)*
- void `print_evaluation_summary (ostream &s, bool minimal_header=false, bool relative_count=true)` const  
*forwarded to `subModel`*

### Private Member Functions

- void `asv_mapping (const ShortArray &recast_asv, ShortArray &sub_model_asv)`  
*into `sub_model_asv` for use with `subModel`.*
- void `update_from_sub_model ()`  
*update current variables/labels/bounds/targets from `subModel`*

### Private Attributes

- `Model subModel`  
*the sub-model underlying the function pointers*
- `Sizet2DArray varsMapIndices`  
*`subModel` variables)*
- bool `nonlinearVarsMapping`  
*Hessians are managed per function, not per variable.*
- bool `respMapping`  
*are supplied*
- `Sizet2DArray primaryRespMapIndices`  
*to `RecastModel Response`).*
- `Sizet2DArray secondaryRespMapIndices`

to *RecastModel* response).

- [BoolDequeArray nonlinearRespMapping](#)  
augment the *subModel* function value/gradient requirements.
- [IntActiveSetMap recastSetMap](#)  
Needed for *currentResponse* update in synchronization routines.
- [IntVariablesMap recastVarsMap](#)  
synchronization routines.
- [IntVariablesMap subModelVarsMap](#)  
synchronization routines.
- [ResponseArray recastResponseArray](#)  
array of recast responses used by *RecastModel::derived\_synchronize()*
- [IntResponseMap recastResponseMap](#)  
map of recast responses used by *RecastModel::derived\_synchronize\_nowait()*
- `void(* variablesMapping )(const Variables &recast_vars, Variables &sub_model_vars)`  
holds pointer for variables mapping function passed in ctor/initialize
- `void(* asvMapping )(const ShortArray &recast_asv, ShortArray &sub_model_asv)`  
holds pointer for asv mapping function passed in ctor/initialize
- `void(* primaryRespMapping )(const Variables &sub_model_vars, const Variables &recast_vars, const Response &sub_model_response, Response &recast_response)`  
ctor/initialize
- `void(* secondaryRespMapping )(const Variables &sub_model_vars, const Variables &recast_vars, const Response &sub_model_response, Response &recast_response)`  
ctor/initialize

### 8.101.1 Detailed Description

in order to recast the form of its inputs and/or outputs.

The [RecastModel](#) class uses function pointers to allow recasting of the *subModel* input/output into new problem forms. This is currently used to recast SBO approximate subproblems, but can be used for multiobjective, input/output scaling, and other problem modifications in the future.

### 8.101.2 Constructor & Destructor Documentation

### 8.101.2.1 **RecastModel** (**Model** & *sub\_model*, **const size\_t** & *num\_recast\_primary\_fns*, **const size\_t** & *num\_recast\_secondary\_fns*, **const size\_t** & *recast\_secondary\_offset*)

alternate constructor

This alternate constructor defers initialization of the function pointers until a separate call to [initialize\(\)](#), and accepts the minimum information needed to construct `currentVariables`, `currentResponse`, and `userDefinedConstraints`. The resulting model is sufficiently complete for passing to an [Iterator](#).

## 8.101.3 Member Function Documentation

### 8.101.3.1 **void initialize** (**const Siset2DArray** & *vars\_map\_indices*, **bool** *nonlinear\_vars\_mapping*, **void(\*)**(**const Variables** &*recast\_vars*, **Variables** &*sub\_model\_vars*) *variables\_map*, **void(\*)**(**const ShortArray** &*recast\_asv*, **ShortArray** &*sub\_model\_asv*) *asv\_map*, **const Siset2DArray** & *primary\_resp\_map\_indices*, **const Siset2DArray** & *secondary\_resp\_map\_indices*, **const BoolDequeArray** & *nonlinear\_resp\_mapping*, **void(\*)**(**const Variables** &*sub\_model\_vars*, **const Variables** &*recast\_vars*, **const Response** &*sub\_model\_response*, **Response** &*recast\_response*) *primary\_resp\_map*, **void(\*)**(**const Variables** &*sub\_model\_vars*, **const Variables** &*recast\_vars*, **const Response** &*sub\_model\_response*, **Response** &*recast\_response*) *secondary\_resp\_map*)

completes initialization of the [RecastModel](#) after alternate construction

This function is used for late initialization of the recasting functions. It is used in concert with the alternate constructor.

### 8.101.3.2 **void update\_from\_sub\_model()** [private]

update current variables/labels/bounds/targets from subModel

Update inactive values and labels in `currentVariables` and inactive bound constraints in `userDefinedConstraints` from variables and constraints data within `subModel`.

The documentation for this class was generated from the following files:

- `RecastModel.H`
- `RecastModel.C`

## 8.102 Response Class Reference

[Response](#) provides the handle class.

### Public Member Functions

- [Response](#) ()  
*default constructor*
- [Response](#) (const [Variables](#) &vars, const [ProblemDescDB](#) &problem\_db)  
*standard constructor built from problem description database*
- [Response](#) (const [ActiveSet](#) &set)  
*alternate constructor using limited data*
- [Response](#) (const [Response](#) &response)  
*copy constructor*
- [~Response](#) ()  
*destructor*
- [Response operator=](#) (const [Response](#) &response)  
*assignment operator*
- [size\\_t num\\_functions](#) () const  
*return the number of response functions*
- const [ActiveSet](#) & [active\\_set](#) () const  
*return the active set*
- void [active\\_set](#) (const [ActiveSet](#) &set)  
*set the active set*
- const [ShortArray](#) & [active\\_set\\_request\\_vector](#) () const  
*return the active set request vector*
- void [active\\_set\\_request\\_vector](#) (const [ShortArray](#) &asrv)  
*set the active set request vector*
- const [IntArray](#) & [active\\_set\\_derivative\\_vector](#) () const  
*return the active set derivative vector*

- void `active_set_derivative_vector` (const `IntArray` &asdv)  
*set the active set derivative vector*
- const `String` & `responses_id` () const  
*return the response identifier*
- const `StringArray` & `function_labels` () const  
*return the response function identifier strings*
- void `function_labels` (const `StringArray` &labels)  
*set the response function identifier strings*
- const `Real` & `function_value` (const `size_t` &i) const  
*return a function value*
- const `RealVector` & `function_values` () const  
*return all function values*
- void `function_value` (const `Real` &function\_val, const `size_t` &i)  
*set a function value*
- void `function_values` (const `RealVector` &function\_vals)  
*set all function values*
- const `RealBaseVector` & `function_gradient` (const `size_t` &i) const  
*return a function gradient*
- const `RealMatrix` & `function_gradients` () const  
*return all function gradients*
- void `function_gradient` (const `RealBaseVector` &function\_grad, const `size_t` &i)  
*set a function gradient*
- void `function_gradients` (const `RealMatrix` &function\_grads)  
*set all function gradients*
- const `RealMatrix` & `function_hessian` (const `size_t` &i) const  
*return a function Hessian*
- const `RealMatrixArray` & `function_hessians` () const  
*return all function Hessians*
- void `function_hessian` (const `RealMatrix` &function\_hessian, const `size_t` &i)  
*set a function Hessian*
- void `function_hessians` (const `RealMatrixArray` &function\_hessians)



*set all function Hessians*

- void [read](#) (istream &s)  
*read a response object from an istream*
- void [write](#) (ostream &s) const  
*write a response object to an ostream*
- void [read\\_annotated](#) (istream &s)  
*read a response object in annotated format from an istream*
- void [write\\_annotated](#) (ostream &s) const  
*write a response object in annotated format to an ostream*
- void [read\\_tabular](#) (istream &s)  
*read responseRep::functionValues in tabular format from an istream*
- void [write\\_tabular](#) (ostream &s) const  
*write responseRep::functionValues in tabular format to an ostream*
- void [read](#) (BiStream &s)  
*read a response object from the binary restart stream*
- void [write](#) (BoStream &s) const  
*write a response object to the binary restart stream*
- void [read](#) (MPIUnpackBuffer &s)  
*read a response object from a packed MPI buffer*
- void [write](#) (MPIPackBuffer &s) const  
*write a response object to a packed MPI buffer*
- [Response copy](#) () const  
*a deep copy for use in history mechanisms*
- int [data\\_size](#) ()  
*handle class forward to corresponding body class member function*
- void [read\\_data](#) (double \*response\_data)  
*handle class forward to corresponding body class member function*
- void [write\\_data](#) (double \*response\_data)  
*handle class forward to corresponding body class member function*
- void [overlay](#) (const [Response](#) &response)  
*handle class forward to corresponding body class member function*

- void `copy_results` (const [Response](#) &response)  
*different derivative array sizing between the two response objects.*
- void `copy_results` (const [RealVector](#) &source\_fn\_vals, const [RealMatrix](#) &source\_fn\_grads, const [RealMatrixArray](#) &source\_fn\_hessians, const [ActiveSet](#) &source\_set)  
*object. Care is taken to allow different derivative array sizing.*
- void `reshape` (const size\_t &num\_fns, const size\_t &num\_params, bool grad\_flag, bool hess\_flag)  
*reshapes response data arrays*
- void `reset` ()  
*handle class forward to corresponding body class member function*
- void `reset_inactive` ()  
*handle class forward to corresponding body class member function*
- bool `is_null` () const  
*function to check responseRep (does this handle contain a body)*

## Private Attributes

- [ResponseRep](#) \* responseRep  
*pointer to the body (handle-body idiom)*

## Friends

- bool `operator==` (const [Response](#) &resp1, const [Response](#) &resp2)  
*equality operator*
- bool `operator!=` (const [Response](#) &resp1, const [Response](#) &resp2)  
*inequality operator*

### 8.102.1 Detailed Description

[Response](#) provides the handle class.

The [Response](#) class is a container class for an abstract set of functions (functionValues) and their first (functionGradients) and second (functionHessians) derivatives. The functions may involve objective and constraint functions (optimization data set), least squares terms (parameter estimation data set), or generic response functions (uncertainty quantification data set). It is not currently part of a class hierarchy, since the abstraction has been sufficiently general and has not required specialization. For memory efficiency, it employs the "handle-body idiom" approach to reference counting and representation sharing (see Coplien "Advanced C++", p. 58), for which [Response](#) serves as the handle and [ResponseRep](#) serves as the body.

## 8.102.2 Constructor & Destructor Documentation

### 8.102.2.1 [Response](#) ()

default constructor

Need a populated problem description database to build a meaningful [Response](#) object, so set the response-Rep=NULL in default constructor for efficiency. This then requires a check on NULL in the copy constructor, assignment operator, and destructor.

The documentation for this class was generated from the following files:

- [DakotaResponse.H](#)
- [DakotaResponse.C](#)

## 8.103 ResponseRep Class Reference

[ResponseRep](#) provides the body class.

### Private Member Functions

- [ResponseRep](#) ()  
*default constructor*
- [ResponseRep](#) (const [Variables](#) &vars, const [ProblemDescDB](#) &problem\_db)  
*standard constructor built from problem description database*
- [ResponseRep](#) (const [ActiveSet](#) &set)  
*alternate constructor using limited data*
- [~ResponseRep](#) ()  
*destructor*
- void [read](#) (istream &s)  
*read a responseRep object from an istream*
- void [write](#) (ostream &s) const  
*write a responseRep object to an ostream*
- void [read\\_annotated](#) (istream &s)  
*read a responseRep object from an istream (annotated format)*
- void [write\\_annotated](#) (ostream &s) const  
*write a responseRep object to an ostream (annotated format)*
- void [read\\_tabular](#) (istream &s)  
*read functionValues from an istream (tabular format)*
- void [write\\_tabular](#) (ostream &s) const  
*write functionValues to an ostream (tabular format)*
- void [read](#) ([BiStream](#) &s)  
*read a responseRep object from a binary stream*
- void [write](#) ([BoStream](#) &s) const  
*write a responseRep object to a binary stream*

- void [read](#) ([MPIUnpackBuffer](#) &s)  
*read a responseRep object from a packed MPI buffer*
- void [write](#) ([MPIPackBuffer](#) &s) const  
*write a responseRep object to a packed MPI buffer*
- int [data\\_size](#) ()  
*double\* response\_data arrays passed into read\_data and write\_data.*
- void [read\\_data](#) (double \*response\_data)  
*read from an incoming double\* array*
- void [write\\_data](#) (double \*response\_data)  
*write to an incoming double\* array*
- void [overlay](#) (const [Response](#) &response)  
*add incoming response to functionValues/Gradients/Hessians*
- void [copy\\_results](#) (const [RealVector](#) &source\_fn\_vals, const [RealMatrix](#) &source\_fn\_grads, const [RealMatrixArray](#) &source\_fn\_hessians, const [ActiveSet](#) &source\_set)  
*update this response object from components of another response object*
- void [reshape](#) (const size\_t &num\_fns, const size\_t &num\_params, bool grad\_flag, bool hess\_flag)  
*reshapes response data arrays*
- void [reset](#) ()  
*resets all response data to zero*
- void [reset\\_inactive](#) ()  
*resets all inactive response data to zero*
- void [active\\_set\\_request\\_vector](#) (const [ShortArray](#) &asrv)  
*of response functions*
- void [active\\_set\\_derivative\\_vector](#) (const [IntArray](#) &asdv)  
*functionGradients/functionHessians if needed*

### Private Attributes

- int [referenceCount](#)  
*number of handle objects sharing responseRep*
- [RealVector](#) [functionValues](#)  
*abstract set of response functions*

- [RealMatrix](#) functionGradients  
*first derivatives of the response functions*
- [RealMatrixArray](#) functionHessians  
*second derivatives of the response functions*
- [ActiveSet](#) responseActiveSet  
*copy of the [ActiveSet](#) used by the [Model](#) to generate a [Response](#) instance*
- [StringArray](#) functionLabels  
*response function identifiers used to improve output readability*
- [String](#) idResponses  
*response identifier string from the input file*

## Friends

- class [Response](#)  
*the handle class can access attributes of the body class directly*
- bool `operator==` (const [ResponseRep](#) &rep1, const [ResponseRep](#) &rep2)  
*equality operator*

### 8.103.1 Detailed Description

[ResponseRep](#) provides the body class.

The [ResponseRep](#) class is the "representation" of the response container class. It is the "body" portion of the "handle-body idiom" (see Coplien "Advanced C++", p. 58). The handle class ([Response](#)) provides for memory efficiency in management of multiple response objects through reference counting and representation sharing. The body class ([ResponseRep](#)) actually contains the response data (functionValues, functionGradients, functionHessians, etc.). The representation is hidden in that an instance of [ResponseRep](#) may only be created by [Response](#). Therefore, programmers create instances of the [Response](#) handle class, and only need to be aware of the handle/body mechanisms when it comes to managing shallow copies (shared representation) versus deep copies (separate representation used for history mechanisms).

### 8.103.2 Constructor & Destructor Documentation

#### 8.103.2.1 [ResponseRep](#) (const [Variables](#) & vars, const [ProblemDescDB](#) & problem\_db) [private]

standard constructor built from problem description database

The standard constructor used by Dakota::ModelRep.

### 8.103.2.2 ResponseRep (const ActiveSet & set) [private]

alternate constructor using limited data

Used for building a response object of the correct size on the fly (e.g., by slave analysis servers performing `execute()` on a `local_response`). `functionLabels` is not needed for this purpose since it's not passed in the MPI send/recv buffers. However, `NPSOLOptimizer`'s user-defined functions option uses this constructor to build `bestResponses` and `bestResponses` needs `functionLabels` for I/O, so construction of `functionLabels` has been added.

## 8.103.3 Member Function Documentation

### 8.103.3.1 void read (istream & s) [private]

read a responseRep object from an istream

ASCII version of `read` needs capabilities for capturing data omissions or formatting errors (resulting from user error or asynch race condition) and analysis failures (resulting from nonconvergence, instability, etc.).

### 8.103.3.2 void write (ostream & s) const [private]

write a responseRep object to an ostream

ASCII version of `write`.

### 8.103.3.3 void read\_annotated (istream & s) [private]

read a responseRep object from an istream (annotated format)

`read_annotated()` is used for neutral file translation of restart files. Since objects are built solely from this data, annotations are used. This version closely mirrors the `BiStream` version.

### 8.103.3.4 void write\_annotated (ostream & s) const [private]

write a responseRep object to an ostream (annotated format)

`write_annotated()` is used for neutral file translation of restart files. Since objects need to be build solely from this data, annotations are used. This version closely mirrors the `BoStream` version, with the exception of the use of white space between fields.

### 8.103.3.5 void read\_tabular (istream & s) [private]

read functionValues from an istream (tabular format)

`read_tabular` is used to read functionValues in tabular format. It is currently only used by `ApproximationInterfaces` in reading samples from a file. There is insufficient data in a tabular file to build complete response objects; rather, the response object must be constructed a priori and then its functionValues can be set.

**8.103.3.6 void write\_tabular (ostream & s) const [private]**

write functionValues to an ostream (tabular format)

write\_tabular is used for output of functionValues in a tabular format for convenience in post-processing/plotting of DAKOTA results.

**8.103.3.7 void read (BiStream & s) [private]**

read a responseRep object from a binary stream

Binary version differs from ASCII version in 2 primary ways: (1) it lacks formatting. (2) the [Response](#) has not been sized a priori. In reading data from the binary restart file, a [ParamResponsePair](#) was constructed with its default constructor which called the [Response](#) default constructor. Therefore, we must first read sizing data and resize all of the arrays.

**8.103.3.8 void write (BoStream & s) const [private]**

write a responseRep object to a binary stream

Binary version differs from ASCII version in 2 primary ways: (1) It lacks formatting. (2) In reading data from the binary restart file, ParamResponsePairs are constructed with their default constructor which calls the [Response](#) default constructor. Therefore, we must first write sizing data so that ResponseRep::read(BoStream& s) can resize the arrays.

**8.103.3.9 void read (MPIUnpackBuffer & s) [private]**

read a responseRep object from a packed MPI buffer

UnpackBuffer version differs from [BiStream](#) version in the omission of functionLabels. Master processor retains labels and interface ids and communicates asv and response data only with slaves.

**8.103.3.10 void write (MPIPackBuffer & s) const [private]**

write a responseRep object to a packed MPI buffer

[MPIPackBuffer](#) version differs from [BoStream](#) version only in the omission of functionLabels. The master processor retains labels and ids and communicates asv and response data only with slaves.

**8.103.3.11 void copy\_results (const RealVector & source\_fn\_vals, const RealMatrix & source\_fn\_grads, const RealMatrixArray & source\_fn\_hessians, const ActiveSet & source\_set) [private]**

update this response object from components of another response object

Copy function values/gradients/Hessians data \_only\_. Prevents unwanted overwriting of responseActiveSet, functionLabels, etc. Also, care is taken to account for differences in derivative variable matrix sizing.



**8.103.3.12** `void reshape (const size_t & num_fns, const size_t & num_params, bool grad_flag, bool hess_flag) [private]`

reshapes response data arrays

Reshape functionValues, functionGradients, and functionHessians according to num\_fns, num\_params, grad\_flag, and hess\_flag.

**8.103.3.13** `void reset () [private]`

resets all response data to zero

Reset all numerical response data (not labels, ids, or active set) to zero.

**8.103.3.14** `void reset_inactive () [private]`

resets all inactive response data to zero

Used to clear out any inactive data left over from previous evaluations.

## 8.103.4 Member Data Documentation

**8.103.4.1** [RealMatrix functionGradients](#) [private]

first derivatives of the response functions

the gradient vectors (plural) are arranged as a Jacobian matrix (singular) with (row, col) = (response fn index, variable index).

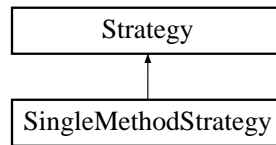
The documentation for this class was generated from the following files:

- DakotaResponse.H
- DakotaResponse.C

## 8.104 SingleMethodStrategy Class Reference

single model.

Inheritance diagram for SingleMethodStrategy::



### Public Member Functions

- [SingleMethodStrategy \(ProblemDescDB &problem\\_db\)](#)  
*constructor*
- [~SingleMethodStrategy \(\)](#)  
*destructor*
- void [run\\_strategy \(\)](#)  
*Perform the strategy by executing selectedIterator on userDefinedModel.*
- const [Variables & variables\\_results \(\)](#) const  
*return the final solution from selectedIterator (variables)*
- const [Response & response\\_results \(\)](#) const  
*return the final solution from selectedIterator (response)*

### Private Attributes

- [Model userDefinedModel](#)  
*the model to be iterated*
- [Iterator selectedIterator](#)  
*the iterator*

### 8.104.1 Detailed Description

single model.

This strategy executes a single iterator on a single model. Since it does not provide coordination for multiple iterators and models, it can be considered to be a "fall-through" strategy in that it allows control to fall through immediately to the iterator.

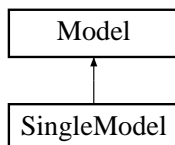
The documentation for this class was generated from the following files:

- SingleMethodStrategy.H
- SingleMethodStrategy.C

## 8.105 SingleModel Class Reference

variables into responses.

Inheritance diagram for SingleModel::



### Public Member Functions

- [SingleModel](#) ([ProblemDescDB](#) &problem\_db)  
*constructor*
- [~SingleModel](#) ()  
*destructor*

### Protected Member Functions

- [Interface](#) & [interface](#) ()  
*return userDefinedInterface*
- void [derived\\_compute\\_response](#) (const [ActiveSet](#) &set)  
*(invokes a synchronous map() on userDefinedInterface)*
- void [derived\\_asynch\\_compute\\_response](#) (const [ActiveSet](#) &set)  
*(invokes an asynchronous map() on userDefinedInterface)*
- const [ResponseArray](#) & [derived\\_synchronize](#) ()  
*(invokes synch() on userDefinedInterface)*
- const [IntResponseMap](#) & [derived\\_synchronize\\_nowait](#) ()  
*(invokes synch\_nowait() on userDefinedInterface)*
- void [component\\_parallel\\_mode](#) (short mode)  
*so this virtual function redefinition is simply a sanity check.*
- [String](#) [local\\_eval\\_synchronization](#) ()

*return userDefinedInterface synchronization setting*

- `int local_eval_concurrency ()`  
*return userDefinedInterface asynchronous evaluation concurrency*
- `bool derived_master_overload () const`  
*evaluation (request forwarded to userDefinedInterface)*
- `void derived_init_communicators (const int &max_iterator_concurrency, bool recurse_flag=true)`  
*userDefinedInterface)*
- `void derived_init_serial ()`  
*userDefinedInterface).*
- `void derived_set_communicators (const int &max_iterator_concurrency, bool recurse_flag=true)`  
*(request forwarded to userDefinedInterface)*
- `void derived_free_communicators (const int &max_iterator_concurrency, bool recurse_flag=true)`  
*(request forwarded to userDefinedInterface)*
- `void serve ()`  
*Completes when a termination message is received from stop\_servers().*
- `void stop_servers ()`  
*operations when SingleModel iteration is complete.*
- `const String & interface_id () const`  
*return the userDefinedInterface identifier*
- `int evaluation_id () const`  
*(request forwarded to userDefinedInterface)*
- `void set_evaluation_reference ()`  
*(request forwarded to userDefinedInterface)*
- `void print_evaluation_summary (ostream &s, bool minimal_header=false, bool relative_count=true) const`  
*(request forwarded to userDefinedInterface)*

## Private Attributes

- `Interface userDefinedInterface`  
*the interface used for mapping variables to responses*

### 8.105.1 Detailed Description

variables into responses.

The [SingleModel](#) class is the simplest of the derived model classes. It provides the capabilities of the original [Model](#) class, prior to the development of surrogate and nested model extensions. The derived response computation and synchronization functions utilize a single interface to perform the function evaluations.

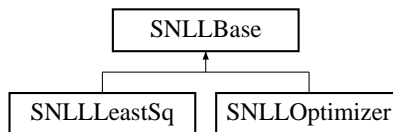
The documentation for this class was generated from the following files:

- SingleModel.H
- SingleModel.C

## 8.106 SNLLBase Class Reference

Base class for OPT++ optimization and least squares methods.

Inheritance diagram for SNLLBase::



### Public Member Functions

- [SNLLBase \(\)](#)  
*default constructor*
- [SNLLBase \(Model &model\)](#)  
*standard constructor*
- [~SNLLBase \(\)](#)  
*destructor*

### Protected Member Functions

- void [copy\\_con\\_vals](#) (const [RealVector](#) &local\_fn\_vals, [NEWMAT::ColumnVector](#) &g, const size\_t &offset)  
*constraint evaluator functions*
- void [copy\\_con\\_vals](#) (const [NEWMAT::ColumnVector](#) &g, [RealVector](#) &local\_fn\_vals, const size\_t &offset)  
*final solution logging*
- void [copy\\_con\\_grad](#) (const [RealMatrix](#) &local\_fn\_grads, [NEWMAT::Matrix](#) &grad\_g, const size\_t &offset)  
*used by constraint evaluator functions*
- void [copy\\_con\\_hess](#) (const [RealMatrixArray](#) &local\_fn\_hessians, [OPTPP::OptppArray](#)<[NEWMAT::SymmetricMatrix](#)> &hess\_g, const size\_t &offset)  
*used by constraint evaluator functions*
- void [snll\\_pre\\_instantiate](#) (const [String](#) &merit\_fn, bool bound\_constr\_flag, const int &num\_constr)

*method instantiation*

- void [snll\\_post\\_instantiate](#) (const int &num\_cv, bool vendor\_num\_grad\_flag, const [String](#) &finite\_diff\_type, const Real &fdss, const int &max\_iter, const int &max\_fn\_evals, const Real &conv\_tol, const Real &grad\_tol, const Real &max\_step, bool bound\_constr\_flag, const int &num\_constr, bool debug\_output, OPTPP::OptimizeClass \*the\_optimizer, OPTPP::NLP0 \*nlf\_objective, OPTPP::FDNLF1 \*fd\_nlf1, OPTPP::FDNLF1 \*fd\_nlf1\_con)

*method instantiation*

- void [snll\\_pre\\_run](#) (OPTPP::NLP0 \*nlf\_objective, OPTPP::NLP \*nlp\_constraint, const [RealVector](#) &init\_pt, bool bound\_constr\_flag, const [RealVector](#) &lower\_bnds, const [RealVector](#) &upper\_bnds, const [RealMatrix](#) &lin\_ineq\_coeffs, const [RealVector](#) &lin\_ineq\_l\_bnds, const [RealVector](#) &lin\_ineq\_u\_bnds, const [RealMatrix](#) &lin\_eq\_coeffs, const [RealVector](#) &lin\_eq\_targets, const [RealVector](#) &nln\_ineq\_l\_bnds, const [RealVector](#) &nln\_ineq\_u\_bnds, const [RealVector](#) &nln\_eq\_targets)

*method invocation*

- void [snll\\_post\\_run](#) (OPTPP::NLP0 \*nlf\_objective)

*method instantiations*

## Static Protected Member Functions

- static void [init\\_fn](#) (int n, NEWMAT::ColumnVector &x)

*An initialization mechanism provided by OPT++ (not currently used).*

## Protected Attributes

- [String](#) [searchMethod](#)

*trust\_region, or tr\_pds*

- OPTPP::SearchStrategy [searchStrat](#)

*enum: LineSearch, TrustRegion, or TrustPDS*

- OPTPP::MeritFcn [meritFn](#)

*enum: NormFmu, ArgaezTapia, or VanShanno*

- bool [constantASVFlag](#)

*this into mode override, reliance on duplicate detection can be avoided.*

## Static Protected Attributes

- static [Minimizer](#) \* [optLsqInstance](#)

*evaluator functions in order to avoid the need for static data*



- static bool [modeOverrideFlag](#)  
*Hessian requests).*
- static [EvalType](#) [lastFnEvalLocn](#)  
*evaluator was the last location of a function evaluation*
- static int [lastEvalMode](#)  
*copy of mode from constraint evaluators*
- static [RealVector](#) [lastEvalVars](#)  
*copy of variables from constraint evaluators*

### 8.106.1 Detailed Description

Base class for OPT++ optimization and least squares methods.

The [SNLLBase](#) class provides a common base class for [SNLLOptimizer](#) and [SNLLLeastSq](#), both of which are wrappers for OPT++, a C++ optimization library from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site.

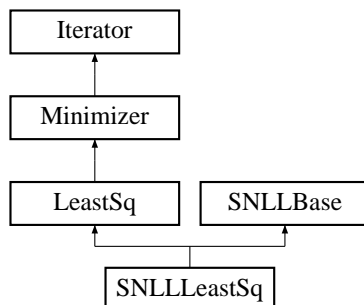
The documentation for this class was generated from the following files:

- [SNLLBase.H](#)
- [SNLLBase.C](#)

## 8.107 SNLLLeastSq Class Reference

Wrapper class for the OPT++ optimization library.

Inheritance diagram for SNLLLeastSq::



### Public Member Functions

- [SNLLLeastSq \(Model &model\)](#)  
*constructor*
- [~SNLLLeastSq \(\)](#)  
*destructor*
- void [minimize\\_residuals \(\)](#)  
*Performs the iterations to determine the least squares solution.*

### Protected Member Functions

- virtual void [derived\\_pre\\_run \(\)](#)  
*invokes [SNLLBase::snll\\_pre\\_run\(\)](#) and performs other set-up*
- virtual void [derived\\_post\\_run \(\)](#)  
*invokes [SNLLBase::snll\\_post\\_run\(\)](#) and performs other solution processing*

### Static Private Member Functions

- static void [nlf2\\_evaluator\\_gn](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, NEWMAT::ColumnVector &grad\_f, NEWMAT::SymmetricMatrix &hess\_f, int &result\_mode)

*value, gradient, and Hessian using the Gauss-Newton approximation.*

- static void [constraint1\\_evaluator\\_gn](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad\_g, int &result\_mode)  
*values and gradients to OPT++ Gauss-Newton methods.*
- static void [constraint2\\_evaluator\\_gn](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad\_g, OPTPP::OptppArray< NEWMAT::SymmetricMatrix > &hess\_g, int &result\_mode)  
*values, gradients, and Hessians to OPT++ Gauss-Newton methods.*

## Private Attributes

- [SNLLLeastSq](#) \* [prevInstance](#)  
*restoration in the case of iterator/model recursion*
- OPTPP::NLP0 \* [nlfObjective](#)  
*objective NLF base class pointer*
- OPTPP::NLP0 \* [nlfConstraint](#)  
*constraint NLF base class pointer*
- OPTPP::NLP \* [nlpConstraint](#)  
*constraint NLP pointer*
- OPTPP::NLF2 \* [nlf2](#)  
*pointer to objective NLF for full Newton optimizers*
- OPTPP::NLF2 \* [nlf2Con](#)  
*pointer to constraint NLF for full Newton optimizers*
- OPTPP::NLF1 \* [nlf1Con](#)  
*pointer to constraint NLF for Quasi Newton optimizers*
- OPTPP::OptimizeClass \* [theOptimizer](#)  
*optimizer base class pointer*
- OPTPP::OptNewton \* [optnewton](#)  
*Newton optimizer pointer.*
- OPTPP::OptBCNewton \* [optbcnewton](#)  
*Bound constrained Newton optimizer ptr.*
- OPTPP::OptDHNIPS \* [optdhnips](#)  
*Disaggregated Hessian NIPS optimizer ptr.*

## Static Private Attributes

- static [SNLLLeastSq](#) \* [snllSqInstance](#)

*functions in order to avoid the need for static data*

### 8.107.1 Detailed Description

Wrapper class for the OPT++ optimization library.

The [SNLLLeastSq](#) class provides a wrapper for OPT++, a C++ optimization library of nonlinear programming and pattern search techniques from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function, a static member, or accessed by static pointer.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `max_step`, `gradient_tolerance`, `search_method`, and `search_scheme_size` are set using OPT++'s `setMaxIter()`, `setMaxFeval()`, `setFcnTol()`, `setMaxStep()`, `setGradTol()`, `setSearchStrategy()`, and `setSSS()` member functions, respectively; `output_verbosity` is used to toggle OPT++'s debug mode using the `setDebug()` member function. Internal to OPT++, there are 3 search strategies, while the DAKOTA `search_method` specification supports 4 (`value_based_line_search`, `gradient_based_line_search`, `trust_region`, or `tr_pds`). The difference stems from the "is\_expensive" flag in OPT++. If the search strategy is `LineSearch` and "is\_expensive" is turned on, then the `value_based_line_search` is used. Otherwise (the "is\_expensive" default is off), the algorithm will use the `gradient_based_line_search`. Refer to [Meza, J.C., 1994] and to the OPT++ source in the `Dakota/methods/OPTPP` directory for information on OPT++ class member functions.

### 8.107.2 Member Function Documentation

**8.107.2.1** `void nlf2_evaluator_gn (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::Real & f, NEWMAT::ColumnVector & grad_f, NEWMAT::SymmetricMatrix & hess_f, int & result_mode) [static, private]`

value, gradient, and Hessian using the Gauss-Newton approximation.

This `nlf2` evaluator function is used for the Gauss-Newton method in order to exploit the special structure of the nonlinear least squares problem. Here,  $fx = \sum (T_i - Tbar_i)^2$  and [Response](#) is made up of residual functions and their gradients along with any nonlinear constraints. The objective function and its gradient vector and Hessian matrix are computed directly from the residual functions and their derivatives (which are returned from the [Response](#) object).

**8.107.2.2** `void constraint1_evaluator_gn (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::ColumnVector & g, NEWMAT::Matrix & grad_g, int & result_mode) [static, private]`

values and gradients to OPT++ Gauss-Newton methods.

While it does not employ the Gauss-Newton approximation, it is distinct from `constraint1_evaluator()` due to its need to anticipate the required modes for the least squares terms. This constraint evaluator function is used with diagggregated Hessian NIPS and is currently active.

**8.107.2.3** `static void constraint2_evaluator_gn (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::ColumnVector & g, NEWMAT::Matrix & grad_g, OPTPP::OptppArray< NEWMAT::SymmetricMatrix > & hess_g, int & result_mode) [static, private]`

values, gradients, and Hessians to OPT++ Gauss-Newton methods.

While it does not employ the Gauss-Newton approximation, it is distinct from `constraint2_evaluator()` due to its need to anticipate the required modes for the least squares terms. This constraint evaluator function is used with full Newton NIPS and is currently inactive.

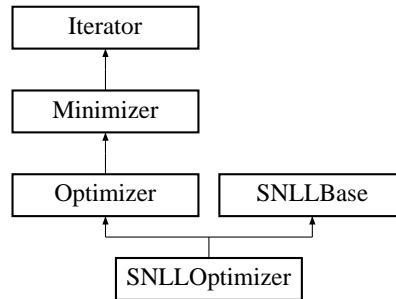
The documentation for this class was generated from the following files:

- SNLLLeastSq.H
- SNLLLeastSq.C

## 8.108 SNLLOptimizer Class Reference

Wrapper class for the OPT++ optimization library.

Inheritance diagram for SNLLOptimizer::



### Public Member Functions

- [SNLLOptimizer](#) ([Model](#) &model)
  - standard constructor*
- [SNLLOptimizer](#) ([Model](#) &model, const [String](#) &method)
  - alternate constructor for instantiations "on the fly"*
- [SNLLOptimizer](#) (const [RealVector](#) &initial\_point, const [RealVector](#) &var\_lower\_bnds, const [RealVector](#) &var\_upper\_bnds, const [RealMatrix](#) &lin\_ineq\_coeffs, const [RealVector](#) &lin\_ineq\_lower\_bnds, const [RealVector](#) &lin\_ineq\_upper\_bnds, const [RealMatrix](#) &lin\_eq\_coeffs, const [RealVector](#) &lin\_eq\_targets, const [RealVector](#) &nonlin\_ineq\_lower\_bnds, const [RealVector](#) &nonlin\_ineq\_upper\_bnds, const [RealVector](#) &nonlin\_eq\_targets, void(\*user\_obj\_eval)(int mode, int n, const [NEWMAT::ColumnVector](#) &x, [NEWMAT::Real](#) &f, [NEWMAT::ColumnVector](#) &grad\_f, int &result\_mode), void(\*user\_con\_eval)(int mode, int n, const [NEWMAT::ColumnVector](#) &x, [NEWMAT::ColumnVector](#) &g, [NEWMAT::Matrix](#) &grad\_g, int &result\_mode))
  - alternate constructor for instantiations "on the fly"*
- [~SNLLOptimizer](#) ()
  - destructor*
- void [find\\_optimum](#) ()
  - Performs the iterations to determine the optimal solution.*

## Protected Member Functions

- virtual void [derived\\_pre\\_run](#) ()  
*invokes `SNLLBase::snll_pre_run()` and performs other set-up*

## Static Private Member Functions

- static void [nlf0\\_evaluator](#) (int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, int &result\_mode)  
*require only function values.*
- static void [nlf1\\_evaluator](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, NEWMAT::ColumnVector &grad\_f, int &result\_mode)  
*values and gradients to OPT++ methods.*
- static void [nlf2\\_evaluator](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, NEWMAT::ColumnVector &grad\_f, NEWMAT::SymmetricMatrix &hess\_f, int &result\_mode)  
*values, gradients, and Hessians to OPT++ methods.*
- static void [constraint0\\_evaluator](#) (int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, int &result\_mode)  
*only constraint values.*
- static void [constraint1\\_evaluator](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad\_g, int &result\_mode)  
*values and gradients to OPT++ methods.*
- static void [constraint2\\_evaluator](#) (int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad\_g, OPTPP::OptppArray< NEWMAT::SymmetricMatrix > &hess\_g, int &result\_mode)  
*values, gradients, and Hessians to OPT++ methods.*

## Private Attributes

- [SNLLOptimizer \\* prevInstance](#)  
*restoration in the case of iterator/model recursion*
- [OPTPP::NLP0 \\* nlfObjective](#)  
*objective NLF base class pointer*
- [OPTPP::NLP0 \\* nlfConstraint](#)  
*constraint NLF base class pointer*
- [OPTPP::NLP \\* nlpConstraint](#)

*constraint NLP pointer*

- OPTPP::NLF0 \* [nlf0](#)  
*pointer to objective NLF for nongradient optimizers*
- OPTPP::NLF1 \* [nlf1](#)  
*pointer to objective NLF for (analytic) gradient-based optimizers*
- OPTPP::NLF1 \* [nlf1Con](#)  
*pointer to constraint NLF for (analytic) gradient-based optimizers*
- OPTPP::FDNLF1 \* [fdnlf1](#)  
*pointer to objective NLF for (finite diff) gradient-based optimizers*
- OPTPP::FDNLF1 \* [fdnlf1Con](#)  
*pointer to constraint NLF for (finite diff) gradient-based optimizers*
- OPTPP::NLF2 \* [nlf2](#)  
*pointer to objective NLF for full Newton optimizers*
- OPTPP::NLF2 \* [nlf2Con](#)  
*pointer to constraint NLF for full Newton optimizers*
- OPTPP::OptimizeClass \* [theOptimizer](#)  
*optimizer base class pointer*
- OPTPP::OptPDS \* [optpds](#)  
*PDS optimizer pointer.*
- OPTPP::OptCG \* [optcg](#)  
*CG optimizer pointer.*
- OPTPP::OptLBFGS \* [optlbfgs](#)  
*L-BFGS optimizer pointer.*
- OPTPP::OptNewton \* [optnewton](#)  
*Newton optimizer pointer.*
- OPTPP::OptQNewton \* [optqnewton](#)  
*Quasi-Newton optimizer pointer.*
- OPTPP::OptFDNewton \* [optfdnewton](#)  
*Finite Difference Newton opt pointer.*
- OPTPP::OptBCNewton \* [optbcnewton](#)  
*Bound constrained Newton opt pointer.*



- [OPTPP::OptBCQNewton \\* optbcqnewton](#)  
*Bnd constrained Quasi-Newton opt ptr.*
- [OPTPP::OptBCFDNewton \\* optbcfdnewton](#)  
*Bnd constrained FD-Newton opt ptr.*
- [OPTPP::OptNIPS \\* optnips](#)  
*NIPS optimizer pointer.*
- [OPTPP::OptQNIPS \\* optqnips](#)  
*Quasi-Newton NIPS optimizer pointer.*
- [OPTPP::OptFDNIPS \\* optfdnips](#)  
*Finite Difference NIPS opt pointer.*
- [String setUpType](#)  
*NonDReliability currently uses the user\_functions mode.*
- [RealVector initialPoint](#)  
*holds initial point passed in for "user\_functions" mode.*
- [RealVector lowerBounds](#)  
*holds variable lower bounds passed in for "user\_functions" mode.*
- [RealVector upperBounds](#)  
*holds variable upper bounds passed in for "user\_functions" mode.*

### Static Private Attributes

- static [SNLLOptimizer \\* snllOptInstance](#)  
*functions in order to avoid the need for static data*

#### 8.108.1 Detailed Description

Wrapper class for the OPT++ optimization library.

The [SNLLOptimizer](#) class provides a wrapper for OPT++, a C++ optimization library of nonlinear programming and pattern search techniques from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function, a static member, or accessed by static pointer.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `max_step`, `gradient_tolerance`, `search_method`, and `search_scheme_size` are set using OPT++'s `setMaxIter()`, `setMaxFeval()`, `setFcnTol()`, `setMaxStep()`, `setGradTol()`, `setSearchStrategy()`, and `setSSS()` member functions, respectively; `output_verbosity` is used to toggle OPT++'s debug mode using the `setDebug()` member function. Internal to OPT++, there are 3 search strategies, while the DAKOTA `search_method` specification supports 4 (`value_based_line_search`, `gradient_based_line_search`, `trust_region`, or `tr_pds`). The difference stems from the "is\_expensive" flag in OPT++. If the search strategy is `LineSearch` and "is\_expensive" is turned on, then the `value_based_line_search` is used. Otherwise (the "is\_expensive" default is off), the algorithm will use the `gradient_based_line_search`. Refer to [Meza, J.C., 1994] and to the OPT++ source in the `Dakota/methods/OPTPP` directory for information on OPT++ class member functions.

## 8.108.2 Constructor & Destructor Documentation

### 8.108.2.1 [SNLLOptimizer](#) (Model & model)

standard constructor

This constructor is used for normal instantiations using data from the [ProblemDescDB](#).

### 8.108.2.2 [SNLLOptimizer](#) (Model & model, const String & method)

alternate constructor for instantiations "on the fly"

This is an alternate constructor for instantiations on the fly using a [Model](#) but no [ProblemDescDB](#).

### 8.108.2.3 [SNLLOptimizer](#) (const RealVector & initial\_point, const RealVector & var\_lower\_bnds, const RealVector & var\_upper\_bnds, const RealMatrix & lin\_ineq\_coeffs, const RealVector & lin\_ineq\_lower\_bnds, const RealVector & lin\_ineq\_upper\_bnds, const RealMatrix & lin\_eq\_coeffs, const RealVector & lin\_eq\_targets, const RealVector & nonlin\_ineq\_lower\_bnds, const RealVector & nonlin\_ineq\_upper\_bnds, const RealVector & nonlin\_eq\_targets, void(\*)(int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::Real &f, NEWMAT::ColumnVector &grad\_f, int &result\_mode) user\_obj\_eval, void(\*)(int mode, int n, const NEWMAT::ColumnVector &x, NEWMAT::ColumnVector &g, NEWMAT::Matrix &grad\_g, int &result\_mode) user\_con\_eval)

alternate constructor for instantiations "on the fly"

This is an alternate constructor for performing an optimization using the passed in objective function and constraint function pointers.

## 8.108.3 Member Function Documentation

**8.108.3.1** `void nlf0_evaluator (int n, const NEWMAT::ColumnVector & x, NEWMAT::Real & f, int & result_mode) [static, private]`

require only function values.

For use when DAKOTA computes f and gradients are not directly available. This is used by nongradient-based optimizers such as PDS and by gradient-based optimizers in vendor numerical gradient mode (opt++'s internal finite difference routine is used).

**8.108.3.2** `void nlf1_evaluator (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::Real & f, NEWMAT::ColumnVector & grad_f, int & result_mode) [static, private]`

values and gradients to OPT++ methods.

For use when DAKOTA computes f and df/dX (regardless of gradientType). Vendor numerical gradient case is handled by nlf0\_evaluator.

**8.108.3.3** `void nlf2_evaluator (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::Real & f, NEWMAT::ColumnVector & grad_f, NEWMAT::SymmetricMatrix & hess_f, int & result_mode) [static, private]`

values, gradients, and Hessians to OPT++ methods.

For use when DAKOTA receives f, df/dX, &  $d^2f/dx^2$  from the [ApplicationInterface](#) (analytic only). Finite differencing does not make sense for a full Newton approach, since lack of analytic gradients & Hessian should dictate the use of quasi-newton or fd-newton. Thus, there is no fdnlf2\_evaluator for use with full Newton approaches, since it is preferable to use quasi-newton or fd-newton with nlf1. Gauss-Newton does not fit this model; it uses nlf2\_evaluator\_gn instead of nlf2\_evaluator.

**8.108.3.4** `void constraint0_evaluator (int n, const NEWMAT::ColumnVector & x, NEWMAT::ColumnVector & g, int & result_mode) [static, private]`

only constraint values.

For use when DAKOTA computes g and gradients are not directly available. This is used by nongradient-based optimizers and by gradient-based optimizers in vendor numerical gradient mode (opt++'s internal finite difference routine is used).

**8.108.3.5** `void constraint1_evaluator (int mode, int n, const NEWMAT::ColumnVector & x, NEWMAT::ColumnVector & g, NEWMAT::Matrix & grad_g, int & result_mode) [static, private]`

values and gradients to OPT++ methods.

For use when DAKOTA computes g and dg/dX (regardless of gradientType). Vendor numerical gradient case is handled by constraint0\_evaluator.

The documentation for this class was generated from the following files:

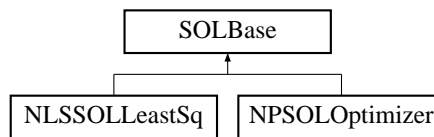
- SNLLOptimizer.H

- SNLLOptimizer.C

## 8.109 SOLBase Class Reference

Base class for Stanford SOL software.

Inheritance diagram for SOLBase::



### Public Member Functions

- [SOLBase \(\)](#)  
*default constructor*
- [SOLBase \(Model &model\)](#)  
*standard constructor*
- [~SOLBase \(\)](#)  
*destructor*

### Protected Member Functions

- void [allocate\\_arrays](#) (const int &num\_cv, const size\_t &num\_nln\_con, const [RealMatrix](#) &lin\_ineq\_coeffs, const [RealMatrix](#) &lin\_eq\_coeffs)  
*Allocates miscellaneous arrays for the SOL algorithms.*
- void [deallocate\\_arrays](#) ()  
*Deallocates memory previously allocated by [allocate\\_arrays](#)().*
- void [allocate\\_workspace](#) (const int &num\_cv, const int &num\_nln\_con, const int &num\_lin\_con, const int &num\_lsq)  
*Allocates real and integer workspaces for the SOL algorithms.*
- void [set\\_options](#) (bool speculative\_flag, bool vendor\_num\_grad\_flag, bool verbose\_output, const int &verify\_lev, const Real &fn\_prec, const Real &linesrch\_tol, const int &max\_iter, const Real &constr\_tol, const Real &conv\_tol, const [String](#) &grad\_type, const Real &fdss)  
*Sets SOL method options using calls to [npoptm2](#).*

- void `augment_bounds` (`RealVector` &augmented\_l\_bnds, `RealVector` &augmented\_u\_bnds, const `RealVector` &lin\_ineq\_l\_bnds, const `RealVector` &lin\_ineq\_u\_bnds, const `RealVector` &lin\_eq\_targets, const `RealVector` &nln\_ineq\_l\_bnds, const `RealVector` &nln\_ineq\_u\_bnds, const `RealVector` &nln\_eq\_targets)

*augments variable bounds with linear and nonlinear constraint bounds.*

## Static Protected Member Functions

- static void `constraint_eval` (int &mode, int &ncnln, int &n, int &nrowj, int \*needc, double \*x, double \*c, double \*cjac, int &nstate)

*derivatives of the nonlinear constraint functions*

## Protected Attributes

- int `realWorkSpaceSize`  
*size of realWorkSpace*
- int `intWorkSpaceSize`  
*size of intWorkSpace*
- `RealArray` `realWorkSpace`  
*real work space for NPSOL/NLSSOL*
- `IntArray` `intWorkSpace`  
*int work space for NPSOL/NLSSOL*
- int `nlnConstraintArraySize`  
*used for non-zero array sizing (nonlinear constraints)*
- int `linConstraintArraySize`  
*used for non-zero array sizing (linear constraints)*
- `RealArray` `cLambda`  
*CLAMBDA from NPSOL manual: Langrange multipliers.*
- `IntArray` `constraintState`  
*ISTATE from NPSOL manual: constraint status.*
- int `informResult`  
*INFORM from NPSOL manual: optimization status on exit.*
- int `numberIterations`  
*ITER from NPSOL manual: number of (major) iterations performed.*

- int `boundsArraySize`  
*nonlinear constraint bounds)*
- double \* `linConstraintMatrixF77`  
*[A] matrix from NPSOL manual: linear constraint coefficients*
- double \* `upperFactorHessianF77`  
*the Lagrangian.*
- double \* `constraintJacMatrixF77`  
*[CJAC] matrix from NPSOL manual: nonlinear constraint Jacobian*
- int `fnEvalCntr`  
*counter for testing against maxFunctionEvals*
- size\_t `constrOffset`  
*and NPSOLOptimizer::numObjectiveFunctions*

### Static Protected Attributes

- static `SOLBase * solInstance`  
*functions in order to avoid the need for static data*
- static `Minimizer * optLsqInstance`  
*evaluator functions in order to avoid the need for static data*

#### 8.109.1 Detailed Description

Base class for Stanford SOL software.

The `SOLBase` class provides a common base class for `NPSOLOptimizer` and `NLSSOLLeastSq`, both of which are Fortran 77 sequential quadratic programming algorithms from Stanford University marketed by Stanford Business Associates.

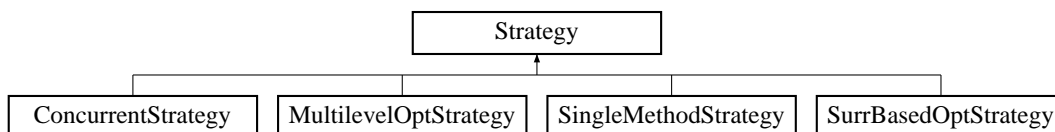
The documentation for this class was generated from the following files:

- `SOLBase.H`
- `SOLBase.C`

## 8.110 Strategy Class Reference

Base class for the strategy class hierarchy.

Inheritance diagram for Strategy::



### Public Member Functions

- [Strategy](#) ()  
*default constructor*
- [Strategy](#) ([ProblemDescDB](#) &problem\_db)  
*envelope constructor*
- [Strategy](#) (const [Strategy](#) &strat)  
*copy constructor*
- virtual [~Strategy](#) ()  
*destructor*
- [Strategy](#) operator= (const [Strategy](#) &strat)  
*assignment operator*
- virtual void [run\\_strategy](#) ()  
*the model(s). Called from main.C.*
- virtual const [Variables](#) & [variables\\_results](#) () const  
*return the final strategy solution (variables)*
- virtual const [Response](#) & [response\\_results](#) () const  
*return the final strategy solution (response)*
- void [run\\_iterator](#) ([Iterator](#) &the\_iterator, [Model](#) &the\_model)  
*due to use by MINLPNode.*
- [ProblemDescDB](#) & [problem\\_description\\_db](#) () const  
*returns the problem description database (probDescDB)*



## Protected Member Functions

- [Strategy](#) ([BaseConstructor](#), [ProblemDescDB](#) &problem\_db)  
*derived class constructors - Coplien, p. 139*
- void [init\\_communicators](#) ([Iterator](#) &the\_iterator, [Model](#) &the\_model)  
*convenience function for allocating comms prior to running an iterator*
- void [free\\_communicators](#) ([Iterator](#) &the\_iterator, [Model](#) &the\_model)  
*convenience function for deallocating comms after running an iterator*
- void [initialize\\_graphics](#) (const [Model](#) &model)  
*data tabulation*

## Protected Attributes

- [ProblemDescDB](#) & [probDescDB](#)  
*class member reference to the problem description database*
- [ParallelLibrary](#) & [parallelLib](#)  
*class member reference to the parallel library*
- [String](#) [strategyName](#)  
*opt\_under\_uncertainty, branch\_and\_bound, multi\_start, or pareto\_set.*
- int [worldRank](#)  
*processor rank in MPI\_COMM\_WORLD*
- int [worldSize](#)  
*size of MPI\_COMM\_WORLD*
- int [iteratorCommRank](#)  
*processor rank in iteratorComm*
- int [iteratorCommSize](#)  
*number of processors in iteratorComm*
- bool [mpirunFlag](#)  
*flag for parallel MPI launch of DAKOTA*
- bool [graphicsFlag](#)  
*flag for using graphics in a graphics executable*
- bool [tabularDataFlag](#)  
*flag for file tabulation of graphics data*

- [String tabularDataFile](#)

*filename for tabulation of graphics data*

## Private Member Functions

- [Strategy \\* get\\_strategy \(\)](#)

*Used by the envelope to instantiate the correct letter class.*

## Private Attributes

- [Strategy \\* strategyRep](#)

*pointer to the letter (initialized only for the envelope)*

- [int referenceCount](#)

*number of objects sharing strategyRep*

## 8.110.1 Detailed Description

Base class for the strategy class hierarchy.

The [Strategy](#) class is the base class for the class hierarchy providing the top level control in DAKOTA. The strategy is responsible for creating and managing iterators and models. For memory efficiency and enhanced polymorphism, the strategy hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Strategy](#)) serves as the envelope and one of the derived classes (selected in [Strategy::get\\_strategy\(\)](#)) serves as the letter.

## 8.110.2 Constructor & Destructor Documentation

### 8.110.2.1 [Strategy \(\)](#)

default constructor

Default constructor. [strategyRep](#) is NULL in this case (a populated [problem\\_db](#) is needed to build a meaningful [Strategy](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

### 8.110.2.2 Strategy (ProblemDescDB & problem\_db)

envelope constructor

Used in `main.C` instantiation to build the envelope. This constructor only needs to extract enough data to properly execute `get_strategy`, since `Strategy::Strategy(BaseConstructor, problem_db)` builds the actual base class data inherited by the derived strategies.

### 8.110.2.3 Strategy (const Strategy & strat)

copy constructor

Copy constructor manages sharing of `strategyRep` and incrementing of `referenceCount`.

### 8.110.2.4 ~Strategy () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `strategyRep` when `referenceCount` reaches zero.

### 8.110.2.5 Strategy (BaseConstructor, ProblemDescDB & problem\_db) [protected]

derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all inherited strategies. `get_strategy()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_strategy()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Strategy`).

## 8.110.3 Member Function Documentation

### 8.110.3.1 Strategy operator= (const Strategy & strat)

assignment operator

Assignment operator decrements `referenceCount` for old `strategyRep`, assigns new `strategyRep`, and increments `referenceCount` for new `strategyRep`.

### 8.110.3.2 void run\_iterator (Iterator & the\_iterator, Model & the\_model)

due to use by `MINLPNode`.

This is a convenience function for encapsulating the parallel features (run/serve) of running an iterator. This function omits allocation/deallocation of communicators to provide greater efficiency in those strategies which involve multiple iterator executions but only require communicator allocation/deallocation to be performed once.

It does not require a strategyRep forward since it is only used by letter objects. While it is currently a public function due to its use in MINLPNode, this usage still involves a strategy letter object.

#### **8.110.3.3** void `init_communicators` (*Iterator & the\_iterator, Model & the\_model*) [protected]

convenience function for allocating comms prior to running an iterator

This is a convenience function for encapsulating the allocation of communicators prior to running an iterator. It does not require a strategyRep forward since it is only used by letter objects.

#### **8.110.3.4** void `free_communicators` (*Iterator & the\_iterator, Model & the\_model*) [protected]

convenience function for deallocating comms after running an iterator

This is a convenience function for encapsulating the deallocation of communicators after running an iterator. It does not require a strategyRep forward since it is only used by letter objects.

#### **8.110.3.5** void `initialize_graphics` (*const Model & model*) [protected]

data tabulation

This is a convenience function for encapsulating graphics initialization operations. It does not require a strategy-Rep forward since it is only used by letter objects.

#### **8.110.3.6** *Strategy* \* `get_strategy` () [private]

Used by the envelope to instantiate the correct letter class.

Used only by the envelope constructor to initialize strategyRep to the appropriate derived type, as given by the strategyName attribute.

The documentation for this class was generated from the following files:

- DakotaStrategy.H
- DakotaStrategy.C

## 8.111 String Class Reference

[Dakota::String](#) class, used as main string class for [Dakota](#).

### Public Member Functions

- [String](#) ()  
*Default constructor.*
- [String](#) (const [String](#) &a)  
*Copy constructor for incoming [String](#).*
- [String](#) (const [String](#) &a, size\_t start\_index, size\_t num\_items)  
*Copy constructor for portion of incoming [String](#).*
- [String](#) (const char \*c\_string)  
*Copy constructor for incoming char\* array.*
- [String](#) (const DAKOTA\_BASE\_STRING &a)  
*Copy constructor for incoming base string.*
- [~String](#) ()  
*Destructor.*
- [String](#) & operator= (const [String](#) &)  
*Assignment operator for incoming [String](#).*
- [String](#) & operator= (const DAKOTA\_BASE\_STRING &)  
*Assignment operator for incoming base string.*
- [String](#) & operator= (const char \*)  
*Assignment operator for incoming char\* array.*
- operator const char \* () const  
*The operator() returns pointer to standard C char array.*
- [String](#) & toUpper ()  
*Convert to upper case string.*
- void upper ()
- [String](#) & toLower ()  
*Convert to lower case string.*

- void `lower ()`
- bool `contains (const char *sub_string) const`  
*Returns true if `String` contains `char* substring`.*
- bool `begins (const char *sub_string) const`  
*Returns true if `String` starts with `char* substring`.*
- bool `ends (const char *sub_string) const`  
*Returns true if `String` ends with `char* substring`.*
- char \* `data () const`  
*Returns pointer to standard C char array.*

### 8.111.1 Detailed Description

`Dakota::String` class, used as main string class for `Dakota`.

The `Dakota::String` class is the common string class for `Dakota`. It provides a common interface for string operations whether inheriting from the STL `basic_string` or the Rogue Wave `RWCString` class

### 8.111.2 Member Function Documentation

#### 8.111.2.1 `operator const char * () const` [inline]

The `operator()` returns pointer to standard C char array.

The `operator ()` returns a pointer to a char string. Uses the STL `c_str()` method. This allows for the `String` to be used in method calls without having to call the `data()` or `c_str()` methods.

#### 8.111.2.2 `void upper ()`

Private method which converts `String` to upper. Utilizes an STL iterator to step through the string and then calls the STL `toupper()` method. Needs to be done this way because STL only provides a single char `toupper` method.

#### 8.111.2.3 `void lower ()`

Private method which converts `String` to lower. Utilizes an STL iterator to step through the string and then calls the STL `tolower()` method. Needs to be done this way because STL only provides a single char `tolower` method.

**8.111.2.4 bool contains (const char \* *sub\_string*) const** [inline]

Returns true if [String](#) contains char\* substring.

Returns true if the [String](#) contains the char\* sub\_string. Uses the STL find() method.

**8.111.2.5 bool begins (const char \* *sub\_string*) const** [inline]

Returns true if [String](#) starts with char\* substring.

Returns true if the [String](#) begins with the char\* sub\_string. Uses the STL compare() method.

**8.111.2.6 bool ends (const char \* *sub\_string*) const** [inline]

Returns true if [String](#) ends with char\* substring.

Returns true if the [String](#) ends with the char\* sub\_string. Uses the STL compare() method.

**8.111.2.7 char \* data () const** [inline]

Returns pointer to standard C char array.

Returns a pointer to C style char array. Needed to mimic the Rogue Wave string class. USE WITH CARE.

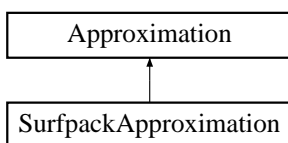
The documentation for this class was generated from the following files:

- DakotaString.H
- DakotaString.C

## 8.112 SurfpackApproximation Class Reference

Interface between Surfpack and Dakota.

Inheritance diagram for SurfpackApproximation::



### Public Member Functions

- [SurfpackApproximation](#) ()  
*default constructor*
- [SurfpackApproximation](#) ([ProblemDescDB](#) &problem\_db, const size\_t &num\_acv)  
*the Dakota/Surfpack boundary*
- [~SurfpackApproximation](#) ()  
*destructor*

### Protected Member Functions

- int [num\\_coefficients](#) () const  
*derived class approximation type in numVars dimensions*
- void [find\\_coefficients](#) ()  
*and the appropriate Surfpack build method will be invoked*
- const Real & [get\\_value](#) (const [RealVector](#) &x)  
*Return the value of the Surfpack surface for a given parameter vector x.*
- const [RealBaseVector](#) & [get\\_gradient](#) (const [RealVector](#) &x)  
*retrieve the approximate function gradient for a given parameter vector x*
- const [RealMatrix](#) & [get\\_hessian](#) (const [RealVector](#) &x)  
*retrieve the approximate function Hessian for a given parameter vector x*



## Private Member Functions

- void [checkForEqualityConstraints](#) ()  
*point, gradient, and/or hessian*
- SurfData \* [surrogates\\_to\\_surf\\_data](#) ()  
*copy from [SurrogateDataPoint](#) to [SurfPoint](#)/[SurfData](#)*

## Private Attributes

- Surface \* [surface](#)  
*The native Surfpack approximation.*
- SurfData \* [surfData](#)  
*The data used to build the approximation, in Surfpack format.*

### 8.112.1 Detailed Description

[Interface](#) between Surfpack and [Dakota](#).

The [SurfpackApproximation](#) class is the interface between [Dakota](#) and Surfpack. Based on the information in the [ProblemDescDB](#) that is passed in through the constructor, [SurfpackApproximation](#) builds a Surfpack Surface object that corresponds to one of the following data-fitting techniques: polynomial regression, kriging, artificial neural networks, radial basis function network, or multivariate adaptive regression splines (MARS).

### 8.112.2 Constructor & Destructor Documentation

#### 8.112.2.1 [SurfpackApproximation](#) ([ProblemDescDB](#) & *problem\_db*, const size\_t & *num\_acv*)

the Dakota/Surfpack boundary

Initialize the embedded Surfpack surface object and configure it using the specifications from the input file. Data for the surface is created later.

#### [Todo](#)

Add RBFNet surface fit interface

### 8.112.3 Member Function Documentation

**8.112.3.1 void find\_coefficients ()** [protected, virtual]

and the appropriate Surfpack build method will be invoked  
surfData will be deleted in dtor

**Todo**

Right now, we're completely deleting the old data and then  
recopying the current data into a SurfData object. This was just  
the easiest way to arrive at a solution that would build and run.  
This function is frequently called from addPoint rebuild, however,  
and it's not good to go through this whole process every time one  
more data point is added.  
Reimplemented from [Approximation](#).

**8.112.3.2 const RealMatrix & get\_hessian (const RealVector & x)** [protected, virtual]

retrieve the approximate function Hessian for a given parameter vector x

**Todo**

Make this acceptably efficient

Reimplemented from [Approximation](#).

**8.112.3.3 void checkForEqualityConstraints ()** [private]

point, gradient, and/or hessian

If there is an anchor point, add an equality constraint for its response value. Also add constraints for gradient and hessian, if applicable.

**Todo**

improve efficiency of conversion

**8.112.3.4 SurfData \* surrogates\_to\_surf\_data ()** [private]

copy from [SurrogateDataPoint](#) to SurfPoint/SurfData

Copy the data stored in Dakota-style [SurrogateDataPoint](#) objects into Surfpack-style SurfPoint and SurfData objects.

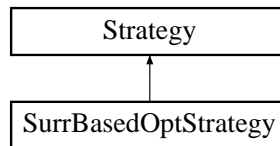
The documentation for this class was generated from the following files:

- SurfpackApproximation.H
- SurfpackApproximation.C

## 8.113 SurrBasedOptStrategy Class Reference

[Strategy](#) for provably-convergent surrogate-based optimization.

Inheritance diagram for SurrBasedOptStrategy::



### Public Member Functions

- [SurrBasedOptStrategy](#) ([ProblemDescDB](#) &problem\_db)  
*constructor*
- [~SurrBasedOptStrategy](#) ()  
*destructor*
- void [run\\_strategy](#) ()  
*global, or hierarchical surrogates over a series of trust regions.*
- const [Variables](#) & [variables\\_results](#) () const  
*return the SBO final solution (variables)*
- const [Response](#) & [response\\_results](#) () const  
*return the SBO final solution (response)*

### Private Member Functions

- void [run\\_surrogate\\_based\\_optimization](#) ()  
*the core SBO algorithm, as called from [run\\_strategy](#)()*
- bool [tr\\_bounds](#) (const [RealVector](#) &global\_lower\_bnds, const [RealVector](#) &global\_upper\_bnds, [RealVector](#) &tr\_lower\_bnds, [RealVector](#) &tr\_upper\_bnds)  
*compute current trust region bounds*
- void [find\\_center\\_truth](#) (const [Iterator](#) &dace\_iterator, [Model](#) &truth\_model)  
*retrieve responseCenterTruth if possible, evaluate it if not*

- void `find_center_approx` ()  
*retrieve responseCenter\_approx if possible, evaluate it if not*
- void `hard_convergence_check` (const `Response` &response\_truth, const `RealVector` &c\_vars, const `RealVector` &lower\_bnds, const `RealVector` &upper\_bnds)  
*merit function near zero)*
- void `tr_ratio_check` (const `RealVector` &c\_vars\_star, const `RealVector` &tr\_lower\_bounds, const `RealVector` &tr\_upper\_bounds)  
*next trust region and check for soft convergence (diminishing returns)*
- void `update_penalty` (const `RealVector` &fns\_center\_truth, const `RealVector` &fns\_star\_truth)  
*initialize and update the penaltyParameter*
- void `update_lagrange_multipliers` (const `RealVector` &fn\_vals, const `RealMatrix` &fn\_grads)  
*initialize and update Lagrange multipliers for basic Lagrangian*
- void `update_augmented_lagrange_multipliers` (const `RealVector` &fn\_vals)  
*initialize and update the Lagrange multipliers for augmented Lagrangian*
- bool `update_filter` (const `RealVector` &fn\_vals)  
*update a filter from a set of function values*
- Real `lagrangian_merit` (const `RealVector` &fn\_vals, const `RealVector` &nln\_ineq\_l\_bnds, const `RealVector` &nln\_ineq\_u\_bnds, const `RealVector` &nln\_eq\_tgts)  
*compute a Lagrangian function from a set of function values*
- void `lagrangian_gradient` (const `RealVector` &fn\_vals, const `RealMatrix` &fn\_grads, const `RealVector` &nln\_ineq\_l\_bnds, const `RealVector` &nln\_ineq\_u\_bnds, const `RealVector` &nln\_eq\_tgts, `RealBaseVector` &lag\_grad)  
*compute the gradient of the Lagrangian function*
- Real `augmented_lagrangian_merit` (const `RealVector` &fn\_vals, const `RealVector` &nln\_ineq\_l\_bnds, const `RealVector` &nln\_ineq\_u\_bnds, const `RealVector` &nln\_eq\_tgts)  
*compute an augmented Lagrangian function from a set of function values*
- void `augmented_lagrangian_gradient` (const `RealVector` &fn\_vals, const `RealMatrix` &fn\_grads, const `RealVector` &nln\_ineq\_l\_bnds, const `RealVector` &nln\_ineq\_u\_bnds, const `RealVector` &nln\_eq\_tgts, `RealBaseVector` &alag\_grad)  
*compute the gradient of the augmented Lagrangian function*
- Real `penalty_merit` (const `RealVector` &fn\_vals)  
*compute a penalty function from a set of function values*
- void `penalty_gradient` (const `RealVector` &fn\_vals, const `RealMatrix` &fn\_grads, `RealBaseVector` &pen\_grad)  
*compute the gradient of the penalty function*

- Real `objective` (const `RealVector` &fn\_vals)  
*compute a composite objective value from one or more objective functions*
- void `objective_gradient` (const `RealMatrix` &fn\_grads, `RealBaseVector` &obj\_grad)  
*compute the gradient of the composite objective function*
- Real `constraint_violation` (const `RealVector` &fn\_vals, const Real &constraint\_tol)  
*compute the constraint violation from a set of function values*
- void `relax_constraints` (const `RealVector` &lower\_bnds, const `RealVector` &upper\_bnds)  
*relax constraints by updating bounds when current iterate is infeasible*

### Static Private Member Functions

- static void `approx_subprob_objective_eval` (const `Variables` &surrogate\_vars, const `Variables` &recast\_vars, const `Response` &surrogate\_response, `Response` &recast\_response)  
*static function used to define the approximate subproblem objective.*
- static void `approx_subprob_constraint_eval` (const `Variables` &surrogate\_vars, const `Variables` &recast\_vars, const `Response` &surrogate\_response, `Response` &recast\_response)  
*static function used to define the approximate subproblem constraints.*
- static void `hom_objective_eval` (int &mode, int &n, double \*tau\_and\_x, double &f, double \*grad\_f, int &)  
*homotopy constraint relaxation formulation.*
- static void `hom_constraint_eval` (int &mode, int &ncnln, int &n, int &nrowj, int \*needc, double \*tau\_and\_x, double \*c, double \*cjac, int &nstate)  
*homotopy constraint relaxation formulation.*

### Private Attributes

- `Model` `surrogateModel`  
*the surrogate model (a `SurrogateModel` object)*
- `Iterator` `selectedIterator`  
*the optimizer used on `surrogateModel`*
- Real `trustRegionFactor`  
*bound - lower bound for each design variable).*
- Real `minTrustRegionFactor`

*factor is reduced below the value of minTrustRegionFactor*

- Real [convergenceTol](#)  
*soft convergence checks*
- Real [constraintTol](#)  
*be a violated constraint.*
- Real [trRatioContractValue](#)  
*trust region ratio min value: contract tr if ratio below this value*
- Real [trRatioExpandValue](#)  
*trust region ratio sufficient value: expand tr if ratio above this value*
- Real [gammaContract](#)  
*trust region contraction factor*
- Real [gammaExpand](#)  
*trust region expansion factor*
- Real [gammaNoChange](#)  
*factor for maintaining the current trust region size (normally 1.0)*
- short [approxSubProbObj](#)  
*or AUGMENTED\_LAGRANGIAN\_OBJ*
- short [approxSubProbCon](#)  
*ORIGINAL\_CON.*
- [Model approxSubProbModel](#)  
*envelope object used to keep [RecastModel](#) instance in scope*
- short [trConstraintRelax](#)  
*points: NO\_RELAX or HOMOTOPY*
- short [meritFnType](#)  
*ADAPTIVE\_PENALTY\_MERIT, LAGRANGIAN\_MERIT, or AUGMENTED\_LAGRANGIAN\_MERIT.*
- short [acceptLogic](#)  
*type of iterate acceptance test logic: FILTER or TR\_RATIO*
- [RealVectorList sboFilter](#)  
*constraint violation) for iterate selection/rejection*
- [RealVector lagrangeMult](#)  
*Lagrange multipliers for basic Lagrangian calculations.*

- [RealVector augLagrangeMult](#)  
*Lagrange multipliers for augmented Lagrangian calculations.*
- [Real penaltyParameter](#)  
*penalty calculations; increased in `update_penalty()`*
- [int penaltyIterOffset](#)  
*for `adaptive_penalty` merit functions*
- [Real eta](#)  
*constant used in `etaSequence` updates*
- [Real alphaEta](#)  
*power for `etaSequence` updates when updating penalty*
- [Real betaEta](#)  
*power for `etaSequence` updates when updating multipliers*
- [Real etaSequence](#)  
*Lagrangian updates (refer to Conn, Gould, and Toint, section 14.4).*
- [int sboIterNum](#)  
*SBO iteration number.*
- [int sboIterMax](#)  
*maximum number of SBO iterations*
- [short convergenceFlag](#)  
*code indicating satisfaction of hard or soft convergence conditions*
- [size\\_t numFns](#)  
*number of response functions*
- [size\\_t numVars](#)  
*number of active continuous variables*
- [short softConvCount](#)  
*count reaches `softConvLimit`, stop SBO.*
- [short softConvLimit](#)  
*exceeded by `softConvCount`, stop SBO.*
- [bool truthGradientFlag](#)  
*flags the use/availability of truth gradients within the SBO process*



- bool [approxGradientFlag](#)  
*flags the use/availability of surrogate gradients within the SBO process*
- bool [truthHessianFlag](#)  
*flags the use/availability of truth Hessians within the SBO process*
- bool [approxHessianFlag](#)  
*flags the use/availability of surrogate Hessians within the SBO process*
- bool [correctionFlag](#)  
*of each trust region*
- bool [globalApproxFlag](#)  
*flags the use of a global data fit surrogate (rsm, ann, mars, kriging)*
- bool [multiptApproxFlag](#)  
*flags the use of a multipoint data fit surrogate (TANA)*
- bool [localApproxFlag](#)  
*flags the use of a local data fit surrogate (Taylor series)*
- bool [hierarchApproxFlag](#)  
*flags the use of a model hierarchy/multifidelity surrogate*
- bool [newCenterFlag](#)  
*a new trust region center*
- bool [daceCenterPtFlag](#)  
*evaluations for global approximations (CCD, Box-Behnken)*
- bool [multiLayerBypassFlag](#)  
*(responseCenterTruth and responseStarTruth).*
- bool [useGradsFlag](#)  
*to be evaluated for each DACE point in global surrogate builds.*
- size\_t [numObjFns](#)  
*number of objective functions*
- size\_t [numNonlinIneqConstr](#)  
*number of nonlinear inequality constraints*
- size\_t [numNonlinEqConstr](#)  
*number of nonlinear equality constraints*
- [RealVector](#) [multiObjWts](#)

*vector of multiobjective weights.*

- [RealVector origNonlinIneqLowerBnds](#)  
*original nonlinear inequality constraint lower bounds (no relaxation)*
- [RealVector origNonlinIneqUpperBnds](#)  
*original nonlinear inequality constraint upper bounds (no relaxation)*
- [RealVector origNonlinEqTargets](#)  
*original nonlinear equality constraint targets (no relaxation)*
- [Real bigRealBoundSize](#)  
*cutoff value for continuous bounds*
- [RealVector nonlinIneqLowerBndsSlack](#)  
*individual violations of nonlinear inequality constraint lower bounds*
- [RealVector nonlinIneqUpperBndsSlack](#)  
*individual violations of nonlinear inequality constraint upper bounds*
- [RealVector nonlinEqTargetsSlack](#)  
*individual violations of nonlinear equality constraint targets*
- [Real tau](#)  
*constraint relaxation parameter*
- [Real alpha](#)  
*constraint relaxation parameter backoff parameter (multiplier)*
- [Variables varsCenter](#)  
*variables at the trust region center*
- [Response responseCenterApprox](#)  
*approx response at trust region center*
- [Response responseStarApprox](#)  
*approx response at SBO cycle optimum*
- [Response responseCenterTruth](#)  
*truth response at trust region center*
- [Response responseStarTruth](#)  
*truth response at SBO cycle optimum*
- [Variables bestVariables](#)  
*best variables found in SBO*

- [Response bestResponses](#)

*best responses found in SBO*

## Static Private Attributes

- static [SurrBasedOptStrategy \\* sboInstance](#)

*pointer to SBO strategy used in static member functions*

### 8.113.1 Detailed Description

[Strategy](#) for provably-convergent surrogate-based optimization.

This strategy uses a [SurrogateModel](#) to perform optimization based on local, global, or hierarchical surrogates. It achieves provable convergence through the use of a sequence of trust regions and the application of surrogate corrections at the trust region centers.

### 8.113.2 Member Function Documentation

#### 8.113.2.1 void run\_strategy() [virtual]

global, or hierarchical surrogates over a series of trust regions.

Trust region-based strategy to perform surrogate-based optimization in subregions (trust regions) of the parameter space. The optimizer operates on approximations in lieu of the more expensive simulation-based response functions. The size of the trust region is varied according to the goodness of the agreement between the approximations and the true response functions.

Reimplemented from [Strategy](#).

#### 8.113.2.2 void hard\_convergence\_check (const [Response](#) & response\_truth, const [RealVector](#) & c\_vars, const [RealVector](#) & lower\_bnds, const [RealVector](#) & upper\_bnds) [private]

merit function near zero)

The hard convergence check computes the gradient of the merit function at the trust region center, performs a projection for active bound constraints (removing any gradient component directed into an active bound), and signals convergence if the 2-norm of this projected gradient is less than convergenceTol.

#### 8.113.2.3 void tr\_ratio\_check (const [RealVector](#) & c\_vars\_star, const [RealVector](#) & tr\_lower\_bounds, const [RealVector](#) & tr\_upper\_bounds) [private]

next trust region and check for soft convergence (diminishing returns)

Assess acceptance of SBO iterate (trust region ratio or filter) and compute soft convergence metrics (number of consecutive failures, min trust region size, etc.) to assess whether the convergence rate has decreased to a point where the process should be terminated (diminishing returns).

**8.113.2.4 void update\_penalty (const RealVector & *fns\_center\_truth*, const RealVector & *fns\_star\_truth*)**  
[private]

initialize and update the penaltyParameter

Scaling of the penalty value is important to avoid rejecting SBO iterates which must increase the objective to achieve a reduction in constraint violation. In the basic penalty case, the penalty is ramped exponentially based on the iteration counter. In the adaptive case, the ratio of relative change between center and star points for the objective and constraint violation values is used to rescale penalty values.

**8.113.2.5 void update\_lagrange\_multipliers (const RealVector & *fn\_vals*, const RealMatrix & *fn\_grads*)**  
[private]

initialize and update Lagrange multipliers for basic Lagrangian

For the Rockafellar augmented Lagrangian, simple Lagrange multiplier updates are available which do not require the active constraint gradients. For the basic Lagrangian, Lagrange multipliers are estimated through solution of a nonnegative linear least squares problem.

**8.113.2.6 void update\_augmented\_lagrange\_multipliers (const RealVector & *fn\_vals*)** [private]

initialize and update the Lagrange multipliers for augmented Lagrangian

For the Rockafellar augmented Lagrangian, simple Lagrange multiplier updates are available which do not require the active constraint gradients. For the basic Lagrangian, Lagrange multipliers are estimated through solution of a nonnegative linear least squares problem.

**8.113.2.7 bool update\_filter (const RealVector & *fn\_vals*)** [private]

update a filter from a set of function values

Update the sboFilter with *fn\_vals* if new iterate is non-dominated.

**8.113.2.8 Real lagrangian\_merit (const RealVector & *fn\_vals*, const RealVector & *nln\_ineq\_l\_bnds*, const RealVector & *nln\_ineq\_u\_bnds*, const RealVector & *nln\_eq\_tgts*)** [private]

compute a Lagrangian function from a set of function values

The Lagrangian function computation sums the objective function and the Lagrange multiplier terms for inequality/equality constraints. This implementation follows the convention in Vanderplaats with  $g \leq 0$  and  $h = 0$ . The bounds/targets passed in may reflect the original constraints or the relaxed constraints.

**8.113.2.9 Real augmented\_lagrangian\_merit** (const [RealVector](#) & *fn\_vals*, const [RealVector](#) & *nln\_ineq\_l\_bnds*, const [RealVector](#) & *nln\_ineq\_u\_bnds*, const [RealVector](#) & *nln\_eq\_tgts*) [private]

compute an augmented Lagrangian function from a set of function values

The Rockafellar augmented Lagrangian function sums the objective function, Lagrange multiplier terms for inequality/equality constraints, and quadratic penalty terms for inequality/equality constraints. This implementation follows the convention in Vanderplaats with  $g \leq 0$  and  $h = 0$ . The bounds/targets passed in may reflect the original constraints or the relaxed constraints.

**8.113.2.10 Real penalty\_merit** (const [RealVector](#) & *fn\_vals*) [private]

compute a penalty function from a set of function values

The penalty function computation applies a quadratic penalty to any constraint violations and adds this to the objective function(s)  $p = f + r_p cv$ .

**8.113.2.11 Real objective** (const [RealVector](#) & *fn\_vals*) [private]

compute a composite objective value from one or more objective functions

The composite objective computation sums up the contributions from one of more objective functions using the multiobjective weights.

**8.113.2.12 void objective\_gradient** (const [RealMatrix](#) & *fn\_grads*, [RealBaseVector](#) & *obj\_grad*) [private]

compute the gradient of the composite objective function

The composite objective gradient computation sums up the contributions from one of more objective function gradients using the multiobjective weights.

**8.113.2.13 Real constraint\_violation** (const [RealVector](#) & *fn\_vals*, const [Real](#) & *constraint\_tol*) [private]

compute the constraint violation from a set of function values

Compute the quadratic constraint violation defined as  $cv = g + ^T g + h + ^T h$ . This implementation supports equality constraints and 2-sided inequalities. The *constraint\_tol* allows for a small constraint infeasibility (used for penalty methods, but not Lagrangian methods).

**8.113.2.14 void approx\_subprob\_objective\_eval** (const [Variables](#) & *surrogate\_vars*, const [Variables](#) & *recast\_vars*, const [Response](#) & *surrogate\_response*, [Response](#) & *recast\_response*) [static, private]

static function used to define the approximate subproblem objective.

Objective functions evaluator for solution of approximate subproblem using a [RecastModel](#).

**8.113.2.15** void `approx_subprob_constraint_eval` (const [Variables](#) & `surrogate_vars`, const [Variables](#) & `recast_vars`, const [Response](#) & `surrogate_response`, [Response](#) & `recast_response`) [`static`, `private`]

static function used to define the approximate subproblem constraints.

Constraint functions evaluator for solution of approximate subproblem using a [RecastModel](#).

**8.113.2.16** void `hom_objective_eval` (int & `mode`, int & `n`, double \* `tau_and_x`, double & `f`, double \* `grad_f`, int &) [`static`, `private`]

homotopy constraint relaxation formulation.

NPSOL objective functions evaluator for solution of homotopy constraint relaxation parameter optimization. This constrained optimization problem performs the update of the tau parameter in the homotopy heuristic approach used to relax the constraints in the original problem .

**8.113.2.17** void `hom_constraint_eval` (int & `mode`, int & `ncnln`, int & `n`, int & `nrowj`, int \* `needc`, double \* `tau_and_x`, double \* `c`, double \* `cjac`, int & `nstate`) [`static`, `private`]

homotopy constraint relaxation formulation.

NPSOL constraint functions evaluator for solution of homotopy constraint relaxation parameter optimization. This constrained optimization problem performs the update of the tau parameter in the homotopy heuristic approach used to relax the constraints in the original problem.

The documentation for this class was generated from the following files:

- `SurrBasedOptStrategy.H`
- `SurrBasedOptStrategy.C`

## 8.114 SurrogateDataPoint Class Reference

for defining a "truth" data point.

### Public Member Functions

- [SurrogateDataPoint \(\)](#)  
*default constructor*
- [SurrogateDataPoint \(const RealVector &x, const Real &fn\\_val, const RealBaseVector &fn\\_grad, const RealMatrix &fn\\_hess\)](#)  
*standard constructor*
- [SurrogateDataPoint \(const SurrogateDataPoint &sdp\)](#)  
*copy constructor*
- [~SurrogateDataPoint \(\)](#)  
*destructor*
- [SurrogateDataPoint & operator= \(const SurrogateDataPoint &sdp\)](#)  
*assignment operator*
- [bool operator== \(const SurrogateDataPoint &sdp\) const](#)  
*equality operator*
- [const RealVector & continuous\\_variables \(\) const](#)  
*return continuousVars*
- [const Real & response\\_function \(\) const](#)  
*return responseFn*
- [const RealBaseVector & response\\_gradient \(\) const](#)  
*return responseGrad*
- [const RealMatrix & response\\_hessian \(\) const](#)  
*return responseHess*
- [bool is\\_null \(\) const](#)  
*function to check sdpRep (does this handle contain a body)*

## Private Attributes

- [SurrogateDataPointRep](#) \* `sdpRep`  
*pointer to the body (handle-body idiom)*

### 8.114.1 Detailed Description

for defining a "truth" data point.

A list of these data points is contained in each [Approximation](#) instance ([Approximation::currentPoints](#)) and provides the data to build the approximation. A handle-body idiom is used to avoid excessive data copying overhead.

The documentation for this class was generated from the following file:

- `DakotaApproximation.H`



## 8.115 SurrogateDataPointRep Class Reference

or body, may be shared by multiple [SurrogateDataPoint](#) handle instances.

### Private Member Functions

- [SurrogateDataPointRep](#) (const [RealVector](#) &x, const Real &fn\_val, const [RealBaseVector](#) &fn\_grad, const [RealMatrix](#) &fn\_hess)  
*constructor*
- [~SurrogateDataPointRep](#) ()  
*destructor*

### Private Attributes

- [RealVector](#) `continuousVars`  
*continuous variables*
- Real `responseFn`  
*truth response function value*
- [RealBaseVector](#) `responseGrad`  
*truth response function gradient*
- [RealMatrix](#) `responseHess`  
*truth response function Hessian*
- int `referenceCount`  
*number of handle objects sharing sdpRep*

### Friends

- class [SurrogateDataPoint](#)  
*the handle class can access attributes of the body class directly*

### 8.115.1 Detailed Description

or body, may be shared by multiple [SurrogateDataPoint](#) handle instances.

The SurrogateDataPoint/SurrogateDataPointRep pairs utilize a handle-body idiom (Coplien, Advanced C++).

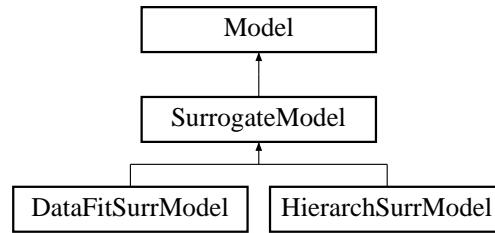
The documentation for this class was generated from the following file:

- DakotaApproximation.H

## 8.116 SurrogateModel Class Reference

Base class for surrogate models ([DataFitSurrModel](#) and [HierarchSurrModel](#)).

Inheritance diagram for SurrogateModel::



### Protected Member Functions

- [SurrogateModel](#) ([ProblemDescDB](#) &problem\_db)  
*constructor*
- [SurrogateModel](#) (const pair< short, short > &view, const [ActiveSet](#) &set, const [String](#) &corr\_type, const short &corr\_order)  
*alternate constructor*
- [~SurrogateModel](#) ()  
*destructor*
- void [compute\\_correction](#) (const [Response](#) &truth\_response, const [Response](#) &approx\_response, const [RealVector](#) &c\_vars)  
*agreement with truth\_response*
- void [apply\\_correction](#) ([Response](#) &approx\_response, const [RealVector](#) &c\_vars, bool quiet\_flag=false)  
*apply the correction computed in [compute\\_correction\(\)](#) to approx\_response*
- void [auto\\_correction](#) (bool correction\_flag)  
*sets autoCorrection to on (true) or off (false)*
- bool [auto\\_correction](#) ()  
*returns autoCorrection setting*
- void [check\\_submodel\\_compatibility](#) (const [Model](#) &sub\_model)  
*[HierarchSurrModel::highFidelityModel](#)).*
- bool [force\\_rebuild](#) ()

*forced based on changes in the inactive data*

- void `asv_mapping` (const `ShortArray` &orig\_asv, `ShortArray` &actual\_asv, `ShortArray` &approx\_asv, bool build\_flag)  
*distributes the incoming orig\_asv among actual\_asv and approx\_asv*
- void `asv_mapping` (const `ShortArray` &actual\_asv, const `ShortArray` &approx\_asv, `ShortArray` &combined\_asv)  
*reconstitutes a combined\_asv from actual\_asv and approx\_asv*
- void `response_mapping` (const `Response` &actual\_response, const `Response` &approx\_response, `Response` &combined\_response)  
*overlays actual\_response and approx\_response to update combined\_response*
- void `cached_mapping` (const `ResponseArray` &orig\_resp\_array, `IntResponseMap` &cached\_map, const `Int-IntMap` &id\_map, `ResponseArray` &merged\_array)  
*inserts a cached response map into a response array in order*

## Protected Attributes

- bool `mixedResponseSet`  
*flag for mixed approximate/actual responses*
- `IntSet` `surrogateFnIndices`  
*subset that is approximated*
- `ResponseArray` `surrResponseArray`  
*array of surrogate responses used in `derived_synchronize()` functions*
- `IntResponseMap` `surrResponseMap`  
*map of surrogate responses used in `derived_synchronize_nowait()` functions*
- `IntRealVectorMap` `rawCVarsMap`  
*not contain lower level variables sets from finite differencing.*
- `IntIntMap` `truthIdMap`  
*DataFitSurrModel/HierarchSurrModel id.*
- `IntIntMap` `surrIdMap`  
*DataFitSurrModel/HierarchSurrModel ids.*
- `IntResponseMap` `cachedApproxRespMap`  
*portions were still pending.*
- `String` `correctionType`

*approximation correction approach to be used: additive or multiplicative*

- short `correctionOrder`  
*approximation correction order to be used: 0, 1, or 2*
- bool `autoCorrection`  
*and `HierarchSurrModel` approximate response computations*
- bool `correctionComputed`  
*and is available for application*
- size\_t `approxBuilds`  
*number of calls to `build_approximation()`*
- bool `surrogateBypass`  
*on the underlying truth model.*
- `RealVector` `fitCLBnds`  
*the approximation is built; used to detect when a rebuild is required.*
- `RealVector` `fitCUBnds`  
*the approximation is built; used to detect when a rebuild is required.*
- `IntVector` `fitDLBnds`  
*the approximation is built; used to detect when a rebuild is required.*
- `IntVector` `fitDUBnds`  
*the approximation is built; used to detect when a rebuild is required.*
- `RealVector` `fitInactCVars`  
*rebuild is required.*
- `IntVector` `fitInactDVars`  
*rebuild is required.*

## Private Member Functions

- void `apply_additive_correction` (`RealVector` &alpha\_corrected\_fns, `RealMatrix` &alpha\_corrected\_grads, `RealMatrixArray` &alpha\_corrected\_hessians, const `RealVector` &c\_vars, const `ActiveSet` &set)  
*internal convenience function for applying additive corrections*
- void `apply_multiplicative_correction` (`RealVector` &beta\_corrected\_fns, `RealMatrix` &beta\_corrected\_grads, `RealMatrixArray` &beta\_corrected\_hessians, const `RealVector` &c\_vars, const `ActiveSet` &set)  
*internal convenience function for applying multiplicative corrections*

## Private Attributes

- bool `badScalingFlag`  
*corrections; triggers an automatic switch to additive corrections*
- bool `combinedFlag`  
*flag indicating the combination of additive/multiplicative corrections*
- bool `computeAdditive`  
*flag indicating the need for additive correction calculations*
- bool `computeMultiplicative`  
*flag indicating the need for multiplicative correction calculations*
- `RealVector` `addCorrFns`  
*high and low fidelity model values at  $x=x\_center$ .*
- `RealMatrix` `addCorrGrads`  
*high/low function difference at  $x=x\_center$ .*
- `RealMatrixArray` `addCorrHessians`  
*high/low function difference at  $x=x\_center$ .*
- `RealVector` `multCorrFns`  
*high fidelity to low fidelity model values at  $x=x\_center$ .*
- `RealMatrix` `multCorrGrads`  
*of the high/low function ratio at  $x=x\_center$ .*
- `RealMatrixArray` `multCorrHessians`  
*of the high/low function ratio at  $x=x\_center$ .*
- `RealVector` `combineFactors`  
*correction instead of a strictly local correction.*
- `RealVector` `correctionCenterPt`  
 *$(x - x\_c)$  terms in 1st-/2nd-order corrections.*
- `RealVector` `correctionPrevCenterPt`  
*copy of `correctionCenterPt` from the previous correction cycle*
- `RealVector` `approxFnsCenter`  
*unavailable when applying 1st-/2nd-order multiplicative corrections.*
- `RealVector` `approxFnsPrevCenter`  
*copy of `approxFnsCenter` from the previous correction cycle*

- [RealMatrix approxGradsCenter](#)  
*unavailable when applying 1st-/2nd-order multiplicative corrections.*
- [RealVector truthFnsCenter](#)  
*Truth function values at the current correction point.*
- [RealVector truthFnsPrevCenter](#)  
*copy of truthFnsCenter from the previous correction cycle*
- [Variables subModelVars](#)  
*among differing variable views in `force_rebuild()`*
- [Constraints subModelCons](#)  
*among differing variable views in `force_rebuild()`*

### 8.116.1 Detailed Description

Base class for surrogate models ([DataFitSurrModel](#) and [HierarchSurrModel](#)).

The [SurrogateModel](#) class provides common functions to derived classes for computing and applying corrections to approximations.

### 8.116.2 Member Function Documentation

#### 8.116.2.1 void compute\_correction (const [Response](#) & *truth\_response*, const [Response](#) & *approx\_response*, const [RealVector](#) & *c\_vars*) [`protected`, `virtual`]

agreement with *truth\_response*

Compute an additive or multiplicative correction that corrects the *approx\_response* to have 0th-order consistency (matches values), 1st-order consistency (matches values and gradients), or 2nd-order consistency (matches values, gradients, and Hessians) with the *truth\_response* at a single point (e.g., the center of a trust region). The 0th-order, 1st-order, and 2nd-order corrections use scalar values, linear scaling functions, and quadratic scaling functions, respectively, for each response function.

Reimplemented from [Model](#).

#### 8.116.2.2 bool force\_rebuild () [`protected`]

forced based on changes in the inactive data

This function forces a rebuild of the approximation according to the sub-model variables view, the approximation type, and whether the active approximation bounds or inactive variable values have changed since the last approximation build.

### 8.116.3 Member Data Documentation

#### 8.116.3.1 `bool autoCorrection` [protected]

and `HierarchSurrModel` approximate response computations

`SurrBasedOptStrategy` must toggle this value since `compute_correction()` no longer automatically backs out an old correction.

#### 8.116.3.2 `size_t approxBuilds` [protected]

number of calls to `build_approximation()`

used as a flag to automatically build the approximation if one of the derived `compute_response` functions is called prior to `build_approximation()`.

The documentation for this class was generated from the following files:

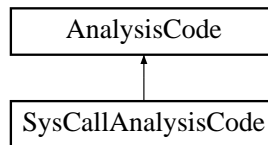
- `SurrogateModel.H`
- `SurrogateModel.C`



## 8.117 SysCallAnalysisCode Class Reference

simulations using system calls.

Inheritance diagram for SysCallAnalysisCode::



### Public Member Functions

- [SysCallAnalysisCode](#) (const [ProblemDescDB](#) &problem\_db)  
*constructor*
- [~SysCallAnalysisCode](#) ()  
*destructor*
- void [spawn\\_evaluation](#) (const bool block\_flag)  
*spawn a complete function evaluation*
- void [spawn\\_input\\_filter](#) (const bool block\_flag)  
*spawn the input filter portion of a function evaluation*
- void [spawn\\_analysis](#) (const int &analysis\_id, const bool block\_flag)  
*spawn a single analysis as part of a function evaluation*
- void [spawn\\_output\\_filter](#) (const bool block\_flag)  
*spawn the output filter portion of a function evaluation*
- const [String](#) & [command\\_usage](#) () const  
*return commandUsage*

### Private Attributes

- [String](#) [commandUsage](#)  
*command syntax (supported only by SysCall analysis codes)*

### 8.117.1 Detailed Description

simulations using system calls.

[SysCallAnalysisCode](#) creates separate simulation processes using the C `system()` command. It utilizes [CommandShell](#) to manage shell syntax and asynchronous invocations.

### 8.117.2 Member Function Documentation

#### 8.117.2.1 `void spawn_evaluation (const bool block_flag)`

spawn a complete function evaluation

Put the [SysCallAnalysisCode](#) to the shell using either the default syntax or specified `commandUsage` syntax. This function is used when all portions of the function evaluation (i.e., all analysis drivers) are executed on the local processor.

#### 8.117.2.2 `void spawn_input_filter (const bool block_flag)`

spawn the input filter portion of a function evaluation

Put the input filter to the shell. This function is used when multiple analysis drivers are spread between processors. No need to check for a Null input filter, as this is checked externally. Use of nonblocking shells is supported in this fn, although its use is currently prevented externally.

#### 8.117.2.3 `void spawn_analysis (const int & analysis_id, const bool block_flag)`

spawn a single analysis as part of a function evaluation

Put a single analysis to the shell using the default syntax (no `commandUsage` support for analyses). This function is used when multiple analysis drivers are spread between processors. Use of nonblocking shells is supported in this fn, although its use is currently prevented externally.

#### 8.117.2.4 `void spawn_output_filter (const bool block_flag)`

spawn the output filter portion of a function evaluation

Put the output filter to the shell. This function is used when multiple analysis drivers are spread between processors. No need to check for a Null output filter, as this is checked externally. Use of nonblocking shells is supported in this fn, although its use is currently prevented externally.

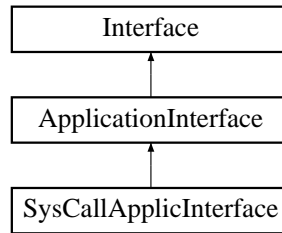
The documentation for this class was generated from the following files:

- `SysCallAnalysisCode.H`
- `SysCallAnalysisCode.C`

## 8.118 SysCallApplicInterface Class Reference

using system calls.

Inheritance diagram for SysCallApplicInterface::



### Public Member Functions

- [SysCallApplicInterface](#) (const [ProblemDescDB](#) &problem\_db)  
*constructor*
- [~SysCallApplicInterface](#) ()  
*destructor*
- void [derived\\_map](#) (const [Variables](#) &vars, const [ActiveSet](#) &set, [Response](#) &response, int fn\_eval\_id)  
*that is specific to a derived class.*
- void [derived\\_map\\_asynch](#) (const [ParamResponsePair](#) &pair)  
*asynchronous evaluation that is specific to a derived class.*
- void [derived\\_synch](#) ([PRPList](#) &prp\_list)
- void [derived\\_synch\\_nowait](#) ([PRPList](#) &prp\_list)
- int [derived\\_synchronous\\_local\\_analysis](#) (const int &analysis\_id)
- const [StringArray](#) & [analysis\\_drivers](#) () const  
*retrieve the analysis drivers specification for application interfaces*

### Private Member Functions

- void [spawn\\_application](#) (const bool block\_flag)  
*and output filter. Called from [derived\\_map\(\)](#) & [derived\\_map\\_asynch\(\)](#).*
- void [derived\\_synch\\_kernel](#) ([PRPList](#) &prp\_list)  
*[derived\\_synch\\_nowait\(\)](#)*

- bool `system_call_file_test` (const `String` &root\_file)  
*the necessary results file(s)*

## Private Attributes

- `SysCallAnalysisCode` `sysCallSimulator`  
*to a `CommandShell` in various combinations*
- `IntSet` `sysCallSet`  
*system call evaluations*
- `IntShortMap` `failCountMap`  
*map linking function evaluation id's to number of response read failures*

### 8.118.1 Detailed Description

using system calls.

`SysCallApplicInterface` uses a `SysCallAnalysisCode` object for performing simulation invocations.

### 8.118.2 Member Function Documentation

#### 8.118.2.1 void `derived_synch` (`PRPList` & `prp_list`) [inline, virtual]

Check for completion of active asynch jobs (tracked with `sysCallSet`). Wait for at least one completion and complete all jobs that have returned. This satisfies a "fairness" principle, in the sense that a completed job will `_always_` be processed (whereas accepting only a single completion could always accept the same completion - the case of very inexpensive fn. evals. - and starve some servers).

Reimplemented from `ApplicationInterface`.

#### 8.118.2.2 void `derived_synch_nowait` (`PRPList` & `prp_list`) [inline, virtual]

Check for completion of active asynch jobs (tracked with `sysCallSet`). Make one pass through `sysCallSet` & complete all jobs that have returned.

Reimplemented from `ApplicationInterface`.

**8.118.2.3** `int derived_synchronous_local_analysis(const int & analysis_id)` [inline, virtual]

This code provides the derived function used by [ApplicationInterface::serve\\_analyses\\_synch\(\)](#).

Reimplemented from [ApplicationInterface](#).

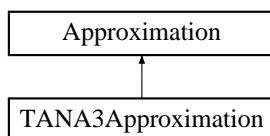
The documentation for this class was generated from the following files:

- SysCallApplicInterface.H
- SysCallApplicInterface.C

## 8.119 TANA3Approximation Class Reference

approximation (a multipoint approximation).

Inheritance diagram for TANA3Approximation::



### Public Member Functions

- [TANA3Approximation \(\)](#)  
*default constructor*
- [TANA3Approximation \(ProblemDescDB &problem\\_db, const size\\_t &num\\_vars\)](#)  
*standard constructor*
- [~TANA3Approximation \(\)](#)  
*destructor*

### Protected Member Functions

- int [num\\_coefficients \(\)](#) const  
*derived class approximation type in numVars dimensions*
- int [num\\_constraints \(\)](#) const  
*return the number of constraints to be enforced via anchorPoint*
- void [find\\_coefficients \(\)](#)  
*calculate the data fit coefficients using currentPoints and anchorPoint*
- const Real & [get\\_value](#) (const [RealVector](#) &x)  
*retrieve the approximate function value for a given parameter vector*
- const [RealBaseVector](#) & [get\\_gradient](#) (const [RealVector](#) &x)  
*retrieve the approximate function gradient for a given parameter vector*
- void [clear\\_current \(\)](#)

## Private Member Functions

- void [find\\_scaled\\_coefficients](#) ()  
*compute TANA coefficients based on scaled inputs*
- void [offset](#) (const [RealVector](#) &x, [RealVector](#) &s)  
*based on minX, apply offset scaling to x to define s*

## Private Attributes

- [RealVector](#) pExp  
*the vector of exponent values*
- [RealVector](#) minX  
*the vector of minimum parameter values used in scaling*
- [RealVector](#) scX1  
*the vector of scaled x1 values*
- [RealVector](#) scX2  
*the vector of scaled x2 values*
- [Real](#) H  
*the scalar Hessian value in the TANA-3 approximation*

### 8.119.1 Detailed Description

approximation (a multipoint approximation).

The [TANA3Approximation](#) class provides a multipoint approximation based on matching value and gradient data from two points (typically the current and previous iterates) in parameter space. It forms an exponential approximation in terms of intervening variables.

### 8.119.2 Member Function Documentation

#### 8.119.2.1 void [clear\\_current](#) () [inline, protected, virtual]

Redefine default implementation to support history mechanism.

Reimplemented from [Approximation](#).

The documentation for this class was generated from the following files:

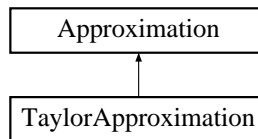
- TANA3Approximation.H
- TANA3Approximation.C



## 8.120 TaylorApproximation Class Reference

series (a local approximation).

Inheritance diagram for TaylorApproximation::



### Public Member Functions

- [TaylorApproximation \(\)](#)  
*default constructor*
- [TaylorApproximation \(ProblemDescDB &problem\\_db, const size\\_t &num\\_vars\)](#)  
*standard constructor*
- [~TaylorApproximation \(\)](#)  
*destructor*

### Protected Member Functions

- `int num_coefficients () const`  
*derived class approximation type in numVars dimensions*
- `void find_coefficients ()`  
*calculate the data fit coefficients using currentPoints and anchorPoint*
- `const Real & get_value (const RealVector &x)`  
*retrieve the approximate function value for a given parameter vector*
- `const RealBaseVector & get_gradient (const RealVector &x)`  
*retrieve the approximate function gradient for a given parameter vector*
- `const RealMatrix & get_hessian (const RealVector &x)`  
*retrieve the approximate function Hessian for a given parameter vector*

### 8.120.1 Detailed Description

series (a local approximation).

The [TaylorApproximation](#) class provides a local approximation based on data from a single point in parameter space. It uses a first- or second-order Taylor series expansion:  $f(x) = f(x_c) + \text{grad}(x_c)' (x - x_c) + (x - x_c)' \text{Hess}(x_c) (x - x_c) / 2$ .

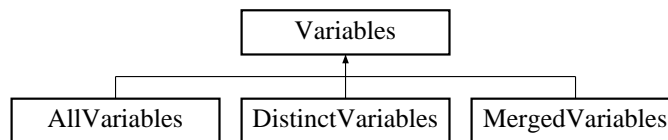
The documentation for this class was generated from the following files:

- TaylorApproximation.H
- TaylorApproximation.C

## 8.121 Variables Class Reference

Base class for the variables class hierarchy.

Inheritance diagram for Variables::



### Public Member Functions

- [Variables](#) ()  
*default constructor*
- [Variables](#) (const [ProblemDescDB](#) &problem\_db)  
*standard constructor*
- [Variables](#) (const pair< short, short > &view)  
*alternate constructor for instantiations on the fly*
- [Variables](#) (const [Variables](#) &vars)  
*copy constructor*
- virtual [~Variables](#) ()  
*destructor*
- [Variables](#) operator= (const [Variables](#) &vars)  
*assignment operator*
- virtual size\_t [tv](#) () const  
*Returns total number of vars.*
- virtual const [IntArray](#) & [merged\\_discrete\\_ids](#) () const  
*returns the list of discrete variables merged into a continuous array*
- virtual const [RealVector](#) & [continuous\\_variables](#) () const  
*return the active continuous variables*
- virtual void [continuous\\_variables](#) (const [RealVector](#) &c\_vars)  
*set the active continuous variables*

- virtual const [IntVector](#) & [discrete\\_variables](#) () const  
*return the active discrete variables*
- virtual void [discrete\\_variables](#) (const [IntVector](#) &d\_vars)  
*set the active discrete variables*
- virtual const [StringArray](#) & [continuous\\_variable\\_labels](#) () const  
*return the active continuous variable labels*
- virtual void [continuous\\_variable\\_labels](#) (const [StringArray](#) &cv\_labels)  
*set the active continuous variable labels*
- virtual const [StringArray](#) & [discrete\\_variable\\_labels](#) () const  
*return the active discrete variable labels*
- virtual void [discrete\\_variable\\_labels](#) (const [StringArray](#) &dv\_labels)  
*set the active discrete variable labels*
- virtual const [RealVector](#) & [inactive\\_continuous\\_variables](#) () const  
*return the inactive continuous variables*
- virtual void [inactive\\_continuous\\_variables](#) (const [RealVector](#) &i\_c\_vars)  
*set the inactive continuous variables*
- virtual const [IntVector](#) & [inactive\\_discrete\\_variables](#) () const  
*return the inactive discrete variables*
- virtual void [inactive\\_discrete\\_variables](#) (const [IntVector](#) &i\_d\_vars)  
*set the inactive discrete variables*
- virtual const [StringArray](#) & [inactive\\_continuous\\_variable\\_labels](#) () const  
*return the inactive continuous variable labels*
- virtual void [inactive\\_continuous\\_variable\\_labels](#) (const [StringArray](#) &i\_c\_vars)  
*set the inactive continuous variable labels*
- virtual const [StringArray](#) & [inactive\\_discrete\\_variable\\_labels](#) () const  
*return the inactive discrete variable labels*
- virtual void [inactive\\_discrete\\_variable\\_labels](#) (const [StringArray](#) &i\_d\_vars)  
*set the inactive discrete variable labels*
- virtual size\_t [acv](#) () const  
*returns total number of continuous vars*

- virtual `size_t adv () const`  
*returns total number of discrete vars*
- virtual `RealVector all_continuous_variables () const`  
*returns a single array with all continuous variables*
- virtual `void all_continuous_variables (const RealVector &a_c_vars)`  
*sets all continuous variables using a single array*
- virtual `IntVector all_discrete_variables () const`  
*returns a single array with all discrete variables*
- virtual `void all_discrete_variables (const IntVector &a_d_vars)`  
*sets all discrete variables using a single array*
- virtual `StringArray all_continuous_variable_labels () const`  
*returns a single array with all continuous variable labels*
- virtual `void all_continuous_variable_labels (const StringArray &a_c_v_labels)`  
*sets all continuous variable labels using a single array*
- virtual `StringArray all_discrete_variable_labels () const`  
*returns a single array with all discrete variable labels*
- virtual `void all_discrete_variable_labels (const StringArray &a_d_v_labels)`  
*sets all discrete variable labels using a single array*
- virtual `StringArray all_variable_labels () const`  
*returns a single array with all variable labels*
- virtual `void read (istream &s)`  
*read a variables object from an istream*
- virtual `void write (ostream &s) const`  
*write a variables object to an ostream*
- virtual `void write_aprepro (ostream &s) const`  
*write a variables object to an ostream in aprepro format*
- virtual `void read_annotated (istream &s)`  
*read a variables object in annotated format from an istream*
- virtual `void write_annotated (ostream &s) const`  
*write a variables object in annotated format to an ostream*
- virtual `void write_tabular (ostream &s) const`

*write a variables object in tabular format to an ostream*

- virtual void [read \(BiStream &s\)](#)  
*read a variables object from the binary restart stream*
- virtual void [write \(BoStream &s\)](#) const  
*write a variables object to the binary restart stream*
- virtual void [read \(MPIUnpackBuffer &s\)](#)  
*read a variables object from a packed MPI buffer*
- virtual void [write \(MPIPackBuffer &s\)](#) const  
*write a variables object to a packed MPI buffer*
- size\_t [cv \(\)](#) const  
*Returns number of active continuous vars.*
- size\_t [dv \(\)](#) const  
*Returns number of active discrete vars.*
- size\_t [icv \(\)](#) const  
*returns number of inactive continuous vars*
- size\_t [idv \(\)](#) const  
*returns number of inactive discrete vars*
- [Variables copy \(\)](#) const  
*for use when a deep copy is needed (the representation is `_not_shared`)*
- void [reshape](#) (const [Sizet2DArray](#) &vars\_comps)  
*variablesComponents*
- const pair< short, short > & [view \(\)](#) const  
*returns variablesView*
- pair< short, short > [get\\_view](#) (const [ProblemDescDB](#) &problem\_db) const  
*defines variablesView from problem\_db attributes*
- const [String](#) & [variables\\_id \(\)](#) const  
*returns the variables identifier string*
- const [Sizet2DArray](#) & [variables\\_components \(\)](#) const  
*returns the number of variables for each of the constitutive components*
- const [StringArray](#) & [continuous\\_variable\\_types \(\)](#) const  
*return the active continuous variable types*

- const [StringArray](#) & [discrete\\_variable\\_types](#) () const  
*return the active discrete variable types*
- const [IntArray](#) & [continuous\\_variable\\_ids](#) () const  
*return the active continuous variable position identifiers*
- const [IntArray](#) & [inactive\\_continuous\\_variable\\_ids](#) () const  
*return the inactive continuous variable position identifiers*
- const [IntArray](#) & [all\\_continuous\\_variable\\_ids](#) () const  
*return the all continuous variable position identifiers*
- bool [is\\_null](#) () const  
*function to check variablesRep (does this envelope contain a letter)*

### Protected Member Functions

- [Variables](#) ([BaseConstructor](#), const [ProblemDescDB](#) &problem\_db, const pair< short, short > &view)  
*derived class constructors - Coplien, p. 139)*
- virtual void [copy\\_rep](#) (const [Variables](#) \*vars\_rep)  
*Used by [copy\(\)](#) to copy the contents of a letter class.*
- virtual void [reshape\\_rep](#) (const [Sizet2DArray](#) &vars\_comps)  
*Used by [reshape\(\)](#) to reshape the contents of a letter class.*

### Protected Attributes

- pair< short, short > [variablesView](#)  
*view enumerations*
- [Sizet2DArray](#) [variablesComponents](#)  
*design/uncertain/state (first index) by sub-type (second index)*
- [StringArray](#) [continuousVarTypes](#)  
*array of variable types for the active continuous variables*
- [StringArray](#) [discreteVarTypes](#)  
*array of variable types for the active discrete variables*
- [IntArray](#) [continuousVarIds](#)  
*array of position identifiers for the active continuous variables*

- [IntArray inactiveContinuousVarIds](#)  
*array of position identifiers for the inactive continuous variables*
- [IntArray allContinuousVarIds](#)  
*array of position identifiers for the all continuous variables array*
- [RealVector emptyRealVector](#)  
*no variables corresponding to the request*
- [IntVector emptyIntVector](#)  
*no variables corresponding to the request*
- [StringArray emptyStringArray](#)  
*no variables corresponding to the request*

### Private Member Functions

- [Variables \\* get\\_variables](#) (const [ProblemDescDB](#) &problem\_db)  
*correct letter class*
- [Variables \\* get\\_variables](#) (const pair< short, short > &view) const  
*and by [copy\(\)](#) to instantiate a new letter class*

### Private Attributes

- [String idVariables](#)  
*variables identifier string from the input file*
- [Variables \\* variablesRep](#)  
*pointer to the letter (initialized only for the envelope)*
- int [referenceCount](#)  
*number of objects sharing variablesRep*

### Friends

- bool [operator==](#) (const [Variables](#) &vars1, const [Variables](#) &vars2)  
*equality operator*
- bool [operator!=](#) (const [Variables](#) &vars1, const [Variables](#) &vars2)  
*inequality operator*



### 8.121.1 Detailed Description

Base class for the variables class hierarchy.

The [Variables](#) class is the base class for the class hierarchy providing design, uncertain, and state variables for continuous and discrete domains within a [Model](#). Using the fundamental arrays from the input specification, different derived classes define different views of the data. For memory efficiency and enhanced polymorphism, the variables hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Variables](#)) serves as the envelope and one of the derived classes (selected in [Variables::get\\_variables\(\)](#)) serves as the letter.

### 8.121.2 Constructor & Destructor Documentation

#### 8.121.2.1 [Variables](#) ()

default constructor

The default constructor: variablesRep is NULL in this case (a populated problem\_db is needed to build a meaningful [Variables](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

#### 8.121.2.2 [Variables](#) (const [ProblemDescDB](#) & *problem\_db*)

standard constructor

This is the primary envelope constructor which uses problem\_db to build a fully populated variables object. It only needs to extract enough data to properly execute get\_variables(problem\_db), since the constructor overloaded with [BaseConstructor](#) builds the actual base class data inherited by the derived classes.

#### 8.121.2.3 [Variables](#) (const pair< short, short > & *view*)

alternate constructor for instantiations on the fly

This is the alternate envelope constructor for instantiations on the fly. Since it does not have access to problem\_db, the letter class is not fully populated. This constructor executes get\_variables(view), which invokes the default constructor of the derived letter class, which in turn invokes the default constructor of the base class.

#### 8.121.2.4 [Variables](#) (const [Variables](#) & *vars*)

copy constructor

Copy constructor manages sharing of variablesRep and incrementing of referenceCount.

#### 8.121.2.5 [~Variables](#) () [virtual]

destructor

Destructor decrements referenceCount and only deletes variablesRep when referenceCount reaches zero.

#### 8.121.2.6 **Variables** (BaseConstructor, const ProblemDescDB & problem\_db, const pair< short, short > & view) [protected]

derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. `get_variables()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_variables()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Variables`).

### 8.121.3 Member Function Documentation

#### 8.121.3.1 **Variables** operator= (const Variables & vars)

assignment operator

Assignment operator decrements referenceCount for old variablesRep, assigns new variablesRep, and increments referenceCount for new variablesRep.

#### 8.121.3.2 **Variables** copy () const

for use when a deep copy is needed (the representation is `_not_shared`)

Deep copies are used for history mechanisms such as `bestVariables` and `data_pairs` since these must catalogue copies (and should not change as the representation within `currentVariables` changes).

#### 8.121.3.3 **Variables** \* get\_variables (const ProblemDescDB & problem\_db) [private]

correct letter class

Initializes variablesRep to the appropriate derived type, as given by `problem_db` attributes. The standard derived class constructors are invoked.

#### 8.121.3.4 **Variables** \* get\_variables (const pair< short, short > & view) const [private]

and by `copy()` to instantiate a new letter class

Initializes variablesRep to the appropriate derived type, as given by `view`. The default derived class constructors are invoked.

### 8.121.4 Member Data Documentation

**8.121.4.1** [IntArray continuousVarIds](#) [protected]

array of position identifiers for the active continuous variables

These identifiers define positions of the active continuous variables within the total variable sequence.

**8.121.4.2** [IntArray inactiveContinuousVarIds](#) [protected]

array of position identifiers for the inactive continuous variables

These identifiers define positions of the inactive continuous variables within the total variable sequence.

**8.121.4.3** [IntArray allContinuousVarIds](#) [protected]

array of position identifiers for the all continuous variables array

These identifiers define positions of the all continuous variables array within the total variable sequence.

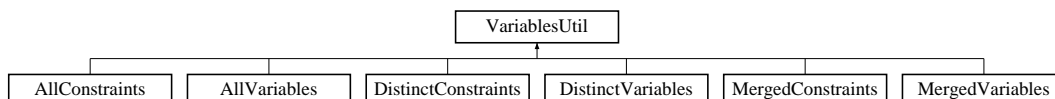
The documentation for this class was generated from the following files:

- DakotaVariables.H
- DakotaVariables.C

## 8.122 VariablesUtil Class Reference

continuous and discrete variable domains.

Inheritance diagram for VariablesUtil::



### Public Member Functions

- [VariablesUtil \(\)](#)  
*constructor*
- [~VariablesUtil \(\)](#)  
*destructor*

### Protected Member Functions

- void [update\\_merged](#) (const [RealVector](#) &c\_array, const [IntVector](#) &d\_array, [RealVector](#) &m\_array) const  
*array through promotion of integers to reals (merged view)*
- void [update\\_all\\_continuous](#) (const [RealVector](#) &c1\_array, const [RealVector](#) &c2\_array, const [RealVector](#) &c3\_array, [RealVector](#) &all\_array) const  
*continuous array (all view)*
- void [update\\_all\\_discrete](#) (const [IntVector](#) &d1\_array, const [IntVector](#) &d2\_array, [IntVector](#) &all\_array) const  
*(all view)*
- void [update\\_from\\_merged](#) (const [RealVector](#) &m\_array, [RealVector](#) &c\_array, [IntVector](#) &d\_array) const  
*array through truncation of reals to integers (merged view)*
- void [update\\_from\\_all\\_continuous](#) (const [RealVector](#) &all\_array, [RealVector](#) &c1\_array, [RealVector](#) &c2\_array, [RealVector](#) &c3\_array) const  
*continuous array (all view)*
- void [update\\_from\\_all\\_discrete](#) (const [IntVector](#) &all\_array, [IntVector](#) &d1\_array, [IntVector](#) &d2\_array) const

(all view)

- void `update_labels` (const `StringArray` &11\_array, const `StringArray` &12\_array, const `StringArray` &13\_array, `StringArray` &all\_array) const  
*single label array (all view)*
- void `update_labels` (const `StringArray` &11\_array, const `StringArray` &12\_array, `StringArray` &all\_array) const  
*combine 2 label arrays into a single label array (merged or all views)*
- void `update_labels_partial` (size\_t num\_items, const `StringArray` &src\_array, size\_t src\_start\_index, `StringArray` &tgt\_array, size\_t tgt\_start\_index) const  
*label array (all view)*
- void `update_from_labels` (const `StringArray` &all\_array, `StringArray` &11\_array, `StringArray` &12\_array, `StringArray` &13\_array)  
*single label array (all view)*
- void `update_from_labels` (const `StringArray` &all\_array, `StringArray` &11\_array, `StringArray` &12\_array)  
*extract 2 label arrays from a single label array (merged or all views)*

### 8.122.1 Detailed Description

continuous and discrete variable domains.

Derived classes within the `Variables` and `Constraints` hierarchies use multiple inheritance to inherit these utilities.

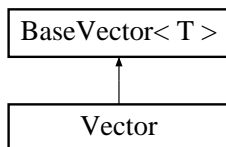
The documentation for this class was generated from the following file:

- VariablesUtil.H

## 8.123 Vector Class Template Reference

Template class for the [Dakota](#) numerical vector.

Inheritance diagram for Vector::



### Public Member Functions

- [Vector](#) ()  
*Default constructor.*
- [Vector](#) (size\_t len)  
*Constructor which takes an initial length.*
- [Vector](#) (size\_t len, const T &initial\_val)  
*Constructor which takes an initial length and an initial value.*
- [Vector](#) (const [Vector](#)< T > &a)  
*Copy constructor.*
- [Vector](#) (const T \*p, size\_t len)  
*Constructor which copies len entries from T\*.*
- [~Vector](#) ()  
*Destructor.*
- [Vector](#)< T > & [operator=](#) (const [Vector](#)< T > &a)  
*Normal const assignment operator.*
- [Vector](#)< T > & [operator=](#) (const T &ival)  
*Sets all elements in self to the value ival.*
- [operator T \\*](#) () const  
*Use with care!*
- void [read](#) (istream &s)  
*Reads a [Vector](#) from an input stream.*

- void `read` (istream &s, Array< String > &label\_array)  
*Reads a [Vector](#) and associated label array from an input stream.*
- void `read_partial` (istream &s, size\_t start\_index, size\_t num\_items)  
*Reads part of a [Vector](#) from an input stream.*
- void `read_partial` (istream &s, size\_t start\_index, size\_t num\_items, Array< String > &label\_array)  
*Reads part of a [Vector](#) and the corresponding labels from an input stream.*
- void `read_tabular` (istream &s)  
*Reads a [Vector](#) from a tabular text input file.*
- void `read_annotated` (istream &s, Array< String > &label\_array)  
*input stream*
- void `write` (ostream &s) const  
*Writes a [Vector](#) to an output stream.*
- void `write` (ostream &s, const Array< String > &label\_array) const  
*Writes a [Vector](#) and associated label array to an output stream.*
- void `write_partial` (ostream &s, size\_t start\_index, size\_t num\_items) const  
*Writes part of a [Vector](#) to an output stream.*
- void `write_partial` (ostream &s, size\_t start\_index, size\_t num\_items, const Array< String > &label\_array) const  
*output stream*
- void `write_aprepro` (ostream &s, const Array< String > &label\_array) const  
*in aprepro format*
- void `write_partial_aprepro` (ostream &s, size\_t start\_index, size\_t num\_items, const Array< String > &label\_array) const  
*output stream in aprepro format*
- void `write_annotated` (ostream &s, const Array< String > &label\_array) const  
*to an output stream*
- void `write_tabular` (ostream &s) const  
*Writes a [Vector](#) in tabular form to an output stream.*
- void `write_partial_tabular` (ostream &s, size\_t start\_index, size\_t num\_items) const  
*Writes part of a [Vector](#) in tabular form to an output stream.*
- void `read` (BiStream &s, Array< String > &label\_array)

*Reads a [Vector](#) and associated label array from a binary input stream.*

- void [write](#) ([BoStream](#) &s, const [Array](#)< [String](#) > &label\_array) const  
*Writes a [Vector](#) and associated label array to a binary output stream.*
- void [read](#) ([MPIUnpackBuffer](#) &s)  
*Reads a [Vector](#) from a buffer after an MPI receive.*
- void [read](#) ([MPIUnpackBuffer](#) &s, [Array](#)< [String](#) > &label\_array)  
*MPI receive.*
- void [write](#) ([MPIPackBuffer](#) &s) const  
*Writes a [Vector](#) to a buffer prior to an MPI send.*
- void [write](#) ([MPIPackBuffer](#) &s, const [Array](#)< [String](#) > &label\_array) const  
*an MPI send*

### 8.123.1 Detailed Description

```
template<class T> class Dakota::Vector< T >
```

Template class for the [Dakota](#) numerical vector.

The [Dakota::Vector](#) class is the numeric vector class. It inherits from the common vector class [Dakota::BaseVector](#) which provides the same interface for both the STL and RW vector classes. If the STL version of [BaseVector](#) is based on the valarray class then some basic vector operations such as + , \* are available. This class adds functionality to read/write vectors in a variety of ways

### 8.123.2 Constructor & Destructor Documentation

#### 8.123.2.1 [Vector](#) (const T \* p, size\_t len) [inline]

Constructor which copies len entries from T\*.

Assigns size values from p into array.

### 8.123.3 Member Function Documentation



**8.123.3.1** `Vector< T > & operator=(const T & ival)` [inline]

Sets all elements in self to the value ival.

Assigns all values of array to ival. If STL, uses the vector assign method because there is no operator=(ival).

Reimplemented from [BaseVector](#).

The documentation for this class was generated from the following file:

- [DakotaVector.H](#)



# Chapter 9

## DAKOTA File Documentation

### 9.1 JEGAOptimizer.C File Reference

Contains the implementation of the JEGAOptimizer class.

#### Namespaces

- namespace [Dakota](#)
- namespace `std`
- namespace `JEGA::Logging`
- namespace `eddy::utilities`

#### Classes

- class [JEGAOptimizer::EvaluatorCreator](#)  
*A specialization of the `JEGA::FrontEnd::EvaluatorCreator` that creates a new instance of a `Evaluator`.*
- class [JEGAOptimizer::Driver](#)  
*A subclass of the `JEGA` front end driver that exposes the individual protected methods to execute the algorithm.*

#### Functions

- `template<typename T> string asstring (const T &val)`  
*Creates a string from the argument `val` using an `ostringstream`.*

### 9.1.1 Detailed Description

Contains the implementation of the JEGAOptimizer class.

## 9.2 JEGAOptimizer.H File Reference

Contains the definition of the JEGAOptimizer class.

### Namespaces

- namespace **JEGA**
- namespace **JEGA::Utilities**
- namespace **JEGA::FrontEnd**
- namespace **JEGA::Algorithms**
- namespace [Dakota](#)

### Classes

- class [JEGAOptimizer](#)  
*A version of [Dakota::Optimizer](#) for instantiation of John Eddy's Genetic Algorithms (JEGA).*

### 9.2.1 Detailed Description

Contains the definition of the JEGAOptimizer class.

## 9.3 keywordtable.C File Reference

file containing keywords for the strategy, method, model, variables, interface, and responses input specifications from **dakota.input.spec**

### Variables

- KeywordHandler [idrKeywordTable](#) []  
*KeywordHandler structure signifies the end of the keyword table.*

### 9.3.1 Detailed Description

file containing keywords for the strategy, method, model, variables, interface, and responses input specifications from **dakota.input.spec**

## 9.4 main.C File Reference

file containing the main program for DAKOTA

### Functions

- `int main (int argc, char *argv[])`  
*The main DAKOTA program.*

#### 9.4.1 Detailed Description

file containing the main program for DAKOTA

#### 9.4.2 Function Documentation

##### 9.4.2.1 `int main (int argc, char * argv[])`

The main DAKOTA program.

Manage command line inputs, input files, restart file(s), output streams, and top level parallel iterator communicators. Instantiate the Strategy and invoke its `run_strategy()` virtual function.

## 9.5 restart\_util.C File Reference

file containing the DAKOTA restart utility main program

### Namespaces

- namespace [Dakota](#)

### Functions

- void [print\\_restart](#) (int argc, char \*\*argv, [String](#) print\_dest)  
*print a restart file*
- void [print\\_restart\\_tabular](#) (int argc, char \*\*argv, [String](#) print\_dest)  
*print a restart file (tabular format)*
- void [read\\_neutral](#) (int argc, char \*\*argv)  
*read a restart file (neutral file format)*
- void [repair\\_restart](#) (int argc, char \*\*argv, [String](#) identifier\_type)  
*repair a restart file by removing corrupted evaluations*
- void [concatenate\\_restart](#) (int argc, char \*\*argv)  
*concatenate multiple restart files*
- int [main](#) (int argc, char \*argv[])  
*The main program for the DAKOTA restart utility.*

### 9.5.1 Detailed Description

file containing the DAKOTA restart utility main program

### 9.5.2 Function Documentation



**9.5.2.1 int main (int argc, char \* argv[ ])**

The main program for the DAKOTA restart utility.

Parse command line inputs and invoke the appropriate utility function ([print\\_restart\(\)](#), [print\\_restart\\_tabular\(\)](#), [read\\_neutral\(\)](#), [repair\\_restart\(\)](#), or [concatenate\\_restart\(\)](#)).



## Chapter 10

# Recommended Practices for DAKOTA Development

### 10.1 Introduction

Common code development practices can be extremely useful in multiple developer environments. Particular styles for code components lead to improved readability of the code and can provide important visual cues to other developers.

Much of this recommended practices document is borrowed from the CUBIT mesh generation project, which in turn borrows its recommended practices from other projects. As a result, C++ coding styles are fairly standard across a variety of Sandia software projects in the engineering and computational sciences.

### 10.2 Style Guidelines

Style guidelines involve the ability to discern at a glance the type and scope of a variable or function.

#### 10.2.1 Class and variable styles

Class names should be composed of two or more descriptive words, with the first character of each word capitalized, e.g.:

```
class ClassName;
```

Class member variables should be composed of two or more descriptive words, with the first character of the second and succeeding words capitalized, e.g.:

```
double classMemberVariable;
```

Temporary (i.e. local) variables are lower case, with underscores separating words in a multiple word temporary variable, e.g.:

```
int temporary_variable;
```

Constants (i.e. parameters) and enumeration values are upper case, with underscores separating words, e.g.:

```
const double CONSTANT_VALUE;
```

## 10.2.2 Function styles

Function names are lower case, with underscores separating words, e.g.:

```
int function_name();
```

There is no need to distinguish between member and non-member functions by style, as this distinction is usually clear by context. This style convention allows member function names which set and return the value of a similarly-named private member variable, e.g.:

```
int memberVariable;
void member_variable(int a) { // set
    memberVariable = a;
}
int member_variable() const { // get
    return memberVariable;
}
```

In cases where the data to be set or returned is more than a few bytes, it is highly desirable to employ const references to avoid unnecessary copying, e.g.:

```
void continuous_variables(const RealVector& c_vars) { // set
    continuousVariables = c_vars;
}
const RealVector& continuous_variables() const { // get
    return continuousVariables;
}
```

Note that it is not necessary to always accept the returned data as a const reference. If it is desired to be able change this data, then accepting the result as a new variable will generate a copy, e.g.:

```
const RealVector& c_vars = model.continuous_variables(); // reference to continuousVariables cannot be changed
RealVector c_vars = model.continuous_variables(); // local copy of continuousVariables can be changed
```

### 10.2.3 Miscellaneous

Appearance of typedefs to redefine or alias basic types is isolated to a few header files (`data_types.h`, `template_defs.h`), so that issues like program precision can be changed by changing a few lines of typedefs rather than many lines of code, e.g.:

```
typedef double Real;
```

`xemacs` is the preferred source code editor, as it has C++ modes for enhancing readability through color (turn on "Syntax highlighting"). Other helpful features include "Paren highlighting" for matching parentheses and the "New Frame" utility to have more than one window operating on the same set of files (note that this is still the same edit session, so all windows are synchronized with each other). Window width should be set to 80 internal columns, which can be accomplished by manual resizing, or preferably, using the following alias in your shell resource file (e.g., `.cshrc`):

```
alias xemacs "xemacs -g 81x63"
```

where an external width of 81 gives 80 columns internal to the window and the desired height of the window will vary depending on monitor size. This window width imposes a coding standard since you should avoid line wrapping by continuing anything over 80 columns onto the next line.

Indenting increments are 2 spaces per indent and comments are aligned with the code they describe, e.g.:

```
void abort_handler(int code)
{
    int initialized = 0;
    MPI_Initialized(&initialized);
    if (initialized) {
        // comment aligned to block it describes
        int size;
        MPI_Comm_size(MPI_COMM_WORLD, &size);
        if (size>1)
            MPI_Abort(MPI_COMM_WORLD, code);
        else
            exit(code);
    }
    else
        exit(code);
}
```

Also, the continuation of a long command is indented 2 spaces, e.g.:

```
const String& iterator_scheduling
    = problem_db.get_string("strategy.iterator_scheduling");
```

and similar lines are aligned for readability, e.g.:

```
cout << "Numerical gradients using " << finiteDiffStepSize*100. << "%"
    << finiteDiffType << " differences\nto be calculated by the "
    << methodSource << " finite difference routine." << endl;
```

Lastly, `#ifdef`'s are not indented (to make use of syntax highlighting in `xemacs`).

## 10.3 File Naming Conventions

In addition to the style outlined above, the following file naming conventions have been established for the DAKOTA project.

File names for C++ classes should, in general, use the same name as the class defined by the file. Exceptions include:

- with the introduction of the `Dakota` namespace, base classes which previously utilized prepended Dakota identifiers can now safely omit the identifiers. However, since file names do not have namespace protection from name collisions, they retain the prepended Dakota identifier. For example, a class previously named `DakotaModel` which resided in `DakotaModel.[CH]`, is now `Dakota::Model` (class `Model` in namespace `Dakota`) residing in the same filenames. The retention of the previous filenames reduces the possibility of multiple instances of a `Model.H` causing problems. Derived classes (e.g., `NestedModel`) do not require a prepended Dakota identifier for either the class or file names.
- in a few cases, it is convenient to maintain several closely related classes in a single file, in which case the file name may reflect the top level class or some generalization of the set of classes (e.g., `DakotaResponse.[CH]` files contain `Dakota::Response` and `Dakota::ResponseRep` classes, and `DakotaBinStream.[CH]` files contain the `Dakota::BiStream` and `Dakota::BoStream` classes).

The type of file is determined by one of the four file name extensions listed below:

- **.H** A class header file ends in the suffix `.H`. The header file provides the class declaration. This file does not contain code for implementing the methods, except for the case of inline functions. Inline functions are to be placed at the bottom of the file with the keyword `inline` preceding the function name.
- **.C** A class implementation file ends in the suffix `.C`. An implementation file contains the definitions of the members of the class.
- **.h** A header file ends in the suffix `.h`. The header file contains information usually associated with procedures. Defined constants, data structures and function prototypes are typical elements of this file.
- **.c** A procedure file ends in the suffix `.c`. The procedure file contains the actual procedures.

## 10.4 Class Documentation Conventions

Class documentation uses the doxygen tool available from <http://www.doxygen.org> and employs the JAVA-doc comment style. Brief comments appear in header files next to the attribute or function declaration. Detailed descriptions for functions should appear alongside their implementations (i.e., in the `.C` files for non-inlined, or in the headers next to the function definition for inlined). Detailed comments for a class or a class attribute must go in the header file as this is the only option.

NOTE: Previous class documentation utilities (`class2frame` and `class2html`) used the `/// comment style and comment blocks such as this:`

```
/// Class:      Model
/// Description: The model to be iterated by the Iterator.  Contains Variables, Interface, and Response objects.
/// Owner:      Mike Eldred
/// Version:    $Id: Dev_Recomm_Pract.dox 4549 2007-09-20 18:25:03Z mseldre $
```

These tools are no longer used, so remaining comment blocks of this type are informational only and will not appear in the documentation generated by doxygen.





## Chapter 11

# Instructions for Modifying DAKOTA's Input Specification

### 11.1 Modify `dakota.input.spec`

The master input specification resides in `dakota.input.spec` in `Dakota/src`. As part of the Input Deck Reader (IDR) build process, a soft link to this file is created in `Dakota/packages/idr`. The master input specification can be modified with the addition of new constructs using the following logical relationships:

- `{ }` for required individual specifications
- `( )` for required group specifications
- `[ ]` for optional individual specifications
- `[ ]` for optional group specifications
- `|` for "or" conditionals

These constructs can be used to define a variety of dependency relationships in the input specification. It is recommended that you review the existing specification and have an understanding of the constructs in use before attempting to add new constructs.

#### **Warning:**

- Do *not* skip this step. Attempts to modify the `keywordtable.C` and `ProblemDescDB.C` files in `Dakota/src` without reference to the results of the code generator are very error-prone. Moreover, the input specification provides a reference to the allowable inputs of a particular executable and should be kept in synch with the parser files (modifying the parser files independent of the input specification creates, at a minimum, undocumented features).

- All keywords in **dakota.input.spec** are currently lower case by convention. All user inputs are converted to lower case by the parser prior to keyword match testing, resulting in case insensitive parsing. [To allow keywords with capitalization and case sensitive parsing, `IDR_NO_CONVRN` should be passed in `idr_init()` and uses of `idr_case_convert()` within `idr.c` should be reviewed.]
- Since the Input Deck Reader (IDR) parser allows abbreviation of keywords, you *must* avoid adding a keyword that could be misinterpreted as an abbreviation for a different keyword within the same keyword handler (the term "keyword handler" refers to the `strategy_kwhandler()`, `method_kwhandler()`, `variables_kwhandler()`, `interface_kwhandler()`, and `responses_kwhandler()` member functions in the [IDRProblemDescDB](#) class). For example, adding the keyword "expansion" within the method specification would be a mistake if the keyword "expansion\_factor" already was being used in this specification.
- Since IDR input is order-independent, the same keyword may be reused multiple times in the specification if and only if the specification blocks are mutually exclusive. For example, method selections (e.g., `dot_frcg`, `dot_bfgs`) can reuse the same method setting keywords (e.g., `optimization_type`) since the method selection blocks are all separated by logical "or"s. If `dot_frcg` and `dot_bfgs` were not exclusive and could be specified at the same time, then association of the `optimization_type` setting with a particular method would be ambiguous. This is the reason why repeated specifications which are non-exclusive must be made unique, typically with a prepended identifier (e.g., `cdv_initial_point`, `ddv_initial_point`).

## 11.2 Rebuild IDR

```
cd Dakota/packages/idr/native
make
```

These steps regenerate [keywordtable.C](#), `idr-gen-code.C` and `idr-keyword.h` in the `Dakota/packages/idr/native` directory and copy the updated [keywordtable.C](#) to `Dakota/src`. As described in more detail in the next section, you must manually update `IDRProblemDescDB.C` in `Dakota/src`, based on `idr-gen-code.C`. If you commit changes to a source repository, be sure to commit the updated `Dakota/packages/idr/native/idr-keyword.h`, **`Dakota/src/dakota.input.spec`**, [Dakota/src/keywordtable.C](#), and your manually updated `Dakota/src/IDRProblemDescDB.C`.

## 11.3 Update `IDRProblemDescDB.C` in `Dakota/src`

Find the keyword handler functions (e.g., `variables_kwhandler()`) in `Dakota/packages/idr/native/idr-gen-code.C` and `Dakota/src/IDRProblemDescDB.C` which correspond to your modifications to the input specification. The `idr-gen-code.C` file is the result of a code generator and contains skeleton constructs for extracting data from IDR. You will be copying over parts of this skeleton to `IDRProblemDescDB.C` and then adding code to populate attributes within Data class container objects.

### 11.3.1 Replace keyword handler declarations and counter loop

Rather than trying to update these line by line, it is recommended to delete the entire block starting with the keyword declarations and ending at the bottom of the keyword counter loop. The declarations assign -1 to keywords

and look like this:

```
Int cdv_descriptor = -1;
Int cdv_initial_point = -1;
```

They start after the line "Int cntr;". The keyword counter loop looks like this:

```
for ( cntr=data_len; cntr--; ) {
  if ( idr_find_id( &cdv_descriptor, cntr,
                  "cdv_descriptor", id_str, kw_str ) ) continue;
  ...
  if ( idr_find_id( &wuv_dist_upper_bounds, cntr,
                  "wuv_dist_upper_bounds", id_str, kw_str ) ) continue;
}
```

Once the old keyword declarations and keyword counter loop have been deleted, replace them with the corresponding blocks from `idr-gen-code.C` containing the updated keyword declarations and counter loop.

### 11.3.2 Update keyword handler logic blocks

For the newly added or modified input specifications, copy the appropriate skeleton constructs from `idr-gen-code.C` and paste them into the corresponding location in `IDRProblemDescDB.C`.

The next step is to add code to these skeletons to set data attributes within the `Data` class object used by the keyword handler. At the top of the method, variables, interface, and responses keyword handlers, a `Data` class object is instantiated in order to store attributes, e.g.:

```
DataMethod data_method;
```

and within the strategy keyword handler, a reference to the [strategySpec](#) data class object is used to store attributes. Each of these data class objects is a simple container class which contains the data from a single keyword handler invocation. Within each skeleton construct, you will extract data from the IDR data structures and then use this data to set the corresponding attribute within the `Data` class.

Integer, real, and string data are extracted using the `idata`, `rdata`, and `cdata` arrays provided by IDR. These arrays are indexed using a bracket operator with the keyword as an index. Lists of integer, list of real, and list of string data are extracted using the `IDRProblemDescDB::idr_get_int_table()`, `IDRProblemDescDB::idr_get_real_table()`, and `IDRProblemDescDB::idr_get_string_table()` functions, respectively.

**Example 1:** if you added the specification:

```
[method_setting = <REAL>]
```

you would copy over

```
if ( method_setting >= 0 ) {
}
```

from `idr-gen-code.C` into `IDRProblemDescDB.C` and then populate the if block with a call to set the corresponding attribute within the `data_method` object using data extracted using the `rdata` array:

```

if ( method_setting >= 0 ) {
    data_method.methodSetting = rdata[method_setting];
}

```

Use of a set member function within `DataMethod` is not needed since the data is public. The data is public since `ProblemDescDB` already provides sufficient encapsulation (`ProblemDescDB::dataMethodList`, `ProblemDescDB::dataModelList`, `ProblemDescDB::dataVariablesList`, `ProblemDescDB::dataInterfaceList`, `ProblemDescDB::dataResponsesList`, and `ProblemDescDB::strategySpec` are private attributes), and public access reduces the amount of code to manage when performing input specification modifications by omitting the need to add/modify set/get functions.

**Example 2:** if you added the specification

```
[method_setting = <LISTof><REAL>]
```

you would copy over

```

if ( method_setting >= 0 ) {
    { Int idr_table_len;
      Real** idr_table = idr_get_real_table( parsed_data, method_setting,
                                           idr_table_len, 1, 1 );
    }
}

```

from `idr-gen-code.C` into `IDRProblemDescDB.C` and then populate it with a loop which extracts each entry of the table and populates the corresponding attribute within the `data_method` object. The `idr_table_len` attribute is used for the loop limit and to size the `data_method` object.

```

if ( method_setting >= 0 ) {
    { Int idr_table_len;
      Real** idr_table = idr_get_real_table( parsed_data, method_setting,
                                           idr_table_len, 1, 1 );

      data_method.methodSetting.reshape(idr_table_len);
      for (int i = 0; i<idr_table_len; i++)
          data_method.methodSetting[i] = idr_table[0][i];
    }
}

```

**Attention:**

If no new data attributes have been added, but instead there are only new settings for existing attributes, then you're done with the database augmentation at this point (you just need to add code to use these new settings in the places where the existing attributes are used).

## 11.4 Update ProblemDescDB.C in Dakota/src

### 11.4.1 Augment/update get\_<data\_type>() functions

The next update step involves extending the database retrieval functions in ProblemDescDB.C. These retrieval functions accept an identifier string and return a database attribute of a particular type, e.g. a RealVector:

```
const RealVector& get_drv(const String& entry_name);
```

The implementation of each of these functions has a simple series of if-else checks which return the appropriate attribute based on the identifier string. For example,

```
if (entry_name == "variables.continuous_design.initial_point")
    return dbRep->dataVariablesIter->continuousDesignVars;
```

appears at the top of `ProblemDescDB::get_drv()`. Based on the identifier string, it returns the `continuousDesignVars` attribute from a `DataVariables` object. Since there may be multiple variables specifications, the `dataVariablesIter` list iterator identifies which node in the list of `DataVariables` objects is used. In particular, `dataVariablesList` contains a list of all of the `data_variables` objects, one for each time `variables_kwhandler()` has been called by the parser. The particular variables object used for the data retrieval is managed by `dataVariablesIter`, which is set in a `set_db_list_nodes()` operation that will not be described here.

There may be multiple `DataMethod`, `DataModel`, `DataVariables`, `DataInterface`, and/or `DataResponses` objects. However, only one strategy specification is currently allowed so a list of `DataStrategy` objects is not needed. Rather, `ProblemDescDB::strategySpec` is the lone `DataStrategy` object.

To augment the `get_<data_type>()` functions, add `else` blocks with new identifier strings which retrieve the appropriate data attributes from the Data class object. The style for the identifier strings is a top-down hierarchical description, with specification levels separated by periods and words separated with underscores, e.g. "keyword.group\_specification.individual\_specification". Use the `dbRep->listIter->attribute` syntax for variables, interface, responses, and method specifications. For example, the `method_setting` example attribute would be added to `get_drv()` as:

```
else if (entry_name == "method.method_name.method_setting")
    return dbRep->dataMethodIter->methodSetting;
```

A strategy specification addition would not use a list iterator, and would instead look like:

```
else if (entry_name == "strategy.strategy_name.strategy_setting")
    return dbRep->strategySpec.strategySetting;
```

## 11.5 Update Corresponding Data Classes

In this step, we extend the Data class definitions (`DataStrategy`, `DataMethod`, `DataModel`, `DataVariables`, `DataInterface`, and/or `DataResponses`) to include the new attributes referenced in Update keyword handler logic blocks and Augment/update `get_<data_type>()` functions.

### 11.5.1 Update the Data class header file

Add a new attribute to the public data for each of the new specifications. Follow the style guide for class attribute naming conventions (or mimic the existing code).

### 11.5.2 Update the .C file

Define defaults for the new attributes in the constructor initialization list. Add the new attributes to the assign() function for use by the copy constructor and assignment operator. Add the new attributes to the write(MPIPackBuffer&), read(MPIUnpackBuffer&), and write(ostream&) functions, paying careful attention to the use of a consistent ordering.

## 11.6 Use get\_<data\_type>() Functions

At this point, the new specifications have been mapped through all of the database classes. The only remaining step is to retrieve the new data within the constructors of the classes that need it. This is done by invoking the get\_<data\_type>() function on the [ProblemDescDB](#) object using the identifier string you selected in [Augment/update get\\_<data\\_type>\(\) functions](#). For example:

```
const String& interface_type = problem_db.get_string("interface.type");
```

passes the "interface.type" identifier string to the [ProblemDescDB::get\\_string\(\)](#) retrieval function, which returns the desired attribute from the active [DataInterface](#) object.

#### Warning:

Use of the get\_<data\_type>() functions is restricted to class constructors, since only in class constructors are the data list iterators (i.e., [dataMethodIter](#), [dataModelIter](#), [dataVariablesIter](#), [dataInterfaceIter](#), and [dataResponsesIter](#)) guaranteed to be set correctly. Outside of the constructors, the database list nodes will correspond to the last set operation, and may not return data from the desired list node.

## 11.7 Update the Documentation

Doxygen comments should be added to the Data class headers for the new attributes, and the reference manual sections describing the portions of [dakota.input.spec](#) that have been modified should be updated.







# Chapter 12

## Interfacing with DAKOTA as a Library

### 12.1 Introduction

Some users may be interested in linking the DAKOTA toolkit into another application for use as an algorithm library. While this is not the primary usage model for DAKOTA, certain facilities are in place to allow this type of integration.

As part of the normal DAKOTA build process, where `Dakota/configure -prefix='pwd'` has been run prior to `make` and `make install`, a `libdakota.a` is created and a copy of it is placed in `Dakota/lib`. This library contains all source files from `Dakota/src` excepting the `main.C` and `restart_util.C` main programs. This library may be linked with another application through inclusion of `-ldakota` on the link line. Library and header paths may also be specified using the `-L` and `-I` compiler options (using `Dakota/lib` and `Dakota/include`, respectively). Depending on the configuration used when building this library, other libraries for the vendor optimizers and vendor packages will also be needed to resolve DAKOTA symbols for DOT, NPSOL, OPT++, SGOPT, LHS, Epetra, etc. Copies of these libraries are also placed in `Dakota/lib`. An XML specification of library names and paths is also available in `Dakota/dependency`.

#### Warning:

While users are free to interface DAKOTA as a library within other software applications for their own internal use, the GNU GPL license stipulates that any application linked with DAKOTA in this way defines a "derivative work" and can only be distributed externally under the same GNU GPL open source license. Refer to <http://www.gnu.org/licenses/gpl.html> or contact the DAKOTA team for additional information.

#### Attention:

The use of DAKOTA as an algorithm library should be distinguished from the linking of simulations within DAKOTA using the direct application interface (see [DirectFnApplicInterface](#)). In the former, DAKOTA is providing algorithm services to another software application, and in the latter, a linked simulation is providing analysis services to DAKOTA. It is not uncommon for these two capabilities to be used in combination, resulting in a "sandwich" implementation.

The procedure for utilizing DAKOTA as a library within another application involves a number of steps that are similar to those used in the stand-alone DAKOTA application. The stand-alone procedure can be viewed in the file `main.C`, and the differences for the library approach are most easily explained with reference to that file. The basic steps of executing DAKOTA include instantiating the `ParallelLibrary`, `CommandLineHandler`, and `ProblemDescDB` objects; managing the DAKOTA input file (`ProblemDescDB::manage_inputs()`); specifying restart files and output streams (`ParallelLibrary::specify_outputs_restart()`); and instantiating the `Strategy` and running it (`Strategy::run_strategy()`). When using DAKOTA as an algorithm library, the operations are quite similar, although command line information (`argc`, `argv`, and therefore `CommandLineHandler`) will not in general be accessible. In particular, `main.C` can pass `argc` and `argv` into the `ParallelLibrary` and `CommandLineHandler` constructors and then pass the `CommandLineHandler` object into `ProblemDescDB::manage_inputs()` and `ParallelLibrary::specify_outputs_restart()`. In an algorithm library approach, a `CommandLineHandler` object is not instantiated and overloaded forms of the `ParallelLibrary` constructor, `ProblemDescDB::manage_inputs()`, and `ParallelLibrary::specify_outputs_restart()` are used.

The overloaded forms of these functions are as follows. For instantiation of the `ParallelLibrary` object, the default constructor may be used. This constructor assumes that MPI is initialized elsewhere in the parent application. That is, the instantiation

```
ParallelLibrary parallel_lib(argc, argv);
```

is replaced with

```
ParallelLibrary parallel_lib;
```

In the case of specifying restart files and output streams, the call to

```
parallel_lib.specify_outputs_restart(cmd_line_handler);
```

should be replaced with its overloaded form in order to pass the required information through the parameter list

```
parallel_lib.specify_outputs_restart(std_output_filename, std_error_filename,
    read_restart_filename, write_restart_filename, restart_evals);
```

where file names for standard output and error and restart read and write as well as the integer number of restart evaluations are passed through the parameter list rather than read from the command line of the main DAKOTA program. The definition of these attributes is performed elsewhere in the parent application (e.g., specified in the parent application input file or GUI).

With respect to alternate forms of `ProblemDescDB::manage_inputs()`, the two following sections describe different approaches to populating data within DAKOTA's problem description database. It is this database from which all DAKOTA objects draw data upon instantiation.

## 12.2 Problem database populated through input file parsing

The simplest approach to linking an application with the DAKOTA library is to rely on DAKOTA's normal parsing system to populate DAKOTA's problem database (`ProblemDescDB`) through the reading of an input file. The disadvantage to this approach is the requirement for an additional input file beyond those already required by the parent application.

In this approach, the call to

```
problem_db.manage_inputs(cmd_line_handler);
```

should be replaced with its overloaded form

```
problem_db.manage_inputs(dakota_input_file);
```

where the file name for the DAKOTA input is passed through the parameter list rather than read from the command line of the main DAKOTA program. Again, the definition of the DAKOTA input file name is performed elsewhere in the parent application (e.g., specified in the parent application input file or GUI).

## 12.3 Problem database populated through external means

This approach is more involved than the previous approach, but it allows the application to publish all needed data to DAKOTA's database directly, thereby eliminating the need for the parsing of a separate DAKOTA input file. In this case, `ProblemDescDB::manage_inputs()` is not called. Rather, `DataStrategy`, `DataMethod`, `DataModel`, `DataVariables`, `DataInterface`, and `DataResponses` objects must be instantiated and populated with the desired problem data. These objects are then published to the problem database using `ProblemDescDB::insert_node()`, e.g.:

```
// instantiate the data object
DataMethod data_method;

// set the attributes within the data object
data_method.methodName = "nond_sampling";
...

// publish the data object to the ProblemDescDB
problem_db.insert_node(data_method);
```

The data objects are populated with their default values upon instantiation, so only the non-default values need to be specified. Refer to the `DataStrategy`, `DataMethod`, `DataModel`, `DataVariables`, `DataInterface`, and `DataResponses` class documentation and source code for lists of attributes and their defaults.

The default strategy is `single_method`, which runs a single iterator on a single model, and the default model is `single`, so it is not necessary to instantiate and publish a `DataStrategy` or `DataModel` object if advanced multi-component capabilities are not required. Rather, instantiation and insertion of a single `DataMethod`, `DataVariables`, `DataInterface`, and `DataResponses` object is sufficient for basic DAKOTA capabilities.

Once the data objects have been published to the `ProblemDescDB` object, a call to

```
problem_db.check_input();
```

will perform basic database error checking.

### Attention:

The use of the `insert_node()` approach bypasses a considerable amount of data consistency enforcement within the keyword handler functions of `IDRProblemDescDB`. Application developers should study this logic and replicate as needed within their calling code in order to avoid run time errors resulting from data inconsistency. Abstraction of this consistency enforcement to the base `ProblemDescDB` level will simplify this process in the future.

## 12.4 Instantiating the strategy

With the [ProblemDescDB](#) object populated with problem data, we may now instantiate the strategy.

```
// instantiate the strategy
Strategy selected_strategy(problem_db);
```

Following strategy construction, all MPI communicator partitioning has been performed and the [ParallelLibrary](#) instance may be interrogated for parallel configuration data. For example, the lowest level communicators in DAKOTA's multilevel parallel partitioning are the analysis communicators, which can be retrieved using:

```
// retrieve the set of analysis communicators for simulation initialization:
// one analysis comm per ParallelConfiguration (PC), one PC per Model.
Array<MPI_Comm> analysis_comms = parallel_lib.analysis_intra_communicators();
```

These communicators can then be used for initializing parallel simulation instances, where the number of MPI communicators in the array corresponds to one communicator per [ParallelConfiguration](#) instance.

## 12.5 Defining the direct application interface

When employing a library interface to DAKOTA, it is frequently desirable to also use a direct interface between DAKOTA and the simulation. There are two approaches to defining this direct interface.

### 12.5.1 Extension

The first approach involves extending the existing [DirectFnApplicInterface](#) class to support additional direct simulation interfaces. In this case, a new simulation interface function can be added to `Dakota/src/DirectFnApplicInterface.[CH]` for the simulation of interest. If the new function will not be a member function, then the following prototype should be used in order to pass the required data:

```
int sim(const Dakota::Variables& vars, const Dakota::ActiveSet& set,
        Dakota::Response& response);
```

If the new function will be a member function, then this can be simplified to

```
int sim();
```

since the data access can be performed through the [DirectFnApplicInterface](#) class attributes.

This simulation can then be added to the logic blocks in [DirectFnApplicInterface::derived\\_map\\_ac\(\)](#). In addition, [DirectFnApplicInterface::derived\\_map\\_if\(\)](#) and [DirectFnApplicInterface::derived\\_map\\_of\(\)](#) can be extended to perform pre- and post-processing tasks if desired, but this is not required.

While this approach is the simplest, it has the disadvantage that the DAKOTA library may need to be recompiled when the simulation or its direct interface is modified. If it is desirable to maintain the independence of the DAKOTA library from the host application, then the following derivation approach should be employed.

## 12.5.2 Derivation

The second approach is to derive a new interface from [DirectFnApplicInterface](#) in order to redefine several virtual functions. A typical derived class declaration might be

```
namespace SIM {

class DirectFnApplicInterface: public Dakota::DirectFnApplicInterface
{
public:

    // Constructor and destructor

    DirectFnApplicInterface(const Dakota::ProblemDescDB& problem_db);
    ~DirectFnApplicInterface();

protected:

    // Virtual function redefinitions

    int derived_map_if(const Dakota::String& if_name);
    int derived_map_ac(const Dakota::String& ac_name);
    int derived_map_of(const Dakota::String& of_name);

private:

    // Data
}

} // namespace SIM
```

where the new derived class resides in the simulation's namespace. Similar to the case of [Extension](#), the [DirectFnApplicInterface::derived\\_map\\_ac\(\)](#) function is the required redefinition, and [DirectFnApplicInterface::derived\\_map\\_if\(\)](#) and [DirectFnApplicInterface::derived\\_map\\_of\(\)](#) are optional.

The new derived interface object (from namespace [SIM](#)) must now be plugged into the strategy. In the simplest case of a single model and interface, one could use

```
// retrieve the interface of interest
ModelList& all_models = problem_db.model_list();
Model& first_model = *all_models.begin();
Interface& interface = first_model.interface();
// plug in the new direct interface instance (DB does not need to be set)
interface.assign_rep(new SIM::DirectFnApplicInterface(problem_db), false);
```

from within the [Dakota](#) namespace. In a more advanced case of multiple models and multiple interface plug-ins, one might use

```
// retrieve the list of Models from the Strategy
ModelList& models = problem_db.model_list();
// iterate over the Model list
for (ModelLIter ml_iter = models.begin(); ml_iter != models.end(); ml_iter++) {
    Interface& interface = ml_iter->interface();
    if (interface.interface_type() == "direct" &&
        interface.analysis_drivers().contains("SIM") ) {
        // set the correct list nodes within the DB prior to new instantiations
        problem_db.set_db_model_nodes(ml_iter->model_id());
    }
}
```

```

    // plug in the new direct interface instance
    interface.assign_rep(new SIM::DirectFnApplicInterface(problem_db), false);
  }
}

```

New derived direct interface instances inherit various attributes of use in configuring the simulation. In particular, the [ApplicationInterface::parallelLib](#) reference provides access to MPI communicator data (e.g., the analysis communicators discussed in [Instantiating the strategy](#)), [DirectFnApplicInterface::analysisDrivers](#) provides the analysis driver names specified by the user in the input file, and [DirectFnApplicInterface::analysisComponents](#) provides additional analysis component identifiers (such as mesh file names) provided by the user which can be used to distinguish different instances of the same simulation interface.

## 12.6 Executing the strategy

Finally, with simulation configuration and plug-ins completed, we execute the strategy:

```

// run the strategy
selected_strategy.run_strategy();

```

## 12.7 Retrieving data after a run

After executing the strategy, final results can be obtained through the use of [Strategy::variables\\_results\(\)](#) and [Strategy::response\\_results\(\)](#), e.g.:

```

// retrieve the final parameter values
const Variables& vars = selected_strategy.variables_results();

// retrieve the final response values
const Response& resp = selected_strategy.response_results();

```

In the case of optimization, the final design is returned, and in the case of uncertainty quantification, the final statistics are returned.

## 12.8 Summary

To utilize the DAKOTA library within a parent software application, the basic steps of [main.C](#) and the order of invocation of these steps should be mimicked from within the parent application. Of these steps, [ParallelLibrary](#) instantiation, [ProblemDescDB::manage\\_inputs\(\)](#) and [ParallelLibrary::specify\\_outputs\\_restart\(\)](#) require the use of overloaded forms in order to function in an environment without direct command line access and, potentially, without file parsing. Additional optional steps not performed in [main.C](#) include the extension/derivation of the direct interface and the retrieval of strategy results after a run.

DAKOTA's library mode has stabilized and is now being used successfully by several Sandia and external simulation codes/frameworks.







## Chapter 13

# Performing Function Evaluations

Performing function evaluations is one of the most critical functions of the DAKOTA software. It can also be one of the most complicated, as a variety of scheduling approaches and parallelism levels are supported. This complexity manifests itself in the code through a series of cascaded member functions, from the top level model evaluation functions, through various scheduling routines, to the low level details of performing a system call, fork, or direct function invocation. This section provides an overview of the primary classes and member functions involved.

### 13.1 Synchronous function evaluations

For a synchronous (i.e., blocking) mapping of parameters to responses, an iterator invokes [Model::compute\\_response\(\)](#) to perform a function evaluation. This function is all that is seen from the iterator level, as underlying complexities are isolated. The binding of this top level function with lower level functions is as follows:

- [Model::compute\\_response\(\)](#) utilizes [Model::derived\\_compute\\_response\(\)](#) for portions of the response computation specific to derived model classes.
- [Model::derived\\_compute\\_response\(\)](#) directly or indirectly invokes [Interface::map\(\)](#).
- [Interface::map\(\)](#) utilizes [ApplicationInterface::derived\\_map\(\)](#) for portions of the mapping specific to derived application interface classes.

### 13.2 Asynchronous function evaluations

For an asynchronous (i.e., nonblocking) mapping of parameters to responses, an iterator invokes [Model::asynch\\_compute\\_response\(\)](#) multiple times to queue asynchronous jobs and then invokes either [Model::synchronize\(\)](#) or [Model::synchronize\\_nowait\(\)](#) to schedule the queued jobs in blocking or nonblocking fashion. Again, these functions are all that is seen from the iterator level, as underlying complexities are isolated. The binding of these top level functions with lower level functions is as follows:

- `Model::asynch_compute_response()` utilizes `Model::derived_asynch_compute_response()` for portions of the response computation specific to derived model classes.
- This derived model class function directly or indirectly invokes `Interface::map()` in asynchronous mode, which adds the job to a scheduling queue.
- `Model::synchronize()` or `Model::synchronize_nowait()` utilize `Model::derived_synchronize()` or `Model::derived_synchronize_nowait()` for portions of the scheduling process specific to derived model classes.
- These derived model class functions directly or indirectly invoke `Interface::synch()` or `Interface::synch_nowait()`.
- For application interfaces, these interface synchronization functions are responsible for performing evaluation scheduling in one of the following modes:
  - asynchronous local mode (using `ApplicationInterface::asynchronous_local_evaluations()` or `ApplicationInterface::asynchronous_local_evaluations_nowait()`)
  - message passing mode (using `ApplicationInterface::self_schedule_evaluations()` or `ApplicationInterface::static_schedule_evaluations()` on the iterator master and `ApplicationInterface::serve_evaluations_synch()` or `ApplicationInterface::serve_evaluations_peer()` on the servers)
  - hybrid mode (using `ApplicationInterface::self_schedule_evaluations()` or `ApplicationInterface::static_schedule_evaluations()` on the iterator master and `ApplicationInterface::serve_evaluations_asynch()` on the servers)
- These scheduling functions utilize `ApplicationInterface::derived_map()` and `ApplicationInterface::derived_map_asynch()` for portions of asynchronous job launching specific to derived application interface classes, as well as `ApplicationInterface::derived_synch()` and `ApplicationInterface::derived_synch_nowait()` for portions of job capturing specific to derived application interface classes.

### 13.3 Analyses within each function evaluation

The discussion above covers the parallelism level of concurrent function evaluations serving an iterator. For the parallelism level of concurrent analyses serving a function evaluation, similar schedulers are involved (`ForkApplicInterface::synchronous_local_analyses()`, `ForkApplicInterface::asynchronous_local_analyses()`, `ApplicationInterface::self_schedule_analyses()`, `ApplicationInterface::serve_analyses_synch()`, `ForkApplicInterface::serve_analyses_asynch()`) to support synchronous local, asynchronous local, message passing, and hybrid modes. Not all of the schedulers are elevated to the `ApplicationInterface` level since the system call and direct function interfaces do not yet support nonblocking local analyses (and therefore support synchronous local and message passing modes, but not asynchronous local or hybrid modes). Fork interfaces, however, support all modes of analysis parallelism.

## 13.4 Software Tools for DAKOTA Development

### 13.4.1 Introduction

DAKOTA development relies on Subversion for revision control and the GNU Autotools for configuration management. This section lists these tools, where to acquire recommended versions, and how to configure them.

### 13.4.2 Subversion for Version Control

The DAKOTA project uses Subversion (<http://subversion.tigris.org/>) for software version control. To check DAKOTA out of the Subversion revision control system on `development.sandia.gov`, it may be necessary to install or upgrade the Subversion client on your system. We are presently using version 1.3.2 available from <http://subversion.tigris.org/downloads/subversion-1.3.2.tar.gz>.

To configure and build Subversion from source on your machine, the following settings should be used, since DAKOTA is hosted as a FSFS-type repository and depends on the external `acro` which is stored in a repository requiring SSL certificate handling:

```
tar xzf subversion-1.3.2.tar.gz
cd subversion-1.3.2
./configure --prefix=$HOME/local --with-ssl --without-berkeley-db CFLAGS=-O2
cd neon
./configure --prefix=$HOME/local --enable-shared --with-ssl --without-berkeley-db CFLAGS=-O2
cd ..
make && make check && make -k install
```

The `make` command as specified will ensure that Subversion is only installed if it passes all its self-tests, as well as making sure that the client install works correctly. Under some conditions, the Subversion build will attempt to write to `/usr/lib`, even when a `-prefix` option is passed to `./configure`. This error may be disregarded when building the Subversion client, hence the `-k` option.

Once Subversion is working, DAKOTA (including externals) can be checked out with the single command

```
svn checkout svn+ssh://development.sandia.gov/usr/local/svn/Dakota/trunk Dakota
```

If you experience server timeouts when SVN attempts to fetch external packages through a proxy server, you might need to make a change to your `$HOME/.subversion/servers` file (generated for you the first time you run `svn`) by adding

```
[global]
http-proxy-exceptions = localhost, *.intranet.mydomain.com
http-proxy-host = wwwproxy.mydomain.com
```

to the bottom of the file. You should no longer get server timeouts when getting `acro` from `software.sandia.gov`. If you find that checking these three packages out from `software` is unacceptably slow, you may add your `hostname`

to the end of the `http-proxy-exceptions` line. Finally, `svn` will prompt you as to whether you wish to accept the SSL certificate from software; type 'p' for permanent.

To set the default editor for Subversion commits, you may add the following to `.cshrc`:

```
setenv EDITOR "xemacs -g 81X50"
```

### 13.4.3 GNU Autotools for Configuration Management

DAKOTA uses the GNU Autotools (<http://www.gnu.org/software/autoconf/>) for configuration management. Developers are currently using the following versions:

1. m4-1.4.3 (<http://ftp.gnu.org/gnu/m4/m4-1.4.3.tar.gz>)
2. libtool-1.5.22 (<http://ftp.gnu.org/gnu/libtool/libtool-1.5.22.tar.gz>)
3. automake-1.9.6 (<http://ftp.gnu.org/gnu/automake/automake-1.9.6.tar.gz>)
4. autoconf-2.59 (<http://ftp.gnu.org/gnu/autoconf/autoconf-2.59.tar.gz>)

Building the tools in the order listed above should satisfy dependencies. For each PACKAGE the following build process should suffice:

```
tar xzf $PACKAGE.tar.gz
cd $PACKAGE
./configure --prefix=$HOME/local
make
[make check]
make install
```

(Make check is useful for debugging builds of these packages, but optional and does take considerable time for some packages.)

## 13.5 Todo List

**Member `Dakota::SurfpackApproximation::SurfpackApproximation(ProblemDescDB &problem_db, const size_t &num_a`**  
The dakota data structures like RealVector inherit from std::vector.

**Member `Dakota::SurfpackApproximation::SurfpackApproximation(ProblemDescDB &problem_db, const size_t &num_a`**  
Add RBFNet surface fit interface

**Member `Dakota::SurfpackApproximation::num_coefficients() const`** : Check to make sure that the number of points required does not

**Member `Dakota::SurfpackApproximation::num_coefficients() const`** : The reported number of points required is computed in a rather

**Member `Dakota::SurfpackApproximation::find_coefficients()`** Right now, we're completely deleting the old data and then

**Member `Dakota::SurfpackApproximation::get_hessian(const RealVector &x)`** Make this acceptably efficient

**Member `Dakota::SurfpackApproximation::checkForEqualityConstraints()`** improve efficiency of conversion

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