## **Radiance to Reflectance for GOES-8 Channel 1**

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The following is a discussion on converting GOES-8 Imager visible radiance measurements to reflectance values. An overview of GOES-8 Imager is provided then the reflectance equation is derived.

## GOES-8 Imager - Channel One

The Imager aboard GOES-8 reports radiance measurements in count values ranging from 0 to 1023 counts. The linear response of the sensor provides the following calibration equation to convert counts (n) to radiance (L):

$$\mathbf{L} = \mathbf{mn} + \mathbf{b} \tag{A.1}$$

where m is the inverse of sensor responsivity and b is the offset. The pre-launch values of these calibration coefficients, measured at ITT in Fort Wayne, Indiana, are  $m = 0.551 \text{ Wm}^{-2}$  ster<sup>-1</sup> $\mu$ m<sup>-1</sup>count<sup>-1</sup> and b = -15.3 Wm<sup>-2</sup>ster<sup>-1</sup> $\mu$ m<sup>-1</sup> (available at the WWW site http://climate-f.gsfc.nasa.gov/~chesters/text/imager.calibration.html).

These values are only valid prior to launch and soon thereafter. Otherwise, the sensor is subject to response drift, which has been noticed in visible data from GOES-8. Weinreb (1995) calculated a decrease in responsivity of about 15%. But, there exist methods to determine these calibration coefficients in-flight, although they require a priori knowledge of the surface reflectance and atmospheric optical properties. Surfaces such as the ocean and deserts are useful for this process because their spatially homogeneous

reflectances are well-studied. Whereas atmospheric optical properties, such as vertical structure of optical depth, single scatter albedo and asymmetry parameter of aerosols, are usually assumed variables. Aerosols over the ocean have a relatively constant distribution and optical parameters, whereas aerosols over land are variable in both respects. These atmospheric variables are used in a radiative transfer model to calculate a radiance the satellite sensor should detect. This method was used by Fraser et al. (1984) to calculate GOES-7 VISSR coefficients from a region in the Atlantic Ocean.

## Reflectance

The following discussion of reflectance does not include spectral dependence. Surface reflectance, solar emittance and the Imager sensor response have different spectral dependencies. Therefore, radiances mentioned hereafter are band-averaged quantities, averaged over the spectral response of the GOES-8 Imager. The process of this band averaging is discussed in the next section.

Figure A.1 shows the geometry of a radiance from a source direction (the Sun) with zenith angle  $\theta_0$  and azimuth angle  $\phi_0$  reflected by a surface (dA) into the direction  $\theta$  and  $\phi$  (Stephens, 1994). The equation of reflected radiance (L<sub>r</sub>) defined by Kidder and Vonder Haar (1995) is:

$$L_{r}(\theta_{r},\phi_{r}) = \int_{0}^{2\pi} \int_{0}^{\pi/2} L_{i}(\theta_{i},\phi_{i}) \gamma_{r}(\theta_{i},\phi_{i};\theta_{r},\phi_{r}) \cos\theta_{i} \sin\theta_{i} d\theta_{i} d\phi_{i}$$
(A.2)

where  $L_i$  is the incident radiance from the direction ( $\theta_i$ ,  $\phi_i$ ), which is partially reflected ( $\gamma_r$ ) into the direction ( $\theta_r$ ,  $\phi_r$ ).  $\gamma_r$  is the bi-directional reflection function (BDRF) which requires:

$$\int_{0}^{2\pi} \int_{0}^{\pi/2} \gamma_{\rm r} (\theta_{\rm r}, \phi_{\rm r}; \theta_{\rm o}, \phi_{\rm o}) \cos \theta_{\rm r} \sin \theta_{\rm r} d\theta_{\rm r} d\phi_{\rm r} \equiv A \tag{A.3}$$

such that  $\gamma_r$  is the fraction of  $L_i$  reflected to the direction  $\theta_r$ ,  $\phi_r$  and A is the total fraction of reflected light in all directions, the albedo. Then, considering the sun as the only source,  $L_i$  becomes a delta function:

$$L_{i}(\theta_{i}, \phi_{i}) = \begin{cases} L_{o} & \theta_{i} = \theta_{o}, \phi_{i} = \phi_{o} \\ 0 & \theta_{i} \neq \theta_{o}, \phi_{i} \neq \phi_{o} \end{cases}$$
(A.4)

where  $L_o$  is the solar emitted radiance. Also, if the reflecting surface is assumed to be a Lambertian reflector, then incident radiance is reflected uniformly in all directions. Defining:

$$\gamma_{\rm r} (\theta_{\rm r}, \phi_{\rm r}; \theta_{\rm o}, \phi_{\rm o}) = \frac{\rho}{\pi}$$
(A.5)

so

$$\int_{0}^{2\pi} \int_{0}^{\pi/2} \gamma_{r} (\theta_{r}, \phi_{r}; \theta_{i}, \phi_{i}) \cos \theta_{r} \sin \theta_{r} d\theta_{r} d\phi_{r} \equiv \rho.$$
 (A.6)

Using equations A.4 and A.5, equation A.2 becomes:

$$L_{r}(\theta_{r},\phi_{r}) = L_{o}\cos\theta_{o}\Omega_{o}\frac{\rho}{\pi}$$
(A.7)

where  $\Omega_{o}$  is the solid angle of the sun subtended by the earth. Thus,

$$L_{r}(\theta_{r},\phi_{r}) = \frac{\rho}{\pi} F_{o} \cos\theta_{o}$$
 (A.8)

where  $F_o = L_o \Omega_o$ .

## Calculation of GOES-8 Imager Channel 1 Reflectance

So from equation A.8, visible reflectance is calculated from the GOES-8 Imager by:

$$\rho = \frac{\pi L_r(\theta_r, \phi_r)}{F_o \cos \theta_o}.$$
 (A.9)

 $L_r$  is calculated from Imager data and the calibration coefficients discussed above. The latitude and longitude of the image pixel and time of satellite scan determine  $\cos \theta_o$ .  $F_o$  is the incident radiance at the same wavelengths that measure  $L_r$ . So  $F_o$  is the theoretical value if the satellite were to look directly at the sun. It is determined by:

$$F_{o} = \frac{\int_{0}^{\infty} S_{\lambda} w_{\lambda} d\lambda}{\int_{0}^{\infty} w_{\lambda} d\lambda}$$
(A.10)

where  $w_{\lambda}$  is the spectral response, or weighting function, of channel 1 of the Imager and  $S_{\lambda}$  is the spectral irradiance of the Sun. Figure A.2 shows the solar emittance and figure A.3 shows the relative weighting function of channel 1 of the Imager on GOES-8. From figure A.3, it can be seen that there exist limits on the weighting function outside of which the sum approaches zero:

$$\int_{0}^{\lambda_{\min}} w_{\lambda} d\lambda + \int_{\lambda_{\max}}^{\infty} w_{\lambda} d\lambda \approx 0$$
 (A.11)

where  $\lambda_{\min}$  and  $\lambda_{\max}$  are determined from  $w_{\lambda}$ . In the weighting function provided (Weinreb, personal communication),  $[\lambda_{\min}, \lambda_{\max}] = [0.45, 1.01 \mu m]$ . So equation A.11 becomes:

$$F_{o} = \frac{\int_{\lambda_{min}}^{\lambda_{max}} S_{\lambda} w_{\lambda} d\lambda}{\int_{\lambda_{min}}^{\lambda_{max}} w_{\lambda} d\lambda}$$
(A.12)

Applying the data in figures A.2 and A.3 to equation A.12 results in:

$$F_0 = 1627.945 \text{ Wm}^{-2}$$
 (A.13)

Therefore, visible reflectance is calculated by:

$$\rho = \frac{L_r(\theta_r, \phi_r)\pi}{1627945\cos\theta_o} = \frac{L_r(\theta_r, \phi_r)}{518.191\cos\theta_o} = \frac{L_r(\theta_r, \phi_r)}{\cos\theta_o} 192979 \times 10^{-3}.$$
(A.14)

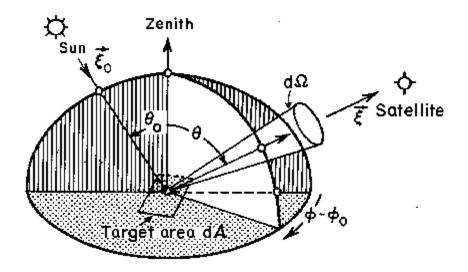


Figure A.1 - Schematic of reflected radiance,  $L(\theta, \phi)$ , by target area, dA, for the source being the sun,  $F_o$ (Stephens, 1994).

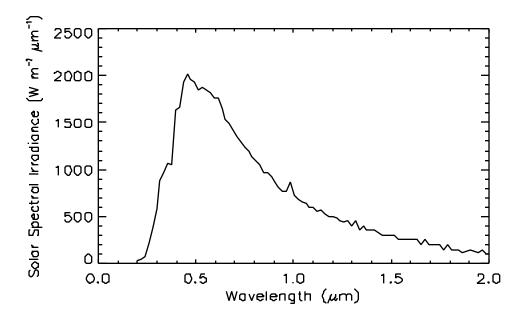


Figure A.2 - The solar spectral irradiance as a function of wavelength.

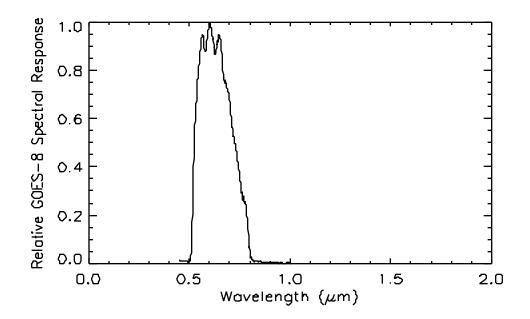


Figure A.3 - The relative weighting function (or spectral response) as a function of wavelength.