## Application of Kronecker products in Fusion Applications *

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## 1 Introduction

We describe the application of Kronecker product formulation in speeding up key calculations in fusion codes used in the modeling of wave-plasma interaction within the Department of Energy SciDAC (Scientific Discovery through Advanced Computing $)^{1}$ program. By taking advantage of the compact representation and efficient matrix-matrix calculations, the Kronecker product formulation leads to an order of magnitude speedup in the matrix assembly in RANT3D (Three Dimensional Recesses Antenna Model) code [1]. Interpolation computed as Kronecker products leads to significant speedup in the 'WDOT' power calculation in AORSA2D (AllOrders Spectral Algorithm in Two Dimensions) [4, 5].

## 2 Kronecker Product

Kronecker product (also known as outer product or tensor product) has been successfully used as a framework for understanding different variants of the Fast Fourier Transform [7]. Van Loan [8, 9] has described various interesting properties of Kronecker products and their applications. We shall only briefly review the properties of Kronecker product of matrices.

[^0]Let matrice $A$ be $m A \times n A$ and $B$ be $m B \times n B$. For convenience, let them be indexed as $A(i a, j a)$ and $B(i b, j b)$. Let $C=A \otimes B$ (or $\operatorname{kron}(A, B)$ in MATLAB notation), then matrix $C$ is size $(m A * m B) \times(n A * n B)$. If matrix $A$ is $3 \times 3$, then

$$
C=\left[\begin{array}{ccc}
a_{11} B & a_{12} B & a_{13} B \\
a_{21} B & a_{22} B & a_{23} B \\
a_{31} B & a_{32} B & a_{33} B
\end{array}\right]
$$

Matrix $C$ can be interpreted as a 4 -index array $C([i b, i a],[j b, j a])=A(i a, j a) *$ $B(i b, j b)$, where the composite index $[i b, i a]=i b+(i a-1) * m B$ is the index in Fortran column-wise order. Matrix-vector multiply can be written as very efficient matrix-matrix operations ${ }^{2}$,

$$
\begin{aligned}
Y([i b, i a]) & =C([i b, i a],[j b, j a]) * X([j b, j a]) \\
& =A(i a, j a) * B(i b, j b) * X([j b, j a]) \\
& =B(i b, j b) * X(j b, j a) * A(i a, j a) \\
Y & =B * X * A^{t}
\end{aligned}
$$

Other interesting properties of Kronecker products are summarized below,

$$
\begin{align*}
& (A \otimes B) *(E \otimes F)=(A * E) \otimes(B * F)  \tag{1}\\
& (A+B) \otimes E=A \otimes E+B \otimes E  \tag{2}\\
& (A \otimes B) \otimes E=A \otimes(B \otimes E)  \tag{3}\\
& (A \otimes B)^{-1}=\left(A^{-1} \otimes B^{-1}\right)  \tag{4}\\
& (A \otimes B)^{t}=\left(A^{t} \otimes B^{t}\right) \tag{5}
\end{align*}
$$

## 3 Interpolation

Kronecker products also arise from interpolation of tabulated function values. Let a matrix $F=\left(F_{i j}\right)$ represent tabulated function values for $F_{i j}=F\left(x_{i}, y_{j}\right)$. The function $F(x, y)$ can be approximated as $F(x, y)=\sum_{k, \ell} C_{k \ell} \phi_{k}(x) \phi_{\ell}(y)$, where the basis functions $\phi_{k}(x)$ may be chosen for example to be B-splines or $(k-1)^{t h}$ degree Chebyshev polynomials. The coefficients $C_{k \ell}$ can be computed to satisfy the interpolation conditions

$$
\begin{equation*}
F_{i j}=\sum_{k, \ell} C_{k \ell} \phi_{k}\left(x_{i}\right) \phi_{\ell}\left(y_{j}\right) \tag{6}
\end{equation*}
$$

The interpolation conditions can be expressed as a Kronecker product, $F=\left(T_{y} \otimes\right.$ $\left.T_{x}\right) * C$, where

$$
T_{x}=\left(\begin{array}{ccc}
\phi_{1}\left(x_{1}\right) & \cdots & \phi_{n}\left(x_{1}\right)  \tag{7}\\
\vdots & \ddots & \vdots \\
\phi_{1}\left(x_{n}\right) & \cdots & \phi_{n}\left(x_{n}\right)
\end{array}\right), \quad T_{y}=\left(\begin{array}{ccc}
\phi_{1}\left(y_{1}\right) & \cdots & \phi_{n}\left(y_{1}\right) \\
\vdots & \ddots & \vdots \\
\phi_{1}\left(y_{n}\right) & \cdots & \phi_{n}\left(y_{n}\right)
\end{array}\right) .
$$

[^1]The columns of $T_{x}$ and $T_{y}$ contain the values of the basis functions evaluated as the interpolation knots. The coefficients $C_{k \ell}$ can be efficiently computed using the property of Kronecker products as

$$
\begin{equation*}
C=\left(T_{y} \otimes T_{x}\right)^{-1} * F=\left(T_{y}^{-1} \otimes T_{x}^{-1}\right) * F=T_{x}^{-1} * F * T_{y}^{-t} \tag{8}
\end{equation*}
$$

Once the coefficients are known, extrapolation at the set of new values $F\left(\tilde{x}_{m}, \tilde{y}_{n}\right)=$ $\left(\tilde{F}_{m n}\right)$ can be computed as Kronecker products,

$$
\begin{align*}
& \tilde{F}=T_{\tilde{x}} * C * T_{\tilde{y}} t=T_{\tilde{x}} *\left(T_{x}^{-1} * F * T_{y}^{-t}\right) * T_{\tilde{y}} t, \quad \text { from }(8) \\
& \tilde{F}=\left(T_{\tilde{x}} * T_{x}^{-1}\right) * F *\left(T_{\tilde{y}} * T_{y}^{-1}\right)^{t} \tag{9}
\end{align*}
$$

where

$$
T_{\tilde{y}}=\left(\begin{array}{ccc}
\phi_{1}\left(\tilde{y}_{1}\right) & \cdots & \phi_{n}\left(\tilde{y}_{1}\right)  \tag{10}\\
\vdots & \ddots & \vdots \\
\phi_{1}\left(\tilde{y}_{n}\right) & \cdots & \phi_{n}\left(\tilde{y}_{n}\right)
\end{array}\right)
$$

The above can be generalized to higher dimentions. For a 4 -variable function indexed as $F(w, x, y, z)$, the corresponding interpolation scheme would be

$$
\begin{equation*}
F(w, x, y, z)=\sum_{i, j, k, \ell} C_{i j k \ell} \phi_{i}(w) \phi_{j}(x) \phi_{k}(y) \phi_{\ell}(z) \tag{11}
\end{equation*}
$$

The interpolation conditions can be written as

$$
\begin{equation*}
F=\left(\left(T_{z} \otimes T_{y}\right) \otimes\left(T_{x} \otimes T_{w}\right)\right) * C \tag{12}
\end{equation*}
$$

so that coefficients $C_{i j k \ell}$ can be efficiently computed as

$$
\begin{align*}
C & =\left(T_{x} \otimes T_{w}\right)^{-1} * F *\left(T_{z} \otimes T_{y}\right)^{-t}  \tag{13}\\
& =\left(T_{x}^{-1} \otimes T_{w}^{-1}\right) * F *\left(T_{z}^{-t} \otimes T_{y}^{-t}\right) \tag{14}
\end{align*}
$$

## 4 RANT3D

The RANT3D [1, 2] antenna modeling code solves Maxwell's equations in two and three dimensions. The antenna geometry is specified in Cartesian coordinates through a series of rectangular recesses and current straps. The code is used in the design of radio-frequency (rf) antenna for heating and current drive in tokamaks. The Kronecker product algebra implemented as matrix-matrix multply was used for calculating strap impedance matrices. This reduced the time for multiple strap antenna arrays by an order of magnitude.

RANT3D solves Maxwell's equation in vacuum with a generalized plama boundary

$$
\begin{equation*}
\nabla(\nabla \cdot \mathbf{E})-\left(\nabla^{2}+\frac{\omega^{2}}{c^{2}}\right) \mathbf{E}=i \omega \mu_{0} \mathbf{J} \tag{15}
\end{equation*}
$$

Each component of $\mathbf{E}$ is represented in a variable separable manner by Fourier basis

$$
\begin{equation*}
E_{c}(x, y, z)=\sum_{m, n} E_{c}^{m n}(x) \eta_{c}^{m}(y) \eta_{c}^{n}(z), \quad J_{c}(x, y, z)=\sum_{m, n} J_{c}^{m n} \eta_{c}^{m}(y) \eta_{c}^{n}(z) \tag{16}
\end{equation*}
$$

where subscript $c=x, y$, or $z$, and the basis functions $\eta_{c}^{m}$ are of the form sin, cos or exp.

The constraints that enforce continuity of tangential electric and magnetic fields lead to repeated evaluations of the form

$$
\begin{equation*}
Y(m, n)=\sum_{i, j} B(m, i) X(i, j) A(n, j), \quad \text { for each } m, n \tag{17}
\end{equation*}
$$

The above computation can be seen to be $Y=(A \otimes B) * X$ can this form can be evaluated in $O\left(2 N^{3}\right)$ instead of $O\left(N^{4}\right)$ work. On a model for NSTX (National Spherical Torus Experiment) with 37 recesses, the Kronecker product formulation reduced the time for impedance matrix assembly from about 682 sec to about 55 sec on a 1.3 Ghz Power 4.

## 5 Power Calculations

The AORSA2D code $[3,4,5]$ uses a spectral representation to model the response of plasma to radio frequency (rf) waves in a tokamak geometry by solving the inhomogeneous wave equation or Helmholtz equation,

$$
\begin{equation*}
-\nabla \times \nabla \times \mathbf{E}+\frac{\omega^{2}}{c^{2}}\left(\mathbf{E}+\frac{i}{\omega \epsilon_{0}} \mathbf{J}_{p}\right)=-i \omega \mu_{0} \mathbf{J}_{a n t} \tag{18}
\end{equation*}
$$

where $\mathbf{E}$ is the wave electric field and $\mathbf{J}_{a n t}$ is a specified external antenna current. Most of the complication in (18) arises from the response of the plasma to the electromagnetic wave field, which is included through the plasma current, $\mathbf{J}_{p}$. The rf electric field $\mathbf{E}$ and plasma current $\mathbf{J}_{p}$ are expanded in Fourier harmonics of the radial dimension as

$$
\begin{align*}
\mathbf{E}(x, y) & =\sum_{n, m} \mathbf{E}_{n m} e^{i\left(k_{n} x+k_{m} y\right)}=\sum_{n, m} \mathbf{E}_{n m} e^{i \vec{k}_{n} \cdot r},  \tag{19}\\
\mathbf{J}_{p}(x) & =\sum_{n, m} \sigma\left(x, y, k_{n}, k_{m}\right) \cdot \mathbf{E}_{n m} e^{i\left(k_{n} x+k_{m} y\right)} \tag{20}
\end{align*}
$$

The tensor $\sigma\left(x, y, k_{n}, k_{m}\right)$ can be derived from the first-order rf distribution function given by Stix [6]. It depends on the Fourier mode $k_{n}, k_{m}$ and is a complicated function of modified Bessel functions and plasma $Z$ functions. AORSA2D uses the method of collocation and constructs a large dense complex linear system that is solved in parallel by ScaLAPACK. For example, with $200 \times 200$ Fourier modes, it is necessary to solve 120,000 coupled complex equations, and the storage required for the resulting matrix is about 230 GBytes and require about 1.3 Tflops-hour of computation.

One costly computation is the calculation of the local energy absorption at every grid point in the plasma, after $\mathbf{E}(x, y)$ is available,

$$
\begin{align*}
\dot{W} & =\frac{\partial W\left(\vec{k}_{n}, \vec{k}_{m}\right)}{\partial t}  \tag{21}\\
& =\frac{1}{2} \operatorname{Re} \sum_{n, m} e^{i\left(\vec{k}_{n}-\vec{k}_{m}\right) \cdot \vec{r}} \sum_{\ell=-\infty}^{\infty} \mathbf{E}_{m}^{*} \cdot W_{\ell} \cdot \mathbf{E}_{n}  \tag{22}\\
& =\frac{1}{2} \operatorname{Re} \sum_{n, m} e^{-i \vec{k}_{m} \cdot \vec{r}_{\mathbf{E}}^{m}}{ }_{m}^{*} \cdot\left(\sum_{\ell=-\infty}^{\infty} W_{\ell}\right) \cdot \mathbf{E}_{n} e^{i \vec{k}_{n} \cdot \vec{r}} \tag{23}
\end{align*}
$$

where $W\left(x, y, \vec{k}_{n}, \vec{k}_{m}\right)$ involve costly evaluaton of modified Bessel functions,

$$
\begin{gather*}
W_{\ell}=C *\left(\begin{array}{ccc}
\frac{\ell^{2} I_{\ell}}{\tilde{\Gamma}} Z_{\ell} & -i \ell\left(\frac{\Gamma_{n}}{\tilde{\Gamma}} I_{\ell}-I_{\ell}^{\prime}\right) Z_{\ell} & -k_{\perp, n} \frac{\ell I_{\ell}}{\tilde{\Gamma}} \frac{\alpha Z_{\ell}^{\prime}}{2 \Omega} \\
i \ell\left(\frac{\Gamma_{m}}{\tilde{\Gamma}} I_{\ell}-I_{\ell}^{\prime}\right) Z_{\ell} & {\left[\frac{\ell^{2}}{\tilde{\Gamma}} I_{\ell}+2 \tilde{\Gamma} I_{\ell}-2 \bar{\Gamma} I_{\ell}^{\prime}\right] Z_{\ell}} & -i\left(k_{\perp, m} I_{\ell}-k_{\perp, n} I_{\ell}^{\prime} \frac{\alpha Z_{\ell}^{\prime}}{2 \Omega}\right. \\
-k_{\perp, m} \frac{\ell I_{\ell}}{\tilde{\Gamma}} \frac{\alpha Z_{\ell}^{\prime}}{2 \Omega} & i\left(k_{\perp, n} I_{\ell}-k_{\perp, m} I_{\ell}^{\prime}\right) \frac{\alpha Z_{\ell}^{\prime}}{2 \Omega} & -\zeta_{\ell} I_{\ell} Z_{\ell}^{\prime}
\end{array}\right), \\
I_{\ell}=I_{\ell}(\tilde{\Gamma}), \quad I_{\ell}^{\prime}=I_{\ell}^{\prime}(\tilde{\Gamma}), \quad C=-i \epsilon_{0} \frac{\omega_{p}^{2}}{k_{\perp} \alpha} e^{-\bar{\Gamma}}  \tag{24}\\
\tilde{\Gamma}=\sqrt{\Gamma_{n} \Gamma_{m}}, \quad \bar{\Gamma}=\frac{1}{2}\left(\Gamma_{n}+\Gamma_{m}\right), \quad \Gamma_{n}=\frac{1}{2}\left(k_{\perp, n} \alpha / \Omega\right)^{2} \tag{25}
\end{gather*}
$$

Here $I_{\ell}$ is the modified Bessel function of order $\ell, Z_{\ell}$ is the plasma dispersion function with arguments $\zeta_{\ell}=(\omega-\ell \Omega) /\left|k_{\perp}\right| \alpha$, and derivative of $Z_{\ell}$ is $Z_{\ell}^{\prime}\left(\zeta_{\ell}\right)=$ $-2\left[1+\zeta_{\ell} Z\left(\zeta_{\ell}\right)\right]$. There is an additional 'Swanson's rotation' to transform $\mathbf{E}(x, y)$ and other quantities between the 'Stix frame' and local coordinate aligned to the magnetic field.

Two simplifying assumptions are used to reduce the cost for computing $\dot{W}$. The first is to truncate the expansion of $W_{\ell}$ typically to $-2 \leq \ell \leq 2$. The second is to restrict the evaluation to a smaller number of local Fourier modes (say 32 modes instead of 96 modes) and with some overlap with neigboring nodes. Even with these simplications for the evaluation of $\dot{W}$, the relative error in evaluation is typically less than $5 \%$.

This costly evaluation can be further reduced by using interpolation and extrapolation expressed as Kronecker products in (9). We shall consider, for example, the evaluation of the $(1,1)$ component in $\dot{W}$. The evaluation of other entries can be similarly derived. The main contribution is

$$
\begin{equation*}
\sum_{m, n} u_{m}\left(\sum_{\ell} \ell^{2} I_{\ell} Z_{\ell}\right) v_{n} \tag{26}
\end{equation*}
$$

where $u_{m}=e^{-i \vec{k}_{m} \cdot \vec{r}_{\mathbf{E}}^{m}} / \sqrt{\Gamma_{m}}, v_{n}=e^{i \vec{k}_{n} \cdot \vec{r}} \mathbf{E}_{n} / \sqrt{\Gamma_{n}}\left(\right.$ with $\tilde{\Gamma}=\sqrt{\Gamma_{n} \Gamma_{m}}$ ). This can be interpreted as the algebraic evaluation of a vector product, $u^{t} * \tilde{F} * v$ where entries in matrix $\tilde{F}, \tilde{F}_{n, m}=\sum_{\ell} \ell^{2} I_{\ell}\left(\sqrt{\Gamma_{n} \Gamma_{m}}\right) Z_{\ell}$ are costly to compute.

As entries in the matrix $\tilde{F}$ (size $M \times M$ ) are smooth functions of modified Bessel functions and plasma $Z$ dispersion functions, we can consider approximating matrix $\tilde{F}$ by evaluating only a $m \times m$ submatrix $F$ and performing interpolation. Using equations (8) and (9), we have

$$
\begin{align*}
u^{t} \tilde{F} v & =u^{t} *\left(T_{\tilde{x}} * T_{x}^{-1}\right) * F *\left(T_{\tilde{y}} * T_{y}^{-1}\right)^{t} * v  \tag{27}\\
& =\left(u^{t} * T_{\tilde{x}} * T_{x}^{-1}\right) * F *\left(T_{y}^{-t} T_{\tilde{y}}{ }^{t} v\right)  \tag{28}\\
& =\tilde{u}^{t} * F * \tilde{v}, \quad \text { where } \tilde{u}=T_{x}^{-t} * T_{\tilde{x}}^{t} * u, \tilde{v}=T_{y}^{-t} * T_{\tilde{y}}{ }^{t} * v . \tag{29}
\end{align*}
$$

Since the evaluation of $\dot{W}$ is repeated many times at each grid point in the plasma, we can amortize the cost for precomputing the transformation matrices

$$
\begin{equation*}
\hat{T}_{y}=T_{y}^{-t} * T_{\tilde{y}}^{t}, \quad \hat{T}_{x}=T_{x}^{-t} * T_{\tilde{x}}^{t} \tag{30}
\end{equation*}
$$

The overall approximate computation of $u^{t} * \tilde{F} * v$ can be arranged as (i) evaluation of a submatrix $F$, (ii) transform vectors $\tilde{u}=\hat{T}_{y} * u, \tilde{v}=\hat{T}_{x} * v$ (in $O(2 m M)$ work) and (iii) final evaluation of $\hat{u}^{t} * F * \hat{v}$ (in $O\left(2 m^{2}\right)$ work). Note that explicit computation of the interpolation coefficients by (8) (in $O\left(2 m^{3}\right)$ work) and evaluation of $\tilde{F}$ by (9) (in $O\left(m M^{2}\right)$ work) to evaluate $u^{t} * F * v$ (in $O\left(2 M^{2}\right)$ work) would be more costly.

This approximate evaluation of $\dot{W}$ has been incorporated into the AORSA2D code. For one typical computation with $96 \times 96$ modes, the time for evaluating $\dot{W}$ using 32 local Fourier modes required about 78.3 min while the Kronecker version that evaluated a $9 \times 9$ submatrix (instead of $32 \times 32$ matrix for each component) reduced the time to about 7.1 minutes with less than $3 \%$ difference in the results.

There is an on-going effort to incorporate similar Kronecker technology for evaluate of $\dot{W}$ in the three-dimensional version of AORSA.

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[^1]:    ${ }^{2}$ We blur the distinction between the matrix $X(j b, j a)$ and vector $X([j b, j a])$ with composite index.

