# Algorithms for Processing Cloud Microphysical Data Acquired by Atmospheric Radiation Measurement Program Unmanned Aerospace Vehicle Applications to TWP-ICE

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# Introduction

The Atmospheric Radiation Measurement (ARM) Program's Unmanned Aerospace Vehicle program currently maintains and operates a complete suite of cloud probes that provide in situ measurements of the size and shape distributions of ice crystals over a wide range of sizes and bulk measurements of extinction (βe) and ice water content (IWC).

Processing programs, developed in MatLab, allow users to easily obtain, view and plot higher level data products using a graphical user interface (GUI). This allows quality control immediately after the data is downloaded from the aircraft.

# **Cloud Particle Images and Size Distributions**

For the Cloud Aerosol Precipitation Spectrometer (CAPS), a code converts the measured particle counts into size distributions (SDs), total concentration, IWC and  $\beta e$ . Figure 1 shows the GUI used to plot data from all in-situ probes, including the CAPS. Particle images from the Cloud Imaging Probe (CIP) are displayed in Figure 2. Matlab routines determine each particle's diameter, area, axis ratio, circularity, and habit. In Figure 3, number concentrations from the CIP and Cloud Aerosol Spectrometer (CAS), components of the CAPS, are shown.

|        | Current File: caps.20060202.a3.cdf  |       |
|--------|---|-------|
| CAPS T | otal Time: 3342-71812 🔄 All Time  |       |
| S      | Start Time 024700   |       |
| 1      | End Time 71812 Plot Temp  |       |
| 1      | - Plot Particle Counts  | T     |
|        |   |       |
|        | Scatter Plot (must pick two parameters)                                   |       |
|        | Plot Particle Size Distribution   |       |
|        | CAS CDP CPI   |       |
| 1      | - Plot Number Concentration   | T     |
|        | CIP CAS CAS+CIP CDP   |       |
|        | Plot TVVC   | 1     |
|        | CIP CAS CAS+CIP Nevz CSI LVVC   | 12    |
| -      | Plot Extinction Coefficient   | 1     |
|        | CIP CAS CAS+CIP CIN 0 CIN Aver<br>Scatter Plot (Must Pick two parameters) | aging |
| 1-     | Time per graph 10 Graph dimensions 1 x 1                                  |       |
|        | Prev Set Graph Next Set   |       |
|        | Auto-Graph  |       |

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Figure 1. Example of GUI.



**Figure 2**. CIP particle images plotted using CAPS processing routine. Vertical bars denote timing bar needed for concentration calculation in Matlab.



**Figure 3**. Total number concentration measured by the CIP and CAS during the first spiral in an anvil on February 2 during Tropical Warm Pool-International Cloud Experiment (TWP-ICE).

The Proteus also carried a Cloud Particle Imager (CPI). Particle images and SDs are generated using CPIView, developed by The Stratton Park Engineering Company Inc. The Matlab code imports the CPI SDs and combines them with the CAS and CIP SDs. Figure 4 shows example SDs from the CPI and CAPS.



Figure 4. CAPS and CPI SDs from the first spiral on February 2 during TWP-ICE.

#### **Bulk Microphysical Measurements**

A bulk measurement of total water content (TWC) is provided by the CSI, whereas channel voltages from the Nevzorov probe are converted to bulk measures of TWC and liquid water content using a point outside cloud to correct for an altitude dependent baseline drift. The Matlab code compares IWC from the bulk probes against that derived from the CAPS SDs (Figure 5).



**Figure 5**. Nevzorov, CSI and derived CAPS derived TWC for the first spiral on February 2 during TWP-ICE.

The Matlab code also calculates bulk measures of  $\beta$ e and asymmetry parameter (g) from the convective inhibition (CIN) with averaging intervals specified by the user. The CIN  $\beta$ e can be compared against  $\beta$ e derived from integrating the CAPS SDs assuming geometric optics (Figure 6).

![](_page_5_Figure_1.jpeg)

Figure 6. Comparison between CAPS and CIN βe for 1st spiral on February 2 during TWP-ICE.

### **Cloud Boundaries**

The Matlab code applies Wang and Sassen's (2001) cloud detection algorithm to cloud lidar data to determine tops and bottoms for up to 10 cloud layers. The GUI (Figure 7) allows the user to set threshold values for the boundaries and the time domain over which the boundaries should be computed. It can plot the normalized backscatter return, the cloud boundaries (Figure 8) or histograms of the derived cloud heights (Figure 9).

![](_page_6_Figure_1.jpeg)

Figure 7. Example of GUI that runs in Matlab for identifying cloud boundaries.

![](_page_7_Figure_1.jpeg)

Figure 8. Cloud boundaries determined by applying Wang and Sassen algorithm to lidar signal.

![](_page_8_Figure_1.jpeg)

**Figure 9**. Histograms of normalized frequency of occurrence of cloud heights. Points with aircraft pitch angles > 5 degrees excluded from analysis.

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## References

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