Mapping PM_{2.5} – Methods and Uncertainties

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Overview

- Mapping issues
- Uncertainty analysis of common mapping methods
- A method to improve PM_{2.5} mapping
- Understanding PM_{2.5} characteristics can improve mapping
- Alternative displays of PM_{2.5} data



Mapping Issues (1 of 2)

• Limited number of continuous PM_{2.5} monitors in the U.S.





Mapping Issues (2 of 2)

- PM_{2.5} is a regional and local pollutant
- PM_{2.5} characteristics vary from region to region (e.g. urban vs. rural)
- Varying terrain and seasonal characteristics also affect consistency of mapping





Summary of IDW results:

Parameter	RMSE*	Uncertainty (%)
Temp	2 - 3 °F	2 - 3
Ozone	6 - 10 ppb	8 - 10
PM _{2.5}	4 - 12 µg/m ³	10 - 20

Summary of kriging results:

Parameter	RMSE*	Uncertainty (%)
Ozone	5 - 10 ppb	8 - 10
PM _{2.5}	4 - 7.5 μg/m ³	10 - 15

*RMSE = Root Mean Square Error



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A Method to Improve PM_{2.5} Mapping

Cokriging: surrogate data used to augment spatial coverage of PM_{2.5} monitors:

- visibility data as a mapping surrogate
- population density or urban boundaries as surrogates
- topography to define regions of influence





Understanding the Characteristics of PM_{2.5}

- A better understanding of PM_{2.5} by region is needed to improve mapping results
- Explore relationships with possible surrogate data sets

 ASOS visibility data, satellite data, digital elevation data, etc.



