

SAND2001-3514
Unlimited Release
Updated April 2003
Updated July 2004
Updated December 2004

DAKOTA, A Multilevel Parallel Object-Oriented Framework for Design Optimization, Parameter Estimation, Uncertainty Quantification, and Sensitivity Analysis

Version 3.3 Developers Manual

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Abstract

The DAKOTA (Design Analysis Kit for Optimization and Terascale Applications) toolkit provides a flexible and extensible interface between simulation codes and iterative analysis methods. DAKOTA contains algorithms for optimization with gradient and nongradient-based methods; uncertainty quantification with sampling, reliability, and stochastic finite element methods; parameter estimation with nonlinear least squares methods; and sensitivity/variance analysis with design of experiments and parameter study methods. These capabilities may be used on their own or as components within advanced strategies such as surrogate-based optimization, mixed integer nonlinear programming, or optimization under uncertainty. By employing object-oriented design to implement abstractions of the key components required for iterative systems analyses, the DAKOTA toolkit provides a flexible and extensible problem-solving environment for design and performance analysis of computational models on high performance computers.

This report serves as a developers manual for the DAKOTA software and describes the DAKOTA class hierarchies and their interrelationships. It derives directly from annotation of the actual source code and provides detailed class documentation, including all member functions and attributes.

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Chapter 1

DAKOTA Developers Manual

Author:

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1.1 Introduction

The DAKOTA (Design Analysis Kit for Optimization and Terascale Applications) toolkit provides a flexible, extensible interface between analysis codes and iteration methods. DAKOTA contains algorithms for optimization with gradient and nongradient-based methods, uncertainty quantification with sampling, reliability, and stochastic finite element methods, parameter estimation with nonlinear least squares methods, and sensitivity/variance analysis with design of experiments and parameter study capabilities. These capabilities may be used on their own or as components within advanced strategies such as surrogate-based optimization, mixed integer nonlinear programming, or optimization under uncertainty. By employing object-oriented design to implement abstractions of the key components required for iterative systems analyses, the DAKOTA toolkit provides a flexible problem-solving environment as well as a platform for rapid prototyping of new solution approaches.

The Developers Manual focuses on documentation of the class structures used by the DAKOTA system. It derives directly from annotation of the actual source code. For information on input command syntax, refer to the [Reference Manual](#), and for a tour of DAKOTA features and capabilities, refer to the Users Manual.

1.2 Overview of DAKOTA

In the DAKOTA system, the *strategy* creates and manages *iterators* and *models*. In the simplest case, the strategy creates a single iterator and a single model and executes the iterator on the model to perform a single study. In a more advanced case, a hybrid optimization strategy might manage a global optimizer operating on a low-fidelity model in coordination with a local optimizer operating on a high-fidelity model. And on the high end, a surrogate-based optimization under uncertainty strategy would employ an uncertainty quantification iterator nested within an optimization iterator and would employ truth models layered

within surrogate models. Thus, iterators and models provide both stand-alone capabilities as well as building blocks for more sophisticated studies.

A model contains a set of *variables*, an *interface*, and a set of *responses*, and the iterator operates on the model to map the variables into responses using the interface. Each of these components is a flexible abstraction with a variety of specializations for supporting different types of iterative studies. In a DAKOTA input file, the user specifies these components through strategy, method, variables, interface, and responses keyword specifications.

The use of class hierarchies provides a clear direction for extensibility in DAKOTA components. In each of the various class hierarchies, adding a new capability typically involves deriving a new class and providing a small number of virtual function redefinitions. These redefinitions define the coding portions specific to the new derived class, with the common portions already defined at the base class. Thus, with a small amount of new code, the existing facilities can be extended, reused, and leveraged for new purposes.

The software components are presented in the following sections using a top-down order.

1.2.1 Strategies

Class hierarchy: [Strategy](#).

Strategies provide a control layer for creation and management of iterators and models. Specific strategies include:

- [SingleMethodStrategy](#): the simplest strategy. A single iterator is run on a single model to perform a single study.
- [MultilevelOptStrategy](#): hybrid optimization using a succession of iterators employing a succession of models of varying fidelity. The best results obtained are passed from one iterator to the next.
- [SurrBasedOptStrategy](#): surrogate-based optimization. Employs a single iterator with a [LayeredModel](#) (either data fit or hierarchical). A sequence of approximate optimizations is performed, each of which involves build, optimize, and verify steps.
- [NonDOptStrategy](#): optimization under uncertainty (OUU). Employs a single optimization iterator with a [NestedModel](#). This [NestedModel](#) contains a sub-iterator and sub-model for performing uncertainty quantifications. In OUU approaches involving surrogates, [NestedModels](#) and [LayeredModels](#) can be chained together in a variety of ways using recursion in sub-models.
- [BranchBndStrategy](#): mixed integer nonlinear programming using the PICO library for parallel branch and bound. Employs a single iterator with a single model, but runs multiple instances of the iterator concurrently for different variable bounds within the model.
- [ConcurrentStrategy](#): two similar algorithms are available: (1) multi-start iteration from several different starting points, and (2) pareto set optimization for several different multiobjective weightings. Employs a single iterator with a single model, but runs multiple instances of the iterator concurrently for different settings within the model.

1.2.2 Iterators

Class hierarchy: [Iterator](#).

The iterator hierarchy contains a variety of iterative algorithms for optimization, uncertainty quantification, nonlinear least squares, design of experiments, and parameter studies. The hierarchy is divided into [Minimizer](#) and [Analyzer](#) algorithms. The [Minimizer](#) classes include:

- Optimization: [Optimizer](#) provides a base class for the [DOTOptimizer](#), [CONMINOptimizer](#), [NPSOLOptimizer](#), [rSQPOptimizer](#), and [SNLLOptimizer](#) gradient-based optimization libraries and the [SGOPTOptimizer](#), [COLINOptimizer](#), and [JEGAOptimizer](#) nongradient-based optimization libraries.
- Parameter estimation: [LeastSq](#) provides a base class for [NL2SOLLeastSq](#), a least-squares solver based on NL2SOL, [SNLLLeastSq](#), a Gauss-Newton least-squares solver, and [NLSSOLLeastSq](#), an SQP-based least-squares solver.

and the [Analyzer](#) classes include:

- Uncertainty quantification: [NonD](#) provides a base class for [NonDReliability](#) and [NonDSampling](#). [NonDSampling](#) is then further specialized with the [NonDLHSSampling](#) class for latin hypercube and Monte Carlo sampling and the [NonDPCESampling](#) class for polynomial chaos expansions.
- Parameter studies and design of experiments: [PStudyDACE](#) provides a base class for [ParamStudy](#), which provides capabilities for directed parameter space interrogation, and [DDACEDesignCompExp](#) and [FSUDesignCompExp](#), which provide for parameter space exploration through design and analysis of computer experiments. [NonDLHSSampling](#) from the uncertainty quantification branch also supports a design of experiments mode.

1.2.3 Models

Class hierarchy: [Model](#).

The model classes are responsible for mapping variables into responses when an iterator makes a function evaluation request. There are several types of models, some supporting sub-iterators and sub-models for enabling layered and nested relationships. When sub-models are used, they may be of arbitrary type so that a variety of recursions are supported.

- [SingleModel](#): variables are mapped into responses using a single [Interface](#) object. No sub-iterators or sub-models are used.
- [LayeredModel](#): variables are mapped into responses using an approximation. The approximation is built and/or corrected using data from a sub-model (the truth model) and the data may be obtained using a sub-iterator (a design of experiments iterator). [LayeredModel](#) has two derived classes: [SurrLayeredModel](#) for data fit surrogates and [HierLayeredModel](#) for hierarchical models of varying fidelity. The relationship of the sub-iterators and sub-models is considered to be "layered" since they are not used as part of every response evaluation on the top level model, but rather used periodically in surrogate update and verification steps.
- [NestedModel](#): variables are mapped into responses using a combination of an optional [Interface](#) and a sub-iterator/sub-model pair. The relationship of the sub-iterators and sub-models is considered to be "nested" since they are used to perform a complete iterative study as part of every response evaluation on the top level model.

1.2.4 Variables

Class hierarchy: [Variables](#).

The [Variables](#) class hierarchy manages design, uncertain, and state variable types for continuous and discrete domain types. This hierarchy is specialized according to various views of the data.

- [FundamentalVariables](#): both variable and domain type distinctions are retained, i.e. separate arrays for design, uncertain, and state variables types and for continuous and discrete domains.
- [AllVariables](#): variable types are combined and domain type distinction is retained, i.e. design, uncertain, and state variable types combined into a single continuous variables array and a single discrete variables array.
- [MergedVariables](#): variable type distinction is retained and domain types are combined, i.e. continuous and discrete variables merged into continuous arrays (integrality is relaxed) for design, uncertain, and state variable types.
- [AllMergedVariables](#): both variable and domain types are combined, i.e. design, uncertain, and state variable types combined (all) and continuous and discrete domain types combined (merged). The result is a single array of continuous variables.

The variables view that is chosen depends on the type of iterative study. For design optimization and uncertainty quantification, for example, variable and domain type distinctions are important and a [FundamentalVariables](#) view is used. For parameter studies and design of experiments, however, the variable type distinctions can be ignored and an [AllVariables](#) view is used. Finally, the branch and bound strategy relies on relaxation of integrality so that continuous optimizers may be used for mixed integer problems. In this case, a [MergedVariables](#) view is used. [AllMergedVariables](#) is included for completeness.

The [VarConstraints](#) hierarchy contains the same specializations for managing linear and bound constraints on the variables (see [FundamentalVarConstraints](#), [AllVarConstraints](#), [MergedVarConstraints](#), and [AllMergedVarConstraints](#)).

1.2.5 Interfaces

Class hierarchy: [Interface](#).

Interfaces provide access to simulation codes or, conversely, approximations based on simulation code data. In the simulation case, an [ApplicationInterface](#) is used. [ApplicationInterface](#) is specialized according to the simulation invocation mechanism, for which the following nonintrusive approaches

- [SysCallApplicInterface](#): the simulation is invoked using a system call (the C function `system()`). Asynchronous invocation utilizes a background system call. Utilizes the [SysCallAnalysisCode](#) class to define syntax for input filter, analysis code, output filter, or combined spawning, which in turn utilize the [CommandShell](#) utility.
- [ForkApplicInterface](#): the simulation is invoked using a fork (the `fork/exec/wait` family of functions). Asynchronous invocation utilizes a nonblocking fork. Utilizes the [ForkAnalysisCode](#) class for lower level fork operations.
- [GridApplicInterface](#): the simulation is invoked using distributed resource facilities. This capability is experimental and still under development. The design is evolving into the use of Condor and/or Globus tools.

and the following semi-intrusive approach

- [DirectFnApplicInterface](#): the simulation is linked into the DAKOTA executable and is invoked using a procedure call. Asynchronous invocation utilizes a nonblocking thread (capability not yet available).

are supported. Scheduling of jobs for asynchronous local, message passing, and hybrid parallelism approaches is performed in the [ApplicationInterface](#) class, with job initiation and job capture specifics implemented in the derived classes.

In the data fit approximation case, global, multipoint, or local approximations to simulation code response data can be built and used as surrogates for the actual, expensive simulation. The interface class providing this capability is

- [ApproximationInterface](#): builds an approximation using data from a truth model and then employs the approximation for mapping variables to responses. This class contains an array of [Approximation](#) objects, one per response function, which allows mixing of approximation types (using the [Approximation](#) derived classes: [ANNSurf](#), [KrigingSurf](#), [MARSSurf](#), [RespSurf](#), [HermiteSurf](#), and [TaylorSurf](#)).

Note: in the data fit approximation case, [SurrLayeredModel](#) provides the bulk of the surrogate management logic. It contains an [ApproximationInterface](#) object which provides the approximate parameter to response mappings. In the hierarchical approximation case, an [ApproximationInterface](#) object is not used since [HierLayeredModel](#) contains low and high fidelity application interfaces.

1.2.6 Responses

Class: [Response](#).

The [Response](#) class provides an abstract data representation of response functions and their first and second derivatives (gradient vectors and Hessian matrices). These response functions can be interpreted as an objective function and constraints (optimization data set), residual functions and constraints (least squares data set), or generic response functions (uncertainty quantification data set). This class is not currently part of a class hierarchy, since the abstraction has been sufficiently general and has not required specialization.

1.3 Services

A variety of services are provided in DAKOTA for parallel computing, failure capturing, restart, graphics, etc. An overview of the classes and member functions involved in performing these services is included below.

- Multilevel parallel computing: DAKOTA supports multiple levels of nested parallelism. A strategy can manage concurrent iterators, each of which manages concurrent function evaluations, each of which manages concurrent analyses executing on multiple processors. Partitioning of these levels with MPI communicators is managed in [ParallelLibrary](#) and scheduling routines for the levels are part of [ConcurrentStrategy](#), [ApplicationInterface](#), and [ForkApplicInterface](#).
- Parsing: DAKOTA employs the Input Deck Reader (IDR) parser to retrieve information from user input files. Parsing options are processed in [CommandLineHandler](#) and parsing occurs in [ProblemDescDB::manage_inputs\(\)](#) called from [main.C](#). IDR populates data within the [ProblemDescDB](#) support class, which maintains a [DataStrategy](#) specification and lists of [DataMethod](#), [DataVariables](#), [DataInterface](#), and [DataResponses](#) specifications. Procedures for modifying the parsing subsystem are described in [Instructions for Modifying DAKOTA's Input Specification](#).
- Failure capturing: Simulation failures can be trapped and managed using exception handling in [ApplicationInterface](#) and its derived classes.

- Restart: DAKOTA maintains a record of all function evaluations both in memory (for capturing any duplication) and on the file system (for restarting runs). Restart options are processed in [CommandLineHandler](#) and retrieved in [ParallelLibrary::specify_outputs_restart\(\)](#), restart file management occurs in [ParallelLibrary::manage_outputs_restart\(\)](#), and restart file insertions occur in [ApplicationInterface](#). The `dakota_restart_util` executable, built from [restart_util.C](#), provides a variety of services for interrogating, converting, repairing, concatenating, and post-processing restart files.
- Memory management: DAKOTA employs the techniques of reference counting and representation sharing through the use of letter-envelope and handle-body idioms (Coplien, "Advanced C++"). The former idiom provides for memory efficiency and enhanced polymorphism in the following class hierarchies: [Strategy](#), [Iterator](#), [Model](#), [Variables](#), [VarConstraints](#), [Interface](#), and [Approximation](#). The latter idiom provides for memory efficiency in data-intensive classes which do not involve a class hierarchy. Currently, only the [Response](#) class uses this idiom.
- Graphics: DAKOTA provides 2D iteration history graphics using Motif widgets and 3D surface plotting graphics from the PLPLOT package. Graphics data can also be catalogued in a tabular data file for post-processing with 3rd party tools such as Matlab, Tecplot, etc. All of these capabilities are encapsulated within the [Graphics](#) class.

1.4 Additional Resources

Additional development resources include:

- [Recommended Practices for DAKOTA Development](#)
- [Instructions for Modifying DAKOTA's Input Specification](#)
- In addition to its normal usage as a stand-alone application, DAKOTA may be interfaced as an algorithm library as described in [Interfacing with DAKOTA as a Library](#).
- The execution of function evaluations is a core component of DAKOTA involving several class hierarchies. An overview of the classes and member functions involved in performing these evaluations is provided in [Performing Function Evaluations](#).
- Project web pages are maintained at <http://endo.sandia.gov/DAKOTA> with software specifics and documentation pointers provided at <http://endo.sandia.gov/DAKOTA/software.html>, and a list of publications provided at <http://endo.sandia.gov/DAKOTA/references.html>

Chapter 2

DAKOTA Namespace Index

2.1 DAKOTA Namespace List

Here is a list of all documented namespaces with brief descriptions:

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Chapter 3

DAKOTA Hierarchical Index

3.1 DAKOTA Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

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Chapter 4

DAKOTA Class Index

4.1 DAKOTA Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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| AllMergedVariables (Derived class within the Variables hierarchy which combines the all and merged data views) | 52 |
| AllVarConstraints (Derived class within the VarConstraints hierarchy which employs the all data view) | 56 |
| AllVariables (Derived class within the Variables hierarchy which employs the all data view) . . | 59 |
| AnalysisCode (Base class providing common functionality for derived classes (SysCallAnalysisCode and ForkAnalysisCode) which spawn separate processes for managing simulations) | 63 |
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Chapter 5

DAKOTA File Index

5.1 DAKOTA File List

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Chapter 6

DAKOTA Page Index

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Chapter 7

DAKOTA Namespace Documentation

7.1

The primary namespace for DAKOTA.

Classes

- class [AllMergedVarConstraints](#)
Derived class within the [VarConstraints](#) hierarchy which combines the all and merged data views.
 - class [AllMergedVariables](#)
Derived class within the [Variables](#) hierarchy which combines the all and merged data views.
 - class [AllVarConstraints](#)
Derived class within the [VarConstraints](#) hierarchy which employs the all data view.
 - class [AllVariables](#)
Derived class within the [Variables](#) hierarchy which employs the all data view.
 - class [AnalysisCode](#)
Base class providing common functionality for derived classes ([SysCallAnalysisCode](#) and [ForkAnalysisCode](#)) which spawn separate processes for managing simulations.
 - class [ANNSurf](#)
Derived approximation class for artificial neural networks.
 - class [ApplicationInterface](#)
Derived class within the interface class hierarchy for supporting interfaces to simulation codes.
 - class [ApproximationInterface](#)
Derived class within the interface class hierarchy for supporting approximations to simulation-based results.
-

- class [BranchBndStrategy](#)
Strategy for mixed integer nonlinear programming using the PICO parallel branch and bound engine.
- class [COLINApplication](#)
- class [COLINOptimizer](#)
Wrapper class for optimizers defined using COLIN.
- class [GetLongOpt](#)
GetLongOpt is a general command line utility from S. Manoharan (Advanced Computer Research Institute, Lyon, France).
- class [CommandLineHandler](#)
Utility class for managing command line inputs to DAKOTA.
- class [CommandShell](#)
Utility class which defines convenience operators for spawning processes with system calls.
- class [ConcurrentStrategy](#)
Strategy for multi-start iteration or pareto set optimization.
- class [CONMINOptimizer](#)
Wrapper class for the CONMIN optimization library.
- class [Analyzer](#)
*Base class for *NonD*, *DACE*, and *ParamStudy* branches of the iterator hierarchy.*
- class [SurrogateDataPoint](#)
Simple container class encapsulating basic parameter and response data for defining a "truth" data point.
- class [Approximation](#)
Base class for the approximation class hierarchy.
- class [Array](#)
*Template class for the *Dakota* bookkeeping array.*
- class [BaseVector](#)
*Base class for the *Dakota::Matrix* and *Dakota::Vector* classes.*
- class [BiStream](#)
The binary input stream class. Overloads the >> operator for all data types.
- class [BoStream](#)
The binary output stream class. Overloads the << operator for all data types.
- class [Graphics](#)
*The *Graphics* class provides a single interface to 2D (motif) and 3D (PLPLOT) graphics as well as tabular cataloging of data for post-processing with Matlab, Tecplot, etc.*
- class [Interface](#)

Base class for the interface class hierarchy.

- class [Iterator](#)

Base class for the iterator class hierarchy.

- class [LeastSq](#)

Base class for the nonlinear least squares branch of the iterator hierarchy.

- class [List](#)

Template class for the [Dakota](#) bookkeeping list.

- class [FunctionCompare](#)

- class [SortCompare](#)

- class [Matrix](#)

Template class for the [Dakota](#) numerical matrix.

- class [Minimizer](#)

Base class for the optimizer and least squares branches of the iterator hierarchy.

- class [Model](#)

Base class for the model class hierarchy.

- class [NonD](#)

Base class for all nondeterministic iterators (the [DAKOTA/UQ](#) branch).

- class [Optimizer](#)

Base class for the optimizer branch of the iterator hierarchy.

- class [PStudyDACE](#)

Base class for managing common aspects of parameter studies and design of experiments methods.

- class [Response](#)

Container class for response functions and their derivatives. [Response](#) provides the handle class.

- class [ResponseRep](#)

Container class for response functions and their derivatives. [ResponseRep](#) provides the body class.

- class [Strategy](#)

Base class for the strategy class hierarchy.

- class [String](#)

[Dakota::String](#) class, used as main string class for [Dakota](#).

- class [VarConstraints](#)

Base class for the variable constraints class hierarchy.

- class [Variables](#)

Base class for the variables class hierarchy.

- class [Vector](#)

Template class for the [Dakota](#) numerical vector.

- class [DataInterface](#)
Container class for interface specification data.
- class [DataMethod](#)
Container class for method specification data.
- class [DataResponses](#)
Container class for responses specification data.
- class [DataStrategy](#)
Container class for strategy specification data.
- class [DataVariables](#)
Container class for variables specification data.
- class [DDACEDesignCompExp](#)
Wrapper class for the DDACE design of experiments library.
- class [DirectFnApplicInterface](#)
Derived application interface class which spawns simulation codes and testers using direct procedure calls.
- class [DOTOptimizer](#)
Wrapper class for the DOT optimization library.
- class [ForkAnalysisCode](#)
Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using forks.
- class [ForkApplicInterface](#)
Derived application interface class which spawns simulation codes using forks.
- class [FSUDesignCompExp](#)
Wrapper class for the FSUDace QMC/CVT library.
- class [FundamentalVarConstraints](#)
Derived class within the [VarConstraints](#) hierarchy which employs the default data view (no variable or domain type array merging).
- class [FundamentalVariables](#)
Derived class within the [Variables](#) hierarchy which employs the default data view (no variable or domain type array merging).
- class [GridApplicInterface](#)
Derived application interface class which spawns simulation codes using grid services such as Condor or Globus.
- class [HermiteSurf](#)
Derived approximation class for Hermite polynomials (global approximation).

- class [HierLayeredModel](#)
Derived model class within the layered model branch for managing hierarchical surrogates (models of varying fidelity).
- class [JEGAEvaluator](#)
This evaluator uses Sandia National Laboratories [Dakota](#) software.
- class [JEGAOptimizer](#)
Version of [Optimizer](#) for instantiation of John Eddy's Genetic Algorithms.
- class [KrigingSurf](#)
Derived approximation class for kriging interpolation.
- class [KrigApprox](#)
Utility class for kriging interpolation.
- class [LayeredModel](#)
Base class for the layered models ([SurrLayeredModel](#) and [HierLayeredModel](#)).
- class [MARSSurf](#)
Derived approximation class for multivariate adaptive regression splines.
- class [MergedVarConstraints](#)
Derived class within the [VarConstraints](#) hierarchy which employs the merged data view.
- class [MergedVariables](#)
Derived class within the [Variables](#) hierarchy which employs the merged data view.
- class [MPIPackBuffer](#)
Class for packing MPI message buffers.
- class [MPIUnpackBuffer](#)
Class for unpacking MPI message buffers.
- class [MultilevelOptStrategy](#)
[Strategy](#) for hybrid optimization using multiple optimizers on multiple models of varying fidelity.
- class [NestedModel](#)
Derived model class which performs a complete sub-iterator execution within every evaluation of the model.
- struct [NI2Misc](#)
Auxiliary information passed to `calcr` and `calcj` via `ur`.
- class [NL2SOLLeastSq](#)
Wrapper class for the NL2SOL nonlinear least squares library.
- class [NLSSOLLeastSq](#)
Wrapper class for the NLSSOL nonlinear least squares library.
- class [NonDLHSSampling](#)

Performs LHS and Monte Carlo sampling for uncertainty quantification.

- class [NonDOptStrategy](#)
Strategy for optimization under uncertainty (robust and reliability-based design).
- class [NonDPCESampling](#)
Stochastic finite element approach to uncertainty quantification using polynomial chaos expansions.
- class [NonDReliability](#)
Class for the analytical reliability methods within DAKOTA/UQ.
- class [NonDSampling](#)
Base class for common code between [NonDLHSSampling](#) and [NonDPCESampling](#).
- class [NPSOLOptimizer](#)
Wrapper class for the NPSOL optimization library.
- class [ParallelLevel](#)
Container class for the data associated with a single level of communicator partitioning.
- class [ParallelConfiguration](#)
Container class for a set of [ParallelLevel](#) list iterators that collectively identify a particular multilevel parallel configuration.
- class [ParallelLibrary](#)
Class for partitioning multiple levels of parallelism and managing message passing within these levels.
- class [ParamResponsePair](#)
Container class for a variables object, a response object, and an evaluation id.
- class [ParamStudy](#)
Class for vector, list, centered, and multidimensional parameter studies.
- struct [BaseConstructor](#)
Dummy struct for overloading letter-envelope constructors.
- struct [NoDBBaseConstructor](#)
Dummy struct for overloading constructors used in on-the-fly instantiations.
- class [ProblemDescDB](#)
The database containing information parsed from the DAKOTA input file.
- class [RespSurf](#)
Derived approximation class for polynomial regression.
- class [rSQPOptimizer](#)
- class [SGOPTApplication](#)
Maps the evaluation functions used by SGOPT algorithms to the DAKOTA evaluation functions.
- class [SGOPTOptimizer](#)

Wrapper class for the SGOPT optimization library.

- class [SingleMethodStrategy](#)
Simple fall-through strategy for running a single iterator on a single model.
- class [SingleModel](#)
Derived model class which utilizes a single interface to map variables into responses.
- class [SNLLBase](#)
Base class for OPT++ optimization and least squares methods.
- class [SNLLLeastSq](#)
Wrapper class for the OPT++ optimization library.
- class [SNLLOptimizer](#)
Wrapper class for the OPT++ optimization library.
- class [SOLBase](#)
Base class for Stanford SOL software.
- class [SurrBasedOptStrategy](#)
Strategy for provably-convergent surrogate-based optimization.
- class [SurrLayeredModel](#)
Derived model class within the layered model branch for managing data fit surrogates (global and local).
- class [SysCallAnalysisCode](#)
Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using system calls.
- class [SysCallApplicInterface](#)
Derived application interface class which spawns simulation codes using system calls.
- class [TaylorSurf](#)
Derived approximation class for first- or second-order Taylor series (local approximation).
- class [VariablesUtil](#)
Utility class for the [Variables](#) and [VarConstraints](#) hierarchies which provides convenience functions for variable vectors and label arrays for combining design, uncertain, and state variable types and merging continuous and discrete variable domains.

Typedefs

- typedef double **Real**
- typedef [Array](#)< Real > **RealArray**
- typedef [Array](#)< int > **IntArray**
- typedef [Array](#)< size_t > **SizetArray**
- typedef [Array](#)< [String](#) > **StringArray**
- typedef [Array](#)< [StringArray](#) > **String2DArray**
- typedef [Array](#)< [Variables](#) > **VariablesArray**

- typedef [Array](#)< [Response](#) > **ResponseArray**
- typedef [Array](#)< [Model](#) > **ModelArray**
- typedef [Array](#)< [Iterator](#) > **IteratorArray**
- typedef [Array](#)< [ParamResponsePair](#) > **PRPArray**
- typedef [List](#)< bool > **BoolList**
- typedef [List](#)< int > **IntList**
- typedef [List](#)< size_t > **SizetList**
- typedef [List](#)< Real > **RealList**
- typedef [List](#)< [String](#) > **StringList**
- typedef [List](#)< [Variables](#) > **VariablesList**
- typedef [List](#)< [Response](#) > **ResponseList**
- typedef [List](#)< [Model](#) > **ModelList**
- typedef [List](#)< [Iterator](#) > **IteratorList**
- typedef [List](#)< [ParamResponsePair](#) > **PRPList**
- typedef [IntList](#)::iterator **ILIter**
- typedef [IntList](#)::const_iterator **ILCIter**
- typedef [SizetList](#)::iterator **StLIter**
- typedef [SizetList](#)::const_iterator **StLCIter**
- typedef [StringList](#)::iterator **StringLIter**
- typedef [StringList](#)::const_iterator **StringLCIter**
- typedef [VariablesList](#)::iterator **VarsLIter**
- typedef [ResponseList](#)::iterator **RespLIter**
- typedef [ModelList](#)::iterator **ModelLIter**
- typedef [IteratorList](#)::iterator **IterLIter**
- typedef [PRPList](#)::iterator **PRPLIter**
- typedef [List](#)< [ParallelLevel](#) >::iterator **ParLevLIter**
- typedef [List](#)< [ParallelConfiguration](#) >::iterator **ParConfigLIter**
- typedef [Vector](#)< Real > **RealVector**
- typedef [Vector](#)< int > **IntVector**
- typedef [BaseVector](#)< Real > **RealBaseVector**
- typedef [Matrix](#)< Real > **RealMatrix**
- typedef [Matrix](#)< int > **IntMatrix**
- typedef [Array](#)< [RealVector](#) > **RealVectorArray**
- typedef [Array](#)< [RealVectorArray](#) > **RealVector2DArray**
- typedef [Array](#)< [RealBaseVector](#) > **RealBaseVectorArray**
- typedef [Array](#)< [RealMatrix](#) > **RealMatrixArray**
- typedef [List](#)< [RealVector](#) > **RealVectorList**
- typedef unsigned char **u_char**
- typedef unsigned short **u_short**
- typedef unsigned int **u_int**
- typedef unsigned long **u_long**
- typedef long long **long_long**
- typedef void(* **Vf**)()
- typedef void(* **Calcrj**)(int *n, int *p, Real *x, int *nf, Real *r, int *ui, void *ur, Vf vf)

Enumerations

- enum **LHSNames** {
NORMAL, LOGNORMAL, UNIFORM, LOGUNIFORM,
WEIBULL, CONSTANT, USERDEFINED }

Functions

- `bool operator==(const AllMergedVariables &vars1, const AllMergedVariables &vars2)`
equality operator
- `bool operator==(const AllVariables &vars1, const AllVariables &vars2)`
equality operator
- `template<> void COLINOptimizer< coliny::DIRECT >::set_rng (void)`

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- `template<> void COLINOptimizer< coliny::DIRECT >::set_method_parameters (void)`
- `template<> void COLINOptimizer< coliny::Cobyla >::set_method_parameters (void)`
- `template<> void COLINOptimizer< coliny::APPS >::set_method_parameters (void)`
- `template<> void COLINOptimizer< coliny::PatternSearch >::set_runtime_parameters ()`
- `template<> void COLINOptimizer< coliny::PatternSearch >::set_method_parameters (void)`
- `template<> void COLINOptimizer< coliny::PEAreal >::set_method_parameters (void)`
- `template<> void COLINOptimizer< coliny::SolisWets >::set_method_parameters (void)`
- `CommandShell & flush (CommandShell &shell)`
convenient shell manipulator function to "flush" the shell
- `template<class T> ostream & operator<< (ostream &s, const Array< T > &data)`
global ostream insertion operator for Array
- `template<class T> MPIPackBuffer & operator<< (MPIPackBuffer &s, const Array< T > &data)`
global MPIPackBuffer insertion operator for Array
- `template<class T> MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, Array< T > &data)`

global MPIUnpackBuffer extraction operator for Array
- `template<class T> ostream & operator<< (ostream &s, const List< T > &data)`
global ostream insertion operator for List
- `template<class T> MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, List< T > &data)`
global MPIUnpackBuffer extraction operator for List
- `template<class T> MPIPackBuffer & operator<< (MPIPackBuffer &s, const List< T > &data)`
global MPIPackBuffer insertion operator for List
- `template<class T> ostream & operator<< (ostream &s, const Matrix< T > &data)`
global ostream insertion operator for Matrix
- `template<class T> MPIUnpackBuffer & operator>> (MPIUnpackBuffer &s, Matrix< T > &data)`

global MPIUnpackBuffer extraction operator for Matrix
- `template<class T> MPIPackBuffer & operator<< (MPIPackBuffer &s, const Matrix< T > &data)`

global *MPIPackBuffer* insertion operator for *Matrix*

- `istream & operator>>` (`istream &s`, `Response &response`)
istream extraction operator for *Response*. Calls `read(istream&)`.
- `ostream & operator<<` (`ostream &s`, `const Response &response`)
ostream insertion operator for *Response*. Calls `write(ostream&)`.
- `BiStream & operator>>` (`BiStream &s`, `Response &response`)
BiStream extraction operator for *Response*. Calls `read(BiStream&)`.
- `BoStream & operator<<` (`BoStream &s`, `const Response &response`)
BoStream insertion operator for *Response*. Calls `write(BoStream&)`.
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `Response &response`)
MPIUnpackBuffer extraction operator for *Response*. Calls `read(MPIUnpackBuffer&)`.
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const Response &response`)
MPIPackBuffer insertion operator for *Response*. Calls `write(MPIPackBuffer&)`.
- `bool operator==` (`const Response &resp1`, `const Response &resp2`)
equality operator
- `bool operator!=` (`const Response &resp1`, `const Response &resp2`)
inequality operator
- `bool operator==` (`const ResponseRep &rep1`, `const ResponseRep &rep2`)
equality operator
- `String toUpper` (`const String &str`)
Return upper-case version of argument.
- `String toLower` (`const String &str`)
Return lower-case version of argument.
- `String operator+` (`const String &s1`, `const String &s2`)
Concatenate two Strings and return the resulting String.
- `String operator+` (`const char *s1`, `const String &s2`)
Append a String to a char and return the resulting String.*
- `String operator+` (`const String &s1`, `const char *s2`)
Append a char to a String and return the resulting String.*
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const String &data`)
Reads String from buffer.
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `String &data`)
Writes String to buffer.

- `istream & operator>>` (`istream &s`, `VarConstraints &vc`)
istream extraction operator for `VarConstraints`
- `ostream & operator<<` (`ostream &s`, `const VarConstraints &vc`)
ostream insertion operator for `VarConstraints`
- `istream & operator>>` (`istream &s`, `Variables &vars`)
istream extraction operator for `Variables`.
- `ostream & operator<<` (`ostream &s`, `const Variables &vars`)
ostream insertion operator for `Variables`.
- `BiStream & operator>>` (`BiStream &s`, `Variables &vars`)
`BiStream` extraction operator for `Variables`.
- `BoStream & operator<<` (`BoStream &s`, `const Variables &vars`)
`BoStream` insertion operator for `Variables`.
- `MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `Variables &vars`)
`MPIUnpackBuffer` extraction operator for `Variables`.
- `MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const Variables &vars`)
`MPIPackBuffer` insertion operator for `Variables`.
- `bool operator==` (`const Variables &vars1`, `const Variables &vars2`)
equality operator
- `bool operator!=` (`const Variables &vars1`, `const Variables &vars2`)
inequality operator
- `template<class T> istream & operator>>` (`istream &s`, `Vector< T > &data`)
global istream extraction operator for `Vector`
- `template<class T> ostream & operator<<` (`ostream &s`, `const Vector< T > &data`)
global ostream insertion operator for `Vector`
- `template<class T> MPIPackBuffer & operator<<` (`MPIPackBuffer &s`, `const Vector< T > &data`)

global `MPIPackBuffer` insertion operator for `Vector`
- `template<class T> MPIUnpackBuffer & operator>>` (`MPIUnpackBuffer &s`, `Vector< T > &data`)

global `MPIUnpackBuffer` extraction operator for `Vector`
- `bool operator==` (`const RealVector &drv1`, `const RealVector &drv2`)
equality operator for `RealVector`
- `bool operator==` (`const IntVector &div1`, `const IntVector &div2`)
equality operator for `IntVector`

- `bool operator==(const IntArray &dia1, const IntArray &dia2)`
equality operator for IntArray
- `bool operator==(const RealMatrix &drm1, const RealMatrix &drm2)`
equality operator for RealMatrix
- `bool operator==(const RealMatrixArray &drma1, const RealMatrixArray &drma2)`
equality operator for RealMatrixArray
- `bool operator==(const StringArray &dsa1, const StringArray &dsa2)`
equality operator for StringArray
- `bool operator!=(const RealVector &drv1, const RealVector &drv2)`
inequality operator for RealVector
- `bool operator!=(const IntVector &div1, const IntVector &div2)`
inequality operator for IntVector
- `bool operator!=(const IntArray &dia1, const IntArray &dia2)`
inequality operator for IntArray
- `bool operator!=(const RealMatrix &drm1, const RealMatrix &drm2)`
inequality operator for RealMatrix
- `bool operator!=(const RealMatrixArray &drma1, const RealMatrixArray &drma2)`
inequality operator for RealMatrixArray
- `bool operator!=(const StringArray &dsa1, const StringArray &dsa2)`
inequality operator for StringArray
- `void copy_data(const Real *ptr, const int ptr_len, RealVector &drv)`
copy Real to RealVector*
- `void copy_data(const Real *ptr, const int ptr_len, RealBaseVector &drbv)`
copy Real to RealBaseVector*
- `void copy_data(const Real *ptr, const int nr, const int nc, RealMatrix &drm, const String &ptr_type)`

copy Real to RealMatrix*
- `void copy_data(const RealMatrix &drm, Real *ptr, const int ptr_len, const String &ptr_type)`
*copy RealMatrix to Real**
- `void copy_data(const Real *ptr, const int num_vec, const int vec_len, RealVectorArray &drva, const String &ptr_type)`
copy Real to RealVectorArray*
- `void copy_data(const RealVector &drv, RealMatrix &drm, size_t nr, size_t nc)`
copy RealVector to RealMatrix

- void `copy_data` (const `RealVector` &drv, `RealVectorArray` &drva, size_t num_vec, size_t vec_len)
copy RealVector to RealVectorArray
- void `copy_data` (const `RealArray` &dra, `RealVector` &drv)
copy RealArray to RealVector
- void `copy_data` (const `RealBaseVector` &drbv, `RealVector` &drv)
copy RealBaseVector to RealVector
- void `copy_data` (const utilib::RealVector &rv, `RealVector` &drv)
copy utilib::RealVector to RealVector
- void `copy_data` (const `RealVector` &drv, utilib::RealVector &rv)
copy RealVector to utilib::RealVector
- void `copy_data` (const utilib::IntVector &iv, `IntVector` &div)
copy utilib::IntVector to IntVector
- void `copy_data` (const `IntVector` &div, utilib::IntVector &iv)
copy IntVector to utilib::IntVector
- void `copy_data` (const utilib::IntVector &iv, `IntArray` &dia)
copy utilib::IntVector to IntArray
- void `copy_data` (const `IntList` &dil, utilib::IntVector &iv)
copy IntList to utilib::IntVector
- void `copy_data` (const ::ColumnVector &cv, `RealBaseVector` &drbv)
copy NEWMAT::ColumnVector to RealBaseVector
- void `copy_data` (const `RealBaseVector` &drbv, ::ColumnVector &cv)
copy RealBaseVector to NEWMAT::ColumnVector
- void `copy_data` (const `RealArray` &dra, ::ColumnVector &cv)
copy RealArray to NEWMAT::ColumnVector
- void `copy_data` (const `RealMatrix` &drm, ::SymmetricMatrix &sm)
copy RealMatrix to NEWMAT::SymmetricMatrix
- void `copy_data` (const `RealMatrix` &drm, ::Matrix &m)
copy RealMatrix to NEWMAT::Matrix
- void `copy_data` (const TNT::Vector< Real > &tntv, `RealVector` &drv)
copy TNT::Vector to RealVector
- void `copy_data` (const `RealVector` &drv, TNT::Vector< Real > &tntv)
copy RealVector to TNT::Vector
- void `copy_data` (const Real *ptr, const int ptr_len, TNT::Vector< Real > &tntv)
copy Real to TNT::Vector*

- void `copy_data` (const [RealMatrix](#) &drm, TNT::Matrix< Real > &tntm)
copy RealMatrix to TNT::Matrix
- void `copy_data` (const Epetra_SerialDenseVector &psdv, [RealVector](#) &drv)
copy Epetra_SerialDenseVector to RealVector
- void `copy_data` (const [RealVector](#) &drv, Epetra_SerialDenseVector &psdv)
copy RealVector to Epetra_SerialDenseVector
- void `copy_data` (const [RealArray](#) &dra, Epetra_SerialDenseVector &psdv)
copy RealArray to Epetra_SerialDenseVector
- void `copy_data` (const [RealBaseVector](#) &drbv, Epetra_SerialDenseVector &psdv)
copy RealBaseVector to Epetra_SerialDenseVector
- void `copy_data` (const Real *ptr, const int ptr_len, Epetra_SerialDenseVector &psdv)
copy Real to Epetra_SerialDenseVector*
- void `copy_data` (const [RealMatrix](#) &drm, Epetra_SerialDenseMatrix &psdm)
copy RealMatrix to Epetra_SerialDenseMatrix
- void `copy_data` (const [RealMatrix](#) &drm, Epetra_SerialSymDenseMatrix &pssdm)
copy RealMatrix to Epetra_SerialSymDenseMatrix
- void `copy_data` (const ::ColumnVector &cv, Epetra_SerialDenseVector &psdv)
copy NEWMAT::ColumnVector to Epetra_SerialDenseVector
- void `copy_data` (const ::Array< DDaceSamplePoint > &dspa, [RealVectorArray](#) &drva)
copy DDACE Array to RealVectorArray
- void `copy_data` (const ::Array< DDaceSamplePoint > &dspa, double *darray)
copy DDACE Array to RealVectorArray
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &s, const [DataInterface](#) &data)
MPIPackBuffer insertion operator for DataInterface.
- [MPIUnpackBuffer](#) & `operator>>` ([MPIUnpackBuffer](#) &s, [DataInterface](#) &data)
MPIUnpackBuffer extraction operator for DataInterface.
- `ostream` & `operator<<` (`ostream` &s, const [DataInterface](#) &data)
ostream insertion operator for DataInterface
- bool `interface_compare` (const [DataInterface](#) &di, void *search_di)
global comparison function for DataInterface
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &s, const [DataMethod](#) &data)
MPIPackBuffer insertion operator for DataMethod.
- [MPIUnpackBuffer](#) & `operator>>` ([MPIUnpackBuffer](#) &s, [DataMethod](#) &data)

MPIUnpackBuffer extraction operator for *DataMethod*.

- ostream & operator<< (ostream &s, const [DataMethod](#) &data)
ostream insertion operator for DataMethod
- bool [method_compare](#) (const [DataMethod](#) &dm, void *search_dm)
global comparison function for DataMethod
- [MPIPackBuffer](#) & operator<< ([MPIPackBuffer](#) &s, const [DataResponses](#) &data)
MPIPackBuffer insertion operator for DataResponses.
- [MPIUnpackBuffer](#) & operator>> ([MPIUnpackBuffer](#) &s, [DataResponses](#) &data)
MPIUnpackBuffer extraction operator for DataResponses.
- ostream & operator<< (ostream &s, const [DataResponses](#) &data)
ostream insertion operator for DataResponses
- bool [responses_compare](#) (const [DataResponses](#) &dr, void *search_dr)
global comparison function for DataResponses
- [MPIPackBuffer](#) & operator<< ([MPIPackBuffer](#) &s, const [DataStrategy](#) &data)
MPIPackBuffer insertion operator for DataStrategy.
- [MPIUnpackBuffer](#) & operator>> ([MPIUnpackBuffer](#) &s, [DataStrategy](#) &data)
MPIUnpackBuffer extraction operator for DataStrategy.
- ostream & operator<< (ostream &s, const [DataStrategy](#) &data)
ostream insertion operator for DataStrategy
- [MPIPackBuffer](#) & operator<< ([MPIPackBuffer](#) &s, const [DataVariables](#) &data)
MPIPackBuffer insertion operator for DataVariables.
- [MPIUnpackBuffer](#) & operator>> ([MPIUnpackBuffer](#) &s, [DataVariables](#) &data)
MPIUnpackBuffer extraction operator for DataVariables.
- ostream & operator<< (ostream &s, const [DataVariables](#) &data)
ostream insertion operator for DataVariables
- bool [variables_compare](#) (const [DataVariables](#) &dv, void *search_dv)
global comparison function for DataVariables
- int [salinas_main](#) (int argc, char *argv[], [MPI_Comm](#) *comm)
subroutine interface to SALINAS simulation code
- bool operator== (const [FundamentalVariables](#) &vars1, const [FundamentalVariables](#) &vars2)
equality operator
- template<typename T> string [asstring](#) (const T &val)
Creates a string from the argument "val" using an ostream.

- `bool operator==` (const [MergedVariables](#) &vars1, const [MergedVariables](#) &vars2)
equality operator
- **PACKBUF** (int, MPI_INT)
- **UNPACKBUF** (int, MPI_INT)
- **PACKSIZE** (int, MPI_INT)
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const int &data)
insert an int
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const u_int &data)
insert a u_int
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const long &data)
insert a long
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const u_long &data)
insert a u_long
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const short &data)
insert a short
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const u_short &data)
insert a u_short
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const char &data)
insert a char
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const u_char &data)
insert a u_char
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const double &data)
insert a double
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const float &data)
insert a float
- [MPIPackBuffer](#) & `operator<<` ([MPIPackBuffer](#) &buff, const bool &data)
insert a bool
- [MPIUnpackBuffer](#) & `operator>>` ([MPIUnpackBuffer](#) &buff, int &data)
extract an int
- [MPIUnpackBuffer](#) & `operator>>` ([MPIUnpackBuffer](#) &buff, u_int &data)
extract a u_int
- [MPIUnpackBuffer](#) & `operator>>` ([MPIUnpackBuffer](#) &buff, long &data)
extract a long
- [MPIUnpackBuffer](#) & `operator>>` ([MPIUnpackBuffer](#) &buff, u_long &data)
extract a u_long

- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, short &data)`
extract a short
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, u_short &data)`
extract a u_short
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, char &data)`
extract a char
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, u_char &data)`
extract a u_char
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, double &data)`
extract a double
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, float &data)`
extract a float
- `MPIUnpackBuffer & operator>> (MPIUnpackBuffer &buff, bool &data)`
extract a bool
- `int MPIPackSize (const int &data, const int num=1)`
return packed size of an int
- `int MPIPackSize (const u_int &data, const int num=1)`
return packed size of a u_int
- `int MPIPackSize (const long &data, const int num=1)`
return packed size of a long
- `int MPIPackSize (const u_long &data, const int num=1)`
return packed size of a u_long
- `int MPIPackSize (const short &data, const int num=1)`
return packed size of a short
- `int MPIPackSize (const u_short &data, const int num=1)`
return packed size of a u_short
- `int MPIPackSize (const char &data, const int num=1)`
return packed size of a char
- `int MPIPackSize (const u_char &data, const int num=1)`
return packed size of a u_char
- `int MPIPackSize (const double &data, const int num=1)`
return packed size of a double
- `int MPIPackSize (const float &data, const int num=1)`

return packed size of a float

- int [MPIPackSize](#) (const bool &data, const int num=1)
return packed size of a bool
- void [dn2f_](#) (int *n, int *p, Real *x, Calcrcj, int *iv, int *liv, int *lv, Real *v, int *ui, void *ur, Vf)
- void [dn2fb_](#) (int *n, int *p, Real *x, Real *b, Calcrcj, int *iv, int *liv, int *lv, Real *v, int *ui, void *ur, Vf)
- void [dn2g_](#) (int *n, int *p, Real *x, Calcrcj, Calcrcj, int *iv, int *liv, int *lv, Real *v, int *ui, void *ur, Vf)
- void [dn2gb_](#) (int *n, int *p, Real *x, Real *b, Calcrcj, Calcrcj, int *iv, int *liv, int *lv, Real *v, int *ui, void *ur, Vf)
- void [divset_](#) (int *, int *, int *, int *, Real *)
- double [dr7mdc_](#) (int *)
- void [calcr](#) (int *np, int *pp, Real *x, int *nfp, Real *r, int *ui, void *ur, Vf vf)
- void [calcj](#) (int *np, int *pp, Real *x, int *nfp, Real *J, int *ui, void *ur, Vf vf)
- double [rnum1](#) (void)
- double [rnum2](#) (void)
- void [abort_handler](#) (int code)
global function which handles serial or parallel aborts
- istream & [operator>>](#) (istream &s, [ParamResponsePair](#) &pair)
istream extraction operator for [ParamResponsePair](#)
- ostream & [operator<<](#) (ostream &s, const [ParamResponsePair](#) &pair)
ostream insertion operator for [ParamResponsePair](#)
- [BiStream](#) & [operator>>](#) ([BiStream](#) &s, [ParamResponsePair](#) &pair)
[BiStream](#) extraction operator for [ParamResponsePair](#).
- [BoStream](#) & [operator<<](#) ([BoStream](#) &s, const [ParamResponsePair](#) &pair)
[BoStream](#) insertion operator for [ParamResponsePair](#).
- [MPIUnpackBuffer](#) & [operator>>](#) ([MPIUnpackBuffer](#) &s, [ParamResponsePair](#) &pair)
[MPIUnpackBuffer](#) extraction operator for [ParamResponsePair](#).
- [MPIPackBuffer](#) & [operator<<](#) ([MPIPackBuffer](#) &s, const [ParamResponsePair](#) &pair)
[MPIPackBuffer](#) insertion operator for [ParamResponsePair](#).
- bool [operator==](#) (const [ParamResponsePair](#) &pair1, const [ParamResponsePair](#) &pair2)
equality operator
- bool [operator!=](#) (const [ParamResponsePair](#) &pair1, const [ParamResponsePair](#) &pair2)
inequality operator
- bool [vars_asv_compare](#) (const [ParamResponsePair](#) &database_pr, void *search_pr)
search function for a particular [ParamResponsePair](#) within a [List](#)
- bool [eval_id_compare](#) (const [ParamResponsePair](#) &pair, void *id)
search function for a particular [ParamResponsePair](#) within a [List](#)

- bool `eval_id_sort_fn` (const `ParamResponsePair` &pr1, const `ParamResponsePair` &pr2)
sort function for `ParamResponsePair`
- void `print_restart` (int argc, char **argv, `String` print_dest)
print a restart file
- void `print_restart_tabular` (int argc, char **argv, `String` print_dest)
print a restart file (tabular format)
- void `read_neutral` (int argc, char **argv)
read a restart file (neutral file format)
- void `repair_restart` (int argc, char **argv, `String` identifier_type)
repair a restart file by removing corrupted evaluations
- void `concatenate_restart` (int argc, char **argv)
concatenate multiple restart files

Variables

- `ParallelLibrary dummy_lib` (0)
dummy `ParallelLibrary` object used for mandatory initializations when a real `ParallelLibrary` instance is unavailable
- `ProblemDescDB dummy_db` (`dummy_lib`)
dummy `ProblemDescDB` object used for mandatory initializations when a real `ProblemDescDB` instance is unavailable
- `Graphics dakota_graphics`
the global `Dakota::Graphics` object used by strategies, models, and approximations
- const int `MAXPOSDEF` = 10
- const int `NONRANDOM` = 0
- const int `RANDOM` = 1
- `Dakota::GSL_Singleton GSL_RNG`
- ostream * `dakota_cout` = &cout
DAKOTA stdout initially points to cout, but may be redirected to a tagged ofstream if there are concurrent iterators.
- ostream * `dakota_cerr` = &cerr
DAKOTA stderr initially points to cerr, but may be redirected to a tagged ofstream if there are concurrent iterators.
- `PRPList data_pairs`
list of all parameter/response pairs
- `BoStream write_restart`

the restart binary output stream (doesn't really need to be global anymore except for Parallel-Library::abort_handler())

- int `mc_ptr_int` = 0
global pointer for ModelCenter API
- const int `LARGE_SCALE` = 100

7.1.1 Detailed Description

The primary namespace for DAKOTA.

The Dakota namespace encapsulates the core classes of the DAKOTA framework and prevents name clashes with third-party libraries from VendorOptimizers and VendorPackages. The C++ source files defining these core classes reside in Dakota/src as *.[CH].

7.1.2 Function Documentation

7.1.2.1 void `COLINOptimizer`< `coliny::DIRECT` >::`set_method_parameters` (void)

specialization of `set_method_parameters()` for DIRECT

7.1.2.2 void `COLINOptimizer`< `coliny::Cobyla` >::`set_method_parameters` (void)

specialization of `set_method_parameters()` for Cobyla

7.1.2.3 void `COLINOptimizer`< `coliny::APPS` >::`set_method_parameters` (void)

specialization of `set_method_parameters()` for APPS

7.1.2.4 void `COLINOptimizer`< `coliny::PatternSearch` >::`set_runtime_parameters` ()

specialization of `set_runtime_parameters()` for PatternSearch

7.1.2.5 void `COLINOptimizer`< `coliny::PatternSearch` >::`set_method_parameters` (void)

specialization of `set_method_parameters()` for PatternSearch

7.1.2.6 void `COLINOptimizer`< `coliny::PEAreal` >::`set_method_parameters` (void)

specialization of `set_method_parameters()` for PEAreal

7.1.2.7 void `COLINOptimizer`< `coliny::SolisWets` >::`set_method_parameters` (void)

specialization of `set_method_parameters()` for SolisWets

7.1.2.8 CommandShell & flush (CommandShell & shell)

convenient shell manipulator function to "flush" the shell

global convenience function for manipulating the shell; invokes the class member flush function.

7.1.2.9 String toUpper (const String & str)

Return upper-case version of argument.

Returns a [String](#) converted to upper case. Calls the [String](#) upper() method.

7.1.2.10 String toLower (const String & str)

Return lower-case version of argument.

Returns a [String](#) converted to lower case. Calls the [String](#) lower() method.

7.1.2.11 bool operator== (const FundamentalVariables & vars1, const FundamentalVariables & vars2)

equality operator

Checks each fundamental array using operator== from [data_types.C](#). Labels are ignored.

7.1.2.12 bool vars_asv_compare (const ParamResponsePair & database_pr, void * search_pr) [inline]

search function for a particular [ParamResponsePair](#) within a [List](#)

a global function to compare the parameter values, ASV, & interface id of a particular database_pr (presumed to be in the global history list) with a passed in set of parameters, ASV, & interface id provided by search_pr.

7.1.2.13 bool eval_id_compare (const ParamResponsePair & pair, void * id) [inline]

search function for a particular [ParamResponsePair](#) within a [List](#)

a global function to compare the evalId of a particular [ParamResponsePair](#) (from a [List](#)) with a passed in evaluation id. *((int*)id) construct casts void* to int* and then dereferences.

7.1.2.14 bool eval_id_sort_fn (const ParamResponsePair & pr1, const ParamResponsePair & pr2) [inline]

sort function for [ParamResponsePair](#)

a global function used to sort a PRPList by evalId's.

7.1.2.15 void print_restart (int argc, char ** argv, String print_dest)

print a restart file

Usage: "dakota_restart_util print dakota.rst"

"dakota_restart_util to_neutral dakota.rst dakota.neu"

Prints all evals. in full precision to either stdout or a neutral file. The former is useful for ensuring that duplicate detection is successful in a restarted run (e.g., starting a new method from the previous best), and the latter is used for translating binary files between platforms.

7.1.2.16 void print_restart_tabular (int argc, char ** argv, String print_dest)

print a restart file (tabular format)

Usage: "dakota_restart_util to_pdb dakota.rst dakota.pdb"

"dakota_restart_util to_tabular dakota.rst dakota.txt"

Unrolls all data associated with a particular tag for all evaluations and then writes this data in a tabular format (e.g., to a PDB database or MATLAB/TECPLOT data file).

7.1.2.17 void read_neutral (int argc, char ** argv)

read a restart file (neutral file format)

Usage: "dakota_restart_util from_neutral dakota.neu dakota.rst"

Reads evaluations from a neutral file. This is used for translating binary files between platforms.

7.1.2.18 void repair_restart (int argc, char ** argv, String identifier_type)

repair a restart file by removing corrupted evaluations

Usage: "dakota_restart_util remove 0.0 dakota_old.rst dakota_new.rst"

"dakota_restart_util remove_ids 2 7 13 dakota_old.rst dakota_new.rst"

Repairs a restart file by removing corrupted evaluations. The identifier for evaluation removal can be either a double precision number (all evaluations having a matching response function value are removed) or a list of integers (all evaluations with matching evaluation ids are removed).

7.1.2.19 void concatenate_restart (int argc, char ** argv)

concatenate multiple restart files

Usage: "dakota_restart_util cat dakota_1.rst ... dakota_n.rst dakota_new.rst"

Combines multiple restart files into a single restart database.

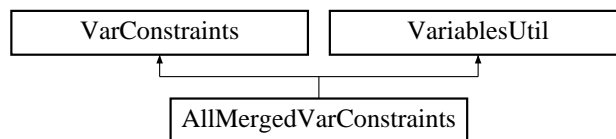
Chapter 8

DAKOTA Class Documentation

8.1 AllMergedVarConstraints Class Reference

Derived class within the [VarConstraints](#) hierarchy which combines the all and merged data views.

Inheritance diagram for AllMergedVarConstraints::



Public Member Functions

- [AllMergedVarConstraints](#) (const [ProblemDescDB](#) &problem_db)
constructor
 - [~AllMergedVarConstraints](#) ()
destructor
 - const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds
 - void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds
 - const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds
 - void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds
-

- `const IntVector & discrete_lower_bounds () const`
return the active discrete variable lower bounds
- `void discrete_lower_bounds (const IntVector &d_l_bnds)`
set the active discrete variable lower bounds
- `const IntVector & discrete_upper_bounds () const`
return the active discrete variable upper bounds
- `void discrete_upper_bounds (const IntVector &d_u_bnds)`
set the active discrete variable upper bounds
- `RealVector all_continuous_lower_bounds () const`
returns a single array with all continuous lower bounds
- `RealVector all_continuous_upper_bounds () const`
returns a single array with all continuous upper bounds
- `IntVector all_discrete_lower_bounds () const`
returns a single array with all discrete lower bounds
- `IntVector all_discrete_upper_bounds () const`
returns a single array with all discrete upper bounds
- `void write (ostream &s) const`
write a variable constraints object to an ostream
- `void read (istream &s)`
read a variable constraints object from an istream

Private Attributes

- `RealVector allMergedLowerBnds`
a continuous lower bounds array combining design, uncertain, and state variable types and merging continuous and discrete domains. The order is continuous design, discrete design, uncertain, continuous state, and discrete state.
- `RealVector allMergedUpperBnds`
a continuous upper bounds array combining design, uncertain, and state variable types and merging continuous and discrete domains. The order is continuous design, discrete design, uncertain, continuous state, and discrete state.

8.1.1 Detailed Description

Derived class within the `VarConstraints` hierarchy which combines the all and merged data views.

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [AllMergedVarConstraints](#) derived class combines design, uncertain, and state variable types (all) and continuous and discrete domain types (merged). The result is a single continuous lower bounds array (`allMergedLowerBnds`) and a single continuous upper bounds array (`allMergedUpperBnds`). No iterators/strategies currently use this approach; it is included for completeness and future capability.

8.1.2 Constructor & Destructor Documentation

8.1.2.1 [AllMergedVarConstraints](#) (const [ProblemDescDB](#) & *problem_db*)

constructor

Extract fundamental variable bounds and combine them into `allMergedLowerBnds` and `allMergedUpperBnds` using utilities from [VariablesUtil](#).

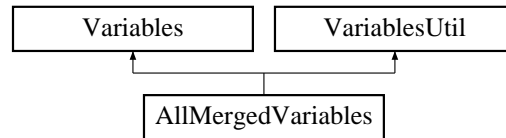
The documentation for this class was generated from the following files:

- [AllMergedVarConstraints.H](#)
- [AllMergedVarConstraints.C](#)

8.2 AllMergedVariables Class Reference

Derived class within the [Variables](#) hierarchy which combines the all and merged data views.

Inheritance diagram for AllMergedVariables::



Public Member Functions

- [AllMergedVariables](#) ()
default constructor
- [AllMergedVariables](#) (const [ProblemDescDB](#) &problem_db)
standard constructor
- [~AllMergedVariables](#) ()
destructor
- size_t [tv](#) () const
Returns total number of vars.
- size_t [cv](#) () const
Returns number of active continuous vars.
- size_t [dv](#) () const
Returns number of active discrete vars.
- const [RealVector](#) & [continuous_variables](#) () const
return the active continuous variables
- void [continuous_variables](#) (const [RealVector](#) &c_vars)
set the active continuous variables
- const [IntVector](#) & [discrete_variables](#) () const
return the active discrete variables
- void [discrete_variables](#) (const [IntVector](#) &d_vars)
set the active discrete variables
- const [StringArray](#) & [continuous_variable_labels](#) () const
return the active continuous variable labels

- void `continuous_variable_labels` (const `StringArray` &cv_labels)
set the active continuous variable labels
- const `StringArray` & `discrete_variable_labels` () const
return the active discrete variable labels
- void `discrete_variable_labels` (const `StringArray` &dv_labels)
set the active discrete variable labels
- size_t `acv` () const
returns total number of continuous vars
- size_t `adv` () const
returns total number of discrete vars
- `RealVector` `all_continuous_variables` () const
returns a single array with all continuous variables
- `IntVector` `all_discrete_variables` () const
returns a single array with all discrete variables
- `StringArray` `all_continuous_variable_labels` () const
returns a single array with all continuous variable labels
- `StringArray` `all_discrete_variable_labels` () const
returns a single array with all discrete variable labels
- `StringArray` `all_variable_labels` () const
returns a single array with all variable labels
- void `read` (istream &s)
read a variables object from an istream
- void `write` (ostream &s) const
write a variables object to an ostream
- void `write_aprepro` (ostream &s) const
write a variables object to an ostream in aprepro format
- void `read_annotated` (istream &s)
read a variables object in annotated format from an istream
- void `write_annotated` (ostream &s) const
write a variables object in annotated format to an ostream
- void `write_tabular` (ostream &s) const
write a variables object in tabular format to an ostream
- void `read` (`BiStream` &s)

read a variables object from the binary restart stream

- void [write](#) ([BoStream](#) &s) const
write a variables object to the binary restart stream
- void [read](#) ([MPIUnpackBuffer](#) &s)
read a variables object from a packed MPI buffer
- void [write](#) ([MPIPackBuffer](#) &s) const
write a variables object to a packed MPI buffer

Private Member Functions

- void [copy_rep](#) (const [Variables](#) *vars_rep)
Used by [copy\(\)](#) to copy the contents of a letter class.

Private Attributes

- [RealVector](#) [allMergedVars](#)
a continuous array combining design, uncertain, and state variable types and merging continuous and discrete domains. The order is continuous design, discrete design, uncertain, continuous state, and discrete state.
- [StringArray](#) [allMergedLabels](#)
an array containing labels for continuous design, discrete design, uncertain, continuous state, and discrete state variables

Friends

- bool [operator==](#) (const [AllMergedVariables](#) &vars1, const [AllMergedVariables](#) &vars2)
equality operator

8.2.1 Detailed Description

Derived class within the [Variables](#) hierarchy which combines the all and merged data views.

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [AllMergedVariables](#) derived class combines design, uncertain, and state variable types (all) and continuous and discrete domain types (merged). The result is a single array of continuous variables ([allMergedVars](#)). No iterators/strategies currently use this approach; it is included for completeness and future capability.

8.2.2 Constructor & Destructor Documentation

8.2.2.1 AllMergedVariables (const ProblemDescDB & problem_db)

standard constructor

Extract fundamental variable types and labels and combine them into allMergedVars and allMergedLabels using utilities from [VariablesUtil](#).

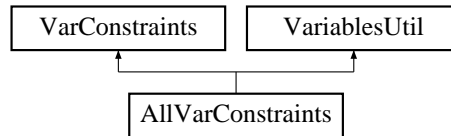
The documentation for this class was generated from the following files:

- AllMergedVariables.H
- AllMergedVariables.C

8.3 AllVarConstraints Class Reference

Derived class within the [VarConstraints](#) hierarchy which employs the all data view.

Inheritance diagram for AllVarConstraints::



Public Member Functions

- [AllVarConstraints](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~AllVarConstraints](#) ()
destructor
- const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds
- void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds
- const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds
- void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds
- const [IntVector](#) & [discrete_lower_bounds](#) () const
return the active discrete variable lower bounds
- void [discrete_lower_bounds](#) (const [IntVector](#) &d_l_bnds)
set the active discrete variable lower bounds
- const [IntVector](#) & [discrete_upper_bounds](#) () const
return the active discrete variable upper bounds
- void [discrete_upper_bounds](#) (const [IntVector](#) &d_u_bnds)
set the active discrete variable upper bounds
- [RealVector](#) [all_continuous_lower_bounds](#) () const
returns a single array with all continuous lower bounds

- [RealVector all_continuous_upper_bounds](#) () const
returns a single array with all continuous upper bounds
- [IntVector all_discrete_lower_bounds](#) () const
returns a single array with all discrete lower bounds
- [IntVector all_discrete_upper_bounds](#) () const
returns a single array with all discrete upper bounds
- void [write](#) (ostream &s) const
write a variable constraints object to an ostream
- void [read](#) (istream &s)
read a variable constraints object from an istream

Private Attributes

- [RealVector allContinuousLowerBnds](#)
a continuous lower bounds array combining continuous design, uncertain, and continuous state variable types (all view).
- [RealVector allContinuousUpperBnds](#)
a continuous upper bounds array combining continuous design, uncertain, and continuous state variable types (all view).
- [IntVector allDiscreteLowerBnds](#)
a discrete lower bounds array combining discrete design and discrete state variable types (all view).
- [IntVector allDiscreteUpperBnds](#)
a discrete upper bounds array combining discrete design and discrete state variable types (all view).
- size_t [numCDV](#)
number of continuous design variables
- size_t [numDDV](#)
number of discrete design variables
- size_t [numUV](#)
number of uncertain variables
- size_t [numCSV](#)
number of continuous state variables
- size_t [numDSV](#)
number of discrete state variables

8.3.1 Detailed Description

Derived class within the [VarConstraints](#) hierarchy which employs the all data view.

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [AllVarConstraints](#) derived class combines design, uncertain, and state variable types but separates continuous and discrete domain types. The result is combined continuous bounds arrays ([allContinuousLowerBnds](#), [allContinuousUpperBnds](#)) and combined discrete bounds arrays ([allDiscreteLowerBnds](#), [allDiscreteUpperBnds](#)). Parameter and DACE studies currently use this approach (see [Variables::get_variables\(problem_db\)](#) for variables type selection; variables type is passed to the [VarConstraints](#) constructor in [Model](#)).

8.3.2 Constructor & Destructor Documentation

8.3.2.1 [AllVarConstraints](#) (const [ProblemDescDB](#) & *problem_db*)

constructor

Extract fundamental lower and upper bounds and combine them into [allContinuousLowerBnds](#), [allContinuousUpperBnds](#), [allDiscreteLowerBnds](#), and [allDiscreteUpperBnds](#) using utilities from [VariablesUtil](#).

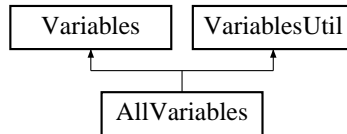
The documentation for this class was generated from the following files:

- [AllVarConstraints.H](#)
- [AllVarConstraints.C](#)

8.4 AllVariables Class Reference

Derived class within the [Variables](#) hierarchy which employs the all data view.

Inheritance diagram for AllVariables::



Public Member Functions

- [AllVariables](#) ()
default constructor
- [AllVariables](#) (const [ProblemDescDB](#) &problem_db)
standard constructor
- [~AllVariables](#) ()
destructor
- `size_t tv () const`
Returns total number of vars.
- `size_t cv () const`
Returns number of active continuous vars.
- `size_t dv () const`
Returns number of active discrete vars.
- `const RealVector & continuous_variables () const`
return the active continuous variables
- `void continuous_variables (const RealVector &c_vars)`
set the active continuous variables
- `const IntVector & discrete_variables () const`
return the active discrete variables
- `void discrete_variables (const IntVector &d_vars)`
set the active discrete variables
- `const StringArray & continuous_variable_labels () const`
return the active continuous variable labels

- void `continuous_variable_labels` (const `StringArray` &cv_labels)
set the active continuous variable labels
- const `StringArray` & `discrete_variable_labels` () const
return the active discrete variable labels
- void `discrete_variable_labels` (const `StringArray` &dv_labels)
set the active discrete variable labels
- size_t `acv` () const
returns total number of continuous vars
- size_t `adv` () const
returns total number of discrete vars
- `RealVector` `all_continuous_variables` () const
returns a single array with all continuous variables
- `IntVector` `all_discrete_variables` () const
returns a single array with all discrete variables
- `StringArray` `all_continuous_variable_labels` () const
returns a single array with all continuous variable labels
- `StringArray` `all_discrete_variable_labels` () const
returns a single array with all discrete variable labels
- `StringArray` `all_variable_labels` () const
returns a single array with all variable labels
- void `read` (istream &s)
read a variables object from an istream
- void `write` (ostream &s) const
write a variables object to an ostream
- void `write_aprepro` (ostream &s) const
write a variables object to an ostream in aprepro format
- void `read_annotated` (istream &s)
read a variables object in annotated format from an istream
- void `write_annotated` (ostream &s) const
write a variables object in annotated format to an ostream
- void `write_tabular` (ostream &s) const
write a variables object in tabular format to an ostream
- void `read` (`BiStream` &s)

read a variables object from the binary restart stream

- void [write](#) ([BoStream](#) &s) const
write a variables object to the binary restart stream
- void [read](#) ([MPIUnpackBuffer](#) &s)
read a variables object from a packed MPI buffer
- void [write](#) ([MPIPackBuffer](#) &s) const
write a variables object to a packed MPI buffer

Private Member Functions

- void [copy_rep](#) (const [Variables](#) *vars_rep)
Used by [copy\(\)](#) to copy the contents of a letter class.

Private Attributes

- [RealVector](#) [allContinuousVars](#)
a continuous array combining all of the continuous variables (design, uncertain, and state).
- [IntVector](#) [allDiscreteVars](#)
a discrete array combining all of the discrete variables (design and state).
- [StringArray](#) [allContinuousLabels](#)
a label array combining all of the continuous variable labels (design, uncertain, and state).
- [StringArray](#) [allDiscreteLabels](#)
a label array combining all of the discrete variable labels (design and state).
- size_t [numCDV](#)
number of continuous design variables
- size_t [numDDV](#)
number of discrete design variables
- size_t [numUV](#)
number of uncertain variables
- size_t [numCSV](#)
number of continuous state variables
- size_t [numDSV](#)
number of discrete state variables

Friends

- bool `operator==` (const [AllVariables](#) &vars1, const [AllVariables](#) &vars2)
equality operator

8.4.1 Detailed Description

Derived class within the [Variables](#) hierarchy which employs the all data view.

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [AllVariables](#) derived class combines design, uncertain, and state variable types but separates continuous and discrete domain types. The result is a single array of continuous variables (`allContinuousVars`) and a single array of discrete variables (`allDiscreteVars`). Parameter and DACE studies currently use this approach (see `Variables::get_variables(problem_db)`).

8.4.2 Constructor & Destructor Documentation

8.4.2.1 [AllVariables](#) (const [ProblemDescDB](#) & *problem_db*)

standard constructor

Extract fundamental variable types and labels and combine them into `allContinuousVars`, `allDiscreteVars`, `allContinuousLabels`, and `allDiscreteLabels` using utilities from [VariablesUtil](#).

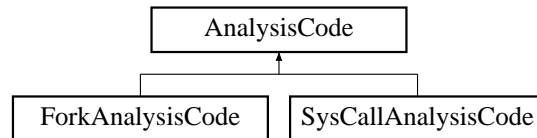
The documentation for this class was generated from the following files:

- `AllVariables.H`
- `AllVariables.C`

8.5 AnalysisCode Class Reference

Base class providing common functionality for derived classes ([SysCallAnalysisCode](#) and [ForkAnalysisCode](#)) which spawn separate processes for managing simulations.

Inheritance diagram for AnalysisCode::



Public Member Functions

- void [define_filenames](#) (const int id)
define modified filenames from user input by handling Unix temp file and tagging options
- void [write_parameters_file](#) (const [Variables](#) &vars, const [IntArray](#) &asv, const int id)
write the variables and active set vector objects to the parameters file in either standard or aprepro format
- void [read_results_file](#) ([Response](#) &response, const int id)
read the response object from the results file
- const [StringArray](#) & [program_names](#) () const
return programNames
- const [String](#) & [input_filter_name](#) () const
return iFilterName
- const [String](#) & [output_filter_name](#) () const
return oFilterName
- const [String](#) & [modified_parameters_filename](#) () const
return modifiedParamsFileName
- const [String](#) & [modified_results_filename](#) () const
return modifiedResFileName
- const [String](#) & [results_fname](#) (const int id) const
return the entry in resultsFNameList corresponding to id
- void [suppress_output_flag](#) (const bool flag)
set suppressOutputFlag
- bool [suppress_output_flag](#) () const
return suppressOutputFlag

Protected Member Functions

- [AnalysisCode](#) (const [ProblemDescDB](#) &problem_db)
constructor
- virtual [~AnalysisCode](#) ()
destructor

Protected Attributes

- bool [suppressOutputFlag](#)
flag set by master processor to suppress output from slave processors
- bool [verboseFlag](#)
flag for additional analysis code output if method verbosity is set
- bool [fileTagFlag](#)
flags tagging of parameter/results files
- bool [fileSaveFlag](#)
flags retention of parameter/results files
- bool [apreproFlag](#)
flags use of the APREPRO (the Sandia "A PRE PROcessor" utility) format for parameter files
- [String](#) [iFilterName](#)
the name of the input filter (input_filter user specification)
- [String](#) [oFilterName](#)
the name of the output filter (output_filter user specification)
- [StringArray](#) [programNames](#)
the names of the analysis code programs (analysis_drivers user specification)
- [size_t](#) [numPrograms](#)
the number of analysis code programs (length of programNames list)
- [String](#) [parametersFileName](#)
the name of the parameters file from user specification
- [String](#) [modifiedParamsFileName](#)
the parameters file name actually used (modified with tagging or temp files)
- [String](#) [resultsFileName](#)
the name of the results file from user specification
- [String](#) [modifiedResFileName](#)
the results file name actually used (modified with tagging or temp files)

- [StringList parametersFNameList](#)
list of parameters file names used in spawning function evaluations
- [StringList resultsFNameList](#)
list of results file names used in spawning function evaluations
- [IntList fileNameKey](#)
stores function evaluation identifiers to allow key-based retrieval of file names from parametersFNameList and resultsFNameList

Private Attributes

- [ParallelLibrary](#) & [parallelLib](#)
reference to the [ParallelLibrary](#) object. Used in [define_filenames\(\)](#).

8.5.1 Detailed Description

Base class providing common functionality for derived classes ([SysCallAnalysisCode](#) and [ForkAnalysisCode](#)) which spawn separate processes for managing simulations.

The [AnalysisCode](#) class hierarchy provides simulation spawning services for [ApplicationInterface](#) derived classes and alleviates these classes of some of the specifics of simulation code management. The hierarchy does not employ the letter-envelope technique since the [ApplicationInterface](#) derived classes instantiate the appropriate derived [AnalysisCode](#) class directly.

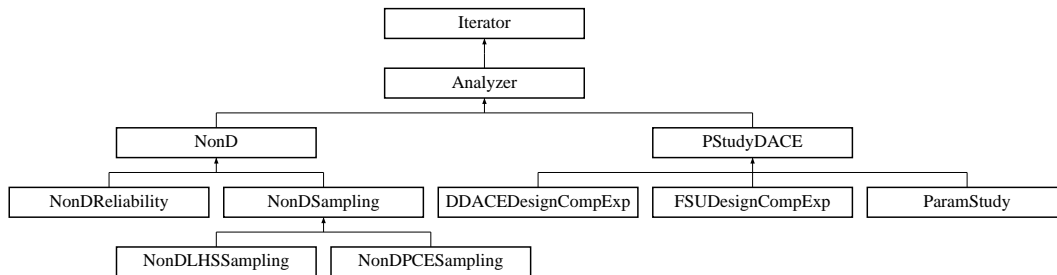
The documentation for this class was generated from the following files:

- [AnalysisCode.H](#)
- [AnalysisCode.C](#)

8.6 Analyzer Class Reference

Base class for [NonD](#), [DACE](#), and [ParamStudy](#) branches of the iterator hierarchy.

Inheritance diagram for Analyzer::



Public Member Functions

- `const VariablesArray & all_variables () const`
return the complete set of evaluated variables
- `const RealVectorArray & all_c_variables () const`
return the complete set of evaluated continuous variables
- `const ResponseArray & all_responses () const`
return the complete set of computed responses
- `const RealVectorArray & all_fn_responses () const`
return the complete set of computed function responses

Protected Member Functions

- `Analyzer ()`
default constructor
- `Analyzer (Model &model)`
standard constructor
- `Analyzer (NoDBBaseConstructor, Model &model)`
alternate constructor for instantiations "on the fly"
- `~Analyzer ()`
destructor
- `virtual void update_best (const RealVector &vars, const Response &response, const int eval_num)`
compares current evaluation to best evaluation and updates best

- virtual void [get_parameter_sets](#) (bool vbd_change_seq_flag)
*Returns one block of samples (ndim * num_samples).*
- void [evaluate_parameter_sets](#) (bool vars_flag, bool resp_flag, bool fns_flag, bool best_flag)
perform function evaluations to map parameter sets (allVariables/allCVariables/allDVariables) into response sets (allResponses/allFnResponses/allGradResponses)
- void [var_based_decomp](#) (const int ndim, const int num_samples)
- void [volumetric_quality](#) (int ndim, int num_samples, double *sample_points)
Calculation of volumetric quality measures.
- void [print_vbd](#) (ostream &s, const [RealVector](#) &S, const [RealVector](#) &T) const
Printing of VBD results.

Protected Attributes

- [VariablesArray](#) allVariables
array of all variables evaluated
- [RealVectorArray](#) allCVariables
array of all continuous variables evaluated (subset of allVariables)
- [ResponseArray](#) allResponses
array of all responses computed
- [RealVectorArray](#) allFnResponses
array of all function responses computed (subset of allResponses)
- [StringArray](#) allHeaders
array of headers to insert into output while evaluating allCVariables
- bool [qualityFlag](#)
flag to indicated if quality metrics were calculated
- double [chiMeas](#)
quality measures
- double [dMeas](#)
quality measures
- double [hMeas](#)
quality measures
- double [tauMeas](#)
quality measures

8.6.1 Detailed Description

Base class for [NonD](#), [DACE](#), and [ParamStudy](#) branches of the iterator hierarchy.

The [Analyzer](#) class provides common data and functionality for various types of systems analysis, including nondeterministic analysis, design of experiments, and parameter studies.

8.6.2 Constructor & Destructor Documentation

8.6.2.1 [Analyzer](#) ([Model](#) & *model*) [protected]

standard constructor

This constructor extracts inherited data for the optimizer and least squares branches and performs sanity checking on constraint settings.

8.6.2.2 [Analyzer](#) ([NoDBBaseConstructor](#), [Model](#) & *model*) [protected]

alternate constructor for instantiations "on the fly"

This constructor extracts inherited data for the optimizer and least squares branches and performs sanity checking on constraint settings.

8.6.3 Member Function Documentation

8.6.3.1 `void evaluate_parameter_sets (bool vars_flag, bool resp_flag, bool fns_flag, bool best_flag)` [protected]

perform function evaluations to map parameter sets (allVariables/allCVariables/allIDVariables) into response sets (allResponses/allFnResponses/allGradResponses)

Convenience function for derived classes with sets of function evaluations to perform (e.g., [NonDSampling](#), [DDACEDesignCompExp](#), [FSUDesignCompExp](#), [ParamStudy](#)).

8.6.3.2 `void var_based_decomp (const int ndim, const int num_samples)` [protected]

Calculation of sensitivity indices obtained by variance based decomposition. These indices are obtained by the Saltelli version of the Sobol' VBD which uses $(K+2)*N$ function evaluations, where K is the number of dimensions (uncertain vars) and N is the number of samples.

8.6.3.3 `void volumetric_quality (int ndim, int num_samples, double * sample_points)` [protected]

Calculation of volumetric quality measures.

Calculation of volumetric quality measures developed by FSU.

8.6.3.4 void print_vbd (ostream & *s*, const RealVector & *S*, const RealVector & *T*) const
[protected]

Printing of VBD results.

printing of variance based decomposition indices.

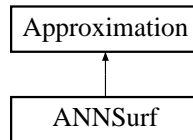
The documentation for this class was generated from the following files:

- DakotaAnalyzer.H
- DakotaAnalyzer.C

8.7 ANNSurf Class Reference

Derived approximation class for artificial neural networks.

Inheritance diagram for ANNSurf::



Public Member Functions

- [ANNSurf](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_acv)
constructor
- [~ANNSurf](#) ()
destructor

Protected Member Functions

- int [required_samples](#) ()
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- void [find_coefficients](#) ()
calculate the data fit coefficients using the currentPoints list of SurrogateDataPoints
- Real [get_value](#) (const [RealVector](#) &x)
retrieve the approximate function value for a given parameter vector

Private Attributes

- ANNAprox * [annObject](#)
pointer to the ANNAprox object (see VendorPackages/ann for class declaration)

8.7.1 Detailed Description

Derived approximation class for artificial neural networks.

The [ANNSurf](#) class uses a layered-perceptron artificial neural network. Unlike most neural networks, it does not employ a back-propagation approach to training. Rather it uses a direct training approach

developed by Prof. David Zimmerman of the University of Houston and modified by Tom Paez and Chris O’Gorman of Sandia. It is more computationally efficient than back-propagation networks, but relative accuracy can be a concern.

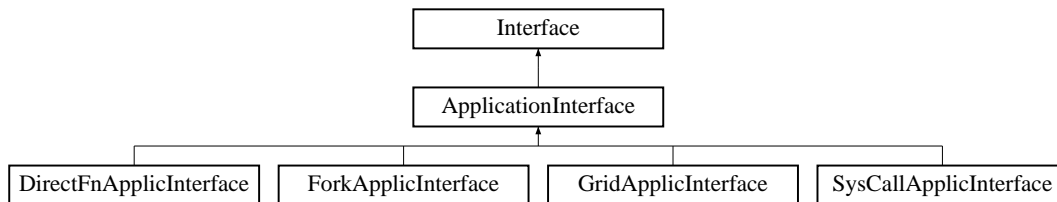
The documentation for this class was generated from the following files:

- ANNSurf.H
- ANNSurf.C

8.8 ApplicationInterface Class Reference

Derived class within the interface class hierarchy for supporting interfaces to simulation codes.

Inheritance diagram for ApplicationInterface::



Protected Member Functions

- [ApplicationInterface](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_fns)
constructor
- [~ApplicationInterface](#) ()
destructor
- void [init_communicators](#) (const [IntArray](#) &message_lengths, const int &max_iterator_concurrency)

allocate communicator partitions for concurrent evaluations within an iterator and concurrent multiprocessor analyses within an evaluation.
- void [reset_communicators](#) (const [IntArray](#) &message_lengths)
reset the local parallel partition data for an interface (the partitions are already allocated in [ParallelLibrary](#)).
- void [free_communicators](#) ()
deallocate communicator partitions for concurrent evaluations within an iterator and concurrent multiprocessor analyses within an evaluation.
- void [init_serial](#) ()
- int [asynch_local_evaluation_concurrency](#) () const
return asynchLocalEvalConcurrency
- [String](#) [interface_synchronization](#) () const
return interfaceSynchronization
- void [map](#) (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response, const bool asynch_flag=false)
Provides a "mapping" of variables to responses using a simulation. Protected due to [Interface](#) letter-envelope idiom.

- void `manage_failure` (const `Variables` &vars, const `IntArray` &asv, `Response` &response, int failed_eval_id)
manages a simulation failure using abort/retry/recover/continuation
- const `ResponseArray` & `synch` ()
executes a blocking schedule for asynchronous evaluations in the beforeSynchPRPList queue and returns all jobs
- const `ResponseList` & `synch_nowait` ()
executes a nonblocking schedule for asynchronous evaluations in the beforeSynchPRPList queue and returns a partial list of completed jobs
- void `serve_evaluations` ()
run on evaluation servers to serve the iterator master
- void `stop_evaluation_servers` ()
used by the iterator master to terminate evaluation servers
- virtual void `derived_map` (const `Variables` &vars, const `IntArray` &asv, `Response` &response, int fn_eval_id)=0
Called by `map()` and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- virtual void `derived_map_async` (const `ParamResponsePair` &pair)=0
Called by `map()` and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- virtual void `derived_synch` (`PRPList` &prp_list)=0
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version waits for at least one completion.
- virtual void `derived_synch_nowait` (`PRPList` &prp_list)=0
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version is nonblocking and will return without any completions if none are immediately available.
- virtual void `clear_bookkeeping` ()
clears any bookkeeping in derived classes
- void `self_schedule_analyses` ()
blocking self-schedule of all analyses within a function evaluation using message passing
- void `serve_analyses_synch` ()
serve the master analysis scheduler and manage one synchronous analysis job at a time
- virtual int `derived_synchronous_local_analysis` (const int &analysis_id)=0
Execute a particular analysis (identified by `analysis_id`) synchronously on the local processor. Used for the derived class specifics within `ApplicationInterface::serve_analyses_synch()`.

Protected Attributes

- **ParallelLibrary & parallellib**
reference to the [ParallelLibrary](#) object used to manage MPI partitions for the concurrent evaluations and concurrent analyses parallelism levels
- **bool suppressOutput**
flag for suppressing output on slave processors
- **int evalCommSize**
size of evalComm
- **int evalCommRank**
processor rank within evalComm
- **int evalServerId**
evaluation server identifier
- **bool eaDedMasterFlag**
flag for dedicated master partitioning at ea level
- **int analysisCommSize**
size of analysisComm
- **int analysisCommRank**
processor rank within analysisComm
- **int analysisServerId**
analysis server identifier
- **int numAnalysisServers**
number of analysis servers
- **bool multiProcAnalysisFlag**
flag for multiprocessor analysis partitions
- **bool asynchLocalAnalysisFlag**
flag for asynchronous local parallelism of analyses
- **int asynchLocalAnalysisConcurrency**
limits the number of concurrent analyses in asynchronous local scheduling and specifies hybrid concurrency when message passing
- **StringArray analysisDrivers**
the set of analyses within each function evaluation (from the `analysis_drivers` interface specification)
- **int numAnalysisDrivers**
length of analysisDrivers list
- **String2DArray analysisComponents**
the set of optional analysis components used by the analysis drivers in completing a simulation within each function evaluation (from the `analysis_drivers` interface specification)

Private Member Functions

- bool `duplication_detect` (const `Variables` &vars, `Response` &response, const bool asynch_flag)
checks data_pairs and beforeSynchPRPList to see if the current evaluation request has already been performed or queued
- void `self_schedule_evaluations` ()
blocking self-schedule of all evaluations in beforeSynchPRPList using message passing; executes on iteratorComm master
- void `static_schedule_evaluations` ()
blocking static schedule of all evaluations in beforeSynchPRPList using message passing; executes on iteratorComm master
- void `asynchronous_local_evaluations` (`PRPList` &prp_list)
perform all jobs in prp_list using asynchronous approaches on the local processor
- void `synchronous_local_evaluations` (`PRPList` &prp_list)
perform all jobs in prp_list using synchronous approaches on the local processor
- void `asynchronous_local_evaluations_nowait` (`PRPList` &prp_list)
launch new jobs in prp_list asynchronously (if capacity is available), perform nonblocking query of all running jobs, and process any completed jobs
- void `serve_evaluations_synch` ()
serve the evaluation message passing schedulers and perform one synchronous evaluation at a time
- void `serve_evaluations_asynch` ()
serve the evaluation message passing schedulers and manage multiple asynchronous evaluations
- void `serve_evaluations_peer` ()
serve the evaluation message passing schedulers and perform one synchronous evaluation at a time as part of the 1st peer
- void `reset_evaluation_communicators` (const `IntArray` &message_lengths)
convenience function for updating the local evaluation partition data following `ParallelLibrary::init_evaluation_communicators()`.
- void `reset_analysis_communicators` ()
convenience function for updating the local analysis partition data following `ParallelLibrary::init_analysis_communicators()`.
- const `ParamResponsePair` & `get_source_pair` (const `Variables` &target_vars)
convenience function for the continuation approach in `manage_failure()` for finding the nearest successful "source" evaluation to the failed "target"
- void `continuation` (const `Variables` &target_vars, const `IntArray` &asv, `Response` &response, const `ParamResponsePair` &source_pair, int failed_eval_id)
performs a 0th order continuation method to step from a successful "source" evaluation to the failed "target". Invoked by `manage_failure()` for failAction == "continuation".

Private Attributes

- int `worldSize`
size of `MPI_COMM_WORLD`
- int `worldRank`
processor rank within `MPI_COMM_WORLD`
- int `iteratorCommSize`
size of `iteratorComm`
- int `iteratorCommRank`
processor rank within `iteratorComm`
- bool `ieMessagePass`
flag for message passing at ie scheduling level
- int `numEvalServers`
number of evaluation servers
- bool `eaMessagePass`
flag for message passing at ea scheduling level
- int `procsPerAnalysis`
processors per analysis servers
- int `lenVarsMessage`
length of a `MPIPackBuffer` containing a `Variables` object; computed in `Model::init_communicators()`
- int `lenVarsASVMessage`
length of a `MPIPackBuffer` containing a `Variables` object and an active set vector object; computed in `Model::init_communicators()`
- int `lenResponseMessage`
length of a `MPIPackBuffer` containing a `Response` object; computed in `Model::init_communicators()`
- int `lenPRPairMessage`
length of a `MPIPackBuffer` containing a `ParamResponsePair` object; computed in `Model::init_communicators()`
- String `evalScheduling`
user specification of evaluation scheduling algorithm (self, static, or no spec). Used for manual overrides of the auto-configure logic in `ParallelLibrary::resolve_inputs()`.
- String `analysisScheduling`
user specification of analysis scheduling algorithm (self, static, or no spec). Used for manual overrides of the auto-configure logic in `ParallelLibrary::resolve_inputs()`.
- int `asynchLocalEvalConcurrency`
limits the number of concurrent evaluations in asynchronous local scheduling and specifies hybrid concurrency when message passing

- **String interfaceSynchronization**
interface synchronization specification: synchronous (default) or asynchronous
- **bool headerFlag**
used by `synch_nowait` to manage output frequency (since this function may be called many times prior to any completions)
- **bool asvControlFlag**
used to manage a user request to deactivate the active set vector control. `true` = modify the ASV each evaluation as appropriate (default); `false` = ASV values are static so that the user need not check them on each evaluation.
- **bool evalCacheFlag**
used to manage a user request to deactivate the function evaluation cache (i.e., queries and insertions using the `data_pairs` list).
- **bool restartFileFlag**
used to manage a user request to deactivate the restart file (i.e., insertions into `write_restart`).
- **IntArray defaultASV**
the static ASV values used when the user has selected `asvControl = off`
- **String failAction**
mitigation action for captured simulation failures: abort, retry, recover, or continuation
- **int failRetryLimit**
limit on the number of retries for the retry failAction
- **RealVector failRecoveryFnVals**
the dummy function values used for the recover failAction
- **IntList historyDuplicateIds**
used to bookkeep `fnEvalId` of asynchronous evaluations which duplicate `data_pairs` evaluations
- **ResponseList historyDuplicateResponses**
used to bookkeep response of asynchronous evaluations which duplicate `data_pairs` evaluations
- **IntList beforeSynchDuplicateIds**
used to bookkeep `fnEvalId` of asynchronous evaluations which duplicate queued beforeSynchPRPList evaluations
- **SizeList beforeSynchDuplicateIndices**
used to bookkeep beforeSynchPRPList index of asynchronous evaluations which duplicate queued beforeSynchPRPList evaluations
- **ResponseList beforeSynchDuplicateResponses**
used to bookkeep response of asynchronous evaluations which duplicate queued beforeSynchPRPList evaluations
- **IntList runningList**

used by `asynchronous_local_nowait` to bookkeep which jobs are running

- **PRPList beforeSynchPRPList**

used to bookkeep vars/asy/response of nonduplicate asynchronous evaluations. This is the queue of jobs populated by asynchronous `map()` invocations which is later scheduled on a call to `synch()` or `synch_nowait()`.

8.8.1 Detailed Description

Derived class within the interface class hierarchy for supporting interfaces to simulation codes.

`ApplicationInterface` provides an interface class for performing parameter to response mappings using simulation code(s). It provides common functionality for a number of derived classes and contains the majority of all of the scheduling algorithms in DAKOTA. The derived classes provide the specifics for managing code invocations using system calls, forks, direct procedure calls, or distributed resource facilities.

8.8.2 Member Function Documentation

8.8.2.1 `void init_serial()` [protected, virtual]

`DataInterface.C` defaults of 0 servers are needed to distinguish an explicit user request for 1 server (serialization of a parallelism level) from no user request (use parallel auto-config). This default causes problems when `init_communicators()` is not called for an interface object (e.g., static scheduling fails in `DirectFnApplicInterface::derived_map()` for `NestedModel::optionalInterface`). This is the reason for this function: to reset certain defaults for interface objects that are used serially.

Reimplemented from `Interface`.

8.8.2.2 `void map(const Variables & vars, const IntArray & asy, Response & response, const bool asynch_flag = false)` [protected, virtual]

Provides a "mapping" of variables to responses using a simulation. Protected due to `Interface` letter-envelope idiom.

The function evaluator for application interfaces. Called from `derived_compute_response()` and `derived_asynch_compute_response()` in derived `Model` classes. If `asynch_flag` is not set, perform a blocking evaluation (using `derived_map()`). If `asynch_flag` is set, add the job to the `beforeSynchPRPList` queue for execution by one of the scheduler routines in `synch()` or `synch_nowait()`. Duplicate function evaluations are detected with `duplication_detect()`.

Reimplemented from `Interface`.

8.8.2.3 `const ResponseArray & synch()` [protected, virtual]

executes a blocking schedule for asynchronous evaluations in the `beforeSynchPRPList` queue and returns all jobs

This function provides blocking synchronization for all cases of asynchronous evaluations, including the local asynchronous case (background system call, nonblocking fork, & multithreads), the message passing case, and the hybrid case. Called from `derived_synchronize()` in derived [Model](#) classes.

Reimplemented from [Interface](#).

8.8.2.4 `const ResponseList & synch_nowait ()` [protected, virtual]

executes a nonblocking schedule for asynchronous evaluations in the `beforeSynchPRPList` queue and returns a partial list of completed jobs

This function will eventually provide nonblocking synchronization for all cases of asynchronous evaluations, however it currently supports only the local asynchronous case since nonblocking message passing schedulers have not yet been implemented. Called from `derived_synchronize_nowait()` in derived [Model](#) classes.

Reimplemented from [Interface](#).

8.8.2.5 `void serve_evaluations ()` [protected, virtual]

run on evaluation servers to serve the iterator master

Invoked by the `serve()` function in derived [Model](#) classes. Passes control to [serve_evaluations_asynch\(\)](#), [serve_evaluations_peer\(\)](#), or [serve_evaluations_synch\(\)](#) according to specified concurrency and self/static scheduler configuration.

Reimplemented from [Interface](#).

8.8.2.6 `void stop_evaluation_servers ()` [protected, virtual]

used by the iterator master to terminate evaluation servers

This code is executed on the `iteratorComm` rank 0 processor when iteration on a particular model is complete. It sends a termination signal (`tag = 0` instead of a valid `fn_eval_id`) to each of the slave analysis servers. NOTE: This function is called from the [Strategy](#) layer even when in serial mode. Therefore, use `iteratorCommSize` to provide appropriate fall through behavior.

Reimplemented from [Interface](#).

8.8.2.7 `void self_schedule_analyses ()` [protected]

blocking self-schedule of all analyses within a function evaluation using message passing

This code is called from derived classes to provide the master portion of a master-slave algorithm for the dynamic self-scheduling of analyses among slave servers. It is patterned after [self_schedule_evaluations\(\)](#). It performs no analyses locally and matches either [serve_analyses_synch\(\)](#) or [serve_analyses_asynch\(\)](#) on the slave servers, depending on the value of `asynchLocalAnalysisConcurrency`. Self-scheduling approach assigns jobs in 2 passes. The 1st pass gives each server the same number of jobs (equal to `asynchLocalAnalysisConcurrency`). The 2nd pass assigns the remaining jobs to slave servers as previous jobs are com-

pleted. Single- and multilevel parallel use intra- and inter-communicators, respectively, for send/receive. Specific syntax is encapsulated within [ParallelLibrary](#).

8.8.2.8 void `serve_analyses_synch()` [protected]

serve the master analysis scheduler and manage one synchronous analysis job at a time

This code is called from derived classes to run synchronous analyses on slave processors. The slaves receive requests (blocking receive), do local derived_map_ac's, and return codes. This is done continuously until a termination signal is received from the master. It is patterned after [serve_evaluations_synch\(\)](#).

8.8.2.9 bool `duplication_detect(const Variables & vars, Response & response, const bool asynch_flag)` [private]

checks data_pairs and beforeSynchPRPList to see if the current evaluation request has already been performed or queued

Check incoming evaluation request for duplication with content of data_pairs and beforeSynchPRPList. If duplication is detected, return true, else return false. Manage bookkeeping with historyDuplicate and beforeSynchDuplicate lists. Called from [map\(\)](#). Note that the list searches can get very expensive if a long list is searched on every new function evaluation (either from a large number of previous jobs, a large number of pending jobs, or both). For this reason, a user request for deactivation of the evaluation cache results in a complete bypass of [duplication_detect\(\)](#), even though a beforeSynchPRPList search would still be meaningful. Since the intent of this request is to streamline operations, both list searches are bypassed.

8.8.2.10 void `self_schedule_evaluations()` [private]

blocking self-schedule of all evaluations in beforeSynchPRPList using message passing; executes on iteratorComm master

This code is called from [synch\(\)](#) to provide the master portion of a master-slave algorithm for the dynamic self-scheduling of evaluations among slave servers. It performs no evaluations locally and matches either [serve_evaluations_synch\(\)](#) or [serve_evaluations_asynch\(\)](#) on the slave servers, depending on the value of asynchLocalEvalConcurrency. Self-scheduling approach assigns jobs in 2 passes. The 1st pass gives each server the same number of jobs (equal to asynchLocalEvalConcurrency). The 2nd pass assigns the remaining jobs to slave servers as previous jobs are completed. Single- and multilevel parallel use intra- and inter-communicators, respectively, for send/receive. Specific syntax is encapsulated within [ParallelLibrary](#).

8.8.2.11 void `static_schedule_evaluations()` [private]

blocking static schedule of all evaluations in beforeSynchPRPList using message passing; executes on iteratorComm master

This code runs on the iteratorCommRank 0 processor (the iterator) and is called from [synch\(\)](#) in order to assign a static schedule. It matches [serve_evaluations_peer\(\)](#) for any other processors within the 1st evaluation partition and [serve_evaluations_synch\(\)/serve_evaluations_asynch\(\)](#) for all other evaluation partitions (depending on asynchLocalEvalConcurrency). It performs function evaluations locally for its portion of the static schedule using either [asynchronous_local_evaluations\(\)](#) or [synchronous_local_evaluations\(\)](#). Single-level and multilevel parallel use intra- and inter-communicators, respectively, for send/receive. Specific syntax is encapsulated within [ParallelLibrary](#). The iteratorCommRank 0 processor assigns the static schedule since it is the only processor with access to beforeSynchPRPList (it runs the iterator and calls

synchronize). The alternate design of each peer selecting its own jobs using the modulus operator would be applicable if execution of this function (and therefore the job list) were distributed.

8.8.2.12 void asynchronous_local_evaluations (PRPList & prp_list) [private]

perform all jobs in prp_list using asynchronous approaches on the local processor

This function provides blocking synchronization for the local asynch case (background system call, non-blocking fork, or threads). It can be called from [synch\(\)](#) for a complete local scheduling of all asynchronous jobs or from [static_schedule_evaluations\(\)](#) to perform a local portion of the total job set. It uses the [derived_map_asynch\(\)](#) to initiate asynchronous evaluations and [derived_synch\(\)](#) to capture completed jobs, and mirrors the [self_schedule_evaluations\(\)](#) message passing scheduler as much as possible ([derived_synch\(\)](#) is modeled after MPI_Waitsome()).

8.8.2.13 void synchronous_local_evaluations (PRPList & prp_list) [private]

perform all jobs in prp_list using synchronous approaches on the local processor

This function provides blocking synchronization for the local synchronous case (foreground system call, blocking fork, or procedure call from [derived_map\(\)](#)). It is called from [static_schedule_evaluations\(\)](#) to perform a local portion of the total job set.

8.8.2.14 void asynchronous_local_evaluations_nowait (PRPList & prp_list) [private]

launch new jobs in prp_list asynchronously (if capacity is available), perform nonblocking query of all running jobs, and process any completed jobs

This function provides nonblocking synchronization for the local asynch case (background system call, nonblocking fork, or threads). It is called from [synch_nowait\(\)](#) and passed the complete set of all asynchronous jobs (beforeSynchPRPList). It uses [derived_map_asynch\(\)](#) to initiate asynchronous evaluations and [derived_synch_nowait\(\)](#) to capture completed jobs in nonblocking mode. It mirrors a nonblocking message passing scheduler as much as possible ([derived_synch_nowait\(\)](#) modeled after MPI_Testsome()). The results of this function are rawResponseList and completionList. Since rawResponseList is in no particular order, completionList must be used as a key. It is assumed that the incoming prp_list contains only active and new jobs - i.e., all completed jobs are cleared by [synch_nowait\(\)](#).

8.8.2.15 void serve_evaluations_synch () [private]

serve the evaluation message passing schedulers and perform one synchronous evaluation at a time

This code is invoked by [serve_evaluations\(\)](#) to perform one synchronous job at a time on each slave/peer server. The servers receive requests (blocking receive), do local synchronous maps, and return results. This is done continuously until a termination signal is received from the master (sent via [stop_evaluation_servers\(\)](#)).

8.8.2.16 void serve_evaluations_asynch () [private]

serve the evaluation message passing schedulers and manage multiple asynchronous evaluations

This code is invoked by [serve_evaluations\(\)](#) to perform multiple asynchronous jobs on each slave/peer server. The servers test for any incoming jobs, launch any new jobs, process any completed jobs, and return any results. Each of these components is nonblocking, although the server loop continues until a termination signal is received from the master (sent via [stop_evaluation_servers\(\)](#)). In the master-slave

case, the master maintains the correct number of jobs on each slave. In the static scheduling case, each server is responsible for limiting concurrency (since the entire static schedule is sent to the peers at start up).

8.8.2.17 void `serve_evaluations_peer()` [private]

serve the evaluation message passing schedulers and perform one synchronous evaluation at a time as part of the 1st peer

This code is invoked by `serve_evaluations()` to perform a synchronous evaluation in coordination with the `iteratorCommRank 0` processor (the iterator) for static schedules. The `bcast()` matches either the `bcast()` in `synchronous_local_evaluations()`, which is invoked by `static_schedule_evaluations()`, or the `bcast()` in `map()`.

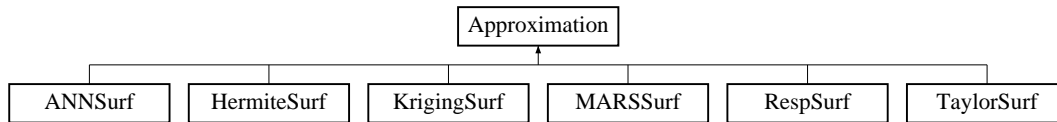
The documentation for this class was generated from the following files:

- `ApplicationInterface.H`
- `ApplicationInterface.C`

8.9 Approximation Class Reference

Base class for the approximation class hierarchy.

Inheritance diagram for Approximation::



Public Member Functions

- [Approximation](#) ()
default constructor
- [Approximation](#) (const [String](#) &approx_type, const [ProblemDescDB](#) &problem_db, const size_t &num_acv)
standard constructor for envelope
- [Approximation](#) (const [Approximation](#) &approx)
copy constructor
- virtual [~Approximation](#) ()
destructor
- [Approximation operator=](#) (const [Approximation](#) &approx)
assignment operator
- virtual Real [get_value](#) (const [RealVector](#) &x)
retrieve the approximate function value for a given parameter vector
- virtual const [RealBaseVector](#) & [get_gradient](#) (const [RealVector](#) &x)
retrieve the approximate function gradient for a given parameter vector
- virtual const [RealMatrix](#) & [get_hessian](#) (const [RealVector](#) &x)
retrieve the approximate function Hessian for a given parameter vector
- virtual int [required_samples](#) ()
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- virtual const [RealVector](#) & [approximation_coefficients](#) ()
return the coefficient array computed by [find_coefficients\(\)](#)

- void **build** (const [RealVectorArray](#) &vars_samples, const [RealVector](#) &fn_samples, const [RealBaseVectorArray](#) &grad_samples)
build the global surface from scratch. Populates currentPoints and invokes [find_coefficients\(\)](#).
- void **build** (const [RealVector](#) &vars_sample, const Real &fn_sample, const [RealBaseVector](#) &grad_sample, const [RealMatrix](#) &hess_sample)
build the local surface from scratch. Populates currentPoints and invokes [find_coefficients\(\)](#).
- void **add_point_rebuild** (const [RealVector](#) &x, const Real &fn_val, const [RealBaseVector](#) &fn_grad, const [RealMatrix](#) &fn_hess)
add a new point to the approximation and rebuild it
- void **set_bounds** (const [RealVector](#) &lower, const [RealVector](#) &upper)
set approximation lower and upper bounds (currently only used by graphics)
- void **draw_surface** ()
render the approximate surface using the 3D graphics (2 variable problems only).
- int **num_variables** () const
return the number of variables used in the approximation

Protected Member Functions

- [Approximation](#) ([BaseConstructor](#), const [ProblemDescDB](#) &problem_db, const size_t &num_acv)
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- virtual void **find_coefficients** ()
calculate the data fit coefficients using the currentPoints list of [SurrogateDataPoints](#)

Protected Attributes

- bool **useGradsFlag**
flag signaling the use of gradient data in global approximation builds as indicated by the user's use_gradients specification. This setting cannot be inferred from the responses spec., since we may need gradient support in the spec. for evaluating gradients at a single point (e.g., the center of a trust region), but not require gradient evaluations at every point.
- bool **verboseFlag**
flag for verbose approximation output
- int **numVars**
number of variables in the approximation
- int **numCurrentPoints**
number of points in the currentPoints list
- int **numSamples**

number of samples passed to `build()` to construct the approximation

- [RealBaseVector gradVector](#)
gradient of the approximation with respect to the variables
- [RealMatrix hessMatrix](#)
Hessian of the approximation with respect to the variables.
- [List< SurrogateDataPoint > currentPoints](#)
list of samples used to build the approximation
- [String approxType](#)
approximation type (long form for diagnostic I/O)

Private Member Functions

- [Approximation * get_approx](#) (const [String](#) &approx_type, const [ProblemDescDB](#) &problem_db, const size_t &num_acv)
Used only by the envelope constructor to initialize approxRep to the appropriate derived type.
- void [add_point](#) (const [RealVector](#) &x, const Real &fn_val, const [RealBaseVector](#) &fn_grad, const [RealMatrix](#) &fn_hess)
add a new point to the approximation (used by build & add_point_rebuild)

Private Attributes

- [RealVector approxLowerBounds](#)
approximation lower bounds (used only by 3D graphics)
- [RealVector approxUpperBounds](#)
approximation upper bounds (used only by 3D graphics)
- [Approximation * approxRep](#)
pointer to the letter (initialized only for the envelope)
- int [referenceCount](#)
number of objects sharing approxRep

8.9.1 Detailed Description

Base class for the approximation class hierarchy.

The [Approximation](#) class is the base class for the data fit surrogate class hierarchy in DAKOTA. One instance of a [Approximation](#) must be created for each function to be approximated (a vector of Approximations is contained in [ApproximationInterface](#)). For memory efficiency and enhanced polymorphism, the approximation hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Approximation](#)) serves as the envelope and one of the derived classes (selected in [Approximation::get_approximation\(\)](#)) serves as the letter.

8.9.2 Constructor & Destructor Documentation

8.9.2.1 [Approximation](#) ()

default constructor

The default constructor is used in `List<Approximation>` instantiations. `approxRep` is NULL in this case (`problem_db` is needed to build a meaningful [Model](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

8.9.2.2 [Approximation](#) (const [String](#) & *approx_type*, const [ProblemDescDB](#) & *problem_db*, const *size_t* & *num_acv*)

standard constructor for envelope

Envelope constructor only needs to extract enough data to properly execute `get_approx`, since `Approximation(BaseConstructor, problem_db)` builds the actual base class data for the derived approximations.

8.9.2.3 [Approximation](#) (const [Approximation](#) & *approx*)

copy constructor

Copy constructor manages sharing of `approxRep` and incrementing of `referenceCount`.

8.9.2.4 `~Approximation` () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `approxRep` when `referenceCount` reaches zero.

8.9.2.5 [Approximation](#) ([BaseConstructor](#), const [ProblemDescDB](#) & *problem_db*, const *size_t* & *num_acv*) [protected]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. `get_approx()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid recursion in the base class constructor calling `get_approx()` again). Since the letter IS the representation, its `rep` pointer is set to NULL (an uninitialized pointer causes problems in `~Approximation`).

8.9.3 Member Function Documentation

8.9.3.1 [Approximation](#) operator= (const [Approximation](#) & *approx*)

assignment operator

Assignment operator decrements referenceCount for old approxRep, assigns new approxRep, and increments referenceCount for new approxRep.

8.9.3.2 **Approximation** * get_approx (const **String** & *approx_type*, const **ProblemDescDB** & *problem_db*, const **size_t** & *num_acv*) [private]

Used only by the envelope constructor to initialize approxRep to the appropriate derived type.

Used only by the envelope constructor to initialize approxRep to the appropriate derived type, as given by the approx_type parameter.

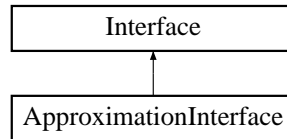
The documentation for this class was generated from the following files:

- DakotaApproximation.H
- DakotaApproximation.C

8.10 ApproximationInterface Class Reference

Derived class within the interface class hierarchy for supporting approximations to simulation-based results.

Inheritance diagram for ApproximationInterface::



Public Member Functions

- [ApproximationInterface](#) ([ProblemDescDB](#) &problem_db, const size_t &num_acv, const size_t &num_fns)
constructor
- [~ApproximationInterface](#) ()
destructor

Protected Member Functions

- void [map](#) (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response, const bool asynch_flag=false)
the function evaluator: provides an approximate "mapping" from the variables to the responses using functionSurfaces
- int [minimum_samples](#) () const
returns minSamples
- void [build_global_approximation](#) ([Iterator](#) &dace_iterator, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)
builds a global approximation for use as a surrogate
- void [build_local_approximation](#) ([Model](#) &actual_model)
builds a local approximation for use as a surrogate
- void [update_approximation](#) (const [RealVector](#) &x_star, const [Response](#) &response_star)
updates an existing global approximation with new data
- const [RealVectorArray](#) & [approximation_coefficients](#) ()
retrieve the approximation coefficients from each [Approximation](#) within an [ApproximationInterface](#)
- const [ResponseArray](#) & [synch](#) ()

recovers data from a series of asynchronous evaluations (blocking)

- const [ResponseList](#) & [synch_nowait](#) ()
recovers data from a series of asynchronous evaluations (nonblocking)

Private Attributes

- [String](#) [daceMethodPointer](#)
string pointer to the dace iterator specified by the user in the global approximation specification
- [String](#) [actualInterfacePointer](#)
string pointer to the actual interface specified by the user in the local/multipoint approximation specifications
- [Array](#)< [Approximation](#) > [functionSurfaces](#)
list of approximations, one per response function
- [RealVectorArray](#) [functionSurfaceCoeffs](#)
array of approximation coefficient vectors, one vector per response function
- [String](#) [sampleReuse](#)
user selection of type of sample reuse for approximation builds: all, region, file, or none (default)
- [String](#) [sampleReuseFile](#)
file name for sampleReuse == "file"
- [bool](#) [graphicsFlag](#)
controls 3D graphics of approximation surfaces
- [bool](#) [useGradsFlag](#)
signals the use of gradient data in global approximation builds
- [int](#) [minSamples](#)
the minimum number of samples over all functionSurfaces
- [ResponseList](#) [beforeSynchResponseList](#)
bookkeeping list to catalogue responses generated in map for use in [synch\(\)](#) and [synch_nowait\(\)](#). This supports pseudo-asynchronous operations (approximate responses all always computed synchronously, but asynchronous virtual functions are supported through bookkeeping).

8.10.1 Detailed Description

Derived class within the interface class hierarchy for supporting approximations to simulation-based results.

[ApproximationInterface](#) provides an interface class for building a set of global/local/multipoint approximations and performing approximate function evaluations using them. It contains a list of [Approximation](#) objects, one for each response function.

8.10.2 Member Data Documentation

8.10.2.1 `String daceMethodPointer` [private]

string pointer to the dace iterator specified by the user in the global approximation specification

This pointer is *not* used for building objects since this is managed in `SurrLayeredModels`. Its use in `ApproximationInterface` is currently limited to flagging dace contributions to data sets in `build_global_approximation()`.

8.10.2.2 `String actualInterfacePointer` [private]

string pointer to the actual interface specified by the user in the local/multipoint approximation specifications

This pointer is *not* used for building objects since this is managed in `SurrLayeredModels`. Its use in `ApproximationInterface` is currently limited to header output.

8.10.2.3 `Array<Approximation> functionSurfaces` [private]

list of approximations, one per response function

This formulation allows the use of mixed approximations (i.e., different approximations used for different response functions), although the input specification is not currently general enough to support it.

The documentation for this class was generated from the following files:

- `ApproximationInterface.H`
- `ApproximationInterface.C`

8.11 Array Class Template Reference

Template class for the [Dakota](#) bookkeeping array.

Public Member Functions

- [Array](#) ()
Default constructor.
- [Array](#) (size_t size)
Constructor which takes an initial size.
- [Array](#) (size_t size, const T &initial_val)
Constructor which takes an initial size and an initial value.
- [Array](#) (const [Array](#)< T > &a)
Copy constructor.
- [Array](#) (const T *p, size_t size)
Constructor which copies size entries from T.*
- [~Array](#) ()
Destructor.
- [Array](#)< T > & [operator=](#) (const [Array](#)< T > &a)
Normal const assignment operator.
- [Array](#)< T > & [operator=](#) ([Array](#)< T > &a)
Normal assignment operator.
- [Array](#)< T > & [operator=](#) (const T &ival)
Sets all elements in self to the value ival.
- [operator T *](#) () const
Converts the [Array](#) to a standard C-style array. Use with care!
- T & [operator](#)[] (int i)
alternate bounds-checked indexing operator for int indices
- const T & [operator](#)[] (int i) const
alternate bounds-checked const indexing operator for int indices
- T & [operator](#)[] (size_t i)
Index operator, returns the ith value of the array.
- const T & [operator](#)[] (size_t i) const

Index operator const, returns the ith value of the array.

- T & `operator()` (size_t i)
Index operator, not bounds checked.
- const T & `operator()` (size_t i) const
Index operator const, not bounds checked.
- void `print` (ostream &s) const
Prints an [Array](#) to an output stream.
- void `read` (MPIUnpackBuffer &s)
Reads an [Array](#) from a buffer after an MPI receive.
- void `print` (MPIPackBuffer &s) const
Writes an [Array](#) to a buffer prior to an MPI send.
- size_t `length` () const
Returns size of array.
- void `reshape` (size_t sz)
Resizes array to size sz.
- size_t `index` (const T &a) const
Returns the index of the first array item which matches the object a.
- bool `contains` (const T &a) const
Checks if the array contains an object which matches the object a.
- size_t `count` (const T &a) const
Returns the number of items in the array matching the object a.
- const T * `data` () const
Returns pointer T to continuous data.*

8.11.1 Detailed Description

```
template<class T> class Dakota::Array< T >
```

Template class for the [Dakota](#) bookkeeping array.

An array class template that provides additional functionality that is specific to Dakota's needs. The [Array](#) class adds additional functionality needed by [Dakota](#) to the inherited base array class. The [Array](#) class can inherit from either the STL or RW vector classes.

8.11.2 Constructor & Destructor Documentation

8.11.2.1 `Array` (`const T * p, size_t size`) [inline]

Constructor which copies size entries from T*.

Assigns size values from p into array.

8.11.3 Member Function Documentation**8.11.3.1** `Array`< T > & `operator=` (`const T & ival`) [inline]

Sets all elements in self to the value ival.

Assigns all values of array to the value passed in as ival. For the Rogue Wave case utilizes base class `operator=(ival),i` while for the ANSI case uses the STL `assign()` method.

8.11.3.2 `operator T * () const` [inline]

Converts the `Array` to a standard C-style array. Use with care!

The `operator()` returns a c style pointer to the data within the array. Calls the `data()` method. USE WITH CARE.

8.11.3.3]

`T & operator[] (size_t i)` [inline]

Index operator, returns the ith value of the array.

Index operator; calls the STL method `at()` which is bounds checked. Mimics the RW vector class. Note: the `at()` method is not supported by the `__GNUG__` STL implementation and by SGI builds omitting exceptions (e.g., SIERRA).

8.11.3.4]

`const T & operator[] (size_t i) const` [inline]

Index operator const, returns the ith value of the array.

A const version of the index operator; calls the STL method `at()` which is bounds checked. Mimics the RW vector class. Note: the `at()` method is not supported by the `__GNUG__` STL implementation and by SGI builds omitting exceptions (e.g., SIERRA).

8.11.3.5 `T & operator() (size_t i)` [inline]

Index operator, not bounds checked.

Non bounds check index operator, calls the STL `operator[]` which is not bounds checked. Needed to mimic the RW vector class

8.11.3.6 const T & operator() (size_t i) const [inline]

Index operator const, not bounds checked.

A const version of the non-bounds check index operator, calls the STL operator[] which is not bounds checked. Needed to mimic the RW vector class

8.11.3.7 const T * data () const [inline]

Returns pointer T* to continuous data.

Returns a C style pointer to the data within the array. USE WITH CARE. Needed to mimic RW vector class, is used in the operator(). Uses the STL front method.

The documentation for this class was generated from the following file:

- DakotaArray.H

8.12 BaseConstructor Struct Reference

Dummy struct for overloading letter-envelope constructors.

Public Member Functions

- [BaseConstructor](#) (int=0)
C++ structs can have constructors.

8.12.1 Detailed Description

Dummy struct for overloading letter-envelope constructors.

[BaseConstructor](#) is used to overload the constructor for the base class portion of letter objects. It avoids infinite recursion (Coplien p.139) in the letter-envelope idiom by preventing the letter from instantiating another envelope. Putting this struct here (rather than in a header of a class that uses it) avoids problems with circular dependencies.

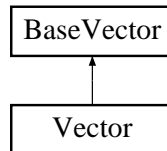
The documentation for this struct was generated from the following file:

- ProblemDescDB.H

8.13 BaseVector Class Template Reference

Base class for the [Dakota::Matrix](#) and [Dakota::Vector](#) classes.

Inheritance diagram for BaseVector::



Public Member Functions

- [BaseVector](#) ()
Default constructor.
- [BaseVector](#) (size_t size)
Constructor, creates vector of size.
- [BaseVector](#) (size_t size, const T &initial_val)
Constructor, creates vector of size with initial value of initial_val.
- [~BaseVector](#) ()
Destructor.
- [BaseVector](#) (const [BaseVector](#)< T > &a)
Copy constructor.
- [BaseVector](#)< T > & [operator=](#) (const [BaseVector](#)< T > &a)
Normal assignment operator.
- [BaseVector](#)< T > & [operator=](#) (const T &ival)
Assigns all values of vector to ival.
- T & [operator\[\]](#) (int i)
alternate bounds-checked indexing operator for int indices
- const T & [operator\[\]](#) (int i) const
alternate bounds-checked const indexing operator for int indices
- T & [operator\[\]](#) (size_t i)
Returns the object at index i, (can use as lvalue).
- const T & [operator\[\]](#) (size_t i) const
Returns the object at index i, const (can't use as lvalue).

- `T & operator() (size_t i)`
Index operator, not bounds checked.
- `const T & operator() (size_t i) const`
Index operator const , not bounds checked.
- `size_t length () const`
Returns size of vector.
- `void reshape (size_t sz)`
Resizes vector to size sz.
- `const T * data () const`
Returns const pointer to standard C array. Use with care.

Protected Member Functions

- `T * array () const`
Returns pointer to standard C array. Use with care.

8.13.1 Detailed Description

`template<class T> class Dakota::BaseVector< T >`

Base class for the `Dakota::Matrix` and `Dakota::Vector` classes.

The `Dakota::BaseVector` class is the base class for the `Dakota::Matrix` class. It is used to define a common vector interface for both the STL and RW vector classes. If the STL version is based on the `valarray` class then some basic vector operations such as `+`, `*` are available.

8.13.2 Constructor & Destructor Documentation

8.13.2.1 `BaseVector (size_t size, const T & initial_val) [inline]`

Constructor, creates vector of size with initial value of `initial_val`.

Constructor which takes an initial size and an initial value, allocates an area of initial size and initializes it with input value. Calls base class constructor

8.13.3 Member Function Documentation

8.13.3.1]

`T & operator[] (size_t i) [inline]`

Returns the object at index *i*, (can use as lvalue).

Index operator, calls the STL method `at()` which is bounds checked. Mimics the RW vector class. Note: the `at()` method is not supported by the `__GNUC__` STL implementation and by SGI builds omitting exceptions (e.g., SIERRA).

8.13.3.2]

`const T & operator[] (size_t i) const [inline]`

Returns the object at index *i*, `const` (can't use as lvalue).

Const versions of the index operator calls the STL method `at()` which is bounds checked. Mimics the RW vector class. Note: the `at()` method is not supported by the `__GNUC__` STL implementation and by SGI builds omitting exceptions (e.g., SIERRA).

8.13.3.3 T & operator() (size_t i) [inline]

Index operator, not bounds checked.

Non bounds check index operator, calls the STL `operator[]` which is not bounds checked. Needed to mimic the RW vector class

8.13.3.4 const T & operator() (size_t i) const [inline]

Index operator `const`, not bounds checked.

Const version of the non-bounds check index operator, calls the STL `operator[]` which is not bounds checked. Needed to mimic the RW vector class

8.13.3.5 size_t length () const [inline]

Returns size of vector.

Returns the length of the array by calling the STL `size` method. Needed to mimic the RW vector class

8.13.3.6 void reshape (size_t sz) [inline]

Resizes vector to size *sz*.

Resizes the array to size *sz* by calling the STL `resize` method. Needed to mimic the RW vector class

8.13.3.7 const T * data () const [inline]

Returns `const` pointer to standard C array. Use with care.

Returns a `const` pointer to the data within the array. USE WITH CARE. Needed to mimic RW vector class.

8.13.3.8 `T * array () const` [inline, protected]

Returns pointer to standard C array. Use with care.

Returns a non-const pointer to the data within the array. Non-const version of [data\(\)](#) used by derived classes.

The documentation for this class was generated from the following file:

- `DakotaBaseVector.H`

8.14 BiStream Class Reference

The binary input stream class. Overloads the >> operator for all data types.

Public Member Functions

- [BiStream \(\)](#)
Default constructor, need to open.
- [BiStream \(const char *s\)](#)
Constructor takes name of input file.
- [BiStream \(const char *s, std::ios_base::openmode mode\)](#)
Constructor takes name of input file, mode.
- [BiStream \(const char *s, int mode\)](#)
Constructor takes name of input file, mode.
- [~BiStream \(\)](#)
Destructor, calls xdr_destroy to delete xdr stream.
- [BiStream & operator>> \(String &ds\)](#)
Binary Input stream operator>>.
- [BiStream & operator>> \(char *s\)](#)
Input operator, reads char from binary stream [BiStream](#).*
- [BiStream & operator>> \(char &c\)](#)
Input operator, reads char from binary stream [BiStream](#).
- [BiStream & operator>> \(int &i\)](#)
Input operator, reads int from binary stream [BiStream](#).*
- [BiStream & operator>> \(long &l\)](#)
Input operator, reads long from binary stream [BiStream](#).
- [BiStream & operator>> \(short &s\)](#)
Input operator, reads short from binary stream [BiStream](#).
- [BiStream & operator>> \(bool &b\)](#)
Input operator, reads bool from binary stream [BiStream](#).
- [BiStream & operator>> \(double &d\)](#)
Input operator, reads double from binary stream [BiStream](#).
- [BiStream & operator>> \(float &f\)](#)

Input operator, reads float from binary stream [BiStream](#).

- [BiStream](#) & [operator>>](#) (unsigned char &c)
Input operator, reads unsigned char from binary stream [BiStream](#).*
- [BiStream](#) & [operator>>](#) (unsigned int &i)
Input operator, reads unsigned int from binary stream [BiStream](#).
- [BiStream](#) & [operator>>](#) (unsigned long &l)
Input operator, reads unsigned long from binary stream [BiStream](#).
- [BiStream](#) & [operator>>](#) (unsigned short &s)
Input operator, reads unsigned short from binary stream [BiStream](#).

Private Attributes

- XDR [xdrInBuf](#)
XDR input stream buffer.
- char [inBuf](#) [MAX_NETOBJ_SZ]
Buffer to hold data as it is read in.

8.14.1 Detailed Description

The binary input stream class. Overloads the >> operator for all data types.

The `Dakota::BiStream` class is a binary input class which overloads the >> operator for all standard data types (int, char, float, etc). The class relies on the methods within the `ifstream` base class. The `Dakota::BiStream` class inherits from the `ifstream` class. If available, the class utilize `rpc/xdr` to construct machine independent binary files. These [Dakota](#) restart files can be moved from host to host. The motivation to develop these classes was to replace the Rogue wave classes which [Dakota](#) historically used for binary I/O.

8.14.2 Constructor & Destructor Documentation

8.14.2.1 [BiStream](#) ()

Default constructor, need to open.

Default constructor, allocates `xdr stream` , but does not call the `open` method. The `open` method must be called before stream can be read.

8.14.2.2 [BiStream](#) (const char * s)

Constructor takes name of input file.

Constructor which takes a `char*` filename. Calls the base class `open` method with the filename and no other arguments. Also allocates the `xdr stream`.

8.14.2.3 [BiStream](#) (const char * s, std::ios_base::openmode mode)

Constructor takes name of input file, mode.

Constructor which takes a char* filename and int flags. Calls the base class open method with the filename and flags as arguments. Also allocates xdr stream.

8.14.2.4 [~BiStream](#) ()

Destructor, calls xdr_destroy to delete xdr stream.

Destructor, destroys the xdr stream allocated in constructor

8.14.3 Member Function Documentation

8.14.3.1 [BiStream & operator>>](#) (String & ds)

Binary Input stream operator>>.

The [String](#) input operator must first read both the xdr buffer size and the size of the string written. Once these are read it can then read and convert the [String](#) correctly.

8.14.3.2 [BiStream & operator>>](#) (char * s)

Input operator, reads char* from binary stream [BiStream](#).

Reading char array is a special case. The method has no way of knowing if the length to the input array is large enough, it assumes it is one char longer than actual string, (Null terminator added). As with the [String](#) the size of the xdr buffer as well as the char array size written must be read from the stream prior to reading and converting the char array.

The documentation for this class was generated from the following files:

- DakotaBinStream.H
- DakotaBinStream.C

8.15 BoStream Class Reference

The binary output stream class. Overloads the << operator for all data types.

Public Member Functions

- [BoStream \(\)](#)
Default constructor, need to open.
- [BoStream \(const char *s\)](#)
Constructor takes name of input file.
- [BoStream \(const char *s, std::ios_base::openmode mode\)](#)
Constructor takes name of input file, mode.
- [BoStream \(const char *s, int mode\)](#)
Constructor takes name of input file, mode.
- [~BoStream \(\)](#)
Destructor, calls xdr_destroy to delete xdr stream.
- [BoStream & operator<< \(const String &ds\)](#)
Binary Output stream operator<<.
- [BoStream & operator<< \(const char *s\)](#)
Output operator, writes char TO binary stream [BoStream](#).*
- [BoStream & operator<< \(const char &c\)](#)
Output operator, writes char to binary stream [BoStream](#).
- [BoStream & operator<< \(const int &i\)](#)
Output operator, writes int to binary stream [BoStream](#).
- [BoStream & operator<< \(const long &l\)](#)
Output operator, writes long to binary stream [BoStream](#).
- [BoStream & operator<< \(const short &s\)](#)
Output operator, writes short to binary stream [BoStream](#).
- [BoStream & operator<< \(const bool &b\)](#)
Output operator, writes bool to binary stream [BoStream](#).
- [BoStream & operator<< \(const double &d\)](#)
Output operator, writes double to binary stream [BoStream](#).
- [BoStream & operator<< \(const float &f\)](#)

Output operator, writes float to binary stream [BoStream](#).

- [BoStream](#) & `operator<<` (const unsigned char &c)
Output operator, writes unsigned char to binary stream [BoStream](#).
- [BoStream](#) & `operator<<` (const unsigned int &i)
Output operator, writes unsigned int to binary stream [BoStream](#).
- [BoStream](#) & `operator<<` (const unsigned long &l)
Output operator, writes unsigned long to binary stream [BoStream](#).
- [BoStream](#) & `operator<<` (const unsigned short &s)
Output operator, writes unsigned short to binary stream [BoStream](#).

Private Attributes

- XDR [xdrOutBuf](#)
XDR output stream buffer.
- char [outBuf](#) [MAX_NETOBJ_SZ]
Buffer to hold converted data before it is written.

8.15.1 Detailed Description

The binary output stream class. Overloads the << operator for all data types.

The `Dakota::BoStream` class is a binary output classes which overloads the << operator for all standard data types (int, char, float, etc). The class relies on the built in write methods within the ostream base classes. `Dakota::BoStream` inherits from the ostream class. The motivation to develop this class was to replace the Rogue wave class which [Dakota](#) historically used for binary I/O. If available, the class utilize rpc/xdr to construct machine independent binary files. These [Dakota](#) restart files can be moved between hosts.

8.15.2 Constructor & Destructor Documentation

8.15.2.1 [BoStream](#) ()

Default constructor, need to open.

Default constructor allocates the xdr stream but does not call the open() method. The open() method must be called before stream can be written to.

8.15.2.2 **BoStream** (const char * s)

Constructor takes name of input file.

Constructor, takes char * filename as argument. Calls base class open method with filename and no other arguments. Also allocates xdr stream

8.15.2.3 **BoStream** (const char * s, std::ios_base::openmode mode)

Constructor takes name of input file, mode.

Constructor, takes char * filename and int flags as arguments. Calls base class open method with filename and flags as arguments. Also allocates xdr stream. Note : If no rpc/xdr support xdr calls are #ifdef'd out.

8.15.3 Member Function Documentation

8.15.3.1 **BoStream** & operator<< (const String & ds)

Binary Output stream operator<<.

The [String](#) operator<< must first write the xdr buffer size and the original string size to the stream. The input operator needs this information to be able to correctly read and convert the [String](#).

8.15.3.2 **BoStream** & operator<< (const char * s)

Output operator, writes char* TO binary stream [BoStream](#).

The output of char* is the same as the output of the [String](#). The size of the xdr buffer and the size of the string must be written first, then the string itself.

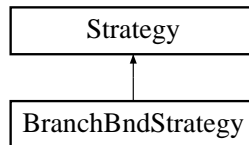
The documentation for this class was generated from the following files:

- DakotaBinStream.H
- DakotaBinStream.C

8.16 BranchBndStrategy Class Reference

[Strategy](#) for mixed integer nonlinear programming using the PICO parallel branch and bound engine.

Inheritance diagram for BranchBndStrategy::



Public Member Functions

- [BranchBndStrategy](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~BranchBndStrategy](#) ()
destructor
- void [run_strategy](#) ()
Performs the branch and bound strategy by executing selectedIterator on userDefinedModel multiple times in parallel for different variable bounds within the model.
- [IteratorList](#) & [iterators](#) (bool recurse_flag=true)
returns selectedIterator and any subordinate iterators
- [ModelList](#) & [models](#) (bool recurse_flag=true)
returns userDefinedModel and any subordinate models

Private Attributes

- [Model](#) [userDefinedModel](#)
the model used by the iterator
- [Iterator](#) [selectedIterator](#)
the iterator used by BranchBndStrategy
- int [numRootSamples](#)
number of samples to perform at the root of the branching structure
- int [numNodeSamples](#)
number of samples to perform at each node of the branching structure
- int [picoCommRank](#)

processor rank in strategy-iterator intra comm

- int `picoCommSize`
number of processors in strategy-iterator intra comm
- int `argC`
dummy argument count passed to pico classes in `init()`, `readAll()`, and `readAndBroadcast()`
- char ** `argV`
dummy argument vector passed to pico classes in `init()`, `readAll()`, and `readAndBroadcast()`
- `utilib::DoubleVector` `picoLowerBnds`
global lower bounds for merged continuous & discrete design variables passed to PICO (copied from `user-DefinedModel`)
- `utilib::DoubleVector` `picoUpperBnds`
global upper bounds for merged continuous & discrete design variables passed to PICO (copied from `user-DefinedModel`)
- `utilib::IntVector` `picoListOfIntegers`
key to the discrete variables which have been relaxed and merged into the continuous variables and bounds arrays (indices in the combined arrays)

8.16.1 Detailed Description

Strategy for mixed integer nonlinear programming using the PICO parallel branch and bound engine.

This strategy combines the PICO branching engine with nonlinear programming optimizers from DAKOTA (e.g., DOT, NPSOL, OPT++) to solve mixed integer nonlinear programs. The discrete variables in the problem must support relaxation, i.e., they must be able to assume nonintegral values during the solution process. PICO selects solution "branches", each of which constrains the problem to lie within different variable bounds. The series of branches selected is designed to drive integer variables to their integral values. For each of the branches, a nonlinear DAKOTA optimizer is used to solve the optimization problem and return the solution to PICO. If this solution has all of the integer variables at integral values, then it provides an upper bound on the true solution. This bound can be used to prune other branches, since there is no need to further investigate a branch which does not yet have integral values for the integer variables and which has an objective function worse than the bound. In linear programs, the bounding and pruning processes are rigorous and will lead to the exact global optimum. In nonlinear problems, the bounding and pruning processes are heuristic, i.e. they will find local optima but the global optimum may be missed. PICO supports parallelism between "hubs," each of which drives a concurrent iterator partition in DAKOTA (and each of these iterator partitions may have lower levels of nested parallelism). This complexity is hidden from PICO through the use of `picoComm`, which contains the set of master iterator processors, one from each iterator partition. Thus, PICO can schedule jobs among single-processor hubs in its normal manner, unaware of the nested parallelism complexities that may occur within each nonlinear optimization.

The documentation for this class was generated from the following files:

- `BranchBndStrategy.H`
- `BranchBndStrategy.C`

8.17 COLINApplication Class Template Reference

Public Member Functions

- [COLINApplication](#) ([Model](#) &model, [COLINOptimizerBase](#) *opt_)
constructor
- [~COLINApplication](#) ()
destructor
- void [DoEval](#) ([DomainT](#) &point, int &priority, [ResponseT](#) *response, bool synch_flag)
launch a function evaluation either synchronously or asynchronously
- unsigned int [num_evaluation_servers](#) ()
The number of 'slave' processors that can perform evaluations. The value '0' indicates that this is a sequential application.
- void [synchronize](#) ()
blocking retrieval of all pending jobs
- int [next_eval](#) ()
nonblocking query and retrieval of a job if completed
- void [dakota_asynch_flag](#) (const bool &asynch_flag)
This function publishes the iterator's asynchFlag at run time (asynchFlag not available at construction).

Private Types

- typedef [colin::OptApplication](#)< [DomainT](#), [ResponseT](#) > [base_t](#)
a convenience typedef for shortening base class scoping

Private Member Functions

- void [map_response](#) ([ResponseT](#) &colin_response, const [Response](#) &dakota_response)
utility function for mapping a DAKOTA response to a COLIN response

Private Attributes

- [Model](#) & [userDefinedModel](#)
reference to the COLINOptimizer's model passed in the constructor
- [IntArray](#) [activeSetVector](#)

copy/conversion of the COLIN request vector

- `bool dakotaModelAsynchFlag`
a flag for asynchronous DAKOTA evaluations
- `ResponseList dakotaResponseList`
list of DAKOTA responses returned by `synchronize_nowait()`
- `IntList dakotaCompletionList`
list of DAKOTA completions returned by `synchronize_nowait_completions()`
- `size_t numObjFns`
number of objective functions
- `size_t numNonlinCons`
number of nonlinear constraints
- `COLINOptimizerBase * opt`
pointer to the DAKOTA [Optimizer](#) hierarchy passed through the [COLINApplication](#) constructor. This is needed for accessing [Optimizer](#) functions (e.g., `multi_objective_modify()`) needed by [COLINApplication](#).
- `int num_real_params`
number of continuous design variables
- `int num_integer_params`
number of discrete design variables
- `Variables * dakota_vars`
a DAKOTA variables instance used for mapping COLIN variables data
- `int synchronization_state`
tracks the state of asynchronous evaluations

8.17.1 Detailed Description

```
template<class DomainT, class ResponseT> class Dakota::COLINApplication< DomainT, ResponseT >
```

[COLINApplication](#) is a DAKOTA class that is derived from COLIN's [OptApplication](#) hierarchy. It redefines a variety of virtual COLIN functions to use the corresponding DAKOTA functions. This is a more flexible algorithm library interfacing approach than can be obtained with the function pointer approaches used by [NPSOLOptimizer](#) and [SNLLOptimizer](#).

8.17.2 Member Function Documentation

8.17.2.1 void DoEval (DomainT & pt, int & priority, ResponseT * prob_response, bool synch_flag)

launch a function evaluation either synchronously or asynchronously

Converts the DomainT variables and request vector to DAKOTA variables and active set vector, performs a DAKOTA function evaluation with synchronization governed by synch_flag, and then copies the [Response](#) data to the ResponseT response (synchronous) or bookkeeps the response object (asynchronous).

8.17.2.2 void synchronize ()

blocking retrieval of all pending jobs

Blocking synchronize of asynchronous DAKOTA jobs followed by conversion of the [Response](#) objects to ResponseT response objects.

8.17.2.3 int next_eval ()

nonblocking query and retrieval of a job if completed

Nonblocking job retrieval. Finds a completion (if available), populates the COLIN response, and sets id to the completed job's id. Else set id = -1.

8.17.2.4 void map_response (ResponseT & colin_response, const [Response](#) & dakota_response)
[private]

utility function for mapping a DAKOTA response to a COLIN response

map_response Maps a [Response](#) object into a ResponseT class that is compatible with COLIN.

The documentation for this class was generated from the following file:

- COLINApplication.H

8.18 COLINOptimizer Class Template Reference

Wrapper class for optimizers defined using COLIN.

Public Member Functions

- [COLINOptimizer \(Model &model\)](#)

Section 2

- [~COLINOptimizer \(\)](#)

destructor

- void [find_optimum](#) (void)

Performs the iterations to determine the optimal solution.

Protected Member Functions

- virtual void [set_rng](#) (void)

sets up the random number generator for stochastic methods

- virtual void [set_initial_point](#) (ColinPoint &pt)

sets the iteration starting point prior to minimization

- virtual void [get_min_point](#) (ColinPoint &pt)

retrieves the final solution after minimization

- virtual void [set_method_parameters](#) (void)

sets options for specific methods based on user specifications (called at construction time)

- void [set_standard_method_parameters](#) (void)

sets the standard method parameters shared by all methods

- virtual void [set_runtime_parameters](#) (void)

sets method parameters for specific methods using data that is not available until run time

Protected Attributes

- OptimizerT * [optimizer](#)

Pointer to COLIN base optimizer object.

- [COLINApplication](#)< ColinPoint, ColinResponse > * [application](#)

Pointer to the COLINApplication object.

- `OptProblem< ColinPoint > problem`
the COLIN problem object
- `RNG * rng`
RNG ptr.
- `String evalSynch`
the synchronization setting (blocking or nonblocking)

8.18.1 Detailed Description

```
template<class OptimizerT> class Dakota::COLINOptimizer< OptimizerT >
```

Wrapper class for optimizers defined using COLIN.

The `COLINOptimizer` class provides a templated wrapper for COLIN, a Sandia-developed C++ optimization interface library. A variety of COLIN optimizers are defined in the COLINY optimization library, which contains the optimization components from the old SGOPT library. COLINY contains optimizers such as genetic algorithms, pattern search methods, and other nongradient-based techniques. `COLINOptimizer` uses a `COLINApplication` object to perform the function evaluations.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `solution_accuracy` and `max_cpu_time` are mapped into COLIN's `max_iters`, `max_neval`, `ftol`, `accuracy`, and `max_time` data attributes. An output setting of `verbose` is passed to COLIN's `set_output()` function and a setting of `debug` activates output of method initialization and sets the COLIN `debug` attribute to 10000. COLIN methods assume asynchronous operations whenever the algorithm has independent evaluations which can be performed simultaneously (implicit parallelism). Therefore, parallel configuration is not mapped into the method, rather it is used in `COLINApplication` to control whether or not an asynchronous evaluation request from the method is honored by the model (exception: pattern search exploratory moves is set to `best_all` for parallel function evaluations). Refer to [Hart, W.E., 1997] for additional information on COLIN objects and controls.

8.18.2 Member Function Documentation

8.18.2.1 void find_optimum (void)

Performs the iterations to determine the optimal solution.

`find_optimum` redefines the `Optimizer` virtual function to perform the optimization using COLIN. It first sets up the problem data, then executes `minimize()` on the COLIN optimizer, and finally catalogues the results.

8.18.2.2 void set_standard_method_parameters (void) [protected]

sets the standard method parameters shared by all methods

`set_standard_method_parameters` propagates standard DAKOTA user input to the optimizer.

The documentation for this class was generated from the following file:

- COLINOptimizer.H

8.19 ColinPoint Class Reference

Public Attributes

- `vector< double > rvec`
continuous parameter values
- `vector< int > ivec`
discrete parameter values

8.19.1 Detailed Description

A class containing a vector of doubles and integers.

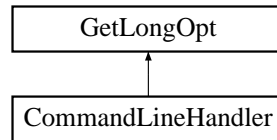
The documentation for this class was generated from the following file:

- COLINOptimizerBase.H

8.20 CommandLineHandler Class Reference

Utility class for managing command line inputs to DAKOTA.

Inheritance diagram for CommandLineHandler::



Public Member Functions

- [CommandLineHandler](#) ()
default constructor; requires [check_usage\(\)](#) call for parsing
- [CommandLineHandler](#) (int argc, char **argv)
constructor with parsing
- [~CommandLineHandler](#) ()
destructor
- void [check_usage](#) (int argc, char **argv)
Verifies that DAKOTA is called with the correct command usage. Prints a descriptive message and exits the program if incorrect.
- int [read_restart_evals](#) () const
Returns the number of evaluations to be read from the restart file (as specified on the DAKOTA command line) as an integer instead of a const char.*

Private Member Functions

- void [initialize_options](#) ()
enrolls the supported command line inputs.

8.20.1 Detailed Description

Utility class for managing command line inputs to DAKOTA.

[CommandLineHandler](#) provides additional functionality that is specific to DAKOTA's needs for the definition and parsing of command line options. Inheritance is used to allow the class to have all the functionality of the base class, [GetLongOpt](#).

The documentation for this class was generated from the following files:

- CommandLineHandler.H
- CommandLineHandler.C

8.21 CommandShell Class Reference

Utility class which defines convenience operators for spawning processes with system calls.

Public Member Functions

- [CommandShell \(\)](#)
constructor
- [~CommandShell \(\)](#)
destructor
- [CommandShell & operator<< \(const char *string\)](#)
adds string to unixCommand
- [CommandShell & operator<< \(CommandShell &\(*f\)\(CommandShell &\)\)](#)
allows passing of the flush function to the shell using <<
- [CommandShell & flush \(\)](#)
"flushes" the shell; i.e. executes the unixCommand
- void [asynch_flag](#) (const bool flag)
set the asynchFlag
- bool [asynch_flag](#) () const
get the asynchFlag
- void [suppress_output_flag](#) (const bool flag)
set the suppressOutputFlag
- bool [suppress_output_flag](#) () const
get the suppressOutputFlag

Private Attributes

- [String unixCommand](#)
the command string that is constructed through one or more << insertions and then executed by flush
- bool [asynchFlag](#)
flags nonblocking operation (background system calls)
- bool [suppressOutputFlag](#)
flags suppression of shell output (no command echo)

8.21.1 Detailed Description

Utility class which defines convenience operators for spawning processes with system calls.

The [CommandShell](#) class wraps the C `system()` utility and defines convenience operators for building a command string and then passing it to the shell.

8.21.2 Member Function Documentation

8.21.2.1 [CommandShell](#) & `flush ()`

"flushes" the shell; i.e. executes the `unixCommand`

Executes the `unixCommand` by passing it to `system()`. Appends an "&" if `asynchFlag` is set (background system call) and echos the `unixCommand` to `Cout` if `suppressOutputFlag` is not set.

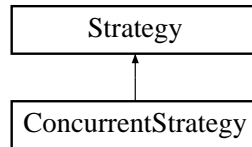
The documentation for this class was generated from the following files:

- `CommandShell.H`
- `CommandShell.C`

8.22 ConcurrentStrategy Class Reference

[Strategy](#) for multi-start iteration or pareto set optimization.

Inheritance diagram for ConcurrentStrategy::



Public Member Functions

- [ConcurrentStrategy](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~ConcurrentStrategy](#) ()
destructor
- void [run_strategy](#) ()
Performs the concurrent strategy by executing selectedIterator on userDefinedModel multiple times in parallel for different settings within the iterator or model.
- [IteratorList](#) & [iterators](#) (bool recurse_flag=true)
returns selectedIterator and any subordinate iterators
- [ModelList](#) & [models](#) (bool recurse_flag=true)
returns userDefinedModel and any subordinate models

Private Member Functions

- void [self_schedule_iterators](#) ()
executed by the strategy master to self-schedule iterator jobs among slave iterator servers (called by [run_strategy\(\)](#))
- void [serve_iterators](#) ()
executed on the slave iterator servers to perform iterator jobs assigned by the strategy master (called by [run_strategy\(\)](#))
- void [static_schedule_iterators](#) ()
executed on iterator peers to statically schedule iterator jobs (called by [run_strategy\(\)](#))
- void [print_strategy_results](#) ()
prints the concurrent iteration results summary (called by [run_strategy\(\)](#))

Private Attributes

- [Model userDefinedModel](#)
the model used by the iterator
- [Iterator selectedIterator](#)
the iterator used by the concurrent strategy
- [int numIteratorServers](#)
number of concurrent iterator partitions
- [int numIteratorJobs](#)
total number of iterator executions to schedule over the servers
- [RealVectorArray parameterSets](#)
an array of parameter set vectors (either multistart variable sets or pareto multiobjective weighting sets) to be performed.
- [PRPArray prpResults](#)
an array of results corresponding to the parameter set vectors.
- [bool multiStartFlag](#)
distinguishes multi-start from Pareto-set
- [bool strategyDedicatedMasterFlag](#)
signals ded. master partitioning
- [int iteratorServerId](#)
identifier for an iterator server
- [int drvMsgLen](#)
length of an MPI buffer containing a RealVector from parameterSets

8.22.1 Detailed Description

[Strategy](#) for multi-start iteration or pareto set optimization.

This strategy maintains two concurrent iterator capabilities. First, a general capability for running an iterator multiple times from different starting points is provided (often used for multi-start optimization, but not restricted to optimization). Second, a simple capability for mapping the "pareto frontier" (the set of optimal solutions in mutiobjective formulations) is provided. This pareto set is mapped through running an optimizer multiple times for different sets of multiobjective weightings.

8.22.2 Member Function Documentation

8.22.2.1 void self_schedule_iterators() [private]

executed by the strategy master to self-schedule iterator jobs among slave iterator servers (called by [run_strategy\(\)](#))

This function is adapted from [ApplicationInterface::self_schedule_evaluations\(\)](#).

8.22.2.2 void serve_iterators() [private]

executed on the slave iterator servers to perform iterator jobs assigned by the strategy master (called by [run_strategy\(\)](#))

This function is similar in structure to [ApplicationInterface::serve_evaluations_synch\(\)](#).

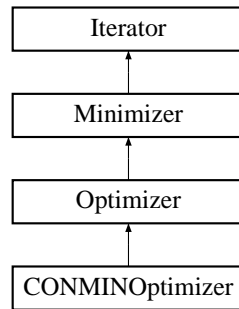
The documentation for this class was generated from the following files:

- ConcurrentStrategy.H
- ConcurrentStrategy.C

8.23 CONMINOptimizer Class Reference

Wrapper class for the CONMIN optimization library.

Inheritance diagram for CONMINOptimizer::



Public Member Functions

- [CONMINOptimizer \(Model &model\)](#)
constructor
- [~CONMINOptimizer \(\)](#)
destructor
- void [find_optimum \(\)](#)
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.

Private Member Functions

- void [allocate_workspace \(\)](#)
Allocates workspace for the optimizer.

Private Attributes

- int [conminInfo](#)
INFO from CONMIN manual.
- int [printControl](#)
IPRINT from CONMIN manual (controls output verbosity).
- int [optimizationType](#)
MINMAX from DOT manual (minimize or maximize).

- **RealVector localConstraintValues**
array of nonlinear constraint values passed to CONMIN
- **SizeList constraintMappingIndices**
a list of indices for referencing the corresponding [Response](#) constraints used in computing the CONMIN constraints.
- **RealList constraintMappingMultipliers**
a list of multipliers for mapping the [Response](#) constraints to the CONMIN constraints.
- **RealList constraintMappingOffsets**
a list of offsets for mapping the [Response](#) constraints to the CONMIN constraints.
- **int N1**
Size variable for CONMIN arrays. See CONMIN manual.
- **int N2**
Size variable for CONMIN arrays. See CONMIN manual.
- **int N3**
Size variable for CONMIN arrays. See CONMIN manual.
- **int N4**
Size variable for CONMIN arrays. See CONMIN manual.
- **int N5**
Size variable for CONMIN arrays. See CONMIN manual.
- **int NFDG**
Finite difference flag.
- **int IPRINT**
Flag to control amount of output data.
- **int ITMAX**
Flag to specify the maximum number of iterations.
- **Real FDCH**
Relative finite difference step size.
- **Real FDCHM**
Absolute finite difference step size.
- **Real CT**
Constraint thickness parameter.
- **Real CTMIN**
Minimum absolute value of CT used during optimization.

- Real **CTL**
Constraint thickness parameter for linear and side constraints.
- Real **CTLMIN**
Minimum value of CTL used during optimization.
- Real **DELFUN**
Relative convergence criterion threshold.
- Real **DABFUN**
Absolute convergence criterion threshold.
- Real * **conminDesVars**
Array of design variables used by CONMIN (length N1 = numdv+2).
- Real * **conminLowerBnds**
Array of lower bounds used by CONMIN (length N1 = numdv+2).
- Real * **conminUpperBnds**
Array of upper bounds used by CONMIN (length N1 = numdv+2).
- Real * **S**
Internal CONMIN array.
- Real * **G1**
Internal CONMIN array.
- Real * **G2**
Internal CONMIN array.
- Real * **B**
Internal CONMIN array.
- Real * **C**
Internal CONMIN array.
- int * **MS1**
Internal CONMIN array.
- Real * **SCAL**
Internal CONMIN array.
- Real * **DF**
Internal CONMIN array.
- Real * **A**
Internal CONMIN array.
- int * **ISC**
Internal CONMIN array.

- `int * IC`

Internal CONMIN array.

8.23.1 Detailed Description

Wrapper class for the CONMIN optimization library.

The [CONMINOptimizer](#) class provides a wrapper for CONMIN, a Public-domain Fortran 77 optimization library written by Gary Vanderplaats under contract to NASA Ames Research Center. The CONMIN User's Manual is contained in NASA Technical Memorandum X-62282, 1978. CONMIN uses a reverse communication mode, which avoids the static member function issues that arise with function pointer designs (see [NPSOLOptimizer](#) and [SNLLOptimizer](#)).

The user input mappings are as follows: `max_iterations` is mapped into CONMIN's `ITMAX` parameter, `max_function_evaluations` is implemented directly in the `find_optimum()` loop since there is no CONMIN equivalent, `convergence_tolerance` is mapped into CONMIN's `DELFUN` and `DABFUN` parameters, `output verbosity` is mapped into CONMIN's `IPRINT` parameter (verbose: `IPRINT = 4`; quiet: `IPRINT = 2`), `gradient mode` is mapped into CONMIN's `NFDG` parameter, and `finite difference step size` is mapped into CONMIN's `FDCH` and `FDCHM` parameters. Refer to [Vanderplaats, 1978] for additional information on CONMIN parameters.

8.23.2 Member Data Documentation

8.23.2.1 `int conminInfo` [private]

INFO from CONMIN manual.

Information requested by CONMIN: 1 = evaluate objective and constraints, 2 = evaluate gradients of objective and constraints.

8.23.2.2 `int printControl` [private]

IPRINT from CONMIN manual (controls output verbosity).

Values range from 0 (nothing) to 4 (most output). 0 = nothing, 1 = initial and final function information, 2 = all of #1 plus function value and design vars at each iteration, 3 = all of #2 plus constraint values and direction vectors, 4 = all of #3 plus gradients of the objective function and constraints, 5 = all of #4 plus proposed design vector, plus objective and constraint functions from the 1-D search

8.23.2.3 `int optimizationType` [private]

MINMAX from DOT manual (minimize or maximize).

Values of 0 or -1 (minimize) or 1 (maximize).

8.23.2.4 `RealVector localConstraintValues` [private]

array of nonlinear constraint values passed to CONMIN

This array must be of nonzero length (sized with `localConstraintArraySize`) and must contain only one-sided inequality constraints which are ≤ 0 (which requires a transformation from 2-sided inequalities and equalities).

8.23.2.5 `SizeList constraintMappingIndices` [private]

a list of indices for referencing the corresponding `Response` constraints used in computing the CONMIN constraints.

The length of the list corresponds to the number of CONMIN constraints, and each entry in the list points to the corresponding DAKOTA constraint.

8.23.2.6 `RealList constraintMappingMultipliers` [private]

a list of multipliers for mapping the `Response` constraints to the CONMIN constraints.

The length of the list corresponds to the number of CONMIN constraints, and each entry in the list contains a multiplier for the DAKOTA constraint identified with `constraintMappingIndices`. These multipliers are currently +1 or -1.

8.23.2.7 `RealList constraintMappingOffsets` [private]

a list of offsets for mapping the `Response` constraints to the CONMIN constraints.

The length of the list corresponds to the number of CONMIN constraints, and each entry in the list contains an offset for the DAKOTA constraint identified with `constraintMappingIndices`. These offsets involve inequality bounds or equality targets, since CONMIN assumes constraint allowables = 0.

8.23.2.8 `int N1` [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N1 = \text{number of variables} + 2$

8.23.2.9 `int N2` [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N2 = \text{number of constraints} + 2 * (\text{number of variables})$

8.23.2.10 `int N3` [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N3 = \text{Maximum possible number of active constraints.}$

8.23.2.11 `int N4` [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N4 = \text{Maximum}(N3, \text{number of variables})$

8.23.2.12 int N5 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$$N5 = 2*(N4)$$

8.23.2.13 Real CT [private]

Constraint thickness parameter.

The value of CT decreases in magnitude during optimization.

8.23.2.14 Real* S [private]

Internal CONMIN array.

Move direction in N-dimensional space.

8.23.2.15 Real* G1 [private]

Internal CONMIN array.

Temporary storage of constraint values.

8.23.2.16 Real* G2 [private]

Internal CONMIN array.

Temporary storage of constraint values.

8.23.2.17 Real* B [private]

Internal CONMIN array.

Temporary storage for computations involving array S.

8.23.2.18 Real* C [private]

Internal CONMIN array.

Temporary storage for use with arrays B and S.

8.23.2.19 int* MS1 [private]

Internal CONMIN array.

Temporary storage for use with arrays B and S.

8.23.2.20 Real* SCAL [private]

Internal CONMIN array.

Vector of scaling parameters for design parameter values.

8.23.2.21 Real* DF [private]

Internal CONMIN array.

Temporary storage for analytic gradient data.

8.23.2.22 Real* A [private]

Internal CONMIN array.

Temporary 2-D array for storage of constraint gradients.

8.23.2.23 int* ISC [private]

Internal CONMIN array.

[Array](#) of flags to identify linear constraints. (not used in this implementation of CONMIN)

8.23.2.24 int* IC [private]

Internal CONMIN array.

[Array](#) of flags to identify active and violated constraints

The documentation for this class was generated from the following files:

- CONMINOptimizer.H
- CONMINOptimizer.C

8.24 CtelRegexp Class Reference

Public Types

- enum `RStatus` {
 GOOD = 0, **EXP_TOO_BIG**, **OUT_OF_MEM**, **TOO_MANY_PAR**,
 UNMATCH_PAR, **STARPLUS_EMPTY**, **STARPLUS_NESTED**, **INDEX_RANGE**,
 INDEX_MATCH, **STARPLUS_NOthing**, **TRAILING**, **INT_ERROR**,
 BAD_PARAM, **BAD_OPCODE** }

Error codes reported by the engine - Most of these codes never really occurs with this implementation.

Public Member Functions

- `CtelRegexp` (const std::string &pattern)
Constructor - compile a regular expression.
- `~CtelRegexp` ()
Destructor.
- bool `compile` (const std::string &pattern)
Compile a new regular expression.
- std::string `match` (const std::string &str)
matches a particular string; this method returns a string that is a sub-string matching with the regular expression
- bool `match` (const std::string &str, size_t *start, size_t *size)
another form of matching; returns the indexes of the matching
- `RStatus` `getStatus` ()
Get status.
- const std::string & `getStatusMsg` ()
Get status message.
- void `clearErrors` ()
Clear all errors.
- const std::string & `getRe` ()
Return regular expression pattern.
- bool `split` (const std::string &str, std::vector< std::string > &all_matches)
Split.

Private Member Functions

- [CtelRegexp](#) (const [CtelRegexp](#) &)
Private copy constructor.
- [CtelRegexp](#) & [operator=](#) (const [CtelRegexp](#) &)
Private assignment operator.

Private Attributes

- `std::string` [strPattern](#)
STL string to hold pattern.
- `regexp * r`
Pointer to regexp.
- [RStatus](#) [status](#)
Return status, enumerated type.
- `std::string` [statusMsg](#)
STL string to hold status message.

8.24.1 Detailed Description

DESCRIPTION: Wrapper for the Regular Expression engine(`regexp`) released by Henry Spencer of the University of Toronto.

The documentation for this class was generated from the following files:

- `CtelRegExp.H`
- `CtelRegExp.C`

8.25 DataInterface Class Reference

Container class for interface specification data.

Public Member Functions

- [DataInterface](#) ()
constructor
- [DataInterface](#) (const [DataInterface](#) &)
copy constructor
- [~DataInterface](#) ()
destructor
- [DataInterface](#) & [operator=](#) (const [DataInterface](#) &)
assignment operator
- bool [operator==](#) (const [DataInterface](#) &)
equality operator
- void [write](#) (ostream &s) const
write a [DataInterface](#) object to an ostream
- void [read](#) (MPIUnpackBuffer &s)
read a [DataInterface](#) object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a [DataInterface](#) object to a packed MPI buffer

Public Attributes

- [String](#) [interfaceType](#)
the interface selection: application_system/fork/direct/grid or approximation_ann/rsm/mars/hermite/ksm/mpa/taylor/hierarchical
- [String](#) [idInterface](#)
string identifier for an interface specification data set (from the id_interface specification in InterfSetId)
- [String](#) [inputFilter](#)
the input filter for a simulation-based interface (from the input_filter specification in InterfApplic)
- [String](#) [outputFilter](#)
the output filter for a simulation-based interface (from the output_filter specification in InterfApplic)

- **StringArray analysisDrivers**
the set of analysis drivers for a simulation-based interface (from the analysis_drivers specification in InterfApplic)
- **String2DArray analysisComponents**
the set of analysis components for a simulation-based interface (from the analysis_components specification in InterfApplic)
- **String parametersFile**
the parameters file for system call and fork interfaces (from the parameters_file specification in InterfApplic)
- **String resultsFile**
the results file for system call and fork interfaces (from the results_file specification in InterfApplic)
- **String analysisUsage**
the analysis command usage string for a system call interface (from the analysis_usage specification in InterfApplic)
- **bool apreproFormatFlag**
the flag for aprepro format usage in the parameters file for system call and fork interfaces (from the aprepro specification in InterfApplic)
- **bool fileTagFlag**
the flag for file tagging of parameters and results files for system call and fork interfaces (from the file_tag specification in InterfApplic)
- **bool fileSaveFlag**
the flag for saving of parameters and results files for system call and fork interfaces (from the file_save specification in InterfApplic)
- **int procsPerAnalysis**
processors per parallel analysis for a direct interface (from the processors_per_analysis specification in InterfApplic)
- **String modelCenterFile**
configuration file for defining the simulation model accessed via the direct interface to the ModelCenter framework from Phoenix Integration (from the modelcenter_file specification in InterfApplic)
- **StringArray gridHostNames**
names of host machines for a grid interface (from the hostnames specification in InterfApplic)
- **IntArray gridProcsPerHost**
processors per host machine for a grid interface (from the processors_per_host specification in InterfApplic)
- **String interfaceSynchronization**
parallel mode for a simulation-based interface: synchronous or asynchronous (from the asynchronous specification in InterfApplic)
- **int asynchLocalEvalConcurrency**

evaluation concurrency for asynchronous simulation-based interfaces (from the evaluation_concurrency specification in InterfApplic)

- **int** `asynchLocalAnalysisConcurrency`
analysis concurrency for asynchronous simulation-based interfaces (from the analysis_concurrency specification in InterfApplic)
- **int** `evalServers`
number of evaluation servers to be used in the parallel configuration (from the evaluation_servers specification in InterfApplic)
- **String** `evalScheduling`
the scheduling approach to be used for concurrent evaluations within an iterator (from the evaluation_self_scheduling and evaluation_static_scheduling specifications in InterfApplic)
- **int** `analysisServers`
number of analysis servers to be used in the parallel configuration (from the analysis_servers specification in InterfApplic)
- **String** `analysisScheduling`
the scheduling approach to be used for concurrent analyses within a function evaluation (from the analysis_self_scheduling and analysis_static_scheduling specifications in InterfApplic)
- **String** `failAction`
the selected action upon capture of a simulation failure: abort, retry, recover, or continuation (from the failure_capture specification in InterfApplic)
- **int** `retryLimit`
the limit on retries for captured simulation failures (from the retry specification in InterfApplic)
- **RealVector** `recoveryFnVals`
the function values to be returned in a recovery operation for captured simulation failures (from the recover specification in InterfApplic)
- **bool** `activeSetVectorFlag`
active set vector: 1=active (ASV control on), 0=inactive (ASV control off) (from the deactivate active_set_vector specification in InterfApplic)
- **bool** `evalCacheFlag`
function evaluation cache: 1=active (all new evaluations checked against existing cache and then added to cache), 0=inactive (cache neither queried nor augmented) (from the deactivate evaluation_cache specification in InterfApplic)
- **bool** `restartFileFlag`
function evaluation cache: 1=active (all new evaluations written to restart), 0=inactive (no records written to restart) (from the deactivate restart_file specification in InterfApplic)
- **String** `approxType`
the selected approximation type: global, multipoint, local, or hierarchical
- **String** `actualInterfacePtr`

pointer to the interface specification for constructing the truth model used in building local and multipoint approximations (from the `actual_interface_pointer` specification in `InterfApprox`)

- **String `actualInterfaceResponsesPtr`**

pointer to the responses specification for constructing the truth model used in building local approximations (from the `actual_interface_responses_pointer` specification in `InterfApprox`). This allows differences in gradient specifications between the responses used to build the approximation and the responses computed from the approximation.

- **String `lowFidelityInterfacePtr`**

pointer to the low fidelity interface specification used in hierarchical approximations (from the `low_fidelity_interface_pointer` specification in `InterfApprox`)

- **String `highFidelityInterfacePtr`**

pointer to the high fidelity interface specification used in hierarchical approximations (from the `high_fidelity_interface_pointer` specification in `InterfApprox`)

- **String `approxDaceMethodPtr`**

pointer to the design of experiments method used in building global approximations (from the `dace_method_pointer` specification in `InterfApprox`)

- **String `approxSampleReuse`**

sample reuse selection for building global approximations: none, all, region, or file (from the `reuse_samples` specification in `InterfApprox`)

- **String `approxSampleReuseFile`**

the file name for the "file" setting for the `reuse_samples` specification in `InterfApprox`

- **String `approxCorrectionType`**

correction type for global and hierarchical approximations: additive or multiplicative (from the `correction` specification in `InterfApprox`)

- **short `approxCorrectionOrder`**

correction order for global and hierarchical approximations: 0, 1, or 2 (from the `correction` specification in `InterfApprox`)

- **bool `approxGradUsageFlag`**

flags the use of gradients in building global approximations (from the `use_gradients` specification in `InterfApprox`)

- **RealVector `krigingCorrelations`**

vector of correlations used in building a kriging approximation (from the `correlations` specification in `InterfApprox`)

- **short `polynomialOrder`**

scalar integer indicating the order of the polynomial approximation (1=linear, 2=quadratic, 3=cubic)

Private Member Functions

- void `assign` (const `DataInterface` &`data_interface`)

convenience function for setting this objects attributes equal to the attributes of the incoming data_interface object (used by copy constructor and assignment operator)

8.25.1 Detailed Description

Container class for interface specification data.

The [DataInterface](#) class is used to contain the data from an interface keyword specification. It is populated by [ProblemDescDB::interface_kwhandler\(\)](#) and is queried by the [ProblemDescDB::get_<datatype>\(\)](#) functions. A list of [DataInterface](#) objects is maintained in [ProblemDescDB::interfaceList](#), one for each interface specification in an input file. Default values are managed in the [DataInterface](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since [ProblemDescDB::interfaceList](#) is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataInterface.H](#)
- [DataInterface.C](#)

8.26 DataMethod Class Reference

Container class for method specification data.

Public Member Functions

- [DataMethod \(\)](#)
constructor
- [DataMethod \(const DataMethod &\)](#)
copy constructor
- [~DataMethod \(\)](#)
destructor
- [DataMethod & operator= \(const DataMethod &\)](#)
assignment operator
- [bool operator== \(const DataMethod &\)](#)
equality operator
- [void write \(ostream &s\) const](#)
write a DataMethod object to an ostream
- [void read \(MPIUnpackBuffer &s\)](#)
read a DataMethod object from a packed MPI buffer
- [void write \(MPIPackBuffer &s\) const](#)
write a DataMethod object to a packed MPI buffer

Public Attributes

- [String methodName](#)
the method selection: one of the dot, npsol, opt++, apps, sgopt, nond, dace, or parameter study methods
- [String idMethod](#)
string identifier for the method specification data set (from the id_method specification in MethodIndControl)
- [String variablesPointer](#)
string pointer to the variables specification to be used by this method (from the variables_pointer specification in MethodIndControl)
- [String interfacePointer](#)

string pointer to the interface specification to be used by this method (from the `interface_pointer` specification in `MethodIndControl`)

- **String responsesPointer**

string pointer to the responses specification to be used by this method (from the `responses_pointer` specification in `MethodIndControl`)

- **String modelType**

model type selection: single, nested, or layered (from the `model_type` specification in `MethodIndControl`)

- **String subMethodPointer**

string pointer to the sub-iterator used by nested models (from the `sub_method_pointer` specification in `MethodIndControl`)

- **String optionalInterfaceResponsesPointer**

string pointer to the responses specification used by the optional interface in nested models (from the `interface_responses_pointer` specification in `MethodIndControl`)

- **StringArray primaryVarMaps**

the primary variable mappings used in nested models for identifying the lower level variable targets for inserting top level variable values (from the `primary_variable_mapping` specification in `MethodIndControl`)

- **StringArray secondaryVarMaps**

the secondary variable mappings used in nested models for identifying the (distribution) parameter targets within the lower level variables for inserting top level variable values (from the `secondary_variable_mapping` specification in `MethodIndControl`)

- **RealVector primaryRespCoeffs**

the primary response mapping matrix used in nested models for weighting contributions from the sub-iterator responses in the top level (objective) functions (from the `primary_response_mapping` specification in `MethodIndControl`)

- **RealVector secondaryRespCoeffs**

the secondary response mapping matrix used in nested models for weighting contributions from the sub-iterator responses in the top level (constraint) functions (from the `secondary_response_mapping` specification in `MethodIndControl`)

- **String methodOutput**

method verbosity control: quiet, verbose, debug, or normal (default) (from the `output` specification in `MethodIndControl`)

- **Real convergenceTolerance**

iteration convergence tolerance for the method (from the `convergence_tolerance` specification in `MethodIndControl`)

- **Real constraintTolerance**

tolerance for controlling the amount of infeasibility that is allowed before an active constraint is considered to be violated (from the `constraint_tolerance` specification in `MethodIndControl`)

- **int maxIterations**

maximum number of iterations allowed for the method (from the `max_iterations` specification in `MethodIndControl`)

- **int** [maxFunctionEvaluations](#)
maximum number of function evaluations allowed for the method (from the max_function_evaluations specification in MethodIndControl)
- **bool** [speculativeFlag](#)
flag for use of speculative gradient approaches for maintaining parallel load balance during the line search portion of optimization algorithms (from the speculative specification in MethodIndControl)
- **RealVector** [linearIneqConstraintCoeffs](#)
coefficient matrix for the linear inequality constraints (from the linear_inequality_constraint_matrix specification in MethodIndControl)
- **RealVector** [linearIneqLowerBnds](#)
lower bounds for the linear inequality constraints (from the linear_inequality_lower_bounds specification in MethodIndControl)
- **RealVector** [linearIneqUpperBnds](#)
upper bounds for the linear inequality constraints (from the linear_inequality_upper_bounds specification in MethodIndControl)
- **RealVector** [linearEqConstraintCoeffs](#)
coefficient matrix for the linear equality constraints (from the linear_equality_constraint_matrix specification in MethodIndControl)
- **RealVector** [linearEqTargets](#)
targets for the linear equality constraints (from the linear_equality_targets specification in MethodIndControl)
- **String** [minMaxType](#)
the optimization_type specification in MethodDOTDC
- **int** [verifyLevel](#)
the verify_level specification in MethodNPSOLDC
- **Real** [functionPrecision](#)
the function_precision specification in MethodNPSOLDC
- **Real** [lineSearchTolerance](#)
the linesearch_tolerance specification in MethodNPSOLDC
- **Real** [absConvTol](#)
absolute function convergence tolerance
- **Real** [xConvTol](#)
x-convergence tolerance
- **Real** [singConvTol](#)
singular convergence tolerance
- **Real** [singRadius](#)

radius for singular convergence test

- Real `falseConvTol`
false-convergence tolerance
- Real `initTRRadius`
initial trust radius
- int `covarianceType`
kind of covariance required
- bool `regressDiag`
whether to print the regression diagnostic vector
- String `searchMethod`
the search_method specification for Newton and nonlinear interior-point methods in MethodOPTPPDC
- Real `gradientTolerance`
the gradient_tolerance specification in MethodOPTPPDC
- Real `maxStep`
the max_step specification in MethodOPTPPDC
- String `meritFn`
the merit_function specification for nonlinear interior-point methods in MethodOPTPPDC
- String `centralPath`
the central_path specification for nonlinear interior-point methods in MethodOPTPPDC
- Real `stepLenToBoundary`
the steplength_to_boundary specification for nonlinear interior-point methods in MethodOPTPPDC
- Real `centeringParam`
the centering_parameter specification for nonlinear interior-point methods in MethodOPTPPDC
- int `searchSchemeSize`
the search_scheme_size specification for PDS methods in MethodOPTPPDC
- String `evalSynchronization`
the synchronization setting for parallel pattern search methods in MethodCOLINYPS and MethodCOLINYAPPS
- Real `constraintPenalty`
the initial constraint_penalty for COLINY methods in MethodCOLINYAPPS, MethodCOLINYDIR, MethodCOLINYPS, and MethodCOLINYSW
- bool `constantPenalty`
the constant_penalty flag for COLINY methods in MethodCOLINYPS and MethodCOLINYSW

- Real [globalBalanceParam](#)
the global_balance_parameter for the DIRECT method in MethodCOLINYDIR
- Real [localBalanceParam](#)
the local_balance_parameter for the DIRECT method in MethodCOLINYDIR
- Real [maxBoxSize](#)
the max_boxsize_limit for the DIRECT method in MethodCOLINYDIR
- Real [minBoxSize](#)
the min_boxsize_limit for the DIRECT method in MethodCOLINYDIR
- String [boxDivision](#)
the division_setting (major_dimension or all_dimensions) for the DIRECT method in MethodCOLINYDIR
- bool [showMiscOptions](#)
the show_misc_options specification in MethodCOLINYDC
- StringArray [miscOptions](#)
the misc_options specification in MethodCOLINYDC
- Real [solnAccuracy](#)
the solution_accuracy specification in MethodSGOPTDC
- Real [crossoverRate](#)
the crossover_rate specification for GA/EPSSA methods in MethodSGOPTEA
- Real [mutationDimRate](#)
the dimension_rate specification for mutation in GA/EPSSA methods in MethodSGOPTEA
- Real [mutationPopRate](#)
the population_rate specification for mutation in GA/EPSSA methods in MethodSGOPTEA
- Real [mutationScale](#)
the mutation_scale specification for GA/EPSSA methods in MethodSGOPTEA
- Real [mutationMinScale](#)
the min_scale specification for mutation in EPSSA methods in MethodSGOPTEA
- Real [initDelta](#)
the initial_delta specification for APPS/PS/SW methods in MethodCOLINYAPPS, MethodSGOPTPS, and MethodSGOPTSW
- Real [threshDelta](#)
the threshold_delta specification for APPS/PS/SW methods in MethodCOLINYAPPS, MethodSGOPTPS, and MethodSGOPTSW
- Real [contractFactor](#)
the contraction_factor specification for APPS/PS/SW methods in MethodCOLINYAPPS, MethodSGOPTPS, and MethodSGOPTSW

- **int newSolnsGenerated**
the new_solutions_generated specification for GA/EP SA methods in MethodSGOPT EA
- **int numberRetained**
the integer assignment to random, chc, or elitist in the replacement_type specification for GA/EP SA methods in MethodSGOPT EA
- **bool expansionFlag**
the no_expansion specification for APPS/PS/SW methods in MethodCOLINYAPPS, MethodSGOPTPS, and MethodSGOPTSW
- **int expandAfterSuccess**
the expand_after_success specification for PS/SW methods in MethodSGOPTPS and MethodSGOPTSW
- **int contractAfterFail**
the contract_after_failure specification for the SW method in MethodSGOPTSW
- **int mutationRange**
the mutation_range specification for the pga_int method in MethodSGOPT EA
- **int numPartitions**
the num_partitions specification for EP SA methods in MethodSGOPT EA
- **int totalPatternSize**
the total_pattern_size specification for APPS/PS methods in MethodCOLINYAPPS and MethodSGOPTPS
- **int batchSize**
the batch_size specification for the sMC method in MethodSGOPTSMC
- **bool nonAdaptiveFlag**
the non_adaptive specification for the pga_real method in MethodSGOPT EA
- **bool randomizeOrderFlag**
the stochastic specification for the PS method in MethodSGOPTPS
- **String selectionPressure**
the selection_pressure specification for GA/EP SA methods in MethodSGOPT EA
- **String replacementType**
the replacement_type specification for GA/EP SA methods in MethodSGOPT EA
- **String crossoverType**
the crossover_type specification for GA/EP SA methods in MethodSGOPT EA
- **String mutationType**
the mutation_type specification for GA/EP SA methods in MethodSGOPT EA

- **String exploratoryMoves**
the exploratory_moves specification for the PS method in MethodSGOPTPS
- **String patternBasis**
the pattern_basis specification for APPS/PS methods in MethodCOLINYAPPS and MethodSGOPTPS
- **IntArray varPartitions**
the partitions specification for sMC/PStudy methods in MethodSGOPTSMC and MethodPSMPS
- **size_t numCrossPoints**
The number of crossover points or multi-point schemes.
- **size_t numParents**
The number of parents to use in a crossover operation.
- **size_t numOffspring**
The number of children to produce in a crossover operation.
- **String fitnessType**
the fitness assessment operator to use.
- **String convergenceType**
The means by which this JEGA should converge.
- **size_t dominationCutoff**
The cutoff value for survival in domination count selection.
- **Real shrinkagePercent**
The minimum percentage of the requested number of selections that must take place on each call to the selector (0, 1).
- **Real percentChange**
The minimum percent change before convergence for a fitness tracker converger.
- **size_t numGenerations**
The number of generations over which a fitness tracker converger should track.
- **Real exteriorPenaltyMultiplier**
The penalty multiplier to use with penalty fitness assessors.
- **String initializationType**
The means by which the JEGA should initialize the population.
- **String flatFile**
The filename to use for initialization.
- **int populationSize**
the population_size specification for GA methods in MethodSGOPTPEA, MethodCOLINY, and
- **String daceMethod**

the dace method selection: grid, random, oas, lhs, oa_lhs, box_behnken, or central_composite (from the dace specification in MethodDDACE)

- **int numSymbols**
the symbols specification for DACE methods
- **bool latinizeFlag**
the latinize specification for FSU QMC and CVT methods in MethodFSUDACE
- **bool volQualityFlag**
the quality_metrics specification for sampling methods (FSU QMC and CVT methods in MethodFSUDACE)
- **bool varBasedDecompFlag**
the var_based_decomp specification for sampling methods (FSU QMC and CVT methods in MethodFSUDACE)
- **IntVector sequenceStart**
the sequenceStart specification in MethodFSUDACE
- **IntVector sequenceLeap**
the sequenceLeap specification in MethodFSUDACE
- **IntVector primeBase**
the primeBase specification in MethodFSUDACE
- **int numTrials**
the numTrials specification in MethodFSUDACE
- **String trialType**
the trial_type specification in MethodFSUDACE
- **int randomSeed**
the seed specification for SGOPT, NonD, & DACE methods
- **int numSamples**
the samples specification for NonD & DACE methods
- **bool fixedSeedFlag**
flag for fixing the value of the seed among different NonD/DACE sample sets. This results in the use of the same sampling stencil/pattern throughout a strategy with repeated sampling.
- **bool fixedSequenceFlag**
flag for fixing the sequence for Halton or Hammersley QMC sample sets. This results in the use of the same sampling stencil/pattern throughout a strategy with repeated sampling.
- **int expansionTerms**
the expansion_terms specification in MethodNonDPCE
- **int expansionOrder**
the expansion_order specification in MethodNonDPCE

- [String sampleType](#)
the sample_type specification in MethodNonDMC and MethodNonDPCE
- [String reliabilitySearchType](#)
the type of MPP search as specified by x_linearize_mean, x_linearize_mpp, u_linearize_mean, u_linearize_mpp, or no_linearize in MethodNonDRel
- [String reliabilitySearchAlgorithm](#)
the algorithm selection used for computing the MPP as specified by sqp or nip in MethodNonDRel
- [String reliabilityIntegration](#)
the first_order/second_order integration selection in MethodNonDRel
- [String distributionType](#)
the distribution cumulative or complementary specification in MethodNonDMC, MethodNonDPCE, and MethodNonDRel
- [String responseLevelMappingType](#)
the compute probabilities or reliabilities specification in MethodNonDMC, MethodNonDPCE, and MethodNonDRel
- [RealVectorArray responseLevels](#)
the response_levels specification in MethodNonDMC, MethodNonDPCE, and MethodNonDRel
- [RealVectorArray probabilityLevels](#)
the probability_levels specification in MethodNonDMC, MethodNonDPCE, and MethodNonDRel
- [RealVectorArray reliabilityLevels](#)
the reliability_levels specification in MethodNonDMC, MethodNonDPCE, and MethodNonDRel
- [bool allVarsFlag](#)
the all_variables specification in MethodNonDMC
- [int paramStudyType](#)
the type of parameter study: list(-1), vector(1, 2, or 3), centered(4), or multidim(5)
- [RealVector finalPoint](#)
the final_point specification in MethodPSVPS
- [RealVector stepVector](#)
the step_vector specification in MethodPSVPS
- [Real stepLength](#)
the step_length specification in MethodPSVPS
- [int numSteps](#)
the num_steps specification in MethodPSVPS
- [RealVector listOfPoints](#)

the list_of_points specification in MethodPSLPS

- Real [percentDelta](#)

the percent_delta specification in MethodPSCPS

- int [deltasPerVariable](#)

the deltas_per_variable specification in MethodPSCPS

Private Member Functions

- void [assign](#) (const [DataMethod](#) &data_method)

convenience function for setting this objects attributes equal to the attributes of the incoming data_method object (used by copy constructor and assignment operator)

8.26.1 Detailed Description

Container class for method specification data.

The [DataMethod](#) class is used to contain the data from a method keyword specification. It is populated by [ProblemDescDB::method_kw_handler\(\)](#) and is queried by the [ProblemDescDB::get_<datatype>\(\)](#) functions. A list of [DataMethod](#) objects is maintained in [ProblemDescDB::methodList](#), one for each method specification in an input file. Default values are managed in the [DataMethod](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since [ProblemDescDB::methodList](#) is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataMethod.H](#)
- [DataMethod.C](#)

8.27 DataResponses Class Reference

Container class for responses specification data.

Public Member Functions

- [DataResponses](#) ()
constructor
- [DataResponses](#) (const [DataResponses](#) &)
copy constructor
- [~DataResponses](#) ()
destructor
- [DataResponses](#) & [operator=](#) (const [DataResponses](#) &)
assignment operator
- bool [operator==](#) (const [DataResponses](#) &)
equality operator
- void [write](#) (ostream &s) const
write a [DataResponses](#) object to an ostream
- void [read](#) (MPIUnpackBuffer &s)
read a [DataResponses](#) object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a [DataResponses](#) object to a packed MPI buffer

Public Attributes

- size_t [numObjectiveFunctions](#)
number of objective functions (from the num_objective_functions specification in RespFnOpt)
- size_t [numNonlinearIneqConstraints](#)
number of nonlinear inequality constraints (from the num_nonlinear_inequality_constraints specification in RespFnOpt)
- size_t [numNonlinearEqConstraints](#)
number of nonlinear equality constraints (from the num_nonlinear_equality_constraints specification in RespFnOpt)
- size_t [numLeastSqTerms](#)
number of least squares terms (from the num_least_squares_terms specification in RespFnLS)

- **size_t numResponseFunctions**
number of generic response functions (from the num_response_functions specification in RespFnGen)
- **RealVector multiObjectiveWeights**
vector of multiobjective weightings (from the multi_objective_weights specification in RespFnOpt)
- **RealVector nonlinearIneqLowerBnds**
vector of nonlinear inequality constraint lower bounds (from the nonlinear_inequality_lower_bounds specification in RespFnOpt)
- **RealVector nonlinearIneqUpperBnds**
vector of nonlinear inequality constraint upper bounds (from the nonlinear_inequality_upper_bounds specification in RespFnOpt)
- **RealVector nonlinearEqTargets**
vector of nonlinear equality constraint targets (from the nonlinear_equality_targets specification in RespFnOpt)
- **String gradientType**
gradient type: none, numerical, analytic, or mixed (from the no_gradients, numerical_gradients, analytic_gradients, and mixed_gradients specifications in RespGrad)
- **String hessianType**
Hessian type: none, numerical, quasi, analytic, or mixed (from the no_hessians, numerical_hessians, quasi_hessians, analytic_hessians, and mixed_hessians specifications in RespHess).
- **String quasiHessianType**
quasi-Hessian type: bfgs, damped_bfgs, or srl (from the bfgs and srl specifications in RespHess)
- **String methodSource**
numerical gradient method source: dakota or vendor (from the method_source specification in RespGradNum and RespGradMixed)
- **String intervalType**
numerical gradient interval type: forward or central (from the interval_type specification in RespGradNum and RespGradMixed)
- **RealVector fdGradStepSize**
vector of finite difference step sizes for numerical gradients, one step size per active continuous variable, used in computing 1st-order forward or central differences (from the fd_gradient_step_size specification in RespGradNum and RespGradMixed)
- **RealVector fdHessStepSize**
vector of finite difference step sizes for numerical Hessians, one step size per active continuous variable, used in computing 1st-order gradient-based differences and 2nd-order function-based differences (from the fd_hessian_step_size specification in RespHessNum and RespHessMixed)
- **IntList idNumericalGrads**

mixed gradient numerical identifiers (from the id_numerical_gradients specification in RespGrad-Mixed)

- [IntList idAnalyticGrads](#)

mixed gradient analytic identifiers (from the id_analytic_gradients specification in RespGrad-Mixed)

- [IntList idNumericalHessians](#)

mixed Hessian numerical identifiers (from the id_numerical_hessians specification in RespHess-Mixed)

- [IntList idQuasiHessians](#)

mixed Hessian quasi identifiers (from the id_quasi_hessians specification in RespHessMixed)

- [IntList idAnalyticHessians](#)

mixed Hessian analytic identifiers (from the id_analytic_hessians specification in RespHessMixed)

- [String idResponses](#)

string identifier for the responses specification data set (from the id_responses specification in Resp-SetId)

- [StringArray responseLabels](#)

the response labels array (from the response_descriptors specification in RespLabels)

Private Member Functions

- void [assign](#) (const [DataResponses](#) &data_responses)

convenience function for setting this objects attributes equal to the attributes of the incoming data_responses object (used by copy constructor and assignment operator)

8.27.1 Detailed Description

Container class for responses specification data.

The [DataResponses](#) class is used to contain the data from a responses keyword specification. It is populated by [ProblemDescDB::responses_kwhandler\(\)](#) and is queried by the [ProblemDescDB::get_<datatype>\(\)](#) functions. A list of [DataResponses](#) objects is maintained in [ProblemDescDB::responsesList](#), one for each responses specification in an input file. Default values are managed in the [DataResponses](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since [ProblemDescDB::responsesList](#) is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataResponses.H](#)
- [DataResponses.C](#)

8.28 DataStrategy Class Reference

Container class for strategy specification data.

Public Member Functions

- [DataStrategy \(\)](#)
constructor
- [DataStrategy \(const DataStrategy &\)](#)
copy constructor
- [~DataStrategy \(\)](#)
destructor
- [DataStrategy & operator= \(const DataStrategy &\)](#)
assignment operator
- void [write](#) (ostream &s) const
write a DataStrategy object to an ostream
- void [read](#) (MPIUnpackBuffer &s)
read a DataStrategy object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a DataStrategy object to a packed MPI buffer

Public Attributes

- [String strategyType](#)
the strategy selection: multi_level, surrogate_based_opt, opt_under_uncertainty, branch_and_bound, multi_start, pareto_set, or single_method
- bool [graphicsFlag](#)
flags use of graphics by the strategy (from the graphics specification in StratIndControl)
- bool [tabularDataFlag](#)
flags tabular data collection by the strategy (from the tabular_graphics_data specification in StratIndControl)
- [String tabularDataFile](#)
the filename used for tabular data collection by the strategy (from the tabular_graphics_file specification in StratIndControl)
- int [iteratorServers](#)

number of servers for concurrent iterator parallelism (from the `iterator_servers` specification in `StratIndControl`)

- **String `iteratorScheduling`**

type of scheduling (self or static) used in concurrent iterator parallelism (from the `iterator_self_scheduling` and `iterator_static_scheduling` specifications in `StratIndControl`)

- **String `methodPointer`**

method identifier for the strategy (from the `opt_method_pointer` specifications in `StratSBO`, `StratOUU`, `StratBandB`, and `StratParetoSet` and `method_pointer` specifications in `StratSingle` and `StratMultiStart`)

- **int `branchBndNumSamplesRoot`**

number of samples at the root for the branch and bound strategy (from the `num_samples_at_root` specification in `StratBandB`)

- **int `branchBndNumSamplesNode`**

number of samples at each node for the branch and bound strategy (from the `num_samples_at_node` specification in `StratBandB`)

- **StringArray `multilevelMethodList`**

array of methods for the multilevel hybrid optimization strategy (from the `method_list` specification in `StratML`)

- **String `multilevelType`**

the type of multilevel hybrid optimization strategy: `uncoupled`, `uncoupled_adaptive`, or `coupled` (from the `uncoupled`, `adaptive`, and `coupled` specifications in `StratML`)

- **Real `multilevelProgThresh`**

progress threshold for `uncoupled_adaptive` multilevel hybrids (from the `progress_threshold` specification in `StratML`)

- **String `multilevelGlobalMethodPointer`**

global method pointer for coupled multilevel hybrids (from the `global_method_pointer` specification in `StratML`)

- **String `multilevelLocalMethodPointer`**

local method pointer for coupled multilevel hybrids (from the `local_method_pointer` specification in `StratML`)

- **Real `multilevelLSProb`**

local search probability for coupled multilevel hybrids (from the `local_search_probability` specification in `StratML`)

- **int `surrBasedOptMaxIterations`**

maximum number of iterations in the surrogate-based optimization strategy (from the `max_iterations` specification in `StratSBO`)

- **Real `surrBasedOptConvTol`**

convergence tolerance in the surrogate-based optimization strategy (from the `convergence_tolerance` specification in `StratSBO`)

- **int `surrBasedOptSoftConvLimit`**

number of consecutive iterations with change less than `surrBasedOptConvTol` required to trigger convergence within the surrogate-based optimization strategy (from the `soft_convergence_limit` specification in `StratSBO`)

- bool `surrBasedOptLayerBypass`

flag to indicate user-specification of a bypass of any/all layerings in evaluating truth response values in SBO.

- Real `surrBasedOptTRInitSize`

initial trust region size in the surrogate-based optimization strategy (from the `initial_size` specification in `StratSBO`) note: this is a relative value, e.g., 0.1 = 10% of global bounds distance (upper bound - lower bound) for each variable

- Real `surrBasedOptTRMinSize`

minimum trust region size in the surrogate-based optimization strategy (from the `minimum_size` specification in `StratSBO`), if the trust region size falls below this threshold the SBO iterations are terminated (note: if kriging is used with SBO, the min trust region size is set to 1.0e-3 in attempt to avoid ill-conditioned matrixes that arise in kriging over small trust regions)

- Real `surrBasedOptTRContractTrigger`

trust region minimum improvement level (ratio of actual to predicted decrease in objective fcn) in the surrogate-based optimization strategy (from the `contract_region_threshold` specification in `StratSBO`), the trust region shrinks or is rejected if the ratio is below this value ("`eta_1`" in the Conn-Gould-Toint trust region book)

- Real `surrBasedOptTRExpandTrigger`

trust region sufficient improvement level (ratio of actual to predicted decrease in objective fcn) in the surrogate-based optimization strategy (from the `expand_region_threshold` specification in `StratSBO`), the trust region expands if the ratio is above this value ("`eta_2`" in the Conn-Gould-Toint trust region book)

- Real `surrBasedOptTRContract`

trust region contraction factor in the surrogate-based optimization strategy (from the `contraction_factor` specification in `StratSBO`)

- Real `surrBasedOptTRExpand`

trust region expansion factor in the surrogate-based optimization strategy (from the `expansion_factor` specification in `StratSBO`)

- int `concurrentRandomJobs`

number of random jobs to perform in the concurrent strategy (from the `random_starts` and `random_weight_sets` specifications in `StratMultiStart` and `StratParetoSet`)

- int `concurrentSeed`

seed for the selected random jobs within the concurrent strategy (from the `seed` specification in `StratMultiStart` and `StratParetoSet`)

- RealVector `concurrentParameterSets`

user-specified (i.e., nonrandom) parameter sets to evaluate in the concurrent strategy (from the `starting_points` and `multi_objective_weight_sets` specifications in `StratMultiStart` and `StratParetoSet`)

Private Member Functions

- void `assign` (const [DataStrategy](#) &data_strategy)
convenience function for setting this objects attributes equal to the attributes of the incoming data_strategy object (used by copy constructor and assignment operator)

8.28.1 Detailed Description

Container class for strategy specification data.

The [DataStrategy](#) class is used to contain the data from a strategy keyword specification. It is populated by [ProblemDescDB::strategy_kwhandler\(\)](#) and is queried by the [ProblemDescDB::get_<datatype>\(\)](#) functions. Default values are managed in the [DataStrategy](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since [ProblemDescDB::strategySpec](#) is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

The documentation for this class was generated from the following files:

- [DataStrategy.H](#)
- [DataStrategy.C](#)

8.29 DataVariables Class Reference

Container class for variables specification data.

Public Member Functions

- [DataVariables](#) ()
constructor
- [DataVariables](#) (const [DataVariables](#) &)
copy constructor
- [~DataVariables](#) ()
destructor
- [DataVariables](#) & [operator=](#) (const [DataVariables](#) &)
assignment operator
- bool [operator==](#) (const [DataVariables](#) &)
equality operator
- void [write](#) (ostream &s) const
write a [DataVariables](#) object to an ostream
- void [read](#) (MPIUnpackBuffer &s)
read a [DataVariables](#) object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a [DataVariables](#) object to a packed MPI buffer
- size_t [design](#) ()
return total number of design variables
- size_t [uncertain](#) ()
return total number of uncertain variables
- size_t [state](#) ()
return total number of state variables
- size_t [num_continuous_variables](#) ()
return total number of continuous variables
- size_t [num_discrete_variables](#) ()
return total number of discrete variables
- size_t [num_variables](#) ()
return total number of variables

Public Attributes

- **String idVariables**
string identifier for the variables specification data set (from the id_variables specification in VarSetId)
- **size_t numContinuousDesVars**
number of continuous design variables (from the continuous_design specification in VarDV)
- **size_t numDiscreteDesVars**
number of discrete design variables (from the discrete_design specification in VarDV)
- **size_t numNormalUncVars**
number of normal uncertain variables (from the normal_uncertain specification in VarUV)
- **size_t numLognormalUncVars**
number of lognormal uncertain variables (from the lognormal_uncertain specification in VarUV)
- **size_t numUniformUncVars**
number of uniform uncertain variables (from the uniform_uncertain specification in VarUV)
- **size_t numLoguniformUncVars**
number of loguniform uncertain variables (from the loguniform_uncertain specification in VarUV)
- **size_t numWeibullUncVars**
number of weibull uncertain variables (from the weibull_uncertain specification in VarUV)
- **size_t numHistogramUncVars**
number of histogram uncertain variables (from the histogram_uncertain specification in VarUV)
- **size_t numContinuousStateVars**
number of continuous state variables (from the continuous_state specification in VarSV)
- **size_t numDiscreteStateVars**
number of discrete state variables (from the discrete_state specification in VarSV)
- **RealVector continuousDesignVars**
initial values for the continuous design variables array (from the cdv_initial_point specification in VarDV)
- **RealVector continuousDesignLowerBnds**
the continuous design lower bounds array (from the cdv_lower_bounds specification in VarDV)
- **RealVector continuousDesignUpperBnds**
the continuous design upper bounds array (from the cdv_upper_bounds specification in VarDV)
- **IntVector discreteDesignVars**
initial values for the discrete design variables array (from the ddv_initial_point specification in VarDV)
- **IntVector discreteDesignLowerBnds**

the discrete design lower bounds array (from the `ddv_lower_bounds` specification in `VarDV`)

- **IntVector discreteDesignUpperBnds**
the discrete design upper bounds array (from the `ddv_upper_bounds` specification in `VarDV`)
- **StringArray continuousDesignLabels**
the continuous design labels array (from the `cdv_descriptors` specification in `VarDV`)
- **StringArray discreteDesignLabels**
the discrete design labels array (from the `ddv_descriptors` specification in `VarDV`)
- **RealVector normalUncMeans**
means of the normal uncertain variables (from the `nuv_means` specification in `VarUV`)
- **RealVector normalUncStdDevs**
standard deviations of the normal uncertain variables (from the `nuv_std_deviations` specification in `VarUV`)
- **RealVector normalUncDistLowerBnds**
distribution lower bounds for the normal uncertain variables (from the `nuv_dist_lower_bounds` specification in `VarUV`)
- **RealVector normalUncDistUpperBnds**
distribution upper bounds for the normal uncertain variables (from the `nuv_dist_upper_bounds` specification in `VarUV`)
- **RealVector lognormalUncMeans**
means of the lognormal uncertain variables (from the `lnuv_means` specification in `VarUV`)
- **RealVector lognormalUncStdDevs**
standard deviations of the lognormal uncertain variables (from the `lnuv_std_deviations` specification in `VarUV`)
- **RealVector lognormalUncErrFacts**
error factors for the lognormal uncertain variables (from the `lnuv_error_factors` specification in `VarUV`)
- **RealVector lognormalUncDistLowerBnds**
distribution lower bounds for the lognormal uncertain variables (from the `lnuv_dist_lower_bounds` specification in `VarUV`)
- **RealVector lognormalUncDistUpperBnds**
distribution upper bounds for the lognormal uncertain variables (from the `lnuv_dist_upper_bounds` specification in `VarUV`)
- **RealVector uniformUncDistLowerBnds**
distribution lower bounds for the uniform uncertain variables (from the `uuv_dist_lower_bounds` specification in `VarUV`)
- **RealVector uniformUncDistUpperBnds**
distribution upper bounds for the uniform uncertain variables (from the `uuv_dist_upper_bounds` specification in `VarUV`)

- [RealVector loguniformUncDistLowerBnds](#)
distribution lower bounds for the loguniform uncertain variables (from the `luuv_dist_lower_bounds` specification in `VarUV`)
- [RealVector loguniformUncDistUpperBnds](#)
distribution upper bounds for the loguniform uncertain variables (from the `luuv_dist_upper_bounds` specification in `VarUV`)
- [RealVector weibullUncAlphas](#)
alpha factors for the weibull uncertain variables (from the `wuv_alphas` specification in `VarUV`)
- [RealVector weibullUncBetas](#)
beta factors for the weibull uncertain variables (from the `wuv_betas` specification in `VarUV`)
- [RealVector weibullUncDistLowerBnds](#)
distribution lower bounds for the weibull uncertain variables (from the `wuv_dist_lower_bounds` specification in `VarUV`)
- [RealVector weibullUncDistUpperBnds](#)
distribution upper bounds for the weibull uncertain variables (from the `wuv_dist_upper_bounds` specification in `VarUV`)
- [RealVectorArray histogramUncBinPairs](#)
an array containing a vector of (x,y) pairs for each bin-based histogram uncertain variable (see continuous linear histogram in LHS manual; from the `huv_num_bin_pairs` and `huv_bin_pairs` specifications in `VarUV`)
- [RealVectorArray histogramUncPointPairs](#)
an array containing a vector of (x,y) pairs for each point-based histogram uncertain variable (see discrete histogram in LHS manual; from the `huv_num_point_pairs` and `huv_point_pairs` specifications in `VarUV`)
- [RealMatrix uncertainCorrelations](#)
correlation matrix for all uncertain variables (from the `uncertain_correlation_matrix` specification in `VarUV`). This matrix specifies rank correlations for sampling methods (i.e., LHS) and correlation coefficients (ρ_{ij} = normalized covariance matrix) for analytic reliability methods.
- [RealVector uncertainVars](#)
array of values for all uncertain variables (built and initialized in `ProblemDescDB::variables_kwhandler()`)
- [RealVector uncertainDistLowerBnds](#)
distribution lower bounds for all uncertain variables (collected from `nuv_dist_lower_bounds`, `lnuv_dist_lower_bounds`, `uuv_dist_lower_bounds`, `luuv_dist_lower_bounds`, `wuv_dist_lower_bounds`, and `huv_dist_lower_bounds` specifications in `VarUV`)
- [RealVector uncertainDistUpperBnds](#)
distribution upper bounds for all uncertain variables (collected from `nuv_dist_upper_bounds`, `lnuv_dist_upper_bounds`, `uuv_dist_upper_bounds`, `luuv_dist_upper_bounds`, `wuv_dist_upper_bounds`, and `huv_dist_upper_bounds` specifications in `VarUV`)
- [StringArray uncertainLabels](#)

labels for all uncertain variables (collected from `nuv_descriptors`, `lnuv_descriptors`, `uuv_descriptors`, `luuv_descriptors`, `wuv_descriptors`, and `huv_descriptors` specifications in `VarUV`)

- [RealVector continuousStateVars](#)

initial values for the continuous state variables array (from the `csv_initial_state` specification in `VarSV`)

- [RealVector continuousStateLowerBnds](#)

the continuous state lower bounds array (from the `csv_lower_bounds` specification in `VarSV`)

- [RealVector continuousStateUpperBnds](#)

the continuous state upper bounds array (from the `csv_upper_bounds` specification in `VarSV`)

- [IntVector discreteStateVars](#)

initial values for the discrete state variables array (from the `dsv_initial_state` specification in `VarSV`)

- [IntVector discreteStateLowerBnds](#)

the discrete state lower bounds array (from the `dsv_lower_bounds` specification in `VarSV`)

- [IntVector discreteStateUpperBnds](#)

the discrete state upper bounds array (from the `dsv_upper_bounds` specification in `VarSV`)

- [StringArray continuousStateLabels](#)

the continuous state labels array (from the `csv_descriptors` specification in `VarSV`)

- [StringArray discreteStateLabels](#)

the discrete state labels array (from the `dsv_descriptors` specification in `VarSV`)

Private Member Functions

- `void assign` (const [DataVariables](#) &data_variables)

convenience function for setting this objects attributes equal to the attributes of the incoming data_variables object (used by copy constructor and assignment operator)

8.29.1 Detailed Description

Container class for variables specification data.

The [DataVariables](#) class is used to contain the data from a variables keyword specification. It is populated by [ProblemDescDB::variables_kwhandler\(\)](#) and is queried by the [ProblemDescDB::get_<datatype>\(\)](#) functions. A list of [DataVariables](#) objects is maintained in [ProblemDescDB::variablesList](#), one for each variables specification in an input file. Default values are managed in the [DataVariables](#) constructor. Data is public to avoid maintaining set/get functions, but is still encapsulated within [ProblemDescDB](#) since [ProblemDescDB::variablesList](#) is private (a similar model is used with [SurrogateDataPoint](#) objects contained in [Dakota::Approximation](#)).

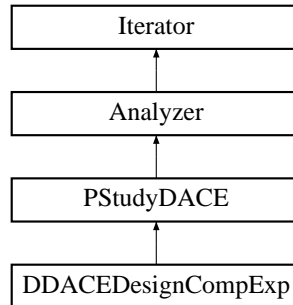
The documentation for this class was generated from the following files:

- [DataVariables.H](#)
- [DataVariables.C](#)

8.30 DDACEDesignCompExp Class Reference

Wrapper class for the DDACE design of experiments library.

Inheritance diagram for DDACEDesignCompExp::



Public Member Functions

- [DDACEDesignCompExp \(Model &model\)](#)
primary constructor for building a standard DACE iterator
- [~DDACEDesignCompExp \(\)](#)
destructor
- void [extract_trends \(\)](#)
Redefines the run_iterator virtual function for the PStudy/DACE branch.
- void [sampling_reset](#) (int min_samples, bool all_data_flag, bool stats_flag)
reset sampling iterator
- const [String & sampling_scheme \(\)](#) const
return sampling name
- void [get_parameter_sets](#) (bool vbd_change_seq_flag)
*Returns one block of samples (ndim * num_samples).*

Private Member Functions

- void [resolve_samples_symbols \(\)](#)
convenience function for resolving number of samples and number of symbols from input.

Private Attributes

- [String daceMethod](#)
oas, lhs, oa_lhs, random, box_behnken, central_composite, or grid
- [int numSamples](#)
number of samples to be evaluated
- [int numSymbols](#)
number of symbols to be used in generating the sample set (inversely related to number of replications)
- [const int originalSeed](#)
the user seed specification for the random number generator (allows repeatable results)
- [int randomSeed](#)
current seed for the random number generator
- [bool allDataFlag](#)
flag which triggers the update of allVars/allResponses for use by [Iterator::all_variables\(\)](#) and [Iterator::all_responses\(\)](#)
- [size_t numDACERuns](#)
counter for number of executions of [run_iterator\(\)](#) for this object
- [bool varyPattern](#)
flag for continuing the random number sequence from a previous [run_iterator\(\)](#) execution (e.g., for surrogate-based optimization) so that multiple executions are repeatable but not correlated.
- [bool volQualityFlag](#)
flag which specifies evaluating the volumetric quality measures
- [bool varBasedDecompFlag](#)
flag which specifies variance based decomposition

8.30.1 Detailed Description

Wrapper class for the DDACE design of experiments library.

The [DDACEDesignCompExp](#) class provides a wrapper for DDACE, a C++ design of experiments library from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site. This class uses design and analysis of computer experiments (DACE) methods to sample the design space spanned by the bounds of a [Model](#). It returns all generated samples and their corresponding responses as well as the best sample found.

8.30.2 Constructor & Destructor Documentation

8.30.2.1 DDACEDesignCompExp (Model & model)

primary constructor for building a standard DACE iterator

This constructor is called for a standard iterator built with data from probDescDB.

8.30.3 Member Function Documentation

8.30.3.1 void resolve_samples_symbols () [private]

convenience function for resolving number of samples and number of symbols from input.

This function must define a combination of samples and symbols that is acceptable for a particular sampling algorithm. Users provide requests for these quantities, but this function must enforce any restrictions imposed by the sampling algorithms.

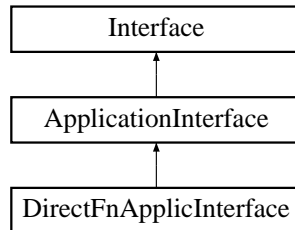
The documentation for this class was generated from the following files:

- DDACEDesignCompExp.H
- DDACEDesignCompExp.C

8.31 DirectFnApplicInterface Class Reference

Derived application interface class which spawns simulation codes and testers using direct procedure calls.

Inheritance diagram for DirectFnApplicInterface::



Public Member Functions

- [DirectFnApplicInterface](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_fns)
constructor
- [~DirectFnApplicInterface](#) ()
destructor
- void [derived_map](#) (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response, int fn_eval_id)
Called by [map\(\)](#) and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- void [derived_map_asynch](#) (const [ParamResponsePair](#) &pair)
Called by [map\(\)](#) and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- void [derived_synch](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version waits for at least one completion.
- void [derived_synch_nowait](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version is nonblocking and will return without any completions if none are immediately available.
- int [derived_synchronous_local_analysis](#) (const int &analysis_id)
Execute a particular analysis (identified by [analysis_id](#)) synchronously on the local processor. Used for the derived class specifics within [ApplicationInterface::serve_analyses_synch\(\)](#).

Protected Member Functions

- virtual int `derived_map_if` (const `String` &if_name)
execute the input filter portion of a direct evaluation invocation
- virtual int `derived_map_ac` (const `String` &ac_name)
execute an analysis code portion of a direct evaluation invocation
- virtual int `derived_map_of` (const `String` &of_name)
execute the output filter portion of a direct evaluation invocation
- void `set_local_data` ()
convenience function for local test simulators which sets variable attributes and zeros response data
- void `overlay_response` (`Response` &response)
convenience function for local test simulators which overlays response contributions from multiple analyses using `MPI_Reduce`

Protected Attributes

- `String` `iFilterName`
name of the direct function input filter
- `String` `oFilterName`
name of the direct function output filter
- `String` `pxcFile`
name of the ModelCenter simulation config file
- bool `gradFlag`
signals use of `fnGrads` in direct simulator functions
- bool `hessFlag`
signals use of `fnHessians` in direct simulator functions
- size_t `numFns`
number of functions in `fnVals`
- size_t `numVars`
total number of continuous and discrete variables
- size_t `numGradVars`
number of active continuous variables
- `RealVector` `xC`
continuous variable set used within direct simulator functions
- `IntVector` `xD`
discrete variable set used within direct simulator functions

- [RealVector fnVals](#)
response function values set within direct simulator functions
- [RealMatrix fnGrads](#)
response function gradients set within direct simulator functions
- [RealMatrixArray fnHessians](#)
response function Hessians set within direct simulator functions
- [Variables directFnVars](#)
class scope variables object
- [IntArray directFnASV](#)
class scope active set vector object
- [Response directFnResponse](#)
class scope response object

Private Member Functions

- `int cantilever` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
the cantilever optimization under uncertainty test function
- `int cyl_head` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
the cylinder head constrained optimization test function
- `int rosenbrock` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
the rosenbrock optimization and least squares test function
- `int text_book` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
the text_book constrained optimization test function
- `int text_book1` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
portion of `text_book()` evaluating the objective function and its derivatives
- `int text_book2` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
portion of `text_book()` evaluating constraint 1 and its derivatives
- `int text_book3` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
portion of `text_book()` evaluating constraint 2 and its derivatives
- `int text_book_ouu` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
the text_book_ouu optimization under uncertainty test function
- `int log_ratio` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
the log_ratio uncertainty quantification test function

- int `short_column` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
the short_column uncertainty quantification/optimization under uncertainty test function
- int `salinas` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
direct interface to the SALINAS structural dynamics simulation code
- int `mc_api_run` (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response)
Call ModelCenter via API, HKIM 4/3/03.

8.31.1 Detailed Description

Derived application interface class which spawns simulation codes and testers using direct procedure calls.

DerivedFnApplicInterface uses a few linkable simulation codes and several internal member functions to perform parameter to response mappings.

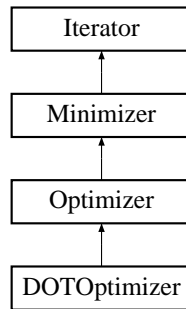
The documentation for this class was generated from the following files:

- `DirectFnApplicInterface.H`
- `DirectFnApplicInterface.C`

8.32 DOTOptimizer Class Reference

Wrapper class for the DOT optimization library.

Inheritance diagram for DOTOptimizer::



Public Member Functions

- [DOTOptimizer \(Model &model\)](#)
constructor
- [~DOTOptimizer \(\)](#)
destructor
- void [find_optimum \(\)](#)
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.

Private Member Functions

- void [allocate_workspace \(\)](#)
Allocates workspace for the optimizer.

Private Attributes

- int [dotInfo](#)
INFO from DOT manual.
- int [dotFDSinfo](#)
internal DOT parameter NGOTOZ
- int [dotMethod](#)
METHOD from DOT manual.

- `int printControl`
IPRINT from DOT manual (controls output verbosity).
- `int optimizationType`
MINMAX from DOT manual (minimize or maximize).
- `RealArray realCntlParmArray`
RPRM from DOT manual.
- `IntArray intCntlParmArray`
IPRM from DOT manual.
- `RealVector localConstraintValues`
array of nonlinear constraint values passed to DOT
- `int realWorkSpaceSize`
size of realWorkSpace
- `int intWorkSpaceSize`
size of intWorkSpace
- `RealArray realWorkSpace`
real work space for DOT
- `IntArray intWorkSpace`
int work space for DOT
- `SizeList constraintMappingIndices`
a list of indices for referencing the corresponding [Response](#) constraints used in computing the DOT constraints.
- `RealList constraintMappingMultipliers`
a list of multipliers for mapping the [Response](#) constraints to the DOT constraints.
- `RealList constraintMappingOffsets`
a list of offsets for mapping the [Response](#) constraints to the DOT constraints.

8.32.1 Detailed Description

Wrapper class for the DOT optimization library.

The `DOTOptimizer` class provides a wrapper for DOT, a commercial Fortran 77 optimization library from Vanderplaats Research and Development. It uses a reverse communication mode, which avoids the static member function issues that arise with function pointer designs (see [NPSOLOptimizer](#) and [SNLLOptimizer](#)).

The user input mappings are as follows: `max_iterations` is mapped into DOT's `ITMAX` parameter within its `IPRM` array, `max_function_evaluations` is implemented directly in the `find_optimum()` loop since there is no DOT parameter equivalent, `convergence_tolerance` is mapped into DOT's

DELOBJ parameter (the relative convergence tolerance) within its RPRM array, output verbosity is mapped into DOT's IPRINT parameter within its function call parameter list (verbose: IPRINT = 7; quiet: IPRINT = 3), and `optimization_type` is mapped into DOT's MINMAX parameter within its function call parameter list. Refer to [Vanderplaats Research and Development, 1995] for information on IPRM, RPRM, and the DOT function call parameter list.

8.32.2 Member Data Documentation

8.32.2.1 `int dotInfo` [private]

INFO from DOT manual.

Information requested by DOT: 0=optimization complete, 1=get values, 2=get gradients

8.32.2.2 `int dotFDSinfo` [private]

internal DOT parameter NGOTOZ

the DOT parameter list has been modified to pass NGOTOZ, which signals whether DOT is finite-differencing (nonzero value) or performing the line search (zero value).

8.32.2.3 `int dotMethod` [private]

METHOD from DOT manual.

For nonlinear constraints: 0/1 = dot_mmfd, 2 = dot_slp, 3 = dot_sqp. For unconstrained: 0/1 = dot_bfgs, 2 = dot_frcg.

8.32.2.4 `int printControl` [private]

IPRINT from DOT manual (controls output verbosity).

Values range from 0 (least output) to 7 (most output).

8.32.2.5 `int optimizationType` [private]

MINMAX from DOT manual (minimize or maximize).

Values of 0 or -1 (minimize) or 1 (maximize).

8.32.2.6 `RealArray realCntlParmArray` [private]

RPRM from DOT manual.

[Array](#) of real control parameters.

8.32.2.7 `IntArray intCntlParmArray` [private]

IPRM from DOT manual.

Array of integer control parameters.

8.32.2.8 RealVector localConstraintValues [private]

array of nonlinear constraint values passed to DOT

This array must be of nonzero length (sized with localConstraintArraySize) and must contain only one-sided inequality constraints which are ≤ 0 (which requires a transformation from 2-sided inequalities and equalities).

8.32.2.9 SizeList constraintMappingIndices [private]

a list of indices for referencing the corresponding Response constraints used in computing the DOT constraints.

The length of the list corresponds to the number of DOT constraints, and each entry in the list points to the corresponding DAKOTA constraint.

8.32.2.10 RealList constraintMappingMultipliers [private]

a list of multipliers for mapping the Response constraints to the DOT constraints.

The length of the list corresponds to the number of DOT constraints, and each entry in the list contains a multiplier for the DAKOTA constraint identified with constraintMappingIndices. These multipliers are currently +1 or -1.

8.32.2.11 RealList constraintMappingOffsets [private]

a list of offsets for mapping the Response constraints to the DOT constraints.

The length of the list corresponds to the number of DOT constraints, and each entry in the list contains an offset for the DAKOTA constraint identified with constraintMappingIndices. These offsets involve inequality bounds or equality targets, since DOT assumes constraint allowables = 0.

The documentation for this class was generated from the following files:

- DOTOptimizer.H
- DOTOptimizer.C

8.33 ErrorTable Struct Reference

Data structure to hold errors.

Public Attributes

- [CtelRegexp::RStatus rc](#)
Enumerated type to hold status codes.
- `const char * msg`
Holds character string error message.

8.33.1 Detailed Description

Data structure to hold errors.

This module implements a C++ wrapper for Regular Expressions based on the public domain engine for regular expressions released by: Copyright (c) 1986 by University of Toronto. Written by Henry Spencer. Not derived from licensed software.

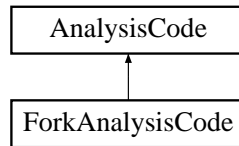
The documentation for this struct was generated from the following file:

- CtelRegExp.C

8.34 ForkAnalysisCode Class Reference

Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using forks.

Inheritance diagram for ForkAnalysisCode::



Public Member Functions

- [ForkAnalysisCode](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~ForkAnalysisCode](#) ()
destructor
- pid_t [fork_program](#) (const bool block_flag)
spawn a child process using fork()/vfork()/execvp() and wait for completion using waitpid() if block_flag is true
- void [check_status](#) (const int status)
check the exit status of a forked process and abort if an error code was returned
- void [argument_list](#) (const int index, const [String](#) &arg)
set argList[index] to arg
- void [tag_argument_list](#) (const int index, const int tag)
append an additional tag to argList[index] (beyond that already present in the modified file names) for managing concurrent analyses within a function evaluation

Private Attributes

- const char * [argList](#) [4]
*an array of strings for use with execvp(const char *, char * const *) (an argList entry can be passed as the first argument, and the entire argList can be cast as the second argument)*

8.34.1 Detailed Description

Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using forks.

[ForkAnalysisCode](#) creates a copy of the parent DAKOTA process using `fork()/vfork()` and then replaces the copy with a simulation process using `execvp()`. The parent process can then use `waitpid()` to wait on completion of the simulation process.

8.34.2 Member Function Documentation

8.34.2.1 `void check_status (const int status)`

check the exit status of a forked process and abort if an error code was returned

Check to see if the 3-piece interface terminated abnormally (`WIFEXITED(status)==0`) or if either `execvp` or the application returned a status code of -1 (`WIFEXITED(status)!=0 && (signed char)WEXITSTATUS(status)==-1`). If one of these conditions is detected, output a failure message and abort. Note: the application code should not return a status code of -1 unless an immediate abort of dakota is wanted. If for instance, failure capturing is to be used, the application code should write the word "FAIL" to the appropriate results file and return a status code of 0 through `exit()`.

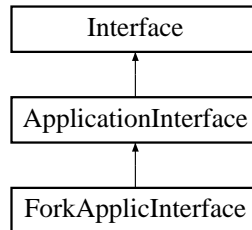
The documentation for this class was generated from the following files:

- `ForkAnalysisCode.H`
- `ForkAnalysisCode.C`

8.35 ForkApplicInterface Class Reference

Derived application interface class which spawns simulation codes using forks.

Inheritance diagram for ForkApplicInterface::



Public Member Functions

- [ForkApplicInterface](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_fns)
constructor
- [~ForkApplicInterface](#) ()
destructor
- void [derived_map](#) (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response, int fn_eval_id)
Called by [map\(\)](#) and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- void [derived_map_async](#) (const [ParamResponsePair](#) &pair)
Called by [map\(\)](#) and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- void [derived_synch](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version waits for at least one completion.
- void [derived_synch_nowait](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version is nonblocking and will return without any completions if none are immediately available.
- int [derived_synchronous_local_analysis](#) (const int &analysis_id)
Execute a particular analysis (identified by analysis_id) synchronously on the local processor. Used for the derived class specifics within [ApplicationInterface::serve_analyses_synch\(\)](#).

Private Member Functions

- void [derived_synch_kernel](#) (PRPList &prp_list, const pid_t pid)
Convenience function for common code between [derived_synch\(\)](#) & [derived_synch_nowait\(\)](#).
- pid_t [fork_application](#) (const bool block_flag)
perform the complete function evaluation by managing the input filter, analysis programs, and output filter
- void [asynchronous_local_analyses](#) (const int &start, const int &end, const int &step)
execute analyses asynchronously on the local processor
- void [synchronous_local_analyses](#) (const int &start, const int &end, const int &step)
execute analyses synchronously on the local processor
- void [serve_analyses_asynch](#) ()
serve the analysis scheduler and execute analysis assignments asynchronously

Private Attributes

- [ForkAnalysisCode](#) [forkSimulator](#)
[ForkAnalysisCode](#) provides convenience functions for forking individual programs and checking fork exit status.
- [List< pid_t >](#) [processIdList](#)
list of process id's for asynchronous evaluations; correspondence to [evalIdList](#) used for mapping captured fork process id's to function evaluation id's
- [IntList](#) [evalIdList](#)
list of function evaluation id's for asynchronous evaluations; correspondence to [processIdList](#) used for mapping captured fork process id's to function evaluation id's

8.35.1 Detailed Description

Derived application interface class which spawns simulation codes using forks.

[ForkApplicInterface](#) uses a [ForkAnalysisCode](#) object for performing simulation invocations.

8.35.2 Member Function Documentation

8.35.2.1 pid_t [fork_application](#) (const bool *block_flag*) [private]

perform the complete function evaluation by managing the input filter, analysis programs, and output filter
Manage the input filter, 1 or more analysis programs, and the output filter in blocking or nonblocking mode as governed by *block_flag*. In the case of a single analysis and no filters, a single fork is performed, while in other cases, an initial fork is reforked multiple times. Called from [derived_map\(\)](#) with

block_flag == BLOCK and from [derived_map_asynch\(\)](#) with block_flag == FALL_THROUGH. Uses [ForkAnalysisCode::fork_program\(\)](#) to spawn individual program components within the function evaluation.

8.35.2.2 void asynchronous_local_analyses (const int & start, const int & end, const int & step) [private]

execute analyses asynchronously on the local processor

Schedule analyses asynchronously on the local processor using a self-scheduling approach (start to end in step increments). Concurrency is limited by `asynchLocalAnalysisConcurrency`. Modeled after [ApplicationInterface::asynchronous_local_evaluations\(\)](#). NOTE: This function should be elevated to [ApplicationInterface](#) if and when another derived interface class supports asynchronous local analyses.

8.35.2.3 void synchronous_local_analyses (const int & start, const int & end, const int & step) [private]

execute analyses synchronously on the local processor

Execute analyses synchronously in succession on the local processor (start to end in step increments). Modeled after [ApplicationInterface::synchronous_local_evaluations\(\)](#).

8.35.2.4 void serve_analyses_asynch () [private]

serve the analysis scheduler and execute analysis assignments asynchronously

This code runs multiple asynch analyses on each server. It is modeled after [ApplicationInterface::serve_evaluations_asynch\(\)](#). NOTE: This fn should be elevated to [ApplicationInterface](#) if and when another derived interface class supports hybrid analysis parallelism.

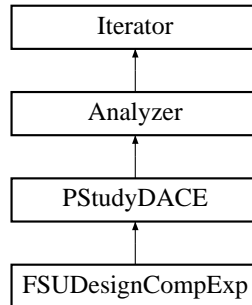
The documentation for this class was generated from the following files:

- ForkApplicInterface.H
- ForkApplicInterface.C

8.36 FSUDesignCompExp Class Reference

Wrapper class for the FSUDace QMC/CVT library.

Inheritance diagram for FSUDesignCompExp::



Public Member Functions

- [FSUDesignCompExp \(Model &model\)](#)
primary constructor for building a standard DACE iterator
- [~FSUDesignCompExp \(\)](#)
destructor
- void [extract_trends \(\)](#)
Redefines the run_iterator virtual function for the PStudy/DACE branch.
- void [get_parameter_sets \(bool vbd_change_seq_flag\)](#)
*Returns one block of samples (ndim * num_samples).*
- void [sampling_reset \(int min_samples, bool all_data_flag, bool stats_flag\)](#)
reset sampling iterator
- const [String & sampling_scheme \(\)](#) const
return sampling name

Private Member Functions

- void [enforce_input_rules \(\)](#)
enforce sanity checks/modifications for the user input specification

Private Attributes

- int `numSamples`
number of samples to be evaluated
- bool `allDataFlag`
flag which triggers the update of `allVars/allResponses` for use by `Iterator::all_variables()` and `Iterator::all_responses()`
- size_t `numDACERuns`
counter for number of executions of `run_iterator()` for this object
- bool `latinizeFlag`
flag which specifies latinization of QMC or CVT sample sets
- bool `volQualityFlag`
flag which specifies evaluating the volumetric quality measures
- bool `varBasedDecompFlag`
flag which specifies calculating variance based decomposition sensitivity analysis metrics
- `IntVector` `sequenceStart`
Integer vector defining a starting index into the sequence for random variable sampled. Default is 0 0 0 (e.g. for three random variables).
- `IntVector` `sequenceLeap`
Integer vector defining the leap number for each sequence being generated. Default is 1 1 1 (e.g. for three random vars.).
- `IntVector` `primeBase`
Integer vector defining the prime base for each sequence being generated. Default is 2 3 5 (e.g., for three random vars.).
- int `originalSeed`
the user seed specification for the random number generator (allows repeatable results)
- int `randomSeed`
current seed for the random number generator
- bool `varyPattern`
flag for continuing the random number or QMC sequence from a previous `run_iterator()` execution (e.g., for surrogate-based optimization) so that multiple executions are repeatable but not identical.
- int `numCVTTrials`
specifies the number of sample points taken at internal CVT iteration
- int `trialType`
Trial type in CVT. Specifies where the points are placed for consideration relative to the centroids. Choices are grid (2), halton (1), uniform (0), or random (-1). Default is random.

8.36.1 Detailed Description

Wrapper class for the FSUDace QMC/CVT library.

The [FSUDesignCompExp](#) class provides a wrapper for FSUDace, a C++ design of experiments library from Florida State University. This class uses quasi Monte Carlo (QMC) and Centroidal Voronoi Tessellation (CVT) methods to uniformly sample the parameter space spanned by the active bounds of the current [Model](#). It returns all generated samples and their corresponding responses as well as the best sample found.

8.36.2 Constructor & Destructor Documentation

8.36.2.1 [FSUDesignCompExp](#) ([Model](#) & *model*)

primary constructor for building a standard DACE iterator

This constructor is called for a standard iterator built with data from probDescDB.

8.36.3 Member Function Documentation

8.36.3.1 `void enforce_input_rules () [private]`

enforce sanity checks/modifications for the user input specification

Users may input a variety of quantities, but this function must enforce any restrictions imposed by the sampling algorithms.

The documentation for this class was generated from the following files:

- [FSUDesignCompExp.H](#)
- [FSUDesignCompExp.C](#)

8.37 FunctionCompare Class Template Reference

Public Member Functions

- [FunctionCompare](#) (bool(*func)(const T &, void *), void *v)
Constructor that defines the pointer to function and search value.
- bool [operator\(\)](#) (T t) const
The operator() must be defined. Calls the function testFunction.

Private Attributes

- bool(* [testFunction](#))(const T &, void *)
Pointer to test function.
- void * [search_val](#)
Holds the value to search for.

8.37.1 Detailed Description

template<class T> class Dakota::FunctionCompare< T >

Internal functor to mimic the RW find and index functions using the STL find_if() method. The class holds a pointer to the test function and the search value.

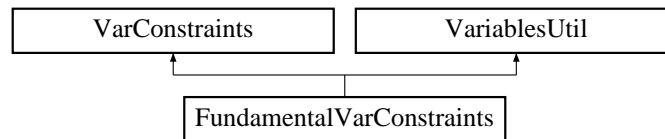
The documentation for this class was generated from the following file:

- DakotaList.H

8.38 FundamentalVarConstraints Class Reference

Derived class within the [VarConstraints](#) hierarchy which employs the default data view (no variable or domain type array merging).

Inheritance diagram for FundamentalVarConstraints::



Public Member Functions

- [FundamentalVarConstraints](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~FundamentalVarConstraints](#) ()
destructor
- const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds
- void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds
- const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds
- void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds
- const [IntVector](#) & [discrete_lower_bounds](#) () const
return the active discrete variable lower bounds
- void [discrete_lower_bounds](#) (const [IntVector](#) &d_l_bnds)
set the active discrete variable lower bounds
- const [IntVector](#) & [discrete_upper_bounds](#) () const
return the active discrete variable upper bounds
- void [discrete_upper_bounds](#) (const [IntVector](#) &d_u_bnds)
set the active discrete variable upper bounds
- const [RealVector](#) & [inactive_continuous_lower_bounds](#) () const

return the inactive continuous lower bounds

- void `inactive_continuous_lower_bounds` (const `RealVector` &i_c_l_bnds)
set the inactive continuous lower bounds
- const `RealVector` & `inactive_continuous_upper_bounds` () const
return the inactive continuous upper bounds
- void `inactive_continuous_upper_bounds` (const `RealVector` &i_c_u_bnds)
set the inactive continuous upper bounds
- const `IntVector` & `inactive_discrete_lower_bounds` () const
return the inactive discrete lower bounds
- void `inactive_discrete_lower_bounds` (const `IntVector` &i_d_l_bnds)
set the inactive discrete lower bounds
- const `IntVector` & `inactive_discrete_upper_bounds` () const
return the inactive discrete upper bounds
- void `inactive_discrete_upper_bounds` (const `IntVector` &i_d_u_bnds)
set the inactive discrete upper bounds
- `RealVector` `all_continuous_lower_bounds` () const
returns a single array with all continuous lower bounds
- `RealVector` `all_continuous_upper_bounds` () const
returns a single array with all continuous upper bounds
- `IntVector` `all_discrete_lower_bounds` () const
returns a single array with all discrete lower bounds
- `IntVector` `all_discrete_upper_bounds` () const
returns a single array with all discrete upper bounds
- void `write` (ostream &s) const
write a variable constraints object to an ostream
- void `read` (istream &s)
read a variable constraints object from an istream

Private Attributes

- bool `nonDFlag`
this flag is set if uncertain variables are active (the default is design variables are active; see constructor for logic)
- `RealVector` `continuousDesignLowerBnds`
the continuous design lower bounds array

- [RealVector continuousDesignUpperBnds](#)
the continuous design upper bounds array
- [IntVector discreteDesignLowerBnds](#)
the discrete design lower bounds array
- [IntVector discreteDesignUpperBnds](#)
the discrete design upper bounds array
- [RealVector uncertainDistLowerBnds](#)
the uncertain distribution lower bounds array
- [RealVector uncertainDistUpperBnds](#)
the uncertain distribution upper bounds array
- [RealVector continuousStateLowerBnds](#)
the continuous state lower bounds array
- [RealVector continuousStateUpperBnds](#)
the continuous state upper bounds array
- [IntVector discreteStateLowerBnds](#)
the discrete state lower bounds array
- [IntVector discreteStateUpperBnds](#)
the discrete state upper bounds array

8.38.1 Detailed Description

Derived class within the [VarConstraints](#) hierarchy which employs the default data view (no variable or domain type array merging).

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [FundamentalVarConstraints](#) derived class separates the design, uncertain, and state variable types as well as the continuous and discrete domain types. The result is separate lower and upper bounds arrays for continuous design, discrete design, uncertain, continuous state, and discrete state variables. This is the default approach, so all iterators and strategies not specifically utilizing the All, Merged, or AllMerged views use this approach (see `Variables::get_variables(problem_db)` for variables type selection; variables type is passed to the [VarConstraints](#) constructor in [Model](#)).

8.38.2 Constructor & Destructor Documentation

8.38.2.1 FundamentalVarConstraints (const **ProblemDescDB** & *problem_db*)

constructor

Extract fundamental lower and upper bounds (**VariablesUtil** is not used).

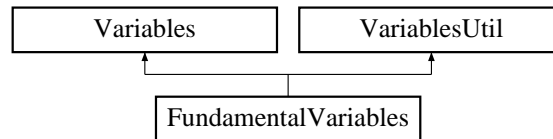
The documentation for this class was generated from the following files:

- FundamentalVarConstraints.H
- FundamentalVarConstraints.C

8.39 FundamentalVariables Class Reference

Derived class within the [Variables](#) hierarchy which employs the default data view (no variable or domain type array merging).

Inheritance diagram for FundamentalVariables::



Public Member Functions

- [FundamentalVariables](#) ()
default constructor
- [FundamentalVariables](#) (const [ProblemDescDB](#) &problem_db)
standard constructor
- [~FundamentalVariables](#) ()
destructor
- size_t [tv](#) () const
Returns total number of vars.
- size_t [cv](#) () const
Returns number of active continuous vars.
- size_t [dv](#) () const
Returns number of active discrete vars.
- const [RealVector](#) & [continuous_variables](#) () const
return the active continuous variables
- void [continuous_variables](#) (const [RealVector](#) &c_vars)
set the active continuous variables
- const [IntVector](#) & [discrete_variables](#) () const
return the active discrete variables
- void [discrete_variables](#) (const [IntVector](#) &d_vars)
set the active discrete variables
- const [StringArray](#) & [continuous_variable_labels](#) () const

return the active continuous variable labels

- void `continuous_variable_labels` (const `StringArray` &c_v_labels)
set the active continuous variable labels
- const `StringArray` & `discrete_variable_labels` () const
return the active discrete variable labels
- void `discrete_variable_labels` (const `StringArray` &d_v_labels)
set the active discrete variable labels
- const `RealVector` & `inactive_continuous_variables` () const
return the inactive continuous variables
- void `inactive_continuous_variables` (const `RealVector` &i_c_vars)
set the inactive continuous variables
- const `IntVector` & `inactive_discrete_variables` () const
return the inactive discrete variables
- void `inactive_discrete_variables` (const `IntVector` &i_d_vars)
set the inactive discrete variables
- const `StringArray` & `inactive_continuous_variable_labels` () const
return the inactive continuous variable labels
- void `inactive_continuous_variable_labels` (const `StringArray` &i_c_v_labels)
set the inactive continuous variable labels
- const `StringArray` & `inactive_discrete_variable_labels` () const
return the inactive discrete variable labels
- void `inactive_discrete_variable_labels` (const `StringArray` &i_d_v_labels)
set the inactive discrete variable labels
- size_t `acv` () const
returns total number of continuous vars
- size_t `adv` () const
returns total number of discrete vars
- `RealVector` `all_continuous_variables` () const
returns a single array with all continuous variables
- `IntVector` `all_discrete_variables` () const
returns a single array with all discrete variables
- `StringArray` `all_continuous_variable_labels` () const
returns a single array with all continuous variable labels

- [StringArray all_discrete_variable_labels](#) () const
returns a single array with all discrete variable labels
- [StringArray all_variable_labels](#) () const
returns a single array with all variable labels
- void [read](#) (istream &s)
read a variables object from an istream
- void [write](#) (ostream &s) const
write a variables object to an ostream
- void [write_aprepro](#) (ostream &s) const
write a variables object to an ostream in aprepro format
- void [read_annotated](#) (istream &s)
read a variables object in annotated format from an istream
- void [write_annotated](#) (ostream &s) const
write a variables object in annotated format to an ostream
- void [write_tabular](#) (ostream &s) const
write a variables object in tabular format to an ostream
- void [read](#) (BiStream &s)
read a variables object from the binary restart stream
- void [write](#) (BoStream &s) const
write a variables object to the binary restart stream
- void [read](#) (MPIUnpackBuffer &s)
read a variables object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a variables object to a packed MPI buffer

Private Member Functions

- void [copy_rep](#) (const Variables *vars_rep)
Used by [copy\(\)](#) to copy the contents of a letter class.

Private Attributes

- bool [nonDFlag](#)
this flag is set if uncertain variables are active (the default is design variables are active; see constructor for logic)

- [RealVector continuousDesignVars](#)
the continuous design variables array
- [IntVector discreteDesignVars](#)
the discrete design variables array
- [RealVector uncertainVars](#)
the uncertain variables array
- [RealVector continuousStateVars](#)
the continuous state variables array
- [IntVector discreteStateVars](#)
the discrete state variables array
- [StringArray continuousDesignLabels](#)
the continuous design variables label array
- [StringArray discreteDesignLabels](#)
the discrete design variables label array
- [StringArray uncertainLabels](#)
the uncertain variables label array
- [StringArray continuousStateLabels](#)
the continuous state variables label array
- [StringArray discreteStateLabels](#)
the discrete state variables label array

Friends

- `bool operator==(const FundamentalVariables &vars1, const FundamentalVariables &vars2)`
equality operator

8.39.1 Detailed Description

Derived class within the [Variables](#) hierarchy which employs the default data view (no variable or domain type array merging).

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [FundamentalVariables](#) derived class separates the design, uncertain, and state variable types as well as the continuous and discrete domain types. The result is separate arrays for continuous design, discrete design, uncertain, continuous state, and discrete state variables. This is the default approach, so all iterators and strategies not specifically utilizing the All, Merged, or AllMerged views use this approach (see `Variables::get_variables(problem_db)`).

8.39.2 Constructor & Destructor Documentation

8.39.2.1 `FundamentalVariables` (const `ProblemDescDB` & `problem_db`)

standard constructor

Extract fundamental variable types and labels (`VariablesUtil` is not used).

8.39.3 Friends And Related Function Documentation

8.39.3.1 `bool operator==(const FundamentalVariables & vars1, const FundamentalVariables & vars2)` [`friend`]

equality operator

Checks each fundamental array using `operator==` from `data_types.C`. Labels are ignored.

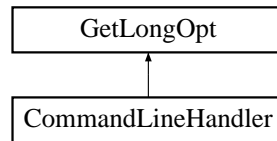
The documentation for this class was generated from the following files:

- `FundamentalVariables.H`
- `FundamentalVariables.C`

8.40 GetLongOpt Class Reference

[GetLongOpt](#) is a general command line utility from S. Manoharan (Advanced Computer Research Institute, Lyon, France).

Inheritance diagram for GetLongOpt::



Public Types

- enum [OptType](#) { [Valueless](#), [OptionalValue](#), [MandatoryValue](#) }
enum for different types of values associated with command line options.

Public Member Functions

- [GetLongOpt](#) (const char optmark= '-')
Constructor.
- [~GetLongOpt](#) ()
Destructor.
- int [parse](#) (int argc, char *const *argv)
parse the command line args (argc, argv).
- int [parse](#) (char *const str, char *const p)
parse a string of options (typically given from the environment).
- int [enroll](#) (const char *const opt, const [OptType](#) t, const char *const desc, const char *const val)
Add an option to the list of valid command options.
- const char * [retrieve](#) (const char *const opt) const
Retrieve value of option.
- void [usage](#) (ostream &outfile=cout) const
Print usage information to outfile.
- void [usage](#) (const char *str)
Change header of usage output to str.

Private Member Functions

- char * [basename](#) (char *const p) const
extract the base name from a string as delimited by '/'
- int [setcell](#) (Cell *c, char *valtoken, char *nexttoken, const char *p)
internal convenience function for setting Cell::value

Private Attributes

- Cell * [table](#)
option table
- const char * [ustring](#)
usage message
- char * [pname](#)
program basename
- char [optmarker](#)
option marker
- int [enroll_done](#)
finished enrolling
- Cell * [last](#)
last entry in option table

8.40.1 Detailed Description

[GetLongOpt](#) is a general command line utility from S. Manoharan (Advanced Computer Research Institute, Lyon, France).

[GetLongOpt](#) manages the definition and parsing of "long options." Command line options can be abbreviated as long as there is no ambiguity. If an option requires a value, the value should be separated from the option either by whitespace or an "=".

8.40.2 Constructor & Destructor Documentation

8.40.2.1 [GetLongOpt](#) (const char *optmark* = ' - ')

Constructor.

Constructor for [GetLongOpt](#) takes an optional argument: the option marker. If unspecified, this defaults to '-', the standard (?) Unix option marker.

8.40.3 Member Function Documentation

8.40.3.1 `int parse (int argc, char *const * argv)`

parse the command line args (argc, argv).

A return value < 1 represents a parse error. Appropriate error messages are printed when errors are seen. parse returns the the optind (see getopt(3)) if parsing is successful.

8.40.3.2 `int parse (char *const str, char *const p)`

parse a string of options (typically given from the environment).

A return value < 1 represents a parse error. Appropriate error messages are printed when errors are seen. parse takes two strings: the first one is the string to be parsed and the second one is a string to be prefixed to the parse errors.

8.40.3.3 `int enroll (const char *const opt, const OptType t, const char *const desc, const char *const val)`

Add an option to the list of valid command options.

enroll adds option specifications to its internal database. The first argument is the option sting. The second is an enum saying if the option is a flag (Valueless), if it requires a mandatory value (MandatoryValue) or if it takes an optional value (OptionalValue). The third argument is a string giving a brief description of the option. This description will be used by [GetLongOpt::usage](#). [GetLongOpt](#), for usage-printing, uses {\$val} to represent values needed by the options. {<\$val>} is a mandatory value and {[\$val]} is an optional value. The final argument to enroll is the default string to be returned if the option is not specified. For flags (options with Valueless), use "" (empty string, or in fact any arbitrary string) for specifying TRUE and 0 (null pointer) to specify FALSE.

8.40.3.4 `const char * retrieve (const char *const opt) const`

Retrieve value of option.

The values of the options that are enrolled in the database can be retrieved using retrieve. This returns a string and this string should be converted to whatever type you want. See atoi, atof, atol, etc. If a "parse" is not done before retrieving all you will get are the default values you gave while enrolling! Ambiguities while retrieving (may happen when options are abbreviated) are resolved by taking the matching option that was enrolled last. For example, `-{v}` will expand to `{-verify}`. If you try to retrieve something you didn't enroll, you will get a warning message.

8.40.3.5 `void usage (const char * str) [inline]`

Change header of usage output to str.

[GetLongOpt::usage](#) is overloaded. If passed a string "str", it sets the internal usage string to "str". Otherwise it simply prints the command usage.

The documentation for this class was generated from the following files:

- CommandLineHandler.H
- CommandLineHandler.C

8.41 Graphics Class Reference

The [Graphics](#) class provides a single interface to 2D (motif) and 3D (PLPLOT) graphics as well as tabular cataloguing of data for post-processing with Matlab, Tecplot, etc.

Public Member Functions

- [Graphics](#) ()
constructor
- [~Graphics](#) ()
destructor
- void [create_plots_2d](#) (const [Variables](#) &vars, const [Response](#) &response)
creates the 2d graphics window and initializes the plots
- void [create_tabular_datastream](#) (const [Variables](#) &vars, const [Response](#) &response, const [String](#) &tabular_data_file)
opens the tabular data file stream and prints the headings
- void [add_datapoint](#) (const [Variables](#) &vars, const [Response](#) &response)
adds data to each window in the 2d graphics and adds a row to the tabular data file based on the results of a model evaluation
- void [add_datapoint](#) (int i, double x, double y)
adds data to a single window in the 2d graphics
- void [new_dataset](#) (int i)
creates a separate line graphic for subsequent data points for a single window in the 2d graphics
- void [show_data_3d](#) (const [RealVector](#) &X, const [RealVector](#) &Y, const [RealMatrix](#) &F)
generate a new 3d plot for F(X,Y)
- void [close](#) ()
close graphics windows and tabular datastream
- void [set_x_labels2d](#) (const char *x_label)
set x label for each plot equal to x_label
- void [set_y_labels2d](#) (const char *y_label)
set y label for each plot equal to y_label
- void [set_x_label2d](#) (int i, const char *x_label)
set x label for ith plot equal to x_label
- void [set_y_label2d](#) (int i, const char *y_label)

set y label for ith plot equal to y_label

- void `graphics_counter` (int cntr)
set graphicsCntr equal to cntr
- void `tabular_counter_label` (const `String` &label)
set tabularCntrLabel equal to label

Private Attributes

- Graphics2D * `graphics2D`
pointer to the 2D graphics object
- bool `win2dOn`
flag to indicate if 2D graphics window is active
- bool `win3dOn`
flag to indicate if 3D graphics window is active
- bool `tabularDataFlag`
flag to indicate if tabular data stream is active
- int `graphicsCntr`
used for x axis values in 2D graphics and for 1st column in tabular data
- `String` `tabularCntrLabel`
label for counter used in first line comment w/i the tabular data file
- ofstream `tabularDataFStream`
file stream for tabulation of graphics data within compute_response

8.41.1 Detailed Description

The `Graphics` class provides a single interface to 2D (motif) and 3D (PLPLOT) graphics as well as tabular cataloging of data for post-processing with Matlab, Tecplot, etc.

There is only one `Graphics` object (`dakotaGraphics`) and it is global (for convenient access from strategies, models, and approximations).

8.41.2 Member Function Documentation

8.41.2.1 void create_plots_2d (const Variables & vars, const Response & response)

creates the 2d graphics window and initializes the plots

Sets up a single event loop for duration of the dakotaGraphics object, continuously adding data to a single window. There is no reset. To start over with a new data set, you need a new object (delete old and instantiate new).

8.41.2.2 void create_tabular_datastream (const Variables & vars, const Response & response, const String & tabular_data_file)

opens the tabular data file stream and prints the headings

Opens the tabular data file stream and prints headings, one for each continuous and discrete variable and one for each response function, using the variable and response function labels. This tabular data is used for post-processing of DAKOTA results in Matlab, Tecplot, etc.

8.41.2.3 void add_datapoint (const Variables & vars, const Response & response)

adds data to each window in the 2d graphics and adds a row to the tabular data file based on the results of a model evaluation

Adds data to each 2d plot and each tabular data column (one for each active variable and for each response function). graphicsCntr is used for the x axis in the graphics and the first column in the tabular data.

8.41.2.4 void add_datapoint (int i, double x, double y)

adds data to a single window in the 2d graphics

Adds data to a single 2d plot. Allows complete flexibility in defining other kinds of x-y plotting in the 2D graphics.

8.41.2.5 void new_dataset (int i)

creates a separate line graphic for subsequent data points for a single window in the 2d graphics

Used for displaying multiple data sets within the same plot.

8.41.2.6 void show_data_3d (const RealVector & X, const RealVector & Y, const RealMatrix & F)

generate a new 3d plot for F(X,Y)

3D plotting clears data set and builds from scratch each time show_data3d is called. This still involves an event loop waiting for a mouse click (right button) to continue. X = 1-D x grid values only and Y = 1-D Y grid values only [X and Y are _not_ (X,Y) pairs]. F = 2-d grid of values for a single function for all (X,Y) combinations.

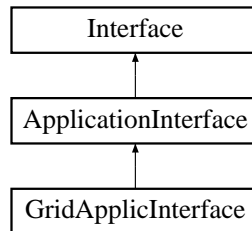
The documentation for this class was generated from the following files:

- DakotaGraphics.H
- DakotaGraphics.C

8.42 GridApplicInterface Class Reference

Derived application interface class which spawns simulation codes using grid services such as Condor or Globus.

Inheritance diagram for GridApplicInterface::



Public Member Functions

- [GridApplicInterface](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_fns)
constructor
- [~GridApplicInterface](#) ()
destructor
- void [derived_map](#) (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response, int fn_eval_id)
Called by [map\(\)](#) and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- void [derived_map_asynch](#) (const [ParamResponsePair](#) &pair)
Called by [map\(\)](#) and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- void [derived_synch](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version waits for at least one completion.
- void [derived_synch_nowait](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version is nonblocking and will return without any completions if none are immediately available.
- int [derived_synchronous_local_analysis](#) (const int &analysis_id)
Execute a particular analysis (identified by analysis_id) synchronously on the local processor. Used for the derived class specifics within [ApplicationInterface::serve_analyses_synch\(\)](#).

Private Member Functions

- XMLObject [getXML](#) (const [Variables](#) &vars)
convert [Variables](#) -> XMLObject
- Response [getResponse](#) (const XMLObject &xml)
convert XMLObject -> [Variables](#)

Private Attributes

- [StringArray](#) [hostNames](#)
array of host names to execute remote jobs
- [IntArray](#) [procsPerHost](#)
number of processors available on each of the remote hosts
- MessageHandler * [ideaMessageHandler](#)
data required by the IDEA framework

8.42.1 Detailed Description

Derived application interface class which spawns simulation codes using grid services such as Condor or Globus.

This class is currently a placeholder.

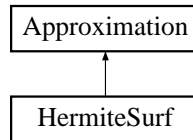
The documentation for this class was generated from the following files:

- GridApplicInterface.H
- GridApplicInterface.C

8.43 HermiteSurf Class Reference

Derived approximation class for Hermite polynomials (global approximation).

Inheritance diagram for HermiteSurf::



Public Member Functions

- [HermiteSurf](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_acv)
constructor
- [~HermiteSurf](#) ()
destructor

Protected Member Functions

- int [required_samples](#) ()
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- const [RealVector](#) & [approximation_coefficients](#) ()
return the coefficient array computed by [find_coefficients\(\)](#)
- void [find_coefficients](#) ()
find the Polynomial Chaos coefficients for the response surface
- Real [get_value](#) (const [RealVector](#) &x)
retrieve the function value for a given parameter set x

Private Member Functions

- void [get_num_chaos](#) ()
calculate number of Chaos according to the highest order of Chaos
- [RealVector](#) [get_chaos](#) (const [RealVector](#) &x, int order)
calculate the Polynomial Chaos from variables

Private Attributes

- [RealVector chaosCoeffs](#)
numChaos entries
- [RealVectorArray chaosSamples](#)
*numChaos*numCurrentPoints entries*
- int [numChaos](#)
Number of terms in Polynomial Chaos Expansion.
- int [highestOrder](#)
Highest order of Hermite Polynomials in Expansion.

8.43.1 Detailed Description

Derived approximation class for Hermite polynomials (global approximation).

The [HermiteSurf](#) class provides a global approximation based on Hermite polynomials. It is used primarily for polynomial chaos expansions (for stochastic finite element approaches to uncertainty quantification).

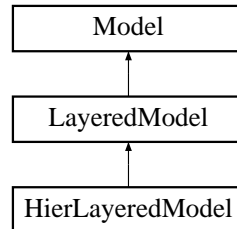
The documentation for this class was generated from the following files:

- HermiteSurf.H
- HermiteSurf.C

8.44 HierLayeredModel Class Reference

Derived model class within the layered model branch for managing hierarchical surrogates (models of varying fidelity).

Inheritance diagram for HierLayeredModel::



Public Member Functions

- [HierLayeredModel](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~HierLayeredModel](#) ()
destructor

Protected Member Functions

- void [derived_compute_response](#) (const [IntArray](#) &asv)
portion of [compute_response\(\)](#) specific to [HierLayeredModel](#)
- void [derived_async_compute_response](#) (const [IntArray](#) &asv)
portion of [async_compute_response\(\)](#) specific to [HierLayeredModel](#)
- const [ResponseArray](#) & [derived_synchronize](#) ()
portion of [synchronize\(\)](#) specific to [HierLayeredModel](#)
- const [ResponseList](#) & [derived_synchronize_nowait](#) ()
portion of [synchronize_nowait\(\)](#) specific to [HierLayeredModel](#)
- const [IntList](#) & [synchronize_nowait_completions](#) ()
return completion id's matching response list from [derived_synchronize_nowait\(\)](#)
- [Model](#) [subordinate_model](#) ()
return [highFidelityModel](#)
- [Interface](#) & [interface](#) ()
return [lowFidelityInterface](#)

- void [layering_bypass](#) (bool bypass_flag)
set layeringBypass flag and pass request on to highFidelityModel for any lower-level layerings.
- void [build_approximation](#) ()
use highFidelityModel to compute the truth values needed for correction of lowFidelityInterface results
- void [component_parallel_mode](#) (int mode)
update component parallel mode for supporting parallelism in lowFidelityInterface and highFidelityModel
- [String local_eval_synchronization](#) ()
return lowFidelityInterface local evaluation synchronization setting
- int [local_eval_concurrency](#) ()
return lowFidelityInterface asynchronous evaluation concurrency
- bool [derived_master_overload](#) () const
flag which prevents overloading the master with a multiprocessor evaluation (request forwarded to lowFidelityInterface)
- void [derived_init_communicators](#) (const int &max_iterator_concurrency)
set up lowFidelityInterface and highFidelityModel for parallel operations
- void [derived_init_serial](#) ()
set up lowFidelityInterface and highFidelityModel for serial operations.
- void [reset_communicators](#) ()
reset communicator partition data for the [HierLayeredModel](#) (request forwarded to lowFidelityInterface and highFidelityModel)
- void [free_communicators](#) ()
deallocate communicator partitions for the [HierLayeredModel](#) (request forwarded to lowFidelityInterface and highFidelityModel)
- void [serve](#) ()
Service lowFidelityInterface and highFidelityModel job requests received from the master. Completes when a termination message is received from [stop_servers](#)().
- void [stop_servers](#) ()
Executed by the master to terminate lowFidelityInterface and highFidelityModel server operations when iteration on the [HierLayeredModel](#) is complete.
- int [total_eval_counter](#) () const
return the total evaluation count for the [HierLayeredModel](#) (request forwarded to lowFidelityInterface)
- int [new_eval_counter](#) () const
return the new evaluation count for the [HierLayeredModel](#) (request forwarded to lowFidelityInterface)

Private Member Functions

- void [update_high_fidelity_model\(\)](#)
update highFidelityModel with current variable values/bounds/labels

Private Attributes

- [Interface lowFidelityInterface](#)
manages the approximate low fidelity function evaluations
- [Model highFidelityModel](#)
provides truth evaluations for computing corrections to the low fidelity results
- [Response highFidResponse](#)
the high fidelity response is computed in [build_approximation\(\)](#) and needs class scope for use in automatic surrogate construction in derived [compute_response](#) functions.
- [IntList evalIdList](#)
bookkeeps fnEvalId's for correction of asynchronous low fidelity evaluations

8.44.1 Detailed Description

Derived model class within the layered model branch for managing hierarchical surrogates (models of varying fidelity).

The [HierLayeredModel](#) class manages hierarchical models of varying fidelity. In particular, it uses a low fidelity model as a surrogate for a high fidelity model. The class contains a [lowFidelityInterface](#) which manages the approximate low fidelity function evaluations and a [highFidelityModel](#) which provides truth evaluations for computing corrections to the low fidelity results.

8.44.2 Member Function Documentation

8.44.2.1 void [derived_compute_response](#)(const [IntArray](#) & *asv*) [[protected](#), [virtual](#)]

portion of [compute_response\(\)](#) specific to [HierLayeredModel](#)

Evaluate the approximate response using [lowFidelityInterface](#), compute the high fidelity response with [build_approximation\(\)](#) (if not performed previously), and, if correction is active, correct the low fidelity results.

Reimplemented from [Model](#).

8.44.2.2 void derived_async_compute_response (const [IntArray](#) & *asv*) [protected, virtual]

portion of [async_compute_response\(\)](#) specific to [HierLayeredModel](#)

Evaluate the approximate response using an asynchronous [lowFidelityInterface](#) mapping and compute the high fidelity response with [build_approximation\(\)](#) (for correcting the low fidelity results in [derived_synchronize\(\)](#) and [derived_synchronize_nowait\(\)](#)) if not performed previously.

Reimplemented from [Model](#).

8.44.2.3 const [ResponseArray](#) & derived_synchronize () [protected, virtual]

portion of [synchronize\(\)](#) specific to [HierLayeredModel](#)

Perform a blocking retrieval of all asynchronous evaluations from [lowFidelityInterface](#) and, if automatic correction is on, apply correction to each response in the array.

Reimplemented from [Model](#).

8.44.2.4 const [ResponseList](#) & derived_synchronize_nowait () [protected, virtual]

portion of [synchronize_nowait\(\)](#) specific to [HierLayeredModel](#)

Perform a nonblocking retrieval of currently available asynchronous evaluations from [lowFidelityInterface](#) and, if automatic correction is on, apply correction to each response in the list.

Reimplemented from [Model](#).

8.44.2.5 [String](#) local_eval_synchronization () [inline, protected, virtual]

return [lowFidelityInterface](#) local evaluation synchronization setting

Used in setting [Model::asynchEvalFlag](#). [highFidelityModel](#) synchronization is used for setting [asynchEvalFlag](#) within [highFidelityModel](#).

Reimplemented from [Model](#).

8.44.2.6 int local_eval_concurrency () [inline, protected, virtual]

return [lowFidelityInterface](#) asynchronous evaluation concurrency

Used in setting [Model::evaluationCapacity](#). [highFidelityModel](#) concurrency is used for setting [evaluationCapacity](#) within [highFidelityModel](#).

Reimplemented from [Model](#).

8.44.2.7 bool derived_master_overload () const [inline, protected, virtual]

flag which prevents overloading the master with a multiprocessor evaluation (request forwarded to lowFidelityInterface)

iterator_eval_dedicated_master_flag() and multi_proc_eval_flag() flags from lowFidelityInterface are used. Derived master overload for highFidelityModel is handled separately in highFidelityModel.compute_response().

Reimplemented from [Model](#).

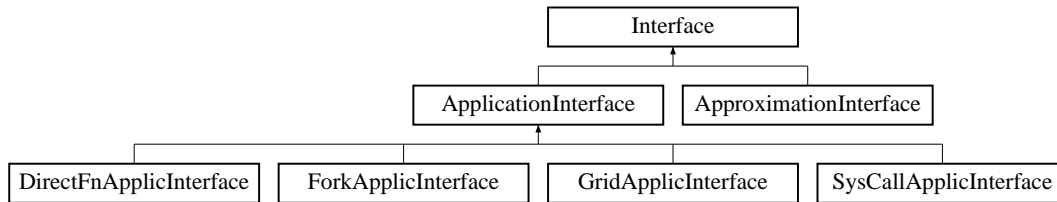
The documentation for this class was generated from the following files:

- HierLayeredModel.H
- HierLayeredModel.C

8.45 Interface Class Reference

Base class for the interface class hierarchy.

Inheritance diagram for Interface::



Public Member Functions

- [Interface](#) ()
default constructor
- [Interface](#) ([ProblemDescDB](#) &problem_db, const size_t &num_acv, const size_t &num_fns)
standard constructor for envelope
- [Interface](#) (const [Interface](#) &interface)
copy constructor
- virtual [~Interface](#) ()
destructor
- [Interface operator=](#) (const [Interface](#) &interface)
assignment operator
- virtual void [map](#) (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response, const bool asynch_flag=false)
the function evaluator: provides a "mapping" from the variables to the responses.
- virtual const [ResponseArray](#) & [synch](#) ()
recovers data from a series of asynchronous evaluations (blocking)
- virtual const [ResponseList](#) & [synch_nowait](#) ()
recovers data from a series of asynchronous evaluations (nonblocking)
- virtual void [serve_evaluations](#) ()
evaluation server function for multiprocessor executions
- virtual void [stop_evaluation_servers](#) ()
send messages from iterator rank 0 to terminate evaluation servers

- virtual void [init_communicators](#) (const [IntArray](#) &message_lengths, const int &max_iterator_concurrency)

allocate communicator partitions for concurrent evaluations within an iterator and concurrent multiprocessor analyses within an evaluation.
- virtual void [reset_communicators](#) (const [IntArray](#) &message_lengths)

reset the local parallel partition data for an interface (the partitions are already allocated in [ParallelLibrary](#)).
- virtual void [free_communicators](#) ()

deallocate communicator partitions for concurrent evaluations within an iterator and concurrent multiprocessor analyses within an evaluation.
- virtual void [init_serial](#) ()

reset certain defaults for serial interface objects.
- virtual int [asynch_local_evaluation_concurrency](#) () const

return the user-specified concurrency for asynch local evaluations
- virtual [String](#) [interface_synchronization](#) () const

return the user-specified interface synchronization
- virtual int [minimum_samples](#) () const

returns the minimum number of samples required to build a particular [ApproximationInterface](#) (used by [SurrLayeredModels](#)).
- virtual void [build_global_approximation](#) ([Iterator](#) &dace_iterator, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)

builds a global approximation for use as a surrogate
- virtual void [build_local_approximation](#) ([Model](#) &actual_model)

builds a local approximation for use as a surrogate
- virtual void [update_approximation](#) (const [RealVector](#) &x_star, const [Response](#) &response_star)

updates an existing global approximation with new data
- virtual const [RealVectorArray](#) & [approximation_coefficients](#) ()

retrieve the approximation coefficients from each [Approximation](#) within an [ApproximationInterface](#)
- void [assign_rep](#) ([Interface](#) *interface_rep)

replaces existing letter with a new one
- const [IntList](#) & [synch_nowait_completions](#) ()

returns id's matching response list from [synch_nowait](#)()
- const [String](#) & [interface_type](#) () const

returns the interface type
- int [total_eval_counter](#) () const

returns the total number of evaluations of the interface

- int `new_eval_counter` () const
returns the number of new (nonduplicate) evaluations of the interface
- bool `multi_proc_eval_flag` () const
returns a flag signaling the use of multiprocessor evaluation partitions
- bool `iterator_eval_dedicated_master_flag` () const
returns a flag signaling the use of a dedicated master processor at the iterator-evaluation scheduling level
- bool `is_null` () const
function to check interfaceRep (does this envelope contain a letter?)

Protected Member Functions

- **Interface** (`BaseConstructor`, const `ProblemDescDB` &`problem_db`)
constructor initializes the base class part of letter classes (`BaseConstructor` overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

Protected Attributes

- **String** `interfaceType`
interface type may be (1) application: system, fork, direct, or grid; or (2) approximation: ann, rsm, mars, hermite, ksm, mpa, taylor, or hierarchical.
- int `fnEvalId`
total evaluation counter
- int `newFnEvalId`
new (non-duplicate) evaluation counter
- **IntList** `beforeSynchIdList`
bookkeeps fnEvalId's of _all_ asynchronous evaluations (new & duplicate)
- **ResponseArray** `rawResponseArray`
The complete array of responses returned after a blocking schedule of asynchronous evaluations.
- **ResponseList** `rawResponseList`
The partial list of responses returned after a nonblocking schedule of asynchronous evaluations.
- **IntList** `completionList`
identifies the responses in rawResponseList for nonblocking schedules.
- bool `multiProcEvalFlag`
flag for multiprocessor evaluation partitions (evalComm)
- bool `ieDedMasterFlag`
flag for dedicated master partitioning at the iterator level

- bool [silentFlag](#)
flag for really quiet (silent) interface output
- bool [quietFlag](#)
flag for quiet interface output
- bool [verboseFlag](#)
flag for verbose interface output
- bool [debugFlag](#)
flag for really verbose (debug) interface output

Private Member Functions

- [Interface](#) * [get_interface](#) ([ProblemDescDB](#) &problem_db, const size_t &num_acv, const size_t &num_fns)
Used by the envelope to instantiate the correct letter class.

Private Attributes

- [Interface](#) * [interfaceRep](#)
pointer to the letter (initialized only for the envelope)
- int [referenceCount](#)
number of objects sharing interfaceRep

8.45.1 Detailed Description

Base class for the interface class hierarchy.

The [Interface](#) class hierarchy provides the part of a [Model](#) that is responsible for mapping a set of [Variables](#) into a set of Responses. The mapping is performed using either a simulation-based application interface or a surrogate-based approximation interface. For memory efficiency and enhanced polymorphism, the interface hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Interface](#)) serves as the envelope and one of the derived classes (selected in [Interface::get_interface\(\)](#)) serves as the letter.

8.45.2 Constructor & Destructor Documentation

8.45.2.1 [Interface](#) ()

default constructor

used in [Model](#) envelope class instantiations

8.45.2.2 **Interface** (**ProblemDescDB** & *problem_db*, *const size_t* & *num_acv*, *const size_t* & *num_fns*)

standard constructor for envelope

Used in [Model](#) instantiation to build the envelope. This constructor only needs to extract enough data to properly execute `get_interface`, since `Interface::Interface(BaseConstructor, problem_db)` builds the actual base class data inherited by the derived interfaces.

8.45.2.3 **Interface** (*const Interface* & *interface*)

copy constructor

Copy constructor manages sharing of `interfaceRep` and incrementing of `referenceCount`.

8.45.2.4 **~Interface** () [*virtual*]

destructor

Destructor decrements `referenceCount` and only deletes `interfaceRep` if `referenceCount` is zero.

8.45.2.5 **Interface** (**BaseConstructor**, *const ProblemDescDB* & *problem_db*) [*protected*]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all inherited interfaces. `get_interface()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_interface()` again). Since this is the letter and the letter IS the representation, `interfaceRep` is set to NULL (an uninitialized pointer causes problems in `~Interface`).

8.45.3 Member Function Documentation

8.45.3.1 **Interface** `operator=` (*const Interface* & *interface*)

assignment operator

Assignment operator decrements `referenceCount` for old `interfaceRep`, assigns new `interfaceRep`, and increments `referenceCount` for new `interfaceRep`.

8.45.3.2 **void** `assign_rep` (**Interface** * *interface_rep*)

replaces existing letter with a new one

Similar to the assignment operator, the `assign_rep()` function decrements `referenceCount` for the old `interfaceRep` and assigns the new `interfaceRep`. It is different in that it is used for publishing derived class letters to existing envelopes, as opposed to sharing representations among multiple envelopes (in particular, `assign_rep` is passed a letter object and `operator=` is passed an envelope object). Letter assignment is modeled after `get_interface()` in that it does not increment the `referenceCount` for the new `interfaceRep`.

8.45.3.3 **Interface** * `get_interface (ProblemDescDB & problem_db, const size_t & num_acv, const size_t & num_fns)` [private]

Used by the envelope to instantiate the correct letter class.

used only by the envelope constructor to initialize interfaceRep to the appropriate derived type, as given by the interfaceType attribute.

8.45.4 Member Data Documentation

8.45.4.1 **ResponseArray** `rawResponseArray` [protected]

The complete array of responses returned after a blocking schedule of asynchronous evaluations.

The array is the raw set of responses corresponding to all asynchronous map calls. This raw array is postprocessed (i.e., finite difference gradients merged) in `Model::synchronize()` where it becomes response-Array.

8.45.4.2 **ResponseList** `rawResponseList` [protected]

The partial list of responses returned after a nonblocking schedule of asynchronous evaluations.

The list is a partial set of completions which must be identified through the use of completionList. Post-processing from raw to combined form (i.e., finite difference gradient merging) is not currently supported in `Model::synchronize_nowait()`.

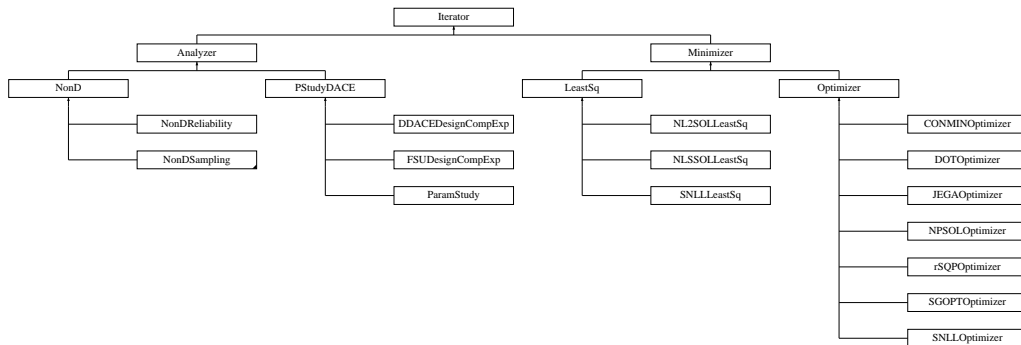
The documentation for this class was generated from the following files:

- DakotaInterface.H
- DakotaInterface.C

8.46 Iterator Class Reference

Base class for the iterator class hierarchy.

Inheritance diagram for Iterator::



Public Member Functions

- [Iterator](#) ()
default constructor
- [Iterator](#) ([Model](#) &model)
standard constructor for envelope
- [Iterator](#) (const [Iterator](#) &iterator)
copy constructor
- virtual [~Iterator](#) ()
destructor
- [Iterator operator=](#) (const [Iterator](#) &iterator)
assignment operator
- virtual void [run_iterator](#) ()
run the iterator
- virtual const [Variables](#) & [iterator_variable_results](#) () const
return the final iterator solution (variables)
- virtual const [Response](#) & [iterator_response_results](#) () const
return the final iterator solution (response)
- virtual void [print_iterator_results](#) (ostream &s) const
print the final iterator results

- virtual void [multi_objective_weights](#) (const [RealVector](#) &multi_obj_wts)
set the relative weightings for multiple objective functions. Used by [ConcurrentStrategy](#) for Pareto set optimization.
- virtual void [sampling_reset](#) (int min_samples, bool all_data_flag, bool stats_flag)
reset sampling iterator
- virtual const [String](#) & [sampling_scheme](#) () const
return sampling name
- virtual [String](#) [uses_method](#) () const
return name of any enabling iterator used by this iterator
- virtual void [method_recourse](#) ()
perform a method switch, if possible, due to a detected conflict
- virtual const [VariablesArray](#) & [all_variables](#) () const
return the complete set of evaluated variables
- virtual const [RealVectorArray](#) & [all_c_variables](#) () const
return the complete set of evaluated continuous variables
- virtual const [ResponseArray](#) & [all_responses](#) () const
return the complete set of computed responses
- virtual const [RealVectorArray](#) & [all_fn_responses](#) () const
return the complete set of computed function responses
- void [assign_rep](#) ([Iterator](#) *iterator_rep)
replaces existing letter with a new one
- void [user_defined_model](#) (const [Model](#) &the_model)
set the model
- [Model](#) [user_defined_model](#) () const
return the model
- const [String](#) & [method_name](#) () const
return the method name
- const int & [maximum_concurrency](#) () const
return the maximum concurrency supported by the iterator
- void [active_set_vector](#) (const [IntArray](#) &asv)
set the default active set vector (for use with iterators that employ [evaluate_parameter_sets\(\)](#))
- void [iterator_response_results_asv](#) (const [IntArray](#) &asv)
set the requested data for the final iterator response results
- void [sub_iterator_flag](#) (bool si_flag)

set subIteratorFlag

- bool `is_null ()` const
function to check iteratorRep (does this envelope contain a letter?)

Protected Member Functions

- `Iterator` (`BaseConstructor`, `Model` &model)
constructor initializes the base class part of letter classes (`BaseConstructor` overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- `Iterator` (`NoDBBaseConstructor`, `Model` &model)
base class for iterator classes constructed on the fly (no DB queries)

Protected Attributes

- `Model` `userDefinedModel`
shallow copy (shared rep) of the model passed into the constructor. A class member reference is not needed in this case due to the presence of representation sharing in Models.
- const `ProblemDescDB` & `probDescDB`
class member reference to the problem description database
- `String` `methodName`
name of the iterator (the user's method spec)
- int `maxIterations`
maximum number of iterations for the iterator
- int `maxFunctionEvals`
maximum number of fn evaluations for the iterator
- int `numFunctions`
number of response functions
- int `maxConcurrency`
maximum coarse-grained concurrency
- int `numContinuousVars`
number of active continuous vars.
- int `numDiscreteVars`
number of active discrete vars.
- int `numVars`
total number of vars. (active and inactive)

- **IntArray activeSetVector**
this vector tracks the data requirements for the response functions. It uses a 0 value for inactive functions and, for active functions, sums 1 for value, 2 for gradient, and 4 for Hessian.
- **IntArray finalResultsASV**
this active set vector specifies the required final results to be returned by `iterator_response_results()`
- **bool subIteratorFlag**
flag indicating if this `Iterator` is a sub-iterator (`NestedModel::subIterator`) or `SurrLayeredModel::daceIterator`).
- **String gradientType**
type of gradient data: analytic, numerical, mixed, or none
- **String intervalType**
type of numerical gradient interval: central or forward
- **String methodSource**
source of numerical gradient routine: dakota or vendor
- **String hessianType**
type of Hessian data: analytic, numerical, quasi, mixed, or none
- **Real fdGradStepSize**
relative finite difference step size for numerical gradients
- **Real fdHessByGradStepSize**
relative finite difference step size for numerical Hessians estimated using first-order differences of gradients
- **Real fdHessByFnStepSize**
relative finite difference step size for numerical Hessians estimated using second-order differences of function values
- **bool silentOutput**
flag for really quiet (silent) algorithm output
- **bool quietOutput**
flag for quiet algorithm output
- **bool verboseOutput**
flag for verbose algorithm output
- **bool debugOutput**
flag for really verbose (debug) algorithm output
- **bool asynchFlag**
copy of the model's asynchronous evaluation flag

Private Member Functions

- [Iterator * get_iterator \(Model &model\)](#)
Used by the envelope to instantiate the correct letter class.

Private Attributes

- [Iterator * iteratorRep](#)
pointer to the letter (initialized only for the envelope)
- [int referenceCount](#)
number of objects sharing iteratorRep

8.46.1 Detailed Description

Base class for the iterator class hierarchy.

The [Iterator](#) class is the base class for one of the primary class hierarchies in DAKOTA. The iterator hierarchy contains all of the iterative algorithms which use repeated execution of simulations as function evaluations. For memory efficiency and enhanced polymorphism, the iterator hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Iterator](#)) serves as the envelope and one of the derived classes (selected in [Iterator::get_iterator\(\)](#)) serves as the letter.

8.46.2 Constructor & Destructor Documentation

8.46.2.1 [Iterator \(\)](#)

default constructor

The default constructor is used in `Vector<Iterator>` instantiations and for initialization of [Iterator](#) objects contained in [Strategy](#) derived classes (see derived class header files). `iteratorRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful [Iterator](#) object). This makes it necessary to check for NULL pointers in the copy constructor, assignment operator, and destructor.

8.46.2.2 [Iterator \(Model & model\)](#)

standard constructor for envelope

Used in iterator instantiations within strategy constructors. Envelope constructor only needs to extract enough data to properly execute `get_iterator`, since [Iterator\(BaseConstructor, model\)](#) builds the actual base class data inherited by the derived iterators.

8.46.2.3 [Iterator \(const Iterator & iterator\)](#)

copy constructor

Copy constructor manages sharing of `iteratorRep` and incrementing of `referenceCount`.

8.46.2.4 `~Iterator()` [virtual]

destructor

Destructor decrements referenceCount and only deletes iteratorRep when referenceCount reaches zero.

8.46.2.5 `Iterator(BaseConstructor, Model & model)` [protected]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor builds the base class data for all inherited iterators. `get_iterator()` instantiates a derived class and the derived class selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_iterator()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Iterator`).

8.46.2.6 `Iterator(NoDBBaseConstructor, Model & model)` [protected]

base class for iterator classes constructed on the fly (no DB queries)

This constructor also builds base class data for inherited iterators. However, it is used for on-the-fly instantiations for which DB queries cannot be used (e.g., [ApproximationInterface](#) instantiation of [DDACEDesignCompExp](#) or [NonDSampling](#), [NonDReliability](#) usage of optimizers, etc.). Therefore it only sets attributes taken from the incoming model.

8.46.3 Member Function Documentation**8.46.3.1** `Iterator operator= (const Iterator & iterator)`

assignment operator

Assignment operator decrements referenceCount for old iteratorRep, assigns new iteratorRep, and increments referenceCount for new iteratorRep.

8.46.3.2 `void run_iterator()` [virtual]

run the iterator

This function is the primary run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented in [LeastSq](#), [NonD](#), [Optimizer](#), and [PStudyDACE](#).

8.46.3.3 `void assign_rep (Iterator * iterator_rep)`

replaces existing letter with a new one

Similar to the assignment operator, the `assign_rep()` function decrements referenceCount for the old iteratorRep and assigns the new iteratorRep. It is different in that it is used for publishing derived class

letters to existing envelopes, as opposed to sharing representations among multiple envelopes (in particular, `assign_rep` is passed a letter object and `operator=` is passed an envelope object). Letter assignment is modeled after `get_iterator()` in that it does not increment the `referenceCount` for the new `iteratorRep`.

8.46.3.4 Iterator * `get_iterator (Model & model)` [private]

Used by the envelope to instantiate the correct letter class.

Used only by the envelope constructor to initialize `iteratorRep` to the appropriate derived type, as given by the `methodName` attribute.

8.46.4 Member Data Documentation

8.46.4.1 Real `fdGradStepSize` [protected]

relative finite difference step size for numerical gradients

A scalar value (instead of the vector `fd_gradient_step_size spec`) is used within the iterator hierarchy since this attribute is only used to publish a step size to vendor numerical gradient algorithms.

8.46.4.2 Real `fdHessByGradStepSize` [protected]

relative finite difference step size for numerical Hessians estimated using first-order differences of gradients

A scalar value (instead of the vector `fd_hessian_step_size spec`) is used within the iterator hierarchy since this attribute is only used to publish a step size to vendor numerical Hessian algorithms.

8.46.4.3 Real `fdHessByFnStepSize` [protected]

relative finite difference step size for numerical Hessians estimated using second-order differences of function values

A scalar value (instead of the vector `fd_hessian_step_size spec`) is used within the iterator hierarchy since this attribute is only used to publish a step size to vendor numerical Hessian algorithms.

The documentation for this class was generated from the following files:

- `DakotaIterator.H`
- `DakotaIterator.C`

8.47 JEGAEvaluator Class Reference

This evaluator uses Sandia National Laboratories [Dakota](#) software.

Public Member Functions

- const [Model](#) & [GetDakotaModel](#) () const
Returns the "_model" object by const reference.
- virtual bool [Evaluate](#) (DesignGroup &group)
Does evaluation of each design in "group".
- virtual bool [Evaluate](#) (Design &des)
This method cannot be used!!
- virtual string [GetName](#) () const
Returns the proper name of this operator.
- virtual string [GetDescription](#) () const
Returns a full description of what this operator does and how.
- virtual GeneticAlgorithmOperator * [Clone](#) (GeneticAlgorithm &algorithm) const
Creates and returns a pointer to an exact duplicate of this operator.
- [JEGAEvaluator](#) (GeneticAlgorithm &alg, [Model](#) &model)
Constructs a JEGAEvaluator for use by "alg".
- [JEGAEvaluator](#) (const [JEGAEvaluator](#) ©)
Copy constructs a JEGAEvaluator.
- [JEGAEvaluator](#) (const [JEGAEvaluator](#) ©, GeneticAlgorithm &algorithm, [Model](#) &model)
Copy constructs a JEGAEvaluator for use by "algorithm".

Static Public Member Functions

- string [Name](#) ()
Returns the proper name of this operator.
- string [Description](#) ()
Returns a full description of what this operator does and how.
- GeneticAlgorithmOperator * [Create](#) (GeneticAlgorithm &algorithm)
returns a new instance of this operator class for use by "algorithm"

Protected Member Functions

- [Model](#) & [GetDakotaModel](#) ()
Returns the "_model" object by reference.
- [RealVector](#) [GetContinuumVariableValues](#) (const [Design](#) &des) const
Returns the continuous Design variable values held in Design "des".
- [IntVector](#) [GetDiscreteVariableValues](#) (const [Design](#) &des) const
Returns the discrete Design variable values held in Design "des".
- void [GetContinuumVariableValues](#) (const [Design](#) &from, [RealVector](#) &into) const
Places the continuous Design variable values from Design "from" into RealVector "into".
- void [GetDiscreteVariableValues](#) (const [Design](#) &from, [IntVector](#) &into) const
Places the discrete Design variable values from Design "from" into IntVector "into".
- void [SeparateVariables](#) (const [Design](#) &from, [IntVector](#) &intoDisc, [RealVector](#) &intoCont) const
This method fills "intoDisc" and "intoCont" appropriately using the values of "from".
- void [RecordResponses](#) (const [RealVector](#) &from, [Design](#) &into) const
Records the computed objective and constraint function values into "into".
- size_t [GetNumberNonLinearConstraints](#) () const
Returns the number of non-linear constraints for the problem.
- size_t [GetNumberLinearConstraints](#) () const
Returns the number of linear constraints for the problem.

Private Member Functions

- [JEGAEvaluator](#) (GeneticAlgorithm &alg)
This constructor has no implementation and cannot be used.

Private Attributes

- [Model](#) & [_model](#)
The [Model](#) known by this evaluator.

Static Private Attributes

- const bool [_is_standard_registered](#)
Initialization causes registry with the [StandarOperatorGroup](#).

8.47.1 Detailed Description

This evaluator uses Sandia National Laboratories [Dakota](#) software.

Evaluations are carried out using a [Model](#) which is known by reference to this class. This provides the advantage of execution on massively parallel computing architectures.

8.47.2 Constructor & Destructor Documentation

8.47.2.1 [JEGAEvaluator](#) ([GeneticAlgorithm](#) & *alg*) [private]

This constructor has no implementation and cannot be used.

This constructor can never be used. It is provided so that this operator can still be registered in an operator registry even though it can never be instantiated from there.

8.47.3 Member Function Documentation

8.47.3.1 [GeneticAlgorithmOperator](#) * [Create](#) ([GeneticAlgorithm](#) & *algorithm*) [static]

returns a new instance of this operator class for use by "algorithm"

This method cannot be used. It is provided so that this operator can still be registered in operator groups. Attempts to use this method will result in program abort.

8.47.3.2 [RealVector](#) [GetContinuumVariableValues](#) (const [Design](#) & *des*) const [protected]

Returns the continuous Design variable values held in Design "des".

It returns them as a [RealVector](#) for use in the [Dakota](#) interface. The values in the returned vector will be the actual values intended for use in the evaluation functions.

8.47.3.3 [IntVector](#) [GetDiscreteVariableValues](#) (const [Design](#) & *des*) const [protected]

Returns the discrete Design variable values held in Design "des".

It returns them as a [IntVector](#) for use in the [Dakota](#) interface. The values in the returned vector will be the values for the design variables as far as JEGA knows. However, in actuality, the values are the representations due to the way that [Dakota](#) manages discrete variables.

8.47.3.4 void [GetContinuumVariableValues](#) (const [Design](#) & *from*, [RealVector](#) & *into*) const [protected]

Places the continuous Design variable values from Design "from" into [RealVector](#) "into".

The values in the returned vector will be the actual values intended for use in the evaluation functions.

8.47.3.5 void GetDiscreteVariableValues (const Design & from, IntVector & into) const [protected]

Places the discrete Design variable values from Design "from" into IntVector "into".

The values placed in the vector will be the values for the design variables as far as JEGA knows. However, in actuality, the values are the representations due to the way that [Dakota](#) manages discrete variables.

8.47.3.6 void SeparateVariables (const Design & from, IntVector & intoDisc, RealVector & intoCont) const [protected]

This method fills "intoDisc" and "intoCont" appropriately using the values of "from".

It is more efficient to use this method than to use GetDiscreteVariableValues and GetContinuumVariableValues separately if you want both.

8.47.3.7 void RecordResponses (const RealVector & from, Design & into) const [protected]

Records the computed objective and constraint function values into "into".

This method takes the response values stored in "from" and properly transfers them into the "into" design.

8.47.3.8 bool Evaluate (DesignGroup & group) [virtual]

Does evaluation of each design in "group".

This method uses the [Model](#) know by this class to get Designs evaluated. It properly formats the Design class information in a way that [Dakota](#) will understand and then interprets the [Dakota](#) results and puts them back into the Design class object. It respects the asynchronous flag in the [Model](#) so evaluations may occur synchronously or asynchronously.

8.47.3.9 bool Evaluate (Design & des) [virtual]

This method cannot be used!!

This method does nothing and cannot be called. This is because in the case of asynchronous evaluation, this method would be unable to conform. It would require that each evaluation be done in a synchronous fashion.

8.47.4 Member Data Documentation

8.47.4.1 const bool [_is_standard_registered](#) [static, private]

Initial value:

```
StandardOperatorGroup::EvaluatorRegistry().Register(
    JEGAEvaluator::Name(), &JEGAEvaluator::Create)
```

Initialization causes registry with the StandarOperatorGroup.

This flag indicates whether or not this class was properly registered with the StandardOperatorGroup on startup. The [JEGAEvaluator](#) is a special case that registers itself with the group instead of having the group register it.

8.47.4.2 [Model& _model](#) [private]

The [Model](#) known by this evaluator.

It is through this model that evaluations will take place.

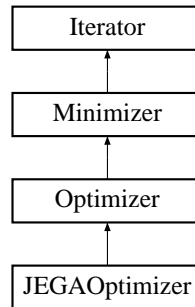
The documentation for this class was generated from the following files:

- [JEGAEvaluator.H](#)
- [JEGAEvaluator.C](#)

8.48 JEGAOptimizer Class Reference

Version of [Optimizer](#) for instantiation of John Eddy's Genetic Algorithms.

Inheritance diagram for JEGAOptimizer::



Public Member Functions

- `const GeneticAlgorithm & GetTheGA () const`
Returns the JEGA being used to optimize the problem (const).
- `GeneticAlgorithm & GetTheGA ()`
Returns the JEGA being used to optimize the problem (non-const).
- `const DesignTarget & GetTheTarget () const`
Returns the DesignTarget created here being used by the GA (const).
- `DesignTarget & GetTheTarget ()`
Returns the DesignTarget created here being used by the GA (non-const).
- `virtual void find_optimum ()`
Performs the iterations to determine the optimal set of solution.
- `JEGAOptimizer (Model &model, const string &method)`
Constructs a JEGAOptimizer class object.
- `~JEGAOptimizer ()`
Destructs a JEGAOptimizer.

Protected Member Functions

- `void CreateTheGA ()`
This method creates the GA.
- `void LoadTheGA ()`

Loads required information into a GA.

- void [CreateTheTarget](#) ()
This method creates but doesn't load the DesignTarget.
- void [LoadTheTarget](#) ()
This method creates but doesn't load the DesignTarget.
- void [CreateDesignVariableInfos](#) ()
Creates but doesn't load DesignVariableInfo objects.
- void [LoadDesignVariableInfos](#) ()
Loads information into the DesignVariableInfo objects.
- void [CreateConstraintInfos](#) ()
Creates but doesn't load ConstraintInfo objects.
- void [LoadConstraintInfos](#) ()
Loads information into the ConstraintInfo objects.
- void [ExtractOperatorParameters](#) (GeneticAlgorithmOperator *op)
This method requests that "op" retrieve its parameter values from "params".
- void [VerifyValidOperator](#) (GeneticAlgorithmOperator *op, const string &str)
This method verifies that "op" is not null.

Private Attributes

- GeneticAlgorithm * [_theGA](#)
This is a pointer to the instantiated GeneticAlgorithm.
- DesignTarget * [_theTarget](#)
This is a pointer to the DesignTarget object for the GeneticAlgorithm.
- JEGAEvaluator * [_theEvaluator](#)
A persistent pointer to the Evaluator created for the GeneticAlgorithm.
- string [_method](#)
The type of GA to create. Currently one of "moga" and "soga".

Static Private Attributes

- string [_sogaMethodText](#)
The text that indicates the SOGA method.
- string [_mogaMethodText](#)
The text that indicates the MOGA method.

8.48.1 Detailed Description

Version of [Optimizer](#) for instantiation of John Eddy's Genetic Algorithms.

This class encapsulates the necessary functionality for creating and properly initializing a Genetic-Algorithm.

8.48.2 Constructor & Destructor Documentation

8.48.2.1 [JEGAOptimizer](#) (*Model* & *model*, *const string* & *method*)

Constructs a [JEGAOptimizer](#) class object.

This method does much of the initialization work for the algorithm.

8.48.3 Member Function Documentation

8.48.3.1 `void CreateTheGA ()` [`protected`]

This method creates the GA.

It instantiates the GA and all the operators.

8.48.3.2 `void LoadTheGA ()` [`protected`]

Loads required information into a GA.

This method must be called prior to attempting any optimization with the GA. It does what is necessary to load the target properly.

8.48.3.3 `void CreateTheTarget ()` [`protected`]

This method creates but doesn't load the DesignTarget.

It instantiates the Target and the associated information objects. The information however is not considered current until LoadTheTarget is called (which should not be done in the constructor).

8.48.3.4 `void LoadTheTarget ()` [`protected`]

This method creates but doesn't load the DesignTarget.

This method must be called prior to attempting any optimization with the GA. It does what is necessary to load the target properly.

8.48.3.5 `void CreateDesignVariableInfos ()` [`protected`]

Creates but doesn't load DesignVariableInfo objects.

This method records the info objects with the target which must already have been created.

8.48.3.6 void LoadDesignVariableInfos () [protected]

Loads information into the DesignVariableInfo objects.

Information includes stuff like bounds, labels, discrete values, etc.

8.48.3.7 void CreateConstraintInfos () [protected]

Creates but doesn't load ConstraintInfo objects.

This method records the info objects with the target which must already have been created.

8.48.3.8 void LoadConstraintInfos () [protected]

Loads information into the ConstraintInfo objects.

Information includes stuff like targets and bounds, labels, and coefficients for linear constraints.

8.48.3.9 void ExtractOperatorParameters (GeneticAlgorithmOperator * op) [protected]

This method requests that "op" retrieve its parameter values from "params".

If "op" is unable to do so, this method causes an abort.

8.48.3.10 void VerifyValidOperator (GeneticAlgorithmOperator * op, const string & str) [protected]

This method verifies that "op" is not null.

If it is, this method causes an abort.

8.48.3.11 void find_optimum () [virtual]

Performs the iterations to determine the optimal set of solution.

Override of pure virtual method in [Optimizer](#) base class.

Implements [Optimizer](#).

The documentation for this class was generated from the following files:

- JEGAOptimizer.H
- JEGAOptimizer.C

8.49 KrigApprox Class Reference

Utility class for kriging interpolation.

Public Member Functions

- [KrigApprox](#) (int, int, const [RealVector](#) &, const [RealVector](#) &, const [RealVector](#) &)
constructor
- [~KrigApprox](#) ()
destructor
- void [ModelBuild](#) (int, int, const [RealVector](#) &, const [RealVector](#) &, bool)
Function to compute vector and matrix terms in the kriging surface.
- Real [ModelApply](#) (int, int, const [RealVector](#) &)
Function returns a response value using the kriging surface.

Private Attributes

- int [N1](#)
Size variable for CONMIN arrays. See CONMIN manual.
- int [N2](#)
Size variable for CONMIN arrays. See CONMIN manual.
- int [N3](#)
Size variable for CONMIN arrays. See CONMIN manual.
- int [N4](#)
Size variable for CONMIN arrays. See CONMIN manual.
- int [N5](#)
Size variable for CONMIN arrays. See CONMIN manual.
- int [conminSingleArray](#)
Array size parameter needed in interface to CONMIN.
- int [numcon](#)
CONMIN variable: Number of constraints.
- int [NFDG](#)
CONMIN variable: Finite difference flag.
- int [IPRINT](#)

CONMIN variable: Flag to control amount of output data.

- int **ITMAX**

CONMIN variable: Flag to specify the maximum number of iterations.

- Real **FDCH**

CONMIN variable: Relative finite difference step size.

- Real **FDCHM**

CONMIN variable: Absolute finite difference step size.

- Real **CT**

CONMIN variable: Constraint thickness parameter.

- Real **CTMIN**

CONMIN variable: Minimum absolute value of CT used during optimization.

- Real **CTL**

CONMIN variable: Constraint thickness parameter for linear and side constraints.

- Real **CTLMIN**

CONMIN variable: Minimum value of CTL used during optimization.

- Real **DELFUN**

CONMIN variable: Relative convergence criterion threshold.

- Real **DABFUN**

CONMIN variable: Absolute convergence criterion threshold.

- int **conminInfo**

CONMIN variable: status flag for optimization.

- Real * **S**

Internal CONMIN array.

- Real * **G1**

Internal CONMIN array.

- Real * **G2**

Internal CONMIN array.

- Real * **B**

Internal CONMIN array.

- Real * **C**

Internal CONMIN array.

- int * **MS1**

Internal CONMIN array.

- Real * **SCAL**
Internal CONMIN array.
- Real * **DF**
Internal CONMIN array.
- Real * **A**
Internal CONMIN array.
- int * **ISC**
Internal CONMIN array.
- int * **IC**
Internal CONMIN array.
- Real * **conminThetaVars**
Temporary array of design variables used by CONMIN (length N1 = numdv+2).
- Real * **conminThetaLowerBnds**
Temporary array of lower bounds used by CONMIN (length N1 = numdv+2).
- Real * **conminThetaUpperBnds**
Temporary array of upper bounds used by CONMIN (length N1 = numdv+2).
- Real **ALPHAX**
Internal CONMIN variable: 1-D search parameter.
- Real **ABOBJ1**
Internal CONMIN variable: 1-D search parameter.
- Real **THETA**
Internal CONMIN variable: mean value of push-off factor.
- Real **PHI**
Internal CONMIN variable: "participation coefficient".
- int **NSIDE**
Internal CONMIN variable: side constraints parameter.
- int **NSCAL**
Internal CONMIN variable: scaling control parameter.
- int **NACMX1**
Internal CONMIN variable: estimate of 1+(max # of active constraints).
- int **LINOBJ**
Internal CONMIN variable: linear objective function identifier (unused).
- int **ITRM**
Internal CONMIN variable: diminishing return criterion iteration number.

- int **ICNDIR**
Internal CONMIN variable: conjugate direction restart parameter.
- int **IGOTO**
Internal CONMIN variable: internal optimization termination flag.
- int **NAC**
Internal CONMIN variable: number of active and violated constraints.
- int **INFOG**
Internal CONMIN variable: gradient information flag.
- int **ITER**
Internal CONMIN variable: iteration count.
- int **iFlag**
Fortran77 flag for kriging computations.
- Real **betaHat**
Estimate of the beta term in the kriging model..
- Real **maxLikelihoodEst**
Error term computed via Maximum Likelihood Estimation.
- int **numNewPts**
Size variable for the arrays used in kriging computations.
- int **numSampQuad**
Size variable for the arrays used in kriging computations.
- Real * **thetaVector**
Array of correlation parameters for the kriging model.
- Real * **xMatrix**
A 2-D array of design points used to build the kriging model.
- Real * **yValueVector**
Array of response values corresponding to the array of design points.
- Real * **xNewVector**
A 2-D array of design points where the kriging model will be evaluated.
- Real * **yNewVector**
Array of response values corresponding to the design points specified in xNewVector.
- Real * **thetaLoBndVector**
Array of lower bounds in optimizer-to-kriging interface.
- Real * **thetaUpBndVector**

Array of upper bounds in optimizer-to-kriging interface.

- Real * [constraintVector](#)
Array of constraint values (used with optimizer).
- Real * [rhsTermsVector](#)
Internal array for kriging Fortran77 code: matrix algebra result.
- int * [iPivotVector](#)
Internal array for kriging Fortran77 code: pivot vector for linear algebra.
- Real * [correlationMatrix](#)
Internal array for kriging Fortran77 code: correlation matrix.
- Real * [invcorrelMatrix](#)
Internal array for kriging Fortran77 code: inverse correlation matrix.
- Real * [fValueVector](#)
Internal array for kriging Fortran77 code: response value vector.
- Real * [fRinvVector](#)
*Internal array for kriging Fortran77 code: vector*matrix result.*
- Real * [yfbVector](#)
Internal array for kriging Fortran77 code: vector arithmetic result.
- Real * [yfbRinvVector](#)
*Internal array for kriging Fortran77 code: vector*matrix result.*
- Real * [rXhatVector](#)
Internal array for kriging Fortran77 code: local correlation vector.
- Real * [workVector](#)
Internal array for kriging Fortran77 code: temporary storage.
- Real * [workVectorQuad](#)
Internal array for kriging Fortran77 code: temporary storage.
- int * [iworkVector](#)
Internal array for kriging Fortran77 code: temporary storage.

8.49.1 Detailed Description

Utility class for kriging interpolation.

The [KrigApprox](#) class provides utilities for the [KrigingSurf](#) class. It is based on the Ph.D. thesis work of Tony Giunta.

8.49.2 Member Function Documentation

8.49.2.1 Real ModelApply (int, int, const RealVector &)

Function returns a response value using the kriging surface.

The response value is computed at the design point specified by the RealVector function argument.

8.49.3 Member Data Documentation

8.49.3.1 int N1 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N1 = \text{number of variables} + 2$

8.49.3.2 int N2 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N2 = \text{number of constraints} + 2 * (\text{number of variables})$

8.49.3.3 int N3 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N3 = \text{Maximum possible number of active constraints.}$

8.49.3.4 int N4 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N4 = \text{Maximum}(N3, \text{number of variables})$

8.49.3.5 int N5 [private]

Size variable for CONMIN arrays. See CONMIN manual.

$N5 = 2 * (N4)$

8.49.3.6 Real CT [private]

CONMIN variable: Constraint thickness parameter.

The value of CT decreases in magnitude during optimization.

8.49.3.7 Real* S [private]

Internal CONMIN array.

Move direction in N-dimensional space.

8.49.3.8 Real* G1 [private]

Internal CONMIN array.

Temporary storage of constraint values.

8.49.3.9 Real* G2 [private]

Internal CONMIN array.

Temporary storage of constraint values.

8.49.3.10 Real* B [private]

Internal CONMIN array.

Temporary storage for computations involving array S.

8.49.3.11 Real* C [private]

Internal CONMIN array.

Temporary storage for use with arrays B and S.

8.49.3.12 int* MS1 [private]

Internal CONMIN array.

Temporary storage for use with arrays B and S.

8.49.3.13 Real* SCAL [private]

Internal CONMIN array.

[Vector](#) of scaling parameters for design parameter values.

8.49.3.14 Real* DF [private]

Internal CONMIN array.

Temporary storage for analytic gradient data.

8.49.3.15 Real* A [private]

Internal CONMIN array.

Temporary 2-D array for storage of constraint gradients.

8.49.3.16 `int* ISC` [private]

Internal CONMIN array.

[Array](#) of flags to identify linear constraints. (not used in this implementation of CONMIN)

8.49.3.17 `int* IC` [private]

Internal CONMIN array.

[Array](#) of flags to identify active and violated constraints

8.49.3.18 `int iFlag` [private]

Fortran77 flag for kriging computations.

iFlag=1 computes vector and matrix terms for the kriging surface, iFlag=2 computes the response value (using kriging) at the user-supplied design point.

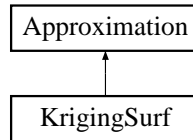
The documentation for this class was generated from the following files:

- KSMSurf.H
- KSMSurf.C

8.50 KrigingSurf Class Reference

Derived approximation class for kriging interpolation.

Inheritance diagram for KrigingSurf::



Public Member Functions

- [KrigingSurf](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_acv)
constructor
- [~KrigingSurf](#) ()
destructor

Protected Member Functions

- void [find_coefficients](#) ()
calculate the data fit coefficients using the currentPoints list of SurrogateDataPoints
- int [required_samples](#) ()
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- Real [get_value](#) (const [RealVector](#) &x)
retrieve the approximate function value for a given parameter vector

Private Attributes

- [KrigApprox](#) * [krigObject](#)
Kriging Surface object declaration.
- [RealVector](#) [x_matrix](#)
A 2-d array of all sample sites (design points) used to create the kriging surface.
- [RealVector](#) [f_of_x_array](#)
An array of response values; one response value per sample site.
- [RealVector](#) [correlationVector](#)

An array of correlation parameter values used to build the kriging surface.

- bool [runConminFlag](#)

Flag to run CONMIN (value=1) or use user-supplied correlations (value=0).

8.50.1 Detailed Description

Derived approximation class for kriging interpolation.

The [KrigingSurf](#) class uses a the kriging approach to interpolate between data points. It is based on the Ph.D. thesis work of Tony Giunta.

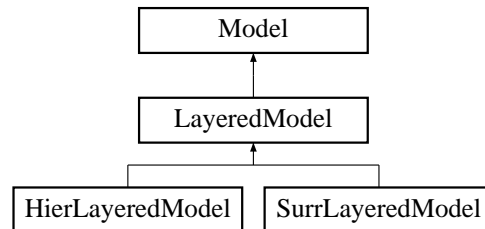
The documentation for this class was generated from the following files:

- KSMSurf.H
- KSMSurf.C

8.51 LayeredModel Class Reference

Base class for the layered models ([SurrLayeredModel](#) and [HierLayeredModel](#)).

Inheritance diagram for LayeredModel::



Protected Member Functions

- [LayeredModel](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~LayeredModel](#) ()
destructor
- void [compute_correction](#) (const [Response](#) &truth_response, const [Response](#) &approx_response, const [RealVector](#) &c_vars)
compute the correction required to bring approx_response into agreement with truth_response
- void [apply_correction](#) ([Response](#) &approx_response, const [RealVector](#) &c_vars, bool quiet_flag=false)
apply the correction computed in [compute_correction\(\)](#) to approx_response
- void [check_submodel_compatibility](#) (const [Model](#) &sub_model)
verify compatibility between [LayeredModel](#) attributes and attributes of the submodel ([SurrLayeredModel::actualModel](#) or [HierLayeredModel::highFidelityModel](#))
- bool [force_rebuild](#) ()
evaluate whether a rebuild of the approximation should be forced based on changes in the inactive data
- void [auto_correction](#) (bool correction_flag)
sets autoCorrection to on (true) or off (false)
- bool [auto_correction](#) ()
returns autoCorrection setting

Protected Attributes

- [ResponseArray correctedResponseArray](#)
array of corrected responses used in `derived_synchronize()` functions
- [ResponseList correctedResponseList](#)
list of corrected responses used in `derived_synchronize_nowait()` functions
- [RealVectorList rawCVarsList](#)
list of raw continuous variables used by `apply_correction()`. `Model::varsList` cannot be used for this purpose since it does not contain lower level variables sets from finite differencing.
- [String correctionType](#)
approximation correction approach to be used: additive or multiplicative
- short [correctionOrder](#)
approximation correction order to be used: 0, 1, or 2
- size_t [approxBuilds](#)
number of calls to `build_approximation()`
- bool [autoCorrection](#)
a flag which controls the use of `apply_correction()` in `SurrLayeredModel` and `HierLayeredModel` approximate response computations
- bool [layeringBypass](#)
a flag which allows bypassing the approximation for evaluations on the underlying truth model.
- [String approxType](#)
approximation type identifier string: global, local, or hierarchical
- [String refitInactive](#)
flag denoting a user setting for rebuilding the approximation when changes occur to the inactive variables data.
- [RealVector fitInactiveCVars](#)
stores a copy of the inactive continuous variables when the approximation is built; used to detect when a rebuild is required.
- [RealVector fitInactiveCLowerBnds](#)
stores a copy of the inactive continuous lower bounds when the approximation is built; used to detect when a rebuild is required.
- [RealVector fitInactiveCUpperBnds](#)
stores a copy of the inactive continuous upper bounds when the approximation is built; used to detect when a rebuild is required.
- [IntVector fitInactiveDVars](#)
stores a copy of the inactive discrete variables when the approximation is built; used to detect when a rebuild is required.

- [IntVector fitInactiveDLowerBnds](#)
stores a copy of the inactive discrete lower bounds when the approximation is built; used to detect when a rebuild is required.
- [IntVector fitInactiveDUpperBnds](#)
stores a copy of the inactive discrete upper bounds when the approximation is built; used to detect when a rebuild is required.

Private Member Functions

- void [apply_additive_correction](#) ([RealVector](#) &alpha_corrected_fns, [RealMatrix](#) &alpha_corrected_grads, [RealMatrixArray](#) &alpha_corrected_hessians, const [RealVector](#) &c_vars, const [IntArray](#) &asv)
internal convenience function for applying additive corrections
- void [apply_multiplicative_correction](#) ([RealVector](#) &beta_corrected_fns, [RealMatrix](#) &beta_corrected_grads, [RealMatrixArray](#) &beta_corrected_hessians, const [String](#) &approx_interf_id, const [RealVector](#) &c_vars, const [IntArray](#) &asv)
internal convenience function for applying multiplicative corrections

Private Attributes

- bool [correctionComputed](#)
flag indicating whether or not a correction is available
- bool [badScalingFlag](#)
flag used to indicate function values near zero for multiplicative corrections; triggers an automatic switch to additive corrections
- bool [combinedFlag](#)
flag indicating the combination of additive/multiplicative corrections
- bool [computeAdditive](#)
flag indicating the need for additive correction calculations
- bool [computeMultiplicative](#)
flag indicating the need for multiplicative correction calculations
- [RealVector](#) [addCorrFns](#)
0th-order additive correction term: equals the difference between high and low fidelity model values at $x=x_center$.
- [RealMatrix](#) [addCorrGrads](#)
1st-order additive correction term: equals the gradient of the high/low function difference at $x=x_center$.
- [RealMatrixArray](#) [addCorrHessians](#)
2nd-order additive correction term: equals the Hessian of the high/low function difference at $x=x_center$.

- [RealVector multCorrFns](#)
0th-order multiplicative correction term: equals the ratio of high fidelity to low fidelity model values at $x=x_center$.
- [RealMatrix multCorrGrads](#)
1st-order multiplicative correction term: equals the gradient of the high/low function ratio at $x=x_center$.
- [RealMatrixArray multCorrHessians](#)
2nd-order multiplicative correction term: equals the Hessian of the high/low function ratio at $x=x_center$.
- [RealVector combineFactors](#)
factors for combining additive and multiplicative corrections. Each factor is the weighting applied to the additive correction and 1.-factor is the weighting applied to the multiplicative correction. The factor value is determined by an additional requirement to match the high fidelity function value at the previous correction point (e.g., previous trust region center). This results in a multipoint correction instead of a strictly local correction.
- [RealVector correctionCenterPt](#)
The point in parameter space where the current correction is calculated (often the center of the current trust region). Used in calculating $(x - x_c)$ terms in 1st-/2nd-order corrections.
- [RealVector correctionPrevCenterPt](#)
copy of correctionCenterPt from the previous correction cycle
- [RealVector approxFnsCenter](#)
Surrogate function values at the current correction point which are needed as a fall back if the current surrogate function values are unavailable when applying 1st-/2nd-order multiplicative corrections.
- [RealVector approxFnsPrevCenter](#)
copy of approxFnsCenter from the previous correction cycle
- [RealMatrix approxGradsCenter](#)
Surrogate gradient values at the current correction point which are needed as a fall back if the current surrogate function gradients are unavailable when applying 1st-/2nd-order multiplicative corrections.
- [RealVector truthFnsCenter](#)
Truth function values at the current correction point.
- [RealVector truthFnsPrevCenter](#)
copy of truthFnsCenter from the previous correction cycle

8.51.1 Detailed Description

Base class for the layered models ([SurrLayeredModel](#) and [HierLayeredModel](#)).

The [LayeredModel](#) class provides common functions to derived classes for computing and applying corrections to approximations.

8.51.2 Member Function Documentation

8.51.2.1 void compute_correction (const [Response](#) & truth_response, const [Response](#) & approx_response, const [RealVector](#) & c_vars) [protected, virtual]

compute the correction required to bring approx_response into agreement with truth_response

Compute an additive or multiplicative correction that corrects the approx_response to have 0th-order consistency (matches values), 1st-order consistency (matches values and gradients), or 2nd-order consistency (matches values, gradients, and Hessians) with the truth_response at a single point (e.g., the center of a trust region). The 0th-order, 1st-order, and 2nd-order corrections use scalar values, linear scaling functions, and quadratic scaling functions, respectively, for each response function.

Reimplemented from [Model](#).

8.51.2.2 bool force_rebuild () [protected]

evaluate whether a rebuild of the approximation should be forced based on changes in the inactive data

This function forces a rebuild of the approximation according to the approximation type, the refitInactive setting, and whether any inactive data has changed since the last build.

8.51.3 Member Data Documentation

8.51.3.1 size_t approxBuilds [protected]

number of calls to [build_approximation\(\)](#)

used as a flag to automatically build the approximation if one of the derived compute_response functions is called prior to [build_approximation\(\)](#).

8.51.3.2 bool autoCorrection [protected]

a flag which controls the use of [apply_correction\(\)](#) in [SurrLayeredModel](#) and [HierLayeredModel](#) approximate response computations

the default is on (true) once [compute_correction\(\)](#) has been called. However this should be overridden when a new correction is desired, since [compute_correction\(\)](#) no longer automatically backs out an old correction.

8.51.3.3 String refitInactive [protected]

flag denoting a user setting for rebuilding the approximation when changes occur to the inactive variables data.

A setting of "all" denotes that the approximation should be rebuilt every time the inactive variables change (e.g., for each instance of {d} in OUU). A setting of "region" denotes that the approximation should be rebuilt every time the bounded region for the inactive variables changes (e.g., for each new trust region on {d} in OUU).

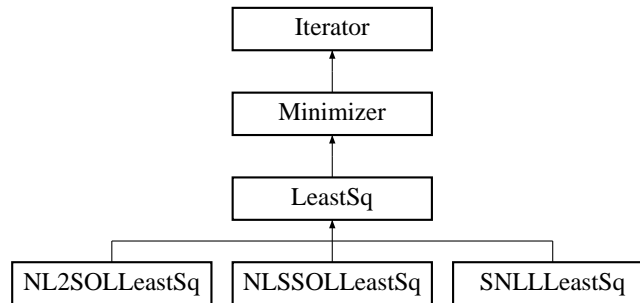
The documentation for this class was generated from the following files:

- LayeredModel.H
- LayeredModel.C

8.52 LeastSq Class Reference

Base class for the nonlinear least squares branch of the iterator hierarchy.

Inheritance diagram for LeastSq::



Protected Member Functions

- [LeastSq \(\)](#)
default constructor
- [LeastSq \(Model &model\)](#)
standard constructor
- [~LeastSq \(\)](#)
destructor
- void [run_iterator \(\)](#)
run the iterator
- void [print_iterator_results](#) (ostream &s) const
- virtual void [minimize_residuals \(\)=0](#)
Used within the least squares branch for minimizing the sum of squares residuals. Redefines the run_iterator virtual function for the least squares branch.

Protected Attributes

- int [numLeastSqTerms](#)
number of least squares terms

8.52.1 Detailed Description

Base class for the nonlinear least squares branch of the iterator hierarchy.

The [LeastSq](#) class provides common data and functionality for [NLSSOLLeastSq](#) and [SNLLLeastSq](#).

8.52.2 Constructor & Destructor Documentation

8.52.2.1 `LeastSq` (`Model & model`) [`protected`]

standard constructor

This constructor extracts the inherited data for the least squares branch and performs sanity checking on gradient and constraint settings.

8.52.3 Member Function Documentation

8.52.3.1 `void run_iterator()` [`inline`, `protected`, `virtual`]

run the iterator

This function is the primary run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented from [Iterator](#).

8.52.3.2 `void print_iterator_results(ostream & s) const` [`protected`, `virtual`]

Redefines default iterator results printing to include optimization results (objective function and constraints).

Reimplemented from [Iterator](#).

The documentation for this class was generated from the following files:

- `DakotaLeastSq.H`
- `DakotaLeastSq.C`

8.53 List Class Template Reference

Template class for the [Dakota](#) bookkeeping list.

Public Member Functions

- [List](#) ()
Default constructor.
- [List](#) (const [List](#)< T > &a)
Copy constructor.
- [~List](#) ()
Destructor.
- template<class InputIter> [List](#) (InputIter first, InputIter last)
Range constructor (member template).
- [List](#)< T > & [operator=](#) (const [List](#)< T > &a)
assignment operator
- void [print](#) (ostream &s) const
Prints a [List](#) to an output stream.
- void [read](#) ([MPIUnpackBuffer](#) &s)
Reads a [List](#) from an [MPIUnpackBuffer](#) after an MPI receive.
- void [print](#) ([MPIPackBuffer](#) &s) const
Prints a [List](#) to a [MPIPackBuffer](#) prior to an MPI send.
- size_t [entries](#) () const
Returns the number of items that are currently in the list.
- T [get](#) ()
Removes and returns the first item in the list.
- T [removeAt](#) (size_t index)
Removes and returns the item at the specified index.
- bool [remove](#) (const T &a)
Removes the specified item from the list.
- void [insert](#) (const T &a)
Adds the item a to the end of the list.
- bool [contains](#) (const T &a) const

Returns *TRUE* if list contains object *a*, returns *FALSE* otherwise.

- `bool find (bool(*testFun)(const T &, void *), void *d, T &k) const`
Returns *TRUE* if the list contains an object which the user defined function finds and sets *k* to this object.
- `size_t index (bool(*testFun)(const T &, void *), void *d) const`
Returns the index of object which the user defined test function finds.
- `void sort (bool(*sortFun)(const T &, const T &))`
Sorts the list into an order based on the predefined sort function.
- `size_t index (const T &a) const`
Returns the index of the object.
- `size_t count (const T &a) const`
Returns the number of items in the list equal to object.
- `T & operator[] (size_t i)`
Returns the object at index *i* (can use as lvalue).
- `const T & operator[] (size_t i) const`
Returns the object at index *i*, const (can't use as lvalue).

8.53.1 Detailed Description

```
template<class T> class Dakota::List< T >
```

Template class for the [Dakota](#) bookkeeping list.

The [List](#) is the common list class for [Dakota](#). It inherits from either the RW list class or the STL list class. Extends the base list class to add [Dakota](#) specific methods Builds upon the previously existing [DakotaVal-List](#) class

8.53.2 Member Function Documentation

8.53.2.1 T get ()

Removes and returns the first item in the list.

Remove and return item from front of list. Returns the object pointed to by the `list::begin()` iterator. It also deletes the first node by calling the `list::pop_front()` method. Note: `get()` is not the same as `list::front()` since the latter would return the 1st item but would not delete it.

8.53.2.2 T removeAt (size_t index)

Removes and returns the item at the specified index.

Removes the item at the index specified. Uses the STL `advance()` function to step to the appropriate position in the list and then calls the `list::erase()` method.

8.53.2.3 bool remove (const T & a)

Removes the specified item from the list.

Removes the first instance matching object a from the list (and therefore differs from the STL `list::remove()` which removes all instances). Uses the STL `find()` algorithm to find the object and the `list::erase()` method to perform the remove.

8.53.2.4 void insert (const T & a) [inline]

Adds the item a to the end of the list.

Insert item at the end of list, calls `list::push_back()` method which places the object at the end of the list.

8.53.2.5 bool contains (const T & a) const [inline]

Returns TRUE if list contains object a, returns FALSE otherwise.

Uses the STL `find()` algorithm to locate the first instance of object a. Returns true if an instance is found.

8.53.2.6 bool find (bool(* testFun)(const T &, void *), void * d, T & k) const

Returns TRUE if the list contains an object which the user defined function finds and sets k to this object.

Find the first item in the list which satisfies the test function. Sets k if the object is found.

8.53.2.7 size_t index (bool(* testFun)(const T &, void *), void * d) const

Returns the index of object which the user defined test function finds.

Returns the index of the first item in the list which satisfies the test function. Uses a single list traversal to both locate the object and return its index (generic algorithms would require two loop traversals).

8.53.2.8 void sort (bool(* sortFun)(const T &, const T &)) [inline]

Sorts the list into an order based on the predefined sort function.

The sort method utilizes the `SortCompare` functor and the base class `list::sort` algorithm to sort a list based on the incoming sorting function `sortFun`. Note that the functor-based sorting method of `std::list` is not supported by all compilers (e.g., SOLARIS, TFLOP) due to use of member templates, but a function pointer-based interface is available in some cases.

8.53.2.9 size_t index (const T & a) const

Returns the index of the object.

Returns the index of the first item in the list which matches the object a. Uses a single list traversal to both locate the object and return its index (generic algorithms would require two loop traversals).

8.53.2.10 size_t count (const T & a) const [inline]

Returns the number of items in the list equal to object.

Uses the STL [count\(\)](#) algorithm to return the number of occurrences of the specified object.

8.53.2.11]

T & operator[] (size_t *i*)

Returns the object at index *i* (can use as lvalue).

Returns item at position *i* of the list by stepping through the list using forward or reverse STL iterators (depending on which end of the list is closer to the desired item). Once the object is found, it returns the value pointed to by the iterator.

This functionality is inefficient in 0->len loop-based list traversals and is being replaced by iterator-based list traversals in the main DAKOTA code. For isolated look-ups of a particular index, however, this approach is acceptable.

8.53.2.12]

const T & operator[] (size_t *i*) const

Returns the object at index *i*, const (can't use as lvalue).

Returns const item at position *i* of the list by stepping through the list using forward or reverse STL iterators (depending on which end of the list is closer to the desired item). Once the object is found it returns the value pointed to by the iterator.

This functionality is inefficient in 0->len loop-based list traversals and is being replaced by iterator-based list traversals in the main DAKOTA code. For isolated look-ups of a particular index, however, this approach is acceptable.

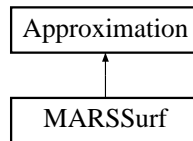
The documentation for this class was generated from the following file:

- DakotaList.H

8.54 MARSSurf Class Reference

Derived approximation class for multivariate adaptive regression splines.

Inheritance diagram for MARSSurf::



Public Member Functions

- [MARSSurf](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_acv)
constructor
- [~MARSSurf](#) ()
destructor

Protected Member Functions

- int [required_samples](#) ()
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- void [find_coefficients](#) ()
calculate the data fit coefficients using the currentPoints list of SurrogateDataPoints
- Real [get_value](#) (const [RealVector](#) &x)
retrieve the approximate function value for a given parameter vector

Private Attributes

- int * [flags](#)
variable type declarations (ordinal, excluded, categorical)
- Mars * [marsObject](#)
pointer to the Mars object (MARS wrapper provided as part of DDACE)

8.54.1 Detailed Description

Derived approximation class for multivariate adaptive regression splines.

The [MARSSurf](#) class provides a global approximation based on regression splines. It employs the C++ wrapper developed by the DDACE team for the Multivariate Adaptive Regression Splines (MARS) package from Prof. Jerome Friedman of Stanford University Dept. of Statistics.

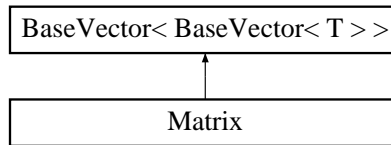
The documentation for this class was generated from the following files:

- MARSSurf.H
- MARSSurf.C

8.55 Matrix Class Template Reference

Template class for the [Dakota](#) numerical matrix.

Inheritance diagram for Matrix::



Public Member Functions

- [Matrix](#) (size_t num_rows=0, size_t num_cols=0)
Constructor, takes number of rows, and number of columns as arguments.
- [~Matrix](#) ()
Destructor.
- [Matrix< T > & operator=](#) (const T &ival)
Sets all elements in the matrix to ival.
- size_t [num_rows](#) () const
Returns the number of rows for the matrix.
- size_t [num_columns](#) () const
Returns the number of columns for the matrix.
- void [reshape_2d](#) (size_t num_rows, size_t num_cols)
Resizes the matrix to num_rows by num_cols.
- void [print](#) (ostream &s, bool rtn) const
Prints a [Matrix](#) to an output stream.
- void [print_row_vector](#) (ostream &s, size_t i, bool rtn) const
Prints a [Matrix](#) to an output stream.
- void [read](#) ([MPIUnpackBuffer](#) &s)
Reads a [Matrix](#) from an [MPIUnpackBuffer](#) after an MPI receive.
- void [print](#) ([MPIPackBuffer](#) &s) const
Prints a [Matrix](#) to a [MPIPackBuffer](#) prior to an MPI send.

8.55.1 Detailed Description

template<class T> class **Dakota::Matrix**< T >

Template class for the [Dakota](#) numerical matrix.

A matrix class template to provide 2D arrays of objects. The matrix is zero-based, rows: 0 to (numRows-1) and cols: 0 to (numColumns-1). The class supports overloading of the subscript operator allowing it to emulate a normal built-in 2D array type. [Matrix](#) relies on the [BaseVector](#) template class to manage any differences between underlying DAKOTA_BASE_VECTOR implementations (RW, STL, etc.).

8.55.2 Member Function Documentation

8.55.2.1 [Matrix](#)< T > & operator=(const T & val) [inline]

Sets all elements in the matrix to ival.

calls base class operator=(ival)

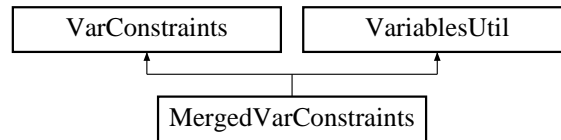
The documentation for this class was generated from the following file:

- [DakotaMatrix.H](#)

8.56 MergedVarConstraints Class Reference

Derived class within the [VarConstraints](#) hierarchy which employs the merged data view.

Inheritance diagram for MergedVarConstraints::



Public Member Functions

- [MergedVarConstraints](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~MergedVarConstraints](#) ()
destructor
- const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds
- void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds
- const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds
- void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds
- const [IntVector](#) & [discrete_lower_bounds](#) () const
return the active discrete variable lower bounds
- void [discrete_lower_bounds](#) (const [IntVector](#) &d_l_bnds)
set the active discrete variable lower bounds
- const [IntVector](#) & [discrete_upper_bounds](#) () const
return the active discrete variable upper bounds
- void [discrete_upper_bounds](#) (const [IntVector](#) &d_u_bnds)
set the active discrete variable upper bounds
- const [RealVector](#) & [inactive_continuous_lower_bounds](#) () const
return the inactive continuous lower bounds

- void `inactive_continuous_lower_bounds` (const `RealVector` &i_c_l_bnds)
set the inactive continuous lower bounds
- const `RealVector` & `inactive_continuous_upper_bounds` () const
return the inactive continuous upper bounds
- void `inactive_continuous_upper_bounds` (const `RealVector` &i_c_u_bnds)
set the inactive continuous upper bounds
- `RealVector` `all_continuous_lower_bounds` () const
returns a single array with all continuous lower bounds
- `RealVector` `all_continuous_upper_bounds` () const
returns a single array with all continuous upper bounds
- `IntVector` `all_discrete_lower_bounds` () const
returns a single array with all discrete lower bounds
- `IntVector` `all_discrete_upper_bounds` () const
returns a single array with all discrete upper bounds
- void `write` (ostream &s) const
write a variable constraints object to an ostream
- void `read` (istream &s)
read a variable constraints object from an istream

Private Attributes

- `RealVector` `mergedDesignLowerBnds`
a design lower bounds array merging continuous and discrete domains (integer values promoted to reals)
- `RealVector` `mergedDesignUpperBnds`
a design upper bounds array merging continuous and discrete domains (integer values promoted to reals)
- `RealVector` `uncertainDistLowerBnds`
the uncertain distribution lower bounds array (no discrete uncertain to merge)
- `RealVector` `uncertainDistUpperBnds`
the uncertain distribution upper bounds array (no discrete uncertain to merge)
- `RealVector` `mergedStateLowerBnds`
a state lower bounds array merging continuous and discrete domains (integer values promoted to reals)
- `RealVector` `mergedStateUpperBnds`
a state upper bounds array merging continuous and discrete domains (integer values promoted to reals)

8.56.1 Detailed Description

Derived class within the [VarConstraints](#) hierarchy which employs the merged data view.

Derived variable constraints classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [MergedVarConstraints](#) derived class combines continuous and discrete domain types but separates design, uncertain, and state variable types. The result is merged design bounds arrays (`mergedDesignLowerBnds`, `mergedDesignUpperBnds`), uncertain distribution bounds arrays (`uncertainDistLowerBnds`, `uncertainDistUpperBnds`), and merged state bounds arrays (`mergedStateLowerBnds`, `mergedStateUpperBnds`). The branch and bound strategy uses this approach (see `Variables::get_variables(problem_db)` for variables type selection; variables type is passed to the [VarConstraints](#) constructor in [Model](#)).

8.56.2 Constructor & Destructor Documentation

8.56.2.1 [MergedVarConstraints](#) (`const ProblemDescDB & problem_db`)

constructor

Extract fundamental lower and upper bounds and merge continuous and discrete domains to create `mergedDesignLowerBnds`, `mergedDesignUpperBnds`, `mergedStateLowerBnds`, and `mergedStateUpperBnds` using utilities from [VariablesUtil](#) (uncertain distribution bounds do not require any merging).

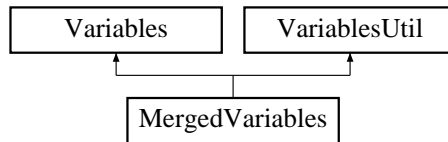
The documentation for this class was generated from the following files:

- [MergedVarConstraints.H](#)
- [MergedVarConstraints.C](#)

8.57 MergedVariables Class Reference

Derived class within the [Variables](#) hierarchy which employs the merged data view.

Inheritance diagram for MergedVariables::



Public Member Functions

- [MergedVariables](#) ()
default constructor
- [MergedVariables](#) (const [ProblemDescDB](#) &problem_db)
standard constructor
- [~MergedVariables](#) ()
destructor
- size_t [tv](#) () const
Returns total number of vars.
- size_t [cv](#) () const
Returns number of active continuous vars.
- size_t [dv](#) () const
Returns number of active discrete vars.
- const [RealVector](#) & [continuous_variables](#) () const
return the active continuous variables
- void [continuous_variables](#) (const [RealVector](#) &c_vars)
set the active continuous variables
- const [IntVector](#) & [discrete_variables](#) () const
return the active discrete variables
- void [discrete_variables](#) (const [IntVector](#) &d_vars)
set the active discrete variables
- const [StringArray](#) & [continuous_variable_labels](#) () const
return the active continuous variable labels

- void `continuous_variable_labels` (const `StringArray` &cv_labels)
set the active continuous variable labels
- const `StringArray` & `discrete_variable_labels` () const
return the active discrete variable labels
- void `discrete_variable_labels` (const `StringArray` &dv_labels)
set the active discrete variable labels
- const `RealVector` & `inactive_continuous_variables` () const
return the inactive continuous variables
- void `inactive_continuous_variables` (const `RealVector` &i_c_vars)
set the inactive continuous variables
- const `StringArray` & `inactive_continuous_variable_labels` () const
return the inactive continuous variable labels
- void `inactive_continuous_variable_labels` (const `StringArray` &i_c_v_labels)
set the inactive continuous variable labels
- size_t `acv` () const
returns total number of continuous vars
- size_t `adv` () const
returns total number of discrete vars
- `RealVector` `all_continuous_variables` () const
returns a single array with all continuous variables
- `IntVector` `all_discrete_variables` () const
returns a single array with all discrete variables
- `StringArray` `all_continuous_variable_labels` () const
returns a single array with all continuous variable labels
- `StringArray` `all_discrete_variable_labels` () const
returns a single array with all discrete variable labels
- `StringArray` `all_variable_labels` () const
returns a single array with all variable labels
- void `read` (istream &s)
read a variables object from an istream
- void `write` (ostream &s) const
write a variables object to an ostream
- void `write_aprepro` (ostream &s) const

write a variables object to an ostream in aprepro format

- void [read_annotated](#) (istream &s)
read a variables object in annotated format from an istream
- void [write_annotated](#) (ostream &s) const
write a variables object in annotated format to an ostream
- void [write_tabular](#) (ostream &s) const
write a variables object in tabular format to an ostream
- void [read](#) (BiStream &s)
read a variables object from the binary restart stream
- void [write](#) (BoStream &s) const
write a variables object to the binary restart stream
- void [read](#) (MPIUnpackBuffer &s)
read a variables object from a packed MPI buffer
- void [write](#) (MPIPackBuffer &s) const
write a variables object to a packed MPI buffer

Private Member Functions

- void [copy_rep](#) (const Variables *vars_rep)
Used by [copy\(\)](#) to copy the contents of a letter class.

Private Attributes

- [RealVector mergedDesignVars](#)
a design variables array merging continuous and discrete domains (integer values promoted to reals)
- [RealVector uncertainVars](#)
the uncertain variables array (no discrete uncertain to merge)
- [RealVector mergedStateVars](#)
a state variables array merging continuous and discrete domains (integer values promoted to reals)
- [StringArray mergedDesignLabels](#)
a label array combining continuous design and discrete design labels
- [StringArray uncertainLabels](#)
the uncertain variables label array (no discrete uncertain to combine)
- [StringArray mergedStateLabels](#)
a label array combining continuous state and discrete state labels

Friends

- bool `operator==` (const [MergedVariables](#) &vars1, const [MergedVariables](#) &vars2)
equality operator

8.57.1 Detailed Description

Derived class within the [Variables](#) hierarchy which employs the merged data view.

Derived variables classes take different views of the design, uncertain, and state variable types and the continuous and discrete domain types. The [MergedVariables](#) derived class combines continuous and discrete domain types but separates design, uncertain, and state variable types. The result is a single continuous array of design variables (`mergedDesignVars`), a single continuous array of uncertain variables (`uncertainVars`), and a single continuous array of state variables (`mergedStateVars`). The branch and bound strategy uses this approach (see `Variables::get_variables(problem_db)`).

8.57.2 Constructor & Destructor Documentation

8.57.2.1 [MergedVariables](#) (const [ProblemDescDB](#) & *problem_db*)

standard constructor

Extract fundamental variable types and labels and merge continuous and discrete domains to create `mergedDesignVars`, `mergedStateVars`, `mergedDesignLabels`, and `mergedStateLabels` using utilities from [VariablesUtil](#) (uncertain variables and labels do not require any merging).

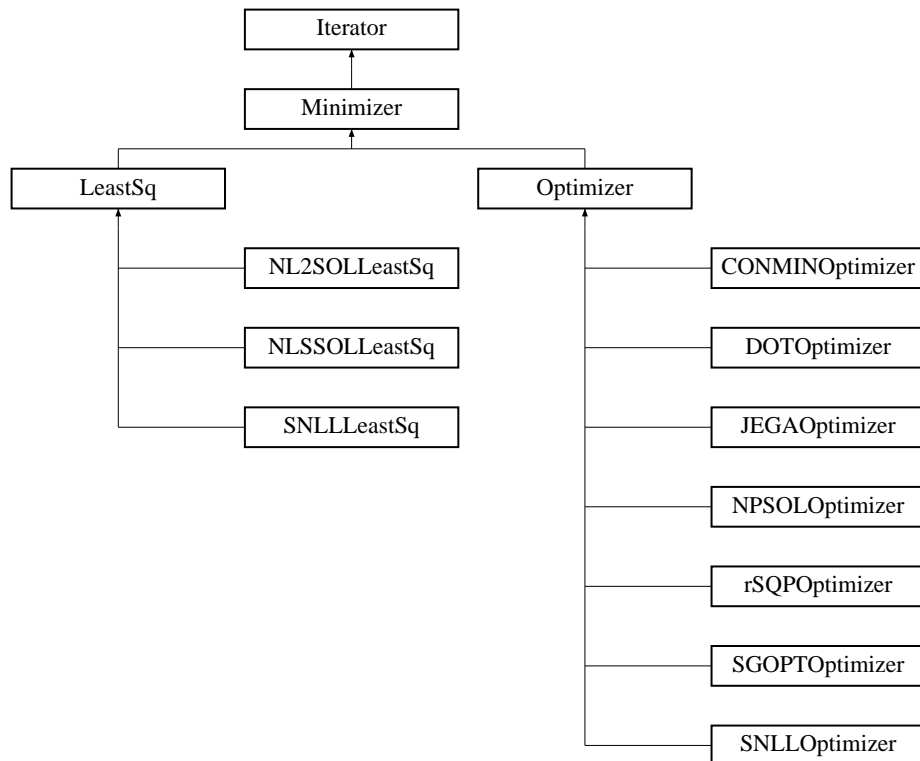
The documentation for this class was generated from the following files:

- `MergedVariables.H`
- `MergedVariables.C`

8.58 Minimizer Class Reference

Base class for the optimizer and least squares branches of the iterator hierarchy.

Inheritance diagram for Minimizer::



Public Member Functions

- `const Variables & iterator_variable_results () const`
return the final iterator solution (variables)
- `const Response & iterator_response_results () const`
return the final iterator solution (response)

Protected Member Functions

- `Minimizer ()`
default constructor
- `Minimizer (Model &model)`
standard constructor

- [~Minimizer \(\)](#)
destructor

Protected Attributes

- Real [convergenceTol](#)
optimizer/least squares convergence tolerance
- Real [constraintTol](#)
optimizer/least squares constraint tolerance
- `size_t` [numNonlinearIneqConstraints](#)
number of nonlinear inequality constraints
- `RealVector` [nonlinearIneqLowerBnds](#)
nonlinear inequality constraint lower bounds
- `RealVector` [nonlinearIneqUpperBnds](#)
nonlinear inequality constraint upper bounds
- Real [bigRealBoundSize](#)
cutoff value for inequality constraint and continuous variable bounds
- `int` [bigIntBoundSize](#)
cutoff value for discrete variable bounds
- `size_t` [numNonlinearEqConstraints](#)
number of nonlinear equality constraints
- `RealVector` [nonlinearEqTargets](#)
nonlinear equality constraint targets
- `size_t` [numLinearIneqConstraints](#)
number of linear inequality constraints
- `RealMatrix` [linearIneqConstraintCoeffs](#)
linear inequality constraint coefficients
- `RealVector` [linearIneqLowerBnds](#)
linear inequality constraint lower bounds
- `RealVector` [linearIneqUpperBnds](#)
linear inequality constraint upper bounds
- `size_t` [numLinearEqConstraints](#)
number of linear equality constraints

- [RealMatrix linearEqConstraintCoeffs](#)
linear equality constraint coefficients
- [RealVector linearEqTargets](#)
linear equality constraint targets
- `int` [numNonlinearConstraints](#)
total number of nonlinear constraints
- `int` [numLinearConstraints](#)
total number of linear constraints
- `int` [numConstraints](#)
total number of linear and nonlinear constraints
- `bool` [boundConstraintFlag](#)
convenience flag for denoting the presence of user-specified bound constraints. Used for method selection and error checking.
- `bool` [speculativeFlag](#)
flag for speculative gradient evaluations
- `bool` [vendorNumericalGradFlag](#)
convenience flag for `gradType == numerical && methodSource == vendor`
- [Variables bestVariables](#)
best variables found in solution
- [Response bestResponses](#)
best responses found in solution

8.58.1 Detailed Description

Base class for the optimizer and least squares branches of the iterator hierarchy.

The [Minimizer](#) class provides common data and functionality for [Optimizer](#) and [LeastSq](#).

8.58.2 Constructor & Destructor Documentation

8.58.2.1 [Minimizer \(Model & model\)](#) [protected]

standard constructor

This constructor extracts inherited data for the optimizer and least squares branches and performs sanity checking on constraint settings.

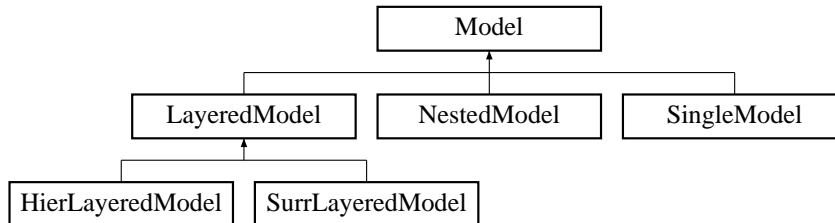
The documentation for this class was generated from the following files:

- `DakotaMinimizer.H`
- `DakotaMinimizer.C`

8.59 Model Class Reference

Base class for the model class hierarchy.

Inheritance diagram for Model::



Public Member Functions

- [Model \(\)](#)
default constructor
- [Model \(ProblemDescDB &problem_db\)](#)
standard constructor for envelope
- [Model \(const Model &model\)](#)
copy constructor
- [virtual ~Model \(\)](#)
destructor
- [Model operator= \(const Model &model\)](#)
assignment operator
- [virtual Model subordinate_model \(\)](#)
return the sub-model in nested and layered models
- [virtual Iterator subordinate_iterator \(\)](#)
return the sub-iterator in nested and layered models
- [virtual Interface & interface \(\)](#)
return the single interface employed by each derived model class: [SingleModel::userDefinedInterface](#), [SurrLayeredModel::approxInterface](#), [HierLayeredModel::lowFidelityInterface](#), or [NestedModel::optionalInterface](#)
- [virtual void layering_bypass \(bool bypass_flag\)](#)
deactivate/reactivate the approximations for any/all layered models contained within this model
- [virtual void build_approximation \(\)](#)
build the approximation in LayeredModels

- virtual void `update_approximation` (const `RealVector` &x_star, const `Response` &response_star)
update the approximation in SurrLayeredModels with new data
- virtual const `RealVectorArray` & `approximation_coefficients` ()
retrieve the approximation coefficients from each `Approximation` within a `SurrLayeredModel`
- virtual void `compute_correction` (const `Response` &truth_response, const `Response` &approx_response, const `RealVector` &c_vars)
compute correction factors for use in `LayeredModels`
- virtual void `auto_correction` (bool correction_flag)
manages automatic application of correction factors in `LayeredModels`
- virtual bool `auto_correction` ()
return flag indicating use of automatic correction within this model's responses
- virtual void `apply_correction` (`Response` &approx_response, const `RealVector` &c_vars, bool quiet_flag=false)
apply correction factors to approx_response (for use in `LayeredModels`)
- virtual void `component_parallel_mode` (int mode)
update component parallel mode for supporting parallelism in a model's interface component, sub-model component, or neither component (componentParallelMode = INTERFACE, SUBMODEL, or 0).
- virtual `String` `local_eval_synchronization` ()
return derived model synchronization setting
- virtual int `local_eval_concurrency` ()
return derived model asynchronous evaluation concurrency
- virtual void `reset_communicators` ()
reset communicator partition data for a model
- virtual void `free_communicators` ()
deallocate communicator partitions for a model
- virtual void `serve` ()
Service job requests received from the master. Completes when a termination message is received from `stop_servers()`.
- virtual void `stop_servers` ()
Executed by the master to terminate all server operations for a particular model when iteration on the model is complete.
- virtual const `IntList` & `synchronize_nowait_completions` ()
Return completion id's matching response list from `synchronize_nowait`.
- virtual bool `derived_master_overload` () const

Return a flag indicating the combination of multiprocessor evaluations and a dedicated master iterator scheduling. Used in synchronous `compute_response` functions to prevent the error of trying to run a multi-processor job on the master.

- virtual int `total_eval_counter` () const
Return the total evaluation count from the interface.
- virtual int `new_eval_counter` () const
Return the new (non-duplicate) evaluation count from the interface.
- void `compute_response` ()
Compute the *Response* at `currentVariables` (default `asv`).
- void `compute_response` (const `IntArray` &`asv`)
Compute the *Response* at `currentVariables` (specified `asv`).
- void `asynch_compute_response` ()
Spawn an asynchronous job (or jobs) that computes the value of the *Response* at `currentVariables` (default `asv`).
- void `asynch_compute_response` (const `IntArray` &`asv`)
Spawn an asynchronous job (or jobs) that computes the value of the *Response* at `currentVariables` (specified `asv`).
- const `ResponseArray` & `synchronize` ()
Execute a blocking scheduling algorithm to collect the complete set of results from a group of asynchronous evaluations.
- const `ResponseList` & `synchronize_nowait` ()
Execute a nonblocking scheduling algorithm to collect all available results from a group of asynchronous evaluations.
- void `init_communicators` (const int &`max_iterator_concurrency`)
allocate communicator partitions for a model
- void `init_serial` ()
for cases where `init_communicators()` will not be called, modify some default settings to behave properly in serial.
- void `estimate_message_lengths` ()
estimate `messageLengths` for a model
- size_t `tv` () const
return total number of vars
- size_t `cv` () const
return number of active continuous variables
- size_t `dv` () const
return number of active discrete variables

- `size_t num_functions () const`
return number of functions in currentResponse
- `void active_variables (const Variables &vars)`
set the active variables in currentVariables
- `const RealVector & continuous_variables () const`
return the active continuous variables from currentVariables
- `void continuous_variables (const RealVector &c_vars)`
set the active continuous variables in currentVariables
- `const IntVector & discrete_variables () const`
return the active discrete variables from currentVariables
- `void discrete_variables (const IntVector &d_vars)`
set the active discrete variables in currentVariables
- `const RealVector & inactive_continuous_variables () const`
return the inactive continuous variables in currentVariables
- `void inactive_continuous_variables (const RealVector &i_c_vars)`
set the inactive continuous variables in currentVariables
- `const IntVector & inactive_discrete_variables () const`
return the inactive discrete variables in currentVariables
- `void inactive_discrete_variables (const IntVector &i_d_vars)`
set the inactive discrete variables in currentVariables
- `const RealVector & normal_means () const`
return the normal uncertain variable means
- `void normal_means (const RealVector &n_means)`
set the normal uncertain variable means
- `const RealVector & normal_std_deviations () const`
return the normal uncertain variable standard deviations
- `void normal_std_deviations (const RealVector &n_std_devs)`
set the normal uncertain variable standard deviations
- `const RealVector & normal_dist_lower_bounds () const`
return the normal uncertain variable distribution lower bounds
- `void normal_dist_lower_bounds (const RealVector &n_dist_lower_bnds)`
set the normal uncertain variable distribution lower bounds
- `const RealVector & normal_dist_upper_bounds () const`
return the normal uncertain variable distribution upper bounds

- void `normal_dist_upper_bounds` (const `RealVector` &n_dist_upper_bnds)
set the normal uncertain variable distribution upper bounds
- const `RealVector` & `lognormal_means` () const
return the lognormal uncertain variable means
- void `lognormal_means` (const `RealVector` &ln_means)
set the lognormal uncertain variable means
- const `RealVector` & `lognormal_std_deviations` () const
return the lognormal uncertain variable standard deviations
- void `lognormal_std_deviations` (const `RealVector` &ln_std_devs)
set the lognormal uncertain variable standard deviations
- const `RealVector` & `lognormal_error_factors` () const
return the lognormal uncertain variable error factors
- void `lognormal_error_factors` (const `RealVector` &ln_err_facts)
set the lognormal uncertain variable error factors
- const `RealVector` & `lognormal_dist_lower_bounds` () const
return the lognormal uncertain variable distribution lower bounds
- void `lognormal_dist_lower_bounds` (const `RealVector` &ln_dist_lower_bnds)
set the lognormal uncertain variable distribution lower bounds
- const `RealVector` & `lognormal_dist_upper_bounds` () const
return the lognormal uncertain variable distribution upper bounds
- void `lognormal_dist_upper_bounds` (const `RealVector` &ln_dist_upper_bnds)
set the lognormal uncertain variable distribution upper bounds
- const `RealVector` & `uniform_dist_lower_bounds` () const
return the uniform uncertain variable distribution lower bounds
- void `uniform_dist_lower_bounds` (const `RealVector` &u_dist_lower_bnds)
set the uniform uncertain variable distribution lower bounds
- const `RealVector` & `uniform_dist_upper_bounds` () const
return the uniform uncertain variable distribution upper bounds
- void `uniform_dist_upper_bounds` (const `RealVector` &u_dist_upper_bnds)
set the uniform uncertain variable distribution upper bounds
- const `RealVector` & `loguniform_dist_lower_bounds` () const
return the loguniform uncertain variable distribution lower bounds
- void `loguniform_dist_lower_bounds` (const `RealVector` &lu_dist_lower_bnds)

set the loguniform uncertain variable distribution lower bounds

- `const RealVector & loguniform_dist_upper_bounds () const`
return the loguniform uncertain variable distribution upper bounds
- `void loguniform_dist_upper_bounds (const RealVector &lu_dist_upper_bnds)`
set the loguniform uncertain variable distribution upper bounds
- `const RealVector & weibull_alphas () const`
return the weibull uncertain variable alpha parameters
- `void weibull_alphas (const RealVector &alphas)`
set the weibull uncertain variable alpha parameters
- `const RealVector & weibull_betas () const`
return the weibull uncertain variable beta parameters
- `void weibull_betas (const RealVector &betas)`
set the weibull uncertain variable beta parameters
- `const RealVector & weibull_dist_lower_bounds () const`
return the weibull uncertain variable distribution lower bounds
- `void weibull_dist_lower_bounds (const RealVector &w_dist_lower_bnds)`
set the weibull uncertain variable distribution lower bounds
- `const RealVector & weibull_dist_upper_bounds () const`
return the weibull uncertain variable distribution upper bounds
- `void weibull_dist_upper_bounds (const RealVector &w_dist_upper_bnds)`
set the weibull uncertain variable distribution upper bounds
- `const RealVectorArray & histogram_bin_pairs () const`
return the histogram uncertain bin pairs
- `void histogram_bin_pairs (const RealVectorArray &h_bin_pairs)`
set the histogram uncertain bin pairs
- `const RealVectorArray & histogram_point_pairs () const`
return the histogram uncertain point pairs
- `void histogram_point_pairs (const RealVectorArray &h_pt_pairs)`
set the histogram uncertain point pairs
- `const StringArray & continuous_variable_types () const`
return the active continuous variable types from currentVariables
- `const StringArray & discrete_variable_types () const`
return the active discrete variable types from currentVariables

- `const StringArray & continuous_variable_labels () const`
return the active continuous variable labels from currentVariables
- `void continuous_variable_labels (const StringArray &c_v_labels)`
set the active continuous variable labels in currentVariables
- `const StringArray & discrete_variable_labels () const`
return the active discrete variable labels from currentVariables
- `void discrete_variable_labels (const StringArray &d_v_labels)`
set the active discrete variable labels in currentVariables
- `const StringArray & inactive_continuous_variable_labels () const`
return the inactive continuous variable labels in currentVariables
- `void inactive_continuous_variable_labels (const StringArray &i_c_v_labels)`
set the inactive continuous variable labels in currentVariables
- `const StringArray & inactive_discrete_variable_labels () const`
return the inactive discrete variable labels in currentVariables
- `void inactive_discrete_variable_labels (const StringArray &i_d_v_labels)`
set the inactive discrete variable labels in currentVariables
- `const RealVector & continuous_lower_bounds () const`
return the active continuous variable lower bounds from userDefinedVarConstraints
- `void continuous_lower_bounds (const RealVector &c_l_bnds)`
set the active continuous variable lower bounds in userDefinedVarConstraints
- `const RealVector & continuous_upper_bounds () const`
return the active continuous variable upper bounds from userDefinedVarConstraints
- `void continuous_upper_bounds (const RealVector &c_u_bnds)`
set the active continuous variable upper bounds in userDefinedVarConstraints
- `const IntVector & discrete_lower_bounds () const`
return the active discrete variable lower bounds from userDefinedVarConstraints
- `void discrete_lower_bounds (const IntVector &d_l_bnds)`
set the active discrete variable lower bounds in userDefinedVarConstraints
- `const IntVector & discrete_upper_bounds () const`
return the active discrete variable upper bounds from userDefinedVarConstraints
- `void discrete_upper_bounds (const IntVector &d_u_bnds)`
set the active discrete variable upper bounds in userDefinedVarConstraints
- `const RealVector & inactive_continuous_lower_bounds () const`
return the inactive continuous lower bounds in userDefinedVarConstraints

- void `inactive_continuous_lower_bounds` (const `RealVector` &`i_c_l_bnds`)
set the inactive continuous lower bounds in userDefinedVarConstraints
- const `RealVector` & `inactive_continuous_upper_bounds` () const
return the inactive continuous upper bounds in userDefinedVarConstraints
- void `inactive_continuous_upper_bounds` (const `RealVector` &`i_c_u_bnds`)
set the inactive continuous upper bounds in userDefinedVarConstraints
- const `IntVector` & `inactive_discrete_lower_bounds` () const
return the inactive discrete lower bounds in userDefinedVarConstraints
- void `inactive_discrete_lower_bounds` (const `IntVector` &`i_d_l_bnds`)
set the inactive discrete lower bounds in userDefinedVarConstraints
- const `IntVector` & `inactive_discrete_upper_bounds` () const
return the inactive discrete upper bounds in userDefinedVarConstraints
- void `inactive_discrete_upper_bounds` (const `IntVector` &`i_d_u_bnds`)
set the inactive discrete upper bounds in userDefinedVarConstraints
- size_t `num_linear_ineq_constraints` () const
return the number of linear inequality constraints
- size_t `num_linear_eq_constraints` () const
return the number of linear equality constraints
- const `RealMatrix` & `linear_ineq_constraint_coeffs` () const
return the linear inequality constraint coefficients
- const `RealVector` & `linear_ineq_constraint_lower_bounds` () const
return the linear inequality constraint lower bounds
- const `RealVector` & `linear_ineq_constraint_upper_bounds` () const
return the linear inequality constraint upper bounds
- const `RealMatrix` & `linear_eq_constraint_coeffs` () const
return the linear equality constraint coefficients
- const `RealVector` & `linear_eq_constraint_targets` () const
return the linear equality constraint targets
- const `IntList` & `merged_integer_list` () const
return the list of discrete variables merged into a continuous array in currentVariables
- const `IntArray` & `message_lengths` () const
return the array of MPI packed message buffer lengths (messageLengths)
- const `Variables` & `current_variables` () const

return the current variables (currentVariables)

- const [Response](#) & [current_response](#) () const
return the current response (currentResponse)
- const [ProblemDescDB](#) & [prob_desc_db](#) () const
return the problem description database (probDescDB)
- const [String](#) & [model_type](#) () const
return the model type (modelType)
- bool [asynch_flag](#) () const
return the asynchronous evaluation flag (asynchEvalFlag)
- void [asynch_flag](#) (const bool flag)
set the asynchronous evaluation flag (asynchEvalFlag)
- void [auto_graphics](#) (const bool flag)
set modelAutoGraphicsFlag to activate posting of graphics data within compute_response/synchronize functions (automatic graphics posting in the model as opposed to graphics posting at the strategy level).
- const [String](#) & [gradient_method](#) () const
return the gradient evaluation method (gradType)
- const [String](#) & [hessian_method](#) () const
return the Hessian evaluation method (hessType)
- const int & [evaluation_capacity](#) () const
return the evaluation capacity for use in iterator logic
- int [derivative_concurrency](#) () const
return the gradient concurrency for use in parallel configuration logic
- void [parallel_configuration_iterator](#) (const [ParConfigLIter](#) &pc_iter)
set modelPCIter
- const [ParConfigLIter](#) & [parallel_configuration_iterator](#) () const
return modelPCIter
- bool [is_null](#) () const
function to check modelRep (does this envelope contain a letter)

Protected Member Functions

- [Model](#) ([BaseConstructor](#), [ProblemDescDB](#) &problem_db)
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- virtual void [derived_compute_response](#) (const [IntArray](#) &asv)

portion of `compute_response()` specific to derived model classes

- virtual void `derived_asynch_compute_response` (const `IntArray` &asv)
portion of `asynch_compute_response()` specific to derived model classes
- virtual const `ResponseArray` & `derived_synchronize` ()
portion of `synchronize()` specific to derived model classes
- virtual const `ResponseList` & `derived_synchronize_nowait` ()
portion of `synchronize_nowait()` specific to derived model classes
- virtual void `derived_init_communicators` (const int &max_iterator_concurrency)
portion of `init_communicators()` specific to derived model classes
- virtual void `derived_init_serial` ()
portion of `init_serial()` specific to derived model classes

Protected Attributes

- `Variables` `currentVariables`
the set of current variables used by the model for performing function evaluations
- `size_t` `numGradVars`
the number of active continuous variables (used in the finite difference routines)
- `Response` `currentResponse`
the set of current responses that holds the results of model function evaluations
- `size_t` `numFns`
the number of functions in `currentResponse`
- `VarConstraints` `userDefinedVarConstraints`
Explicit constraints on variables are maintained in the `VarConstraints` class hierarchy. Currently, this includes linear constraints and bounds, but could be extended in the future to include other explicit constraints which (1) have their form specified by the user, and (2) are not catalogued in `Response` since their form and coefficients are published to an iterator at startup.
- `IntArray` `messageLengths`
length of packed MPI buffers containing vars, vars/asv, response, and PRPair
- const `ProblemDescDB` & `probDescDB`
class member reference to the problem description database. This reference is a const copy of the incoming `problem_db` non-const reference and is only used in `Model::prob_desc_db()` (it is not inherited).
- `ParallelLibrary` & `parallelLib`
class member reference to the parallel library
- `ParConfigLIter` `modelPCIter`
the `ParallelConfiguration` node used by this model instance

- int `componentParallelMode`
the component parallelism mode: 0 (none), INTERFACE, or SUBMODEL

Private Member Functions

- `Model * get_model (ProblemDescDB &problem_db)`
Used by the envelope to instantiate the correct letter class.
- `size_t estimate_derivatives (const IntArray &map_asv, const IntArray &fd_grad_asv, const IntArray &fd_hess_asv, const IntArray &quasi_hess_asv, const IntArray &original_asv, const bool asynch_flag)`
evaluate numerical gradients using finite differences. This routine is selected with "method_source dakota" (the default method_source) in the numerical gradient specification.
- `void synchronize_derivatives (const Variables &vars, const ResponseArray &fd_responses, Response &new_response, const IntArray &fd_grad_asv, const IntArray &fd_hess_asv, const IntArray &quasi_hess_asv, const IntArray &original_asv)`
combine results from an array of finite difference response objects (fd_grad_responses) into a single response (new_response)
- `void update_response (const Variables &vars, Response &new_response, const IntArray &fd_grad_asv, const IntArray &fd_hess_asv, const IntArray &quasi_hess_asv, const IntArray &original_asv, Response &initial_map_response, const RealMatrix &new_fn_grads, const RealMatrixArray &new_fn_hessians)`
overlay results to update a response object
- `void update_quasi_hessians (const Variables &vars, Response &new_response, const IntArray &original_asv)`
perform quasi-Newton Hessian updates
- `void manage_asv (const IntArray &asv_in, IntArray &map_asv_out, IntArray &fd_grad_asv_out, IntArray &fd_hess_asv_out, IntArray &quasi_hess_asv_out, bool &use_est_deriv)`
Coordinates usage of estimate_derivatives() calls based on asv_in.

Private Attributes

- `Model * modelRep`
pointer to the letter (initialized only for the envelope)
- int `referenceCount`
number of objects sharing modelRep
- `String modelType`
type of model: single, nested, or layered
- bool `asynchFDFlag`
flags use of estimate_derivatives w/i asynch_compute_response

- **bool** `asynchEvalFlag`
flags asynch evaluations (local or distributed)
- **int** `evaluationCapacity`
capacity for concurrent evaluations supported by the `Model`
- **bool** `modelAutoGraphicsFlag`
flag for posting of graphics data within `compute_response` (automatic graphics posting in the model as opposed to graphics posting at the strategy level)
- **bool** `silentFlag`
flag for really quiet (silent) model output
- **bool** `quietFlag`
flag for quiet model output
- **VariablesList** `varsList`
history of vars populated in `asynch_compute_response()` and used in `synchronize()`.
- **List< IntArray >** `asvList`
if `asynchFDFlag` is set, transfers asv sets to synchronize
- **BoolList** `initialMapList`
transfers initial_map flag values from `estimate_derivatives` to `synchronize_derivatives`
- **BoolList** `dbCaptureList`
transfers db_capture flag values from `estimate_derivatives` to `synchronize_derivatives`
- **ResponseList** `dbResponseList`
transfers database captures from `estimate_derivatives` to `synchronize_derivatives`
- **RealList** `deltaList`
transfers deltas from `estimate_derivatives` to `synchronize_derivatives`
- **SizetList** `numMapsList`
tracks the number of maps used in `estimate_derivatives()`. Used in `synchronize()` as a key for combining finite difference responses into numerical gradients.
- **RealMatrix** `xPrev`
previous parameter vectors used in computing `s` for quasi-Newton updates
- **RealMatrix** `fnGradsPrev`
previous gradient vectors used in computing `y` for quasi-Newton updates
- **RealMatrixArray** `quasiHessians`
quasi-Newton Hessian approximations
- **SizetArray** `numQuasiUpdates`
number of quasi-Newton Hessian updates applied

- [ResponseArray responseArray](#)
used to return an array of responses for asynchronous evaluations. This array has the responses in final concatenated form. The similar array in [Interface](#) contains the raw responses.
- [ResponseList responseList](#)
used to return a list of responses for asynchronous evaluations. This list has the responses in final concatenated form. The similar list in [Interface](#) contains the raw responses.
- [String gradType](#)
grad type: none,numerical,analytic,mixed
- [String methodSrc](#)
method source: dakota,vendor
- [String intervalType](#)
interval type: forward,central
- [RealVector fdGradSS](#)
relative step sizes for numerical gradients
- [IntList gradIdAnalytic](#)
analytic id's for mixed gradients
- [IntList gradIdNumerical](#)
numerical id's for mixed gradients
- [String hessType](#)
Hess type: none,numerical,quasi,analytic,mixed.
- [String quasiHessType](#)
quasi-Hessian type: bfgs, damped_bfgs, sr1
- [RealVector fdHessByGradSS](#)
relative step sizes for numerical Hessians estimated with 1st-order grad differences
- [RealVector fdHessByFnSS](#)
relative step sizes for numerical Hessians estimated with 2nd-order fn differences
- [IntList hessIdAnalytic](#)
analytic id's for mixed Hessians
- [IntList hessIdNumerical](#)
numerical id's for mixed Hessians
- [IntList hessIdQuasi](#)
quasi id's for mixed Hessians
- [RealVector normalMeans](#)
normal uncertain variable means

- [RealVector normalStdDevs](#)
normal uncertain variable standard deviations
- [RealVector normalDistLowerBnds](#)
normal uncertain variable distribution lower bounds
- [RealVector normalDistUpperBnds](#)
normal uncertain variable distribution upper bounds
- [RealVector lognormalMeans](#)
lognormal uncertain variable means
- [RealVector lognormalStdDevs](#)
lognormal uncertain variable standard deviations
- [RealVector lognormalErrFacts](#)
lognormal uncertain variable error factors
- [RealVector lognormalDistLowerBnds](#)
lognormal uncertain variable distribution lower bounds
- [RealVector lognormalDistUpperBnds](#)
lognormal uncertain variable distribution upper bounds
- [RealVector uniformDistLowerBnds](#)
uniform uncertain variable distribution lower bounds
- [RealVector uniformDistUpperBnds](#)
uniform uncertain variable distribution upper bounds
- [RealVector loguniformDistLowerBnds](#)
loguniform uncertain variable distribution lower bounds
- [RealVector loguniformDistUpperBnds](#)
loguniform uncertain variable distribution upper bounds
- [RealVector weibullAlphas](#)
weibull uncertain variable alphas
- [RealVector weibullBetas](#)
weibull uncertain variable betas
- [RealVector weibullDistLowerBnds](#)
weibull uncertain variable distribution lower bounds
- [RealVector weibullDistUpperBnds](#)
weibull uncertain variable distribution upper bounds
- [RealVectorArray histogramBinPairs](#)

histogram uncertain (x,y) bin pairs (continuous linear histogram)

- [RealVectorArray histogramPointPairs](#)

histogram uncertain (x,y) point pairs (discrete histogram)

8.59.1 Detailed Description

Base class for the model class hierarchy.

The [Model](#) class is the base class for one of the primary class hierarchies in DAKOTA. The model hierarchy contains a set of variables, an interface, and a set of responses, and an iterator operates on the model to map the variables into responses using the interface. For memory efficiency and enhanced polymorphism, the model hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Model](#)) serves as the envelope and one of the derived classes (selected in [Model::get_model\(\)](#)) serves as the letter.

8.59.2 Constructor & Destructor Documentation

8.59.2.1 [Model](#) ()

default constructor

The default constructor is used in `vector<Model>` instantiations and for initialization of [Model](#) objects contained in [Iterator](#) and derived [Strategy](#) classes. `modelRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful [Model](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

8.59.2.2 [Model](#) ([ProblemDescDB](#) & *problem_db*)

standard constructor for envelope

Used in model instantiations within strategy constructors. Envelope constructor only needs to extract enough data to properly execute `get_model`, since `Model(BaseConstructor, problem_db)` builds the actual base class data for the derived models.

8.59.2.3 [Model](#) (const [Model](#) & *model*)

copy constructor

Copy constructor manages sharing of `modelRep` and incrementing of `referenceCount`.

8.59.2.4 [~Model](#) () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `modelRep` when `referenceCount` reaches zero.

8.59.2.5 Model (BaseConstructor, ProblemDescDB & problem_db) [protected]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor builds the base class data for all inherited models. [get_model\(\)](#) instantiates a derived class and the derived class selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling [get_model\(\)](#) again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Model`).

8.59.3 Member Function Documentation**8.59.3.1 Model operator= (const Model & model)**

assignment operator

Assignment operator decrements referenceCount for old modelRep, assigns new modelRep, and increments referenceCount for new modelRep.

8.59.3.2 String local_eval_synchronization () [virtual]

return derived model synchronization setting

SingleModels and HierLayeredModels redefine this virtual function. A default value of "synchronous" prevents asynch local operations for:

- NestedModels: a subIterator can support message passing parallelism, but not asynch local.
- SurrLayeredModels: while asynch evals on approximations will work due to some added bookkeeping, avoiding them is preferable.

Reimplemented in [HierLayeredModel](#), and [SingleModel](#).

8.59.3.3 int local_eval_concurrency () [virtual]

return derived model asynchronous evaluation concurrency

SingleModels and HierLayeredModels redefine this virtual function.

Reimplemented in [HierLayeredModel](#), and [SingleModel](#).

8.59.3.4 void init_communicators (const int & max_iterator_concurrency)

allocate communicator partitions for a model

The [init_communicators\(\)](#) and [derived_init_communicators\(\)](#) functions are structured to avoid performing the messageLengths estimation more than once. [init_communicators\(\)](#) (not virtual) performs the estimation and then forwards the results to [derived_init_communicators](#) (virtual) which uses the data in different contexts.

8.59.3.5 void `init_serial()`

for cases where `init_communicators()` will not be called, modify some default settings to behave properly in serial.

The `init_serial()` and `derived_init_serial()` functions are structured to separate base class (common) operations from derived class (specialized) operations.

8.59.3.6 void `estimate_message_lengths()`

estimate `messageLengths` for a model

This functionality has been pulled out of `init_communicators()` and defined separately so that it may be used in those cases when `messageLengths` is needed but `model.init_communicators()` is not called, e.g., for the master processor in the self-scheduling of a concurrent iterator strategy.

8.59.3.7 `Model * get_model (ProblemDescDB & problem_db)` [private]

Used by the envelope to instantiate the correct letter class.

Used only by the envelope constructor to initialize `modelRep` to the appropriate derived type, as given by the `modelType` attribute.

8.59.3.8 `size_t estimate_derivatives (const IntArray & map_asv, const IntArray & fd_grad_asv, const IntArray & fd_hess_asv, const IntArray & quasi_hess_asv, const IntArray & original_asv, const bool asynch_flag)` [private]

evaluate numerical gradients using finite differences. This routine is selected with "method_source dakota" (the default `method_source`) in the numerical gradient specification.

Estimate derivatives by computing finite difference gradients, finite difference Hessians, and/or quasi-Newton Hessians. The total number of finite difference evaluations is returned for use by `synchronize()` to track response arrays, and it could be used to improve management of `max_function_evaluations` within the iterators.

8.59.3.9 void `synchronize_derivatives (const Variables & vars, const ResponseArray & fd_responses, Response & new_response, const IntArray & fd_grad_asv, const IntArray & fd_hess_asv, const IntArray & quasi_hess_asv, const IntArray & original_asv)` [private]

combine results from an array of finite difference response objects (`fd_grad_responses`) into a single response (`new_response`)

Merge an array of `fd_responses` into a single `new_response`. This function is used both by synchronous `compute_response()` for the case of asynchronous `estimate_derivatives()` and by `synchronize()` for the case where one or more `asynch_compute_response()` calls has employed asynchronous `estimate_derivatives()`.

8.59.3.10 void `update_response (const Variables & vars, Response & new_response, const IntArray & fd_grad_asv, const IntArray & fd_hess_asv, const IntArray & quasi_hess_asv, const IntArray & original_asv, Response & initial_map_response, const RealMatrix & new_fn_grads, const RealMatrixArray & new_fn_hessians)` [private]

overlay results to update a response object

Overlay the `initial_map_response` with numerically estimated `new_fn_grads` and `new_fn_hessians` to populate `new_response` as governed by `asv` vectors. Quasi-Newton secant Hessian updates are also performed here, since this is where the gradient data needed for the updates is first consolidated. Convenience function used by `estimate_derivatives()` for the synchronous case and by `synchronize_derivatives()` for the asynchronous case.

8.59.3.11 `void manage_asv (const IntArray & asv_in, IntArray & map_asv_out, IntArray & fd_grad_asv_out, IntArray & fd_hess_asv_out, IntArray & quasi_hess_asv_out, bool & use_est_deriv) [private]`

Coordinates usage of `estimate_derivatives()` calls based on `asv_in`.

Splits `asv_in` total request into `map_asv_out`, `fd_grad_asv_out`, `fd_hess_asv_out`, and `quasi_hess_asv_out` as governed by the responses specification. If `use_est_deriv` is set, then these `asv` outputs are used by `estimate_derivatives()` for the initial map, finite difference gradient evals, finite difference Hessian evals, and quasi-Hessian updates, respectively. If `use_est_deriv` is not set, then only `map_asv_out` is used.

The documentation for this class was generated from the following files:

- `DakotaModel.H`
- `DakotaModel.C`

8.60 MPIPackBuffer Class Reference

Class for packing MPI message buffers.

Public Member Functions

- [MPIPackBuffer](#) (int size_=1024)
Constructor, which allows the default buffer size to be set.
- [~MPIPackBuffer](#) ()
Destructor.
- const char * [buf](#) ()
Returns a pointer to the internal buffer that has been packed.
- int [size](#) ()
The number of bytes of packed data.
- int [capacity](#) ()
the allocated size of Buffer.
- void [reset](#) ()
Resets the buffer index in order to reuse the internal buffer.
- void [pack](#) (const int *data, const int num=1)
*Pack one or more **int**'s.*
- void [pack](#) (const u_int *data, const int num=1)
*Pack one or more **unsigned int**'s.*
- void [pack](#) (const long *data, const int num=1)
*Pack one or more **long**'s.*
- void [pack](#) (const u_long *data, const int num=1)
*Pack one or more **unsigned long**'s.*
- void [pack](#) (const short *data, const int num=1)
*Pack one or more **short**'s.*
- void [pack](#) (const u_short *data, const int num=1)
*Pack one or more **unsigned short**'s.*
- void [pack](#) (const char *data, const int num=1)
*Pack one or more **char**'s.*
- void [pack](#) (const u_char *data, const int num=1)

*Pack one or more **unsigned char**'s.*

- void `pack` (const double *data, const int num=1)
*Pack one or more **double**'s.*
- void `pack` (const float *data, const int num=1)
*Pack one or more **fbat**'s.*
- void `pack` (const bool *data, const int num=1)
*Pack one or more **bool**'s.*
- void `pack` (const int &data)
*Pack a **int**.*
- void `pack` (const u_int &data)
*Pack a **unsigned int**.*
- void `pack` (const long &data)
*Pack a **long**.*
- void `pack` (const u_long &data)
*Pack a **unsigned long**.*
- void `pack` (const short &data)
*Pack a **short**.*
- void `pack` (const u_short &data)
*Pack a **unsigned short**.*
- void `pack` (const char &data)
*Pack a **char**.*
- void `pack` (const u_char &data)
*Pack a **unsigned char**.*
- void `pack` (const double &data)
*Pack a **double**.*
- void `pack` (const float &data)
*Pack a **fbat**.*
- void `pack` (const bool &data)
*Pack a **bool**.*

Protected Member Functions

- void `resize` (const int newsize)
Resizes the internal buffer.

Protected Attributes

- char * [Buffer](#)
The internal buffer for packing.
- int [Index](#)
The index into the current buffer.
- int [Size](#)
The total size that has been allocated for the buffer.

8.60.1 Detailed Description

Class for packing MPI message buffers.

A class that provides a facility for packing message buffers using the MPI_Pack facility. The [MPIPackBuffer](#) class dynamically resizes the internal buffer to contain enough memory to pack the entire object. When deleted, the [MPIPackBuffer](#) object deletes this internal buffer. This class is based on the Dakota_Version_3_0 version of utilib::PackBuffer from utilib/src/io/PackBuf.[cpp,h]

The documentation for this class was generated from the following files:

- MPIPackBuffer.H
- MPIPackBuffer.C

8.61 MPIUnpackBuffer Class Reference

Class for unpacking MPI message buffers.

Public Member Functions

- void [setup](#) (char *buf_, int size_, bool flag_=false)
Method that does the setup for the constructors.
- [MPIUnpackBuffer](#) ()
Default constructor.
- [MPIUnpackBuffer](#) (int size_)
Constructor that specifies the size of the buffer.
- [MPIUnpackBuffer](#) (char *buf_, int size_, bool flag_=false)
Constructor that sets the internal buffer to the given array.
- [~MPIUnpackBuffer](#) ()
Destructor.
- void [resize](#) (const int newsize)
Resizes the internal buffer.
- const char * [buf](#) ()
Returns a pointer to the internal buffer.
- int [size](#) ()
Returns the length of the buffer.
- int [curr](#) ()
Returns the number of bytes that have been unpacked from the buffer.
- void [reset](#) ()
Resets the index of the internal buffer.
- void [unpack](#) (int *data, const int num=1)
*Unpack one or more **int**'s.*
- void [unpack](#) (u_int *data, const int num=1)
*Unpack one or more **unsigned int**'s.*
- void [unpack](#) (long *data, const int num=1)
*Unpack one or more **long**'s.*
- void [unpack](#) (u_long *data, const int num=1)

*Unpack one or more **unsigned long**'s.*

- void `unpack` (short *data, const int num=1)
*Unpack one or more **short**'s.*
- void `unpack` (u_short *data, const int num=1)
*Unpack one or more **unsigned short**'s.*
- void `unpack` (char *data, const int num=1)
*Unpack one or more **char**'s.*
- void `unpack` (u_char *data, const int num=1)
*Unpack one or more **unsigned char**'s.*
- void `unpack` (double *data, const int num=1)
*Unpack one or more **double**'s.*
- void `unpack` (float *data, const int num=1)
*Unpack one or more **float**'s.*
- void `unpack` (bool *data, const int num=1)
*Unpack one or more **bool**'s.*
- void `unpack` (int &data)
*Unpack a **int**.*
- void `unpack` (u_int &data)
*Unpack a **unsigned int**.*
- void `unpack` (long &data)
*Unpack a **long**.*
- void `unpack` (u_long &data)
*Unpack a **unsigned long**.*
- void `unpack` (short &data)
*Unpack a **short**.*
- void `unpack` (u_short &data)
*Unpack a **unsigned short**.*
- void `unpack` (char &data)
*Unpack a **char**.*
- void `unpack` (u_char &data)
*Unpack a **unsigned char**.*
- void `unpack` (double &data)
*Unpack a **double**.*

- void `unpack` (float &data)
*Unpack a **float**.*
- void `unpack` (bool &data)
*Unpack a **bool**.*

Protected Attributes

- char * `Buffer`
The internal buffer for unpacking.
- int `Index`
The index into the current buffer.
- int `Size`
The total size that has been allocated for the buffer.
- bool `ownFlag`
If `TRUE`, then this class owns the internal buffer.

8.61.1 Detailed Description

Class for unpacking MPI message buffers.

A class that provides a facility for unpacking message buffers using the `MPI_Unpack` facility. This class is based on the `Dakota_Version_3_0` version of `utilib::UnPackBuffer` from `utilib/src/io/PackBuf.[cpp,h]`

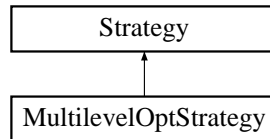
The documentation for this class was generated from the following files:

- `MPIPackBuffer.H`
- `MPIPackBuffer.C`

8.62 MultilevelOptStrategy Class Reference

[Strategy](#) for hybrid optimization using multiple optimizers on multiple models of varying fidelity.

Inheritance diagram for MultilevelOptStrategy::



Public Member Functions

- [MultilevelOptStrategy](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~MultilevelOptStrategy](#) ()
destructor
- void [run_strategy](#) ()
Performs the hybrid optimization strategy by executing multiple iterators on different models of varying fidelity.
- const [Variables](#) & [strategy_variable_results](#) () const
return the final solution from selectedIterators (variables)
- const [Response](#) & [strategy_response_results](#) () const
return the final solution from selectedIterators (response)
- [IteratorList](#) & [iterators](#) (bool recurse_flag=true)
returns selectedIterators and any subordinate iterators
- [ModelList](#) & [models](#) (bool recurse_flag=true)
returns userDefinedModels and any subordinate models

Private Member Functions

- void [run_coupled](#) ()
run a tightly coupled hybrid
- void [run_uncoupled](#) ()
run an uncoupled hybrid
- void [run_uncoupled_adaptive](#) ()
run an uncoupled adaptive hybrid

Private Attributes

- [String multiLevelType](#)
coupled, uncoupled, or uncoupled_adaptive
- [StringArray methodList](#)
the list of method identifiers
- [int numIterators](#)
number of methods in methodList
- [Real localSearchProb](#)
the probability of running a local search refinement within phases of the global optimization for coupled hybrids
- [Real progressMetric](#)
the amount of progress made in a single iterator++ cycle within an uncoupled adaptive hybrid
- [Real progressThreshold](#)
when the progress metric falls below this threshold, the uncoupled adaptive hybrid switches to the next method
- [IteratorArray selectedIterators](#)
the set of iterators, one for each entry in methodList
- [ModelArray userDefinedModels](#)
the set of models, one for each iterator

8.62.1 Detailed Description

[Strategy](#) for hybrid optimization using multiple optimizers on multiple models of varying fidelity.

This strategy has three approaches to hybrid optimization: (1) the uncoupled hybrid runs one method to completion, passes its best results as the starting point for a subsequent method, and continues this succession until all methods have been executed; (2) the uncoupled adaptive hybrid is similar to the uncoupled hybrid, except that the stopping rules for the optimizers are controlled adaptively by the strategy instead of internally by each optimizer; and (3) the coupled hybrid uses multiple methods in close coordination, generally using a local search optimizer repeatedly within a global optimizer (the local search optimizer refines candidate optima which are fed back to the global optimizer). The uncoupled strategies only pass information forward, whereas the coupled strategy allows both feed forward and feedback. Note that while the strategy is targeted at optimizers, any iterator may be used so long as it defines the notion of a final solution which can be passed as the starting point for subsequent iterators.

8.62.2 Member Function Documentation

8.62.2.1 void run_coupled () [private]

run a tightly coupled hybrid

In the coupled case, use is made of external hybridization capabilities, such as those available in the global/local hybrids from SGOPT. This function is responsible only for publishing the local optimizer selection to the global optimizer and then invoking the global optimizer; the logic of method switching is handled entirely within the global optimizer. Status: incomplete.

8.62.2.2 void run_uncoupled () [private]

run an uncoupled hybrid

In the uncoupled nonadaptive case, there is no interference with the iterators. Each runs until its own convergence criteria is satisfied (using `iterator.run_iterator()`). Status: fully operational.

8.62.2.3 void run_uncoupled_adaptive () [private]

run an uncoupled adaptive hybrid

In the uncoupled adaptive case, there is interference with the iterators through the use of the ++ overloaded operator. `iterator++` runs the iterator for one cycle, after which a `progress_metric` is computed. This progress metric is used to dictate method switching instead of each iterator's internal convergence criteria. Status: incomplete.

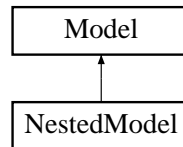
The documentation for this class was generated from the following files:

- MultilevelOptStrategy.H
- MultilevelOptStrategy.C

8.63 NestedModel Class Reference

Derived model class which performs a complete sub-iterator execution within every evaluation of the model.

Inheritance diagram for NestedModel::



Public Member Functions

- [NestedModel \(ProblemDescDB &problem_db\)](#)
constructor
- [~NestedModel \(\)](#)
destructor

Protected Member Functions

- void [derived_compute_response](#) (const [IntArray](#) &asv)
portion of [compute_response\(\)](#) specific to [NestedModel](#)
- void [derived_async_compute_response](#) (const [IntArray](#) &asv)
portion of [async_compute_response\(\)](#) specific to [NestedModel](#)
- const [ResponseArray](#) & [derived_synchronize](#) ()
portion of [synchronize\(\)](#) specific to [NestedModel](#)
- const [ResponseList](#) & [derived_synchronize_nowait](#) ()
portion of [synchronize_nowait\(\)](#) specific to [NestedModel](#)
- const [IntList](#) & [synchronize_nowait_completions](#) ()
Return completion id's matching response list from [synchronize_nowait](#).
- [Model](#) [subordinate_model](#) ()
return subModel
- [Iterator](#) [subordinate_iterator](#) ()
return subIterator
- [Interface](#) & [interface](#) ()

return optionalInterface

- void [layering_bypass](#) (bool bypass_flag)
NestedModels have nothing to bypass, but must pass request on to the subModel for any lower-level layerings.
- void [component_parallel_mode](#) (int mode)
update component parallel mode for supporting parallelism in optionalInterface and subModel
- bool [derived_master_overload](#) () const
flag which prevents overloading the master with a multiprocessor evaluation (forwarded to optionalInterface)
- void [derived_init_communicators](#) (const int &max_iterator_concurrency)
set up optionalInterface and subModel for parallel operations
- void [derived_init_serial](#) ()
set up optionalInterface and subModel for serial operations.
- void [reset_communicators](#) ()
reset communicator partitions for the [NestedModel](#) (forwarded to optionalInterface and subModel)
- void [free_communicators](#) ()
deallocate communicator partitions for the [NestedModel](#) (forwarded to optionalInterface and subModel)
- void [serve](#) ()
Service optionalInterface and subModel job requests received from the master. Completes when a termination message is received from [stop_servers](#)().
- void [stop_servers](#) ()
Executed by the master to terminate server operations for subModel and optionalInterface when iteration on the [NestedModel](#) is complete.
- int [total_eval_counter](#) () const
Return the total evaluation count for the [NestedModel](#).
- int [new_eval_counter](#) () const
Return the new evaluation count for the [NestedModel](#).

Private Member Functions

- void [asv_mapping](#) (const [IntArray](#) &mapped_asv, [IntArray](#) &interface_asv, [IntArray](#) &sub_iterator_asv)
define the evaluation requirements for the optionalInterface (interface_asv) and the subIterator (sub_iterator_asv) from the total model evaluation requirements (mapped_asv)
- void [response_mapping](#) (const [Response](#) &interface_response, const [Response](#) &sub_iterator_response, [Response](#) &mapped_response)
combine the response from the optional interface evaluation with the response from the sub-iteration using the objLSqCoeffs/constrCoeffs mappings to create the total response for the model

- void [update_sub_model](#) ()
update subModel with current variable values/bounds/labels

Private Attributes

- int [nestedEvals](#)
number of calls to [derived_compute_response\(\)](#)
- [Iterator](#) [subIterator](#)
the sub-iterator that is executed on every evaluation of this model
- [Model](#) [subModel](#)
the sub-model used in sub-iterator evaluations
- size_t [numSubIterFns](#)
number of sub-iterator response functions prior to mapping
- size_t [numSubIterMappedIneqCon](#)
number of top-level inequality constraints mapped from the sub-iteration results
- size_t [numSubIterMappedEqCon](#)
number of top-level equality constraints mapped from the sub-iteration results
- [Interface](#) [optionalInterface](#)
the optional interface contributes nonnested response data to the total model response
- [String](#) [interfacePointer](#)
the optional interface pointer from the nested model specification
- [Response](#) [interfaceResponse](#)
the response object resulting from optional interface evaluations
- size_t [numInterfObjLSq](#)
number of objective functions/least squares terms resulting from optional interface evaluations
- size_t [numInterfIneqCon](#)
number of inequality constraints resulting from optional interface evaluations
- size_t [numInterfEqCon](#)
number of equality constraints resulting from the optional interface evaluations
- [IntArray](#) [primaryCVarMapIndices](#)
"primary" variable mappings for inserting active continuous currentVariables into active continuous sub-Model variables. If there are no secondary mappings defined, then the insertions replace the subModel variable values.
- [IntArray](#) [primaryDVarMapIndices](#)

"primary" variable mappings for inserting active discrete currentVariables into active discrete subModel variables. No secondary mappings are defined for discrete variables, so the insertions replace the subModel variable values.

- [IntArray secondaryVarMapIndices](#)
"secondary" variable mappings for inserting active continuous currentVariables into sub-parameters (e.g., distribution parameters for uncertain variables) of the active continuous subModel variables.
- [RealMatrix objLSqCoeffs](#)
"primary" response_mapping matrix applied to the sub-iterator response functions. For OUU, the matrix is applied to UQ statistics to create contributions to the top-level objective functions/least squares terms.
- [RealMatrix constrCoeffs](#)
"secondary" response_mapping matrix applied to the sub-iterator response functions. For OUU, the matrix is applied to UQ statistics to create contributions to the top-level inequality and equality constraints.
- [ResponseArray responseArray](#)
dummy response array for derived_synchronize() prior to derived_asynch_compute_response() support
- [ResponseList responseList](#)
dummy response list for derived_synchronize_nowait() prior to derived_asynch_compute_response() support
- [IntList completionList](#)
dummy completion list for synchronize_nowait_completions() prior to derived_asynch_compute_response() support

8.63.1 Detailed Description

Derived model class which performs a complete sub-iterator execution within every evaluation of the model.

The [NestedModel](#) class nests a sub-iterator execution within every model evaluation. This capability is most commonly used for optimization under uncertainty, in which a nondeterministic iterator is executed on every optimization function evaluation. The [NestedModel](#) also contains an optional interface, for portions of the model evaluation which are independent from the sub-iterator, and a set of mappings for combining sub-iterator and optional interface data into a top level response for the model.

8.63.2 Member Function Documentation

8.63.2.1 void derived_compute_response (const [IntArray](#) & asv) [protected, virtual]

portion of [compute_response\(\)](#) specific to [NestedModel](#)

Update subModel's inactive variables with active variables from currentVariables, compute the optional interface and sub-iterator responses, and map these to the total model response.

Reimplemented from [Model](#).

8.63.2.2 `void derived_async_compute_response (const IntArray & asv)` [protected, virtual]

portion of [async_compute_response\(\)](#) specific to [NestedModel](#)

Not currently supported by NestedModels (need to add concurrent iterator support). As a result, [derived_synchronize\(\)](#), [derived_synchronize_nowait\(\)](#), and [synchronize_nowait_completions\(\)](#) are inactive as well).

Reimplemented from [Model](#).

8.63.2.3 `const ResponseArray & derived_synchronize ()` [protected, virtual]

portion of [synchronize\(\)](#) specific to [NestedModel](#)

Asynchronous response computations are not currently supported by NestedModels. Return a dummy responseArray to satisfy the compiler.

Reimplemented from [Model](#).

8.63.2.4 `const ResponseList & derived_synchronize_nowait ()` [protected, virtual]

portion of [synchronize_nowait\(\)](#) specific to [NestedModel](#)

Asynchronous response computations are not currently supported by NestedModels. Return a dummy responseList to satisfy the compiler.

Reimplemented from [Model](#).

8.63.2.5 `const IntList & synchronize_nowait_completions ()` [inline, protected, virtual]

Return completion id's matching response list from [synchronize_nowait](#).

Asynchronous response computations are not currently supported by NestedModels. Return a dummy completionList to satisfy the compiler.

Reimplemented from [Model](#).

8.63.2.6 `bool derived_master_overload () const` [inline, protected, virtual]

flag which prevents overloading the master with a multiprocessor evaluation (forwarded to optional-Interface)

Derived master overload for subModel is handled separately in [subModel.compute_response\(\)](#) within [sub-iterator.run_iterator\(\)](#).

Reimplemented from [Model](#).

8.63.2.7 void derived_init_communicators (const int & max_iterator_concurrency) [inline, protected, virtual]

set up optionalInterface and subModel for parallel operations

Asynchronous flags need to be initialized for the subModel. In addition, max_iterator_concurrency is the outer level iterator concurrency, not the subIterator concurrency that subModel will see, and recomputing the message_lengths on the subModel is probably not a bad idea either. Therefore, recompute everything on subModel using `init_communicators()`.

Reimplemented from [Model](#).

8.63.2.8 void response_mapping (const Response & interface_response, const Response & sub_iterator_response, Response & mapped_response) [private]

combine the response from the optional interface evaluation with the response from the sub-iteration using the objLSqCoeffs/constrCoeffs mappings to create the total response for the model

In the OUU case,

```
optionalInterface fns = {f}, {g} (deterministic obj fns/lsq terms & constraints)
subIterator fns      = {S}      (UQ response statistics)
```

Problem formulation for mapped functions:

```
minimize    {f} + [W]{S}
subject to  {g_l} <= {g}    <= {g_u}
            {a_l} <= [A]{S} <= {a_u}
            {g}    == {g_t}
            [A]{S} == {a_t}
```

where [W] is the primary_mapping_matrix user input (objLSqCoeffs class attribute), [A] is the secondary_mapping_matrix user input (constrCoeffs class attribute), {{g_l},{a_l}} are the top level inequality constraint lower bounds, {{g_u},{a_u}} are the top level inequality constraint upper bounds, and {{g_t},{a_t}} are the top level equality constraint targets.

NOTE: optionalInterface/subIterator primary fns (obj fns/lsq terms) overlap but optionalInterface/subIterator secondary fns (ineq/eq constraints) do not. The [W] matrix can be specified so as to allow

- some purely deterministic primary functions and some combined: [W] filled and [W].num_rows() < {f}.length() [combined first] or [W].num_rows() == {f}.length() and [W] contains rows of zeros [combined last]
- some combined and some purely stochastic primary functions: [W] filled and [W].num_rows() > {f}.length()
- separate deterministic and stochastic primary functions: [W].num_rows() > {f}.length() and [W] contains {f}.length() rows of zeros.

If the need arises, could change constraint definition to allow overlap as well: {g_l} <= {g} + [A]{S} <= {g_u} with [A] usage the same as for [W] above.

In the UOO case, things are simpler, just compute statistics of each optimization response function: [W] = [I], {f}/{g}/[A] are empty.

8.63.3 Member Data Documentation

8.63.3.1 `Model subModel` [private]

the sub-model used in sub-iterator evaluations

There are no restrictions on `subModel`, so arbitrary nestings are possible. This is commonly used to support surrogate-based optimization under uncertainty by having `NestedModels` contain `LayeredModels` and vice versa.

The documentation for this class was generated from the following files:

- `NestedModel.H`
- `NestedModel.C`

8.64 NL2Misc Struct Reference

Auxiliary information passed to `calcr` and `calcj` via `ur`.

Public Attributes

- `Model * m`
Dakota "Model".
- `Real * J [2]`
cache the two most recent Jacobian values in speculative-evaluation mode
- `int nf [2]`
function-evaluation counts corresponding to cached Jacobian values (used to tell which J value to use)
- `int specgrad`
whether to cache J values (0 == no, 1 == yes)

8.64.1 Detailed Description

Auxiliary information passed to `calcr` and `calcj` via `ur`.

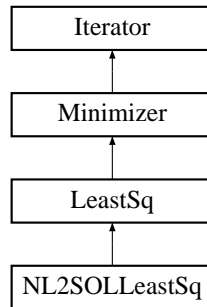
The documentation for this struct was generated from the following file:

- `NL2SOLLeastSq.C`

8.65 NL2SOLLeastSq Class Reference

Wrapper class for the NL2SOL nonlinear least squares library.

Inheritance diagram for NL2SOLLeastSq::



Public Member Functions

- [NL2SOLLeastSq \(Model &model\)](#)
standard constructor
- [~NL2SOLLeastSq \(\)](#)
destructor
- void [minimize_residuals \(\)](#)

Private Attributes

- int [auxprt](#)
auxiliary printing bits (see [Dakota Ref Manual](#)): sum of 1 = x0prt (print initial guess) 2 = solprt (print final solution) 4 = statpr (print solution statistics) 8 = parprt (print nondefault parameters) 16 = dradpr (print bound constraint drops/adds) debug/verbose/normal use default = 31 (everything), quiet uses 3, silent uses 0.
- int [outlev](#)
frequency of output summary lines in number of iterations (debug/verbose/normal/quiet use default = 1, silent uses 0)
- Real [dltfdj](#)
finite-diff step size for computing Jacobian approximation (fd_gradient_step_size)
- Real [delta0](#)
finite-diff step size for gradient differences for H (a component of some covariance approximations, if desired) (fd_hessian_step_size)
- Real [dltfdc](#)

finite-diff step size for function differences for H (fd_hessian_step_size)

- int **mxfc**
function-evaluation limit (max_function_evaluations)
- int **mxiter**
iteration limit (max_iterations)
- Real **rfctol**
relative fn convergence tolerance (convergence_tolerance)
- Real **afctol**
absolute fn convergence tolerance (absolute_conv_tol)
- Real **xctol**
x-convergence tolerance (x_conv_tol)
- Real **sctol**
singular convergence tolerance (singular_conv_tol)
- Real **lmaxs**
radius for singular-convergence test (singular_radius)
- Real **xftol**
false-convergence tolerance (false_conv_tol)
- int **covreq**
kind of covariance required (covariance): 1 or -1 ==> $\sigma^2 H^{-1} J^T J H^{-1}$ 2 or -2 ==> $\sigma^2 H^{-1} 3$ or -3 ==> $\sigma^2 (J^T J)^{-1}$ 1 or 2 ==> use gradient diffs to estimate H -1 or -2 ==> use function diffs to estimate H default = 0 (no covariance)
- int **rdreq**
whether to compute the regression diagnostic vector (regression_diagnostics)
- Real **fprec**
expected response function precision (function_precision)
- Real **lmax0**
initial trust-region radius (initial_trust_radius)

8.65.1 Detailed Description

Wrapper class for the NL2SOL nonlinear least squares library.

The [NL2SOLLeastSq](#) class provides a wrapper for NL2SOL, a C library from Bell Labs. It uses a function pointer approach for which passed functions must be either global functions or static member functions.

8.65.2 Member Function Documentation

8.65.2.1 void minimize_residuals () [virtual]

Details on the following subscript values appear in "Usage Summary for Selected Optimization Routines" by David M. Gay, Computing Science Technical Report No. 153, AT&T Bell Laboratories, 1990. <http://netlib.bell-labs.com/cm/cs/cstr/153.ps.gz>

Implements [LeastSq](#).

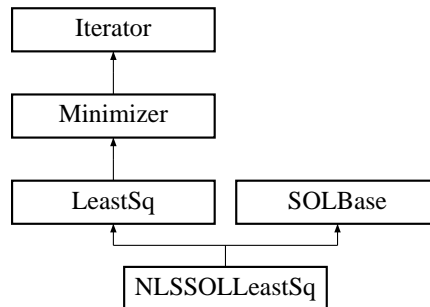
The documentation for this class was generated from the following files:

- NL2SOLLeastSq.H
- NL2SOLLeastSq.C

8.66 NLSSOLLeastSq Class Reference

Wrapper class for the NLSSOL nonlinear least squares library.

Inheritance diagram for NLSSOLLeastSq::



Public Member Functions

- [NLSSOLLeastSq \(Model &model\)](#)
standard constructor
- [~NLSSOLLeastSq \(\)](#)
destructor
- void [minimize_residuals \(\)](#)
Used within the least squares branch for minimizing the sum of squares residuals. Redefines the run_iterator virtual function for the least squares branch.

Static Private Member Functions

- void [least_sq_eval](#) (int &mode, int &m, int &n, int &nrowfj, double *x, double *f, double *gradf, int &nstate)
Evaluator for NLSSOL: computes the values and first derivatives of the least squares terms (passed by function pointer to NLSSOL).

Static Private Attributes

- [NLSSOLLeastSq * nlssolInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

8.66.1 Detailed Description

Wrapper class for the NLSSOL nonlinear least squares library.

The `NLSSOLLeastSq` class provides a wrapper for NLSSOL, a Fortran 77 sequential quadratic programming library from Stanford University marketed by Stanford Business Associates. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any non-static attribute used within static member functions must be either local to that function or accessed through a static pointer.

The user input mappings are as follows: `max_function_evaluations` is implemented directly in `NLSSOLLeastSq`'s evaluator functions since there is no NLSSOL parameter equivalent, and `max_`
`iterations`, `convergence_tolerance`, `output_verbosity`, `verify_level`, `function_`
`precision`, and `linesearch_tolerance` are mapped into NLSSOL's "Major Iteration Limit", "Optimality Tolerance", "Major Print Level" (`verbose`: Major Print Level = 20; `quiet`: Major Print Level = 10), "Verify Level", "Function Precision", and "Linesearch Tolerance" parameters, respectively, using NLSSOL's `npoptn()` subroutine (as wrapped by `npoptn2()` from the `npoptn_wrapper.f` file). Refer to [Gill, P.E., Murray, W., Saunders, M.A., and Wright, M.H., 1986] for information on NLSSOL's optional input parameters and the `npoptn()` subroutine.

The documentation for this class was generated from the following files:

- `NLSSOLLeastSq.H`
- `NLSSOLLeastSq.C`

8.67 NoDBBaseConstructor Struct Reference

Dummy struct for overloading constructors used in on-the-fly instantiations.

Public Member Functions

- [NoDBBaseConstructor](#) (int=0)
C++ structs can have constructors.

8.67.1 Detailed Description

Dummy struct for overloading constructors used in on-the-fly instantiations.

[NoDBBaseConstructor](#) is used to overload the constructor used for on-the-fly iterator instantiations in which [ProblemDescDB](#) queries cannot be used. Putting this struct here (rather than in a header of a class that uses it) avoids problems with circular dependencies.

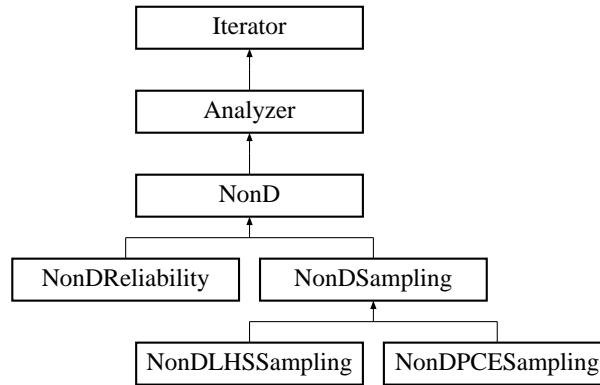
The documentation for this struct was generated from the following file:

- ProblemDescDB.H

8.68 NonD Class Reference

Base class for all nondeterministic iterators (the DAKOTA/UQ branch).

Inheritance diagram for NonD::



Protected Member Functions

- [NonD \(Model &model\)](#)
constructor
- [NonD \(NoDBBaseConstructor, Model &model, int num_vars, const RealVector &lower_bnds, const RealVector &upper_bnds\)](#)
alternate constructor for instantiations "on the fly"
- [~NonD \(\)](#)
destructor
- void [run_iterator \(\)](#)
redefines the main iterator hierarchy virtual function to invoke quantify_uncertainty
- const [Response & iterator_response_results \(\)](#) const
return the final statistics from the nondeterministic iteration
- virtual void [quantify_uncertainty \(\)=0](#)
performs a forward uncertainty propagation of parameter distributions into response statistics

Protected Attributes

- [RealMatrix uncertainCorrelations](#)
uncertain variable correlation matrix (rank correlations for sampling and correlation coefficients for analytic reliability)

- `size_t numNormalVars`
number of normal uncertain variables
- `size_t numLognormalVars`
number of lognormal uncertain variables
- `size_t numUniformVars`
number of uniform uncertain variables
- `size_t numLoguniformVars`
number of loguniform uncertain variables
- `size_t numWeibullVars`
number of weibull uncertain variables
- `size_t numHistogramVars`
number of histogram uncertain variables
- `size_t numUncertainVars`
total number of uncertain variables
- `size_t numResponseFunctions`
number of response functions
- `RealVector meanStats`
means of response functions calculated in `compute_statistics()`
- `RealVector mean95CIDeltas`
Plus/minus deltas on response function means for 95% confidence intervals (calculated in `compute_statistics()`).
- `RealVector stdDevStats`
std deviations of response functions (calculated in `compute_statistics()`)
- `RealVector stdDev95CILowerBnds`
Lower bound for 95% confidence interval on std deviation (calculated in `compute_statistics()`).
- `RealVector stdDev95CIUpperBnds`
Upper bound for 95% confidence interval on std deviation (calculated in `compute_statistics()`).
- `RealVectorArray requestedRespLevels`
requested response levels for all response functions
- `RealVectorArray computedProbLevels`
output probability levels for all response functions resulting from `requestedRespLevels`
- `RealVectorArray computedRelLevels`
output reliability levels for all response functions resulting from `requestedRespLevels`
- `RealVectorArray requestedProbLevels`

requested probability levels for all response functions

- [RealVectorArray requestedRelLevels](#)
requested reliability (beta) levels for all response functions
- [RealVectorArray computedRespLevels](#)
output response levels for all response functions resulting from either requestedProbLevels or requested-RelLevels
- `size_t totalLevelRequests`
total number of levels specified within requestedRespLevels, requestedProbLevels, and requestedRelLevels
- `bool cdfFlag`
flag for type of probabilities/reliabilities used in mappings: cumulative/CDF (true) or complementary/CCDF (false)
- `bool respLevelProbFlag`
flag to indicate mapping of $z \rightarrow p$ (true) or $z \rightarrow \beta$ (false)
- `bool correlationFlag`
flag for indicating if correlation exists among the uncertain variables
- `bool strategyFlag`
flag indicating a strategy other than "single_method". Used to compute additional statistics for use at the strategy level or to deactivate additional output not needed for strategy executions.
- [Response finalStatistics](#)
final statistics from the uncertainty propagation used in strategies: response means, standard deviations, and probabilities of failure

Private Member Functions

- `void distribute_levels (RealVectorArray &levels)`
convenience function for distributing a vector of levels among multiple response functions if a short-hand specification is employed.

8.68.1 Detailed Description

Base class for all nondeterministic iterators (the DAKOTA/UQ branch).

The base class for nondeterministic iterators consolidates uncertain variable data and probabilistic utilities for inherited classes.

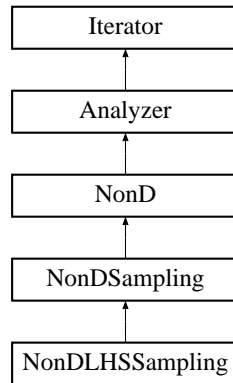
The documentation for this class was generated from the following files:

- DakotaNonD.H
- DakotaNonD.C

8.69 NonDLHSSampling Class Reference

Performs LHS and Monte Carlo sampling for uncertainty quantification.

Inheritance diagram for NonDLHSSampling::



Public Member Functions

- [NonDLHSSampling](#) ([Model](#) &model)
constructor
- [NonDLHSSampling](#) ([Model](#) &model, int samples, int seed, int num_vars, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)
alternate constructor for instantiations "on the fly"
- [~NonDLHSSampling](#) ()
destructor
- void [quantify_uncertainty](#) ()
performs a forward uncertainty propagation by using LHS to generate a set of parameter samples, performing function evaluations on these parameter samples, and computing statistics on the ensemble of results.
- void [print_iterator_results](#) (ostream &s) const
print the final statistics

Private Attributes

- bool [allVarsFlag](#)
flags DACE mode using all variables
- bool [varBasedDecompFlag](#)
flags computation of VBD

8.69.1 Detailed Description

Performs LHS and Monte Carlo sampling for uncertainty quantification.

The Latin Hypercube Sampling (LHS) package from Sandia Albuquerque's Risk and Reliability organization provides comprehensive capabilities for Monte Carlo and Latin Hypercube sampling within a broad array of user-specified probabilistic parameter distributions. It enforces user-specified rank correlations through use of a mixing routine. The [NonDLHSSampling](#) class provides a C++ wrapper for the LHS library and is used for performing forward propagations of parameter uncertainties into response statistics.

8.69.2 Constructor & Destructor Documentation

8.69.2.1 [NonDLHSSampling](#) (*Model & model*)

constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification.

8.69.2.2 [NonDLHSSampling](#) (*Model & model, int samples, int seed, int num_vars, const RealVector & lower_bnds, const RealVector & upper_bnds*)

alternate constructor for instantiations "on the fly"

This alternate constructor is used by [ConcurrentStrategy](#) for generation of uniform, uncorrelated sample sets. It is `_not_` a letter-envelope instantiation and a `set_db_list_nodes` has not been performed. It is called with all needed data passed through the constructor and is designed to allow more flexibility in variables set definition (i.e., relax connection to a variables specification and allow sampling over parameter sets such as multiobjective weights). Data attributes taken from the model in the [NoDBBaseConstructor](#) constructors for [NonD](#) and [Iterator](#) are not used, and other data attributes are not initialized and should not be avoided.

8.69.3 Member Function Documentation

8.69.3.1 `void quantify_uncertainty () [virtual]`

performs a forward uncertainty propagation by using LHS to generate a set of parameter samples, performing function evaluations on these parameter samples, and computing statistics on the ensemble of results.

Loop over the set of samples and compute responses. Compute statistics on the set of responses if `statsFlag` is set.

Implements [NonD](#).

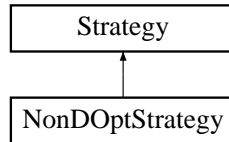
The documentation for this class was generated from the following files:

- [NonDLHSSampling.H](#)
- [NonDLHSSampling.C](#)

8.70 NonDOptStrategy Class Reference

[Strategy](#) for optimization under uncertainty (robust and reliability-based design).

Inheritance diagram for NonDOptStrategy::



Public Member Functions

- [NonDOptStrategy](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~NonDOptStrategy](#) ()
destructor
- void [run_strategy](#) ()
Perform the strategy by executing [optIterator](#) (an optimizer) on [designModel](#) (a layered or nested model containing a nondeterministic iterator at a lower level).
- const [Variables](#) & [strategy_variable_results](#) () const
return the final solution from [optIterator](#) (variables)
- const [Response](#) & [strategy_response_results](#) () const
return the final solution from [optIterator](#) (response)
- [IteratorList](#) & [iterators](#) (bool recurse_flag=true)
returns [optIterator](#) and any subordinate iterators
- [ModelList](#) & [models](#) (bool recurse_flag=true)
returns [designModel](#) and any subordinate models

Private Attributes

- [Model](#) [designModel](#)
the nested or layered model interfaced with [optIterator](#)
- [Iterator](#) [optIterator](#)
the top level optimizer

8.70.1 Detailed Description

[Strategy](#) for optimization under uncertainty (robust and reliability-based design).

This strategy uses a [NestedModel](#) to nest an uncertainty quantification iterator within an optimization iterator in order to perform optimization using nondeterministic data. For OUU based on surrogates, LayeredModels are also employed, and the general recursion facilities supported by nested and layered models allow a broad array of OUU formulations. This class is very simple and is essentially identical to [SingleMethodStrategy](#) since all of the nested iteration mappings are contained within [NestedModel::response_mapping\(\)](#).

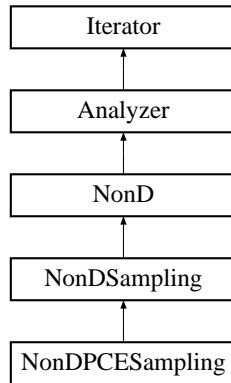
The documentation for this class was generated from the following files:

- NonDOptStrategy.H
- NonDOptStrategy.C

8.71 NonDPCESampling Class Reference

Stochastic finite element approach to uncertainty quantification using polynomial chaos expansions.

Inheritance diagram for NonDPCESampling::



Public Member Functions

- [NonDPCESampling](#) ([Model](#) &model)
constructor
- [~NonDPCESampling](#) ()
destructor
- void [quantify_uncertainty](#) ()
perform a forward uncertainty propagation using SFEM/PCE methods
- void [print_iterator_results](#) (ostream &s) const
print the final statistics and PCE coefficient array

Private Attributes

- [RealVectorArray](#) coeffArray
Array containing Polynomial Chaos coefficients, one real vector per response function.
- int [highestOrder](#)
Highest order of Hermite Polynomials in Expansion.
- int [numChaos](#)
Number of terms in Polynomial Chaos Expansion.

8.71.1 Detailed Description

Stochastic finite element approach to uncertainty quantification using polynomial chaos expansions.

The NonDPCE class uses a polynomial chaos expansion (PCE) approach to approximate the effect of parameter uncertainties on response functions of interest. It utilizes the [HermiteSurf](#) and HermiteChaos classes to perform the PCE.

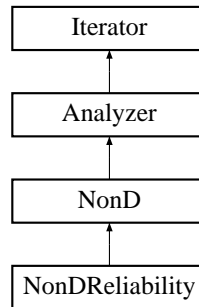
The documentation for this class was generated from the following files:

- NonDPCESampling.H
- NonDPCESampling.C

8.72 NonDReliability Class Reference

Class for the analytical reliability methods within DAKOTA/UQ.

Inheritance diagram for NonDReliability::



Public Member Functions

- [NonDReliability](#) ([Model](#) &model)
constructor
- [~NonDReliability](#) ()
destructor
- void [quantify_uncertainty](#) ()
performs an uncertainty propagation using analytical reliability methods which solve constrained optimization problems to obtain approximations of the cumulative distribution function of response
- void [print_iterator_results](#) (ostream &s) const
print the approximate mean, standard deviation, and importance factors when using the mean value method (MV) or the CDF information when using other reliability methods (AMV,AMV+,FORM)
- [String](#) [uses_method](#) () const
return name of active MPP optimizer
- void [method_recourse](#) ()
perform an MPP optimizer method switch due to a detected conflict

Private Member Functions

- void [mean_value](#) ()
convenience function for encapsulating the simple Mean Value computation of approximate statistics and importance factors
- void [iterated_mean_value](#) ()

convenience function for encapsulating the iterated reliability methods (AMV, AMV+, FORM, SORM)

- void `initialize_mpp_search_data()`
convenience function for initializing/warm starting MPP search data for each z/p/beta level for each response function
- void `g_eval(int &mode, const Epetra_SerialDenseVector &u, Real &g)`
convenience function for evaluating $G(u)$ and $fnGradU(u)$. Used by `RIA_constraint_eval()` and both `PMA_objective_eval()` implementations.
- void `transUToX(const Epetra_SerialDenseVector &uncorr_normal_vars, Epetra_SerialDenseVector &random_vars)`
Transformation Routine from u-space of random variables to x-space of random variables for Petra data types.
- void `transUToX(const RealVector &uncorr_normal_vars, RealVector &random_vars)`
Transformation Routine from u-space of random variables to x-space of random variables for RealVector data types.
- void `transUToZ(const Epetra_SerialDenseVector &uncorr_normal_vars, Epetra_SerialDenseVector &correlated_normal_vars)`
Transformation Routine from u-space of random variables to z-space of random variables for Petra data types.
- void `transZToX(const Epetra_SerialDenseVector &correlated_normal_vars, Epetra_SerialDenseVector &random_vars)`
Transformation Routine from z-space of random variables to x-space of random variables for Petra data types.
- void `transXToU(const Epetra_SerialDenseVector &random_vars, Epetra_SerialDenseVector &uncorr_normal_vars)`
Transformation Routine from x-space of random variables to u-space of random variables for Petra data types.
- void `transXToZ(const Epetra_SerialDenseVector &random_vars, Epetra_SerialDenseVector &correlated_normal_vars)`
Transformation Routine from x-space of random variables to z-space of random variables for Petra data types.
- void `transZToU(Epetra_SerialDenseVector &correlated_normal_vars, Epetra_SerialDenseVector &uncorr_normal_vars)`
Transformation Routine from z-space of random variables to u-space of random variables for Petra data types.
- void `jacXToU(const Epetra_SerialDenseVector &random_vars, Epetra_SerialDenseMatrix &jacobianXU)`
Jacobian of mapping from x to u random variable space.
- void `jacXToZ(const Epetra_SerialDenseVector &random_vars, Epetra_SerialDenseMatrix &jacobianXZ)`
Jacobian of mapping from x to z random variable space.

- void `jacUToX` (const Epetra_SerialDenseVector &uncorr_normal_vars, Epetra_SerialDenseMatrix &jacobianUX)
Jacobian of mapping from u to x random variable space.
- void `jacZToX` (const Epetra_SerialDenseVector &correlated_normal_vars, Epetra_SerialDenseMatrix &jacobianZX)
Jacobian of mapping from z to x random variable space.
- void `transNataf` (Epetra_SerialSymDenseMatrix &mod_corr_matrix)
This procedure modifies the correlation matrix input by the user to be used in the Nataf distribution model.
- double `phi` (const double &beta)
Standard normal cumulative distribution function.
- double `phi_inverse` (const double &p)
Inverse of standard normal cumulative distribution function.
- double `erf_inverse` (const double &p)
Inverse of error function used in `phi_inverse()`.

Static Private Member Functions

- void `RIA_objective_eval` (int &mode, int &n, Real *u, Real &f, Real *grad_f, int &)
static function used by NPSOL as the objective function in the Reliability Index Approach (RIA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the objective function of $(\text{norm } u)^2$.
- void `RIA_constraint_eval` (int &mode, int &ncnln, int &n, int &nrowj, int *needc, Real *u, Real *c, Real *cjac, int &nstate)
static function used by NPSOL as the constraint function in the Reliability Index Approach (RIA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the constraint of $G(u) = \text{response level}$.
- void `PMA_objective_eval` (int &mode, int &n, Real *u, Real &f, Real *grad_f, int &)
static function used by NPSOL as the objective function in the Performance Measure Approach (PMA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the objective function of $G(u)$.
- void `PMA_constraint_eval` (int &mode, int &ncnln, int &n, int &nrowj, int *needc, Real *u, Real *c, Real *cjac, int &nstate)
static function used by NPSOL as the constraint function in the Performance Measure Approach (PMA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the constraint of $(\text{norm } u)^2 = \text{beta}^2$.
- void `RIA_objective_eval` (int mode, int n, const ColumnVector &u, Real &f, ColumnVector &grad_f, int &result_mode)
static function used by OPT++ as the objective function in the Reliability Index Approach (RIA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the objective function of $(\text{norm } u)^2$.

- void [RIA_constraint_eval](#) (int mode, int n, const ColumnVector &u, ColumnVector &g,::Matrix &grad_g, int &result_mode)
static function used by OPT++ as the constraint function in the Reliability Index Approach (RIA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the constraint of $G(u) = \text{response level}$.
- void [PMA_objective_eval](#) (int mode, int n, const ColumnVector &u, Real &f, ColumnVector &grad_f, int &result_mode)
static function used by OPT++ as the objective function in the Performance Measure Approach (PMA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the objective function of $G(u)$.
- void [PMA_constraint_eval](#) (int mode, int n, const ColumnVector &u, ColumnVector &g,::Matrix &grad_g, int &result_mode)
static function used by OPT++ as the constraint function in the Performance Measure Approach (PMA) problem formulation. This equality-constrained optimization problem performs the search for the most probable point (MPP) with the constraint of $(\text{norm } u)^2 = \text{beta}^2$.

Private Attributes

- size_t [numRelAnalyses](#)
number of invocations of [quantify_uncertainty\(\)](#)
- Epetra_SerialDenseVector [fnValsMeanX](#)
copy of response fn values evaluated at mean x
- Epetra_SerialDenseMatrix [fnGradsMeanX](#)
copy of response fn gradients evaluated at mean x
- Epetra_SerialDenseVector [fnGradX](#)
gradient of current response function in x-space
- Epetra_SerialDenseVector [fnGradU](#)
gradient of current response function in u-space
- RealVector [medianFnVals](#)
vector of median values of functions used to determine which side of probability equal 0.5 the response level is
- Epetra_SerialSymDenseMatrix [petraCorrMatrix](#)
petra copy of [uncertainCorrelations](#)
- Epetra_SerialDenseMatrix [cholCorrMatrix](#)
cholesky factor of [petraCorrMatrix](#)
- RealVector [initialPtU](#)
initial guess for MPP search in u-space
- Epetra_SerialDenseVector [mostProbPointX](#)
location of MPP in x-space

- Epetra_SerialDenseVector [mostProbPointU](#)
location of MPP in u-space
- RealVectorArray [mostProbPointULev0](#)
array of converged MPP's in u-space for level 0. Used for warm-starting of reliability analyses within strategies such as nested RBDO.
- IntVector [ranVarType](#)
vector of indices indicating the type of each uncertain variable
- Epetra_SerialDenseVector [ranVarMeansX](#)
vector of means for all uncertain random variables in x-space
- Epetra_SerialDenseVector [ranVarMeansU](#)
vector of means for all uncertain random variables in u-space
- Epetra_SerialDenseVector [ranVarStdDevsX](#)
vector of standard deviations for all uncertain random variables in x-space
- int [respFnCount](#)
counter for which response function is being analyzed
- int [levelCount](#)
counter for which response/probability level is being analyzed
- Real [requestedRespLevel](#)
the response level target for the current response function
- Real [requestedCDFRelLevel](#)
the CDF reliability level target for the current response function
- Real [computedRespLevel](#)
output response level calculated
- Real [computedProbLevel](#)
output probability level calculated
- Real [computedRelLevel](#)
output reliability level calculated
- short [mppSearchFlag](#)
flag representing the MPP search type selection (MV, AMV, transformed AMV, AMV+, transformed AMV+, or FORM)
- bool [npsolFlag](#)
flag representing the optimization MPP search algorithm selection (SQP or NIP)
- bool [warmStartFlag](#)
flag indicating the use of warm starts

- [String integrationMethod](#)
integration method identifier provided by integration specification
- [RealMatrix impFactor](#)
importance factors predicted by MV
- [int npsolDerivLevel](#)
derivative level for NPSOL executions (1 = analytic grads of objective fn, 2 = analytic grads of constraints, 3 = analytic grads of both).
- [Real Pi](#)
the value for Pi used in several numerical routines

Static Private Attributes

- [NonDReliability * nondRelInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

8.72.1 Detailed Description

Class for the analytical reliability methods within DAKOTA/UQ.

The [NonDReliability](#) class implements the following analytic reliability methods: advanced mean value method (AMV), iterated advanced mean value method (AMV+), first order reliability method (FORM), and second order reliability method (SORM). Each of these employ an optimizer (currently NPSOL) to perform a search for the most probable point (MPP).

8.72.2 Member Function Documentation

8.72.2.1 void initialize_mpp_search_data () [private]

convenience function for initializing/warm starting MPP search data for each z/p/beta level for each response function

Initialize/warm-start optimizer initial guess (initialPtU), linearization point (mostProbPointX/U), and associated response data (computedRespLevel and fnGradX/U).

8.72.2.2 void transUToX (const Epetra_SerialDenseVector & uncorr_normal_vars, Epetra_SerialDenseVector & random_vars) [private]

Transformation Routine from u-space of random variables to x-space of random variables for Petra data types.

This procedure performs the transformation from u to x space. `uncorr_normal_vars` is the vector of random variables in standard normal space (u-space). `random_vars` is the vector of the random variables in the user-defined x-space

**8.72.2.3 void transUToZ (const Epetra_SerialDenseVector & *uncorr_normal_vars*,
Epetra_SerialDenseVector & *correlated_normal_vars*) [private]**

Transformation Routine from u-space of random variables to z-space of random variables for Petra data types.

This procedure computes the transformation from u to z space. `uncorr_normal_vars` is the vector of random variables in standard normal space (u-space). `correlated_normal_vars` is the vector of random variables in normal space with proper correlations (z-space).

**8.72.2.4 void transZToX (const Epetra_SerialDenseVector & *correlated_normal_vars*,
Epetra_SerialDenseVector & *random_vars*) [private]**

Transformation Routine from z-space of random variables to x-space of random variables for Petra data types.

This procedure computes the transformation from z to x space. `correlated_normal_vars` is the vector of random variables in normal space with proper correlations (z-space). `random_vars` is the vector of the random variables in the user-defined x-space

**8.72.2.5 void transXToU (const Epetra_SerialDenseVector & *random_vars*,
Epetra_SerialDenseVector & *uncorr_normal_vars*) [private]**

Transformation Routine from x-space of random variables to u-space of random variables for Petra data types.

This procedure performs the transformation from x to u space `uncorr_normal_vars` is the vector of random variables in standard normal space (u-space). `random_vars` is the vector of the random variables in the user-defined x-space.

**8.72.2.6 void transXToZ (const Epetra_SerialDenseVector & *random_vars*,
Epetra_SerialDenseVector & *correlated_normal_vars*) [private]**

Transformation Routine from x-space of random variables to z-space of random variables for Petra data types.

This procedure performs the transformation from x to z space: `correlated_normal_vars` is the vector of random variables in normal space with proper correlations(z-space). `random_vars` is the vector of the random variables in the user-defined x-space.

**8.72.2.7 void transZToU (Epetra_SerialDenseVector & *correlated_normal_vars*,
Epetra_SerialDenseVector & *uncorr_normal_vars*) [private]**

Transformation Routine from z-space of random variables to u-space of random variables for Petra data types.

This procedure computes the transformation from z to u space. `uncorr_normal_vars` is the vector of random variables in standard normal space (u-space). `correlated_normal_vars` is the vector of random variables in normal space with proper correlations (z-space).

**8.72.2.8 void jacXToU (const Epetra_SerialDenseVector & *random_vars*,
Epetra_SerialDenseMatrix & *jacobianXU*) [private]**

Jacobian of mapping from x to u random variable space.

This procedure computes the jacobian of the transformation from x to u space. *random_vars* is the vector of the random variables in the user-defined x-space.

**8.72.2.9 void jacXToZ (const Epetra_SerialDenseVector & *random_vars*,
Epetra_SerialDenseMatrix & *jacobianXZ*) [private]**

Jacobian of mapping from x to z random variable space.

This procedure computes the jacobian of the transformation from x to z space. *random_vars* is the vector of the random variables in the user-defined x-space.

**8.72.2.10 void jacUToX (const Epetra_SerialDenseVector & *uncorr_normal_vars*,
Epetra_SerialDenseMatrix & *jacobianUX*) [private]**

Jacobian of mapping from u to x random variable space.

This procedure computes the jacobian of the transformation from u to x space. *uncorr_normal_vars* is the vector of random variables in standard normal space (u-space).

**8.72.2.11 void jacZToX (const Epetra_SerialDenseVector & *correlated_normal_vars*,
Epetra_SerialDenseMatrix & *jacobianZX*) [private]**

Jacobian of mapping from z to x random variable space.

This procedure computes the jacobian of the transformation from z to x space. *correlated_normal_vars* is the vector of random variables in normal space with proper correlations (z-space).

8.72.2.12 void transNataf (Epetra_SerialSymDenseMatrix & *mod_corr_matrix*) [private]

This procedure modifies the correlation matrix input by the user to be used in the Nataf distribution model.

This procedure modifies the correlation matrix input by the user to be used in the Nataf distribution model (der Kiureghian and Liu, ASCE JEM 112:1, 1986).

R: the correlation coefficient matrix of the random variables

mod_corr_matrix: modified correlation matrix

Note: The modification is exact for log-log, normal-log, normal-normal, normal-uniform transformations (numerical precision). The uniform-uniform and uniform-log case are approximations obtained in the above reference.

8.72.2.13 double phi (const double & *beta*) [private]

Standard normal cumulative distribution function.

returns a probability < 0.5 for negative beta and a probability > 0.5 for positive beta.

8.72.2.14 double phi_inverse (const double & p) [private]

Inverse of standard normal cumulative distribution function.

returns a negative beta for probability < 0.5 and a positive beta for probability > 0.5.

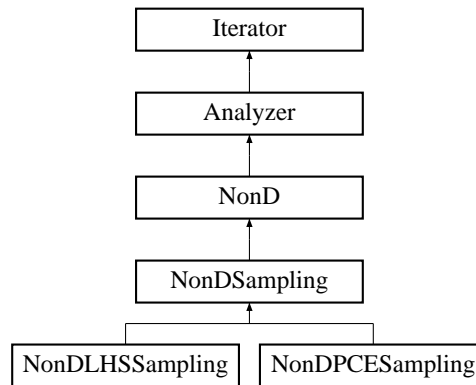
The documentation for this class was generated from the following files:

- NonDReliability.H
- NonDReliability.C

8.73 NonDSampling Class Reference

Base class for common code between [NonDLHSSampling](#) and [NonDPCESampling](#).

Inheritance diagram for NonDSampling::



Protected Member Functions

- [NonDSampling](#) ([Model](#) &model)
constructor
- [NonDSampling](#) ([NoDBBaseConstructor](#), [Model](#) &model, int samples, int seed, int num_vars, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)
alternate constructor for instantiations "on the fly"
- [~NonDSampling](#) ()
destructor
- void [sampling_reset](#) (int min_samples, bool all_data_flag, bool stats_flag)
resets number of samples and sampling flags
- const [String](#) & [sampling_scheme](#) () const
return sampleType: "lhs" or "random"
- void [get_parameter_sets](#) (bool vbd_change_seq_flag)
Uses [run_lhs\(\)](#) to generate a set of samples. In the usual mode, this will be called once. In variance-based decomposition or replicated LHS, it may be called several times.
- void [run_lhs](#) ()
generates the desired set of parameter samples from within user-specified probabilistic distributions. Supports both old and new LHS libraries. Used by [NonDLHSSampling](#) and [NonDPCESampling](#).
- void [compute_statistics](#) (const [RealVectorArray](#) &samples)
computes mean, standard deviation, and probability of failure for the samples input

- void `compute_correlations` (const `RealVectorArray` &all_c_vars, const `RealVectorArray` &all_fns)
computes four correlation matrices for input and output data simple, partial, simple rank, and partial rank
- void `simple_corr` (Epetra_SerialDenseMatrix &total_data, const int &num_obs, const int &num_corr, const bool &rank_on)
computes simple correlations
- void `partial_corr` (Epetra_SerialDenseMatrix &total_data, const int &num_obs, const int &num_corr, const bool &rank_on)
computes partial correlations
- void `print_statistics` (ostream &s) const
prints the mean, standard deviation, and probability of failure statistics computed in `compute_statistics()`

Static Protected Member Functions

- bool `rank_sort` (const int &x, const int &y)
sort algorithm to compute ranks for rank correlations

Protected Attributes

- int `numObservations`
the number of samples to evaluate
- String `sampleType`
the sample type: "lhs" or "random"
- bool `statsFlag`
flags computation/output of statistics
- bool `allDataFlag`
flags update of allVariables/allResponses
- size_t `numActiveVars`
total number of variables published to LHS
- size_t `numDesignVars`
number of design variables (treated as uniform distribution within design variable bounds for DACE usage of `NonDSampling`)
- size_t `numStateVars`
number of state variables (treated as uniform distribution within state variable bounds for DACE usage of `NonDSampling`)
- bool `varyPattern`
flag for generating a sequence of seed values within multiple `run_lhs()` calls so that the `run_lhs()` executions (e.g., for surrogate-based optimization) are repeatable but not correlated.

Private Member Functions

- void [check_error](#) (const int &err_code, const char *err_source) const
checks the return codes from LHS routines and aborts if an error is returned

Private Attributes

- const int [originalSeed](#)
the user seed specification (default is 0)
- int [randomSeed](#)
the current random number seed
- size_t [numLHSRuns](#)
counter for number of executions of [run_lhs\(\)](#) for this object
- Epetra_SerialDenseMatrix [simpleCorr](#)
matrix to hold simple raw correlations
- Epetra_SerialDenseMatrix [simpleRankCorr](#)
matrix to hold simple rank correlations
- Epetra_SerialDenseMatrix [partialCorr](#)
matrix to hold partial raw correlations
- Epetra_SerialDenseMatrix [partialRankCorr](#)
matrix to hold partial rank correlations

Static Private Attributes

- [RealArray](#) [rawData](#)
vector to hold raw data before rank sort
- int [pgf90Initialized](#)
flag indicating whether [pghpf_init\(\)](#) has been called.

8.73.1 Detailed Description

Base class for common code between [NonDLHSSampling](#) and [NonDPCESampling](#).

This base class provides common code for sampling methods which employ the Latin Hypercube Sampling (LHS) package from Sandia Albuquerque's Risk and Reliability organization. [NonDSampling](#) manages two LHS versions within a `#ifdef` construct in [run_lhs\(\)](#): (1) the 1998 Fortran 90 LHS version as documented in SAND98-0210, which was converted to a UNIX link library in 2001, (2) the 1970's vintage LHS that had been f2c'd and converted to (incomplete) classes.

8.73.2 Constructor & Destructor Documentation

8.73.2.1 [NonDSampling](#) ([Model](#) & *model*) [protected]

constructor

This constructor is called for a standard letter-envelope iterator instantiation. In this case, `set_db_list_nodes` has been called and `probDescDB` can be queried for settings from the method specification.

8.73.2.2 [NonDSampling](#) ([NoDBBaseConstructor](#), [Model](#) & *model*, *int samples*, *int seed*, *int num_vars*, [const RealVector](#) & *lower_bnds*, [const RealVector](#) & *upper_bnds*) [protected]

alternate constructor for instantiations "on the fly"

This alternate constructor is used by [ConcurrentStrategy](#) for generation of uniform, uncorrelated sample sets.

8.73.3 Member Function Documentation

8.73.3.1 `void sampling_reset` (*int min_samples*, *bool all_data_flag*, *bool stats_flag*) [inline, protected, virtual]

resets number of samples and sampling flags

used by [ApproximationInterface::build_global_approximation\(\)](#) to publish the minimum number of samples needed from the sampling routine (to build a particular global approximation) and to set `allDataFlag` and `statsFlag`. In this case, `allDataFlag` is set to true (vectors of variable and response sets must be returned to build the global approximation) and `statsFlag` is set to false (statistics computations are not needed).

Reimplemented from [Iterator](#).

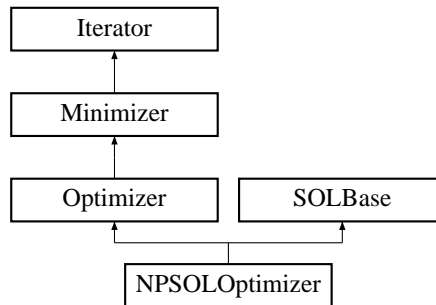
The documentation for this class was generated from the following files:

- [NonDSampling.H](#)
- [NonDSampling.C](#)

8.74 NPSOLOptimizer Class Reference

Wrapper class for the NPSOL optimization library.

Inheritance diagram for NPSOLOptimizer::



Public Member Functions

- [NPSOLOptimizer \(Model &model\)](#)
standard constructor
- [NPSOLOptimizer \(const RealVector &initial_point, const RealVector &var_lower_bnds, const RealVector &var_upper_bnds, int num_lin_ineq, int num_lin_eq, int num_nln_ineq, int num_nln_eq, const RealMatrix &lin_ineq_coeffs, const RealVector &lin_ineq_lower_bnds, const RealVector &lin_ineq_upper_bnds, const RealMatrix &lin_eq_coeffs, const RealVector &lin_eq_targets, const RealVector &nonlin_ineq_lower_bnds, const RealVector &nonlin_ineq_upper_bnds, const RealVector &nonlin_eq_targets, void\(*user_obj_eval\)\(int &, int &, Real *, Real &, Real *, int &\), void\(*user_con_eval\)\(int &, int &, int &, int &, int *, Real *, Real *, Real *, int &\), const int &derivative_level, const Real &conv_tol\)](#)
alternate constructor for instantiations "on the fly"
- [~NPSOLOptimizer \(\)](#)
destructor
- [void find_optimum \(\)](#)
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.

Private Member Functions

- [void find_optimum_on_model \(\)](#)
called by find_optimum for setUpType == "model"
- [void find_optimum_on_user_functions \(\)](#)
called by find_optimum for setUpType == "user_functions"

Static Private Member Functions

- void [objective_eval](#) (int &mode, int &n, double *x, double &f, double *gradf, int &nstate)
OBJFUN in NPSOL manual: computes the value and first derivatives of the objective function (passed by function pointer to NPSOL).

Private Attributes

- [String](#) [setUpType](#)
controls iteration mode: "model" (normal usage) or "user_functions" (user-supplied functions mode for "on the fly" instantiations). [NonDReliability](#) currently uses the user_functions mode.
- [RealVector](#) [initialPoint](#)
holds initial point passed in for "user_functions" mode.
- [RealVector](#) [lowerBounds](#)
holds variable lower bounds passed in for "user_functions" mode.
- [RealVector](#) [upperBounds](#)
holds variable upper bounds passed in for "user_functions" mode.
- void(* [userObjectiveEval](#))(int &, int &, Real *, Real &, Real *, int &)
holds function pointer for objective function evaluator passed in for "user_functions" mode.
- void(* [userConstraintEval](#))(int &, int &, int &, int &, int *, Real *, Real *, Real *, int &)
holds function pointer for constraint function evaluator passed in for "user_functions" mode.

Static Private Attributes

- [NPSOLOptimizer](#) * [npsolInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

8.74.1 Detailed Description

Wrapper class for the NPSOL optimization library.

The [NPSOLOptimizer](#) class provides a wrapper for NPSOL, a Fortran 77 sequential quadratic programming library from Stanford University marketed by Stanford Business Associates. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function or accessed through a static pointer.

The user input mappings are as follows: `max_function_evaluations` is implemented directly in `NPSOLOptimizer`'s evaluator functions since there is no NPSOL parameter equivalent, and `max_`
`iterations`, `convergence_tolerance`, `output_verbosity`, `verify_level`, `function_`
`precision`, and `linesearch_tolerance` are mapped into NPSOL's "Major Iteration Limit", "Optimality Tolerance", "Major Print Level" (`verbose`: Major Print Level = 20; `quiet`: Major Print Level

= 10), "Verify Level", "Function Precision", and "LineSearch Tolerance" parameters, respectively, using NPSOL's `npoptn()` subroutine (as wrapped by `npoptn2()` from the `npoptn_wrapper.f` file). Refer to [Gill, P.E., Murray, W., Saunders, M.A., and Wright, M.H., 1986] for information on NPSOL's optional input parameters and the `npoptn()` subroutine.

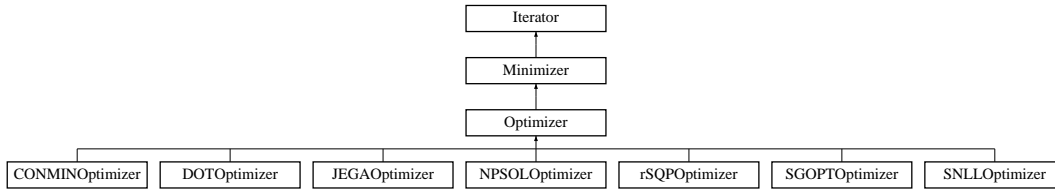
The documentation for this class was generated from the following files:

- NPSOLOptimizer.H
- NPSOLOptimizer.C

8.75 Optimizer Class Reference

Base class for the optimizer branch of the iterator hierarchy.

Inheritance diagram for Optimizer::



Public Member Functions

- void [run_iterator](#) ()
run the iterator

Protected Member Functions

- [Optimizer](#) ()
default constructor
- [Optimizer](#) ([Model](#) &model)
standard constructor
- [~Optimizer](#) ()
destructor
- void [print_iterator_results](#) (ostream &s) const
- void [multi_objective_weights](#) (const [RealVector](#) &multi_obj_wts)
set the relative weightings for multiple objective functions. Used by [ConcurrentStrategy](#) for Pareto set optimization.
- virtual void [find_optimum](#) ()=0
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.
- [Response](#) [multi_objective_modify](#) (const [Response](#) &raw_response) const
forward mapping: maps multiple objective functions to a single objective for single-objective optimizers
- const [RealVector](#) & [multi_objective_retrieve](#) (const [Variables](#) &vars, const [Response](#) &response) const
inverse mapping: retrieves values for multiple objective functions from the solution of a single-objective optimizer

Protected Attributes

- `size_t numObjectiveFunctions`
number of objective functions
- `RealVector multiObjWeights`
user-specified weights for multiple objective functions

8.75.1 Detailed Description

Base class for the optimizer branch of the iterator hierarchy.

The `Optimizer` class provides common data and functionality for `DOTOptimizer`, `NPSOLOptimizer`, `SNLLOptimizer`, and `SGOPTOptimizer`.

8.75.2 Constructor & Destructor Documentation

8.75.2.1 `Optimizer (Model & model)` [protected]

standard constructor

This constructor extracts the inherited data for the optimizer branch and performs sanity checking on gradient and constraint settings.

8.75.3 Member Function Documentation

8.75.3.1 `void run_iterator()` [inline, virtual]

run the iterator

This function is the primary run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented from `Iterator`.

8.75.3.2 `void print_iterator_results (ostream & s) const` [protected, virtual]

Redefines default iterator results printing to include optimization results (objective function and constraints).

Reimplemented from `Iterator`.

8.75.3.3 **Response** `multi_objective_modify` (`const Response & raw_response`) `const` [protected]

forward mapping: maps multiple objective functions to a single objective for single-objective optimizers

This function is responsible for the mapping of multiple objective functions into a single objective for publishing to single-objective optimizers. Used in [DOTOptimizer](#), [NPSOLOptimizer](#), [SNLLOptimizer](#), and [SGOPTApplication](#) on every function evaluation. The simple weighting approach (using `multiObjWeights`) is the only technique supported currently. The weightings are used to scale function values, gradients, and Hessians as needed.

8.75.3.4 `const RealVector & multi_objective_retrieve` (`const Variables & vars`, `const Response & response`) `const` [protected]

inverse mapping: retrieves values for multiple objective functions from the solution of a single-objective optimizer

Retrieve a full multiobjective response based on the data returned by a single objective optimizer by performing a `data_pairs` search.

The documentation for this class was generated from the following files:

- `DakotaOptimizer.H`
- `DakotaOptimizer.C`

8.76 ParallelConfiguration Class Reference

Container class for a set of [ParallelLevel](#) list iterators that collectively identify a particular multilevel parallel configuration.

Public Member Functions

- [ParallelConfiguration](#) ()
default constructor
- [ParallelConfiguration](#) (const [ParallelConfiguration](#) &pl)
copy constructor
- [~ParallelConfiguration](#) ()
destructor
- [ParallelConfiguration](#) & operator= (const [ParallelConfiguration](#) &pl)
assignment operator
- const [ParallelLevel](#) & w_parallel_level () const
return the [ParallelLevel](#) corresponding to wPLIter
- const [ParallelLevel](#) & si_parallel_level () const
return the [ParallelLevel](#) corresponding to siPLIter
- const [ParallelLevel](#) & ie_parallel_level () const
return the [ParallelLevel](#) corresponding to iePLIter
- const [ParallelLevel](#) & ea_parallel_level () const
return the [ParallelLevel](#) corresponding to eaPLIter

Private Member Functions

- void [assign](#) (const [ParallelConfiguration](#) &pl)
assign the attributes of the incoming pl to this object

Private Attributes

- short [numParallelLevels](#)
number of parallel levels
- ParLevLIter [wPLIter](#)
list iterator for MPI_COMM_WORLD (not strictly required, but improves modularity by avoiding explicit usage of MPI_COMM_WORLD)

- [ParLevLIter siPLIter](#)
list iterator for concurrent iterator partitions (there may be more than one per parallel configuration instance)
- [ParLevLIter iePLIter](#)
list iterator identifying the iterator-evaluation parallelLevel (there can only be one)
- [ParLevLIter eaPLIter](#)
list iterator identifying the evaluation-analysis parallelLevel (there can only be one)

8.76.1 Detailed Description

Container class for a set of [ParallelLevel](#) list iterators that collectively identify a particular multilevel parallel configuration.

Rather than containing the multilevel parallel configuration directly, [ParallelConfiguration](#) instead provides a set of list iterators which point into a combined list of [ParallelLevels](#). This approach allows different configurations to reuse [ParallelLevels](#) without copying them. A list of [ParallelConfigurations](#) is contained in [ParallelLibrary](#) ([ParallelLibrary::parallelConfigurations](#)).

The documentation for this class was generated from the following file:

- [ParallelLibrary.H](#)

8.77 ParallelLevel Class Reference

Container class for the data associated with a single level of communicator partitioning.

Public Member Functions

- [ParallelLevel \(\)](#)
default constructor
- [ParallelLevel \(const ParallelLevel &pl\)](#)
copy constructor
- [~ParallelLevel \(\)](#)
destructor
- [ParallelLevel & operator= \(const ParallelLevel &pl\)](#)
assignment operator
- [bool dedicated_master_flag \(\) const](#)
return dedicatedMasterFlag
- [bool communicator_split_flag \(\) const](#)
return commSplitFlag
- [bool server_master_flag \(\) const](#)
return serverMasterFlag
- [bool message_pass \(\) const](#)
return messagePass
- [const int & num_servers \(\) const](#)
return numServers
- [const int & processors_per_server \(\) const](#)
return procsPerServer
- [const MPI_Comm & server_intra_communicator \(\) const](#)
return serverIntraComm
- [const int & server_communicator_rank \(\) const](#)
return serverCommRank
- [const int & server_communicator_size \(\) const](#)
return serverCommSize
- [const MPI_Comm & hub_server_intra_communicator \(\) const](#)

return hubServerIntraComm

- const int & [hub_server_communicator_rank](#) () const
return hubServerCommRank
- const int & [hub_server_communicator_size](#) () const
return hubServerCommSize
- const MPI_Comm & [hub_server_inter_communicator](#) () const
return hubServerInterComm
- MPI_Comm * [hub_server_inter_communicators](#) () const
return hubServerInterComms
- const int & [server_id](#) () const
return serverId

Private Member Functions

- void [assign](#) (const [ParallelLevel](#) &pl)
assign the attributes of the incoming pl to this object

Private Attributes

- bool [dedicatedMasterFlag](#)
signals dedicated master partitioning
- bool [commSplitFlag](#)
signals a communicator split was used
- bool [serverMasterFlag](#)
identifies master server processors
- bool [messagePass](#)
flag for message passing at this level
- int [numServers](#)
number of servers
- int [procsPerServer](#)
processors per server
- MPI_Comm [serverIntraComm](#)
intracomm. for each server partition
- int [serverCommRank](#)
rank in serverIntraComm

- int [serverCommSize](#)
size of serverIntraComm
- MPI_Comm [hubServerIntraComm](#)
intracomm for all serverCommRank==0 w/i next higher level serverIntraComm
- int [hubServerCommRank](#)
rank in hubServerIntraComm
- int [hubServerCommSize](#)
size of hubServerIntraComm
- MPI_Comm [hubServerInterComm](#)
intercomm. between a server & the hub (on server partitions only)
- MPI_Comm * [hubServerInterComms](#)
intercomm. array on hub processor
- int [serverId](#)
server identifier

8.77.1 Detailed Description

Container class for the data associated with a single level of communicator partitioning.

A list of these levels is contained in [ParallelLibrary](#) ([ParallelLibrary::parallelLevels](#)), which defines all of the parallelism levels across one or more multilevel parallelism configurations.

The documentation for this class was generated from the following file:

- [ParallelLibrary.H](#)

8.78 ParallelLibrary Class Reference

Class for partitioning multiple levels of parallelism and managing message passing within these levels.

Public Member Functions

- [ParallelLibrary](#) (int &argc, char **&argv)
stand-alone mode constructor
- [ParallelLibrary](#) ()
library mode constructor
- [ParallelLibrary](#) (int dummy)
dummy constructor (used for dummy_lib)
- [~ParallelLibrary](#) ()
destructor
- const [ParallelLevel](#) & [init_iterator_communicators](#) (const int &iterator_servers, const int &procs_per_iterator, const int &max_iterator_concurrency, const [String](#) &default_config, const [String](#) &iterator_scheduling)
split MPI_COMM_WORLD into iterator communicators
- const [ParallelLevel](#) & [init_evaluation_communicators](#) (const int &evaluation_servers, const int &procs_per_evaluation, const int &max_evaluation_concurrency, const int &asynch_local_evaluation_concurrency, const [String](#) &default_config, const [String](#) &evaluation_scheduling)
split an iterator communicator into evaluation communicators
- const [ParallelLevel](#) & [init_analysis_communicators](#) (const int &analysis_servers, const int &procs_per_analysis, const int &max_analysis_concurrency, const int &asynch_local_analysis_concurrency, const [String](#) &default_config, const [String](#) &analysis_scheduling)
split an evaluation communicator into analysis communicators
- void [free_iterator_communicators](#) ()
deallocate iterator communicators
- void [free_evaluation_communicators](#) ()
deallocate evaluation communicators
- void [free_analysis_communicators](#) ()
deallocate analysis communicators
- void [print_configuration](#) ()
print the parallel level settings for a particular parallel configuration
- void [specify_outputs_restart](#) ([CommandLineHandler](#) &cmd_line_handler)
specify output streams and restart file(s) using command line inputs (normal mode)

- void `specify_outputs_restart` (const char *clh_std_output_filename, const char *clh_std_error_filename, const char *clh_read_restart_filename, const char *clh_write_restart_filename, int restart_evals)
specify output streams and restart file(s) using external inputs (library mode).
- void `manage_outputs_restart` (const `ParallelLevel` &pl)
manage output streams and restart file(s) (both modes)
- void `close_streams` ()
close streams, files, and any other services
- void `send_si` (`MPIPackBuffer` &send_buff, int dest, int tag)
blocking send at the strategy-iterator communication level
- void `isend_si` (`MPIPackBuffer` &send_buff, int dest, int tag, `MPI_Request` &send_req)
nonblocking send at the strategy-iterator communication level
- void `recv_si` (`MPIUnpackBuffer` &recv_buff, int source, int tag, `MPI_Status` &status)
blocking receive at the strategy-iterator communication level
- void `irecv_si` (`MPIUnpackBuffer` &recv_buff, int source, int tag, `MPI_Request` &recv_req)
nonblocking receive at the strategy-iterator communication level
- void `send_ie` (`MPIPackBuffer` &send_buff, int dest, int tag)
blocking send at the iterator-evaluation communication level
- void `isend_ie` (`MPIPackBuffer` &send_buff, int dest, int tag, `MPI_Request` &send_req)
nonblocking send at the iterator-evaluation communication level
- void `recv_ie` (`MPIUnpackBuffer` &recv_buff, int source, int tag, `MPI_Status` &status)
blocking receive at the iterator-evaluation communication level
- void `irecv_ie` (`MPIUnpackBuffer` &recv_buff, int source, int tag, `MPI_Request` &recv_req)
nonblocking receive at the iterator-evaluation communication level
- void `send_ea` (int &send_int, int dest, int tag)
blocking send at the evaluation-analysis communication level
- void `isend_ea` (int &send_int, int dest, int tag, `MPI_Request` &send_req)
nonblocking send at the evaluation-analysis communication level
- void `recv_ea` (int &recv_int, int source, int tag, `MPI_Status` &status)
blocking receive at the evaluation-analysis communication level
- void `irecv_ea` (int &recv_int, int source, int tag, `MPI_Request` &recv_req)
nonblocking receive at the evaluation-analysis communication level
- void `bcast_w` (int &data)
broadcast an integer across MPI_COMM_WORLD

- void `bcast_i` (int &data)
broadcast an integer across an iterator communicator
- void `bcast_e` (int &data)
broadcast an integer across an evaluation communicator
- void `bcast_a` (int &data)
broadcast an integer across an analysis communicator
- void `bcast_si` (int &data)
broadcast an integer across a strategy-iterator intra communicator
- void `bcast_w` (MPIPackBuffer &send_buff)
broadcast a packed buffer across MPI_COMM_WORLD
- void `bcast_i` (MPIPackBuffer &send_buff)
broadcast a packed buffer across an iterator communicator
- void `bcast_e` (MPIPackBuffer &send_buff)
broadcast a packed buffer across an evaluation communicator
- void `bcast_a` (MPIPackBuffer &send_buff)
broadcast a packed buffer across an analysis communicator
- void `bcast_si` (MPIPackBuffer &send_buff)
broadcast a packed buffer across a strategy-iterator intra communicator
- void `bcast_w` (MPIUnpackBuffer &recv_buff)
matching receive for packed buffer broadcast across MPI_COMM_WORLD
- void `bcast_i` (MPIUnpackBuffer &recv_buff)
matching receive for packed buffer bcast across an iterator communicator
- void `bcast_e` (MPIUnpackBuffer &recv_buff)
matching receive for packed buffer bcast across an evaluation communicator
- void `bcast_a` (MPIUnpackBuffer &recv_buff)
matching receive for packed buffer bcast across an analysis communicator
- void `bcast_si` (MPIUnpackBuffer &recv_buff)
matching recv for packed buffer bcast across a strat-iterator intra comm
- void `barrier_w` ()
enforce MPI_Barrier on MPI_COMM_WORLD
- void `barrier_i` ()
enforce MPI_Barrier on an iterator communicator
- void `barrier_e` ()

enforce MPI_Barrier on an evaluation communicator

- void `barrier_a` ()
enforce MPI_Barrier on an analysis communicator
- void `reduce_sum_ea` (double *local_vals, double *sum_vals, const int &num_vals)
compute a sum over an eval-analysis intra-communicator using MPI_Reduce
- void `reduce_sum_a` (double *local_vals, double *sum_vals, const int &num_vals)
compute a sum over an analysis communicator using MPI_Reduce
- void `test` (MPI_Request &request, int &test_flag, MPI_Status &status)
test a nonblocking send/receive request for completion
- void `wait` (MPI_Request &request, MPI_Status &status)
wait for a nonblocking send/receive request to complete
- void `waitall` (const int &num_recv, MPI_Request *&recv_reqs)
wait for all messages from a series of nonblocking receives
- void `waitsome` (const int &num_sends, MPI_Request *&recv_requests, int &num_recv, int *&index_array, MPI_Status *&status_array)
wait for at least one message from a series of nonblocking receives but complete all that are available
- void `free` (MPI_Request &request)
free an MPI_Request
- const int & `world_size` () const
return worldSize
- const int & `world_rank` () const
return worldRank
- bool `mpirun_flag` () const
return mpirunFlag
- bool `is_null` () const
return dummyFlag
- Real `parallel_time` () const
returns current MPI wall clock time
- void `parallel_configuration_iterator` (const ParConfigLIter &pc_iter)
set the current ParallelConfiguration node
- const ParConfigLIter & `parallel_configuration_iterator` () const
return the current ParallelConfiguration node
- const `ParallelConfiguration` & `parallel_configuration` () const
return the current ParallelConfiguration instance

- bool [parallel_configuration_is_complete](#) ()
identifies if the current [ParallelConfiguration](#) has been fully populated
- void [increment_parallel_configuration](#) ()
add a new node to parallelConfigurations and increment currPCIter
- void [decrement_parallel_configuration](#) ()
decrement currPCIter
- [Array](#)< [MPI_Comm](#) > [analysis_intra_communicators](#) ()
return the set of analysis intra communicators for all parallel configurations (used for setting up direct simulation interfaces prior to execution time).

Private Member Functions

- void [init_communicators](#) (const [ParallelLevel](#) &parent_pl, const int &num_servers, const int &procs_per_server, const int &max_concurrency, const int &asynch_local_concurrency, const [String](#) &default_config, const [String](#) &scheduling_override)
split a parent communicator into child server communicators
- void [free_communicators](#) ([ParallelLevel](#) &pl)
deallocate intra/inter communicators for a particular [ParallelLevel](#)
- bool [split_communicator_dedicated_master](#) (const [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl, const int &proc_remainder)
split a parent communicator into a dedicated master processor and num_servers child communicators
- bool [split_communicator_peer_partition](#) (const [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl, const int &proc_remainder)
split a parent communicator into num_servers peer child communicators (no dedicated master processor)
- bool [resolve_inputs](#) (int &num_servers, int &procs_per_server, const int &avail_procs, int &proc_remainder, const int &max_concurrency, const int &capacity_multiplier, const [String](#) &default_config, const [String](#) &scheduling_override)
resolve user inputs into a sensible partitioning scheme
- void [send](#) ([MPIPackBuffer](#) &send_buff, const int &dest, const int &tag, [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl)
blocking buffer send at the current communication level
- void [send](#) (int &send_int, const int &dest, const int &tag, [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl)
blocking integer send at the current communication level
- void [isend](#) ([MPIPackBuffer](#) &send_buff, const int &dest, const int &tag, [MPI_Request](#) &send_req, [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl)
nonblocking buffer send at the current communication level

- void `isend` (int &send_int, const int &dest, const int &tag, MPI_Request &send_req, [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl)
nonblocking integer send at the current communication level
- void `recv` ([MPIUnpackBuffer](#) &recv_buff, const int &source, const int &tag, MPI_Status &status, [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl)
blocking buffer receive at the current communication level
- void `recv` (int &recv_int, const int &source, const int &tag, MPI_Status &status, [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl)
blocking integer receive at the current communication level
- void `irecv` ([MPIUnpackBuffer](#) &recv_buff, const int &source, const int &tag, MPI_Request &recv_req, [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl)
nonblocking buffer receive at the current communication level
- void `irecv` (int &recv_int, const int &source, const int &tag, MPI_Request &recv_req, [ParallelLevel](#) &parent_pl, [ParallelLevel](#) &child_pl)
nonblocking integer receive at the current communication level
- void `bcast` (int &data, const MPI_Comm &comm)
broadcast an integer across a communicator
- void `bcast` ([MPIPackBuffer](#) &send_buff, const MPI_Comm &comm)
send a packed buffer across a communicator using a broadcast
- void `bcast` ([MPIUnpackBuffer](#) &recv_buff, const MPI_Comm &comm)
matching receive for a packed buffer broadcast
- void `barrier` (const MPI_Comm &comm)
enforce MPI_Barrier on comm
- void `reduce_sum` (double *local_vals, double *sum_vals, const int &num_vals, const MPI_Comm &comm)
compute a sum over comm using MPI_Reduce
- void `check_error` (const [String](#) &err_source, const int &err_code)
check the MPI return code and abort if error

Private Attributes

- ofstream `output_ofstream`
tagged file redirection of stdout
- ofstream `error_ofstream`
tagged file redirection of stderr
- int `worldRank`
rank in MPI_COMM_WORLD

- int [worldSize](#)
size of MPI_COMM_WORLD
- bool [mpirunFlag](#)
flag for a parallel mpirun/yod launch
- bool [ownMPIFlag](#)
flag for ownership of MPI_Init/MPI_Finalize
- bool [dummyFlag](#)
prevents multiple MPI_Finalize calls due to dummy_lib
- bool [stdOutputFlag](#)
flags redirection of DAKOTA std output to a file
- bool [stdErrorFlag](#)
flags redirection of DAKOTA std error to a file
- Real [startCPUTime](#)
start reference for UTILIB CPU timer
- Real [startWCTime](#)
start reference for UTILIB wall clock timer
- Real [startMPITime](#)
start reference for MPI wall clock timer
- long [startClock](#)
start reference for local clock() timer measuring parent+child CPU
- const char * [stdOutputFilename](#)
filename for redirection of stdout
- const char * [stdErrorFilename](#)
filename for redirection of stderr
- const char * [readRestartFilename](#)
input filename for restart
- const char * [writeRestartFilename](#)
output filename for restart
- int [restartEvals](#)
number of restart evals to read
- List< [ParallelLevel](#) > [parallelLevels](#)
the complete set of parallelism levels for managing multilevel parallelism among one or more configurations
- List< [ParallelConfiguration](#) > [parallelConfigurations](#)

the set of parallel configurations which manage list iterators for indexing into parallelLevels

- ParLevLIter [currPLIter](#)
list iterator identifying the current node in parallelLevels
- ParConfigLIter [currPCIter](#)
list iterator identifying the current node in parallelConfigurations

8.78.1 Detailed Description

Class for partitioning multiple levels of parallelism and managing message passing within these levels.

The [ParallelLibrary](#) class encapsulates all of the details of performing message passing within multiple levels of parallelism. It provides functions for partitioning of levels according to user configuration input and functions for passing messages within and across MPI communicators for each of the parallelism levels. If support for other message-passing libraries beyond MPI becomes needed (PVM, ...), then [ParallelLibrary](#) would be promoted to a base class with virtual functions to encapsulate the library-specific syntax.

8.78.2 Constructor & Destructor Documentation

8.78.2.1 [ParallelLibrary](#) (int & argc, char **& argv)

stand-alone mode constructor

This constructor is the one used by [main.C](#). It calls MPI_Init conditionally based on whether a parallel launch is detected.

8.78.2.2 [ParallelLibrary](#) ()

library mode constructor

This constructor provides a library mode and is used by the SIERRA Adak application. It does not call MPI_Init, but rather gathers data from MPI_COMM_WORLD if MPI_Init has been called elsewhere.

8.78.2.3 [ParallelLibrary](#) (int dummy)

dummy constructor (used for dummy_lib)

This constructor is used for creation of the global dummy_lib object, which is used to satisfy initialization requirements when the real [ParallelLibrary](#) object is not available.

8.78.3 Member Function Documentation

8.78.3.1 void specify_outputs_restart (CommandLineHandler & cmd_line_handler)

specify output streams and restart file(s) using command line inputs (normal mode)

Get the -output, -error, -read_restart, and -write_restart filenames and the -stop_restart limit from the command line. Defaults for the filenames from the command line handler are NULL for the filenames and 0 for restart_evals if no user specification. Only worldRank==0 has access to command line arguments and must Bcast this data to all iterator masters.

8.78.3.2 void manage_outputs_restart (const ParallelLevel & pl)

manage output streams and restart file(s) (both modes)

If the user has specified the use of files for DAKOTA standard output and/or standard error, then bind these filenames to the Cout/Cerr macros. In addition, if concurrent iterators are to be used, create and tag multiple output streams in order to prevent jumbled output. Manage restart file(s) by processing any incoming evaluations from an old restart file and by setting up the binary output stream for new evaluations. Only master iterator processor(s) read & write restart information. This function must follow init_iterator_communicators so that restart can be managed properly for concurrent iterator strategies. In the case of concurrent iterators, each iterator has its own restart file tagged with iterator number.

8.78.3.3 void close_streams ()

close streams, files, and any other services

Close streams associated with manage_outputs and manage_restart and terminate any additional services that may be active.

8.78.3.4 void init_communicators (const ParallelLevel & parent_pl, const int & num_servers, const int & procs_per_server, const int & max_concurrency, const int & asynch_local_concurrency, const String & default_config, const String & scheduling_override) [private]

split a parent communicator into child server communicators

Split parent communicator into concurrent child server partitions as specified by the passed parameters. This constructs new child intra-communicators and parent-child inter-communicators. This function is called from the Strategy constructor for the concurrent iterator level and from ApplicationInterface::init_communicators() for the concurrent evaluation and concurrent analysis levels.

8.78.3.5 bool resolve_inputs (int & num_servers, int & procs_per_server, const int & avail_procs, int & proc_remainder, const int & max_concurrency, const int & capacity_multiplier, const String & default_config, const String & scheduling_override) [private]

resolve user inputs into a sensible partitioning scheme

This function is responsible for the "auto-configure" intelligence of DAKOTA. It resolves a variety of inputs and overrides into a sensible partitioning configuration for a particular parallelism level. It also handles the general case in which a user's specification request does not divide out evenly with the number of available processors for the level. If num_servers & procs_per_server are both nondefault, then the former takes precedence.

The documentation for this class was generated from the following files:

- ParallelLibrary.H
- ParallelLibrary.C

8.79 ParamResponsePair Class Reference

Container class for a variables object, a response object, and an evaluation id.

Public Member Functions

- [ParamResponsePair](#) ()
default constructor
- [ParamResponsePair](#) (const [Variables](#) &vars, const [Response](#) &response)
alternate constructor for temporaries
- [ParamResponsePair](#) (const [Variables](#) &vars, const [Response](#) &response, const int id)
standard constructor for history uses
- [ParamResponsePair](#) (const [ParamResponsePair](#) &pair)
copy constructor
- [~ParamResponsePair](#) ()
destructor
- [ParamResponsePair](#) & operator= (const [ParamResponsePair](#) &pair)
assignment operator
- void [read](#) (istream &s)
read a [ParamResponsePair](#) object from an istream
- void [write](#) (ostream &s) const
write a [ParamResponsePair](#) object to an ostream
- void [read_annotated](#) (istream &s)
read a [ParamResponsePair](#) object in annotated format from an istream
- void [write_annotated](#) (ostream &s) const
write a [ParamResponsePair](#) object in annotated format to an ostream
- void [write_tabular](#) (ostream &s) const
write a [ParamResponsePair](#) object in tabular format to an ostream
- void [read](#) ([BiStream](#) &s)
read a [ParamResponsePair](#) object from the binary restart stream
- void [write](#) ([BoStream](#) &s) const
write a [ParamResponsePair](#) object to the binary restart stream
- void [read](#) ([MPIUnpackBuffer](#) &s)

read a *ParamResponsePair* object from a packed MPI buffer

- void `write (MPIPackBuffer &s) const`
write a *ParamResponsePair* object to a packed MPI buffer
- int `eval_id () const`
return the evaluation identifier
- const `Variables & prp_parameters () const`
return the parameters object
- const `Response & prp_response () const`
return the response object
- void `prp_response (const Response &response)`
set the response object
- const `IntArray & active_set_vector () const`
return the active set vector from the response object
- void `active_set_vector (const IntArray &asv)`
set the active set vector in the response object
- const `String & interface_id () const`
return the interface identifier from the response object

Private Attributes

- `Variables prPairParameters`
the set of parameters for the function evaluation
- `Response prPairResponse`
the response set for the function evaluation
- int `evalId`
the function evaluation identifier (assigned from *ApplicationInterface::fnEvalId*)

Friends

- bool `operator== (const ParamResponsePair &pair1, const ParamResponsePair &pair2)`
equality operator
- bool `operator!= (const ParamResponsePair &pair1, const ParamResponsePair &pair2)`
inequality operator

8.79.1 Detailed Description

Container class for a variables object, a response object, and an evaluation id.

[ParamResponsePair](#) provides a container class for association of the input for a particular function evaluation (a variables object) with the output from this function evaluation (a response object), along with an evaluation identifier. This container defines the basic unit used in the `data_pairs` list, in restart file operations, and in a variety of scheduling algorithm bookkeeping operations. With the advent of STL, replacement of this class with the `pair<>` template construct may be possible (using `pair<int, pair<vars,response> >`, for example), assuming that deep copies, I/O, alternate constructors, etc., can be adequately addressed.

8.79.2 Constructor & Destructor Documentation

8.79.2.1 [ParamResponsePair](#) (const [Variables](#) & vars, const [Response](#) & response) [inline]

alternate constructor for temporaries

This constructor can use the standard [Variables](#) and [Response](#) copy constructors to share representations since this constructor is used for `search_pairs` (which are local instantiations that go out of scope prior to any changes to values; i.e., they are not used for history).

8.79.2.2 [ParamResponsePair](#) (const [Variables](#) & vars, const [Response](#) & response, const int id) [inline]

standard constructor for history uses

This constructor cannot share representations since it involves a history mechanism (`beforeSynchPRPList` or `data_pairs`). Deep copies must be made.

8.79.3 Member Data Documentation

8.79.3.1 int `evalId` [private]

the function evaluation identifier (assigned from [ApplicationInterface::fnEvalId](#))

`evalId` belongs here rather than in [Response](#) since some [Response](#) objects involve consolidation of several fn evals (e.g., [Model::synchronize_derivatives\(\)](#)). The `prPair`, on the other hand, is used for storage of all low level fn evals that get evaluated, so `evalId` is meaningful.

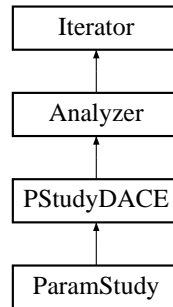
The documentation for this class was generated from the following files:

- [ParamResponsePair.H](#)
- [ParamResponsePair.C](#)

8.80 ParamStudy Class Reference

Class for vector, list, centered, and multidimensional parameter studies.

Inheritance diagram for ParamStudy::



Public Member Functions

- [ParamStudy](#) ([Model](#) &model)
constructor
- [~ParamStudy](#) ()
destructor
- void [extract_trends](#) ()
Redefines the run_iterator virtual function for the PStudy/DACE branch.

Private Member Functions

- void [compute_vector_steps](#) ()
computes stepVector and numSteps from initialPoint, finalPoint, and either numSteps or stepLength (pStudy-Type is 1 or 2)
- void [vector_loop](#) (const [RealVector](#) &start, const [RealVector](#) &step_vect, const int &num_steps)
performs the parameter study by looping from start in num_steps increments of step_vect. Total number of evaluations is num_steps + 1.
- void [sample](#) (const [RealVector](#) &list_of_points)
performs the parameter study by sampling from a list of points
- void [centered_loop](#) (const [RealVector](#) &start, const [Real](#) &percent_delta, const int &deltas_per_variable)
performs a number of plus and minus offsets for each parameter centered about start
- void [multidim_loop](#) (const [IntArray](#) &var_partitions)

performs vector_loops recursively in multiple dimensions

- void `recurse` (int nloop, int nindex, `IntArray` ¤t_index, const `IntArray` &max_index, const `RealVector` &start, const `RealVector` &step_vect)

used by multidim_loop to enable a variable number of nested loops

Private Attributes

- `RealVector` `listOfPoints`
list of evaluation points for the list_parameter_study
- `RealVector` `initialPoint`
the starting point for vector and centered parameter studies
- `RealVector` `finalPoint`
the ending point for vector_parameter_study (a specification option)
- `RealVector` `stepVector`
the n-dimensional increment in vector_parameter_study
- int `numSteps`
the number of times stepVector is applied in vector_parameter_study
- int `pStudyType`
internal code for parameter study type: -1 (list), 1,2,3 (different vector specifications), 4 (centered), or 5 (multidim)
- int `deltasPerVariable`
number of offsets in the plus and the minus direction for each variable in a centered_parameter_study
- bool `nestedFlag`
flag set by parameter studies which call other parameter studies in loops
- `Real` `stepLength`
the Cartesian length of multidimensional steps in vector_parameter_study (a specification option)
- `Real` `percentDelta`
size of relative offsets in percent for each variable in a centered_parameter_study
- `IntArray` `variablePartitions`
number of partitions for each variable in a multidim_parameter_study
- int `psCounter`
class-scope counter (needed for asynchronous multidim_loop)

8.80.1 Detailed Description

Class for vector, list, centered, and multidimensional parameter studies.

The [ParamStudy](#) class contains several algorithms for performing parameter studies of different types. It is not a wrapper for an external library, rather its algorithms are self-contained. The vector parameter study steps along an n-dimensional vector from an arbitrary initial point to an arbitrary final point in a specified number of steps. The centered parameter study performs a number of plus and minus offsets in each coordinate direction around a center point. A multidimensional parameter study fills an n-dimensional hypercube based on a specified number of intervals for each dimension. It is a nested study in that it utilizes the vector parameter study internally as it recurses through the variables. And the list parameter study provides for a user specification of a list of points to evaluate, which allows general parameter investigations not fitting the structure of vector, centered, or multidim parameter studies.

The documentation for this class was generated from the following files:

- ParamStudy.H
- ParamStudy.C

8.81 ProblemDescDB Class Reference

The database containing information parsed from the DAKOTA input file.

Public Member Functions

- [ProblemDescDB](#) ([ParallelLibrary](#) ¶llel_lib)
constructor
- [~ProblemDescDB](#) ()
destructor
- void [manage_inputs](#) ([CommandLineHandler](#) &cmd_line_handler)
parses the input file and populates the problem description database. This version reads from the dakota input filename passed with the "-input" option on the DAKOTA command line.
- void [manage_inputs](#) (const char *dakota_input_file)
parses the input file and populates the problem description database. This version reads from the dakota input filename passed in.
- void [check_input](#) ()
verifies that there was at least one of each of the required keywords in the dakota input file. Used by [manage_inputs](#)().
- void [set_db_list_nodes](#) (const [String](#) &method_tag)
set methodIter based on the method identifier string to activate a particular method specification in methodList and use pointers from this method specification to set the other list iterators.
- void [set_db_list_nodes](#) (const size_t &method_index)
set methodIter based on the active index to activate a particular method specification in methodList and use pointers from this method specification to set the other list iterators.
- size_t [get_db_list_nodes](#) ()
return the index of the active node in methodList
- void [set_db_interface_node](#) (const [String](#) &interface_tag)
set interfaceIter based on the interface identifier string
- void [set_db_responses_node](#) (const [String](#) &responses_tag)
set responsesIter based on the responses identifier string
- void [set_db_model_type](#) (const [String](#) &model_type)
set the model type
- [ParallelLibrary](#) & [parallel_library](#) () const
return the parallelLib reference

- const [RealVector](#) & [get_drv](#) (const [String](#) &entry_name) const
get a RealVector out of the database based on an identifier string
- const [IntVector](#) & [get_div](#) (const [String](#) &entry_name) const
get a IntVector out of the database based on an identifier string
- const [IntArray](#) & [get_dia](#) (const [String](#) &entry_name) const
get a IntArray out of the database based on an identifier string
- const [RealMatrix](#) & [get_drm](#) (const [String](#) &entry_name) const
get a RealMatrix out of the database based on an identifier string
- const [RealVectorArray](#) & [get_drva](#) (const [String](#) &entry_name) const
get a RealVectorArray out of the database based on an identifier string
- const [IntList](#) & [get_dil](#) (const [String](#) &entry_name) const
get a IntList out of the database based on an identifier string
- const [StringArray](#) & [get_dsa](#) (const [String](#) &entry_name) const
get a StringArray out of the database based on an identifier string
- const [String2DArray](#) & [get_ds2a](#) (const [String](#) &entry_name) const
get a String2DArray out of the database based on an identifier string
- const [String](#) & [get_string](#) (const [String](#) &entry_name) const
get a String out of the database based on an identifier string
- const [Real](#) & [get_real](#) (const [String](#) &entry_name) const
get a Real out of the database based on an identifier string
- const [int](#) & [get_int](#) (const [String](#) &entry_name) const
get an int out of the database based on an identifier string
- const [short](#) & [get_short](#) (const [String](#) &entry_name) const
get a short int out of the database based on an identifier string
- const [size_t](#) & [get_sizet](#) (const [String](#) &entry_name) const
get a size_t out of the database based on an identifier string
- const [bool](#) & [get_bool](#) (const [String](#) &entry_name) const
get a bool out of the database based on an identifier string
- void [insert_node](#) (const [DataStrategy](#) &data_strategy)
set the DataStrategy object
- void [insert_node](#) (const [DataMethod](#) &data_method)
add a DataMethod object to the methodList
- void [insert_node](#) (const [DataVariables](#) &data_variables)
add a DataVariables object to the variablesList

- void [insert_node](#) (const [DataInterface](#) &data_interface)
add a [DataInterface](#) object to the interfaceList
- void [insert_node](#) (const [DataResponses](#) &data_responses)
add a [DataResponses](#) object to the responsesList

Static Public Member Functions

- void [method_kwhandler](#) (const struct [FunctionData](#) *parsed_data)
method keyword handler called by IDR when a complete method specification is parsed
- void [variables_kwhandler](#) (const struct [FunctionData](#) *parsed_data)
variables keyword handler called by IDR when a complete variables specification is parsed
- void [interface_kwhandler](#) (const struct [FunctionData](#) *parsed_data)
interface keyword handler called by IDR when a complete interface specification is parsed
- void [responses_kwhandler](#) (const struct [FunctionData](#) *parsed_data)
responses keyword handler called by IDR when a complete responses specification is parsed
- void [strategy_kwhandler](#) (const struct [FunctionData](#) *parsed_data)
strategy keyword handler called by IDR when a complete strategy specification is parsed

Private Member Functions

- void [send_db_buffer](#) ()
MPI send of a large buffer containing strategy specification attributes and all the objects in interfaceList, variablesList, methodList, and responsesList. Used by [manage_inputs\(\)](#).
- void [receive_db_buffer](#) ()
MPI receive of a large buffer containing strategy specification attributes and all the objects in interfaceList, variablesList, methodList, and responsesList. Used by [manage_inputs\(\)](#).
- void [build_label](#) ([String](#) &label, const [String](#) &root_label, size_t tag)
create a label by appending tag to root_label
- void [build_labels](#) ([StringArray](#) &label_array, const [String](#) &root_label)
create an array of labels by tagging root_label for each entry in label_array. Uses [build_label\(\)](#).
- void [build_labels_partial](#) ([StringArray](#) &label_array, const [String](#) &root_label, size_t start_index, size_t num_items)
create a partial array of labels by tagging root_label for a subset of entries in label_array. Uses [build_label\(\)](#).
- void [set_other_list_nodes](#) ()
convenience function used by [set_db_list_nodes\(method_tag\)](#) and [set_db_list_nodes\(method_index\)](#) to set the other list iterators once methodIter is set (based on pointers from the method specification).

Static Private Member Functions

- `void idr_kw_id_error` (const char *kw)
Error handler for missing required IDR keyword.
- `Int idr_find_id` (Int *id_pos, const Int cntr, const char *id, const char **id_list, const char *kw)
Function used by the keyword handlers to return the number of parsed instances of a particular keyword.
- `Int ** idr_get_int_table` (const struct FunctionData *parsed_data, Int identifier, Int &table_len, Int num_lists, Int list_entry_len)
Function for creating an IDR table of Ints.
- `Real ** idr_get_real_table` (const struct FunctionData *parsed_data, Int identifier, Int &table_len, Int num_lists, Int list_entry_len)
Function for creating an IDR table of Reals.
- `char *** idr_get_string_table` (const struct FunctionData *parsed_data, Int identifier, Int &table_len, Int num_lists, Int list_entry_len)
Function for creating an IDR table of strings.

Private Attributes

- `ParallelLibrary & parallelLib`
reference to the parallel_lib object passed from main
- `DataStrategy strategySpec`
the strategy specification (only one allowed) resulting from a call to `strategy_kwhandler()` or `insert_node()`
- `List< DataMethod > methodList`
list of method specifications, one for each call to `method_kwhandler()` or `insert_node()`
- `List< DataVariables > variablesList`
list of variables specifications, one for each call to `variables_kwhandler()` or `insert_node()`
- `List< DataInterface > interfaceList`
list of interface specifications, one for each call to `interface_kwhandler()` or `insert_node()`
- `List< DataResponses > responsesList`
list of responses specifications, one for each call to `responses_kwhandler()` or `insert_node()`
- `List< DataMethod >::iterator methodIter`
iterator identifying the active list node in methodList
- `List< DataVariables >::iterator variablesIter`
iterator identifying the active list node in variablesList
- `List< DataInterface >::iterator interfaceIter`
iterator identifying the active list node in interfaceList

- [List< DataResponses >::iterator responsesIter](#)
iterator identifying the active list node in responsesList
- `size_t strategyCntr`
counter for strategy specifications used in check_input
- `bool dbLocked`
prevents use of get_<type> data retrieval functions prior to a set_db_list_nodes invocation
- `bool dummyFlag`
prevents multiple deallocations for true DB/dummy_db

Static Private Attributes

- `ProblemDescDB * pDDBInstance`
pointer to the active object instance used within the static kwhandler functions in order to avoid the need for static data
- `Int ** intTable`
integer table populated in [idr_get_int_table\(\)](#)
- `Real ** realTable`
real table populated in [idr_get_real_table\(\)](#)
- `char *** stringTable`
string table populated in [idr_get_string_table\(\)](#)

8.81.1 Detailed Description

The database containing information parsed from the DAKOTA input file.

The [ProblemDescDB](#) class is a database for DAKOTA input file data that is populated by the Input Deck Reader (IDR) parser. When the parser reads a complete keyword (delimited by a newline), it calls the corresponding kwhandler function from this class which populates a data class object ([DataStrategy](#), [DataMethod](#), [DataVariables](#), [DataInterface](#), or [DataResponses](#)) and, for all cases except strategy, appends the object to a linked list (methodList, variablesList, interfaceList, or responsesList). No strategy linked list is used since only one strategy specification is allowed. For information on modifying the input parsing procedures, refer to [Dakota/docs/spec_change_instructions.txt](#)

8.81.2 Member Function Documentation

8.81.2.1 `void manage_inputs` ([CommandLineHandler](#) & *cmd_line_handler*)

parses the input file and populates the problem description database. This version reads from the dakota input filename passed with the "-input" option on the DAKOTA command line.

Manage command line inputs using the [CommandLineHandler](#) class and parse the input file using the Input Deck Reader (IDR) parsing system. IDR populates the [ProblemDescDB](#) object with the input file data.

8.81.2.2 void manage_inputs (const char * *dakota_input_file*)

parses the input file and populates the problem description database. This version reads from the dakota input filename passed in.

Parse the input file using the Input Deck Reader (IDR) parsing system. IDR populates the [ProblemDescDB](#) object with the input file data.

8.81.2.3 void set_db_model_type (const [String](#) & *model_type*) [inline]

set the model type

Used to avoid recursion in `DakotaModel::get_model()` by a sub model when `get_string("method.model_type")` is not reset by a sub iterator. Note: if more needs of this type arise, could add `set_<type>` member functions to parallel the existing `get_<type>` member functions.

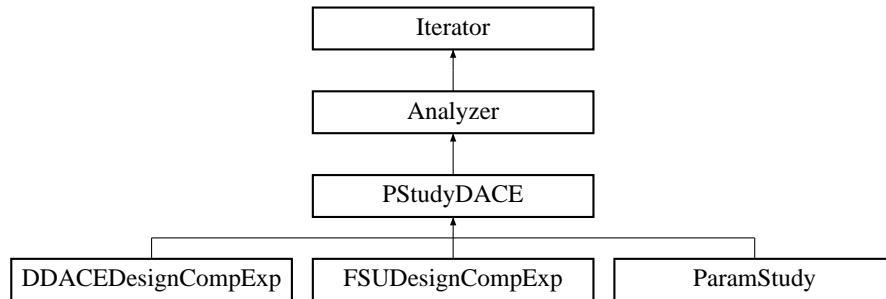
The documentation for this class was generated from the following files:

- ProblemDescDB.H
- ProblemDescDB.C

8.82 PStudyDACE Class Reference

Base class for managing common aspects of parameter studies and design of experiments methods.

Inheritance diagram for PStudyDACE::



Protected Member Functions

- [PStudyDACE](#) ([Model](#) &model)
constructor
- [~PStudyDACE](#) ()
destructor
- void [run_iterator](#) ()
run the iterator
- const [Variables](#) & [iterator_variable_results](#) () const
return the final iterator solution (variables)
- const [Response](#) & [iterator_response_results](#) () const
return the final iterator solution (response)
- void [print_iterator_results](#) (ostream &s) const
print the final iterator results
- virtual void [extract_trends](#) ()=0
Redefines the run_iterator virtual function for the PStudy/DACE branch.
- void [update_best](#) (const [RealVector](#) &vars, const [Response](#) &response, const int eval_num)
compares current evaluation to best evaluation and updates best

Protected Attributes

- [Variables bestVariables](#)
best variables found during the study
- [Response bestResponses](#)
best responses found during the study
- [Real bestObjFn](#)
best objective function found during the study
- [Real bestConViol](#)
best constraint violations found during the study. In the current approach, constraint violation reduction takes strict precedence over objective function reduction.
- [size_t numObjFns](#)
number of objective functions
- [size_t numLSqTerms](#)
number of least squares terms
- [size_t numNonlinIneqCons](#)
number of nonlinear inequality constraints
- [size_t numNonlinEqCons](#)
number of nonlinear equality constraints
- [RealVector multiObjWts](#)
vector of multiobjective weights
- [RealVector nonlinIneqLowerBnds](#)
vector of nonlinear inequality constraint lower bounds
- [RealVector nonlinIneqUpperBnds](#)
vector of nonlinear inequality constraint upper bounds
- [RealVector nonlinEqTargets](#)
vector of nonlinear equality constraint targets

8.82.1 Detailed Description

Base class for managing common aspects of parameter studies and design of experiments methods.

The [PStudyDACE](#) base class manages common data and functions, such as those involving the best solutions located during the parameter set evaluations or the printing of final results.

8.82.2 Member Function Documentation

8.82.2.1 void run_iterator() [inline, protected, virtual]

run the iterator

This function is the primary run function for the iterator class hierarchy. All derived classes need to redefine it.

Reimplemented from [Iterator](#).

The documentation for this class was generated from the following files:

- DakotaPStudyDACE.H
- DakotaPStudyDACE.C

8.83 Response Class Reference

Container class for response functions and their derivatives. [Response](#) provides the handle class.

Public Member Functions

- [Response](#) ()
default constructor
- [Response](#) (int num_params, const [ProblemDescDB](#) &problem_db)
standard constructor built from problem description database
- [Response](#) (int num_params, const [IntArray](#) &asv)
alternate constructor using limited data
- [Response](#) (const [Response](#) &response)
copy constructor
- [~Response](#) ()
destructor
- [Response operator=](#) (const [Response](#) &response)
assignment operator
- size_t [num_functions](#) () const
return the number of response functions
- const [IntArray](#) & [active_set_vector](#) () const
return the active set vector
- void [active_set_vector](#) (const [IntArray](#) &asv)
set the active set vector
- const [String](#) & [interface_id](#) () const
return the interface identifier
- void [interface_id](#) (const [String](#) &id)
set the interface identifier
- const [StringArray](#) & [fn_tags](#) () const
return the function identifier strings
- void [fn_tags](#) (const [StringArray](#) &tags)
set the function identifier strings
- const [RealVector](#) & [function_values](#) () const

return the function values

- void `function_values` (const `RealVector` &function_vals)
set the function values
- const `RealMatrix` & `function_gradients` () const
return the function gradients
- void `function_gradients` (const `RealMatrix` &function_grads)
set the function gradients
- const `RealMatrixArray` & `function_hessians` () const
return the function Hessians
- void `function_hessians` (const `RealMatrixArray` &function_hessians)
set the function Hessians
- void `read` (istream &s)
read a response object from an istream
- void `write` (ostream &s) const
write a response object to an ostream
- void `read_annotated` (istream &s)
read a response object in annotated format from an istream
- void `write_annotated` (ostream &s) const
write a response object in annotated format to an ostream
- void `read_tabular` (istream &s)
read responseRep::functionValues in tabular format from an istream
- void `write_tabular` (ostream &s) const
write responseRep::functionValues in tabular format to an ostream
- void `read` (`BiStream` &s)
read a response object from the binary restart stream
- void `write` (`BoStream` &s) const
write a response object to the binary restart stream
- void `read` (`MPIUnpackBuffer` &s)
read a response object from a packed MPI buffer
- void `write` (`MPIPackBuffer` &s) const
write a response object to a packed MPI buffer
- `Response copy` () const
a deep copy for use in history mechanisms

- `int data_size ()`
handle class forward to corresponding body class member function
- `void read_data (double *response_data)`
handle class forward to corresponding body class member function
- `void write_data (double *response_data)`
handle class forward to corresponding body class member function
- `void overlay (const Response &response)`
handle class forward to corresponding body class member function
- `void copy_results (const Response &response)`
handle class forward to corresponding body class member function
- `void purge_inactive ()`
handle class forward to corresponding body class member function
- `void reset ()`
handle class forward to corresponding body class member function
- `bool is_null () const`
function to check responseRep (does this handle contain a body)

Private Attributes

- `ResponseRep * responseRep`
pointer to the body (handle-body idiom)

Friends

- `bool operator== (const Response &resp1, const Response &resp2)`
equality operator
- `bool operator!= (const Response &resp1, const Response &resp2)`
inequality operator

8.83.1 Detailed Description

Container class for response functions and their derivatives. `Response` provides the handle class.

The `Response` class is a container class for an abstract set of functions (functionValues) and their first (functionGradients) and second (functionHessians) derivatives. The functions may involve objective and constraint functions (optimization data set), least squares terms (parameter estimation data set), or generic response functions (uncertainty quantification data set). It is not currently part of a class hierarchy, since the abstraction has been sufficiently general and has not required specialization. For memory efficiency, it employs the "handle-body idiom" approach to reference counting and representation sharing (see Coplien "Advanced C++", p. 58), for which `Response` serves as the handle and `ResponseRep` serves as the body.

8.83.2 Constructor & Destructor Documentation

8.83.2.1 [Response](#) ()

default constructor

Need a populated problem description database to build a meaningful [Response](#) object, so set the response-Rep=NULL in default constructor for efficiency. This then requires a check on NULL in the copy constructor, assignment operator, and destructor.

The documentation for this class was generated from the following files:

- DakotaResponse.H
- DakotaResponse.C

8.84 ResponseRep Class Reference

Container class for response functions and their derivatives. [ResponseRep](#) provides the body class.

Private Member Functions

- [ResponseRep](#) ()
default constructor
- [ResponseRep](#) (int num_params, const [ProblemDescDB](#) &problem_db)
standard constructor built from problem description database
- [ResponseRep](#) (int num_params, const [IntArray](#) &asv)
alternate constructor using limited data
- [~ResponseRep](#) ()
destructor
- void [read](#) (istream &s)
read a responseRep object from an istream
- void [write](#) (ostream &s) const
write a responseRep object to an ostream
- void [read_annotated](#) (istream &s)
read a responseRep object from an istream (annotated format)
- void [write_annotated](#) (ostream &s) const
write a responseRep object to an ostream (annotated format)
- void [read_tabular](#) (istream &s)
read functionValues from an istream (tabular format)
- void [write_tabular](#) (ostream &s) const
write functionValues to an ostream (tabular format)
- void [read](#) ([BiStream](#) &s)
read a responseRep object from a binary stream
- void [write](#) ([BoStream](#) &s) const
write a responseRep object to a binary stream
- void [read](#) ([MPIUnpackBuffer](#) &s)
read a responseRep object from a packed MPI buffer
- void [write](#) ([MPIPackBuffer](#) &s) const

write a responseRep object to a packed MPI buffer

- `int data_size ()`
return the number of doubles active in response. Used for sizing double response_data arrays passed into read_data and write_data.*
- `void read_data (double *response_data)`
read from an incoming double array*
- `void write_data (double *response_data)`
write to an incoming double array*
- `void overlay (const Response &response)`
add incoming response to functionValues/Gradients/Hessians
- `void copy_results (const Response &response)`
copy functionValues, functionGradients, & functionHessians data only. Do not copy ASV, tags, id's, etc. Used in place of assignment operator for retrieving results data from the data_pairs list without corrupting other data.
- `void purge_inactive ()`
Purge extraneous inactive data from the response object.
- `void reset ()`
resets functionValues, functionGradients, and functionHessians to zero

Private Attributes

- `int referenceCount`
number of handle objects sharing responseRep
- `RealVector functionValues`
abstract set of functions
- `RealMatrix functionGradients`
first derivatives
- `RealMatrixArray functionHessians`
second derivatives
- `IntArray responseASV`
Copy of `Iterator::activeSetVector` needed for operator overloaded I/O.
- `StringArray fnTags`
function identifiers used to improve output readability
- `String interfaceId`
the interface used to generate this response object. Used in `ParamResponsePair::vars_asv_compare`.

Friends

- `bool operator==(const ResponseRep &rep1, const ResponseRep &rep2)`
equality operator

8.84.1 Detailed Description

Container class for response functions and their derivatives. [ResponseRep](#) provides the body class.

The [ResponseRep](#) class is the "representation" of the response container class. It is the "body" portion of the "handle-body idiom" (see Coplien "Advanced C++", p. 58). The handle class ([Response](#)) provides for memory efficiency in management of multiple response objects through reference counting and representation sharing. The body class ([ResponseRep](#)) actually contains the response data (functionValues, functionGradients, functionHessians, etc.). The representation is hidden in that an instance of [ResponseRep](#) may only be created by [Response](#). Therefore, programmers create instances of the [Response](#) handle class, and only need to be aware of the handle/body mechanisms when it comes to managing shallow copies (shared representation) versus deep copies (separate representation used for history mechanisms).

8.84.2 Constructor & Destructor Documentation

8.84.2.1 [ResponseRep](#) (int num_params, const ProblemDescDB & problem_db) [private]

standard constructor built from problem description database

The standard constructor used by `Dakota::ModelRep`. An `interfaceId` identifies a set of results with the interface used in generating them, which allows `vars_asv_compare` to prevent duplicate detection on results from different interfaces.

8.84.2.2 [ResponseRep](#) (int num_params, const IntArray & asv) [private]

alternate constructor using limited data

Used for building a response object of the correct size on the fly (e.g., by slave analysis servers performing `execute()` on a `local_response`). `fnTags` and `interfaceId` are not needed for this purpose since they're not passed in the MPI send/rcv buffers (NOTE: if `interfaceId` becomes needed, it could be set from an `AppInt` attribute passed from `AppInt::serve()`). However, `NPSOLOptimizer`'s `user-defined functions` option uses this constructor to build `bestResponses` and `bestResponses` needs `fnTags` for I/O, so construction of `fnTags` has been added.

8.84.3 Member Function Documentation

8.84.3.1 `void read (istream & s)` [private]

read a `responseRep` object from an `istream`

ASCII version of read needs capabilities for capturing data omissions or formatting errors (resulting from user error or asynch race condition) and analysis failures (resulting from nonconvergence, instability, etc.).

8.84.3.2 void write (ostream & s) const [private]

write a responseRep object to an ostream

ASCII version of write.

8.84.3.3 void read_annotated (istream & s) [private]

read a responseRep object from an istream (annotated format)

read_annotated version is used for neutral file translation of restart files. Since objects are built solely from this data, annotations are used. This version closely mirrors the [BiStream](#) version.

8.84.3.4 void write_annotated (ostream & s) const [private]

write a responseRep object to an ostream (annotated format)

write_annotated version is used for neutral file translation of restart files. Since objects need to be build solely from this data, annotations are used. This version closely mirrors the [BoStream](#) version, with the exception of the use of white space between fields.

8.84.3.5 void read_tabular (istream & s) [private]

read functionValues from an istream (tabular format)

read_tabular is used to read functionValues in tabular format. It is currently only used by Approximation-Interfaces in reading samples from a file. There is insufficient data in a tabular file to build complete response objects; rather, the response object must be constructed a priori and then its functionValues can be set.

8.84.3.6 void write_tabular (ostream & s) const [private]

write functionValues to an ostream (tabular format)

write_tabular is used for output of functionValues in a tabular format for convenience in post-processing/plotting of DAKOTA results.

8.84.3.7 void read (BiStream & s) [private]

read a responseRep object from a binary stream

Binary version differs from ASCII version in 2 primary ways: (1) it lacks formatting. (2) the [Response](#) has not been sized a priori. In reading data from the binary restart file, a [ParamResponsePair](#) was constructed with its default constructor which called the [Response](#) default constructor. Therefore, we must first read sizing data and resize all of the arrays.

8.84.3.8 void write (BoStream & s) const [private]

write a responseRep object to a binary stream

Binary version differs from ASCII version in 2 primary ways: (1) It lacks formatting. (2) In reading data from the binary restart file, ParamResponsePairs are constructed with their default constructor which calls the [Response](#) default constructor. Therefore, we must first write sizing data so that ResponseRep::read(BoStream& s) can resize the arrays.

8.84.3.9 void read (MPIUnpackBuffer & s) [private]

read a responseRep object from a packed MPI buffer

UnpackBuffer version differs from [BiStream](#) version in the omission of interfaceId and fnTags. Master processor retains function tags and interface ids and communicates asv and response data only with slaves.

8.84.3.10 void write (MPIPackBuffer & s) const [private]

write a responseRep object to a packed MPI buffer

[MPIPackBuffer](#) version differs from [BoStream](#) version only in omissions of interfaceId and fnTags. The master processor retains tags and ids and communicates asv and response data only with slaves.

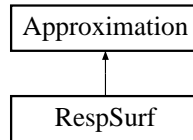
The documentation for this class was generated from the following files:

- DakotaResponse.H
- DakotaResponse.C

8.85 RespSurf Class Reference

Derived approximation class for polynomial regression.

Inheritance diagram for RespSurf::



Public Member Functions

- [RespSurf](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_acv)
constructor
- [~RespSurf](#) ()
destructor

Protected Member Functions

- void [find_coefficients](#) ()
Least squares fit to data using a singular value decomposition.
- int [required_samples](#) ()
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- const [RealVector](#) & [approximation_coefficients](#) ()
return the coefficient array computed by [find_coefficients\(\)](#)
- Real [get_value](#) (const [RealVector](#) &x)
retrieve the approximate function value for a given parameter vector
- const [RealBaseVector](#) & [get_gradient](#) (const [RealVector](#) &x)
retrieve the approximate function gradient for a given parameter vector

Private Attributes

- int [numCoeffs](#)
number of coefficients used by the polynomial model
- [RealVector](#) [polyCoeffs](#)

vector of polynomial coefficients

- short `polyOrder`

flag to indicate a linear (value = 1), quadratic (value = 2), or cubic (value = 3) polynomial model

8.85.1 Detailed Description

Derived approximation class for polynomial regression.

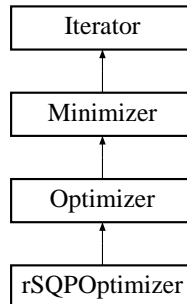
The `RespSurf` class computes a linear, quadratic, or cubic polynomial fit to data. The polynomial has either $n+1$ (linear case), $(n+1)*(n+2)/2$ (quadratic case), or $(n^3+6n^2+11n+6)/6$ (cubic case) coefficients for n variables. A least squares estimation of the polynomial coefficients is performed using LAPACK'S linear least squares subroutine DGELSS which uses a singular value decomposition method.

The documentation for this class was generated from the following files:

- `RespSurf.H`
- `RespSurf.C`

8.86 rSQPOptimizer Class Reference

Inheritance diagram for rSQPOptimizer::



Public Member Functions

- **rSQPOptimizer** ([Model](#) &model)
- **int num_objectives** () const
- **const RealVector & lin_ineq_lb** () const
- **const RealVector & lin_ineq_ub** () const
- **const RealVector & nonlin_ineq_lb** () const
- **const RealVector & nonlin_ineq_ub** () const
- **const RealVector & lin_eq_targ** () const
- **const RealVector & nonlin_eq_targ** () const
- **const RealMatrix & lin_eq_jac** () const
- **const RealMatrix & lin_ineq_jac** () const

Overridden from Optimizer

- **void find_optimum** ()
Used within the optimizer branch for computing the optimal solution. Redefines the run_iterator virtual function for the optimizer branch.

Private Attributes

- [Model](#) * **model_**
- NLPInterfacePack::NLPDakota **nlp_**

8.86.1 Detailed Description

Wrapper class for the rSQP++ optimization library.

The [rSQPOptimizer](#) class provides a wrapper for rSQP++, a C++ sequential quadratic programming library written by Roscoe Bartlett. rSQP++ can currently be used in NAND mode, although use of its SAND

mode for reduced-space SQP is planned. [rSQPOptimizer](#) uses a NLPDakota object to perform the function evaluations.

The user input mappings will ultimately include: `max_iterations`, `convergence_tolerance`, `output_verbosity`.

The documentation for this class was generated from the following files:

- `rSQPOptimizer.H`
- `rSQPOptimizer.C`

8.87 SGOPTApplication Class Reference

Maps the evaluation functions used by SGOPT algorithms to the DAKOTA evaluation functions.

Public Member Functions

- [SGOPTApplication](#) ([SGOPTOptimizer](#) *instance, int type)
constructor
- [~SGOPTApplication](#) ()
destructor
- int [DoEval](#) (OptPoint &pt, OptResponse *response, int synch_flag)
launch a function evaluation either synchronously or asynchronously
- int [synchronize](#) ()
blocking retrieval of all pending jobs
- int [next_eval](#) (int &id)
nonblocking query and retrieval of a job if completed
- void [dakota_asynch_flag](#) (const bool &asynch_flag)
set dakotaModelAsynchFlag

Private Member Functions

- void [copy](#) (const [Response](#) &, OptResponse &)
copy data from a [Response](#) object to an SGOPT OptResponse object

Private Attributes

- [SGOPTOptimizer](#) * [sgoptOptInstance](#)
pointer to the [SGOPTOptimizer](#) instance for access to optimizer data
- [IntArray](#) [activeSetVector](#)
copy/conversion of the SGOPT request vector
- bool [dakotaModelAsynchFlag](#)
a flag for asynchronous DAKOTA evaluations
- [ResponseList](#) [dakotaResponseList](#)
list of DAKOTA responses returned by [synchronize_nowait\(\)](#)

- [IntList dakotaCompletionList](#)

list of DAKOTA completions returned by synchronize_nowait_completions()

8.87.1 Detailed Description

Maps the evaluation functions used by SGOPT algorithms to the DAKOTA evaluation functions.

[SGOPTApplication](#) is a DAKOTA class that is derived from SGOPT's AppInterface hierarchy. It redefines a variety of virtual SGOPT functions to use the corresponding DAKOTA functions. This is a more flexible algorithm library interfacing approach than can be obtained with the function pointer approaches used by [NPSOLOptimizer](#) and [SNLLOptimizer](#).

8.87.2 Member Function Documentation

8.87.2.1 `int DoEval (OptPoint & pt, OptResponse * prob_response, int synch_flag)`

launch a function evaluation either synchronously or asynchronously

Converts SGOPT variables and request vector to DAKOTA variables and active set vector, performs a DAKOTA function evaluation with synchronization governed by `synch_flag`, and then copies the [Response](#) data to the SGOPT response (synchronous) or bookkeeps the SGOPT response object (asynchronous).

8.87.2.2 `int synchronize ()`

blocking retrieval of all pending jobs

Blocking synchronize of asynchronous DAKOTA jobs followed by conversion of the [Response](#) objects to SGOPT response objects.

8.87.2.3 `int next_eval (int & id)`

nonblocking query and retrieval of a job if completed

Nonblocking job retrieval. Finds a completion (if available), populates the SGOPT response, and sets `id` to the completed job's id. Else set `id = -1`.

8.87.2.4 `void dakota_async_flag (const bool & async_flag) [inline]`

set `dakotaModelAsyncFlag`

This function is needed to publish the iterator's `asyncFlag` at run time (`asyncFlag` not available at construction).

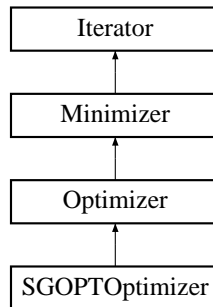
The documentation for this class was generated from the following files:

- [SGOPTApplication.H](#)
- [SGOPTApplication.C](#)

8.88 SGOPTOptimizer Class Reference

Wrapper class for the SGOPT optimization library.

Inheritance diagram for SGOPTOptimizer::



Public Member Functions

- [SGOPTOptimizer \(Model &model\)](#)
constructor
- [~SGOPTOptimizer \(\)](#)
destructor
- void [find_optimum \(\)](#)
Performs the iterations to determine the optimal solution.

Private Member Functions

- void [set_method_options \(\)](#)
sets options for the methods based on user specifications

Private Attributes

- [String exploratoryMoves](#)
user input for desired pattern search algorithm variant
- bool [discreteAppFlag](#)
convenience flag for integer vs. real applications
- `PM_LCG * linConGenerator`
Pointer to random number generator.

- BaseOptimizer * [baseOptimizer](#)
Pointer to SGOPT base optimizer object.
- AppInterface * [sgoptApplication](#)
pointer to the SGOPTApplication object
- RealOptProblem * [realProblem](#)
pointer to RealOptProblem object
- IntOptProblem * [intProblem](#)
pointer to IntOptProblem object
- PGAreal * [pGAREalOptimizer](#)
pointer to PGAreal object
- PGAint * [pGAIntOptimizer](#)
pointer to PGAint object
- EPSA * [ePSAOptimizer](#)
pointer to EPSA object
- PatternSearch * [patternSearchOptimizer](#)
pointer to PatternSearch object
- APPSOpt * [aPPSOptimizer](#)
pointer to APPSOpt object
- SWOpt * [SWOptimizer](#)
pointer to SWOpt object
- sMCreal * [sMCrealOptimizer](#)
pointer to sMCreal object

8.88.1 Detailed Description

Wrapper class for the SGOPT optimization library.

The [SGOPTOptimizer](#) class provides a wrapper for SGOPT, a Sandia-developed C++ optimization library of genetic algorithms, pattern search methods, and other nongradient-based techniques. It uses an [SGOPTApplication](#) object to perform the function evaluations.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `solution_accuracy` and `max_cpu_time` are mapped into SGOPT's `max_iters`, `max_neval`, `ftol`, `accuracy`, and `max_time` data attributes. An output setting of `verbose` is passed to SGOPT's `set_output()` function and a setting of `debug` activates output of method initialization and sets the SGOPT `debug` attribute to 10000. SGOPT methods assume asynchronous operations whenever the algorithm has independent evaluations which can be performed simultaneously (implicit parallelism). Therefore, parallel configuration is not mapped into the method, rather it is used in [SGOPTApplication](#) to control whether or not an asynchronous evaluation request from the method is honored by the model (exception: pattern search exploratory moves is set to `best_all` for parallel function evaluations). Refer to [Hart, W.E., 1997] for additional information on SGOPT objects and controls.

8.88.2 Constructor & Destructor Documentation

8.88.2.1 [SGOPTOptimizer](#) (*Model & model*)

constructor

The constructor allocates the objects and populates the class member pointer attributes.

8.88.2.2 [~SGOPTOptimizer](#) ()

destructor

The destructor deallocates the class member pointer attributes.

8.88.3 Member Function Documentation

8.88.3.1 `void find_optimum (void) [virtual]`

Performs the iterations to determine the optimal solution.

`find_optimum` redefines the [Optimizer](#) virtual function to perform the optimization using SGOPT. It first sets up the problem data, then executes `minimize()` on the SGOPT algorithm, and finally catalogues the results.

Implements [Optimizer](#).

8.88.3.2 `void set_method_options () [private]`

sets options for the methods based on user specifications

`set_method_options` propagates DAKOTA user input to the appropriate SGOPT objects.

8.88.4 Member Data Documentation

8.88.4.1 `AppInterface* sgoptApplication [private]`

pointer to the [SGOPTApplication](#) object

[SGOPTApplication](#) is a DAKOTA class derived from the SGOPT `AppInterface` class. It redefines the virtual SGOPT evaluation functions to use DAKOTA evaluation functions.

The documentation for this class was generated from the following files:

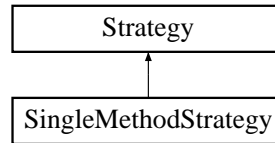
- [SGOPTOptimizer.H](#)

- SGOPTOptimizer.C

8.89 SingleMethodStrategy Class Reference

Simple fall-through strategy for running a single iterator on a single model.

Inheritance diagram for SingleMethodStrategy::



Public Member Functions

- [SingleMethodStrategy \(ProblemDescDB &problem_db\)](#)
constructor
- [~SingleMethodStrategy \(\)](#)
destructor
- void [run_strategy \(\)](#)
Perform the strategy by executing selectedIterator on userDefinedModel.
- const [Variables](#) & [strategy_variable_results \(\)](#) const
return the final solution from selectedIterator (variables)
- const [Response](#) & [strategy_response_results \(\)](#) const
return the final solution from selectedIterator (response)
- [IteratorList](#) & [iterators](#) (bool recurse_flag=true)
returns selectedIterator and any subordinate iterators
- [ModelList](#) & [models](#) (bool recurse_flag=true)
returns userDefinedModel and any subordinate models

Private Attributes

- [Model](#) [userDefinedModel](#)
the model to be iterated
- [Iterator](#) [selectedIterator](#)
the iterator

8.89.1 Detailed Description

Simple fall-through strategy for running a single iterator on a single model.

This strategy executes a single iterator on a single model. Since it does not provide coordination for multiple iterators and models, it can be considered to be a "fall-through" strategy in that it allows control to fall through immediately to the iterator.

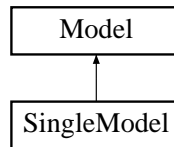
The documentation for this class was generated from the following files:

- SingleMethodStrategy.H
- SingleMethodStrategy.C

8.90 SingleModel Class Reference

Derived model class which utilizes a single interface to map variables into responses.

Inheritance diagram for SingleModel::



Public Member Functions

- [SingleModel](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~SingleModel](#) ()
destructor

Protected Member Functions

- [Interface](#) & [interface](#) ()
return userDefinedInterface
- void [derived_compute_response](#) (const [IntArray](#) &asv)
portion of [compute_response\(\)](#) specific to [SingleModel](#) (invokes a synchronous map() on userDefinedInterface)
- void [derived_asynch_compute_response](#) (const [IntArray](#) &asv)
portion of [asynch_compute_response\(\)](#) specific to [SingleModel](#) (invokes an asynchronous map() on userDefinedInterface)
- const [ResponseArray](#) & [derived_synchronize](#) ()
portion of [synchronize\(\)](#) specific to [SingleModel](#) (invokes synch() on userDefinedInterface)
- const [ResponseList](#) & [derived_synchronize_nowait](#) ()
portion of [synchronize_nowait\(\)](#) specific to [SingleModel](#) (invokes synch_nowait() on userDefinedInterface)
- const [IntList](#) & [synchronize_nowait_completions](#) ()
return completion id's matching response list from [synchronize_nowait](#) (request forwarded to userDefinedInterface)
- void [component_parallel_mode](#) (int mode)
[SingleModel](#) only supports parallelism in userDefinedInterface, so this virtual function redefinition is simply a sanity check.

- [String local_eval_synchronization](#) ()
return userDefinedInterface synchronization setting
- [int local_eval_concurrency](#) ()
return userDefinedInterface asynchronous evaluation concurrency
- [bool derived_master_overload](#) () const
flag which prevents overloading the master with a multiprocessor evaluation (request forwarded to userDefinedInterface)
- [void derived_init_communicators](#) (const int &max_iterator_concurrency)
set up SingleModel for parallel operations (request forwarded to userDefinedInterface)
- [void derived_init_serial](#) ()
set up SingleModel for serial operations (request forwarded to userDefinedInterface).
- [void reset_communicators](#) ()
reset communicator partition data for the SingleModel (request forwarded to userDefinedInterface)
- [void free_communicators](#) ()
deallocate communicator partitions for the SingleModel (request forwarded to userDefinedInterface)
- [void serve](#) ()
Service userDefinedInterface job requests received from the master. Completes when a termination message is received from stop_servers().
- [void stop_servers](#) ()
executed by the master to terminate userDefinedInterface server operations when SingleModel iteration is complete.
- [int total_eval_counter](#) () const
return the total evaluation count for the SingleModel (request forwarded to userDefinedInterface)
- [int new_eval_counter](#) () const
return the new evaluation count for the SingleModel (request forwarded to userDefinedInterface)

Private Attributes

- [Interface userDefinedInterface](#)
the interface used for mapping variables to responses

8.90.1 Detailed Description

Derived model class which utilizes a single interface to map variables into responses.

The [SingleModel](#) class is the simplest of the derived model classes. It provides the capabilities the old [Model](#) class, prior to the development of layered and nested model extensions. The derived response computation and synchronization functions utilize a single interface to perform the function evaluations.

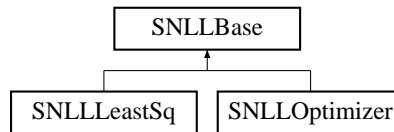
The documentation for this class was generated from the following files:

- SingleModel.H
- SingleModel.C

8.91 SNLLBase Class Reference

Base class for OPT++ optimization and least squares methods.

Inheritance diagram for SNLLBase::



Public Member Functions

- [SNLLBase \(\)](#)
default constructor
- [SNLLBase \(Model &model\)](#)
standard constructor
- [~SNLLBase \(\)](#)
destructor

Protected Member Functions

- void [copy_con_vals](#) (const [RealVector](#) &local_fn_vals, [ColumnVector](#) &g, const size_t &offset)
convenience function for copying local_fn_vals to g; used by constraint evaluator functions
- void [copy_con_vals](#) (const [ColumnVector](#) &g, [RealVector](#) &local_fn_vals, const size_t &offset)
convenience function for copying g to local_fn_vals; used in final solution logging
- void [copy_con_grad](#) (const [RealMatrix](#) &local_fn_grads, [Matrix](#) &grad_g, const size_t &offset)
convenience function for copying local_fn_grads to grad_g; used by constraint evaluator functions
- void [copy_con_hess](#) (const [RealMatrixArray](#) &local_fn_hessians, [OptppArray](#)< [SymmetricMatrix](#) > &hess_g, const size_t &offset)
convenience function for copying local_fn_hessians to hess_g; used by constraint evaluator functions
- void [pre_instantiate](#) (const [String](#) &merit_fn, bool bound_constr_flag, const int &num_constr)
convenience function for setting OPT++ options prior to the method instantiation
- void [post_instantiate](#) (const int &num_cv, bool vendor_num_grad_flag, const [String](#) &finite_diff_type, const [Real](#) &fdss, const int &max_iter, const int &max_fn_evals, const [Real](#) &conv_tol, const [Real](#) &grad_tol, const [Real](#) &max_step, bool bound_constr_flag, const int &num_constr, bool debug_output, [OptimizeClass](#) *the_optimizer, [NLP0](#) *nlf_objective, [FDNLF1](#) *fd_nlf1, [FDNLF1](#) *fd_nlf1_con)

convenience function for setting OPT++ options after the method instantiation

- void `pre_run` (NLP0 *nlf_objective, NLP *nlp_constraint, const [RealVector](#) &init_pt, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds, const [RealMatrix](#) &lin_ineq_coeffs, const [RealVector](#) &lin_ineq_l_bnds, const [RealVector](#) &lin_ineq_u_bnds, const [RealMatrix](#) &lin_eq_coeffs, const [RealVector](#) &lin_eq_targets, const [RealVector](#) &nln_ineq_l_bnds, const [RealVector](#) &nln_ineq_u_bnds, const [RealVector](#) &nln_eq_targets)

convenience function for OPT++ configuration prior to the method invocation

- void `post_run` (NLP0 *nlf_objective)

convenience function for setting OPT++ options after the method instantiations

Static Protected Member Functions

- void `init_fn` (int n, ColumnVector &x)

An initialization mechanism provided by OPT++ (not currently used).

Protected Attributes

- [String](#) `searchMethod`

value_based_line_search, gradient_based_line_search, trust_region, or tr_pds

- [SearchStrategy](#) `searchStrat`

enum: LineSearch, TrustRegion, or TrustPDS

- [MeritFcn](#) `meritFn`

enum: NormFmu, ArgaezTapi, or VanShanno

- bool `constantASVFlag`

flags a user selection of active_set_vector == constant. By mapping this into mode override, reliance on duplicate detection can be avoided.

Static Protected Attributes

- [Minimizer](#) * `optLSqInstance`

pointer to the active base class object instance used within the static evaluator functions in order to avoid the need for static data

- bool `modeOverrideFlag`

flags OPT++ mode override (for combining value, gradient, and Hessian requests)

- [EvalType](#) `lastFnEvalLocn`

an enum used to track whether an nlf evaluator or a constraint evaluator was the last location of a function evaluation

- int `lastEvalMode`

copy of mode from constraint evaluators

- [RealVector lastEvalVars](#)

copy of variables from constraint evaluators

8.91.1 Detailed Description

Base class for OPT++ optimization and least squares methods.

The [SNLLBase](#) class provides a common base class for [SNLLOptimizer](#) and [SNLLLeastSq](#), both of which are wrappers for OPT++, a C++ optimization library from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site.

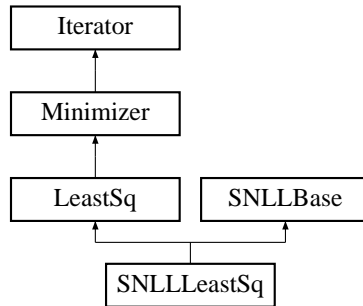
The documentation for this class was generated from the following files:

- SNLLBase.H
- SNLLBase.C

8.92 SNLLLeastSq Class Reference

Wrapper class for the OPT++ optimization library.

Inheritance diagram for SNLLLeastSq::



Public Member Functions

- [SNLLLeastSq \(Model &model\)](#)
constructor
- [~SNLLLeastSq \(\)](#)
destructor
- void [minimize_residuals \(\)](#)
Performs the iterations to determine the least squares solution.

Static Private Member Functions

- void [nlf2_evaluator_gn](#) (int mode, int n, const ColumnVector &x, Real &f, ColumnVector &grad_f, SymmetricMatrix &hess_f, int &result_mode)
objective function evaluator function which obtains values and gradients for least square terms and computes objective function value, gradient, and Hessian using the Gauss-Newton approximation.
- void [constraint1_evaluator_gn](#) (int mode, int n, const ColumnVector &x, ColumnVector &g, Matrix &grad_g, int &result_mode)
constraint evaluator function which provides constraint values and gradients to OPT++ Gauss-Newton methods.
- void [constraint2_evaluator_gn](#) (int mode, int n, const ColumnVector &x, ColumnVector &g, Matrix &grad_g, OptppArray< SymmetricMatrix > &hess_g, int &result_mode)
constraint evaluator function which provides constraint values, gradients, and Hessians to OPT++ Gauss-Newton methods.

Private Attributes

- NLP0 * [nlfObjective](#)
objective NLF base class pointer
- NLP0 * [nlfConstraint](#)
constraint NLF base class pointer
- NLP * [nlpConstraint](#)
constraint NLP pointer
- NLF2 * [nlf2](#)
pointer to objective NLF for full Newton optimizers
- NLF2 * [nlf2Con](#)
pointer to constraint NLF for full Newton optimizers
- NLF1 * [nlf1Con](#)
pointer to constraint NLF for Quasi Newton optimizers
- OptimizeClass * [theOptimizer](#)
optimizer base class pointer
- OptNewton * [optnewton](#)
Newton optimizer pointer.
- OptBCNewton * [optbcnewton](#)
Bound constrained Newton optimizer pointer.
- OptDHNIPS * [optdhnips](#)
Disaggregated Hessian NIPS optimizer ptr.

Static Private Attributes

- SNLLLeastSq * [snllSqInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

8.92.1 Detailed Description

Wrapper class for the OPT++ optimization library.

The [SNLLLeastSq](#) class provides a wrapper for OPT++, a C++ optimization library of nonlinear programming and pattern search techniques from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function, a static member, or accessed by static pointer.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `max_step`, `gradient_tolerance`, `search_method`, and `search_scheme_size` are set using OPT++'s `setMaxIter()`, `setMaxFeval()`, `setFcnTol()`, `setMaxStep()`, `setGradTol()`, `setSearchStrategy()`, and `setSSS()` member functions, respectively; output verbosity is used to toggle OPT++'s debug mode using the `setDebug()` member function. Internal to OPT++, there are 3 search strategies, while the DAKOTA `search_method` specification supports 4 (`value_based_line_search`, `gradient_based_line_search`, `trust_region`, or `tr_pds`). The difference stems from the "is_expensive" flag in OPT++. If the search strategy is `LineSearch` and "is_expensive" is turned on, then the `value_based_line_search` is used. Otherwise (the "is_expensive" default is off), the algorithm will use the `gradient_based_line_search`. Refer to [Meza, J.C., 1994] and to the OPT++ source in the `Dakota/VendorOptimizers/opt++` directory for information on OPT++ class member functions.

8.92.2 Member Function Documentation

8.92.2.1 `void nlf2_evaluator_gn(int mode, int n, const ColumnVector & x, Real & f, ColumnVector & grad_f, SymmetricMatrix & hess_f, int & result_mode)` [static, private]

objective function evaluator function which obtains values and gradients for least square terms and computes objective function value, gradient, and Hessian using the Gauss-Newton approximation.

This `nlf2` evaluator function is used for the Gauss-Newton method in order to exploit the special structure of the nonlinear least squares problem. Here, $fx = \sum (T_i - Tbar_i)^2$ and `Response` is made up of residual functions and their gradients along with any nonlinear constraints. The objective function and its gradient vector and Hessian matrix are computed directly from the residual functions and their derivatives (which are returned from the `Response` object).

8.92.2.2 `void constraint1_evaluator_gn(int mode, int n, const ColumnVector & x, ColumnVector & g, ::Matrix & grad_g, int & result_mode)` [static, private]

constraint evaluator function which provides constraint values and gradients to OPT++ Gauss-Newton methods.

While it does not employ the Gauss-Newton approximation, it is distinct from `constraint1_evaluator()` due to its need to anticipate the required modes for the least squares terms. This constraint evaluator function is used with diagggregated Hessian NIPS and is currently active.

8.92.2.3 `void constraint2_evaluator_gn(int mode, int n, const ColumnVector & x, ColumnVector & g, ::Matrix & grad_g, OptppArray< SymmetricMatrix > & hess_g, int & result_mode)` [static, private]

constraint evaluator function which provides constraint values, gradients, and Hessians to OPT++ Gauss-Newton methods.

While it does not employ the Gauss-Newton approximation, it is distinct from `constraint2_evaluator()` due to its need to anticipate the required modes for the least squares terms. This constraint evaluator function is used with full Newton NIPS and is currently inactive.

The documentation for this class was generated from the following files:

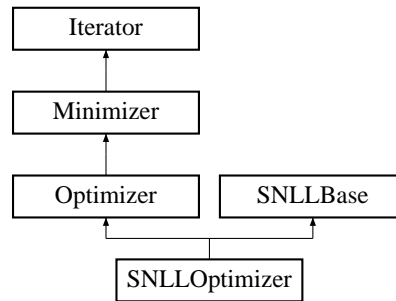
- `SNLLLeastSq.H`

- SNLLLeastSq.C

8.93 SNLLOptimizer Class Reference

Wrapper class for the OPT++ optimization library.

Inheritance diagram for SNLLOptimizer::



Public Member Functions

- [SNLLOptimizer](#) ([Model](#) &model)
standard constructor
- [SNLLOptimizer](#) (const [RealVector](#) &initial_point, const [RealVector](#) &var_lower_bnds, const [RealVector](#) &var_upper_bnds, int num_lin_ineq, int num_lin_eq, int num_nln_ineq, int num_nln_eq, const [RealMatrix](#) &lin_ineq_coeffs, const [RealVector](#) &lin_ineq_lower_bnds, const [RealVector](#) &lin_ineq_upper_bnds, const [RealMatrix](#) &lin_eq_coeffs, const [RealVector](#) &lin_eq_targets, const [RealVector](#) &nonlin_ineq_lower_bnds, const [RealVector](#) &nonlin_ineq_upper_bnds, const [RealVector](#) &nonlin_eq_targets, void(*user_obj_eval)(int mode, int n, const [ColumnVector](#) &x, [Real](#) &f, [ColumnVector](#) &grad_f, int &result_mode), void(*user_con_eval)(int mode, int n, const [ColumnVector](#) &x, [ColumnVector](#) &g,::[Matrix](#) &grad_g, int &result_mode))
alternate constructor for instantiations "on the fly"
- [~SNLLOptimizer](#) ()
destructor
- void [find_optimum](#) ()
Performs the iterations to determine the optimal solution.

Static Private Member Functions

- void [nlf0_evaluator](#) (int n, const [ColumnVector](#) &x, [Real](#) &f, int &result_mode)
objective function evaluator function for OPT++ methods which require only function values.
- void [nlf1_evaluator](#) (int mode, int n, const [ColumnVector](#) &x, [Real](#) &f, [ColumnVector](#) &grad_f, int &result_mode)
objective function evaluator function which provides function values and gradients to OPT++ methods.

- void `nlf2_evaluator` (int mode, int n, const ColumnVector &x, Real &f, ColumnVector &grad_f, SymmetricMatrix &hess_f, int &result_mode)
objective function evaluator function which provides function values, gradients, and Hessians to OPT++ methods.
- void `constraint0_evaluator` (int n, const ColumnVector &x, ColumnVector &g, int &result_mode)
constraint evaluator function for OPT++ methods which require only constraint values.
- void `constraint1_evaluator` (int mode, int n, const ColumnVector &x, ColumnVector &g, Matrix &grad_g, int &result_mode)
constraint evaluator function which provides constraint values and gradients to OPT++ methods.
- void `constraint2_evaluator` (int mode, int n, const ColumnVector &x, ColumnVector &g, Matrix &grad_g, OptppArray< SymmetricMatrix > &hess_g, int &result_mode)
constraint evaluator function which provides constraint values, gradients, and Hessians to OPT++ methods.

Private Attributes

- NLP0 * `nlfObjective`
objective NLF base class pointer
- NLP0 * `nlfConstraint`
constraint NLF base class pointer
- NLP * `nlpConstraint`
constraint NLP pointer
- NLF0 * `nlf0`
pointer to objective NLF for nongradient optimizers
- NLF1 * `nlf1`
pointer to objective NLF for (analytic) gradient-based optimizers
- NLF1 * `nlf1Con`
pointer to constraint NLF for (analytic) gradient-based optimizers
- FDNLF1 * `fdnlf1`
pointer to objective NLF for (finite diff) gradient-based optimizers
- FDNLF1 * `fdnlf1Con`
pointer to constraint NLF for (finite diff) gradient-based optimizers
- NLF2 * `nlf2`
pointer to objective NLF for full Newton optimizers
- NLF2 * `nlf2Con`
pointer to constraint NLF for full Newton optimizers

- [OptimizeClass * theOptimizer](#)
optimizer base class pointer
- [OptPDS * optpds](#)
PDS optimizer pointer.
- [OptCG * optcg](#)
CG optimizer pointer.
- [OptLBFGS * optlbfgs](#)
L-BFGS optimizer pointer.
- [OptNewton * optnewton](#)
Newton optimizer pointer.
- [OptQNewton * optqnewton](#)
Quasi-Newton optimizer pointer.
- [OptFDNewton * optfdnewton](#)
Finite Difference Newton optimizer pointer.
- [OptBCNewton * optbcnewton](#)
Bound constrained Newton optimizer pointer.
- [OptBCQNewton * optbcqnewton](#)
Bnd constrained Quasi-Newton optimizer ptr.
- [OptBCFDNewton * optbcfdnewton](#)
Bnd constrained FD-Newton optimizer ptr.
- [OptNIPS * optnips](#)
NIPS optimizer pointer.
- [OptQNIPS * optqnips](#)
Quasi-Newton NIPS optimizer pointer.
- [OptFDNIPS * optfdnips](#)
Finite Difference NIPS optimizer pointer.
- [String setUpType](#)
flag for iteration mode: "model" (normal usage) or "user_functions" (user-supplied functions mode for "on the fly" instantiations). [NonDReliability](#) currently uses the user_functions mode.
- [RealVector initialPoint](#)
holds initial point passed in for "user_functions" mode.
- [RealVector lowerBounds](#)
holds variable lower bounds passed in for "user_functions" mode.

- [RealVector](#) upperBounds

holds variable upper bounds passed in for "user_functions" mode.

Static Private Attributes

- [SNLLOptimizer](#) * snllOptInstance

pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data

8.93.1 Detailed Description

Wrapper class for the OPT++ optimization library.

The [SNLLOptimizer](#) class provides a wrapper for OPT++, a C++ optimization library of nonlinear programming and pattern search techniques from the Computational Sciences and Mathematics Research (CSMR) department at Sandia's Livermore CA site. It uses a function pointer approach for which passed functions must be either global functions or static member functions. Any attribute used within static member functions must be either local to that function, a static member, or accessed by static pointer.

The user input mappings are as follows: `max_iterations`, `max_function_evaluations`, `convergence_tolerance`, `max_step`, `gradient_tolerance`, `search_method`, and `search_scheme_size` are set using OPT++'s `setMaxIter()`, `setMaxFeval()`, `setFcnTol()`, `setMaxStep()`, `setGradTol()`, `setSearchStrategy()`, and `setSSS()` member functions, respectively; `output_verbosity` is used to toggle OPT++'s debug mode using the `setDebug()` member function. Internal to OPT++, there are 3 search strategies, while the DAKOTA `search_method` specification supports 4 (`value_based_line_search`, `gradient_based_line_search`, `trust_region`, or `tr_pds`). The difference stems from the "is_expensive" flag in OPT++. If the search strategy is `LineSearch` and "is_expensive" is turned on, then the `value_based_line_search` is used. Otherwise (the "is_expensive" default is off), the algorithm will use the `gradient_based_line_search`. Refer to [Meza, J.C., 1994] and to the OPT++ source in the `Dakota/VendorOptimizers/opt++` directory for information on OPT++ class member functions.

8.93.2 Constructor & Destructor Documentation

8.93.2.1 [SNLLOptimizer](#) (Model & model)

standard constructor

This constructor is used for normal instantiations using data from the [ProblemDescDB](#).

8.93.2.2 SNLLOptimizer (const [RealVector](#) & *initial_point*, const [RealVector](#) & *var_lower_bnds*, const [RealVector](#) & *var_upper_bnds*, int *num_lin_ineq*, int *num_lin_eq*, int *num_nln_ineq*, int *num_nln_eq*, const [RealMatrix](#) & *lin_ineq_coeffs*, const [RealVector](#) & *lin_ineq_lower_bnds*, const [RealVector](#) & *lin_ineq_upper_bnds*, const [RealMatrix](#) & *lin_eq_coeffs*, const [RealVector](#) & *lin_eq_targets*, const [RealVector](#) & *nonlin_ineq_lower_bnds*, const [RealVector](#) & *nonlin_ineq_upper_bnds*, const [RealVector](#) & *nonlin_eq_targets*, void(* *user_obj_eval*)(int *mode*, int *n*, const [ColumnVector](#) & *x*, [Real](#) & *f*, [ColumnVector](#) & *grad_f*, int & *result_mode*), void(* *user_con_eval*)(int *mode*, int *n*, const [ColumnVector](#) & *x*, [ColumnVector](#) & *g*, [Matrix](#) & *grad_g*, int & *result_mode*))

alternate constructor for instantiations "on the fly"

This is an alternate constructor for performing an optimization using the passed in objective function and constraint function pointers.

8.93.3 Member Function Documentation

8.93.3.1 void nlf0_evaluator (int *n*, const [ColumnVector](#) & *x*, [Real](#) & *f*, int & *result_mode*)
[static, private]

objective function evaluator function for OPT++ methods which require only function values.

For use when DAKOTA computes f and gradients are not directly available. This is used by nongradient-based optimizers such as PDS and by gradient-based optimizers in vendor numerical gradient mode (opt++'s internal finite difference routine is used).

8.93.3.2 void nlf1_evaluator (int *mode*, int *n*, const [ColumnVector](#) & *x*, [Real](#) & *f*, [ColumnVector](#) & *grad_f*, int & *result_mode*) [static, private]

objective function evaluator function which provides function values and gradients to OPT++ methods.

For use when DAKOTA computes f and df/dX (regardless of gradientType). Vendor numerical gradient case is handled by nlf0_evaluator.

8.93.3.3 void nlf2_evaluator (int *mode*, int *n*, const [ColumnVector](#) & *x*, [Real](#) & *f*, [ColumnVector](#) & *grad_f*, [SymmetricMatrix](#) & *hess_f*, int & *result_mode*) [static, private]

objective function evaluator function which provides function values, gradients, and Hessians to OPT++ methods.

For use when DAKOTA receives f, df/dX, & d^2f/dx^2 from the [ApplicationInterface](#) (analytic only). Finite differencing does not make sense for a full Newton approach, since lack of analytic gradients & Hessian should dictate the use of quasi-newton or fd-newton. Thus, there is no fdnlf2_evaluator for use with full Newton approaches, since it is preferable to use quasi-newton or fd-newton with nlf1. Gauss-Newton does not fit this model; it uses nlf2_evaluator_gn instead of nlf2_evaluator.

8.93.3.4 void constraint0_evaluator (int *n*, const [ColumnVector](#) & *x*, [ColumnVector](#) & *g*, int & *result_mode*) [static, private]

constraint evaluator function for OPT++ methods which require only constraint values.

For use when DAKOTA computes g and gradients are not directly available. This is used by nongradient-based optimizers and by gradient-based optimizers in vendor numerical gradient mode (opt++'s internal finite difference routine is used).

8.93.3.5 `void constraint1_evaluator (int mode, int n, const ColumnVector & x, ColumnVector & g, ::Matrix & grad_g, int & result_mode) [static, private]`

constraint evaluator function which provides constraint values and gradients to OPT++ methods.

For use when DAKOTA computes g and dg/dX (regardless of gradientType). Vendor numerical gradient case is handled by `constraint0_evaluator`.

8.93.3.6 `void constraint2_evaluator (int mode, int n, const ColumnVector & x, ColumnVector & g, ::Matrix & grad_g, OptppArray< SymmetricMatrix > & hess_g, int & result_mode) [static, private]`

constraint evaluator function which provides constraint values, gradients, and Hessians to OPT++ methods.

For use when DAKOTA computes g , dg/dX , & d^2g/dx^2 (analytic only).

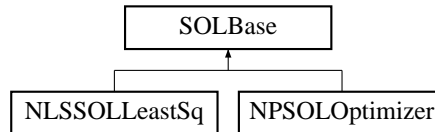
The documentation for this class was generated from the following files:

- SNLLOptimizer.H
- SNLLOptimizer.C

8.94 SOLBase Class Reference

Base class for Stanford SOL software.

Inheritance diagram for SOLBase::



Public Member Functions

- [SOLBase \(\)](#)
default constructor
- [SOLBase \(Model &model\)](#)
standard constructor
- [~SOLBase \(\)](#)
destructor

Protected Member Functions

- void [allocate_arrays](#) (const int &num_cv, const size_t &num_nln_ineq_con, const size_t &num_nln_eq_con, const size_t &num_lin_ineq_con, const size_t &num_lin_eq_con, const [RealMatrix](#) &lin_ineq_coeffs, const [RealMatrix](#) &lin_eq_coeffs)
Allocates miscellaneous arrays for the SOL algorithms.
- void [deallocate_arrays](#) ()
Deallocates memory previously allocated by [allocate_arrays\(\)](#).
- void [allocate_workspace](#) (const int &num_cv, const int &num_nln_con, const int &num_lin_con, const int &num_lsq)
Allocates real and integer workspaces for the SOL algorithms.
- void [set_options](#) (bool speculative_flag, bool vendor_num_grad_flag, bool verbose_output, const int &verify_lev, const [Real](#) &fn_prec, const [Real](#) &linesrch_tol, const int &max_iter, const [Real](#) &constr_tol, const [Real](#) &conv_tol, const [String](#) &grad_type, const [Real](#) &fdss)
Sets SOL method options using calls to [npoptm2](#).
- void [augment_bounds](#) ([RealVector](#) &augmented_l_bnds, [RealVector](#) &augmented_u_bnds, const [RealVector](#) &lin_ineq_l_bnds, const [RealVector](#) &lin_ineq_u_bnds, const [RealVector](#) &lin_eq_targets, const [RealVector](#) &nln_ineq_l_bnds, const [RealVector](#) &nln_ineq_u_bnds, const [RealVector](#) &nln_eq_targets)

augments variable bounds with linear and nonlinear constraint bounds.

Static Protected Member Functions

- void `constraint_eval` (int &mode, int &ncnln, int &n, int &nrowj, int *needc, double *x, double *c, double *cjac, int &nstate)

CONFUN in NPSOL manual: computes the values and first derivatives of the nonlinear constraint functions.

Protected Attributes

- int `realWorkSpaceSize`
size of realWorkSpace
- int `intWorkSpaceSize`
size of intWorkSpace
- `RealArray` `realWorkSpace`
real work space for NPSOL/NLSSOL
- `IntArray` `intWorkSpace`
int work space for NPSOL/NLSSOL
- int `nlnConstraintArraySize`
used for non-zero array sizing (nonlinear constraints)
- int `linConstraintArraySize`
used for non-zero array sizing (linear constraints)
- `RealArray` `cLambda`
CLAMBDA from NPSOL manual: Langrange multipliers.
- `IntArray` `constraintState`
ISTATE from NPSOL manual: constraint status.
- int `informResult`
INFORM from NPSOL manual: optimization status on exit.
- int `numberIterations`
ITER from NPSOL manual: number of (major) iterations performed.
- int `boundsArraySize`
length of augmented bounds arrays (variable bounds plus linear and nonlinear constraint bounds)
- double * `linConstraintMatrixF77`
[A] matrix from NPSOL manual: linear constraint coefficients

- double * [upperFactorHessianF77](#)
[R] matrix from NPSOL manual: upper Cholesky factor of the Hessian of the Lagrangian.
- double * [constraintJacMatrixF77](#)
[CJAC] matrix from NPSOL manual: nonlinear constraint Jacobian
- int [fnEvalCntr](#)
counter for testing against maxFunctionEvals
- size_t [constrOffset](#)
used in `constraint_eval()` to bridge `NLSSOLLeastSq::numLeastSqTerms` and `NPSOLOptimizer::numObjectiveFunctions`

Static Protected Attributes

- [SOLBase](#) * [solInstance](#)
pointer to the active object instance used within the static evaluator functions in order to avoid the need for static data
- [Minimizer](#) * [optLSqInstance](#)
pointer to the active base class object instance used within the static evaluator functions in order to avoid the need for static data

8.94.1 Detailed Description

Base class for Stanford SOL software.

The [SOLBase](#) class provides a common base class for [NPSOLOptimizer](#) and [NLSSOLLeastSq](#), both of which are Fortran 77 sequential quadratic programming algorithms from Stanford University marketed by Stanford Business Associates.

The documentation for this class was generated from the following files:

- [SOLBase.H](#)
- [SOLBase.C](#)

8.95 SortCompare Class Template Reference

Public Member Functions

- `SortCompare` (`bool(*func)(const T &, const T &)`)
Constructor that defines the pointer to function.
- `bool operator()` (`const T &p1, const T &p2`) `const`
The operator() must be defined. Calls the defined sortFunction.

Private Attributes

- `bool(* sortFunction)` (`const T &, const T &`)
Pointer to test function.

8.95.1 Detailed Description

`template<class T> class Dakota::SortCompare< T >`

Internal functor used in the sort algorithm to sort using a specified compare method. The class holds a pointer to the sort function.

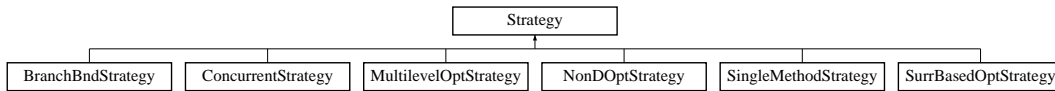
The documentation for this class was generated from the following file:

- `DakotaList.H`

8.96 Strategy Class Reference

Base class for the strategy class hierarchy.

Inheritance diagram for Strategy::



Public Member Functions

- [Strategy](#) ()
default constructor
- [Strategy](#) ([ProblemDescDB](#) &problem_db)
envelope constructor
- [Strategy](#) (const [Strategy](#) &strat)
copy constructor
- virtual [~Strategy](#) ()
destructor
- [Strategy operator=](#) (const [Strategy](#) &strat)
assignment operator
- virtual void [run_strategy](#) ()
the run function for the strategy: invoke the iterator(s) on the model(s). Called from [main.C](#).
- virtual const [Variables](#) & [strategy_variable_results](#) () const
return the final strategy solution (variables)
- virtual const [Response](#) & [strategy_response_results](#) () const
return the final strategy solution (response)
- virtual [IteratorList](#) & [iterators](#) (bool recurse_flag=true)
recurse through nestings/layerings and return all Iterators used in the strategy
- virtual [ModelList](#) & [models](#) (bool recurse_flag=true)
recurse through nestings/layerings and return all Models used in the strategy
- void [run_iterator](#) ([Iterator](#) &the_iterator, [Model](#) &the_model)
Convenience function for invoking an iterator and managing parallelism. This version omits communicator repartitioning. Function must be public due to use by MINLPNode.

- **ProblemDescDB** & **prob_desc_db** () const
returns the problem description database (probDescDB)
- **ParallelLibrary** & **parallel_library** () const
returns the parallel library (parallelLib)

Protected Member Functions

- **Strategy** (**BaseConstructor**, **ProblemDescDB** &problem_db)
*constructor initializes the base class part of letter classes (**BaseConstructor** overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)*
- void **init_communicators** (**Iterator** &the_iterator, **Model** &the_model)
convenience function for allocating comms prior to running an iterator
- void **free_communicators** (**Model** &the_model)
convenience function for deallocating comms after running an iterator
- void **initialize_graphics** (const **Model** &model)
convenience function for initialization of 2D graphics and data tabulation

Protected Attributes

- **ProblemDescDB** & **probDescDB**
class member reference to the problem description database
- **ParallelLibrary** & **parallelLib**
class member reference to the parallel library
- **String strategyName**
type of strategy: single_method, multi_level, surrogate_based_opt, opt_under_uncertainty, branch_and_bound, multi_start, or pareto_set.
- int **worldRank**
processor rank in MPI_COMM_WORLD
- int **worldSize**
size of MPI_COMM_WORLD
- int **iteratorCommRank**
processor rank in iteratorComm
- int **iteratorCommSize**
number of processors in iteratorComm
- bool **mpirunFlag**
flag for parallel MPI launch of DAKOTA

- bool [graphicsFlag](#)
flag for using graphics in a graphics executable
- bool [tabularDataFlag](#)
flag for file tabulation of graphics data
- String [tabularDataFile](#)
filename for tabulation of graphics data
- IteratorList [iteratorList](#)
list of iterators returned by [iterators\(\)](#)
- ModelList [modelList](#)
list of models returned by [models\(\)](#)

Private Member Functions

- Strategy * [get_strategy](#) ()
Used by the envelope to instantiate the correct letter class.

Private Attributes

- Strategy * [strategyRep](#)
pointer to the letter (initialized only for the envelope)
- int [referenceCount](#)
number of objects sharing [strategyRep](#)

8.96.1 Detailed Description

Base class for the strategy class hierarchy.

The [Strategy](#) class is the base class for the class hierarchy providing the top level control in DAKOTA. The strategy is responsible for creating and managing iterators and models. For memory efficiency and enhanced polymorphism, the strategy hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Strategy](#)) serves as the envelope and one of the derived classes (selected in [Strategy::get_strategy\(\)](#)) serves as the letter.

8.96.2 Constructor & Destructor Documentation

8.96.2.1 [Strategy](#) ()

default constructor

Default constructor. `strategyRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful [Strategy](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

8.96.2.2 [Strategy](#) ([ProblemDescDB](#) & *problem_db*)

envelope constructor

Used in [main.C](#) instantiation to build the envelope. This constructor only needs to extract enough data to properly execute `get_strategy`, since `Strategy::Strategy(BaseConstructor, problem_db)` builds the actual base class data inherited by the derived strategies.

8.96.2.3 [Strategy](#) (const [Strategy](#) & *strat*)

copy constructor

Copy constructor manages sharing of `strategyRep` and incrementing of `referenceCount`.

8.96.2.4 [~Strategy](#) () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `strategyRep` when `referenceCount` reaches zero.

8.96.2.5 [Strategy](#) ([BaseConstructor](#), [ProblemDescDB](#) & *problem_db*) [protected]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all inherited strategies. `get_strategy()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_strategy()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Strategy`).

8.96.3 Member Function Documentation

8.96.3.1 [Strategy](#) operator= (const [Strategy](#) & *strat*)

assignment operator

Assignment operator decrements `referenceCount` for old `strategyRep`, assigns new `strategyRep`, and increments `referenceCount` for new `strategyRep`.

8.96.3.2 void run_iterator (*Iterator & the_iterator, Model & the_model*)

Convenience function for invoking an iterator and managing parallelism. This version omits communicator repartitioning. Function must be public due to use by MINLPNode.

This is a convenience function for encapsulating the parallel features (run/serve) of running an iterator. This function omits allocation/deallocation of communicators to provide greater efficiency in those strategies which involve multiple iterator executions but only require communicator allocation/deallocation to be performed once.

It does not require a strategyRep forward since it is only used by letter objects. While it is currently a public function due to its use in MINLPNode, this usage still involves a strategy letter object.

8.96.3.3 void init_communicators (*Iterator & the_iterator, Model & the_model*) [protected]

convenience function for allocating comms prior to running an iterator

This is a convenience function for encapsulating the allocation of communicators prior to running an iterator. It does not require a strategyRep forward since it is only used by letter objects.

8.96.3.4 void free_communicators (*Model & the_model*) [protected]

convenience function for deallocating comms after running an iterator

This is a convenience function for encapsulating the deallocation of communicators after running an iterator. It does not require a strategyRep forward since it is only used by letter objects.

8.96.3.5 void initialize_graphics (*const Model & model*) [protected]

convenience function for initialization of 2D graphics and data tabulation

This is a convenience function for encapsulating graphics initialization operations. It does not require a strategyRep forward since it is only used by letter objects.

8.96.3.6 Strategy * get_strategy () [private]

Used by the envelope to instantiate the correct letter class.

Used only by the envelope constructor to initialize strategyRep to the appropriate derived type, as given by the strategyName attribute.

The documentation for this class was generated from the following files:

- DakotaStrategy.H
- DakotaStrategy.C

8.97 String Class Reference

Dakota::String class, used as main string class for [Dakota](#).

Public Member Functions

- [String](#) ()
Default constructor.
- [String](#) (const [String](#) &a)
Default copy constructor.
- [String](#) (const char *initial_val)
Copy constructor from standard C char array.
- [~String](#) ()
Destructor.
- [String](#) & [operator=](#) (const [String](#) &)
Normal assignment operator.
- [String](#) & [operator=](#) (const DAKOTA_BASE_STRING &)
Assignment operator for base string.
- [String](#) & [operator=](#) (const char *)
Assignment operator, standard C char.*
- [operator const char *](#) () const
The operator() returns pointer to standard C char array.
- [String](#) & [toUpperCase](#) ()
Convert to upper case string.
- void [upper](#) ()
- [String](#) & [toLowerCase](#) ()
Convert to lower case string.
- void [lower](#) ()
- bool [contains](#) (const char *subString) const
Returns true if [String](#) contains char substring.*
- char * [data](#) () const
Returns pointer to standard C char array.

8.97.1 Detailed Description

Dakota::String class, used as main string class for [Dakota](#).

The Dakota::String class is the common string class for [Dakota](#). It provides a common interface for string operations whether inheriting from the STL `basic_string` or the Rogue Wave `RWCString` class

8.97.2 Member Function Documentation

8.97.2.1 `operator const char * () const` [inline]

The operator() returns pointer to standard C char array.

The operator () returns a pointer to a char string. Uses the STL `c_str()` method. This allows for the [String](#) to be used in method calls without having to call the `data()` or `c_str()` methods.

8.97.2.2 `void upper ()`

Private method which converts [String](#) to upper. Utilizes an STL iterator to step through the string and then calls the STL `toupper()` method. Needs to be done this way because STL only provides a single char `toupper` method.

8.97.2.3 `void lower ()`

Private method which converts [String](#) to lower. Utilizes an STL iterator to step through the string and then calls the STL `tolower()` method. Needs to be done this way because STL only provides a single char `tolower` method.

8.97.2.4 `bool contains (const char * subString) const` [inline]

Returns true if [String](#) contains char* substring.

Returns true if the [String](#) contains the char* subString. Calls the STL `rfind()` method, then checks if substring was found within the [String](#)

8.97.2.5 `char * data () const` [inline]

Returns pointer to standard C char array.

Returns a pointer to C style char array. Needed to mimic the Rogue Wave string class. USE WITH CARE.

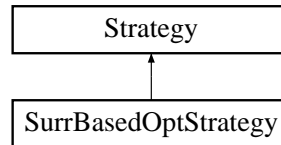
The documentation for this class was generated from the following files:

- [DakotaString.H](#)
- [DakotaString.C](#)

8.98 SurrBasedOptStrategy Class Reference

[Strategy](#) for provably-convergent surrogate-based optimization.

Inheritance diagram for SurrBasedOptStrategy::



Public Member Functions

- [SurrBasedOptStrategy](#) ([ProblemDescDB](#) &problem_db)
constructor
- [~SurrBasedOptStrategy](#) ()
destructor
- void [run_strategy](#) ()
Performs the surrogate-based optimization strategy by optimizing local, global, or hierarchical surrogates over a series of trust regions.
- const [Variables](#) & [strategy_variable_results](#) () const
return the SBO final solution (variables)
- const [Response](#) & [strategy_response_results](#) () const
return the SBO final solution (response)
- [IteratorList](#) & [iterators](#) (bool recurse_flag=true)
returns selectedIterator and any subordinate iterators
- [ModelList](#) & [models](#) (bool recurse_flag=true)
returns approximateModel and any subordinate models

Private Member Functions

- void [hard_convergence_check](#) (const [Response](#) &response_truth, const [RealVector](#) &c_vars, const [RealVector](#) &lower_bnds, const [RealVector](#) &upper_bnds)
check for hard convergence (norm of projected gradient of penalty function near zero)
- void [soft_convergence_check](#) (const [RealVector](#) &c_vars_center, const [RealVector](#) &c_vars_star, const [Response](#) &response_center_truth, const [Response](#) &response_center_approx, const [Response](#) &response_star_truth, const [Response](#) &response_star_approx)

check for soft convergence (diminishing returns)

- void `compute_penalty` (const `RealVector` &fns_center_truth, const `RealVector` &fns_star_truth)
initialize and update the penaltyParameter
- Real `compute_penalty_function` (const `RealVector` &fn_vals)
compute a penalty function from a set of function values
- Real `compute_objective` (const `RealVector` &fn_vals)
compute a single objective value from one or more objective functions
- Real `compute_constraint_violation` (const `RealVector` &fn_vals)
compute the constraint violation from a set of function values

Private Attributes

- `Model approximateModel`
the surrogate model (a `LayeredModel` object)
- `Iterator selectedIterator`
the optimizer used on `approximateModel`
- Real `trustRegionFactor`
the trust region factor is used to compute the total size of the trust region – it is a percentage, e.g. for `trustRegionFactor = 0.1`, the actual size of the trust region will be 10% of the global bounds (upper bound - lower bound for each design variable).
- Real `minTrustRegionFactor`
a soft convergence control: stop SBO when the trust region factor is reduced below the value of `minTrustRegionFactor`
- Real `convergenceTol`
the optimizer convergence tolerance; used in several SBO hard and soft convergence checks
- Real `constraintTol`
a tolerance specifying the distance from a constraint boundary that is allowed before an active constraint is considered to be a violated constraint (only violated constraints are used in penalty function computations).
- Real `trRatioContractValue`
trust region ratio min value: contract tr if ratio below this value
- Real `trRatioExpandValue`
trust region ratio sufficient value: expand tr if ratio above this value
- Real `gammaContract`
trust region contraction factor
- Real `gammaExpand`
trust region expansion factor

- Real `gammaNoChange`
factor for maintaining the current trust region size (normally 1.0)
- Real `penaltyParameter`
the penalization factor for violated constraints used in penalty function calculations; increases exponentially with iteration count
- int `penaltyIterOffset`
iteration offset used to update the scaling of the penalty parameter
- int `sboIterNum`
SBO iteration number.
- int `sboIterMax`
maximum number of SBO iterations
- short `convergenceFlag`
code indicating satisfaction of hard or soft convergence conditions
- int `numFns`
number of response functions
- int `numVars`
number of active continuous variables
- short `softConvCount`
number of consecutive candidate point rejections. If the count reaches softConvLimit, stop SBO.
- short `softConvLimit`
the limit on consecutive candidate point rejections. If exceeded by softConvCount, stop SBO.
- bool `gradientFlag`
flags the use of gradients within the SBO process
- bool `hessianFlag`
flags the use of Hessians within the SBO process
- bool `correctionFlag`
flags the use of surrogate correction techniques at the center of each trust region
- bool `globalApproxFlag`
flags the use of a global data fit surrogate (rsm, ann, mars, kriging)
- bool `localApproxFlag`
flags the use of a local data fit surrogate (Taylor series)
- bool `hierarchApproxFlag`
flags the use of a hierarchical surrogate

- bool [newCenterFlag](#)
flags the acceptance of a candidate point and the existence of a new trust region center
- bool [daceCenterPtFlag](#)
flags the availability of the center point in the DACE evaluations for global approximations (CCD, Box-Behnken)
- bool [multiLayerBypassFlag](#)
flags the simultaneous presence of two conditions: (1) additional layerings within actual_model (e.g., approximateModel = layered/nested/layered -> actual_model = nested/layered), and (2) a user-specification to bypass all layerings within actual_model for the evaluation of truth data (response_center_truth and response_star_truth).
- bool [useGradsFlag](#)
flags the "use_gradients" specification in which gradients are to be evaluated for each DACE point in global surrogate builds.
- size_t [numObjFns](#)
number of objective functions
- size_t [numNonlinIneqConstr](#)
number of nonlinear inequality constraints
- size_t [numNonlinEqConstr](#)
number of nonlinear equality constraints
- [RealVector](#) [multiObjWts](#)
vector of multiobjective weights.
- [RealVector](#) [nonlinIneqLowerBnds](#)
vector of nonlinear inequality constraint lower bounds
- [RealVector](#) [nonlinIneqUpperBnds](#)
vector of nonlinear inequality constraint upper bounds
- [RealVector](#) [nonlinEqTargets](#)
vector of nonlinear equality constraint targets
- [Variables](#) [bestVariables](#)
best variables found in SBO
- [Response](#) [bestResponses](#)
best responses found in SBO

8.98.1 Detailed Description

[Strategy](#) for provably-convergent surrogate-based optimization.

This strategy uses a [LayeredModel](#) to perform optimization based on local, global, or hierarchical surrogates. It achieves provable convergence through the use of a sequence of trust regions and the application of surrogate corrections at the trust region centers.

8.98.2 Member Function Documentation

8.98.2.1 void run_strategy () [virtual]

Performs the surrogate-based optimization strategy by optimizing local, global, or hierarchical surrogates over a series of trust regions.

Trust region-based strategy to perform surrogate-based optimization in subregions (trust regions) of the parameter space. The optimizer operates on approximations in lieu of the more expensive simulation-based response functions. The size of the trust region is varied according to the goodness of the agreement between the approximations and the true response functions.

Reimplemented from [Strategy](#).

8.98.2.2 void hard_convergence_check (const Response & response_truth, const RealVector & c_vars, const RealVector & lower_bnds, const RealVector & upper_bnds) [private]

check for hard convergence (norm of projected gradient of penalty function near zero)

The hard convergence check computes the 2-norm of the projected gradient of the penalty function ($dp/dx = df/dx + 2 r_p g^{+T} dg/dx + 2 r_p h^{+T} dh/dx$) at the trust region center and signals convergence if the 2-norm is close to zero. The projection is needed to remove any gradient component directed into an active bound constraint (since this penalty function does not explicitly include Lagrange multipliers times the bound constraints; if it did, the Lagrange multiplier for an active bound constraint would zero out the total gradient component).

8.98.2.3 void soft_convergence_check (const RealVector & c_vars_center, const RealVector & c_vars_star, const Response & response_center_truth, const Response & response_center_approx, const Response & response_star_truth, const Response & response_star_approx) [private]

check for soft convergence (diminishing returns)

Compute soft convergence metrics (trust region ratio, number of consecutive failures, min trust region size, etc.) and use them to assess whether the convergence rate has decreased to a point where the process should be terminated (diminishing returns).

8.98.2.4 void compute_penalty (const RealVector & fns_center_truth, const RealVector & fns_star_truth) [private]

initialize and update the penaltyParameter

Scaling of the penalty value is important to avoid rejecting iterates which must increase the objective to achieve a reduction in constraint violation. This routine uses the ratio of relative change between center and star points for the objective and constraint violation values to rescale penalty values.

8.98.2.5 Real compute_penalty_function (const RealVector & fn_vals) [private]

compute a penalty function from a set of function values

The penalty function computation applies a quadratic penalty to any constraint violations and adds this to the objective function(s) $p = f + r_p cv$.

8.98.2.6 Real compute_objective (const RealVector & fn_vals) [private]

compute a single objective value from one or more objective functions

The objective computation sums up the contributions from one of more objective functions using the multiobjective weights.

8.98.2.7 Real compute_constraint_violation (const RealVector & fn_vals) [private]

compute the constraint violation from a set of function values

Compute the quadratic constraint violation defined as $cv = g^+{}^T g + h^+{}^T h$. This implementation supports equality constraints and 2-sided inequalities. The constraintTol allows for a small constraint infeasibility.

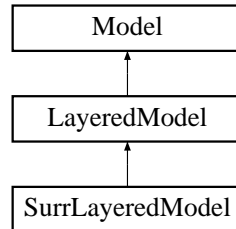
The documentation for this class was generated from the following files:

- SurrBasedOptStrategy.H
- SurrBasedOptStrategy.C

8.99 SurrLayeredModel Class Reference

Derived model class within the layered model branch for managing data fit surrogates (global and local).

Inheritance diagram for SurrLayeredModel::



Public Member Functions

- [SurrLayeredModel \(ProblemDescDB &problem_db\)](#)
constructor
- [~SurrLayeredModel \(\)](#)
destructor

Protected Member Functions

- void [derived_compute_response](#) (const [IntArray](#) &asv)
portion of [compute_response\(\)](#) specific to [SurrLayeredModel](#)
- void [derived_async_compute_response](#) (const [IntArray](#) &asv)
portion of [async_compute_response\(\)](#) specific to [SurrLayeredModel](#)
- const [ResponseArray](#) & [derived_synchronize](#) ()
portion of [synchronize\(\)](#) specific to [SurrLayeredModel](#)
- const [ResponseList](#) & [derived_synchronize_nowait](#) ()
portion of [synchronize_nowait\(\)](#) specific to [SurrLayeredModel](#)
- const [IntList](#) & [synchronize_nowait_completions](#) ()
return completion id's matching response list from [derived_synchronize_nowait\(\)](#)
- [Model](#) [subordinate_model](#) ()
returns actualModel
- [Iterator](#) [subordinate_iterator](#) ()
return daceIterator

- [Interface & interface](#) ()
return approxInterface
- void [layering_bypass](#) (bool bypass_flag)
set layeringBypass flag and pass request on to actualModel for any lower-level layerings.
- void [build_approximation](#) ()
Builds the local/multipoint/global approximation using daceIterator/actualModel.
- void [update_approximation](#) (const [RealVector](#) &x_star, const [Response](#) &response_star)
Adds a point to a global approximation (request forwarded to approxInterface).
- const [RealVectorArray](#) & [approximation_coefficients](#) ()
return the approximation coefficients from each [Approximation](#) (request forwarded to approxInterface)
- void [component_parallel_mode](#) (int mode)
update component parallel mode for supporting parallelism in actualModel
- bool [derived_master_overload](#) () const
prevents overloading the master with a multiprocessor evaluation
- void [derived_init_communicators](#) (const int &max_iterator_concurrency)
set up actualModel for parallel operations
- void [derived_init_serial](#) ()
set up actualModel for serial operations.
- void [reset_communicators](#) ()
reset communicator partitions for the [SurrLayeredModel](#) (request forwarded to actualModel)
- void [free_communicators](#) ()
deallocate communicator partitions for the [SurrLayeredModel](#) (request forwarded to actualModel)
- void [serve](#) ()
Service actualModel job requests received from the master. Completes when a termination message is received from [stop_servers\(\)](#).
- void [stop_servers](#) ()
Executed by the master to terminate actualModel server operations when [SurrLayeredModel](#) iteration is complete.
- int [total_eval_counter](#) () const
return the total evaluation count for the [SurrLayeredModel](#) (request forwarded to approxInterface)
- int [new_eval_counter](#) () const
return the new evaluation count for the [SurrLayeredModel](#) (request forwarded to approxInterface)

Private Member Functions

- void [update_actual_model\(\)](#)
update actualModel with current variable values/bounds/labels

Private Attributes

- [Interface approxInterface](#)
manages the building and subsequent evaluation of the approximations (required for both global and local)
- [String actualInterfacePointer](#)
string identifier for the actual interface from the local approximation specification (required for local); used to build actualModel for local approximations
- [String daceMethodPointer](#)
string identifier for the dace method from the global approximation specification; used in building daceIterator and actualModel for global approximations (optional for global since restart data may also be used)
- [Model actualModel](#)
the truth model which provides evaluations for building the surrogate (optional for global since restart data may also be used, required for local)
- [Iterator daceIterator](#)
selects parameter sets on which to evaluate actualModel in order to generate the necessary data for building global approximations (optional for global since restart data may also be used)

8.99.1 Detailed Description

Derived model class within the layered model branch for managing data fit surrogates (global and local).

The [SurrLayeredModel](#) class manages global or local approximations (surrogates that involve data fits) that are used in place of an expensive model. The class contains an [approxInterface](#) (required for both global and local) which manages the approximate function evaluations, an [actualModel](#) (optional for global, required for local) which provides truth evaluations for building the surrogate, and a [daceIterator](#) (optional for global, not used for local) which selects parameter sets on which to evaluate [actualModel](#) in order to generate the necessary data for building global approximations.

8.99.2 Member Function Documentation

8.99.2.1 void [derived_compute_response\(const \[IntArray\]\(#\) & *asv*\)](#) [protected, virtual]

portion of [compute_response\(\)](#) specific to [SurrLayeredModel](#)

Build the approximation (if needed), evaluate the approximate response using [approxInterface](#), and, if correction is active, correct the results.

Reimplemented from [Model](#).

8.99.2.2 `void derived_async_compute_response (const IntArray & asv)` [protected, virtual]

portion of `async_compute_response()` specific to [SurrLayeredModel](#)

Build the approximation (if needed) and evaluate the approximate response using `approxInterface` in a quasi-asynchronous approach (`ApproximationInterface::map()` performs the map synchronously and book-keeps the results for return in `derived_synchronize()` below).

Reimplemented from [Model](#).

8.99.2.3 `const ResponseArray & derived_synchronize ()` [protected, virtual]

portion of `synchronize()` specific to [SurrLayeredModel](#)

Retrieve quasi-asynchronous evaluations from `approxInterface` and, if correction is active, apply correction to each response in the array.

Reimplemented from [Model](#).

8.99.2.4 `const ResponseList & derived_synchronize_nowait ()` [protected, virtual]

portion of `synchronize_nowait()` specific to [SurrLayeredModel](#)

Retrieve quasi-asynchronous evaluations from `approxInterface` and, if correction is active, apply correction to each response in the list.

Reimplemented from [Model](#).

8.99.2.5 `void build_approximation ()` [protected, virtual]

Builds the local/multipoint/global approximation using `daceIterator/actualModel`.

Build either a global approximation using `daceIterator` or a local approximation using `actualModel`. Selection triggers on `actualInterfacePointer` (required specification for local approximation interfaces, not used in global specification).

Reimplemented from [Model](#).

8.99.2.6 `bool derived_master_overload () const` [inline, protected, virtual]

prevents overloading the master with a multiprocessor evaluation

`compute_response` calls never overload the master since there is no parallelism in the use of `approxInterface`. Derived master overload for `actualModel` is handled separately in `actualModel.compute_response()` (within `daceIterator.run_iterator()`, etc.).

Reimplemented from [Model](#).

8.99.2.7 void derived_init_communicators (const int & max_iterator_concurrency) [inline, protected, virtual]

set up actualModel for parallel operations

asynchronous flags need to be initialized for the sub-models. In addition, max_iterator_concurrency is the outer level iterator concurrency, not the DACE concurrency that actualModel will see, and recomputing the message_lengths on the sub-model is probably not a bad idea either. Therefore, recompute everything on actualModel using init_communicators.

Reimplemented from [Model](#).

8.99.2.8 void update_actual_model () [private]

update actualModel with current variable values/bounds/labels

Update variables data within actualModel using values and labels from currentVariables and bounds from userDefinedVarConstraints.

8.99.3 Member Data Documentation

8.99.3.1 String actualInterfacePointer [private]

string identifier for the actual interface from the local approximation specification (required for local); used to build actualModel for local approximations

Specification is used only for local approximations, since the dace_method_pointer in the global approximation specification is responsible for identifying all actualModel components.

8.99.3.2 Model actualModel [private]

the truth model which provides evaluations for building the surrogate (optional for global since restart data may also be used, required for local)

There are no restrictions on actualModel in the global case, so arbitrary nestings are possible. In the local case, model_type must be set to "single" to avoid recursion on [SurrLayeredModel](#), since there is no additional method specification.

The documentation for this class was generated from the following files:

- SurrLayeredModel.H
- SurrLayeredModel.C

8.100 SurrogateDataPoint Class Reference

Simple container class encapsulating basic parameter and response data for defining a "truth" data point.

Public Member Functions

- [SurrogateDataPoint \(\)](#)
default constructor
- [SurrogateDataPoint \(const \[RealVector\]\(#\) &x, const Real &fn_val, const \[RealBaseVector\]\(#\) &fn_grad, const \[RealMatrix\]\(#\) &fn_hess\)](#)
standard constructor
- [SurrogateDataPoint \(const \[SurrogateDataPoint\]\(#\) &sdp\)](#)
copy constructor
- [~SurrogateDataPoint \(\)](#)
destructor
- [SurrogateDataPoint & operator= \(const \[SurrogateDataPoint\]\(#\) &sdp\)](#)
assignment operator
- [int operator== \(const \[SurrogateDataPoint\]\(#\) &sdp\) const](#)
equality operator

Public Attributes

- [RealVector continuousVars](#)
continuous variables
- Real [responseFn](#)
truth response function value
- [RealBaseVector responseGrad](#)
truth response function gradient
- [RealMatrix responseHess](#)
truth response function Hessian

8.100.1 Detailed Description

Simple container class encapsulating basic parameter and response data for defining a "truth" data point.

A list of these data points is contained in each [Approximation](#) instance ([Approximation::currentPoints](#)) and provides the data to build the approximation. Data is public to avoid maintaining set/get functions, but is still encapsulated within [Approximation](#) since [Approximation::currentPoints](#) is protected (a similar model is used with with Data class objects contained in [ProblemDescDB](#)).

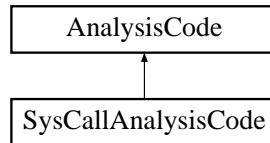
The documentation for this class was generated from the following file:

- DakotaApproximation.H

8.101 SysCallAnalysisCode Class Reference

Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using system calls.

Inheritance diagram for SysCallAnalysisCode::



Public Member Functions

- [SysCallAnalysisCode](#) (const [ProblemDescDB](#) &problem_db)
constructor
- [~SysCallAnalysisCode](#) ()
destructor
- void [spawn_evaluation](#) (const bool block_flag)
spawn a complete function evaluation
- void [spawn_input_filter](#) (const bool block_flag)
spawn the input filter portion of a function evaluation
- void [spawn_analysis](#) (const int &analysis_id, const bool block_flag)
spawn a single analysis as part of a function evaluation
- void [spawn_output_filter](#) (const bool block_flag)
spawn the output filter portion of a function evaluation
- const [String](#) & [command_usage](#) () const
return commandUsage

Private Attributes

- [String](#) [commandUsage](#)
optional command usage string for supporting nonstandard command syntax (supported only by SysCall analysis codes)

8.101.1 Detailed Description

Derived class in the [AnalysisCode](#) class hierarchy which spawns simulations using system calls.

[SysCallAnalysisCode](#) creates separate simulation processes using the C `system()` command. It utilizes [CommandShell](#) to manage shell syntax and asynchronous invocations.

8.101.2 Member Function Documentation

8.101.2.1 `void spawn_evaluation (const bool block_flag)`

spawn a complete function evaluation

Put the [SysCallAnalysisCode](#) to the shell using either the default syntax or specified `commandUsage` syntax. This function is used when all portions of the function evaluation (i.e., all analysis drivers) are executed on the local processor.

8.101.2.2 `void spawn_input_filter (const bool block_flag)`

spawn the input filter portion of a function evaluation

Put the input filter to the shell. This function is used when multiple analysis drivers are spread between processors. No need to check for a Null input filter, as this is checked externally. Use of nonblocking shells is supported in this fn, although its use is currently prevented externally.

8.101.2.3 `void spawn_analysis (const int & analysis_id, const bool block_flag)`

spawn a single analysis as part of a function evaluation

Put a single analysis to the shell using the default syntax (no `commandUsage` support for analyses). This function is used when multiple analysis drivers are spread between processors. Use of nonblocking shells is supported in this fn, although its use is currently prevented externally.

8.101.2.4 `void spawn_output_filter (const bool block_flag)`

spawn the output filter portion of a function evaluation

Put the output filter to the shell. This function is used when multiple analysis drivers are spread between processors. No need to check for a Null output filter, as this is checked externally. Use of nonblocking shells is supported in this fn, although its use is currently prevented externally.

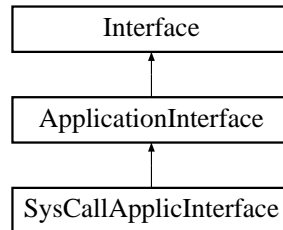
The documentation for this class was generated from the following files:

- `SysCallAnalysisCode.H`
- `SysCallAnalysisCode.C`

8.102 SysCallApplicInterface Class Reference

Derived application interface class which spawns simulation codes using system calls.

Inheritance diagram for SysCallApplicInterface::



Public Member Functions

- [SysCallApplicInterface](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_fns)
constructor
- [~SysCallApplicInterface](#) ()
destructor
- void [derived_map](#) (const [Variables](#) &vars, const [IntArray](#) &asv, [Response](#) &response, int fn_eval_id)
Called by [map\(\)](#) and other functions to execute the simulation in synchronous mode. The portion of performing an evaluation that is specific to a derived class.
- void [derived_map_async](#) (const [ParamResponsePair](#) &pair)
Called by [map\(\)](#) and other functions to execute the simulation in asynchronous mode. The portion of performing an asynchronous evaluation that is specific to a derived class.
- void [derived_synch](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version waits for at least one completion.
- void [derived_synch_nowait](#) ([PRPLList](#) &prp_list)
For asynchronous function evaluations, this method is used to detect completion of jobs and process their results. It provides the processing code that is specific to derived classes. This version is nonblocking and will return without any completions if none are immediately available.
- int [derived_synchronous_local_analysis](#) (const int &analysis_id)
Execute a particular analysis (identified by analysis_id) synchronously on the local processor. Used for the derived class specifics within [ApplicationInterface::serve_analyses_synch\(\)](#).

Private Member Functions

- void [spawn_application](#) (const bool block_flag)
Spawn the application by managing the input filter, analysis drivers, and output filter. Called from [derived_map\(\)](#) & [derived_map_asynch\(\)](#).
- void [derived_synch_kernel](#) (PRPList &prp_list)
Convenience function for common code between [derived_synch\(\)](#) & [derived_synch_nowait\(\)](#).
- bool [system_call_file_test](#) (const String &root_file)
detect completion of a function evaluation through existence of the necessary results file(s)

Private Attributes

- [SysCallAnalysisCode](#) sysCallSimulator
[SysCallAnalysisCode](#) provides convenience functions for passing the input filter, the analysis drivers, and the output filter to a [CommandShell](#) in various combinations.
- [IntList](#) sysCallList
list of function evaluation id's for active asynchronous system call evaluations
- [IntList](#) failIdList
list of function evaluation id's for tracking response file read failures
- [IntList](#) failCountList
list containing the number of response read failures for each function evaluation identified in failIdList

8.102.1 Detailed Description

Derived application interface class which spawns simulation codes using system calls.

[SysCallApplicInterface](#) uses a [SysCallAnalysisCode](#) object for performing simulation invocations.

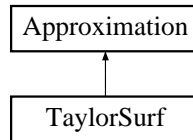
The documentation for this class was generated from the following files:

- SysCallApplicInterface.H
- SysCallApplicInterface.C

8.103 TaylorSurf Class Reference

Derived approximation class for first- or second-order Taylor series (local approximation).

Inheritance diagram for TaylorSurf::



Public Member Functions

- [TaylorSurf](#) (const [ProblemDescDB](#) &problem_db, const size_t &num_acv)
constructor
- [~TaylorSurf](#) ()
destructor

Protected Member Functions

- void [find_coefficients](#) ()
calculate the data fit coefficients using the currentPoints list of SurrogateDataPoints
- int [required_samples](#) ()
return the minimum number of samples required to build the derived class approximation type in numVars dimensions
- Real [get_value](#) (const [RealVector](#) &x)
retrieve the approximate function value for a given parameter vector
- const [RealBaseVector](#) & [get_gradient](#) (const [RealVector](#) &x)
retrieve the approximate function gradient for a given parameter vector
- const [RealMatrix](#) & [get_hessian](#) (const [RealVector](#) &x)
retrieve the approximate function Hessian for a given parameter vector

Private Attributes

- bool [secondOrderFlag](#)
flag to indicate a 2nd-order Taylor series with a Hessian term

8.103.1 Detailed Description

Derived approximation class for first- or second-order Taylor series (local approximation).

The [TaylorSurf](#) class provides a local approximation based on data from a single point in parameter space. It uses a first- or second-order Taylor series expansion: $f(x) = f(x_c) + \text{grad}(x_c)' (x - x_c) + (x - x_c)' \text{Hess}(x_c) (x - x_c) / 2$.

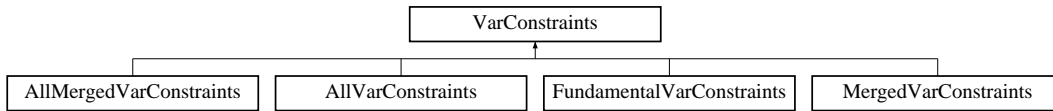
The documentation for this class was generated from the following files:

- TaylorSurf.H
- TaylorSurf.C

8.104 VarConstraints Class Reference

Base class for the variable constraints class hierarchy.

Inheritance diagram for VarConstraints::



Public Member Functions

- [VarConstraints](#) ()
default constructor
- [VarConstraints](#) (const [ProblemDescDB](#) &problem_db, const [String](#) &vars_type)
standard constructor
- [VarConstraints](#) (const [VarConstraints](#) &vc)
copy constructor
- virtual [~VarConstraints](#) ()
destructor
- [VarConstraints operator=](#) (const [VarConstraints](#) &vc)
assignment operator
- virtual const [RealVector](#) & [continuous_lower_bounds](#) () const
return the active continuous variable lower bounds
- virtual void [continuous_lower_bounds](#) (const [RealVector](#) &c_l_bnds)
set the active continuous variable lower bounds
- virtual const [RealVector](#) & [continuous_upper_bounds](#) () const
return the active continuous variable upper bounds
- virtual void [continuous_upper_bounds](#) (const [RealVector](#) &c_u_bnds)
set the active continuous variable upper bounds
- virtual const [IntVector](#) & [discrete_lower_bounds](#) () const
return the active discrete variable lower bounds
- virtual void [discrete_lower_bounds](#) (const [IntVector](#) &d_l_bnds)
set the active discrete variable lower bounds

- virtual const [IntVector](#) & [discrete_upper_bounds](#) () const
return the active discrete variable upper bounds
- virtual void [discrete_upper_bounds](#) (const [IntVector](#) &d_u_bnds)
set the active discrete variable upper bounds
- virtual const [RealVector](#) & [inactive_continuous_lower_bounds](#) () const
return the inactive continuous lower bounds
- virtual void [inactive_continuous_lower_bounds](#) (const [RealVector](#) &i_c_l_bnds)
set the inactive continuous lower bounds
- virtual const [RealVector](#) & [inactive_continuous_upper_bounds](#) () const
return the inactive continuous upper bounds
- virtual void [inactive_continuous_upper_bounds](#) (const [RealVector](#) &i_c_u_bnds)
set the inactive continuous upper bounds
- virtual const [IntVector](#) & [inactive_discrete_lower_bounds](#) () const
return the inactive discrete lower bounds
- virtual void [inactive_discrete_lower_bounds](#) (const [IntVector](#) &i_d_l_bnds)
set the inactive discrete lower bounds
- virtual const [IntVector](#) & [inactive_discrete_upper_bounds](#) () const
return the inactive discrete upper bounds
- virtual void [inactive_discrete_upper_bounds](#) (const [IntVector](#) &i_d_u_bnds)
set the inactive discrete upper bounds
- virtual [RealVector](#) [all_continuous_lower_bounds](#) () const
returns a single array with all continuous lower bounds
- virtual [RealVector](#) [all_continuous_upper_bounds](#) () const
returns a single array with all continuous upper bounds
- virtual [IntVector](#) [all_discrete_lower_bounds](#) () const
returns a single array with all discrete lower bounds
- virtual [IntVector](#) [all_discrete_upper_bounds](#) () const
returns a single array with all discrete upper bounds
- virtual void [write](#) (ostream &s) const
write a variable constraints object to an ostream
- virtual void [read](#) (istream &s)
read a variable constraints object from an istream
- size_t [num_linear_ineq_constraints](#) () const
return the number of linear inequality constraints

- `size_t num_linear_eq_constraints () const`
return the number of linear equality constraints
- `const RealMatrix & linear_ineq_constraint_coeffs () const`
return the linear inequality constraint coefficients
- `const RealVector & linear_ineq_constraint_lower_bounds () const`
return the linear inequality constraint lower bounds
- `const RealVector & linear_ineq_constraint_upper_bounds () const`
return the linear inequality constraint upper bounds
- `const RealMatrix & linear_eq_constraint_coeffs () const`
return the linear equality constraint coefficients
- `const RealVector & linear_eq_constraint_targets () const`
return the linear equality constraint targets

Protected Member Functions

- `VarConstraints (BaseConstructor, const ProblemDescDB &problem_db)`
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)
- `void manage_linear_constraints (const ProblemDescDB &problem_db)`
perform checks on user input, convert linear constraint coefficient input to matrices, and assign defaults

Protected Attributes

- `String variablesType`
All, Merged, AllMerged, or Fundamental.
- `size_t numLinearIneqConstraints`
number of linear inequality constraints
- `size_t numLinearEqConstraints`
number of linear equality constraints
- `RealMatrix linearIneqConstraintCoeffs`
linear inequality constraint coefficients
- `RealMatrix linearEqConstraintCoeffs`
linear equality constraint coefficients
- `RealVector linearIneqConstraintLowerBnds`
linear inequality constraint lower bounds

- [RealVector linearIneqConstraintUpperBnds](#)
linear inequality constraint upper bounds
- [RealVector linearEqConstraintTargets](#)
linear equality constraint targets
- [RealVector emptyRealVector](#)
an empty real vector returned in get functions when there are no variable constraints corresponding to the request
- [IntVector emptyIntVector](#)
an empty int vector returned in get functions when there are no variable constraints corresponding to the request

Private Member Functions

- [VarConstraints * get_var_constraints](#) (const [ProblemDescDB](#) &problem_db)
Used only by the constructor to initialize varConstraintsRep to the appropriate derived type.

Private Attributes

- [VarConstraints * varConstraintsRep](#)
pointer to the letter (initialized only for the envelope)
- [int referenceCount](#)
number of objects sharing varConstraintsRep

8.104.1 Detailed Description

Base class for the variable constraints class hierarchy.

The [VarConstraints](#) class is the base class for the class hierarchy managing linear and bound constraints on the variables. Using the variable lower and upper bounds arrays and linear constraint coefficients and bounds from the input specification, different derived classes define different views of this data. For memory efficiency and enhanced polymorphism, the variable constraints hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([VarConstraints](#)) serves as the envelope and one of the derived classes (selected in [VarConstraints::get_var_constraints\(\)](#)) serves as the letter.

8.104.2 Constructor & Destructor Documentation

8.104.2.1 [VarConstraints](#) ()

default constructor

The default constructor: `varConstraintsRep` is NULL in this case (a populated `problem_db` is needed to build a meaningful [VarConstraints](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

8.104.2.2 [VarConstraints](#) (const [ProblemDescDB](#) & *problem_db*, const [String](#) & *vars_type*)

standard constructor

The envelope constructor only needs to extract enough data to properly execute `get_var_constraints`, since the constructor overloaded with [BaseConstructor](#) builds the actual base class data inherited by the derived classes.

8.104.2.3 [VarConstraints](#) (const [VarConstraints](#) & *vc*)

copy constructor

Copy constructor manages sharing of `varConstraintsRep` and incrementing of `referenceCount`.

8.104.2.4 [~VarConstraints](#) () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `varConstraintsRep` when `referenceCount` reaches zero.

8.104.2.5 [VarConstraints](#) ([BaseConstructor](#), const [ProblemDescDB](#) & *problem_db*)
[protected]

constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. `get_var_constraints()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid recursion in the base class constructor calling `get_var_constraints()` again). Since the letter IS the representation, its `rep` pointer is set to NULL (an uninitialized pointer causes problems in `~VarConstraints`).

8.104.3 Member Function Documentation**8.104.3.1** [VarConstraints](#) operator= (const [VarConstraints](#) & *vc*)

assignment operator

Assignment operator decrements `referenceCount` for old `varConstraintsRep`, assigns new `varConstraintsRep`, and increments `referenceCount` for new `varConstraintsRep`.

8.104.3.2 void manage_linear_constraints (const [ProblemDescDB](#) & *problem_db*) [protected]

perform checks on user input, convert linear constraint coefficient input to matrices, and assign defaults

Convenience function called from derived class constructors. The number of variables active for applying linear constraints is currently defined to be the number of active continuous variables plus the number of active discrete variables (the most general case), even though very few optimizers can currently support mixed variable linear constraints.

8.104.3.3 [VarConstraints](#) * get_var_constraints (const [ProblemDescDB](#) & *problem_db*)
[private]

Used only by the constructor to initialize varConstraintsRep to the appropriate derived type.

Initializes varConstraintsRep to the appropriate derived type, as given by the variablesType attribute.

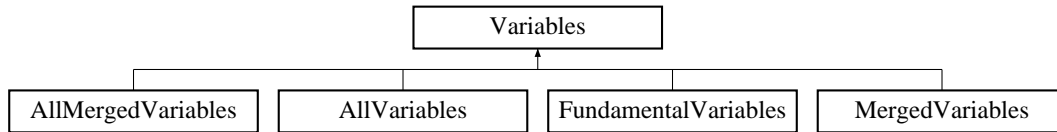
The documentation for this class was generated from the following files:

- [DakotaVarConstraints.H](#)
- [DakotaVarConstraints.C](#)

8.105 Variables Class Reference

Base class for the variables class hierarchy.

Inheritance diagram for Variables::



Public Member Functions

- [Variables](#) ()
default constructor
- [Variables](#) (const [ProblemDescDB](#) &problem_db)
standard constructor
- [Variables](#) (const [String](#) &vars_type)
alternate constructor
- [Variables](#) (const [Variables](#) &vars)
copy constructor
- virtual [~Variables](#) ()
destructor
- [Variables operator=](#) (const [Variables](#) &vars)
assignment operator
- virtual size_t [tv](#) () const
Returns total number of vars.
- virtual size_t [cv](#) () const
Returns number of active continuous vars.
- virtual size_t [dv](#) () const
Returns number of active discrete vars.
- virtual const [RealVector](#) & [continuous_variables](#) () const
return the active continuous variables
- virtual void [continuous_variables](#) (const [RealVector](#) &c_vars)
set the active continuous variables

- virtual const [IntVector](#) & [discrete_variables](#) () const
return the active discrete variables
- virtual void [discrete_variables](#) (const [IntVector](#) &d_vars)
set the active discrete variables
- virtual const [StringArray](#) & [continuous_variable_labels](#) () const
return the active continuous variable labels
- virtual void [continuous_variable_labels](#) (const [StringArray](#) &cv_labels)
set the active continuous variable labels
- virtual const [StringArray](#) & [discrete_variable_labels](#) () const
return the active discrete variable labels
- virtual void [discrete_variable_labels](#) (const [StringArray](#) &dv_labels)
set the active discrete variable labels
- virtual const [RealVector](#) & [inactive_continuous_variables](#) () const
return the inactive continuous variables
- virtual void [inactive_continuous_variables](#) (const [RealVector](#) &i_c_vars)
set the inactive continuous variables
- virtual const [IntVector](#) & [inactive_discrete_variables](#) () const
return the inactive discrete variables
- virtual void [inactive_discrete_variables](#) (const [IntVector](#) &i_d_vars)
set the inactive discrete variables
- virtual const [StringArray](#) & [inactive_continuous_variable_labels](#) () const
return the inactive continuous variable labels
- virtual void [inactive_continuous_variable_labels](#) (const [StringArray](#) &i_c_vars)
set the inactive continuous variable labels
- virtual const [StringArray](#) & [inactive_discrete_variable_labels](#) () const
return the inactive discrete variable labels
- virtual void [inactive_discrete_variable_labels](#) (const [StringArray](#) &i_d_vars)
set the inactive discrete variable labels
- virtual size_t [acv](#) () const
returns total number of continuous vars
- virtual size_t [adv](#) () const
returns total number of discrete vars
- virtual [RealVector](#) [all_continuous_variables](#) () const
returns a single array with all continuous variables

- virtual `IntVector all_discrete_variables ()` const
returns a single array with all discrete variables
- virtual `StringArray all_continuous_variable_labels ()` const
returns a single array with all continuous variable labels
- virtual `StringArray all_discrete_variable_labels ()` const
returns a single array with all discrete variable labels
- virtual `StringArray all_variable_labels ()` const
returns a single array with all variable labels
- virtual void `read (istream &s)`
read a variables object from an istream
- virtual void `write (ostream &s)` const
write a variables object to an ostream
- virtual void `write_aprepro (ostream &s)` const
write a variables object to an ostream in aprepro format
- virtual void `read_annotated (istream &s)`
read a variables object in annotated format from an istream
- virtual void `write_annotated (ostream &s)` const
write a variables object in annotated format to an ostream
- virtual void `write_tabular (ostream &s)` const
write a variables object in tabular format to an ostream
- virtual void `read (BiStream &s)`
read a variables object from the binary restart stream
- virtual void `write (BoStream &s)` const
write a variables object to the binary restart stream
- virtual void `read (MPIUnpackBuffer &s)`
read a variables object from a packed MPI buffer
- virtual void `write (MPIPackBuffer &s)` const
write a variables object to a packed MPI buffer
- `Variables copy ()` const
for use when a true copy is needed (the representation is `_not_shared`).
- const `IntList &merged_integer_list ()` const
returns the list of discrete variables merged into a continuous array
- const `String &variables_type ()` const

returns the variables type: *All, Merged, AllMerged, or Fundamental*

- const [StringArray](#) & [continuous_variable_types](#) () const
return the active continuous variable types
- const [StringArray](#) & [discrete_variable_types](#) () const
return the active discrete variable types

Protected Member Functions

- [Variables](#) ([BaseConstructor](#), const [ProblemDescDB](#) &problem_db)
constructor initializes the base class part of letter classes ([BaseConstructor](#) overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

Protected Attributes

- [IntList](#) [mergedIntegerList](#)
the list of discrete variables for which integrality is relaxed by merging them into a continuous array
- [String](#) [variablesType](#)
All, Merged, AllMerged, or Fundamental.
- [StringArray](#) [continuousVarTypes](#)
array of variable types for the active continuous variables
- [StringArray](#) [discreteVarTypes](#)
array of variable types for the active discrete variables
- [RealVector](#) [emptyRealVector](#)
an empty real vector returned in get functions when there are no variables corresponding to the request
- [IntVector](#) [emptyIntVector](#)
an empty int vector returned in get functions when there are no variables corresponding to the request
- [StringArray](#) [emptyStringArray](#)
an empty label array returned in get functions when there are no variables corresponding to the request

Private Member Functions

- virtual void [copy_rep](#) (const [Variables](#) *vars_rep)
Used by [copy\(\)](#) to copy the contents of a letter class.
- [Variables](#) * [get_variables](#) (const [ProblemDescDB](#) &problem_db)
Used by the standard envelope constructor to instantiate the correct letter class.
- [Variables](#) * [get_variables](#) (const [String](#) &vars_type) const
Used by the alternate envelope constructor, by read functions, and by [copy\(\)](#) to instantiate a new letter class.

Private Attributes

- [Variables](#) * [variablesRep](#)
pointer to the letter (initialized only for the envelope)
- int [referenceCount](#)
number of objects sharing variablesRep

Friends

- bool [operator==](#) (const [Variables](#) &vars1, const [Variables](#) &vars2)
equality operator
- bool [operator!=](#) (const [Variables](#) &vars1, const [Variables](#) &vars2)
inequality operator

8.105.1 Detailed Description

Base class for the variables class hierarchy.

The [Variables](#) class is the base class for the class hierarchy providing design, uncertain, and state variables for continuous and discrete domains within a [Model](#). Using the fundamental arrays from the input specification, different derived classes define different views of the data. For memory efficiency and enhanced polymorphism, the variables hierarchy employs the "letter/envelope idiom" (see Coplien "Advanced C++", p. 133), for which the base class ([Variables](#)) serves as the envelope and one of the derived classes (selected in [Variables::get_variables\(\)](#)) serves as the letter.

8.105.2 Constructor & Destructor Documentation

8.105.2.1 [Variables](#) ()

default constructor

The default constructor: [variablesRep](#) is NULL in this case (a populated [problem_db](#) is needed to build a meaningful [Variables](#) object). This makes it necessary to check for NULL in the copy constructor, assignment operator, and destructor.

8.105.2.2 [Variables](#) (const [ProblemDescDB](#) & *problem_db*)

standard constructor

This is the primary envelope constructor which uses [problem_db](#) to build a fully populated variables object. It only needs to extract enough data to properly execute [get_variables\(problem_db\)](#), since the constructor overloaded with [BaseConstructor](#) builds the actual base class data inherited by the derived classes.

8.105.2.3 Variables (const String & vars_type)

alternate constructor

This is the alternate envelope constructor for instantiations on the fly. Since it does not have access to `problem_db`, the letter class is not fully populated. This constructor executes `get_variables(vars_type)`, which invokes the default constructor of the derived letter class, which in turn invokes the default constructor of the base class.

8.105.2.4 Variables (const Variables & vars)

copy constructor

Copy constructor manages sharing of `variablesRep` and incrementing of `referenceCount`.

8.105.2.5 ~Variables () [virtual]

destructor

Destructor decrements `referenceCount` and only deletes `variablesRep` when `referenceCount` reaches zero.

8.105.2.6 Variables (BaseConstructor, const ProblemDescDB & problem_db) [protected]

constructor initializes the base class part of letter classes (`BaseConstructor` overloading avoids infinite recursion in the derived class constructors - Coplien, p. 139)

This constructor is the one which must build the base class data for all derived classes. `get_variables()` instantiates a derived class letter and the derived constructor selects this base class constructor in its initialization list (to avoid the recursion of the base class constructor calling `get_variables()` again). Since the letter IS the representation, its representation pointer is set to NULL (an uninitialized pointer causes problems in `~Variables`).

8.105.3 Member Function Documentation

8.105.3.1 Variables operator= (const Variables & vars)

assignment operator

Assignment operator decrements `referenceCount` for old `variablesRep`, assigns new `variablesRep`, and increments `referenceCount` for new `variablesRep`.

8.105.3.2 Variables copy () const

for use when a true copy is needed (the representation is `_not_shared`).

Deep copies are used for history mechanisms such as `bestVariables` and `data_pairs` since these must catalogue copies (and should not change as the representation within `currentVariables` changes).

8.105.3.3 Variables * get_variables (const ProblemDescDB & problem_db) [private]

Used by the standard envelope constructor to instantiate the correct letter class.

Initializes variablesRep to the appropriate derived type, as given by problem_db attributes. The standard derived class constructors are invoked.

8.105.3.4 Variables * get_variables (const String & vars_type) const [private]

Used by the alternate envelope constructor, by read functions, and by copy() to instantiate a new letter class.

Initializes variablesRep to the appropriate derived type, as given by the vars_type attribute. The default derived class constructors are invoked.

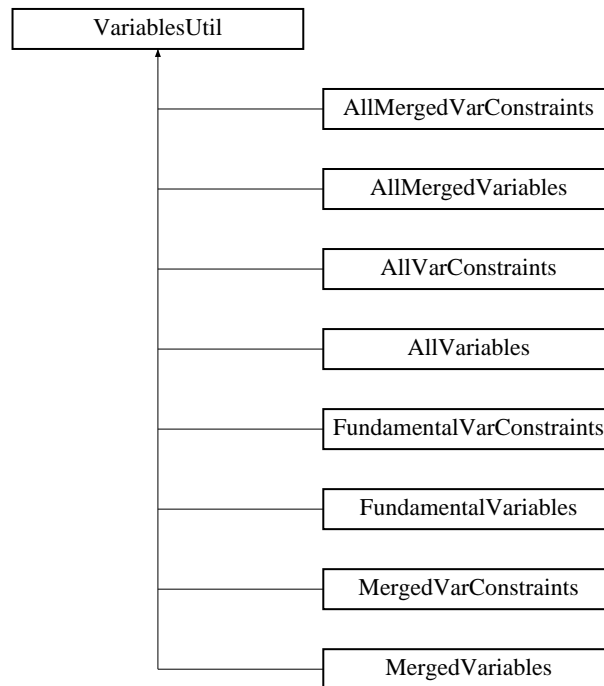
The documentation for this class was generated from the following files:

- DakotaVariables.H
- DakotaVariables.C

8.106 VariablesUtil Class Reference

Utility class for the [Variables](#) and [VarConstraints](#) hierarchies which provides convenience functions for variable vectors and label arrays for combining design, uncertain, and state variable types and merging continuous and discrete variable domains.

Inheritance diagram for VariablesUtil::



Public Member Functions

- [VariablesUtil](#) ()
constructor
- [~VariablesUtil](#) ()
destructor

Protected Member Functions

- void [update_merged](#) (const [RealVector](#) &c_array, const [IntVector](#) &d_array, [RealVector](#) &m_array)
combine a continuous array and a discrete array into a single continuous array through promotion of integers to reals (merged view)

- void `update_all_continuous` (const `RealVector` &c1_array, const `RealVector` &c2_array, const `RealVector` &c3_array, `RealVector` &all_array) const
combine 3 continuous arrays (design, uncertain, state) into a single continuous array (all view)
- void `update_all_discrete` (const `IntVector` &d1_array, const `IntVector` &d2_array, `IntVector` &all_array) const
combine 2 discrete arrays (design, state) into a single discrete array (all view)
- void `update_labels` (const `StringArray` &l1_array, const `StringArray` &l2_array, `StringArray` &all_array) const
combine 2 label arrays into a single label array (merged or all views)
- void `update_labels` (const `StringArray` &l1_array, const `StringArray` &l2_array, const `StringArray` &l3_array, `StringArray` &all_array) const
combine 3 label arrays (design, uncertain, state) into a single label array (all view)
- void `update_labels_partial` (size_t num_items, const `StringArray` &src_array, size_t src_start_index, `StringArray` &tgt_array, size_t tgt_start_index) const
update a portion of one label array from a portion of another label array (all view)

8.106.1 Detailed Description

Utility class for the `Variables` and `VarConstraints` hierarchies which provides convenience functions for variable vectors and label arrays for combining design, uncertain, and state variable types and merging continuous and discrete variable domains.

Derived classes within the `Variables` and `VarConstraints` hierarchies use multiple inheritance to inherit these utilities.

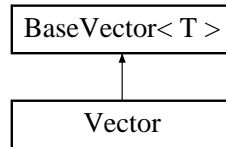
The documentation for this class was generated from the following file:

- `VariablesUtil.H`

8.107 Vector Class Template Reference

Template class for the [Dakota](#) numerical vector.

Inheritance diagram for Vector::



Public Member Functions

- [Vector](#) ()
Default constructor.
- [Vector](#) (size_t len)
Constructor which takes an initial length.
- [Vector](#) (size_t len, const T &initial_val)
Constructor which takes an initial length and an initial value.
- [Vector](#) (const [Vector](#)< T > &a)
Copy constructor.
- [Vector](#) (const T *p, size_t len)
Constructor which copies len entries from T.*
- [~Vector](#) ()
Destructor.
- [Vector](#)< T > & [operator=](#) (const [Vector](#)< T > &a)
Normal const assignment operator.
- [Vector](#)< T > & [operator=](#) (const T &ival)
Sets all elements in self to the value ival.
- [operator T *](#) () const
Converts the [Vector](#) to a standard C-style array. Use with care!
- void [read](#) (istream &s)
Reads a [Vector](#) from an input stream.
- void [read](#) (istream &s, [Array](#)< [String](#) > &label_array)
Reads a [Vector](#) and associated label array from an input stream.

- void `read_partial` (istream &s, size_t start_index, size_t num_items)
Reads part of a `Vector` from an input stream.
- void `read_partial` (istream &s, size_t start_index, size_t num_items, Array< String > &label_array)
Reads part of a `Vector` and the corresponding labels from an input stream.
- void `read_tabular` (istream &s)
Reads a `Vector` from a tabular text input file.
- void `read_annotated` (istream &s, Array< String > &label_array)
Reads a `Vector` and associated label array in annotated from an input stream.
- void `print` (ostream &s) const
Prints a `Vector` to an output stream.
- void `print` (ostream &s, const Array< String > &label_array) const
Prints a `Vector` and associated label array to an output stream.
- void `print_partial` (ostream &s, size_t start_index, size_t num_items) const
Prints part of a `Vector` to an output stream.
- void `print_partial` (ostream &s, size_t start_index, size_t num_items, const Array< String > &label_array) const
Prints part of a `Vector` and the corresponding labels to an output stream.
- void `print_aprepro` (ostream &s, const Array< String > &label_array) const
Prints a `Vector` and associated label array to an output stream in aprepro format.
- void `print_partial_aprepro` (ostream &s, size_t start_index, size_t num_items, const Array< String > &label_array) const
Prints part of a `Vector` and the corresponding labels to an output stream in aprepro format.
- void `print_annotated` (ostream &s, const Array< String > &label_array) const
Prints a `Vector` and associated label array in annotated form to an output stream.
- void `print_tabular` (ostream &s) const
Prints a `Vector` in tabular form to an output stream.
- void `print_partial_tabular` (ostream &s, size_t start_index, size_t num_items) const
Prints part of a `Vector` in tabular form to an output stream.
- void `read` (BiStream &s, Array< String > &label_array)
Reads a `Vector` and associated label array from a binary input stream.
- void `print` (BoStream &s, const Array< String > &label_array) const
Prints a `Vector` and associated label array to a binary output stream.
- void `read` (MPIUnpackBuffer &s)

Reads a *Vector* from a buffer after an MPI receive.

- void `read (MPIUnpackBuffer &s, Array< String > &label_array)`
Reads a *Vector* and associated label array from a buffer after an MPI receive.
- void `print (MPIPackBuffer &s) const`
Writes a *Vector* to a buffer prior to an MPI send.
- void `print (MPIPackBuffer &s, const Array< String > &label_array) const`
Writes a *Vector* and associated label array to a buffer prior to an MPI send.

8.107.1 Detailed Description

`template<class T> class Dakota::Vector< T >`

Template class for the [Dakota](#) numerical vector.

The `Dakota::Vector` class is the numeric vector class. It inherits from the common vector class `Dakota::BaseVector` which provides the same interface for both the STL and RW vector classes. If the STL version of `BaseVector` is based on the `valarray` class then some basic vector operations such as `+`, `*` are available. This class adds functionality to read/print vectors in a variety of ways

8.107.2 Constructor & Destructor Documentation

8.107.2.1 `Vector (const T * p, size_t len) [inline]`

Constructor which copies len entries from T*.

Assigns size values from p into array.

8.107.3 Member Function Documentation

8.107.3.1 `Vector< T > & operator=(const T & ival) [inline]`

Sets all elements in self to the value ival.

Assigns all values of array to ival. If STL, uses the vector assign method because there is no `operator=(ival)`.

Reimplemented from `BaseVector`.

The documentation for this class was generated from the following file:

- `DakotaVector.H`

Chapter 9

DAKOTA File Documentation

9.1 keywordtable.C File Reference

file containing keywords for the strategy, method, variables, interface, and responses input specifications from **dakota.input.spec**

Variables

- const struct KeywordHandler [idrKeywordTable](#) []
Initialize the keyword table as a vector of KeywordHandler structures (KeywordHandler declared in idr-keyword.h). A null KeywordHandler structure signifies the end of the keyword table.

9.1.1 Detailed Description

file containing keywords for the strategy, method, variables, interface, and responses input specifications from **dakota.input.spec**

9.2 main.C File Reference

file containing the main program for DAKOTA

Functions

- int `main` (int argc, char *argv[])
The main DAKOTA program.

Variables

- int `write_precision` = 10
used in ostream data output functions

9.2.1 Detailed Description

file containing the main program for DAKOTA

9.2.2 Function Documentation

9.2.2.1 int main (int argc, char * argv[])

The main DAKOTA program.

Manage command line inputs, input files, restart file(s), output streams, and top level parallel iterator communicators. Instantiate the Strategy and invoke its `run_strategy()` virtual function.

9.3 restart_util.C File Reference

file containing the DAKOTA restart utility main program

Namespaces

- namespace [Dakota](#)

Functions

- void [print_restart](#) (int argc, char **argv, [String](#) print_dest)
print a restart file
- void [print_restart_tabular](#) (int argc, char **argv, [String](#) print_dest)
print a restart file (tabular format)
- void [read_neutral](#) (int argc, char **argv)
read a restart file (neutral file format)
- void [repair_restart](#) (int argc, char **argv, [String](#) identifier_type)
repair a restart file by removing corrupted evaluations
- void [concatenate_restart](#) (int argc, char **argv)
concatenate multiple restart files
- int [main](#) (int argc, char *argv[])
The main program for the DAKOTA restart utility.

Variables

- int [write_precision](#) = 16
used in ostream data output functions

9.3.1 Detailed Description

file containing the DAKOTA restart utility main program

9.3.2 Function Documentation

9.3.2.1 void print_restart (int argc, char ** argv, String print_dest)

print a restart file

Usage: "dakota_restart_util print dakota.rst"

"dakota_restart_util to_neutral dakota.rst dakota.neu"

Prints all evals. in full precision to either stdout or a neutral file. The former is useful for ensuring that duplicate detection is successful in a restarted run (e.g., starting a new method from the previous best), and the latter is used for translating binary files between platforms.

9.3.2.2 void print_restart_tabular (int argc, char ** argv, String print_dest)

print a restart file (tabular format)

Usage: "dakota_restart_util to_pdb dakota.rst dakota.pdb"

"dakota_restart_util to_tabular dakota.rst dakota.txt"

Unrolls all data associated with a particular tag for all evaluations and then writes this data in a tabular format (e.g., to a PDB database or MATLAB/TECPLOT data file).

9.3.2.3 void read_neutral (int argc, char ** argv)

read a restart file (neutral file format)

Usage: "dakota_restart_util from_neutral dakota.neu dakota.rst"

Reads evaluations from a neutral file. This is used for translating binary files between platforms.

9.3.2.4 void repair_restart (int argc, char ** argv, String identifier_type)

repair a restart file by removing corrupted evaluations

Usage: "dakota_restart_util remove 0.0 dakota_old.rst dakota_new.rst"

"dakota_restart_util remove_ids 2 7 13 dakota_old.rst dakota_new.rst"

Repairs a restart file by removing corrupted evaluations. The identifier for evaluation removal can be either a double precision number (all evaluations having a matching response function value are removed) or a list of integers (all evaluations with matching evaluation ids are removed).

9.3.2.5 void concatenate_restart (int argc, char ** argv)

concatenate multiple restart files

Usage: "dakota_restart_util cat dakota_1.rst ... dakota_n.rst dakota_new.rst"

Combines multiple restart files into a single restart database.

9.3.2.6 int main (int argc, char * argv[])

The main program for the DAKOTA restart utility.

Parse command line inputs and invoke the appropriate utility function ([print_restart\(\)](#), [print_restart_tabular\(\)](#), [read_neutral\(\)](#), [repair_restart\(\)](#), or [concatenate_restart\(\)](#)).

Chapter 10

Interfacing with DAKOTA as a Library

10.1 Introduction

Some users may be interested in linking the DAKOTA toolkit into another application for use as an algorithm library. While this is not the primary usage model for DAKOTA, certain facilities are in place to allow this type of integration.

As part of the normal DAKOTA build process, a `libdakota.a` is created and a copy of it is placed in `Dakota/lib`. This library contains all source files from `Dakota/src` excepting the `main.C` and `restart_util.C` main programs. This library may be linked with another application through inclusion of `-ldakota` on the link line. Library and header paths may also be specified using the `-L` and `-I` compiler options. Depending on the configuration used when building this library, other libraries for the vendor optimizers and vendor packages will also be needed to resolve DAKOTA symbols for DOT, NPSOL, OPT++, SGOPT, LHS, Epetra, etc. Copies of these libraries are also placed in `Dakota/lib`. An XML specification of library names and paths is also available in `Dakota/dependency`.

Warning:

While users are free to interface DAKOTA as a library within other software applications for their own internal use, the GNU GPL license stipulates that any application linked with DAKOTA in this way defines a "derivative work" and can only be distributed externally under the same GNU GPL open source license. Refer to <http://www.gnu.org/licenses/gpl.html> or contact the DAKOTA team for additional information.

Attention:

The use of DAKOTA as an algorithm library should be distinguished from the linking of simulations within DAKOTA using the direct application interface (see [DirectFnApplicInterface](#)). In the former, DAKOTA is providing algorithm services to another software application, and in the latter, a linked simulation is providing analysis services to DAKOTA. It is not uncommon for these two capabilities to be used in combination, resulting in a "sandwich" implementation.

The procedure for utilizing DAKOTA as a library within another application involves a number of steps that are similar to those used in the stand-alone DAKOTA application. The stand-alone procedure can be viewed in the file `main.C`, and the differences for the library approach are most easily explained with reference to that file. The basic steps of executing DAKOTA include instantiating the `ParallelLibrary`, `CommandLineHandler`, and `ProblemDescDB` objects; man-

aging the DAKOTA input file (`ProblemDescDB::manage_inputs()`); specifying restart files and output streams (`ParallelLibrary::specify_outputs_restart()`); and instantiating the `Strategy` and running it (`Strategy::run_strategy()`). When using DAKOTA as an algorithm library, the operations are quite similar, although command line information (`argc`, `argv`, and therefore `CommandLineHandler`) will not in general be accessible. In particular, `main.C` can pass `argc` and `argv` into the `ParallelLibrary` and `CommandLineHandler` constructors and then pass the `CommandLineHandler` object into `ProblemDescDB::manage_inputs()` and `ParallelLibrary::specify_outputs_restart()`. In an algorithm library approach, a `CommandLineHandler` object is not instantiated and overloaded forms of the `ParallelLibrary` constructor, `ProblemDescDB::manage_inputs()`, and `ParallelLibrary::specify_outputs_restart()` are used.

The overloaded forms of these functions are as follows. For instantiation of the `ParallelLibrary` object, the default constructor may be used. This constructor assumes that MPI is initialized elsewhere in the parent application. That is, the instantiation

```
ParallelLibrary parallel_lib(argc, argv);
```

is replaced with

```
ParallelLibrary parallel_lib;
```

In the case of specifying restart files and output streams, the call to

```
parallel_lib.specify_outputs_restart(cmd_line_handler);
```

should be replaced with its overloaded form in order to pass the required information through the parameter list

```
parallel_lib.specify_outputs_restart(std_output_filename, std_error_filename,
read_restart_filename, write_restart_filename, restart_evals);
```

where file names for standard output and error and restart read and write as well as the integer number of restart evaluations are passed through the parameter list rather than read from the command line of the main DAKOTA program. The definition of these attributes is performed elsewhere in the parent application (e.g., specified in the parent application input file or GUI).

With respect to modifying `ProblemDescDB::manage_inputs()`, the two following sections describe different approaches to populating data within DAKOTA's problem description database. It is this database from which all DAKOTA objects draw data upon instantiation.

10.2 Problem database populated through input file parsing

The simplest approach to linking an application with the DAKOTA library is to rely on DAKOTA's normal parsing system to populate DAKOTA's problem database (`ProblemDescDB`) through the reading of an input file. The disadvantage to this approach is the requirement for an additional input file beyond those already required by the parent application.

In this approach, the call to

```
problem_db.manage_inputs(cmd_line_handler);
```

should be replaced with its overloaded form

```
problem_db.manage_inputs(dakota_input_file);
```

where the file name for the DAKOTA input is passed through the parameter list rather than read from the command line of the main DAKOTA program. Again, the definition of the DAKOTA input file name is performed elsewhere in the parent application (e.g., specified in the parent application input file or GUI).

10.3 Problem database populated through external means

This approach is more involved than the previous approach, but it allows the application to publish all needed data to DAKOTA's database directly, thereby eliminating the need for the parsing of a separate DAKOTA input file. In this case, `ProblemDescDB::manage_inputs()` is not called. Rather, `DataStrategy`, `DataMethod`, `DataVariables`, `DataInterface`, and `DataResponses` objects must be instantiated and populated with the desired problem data. These objects are then published to the problem database using `ProblemDescDB::insert_node()`, e.g.:

```
// instantiate the data object
DataMethod data_method;

// set the attributes within the data object
data_method.methodName = "nond_sampling";
...

// publish the data object to the ProblemDescDB
problem_db.insert_node(data_method);
```

The data objects are populated with their default values upon instantiation, so only the non-default values need to be specified. Refer to the `DataStrategy`, `DataMethod`, `DataVariables`, `DataInterface`, and `DataResponses` class documentation and source code for lists of attributes and their defaults.

The default strategy is `single_method`, which runs a single iterator on a single model, so it is not necessary to instantiate and publish a `DataStrategy` object if coordination of multiple iterators and models is not required. Rather, instantiation and insertion of a single `DataMethod`, `DataVariables`, `DataInterface`, and `DataResponses` object is sufficient for basic DAKOTA capabilities.

Once the data objects have been published to the `ProblemDescDB` object, a call to

```
problem_db.check_input();
```

will perform basic database error checking.

10.4 Instantiating the strategy

With the `ProblemDescDB` object populated with problem data, we may now instantiate the strategy.

```
// instantiate the strategy
Strategy selected_strategy(problem_db);
```

Following strategy construction, all MPI communicator partitioning has been performed and the `ParallelLibrary` instance may be interrogated for parallel configuration data. For example, the lowest level communicators in DAKOTA's multilevel parallel partitioning are the analysis communicators, which can be retrieved using:

```
// retrieve the set of analysis communicators for simulation initialization:
// one analysis comm per ParallelConfiguration (PC), one PC per Model.
Array<MPI_Comm> analysis_comms = parallel_lib.analysis_intra_communicators();
```

These communicators can then be used for initializing parallel simulation instances, where the number of MPI communicators in the array corresponds to one communicator per [ParallelConfiguration](#) instance, where there is one [ParallelConfiguration](#) instance per [Model](#).

10.5 Defining the direct application interface

When employing a library interface to DAKOTA, it is frequently desirable to also use a direct interface between DAKOTA and the simulation. There are two approaches to defining this direct interface.

10.5.1 Extension

The first approach involves extending the existing [DirectFnApplicInterface](#) class to support additional direct simulation interfaces. In this case, a new interface member function can be added to `Dakota/src/DirectFnApplicInterface.[CH]` for the simulation of interest using the prototype:

```
int sim(const Variables& vars, const IntArray& asv, Response& response);
```

This simulation can then be added to the logic blocks in [DirectFnApplicInterface::derived_map_ac\(\)](#). In addition, [DirectFnApplicInterface::derived_map_if\(\)](#) and [DirectFnApplicInterface::derived_map_of\(\)](#) can be extended to perform pre- and post-processing tasks if desired, but this is not required.

While this approach is the simplest, it has the disadvantage that the DAKOTA library may need to be recompiled when the simulation or its direct interface is modified. If it is desirable to maintain the independence of the DAKOTA library from the host application, then the following derivation approach should be employed.

10.5.2 Derivation

The second approach is to derive a new interface from [DirectFnApplicInterface](#) in order to redefine several virtual functions. A typical derived class declaration might be

```
namespace SIM {

class DirectFnApplicInterface: public Dakota::DirectFnApplicInterface
{
public:

    // Constructor and destructor

    DirectFnApplicInterface(const ProblemDescDB& problem_db, const size_t& num_fns);
    ~DirectFnApplicInterface();

protected:

    // Virtual function redefinitions

    int derived_map_if(const DakotaString& if_name);
    int derived_map_ac(const DakotaString& ac_name);
    int derived_map_of(const DakotaString& of_name);

private:

    // Data
}
```

```
} // namespace SIM
```

where the new derived class resides in the simulation's namespace. Similar to the case of [Extension](#), the [DirectFnApplicInterface::derived_map_ac\(\)](#) function is the required redefinition, and [DirectFnApplicInterface::derived_map_if\(\)](#) and [DirectFnApplicInterface::derived_map_of\(\)](#) are optional.

The new derived interface object (from namespace SIM) must now be plugged into the strategy. In the simplest case of a single model and interface, one could use

```
// retrieve the interface of interest
ModelList& all_models = selected_strategy.models();
Model& first_model = *all_models.begin();
Interface& interface = first_model.interface();
// plug in the new direct interface instance
interface.assign_rep(new DirectFnApplicInterface(problem_db, num_fns));
// repropagate parallel configuration data down to the new interface
first_model.reset_communicators();
```

In a more advanced case of multiple models and multiple interface plug-ins, one might use

```
// retrieve the list of Models from the Strategy
ModelList& models = selected_strategy.models();
// iterate over the Model list
for (ModelListIter ml_iter = models.begin(); ml_iter!=models.end(); ml_iter++) {
    Interface& interface = (*ml_iter).interface();
    if (interface.interface_type() == "application_direct") {
        // plug in the new direct interface instance
        interface.assign_rep(new DirectFnApplicInterface(problem_db, num_fns));
        // repropagate parallel configuration data down to the new interface
        (*ml_iter).reset_communicators();
    }
}
```

New direct interface instances inherit various attributes of use in configuring the simulation. In particular, the [ApplicationInterface::parallelLib](#) reference provides access to MPI communicator data (e.g., the analysis communicators discussed in [Instantiating the strategy](#)), [ApplicationInterface::analysisDrivers](#) provides the analysis driver names specified by the user in the input file, and [ApplicationInterface::analysisComponents](#) provides additional analysis component identifiers (such as mesh file names) provided by the user which can be used to distinguish different instances of the same simulation interface.

10.6 Executing the strategy

Finally, with simulation configuration and plug-ins completed, we execute the strategy:

```
// run the strategy
selected_strategy.run_strategy();
```

10.7 Retrieving data after a run

After executing the strategy, final results can be obtained through the use of [Strategy::strategy_variable_results\(\)](#) and [Strategy::strategy_response_results\(\)](#), e.g.:

```
// retrieve the final parameter values
const Variables& vars = selected_strategy.strategy_variable_results();

// retrieve the final response values
const Response& resp = selected_strategy.strategy_response_results();
```

In the case of optimization, the final design is returned, and in the case of uncertainty quantification, the final statistics are returned.

10.8 Summary

To utilize the DAKOTA library within a parent software application, the basic steps of [main.C](#) and the order of invocation of these steps should be mimicked from within the parent application. Of these steps, [ParallelLibrary](#) instantiation, [ProblemDescDB::manage_inputs\(\)](#) and [ParallelLibrary::specify_outputs_restart\(\)](#) require the use of overloaded forms in order to function in an environment without direct command line access and, potentially, without file parsing. Additional optional steps not performed in [main.C](#) include the extension/derivation of the direct interface and the retrieval of strategy results after a run.

DAKOTA's library mode has stabilized and is now being used successfully by several Sandia and external simulation codes/frameworks.

Chapter 11

Performing Function Evaluations

Performing function evaluations is one of the most critical functions of the DAKOTA software. It can also be one of the most complicated, as a variety of scheduling approaches and parallelism levels are supported. This complexity manifests itself in the code through a series of cascaded member functions, from the top level model evaluation functions, through various scheduling routines, to the low level details of performing a system call, fork, or direct function invocation. This section provides an overview of the primary classes and member functions involved.

11.1 Synchronous function evaluations

For a synchronous (i.e., blocking) mapping of parameters to responses, an iterator invokes [Model::compute_response\(\)](#) to perform a function evaluation. This function is all that is seen from the iterator level, as underlying complexities are isolated. The binding of this top level function with lower level functions is as follows:

- [Model::compute_response\(\)](#) utilizes [Model::derived_compute_response\(\)](#) for portions of the response computation specific to derived model classes.
- [Model::derived_compute_response\(\)](#) directly or indirectly invokes [Interface::map\(\)](#).
- [Interface::map\(\)](#) utilizes [ApplicationInterface::derived_map\(\)](#) for portions of the mapping specific to derived application interface classes.

11.2 Asynchronous function evaluations

For an asynchronous (i.e., nonblocking) mapping of parameters to responses, an iterator invokes [Model::asynch_compute_response\(\)](#) multiple times to queue asynchronous jobs and then invokes either [Model::synchronize\(\)](#) or [Model::synchronize_nowait\(\)](#) to schedule the queued jobs in blocking or non-blocking fashion. Again, these functions are all that is seen from the iterator level, as underlying complexities are isolated. The binding of these top level functions with lower level functions is as follows:

- [Model::asynch_compute_response\(\)](#) utilizes [Model::derived_asynch_compute_response\(\)](#) for portions of the response computation specific to derived model classes.
-

- This derived model class function directly or indirectly invokes `Interface::map()` in asynchronous mode, which adds the job to a scheduling queue.
- `Model::synchronize()` or `Model::synchronize_nowait()` utilize `Model::derived_synchronize()` or `Model::derived_synchronize_nowait()` for portions of the scheduling process specific to derived model classes.
- These derived model class functions directly or indirectly invoke `Interface::synch()` or `Interface::synch_nowait()`.
- For application interfaces, these interface synchronization functions are responsible for performing evaluation scheduling in one of the following modes:
 - asynchronous local mode (using `ApplicationInterface::asynchronous_local_evaluations()` or `ApplicationInterface::asynchronous_local_evaluations_nowait()`)
 - message passing mode (using `ApplicationInterface::self_schedule_evaluations()` or `ApplicationInterface::static_schedule_evaluations()` on the iterator master and `ApplicationInterface::serve_evaluations_synch()` or `ApplicationInterface::serve_evaluations_peer()` on the servers)
 - hybrid mode (using `ApplicationInterface::self_schedule_evaluations()` or `ApplicationInterface::static_schedule_evaluations()` on the iterator master and `ApplicationInterface::serve_evaluations_asynch()` on the servers)
- These scheduling functions utilize `ApplicationInterface::derived_map()` and `ApplicationInterface::derived_map_asynch()` for portions of asynchronous job launching specific to derived application interface classes, as well as `ApplicationInterface::derived_synch()` and `ApplicationInterface::derived_synch_nowait()` for portions of job capturing specific to derived application interface classes.

11.3 Analyses within each function evaluation

The discussion above covers the parallelism level of concurrent function evaluations serving an iterator. For the parallelism level of concurrent analyses serving a function evaluation, similar schedulers are involved (`ForkApplicInterface::synchronous_local_analyses()`, `ForkApplicInterface::asynchronous_local_analyses()`, `ApplicationInterface::self_schedule_analyses()`, `ApplicationInterface::serve_analyses_synch()`, `ForkApplicInterface::serve_analyses_asynch()`) to support synchronous local, asynchronous local, message passing, and hybrid modes. Not all of the schedulers are elevated to the `ApplicationInterface` level since the system call and direct function interfaces do not yet support nonblocking local analyses (and therefore support synchronous local and message passing modes, but not asynchronous local or hybrid modes). Fork interfaces, however, support all modes of analysis parallelism.

Chapter 12

Recommended Practices for DAKOTA Development

12.1 Introduction

Common code development practices can be extremely useful in multiple developer environments. Particular styles for code components lead to improved readability of the code and can provide important visual cues to other developers.

Much of this recommended practices document is borrowed from the CUBIT mesh generation project, which in turn borrows its recommended practices from other projects. As a result, C++ coding styles are fairly standard across a variety of Sandia software projects in the engineering and computational sciences.

12.2 Style Guidelines

Style guidelines involve the ability to discern at a glance the type and scope of a variable or function.

12.2.1 Class and variable styles

Class names should be composed of two or more descriptive words, with the first character of each word capitalized, e.g.:

```
class ClassName;
```

Class member variables should be composed of two or more descriptive words, with the first character of the second and succeeding words capitalized, e.g.:

```
double classMemberVariable;
```

Temporary (i.e. local) variables are lower case, with underscores separating words in a multiple word temporary variable, e.g.:

```
int temporary_variable;
```

Constants (i.e. parameters) are upper case, with underscores separating words, e.g.:

```
const double CONSTANT_VALUE;
```

12.2.2 Function styles

Function names are lower case, with underscores separating words, e.g.:

```
int function_name();
```

There is no need to distinguish between member and non-member functions by style, as this distinction is usually clear by context. This style convention arose from the desire to have member functions which set and return the value of a private member variable, e.g.:

```
int memberVariable;
void member_variable(int a) { // set
    memberVariable = a;
}
int member_variable() const { // get
    return memberVariable;
}
```

In cases where the data to be set or returned is more than a few bytes, it is highly desirable to employ const references to avoid unnecessary copying, e.g.:

```
void continuous_variables(const RealVector& c_vars) { // set
    continuousVariables = c_vars;
}
const RealVector& continuous_variables() const { // get
    return continuousVariables;
}
```

Note that it is not necessary to always accept the returned data as a const reference. If it is desired to be able change this data, then accepting the result as a new variable will generate a copy, e.g.:

```
const RealVector& c_vars = model.continuous_variables(); // reference to continuousVariables cannot be changed
RealVector c_vars = model.continuous_variables(); // local copy of continuousVariables can be changed
```

12.2.3 Miscellaneous

Appearance of typedefs to redefine or alias basic types is isolated to a few header files ([data_types.h](#), [template_defs.h](#)), so that issues like program precision can be changed by changing a few lines of typedefs rather than many lines of code, e.g.:

```
typedef double Real;
```

xemacs is the preferred source code editor, as it has C++ modes for enhancing readability through color (turn on "Syntax highlighting"). Other helpful features include "Paren highlighting" for matching parentheses and the "New Frame" utility to have more than one window operating on the same set of files (note that this is still the same edit session, so all windows are synchronized with each other). Window width should be set to 80 internal columns, which can be accomplished by manual resizing, or preferably, using the following alias in your shell resource file (e.g., .cshrc):

```
alias xemacs "xemacs -g 81x63"
```

where an external width of 81 gives 80 columns internal to the window and the desired height of the window will vary depending on monitor size. This window width imposes a coding standard since you should avoid line wrapping by continuing anything over 80 columns onto the next line.

Indenting increments are 2 spaces per indent and comments are aligned with the code they describe, e.g.:

```
void abort_handler(int code)
{
    int initialized = 0;
    MPI_Initialized(&initialized);
    if (initialized) {
        // comment aligned to block it describes
        int size;
        MPI_Comm_size(MPI_COMM_WORLD, &size);
        if (size>1)
            MPI_Abort(MPI_COMM_WORLD, code);
        else
            exit(code);
    }
    else
        exit(code);
}
```

Also, the continuation of a long command is indented 2 spaces, e.g.:

```
const String& iterator_scheduling
    = problem_db.get_string("strategy.iterator_scheduling");
```

and similar lines are aligned for readability, e.g.:

```
cout << "Numerical gradients using " << finiteDiffStepSize*100. << "%"
    << finiteDiffType << " differences\nto be calculated by the "
    << methodSource << " finite difference routine." << endl;
```

Lastly, #ifdef's are not indented (to make use of syntax highlighting in xemacs).

12.3 File Naming Conventions

In addition to the style outlined above, the following file naming conventions have been established for the DAKOTA project.

File names for C++ classes should, in general, use the same name as the class defined by the file. Exceptions include:

- with the introduction of the Dakota namespace, base classes which previously utilized prepended Dakota identifiers can now safely omit the identifiers. However, since file names do not have namespace protection from name collisions, they retain the prepended Dakota identifier. For example, a

class previously named `DakotaModel` which resided in `DakotaModel.[CH]`, is now `Dakota::Model` (class `Model` in namespace `Dakota`) residing in the same filenames. The retention of the previous filenames reduces the possibility of multiple instances of a `Model.H` causing problems. Derived classes (e.g., `NestedModel`) do not require a prepended `Dakota` identifier for either the class or file names.

- in a few cases, it is convenient to maintain several closely related classes in a single file, in which case the file name may reflect the top level class or some generalization of the set of classes (e.g., `Dakota-Response.[CH]` files contain `Dakota::Response` and `Dakota::ResponseRep` classes, and `DakotaBin-Stream.[CH]` files contain the `Dakota::BiStream` and `Dakota::BoStream` classes).

The type of file is determined by one of the four file name extensions listed below:

- **.H** A class header file ends in the suffix `.H`. The header file provides the class declaration. This file does not contain code for implementing the methods, except for the case of inline functions. Inline functions are to be placed at the bottom of the file with the keyword `inline` preceding the function name.
- **.C** A class implementation file ends in the suffix `.C`. An implementation file contains the definitions of the members of the class.
- **.h** A header file ends in the suffix `.h`. The header file contains information usually associated with procedures. Defined constants, data structures and function prototypes are typical elements of this file.
- **.c** A procedure file ends in the suffix `.c`. The procedure file contains the actual procedures.

12.4 Class Documentation Conventions

Class documentation uses the `doxygen` tool available from <http://www.doxygen.org> and employs the `JAVA-doc` comment style. Brief comments appear in header files next to the attribute or function declaration. Detailed descriptions for functions should appear alongside their implementations (i.e., in the `.C` files for non-inlined, or in the headers next to the function definition for inlined). Detailed comments for a class or a class attribute must go in the header file as this is the only option.

NOTE: Previous class documentation utilities (`class2frame` and `class2html`) used the `"//-"` comment style and comment blocks such as this:

```
// - Class:      Model
// - Description: The model to be iterated by the Iterator.  Contains Variables, Interface, and Response objects
// - Owner:      Mike Eldred
// - Version:    $Id: RecommendPract.dox,v 1.7 2004/05/22 00:29:02 mseldre Exp $
```

These tools are no longer used, so remaining comment blocks of this type are informational only and will not appear in the documentation generated by `doxygen`.

Chapter 13

Instructions for Modifying DAKOTA's Input Specification

13.1 Modify `dakota.input.spec`

The master input specification resides in `dakota.input.spec` in `$DAKOTA/src`. As part of the Input Deck Reader (IDR) build process, a soft link to this file is created in `$DAKOTA/ VendorPackages/idr`. The master input specification can be modified with the addition of new constructs using the following logical relationships:

- `{ }` for required individual specifications
- `()` for required group specifications
- `[]` for optional individual specifications
- `[]` for optional group specifications
- `|` for "or" conditionals

These constructs can be used to define a variety of dependency relationships in the input specification. It is recommended that you review the existing specification and have an understanding of the constructs in use before attempting to add new constructs.

Warning:

- Do *not* skip this step. Attempts to modify the `keywordtable.C` and `ProblemDescDB.C` files in `$DAKOTA/src` without reference to the results of the code generator are very error-prone. Moreover, the input specification provides a reference to the allowable inputs of a particular executable and should be kept in synch with the parser files (modifying the parser files independent of the input specification creates, at a minimum, undocumented features).
 - Since the Input Deck Reader (IDR) parser allows abbreviation of keywords, you *must* avoid adding a keyword that could be misinterpreted as an abbreviation for a different keyword within the same keyword handler (the term "keyword handler" refers to the `strategy_kwhandler()`, `method_kwhandler()`, `variables_kwhandler()`, `interface_kwhandler()`, and `responses_kwhandler()` member functions in the `ProblemDescDB` class). For example, adding
-

the keyword "expansion" within the method specification would be a mistake if the keyword "expansion_factor" already was being used in this specification.

- Since IDR input is order-independent, the same keyword may be reused multiple times in the specification if and only if the specification blocks are mutually exclusive. For example, method selections (e.g., `dot_frcg`, `dot_bfgs`) can reuse the same method setting keywords (e.g., `optimization_type`) since the method selection blocks are all separated by logical "or"s. If `dot_frcg` and `dot_bfgs` were not exclusive and could be specified at the same time, then association of the `optimization_type` setting with a particular method would be ambiguous. This is the reason why repeated specifications which are non-exclusive must be made unique, typically with a prepended identifier (e.g., `cdv_initial_point`, `ddv_initial_point`).

13.2 Rebuild IDR

```
cd $DAKOTA/VendorPackages/idr
make clean
make
```

These steps regenerate [keywordtable.C](#) and `idr-gen-code.C` in the `$DAKOTA/VendorPackages/idr/<canonical_build_directory>` directory for use in updating [keywordtable.C](#) and [ProblemDescDB.C](#) in `$DAKOTA/src`.

13.3 Update keywordtable.C in \$DAKOTA/src

Do *not* directly replace the [keywordtable.C](#) in `$DAKOTA/src` using the one from `idr`, as there are important differences in the `kwhandler` bindings. Rather, update the [keywordtable.C](#) in `$DAKOTA/src` using the one from `idr` as a reference. Once this step is completed, it is a good idea to verify the match by diff'ing the 2 files. The only differences should be in comments, includes, and `kwhandler` declarations.

13.4 Update ProblemDescDB.C in \$DAKOTA/src

Find the keyword handler functions (e.g., `variables_kwhandler()`) in `$DAKOTA/VendorPackages/idr/<canonical_build_directory>/idr-gen-code.C` and `$DAKOTA/src/ProblemDescDB.C` which correspond to your modifications to the input specification. The `idr-gen-code.C` file is the result of a code generator and contains skeleton constructs for extracting data from IDR. You will be copying over parts of this skeleton to [ProblemDescDB.C](#) and then adding code to populate attributes within Data class container objects.

13.4.1 Replace keyword handler declarations and counter loop

Rather than trying to update these line by line, it is recommended to delete the entire block starting with the keyword declarations and ending at the bottom of the keyword counter loop. The declarations assign -1 to keywords and look like this:

```
Int cdv_descriptor = -1;
Int cdv_initial_point = -1;
```

They start after the line "Int cntr;". The keyword counter loop looks like this:

```

for ( cntr=data_len; cntr--; ) {
  if ( idr_find_id( &cdv_descriptor, cntr,
                  "cdv_descriptor", id_str, kw_str ) ) continue;
  ...
  if ( idr_find_id( &wuv_dist_upper_bounds, cntr,
                  "wuv_dist_upper_bounds", id_str, kw_str ) ) continue;
}

```

Once the old keyword declarations and keyword counter loop have been deleted, replace them with the corresponding blocks from `idr-gen-code.C` containing the updated keyword declarations and counter loop.

13.4.2 Update keyword handler logic blocks

For the newly added or modified input specifications, copy the appropriate skeleton constructs from `idr-gen-code.C` and paste them into the corresponding location in `ProblemDescDB.C`.

The next step is to add code to these skeletons to set data attributes within the `Data` class object used by the keyword handler. At the top of the method, interface, and responses keyword handlers, a `Data` class object is instantiated in order to store attributes, e.g.:

```
DataMethod data_method;
```

and within the strategy keyword handler, a reference to the `strategySpec` data class object is used to store attributes. Each of these data class objects is a simple container class which contains the data from a single keyword handler invocation. Within each skeleton construct, you will extract data from the IDR data structures and then use this data to set the corresponding attribute within the `Data` class.

Integer, real, and string data are extracted using the `idata`, `rdata`, and `cdata` arrays provided by IDR. These arrays are indexed using a bracket operator with the keyword as an index. Lists of integer, list of real, and list of string data are extracted using the `ProblemDescDB::idr_get_int_table()`, `ProblemDescDB::idr_get_real_table()`, and `ProblemDescDB::idr_get_string_table()` functions, respectively.

Example 1: if you added the specification:

```
[method_setting = <REAL>]
```

you would copy over

```

if ( method_setting >= 0 ) {
}

```

from `idr-gen-code.C` into `ProblemDescDB.C` and then populate the if block with a call to set the corresponding attribute within the `data_method` object using data extracted using the `rdata` array:

```

if ( method_setting >= 0 ) {
  data_method.methodSetting = rdata[method_setting];
}

```

Use of a set member function within `DataMethod` is not needed since the data is public. The data is public since `ProblemDescDB` already provides sufficient encapsulation (`ProblemDescDB::methodList`, `ProblemDescDB::variablesList`, `ProblemDescDB::interfaceList`, `ProblemDescDB::responsesList`, and

`ProblemDescDB::strategySpec` are private attributes), and public access reduces the amount of code to manage when performing input specification modifications by omitting the need to add/modify set/get functions.

Example 2: if you added the specification

```
[method_setting = <LISTof><REAL>]
```

you would copy over

```
if ( method_setting >= 0 ) {
  { Int idr_table_len;
    Real** idr_table = idr_get_real_table( parsed_data, method_setting,
                                          idr_table_len, 1, 1 );
  }
}
```

from `idr-gen-code.C` into `ProblemDescDB.C` and then populate it with a loop which extracts each entry of the table and populates the corresponding attribute within the `data_method` object. The `idr_table_len` attribute is used for the loop limit and to size the `data_method` object.

```
if ( method_setting >= 0 ) {
  { Int idr_table_len;
    Real** idr_table = idr_get_real_table( parsed_data, method_setting,
                                          idr_table_len, 1, 1 );

    data_method.methodSetting.reshape(idr_table_len);
    for (int i = 0; i<idr_table_len; i++)
      data_method.methodSetting[i] = idr_table[0][i];
  }
}
```

Attention:

If no new data attributes have been added, but instead there are only new settings for existing attributes, then you're done with the database augmentation at this point (you just need to add code to use these new settings in the places where the existing attributes are used).

13.4.3 Augment/update `get_<data_type>()` functions

The final update step for `ProblemDescDB.C` involves extending the database retrieval functions. These retrieval functions accept an identifier string and return a database attribute of a particular type, e.g. a `RealVector`:

```
const RealVector& get_drv(const DakotaString& entry_name);
```

The implementation of each of these functions has a simple series of if-else checks which return the appropriate attribute based on the identifier string. For example,

```
if (entry_name == "variables.continuous_design.initial_point")
  return (*variablesIter).continuousDesignVars;
```


appears at the top of `ProblemDescDB::get_drv()`. Based on the identifier string, it returns the `continuousDesignVars` attribute from a `DataVariables` object. Since there may be multiple variables specifications, the `variablesIter` list iterator identifies which node in the list of `DataVariables` objects is used. In particular, `variablesList` contains a list of all of the `data_variables` objects, one for each time `variables_kwhandler()` has been called by the parser. The particular variables object used for the data retrieval is managed by `variablesIter`, which is set in a `set_db_list_nodes()` operation that will not be described here.

There may be multiple `DataVariables`, `DataInterface`, `DataResponses`, and/or `DataMethod` objects. However, only one strategy specification is currently allowed so a list of `DataStrategy` objects is not needed. Rather, `ProblemDescDB::strategySpec` is the lone `DataStrategy` object.

To augment the `get_<data_type>()` functions, add `else` blocks with new identifier strings which retrieve the appropriate data attributes from the Data class object. The style for the identifier strings is a top-down hierarchical description, with specification levels separated by periods and words separated with underscores, e.g. `"keyword.group_specification.individual_specification"`. Use the `(*listIter).attribute` syntax for variables, interface, responses, and method specifications. For example, the `method_setting` example attribute would be added to `get_drv()` as:

```
else if (entry_name == "method.method_name.method_setting")
    return (*methodIter).methodSetting;
```

A strategy specification addition would not use a `(*listIter)` syntax, but would instead look like:

```
else if (entry_name == "strategy.strategy_name.strategy_setting")
    return strategySpec.strategySetting;
```

13.5 Update Corresponding Data Classes

In this step, we extend the Data class definitions (`DataStrategy`, `DataMethod`, `DataVariables`, `DataInterface`, and/or `DataResponses`) to include the new attributes referenced in [Update keyword handler logic blocks](#) and [Augment/update get_<data_type>\(\) functions](#).

13.5.1 Update the Data class header file

Add a new attribute to the private data for each of the new specifications. Follow the style guide for class attribute naming conventions (or mimic the existing code).

13.5.2 Update the .C file

Define defaults for the new attributes in the constructor initialization list (or in the case of `DataMethod`, in the body of the constructor for readability). Add the new attributes to the `assign()` function for use by the copy constructor and assignment operator. Add the new attributes to the `write(MPIPackBuffer&)`, `read(MPIUnpackBuffer&)`, and `write(ostream&)` functions, paying attention to using a consistent ordering.

13.6 Use get_<data_type>() Functions

At this point, the new specifications have been mapped through all of the database classes. The only remaining step is to retrieve the new data within the constructors of the classes that need it. This is done

by invoking the `get_<data_type>()` function on the `ProblemDescDB` object using the identifier string you selected in `Augment/update get_<data_type>()` functions. For example, from `DakotaModel.C`:

```
const String& interface_type = problem_db.get_string("interface.type");
```

passes the `"interface.type"` identifier string to the `ProblemDescDB::get_string()` retrieval function, which returns the desired attribute from the active `DataInterface` object.

Warning:

Use of the `get_<data_type>()` functions is restricted to class constructors, since only in class constructors are the data list iterators (i.e., `methodIter`, `interfaceIter`, `variablesIter`, and `responsesIter`) guaranteed to be set correctly. Outside of the constructors, the database list nodes will correspond to the last set operation, and may not return data from the desired list node.

13.7 Update the Documentation

Doxygen comments should be added to the Data class headers for the new attributes, and the reference manual sections describing the portions of `dakota.input.spec` that have been modified should be updated.

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