	General Characteristics				
1	Abstract of Model Capabilities	VDI Parts 1 and 2 are individual computer programs designed to model the dispersion of vapor plumes (positively and neutrally buoyant), and denser-than-air vapor releases, respectively. Part 2 may be used to model the dispersion of dense gases in any one of 25 different configurations of street canyons, buildings, or the intersection of basic geometric shapes. Part 2 provides the distance to the lower flammability limit or the distance to the transition point from dense gas to neutrally buoyant behavior. Part 1 predicts the vapor concentration and dose exposure as a function of time and distance from the source either for an initially buoyant release or using the initial conditions provided by Part 2 for a dense gas release. Each part may be run separately or together in the case of toxic vapor exposure by means of a combined program called STOER.			
2	Sponsor and/or Developing Organization	Verein Deutscher Ingenieure (VDI) Kommission Reinhaltung der Luft D-4000 Düsseldorf, Deutschland			
3	Last Custodian/ Point of Contact	Dr. Michael Schatzmann Meteorologisches Institut Universität Hamburg Bundesstra be 55 D-20146 Hamburg Germany 49-40-41235090 49-40-41173350 (Fax)			
4	Life-Cycle	Part 1: Only a single version (version 1.0). Part 2: Version 4.0 (September 1992); Version 3.0 (July 1990); version 2.0 (December 1988).			
5	Model Description Summary Application Limitation	VDI Guidelines Parts 1 and 2 are computerized methodologies for predicting the dispersion of a neutrally buoyant and dense gas release, respectively. Both programs are part of the safety study program for the German Administrative Regulation for the Ordinance on Industrial Accidents. Part 1: This program is a computerized implementation of the Gaussian plume equations for continuous ground-level or elevated releases. The release rate may be time-varying within specific prescribed constraints on variability. Furthermore, reflection of the plume off the mixing layer lower boundary is also modeled. Part 2: This program is a method for predicting the dispersion of denser-than-air gases based on empirical data obtained from wind tunnel studies for "instantaneous" and time-varying continuous releases into a boundary layer shear flow. The model is applicable both for the cases of level, unobstructed dispersion as well as more complex flow and turbulence structure due to the presence of downwind obstacles. Part 1: The model assumes pure reflections of the plume at ground level and the mixing layer.			
		Volume sources are initially approximated as right parallelepipeds. The time dependency of the volume source is approximated by the superposition of the concentration distribution attributed to a series of instantaneous point sources. Part 2: All dense gas releases are assumed to be ground-level sources at a nominal ambient temperature of 15°C whereas the neutrally buoyant model treats both ground-level and elevated with no assumption on ambient temperature. Heat transfer effects are not modeled in the code and the calculations assume a fully developed single-phase vapor cloud is given. Therefore, superheated flashing releases or vapor clouds containing suspended aerosol cannot be treated in a rigorous way but rather relies on the user to approximate these effects by means of initial cloud density and mass.			
7	Strengths/ Limitations	Strengths: The dense gas model has the option of modeling the effect of the presence of obstacles to flow (e.g., street canyons, buildings, or the intersection of basic geometrical shapes for a total of 25 different configurations) on the subsequent downwind vapor dispersion. Provisions for modeling the dispersion from a line, area, and volumetric neutrally buoyant vapor source are available in the code. Limitations: The method used for modeling line, area, and volumetric neutrally buoyant vapor sources is not an accurate solution to the diffusion equation and can potentially incur significant errors in the subsequent downwind concentration estimates when the dimensions of the source are not much less than the downwind distance of interest. The dense gas program assumes no initial dilution of the vapor cloud (however the guidelines can be applied in the case of initial dilution). Furthermore, the dense gas model only gives endpoint results (distance either to the lower flammable limit for flammable gases or 1% of initial concentration for toxic gases) for receptors on the lee side of the specified obstacle configuration.			
8	Model References	 Verein Deutscher Ingenieure, Handbuch 3783, Reinhaltung der Luft, Blatt 1, Mai 1987. Verein Deutscher Ingenieure, Handbuch 3783, Reinhaltung der Luft, Blatt 2, Juli 1990. 			

e elevated above ambient of time in tabular format), re stratification), mixing
a function of time in uildings on the lee side of nt in the crosswind of structures located on table temperature time in tabular format), with y"), initial vapor density, classification.
cted downwind distances eteorological conditions. For worst-case and median el of 1% of the initial ence conditions. Efined differently based on more familiar wind ser guide for more details).
ernment for use in
enced to an associated en prompt. All online 1 and STOER (Parts 1 and glish and German. All
econds maximum on an ing a standard FORTRAN
swer or an integer value calculations. Entering an he user to re-enter the messages (e.g., failure to well as STOER can be run s in a single input file aal problem set in
om continuous release yV Hamburg and Maplin
ret til en se en s

	Specific Characteristics					
Part A: Source Term Submodel Type						
A1	Source Term Algorithm?	_YES <u>~</u> NO				
Part B	Part B: Dispersion Submodel Type					
B1	Gaussian	<u>✓</u> Straight-line plumeSegmented plume Statistical plume Statistical puff				
Part C	: Transport Submodel	Туре				
C2	Deterministic	Yes				
C4	Frame of Reference	<u>✓</u> Eulerian Lagrangian Hybrid Eulerian-Lagrangian				
Part D	: Fire Submodel Type	(Not Applicable)				
Part E	Energetic Events Sub	model Type (Not Applicable)				
Part F:	Health Consequence	Submodel Type				
F1	For Chemical Consequence Assessment Models	Health effects:fatalitiescancerslatent cancers symptom onset Health criteriaTLVTWA				
		ERPG TEEL AEGL WHO Zones with flammable limits:				
		Blast overpressure regions:				
		Fire radiant energy zones:				
		Risk qualification: Concentration: single value time-history integrated dose				
		Probits:				
Part G	: Effects and Countern	neasures Submodel Type (Not Available)				
Part H	Physical Features of	Model				
H2	Release Elevation	<u>✓</u> ground <u>✓</u> roof				
H3	Aerodynamic Effects from	<u>✓</u> building wake <u>✓</u> cavity <u>✓</u> K-factors <u>✓</u> flow separation				
	Buildings and Obstacles	Building wake effects are estimated for 25 different configurations.				
H6	Mixing Layger	trappinglofting _v_reflectionpenetrationinversion breakup fumigationtemporal variability				
Part I:	Part I: Model Input Requirements					
I1	Radio(chemical) and Weapon Release Parameters	Release rate: Continuous Time dependent Instantaneous Release container characteristics: vapor temperature tank diameter tank height tank temperature tank pressure nozzle diameter pipe length				
		Jet release: initial size shape concentration profile at end of jet affected zone				
		Release dimensions: 🗸 point 🗸 line 🗸 area				
		Release elevation: <u>v</u> ground <u>v</u> roof <u>v</u> stack				

Part J: Model Output Capabilities			
J1	Hazard Zone	Part 2 of the VDI guidelines is designed primarily for determination of downwind distance to the lower flammability limit.	
J3	Concentration Versus Time Plots	INELVIZ (see J2 above) has a data base from which concentrations versus time can be obtained; however, time plots must be made by an external plotting program.	
J4	Tabular at Fixed Downwind Locations	Yes	
Part K: Model Usage Considerations (No Information Provided.)			