

# **Evaluation of the State-of-the- Art Contaminated Sediment Transport and Fate Modeling System**

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# **Evaluation of the State-of-the-Art Contaminated Sediment Transport and Fate Modeling System**

by

Earl J. Hayter  
Ecosystems Research Division  
National Exposure Research Laboratory  
U.S. Environmental Protection Agency  
Athens, GA 30605

Rooni Mathew, James Hallden, Edward Garland, and Heidi Salerno  
HydroQual, Inc.  
1200 MacArthur Blvd.  
Mahwah, NJ 07430

and

Susan C. Svirsky  
U.S. Environmental Protection Agency  
Region 1  
1 Congress Street  
Boston, MA 02114-2023

National Exposure Research Laboratory  
Office of Research and Development  
U.S. Environmental Protection Agency  
Research Triangle Park, NC 27711

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## ABSTRACT

Modeling approaches for evaluating the transport and fate of sediment and associated contaminants are briefly reviewed. The main emphasis is on: 1) the application of EFDC (Environmental Fluid Dynamics Code), a state-of-the-art contaminated sediment transport and fate public domain modeling system, to a 19-mile reach of the Housatonic River, MA; and 2) the evaluation of a 15-year simulation of sediment and PCB transport and fate in this 19-mile reach. The development of EFDC has been supported by Regions 1 and 4, the Office of Water, the Office of Superfund Remediation Technology Innovation (OSRTI), and the Office of Research and Development (ORD) - NERL/ERD. EFDC has been used at the following Superfund sites: Housatonic River, MA; Centredale Manor (Woonasquatucket River), RI; Saltville Waste Disposal Ponds (Holston River), VA/TN; Kalamazoo River, MI; Lower Duwamish Waterway, WA; and Portland Harbor, OR.

The evaluation of the modeling results showed that EFDC is capable of simulating the transport and resultant concentrations of TSS and PCBs in this reach of the Housatonic River within specified model performance measures for both relative bias and median relative error of  $\pm 10\%$  at the downstream boundary of the model domain (i.e., Rising Pond Dam) for discharge. The model performance is also within the specified performance measure of  $\pm 30\%$  for median relative error for both TSS (-28.3%) and PCB (-14.4%) concentrations. However, the EFDC model did not satisfy the model performance measure of  $\pm 30\%$  for relative bias for either TSS (-61.4%) or PCB concentrations (-71.1%). Factors that contributed to the failure to satisfy the performance measure for relative bias include a) phasing differences between the simulated results at Rising Pond Dam and the data collected one-mile downstream of the dam at the USGS Gaging Station at Great Barrington, MA; b) phasing and volumetric differences between the actual flows (from direct runoff and seven tributaries) and HSPF-simulated flows and loadings; and c) a higher detection limit for one group of PCB data than for the other data that caused the model-data comparison for PCBs to be extremely poor. Nevertheless, considering the fact that the model was not recalibrated for Reaches 7 & 8, and that the system modeled had widely varying hydraulic and morphologic regimes, the EFDC model's overall performance is considered satisfactory. This demonstrates that EFDC is a robust modeling system that can be successfully implemented at contaminated sediment sites.

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## ACRONYMS

CEAM	Center for Exposure Assessment Modeling
CEC	Cation Exchange Capacity
COC	Chemical of Concern
CSM	Conceptual Site Model
DOC	Dissolved Organic Carbon
EFDC	Environmental Fluid Dynamic Code
FCM	Foodchain Model
GE	General Electric Company
HSPF	Hydrologic Simulation Program FORTRAN
NERL	National Exposure Research Laboratory
PCB	Polychlorinated Biphenyls
POC	Particulate Organic Carbon
PRP	Principal Responsible Party
PSA	Primary Study Area (Reaches 5 and 6)
SAR	Sodium Adsorption Ratio
SSC	Suspended Sediment Concentration
TOC	Total Organic Carbon
tPCB	total PCBs
TSS	Total Suspended Solids
USCOE	U.S. Corps of Engineers
USEPA	U.S. Environmental Protection Agency
USGS	U.S. Geological Survey

# 1 INTRODUCTION

## 1.1 Background

Remediation of bodies of water such as rivers, reservoirs, lakes, harbors and estuaries contaminated with PCBs, metals, metalloids, and other toxic chemicals is usually extremely expensive. The assessment and prediction of the transport and fate of contaminated sediments and the associated chemical bioaccumulation are often key issues for both human and ecological risk assessments and remedial decision-making at Superfund sites, and the need for transparent and consistent approaches to this issue across sites and across Regions is self evident. Modeling the transport and fate of sediments and their adsorbed contaminants is often one of the tasks used to assess remediation alternatives. Advanced numerical models that simulate the transport and fate of contaminants in surface waters are important tasks with which one can understand the complex physical, chemical and biological processes that govern contaminant transport and fate. However, no single assessment approach is appropriate for all sites, so there must also be flexibility in the rigor and scope of assessments while maintaining the consistency of principles.

The National Exposure Research Laboratory's Ecosystem Research Division in Athens, GA has a research program entitled "Contaminated Sediment Transport and Fate Modeling", the goal of which is to develop a consensus framework for transport/fate/bioaccumulation modeling at Superfund sites. This framework is to include modeling protocols for applying the component contaminated sediment transport and bioaccumulation models to evaluate proposed remediation measures at contaminated sediment Superfund sites. To accomplish this task, the following five research objectives are being performed:

1. *Evaluation of existing contaminated sediment mass fate and transport models.* Existing, public-domain contaminated sediment transport models were evaluated in 2003 (see Imhoff *et al.* 2003). The highest ranked model at that time was EFDC (Environmental Fluid Dynamic Code). It ranked higher than ECOMSED (HydroQual, Inc. 2002) mainly because ECOMSED could not simulate wetting and drying or bedload transport of noncohesive sediment at the time of the evaluation. Since that time, both of these capabilities have been added to ECOMSED (HydroQual, Inc. 2007).
2. *Testing of highest ranked contaminated sediment transport model.* Next, EFDC was tested in the following types of surface water bodies: river (Housatonic River, MA; reservoir (Lake Hartwell, GA/SC); salt-wedge estuary (Lower Duwamish Waterway, WA); and partially stratified estuary (St John-Ortega-Cedar Rivers, FL). The purpose of this testing was to evaluate the ability of EFDC to simulate the hydrodynamics, sediment transport and contaminant transport and fate in these different types of surface waters. In the Lower Duwamish Waterway, only the ability of EFDC to simulate the barotropic and baroclinic circulation in a salt-wedge estuary was evaluated (Arega and Hayter, 2007). In the St John-Ortega-Cedar Rivers, the ability of EFDC to simulate the hydrodynamics and sediment transport in a micro-tidal, partially stratified estuary was evaluated (Hayter *et al.*,

2003). In both the Housatonic River and Lake Hartwell, the ability of EFDC to simulate the hydrodynamics, sediment and contaminant transport and fate were evaluated.

3. *Evaluation of EFDC by modeling the transport and fate of sediments and contaminants over a minimum of 10-years at a demonstration site.* This evaluation is presented in this report and is discussed in Section 1.3.
4. *Develop new modules for EFDC to address the identified sediment-related needs of OSRTI and the Regions.* In 2003, OSRTI identified contaminated sediment-related research priorities that included the development of models to simulate processes such as the vertical transport of contaminants dissolved in the pore water of sediment out of the sediment and up through an overlying sediment cap. In response to these identified needs, algorithms to simulate the following processes have been (or are currently being) developed and incorporated into EFDC:
  - a) Simulation of consolidation due to sediment self-weight and cap-induced overburden, and the resulting upward flux of freely dissolved contaminants. This module has been completed and tested and is described elsewhere (Arega and Hayter, 2007).
  - b) Simulation of wave-induced resuspension of highly organic sediments and the associated contaminants. This module is currently being developed under contract to the University of Florida.
  - c) Linking sediment transport, eutrophication and diagenesis modules in EFDC to account for resuspension and settling of inorganic sediment and organic matter. This work is currently being performed by Tetra Tech under a Work Assignment that started in FY2007.
5. *Develop a state-of-the-science transport and fate modeling system for modeling remedial alternatives in surface waters.* The upgraded version of EFDC that contains the new modules described in step 4 above will be placed on the EPA Center for Exposure Assessment Modeling's (CEAM) web site (<http://www.epa.gov/ceampubl/>). In addition the EFDC model, updated model user manuals/documents and example input data sets will also be placed on the CEAM web site.

## 1.2 Components of contaminated sediment transport modeling study

For the sake of completeness, the components of a complete and technically defensible contaminated sediment transport modeling study are briefly reviewed in this section. The reader should refer to EPA's *Contaminated Sediment Remediation Guidance for Hazardous Waste Sites* (USEPA, 2005) for a more in-depth discussion of this topic.

*Develop Conceptual Site Model:* A conceptual site model (CSM) of a contaminated sediment site is a representation of an environmental system (e.g., watershed) and the physical, chemical, and biological processes that govern the transport of sediments and the

transport, fate and transformation of contaminants from sources to receptors. Important elements of a CSM include information about both point and nonpoint sediment and contaminant sources, transport pathways (both over land and in the water body), and exposure pathways (USEPA, 2005). Summarizing this information in one place helps in identifying data gaps and areas of uncertainty that might impact the subsequent remedial investigation (RI) and feasibility study (FS). The initial version of a CSM is usually a set of hypotheses derived from existing site data and possibly knowledge gained from other sites. The subsequent site investigation is a collection of field and laboratory studies conducted to test these hypotheses and quantify the qualitative descriptions in the initial CSM. The initial CSM is modified as additional source, pathway, and contaminant information is collected and analyzed during the site investigation. A thorough CSM along with a site tour are invaluable in determining whether or not a modeling study needs to be performed, and if so, what level of analysis/model is required. Typical elements of a CSM for a contaminated sediment site are listed in Table 1.1. An example schematization of a contaminated sediment CSM that focuses on sediment and contaminant transport and fate processes is shown in Figure 1.1.

*Determine Whether a Modeling Study is Needed/Appropriate:* The following questions (modified from USEPA, 2005) are useful, but not inclusive, for determining the appropriate use (if at all) of site-specific mathematical models:

- Are historical data and/or simple quantitative techniques available to determine the validity of the hypotheses in the CSM with the desired accuracy?
- Have the spatial extent, degree of heterogeneity, and levels of contamination at the site been defined?
- Have all significant ongoing sources of contamination been defined and their fluxes measured?
- Do sufficient data exist to support the use of a mathematical model, and if not, are time and resources available to collect the required data to achieve the desired level of confidence in model results?
- Are time and resources available to perform the modeling study itself?

In theory, the answers to the first three bullets should be given in the CSM. They are included here since the answers to these questions should be considered in addressing this issue. If the decision is made that some type of modeling is needed, the following material should be useful in deciding what type of model (or level of analysis) should be used.

*Determine the Appropriate Level of Analysis:* As in the previous step, the CSM should be consulted during this step. This step concerns determining if the most significant (i.e., first-order) processes and interactions that control the transport and/or fate of sediment and contaminants, as identified in the CSM, can be simulated with one or more existing contaminated sediment transport and fate models. If it is determined that there are existing models capable of simulating these governing processes, then the types of models (e.g., analytical, empirical, numerical) that have this capability should be identified. The model types that do not have this capability should not be used. If it is determined that there are no existing models capable of simulating, at a minimum, the most significant processes and

interactions, then other tools or methods for evaluating proposed approaches should be identified and used. If it is determined that one or more models or types of mathematical models capable of simulating the controlling transport and fate processes and interactions exist, then the process described previously should be used to choose the appropriate type of model. As shown in Imhoff *et al.* (2003), there are existing public domain numerical models that can simulate most of the physical, chemical and biological processes and interactions (e.g., those shown in Figure 1.1) that control the transport and fate of sediment and contaminants in water bodies, e.g., EFDC.

*Choose the most appropriate model and model framework:* If the decision is made to apply a numerical model at a contaminated sediment site, selection of the most appropriate contaminated sediment transport and fate model(s) to use at a specific site is one of the critical steps in the modeling program. It is extremely important that the information contained in the CSM as well as that from the preceding two steps be used in making these choices and in designing the overall model framework. The latter is a network that details how the models chosen to perform different components of the modeling study (e.g., watershed loadings, hydrodynamics, sediment transport, contaminant transport and fate) are linked together. For example, a watershed loading model is usually statically linked to the hydrodynamic model, whereas the latter is often dynamically linked to a sediment transport model such that simulated changes in bathymetry due to erosion and/or deposition are used in subsequent time steps to calculate the flow field. Familiarity with existing sediment and contaminant transport models is essential to perform this step. Comprehensive technical reviews of available sediment and contaminant transport and fate models and chemical bioaccumulation models have been conducted by Imhoff *et al.* (2003) and Imhoff *et al.* (2004).

*Conduct a complete modeling study:* Whenever numerical models are used, the following steps should be performed to yield a scientifically defensible modeling study: verification, calibration, validation, sensitivity analysis, and uncertainty analysis (the latter is not practical to perform with transport and fate models). These steps are discussed in the following:

Model verification: This step involves evaluation of 1) model theory, 2) consistency of the computer code with model theory, and 3) the computer code for integrity in the calculations. Model verification should be documented, or if the model is new, it should be peer-reviewed by an independent party. Whenever possible, public domain verified models, calibrated and validated to site-specific conditions should be used.

Model calibration: Uses site-specific information from a time period of record to adjust model parameters in the governing equations (e.g., bottom friction coefficient in hydrodynamic models) to obtain an optimal agreement between a measured data set and model calculations for the simulated state variables.

Model validation: Also referred to as model confirmation. This step consists of a demonstration that the calibrated model accurately reproduces known conditions over a different time period with the physical parameters and forcing functions changed to reflect the conditions during the new simulation period. The parameters adjusted during

calibration should not be adjusted during validation. Model results from the validation simulation should be compared to the data set. If an acceptable level of agreement is achieved between the data and model simulations, then the model can be considered validated, at least for the range of conditions defined by the calibration and validation data sets. If an acceptable level of agreement is not achieved, then analysis should be performed to determine possible reasons for the differences between the model simulations and data. The latter sometimes leads to refinement of the model (e.g., using a finer model grid) or to the addition of one or more physical/chemical processes represented in the model.

Sensitivity analysis: This process consists of varying each of the input parameters by a fixed percent (while holding the other parameters constant) to determine how the model predictions vary. The resulting variations in simulated state variables are a measure of the sensitivity of model predictions to the parameter whose value was varied.

Uncertainty analysis: This process consists of propagating the relative error in each parameter (that was varied during the sensitivity analysis) to determine the resulting error in the model predictions. A probabilistic model, e.g., Monte Carlo Analysis, is one method of performing an uncertainty analysis. While quantitative uncertainty analyses are possible and practical to perform on watershed loading and food chain models, they are not so at present on transport and fate models. As a result, a thorough sensitivity analysis should be performed for the transport and fate models.

### 1.3 Purpose of model evaluation

The purpose of this research is to evaluate the ability of EFDC, the state-of-the-art contaminated sediment modeling system, to simulate the transport and fate of a contaminant over a time period of at least 10 years. This time period was chosen since models would normally have to be run over a multi-decadal time-scale to evaluate the effectiveness of various remedial measures, e.g., dredging, capping, dredging and capping, monitored natural recovery (MNR), etc., in reducing the contaminant concentrations in both the sediment and water column. The demonstration site chosen was the Housatonic River in western Massachusetts. Specifically, a 30.9 km (19.2 mile) reach of the Housatonic River immediately downstream of Woods Pond (see Figures 1.2 and 1.3) was chosen as the modeling domain. Background information on the Housatonic River relevant to the model evaluation is provided below.

### 1.4 Background information

The Housatonic River flows a distance of approximately 241 km (250 miles) from its headwaters in western Massachusetts to Long Island Sound (see Figure 1.2). It drains an area of approximately 5,050 km<sup>2</sup>. The Housatonic River, its sediment, and floodplains have been contaminated with polychlorinated biphenyls (PCBs) and other hazardous substances released from the General Electric Company (GE) facility in Pittsfield, MA. As seen in Figure 1.3, this facility is located along the Housatonic River in Reach 4. This facility was a major handler of PCBs in western Massachusetts, and is the only known source of PCBs found in the Housatonic River. In 1977, the State of Connecticut posted a fish consumption advisory for most of the Housatonic River that flows through western Connecticut due to the PCB contamination in the



sediment and fish tissue. In 1982, the Massachusetts Department of Public Health (MDPH) issued a consumption advisory for the fish, frogs, and turtles in the Housatonic River. Then in 1999, MDPH issued a waterfowl consumption advisory from Pittsfield to Great Barrington due to PCB concentrations in wood ducks and mallards collected from the river. Numerous studies conducted since 1988 have documented PCB contamination in the floodplain soil downstream of the GE facility. PCBs have been detected in Housatonic River sediment as far downstream as the Derby Dam in Connecticut (see Figure 1.2) and even into Long Island Sound, though other sources of PCBs have been identified downstream of the Derby Dam (WESTON, 2006b).

Under the terms of the Consent Decree established between the U.S. Environmental Protection Agency (EPA) and GE and other parties, EPA was responsible for developing a quantitative model of the fate, transport, and bioaccumulation of PCBs in the Housatonic River system. The goals of the modeling study were to develop a modeling framework that could be used to: a) predict future average PCB concentrations in sediment, water, floodplain soil and aquatic biota in the PSA; b) assess relative performance amongst proposed remedial measures against baseline (i.e., no action) conditions; and c) estimate the magnitude of expected reductions in PCB exposure for the different remedial measures (WESTON, 2006b).

The modeling study was performed by EPA Region 1 that focused on the portion of the Housatonic River from the confluence of the East and West Branches, located 3.2 km (2 miles) downstream of the GE facility, to Woods Pond Dam, and downstream between Woods Pond Dam and Rising Pond Dam (see Figure 1.3). Figure 1.3 also shows reach designations that are relevant for this study, i.e., Reaches 7 and 8. Reaches 5 and 6, the 17.2 km (10.7 mile) reach of the river between the confluence and Woods Pond Dam, constitute the Primary Study Area (PSA). EPA estimated that approximately 90% of the mass of PCBs in the Housatonic River drainage basin is located in the PSA, and the most significant ecological and human health risks are associated with this portion of the river (WESTON, 2006b). In the PSA the river ranges in width from 12 m (40 ft) to 38 m (125 ft), and has an extensive floodplain up to 1.1 km (3,600 ft) in width. The river meanders in many sections of the PSA, and numerous oxbows and backwaters are present. Woods Pond is a shallow 54-acre impoundment that was formed by the construction of a dam in 1864. Downstream of Woods Pond Dam, the river runs 30.9 km (19.2 miles) to Rising Pond Dam in Great Barrington. The downstream boundary for the watershed loading model used by EPA was the USGS gaging station at Great Barrington (see Figure 1.3) was chosen because PCB concentrations show a major decline after Rising Pond. This modeling study is described in the Modeling Framework Document (WESTON, 2004a), the Model Calibration Report (WESTON, 2004b), the Model Validation Report (WESTON, 2006a), and the Final Model Documentation (WESTON, 2006b). The latter is the single most comprehensive source for detailed information on the modeling study of Reaches 5 and 6.

The modeling framework used for the PSA consisted of the following: a) HSPF, a watershed loading model, was used to simulate the point and nonpoint loading of water, sediment and PCBs to the Housatonic River within the PSA; b) EFDC was used to simulate the hydrodynamics, sediment transport and PCB transport in the specified modeling domain, i.e., the 10-year floodplain; and c) EPA's FCM (Foodchain Model) was used to simulate the time variable bioaccumulation of PCBs in aquatic biota within the PSA. This modeling framework and its application to the PSA was peer reviewed at three stages by an external peer review panel. The

three stages consisted of the model framework itself (WESTON, 2004a), the modeling framework after it had been calibrated (WESTON, 2004b), and the modeling framework after it had been validated (WESTON, 2006a). The three validated models, input data files and supporting documentation were delivered to the modeling contractor of the General Electric Company (GE) who is the Principal Responsible Party (PRP) at the Housatonic River Superfund Site. Per the Consent Decree, GE's modeling contractor is using the modeling framework to perform the corrective measures study to determine the optimum remedial measures for the contaminated sediments and floodplains in the PSA.

### 1.5 Scope of model evaluation

For the purposes of this model evaluation, the same version of EFDC used by EPA in modeling Reaches 5 and 6 was applied to Reaches 7 and 8. The application of EFDC to Reaches 7 and 8 is described in detail in Section 3.2. The strategy in applying EFDC to Reaches 7 and 8 was to test its performance in simulating the transport of sediment and PCBs over a multi-year period without the benefit of calibration or validation, thereby testing its robustness to yield satisfactory comparisons with data collected at a sampling station a short distance downstream of Reach 8, i.e., downstream of the downstream boundary of the modeling domain.

While the EFDC model was not re-calibrated, hydrodynamic, sediment and PCB related parameterizations were changed in order to represent the vastly different hydraulic and morphologic regimes in Reaches 7 and 8 compared to those in the PSA. Especially considering the material presented in the previously, it is important for the reader to understand that the EFDC model of Reaches 7 and 8 is in the traditional sense uncalibrated and unvalidated, and thus model results will naturally have a higher level of uncertainty associated with them than results obtained by a calibrated and validated model such as the EFDC model used by EPA to model Reaches 5 and 6. It is noted here and referred to later in this report that EPA Region 1 also modeled the bioaccumulation of PCBs in aquatic biota in Reaches 7 and 8 using the results from the herein described application of EFDC to these two reaches.

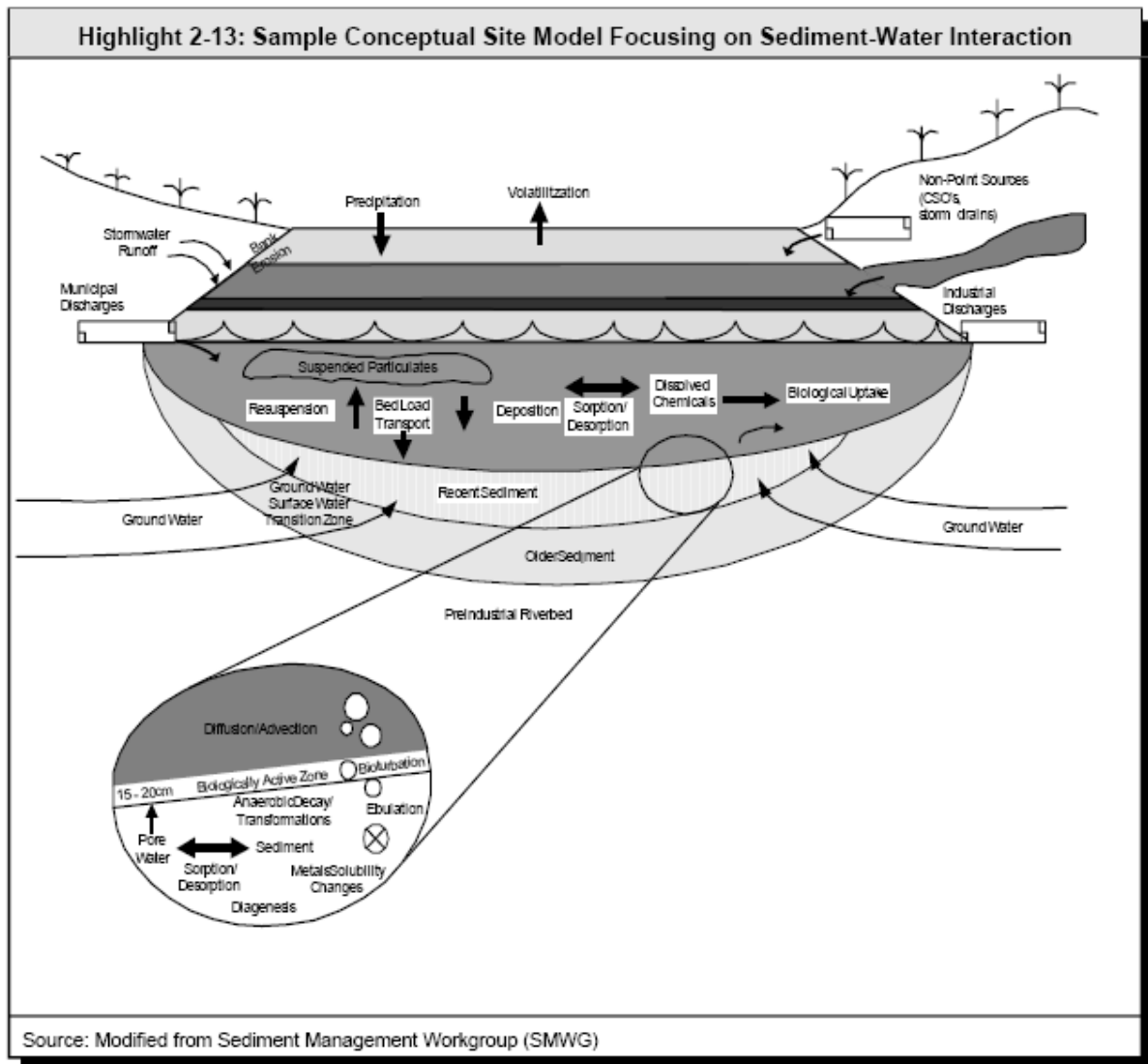
### 1.6 Organization of report

A description of EFDC is presented in Section 2, while a description of the application of EFDC to Reaches 7 and 8 is presented in Section 3. The evaluation of EFDC's ability to simulate the transport of sediment and PCBs in these reaches is discussed in Section 4, and conclusions from this model evaluation study are presented in Section 5. In Appendix A, properties and transport processes of both cohesive and noncohesive sediments are described, while Appendix B contains a sediment gradation scale. Appendix C contains a detailed view of the computation grid for the EFDC model.

Table 1.1 Typical Elements of a CSM for a Contaminated Sediment Site (after USEPA, 2005)

<p><b>Sources of contaminants of concern</b></p> <ul style="list-style-type: none"> <li>• Upland soils</li> <li>• Floodplain soils</li> <li>• Surface water</li> <li>• Groundwater</li> <li>• Non-aqueous phase liquids (NAPL) and other source materials</li> <li>• Sediment “hot spots”</li> <li>• Outfalls, including combined sewer outfalls and storm water runoff outfalls</li> <li>• Atmospheric contaminants</li> </ul>	<p><b>Exposure pathways for humans</b></p> <ul style="list-style-type: none"> <li>• Fish/shellfish ingestion</li> <li>• Dermal uptake from wading, swimming</li> <li>• Water ingestion</li> <li>• Inhalation of volatiles</li> </ul> <p><b>Exposure pathways for biota</b></p> <ul style="list-style-type: none"> <li>• Fish/shellfish/benthic invertebrate ingestion</li> <li>• Incidental ingestion of sediment</li> <li>• Direct uptake from water</li> </ul>
<p><b>Contaminant transport pathways</b></p> <ul style="list-style-type: none"> <li>• Sediment resuspension and deposition</li> <li>• Surface water transport</li> <li>• Runoff</li> <li>• Bank erosion</li> <li>• Groundwater advection</li> <li>• Bioturbation</li> <li>• Molecular diffusion</li> <li>• Food chain</li> </ul>	<p><b>Human receptors</b></p> <ul style="list-style-type: none"> <li>• Recreational fishers</li> <li>• Subsistence fishers</li> <li>• Waders/swimmers/birdwatchers</li> <li>• Workers and transients</li> </ul> <p><b>Ecological receptors</b></p> <ul style="list-style-type: none"> <li>• Benthic/epibenthic invertebrates</li> <li>• Bottom-dwelling/pelagic fish</li> <li>• Mammals and birds (e.g., mink, otter, heron, bald eagle)</li> </ul>

Figure 1.1 Sample CSM for Sediment Site (after USEPA, 2005)



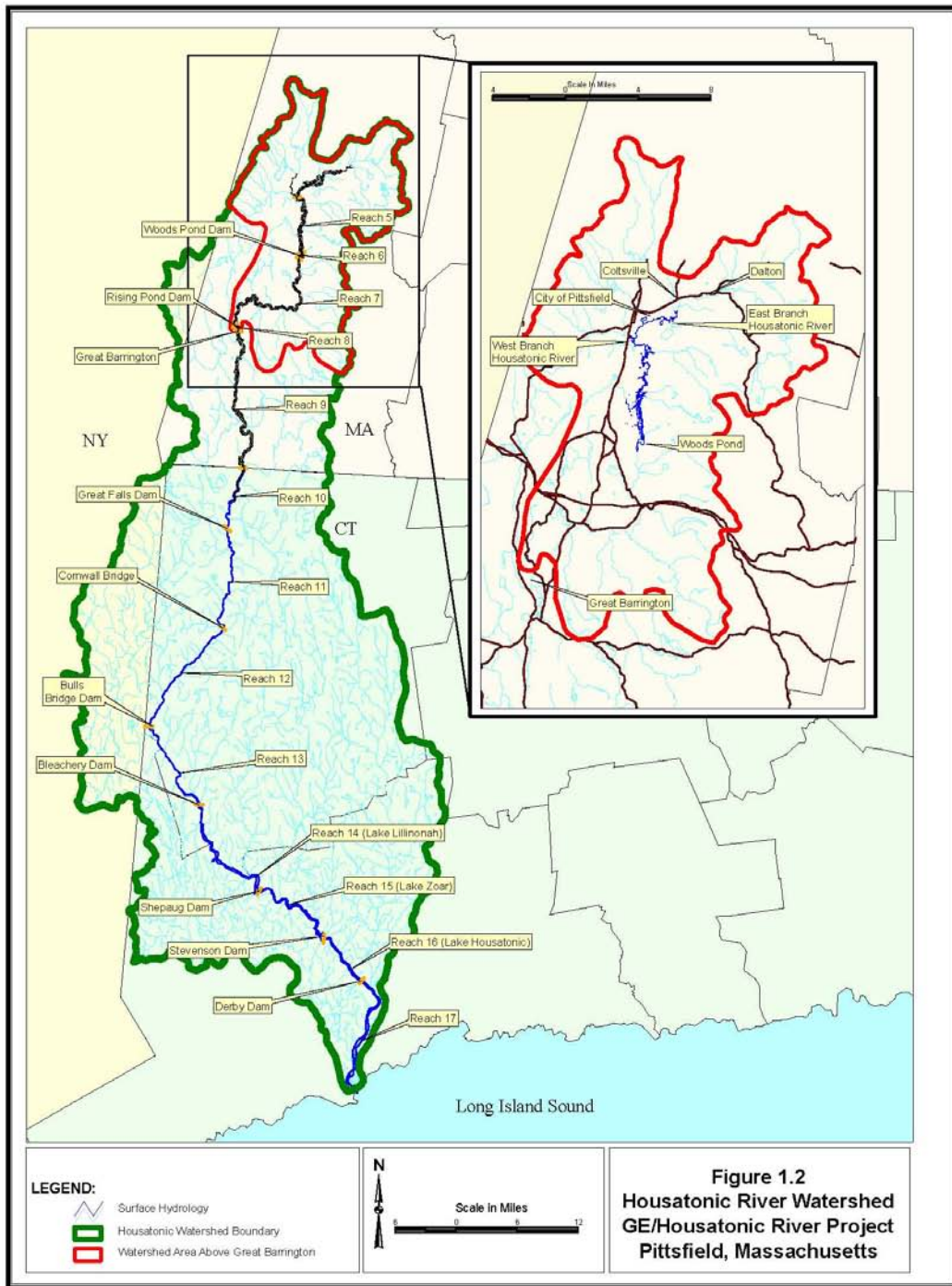


Figure 1.2 Housatonic River Watershed (after WESTON, 2006)

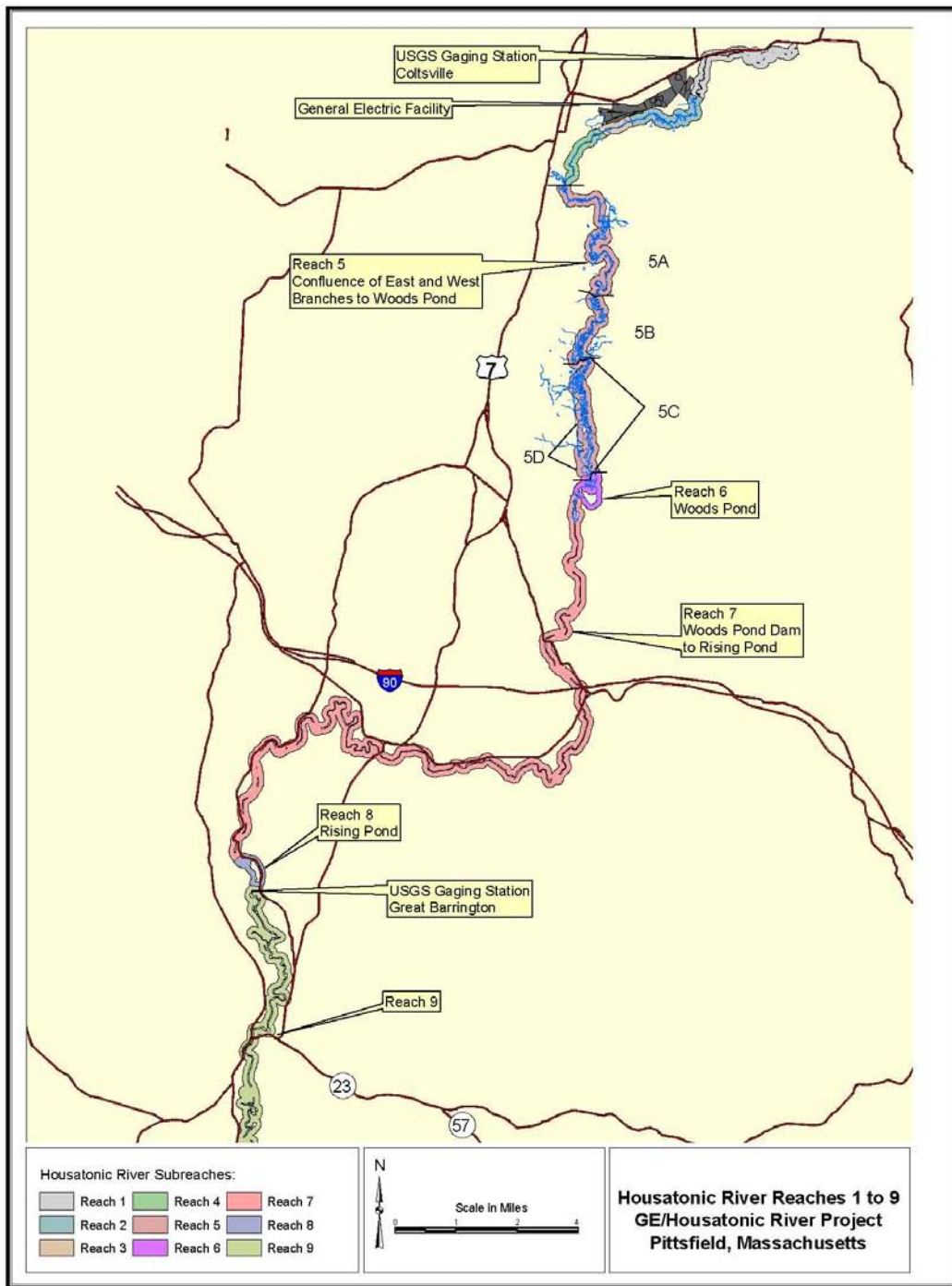


Figure 1.3 Housatonic River Reaches 5 through 8 (after WESTON, 2006)

## 2 DESCRIPTION of EFDC

### 2.1 Description of Model

As discussed in the previous section, the numerical model evaluated in this study was the Environmental Fluid Dynamics Code (EFDC) (Hamrick, 1992). EFDC is currently maintained by Tetra Tech, Inc. and supported by the U.S. EPA. EFDC is a three-dimensional (3D) public domain modeling system that has been widely used in water quality and contaminant transport studies. The application history of EFDC includes: simulating wetting and drying processes of the hydrodynamics and sediment transport in Morro Bay (Ji *et al.*, 2000); thermal discharge study in Conowingo Pond (Hamrick and Mills, 2000); simulating Lake Okeechobee hydrodynamics, thermal, and sediment transport processes (Jin *et al.*, 2002); studying tidal intrusion and its impact on larval dispersion in the James River estuary (Shen *et al.*, 1999); modeling hydrodynamics and sediment transport in the middle Atlantic Bight (Kim *et al.*, 1997); and modeling the hydrodynamics and water quality in Peconic Bay (Tetra Tech, 1999). EFDC has also been used to develop TMDLs in the following water bodies: Charles River, MA; Mashapaug Pond RI; Christiana River, DE and PA; Wissahickon Creek, PA; Cape Fear River, NC; Neuse River, NC; Jordon Lake, NC; Boone Reservoir, NC; Charleston Harbor, SC; Savannah River, GA; Brunswick Harbor, GA; Lake Allatoona, GA; Southern Four Basins, GA; St. Johns River, FL; Fenholloway River, FL; Myakka River Estuary, FL; Mobile Bay, AL; Ward Cover, AL; Alabama River, AL; Flint Creek, AL; Lake Jordon, AL; Lake Mitchell, AL; Logan Martin Lake, AL; Lay Lake, AL; Lake Neeley Henry, AL; Yazoo River, MS; Escatawpa River, MS; St. Louis Bay, MS; East Fork Little Miami River, OH; Ten Killer Ferry Lake, OK; Lake Wister, OK; Armanda Bayou, TX; Arroyo Colorado, TX; San Diego Bay, CA; Los Angeles River, CA; Los Angeles Harbor, CA; Big Bear Lake, CA; Canyon Creek, CA; Clear Lake, CA; a section of the Sacramento River, CA; and South Puget Sound, WA. As stated previously, EFDC has also been used at the following Superfund sites: Housatonic River, MA; the Woonasquatucket River, RI; Kalamazoo River, MI; Lower Duwamish Waterway, WA; and Portland Harbor - Lower Willamette River, OR.

The EFDC model is a public domain, surface water modeling system incorporating fully integrated hydrodynamics. It solves the 3D, vertically hydrostatic, free surface, turbulence averaged equations of motion. EFDC is extremely versatile, and can be used for 1D, 2D-laterally averaged (2DV), 2D-vertically averaged (2DH), or 3D simulations of rivers, lakes, reservoirs, estuaries, coastal seas, and wetlands.

For realistic representation of horizontal boundaries, the governing equations are formulated such that the horizontal coordinates,  $x$  and  $y$ , are curvilinear. To provide uniform resolution in the vertical direction, the sigma (stretching) transformation is used. The equations of motion and transport solved in EFDC are turbulence-averaged, because prior to averaging, although they represent a closed set of instantaneous velocities and concentrations, they cannot be solved for turbulent flows. A statistical approach is applied, where the instantaneous values are decomposed into mean and fluctuating values to enable the solution. Additional terms that represent the turbulence terms are introduced to the equations for the mean flow. Turbulent equations of motion are formulated to utilize the Boussinesq approximation for variable density. The Boussinesq approximation accounts for variations in density only in the gravity term. This

assumption simplifies the governing equations significantly, but may introduce large errors when density gradients are large. The resulting governing equations, presented in the next section, include parameterized, Reynolds-averaged stress and flux terms that account for the turbulent diffusion of momentum, heat and salt. The turbulence parameterization in EFDC is based on the Mellor and Yamada (1982) level 2.5 turbulence closure scheme, as modified by Galerpin *et al.* (1988), that relates turbulent correlation terms to the mean state variables. The EFDC model also solves several transport and transformation equations for different dissolved and suspended constituents, including suspended sediments, toxic contaminants, and water quality state variables. An overview of the governing equations is given in the following; detailed descriptions of the model formulation and numerical solution technique used in EFDC are provided by Hamrick (1992). Additional capabilities of EFDC include: 1) simulation of wetting and drying of flood plains, mud flats, and tidal marshes; 2) integrated, near-field mixing zone model; 3) simulation of hydraulic control structures such as dams and culverts; and 4) simulation of wave boundary layers and wave-induced mean currents.

## 2.2 Hydrodynamics and Transport Model

The 3D, Reynolds-averaged equations of continuity (Eq. 2.1), linear momentum (Eqs. 2.2 and 2.3), hydrostatic pressure (Eq. 2.4), equation of state (Eq. 2.5) and transport equations for salinity and temperature (Eqs. 2.6 and 2.7) written for curvilinear-orthogonal horizontal coordinates and a sigma vertical coordinate are given by Hamrick (1992) and repeated below:

$$\frac{\partial(m\varepsilon)}{\partial t} + \frac{\partial(m_y Hu)}{\partial x} + \frac{\partial(m_x Hv)}{\partial y} + \frac{\partial(mw)}{\partial z} = 0 \quad (2.1)$$

$$\begin{aligned} \frac{\partial(mHu)}{\partial t} + \frac{\partial(m_y Huu)}{\partial x} + \frac{\partial(m_x Hvu)}{\partial y} + \frac{\partial(mwu)}{\partial z} - (mf + v \frac{\partial(m_y)}{\partial x} - u \frac{\partial(m_x)}{\partial y})Hv = \\ m_y H \frac{\partial(g\varepsilon + p)}{\partial x} - m_y \left( \frac{\partial H}{\partial x} - z \frac{\partial H}{\partial x} \right) \frac{\partial p}{\partial z} + \frac{\partial(mH^{-1} A_v \frac{\partial u}{\partial z})}{\partial z} + Q_u \end{aligned} \quad (2.2)$$

$$\begin{aligned} \frac{\partial(mHv)}{\partial t} + \frac{\partial(m_y Huv)}{\partial x} + \frac{\partial(m_x Hvv)}{\partial y} + \frac{\partial(mwv)}{\partial z} + (mf + v \frac{\partial(m_y)}{\partial x} + u \frac{\partial(m_x)}{\partial y})Hu = \\ m_x H \frac{\partial(g\varepsilon + p)}{\partial y} - m_x \left( \frac{\partial H}{\partial y} - z \frac{\partial H}{\partial y} \right) \frac{\partial p}{\partial z} + \frac{\partial(mH^{-1} A_v \frac{\partial v}{\partial z})}{\partial z} + Q_v \end{aligned} \quad (2.3)$$

$$\frac{\partial p}{\partial z} = \frac{gH(\rho - \rho_o)}{\rho_o} = gHb \quad (2.4)$$



$$\rho = \rho(p, S, T) \quad (2.5)$$

$$\frac{\partial(mHS)}{\partial t} + \frac{\partial(m_y HuS)}{\partial x} + \frac{\partial(m_x HvS)}{\partial y} + \frac{\partial(mwS)}{\partial z} = \frac{\partial(\frac{mA_b}{H} \frac{\partial S}{\partial z})}{\partial z} + Q_s \quad (2.6)$$

$$\frac{\partial(mHT)}{\partial t} + \frac{\partial(m_y HuT)}{\partial x} + \frac{\partial(m_x HvT)}{\partial y} + \frac{\partial(mwT)}{\partial z} = \frac{\partial(\frac{mA_b}{H} \frac{\partial T}{\partial z})}{\partial z} + Q_T \quad (2.7)$$

where  $u$  and  $v$  are the mean horizontal velocity components in (x,y) coordinates;  $m_x$  and  $m_y$  are the square roots of the diagonal components of the metric tensor, and  $m = m_x m_y$  is the Jacobian or square root of the metric tensor determinant;  $p$  is the pressure in excess of the reference pressure,  $\frac{\rho_o g H (1-z)}{\rho_o}$ , where  $\rho_o$  is the reference density;  $f$  is the Coriolis parameter for latitudinal variation;  $A_v$  is the vertical turbulent viscosity; and  $A_b$  is the vertical turbulent diffusivity. The buoyancy  $b$  in Equation 2.4 is the normalized deviation of density from the reference value. Equation 2.5 is the equation of state that calculates water density ( $\rho$ ) as functions of  $p$ , salinity ( $S$ ) and temperature ( $T$ ).

The sigma (stretching) transformation and mapping of the vertical coordinate is given as

$$z = \frac{(z^* + h)}{(\xi + h)} \quad (2.8)$$

where  $z^*$  is the physical vertical coordinate, and  $h$  and  $\xi$  are the depth below and the displacement about the undisturbed physical vertical coordinate origin,  $z^* = 0$ , respectively, and  $H = h + \xi$  is the total depth. The vertical velocity in  $z$  coordinates,  $w$ , is related to the physical vertical velocity  $w^*$  by

$$w = w^* - z \left( \frac{\partial \xi}{\partial t} + \frac{u}{m_x} \frac{\partial \xi}{\partial x} + \frac{v}{m_y} \frac{\partial \xi}{\partial y} \right) + (1-z) \left( \frac{u}{m_x} \frac{\partial h}{\partial x} + \frac{v}{m_y} \frac{\partial h}{\partial y} \right) \quad (2.9)$$

The solutions of Eqs. 2.2, 2.3, 2.6 and 2.7 require the values for the vertical turbulent viscosity and diffusivity and the source and sink terms. The vertical eddy viscosity and diffusivity,  $A_v$  and  $A_b$ , are parameterized according to the level 2.5 (second-order) turbulence closure model of Mellor and Yamada (1982), as modified by Galperin *et al.* (1988), in which the vertical eddy viscosities are calculated based on the turbulent kinetic energy and the turbulent macroscale

equations. The Mellor and Yamada level 2.5 (MY2.5) turbulence closure model is derived by starting from the Reynolds stress and turbulent heat flux equations under the assumption of a nearly isotropic environment, where the Reynolds stress is generated due to the exchange of momentum in the turbulent mixing process. To make the turbulence equations closed, all empirical constants are obtained by assuming that turbulent heat production is primarily balanced by turbulent dissipation.

The vertical turbulent viscosity and diffusivity are related to the turbulent intensity,  $q^2$ , turbulent length scale,  $l$  and a Richardson number  $R_q$  as follows:

$$A_v = \Phi_v q l = 0.4(1 + 36R_q)^{-1}(1 + 6R_q)^{-1}(1 + 8R_q) q l \quad (2.10)$$

$$A_b = \Phi_b q l = 0.5(1 + 36R_q)^{-1} q l \quad (2.11)$$

where  $A_v$  and  $A_b$  are stability functions that account for reduced and enhanced vertical mixing or transport in stable and unstable vertical, density-stratified environments, respectively, and the local Richardson number is given as

$$R_q = \frac{gH \frac{\partial b}{\partial z} l^2}{q^2 H^2} \quad (2.12)$$

A critical Richardson number,  $R_q = 0.20$ , was found at which turbulence and mixing cease to exist (Mellor and Yamada, 1982). Galperin *et al.* (1988) introduced a length scale limitation in the MY scheme by imposing an upper limit for the mixing length to account for the limitation of the vertical turbulent excursions in stably stratified flows. They also modified and introduced stability functions that account for reduced or enhanced vertical mixing for different stratification regimes.

The turbulence intensity ( $q^2$ ) and the turbulence length scale ( $l$ ) are computed using the following two transport equations:

$$\begin{aligned} \frac{\partial(mHq^2)}{\partial t} + \frac{\partial(m_y H u q^2)}{\partial x} + \frac{\partial(m_x H v q^2)}{\partial y} + \frac{\partial(mwq^2)}{\partial z} &= \frac{\partial\left(\frac{mA_q}{H} \frac{\partial q^2}{\partial z}\right)}{\partial z} + Q_q \\ + 2\frac{mA_v}{H} \left(\frac{\partial^2 u}{\partial z^2} + \frac{\partial^2 v}{\partial z^2}\right) + 2mgA_b \frac{\partial b}{\partial z} - 2mH \left(\frac{q^3}{B_1 l}\right) \end{aligned} \quad (2.13)$$

$$\begin{aligned} \frac{\partial(mHq^2l)}{\partial t} + \frac{\partial(m_yHuq^2l)}{\partial x} + \frac{\partial(m_xHvq^2l)}{\partial y} + \frac{\partial(mwq^2l)}{\partial z} &= \frac{\partial\left(\frac{mA_q}{H}\frac{\partial q^2l}{\partial z}\right)}{\partial z} + Q_l \\ + 2\frac{mE_1lA_v}{H}\left(\frac{\partial^2u}{\partial z^2}\right) + \left(\frac{\partial^2v}{\partial z^2}\right) + mgE_1E_3lA_b\frac{\partial b}{\partial z} - H\left(\frac{q^3}{(B_1)}\right)(1 + E_2(\kappa L)^{-2}l^2) \end{aligned} \quad (2.14)$$

The above two equations include a wall proximity function,  $W = 1 + E_2l(\kappa L)^{-2}$ , that assures a positive value of diffusion coefficient  $L^{-1} = (H)^{-1}(z^{-1} + (1-z)^{-1})$ .  $B_1$ ,  $E_1$ ,  $E_2$ , and  $E_3$  are empirical constants with values 0.4, 16.6, 1.8, 1.33, and 0.25, respectively. All terms with  $Q$ 's ( $Q_u$ ,  $Q_v$ ,  $Q_q$ ,  $Q_b$ ,  $Q_s$ ,  $Q_T$ ) are sub-grid scale sink-source terms that are modeled as sub-grid scale horizontal diffusion. The vertical diffusivity,  $A_q$ , is in general taken to be equal to the vertical turbulent viscosity,  $A_v$  (Hamrick, 1992).

The vertical boundary conditions for the solutions of the momentum equations are based on the specification of the kinematic shear stresses. At the bottom, the bed shear stresses are computed using the near bed velocity components  $(u_1, v_1)$  as:

$$(\tau_{bx}, \tau_{by}) = c_b \sqrt{u_1^2 + v_1^2} (u_1, v_1) \quad (2.15)$$

where the bottom drag coefficient  $c_b = \left(\frac{\kappa}{\ln(\Delta_1/2z_o)}\right)^2$ , where  $\kappa$  is the von Karman constant,  $\Delta_1$  is the dimensionless thickness of the bottom layer,  $z_o = z_o^*/H$  is the dimensionless roughness height, and  $z_o^*$  is roughness height in m. At the surface layer, the shear stresses are computed using the  $u$ ,  $v$  components of the wind velocity  $(u_w, v_w)$  above the water surface (usually measured at 10 m above the surface) and are given as:

$$(\tau_{sx}, \tau_{sy}) = c_s \sqrt{u_w^2 + v_w^2} (u_w, v_w) \quad (2.16)$$

where  $c_s = 0.001 \frac{\rho_a}{\rho_w} (0.8 + 0.065 \sqrt{u_w^2 + v_w^2})$  and  $\rho_a$  and  $\rho_w$  are the air and water densities, respectively. No flux vertical boundary conditions are used for the transport equations.

Numerically, EFDC is second-order accurate both in space and time. A staggered grid or C grid provides the framework for the second-order accurate spatial finite differencing used to solve the equations of motion. Integration over time involves an internal-external mode splitting procedure separating the internal shear, or baroclinic mode, from the external free surface gravity wave, or barotropic mode. In the external mode, the model uses a semi-implicit scheme that allows the use of relatively large time steps. The internal equations are solved at the same time step as the external equations, and are implicit with respect to vertical diffusion. Details of the finite difference numerical schemes used in the EFDC model are given in Hamrick (1992), and will not be presented in this report.

### 2.3 Sediment Transport Model

This section briefly describes the sediment transport module in EFDC. Hamrick (2002) contains a more detailed description of both the sediment and contaminant transport modules in EFDC. To provide the requisite background for the discussion of sediment transport in this report, a brief overview of sediment properties, with an emphasis on the properties of cohesive sediment, is given in Appendix A.

The sediment transport module in EFDC solves the transport equation for suspended cohesive and noncohesive sediment for multiple size classes. Its capabilities include the following:

- Simulates bedload transport of multiple size classes of noncohesive sediment
- Simulates noncohesive and cohesive sediment settling, deposition and resuspension/entrainment
- Uses a bed model that divides the bed into layers of varying thickness in order to represent vertical profiles in grain size distribution, porosity, bulk density, and fraction of sediment in each layer that is composed of specified size classes of cohesive and noncohesive sediment
- Simulates formation of an armored surficial layer
- Simulates finite-strain consolidation of a bed composed of fine-grained sediment
- Simulates bank erosion and mass failure using a first-order empirical approach.

The generic transport equation solved in EFDC for a dissolved (e.g., chemical contaminant) or suspended (e.g., sediment) constituent having a mass per unit volume concentration  $C$ , is

$$\begin{aligned} \frac{\partial m_x m_y H C}{\partial t} + \frac{\partial m_y H u C}{\partial x} + \frac{\partial m_x H v C}{\partial y} + \frac{\partial m_x m_y w C}{\partial z} - \frac{\partial m_x m_y w_{sc} C}{\partial z} = \\ \frac{\partial}{\partial x} \left( \frac{m_y}{m_x} H K_H \frac{\partial C}{\partial x} \right) + \frac{\partial}{\partial y} \left( \frac{m_x}{m_y} H K_H \frac{\partial C}{\partial y} \right) + \frac{\partial}{\partial z} \left( m_x m_y \frac{K_v}{H} \frac{\partial C}{\partial z} \right) + Q_c \end{aligned} \quad (2.17)$$

where  $K_V$  and  $K_H$  are the vertical and horizontal turbulent diffusion coefficients, respectively;  $w_{sc}$  is a positive settling velocity when  $C$  represents the mass concentration of suspended sediment; and  $Q_c$  represents external sources or sinks and reactive internal sources or sinks. For sediment,  $C = S_j$ , where  $S_j$  represents the concentration of the  $j$ th sediment class. The solution procedure is the same as that for the salinity and heat transport equations, which use a high-order upwind difference solution scheme for the advection terms (Hamrick, 1992). Although the advection scheme is designed to minimize numerical diffusion, a small amount of horizontal diffusion remains inherent in the numerical scheme. As such, the horizontal diffusion terms in (2.17) are omitted by setting  $K_H$  equal to zero.

### 2.3.1 Noncohesive sediment transport processes

The process formulations used in EFDC for modeling noncohesive sediment transport in Reaches 7 and 8 are given in this section. Where applicable, reference is made to equations in Appendix A.

Incipient motion of a given class size of noncohesive sediment is determined using Eqs. A.10 and A.13. Once the applied bed shear stress exceeds the critical shear stress for incipient motion, the mode of transport, i.e., bedload or in suspension, is determined using the logic expressed in Eq. A.22.

Bedload transport is determined using the modified Engelund-Hansen formulation (Wu *et al.*, 2000; Engelund and Hansen, 1967) given by:

$$\frac{q_j^B}{\rho_s D_j \sqrt{g' D_j}} = 0.1 \frac{p_{b,j}}{f'} (\varepsilon_j \theta_j)^{2.5} \quad (2.18)$$

where  $q_j^B$  is the bedload transport rate (mass per unit width per unit time) in the direction of the near-bottom flow velocity;  $p_{b,j}$  is the fraction of grain size class  $j$  in the surface bed layer; and  $f'$  is the friction factor defined as:

$$f' = \frac{2gHS}{U^2} \quad (2.19)$$

where  $U$  = current speed. The term  $\varepsilon_j$  represents the relative magnitude of exposure and hiding due to non-uniformity of the grain size class fractions within the surficial bed layer. The modified Engelund-Hansen method uses the following exposure and hiding formulation, given by Wu *et al.* (2000):

$$\varepsilon_j = \left( \frac{p_{e,j}}{p_{h,j}} \right) \quad (2.20)$$

where the probability of exposure,  $p_{e,j}$ , and the probability of hiding,  $p_{h,j}$ , are given by:

$$p_{e,j} = \sum_j f_{n,j} \frac{D_i}{D_j + D_i} \quad \text{and} \quad p_{h,j} = \sum_j f_{n,j} \frac{D_j}{D_i + D_j} \quad (2.21)$$

where  $D_i$  = diameters of hidden particles,  $D_j$  = diameters of exposed particles, and  $f_{n,j}$  is the fraction of the  $j^{\text{th}}$  noncohesive size class in the surficial bed layer.

Suspended sediment transport, which occurs when the grain-related shear velocity exceeds the settling velocity for a specific grain size class, is a function of the excess shear stress (i.e., the difference between the grain-related bed shear stress and grain-related critical shear stress), the

near-bed equilibrium suspended sediment concentration and its corresponding reference distance above the bed surface. The near-bed equilibrium concentration is the suspended sediment concentration at a reference height,  $z_{eq}$ , above the bed surface. It represents the maximum suspension concentration. Some researchers take  $z_{eq}$  to be equal to the thickness of the bedload transport zone. The method of calculating the near-bed equilibrium concentration,  $C_{eq}$ , and the reference distance above the bed surface for bed material that consists of multiple noncohesive sediment size classes and that accounts for the effect of bed armoring [developed by Garcia and Parker (1991) (see Equation A.26)] is used in the EFDC model. For this model, in which multiple noncohesive sediment size classes are simulated, the equilibrium concentrations for each size class are adjusted by multiplying by their respective sediment volume fractions in the surface layer of the bed.

The settling velocity for noncohesive sediment particles,  $w_{sc}$ , is given by van Rijn (1984b) (see Equation A.20). The deposition rate of a particular size class is equal to the product of the settling velocity and the suspended sediment concentration for that size class, i.e.,  $C_j w_{scj}$ .

### 2.3.2 Cohesive sediment transport processes

The formulations used to represent the resuspension, settling, and deposition of cohesive sediment in the EFDC model are briefly described in this section. The deposition rate for suspended cohesive sediment is given by Equation A.38. The following settling velocity equation (in units of meters per day) is used:

$$w_{sc} = \frac{0.1C_{wl} + 30(C_{coh} - C_{wl})}{C_{coh}} \quad (2.22)$$

where  $C_{wl}$  is the washload concentration (determined to be 5 mg/L through calibration in the PSA model), and  $C_{coh}$  is the concentration of suspended cohesive sediment (WESTON, 2004b).

The resuspension rate of cohesive sediment,  $E_{coh}$ , is modeled using the following excess shear stress power law formulation (Lick *et al.*, 1994):

$$E_{coh} = f_{coh} M \left( \frac{\tau_{b, sed} - \tau_{ce}}{\tau_{ce}} \right)^n \quad (2.23)$$

where  $M = 6.98 \text{ g m}^{-2} \text{ s}^{-1}$ ,  $n = 1.59$ ,  $f_{coh}$  = fraction of cohesive sediment in the surficial bed layer,  $\tau_{ce}$  = critical shear stress for erosion, and  $\tau_b$  = bed shear stress. The values of  $M$  and  $n$  were developed from an analysis of data from Sedflume experiments on cores collected in the PSA domain.

## 2.4 Contaminant Transport and Fate Model

EFDC uses a three-phase partitioning model to simulate the transport of one or more contaminants during a single model simulation, and can be used to simulate the transport of organic chemicals (e.g., PCBs), metalloids (e.g., Arsenic), and metals (e.g., Copper, Zinc). Use of a three-phase partitioning model explicitly accounts for the freely dissolved contaminant, the

phase (or fraction) that is bioavailable via waterborne exposures, and is a better representation of the bioavailable fraction than a two-phase partitioning model as is used in other contaminant fate models such as HSCTM-2D (Hayter *et al.* 1999). Since this model simulation described in this report is of PCB transport in the Housatonic River, the remainder of this section concentrates on the specifics of representing the transport and fate of an organic chemical.

Nonionic organic chemicals, such as PCBs, can be distributed in various phases in aquatic ecosystems. One representation of this distribution is that the chemicals are partitioned among the particulate organic matter (POM), the dissolved organic matter (DOM), and also the freely dissolved form (USEPA, 1998). The degree of partitioning, as characterized by the dissolved, i.e., free plus dissolved organic carbon (DOC) complexed, and particulate fractions,  $f_d$  and  $f_p$ , respectively, is an important parameter that controls the fate of chemicals. This is because the transport of both the dissolved and particulate chemical phases is related to this phase distribution (USEPA, 1998).

In EFDC it is assumed that the total PCB (tPCB) load is distributed among the three phases, i.e., freely dissolved PCBs, DOC-complexed PCBs, and sorbed or particulate organic carbon (POC) bound PCBs, and that the PCBs are in equilibrium across all these phases. While the actual time it takes to reach complete equilibrium can be very long, it is often assumed that equilibrium between the dissolved and particulate phases occurs over a time scale of only a few hours to a day (Jepsen *et al.*, 1995). This is the basis of the equilibrium partitioning assumption that is commonly used in contaminant transport modeling. Transport processes that affect the fate of PCBs, and that are represented in the EFDC model, are discussed next.

Both dissolved and particulate-bound PCBs are advected by the flow in the river. Adsorbed PCBs are transported with sediment particles as the latter are moved as a result of bed load, suspended load, deposition and resuspension as simulated by the sediment transport model. There is also a vertical diffusive flux of PCBs that occurs in proportion to the gradient between the dissolved concentration in the water column and that in the pore water. This diffusive flux is due to molecular diffusion and bioturbation. In addition, advective transport due to groundwater flow may also result in a significant mass flux of other, less hydrophobic contaminants. Another PCB transport process, volatilization, is also simulated in EFDC. Volatilization is the loss of freely dissolved chemicals via transfer from the water column to the atmosphere.

The transport equation for the freely dissolved chemical is:

$$\begin{aligned}
 & \partial_t (m_x m_y H C_w) + \partial_x (m_y H u C_w) + \partial_y (m_x H v C_w) + \partial_z (m_x m_y w C_w) \\
 & = \partial_z \left( m_x m_y \frac{A_b}{H} \partial_z C_w \right) + m_x m_y H \left( \sum_i (K_{ds}^i S^i \chi_S^i) + \sum_j (K_{dD}^j D^j \chi_D^j) \right) \\
 & \quad - m_x m_y H \left( \begin{aligned} & \sum_i (K_{as}^i S^i) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_S^i - \chi_S^i) \\ & + \sum_j (K_{aD}^j D^j) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_D^j - \chi_D^j) + \gamma C_w \end{aligned} \right)
 \end{aligned} \tag{2.24}$$

where  $C_w$  is the mass of freely dissolved contaminant per unit total volume,  $\chi_s$  is the mass of contaminant sorbed to sediment class  $i$  per mass of sediment,  $\chi_D$  is the mass of contaminant sorbed to dissolved material  $j$  per unit mass of dissolved material,  $\phi$  is the porosity,  $\psi_w$  is the fraction of the freely dissolved contaminant available for sorption,  $K_a$  is the adsorption rate,  $K_d$  is the desorption rate, and  $\gamma$  is a net linearized decay rate coefficient. Since equilibrium partitioning is assumed, the adsorption and desorption rates are both equal to zero.

The sorption kinetics are based on the Langmuir isotherm (Chapra, 1997) with  $\hat{\chi}$  denoting the saturation adsorbed mass per carrier mass. The solids and dissolved material (i.e., DOC) concentrations,  $S$  and  $D$ , respectively, are defined as mass per unit total volume. The index  $j$  is the number of contaminants, and the index  $i$  is the number of classes of solids, i.e., organic particulate matter and inorganic sediment. The transport equation for the contaminant adsorbed to DOC is:

$$\begin{aligned} & \partial_t (m_x m_y H D^j \chi_D^j) + \partial_x (m_y H u D^j \chi_D^j) + \partial_y (m_x H v D^j \chi_D^j) + \partial_z (m_x m_y w D^j \chi_D^j) \\ & = \partial_z \left( m_x m_y \frac{A_b}{H} \partial_z (D^j \chi_D^j) \right) + m_x m_y H (K_{sD}^j D^j) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_D^j - \chi_D^j) \\ & \quad - m_x m_y H (K_{dD}^j + \gamma) (D^j \chi_D^j) \end{aligned} \quad (2.25)$$

The transport equation for the contaminant adsorbed to suspended solids is:

$$\begin{aligned} & \partial_t (m_x m_y H S^i \chi_S^i) + \partial_x (m_y H u S^i \chi_S^i) + \partial_y (m_x H v S^i \chi_S^i) + \partial_z (m_x m_y w S^i \chi_S^i) \\ & \quad + \partial_z (m_x m_y w_S^i S^i \chi_S^i) = \partial_z \left( m_x m_y \frac{A_b}{H} \partial_z (S^i \chi_S^i) \right) \\ & \quad + m_x m_y H (K_{aS}^i) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_S^i - \chi_S^i) - m_x m_y H (K_{dS}^i + \gamma) (S^i \chi_S^i) \end{aligned} \quad (2.26)$$

The concentrations (in units of sorbed mass per unit total volume) of chemicals adsorbed to DOC and solids,  $C_D$  and  $C_S$ , respectively, are defined as:

$$C_D^j = D^j \chi_D^j \quad (2.27)$$

$$C_S^i = S^i \chi_S^i \quad (2.28)$$

Introducing Equations 2.27 and 2.28 into Equations 2.24 – 2.26 gives:



$$\begin{aligned}
& \partial_t (m_x m_y H C_w) + \partial_x (m_y H u C_w) + \partial_y (m_x H v C_w) + \partial_z (m_x m_y w C_w) \\
& = \partial_z \left( m_x m_y \frac{A_b}{H} \partial_z C_w \right) + m_x m_y H \left( \sum_i (K_{ds}^i C_S^i) + \sum_j (K_{dD}^j C_D^j) \right) \\
& \quad - m_x m_y H \left( \begin{aligned} & \sum_i (K_{as}^i S^i) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_S^i - \chi_S^i) \\ & + \sum_j (K_{ad}^j D^j) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_D^j - \chi_D^j) + \gamma C_w \end{aligned} \right)
\end{aligned} \tag{2.29}$$

$$\begin{aligned}
& \partial_t (m_x m_y H C_D^j) + \partial_x (m_y H u C_D^j) + \partial_y (m_x H v C_D^j) + \partial_z (m_x m_y w C_D^j) \\
& = \partial_z \left( m_x m_y \frac{A_b}{H} \partial_z C_D^j \right) + m_x m_y H (K_{sD}^j D^j) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_D^j - \chi_D^j) \\
& \quad - m_x m_y H (K_{dD}^j + \gamma) C_D^j
\end{aligned} \tag{2.30}$$

$$\begin{aligned}
& \partial_t (m_x m_y H C_S^i) + \partial_x (m_y H u C_S^i) + \partial_y (m_x H v C_S^i) + \partial_z (m_x m_y w C_S^i) \\
& \quad + \partial_z (m_x m_y w_S^i C_S^i) = \partial_z \left( m_x m_y \frac{A_b}{H} \partial_z C_S^i \right) \\
& \quad + m_x m_y H (K_{as}^i S^i) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_S^i - \chi_S^i) - m_x m_y H (K_{ds}^i + \gamma) C_S^i
\end{aligned} \tag{2.31}$$

The EFDC sorbed contaminant transport formulation currently assumes equilibrium partitioning with the adsorption and desorption terms in Equations 2.30 and 2.31 being equal, such that:

$$(K_{sD}^j D^j) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_D^j - \chi_D^j) = K_{dD}^j C_D^j \tag{2.32}$$

$$(K_{as}^i S^i) \left( \psi_w \frac{C_w}{\phi} \right) (\hat{\chi}_S^i - \chi_S^i) = K_{ds}^i C_S^i \tag{2.33}$$

## 3 MODEL APPLICATION

### 3.1 Overview

As previously described, the EFDC modeling domain included Reaches 7 (Woods Pond Dam to the headwaters of Rising Pond in Great Barrington) and 8 (Rising Pond). The levels of PCB contamination in Reaches 7 and 8 relative to those in Reaches 5 and 6 are lower, but PCB concentrations in the sediment and particulate organic matter (POM) exhibit greater variation among specified subreaches in Reaches 7 and 8 than among the specified subreaches in the PSA. Figure 3.1 shows the locations of Reaches 5 through 8. The remainder of this section describes the application of EFDC to Reaches 7 and 8. Results from a 15-year simulation of this model are described in Section 4.

### 3.2 Spatial Domain

The spatial domain of the EFDC model of Reaches 7 and 8, hereafter referred to as the EFDC model, includes approximately 30.6 km (19 miles) of the Housatonic River, with the upstream boundary of the domain located at the outlet of Woods Pond and the downstream boundary at Rising Pond Dam (Figure 3.2). The domain also includes the floodplain inside the 1-ppm PCB soil concentration isopleth, which in most cases is coincident with the 10-year floodplain. Figure 3.3 shows the entire spatial domain of the EFDC model. The Housatonic River watershed area that drains into the upstream boundary of the EFDC model is 421.3 km<sup>2</sup> (162.6 mi<sup>2</sup>), and the area of the watershed between the upstream and downstream boundaries is 302.0 km<sup>2</sup> (116.6 mi<sup>2</sup>). Figures 3.4a and 3.4b show nine reaches (labeled as Reaches 7a, 7b, 7c, 7d, 7e, 7f, 7g, 7h and 8) into which Reaches 7 and 8 were subdivided for two purposes: 1) to enable specification of spatially varying sediment properties in the EFDC model; and 2) to perform the previously mentioned foodchain modeling of these two reaches. There will be references to these nine foodchain reaches in the subsequent parts of this report. Similarly, Reach 5 was divided into the four foodchain reaches shown in Figure 3.1.

Figure 3.2 shows the local drainage areas (in light green) and the seven tributaries that were explicitly represented in the HSPF model. As described in Section 1.3, HSPF was used to simulate non-point source water flows and the transported sediment and PCB loads into the Housatonic River during runoff events. The modeling domain of the HSPF watershed model used by EPA in the PSA modeling study extended to the USGS gage in Great Barrington, located approximately 1 mile south of Rising Pond Dam, and thus encompassed the floodplains of Reaches 7 and 8 as well. The simulated nonpoint source flows and the sediment loads conveyed by that runoff from the local drainage areas were added directly to the river channel within each local drainage area. The HSPF-simulated flow and associated solids concentration time series in the seven tributaries (i.e., Washington Mountain Brook, Laurel Brook, Greenwater Brook, Hop Brook, West Brook, Konkapot Brook, and Larrywaug Brook) are represented as point sources in the EFDC model. Additional discussion of boundary conditions is presented below.

As shown in Figure 3.5, the longitudinal bottom profile of the Housatonic River along the EFDC model domain divides Reaches 7 and 8 into the following six hydraulic sections with markedly different bathymetric and morphological features:

- Reaches 7A and 7B – From the upstream boundary (Woods Pond Dam) to Columbia Mill Dam. The average gradient in these reaches is 0.0032 meter per meter (m/m).
- Reach 7C and a portion of 7D – From Columbia Mill Dam to the town of Lee. As shown in Figure 3.5, the town of Lee represents a marked change in the river bottom gradient, with the gradient decreasing from 0.0020 m/m upstream of Lee to 0.00075 m/m downstream of Lee.
- Reach 7D remainder and 7E – From Lee to Willow Mill Dam. In this subreach, the bottom gradient, 0.00075 m/m, is less than the two upstream subreaches, and it contains several meanders.
- Reaches 7F and 7G – From Willow Mill Dam to Glendale Dam. These meandering reaches have the smallest average bottom gradient, 0.00017 m/m, and consequently, the lowest flow velocities in the EFDC model domain. The Stockbridge Golf Course is located in this section.
- Reach 7H – From Glendale Dam to the upstream limit of the backwaters from Rising Pond Dam. As shown in Figure 3.5, this section has the highest bottom gradient, 0.0042 m/m, and consequently, the highest flow velocities in the EFDC model.
- Reach 8 – Rising Pond, the impoundment created by Rising Pond Dam. Rising Pond, unlike the much wider Woods Pond at the downstream end of the PSA, resembles a run-of-the-river reservoir. The downstream end of each of these six hydraulic sections was located at a hydraulic control point (e.g., dam, break-in-grade). These figures also show the predicted river centerline water surface profile at a snapshot in time (low flow).

### 3.3 Model Grid

Starting at the upstream boundary of the EFDC model domain, Figures C.1 – C.12 present the vertically integrated, orthogonal-curvilinear grid used to model Reaches 7 and 8. This model grid, composed of 4,938 cells, is shown in that series of 12 images (with overlap on both ends of each image) to give the reader a useful view of the spatial variability. The light gray cells represent the floodplain, whereas the blue to red to blue colored cells represent the Housatonic River. In most locations, the relatively narrow river channel is one cell wide, except for Rising Pond and the other impoundments. This follows the approach used in the PSA model.

In general, the grid resolves the features of the EFDC model domain very well (e.g., meanders in Reaches 7D through 7G). Figures 3.6a and 3.6b, respectively, show a comparison between an aerial photograph of the Stockbridge Golf Course and the computational grid for the same area.

### 3.4 Model Inputs

To simulate the transport and fate of PCBs in the EFDC model domain, the EFDC model required the following hydrodynamic, sediment, and PCB inputs:

- Geometry of the model domain, floodplain topography, and river bathymetry.
- Bottom friction and vegetative resistance in the riverbed and floodplain.
- Sediment bed and floodplain soil composition and associated PCB concentrations.
- Hydraulic characteristics of four dams.
- Initial conditions for hydrodynamic, sediment, and contaminant transport modules.
- Boundary conditions for hydrodynamic, sediment, and contaminant transport modules.

These input parameters are discussed in more detail in the following:

#### 3.4.1 Geometry, floodplain topography, and river bathymetry

The river bathymetry and floodplain topography were developed from a number of different sources for the main channel, Rising Pond, and the floodplain. Detailed surveys of 77 cross-sections in Reaches 7 and 8 were conducted during summer 2005; these were used to describe the bathymetry of grid cells within the river channel and Rising Pond. The surveyed cross-sections provide bottom elevations across the channel at approximately 1-m spacing between surveyed points. Water surface elevation was also recorded at the time of the survey. The bathymetry within the main channel was defined by assigning the average bed elevation for a given cross-section to the EFDC grid cell at that location. Linear interpolation was used to assign the bottom elevation in channel cells between surveyed cross-sections. Bathymetry in Rising Pond was developed using cross-sections surveyed in 1998 and 2005 from an analysis performed in ArcGIS 8.3 with the Spatial Analyst extension. A Triangulated Irregular Network (TIN) surface was selected as the approach for incorporating these data into the model grid. The resulting average-value field was joined to the attributes of the model grid. EFDC floodplain grid cells were assigned bottom elevations from a 1.5-m (5-ft) interval digital elevation model (DEM) developed from USGS contour data.

#### 3.4.2 Bottom friction and vegetative resistance in the river bed and floodplain

For the effective bottom roughness,  $z_o$ , an effective roughness height of 0.04 m was assigned to the channel cells in unarmored free-flowing reaches (i.e., lower half of 7D and 7F), and a roughness of 0.06 m was assigned to the channel cells in the armored free-flowing reaches (Reaches 7A, 7C, upper half of 7D, and 7H). These values reflect the hydraulically rougher river bottom in most of Reaches 7 and 8 (due to the presence of larger noncohesive sediment) as compared to the PSA. In the impoundments formed by the four dams (i.e., Reaches 7B, 7E, 7G, and 8), a roughness height of 0.02 m was used since the sediment beds in the impoundments will, in general, be smoother than in the steeper, free-flowing reaches. A  $z_o$  value of 0.04 m was also uniformly applied to floodplain cells. Submerged aquatic vegetation is not prevalent in Reaches 7

and 8. As a result, the effects of aquatic vegetation were not represented in the EFDC model. In addition, the effect of friction from floodplain vegetation, which is a second order effect at most, was also not represented in the EFDC model. The relatively large  $z_o$  value of 0.04 m used in the floodplain cells implicitly represented the drag forces imposed on the flow when these cells are flooded due to vegetation (grasses, scrubs, trees) as is present on most of the floodplain in Reaches 7 and 8.

### 3.4.3 Sediment bed and floodplain soil composition and PCB concentrations.

The sediment bed within the river channel and soil on the floodplain were analyzed separately to establish the initial conditions for bed properties. Core samples taken at numerous locations throughout the river channel and floodplain were used to determine the spatially varying sediment grain size distribution across the EFDC model domain. Because of limited data on sediment properties with depth in the bed, it was assumed that the bed properties of all five bed layers used in both river channel and floodplain cells were the same. In the reaches of the river channel that are dominated by noncohesive sediment, this assumption would not be expected to result in either an over-prediction or under-prediction of sediment erosion, especially since an armored layer would be expected to form in these reaches once the finer-grained sediment is eroded from the surficial bed layer. However, in the reaches dominated by fine-grained sediment, e.g., the impoundments, this assumption might result in an over-prediction of sediment scour if more than the top layer of sediment is eroded during the simulation. The reason for this is that the consolidation-induced increase in bulk density and critical shear stress for resuspension that typically occurs with depth in a fine-grain sediment bed is not represented. The following thicknesses used for the five bed layers were the same as used in the PSA model: 7 cm for the surface layer, 8.24 cm for the first subsurface layer, and 15.24 cm for the three remaining subsurface layers.

Five grain size classes of solids, one cohesive and four non-cohesive, were used to represent the range of sediment, floodplain soil, and suspended solids grain sizes in Reaches 7 and 8. The cohesive grain size class was specified as  $< 63 \mu\text{m}$ , and ranges were defined for four non-cohesive grain size ranges: 63 to 250  $\mu\text{m}$  (very fine to fine sand), 250 to 2,000  $\mu\text{m}$  (medium to very coarse sand), 2,000 to 8,000  $\mu\text{m}$  (very coarse sand to medium gravel), and  $> 8,000 \mu\text{m}$  (medium gravel and coarser). Because the EFDC model tracks each size class as a single particle size, it was necessary to establish a nominal grain size for each class. The effective diameters used in the model to characterize the four non-cohesive size classes were set equal to the average of the representative sediment diameter values determined using the following three methods:

- Based on the median diameter ( $D_{50}$ ) of particles within each size class
- Based on settling velocities
- Based on critical shear velocities

A brief description of each of these three methods is given next. The first step was to separate the grain size data into four sets, one for each of the noncohesive sediment class ranges.

**Median Diameter Method:** For each non-cohesive size class, a  $D_{50}$  was calculated for each sample. The  $D_{50}$ 's from all samples were then combined, and a mean was calculated as the

effective diameter for each size class. The effective diameters calculated with this method are given in Table 3.1.

**Settling Velocity Method:** In this method, the settling velocity was calculated for each diameter represented by the geometric mean diameter between two sieve sizes. The equations given by van Rijn (1984a) (see Equation A.20) were used to compute the settling velocity. Once the settling velocities for each grain size were determined, a normalized settling velocity was calculated. The equivalent particle diameter was then back-calculated using the settling velocity equation. The effective diameters for the four size classes calculated with this method are given in Table 3.1.

**Critical Shear Velocity Method:** This method was based on the weighted critical shear velocities. First, the critical shear stress was calculated by the van Rijn (1984b) formulation (see Equations A.10 and A.13) and using the geometric mean diameter between two sieve sizes. The critical shear velocities were then calculated from the critical shear stresses, and then they were weighted using the normalized data set to find the effective critical shear velocity. Lastly, the equivalent grain size diameter for each sample was calculated. The effective diameters calculated with this method are again given in Table 3.1.

As seen in Table 3.1, the mean effective diameters for the three methods were very similar, with values ranging from 149 to 179  $\mu\text{m}$  for particles in the 63 to 250  $\mu\text{m}$  grain size class, 585 to 646  $\mu\text{m}$  for the 250  $\mu\text{m}$  to 2 mm class, 3,913 to 4,146  $\mu\text{m}$  for the 2,000  $\mu\text{m}$  to 8,000  $\mu\text{m}$  class, and 13,442 to 13,723  $\mu\text{m}$  for particles in the > 8,000  $\mu\text{m}$  class. For the EFDC model implementation, the effective diameters for the four non-cohesive grain sizes were calculated as the arithmetic mean of the values obtained from the three methods; these effective diameters are 159, 625, 3,993 and 13,560  $\mu\text{m}$ , respectively.

Specification of initial conditions for the percent composition of the five grain size classes for each model grid cell is required. Within the river channel, because of limited data in the free-flowing reaches, sediment data collected between the impoundments formed by Columbia Mill Dam, Willow Mill Dam, Glendale Dam, and Rising Pond Dam were combined to develop uniform initial conditions for these reaches. However, the reaches (i.e., backwaters) formed by the impoundments were analyzed and assigned initial conditions individually. The model grid cells within each reach were assigned the measured average value of the mass fraction within each size class range. Figure 3.7 shows the initial longitudinal distributions of grain sizes for the upper 60.96 cm (divided into four 15.24 cm layers) of river bed sediment. River Mile 124.3 is at the outlet of Woods Pond and River Mile 105.2 is at Rising Pond Dam. This figure shows that, because of the limited data (in comparison to the data available for the PSA), the grain size distributions between the impoundments formed by Columbia Mill Dam, Willow Mill Dam, Glendale Dam, and Rising Pond Dam were assumed to be constant. In addition, the longitudinal grain size distributions were assumed to be constant within the impoundments. Note that the general pattern within the river channel is for the percentages of cohesive sediment to increase in the impoundments and decrease in the reaches between impoundments, as expected. The same general pattern is observed for non-cohesive class 1, whereas the percentages of non-cohesive classes 2 - 4 increase with increasing bottom gradient. The largest non-cohesive size class was made immobile to represent the armoring that exists in Reaches 7A, 7C, and 7H.

The specification of initial conditions for grain size for floodplain cells was based on a spatial weighting analysis of the floodplain soil data. Grain sizes were derived from the data using an inverse distance approach with a 10-m<sup>2</sup> interpolation grid. Properties developed for the surface layer were also applied to the deeper bed layers due to the limited data at depth.

The sediment bulk density and porosity were determined from core samples that were analyzed for solids content. The data were averaged over the same spatial extent as the grain size distribution data described previously, and the average bulk density and porosity within each reach were calculated from the sediment specific gravity and the average sediment density. The model grid cells within each reach were assigned the average bulk density and porosity calculated for that reach. Spatial plots of the initial conditions of bed bulk density and porosity are given in Figures 3.8 and 3.9, respectively. Bulk density and porosity for floodplain soil were determined from soil core solids content data, assuming a specific gravity of 2.65.

Spatial distributions of sediment PCBs and fraction organic carbon ( $f_{oc}$ ) were determined from field measurements and assigned to the channel cells as the initial conditions at the beginning of the simulation. Initial PCB concentrations and  $f_{oc}$  of the sediment bed are plotted versus river mile in Figures 3.10 and 3.11. Initial OC-normalized PCB concentrations segregated into 1-mile bins are shown in Figure 3.12 (top figure uses a logarithmic scale and bottom figure uses an arithmetic scale). The green dotted vertical lines in this figure show the locations of (starting at the left) Woods Pond Dam, Columbia Mill Dam, Willow Mill Dam, Glendale Dam, and Rising Pond Dam. PCB concentrations are greater in the impoundments upstream of these dams than in the free-flowing river reaches upstream of the impoundments. This is particularly noticeable in the impoundment formed by Columbia Mill Dam.

To compute dissolved and particulate PCB concentrations with three-phase equilibrium partitioning used in EFDC, it is necessary to properly represent carbon-normalized PCB concentrations in the sediment. Because PCB and total organic carbon (TOC) data generally follow log-normal distributions, specification of average PCB and TOC concentrations in a given area (e.g., reach) would yield an inaccurate carbon-normalized PCB concentration. This problem was resolved by specifying the average PCB concentration and a different value for the organic carbon content of the sediment, TOC\*, such that the ratio of the two equals the appropriate TOC-normalized PCB concentration. The average PCB and TOC\* concentrations estimated for a given reach were then assigned to the grid cells within that reach. The values of TOC\* are not used for any other purpose in the model.

Modified inverse distance weighting was used to create a fine-scale (3-m<sup>2</sup> grid) distribution of total PCB (tPCB) concentrations in the floodplain soil based on the available data. A similar approach was used to develop initial conditions for  $f_{oc}$  in the floodplain soil by creating a distribution of  $f_{oc}$  on a 10-m<sup>2</sup> grid using the inverse distance weighting approach. The  $f_{oc}$  concentrations within a model grid cell were averaged to develop the model initial conditions.

The EFDC model also requires inputs for DOC in the water column, DOC in the sediment pore water, and fraction organic carbon ( $f_{oc}$ ) of the TSS in the water column. These parameters are necessary for partitioning the PCBs among particulate, DOC-complexed, and truly dissolved phases. As in the PSA model, porewater DOC and TOC in the sediment and the DOC and  $f_{oc}$  in

the water column were assumed to be constant over time. This assumption eliminated the computational complexity of modeling organic carbon production and fate within the sediment and water column. The same values used in the PSA model for DOC in the water column and DOC and TOC in the sediment were also used in the EFDC model of Reaches 7 and 8. However, the  $f_{oc}$  values of the suspended sediment in the water column were specified, as determined from data, as 10% for the cohesive size class and 2% for the four non-cohesive size classes.

#### 3.4.4 Hydraulic characteristics of the four dams

As shown in Figure 3.5, there are four dams within the EFDC model domain. Physical characteristics (e.g., spillway elevation and length) and hydraulic properties (e.g., flow-stage rating curve) of these four dams were obtained from Harza (2001) and BBL (1994). In EFDC, these hydraulic structures are specified as control structures connecting specific upstream and downstream cells. This specification in EFDC allows water, solids, and PCBs to be properly transferred from upstream to downstream of the control structure. To account for the fact that the upstream cell widths were different from the spillway lengths of the dams, the flow-stage rating curves had to be adjusted so that for a given stage height (in this case, stage height represents the difference between the upstream water surface elevation and the spillway crest elevation), the correct discharge flowed over the spillway. Specifically, the coefficients in the original rating curves were adjusted to accomplish this.

#### 3.4.5 Initial Conditions

To begin a simulation, the initial water depth must be defined for each EFDC grid cell. The hydrodynamic module in EFDC is then run in a spin-up mode for a relatively short period of time (typically, on the order of a few days) so that the subsequent model simulation is independent of the initial conditions. For the EFDC model, the initial water depth in each channel cell in free-flowing reaches of the river was set to 1.0-m. In the impoundment areas of the four dams, the initial cell water depths were set equal to the difference between the dam spillway elevation plus 2-cm and the cell bottom elevations. This procedure ensured that the impoundments were full at the start of the spin-up, and thus water flowed over the spillways from the start of the simulation. The initial conditions for the grid cells within the floodplain were assigned the minimum water depth of 10-cm, indicating a dry cell, signaling EFDC to skip calculations in these cells. A four-day hydrodynamic spin-up time was used for the EFDC model.

The sediment transport model was spun-up for one year of simulated time (starting the simulation using the spun-up hydrodynamic module) to establish more spatially representative initial sediment bed conditions than those determined using the procedure described in Section 3.4.3. The bed composition, i.e., bulk density, porosity, and fraction of each of the five simulated sediment size classes, in each grid cell at the end of this one-year simulation was used as the initial bed conditions for the 15-year model simulation discussed in Section 4.

For the start of both the one year sediment spin-up and the subsequent 15-year model simulation, the initial suspended sediment concentrations for cohesive sediment were set to spatially uniform values of 5 mg/L. Zero initial concentrations were used for the four non-cohesive sediment size classes and for tPCBs.



### 3.4.6 Boundary conditions

Time series of flow, suspended solids concentrations, and particulate and dissolved tPCB concentrations calculated at the downstream boundary of the PSA model were used as the upstream boundary conditions for the EFDC model.

As described in the previous sections, the HSPF-simulated runoff and the cohesive and non-cohesive solids loads conveyed by the runoff from the local drainage areas shown in Figure 3.2 were added directly to the river channel within each local drainage area. These nonpoint loads were uniformly distributed to the channel cells within each local drainage area. For example, if there were 50 channel cells within a particular local drainage area, then the HSPF-calculated nonpoint source loads from the local drainage area on both sides of the river channel were added, the total load was divided by 50, and the result added to each of the 50 channel cells. The HSPF-simulated time series of flow and solids loads from the seven tributaries (i.e., Washington Mountain Brook, Laurel Brook, Greenwater Brook, Hop Brook, West Brook, Konkapot Brook, and Larrywaug Brook) shown in Figure 3.2 were represented as direct inputs to the seven river channel cells located at the confluence of these seven tributaries with the river.

Outflows at the model boundary at the Rising Pond Dam were controlled by the stage-discharge rating curve and the spillway crest elevation for this dam specified in BBL (1994).

## 3.5 Model Parameters

The parameter values and functions used in the EFDC model in the formulas for cohesive sediment settling and deposition, sediment-water column exchange of dissolved PCBs via diffusion and of sorbed PCBs via sediment particle mixing, PCB volatilization, as well as for these parameters needed for three-phase partitioning calculations, are the same as those used in the PSA model (WESTON, 2004b). Parameters related to the transport and fate of PCBs are briefly described next.

### 3.5.1 Partitioning of PCBs in pore water and the water column

An assumption in equilibrium partitioning theory is that the carbon-normalized PCB concentrations are proportional to the freely dissolved pore water concentrations. A Pore Water Partitioning Study and a Supplemental Surface Water Partitioning Study found that a three-phase partitioning model is a reasonable representation of PCB partitioning in the Housatonic River (Mathew *et al.*, 2002; BBL and QEA, 2003). In these studies, the data were analyzed for individual congeners and as tPCBs, and it was assumed that partitioning to organic carbon is a function of the contaminant-specific octanol-water partition coefficient,  $K_{ow}$  (Karickhoff *et al.*, 1979; Karickhoff, 1981; Di Toro *et al.*, 1985). As reported by Mathew *et al.* (2002), analysis of PCB congener data found the following results: for sorbed carbon  $K_{oc} \sim K_{ow}$ , and for dissolved carbon in the porewater,  $K_{DOC} = \alpha_{DOC} K_{ow} \sim 0.1 K_{ow}$ . These results are in general agreement with those found by Di Toro (1985), EPA (1998), and Burkhard (2000).

The studies mentioned above also found that it was acceptable to model tPCBs instead of individual PCB congeners. As a result, a tPCB partition coefficient that reflects the congener distribution in the sediment and pore water needed to be derived. To accomplish this task, it was assumed that  $K_{oc} = K_{ow}$ , with  $K_{ow}$  values determined using the results presented by Hawker and

Connell (1988). A weighted average value of  $\log(K_{ow}) = 6.5$  was found using the pore water fractions of dissolved PCB homologues. A value of  $\alpha_{DOC} = 0.1$  was determined by fitting the partitioning data with the three-phase partitioning model (WESTON, 2004b).

An analysis of water column partitioning data also indicated that a three-phase partitioning model is a reasonable representation for partitioning in the water column (WESTON, 2004b). However, that analysis also showed that DOC complexation is less important in the water column than in the sediment. BBL and QEA (2003) also reported that DOC complexation in the water column of the Housatonic River was of less importance relative to that in the sediment bed. This is due to, among other factors, lower DOC concentrations in the water column than in the sediment, and differences in the nature of the DOM present in the water column compared to that in the sediment pore water. The latter factor was the reason the water column data were analyzed separately to determine a value of  $K_{DOC}$  for the water column. It was found that the water column data were best reproduced using  $\alpha_{DOC} = 0.01$  (WESTON, 2004b). This value is at the lower end of values of  $\alpha_{DOC}$  found by Butcher *et al.* (1998) for tetra through hexachlorobiphenyl homologues in the water column of the upper Hudson River; those values ranged from 0.011 to 0.049. Given that DOC in the water column usually forms weaker complexes with non-polar, organic contaminants (NPOCs), such as PCBs, than those formed with DOC in the pore water of sediment beds, the results reported by Butcher *et al.* are in general agreement with the results found from analysis of Housatonic River pore water - sediment data.

### 3.5.2 Sediment – water column PCBs exchange

As mentioned previously, exchange of contaminants between the water column and the bed sediment occur by the diffusive flux of dissolved contaminants between the water column and pore water in the sediment, and by transport of contaminants that are adsorbed on sediment that undergoes deposition and resuspension. The contaminant diffusive flux, equal to the product of a mass transfer coefficient (i.e., effective diffusion coefficient) times the concentration gradient of the freely dissolved contaminant between the water column and sediment pore water, is known to be an important transport mechanism (Thomann and Mueller, 1987; Thibodeaux *et al.*, 2002). The diffusive flux is typically of increased importance relative to the resuspension and deposition induced particulate flux during baseflow periods when the particulate flux is usually reduced. It also has a greater impact on water column concentrations during baseflow conditions because there is less dilution of the contaminant mass that diffuses from the sediment due to the smaller volume of water above the sediment. The mass transfer coefficient is a function of the dissolved pore water concentration and the mass of dissolved contaminant transferred to the water column during baseflow conditions. Analyses of sediment-water column mass flux data sets for the PSA portion of the Housatonic River was used to establish that the order of magnitude of the average PCB mass transfer coefficient was from 0.2 to 8.4 cm/day. The value of 1.5 cm/day used in this study was determined during calibration of simulated results to water column data (WESTON, 2004b).

### 3.5.3 Sediment Particle Mixing

Mixing of sediment particles that compose the bed is caused by both physical and biological processes. Physical mixing processes include resuspension, bedload transport, and deposition. Bioturbation is an important biological mixing process that results in the vertical

transport of contaminants adsorbed to sediment within the bed sediment (Di Toro, 2001). In the EFDC model, this process is simulated as a mixing of sediment between the sediment layers in the bed. This particle mixing is set proportional to a particle-mixing rate. In the river channel, the reaches between the impoundments formed by Columbia Mill Dam, Willow Mill Dam, Glendale Dam, and Rising Pond Dam were assigned low particle mixing rates ( $10^{-12}$  m/s over the upper 4 cm in the sediment bed) because benthic activity is expected to be low in these predominantly non-cohesive armored reaches. Similar mixing rates were assigned in the floodplain soils as well. Particle mixing rates were set an order of magnitude lower in the 4-10 cm depth interval, and set to zero below 10 cm. Within the reaches formed by the impoundments, particle mixing rates were calculate in a manner similar to the PSA (WESTON, 2006), and ranged from  $0.69 \times 10^{-9}$  m/s to  $2.1 \times 10^{-9}$  m/s and applied over the upper 7 cm in the sediment bed. Particle mixing rates were set an order of magnitude lower in the 7-15 cm depth interval, and set to zero below 15 cm.

#### 3.5.4 Volatilization

Volatilization of organic contaminants such as PCBs, is proportional to the concentration gradient across the air-water interface, and can be modeled using two film transfer theory (Whitman, 1923). It also depends on the water depth, flow velocity, and wind speed. The driving force for volatilization is the partial pressure gradient in the air and the concentration gradient in the water, and the volatilization flux in each phase can be described using Fick's Law of Diffusion. The transfer coefficient due to volatilization is a function of the transfer coefficients for both liquid and gas phases. Analysis based on congener-specific Henry's Law constants and the relative site-specific congener composition of samples collected in the PSA found that the loss of PCBs via volatilization is a relatively minor transport/fate process. Nevertheless, volatilization was simulated in the model of Reaches 7 and 8 using the PSA derived parameter values.

**Table 3.1**

**Effective Diameters for Non-Cohesive Sediment Classes**

Parameter	Method (1) Grain Size Distribution				Method (2) Weighted Settling Velocities				Method (3) Weighted Critical Shear Velocities			
	63 - 250 $\mu\text{m}$	250 $\mu\text{m}$ - 2 mm	2 - 8 mm	> 8 mm	63 - 250 $\mu\text{m}$	250 $\mu\text{m}$ - 2 mm	2 - 8 mm	> 8 mm	63- 250 $\mu\text{m}$	250 $\mu\text{m}$ - 2 mm	2 - 8 mm	> 8 mm
Mean $d_{eff}$ ( $\mu\text{m}$ )	150	585	4146	13,723	179	646	3913	13,442	149	643	3919	13,515



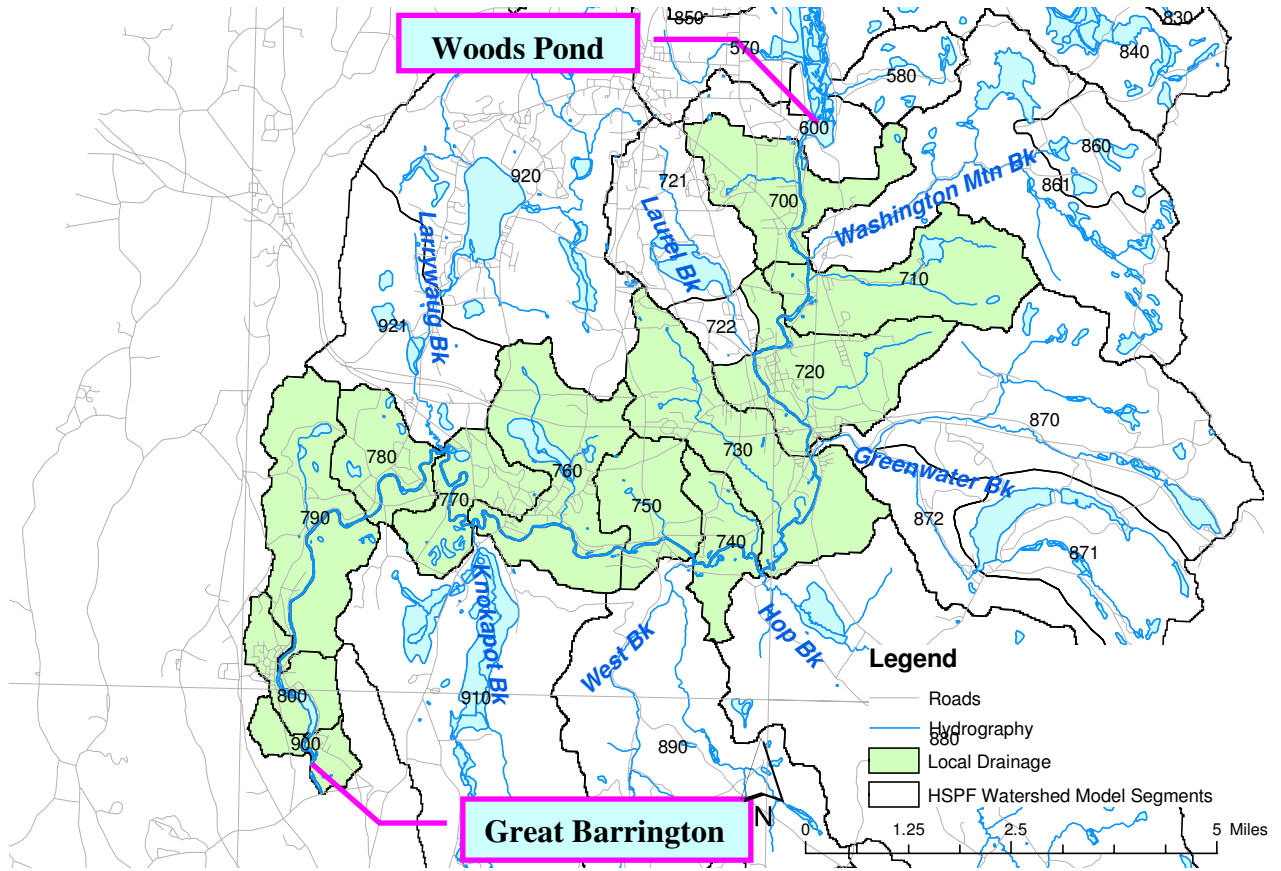


Figure 3.2 Housatonic River between Woods Pond and Great Barrington (after WESTON, 2006)

### Housatonic River Downstream (Reaches 7 & 8) Model

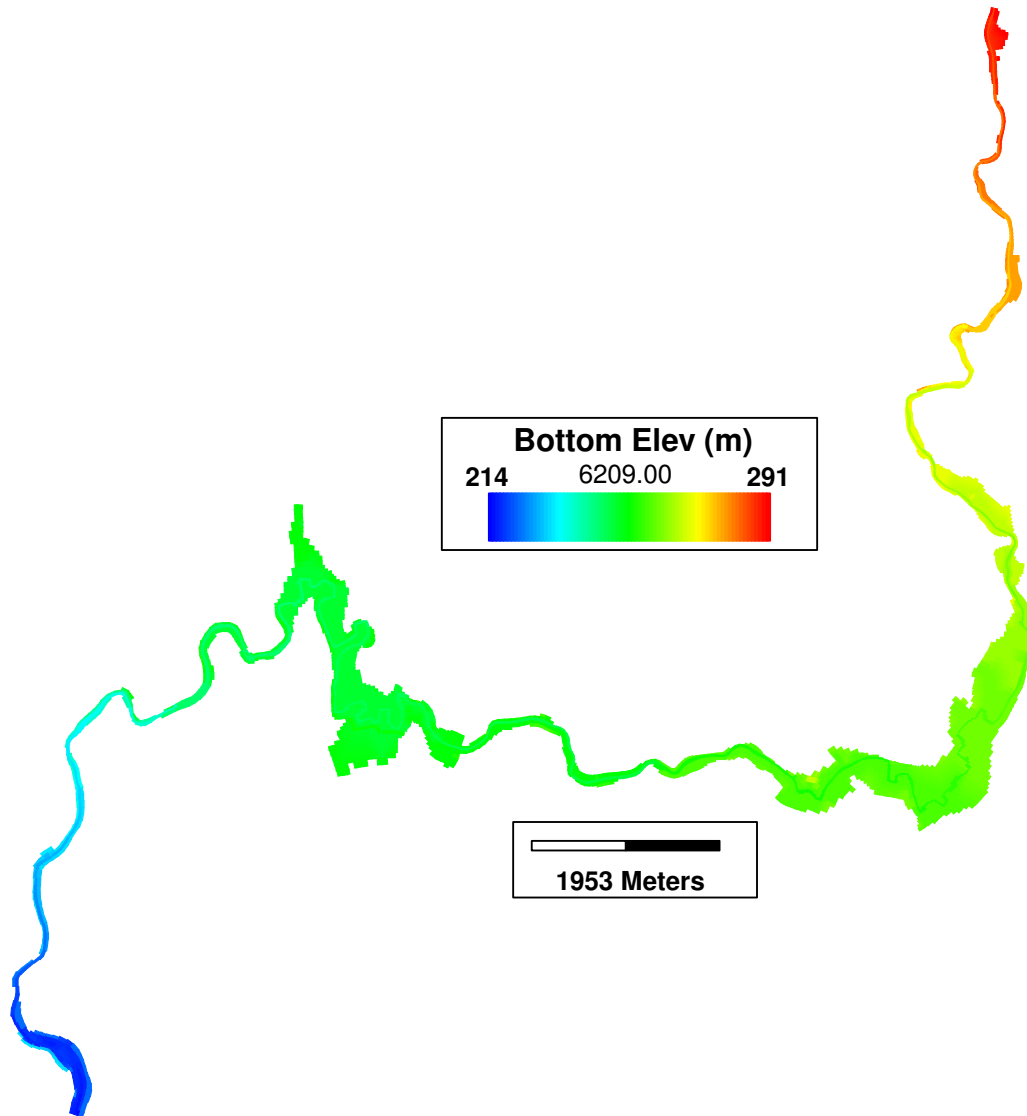


Figure 3.3 Spatial Domain of the EFDC Model Showing Variation in Bottom Elevation (in meters – NAD 83 (86)) (after WESTON, 2006). North is up in this figure.

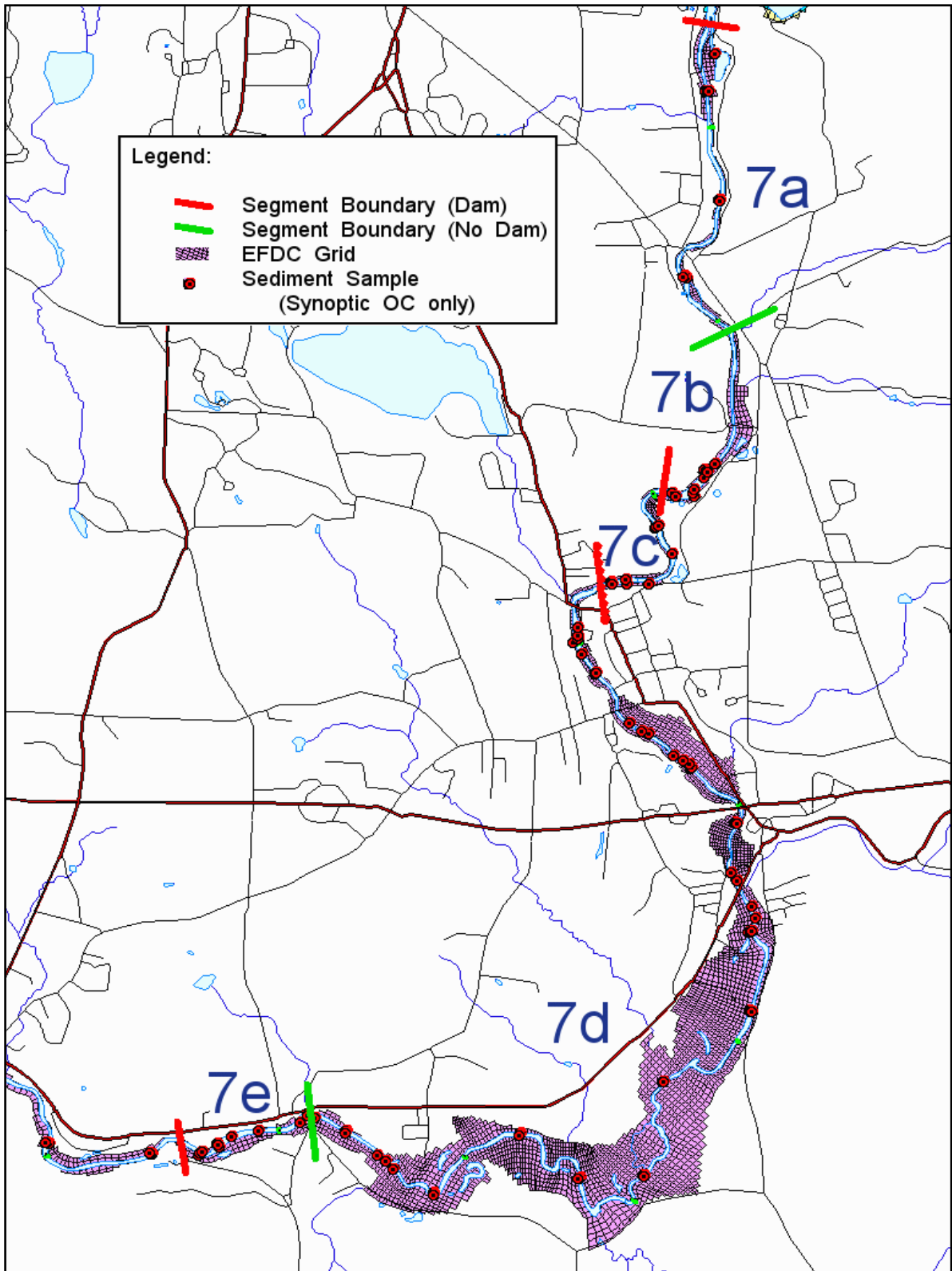


Figure 3.4a Foodchain Reaches 7a – 7e from Woods Pond Dam to Willow Mill Dam (after WESTON, 2006). North is up in this figure.



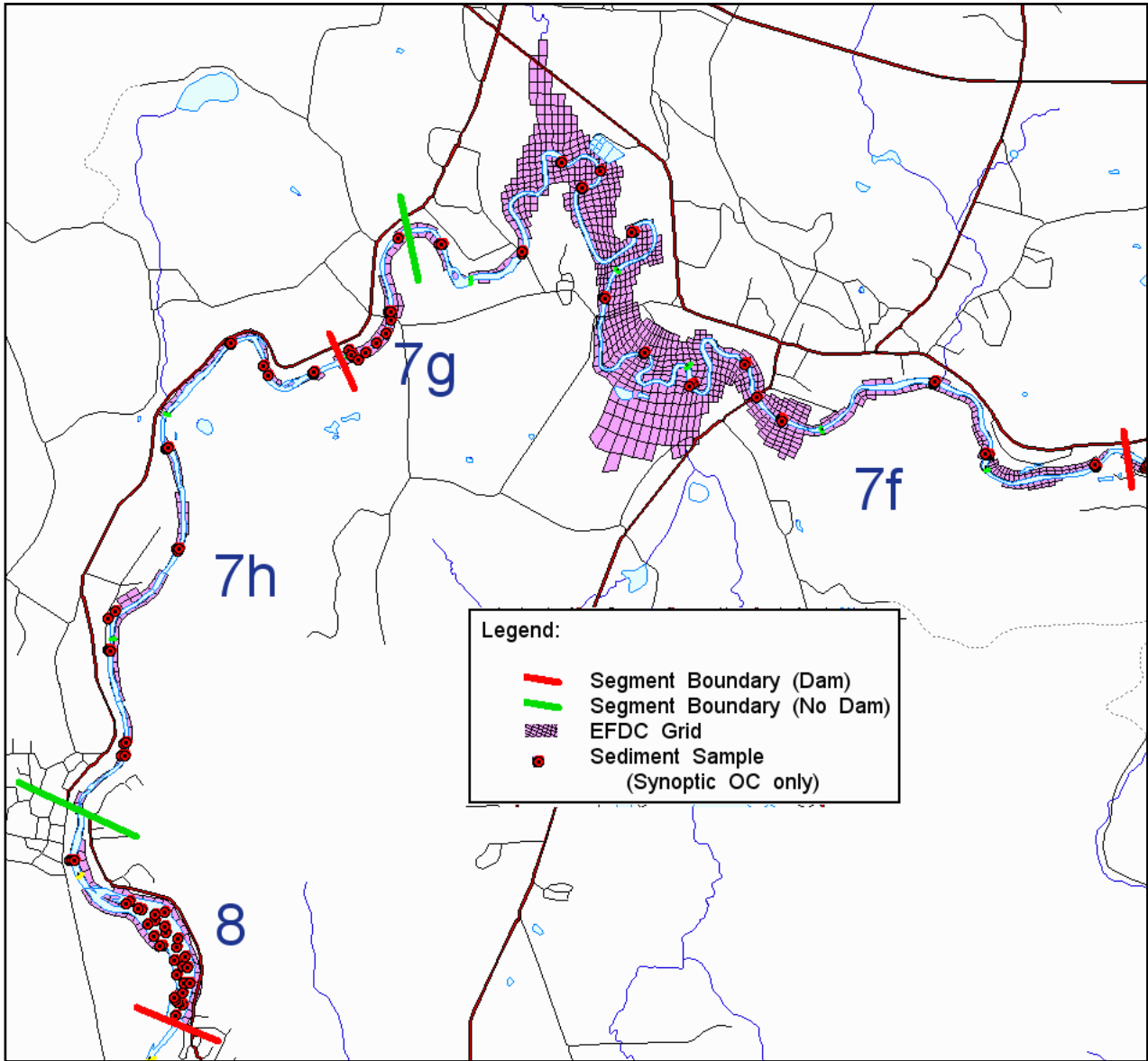


Figure 3.4b Foodchain Reaches 7f – 8 from Willow Mill Dam to Rising Pond Dam (after WESTON, 2006). North is up in this figure.

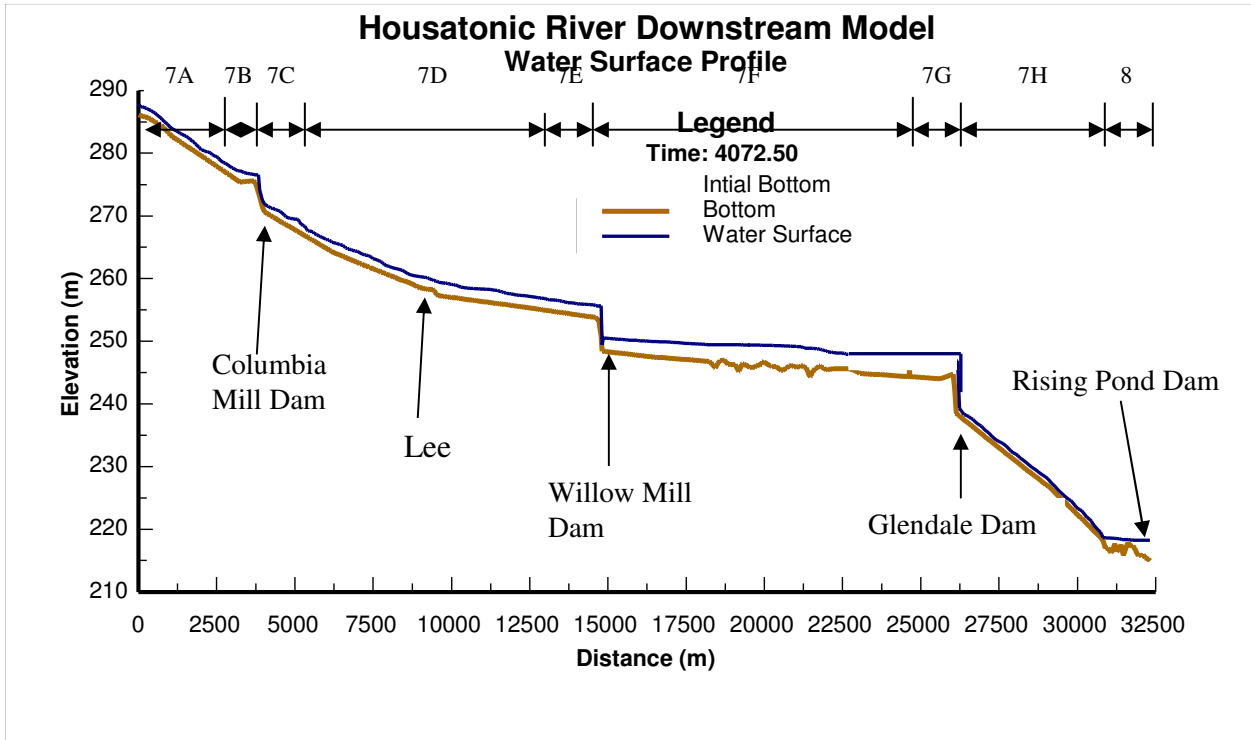


Figure 3.5 Longitudinal Bottom Gradient and Water Surface Profiles in Reaches 7 and 8 Showing Foodchain Reaches 7A – 8 and Location of the Four Dams (after WESTON, 2006)



Figure 3.6a Photo of Stockbridge golf course

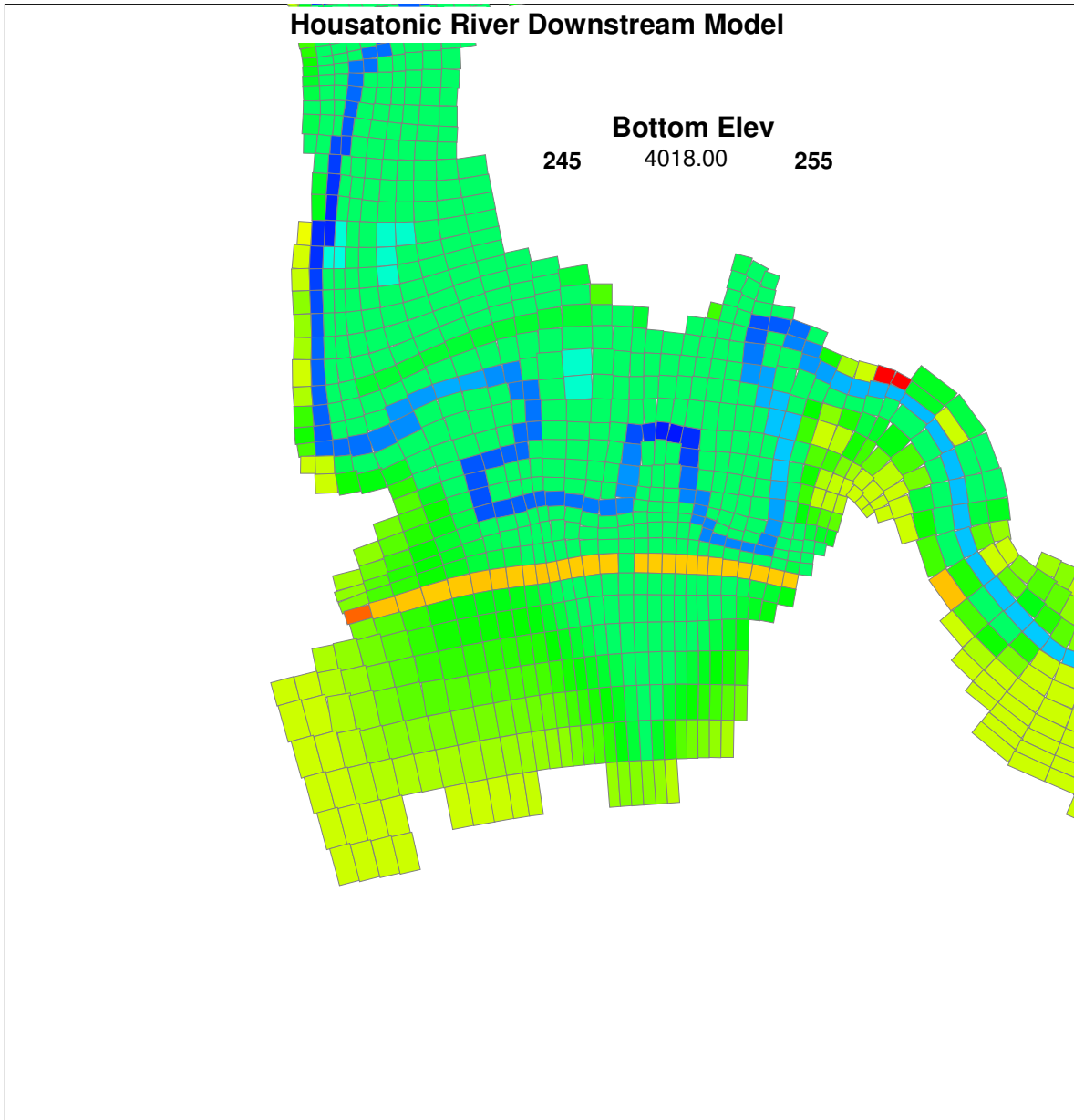


Figure 3.6b    Grid in the area of the Stockbridge golf course. North is up in this figure.

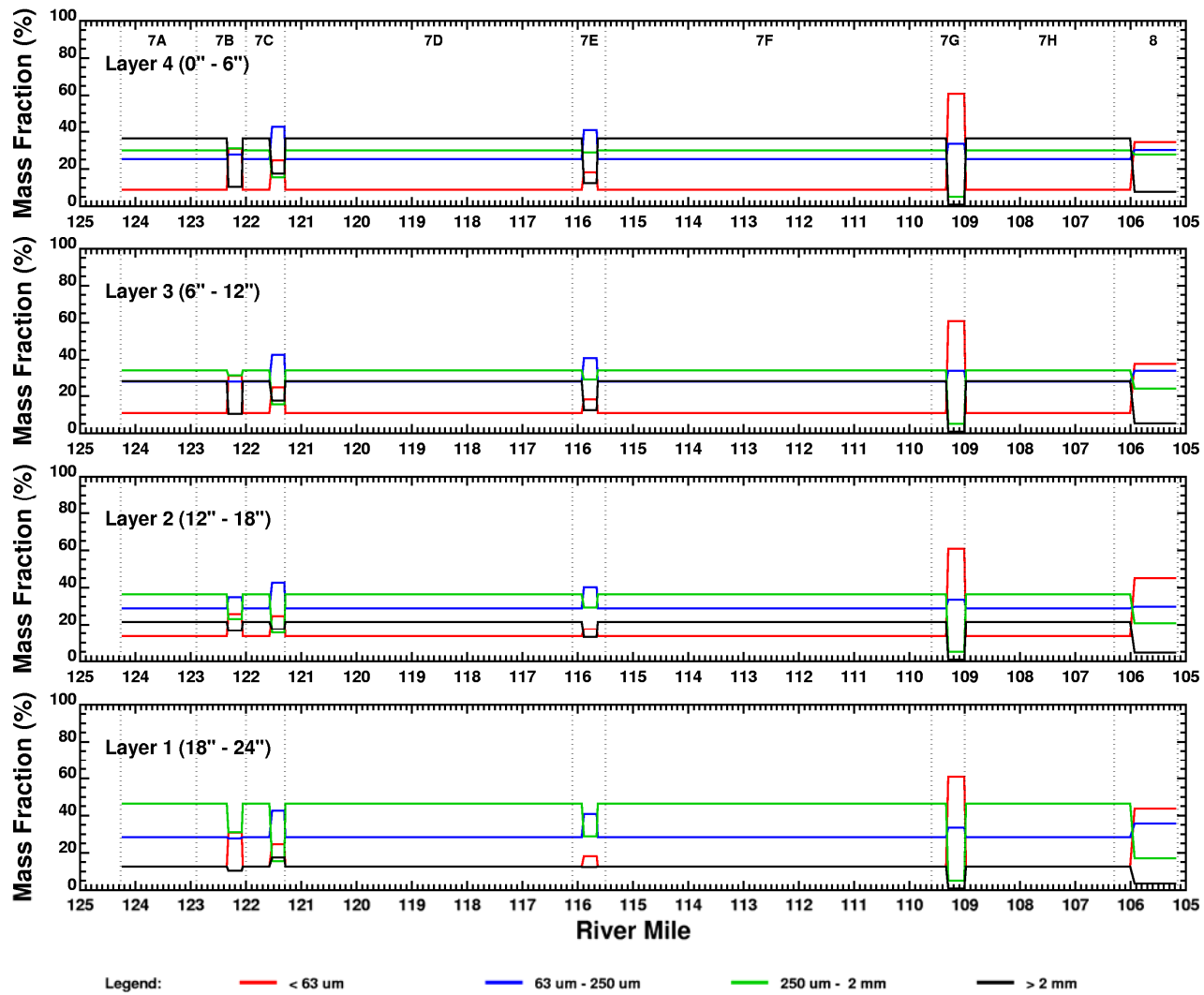


Figure 3.7 Initial Longitudinal Distributions of Grain Sizes for the River Bed Sediment

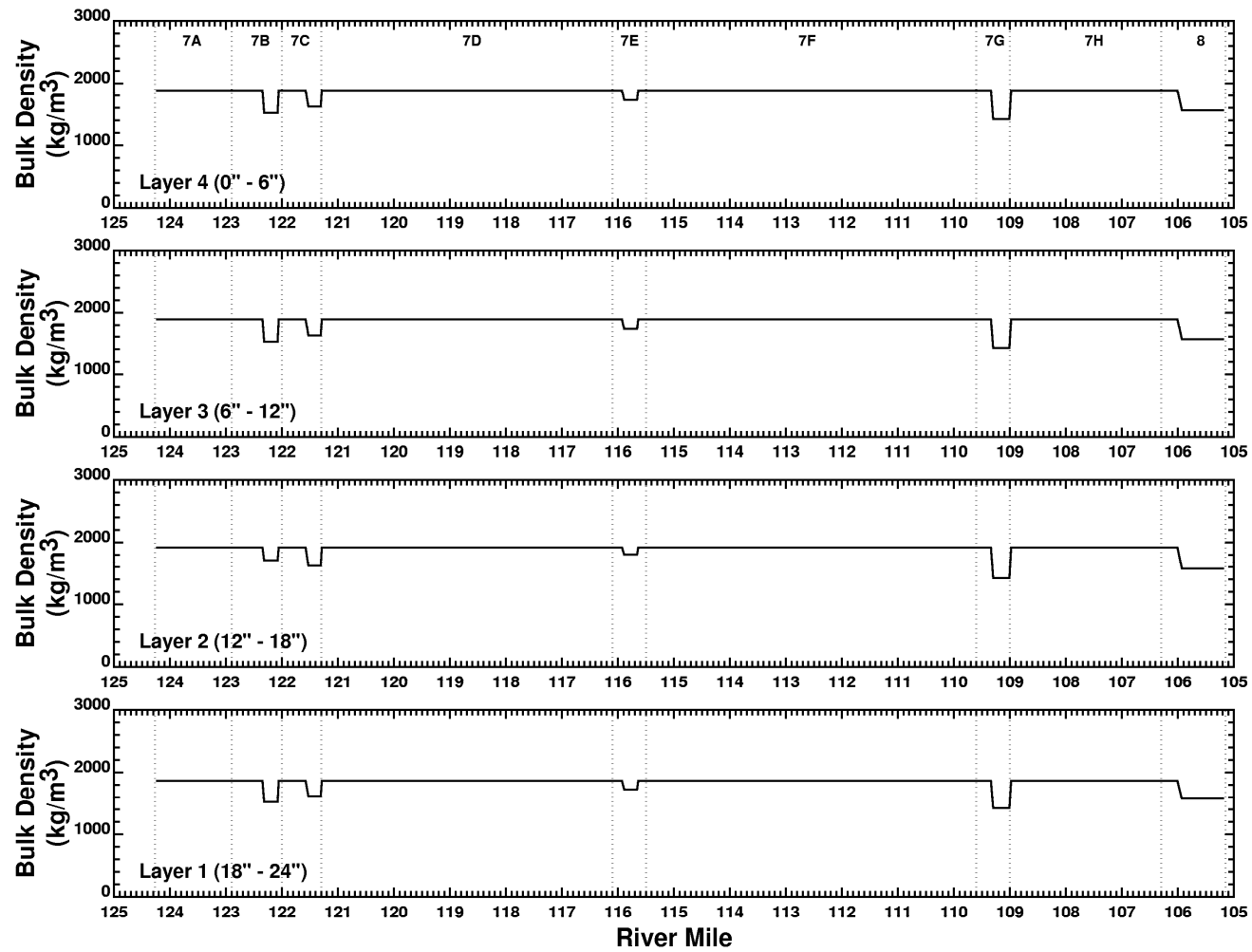


Figure 3.8 Initial Longitudinal Distributions of Bulk Densities for the River Bed Sediment

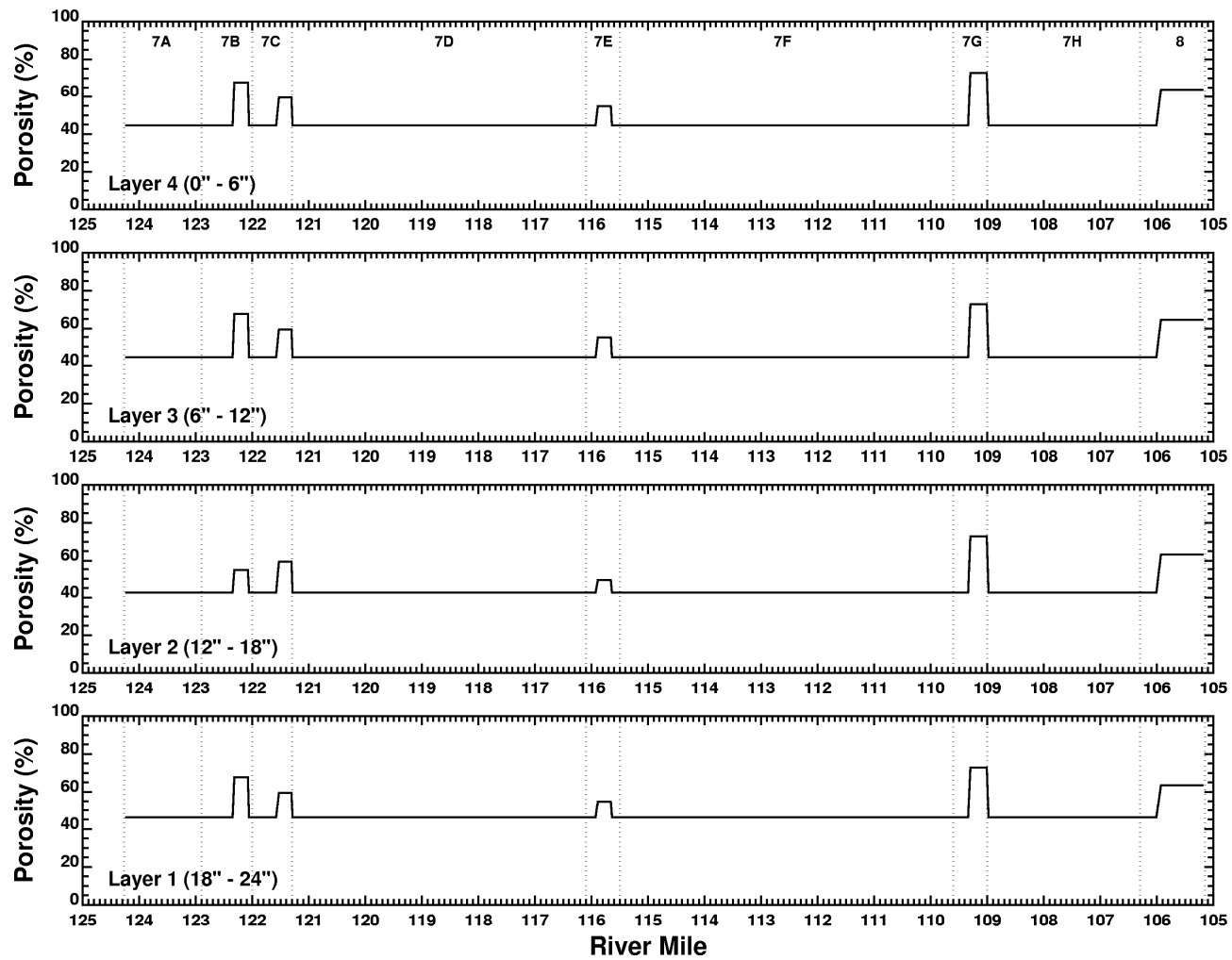


Figure 3.9 Initial Longitudinal Distributions of Porosities for the River Bed Sediment

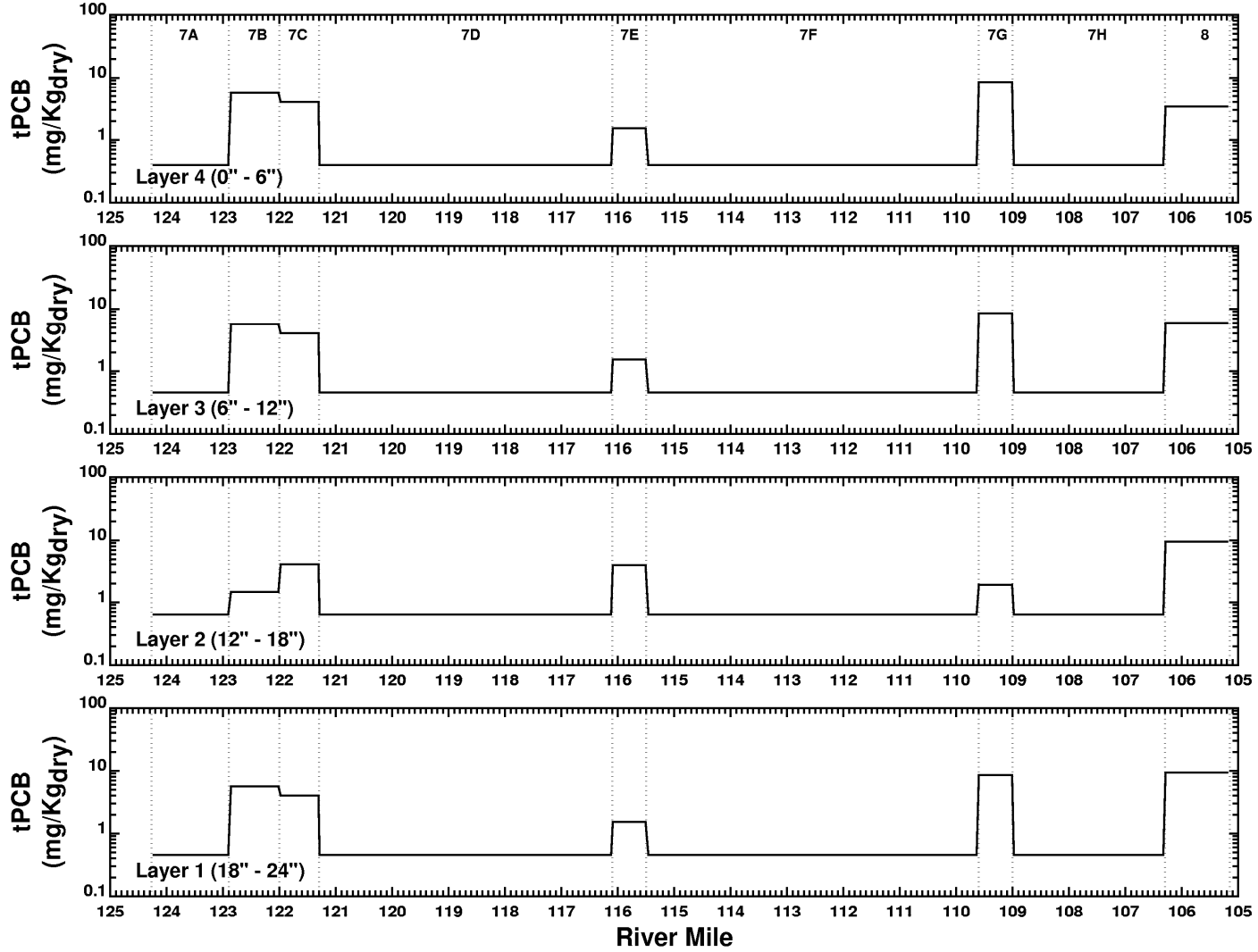


Figure 3.10 Initial Longitudinal Distributions of Sediment tPCB Concentrations



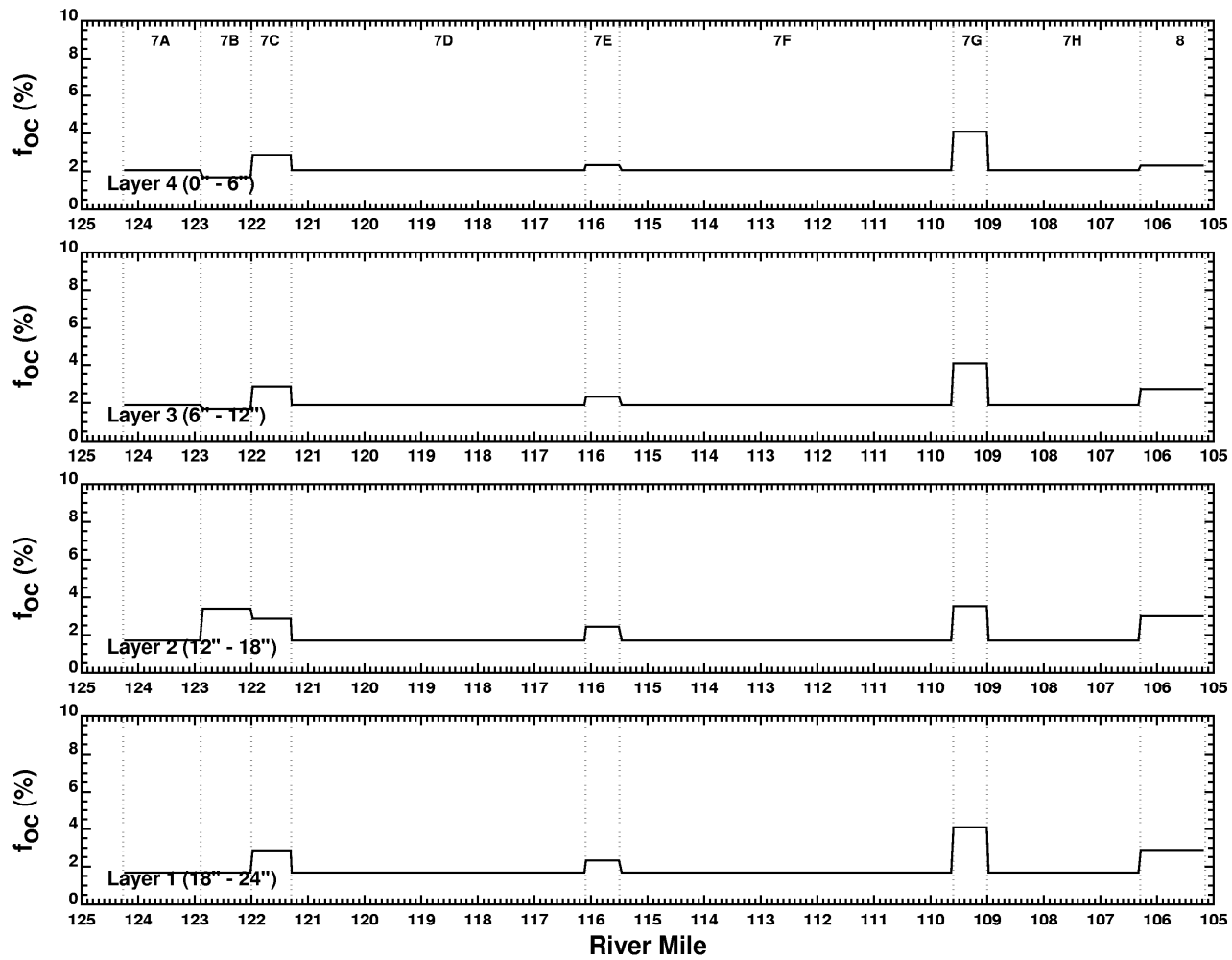


Figure 3.11 Initial Longitudinal Distributions of Fractions of Organic Carbon for the River Bed Sediments

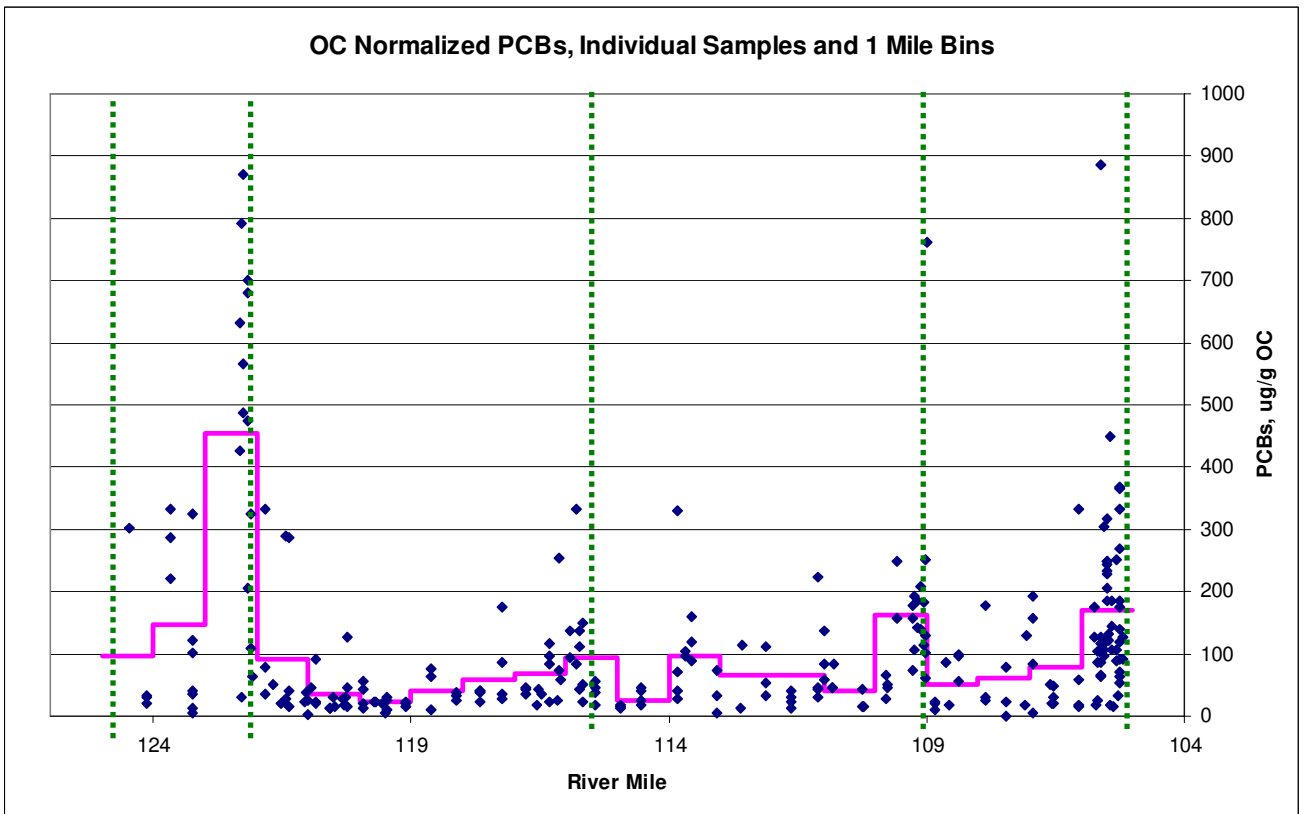
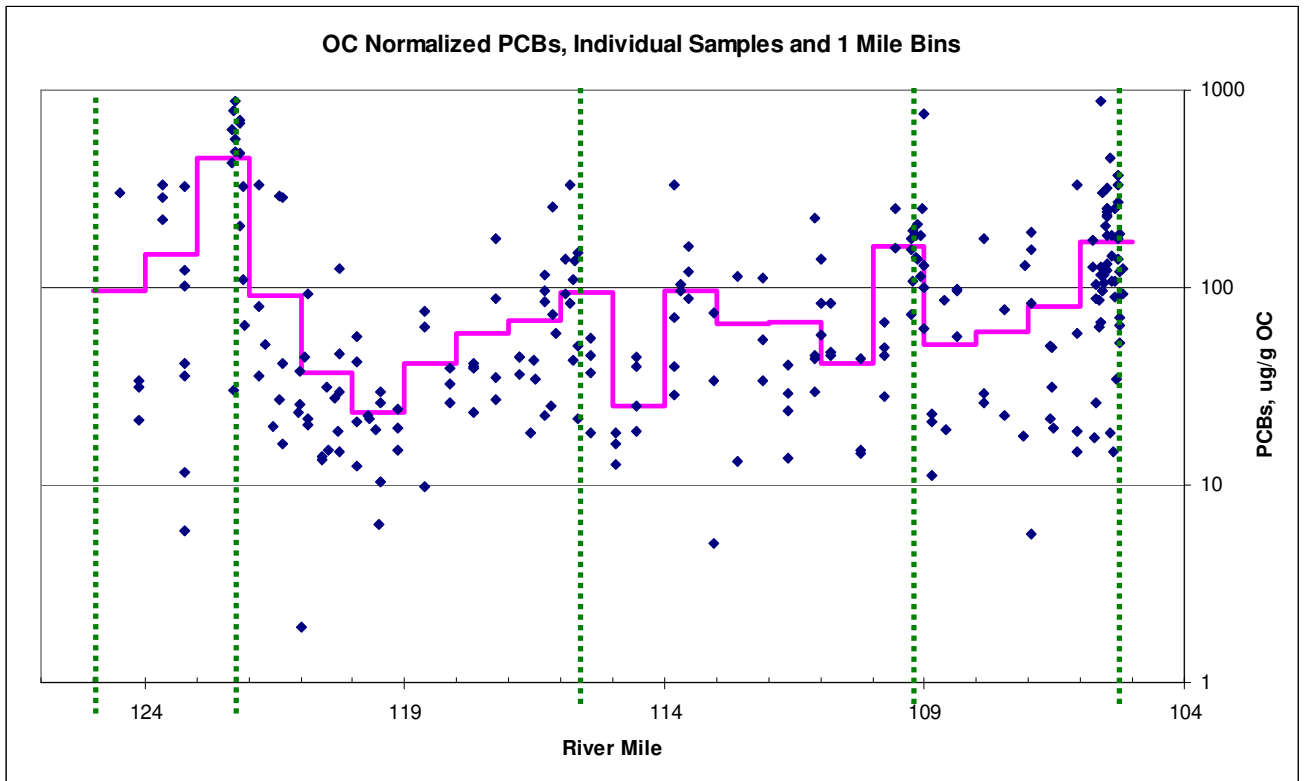


Figure 3.12 Initial OC-Normalized PCB Concentrations (Segregated into 1-Mile Bins) versus River Mile (after WESTON, 2006)

## 4 MODEL EVALUATION

### 4.1 Model Application

The EFDC model was run to simulate sediment and tPCB transport in Reaches 7 and 8 over a 15-year period, from January 1, 1990 – December 31, 2004. This period was selected because it includes the vast majority of the data record available for Reaches 7 and 8. For the simulation, the EFDC model was spun-up using the boundary conditions for the one year period prior to January 1, 1990. The simulated sediment bed conditions at the end of this one year spin-up were used as the initial conditions for the 15-year simulation. The initial PCB concentrations at the beginning of the 15-year simulation were set equal to those at the beginning of the one-year spin-up run since these initial concentrations were determined from data.

Figure 4.1 shows the cumulative change in bed elevations over the 15-year simulation. In this figure, the model domain is divided roughly in half, with the connection point between the labeled “Upstream Half of Reach 7” and the “Downstream Half of Reach 7 and Reach 8” being point ‘a’. As seen in the table entitled “Greatest Cumulative Differences” in the middle of this figure, the maximum cumulative deposition that occurred over the 15-year simulation (1.70 m) occurred at the grid cell (with cell i,j indices 332,204) that is located at the confluence of Hop Brook with the Housatonic River. This cell is located at a 90-degree bend in the river, and the river channel expands from being one cell wide to two cells wide just one cell upstream of the 90-degree bend. The combination of these two factors caused most of the HSPF-simulated sediment load being transported in Hop Brook to deposit at its mouth. The two cells with the next highest cumulative depositions (with cell i,j indices 356,45 and 357,460) are located in proximity to two consecutive 90 degree bends in the river with the river channel expanding to two cells wide immediately downstream of the bends. The two cells (with cell i,j indices 357,101 and 357,147) with the highest cumulative erosion (0.47m and 0.42m) occurred in reaches where there were fairly substantial flood event driven morphologic changes, both upstream and downstream of these cells. These simulated maximum cumulative erosion depths in non-armored reaches of an incised Piedmont river are not at all unreasonable over a 15-year time period.

### 4.2 Model-Data Comparisons for Water Column TSS and PCBs

The only data set for water column PCB and TSS concentrations used to develop model-data comparisons was collected at Division Street (the USGS Great Barrington gaging station), located approximately 1-mile downstream of Rising Pond Dam. Simulated TSS and tPCB concentrations at the outlet of Rising Pond (shown as black lines) are compared with the data (shown as solid red squares) in Figures 4.2a through 4.2h in which the state variable is plotted on a log scale. To make it easier to visualize differences between data and model results, model results at the times when TSS and/or tPCB data were collected are plotted as blue open circles. No data were collected in 1994-1995 (Figure 4.2c). However, in subsequent years, the sampling frequency increased to at least bimonthly. As seen in Figure 4.2d, there was a period during March and April 1997 when relatively high frequency TSS sampling was conducted.

Examination of Figure 4.2 shows that most TSS concentrations measured at the Division Street Bridge were in the range of 1 to 20 mg/L. The low end of the simulated TSS

concentrations is usually between 1 to 2 mg/L, which is consistent with the data. As seen in Figure 4.2, the lowest simulated values occur towards the end of baseflow recession curves. It is also noted that better agreement between TSS data and model results was obtained for the second half of the 15-year simulation, and in particular the last six years, than the first half.

Also apparent in these figures is that simulated TSS values are typically less variable than the measurements. Since simulated TSS concentrations vary in response to changes in the inflow hydrograph (upper panel in Figure 4.2), the variability-related differences are thought to be, at least in part, attributable to differences between the HSPF simulated nonpoint runoff and the flows and solids loadings from the seven modeled tributaries that are used as boundary conditions in the EFDC model compared with the actual nonpoint and point inflows and loadings. That is, it needs to be recognized that at the relatively fine temporal and spatial resolution of the EFDC model, even small differences between the timing and magnitude of HSPF simulated inputs and the actual inputs could cause comparatively large differences between simulation results and measurements. The differences in the results caused by the different locations where the data were collected (Division Street) and the model results were obtained (dam at Rising Pond) are thought to be: 1) mainly phasing-related differences, and 2) secondary to the HSPF-related differences discussed above due to the free-flowing nature of the river and the relatively short distance between these two sites.

Data are typically not available at the time of these simulated peak TSS concentrations. However, during March - April 1997 two high flow events with peak flows greater than 28 cms (1,000 cfs) occurred. Figure 4.3 shows the model-data comparisons for the mid-March to June period. The upper panel shows the comparison between the simulated flow (solid blue line) at Rising Pond Dam and the measured flow (solid black line) at Division Street. As observed, the simulated flows are slightly higher than the measured flows for most of this three month period. TSS measurements during this period ranged from approximately 2 to 20 mg/L and, as noted previously, showed more variability than simulated TSS values. Simulated TSS values during this period are mostly within this range and also capture some of the relationship exhibited by the measurements. For example, the simulated and measured peak TSS values are similar.

While the TSS data are generally higher than the simulated values, as seen in Figures 4.2 and 4.3, the vast majority of the differences are less than 5 mg/L, and thus within the uncertainty associated with the measured values since the latter are based on samples collected at one point in the cross-section at Division Street and the simulated values are the cross-sectionally averaged values at the outflow from Rising Pond. Figure 4.4 shows the model-data comparison for July – September 2004. Notwithstanding the extremely limited number of measurements, the level of agreement seen in this figure between measured and simulated flows and between the three measured values of TSS and tPCB and the simulated values is representative of the model-data agreement achieved in the last six years of the 15-year simulation.

Comparisons between simulated and measured tPCBs show similar behavior to that described for TSS. Measured tPCB values vary mostly from ~0.01 to ~0.05 µg/L and do not show prominent temporal variations. Model results are consistently within this range. However, the data are definitely impacted by changes in detection limits. For example, simulated tPCB values are greater than measured concentrations when the detection limits are lower and are less

than measured values when detection limits are higher. Overall, the simulated values are mostly greater than the measured concentrations. As described previously, this is likely a consequence of the differences between the actual watershed inputs and the simulated values.

#### 4.3 Model Results for Sediment PCB Concentrations

Daily and spatially averaged (over each of the nine FCM reaches) organic carbon (OC) normalized sediment tPCB concentrations over the 15-year simulation are shown in Figure 4.5. In five of the FCM reaches, sediment PCB exposure concentrations change by relatively small amounts (less than  $\pm 15\%$ ) over the 15-year simulation. Subreaches where simulated changes were outside this range are limited to Reaches 7D (221% increase), 7E (53% increase), 7F (109% increase), and 7G (48% decrease). The large increases in Reaches 7D, 7E, and 7F, and the large decrease in 7G are attributed, at least in part, to uncertainty in the initial conditions for sediment tPCB concentrations. There is more uncertainty in the initial conditions in the free-flowing reaches between the Columbia Mill, Willow Mill, Glendale Dam, and Rising Pond impoundments than in the impounded reaches because the sample density in the impoundments (reaches 7B, 7E, 7G and 8) was much higher than it was for the free-flowing reaches. Because of the limited number of samples collected in the free-flowing reaches, data in each of these reaches were aggregated to specify an average initial tPCB sediment concentration. Reach 7F has the smallest bed slope of the free-flowing reaches, and as such it is more conducive to deposition than the other free-flowing reaches. In fact, the increase in sediment tPCB concentrations simulated in Reaches 7D - 7F results from net deposition over the 15-year simulation in these reaches. The decrease in sediment tPCB concentrations in Reach 7G is strongly influenced by the small number of grid cells included in this FCM reach in comparison to the other reaches, and the occurrence of erosion in several of the upstream-most of these cells. These points are further discussed in Section 4.5.

#### 4.4 Evaluation of Model Performance

Figures 4.6 and 4.7 show plots (hereafter called cross-plots) of simulated versus measured TSS and tPCB concentrations, respectively. As discussed in Section 4.2, the differences between the measured and simulated TSS and tPCB concentrations shown in these figures are attributed, at least in part, to the following factors: a) phasing differences between the simulated results at Rising Pond Dam and the data collected from Division Street; and b) phasing and volumetric differences between the actual flows (from direct runoff and the seven represented tributaries in Reach 7) and HSPF-simulated flows. These factors probably account for a good portion of the differences where the simulated tPCB concentrations are, for example, lower than the measured values due to HSPF-simulated flows that are higher than actual flows, resulting in lower simulated tPCB concentrations due to dilution. The reverse situation, i.e., higher simulated tPCB values due to HSPF flows that are lower than actual flows, would likewise contribute to the observed differences.

As seen in Figure 4.6, a large number of model-data comparisons follow the one-to-one line, with simulated TSS values usually within a factor of two of the data. There is also a substantial group of model-data pairs that vary between approximately 2 and 15 mg/L, with corresponding simulated TSS concentrations falling within the narrow range of 2 to 4 mg/L. The regression of the simulated versus measured TSS concentrations is significantly influenced by this

data group because of the large number of points falling within this group. The simulated TSS values within this group could reflect a much smaller variability than the data due to a variety of causes, but a lot of the comparisons are negatively affected by the fact that, for the reasons stated previously, the simulated flow hydrographs typically did not increase as quickly as the actual hydrographs. The differences in the rates of increase of the rising limbs of the simulated and actual hydrographs would result in smaller quantities of sediment being resuspended (and thus correspondingly smaller TSS concentrations) during the simulated accelerating flows since sediment erosion is normally positively correlated with flow acceleration. At the upper end of the simulated TSS concentrations, the simulated concentrations are seen to typically exceed the measured concentrations. These high simulated TSS values occur during high flow events when phase differences between simulated and measured runoff hydrographs are more pronounced. All of these factors contribute to the low value of  $r^2 = 0.12$  shown in Figure 4.6.

The cross-plot of simulated and measured water column tPCB concentrations shown in Figure 4.7 includes only data for which sampling times were reported. The phasing and runoff volume issues related to the simulated versus actual watershed flows and loadings discussed previously for TSS concentrations is further exacerbated when the times of sampling at the Division Street gaging station were not recorded. This was the case for many of the tPCB concentrations in the Division Street database. As a result, these data could not be included in the cross-plot, which explains why  $N$ , the number of plotted data points, was only 67 in this cross-plot as compared to the value  $N = 257$  in the cross-plot for TSS. Approximately 60% of the tPCB data were non-detects (and are plotted using a less than symbol, i.e.,  $<$ , at the detection limit in Figure 4.7). Most of the simulated tPCB concentrations at the times when the sampling times were recorded were typically near the detection limit. One exception to this was a group of data collected in 1998 that had a relatively high detection limit of  $0.125 \mu\text{g/L}$ . Comparison of the simulated and measured tPCB concentrations shown in the cross-plot is even further complicated by the elevated detection limit for this group of data since the actual concentrations could be substantially lower, thus moving the plotted points closer to the one-to-one line. The fact that the simulated tPCB concentrations were cross-sectionally averaged values at the outlet of Rising Pond whereas the measured concentrations were obtained from a water sample collected at one point in the cross-section needs to be emphasized. The negative correlation found between the measured and simulated tPCB concentrations, as indicated by the negative slope of the regression line plotted in Figure 4.7, reflects the cumulative effect of all these factors. In conclusion, these model-data comparisons highlight the significant effects that factors such as detection limits and differences in the timing and runoff magnitudes of actual and simulated hydrographs can have on the comparison of simulated and measured water column tPCB concentrations.

Distributions of the probability of non-exceedance of simulated and measured TSS and tPCB concentrations are presented in Figures 4.8 and 4.9, respectively. As seen in Figure 4.8, for TSS concentrations less than  $10 \text{ mg/L}$  the simulated concentrations have less variability than the measured concentrations, with the exception being approximately the upper 5% of the TSS data, i.e., TSS concentrations greater than  $100 \text{ mg/L}$ . In Reaches 7 and 8, TSS concentrations above  $20 \text{ mg/L}$  occurred during increased flow conditions when watershed flow and loading related phasing issues are more pronounced. Thus, it is not unexpected that the measured and simulated probability distributions for TSS deviate more from each other for these higher concentrations.

The elevated tPCB detection limits for samples collected in 1998 along with the other factors discussed in relation to the tPCB cross-plot (Figure 4.7) complicate the comparison of the simulated and measured tPCB non-exceedance probability distributions shown in Figure 4.9 because the actual tPCB concentrations could be substantially lower. This would shift the measured concentrations above 0.04 µg/L to the right on the plot, i.e., they would occur less frequently, and result in a better agreement between the measured and simulated tPCB probability distributions.

Statistical summaries of the performance of the EFDC model for discharge, and for TSS and tPCB concentrations are presented in Tables 4.1a and 4.1b, respectively. The relative bias at Rising Pond outlet (0.50%) (see Table 4.1a) is very acceptable, especially for an uncalibrated and unvalidated model, as typical model performance measures for simulated discharge are on the order of  $\pm 10\%$ . Likewise, the median relative error of -2.1% for discharge is well within typical performance measures of  $\pm 10\%$ . These results indicate that there is negligible bias in the simulated discharges at the outlet of Rising Pond.

As shown in Table 4.1b, the relative bias at Rising Pond outlet is -61.4% for TSS and is equal to -71.1% for PCB concentrations. The phasing and volumetric differences between actual flows and the HSPF-simulated flows in Reach 7 are once again thought to be the main contributors to these relatively high relative bias values. Median relative errors of -28.3% for TSS and -14.4% for tPCB concentration were obtained. The fact that the relative bias values are larger than the median relative errors demonstrates the significant effect that the elevated tPCB detection limits for the samples collected in 1998 had. The relative bias is more directly impacted by outliers, in this case the data points involving the elevated detection limit, than a median-based statistic such as the median relative error, i.e., the median-based statistic is most robust to outliers than a mean-based one. As such, and after examining Figures 4.7 and 4.9, it was not unexpected that: 1) the relative bias values for tPCB would be relatively high since the elevated detection limit negatively skews these data points; and 2) the elevated detection limit would not affect the median relative error statistic as much.

#### 4.5 Process-Based Flux Summaries

Process-based annual average mass fluxes for solids and PCBs calculated by the EFDC model for Reaches 7 and 8 are presented in Figures 4.10 and 4.11 and summarized in Tables 4.2 and 4.3, respectively. The various mass fluxes in these summaries were not expected to balance exactly because of rounding/truncation in the summation of the mass fluxes across each cell face at each time step of the simulation. The residuals of the balances of the process-based annual average mass flux terms for solids and PCBs represent a small fraction (0.01 to 7.7%) of the total annual mass flux into each reach. The net residuals for solids and PCBs for the entire model domain, 48 MT/year and -0.22 Kg/year, respectively, represent 2.6% and 3.9%, respectively, of the net mass fluxes out of the domain. The net mass fluxes out of the domain were calculated as the net annual average mass fluxes out of Reach 8 minus the net mass fluxes into Reach 7A. These small percentages for the net residuals for both solids and PCBs indicate that the EFDC model adequately conserved mass of both solids and PCBs over the entire model domain as well as for each foodchain reach.

As indicated in Figures 4.10 and 4.11 and Tables 4.2 and 4.3, solids mass fluxes are dominated by the water column advective fluxes, and increase substantially in Reach 7D due to inputs from tributaries and direct runoff, both of which are simulated by HSPF. Spatial patterns of erosion reflect the armored bed conditions in the steep reaches (7A, 7C, upper half of 7D, and 7H). Milder slopes in the lower half of Reach 7D and in Reach 7F result in relatively high deposition and high erosion rates that produce a relatively small net erosion flux in Reach 7D and a small net deposition flux in Reach 7F. Although these two reaches have the smallest bottom slopes (i.e., gradients), relatively high erosion rates occur during the rising limbs of runoff hydrographs, when previously deposited sediments are rapidly eroded due to high bed shear stresses. Deposition on the floodplain is greatest in Reaches 7D and 7F where the floodplains are considerably wider than in the other reaches. Bedload mass fluxes of solids vary through the domain in response to the armoring conditions in the steeper reaches and the physical barriers of the dams.

Water column advective PCB mass fluxes do not vary substantially through Reaches 7 and 8, decreasing from 29 kg/yr at the upstream boundary to 25.5 kg/yr at the downstream boundary. PCB transport associated with bedload is a very small component of the overall PCB transport balance, with annual average fluxes of less than 0.005 kg/yr. PCB transport associated with sediment erosion is higher in the impoundments of Columbia Mill Dam (Reach 7B), Willow Mill Dam (Reach 7E), Glendale Dam (Reach 7G) and Rising Pond Dam (Reach 8) than in the steeper sloped free-flowing sections of the river. These higher PCB mass fluxes result from higher PCB concentrations in the sediments in the impoundments that are in turn related to higher fractions of fine sediment with higher organic carbon content. In Reaches 7D and 7F, PCB mass fluxes associated with erosion are comparable to those in the impoundment reaches because of the relatively higher rates of erosion during the rising limbs of runoff hydrographs.

As expected, depositional mass fluxes of PCBs are related to bed slope, with the highest rates in impoundments and in the lower gradient reaches of 7D and 7F. Generally, deposition rates on the floodplain are small, with the highest rates on the wider floodplains of the lower half of Reach 7D and in Reach 7F. Overall, volatilization losses represent approximately 11% of the PCB inputs entering at the upstream boundary of Reach 7, i.e., Woods Pond Dam. Volatilization losses from the river account for almost 90% of the total volatilization loss. The remainder is lost from water transported across the floodplains in Reaches 7D and 7F.

The process-based annual average mass flux summaries highlight the processes controlling solids and PCB transport through Reaches 7 and 8. The interactive effect of the highly variable bed slopes and solids composition characteristics of the free-flowing sections and impoundments is seen in the relative magnitude of the various mass fluxes in these different reaches. For example, although Reaches 7D and 7F have relatively high solids erosion rates, the lower PCB concentrations in these long free-flowing sections result in PCB mass fluxes that are less than the PCB mass fluxes in the relatively short impoundment reaches, where higher fractions of fine-grained sediment are found. These mass flux summaries for both solids and PCBs provide an additional tool for understanding the major physicochemical processes controlling PCB transport and fate in Reaches 7 and 8.



**Table 4.1a**

Statistical Evaluation of EFDC Model Performance for Flow  
January 1990 – December 2004

Statistical Summary of EFDC Model Performance										
Station	No. of Data (n)	Average of Data	Model Bias Arithmetic	Model Bias Geometric (%)	Relative Bias (%)	Mean Absolute Error (%)	Median Relative Error (%)	Regression of Simulated vs. Measured Values		
								Slope	Y-Intercept	Coefficient of Determination (r <sup>2</sup> )
Flow (cms)										
Rising Pond Outlet	108263	15.6	0.08	0.99	0.50	3.8	-2.1	0.93	0.07	0.87

Definitions:

$$\text{Model Bias (Arithmetic)} = \bar{Y} - \bar{X} \quad \text{Model Bias (Geometric)} = 10^{\left[\frac{\sum \log(Y_i / X_i)}{n}\right]} \quad \text{Relative Bias} = \frac{\bar{Y} - \bar{X}}{\bar{X}}$$

$$\text{Mean Absolute Error} = \frac{1}{n} \sum_{i=1}^n |Y_i - X_i| \quad \text{Relative Error} = (Y_i - X_i) / X_i \quad r^2 = \frac{\sum \left( \hat{Y} - \bar{Y} \right)^2}{\sum \left( Y - \bar{Y} \right)^2}$$

Y = Model, X = Data,  $\bar{Y}$  = Average of Y,  $\bar{X}$  = Average of X,  $\hat{Y}$  = Estimate from regression

**Table 4.1b**

**Statistical Evaluation of EFDC Model Performance for TSS and tPCB  
January 1990 – December 2004**

Statistical Summary of EFDC Model Performance										
Station	No. of Data (n)	Average of Data	Model Bias Arithmetic	Model Bias Geometric (%)	Relative Bias (%)	Mean Absolute Error	Median Relative Error (%)	Regression of Simulated vs. Measured Values		
								Slope	Y-Intercept	Coefficient of Determination (r <sup>2</sup> )
<b>TSS (mg/L)</b>										
Rising Pond Outlet	265	20.3	-12.5	0.63	-61.4	17.1	-28.3	0.25	1.1	0.12
<b>PCB (µg/L)</b>										
Rising Pond Outlet	156	0.11	0.49	0.77	-71.1	0.09	-14.4	-0.15	-4.0	0.04

Table 4.2

Process-Based Annual Average Mass Flux Summary Tabulation for Solids

Channel/Floodplain Process	Solids Flux (MT/yr)								
	7A	7B	7C	7D	7E	7F	7G	7H	8
<b>Channel Water Column Sources</b>									
Advection	2465	2404	2449	2519	4036	4358	4599	4470	4454
Bed load	0	5	0	15	0	0	96	0	0
Import from Floodplain	0	63	45	0	0	-545	0	0	0
HSPF Tributary and Surface Runoff	196	0	0	1911	0	644	0	0	0
Erosion	10	293	79	2337	651	4836	205	18	232
<b>Sum</b>	<b>2661</b>	<b>2765</b>	<b>2573</b>	<b>6782</b>	<b>4687</b>	<b>9293</b>	<b>4900</b>	<b>4488</b>	<b>4686</b>
<b>Channel Water Column Sinks</b>									
Downstream Advection	2404	2449	2519	4036	4358	4599	4470	4454	4300
Bed load	5	0	15	0	0	96	0	0	0
Export to Floodplain	252	0	0	96	-176	0	-10	14	26
Deposition	10	317	39	2651	506	4599	441	20	361
<b>Sum</b>	<b>2671</b>	<b>2766</b>	<b>2573</b>	<b>6783</b>	<b>4688</b>	<b>9301</b>	<b>4901</b>	<b>4488</b>	<b>4687</b>
<b>Floodplain Water Column Sources</b>									
Import from Channel	252	0	0	95	-176	0	-10	14	26
Overland Flow	0	77	0	0	0	1	0	13	0
Erosion	21	12	6	14	0	164	0	14	0
<b>Sum</b>	<b>273</b>	<b>89</b>	<b>6</b>	<b>109</b>	<b>-176</b>	<b>165</b>	<b>-10</b>	<b>41</b>	<b>26</b>
<b>Floodplain Water Column Sinks</b>									0
Export to Channel	0	63	45	0	0	-545	0	0	0
Overland Flow	77	0	0	0	1	0	13	0	0
Deposition	7	30	5	124	0	633	0	18	0
<b>Sum</b>	<b>84</b>	<b>93</b>	<b>50</b>	<b>124</b>	<b>1</b>	<b>88</b>	<b>13</b>	<b>18</b>	<b>0</b>
<b>Reach Residual</b>	<b>179</b>	<b>-5</b>	<b>-44</b>	<b>-16</b>	<b>-178</b>	<b>69</b>	<b>-24</b>	<b>23</b>	<b>25</b>

Table 4.3

Process-Based Annual Average Mass Flux Summary Tabulation for PCBs

Channel / Floodplain Process	PCB Flux (kg/yr)								
	7A	7B	7C	7D	7E	7F	7G	7H	8
<b>Channel Water Column Sources</b>									
Advection	33.8	32.0	33.7	33.6	30.0	30.3	27.2	28.5	28.0
Bed load	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Import from Floodplain	0.0	1.34	0.0	0.0	0.0	-0.71	0.22	0.0	0.0
Diffusion	0.0	0.08	0.01	0.08	0.01	0.06	0.05	0.01	0.20
Erosion	0.0	0.80	0.12	0.18	0.55	0.61	1.38	0.01	0.79
<b>Sum</b>	<b>33.8</b>	<b>34.22</b>	<b>33.83</b>	<b>33.86</b>	<b>30.56</b>	<b>30.26</b>	<b>28.85</b>	<b>28.52</b>	<b>28.99</b>
<b>Channel Water Column Sinks</b>									
Downstream Advection	32.0	33.7	33.6	30.0	30.3	27.2	28.5	28.0	28.2
Bed load	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0
Export to Floodplain	1.38	0.0	0.0	0.26	-0.15	0.0	0.0	0.0	0.0
Volatilization	0.37	0.17	0.20	1.02	0.06	0.69	0.06	0.50	0.29
Deposition	0.02	0.35	0.04	2.58	0.35	2.36	0.30	0.01	0.39
<b>Sum</b>	<b>33.77</b>	<b>34.22</b>	<b>33.84</b>	<b>33.84</b>	<b>30.56</b>	<b>30.25</b>	<b>28.86</b>	<b>28.51</b>	<b>28.88</b>
<b>Floodplain Water Column Sources</b>									
Import from Channel	1.38	0.0	0.0	0.26	-0.15	0.0	0.0	0.0	0.0
Overland Flow	0.0	1.43	0.0	0.0	0.0	0.0	0.30	0.05	0.0
Diffusion	0.0	0.0	0.0	0.12	0.0	0.10	0.0	0.0	0.0
Erosion	0.0	0.01	0.01	0.13	0.0	0.11	0.0	0.0	0.0
<b>Sum</b>	<b>1.38</b>	<b>1.44</b>	<b>0.01</b>	<b>0.51</b>	<b>-0.15</b>	<b>0.21</b>	<b>0.30</b>	<b>0.05</b>	<b>0.0</b>
<b>Floodplain Water Column Sinks</b>									
Export to Channel	0.0	1.34	0.0	0.0	0.0	-0.71	0.22	0.0	0.0
Overland Flow	1.43	0.0	0.0	0.0	0.0	0.30	0.05	0.0	0.0
Volatilization	0.0	0.01	0.0	0.14	0.0	0.21	0.0	0.0	0.0
Deposition	0.0	0.03	0.01	0.33	0.0	0.69	0.0	0.01	0.0
<b>Sum</b>	<b>1.43</b>	<b>1.38</b>	<b>0.01</b>	<b>0.47</b>	<b>0.0</b>	<b>0.49</b>	<b>0.27</b>	<b>0.01</b>	<b>0.0</b>
<b>Reach Residual</b>	<b>-0.02</b>	<b>0.06</b>	<b>0.01</b>	<b>0.06</b>	<b>-0.15</b>	<b>-0.27</b>	<b>0.02</b>	<b>0.05</b>	<b>0.11</b>

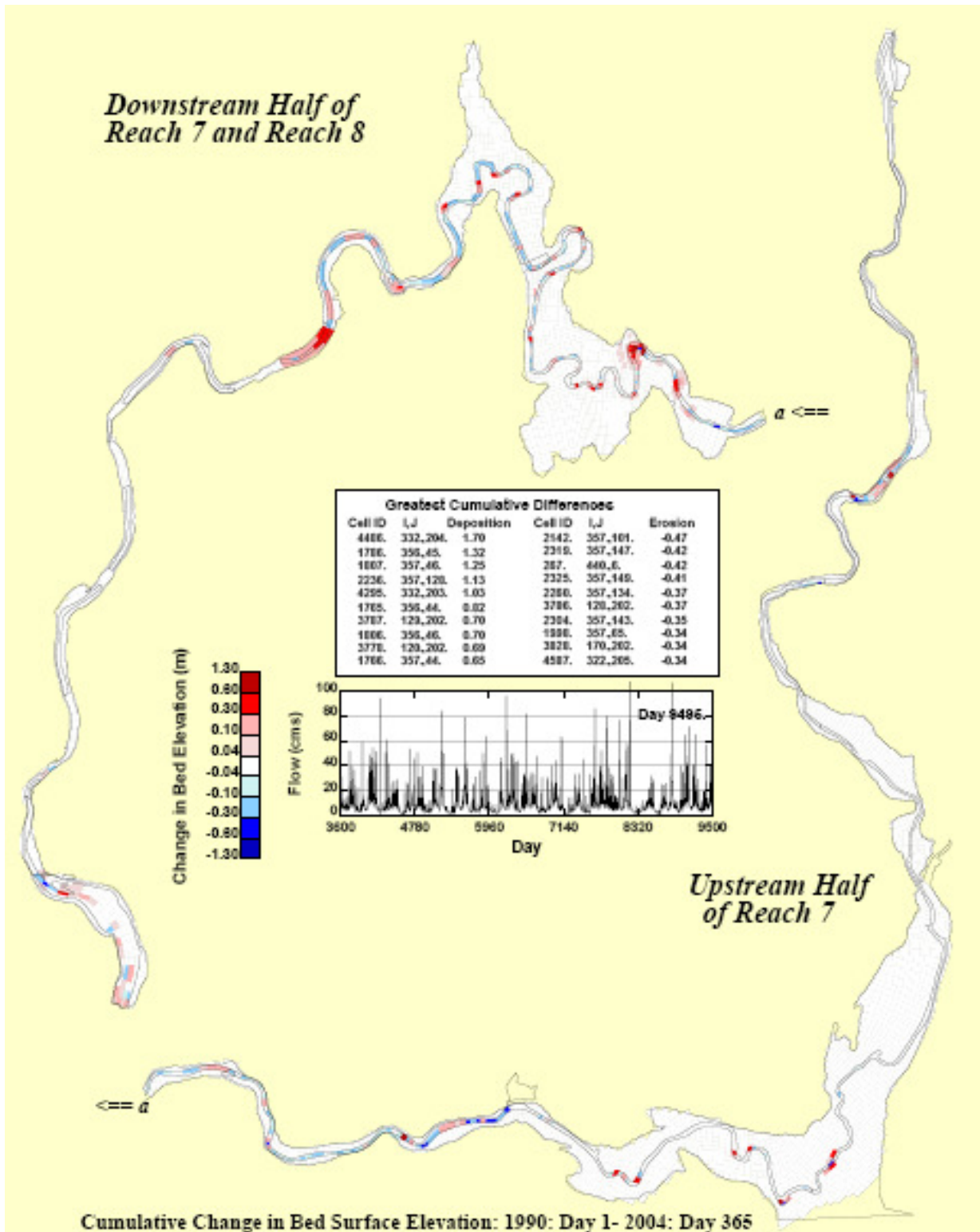


Figure 4.1 Cumulative Change in Bed Surface Elevations over 15-year Simulation

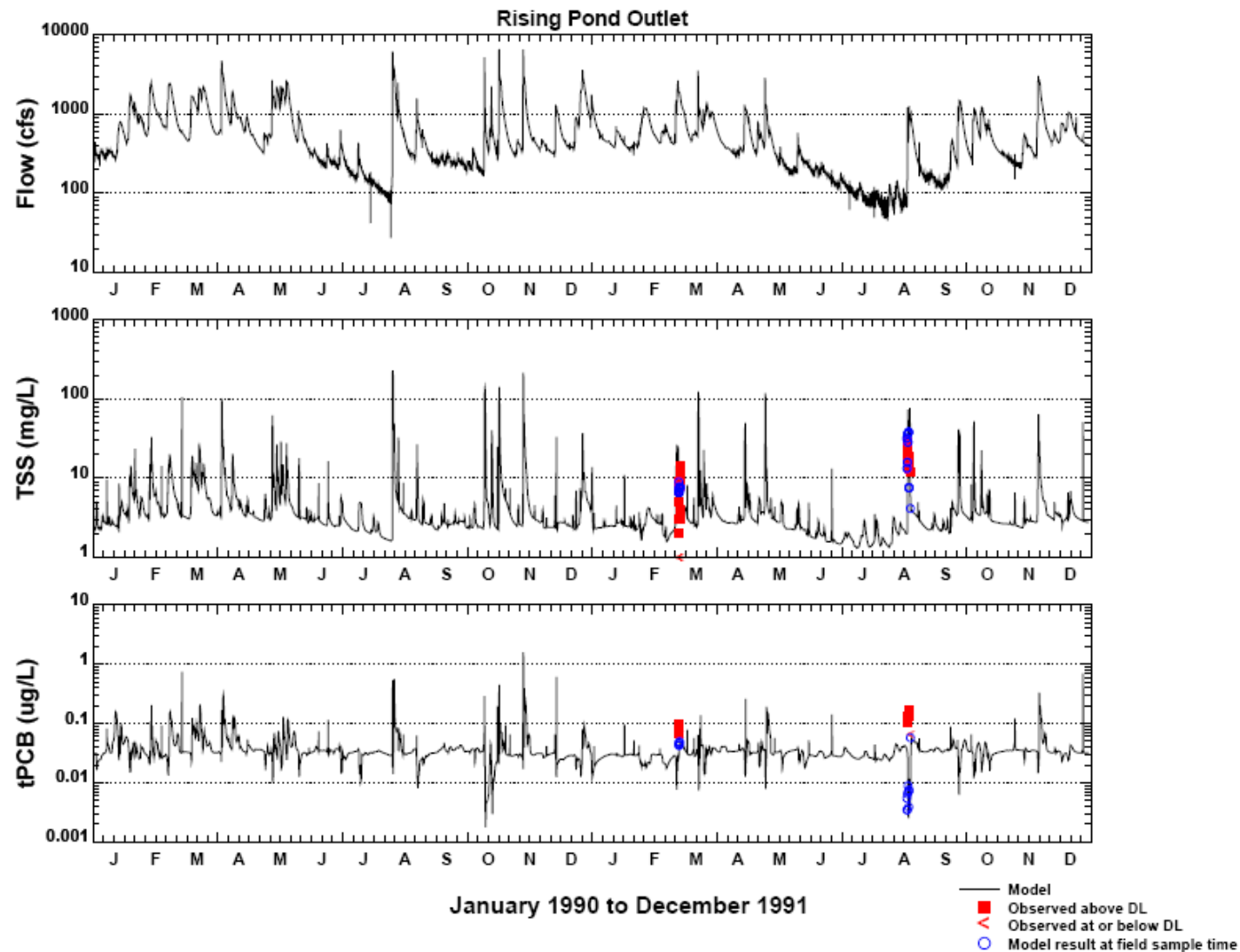


Figure 4.2a Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for 1990-1991. DL = detection limit

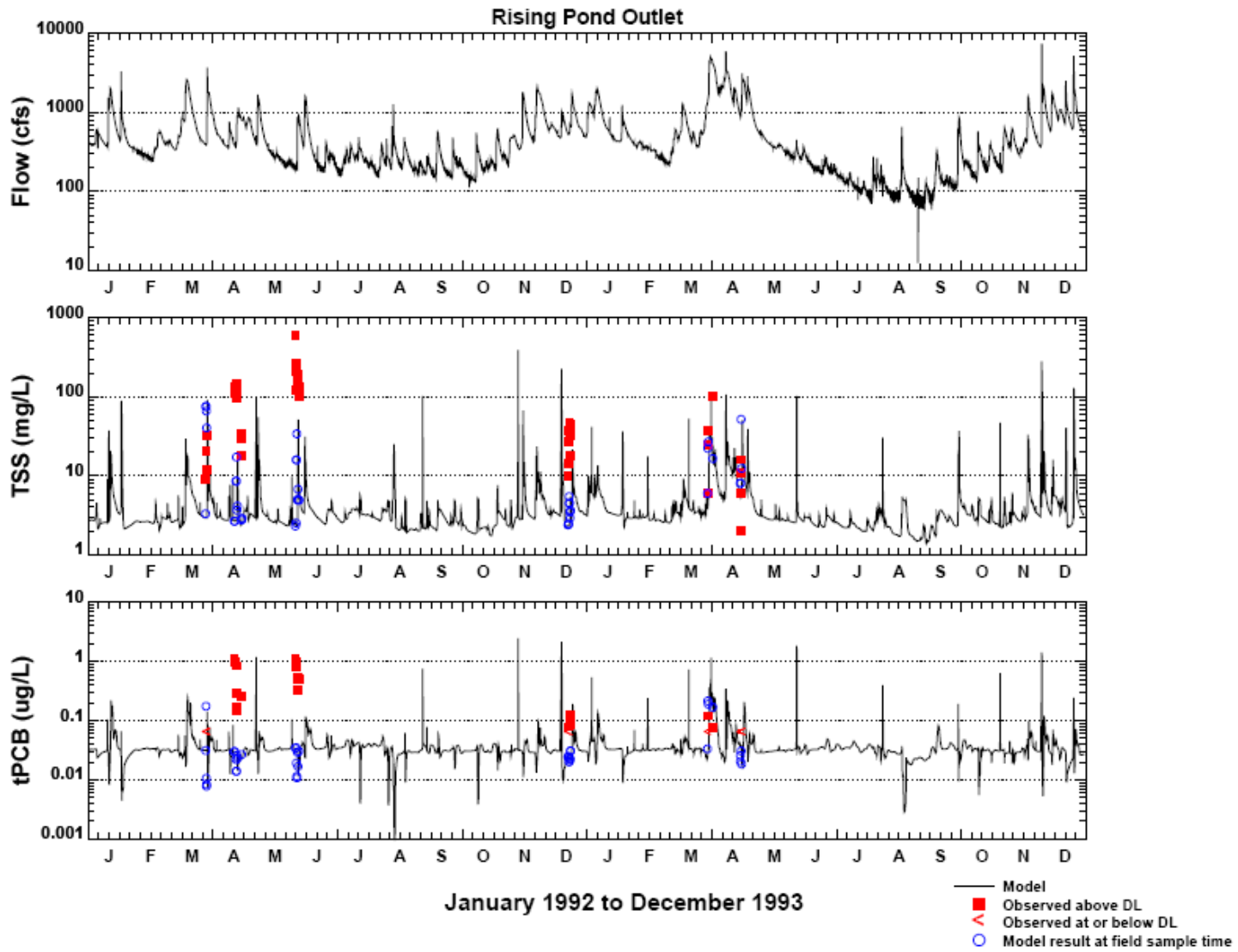


Figure 4.2b Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for 1992-1993. DL = detection limit

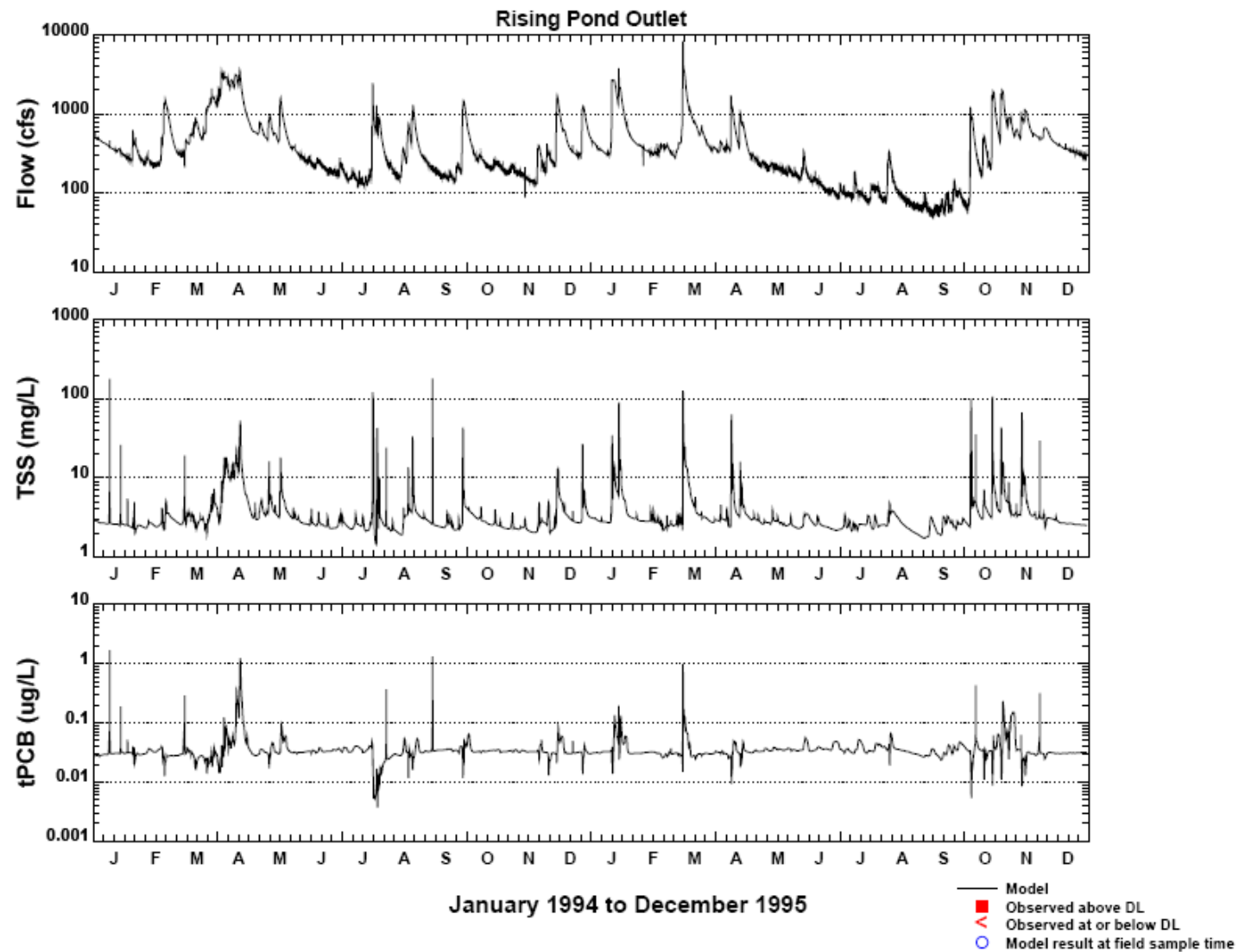


Figure 4.2c Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for 1994-1995. DL = detection limit



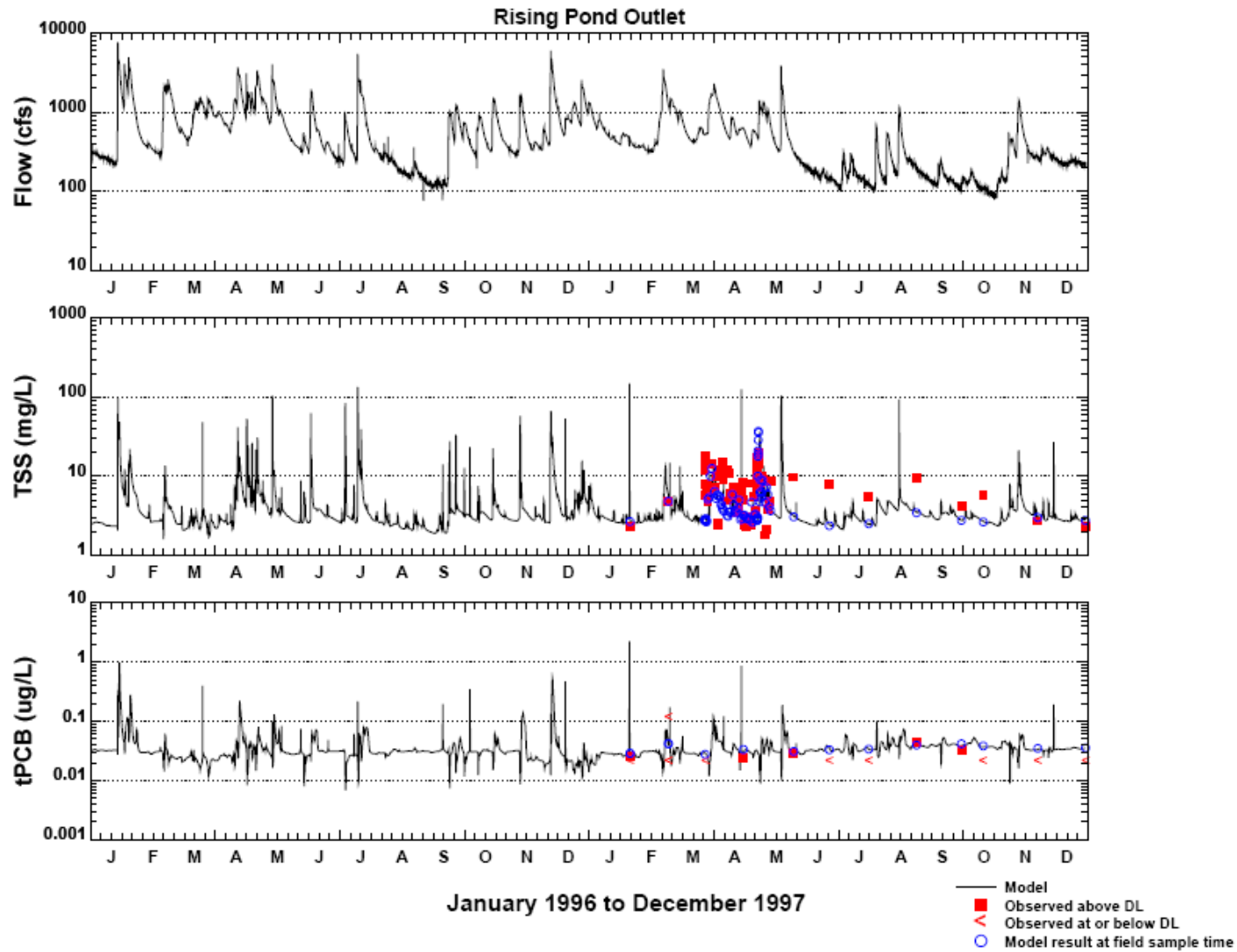


Figure 4.2d Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for 1996-1997. DL = detection limit

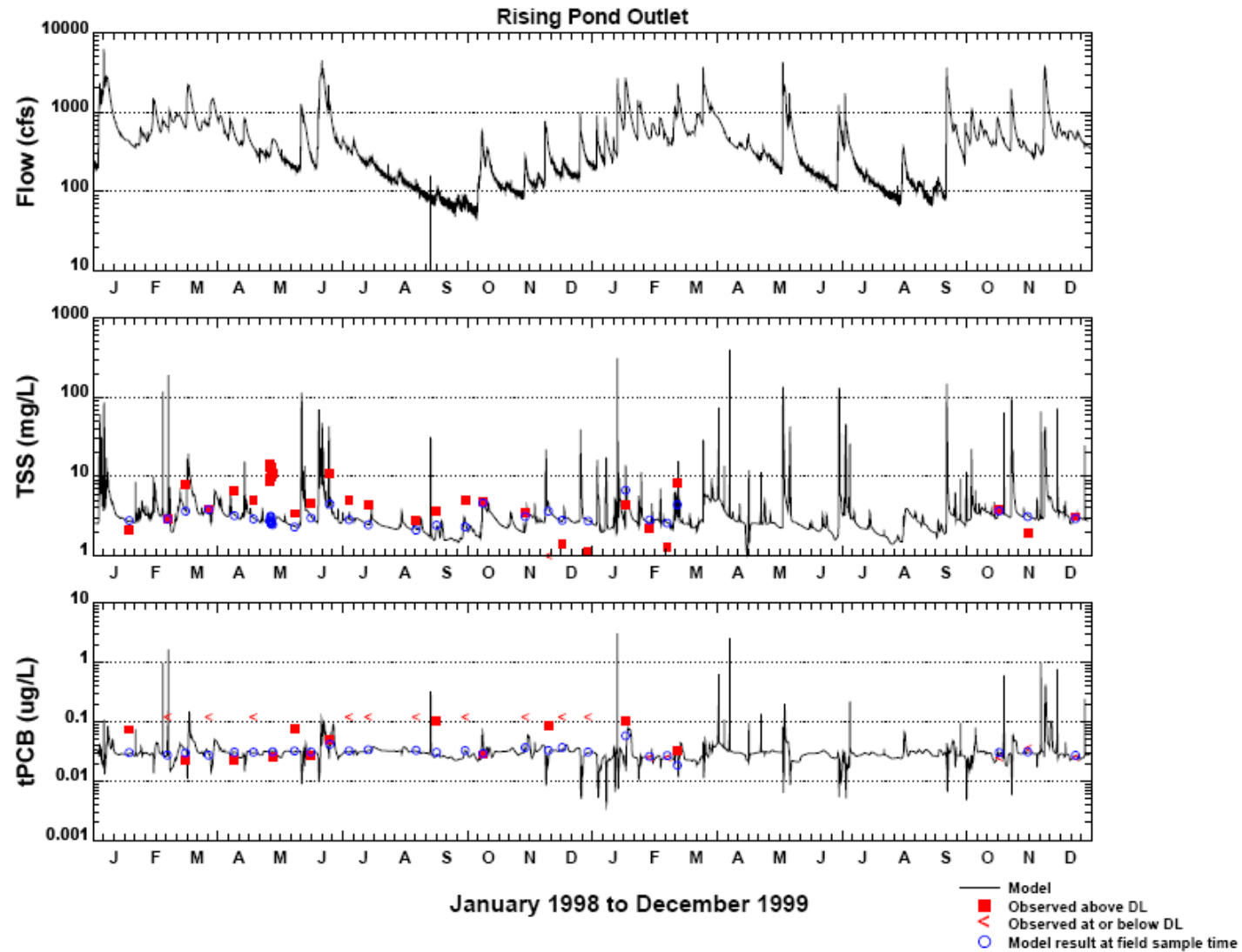


Figure 4.2e Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for 1998-1999. DL = detection limit

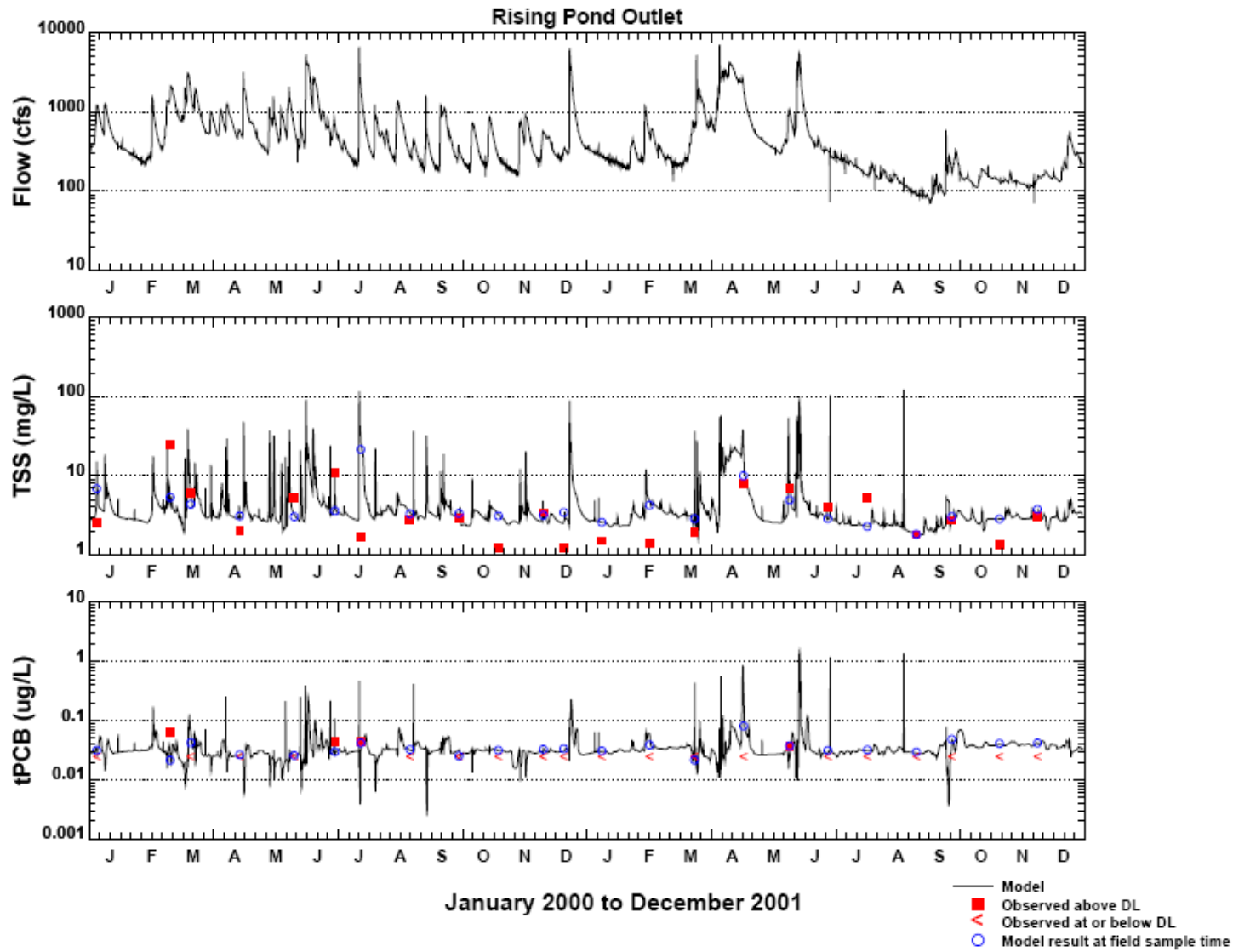


Figure 4.2f Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for 2000-2001. DL = detection limit

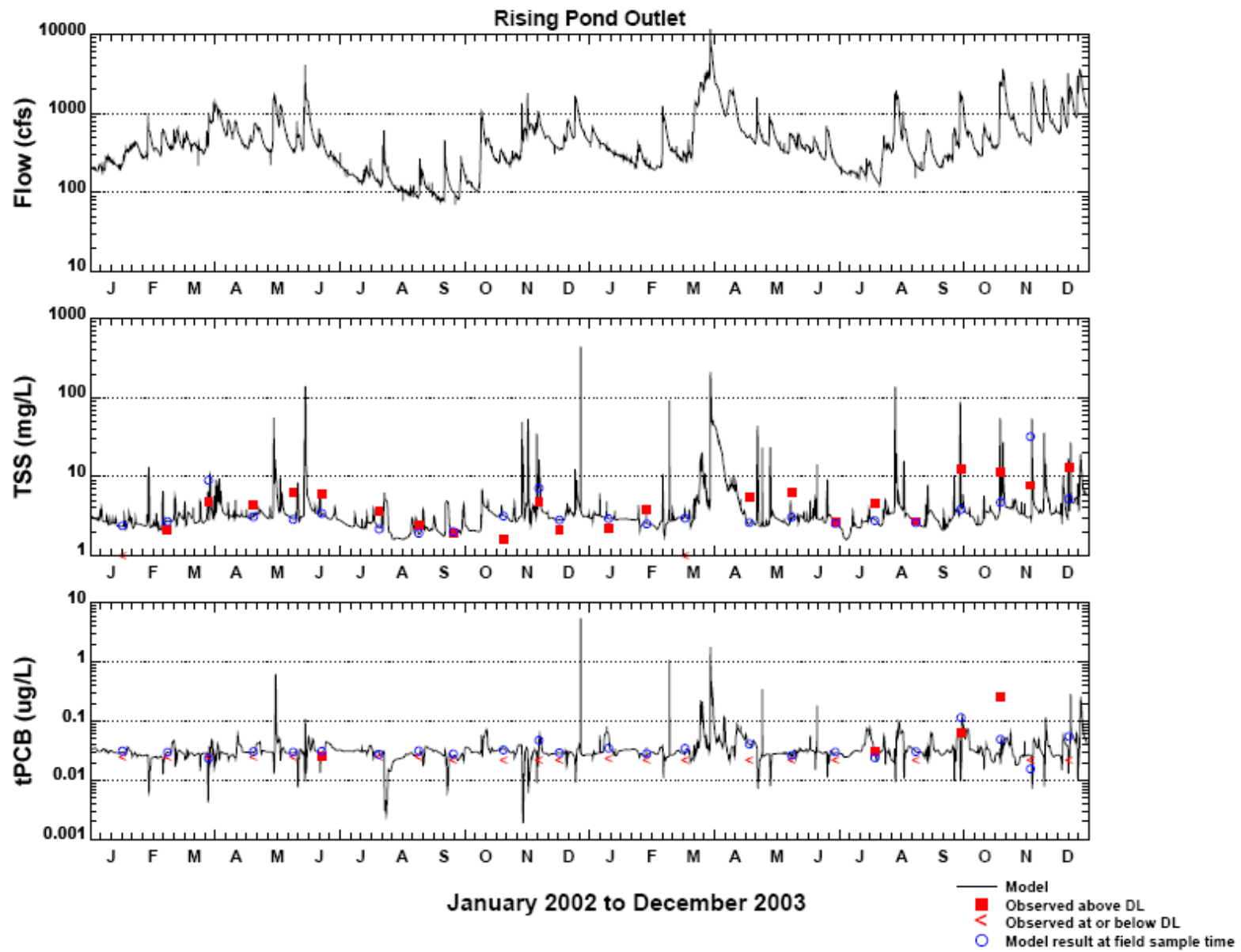


Figure 4.2g Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for 2002-2003. DL = detection limit

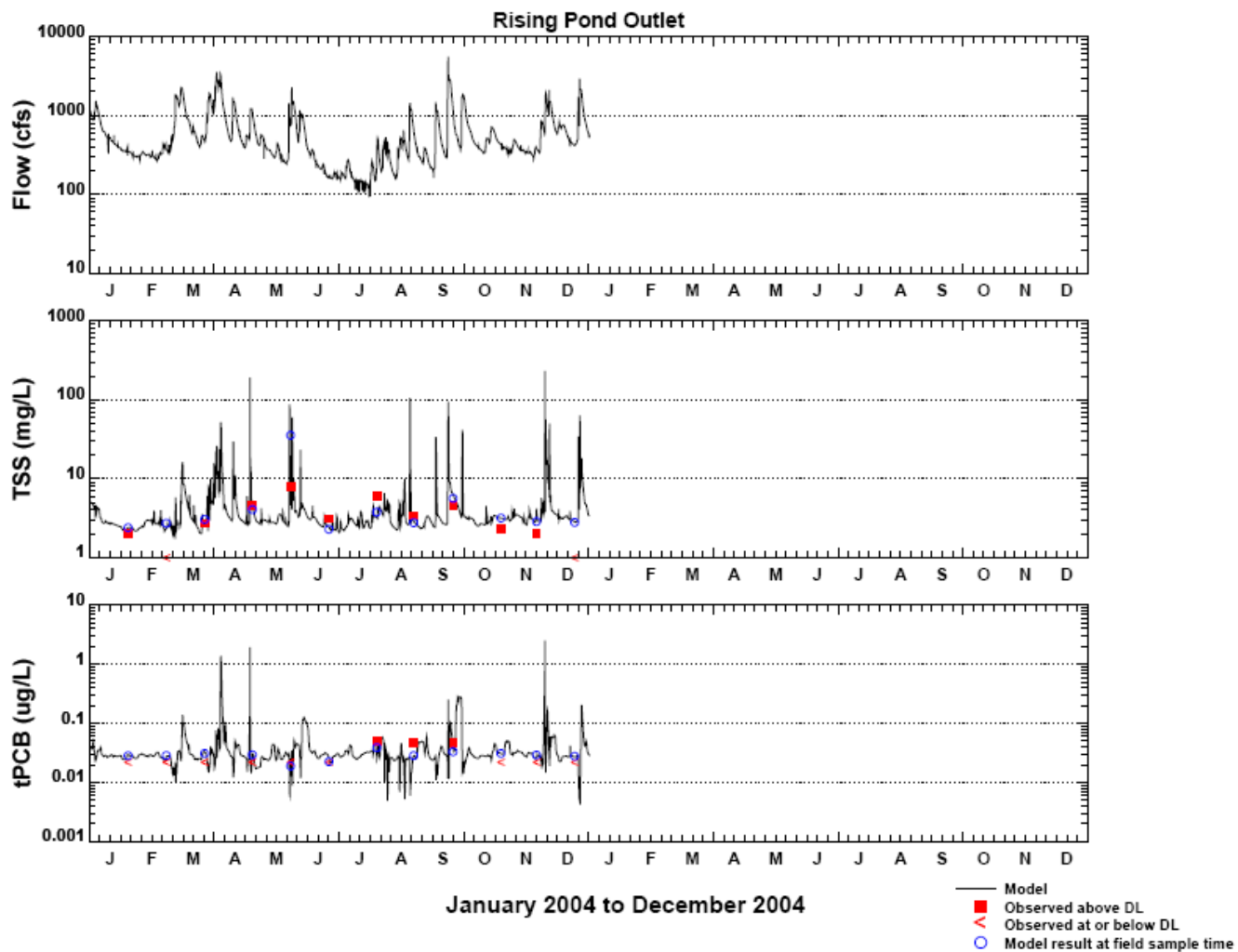


Figure 4.2h Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for 2004. DL = detection limit

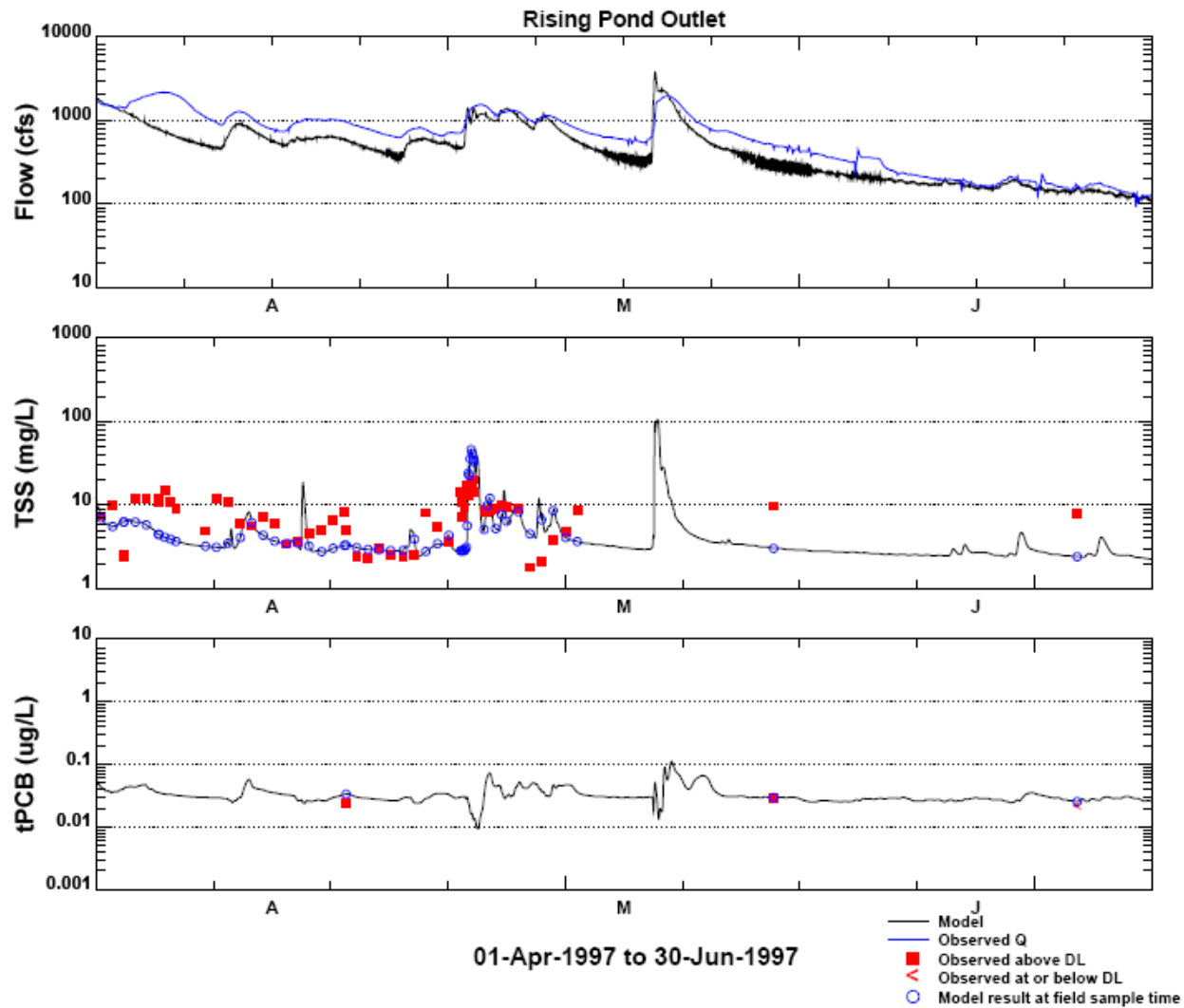


Figure 4.3 Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for April – June 1997. DL = detection limit

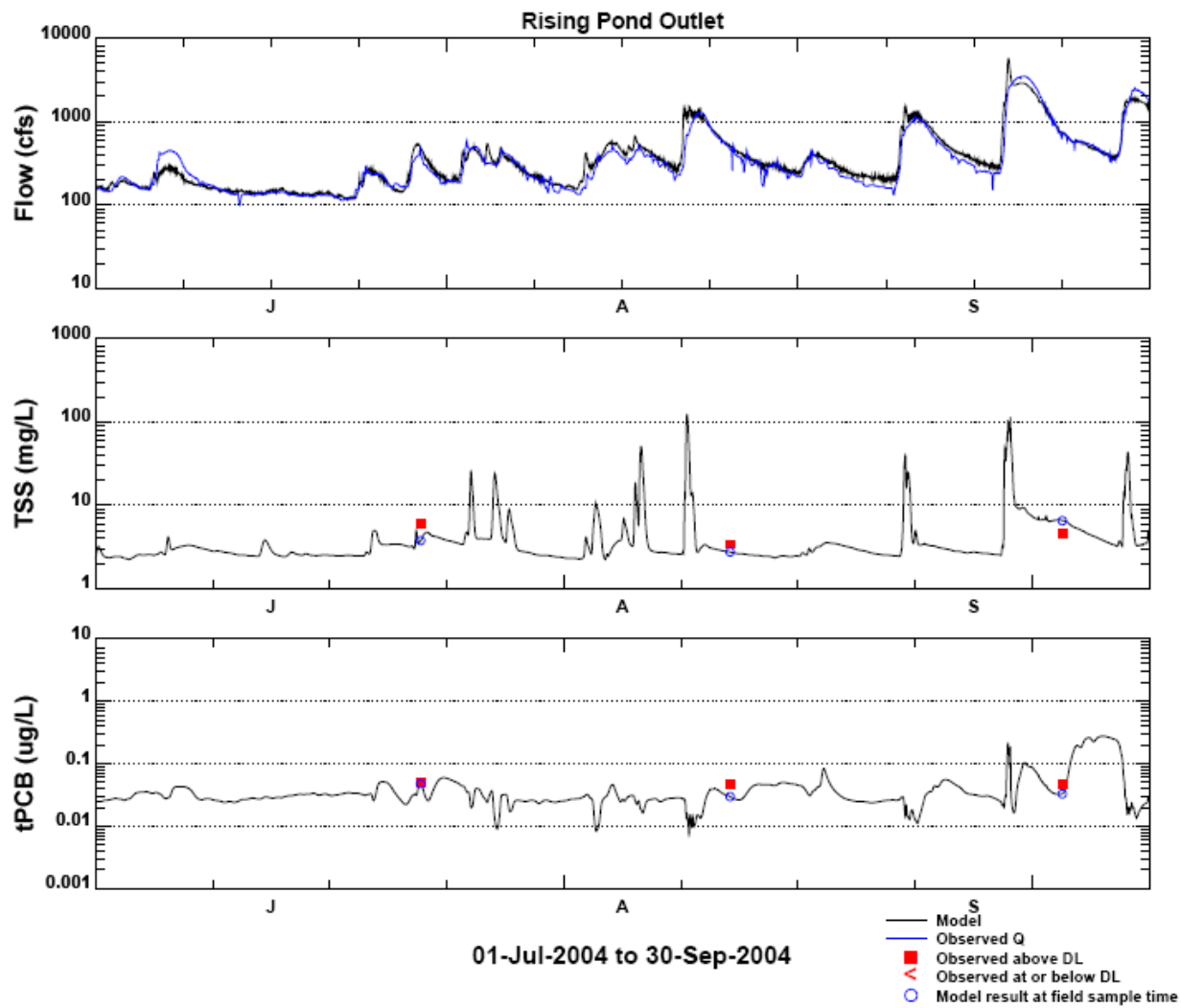


Figure 4.4 Comparison of Simulated (Solid Line) and Measured (Red Symbols) TSS and tPCB Concentrations in the Water Column for July – September 2004. DL = detection limit

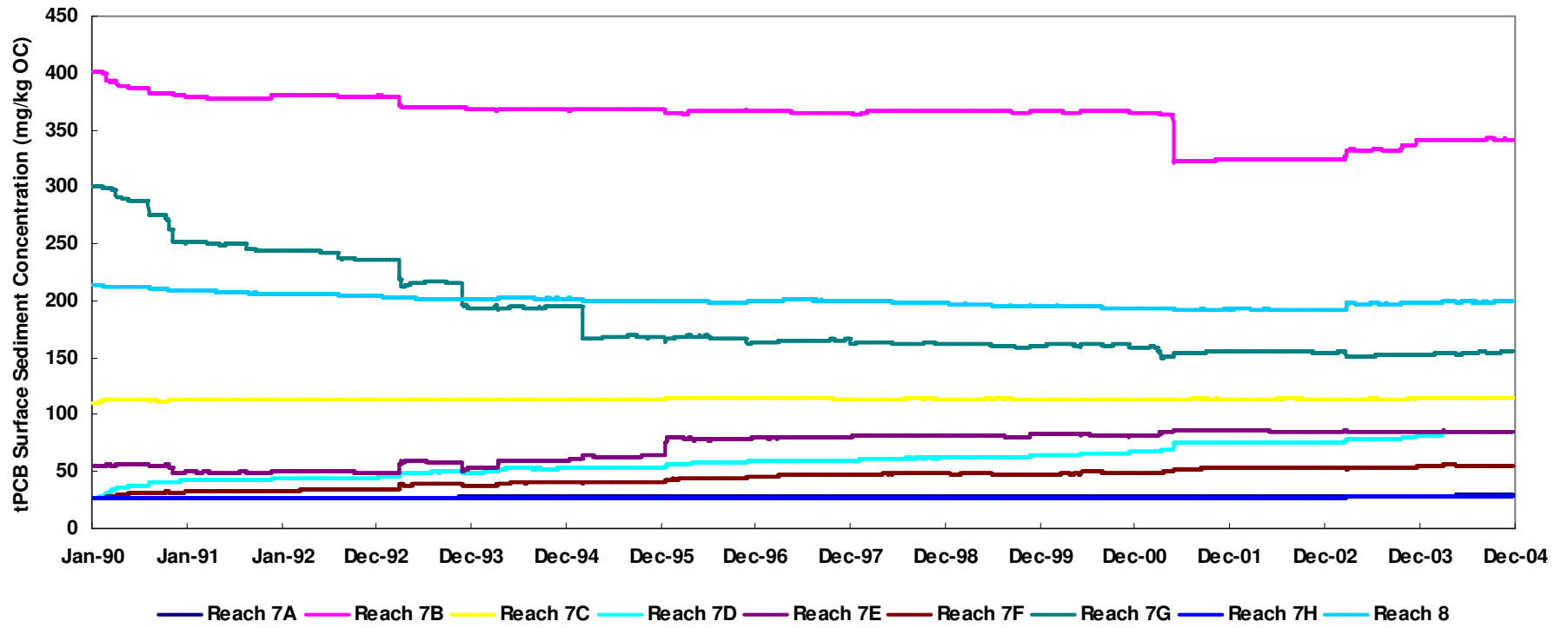
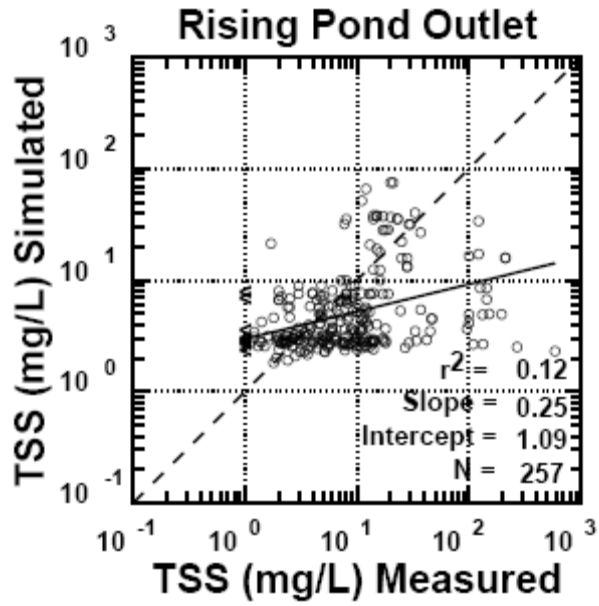


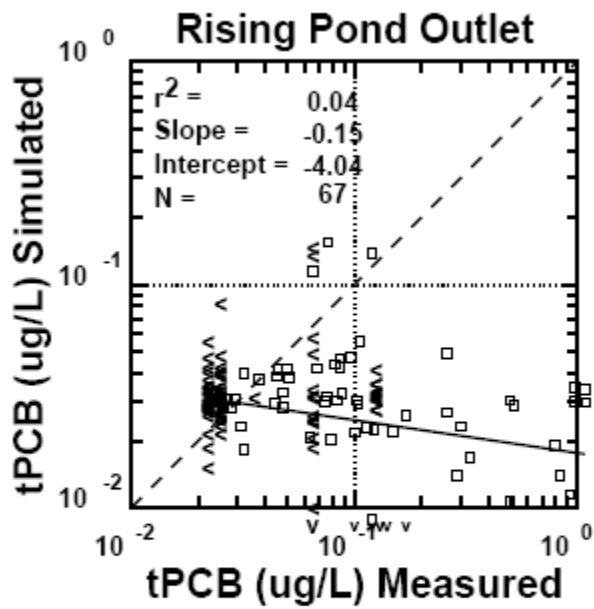
Figure 4.5 Temporal Trend of tPCB Concentrations in Surface Sediments for Foodchain Reaches





Note: Statistics evaluated on log-transformed values  
Non-Detects Excluded from regression  
N = Number of data points excluding non-detects

Figure 4.6 Cross-Plot of Simulated and Measured TSS Concentrations



Note: Statistics evaluated on log-transformed values  
 Non-Detects Excluded from regression  
 N = Number of data points excluding non-detects

Figure 4.7 Cross-Plot of Simulated and Measured tPCB Concentrations

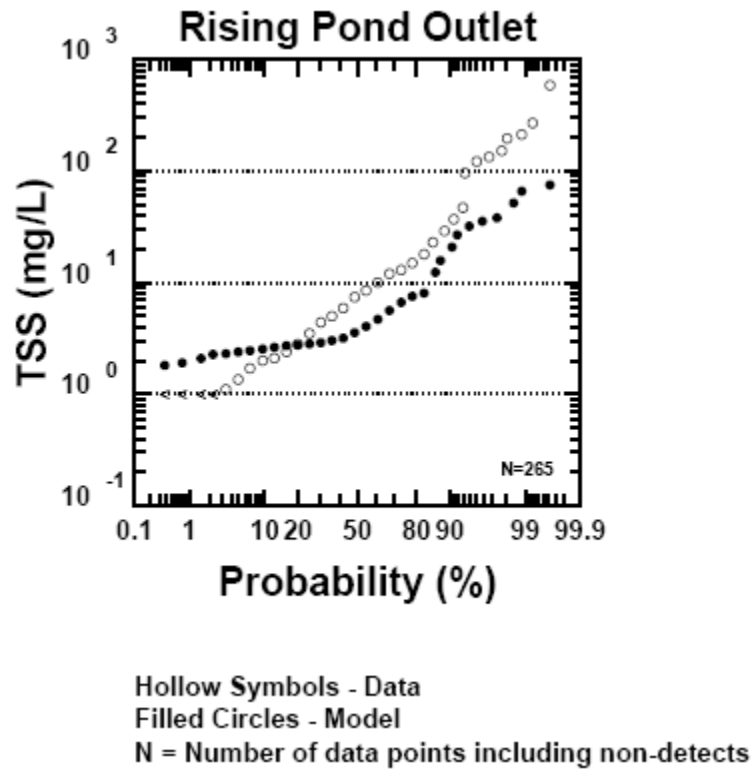
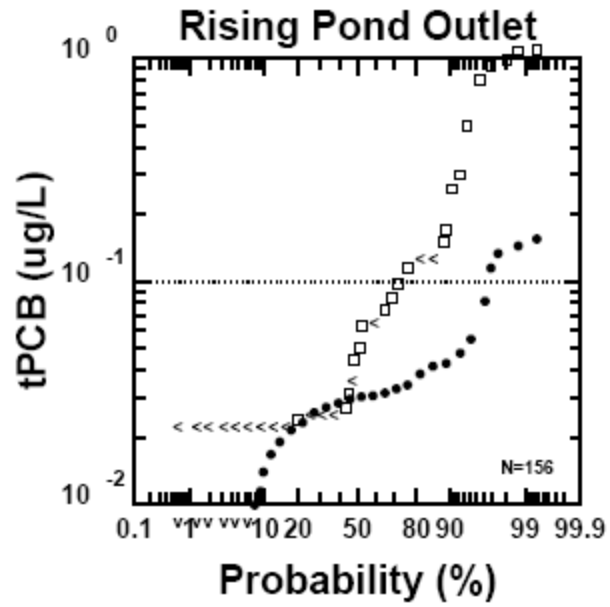


Figure 4.8 Probability Distributions of Simulated and Measured TSS Concentrations

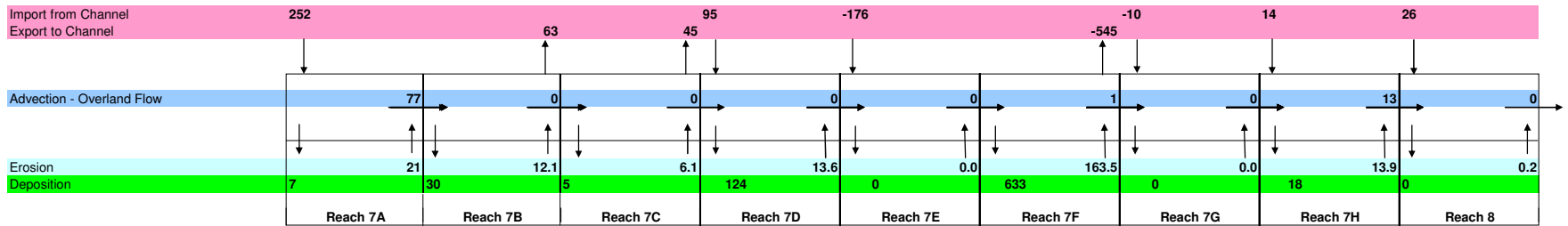


Hollow Symbols - Data  
 Filled Circles - Model  
 N = Number of data points including non-detects

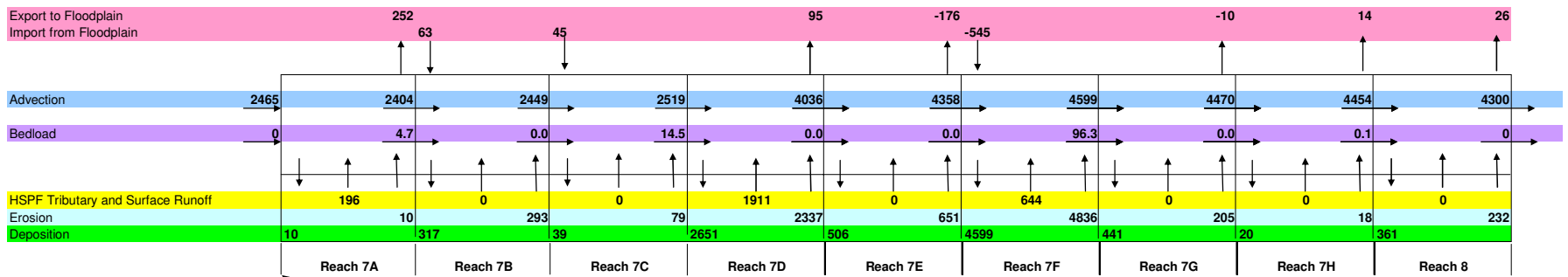
Figure 4.9 Probability Distributions of Simulated and Measured tPCB Concentrations

**Solids Mass Flux (MT/year) Summary - Downstream Model Run (1990 - 2004)**

**Floodplain**



**Main Channel**



**Numerical Residuals (MT/year)**

- Reach 7A Main Channel and Floodplain 190
- Reach 7B Main Channel and Floodplain -5
- Reach 7C Main Channel and Floodplain -45
- Reach 7D Main Channel and Floodplain -17
- Reach 7E Main Channel and Floodplain -176
- Reach 7F Main Channel and Floodplain 74
- Reach 7G Main Channel and Floodplain -10
- Reach 7H Main Channel and Floodplain -3
- Reach 8 Main Channel and Floodplain 39
- Downstream Model Domain 48

190 Woods Pond Dam

Columbia Mill Dam

Willow Mill Dam

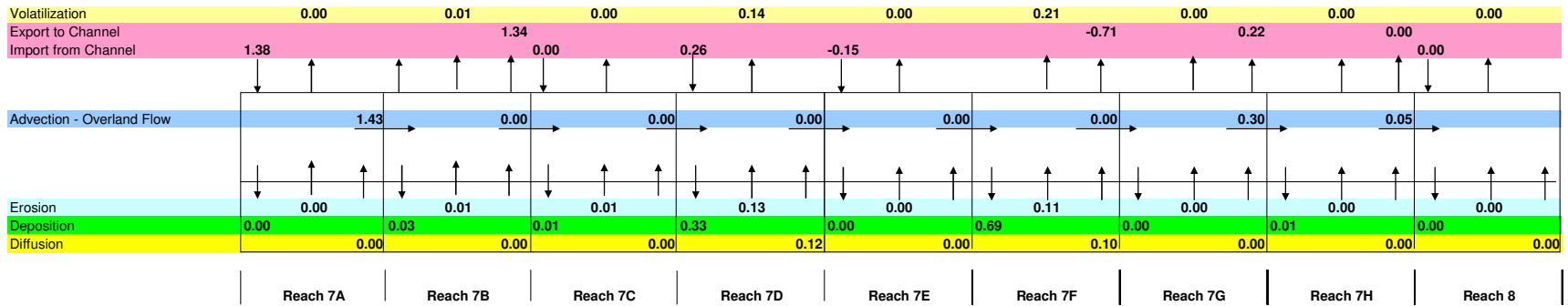
Glendale Dam

Rising Pond Dam

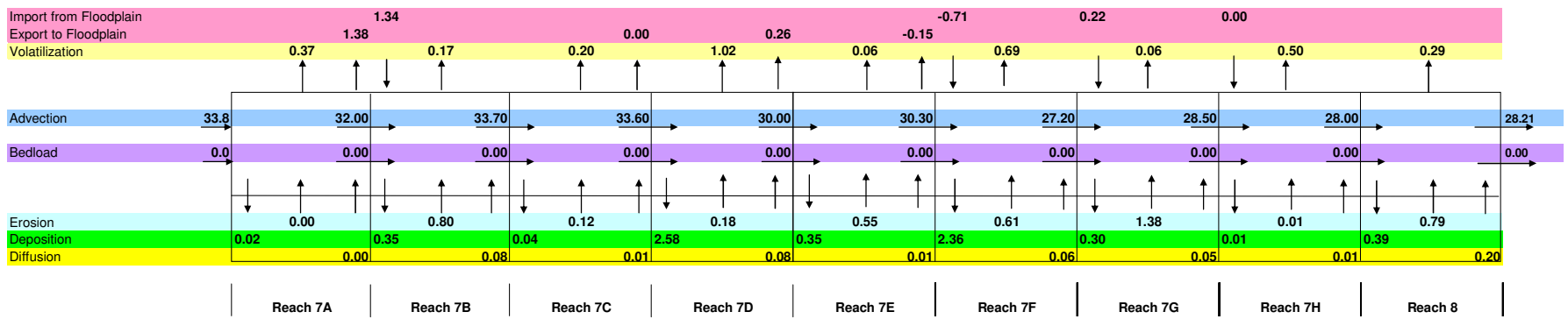
Figure 4.10 Process-Based Annual Average Mass Flux Summary for Solids

**PCB Mass Flux (Kg/year) Summary - Downstream Model Run (1990 - 2004)**

**Floodplain**



**Main Channel**



**Numerical Residuals (Kg/year)**

Reach 7A Main Channel & Floodplain	-0.049
Reach 7B Main Channel & Floodplain	0.061
Reach 7C Main Channel & Floodplain	-0.002
Reach 7D Main Channel & Floodplain	0.027
Reach 7E Main Channel & Floodplain	-0.148
Reach 7F Main Channel & Floodplain	0.022
Reach 7G Main Channel & Floodplain	-0.518
Reach 7H Main Channel & Floodplain	0.237
Reach 8 Main Channel & Floodplain	0.153
Downstream Model Domain	-0.216



Figure 4.11 Process-Based Annual Average Mass Flux Summary for PCBs

## 5 CONCLUSIONS

As stated in Section 1, the purpose of this modeling effort was to evaluate the ability of EFDC, a state-of-the-art contaminated sediment modeling system, to simulate the transport and fate of a contaminant over a time period of at least 10 years. Evaluation of the results of a 15-year simulation using the uncalibrated and unvalidated EFDC model indicate that this model is capable of satisfactorily simulating the transport and resultant concentrations of TSS and PCBs in Reaches 7 and 8 of the Housatonic River. The relative bias for the simulated discharges at the outlet of Rising Pond (0.50%) is very acceptable, as typical model performance measures for discharge are on the order of  $\pm 10\%$ . Likewise, the median relative error of -2.1% for discharge is well within typical performance measures of  $\pm 10\%$ . These results indicate that there is negligible bias in the simulated discharges at the outlet of Rising Pond. The relative bias at the outlet of Rising Pond is -61.4% for TSS and -71.1% for PCB concentrations. The phasing and volumetric differences between actual flows and the HSPF-simulated flows in Reach 7 are once again thought to be the main contributors to these relatively high relative bias values. Median relative errors of -28.3% were obtained for TSS and -14.4% for tPCB concentration. Since the relative bias is more directly impacted by outliers, in this case the data points involving the elevated detection limit for samples collected in 1998, than a median-based statistic such as the median relative error, the higher relative bias values were expected.

Process-based annual average mass fluxes for solids and PCBs were calculated. Residuals of the mass balances of the annual average mass flux terms for solids and PCBs were also calculated for all nine foodchain reaches. The residuals represent a small fraction (0.01 to 7.7%) of the total annual mass flux into each foodchain reach. The net residuals for solids and PCBs for the entire model domain, 48 MT/year and -0.22 Kg/year, respectively, represent 2.6% and 3.9%, respectively, of the net mass fluxes out of the domain. These small percentages for the net residuals for both solids and PCBs indicate that the EFDC model adequately conserved mass of both solids and PCBs over the entire model domain.

Considering the fact that the model was not recalibrated for Reaches 7 & 8, and that the system modeled had widely varying hydraulic and morphologic regimes, the EFDC model's overall performance is considered satisfactory. This demonstrates that EFDC is a robust modeling system that can be successfully implemented at contaminated sediment sites when sufficient data have been obtained to properly calibrate and validate the model.

# APPENDIX A

## Sediment Properties and Transport

### A.1 Sediment Properties

Sediments are weathered rock material that are transported, suspended or deposited by flowing water. All constituents of the parent rock material are usually found in the sediment. Quartz, because of its greater stability, is by far the most common material found in sediments. However, numerous other minerals (e.g., shale, carbonate particles, feldspar, igneous and metamorphic rocks, magnetite) also usually present. Even when material other than quartz particles is present in sediment, the average particle density of sediment is usually very close to that of quartz –  $2.65 \text{ gm/cm}^3$ . The specific gravity of sediment is defined as the ratio of the sediment particle density to the density of water at  $4^\circ\text{C}$  (i.e.,  $1.0 \text{ gm/cm}^3$ ), and thus has an average value of 2.65.

Sediment diameter is denoted as  $D$ , and has dimensions of length. Since sediment particles are rarely exactly spherical, the definition of diameter requires elaboration. For sufficiently coarse particles,  $D$  is often defined to be the dimension of the smallest square mesh opening through which the particle will pass. For finer particles,  $D$  usually denotes the diameter of the equivalent sphere with the same fall (or settling) velocity as the actual particle. A sediment gradation scale (given in Appendix B) has been established to classify sediment in size classes, ranging from very fine clays to very large boulders. Sediment particles with diameters less than  $63 \mu\text{m}$  are classified as fine-grained sediment, and are cohesive in nature. Sediment particles with diameters greater than  $63 \mu\text{m}$  are classified as noncohesive sediment. However, Roberts *et al.* (1998) found evidence of consolidation effects on quartz sediment up to  $200 \mu\text{m}$ ; this suggests that some cohesive effects may exist for particles slightly larger than  $63 \mu\text{m}$ .

Cohesive (or fine-grained) sediments are composed of clay and non-clay mineral components, silt-sized particles, and organic material, including biochemicals (Grim, 1968). Clays are defined as particles with an equivalent diameter of less than  $4 \mu\text{m}$ , and generally consist of one or more clay minerals such as kaolinite, bentonite, illite, chlorite, montmorillonite, vermiculite and halloysite. The non-clay minerals consist of, among others, quartz, calcium carbonate, feldspar, and mica. The organic matter often present in clay materials can be discrete particles, adsorbed organic molecules, or constituents inserted between clay layers (Grim, 1968). Additional possible components of clay materials are water-soluble salts and adsorbed exchangeable ions and contaminants. Clays possess the properties of plasticity, thixotropy and adsorption in water (van Olphen, 1963).

For clay-sized particles, surface physicochemical forces exert a distinct controlling influence on the behavior of the particles due to the large specific area, i.e., ratio of surface area to volume. In fact, the average surface force on one clay particle is several orders of magnitude greater than the gravitational force (Partheniades, 1962).



The relationships between clay particles and water molecules are governed by interparticle electrochemical forces. Interparticle forces are both attractive and repulsive. The attractive forces present are the London-van der Waals and are due to the nearly instantaneous fluctuation of the dipoles that result from the electrostatic attraction of the nucleus of one atom for the electron cloud of a neighboring atom (Grimshaw, 1971). These electrical attractive forces are weak and are only significant when interacting atoms are very close together.

The electrical attractive forces are strong enough to cause structural build-up since they are additive between pairs of atoms. The magnitude of these forces decreases with increasing temperature; they are only slightly dependent on the salt concentration (i.e., salinity) of the medium (van Olphen, 1963). The repulsive forces of clay materials, due to negatively charged particle forces, increase in an exponential fashion with decreasing particle separation. An increase in the salinity, however, causes a decrease in the magnitude of these repulsive forces.

The cation exchange capacity (CEC) is an important property of clays by which they adsorb certain cations and anions in exchange for those already present and retain the new ones in an exchangeable state. The CEC of different clays varies from 3 to 15 milliequivalents per 100 grams (meq/100 gm) for kaolinite to 100 to 150 meq/100 gm for vermiculite. Higher CEC values indicate greater capacity to adsorb/exchange cations. Some of the predominantly occurring cations in cohesive sediments are Na, K, Ca, Al, Pb, Cu, Hg, Cr, Cd, and Zn.

In water with very low salinity (less than about 1 psu), individual cohesive sediment particles are often found in a dispersed state. Small amounts of salts, however, are sufficient to repress the electrochemical surface repulsive forces among the particles, with the result that the particles coagulate to form flocs. Depending primarily on the CEC of the clay minerals, flocs can form even in freshwater. Each floc can contain thousands or even millions of particles. The transport properties of flocs are affected by the hydrodynamic conditions and by the chemical composition of the suspending fluid. Most estuaries and some freshwater water bodies contain abundant quantities of cohesive sediments that usually occur in the coagulated form in various degrees of flocculation. Therefore, an understanding of the transport properties of cohesive sediments requires knowledge of the manner in which flocs are formed.

Coagulation of suspended cohesive sediments depends on interparticle collision and cohesion. Cohesion and collision, discussed in detail elsewhere [Einstein and Krone (1962), Krone (1962), Partheniades (1964), Hunt (1980) and McAnally (1999)] are briefly reviewed here. There are three principal mechanisms of interparticle collision in suspension, and these influence the rate at which individual sediment particles coagulate. The first is due to Brownian motion that results from the thermal motions of the molecules of the suspending water. Generally, coagulation rates by this mechanism are too slow to be significant unless the suspended sediment concentration exceeds 5 - 10 g/L as it sometimes does in fluid mud (a high density, near-bed layer). Flocs formed by this mechanism are weak, with a lace-like structure, and are easily fractured by shearing, especially in the high shears found near the bed in rivers or estuaries, or are crushed easily when deposited (Krone, 1962).

The second mechanism is due to internal shearing produced by local velocity gradients in the fluid. Collision will occur if the paths of the particles' centers in the velocity gradient are displaced by a distance that is less than the sum of their radii. Flocs produced by this mechanism tend to be spherical, and are relatively dense and strong because only those bonds that are strong enough to resist internal shearing can survive.

The third mechanism, differential sedimentation, results from particles of different sizes having different settling velocities. A larger particle, due to its higher settling velocity, will collide with smaller, more slowly settling particles and will have a tendency to pick-up these particles. This mechanism produces relatively weak flocs and contributes to the often observed rapid clarification of estuarial waters at slack tide.

All three collision mechanisms operate in rivers and estuaries, with internal shearing and differential sedimentation generally being predominant in the water column, excluding perhaps in fluid mud where Brownian motion is likely to contribute significantly. The collision efficiency is less than 100%, so not all collisions result in coagulation.

Cohesion of colliding colloidal particles is caused by the presence of net attractive electrochemical surface forces on the particles. Particle cohesion is promoted by an increased concentration of dissolved ions and/or an increased ratio of multivalent to monovalent ions present in saline waters. The CEC, salinity and ratio of multivalent to monovalent ions all serve to determine the net interparticle force and, thus, the potential for clay particles to become cohesive. Kaolinite becomes cohesive at a salinity of 0.6 psu, illite at 1.1 psu and montmorillonite at 2.4 psu (Ariathurai, 1974). Edzwald *et al.* (1974) reported that the cohesiveness of clay particles develops quickly at the given salt concentrations, and that little increase in coagulation occurs at higher salt concentrations, implying that the particles must have attained their maximum degree of cohesion. The rapid development of cohesion and the relatively low salinities at which clays become cohesive indicate that cohesion is primarily affected by salinity variations near the landward end of an estuary where salinities are often less than about 3 psu.

Burban *et al.* (1990) found that the settling speeds of flocs were only a weak function of salinity, whereas the researchers cited here previously have observed salinity effects on both the settling rates and on the erodibility of cohesive sediments. Burban *et al.* concluded that the changes in settling velocities as they are transported through an estuary are rather small, and that flocculation is a secondary cause of estuarine turbidity maxima with the hydrodynamics of the stratified flow being of more importance.

The rate and degree of flocculation are important factors that govern the transport of cohesive sediments. Factors, besides the water chemistry and magnitude of surface forces, known to govern coagulation and flocculation include: sediment size grading, mineralogical composition, particle density, organic content, suspension concentration, water temperature, depth of water through which the flocs have settled, and turbulence intensity (represented by the rate of internal shearing) of the suspending flow (Owen, 1971).

The order of flocculation that characterizes the packing arrangement, density and shear strength of flocs is determined by: 1) sediment type, 2) fluid composition, 3) local shear field, and 4) concentration of particles available for flocculation. Krone (1962) found that floc structure is dependent on salinity for salinities less than about 10 psu. Primary, or 0-order flocs, are highly packed arrangements of clay particles, with each floc consisting of perhaps as many as a million particles. Typical values of the void ratio (volume of pore water divided by volume of solids) have been estimated to be on the order of 1.2. This is equivalent to a porosity of 0.55 and is a more open structure than commonly occurs in noncohesive sediments (Krone, 1963).

Continued flocculation under favorable shear gradients can result in the formation of first or higher order flocs composed of loosely packed arrays of 0-order flocs. Each succeeding order consists of flocs of lower density and lower shear strength. A range of flocs of different shear strengths and densities are typically formed, with the highest order determined by the prevailing shearing rate provided that a sufficient number of suspended clay particles are available for promoting coagulation and flocculation.

## A.2 Sediment Bed Properties

As rivers flow from mountains to coastal plains, noncohesive sediment tends to deposit out, creating an upward concave, long profile of the bed and a pattern of downstream fining of bed sediment. When the sediment transport capacity in a given reach of a river exceeds the total sediment load being transported from upstream reaches, the difference between the capacity and total load is supplied from the bed. This means that the river channel will undergo erosion, i.e., degradation. In a river with nonuniform bed material, the finer surficial bed sediment will be eroded more rapidly than the coarser sediment. By this process, the median diameter of the surficial bed sediment becomes coarser. If the degradation continues, the finer surficial bed sediment will eventually be depleted, leaving a surficial layer of coarser sediment. This process is called armoring and the surficial layer of coarser sediment is called the armor layer.

In response to varying flow conditions, and hence the rate of sediment transport in an alluvial channel, the bed configuration of the water body will change. Simons and Sentürk (1992) defined bed configuration as any irregularity in the bed surface larger than the largest size sediment particle forming the bed. Bed form is one of several synonyms used in the literature for bed configuration. Any one who has ever swam in a sandy bottom river, lake, or ocean has no doubt noticed ripples on the bottom. Ripples are one type of bed form that is created by a certain range of flow conditions. Other types of bed forms include: plane bed, dunes, washed out dunes, anti-dunes, and chutes and pools (Simons and Sentürk, 1992). A plane bed does not have any bed features. In other words, the bed is essentially flat or smooth. These will normally only be found in channels with very low flows. With an increase in flow, ripples form in plane bed alluvial channels. Ripples are small, asymmetric triangular shaped bed forms that are normally less than 5 cm in height and less than 30 cm in length. In general, ripples have long, gentle slopes on their upstream sides and short, steep slopes on their downstream sides. Dunes are typically larger than ripples but smaller than bars, and have similar longitudinal profiles as ripples. Dune formation occurs near the upper end of the subcritical flow regime, and as such, dunes are out of phase with

the water surface; the water surface decreases slightly above the crest of the dune. Washed-out dunes (also referred to as a transitional bed form) consist of intermixed, low amplitude dunes and flat areas. These typically occur around the critical flow condition. Antidunes are usually more symmetrical (in their longitudinal profile) than dunes, and form under supercritical flows. Thus, antidunes are in phase with the water surface elevation and move in the upstream direction. Chutes and pools usually occur on relatively steep channel slopes, and as such, high velocities and sediment discharges occur in the chutes.

Noncohesive sediment beds at a given location are characterized by vertical profiles in grain size distribution and in porosity (or dry bed density). They do not undergo consolidation, and thus their resistance to erosion does not change over time, whereas flow-deposited beds of cohesive sediment flocs typically possess vertical density and bed shear strength profiles. The average values of bed density and bed shear strength increase over time and their vertical profiles change with time, primarily due to consolidation and secondarily due to thixotropy and associated physicochemical changes affecting inter-particle forces. Consolidation is caused by the gravitational force of overlying deposited flocs (overburden) that crushes, and thereby decreases the order of flocculation of the underlying sediment. Consolidation changes the erosive behavior of cohesive sediment beds in two ways: (1) as the shear strength of the bed increases due to consolidation, the susceptibility of the bed to erosion decreases, and (2) the vertical shear strength profile determines the depth into the bed that a bed will erode when subjected to excess shear, i.e., an applied bed shear stress in excess of the bed surface shear strength.

In rivers and other water bodies, sediment beds will often be composed of a mixture of fine-grained and noncohesive sediments. Lick *et al.* (2004) found that percentages of fine-grained sediment as low as 2% in such beds can have a large effect on erosion rates, thus demonstrating the importance of determining the variation in grain size distributions and erosion rates of sediment throughout the water body.

### A.3 Sediment Erosion and Transport

#### A.3.1 Noncohesive sediment transport

Incipient motion of a noncohesive sediment particle occurs when the flow-induced forces are greater than the resistance forces and the particle begins to move across the surface of the sediment bed. Figure A.1 is a diagram of the forces acting on a single, spherical sediment particle in the surface layer of a sediment bed. For simplicity, all the particles are assumed to have the same diameter and to be arranged in the orderly fashion seen in this figure. The dashed brown line in this figure represents the hypothetical bed surface where the mean flow velocity is zero. The angle between the horizontal black line (on the right side of the figure) and the bed surface is shown to be  $\theta$ . The slope of the bed is equal to  $\tan\theta$ . The forces shown in this diagram are the following:  $W_s$  = submerged weight of the particle;  $F_D$  = flow-induced drag force;  $F_L$  = flow-induced lift force; and  $F_R$  = resistance force due to contact between adjacent particles.

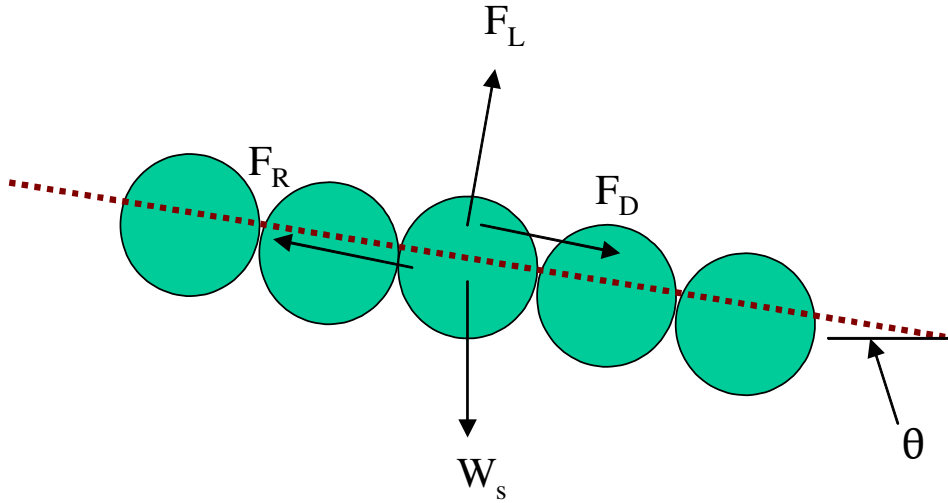


Figure A.1 Diagram of forces acting on a sediment particle

Summing the forces in the direction perpendicular to the bed at the onset of incipient motion, i.e., when the particle has not yet started to move, gives:

$$F_L - W_s \cos \theta = 0 \quad (\text{A.1})$$

The lift force that acts on the particle is given by:

$$F_L = C_L \frac{\pi}{4} D^2 \frac{\rho}{2} V_D^2 \quad (\text{A.2})$$

where  $C_L$  = lift coefficient;  $D$  = particle diameter;  $\rho$  = water density; and  $V_D$  = velocity at a distance  $D$  above the bed. The submerged weight of the particle is given by:

$$W_s = \frac{\pi D^3}{6} (\rho_s - \rho) g \quad (\text{A.3})$$

where  $g$  = gravitational acceleration; and  $\rho_s$  = sediment particle density.

Summing the forces in the direction parallel to the bed at the onset of incipient motion gives:

$$F_D - F_R + W_s \sin \theta = 0 \quad (\text{A.4})$$

The drag force that acts on the particle is given by:

$$F_D = C_D \frac{\pi}{4} D^2 \frac{\rho}{2} V_D^2 \quad (\text{A.5})$$

where  $C_D$  = drag coefficient. Yang (1973) gives the following expression for the resistance force:

$$F_R = \psi(W_s - F_L) \quad (\text{A.6})$$

where  $\psi$  = friction coefficient.

$V_D$  in Eqs. A.2 and A.5 can be determined using a logarithmic velocity distribution:

$$\frac{V_y}{u_*} = 5.75 \log \frac{y}{D} + B \quad (\text{A.7})$$

where  $V_y$  = velocity at a distance  $y$  above the bed;  $B$  = roughness function; and  $u_* = (\tau_b/\rho)^{0.5}$  = shear velocity, with  $\tau_b$  = bed shear stress. In the hydraulically smooth regime, as defined by the shear velocity Reynolds number (given below in Eq. A.8),  $B$  is given by:

$$B = 5.5 + 5.75 \log \frac{u_* D}{\nu} \quad \text{for} \quad 0 < \frac{u_* D}{\nu} < 5 \quad (\text{A.8})$$

In the hydraulically rough regime,  $B$  is given by:

$$B = 8.5 \quad \text{for} \quad \frac{u_* D}{\nu} > 70$$

Substituting  $y = D$  into Eqs. A.7 and A.8 gives  $V_D = Bu_*$ .

The depth-averaged velocity,  $V$ , can be obtained by integrating Eq. A.7 over the flow depth:

$$\frac{V}{u_*} = 5.75 \left( \log \frac{d}{D} - 1 \right) + B \quad (\text{A.9})$$

Three different approaches have been used to develop criteria for incipient motion. These are the shear stress, velocity, and probabilistic approaches. The shear stress approach by Shields (1936) for determining the critical shear stress at the onset of incipient motion,  $\tau_{cs}$ , is probably the most well known of all the approaches. An example of a probabilistic approach is that developed by Gessler (1965, 1970). The Shield's shear stress approach, further developed by van Rijn (1984a), and the velocity approach used by Yang (1973) are summarized below.

The basis of the shear stress approach is that incipient motion of noncohesive sediment occurs when the bed shear stress exceeds a critical shear stress referred to as the Shield's shear stress,  $\tau_{cs}$ . The latter can be defined by the following nondimensional relationship:

$$\theta_{cs} = \frac{\tau_{cs}}{g' D} = f(R_d) \quad (\text{A.10})$$

where  $g'$  = reduced gravitational acceleration, given by:

$$g' = g \left( \frac{\rho_s}{\rho} - 1 \right) \quad (\text{A.11})$$

and  $R_d$  = sediment particle densimetric Reynolds number, given by:

$$R_d = \frac{D \sqrt{g' D}}{\nu} \quad (\text{A.12})$$

where  $\nu$  = kinematic viscosity. van Rijn (1984b) gives the following expressions for  $f(R_d)$  on the right hand side of Eq. A.10:

$$f(R_d) = \begin{cases} 0.24(R_d^{2/3})^{-1} & \text{for } R_d^{2/3} < 4 \\ 0.14(R_d^{2/3})^{-0.64} & \text{for } 4 \leq R_d^{2/3} < 10 \\ 0.04(R_d^{2/3})^{-0.1} & \text{for } 10 \leq R_d^{2/3} < 20 \\ 0.013(R_d^{2/3})^{0.29} & \text{for } 20 \leq R_d^{2/3} < 150 \\ 0.055 & \text{for } R_d^{2/3} \geq 150 \end{cases} \quad (\text{A.13})$$

In his velocity approach, Yang (1973) first assumed that the channel slope was small enough to neglect the component of the sediment particle's weight in the flow direction in Eq. A.4, i.e.,  $W_s \sin \theta = 0$ . Assuming that incipient motion occurs when the two remaining terms in Eq. A.4 are equal, i.e.,  $F_D = F_R$ , he then equated Eqs. A.5 and A.6, substituted Eq. A.9 into both sides of the resulting equation, and then solved for the dimensionless parameter  $V_{cr}/w_s$ , where  $V_{cr}$  = depth-averaged critical velocity at the onset of incipient motion, and  $w_s$  = particle settling velocity (i.e., terminal fall velocity). He also assumed that the drag coefficient was linearly proportional to the lift coefficient. Yang then used laboratory data sets collected by several researchers to determine the values of the friction coefficient in Eq. A.6 and the proportionality coefficient between the drag and lift coefficient to obtain the following expressions for  $V_{cr}/w_s$ :

$$\frac{V_{cr}}{w_s} = \frac{2.5}{\log(u_* D / \nu) - 0.06} + 0.66 \quad \text{for} \quad 1.2 < \frac{u_* D}{\nu} < 70 \quad (\text{A.14})$$

$$\frac{V_{cr}}{w_s} = 2.05 \quad \text{for} \quad 70 \leq \frac{u_* D}{\nu} \quad (\text{A.15})$$

The friction force exerted along the wetted perimeter of an open channel on the flow is usually quantified using a resistance formula that contains a roughness coefficient. The Manning's roughness coefficient is the one most commonly used for open channels with rigid boundaries. This coefficient is normally used as a calibration parameter in hydraulic models to achieve optimum agreement between measured and predicted stages (i.e., water surface elevations) or discharges. Once the model is calibrated, the Manning coefficient is treated as being temporally constant. For movable boundary problems, i.e., when sediment transport is involved, the resistance coefficient 1) will change with time due to changes in the movable bed that result from aggradation and degradation, and 2) can be attributable to two resisting forces; one force is due to the roughness of the bed surface (this is called grain roughness or skin friction), and the other force is due to the presence of bed forms in alluvial (i.e., movable boundary) channels (this is called form roughness or form drag). Einstein and Barbarossa, (1952) and other researchers have developed procedures for calculating both forms of movable boundary resistance.

The approach by Yang (1976) for estimating the grain- and form-related flow resistance in movable boundary open channels does not involve predicting what type of bed form occurs for a given flow regime (Yang, 1976). The basis for his formulation is the theory of minimum rate of energy dissipation that states that when a dynamic system (e.g., alluvial channel) reaches an equilibrium condition, its energy dissipation rate is minimum. This theory was derived from the second law of thermodynamics. The basic assumption made in this approach is that the rate of energy dissipation due to sediment transport can be neglected. For an open channel, the energy dissipation rate per unit weight of water is equal to the unit stream power  $VS$ , where  $V$  is the average flow velocity in the open channel and  $S$  is the slope of the energy grade line. Therefore, the theory of minimum energy dissipation rate requires that (Yang, 1976):

$$VS = V_m S_m \quad (\text{A.16})$$

where the subscript  $m$  indicates the value of  $V$  and  $S$  when the unit stream power is minimized. Yang's approach involves using Eq. A.14 or A.15 to determine the value of  $V_{cr}$ , and then using the following sediment transport equation developed by Yang (1973) to determine the total sediment transport:

$$\log C_{ts} = 5.435 - 0.286 \log \frac{w_s D}{\nu} - 0.457 \log \frac{u_*}{w_s} + \left( 1.799 - 0.409 \log \frac{w_s D}{\nu} - 0.314 \log \frac{u_*}{w_s} \right) \log \left( \frac{VS}{w_s} - \frac{V_{cr} S}{w_s} \right) \quad (\text{A.17})$$



where  $C_{ts}$  = total sediment concentration being transported by the flow (in ppm by weight),  $D$  = median sieve diameter of the sediment, and  $V_{cr}S$  = critical unit stream power required at incipient motion. The iterative procedure developed by Yang (1976) to determine the value of the Manning's coefficient in an alluvial open channel uses known values for  $Q$ ,  $D$ ,  $w_s$ ,  $C_{ts}$ , and  $A(d)$ , where the latter is the functional relationship between the cross-sectional area,  $A$ , of the open channel and the flow depth,  $d$ . The Yang iterative procedure consists of the following six steps:

1. Assume a value for  $d$  = flow depth.
2. Solve the 1-D continuity equation ( $Q = AV$ ) and Eq. A.17 for  $V$  and  $S$ .
3. Compute the unit stream power, i.e.,  $VS$ .
4. Select another value for  $d$  and repeat steps 2 and 3.
5. Step 4 should be repeated a sufficient number of times to allow for an accurate determination of the minimum value of  $VS$ .
6. Once the minimum value of  $VS$  has been determined, the corresponding values of  $V$ ,  $S$  and  $d$  can be calculated using the 1-D continuity equation and Eq. A.17. The Manning equation (given below) can then be used to calculate the value of the Manning's coefficient,  $n$ .

$$V = \frac{1}{n} R^{2/3} S^{1/2} \quad (\text{A.18})$$

where  $R$  = hydraulic radius, which is equal to the ratio  $A/P$ , where  $P$  is the wetted perimeter. Equation A.18 is the Manning's equation form to use with metric units. Using the theory of minimum unit stream power, Yang and Song (1979) found good agreement between the following measured and computed parameters:  $S$ ,  $V$ ,  $d$ ,  $VS$ , and  $n$ . Parker (1977) also found good agreement for flows where the sediment transport rate was not too high, thus justifying Yang's assumption, mentioned previously, under such conditions. However, the method by Yang (1976) should not be used for critical or supercritical flows, or when the sediment transport rate is high, since the assumption is invalid under these conditions.

Immediately after onset of incipient motion, the sediment generally moves as bedload. Bedload transport occurs when noncohesive sediment rolls, slides, or jumps (i.e., saltates) along the bed. If the flow continues to increase, then some of the sediment moving as bedload will usually be entrained by vertical turbulent velocity components into the water column and be transported for extended periods of time in suspension. Thus, it takes more energy for the flow to transport sediment in suspension than as bedload. The sediment that is transported in suspension is referred to as suspended load. The total load is the sum of the bedload and suspended load. Bedload is typically between 10 - 25 percent of the total load, though for beds with a high fraction of coarse sediment, the percentage will normally be higher. Many different methods have been developed for calculating the bedload transport rate in open channels. Some of these methods (along with their references) are listed next. The specific shear stress approach of van Rijn (1984a) is also described in some detail in the following.

1. Shear Stress Method: Shields (1936); Chang et al. (1967), and van Rijn (1984a).
2. Energy Slope Method: Meyer-Peter and Muller (1948).
3. Probabilistic Method: Einstein (1950)

Utilizing a shear stress approach, the dimensionless form of the bedload transport rate is given by van Rijn (1984a) as:

$$\frac{q_b}{\rho_s D \sqrt{g' D}} = \frac{0.053}{R_d^{1/5} \theta_{cs}^{2.1}} (\theta - \theta_{cs})^{2.1} \quad (\text{A.19})$$

where  $\theta = \frac{\tau_b}{\rho g' D}$ ,  $q_b$  = bedload transport rate (with units of mass per unit time per unit width), and  $\theta_{cs}$  is defined in Eq. A.10. Sediment is transported as bedload in the direction of the mean flow.

The settling velocity for individual noncohesive sediment particles,  $w_s$ , is given by van Rijn (1984b) as the following functions of  $D$ ,  $g'$  and  $R_d$ :

$$\frac{w_s}{\sqrt{g' D}} = \begin{cases} \frac{R_d}{18} & \text{for } D \leq 100 \mu\text{m} \\ \frac{10}{R_d} \left( \sqrt{1 + 0.01 R_d^2} - 1 \right) & \text{for } 100 \mu\text{m} < D \leq 1000 \mu\text{m} \\ 1.1 & D > 1000 \mu\text{m} \end{cases} \quad (\text{A.20})$$

Another commonly used formula for the settling velocity of natural noncohesive sediment particles is given by Cheng (1997) as the following function of  $D$ ,  $\nu$  and  $R_d$ :

$$\frac{w_s D}{\nu} = \left( \sqrt{25 + 1.2 \left( \frac{R_d}{\nu} \right)^{2/3}} - 5 \right)^{1.5} \quad (\text{A.21})$$

To predict the noncohesive suspended sediment load in a water body, it is necessary to determine whether, for a given particle size and flow regime, the sediment is transported as bedload or as suspended load. van Rijn (1984a) presented the following approach for distinguishing between bedload and suspended load. When the bed shear velocity,  $u_*$ , is less than the critical shear velocity,  $u_{*cs}$ , no erosion is assumed to occur, and, therefore, no bedload transport occurs. Under this latter flow condition, any sediment in suspension whose critical shear velocity is greater than the bed shear velocity will deposit. When the bed shear velocity exceeds the critical shear velocity for a given particle size, erosion of that size (and smaller) sediment from the bed surface is assumed to occur. Therefore, if the following inequality is true,

sediment will be transported as bedload (and not as suspended load):

$$u_{*cs} < u_* < w_s \quad (\text{A.22})$$

Under this inequality condition, any suspended sediment whose critical shear velocity is greater than the bed shear velocity is assumed to deposit. If the bed shear velocity exceeds both the critical shear velocity and settling velocity for a given particle size, then that size sediment (and any smaller) is assumed to be eroded from the bed and transported as suspended load, and any sediment of that particle size (and smaller) already moving as bedload is assumed to be subsequently transported in suspension.

The rate of suspended load transport can be calculated as:

$$q_s = g \rho_s \int_a^d \bar{u} \bar{c} dz \quad (\text{A.23})$$

where  $q_s$  = suspended load transport rate per unit width of the open channel (with units of kg/s),  $\bar{u}$  = time-averaged velocity at a distance  $z$  above the bed,  $\bar{c}$  = time-averaged suspended sediment concentration (by volume) at a distance  $z$  above the bed, and  $a$  = thickness of the bedload transport zone. Though not described in this report, Lane and Kalinske (1941), Einstein (1950), Brooks (1963), and Chang *et al.* (1965) developed alternative methods to calculate  $q_s$ .

The two general approaches used to calculate the total noncohesive sediment load in an open channel consist of: 1) adding the separately estimated bedload and suspended load, and 2) using a total load function that directly estimates the total amount of bedload and suspended load transport. Various formulations of the latter are briefly reviewed in this section. The advantage of using a total load approach is that sediment particles can be transported in suspension in one reach of an open channel and as bedload in another reach. In this section, only the unit stream power methods developed by Yang (1973) for estimating the total load will be presented.

The total sediment load function given by Eq. A.17 is valid for total sand concentrations less than about 100 ppm by weight. For higher sediment concentrations, Yang (1979) presented the following total load equation, again based on the unit stream power concept:

$$\begin{aligned} \log C_{tg} = & 6.681 - 0.633 \log \frac{w_s D}{\nu} - 4.816 \log \frac{u_*}{w_s} \\ & + \left( 2.784 - 0.305 \log \frac{w_s D}{\nu} - 0.282 \log \frac{u_*}{w_s} \right) \log \left( \frac{VS}{w_s} - \frac{V_{cr} S}{w_s} \right) \end{aligned} \quad (\text{A.24})$$

Yang (1984) also presented the following unit stream power based total load equation that is applicable for gravel sized sediment with median particle sizes between 2 and 10 mm:

$$\log C_{ts} = 5.165 - 0.153 \log \frac{w_s D}{\nu} - 0.297 \log \frac{u_*}{w_s} \quad (\text{A.25})$$

$$+ \left( 1.780 - 0.360 \log \frac{w_s D}{\nu} - 0.480 \log \frac{u_*}{w_s} \right) \log \frac{VS}{w_s}$$

For open channels that have bed sediments in the sand to medium gravel size range, i.e., between 0.063 to 10 mm, the total load would be the sum, depending on the value of  $C_{ts}$ , of either Eqs. A.17 and A.24 or Eqs. A.23 and A.24.

When the sediment transport capacity in a given reach of an open channel exceeds the total sediment load being transported from upstream reaches, the difference between the capacity and total load is supplied from the bed. This means that the channel will undergo erosion, i.e., degradation. In a natural open channel with nonuniform bed material, the finer surficial bed sediment will be eroded more rapidly than the coarser sediment. By this process, the median diameter of the surficial bed sediment becomes coarser. If the degradation continues, the finer surficial bed sediment will eventually be depleted, leaving a layer of coarser sediment on the bed surface. This process is called armoring, and the surficial layer of coarser sediment is called the armor layer.

Garcia and Parker (1991) developed the following approach that accounts for the effect of armoring to estimate the near-bed equilibrium concentration,  $C_{eq}$ , for bed material that consists of multiple, noncohesive sediment size classes:

$$C_{jeq} = \rho_s \frac{A(\lambda Z_j)^5}{\left(1 + 3.33A(\lambda Z_j)^5\right)} \quad (\text{A.26})$$

where  $C_{jeq}$  = near-bed equilibrium concentration for the  $j$ -th sediment size class,  $A = 1.3 \cdot 10^{-7}$ , and

$$\lambda = 1 + \frac{\sigma_\phi}{\sigma_{\phi_0}} (\lambda_0 - 1) \quad (\text{A.27})$$

$$Z_j = \frac{u_*}{w_{sj}} R_{dj}^{3/5} F_H \quad (\text{A.28})$$

$$F_H = \left( \frac{D_j}{D_{50}} \right)^{1/5} \quad (\text{A.29})$$

where  $D_{50}$  = median particle size of the noncohesive bed sediments,  $\sigma_\phi$  = standard deviation on the sedimentological phi scale of the bed sediment size distribution,  $\lambda_o = 0.81$ , and  $\sigma_{\phi o} = 0.67$  (Garcia and Parker, 1991).  $F_H$  is referred to as a hiding factor.

The near-bed equilibrium concentration is the suspended sediment concentration at a reference height,  $z_{eq}$ , above the bed surface. It represents the maximum suspended sediment concentration. Some researchers take  $z_{eq}$  to be equal to  $a$ , i.e., thickness of the bedload transport zone, in Eq. A.22. Einstein (1950) assumed that  $z_{eq} = a = 2D_b$ , where  $D_b$  was defined as the representative bed sediment grain size. van Rijn (1984b) assumed  $z_{eq}$  was equal to three grain diameters. DuBoy (1879) derived the following expression for the thickness of the bedload zone:

$$a = \frac{10(\tau - \tau_c)}{g(1 - \lambda)(\rho - \rho_s)\tan\phi} \quad (\text{A.30})$$

where  $\lambda$  = porosity of bed material, and  $\phi$  = angle of repose of the bed material.

### A.3.2 Cohesive sediment transport

The discussion in this section concentrates on cohesive sediment transport in estuaries. The difference between the description given here and that for cohesive sediment transport in rivers and lakes/reservoirs deals primarily with the hydrodynamics of the water bodies and the effect of salt water on the coagulation/flocculation process. The basic transport processes of erosion, advection, dispersion, settling, deposition, and consolidation are essentially the same in all types of water bodies. Thus, this brief overview of cohesive sediment transport processes in estuaries is, for the most part, relevant to all water bodies, and will provide the reader with an expanded description of sediment transport processes.

Cohesive (fine-grained) sediment transport, especially in estuaries and coastal waters, is a complex process involving a strong coupling among tides, baroclinic circulation, and the coagulated/flocculated sediment. For an extensive description of this process, the reader is referred to Postma (1967), Partheniades (1971), Barnes and Green (1971), Krone (1972), Kirby and Parker (1977), Kranck (1980) and Dyer (1986). Figure A.2 is a schematic depiction of the tidally-averaged sediment transport processes in a stratified (i.e., salt wedge) estuary, e.g., Lower Duwamish Waterway, Seattle, WA. In the case of a partially mixed estuary (e.g., Chesapeake Bay) the description would have to be modified, i.e., there would not be a well developed salt wedge, but since relatively steep vertical density gradients are sometimes present even in such a case, the sediment transport processes would generally remain qualitatively similar to that depicted.

As indicated in Figure A.2, sediments from upstream fresh water sources arrive in the estuarial mixing zone. The high level of turbulence and the increasingly saline waters will cause flocs to form and grow in size as a result of frequent interparticle collisions and increased cohesion. The large flocs will settle to the lower portion of the water column because of their

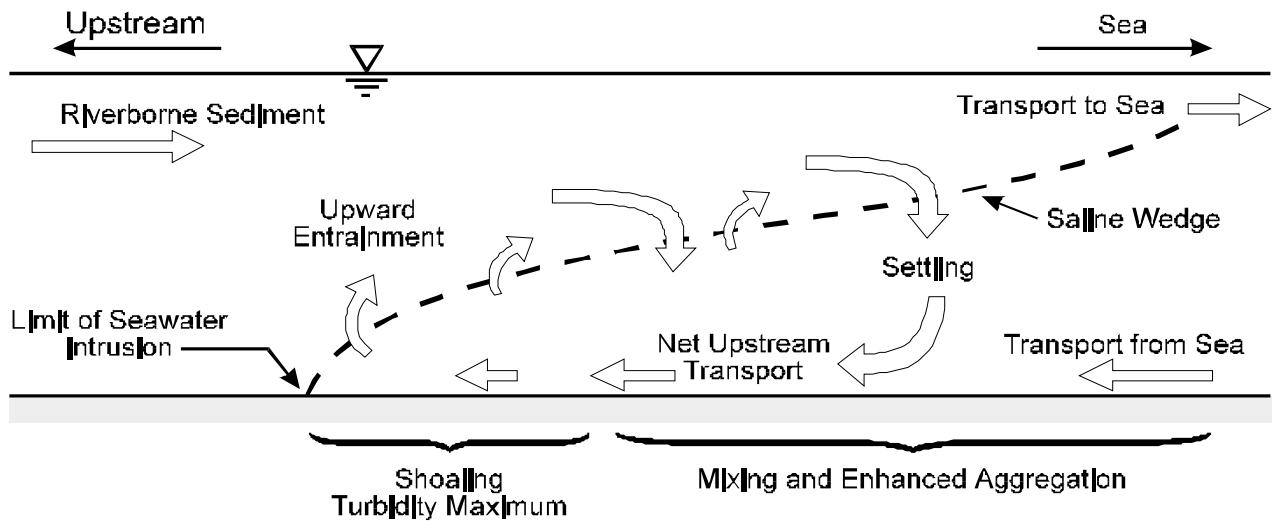


Figure A.2 Schematic representation of transport and sedimentation processes in the mixing zone of a stratified estuary (after Mehta and Hayter, 1981)

high settling velocities. Results from laboratory experiments show that floc settling velocities can be up to four orders of magnitude larger than the settling velocities of the individual particles (Bellessort, 1973). Some of the sediment/flocs will deposit; the remainder will be carried upstream near the bottom until periods close to slack water when the bed shear stresses decrease sufficiently to permit deposition in the so called turbidity maximum, after which the sediment starts to undergo self-weight consolidation. The depth to which the new deposit scours when the currents increase after slack will depend on the bed shear stresses imposed by the flow and the shear strength of the deposit. Net deposition, i.e., sedimentation, will occur when the bed shear during flood, as well as during ebb, is insufficient to resuspend, i.e., erode, all of the material deposited during preceding slack periods. Some of the sediment that is resuspended may be re-entrained throughout most of the length of the mixing zone to levels above the sea water-fresh water interface, and subsequently transported downstream. At the seaward end, some material may be transported out of the estuary, a portion of which could ultimately return with the net upstream bottom current.

In the mixing zone of a typical estuary, the sediment transport rates often are an order of magnitude greater than the rate of inflow of new sediment derived from upland or oceanic sources. The estuarial sedimentary regime is characterized by several periodic (or quasi-periodic) macro-time-scales, the most important of which are the tidal period (diurnal, semi-diurnal, or mixed) and one-half the lunar month (spring-neap-spring cycle). The tidal period is the most important since it is the fundamental period that characterizes the basic mode of sediment transport in an estuary. The lunar month is often significant in determining net sedimentation rates.

From an Eulerian point of view, the superposition of oscillating tidal flows on the quasi-steady state transport phenomenon depicted in Figure A.2 results in corresponding oscillations of the suspended sediment concentration with time as shown in Figure A.3. Such a variation of the suspended load ultimately results from a combination of advective and dispersive transport, erosion, and deposition. Because of the complexity of the phenomenon, more than one interpretation is possible as far as any schematic representation of these phenomena is concerned. One such representation is shown in Figure A.4.

According to this description, cohesive sediments can exist in four different physical states in an estuary: mobile suspension, stationary suspension, partially consolidated bed, and settled bed. The last two are formed as a result of consolidation of a stationary suspension. Stationary here implies little horizontal movement. A stationary suspension, a partially consolidated bed and a settled bed can erode if the shear stress exceeds a certain critical value. Erosion of a stationary suspension is referred to as redispersion or mass erosion, whereas erosion of a partially consolidated bed or a settled bed is termed either resuspension or surface erosion.

To summarize, the sediment transport regime is controlled by the hydrodynamics, the chemical composition of the fluid, and the physicochemical properties of the cohesive sediments. These factors affect the processes of erosion, advection, dispersion, flocculation, settling, deposition, and consolidation. A brief description of these processes follows that of cohesive sediment beds.

A flow-deposited bed of cohesive sediment flocs possesses a vertical density and bed shear, i.e., yield, strength profile. The average values of bed density and bed shear strength increase and their vertical profiles change with time, primarily due to consolidation and secondarily due to thixotropy and associated physicochemical changes affecting inter-particle forces. Consolidation is caused by the gravitational force of overlying deposited flocs (overburden) that crushes, and thereby decreases the order of flocculation of the underlying sediment. Consolidation changes the erosive behavior of cohesive sediment beds in two ways: (1) as the shear strength of the bed increases due to consolidation, the susceptibility of the bed to erosion decreases, and (2) the vertical shear strength profile determines the depth into the bed that a bed will erode when subjected to excess shear, i.e., an applied bed shear stress in excess of the bed surface shear strength.

Estuarial sediment beds, typically composed of flow-deposited cohesive sediments, can be assumed to occur in three different states: stationary suspensions, partially consolidated beds, and settled (or fully consolidated) beds (see Figure A.4). Stationary suspensions are defined by Parker and Lee (1979) as assemblages of high concentrations of sediment particles that are supported jointly by the water and developing skeletal soil framework and have no horizontal movement. These suspensions develop whenever the settling rate of concentrated mobile suspensions exceeds the rate of self-weight consolidation (Parker and Kirby, 1982). They tend to have a high water content (therefore low bulk density) and a very low shear strength that must be at least as high as the bed shear that existed during the deposition period (Mehta *et al.*, 1982a). Thus, they exhibit a definite non-Newtonian rheology. Kirby and Parker (1977) found that the stationary suspensions

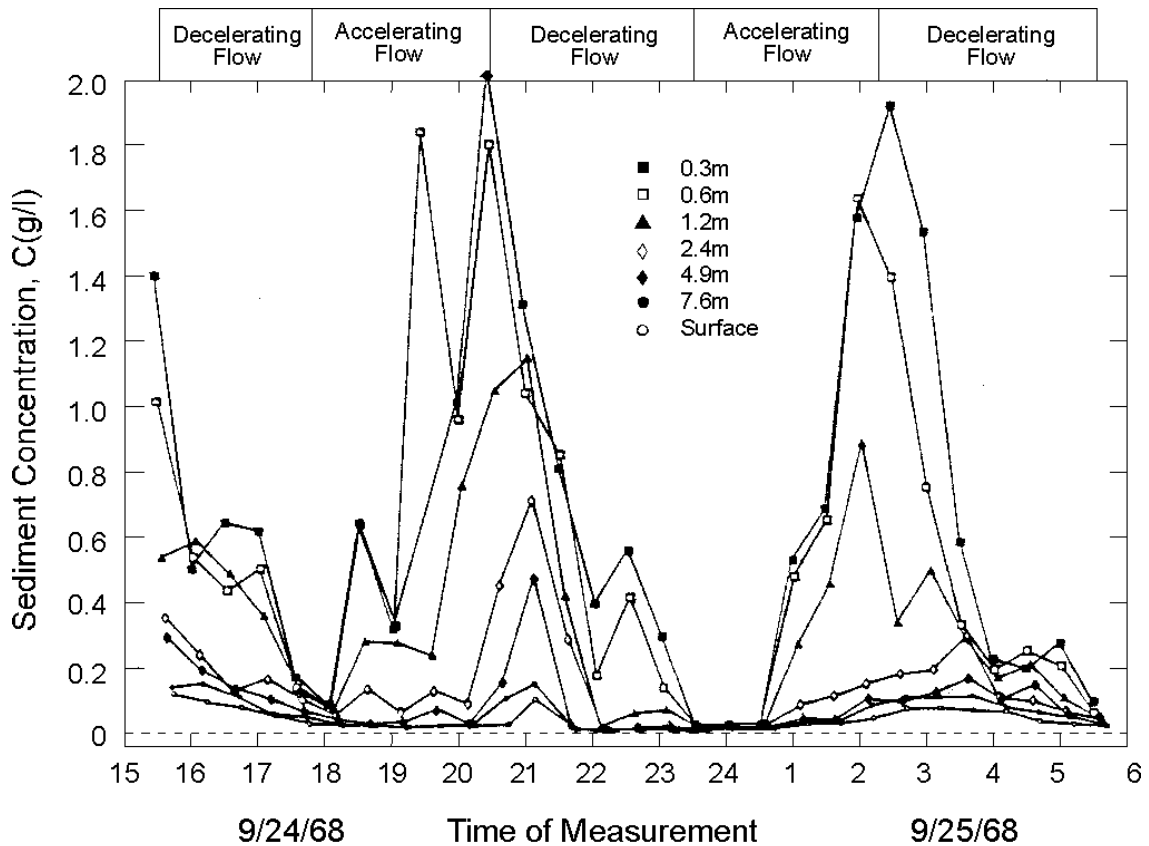


Figure A.3 Time and depth variation of suspended sediment concentration in the Savannah River estuary (after Krone, 1972)

they investigated had a surface bulk density of approximately  $1050 \text{ kg/m}^3$  and a layered structure.

Whether redistribution of these suspensions occurs during periods of erosion depends upon the mechanical shear strength of the floc network. That portion of the flocs remaining on the bed undergoes: 1) self-weight consolidation, and 2) thixotropic effects, defined as the slow rearrangement of deposited flocs attributed to internal energy and unbalanced internal stresses (Mitchell, 1961), both of which reduce the order of flocculation of sub-surface bed layers. This implies that the bed becomes stratified with respect to density and shear strength, with both properties typically increasing monotonically with depth, at least under laboratory conditions (Mehta *et al.*, 1982a).

Continued consolidation eventually results in the formation of settled mud, defined by Parker and Lee (1979) as “assemblages of particles predominantly supported by the effective contact stresses between particles as well as any excess pore water pressure”. This portion of the bed has a lower water content, lower order of flocculation, and higher shear strength. The settled mud in the Severn Estuary and Inner Bristol Channel, United Kingdom, was found to possess a bulk density ranging from  $1300$  to  $1700 \text{ kg/m}^3$  (Kirby and Parker, 1983). The nature of the



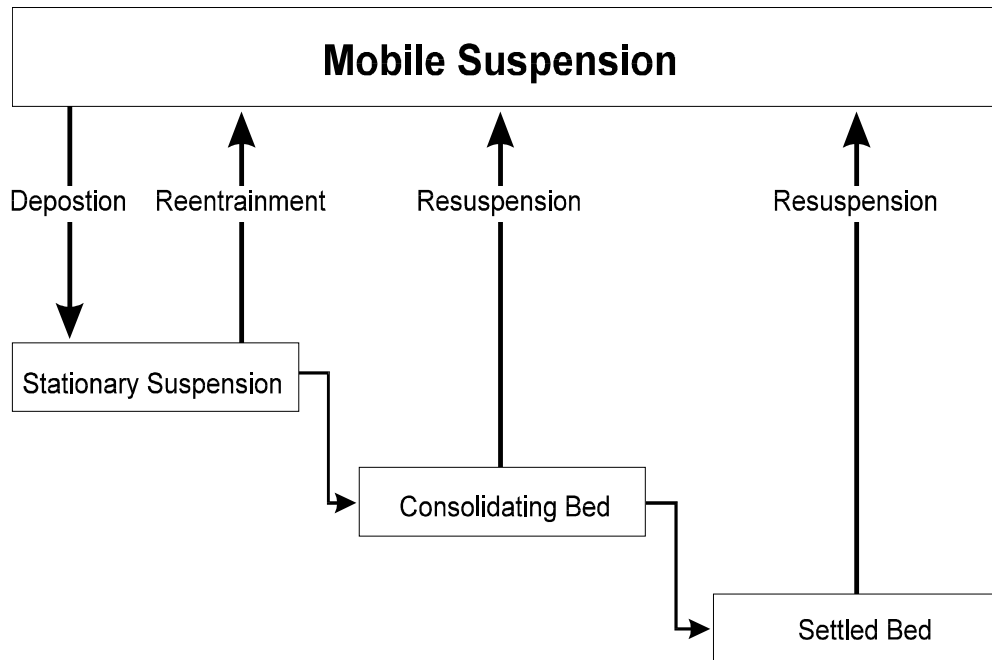


Figure A.4 Schematic representation of the physical states of cohesive sediment in an estuarial mixing zone (after Mehta *et al.*, 1982a)

density and shear strength profiles typically found in cohesive sediment beds has been revealed in laboratory tests by, among others, Richards *et al.* (1974), Owen (1975), Thorn and Parsons (1980), Parchure (1980), Bain (1981), Dixit (1982), and Burt and Parker (1984). A review of this subject is given by Hayter (1983).

Erosion of cohesive sediments occurs whenever the shear stress induced by water flowing over the sediment bed is great enough to break the electrochemical interparticle bonds (Partheniades, 1965; Paaswell, 1973). When this happens, erosion takes place by the removal of individual sediment particles and/or flocs. This type of erosion is time dependent and is defined as surface erosion or resuspension. In contrast, another type of erosion occurs more or less instantaneously by the removal or entrainment of relatively large pieces of the bed. This process is referred to as mass erosion or redispersion, and occurs when the flow-induced shear stresses on the bed exceed the sediment bed bulk strength along some deep-seated plane.

A number of laboratory investigations were carried out in the 1960's and 1970's in order to determine the rate of resuspension,  $\varepsilon$ , defined as the mass of sediment eroded per unit bed surface area per unit time as a function of bed shear in steady, turbulent flows. An important conclusion from those tests was that the usual soil indices, such as liquid and plastic limit, do not adequately describe the erosive behavior of these sediments (Mehta, 1981). For example, Partheniades (1962) concluded that the bed shear strength as measured by standard tests, e.g., the direct-shear

test (Terzaghi and Peck, 1960), has no direct relationship to the sediment's resistance to erosion that is essentially governed by the strength of the interparticle and inter-floc bonds.

The sediment composition, pore and eroding fluid compositions, and structure of the flow-deposited bed at the onset of erosion must be determined in order to properly define the erosion resistance of the bed. Sediment composition is specified by the grain size distribution of the bed material (i.e., weight fraction of clays, silts), the type of clay minerals present, and the amount and type of organic matter. The compositions of the pore and eroding fluids are specified by the temperature, pH, total amounts of salts and type and abundance of ions present, principally  $\text{Cl}^-$ ,  $\text{Na}^+$ ,  $\text{Ca}^{2+}$ , and  $\text{Mg}^{2+}$ . Cementing agents, such as iron oxide, can significantly increase the resistance of a sediment bed to erosion. Measurement of the electrical conductivity is used to determine the total salt concentration in the pore and eroding fluids. The effect of the bed structure, specifically the vertical sediment density and shear strength profiles, on the rate of erosion is discussed by Lambermont and Lebon (1978) and Mehta *et al.* (1982a).

The erosive forces, characterized by the flow-induced instantaneous bed shear stress, are determined by the flow characteristics and the surface roughness of the fluid-bed interface. Several different types of relationships between the rate of erosion,  $\varepsilon$ , and the time-mean value of the flow-induced bed shear stress,  $\tau_b$ , have been reported for non-stratified beds. These include statistical-mechanical models (Partheniades, 1965; Christensen, 1965), a rate process model (Paaswell, 1973; Kelley and Gularte, 1981), and empirical relationships (Ariathurai and Arulanandan, 1978).

Ariathurai and Arulanandan (1978) found the following general relationship for the resuspension rate of consolidated beds:

$$\varepsilon = M' \left( \frac{\tau_b - \tau_c}{\tau_c} \right) \quad (\text{A.31})$$

where  $M' = M \cdot \tau_c$ , where  $M$  is termed the erodibility constant,  $\tau_b$  is the flow-induced bed shear stress and  $\tau_c$  is the bed shear strength. The term inside the parentheses on the right-hand-side of Eq. A.31 is referred to as the normalized excess bed shear stress. Values for  $M$  and  $\tau_c$  are normally determined using either laboratory tests (Parchure, 1984), or using a device such as the SEDFLUME (McNeil *et al.*, 1996).

Gailani *et al.* (1991) found the following relationship between the resuspension potential,  $E$ , defined as the total mass of sediment that can be resuspended at a given shear stress, and the normalized excess shear stress:

$$E = \frac{a_o}{t_d^n} \left[ \frac{\tau_b - \tau_c}{\tau_c} \right]^m \quad (\text{A.32})$$

where  $t_d$  = time after deposition of sediment in units of days; and  $a_o$ ,  $n$ ,  $m$ , and  $\tau_c$  are sediment-specific empirical coefficients. It is stated that  $n$  and  $m$  are approximately equal to 2 and 3, respectively.

Figure A.5 shows the measured variation of  $C$ , expressed as a relative concentration by dividing the measured suspended sediment concentration by the initial suspended sediment concentration before a flow-deposited bed was formed, with time typically found by several investigators (Partheniades, 1962; Mehta and Partheniades, 1979; Mehta *et al.*, 1982a) in laboratory resuspension tests with flow-deposited (i.e., stratified) beds under a constant  $\tau_b$ . As observed,  $dC/dt$  is high initially, decreases monotonically with time, and appears to approach zero. The value of  $\tau_c$  at the depth of erosion at which  $dC/dt$ , and therefore  $\varepsilon$  that is proportional to  $dC/dt$ , becomes essentially zero has been interpreted to be equal to  $\tau_b$  (Mehta *et al.*, 1982a). This interpretation is based on the hypothesis that erosion continues as long as  $\tau_b > \tau_c$ . Erosion is arrested at the bed level at which  $\tau_b - \tau_c = 0$ . This interpretation, coupled with measurement of  $\rho_B(z_b)$ , i.e., the dry bed density profile, and the variation of  $C$  with time resulted in an empirical relationship for the rate of erosion of stratified beds. Utilizing this above approach, resuspension experiments with deposited beds were performed by Parchure (1980) in a rotating annular flume and by Dixit (1982) in a recirculating straight flume. The following empirical relationship between  $\varepsilon$  and  $\tau_b - \tau_c(z_b)$  was derived from these experiments:

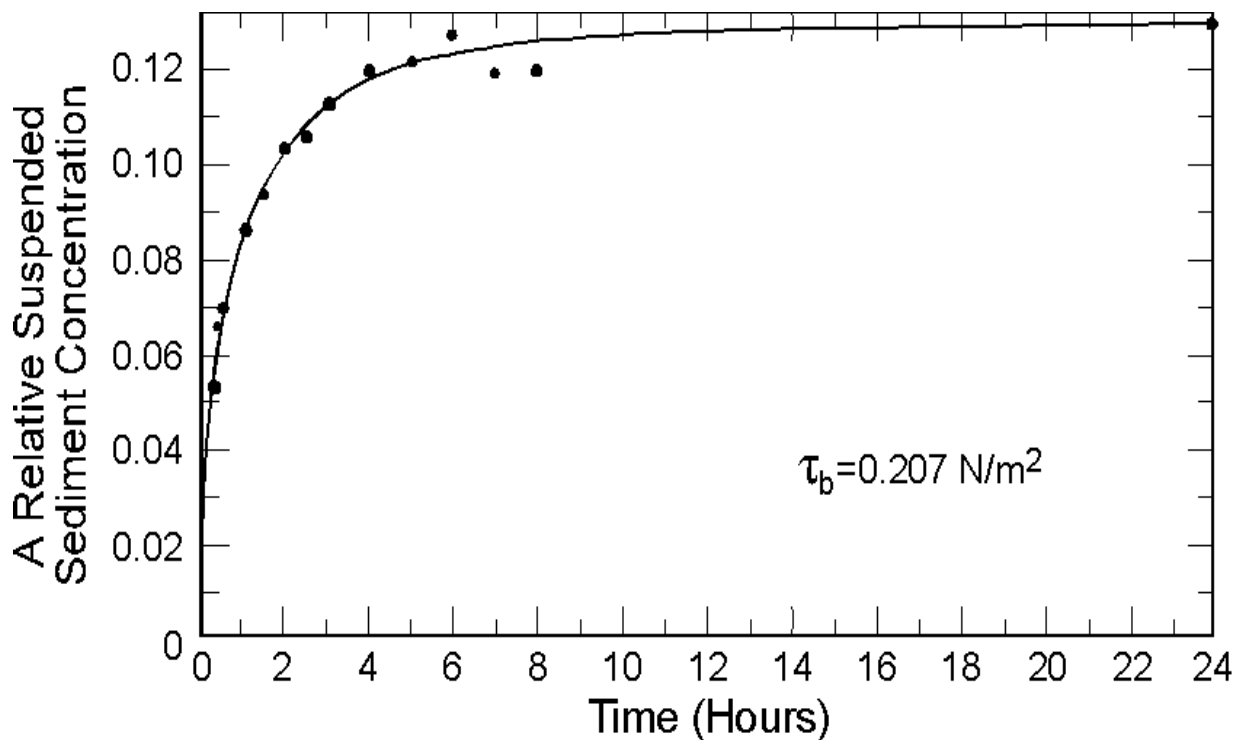


Figure A.5 Relative suspended sediment concentration versus time for a stratified bed (after Mehta and Partheniades, 1979)

$$\varepsilon = \varepsilon_o \exp \left[ \alpha \frac{\tau_b - \tau_c(z_b)}{\tau_c(z_b)} \right] \quad (\text{A.33})$$

where  $\varepsilon_o$  and  $\alpha$  are empirical resuspension coefficients. This relationship is analogous to the rate expression that results from a heuristic interpretation of rate process theory for chemical reactions (Mehta *et al.*, 1982a). Christensen and Das (1973), Paaswell (1973) and Kelley and Gularte (1981) have used the rate process theory in explaining the erosional behavior of cohesive sediment beds. By analogy,  $\varepsilon$  is a quantitative measure of the work done by  $\tau_b$  on the system, i.e., the bed, and  $\varepsilon_o$  and  $\alpha/\tau_c(z_b)$  are measures of the system's internal energy, i.e., bed resistance to an applied external force.

An important conclusion reached from these experiments was that new deposits should be treated differently from consolidated beds (Mehta *et al.*, 1982a). The rate of surface erosion of new deposits is best evaluated using Eq. A.33, while the erosion rate for settled beds is best determined using Eq. A.31, in which  $\varepsilon$  varies linearly with the normalized excess bed shear stress. The reasons for this differentiation in determining  $\varepsilon$  are twofold: 1) Typical  $\tau_c$  and  $\rho_B$  profiles in settled beds vary less significantly with depth than in new deposits, and may even be nearly invariant. Therefore, the value of  $(\tau_b / \tau_c) - 1 = \Delta \tau_b^*$  will be relatively small. For  $\Delta \tau_b^* \ll 1$  the exponential function in Eq. A.31 can be approximated by  $\alpha \cdot (1 + \Delta \tau_b^*)$  that represents the first two terms in the Taylor series expansion of  $\exp(\alpha \cdot \Delta \tau_b^*)$ . Thus, for small values of  $\Delta \tau_b^*$  both expressions for  $\varepsilon$  vary linearly with  $\Delta \tau_b^*$  and, therefore, the variation of  $\varepsilon$  with depth in settled beds can be just as accurately and more simply determined using Eq. A.31; and 2) The laboratory resuspension tests required to evaluate the coefficients  $\varepsilon_o$  and  $\alpha$  for each partially consolidated bed layer cannot be practically or easily performed using vertical sections of an original settled bed (obtained from cores). A simpler laboratory test has been described by Ariathurai and Arulanandan (1978) to evaluate the variability of  $M$  with depth.

Parchure and Mehta (1985) developed the following relationship for  $\varepsilon$  that is applicable for soft, cohesive sediment deposits such as the top, active layer of sediment beds in estuaries:

$$\varepsilon = \varepsilon_f \exp \left[ \alpha (\tau_b - \tau_s)^{1/2} \right] \quad (\text{A.34})$$

where  $\varepsilon_f$  = floc erosion rate ( $\text{gm/m}^2\text{-s}$ ),  $\tau_s$  = bed shear strength (Pa), and  $\alpha$  = a factor that can be shown to be inversely proportional to the absolute temperature (Parchure, 1984).  $\varepsilon_f$  is defined to be the erosion rate when the time-averaged bed shear stress is equal to the bed shear strength, i.e.,  $\tau_b = \tau_s$ . Even under this condition, some erosion of particles or flocs will occur due to the stochastic nature of turbulence and therefore in the instantaneous value of  $\tau_b$ .

Jepsen *et al.* (1997) studied the effect of sediment bulk density on erosion rates of three different types sediment during which the bulk densities of the sediments were experimentally determined as a function of depth into the sediment core for consolidation times varying from 1 to 60 days. The experiments were performed in a SEDFLUME (McNeil *et al.* 1996) during which the gross erosion rates were measured as a function of bed shear stress and depth into the core (from which the bulk density could be determined). The gross erosion rate,  $E$ , was approximated as a function of the bulk density and bed shear stress by the following equation:

$$E = A\tau^n\rho^m \quad (\text{A.35})$$

For the three sediments tested,  $n$  varied from 1.89 to 2.23;  $m$  varied from -45 to -95; and  $A$  varied from  $3.65 \times 10^3$  to  $2.69 \times 10^6$ . This equation for the gross erosion rate implicitly accounted for the effect of consolidation by including the time and depth varying bulk density as one of the independent parameters.

Sea salt is a mixture of salts, with monovalent sodium ions and divalent calcium and magnesium ions prevalent as natural electrolytes. The sodium adsorption ratio ( $SAR$ ), defined as,

$$SAR = \frac{Na^+}{\left[ \frac{1}{2}(Ca^{2+} + Mg^{2+}) \right]^{1/2}} \quad (\text{A.36})$$

is a measure of the relative abundance of the three mentioned salts (cations). The cation concentrations in this equation are in milliequivalents per liter (Arulanandan, 1975). Sherard *et al.* (1972) have shown that the susceptibility of a cohesive sediment bed to erosion depends on two factors: 1) the pore fluid composition, as characterized by the  $SAR$ ; and 2) the salinity of the eroding fluid. It was found that, as the eroding fluid salinity decreases, soil resistivity to resuspension decreases. In addition, Kandiah (1974) and Arulanandan *et al.* (1975) found that erosion resistance decreased and the rate of resuspension increased with increasing  $SAR$  (and therefore decreasing valency of the salt cations) of the pore fluid.

Once eroded from the bed, cohesive sediment is transported mostly as suspended load, though the author has observed clumps of cohesive sediments (i.e., mud) rolling along the bottom of both laboratory flumes and shallow rivers. The latter form of transport cannot be predicted at present. The transport of both unflocculated and flocculated cohesive sediments in suspension is the result of three processes: 1) advection - the sediment is assumed to be transported at the speed of the local mean flow; 2) turbulent diffusion - driven by spatial suspended sediment concentration gradients, the material is diffused laterally across the width of the flow channel, vertically over the depth of flow, and longitudinally in the direction of the transport; and 3) longitudinal dispersion - the suspended sediment is dispersed in the flow direction by spatial velocity gradients (Ippen, 1966).

The principle of conservation of mass with appropriate source and sink terms describes the advective and dispersive transport of suspended sediment in a turbulent flow field. This principle, expressed by the advection-dispersion equation, says that the time-rate of change of mass of sediment in a stationary control volume is equated to the spatial rate of change of mass due to advection by an external flow field plus the spatial rate of change of mass due to turbulent diffusion and dispersion processes. The three-dimensional form of the advection-dispersion transport equation is:

$$\begin{aligned} \frac{\partial C}{\partial t} + u \frac{\partial C}{\partial x} + v \frac{\partial C}{\partial y} + (w - w_{sc}) \frac{\partial C}{\partial z} = \frac{\partial}{\partial x} \left[ K_{xx} \frac{\partial C}{\partial x} + K_{xy} \frac{\partial C}{\partial y} + K_{xz} \frac{\partial C}{\partial z} \right] \\ + \frac{\partial}{\partial y} \left[ K_{yx} \frac{\partial C}{\partial x} + K_{yy} \frac{\partial C}{\partial y} + K_{yz} \frac{\partial C}{\partial z} \right] + \frac{\partial}{\partial z} \left[ K_{zx} \frac{\partial C}{\partial x} + K_{zy} \frac{\partial C}{\partial y} + K_{zz} \frac{\partial C}{\partial z} \right] + S_T \end{aligned} \quad (\text{A.37})$$

where  $K_{ij}$  = effective sediment dispersivity tensor, and  $S_T$  = the net source/sink term that accounts for source(s) (i.e., addition) of sediment to the water column due to erosion and other inputs, and sink(s) (i.e., loss) of sediment due to deposition and other removals. Implicit in this equation is the assumption that suspended material has the same velocity as the water. Sayre (1968) verified the reasonableness of this assumption for sediment particles less than about 100  $\mu\text{m}$  in diameter. Rolling and saltation of sediment that occur during bed load transport can result in a significant difference between the water and sediment velocities. Therefore, the assumption of equal velocity is not applicable to bed load. The net source/sink term in Eq. A.37 can be expressed as:

$$S = \left. \frac{dC}{dt} \right|_e + \left. \frac{dC}{dt} \right|_d + S_L \quad (\text{A.38})$$

where  $\left. \frac{dC}{dt} \right|_e$  is the rate of sediment addition (source) due to erosion from the bed, and  $\left. \frac{dC}{dt} \right|_d$  is

the rate of sediment removal (sink) due to deposition of sediment.  $S_L$  accounts for removal (sink) of a certain mass of sediment, for example, by dredging in one area (e.g., a navigational channel) of a water body, and/or dumping (source) of sediment as dredge spoil in another location.

The dispersive transport terms in Eq. A.37 include the effects of spatial velocity variations in bounded shear flows and turbulent diffusion. Thus, the effective sediment dispersivity tensor in Eq. A.37 must include the effect of all processes whose scale is less than the grid size of the model, or, in other words, what has been averaged over time and/or space (Fischer *et al.*, 1979).

Turbulent diffusion is defined as “the transport in a given direction at a point in the flow due to the difference between the true advection in that direction and the time average of the advection in that direction,” and dispersion is defined as “the transport in a given direction due to the difference between the true advection in that direction and the spatial average of the advection in that direction” (Holley, 1969). Holley delineates the fact that diffusion and dispersion are both actually advective transport mechanisms, and that in a given flow field, the relative importance of

one mechanism over the other depends on the magnitude of the concentration gradient. In Eq. A.37, the effective sediment dispersion coefficients are equal to the sum of the turbulent diffusion and dispersion coefficients. This approach follows the analysis of Aris (1956) that showed that the coefficients due to turbulent diffusion and shear flow (dispersion) were additive. Thus, analytical expressions used for the effective sediment dispersion tensor should represent both diffusion and dispersion.

Fischer (1966) showed that the dispersion of a given quantity of tracer injected into a natural stream is divided into two separate phases. The first is the convective period in which the tracer mixes vertically, laterally, and longitudinally until it is completely distributed across the stream. The second phase is the diffusive period during which the lateral, and possibly the vertical (depending on the nature of the tracer), concentration gradient is small, and the longitudinal concentration profile is highly skewed. Equation A.37 is strictly valid only in the diffusive period. The criterion for determining whether the dispersing tracer is in the diffusive period is if it has been in the flow longer than the Lagrangian time scale and has spread over a distance wider than the Lagrangian length scale (Fischer *et al.*, 1979). The latter scale is a measure of the distance a particle travels before it forgets its initial conditions (i.e., initial position and velocity).

Analytical expressions for the sediment (mass) diffusion coefficients can be obtained by analogy with the kinematic eddy viscosity. The Reynolds analogy assumes that the processes of momentum and mass transfer are similar, and that the turbulent diffusion coefficient and the kinematic eddy viscosity,  $\varepsilon_v$ , are linearly proportional. Jobson and Sayre (1970) verified the Reynolds analogy for sediment particles in the Stokes range (less than about 100  $\mu\text{m}$  in diameter). They found that the “portion of the turbulent mass transfer coefficient for sediment particles that is directly attributable to tangential components of turbulent velocity fluctuations: (a) is approximately proportional to the momentum transfer coefficient and the proportionality constant is less than or equal to 1; and (b) decreases with increasing particle size”. Therefore, the effective sediment mass dispersion coefficients for cohesive sediments may be justifiably assumed to be equal to those for the water itself.

Fischer *et al.* (1979) define four primary mechanisms of dispersion in estuaries: 1) gravitational circulation, 2) shear-flow dispersion, 3) bathymetry-induced dispersion and 4) wind-induced circulations. The last three mechanisms occur in freshwater water bodies as well. Gravitational or baroclinic circulation in estuaries is the flow induced by the density difference between freshwater at the landward end and sea water at the ocean end. There are two types of gravitational circulation. Transverse gravitational circulation is depth-averaged flow that is predominantly seaward in the shallow regions of a cross-section and landward in the deeper parts. The interaction between the cross-sectional bathymetry and baroclinic flow causes the transverse circulation. Vertical gravitational circulation occurs with predominantly seaward flow in the upper part of the water column and landward flow in the lower part of the water column. Fischer (1972) said that vertical gravitational circulation is more important than transverse circulation only in highly stratified estuaries.

The mechanism of shear-flow dispersion is thought to be the dominant mechanism in long, fairly uniform sections of well-mixed and partially stratified estuaries (Fischer *et al.*, 1979). Holley *et al.* (1970) concluded that for wide estuaries, the effect of the vertical velocity distribution on shear-flow dispersion is dominant over that of the transverse velocity distribution. The exact opposite situation was found for relatively narrow estuaries.

The joint influence of bathymetry and density differences on dispersion has already been mentioned in reference to baroclinic circulation. Other examples of bathymetry-induced dispersion include: intrusion of salinity or sediment into certain parts of a cross-section caused by channelization of flood and ebb tides in tidal inlets or narrow estuaries (Fischer *et al.*, 1979), and enhanced dispersion of dissolved substances of concern (e.g., a contaminant) or intrusion of salinity into tidal flats and side embayments that then serve as storage areas for these substances, caused by the out-of-phase flow that occurs between the main channel and such features (Okubo, 1973).

An example of wind-induced circulation is shown in Figure A.6. Here, the steady onshore wind causes circulation in the wind direction in a shallow bay, where the smaller water mass per unit surface area results in a higher acceleration and, therefore, quicker response to the wind-induced surface stresses, and circulation in the opposite direction in the deeper sections of the channel. Such a circulation can cause significant dispersion (Fischer *et al.*, 1979).

The settling rate of coagulated sediment particles depends on, in part, the size and density of the flocs, and as such is a function of the processes of coagulation and flocculation (Owen, 1970). Therefore, the factors that govern these two processes also affect the settling rate of the resulting flocs. The settling velocities of flocs can be several orders of magnitude larger than those of individual clay particles (Bellessort, 1973). For flocs from 10 to 1,000  $\mu\text{m}$  in size, settling velocities have been found to range from  $10^{-5}$  to  $10^{-1}$  m/s (Dyer, 1989).

The following four settling zones have been identified for flocs: free settling, flocculation settling, hindered settling, and negligible settling. In the free settling zone, the settling velocities are independent of the suspension concentration. In the flocculation zone, the settling velocities increase with increasing suspension concentration due to increased interparticle collisions that result in the formation of larger and denser flocs. In the hindered settling zone, the upward transport of interstitial water is inhibited (or hindered) by the high suspension concentration. This, in turn, results in a decrease in the floc settling velocity with increasing suspension concentration. At the upper end of the hindered settling zone, the suspension concentration near the bed is so high that no settling of flocs occurs. Hwang (1989) proposed the following expressions for the floc settling velocity:

$$w_{sf} = \begin{cases} w_{sf} & \text{for } C < C_1 \\ a_w \frac{C^{n_w}}{(C^2 + b_w^2)^{m_w}} & \text{for } C_1 < C < C_3 \\ 1.1 & C > C_3 \end{cases} \quad (\text{A.39})$$



where  $w_{sf}$  = free settling velocity,  $a_w$  = velocity scaling coefficient,  $n_w$  = flocculation settling exponent,  $b_w$  = hindered settling coefficient,  $m_w$  = hindered settling exponent,  $C_1$  = concentration between the free settling and flocculation settling zones,  $C_3$  = concentration at the upper limit of the hindered settling zone, and though not included in Eq. A.39,  $C_2$  = concentration between the flocculation and hindered settling zones (where  $w_{sf}$  is maximum). Ranges of values for  $C_1$ ,  $C_2$ , and  $C_3$  are 100 - 300 mg/L, 1,000 - 15,000 mg/L, and on the order of 75,000 mg/L, respectively (Krone, 1962; Odd and Cooper, 1989).

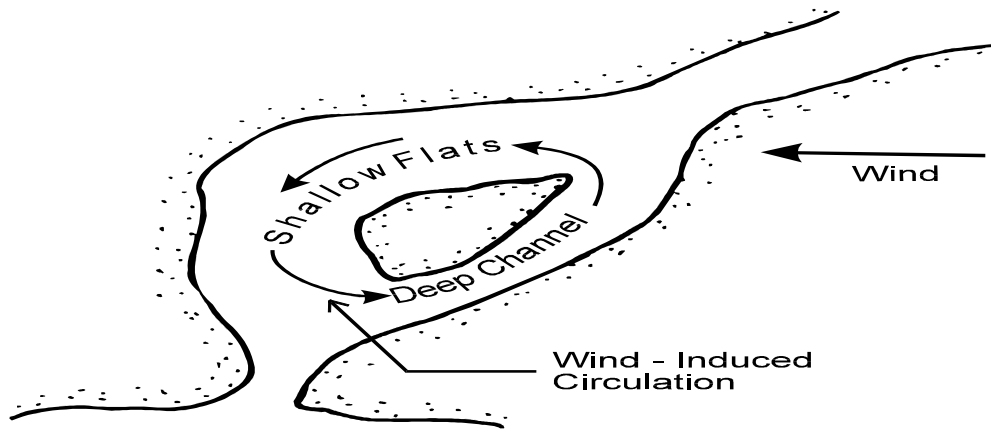


Figure A.6 Illustration of wind-induced circulation (adapted from Fischer *et al.*, 1979)

Shrestha and Orlob (1996) developed the following expression for the settling velocity of flocs that accounts for the effect of both the suspension concentration and flow shear:

$$w_{sf} = C^\alpha \exp(-4.21 + 0.147G) \quad (\text{A.40})$$

where  $\alpha = 0.11 + 0.039G$ , and  $G = \sqrt{\left(\frac{\partial u}{\partial z}\right)^2 + \left(\frac{\partial v}{\partial z}\right)^2}$ ; i.e.,  $G$  is the magnitude of the vertical shear of the horizontal velocity.

Burban *et al.* (1990) found that the settling velocity of flocs was related to the following power law function of the median floc diameter,  $D_f$ :

$$w_{sf} = aD_f^m \quad (\text{A.41})$$

where  $a = B_f(CG)^{-0.85}$

and  $b = -[0.8+0.5\log(CG-B_2)]$

with  $B_1$  and  $B_2$  = experimentally determined constants.

Deposition of flocs occurs relatively quickly during slack water. Settling and deposition also occurs in slowly moving and decelerating flows, as was observed in the Savannah River Estuary (refer back to Figure A.3) during the second half of flood and ebb flows (Krone, 1972). Under these flow conditions, only those flocs with shear strengths of sufficient magnitude to withstand the highly disruptive shear stresses in the near bed region will actually deposit and adhere to the bed. Thus, deposition is governed by the bed shear stresses, turbulence structure above the bed, settling velocity, type of sediment, depth of flow, suspension concentration, and ionic constitution of the suspending fluid (Mehta and Partheniades, 1973). Specifically, deposition has been defined to occur when  $\tau_b$  is not high enough to resuspend sediment material that settles onto and bonds with the bed surface. This process, therefore, involves two other processes, settling and bonding.

Laboratory studies on the depositional behavior of cohesive sediment in steady turbulent flows have been conducted by, among others, Krone (1962), Rosillon and Volkenborn (1964), Partheniades (1965), Lee (1974), Mehta and Partheniades (1975), Mehta *et al.* (1982b), Mehta and Lott (1987), Shrestha and Orlob (1996), and Teeter (2000).

The most commonly used expression for the sediment mass deposition rate, given initially by Einstein and Krone (1962), is:

$$\frac{dC}{dt} = -\frac{w_{sc} C}{d} \left( 1 - \frac{\tau_b}{\tau_{cd}} \right) \quad (\text{A.42})$$

where  $\tau_{cd}$  = critical shear stress for deposition, above which no deposition occurs. The value of  $\tau_{cd}$  was found to be equal to 0.06 Pa for San Francisco Bay mud with  $C < 300$  mg/L (Krone, 1963), and values from 0.02 to 0.2 Pa have been reported in the literature. Mehta and Lott (1987) found Eq. A.42 to agree reasonably well with laboratory data for suspended sediment concentrations up to approximately 1,000 mg/L.

A cohesive sediment bed is formed when deposited sediment particles and/or flocs comprising a stationary suspension begin to interact and form a soil that transmits an effective stress by virtue of particle-to-particle contacts. The self-weight of the particles, as well as deposition of additional material, brings the particles closer together by expulsion of pore water between the particles. A soil is formed when the water content of the sediment-water suspension decreases to the fluid limit. Unfortunately, there is not a unique water content value for cohesive soils at which the suspension changes into a soil (Been and Sills, 1981).

During the transition from suspension to soil, an extremely compressible soil framework or skeleton develops (Been and Sills, 1981). The strains involved in this first stage of consolidation are relatively large and can continue for several days or even months. The straining

and upward expulsion of pore water gradually decreases as the soil skeleton continues to develop. Eventually, this skeleton reaches a state of equilibrium with the normal stress component of the overlying sediment (Parker and Lee, 1979).

During the early stages of consolidation, the self-weight of the soil mass near the bed surface is balanced by the seepage force induced by the upward flow of pore water from the underlying sediment. As the soil continues to undergo self-weight consolidation and the upward flux of pore water lessens, the self-weight of this near surface soil gradually turns into an effective stress. This surface stress and the stress throughout the soil will first crush the soil floc structure and then the flocs themselves. Primary consolidation is defined to end when the excessive pore water pressure has completely dissipated (Spangler and Handy, 1982). Secondary consolidation, that can continue for many weeks or months, is the result of plastic deformation of the soil under its overburden.

The shear strength of clays is due to the frictional resistance and interlocking between particles (physical component), and interparticle forces (physicochemical component) (Karcz and Shanmugam, 1974; Parchure, 1980). Consolidation results in increasing bed density and shear strength (Hanzawa and Kishida, 1981). Figure A.7 shows the increase in the shear strength profile with consolidation time and bed depth for flow-deposited kaolinite beds in tap water.

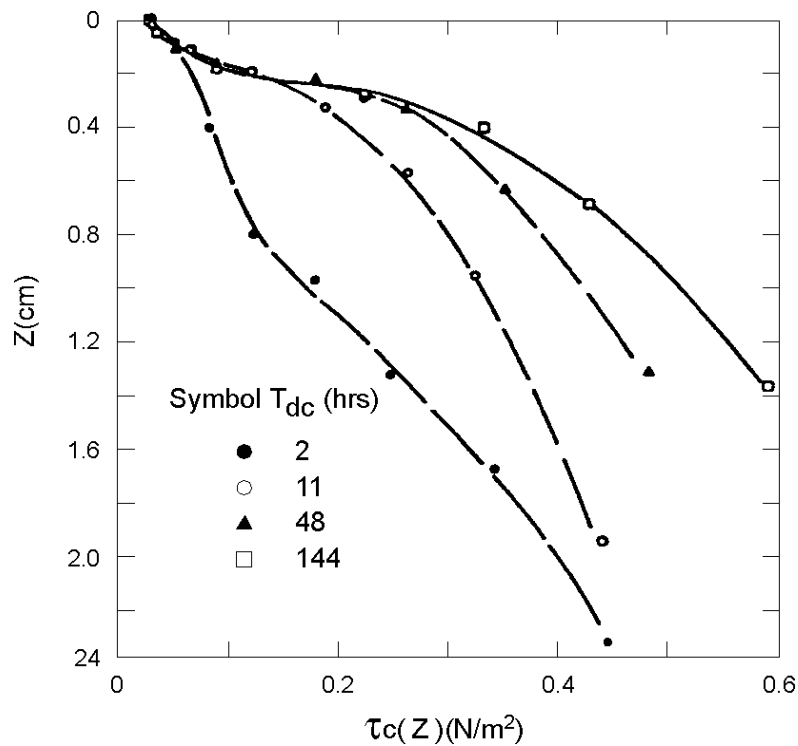


Figure A.7 Bed shear strength versus distance below the initial bed surface for various consolidation periods (after Dixit, 1982)

## APPENDIX B

### Sediment Gradation Scale (adapted from ASCE, 1975)

Sediment Class Name	Size Range (mm)	Size Range ( $\mu\text{m}$ )
Very large boulders	4096 - 2048	
Large boulders	2048 - 1024	
Medium boulders	1024 - 512	
Small boulders	512 - 256	
Large cobbles	256 - 128	
Small cobbles	128 - 64	
Very coarse gravel	64 - 32	
Coarse gravel	32 - 16	
Medium gravel	16 - 8	
Fine gravel	8 - 4	
Very fine gravel	4 - 2	
Very coarse sand	2 - 1	2000 - 1000
Coarse sand	1 - 0.5	1000 - 500
Medium sand	0.5 - 0.25	500 - 250
Fine sand	0.25 - 0.125	250 - 125
Very fine sand	0.125 - 0.063	125 - 63
Coarse silt	0.063 - 0.031	63 - 31
Medium silt	0.031 - 0.016	31 - 16
Fine silt	0.016 - 0.008	16 - 8
Very fine silt	0.008 - 0.004	8 - 4
Coarse clay	0.004 - 0.002	4 - 2
Medium clay	0.002 - 0.001	2 - 1
Fine clay	0.001 - 0.0005	1 - 0.5
Very fine clay	0.0005 - 0.00024	0.5 - 0.24

## **APPENDIX C**

### **Computation Grid for the EFDC Model**

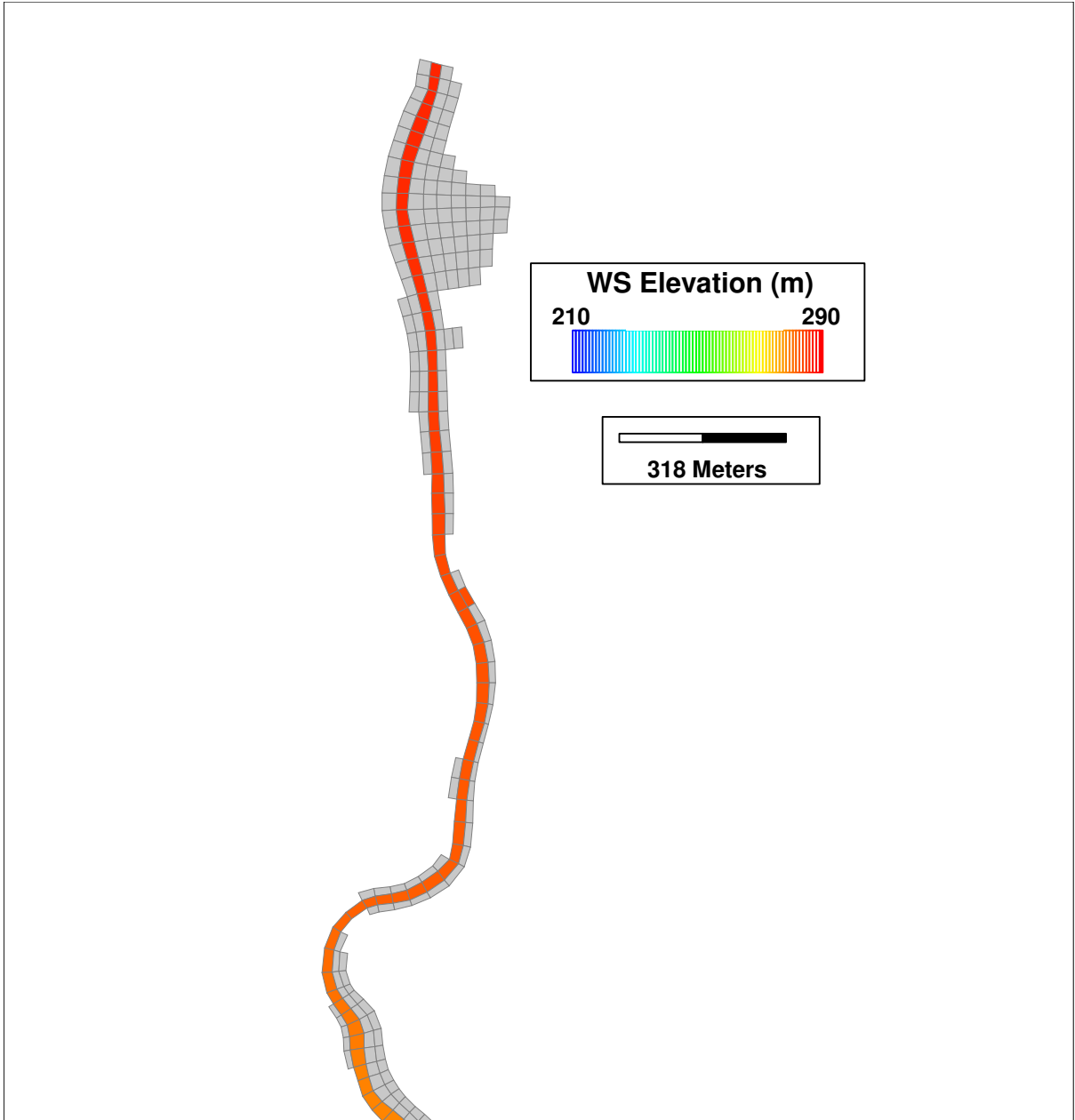


Figure C.1 Computation grid for EFDC model. The upstream boundary is at the top of this figure. North is up in this figure.

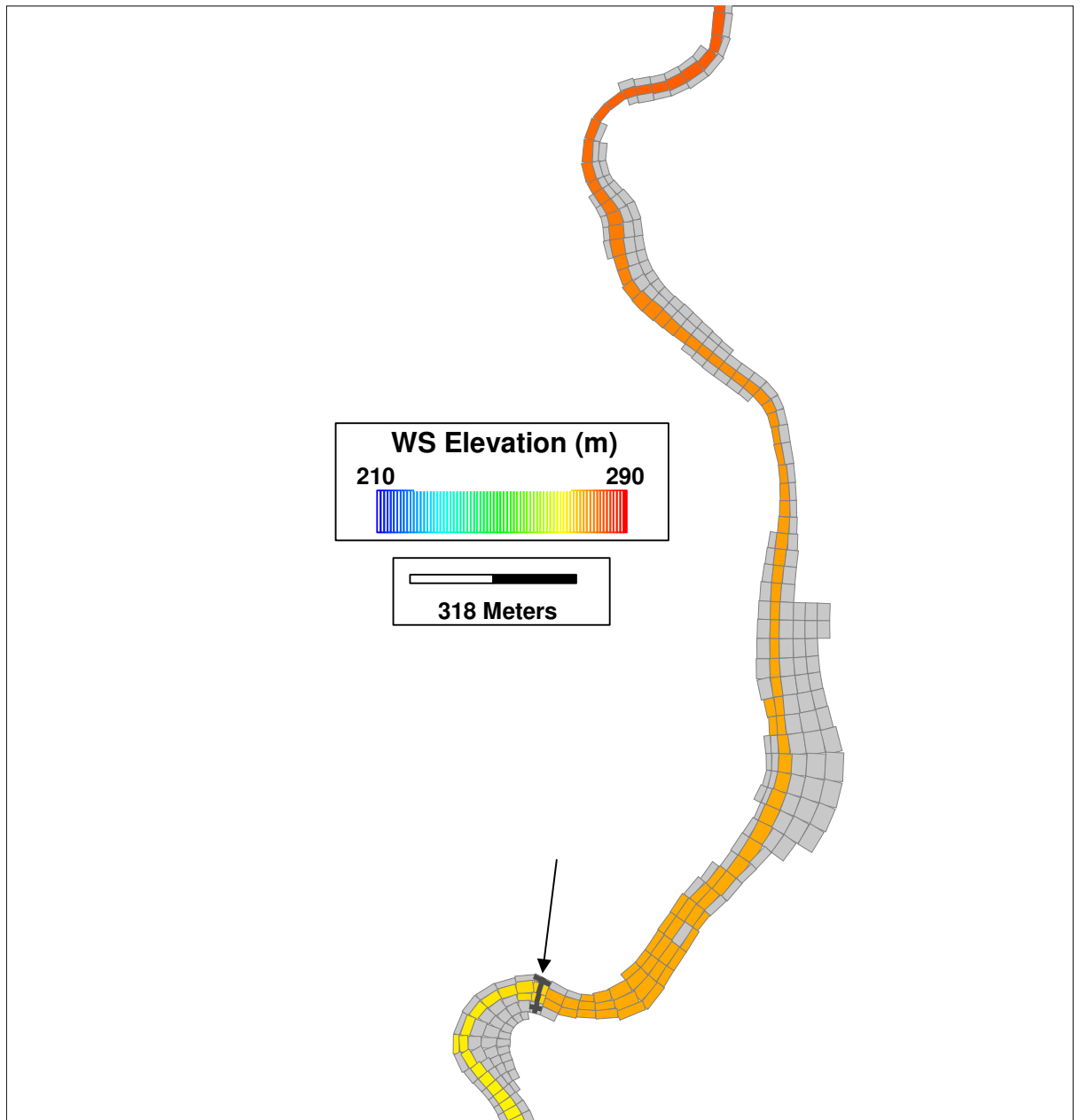


Figure C.2 Computation grid for EFDC model. The arrow points to Columbia Mill Dam. North is up in this figure.

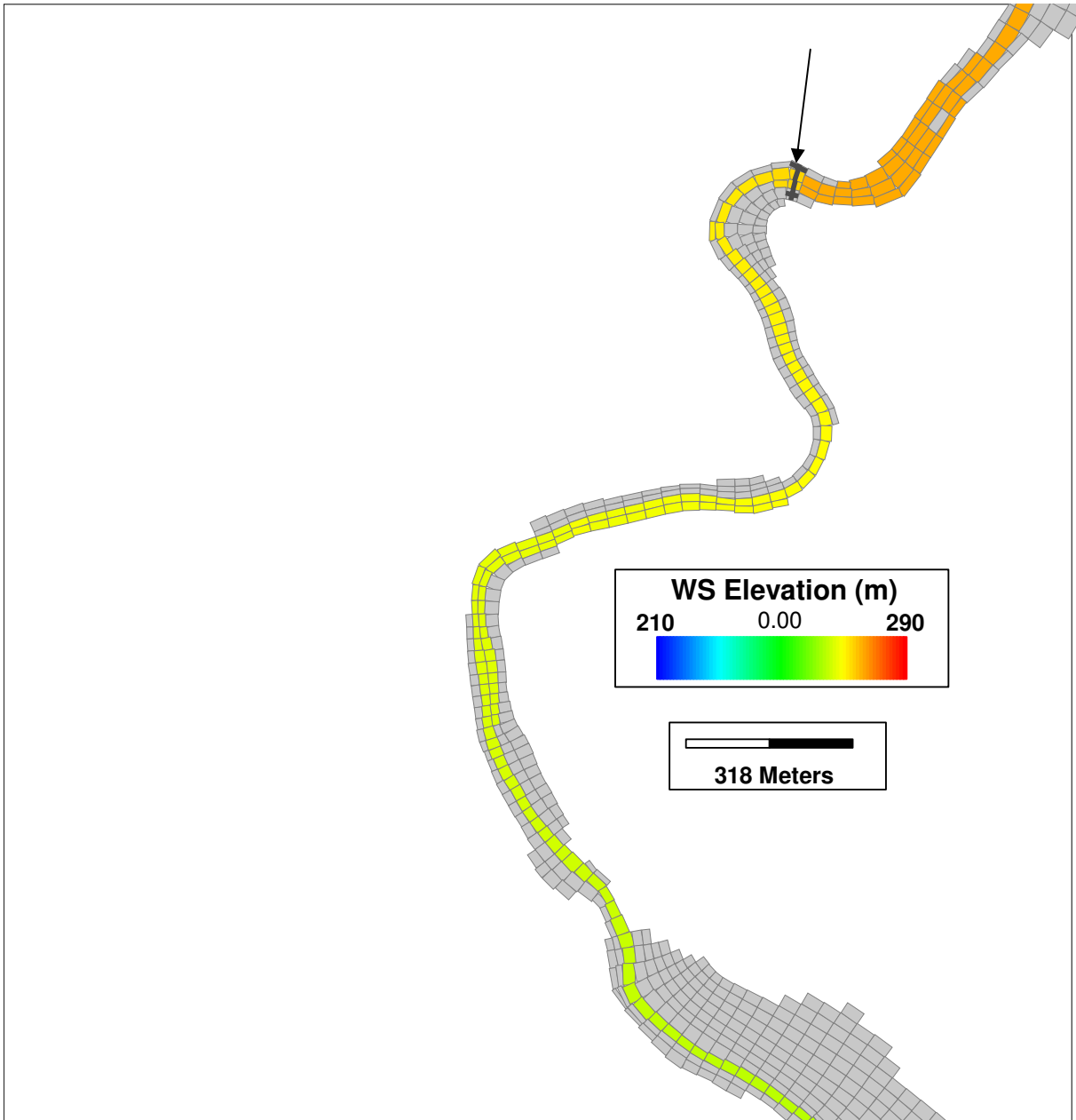


Figure C.3 Computation grid for EFDC model. The arrow points to Columbia Mill Dam. North is up in this figure.



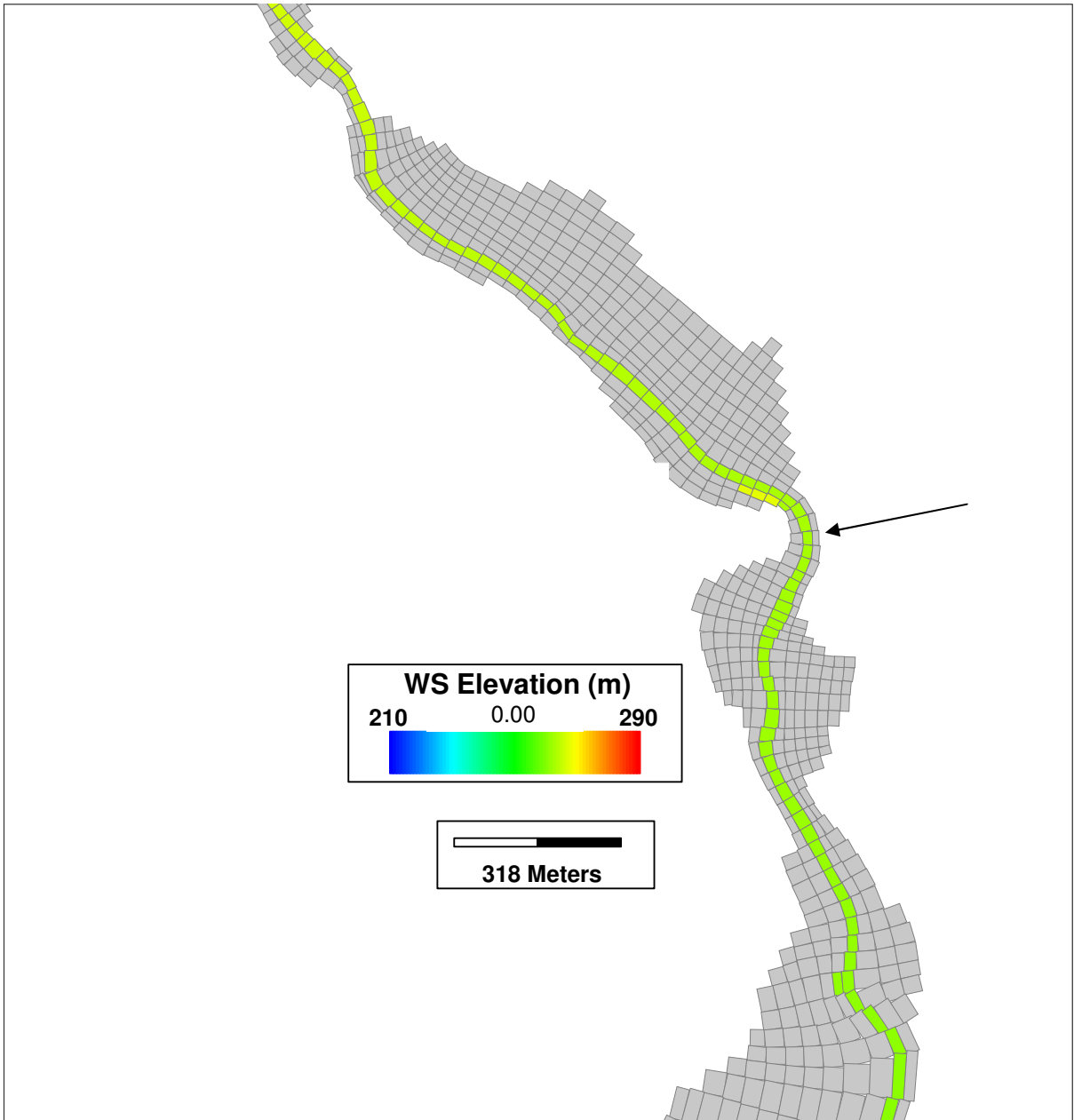


Figure C.4 Computation grid for EFDC model. Arrow identifies the location of the I-90 bridge over the Housatonic River. North is up in this figure.

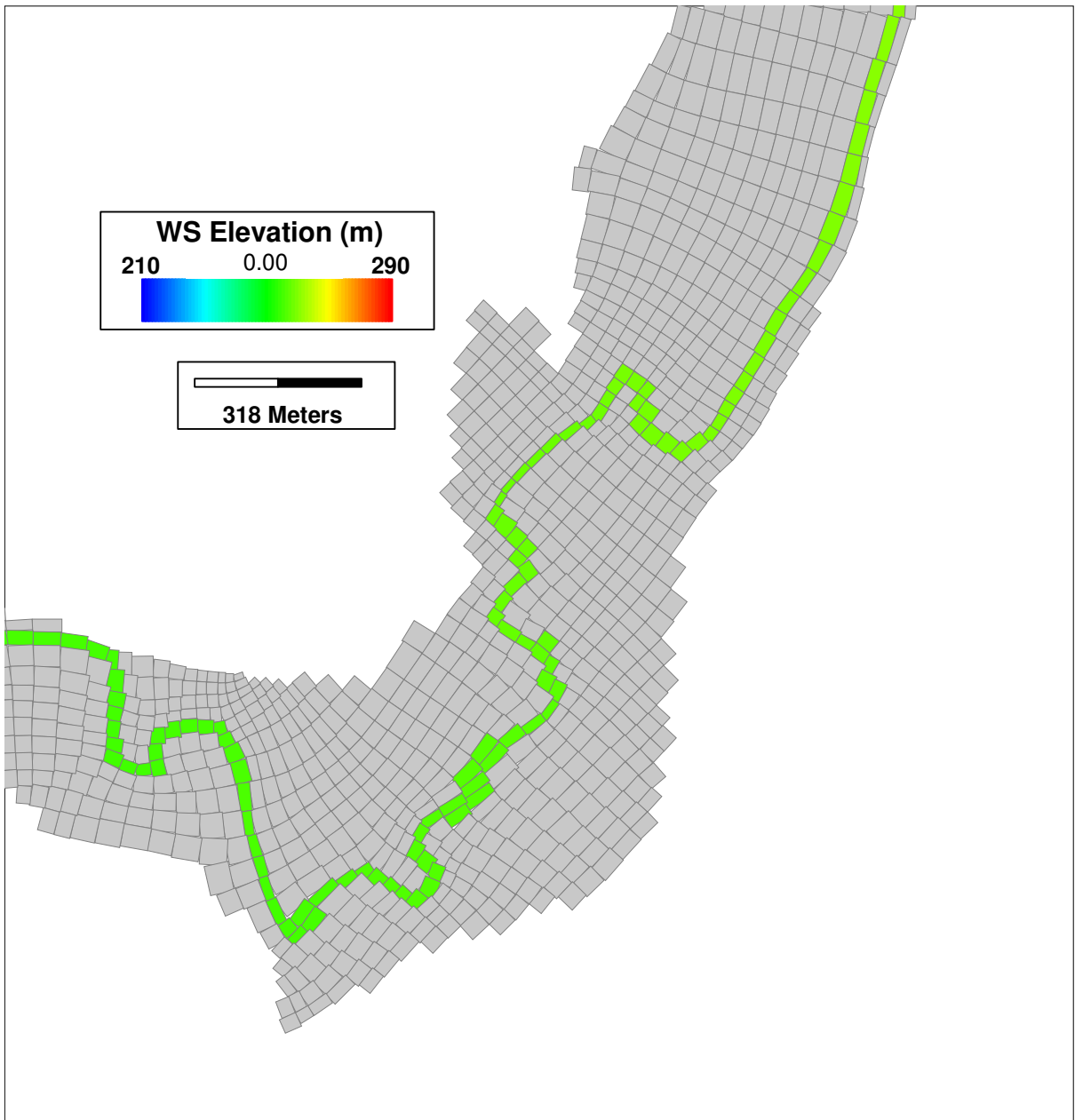


Figure C.5 Computation grid for EFDC model. This is the meandering reach of the river downstream of the town of Lee. North is up in this figure.



Figure C.6 Computation grid for EFDC model. The arrow points to the start of a much narrower floodplain downstream of the meanders. North is up in this figure.

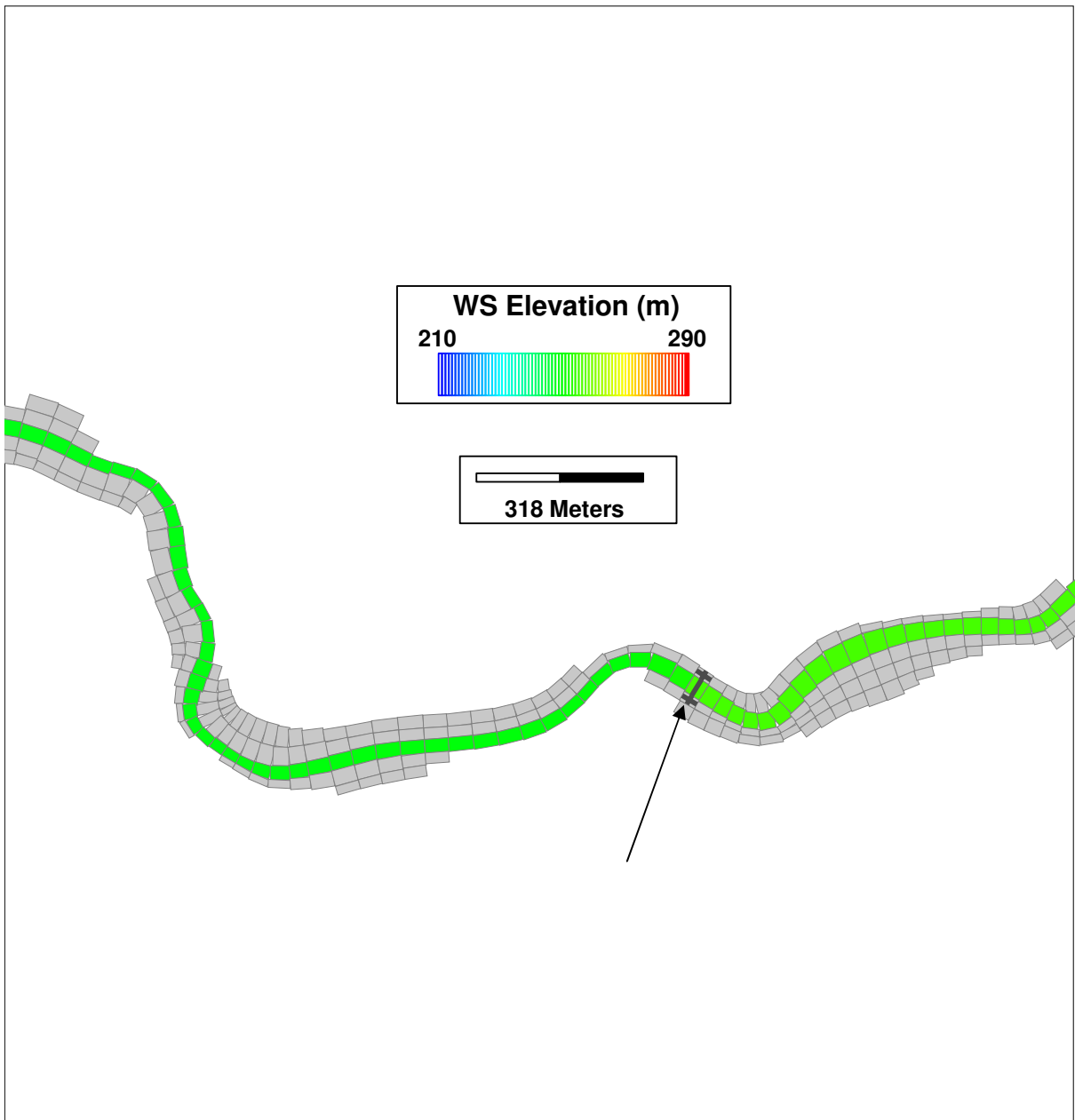


Figure C.7 Computation grid for EFDC model. The arrow points to Willow Mill Dam. North is up in this figure.

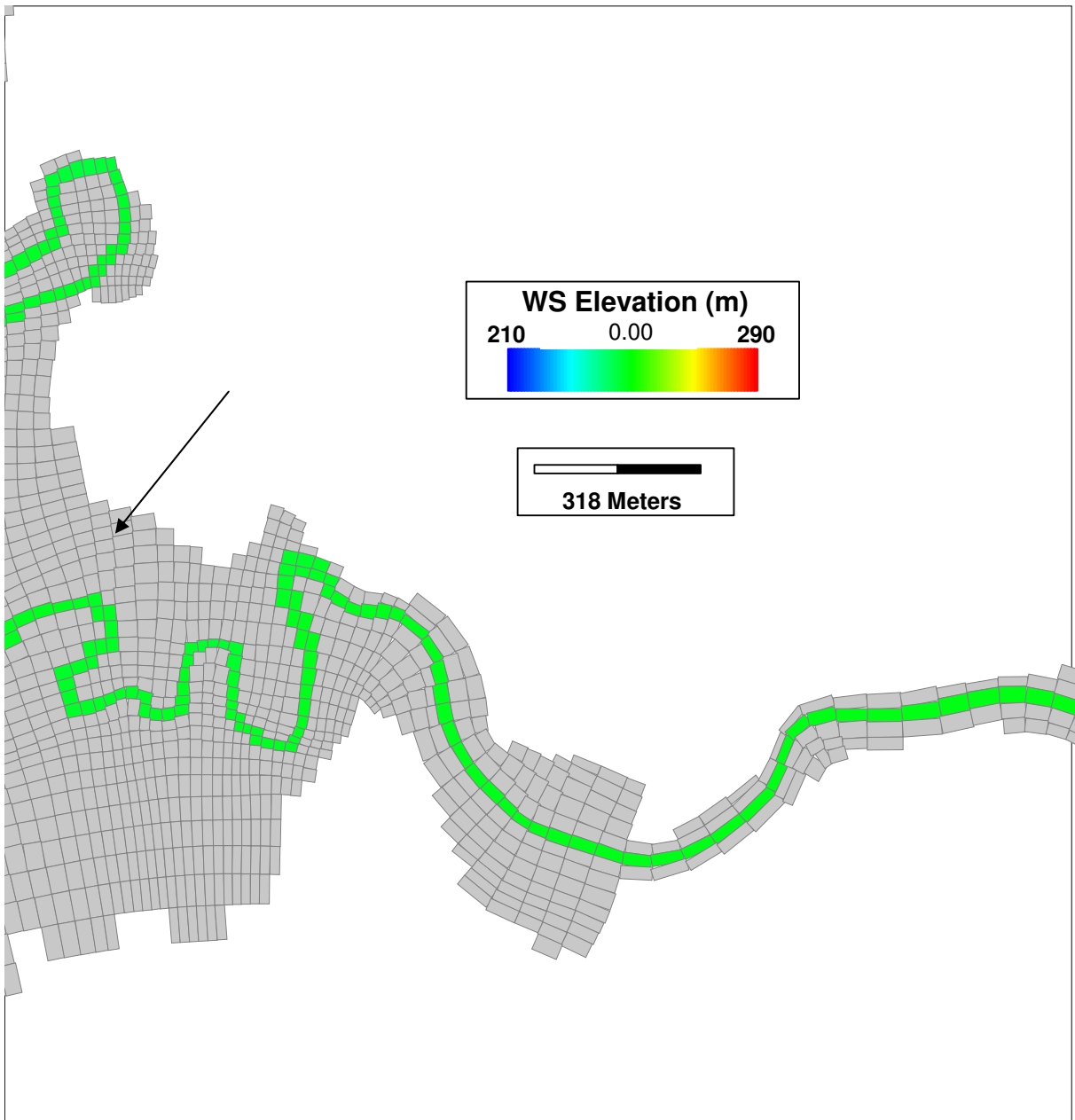


Figure C.8 Computation grid for EFDC model. The arrow points to the middle portion of the Stockbridge golf course. North is up in this figure.

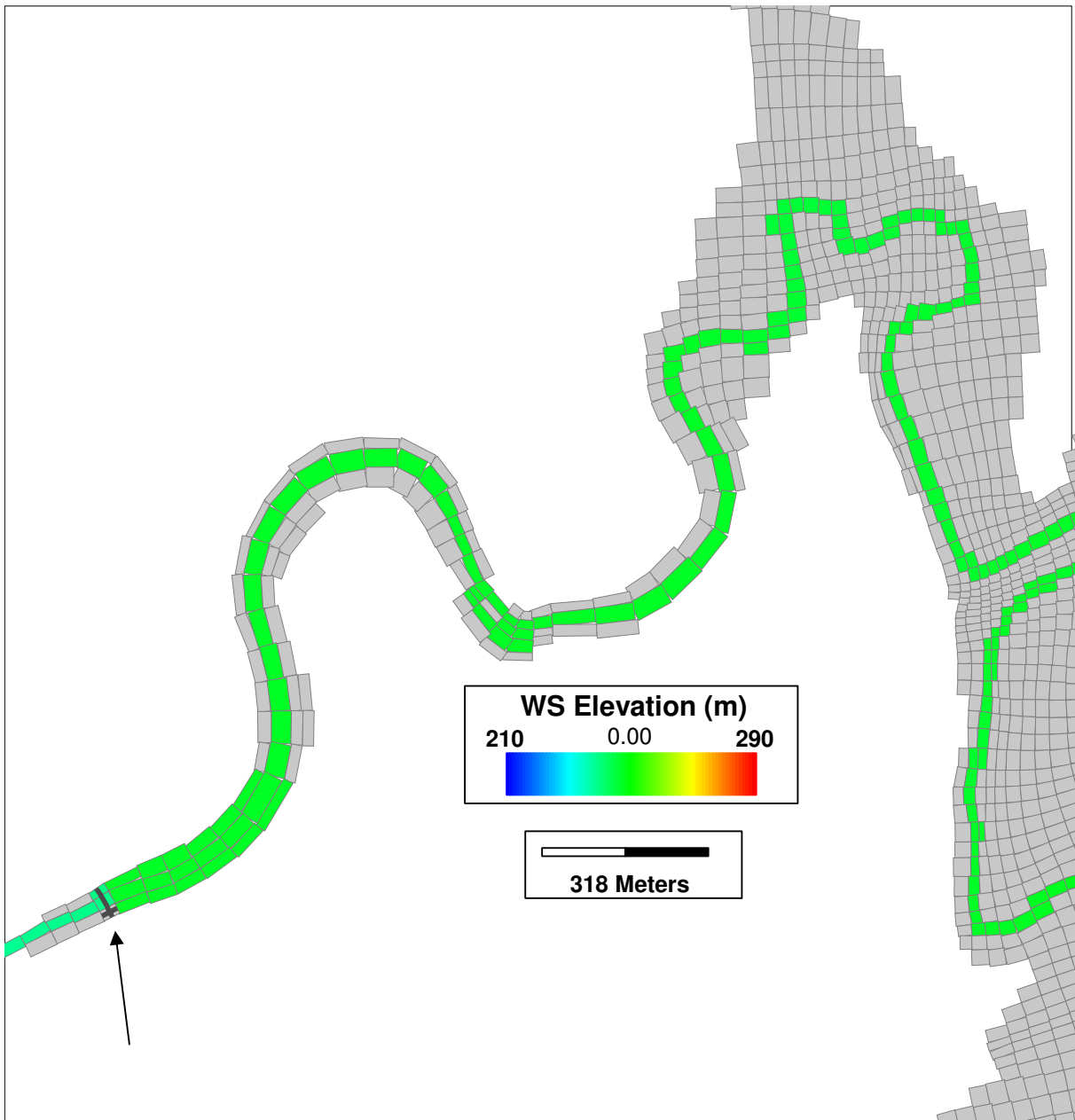


Figure C.9 Computation grid for EFDC model. The arrow points to Glendale Dam. North is up in this figure.

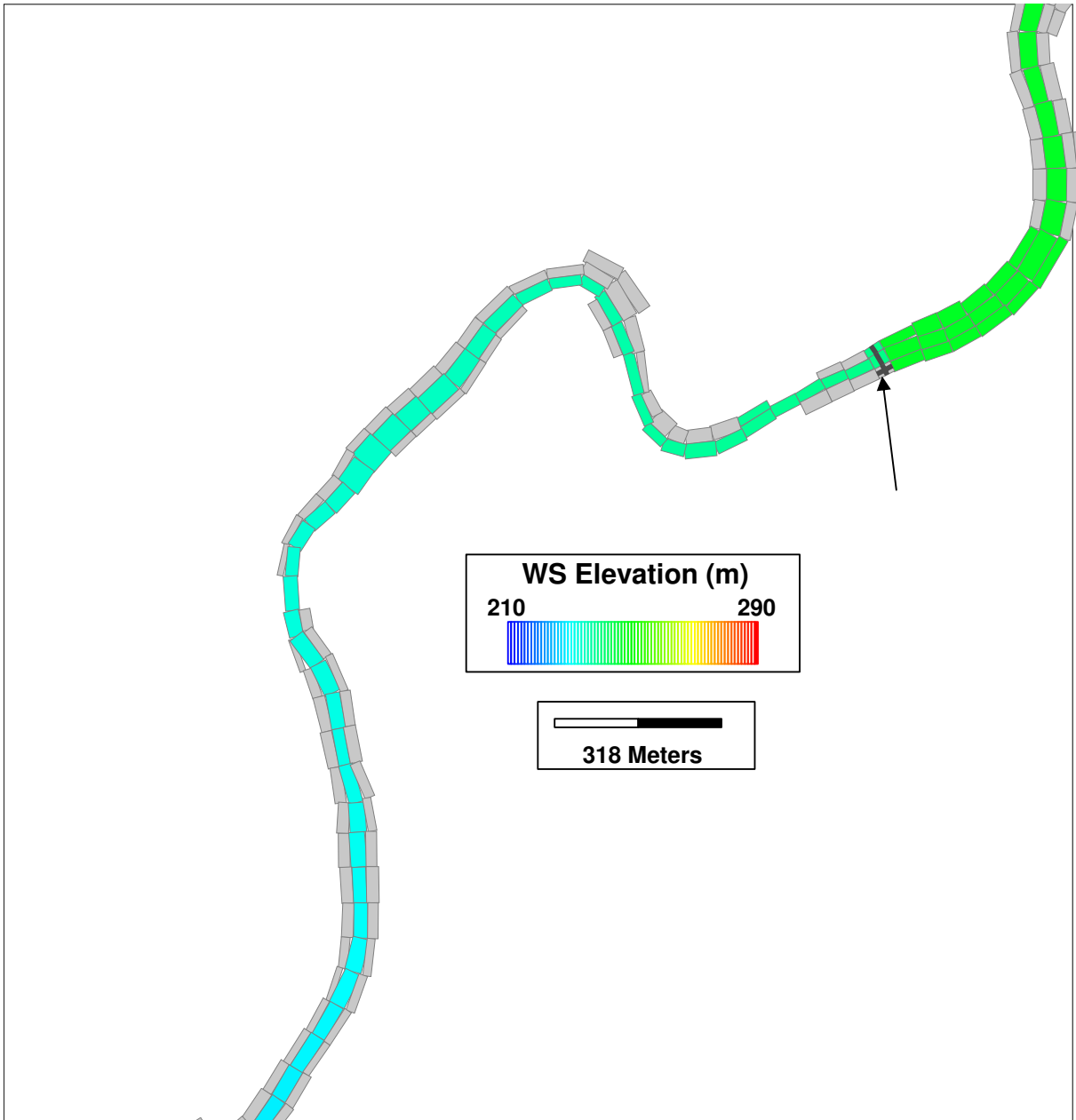


Figure C.10 Computation grid for EFDC model. The arrow points to Glendale Dam. The reach downstream of the dam is the steepest in the modeling domain. North is up in this figure.

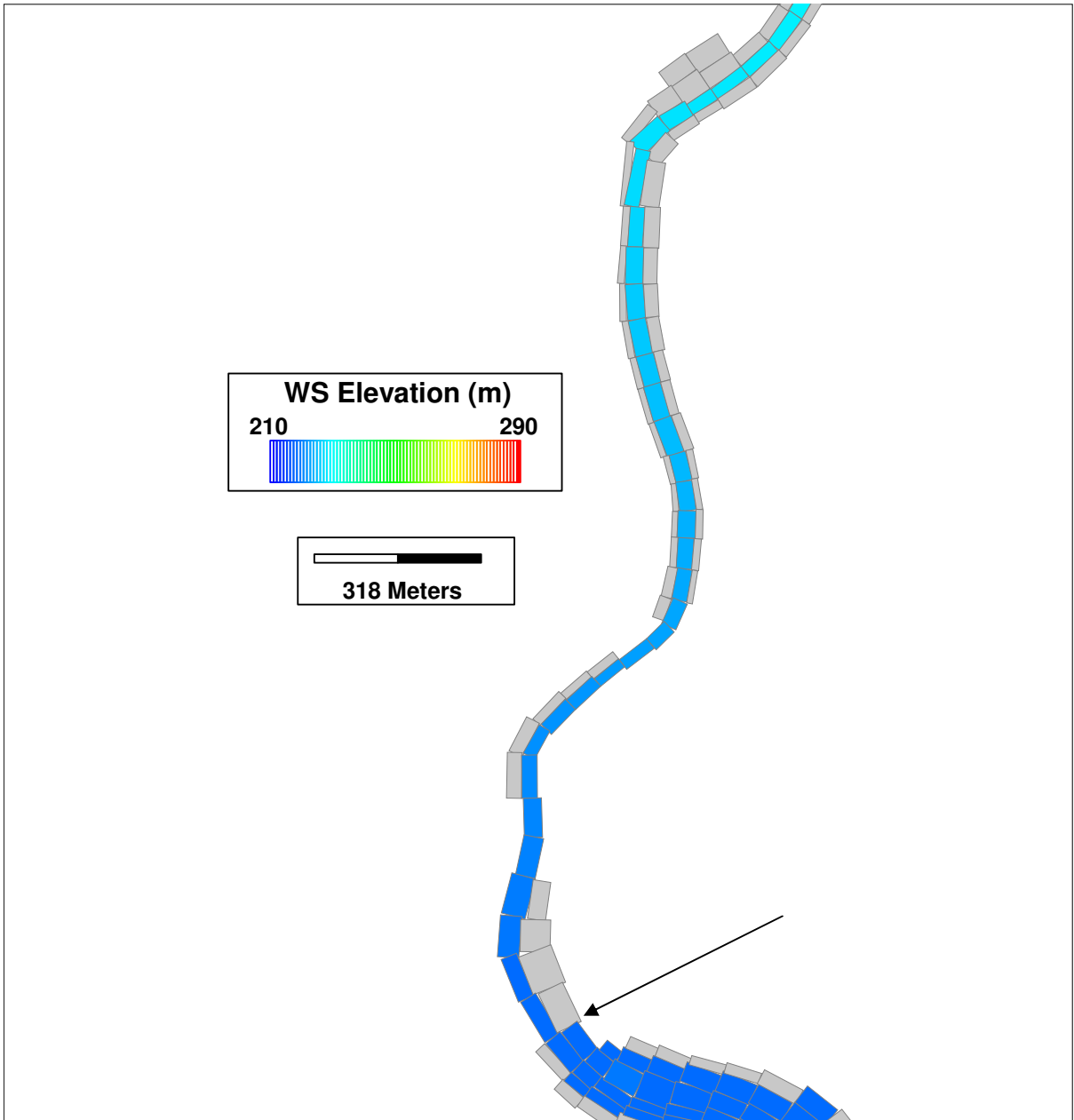


Figure C.11 Computation grid for EFDC model. The arrow points to the upstream end of Rising Pond. North is up in this figure.



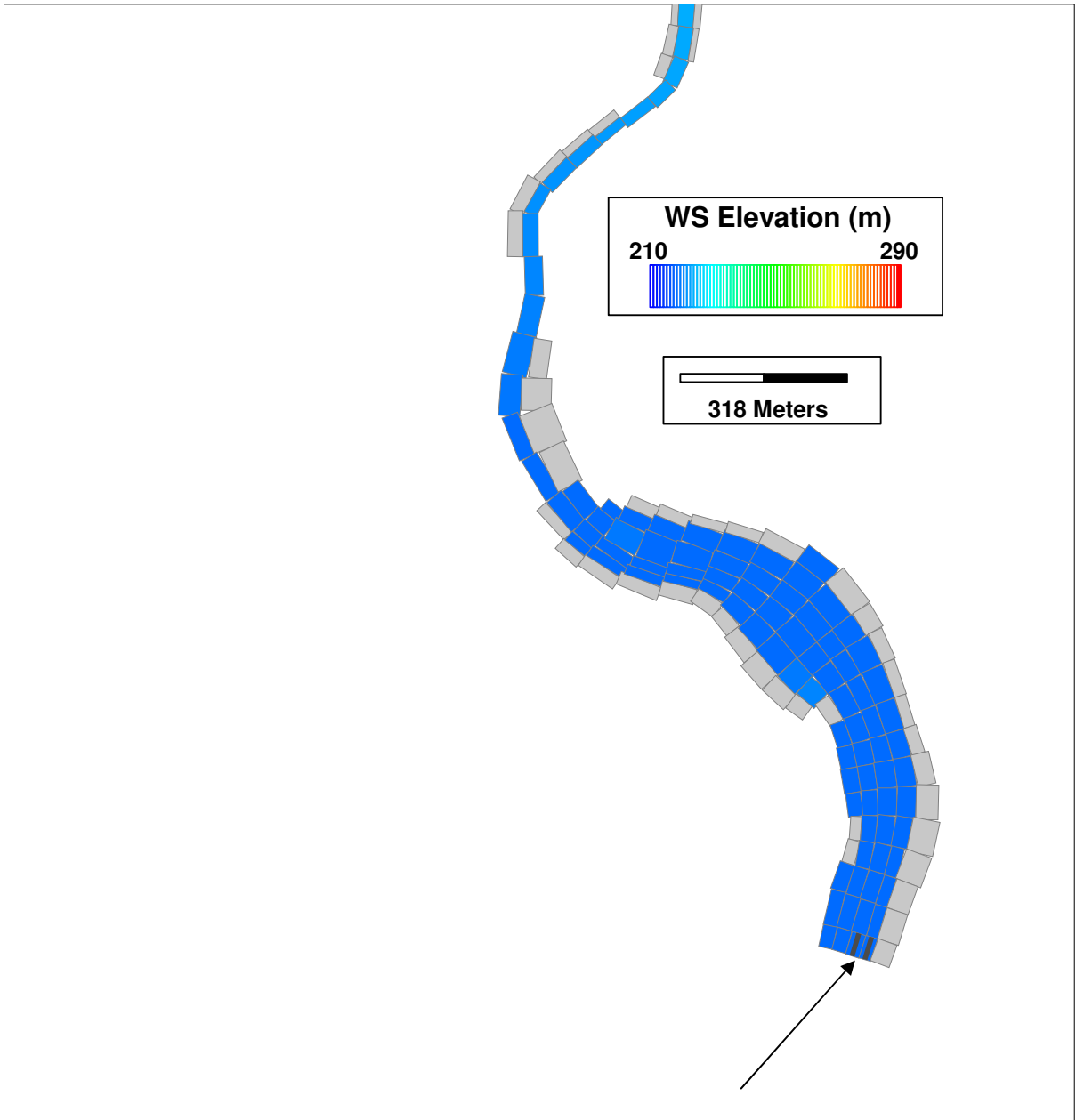


Figure C.12 Computation grid for EFDC model. The arrow points to Rising Pond Dam. North is up in this figure.

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